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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

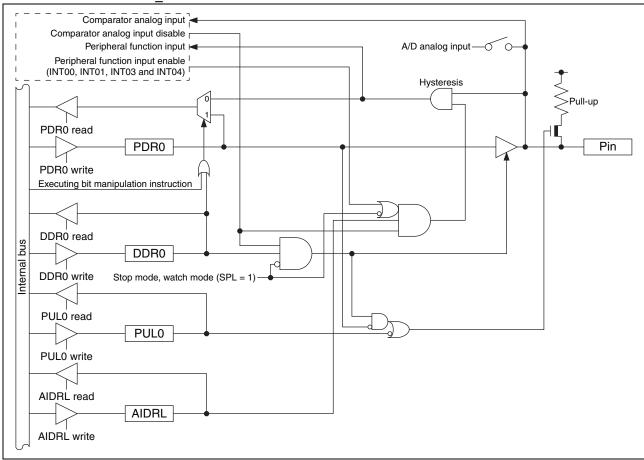
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb95f696kpmc-g-sne2
Supplier Device Package	48-LQFP (7x7)
Package / Case	48-LQFP
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 85°C (TA)
Oscillator Type	External
Data Converters	A/D 12x8/10b
Voltage - Supply (Vcc/Vdd)	2.88V ~ 5.5V
RAM Size	1K x 8
EEPROM Size	-
Program Memory Type	FLASH
Program Memory Size	36KB (36K x 8)
Number of I/O	45
Peripherals	LVD, POR, PWM, WDT
Connectivity	I ² C, LINbus, SIO, UART/USART
Speed	16MHz
Core Size	8-Bit
Core Processor	F ² MC-8FX
Product Status	Obsolete
Details	



Address	Register abbreviation	Register name	R/W	Initial value
0x0055	ECCR	LIN-UART extended communication control register	R/W	0b000000XX
0x0056	SMC10	UART/SIO serial mode control register 1 ch. 0		0b00000000
0x0057	SMC20	UART/SIO serial mode control register 2 ch. 0	R/W	0b00100000
0x0058	SSR0	UART/SIO serial status and data register ch. 0	R/W	0b00000001
0x0059	TDR0	UART/SIO serial output data register ch. 0	R/W	0b00000000
0x005A	RDR0	UART/SIO serial input data register ch. 0	R	0b00000000
0x005B to 0x005F	_	(Disabled)	_	_
0x0060	IBCR00	I ² C bus control register 0 ch. 0	R/W	0b00000000
0x0061	IBCR10	I ² C bus control register 1 ch. 0	R/W	0b00000000
0x0062	IBSR0	I ² C bus status register ch. 0	R/W	0b00000000
0x0063	IDDR0	I ² C data register ch. 0	R/W	0b00000000
0x0064	IAAR0	I ² C address register ch. 0	R/W	0b00000000
0x0065	ICCR0	I ² C clock control register ch. 0	R/W	0b00000000
0x0066	OPCUR	16-bit MPG output control register (upper)	R/W	0b0000000
0x0067	OPCLR	16-bit MPG output control register (lower)	R/W	0b00000000
0x0068	IPCUR	16-bit MPG input control register (upper)	R/W	0b00000000
0x0069	IPCLR	16-bit MPG input control register (lower)	R/W	0b00000000
0x006A	NCCR	16-bit MPG noise cancellation control register	R/W	0b00000000
0x006B	TCSR	16-bit MPG timer control status register	R/W	0b00000000
0x006C	ADC1	8/10-bit A/D converter control register 1	R/W	0b00000000
0x006D	ADC2	8/10-bit A/D converter control register 2	R/W	0b00000000
0x006E	ADDH	8/10-bit A/D converter data register (upper)	R/W	0b00000000
0x006F	ADDL	8/10-bit A/D converter data register (lower)	R/W	0b00000000
0x0070	_	(Disabled)	_	_
0x0071	FSR2	Flash memory status register 2	R/W	0b00000000
0x0072	FSR	Flash memory status register	R/W	0b000X0000
0x0073	SWRE0	Flash memory sector write control register 0	R/W	0b00000000
0x0074	FSR3	Flash memory status register 3	R	0b000XXXXX
0x0075	FSR4	Flash memory status register 4	R/W	0b00000000
0x0076	WREN	Wild register address compare enable register	R/W	0b00000000
0x0077	WROR	Wild register data test setting register		0b00000000
0x0078	_	Mirror of register bank pointer (RP) and direct bank pointer (DP)	_	_
0x0079	ILR0	Interrupt level setting register 0	R/W	0b11111111
0x007A	ILR1	Interrupt level setting register 1	R/W	0b11111111
0x007B	ILR2	Interrupt level setting register 2	R/W	0b11111111



 Block diagram of P00/INT00/AN00/CMP0_P, P01/INT01/AN01/CMP0_N, P03/INT03/AN03/CMP1_P and P04/INT04/AN04/CMP1 N





• P06/INT06/AN06 pin

This pin has the following peripheral functions:

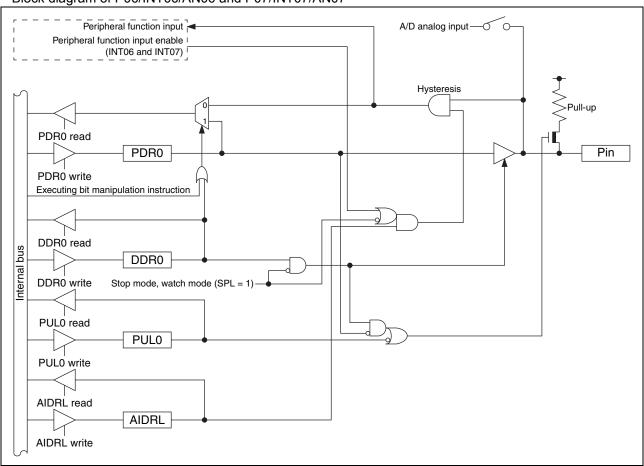
- External interrupt input pin (INT06)
- 8/10-bit A/D converter analog input pin (AN06)

• P07/INT07/AN07 pin

This pin has the following peripheral functions:

- External interrupt input pin (INT07)
- 8/10-bit A/D converter analog input pin (AN07)

Block diagram of P06/INT06/AN06 and P07/INT07/AN07





17.2 Port 1

Port 1 is a general-purpose I/O port. This section focuses on its functions as a general-purpose I/O port. For details of peripheral functions, refer to their respective chapters in "New 8FX MB95690K Series Hardware Manual".

17.2.1 Port 1 configuration

Port 1 is made up of the following elements.

- General-purpose I/O pins/peripheral function I/O pins
- Port 1 data register (PDR1)
- Port 1 direction register (DDR1)
- Port 1 pull-up register (PUL1)

17.2.2 Block diagrams of port 1

P10/PPG10* pin

This pin has the following peripheral function:

- 8/16-bit PPG ch. 1 output pin (PPG10)
- P11/PPG11* pin

This pin has the following peripheral function:

- 8/16-bit PPG ch. 1 output pin (PPG11)
- P13/PPG00* pin

This pin has the following peripheral function:

- 8/16-bit PPG ch. 0 output pin (PPG00)
- P14/PPG01* pin

This pin has the following peripheral function:

- 8/16-bit PPG ch. 0 output pin (PPG01)
- P15/PPG20* pin

This pin has the following peripheral function:

- 8/16-bit PPG ch. 2 output pin (PPG20)
- P16/PPG21* pin

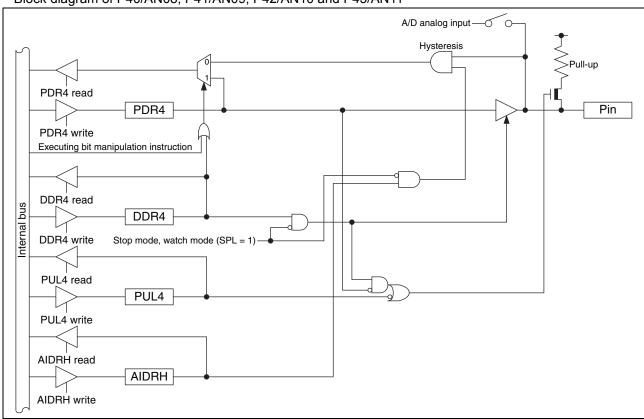
This pin has the following peripheral function:

- 8/16-bit PPG ch. 2 output pin (PPG21)
- *: The 8/16-bit PPG output pins are mapped to pins according to the setting of the PPGSEL bit in the SYSC register. See the table below for details.

8/16-bit PPG output pin	SYSC:PPGSEL = 0	SYSC:PPGSEL = 1			
o/ 16-bit PPG output piii	Pin				
PPG00	P13	P62			
PPG01	P14	P63			
PPG10	P10	P64			
PPG11	P11	P65			
PPG20	P15	P66			
PPG21	P16	P67			



Block diagram of P40/AN08, P41/AN09, P42/AN10 and P43/AN11





17.5 Port 7

Port 7 is a general-purpose I/O port. This section focuses on its functions as a general-purpose I/O port. For details of peripheral functions, refer to their respective chapters in "New 8FX MB95690K Series Hardware Manual".

17.5.1 Port 7 configuration

Port 7 is made up of the following elements.

- · General-purpose I/O pins/peripheral function I/O pins
- Port 7 data register (PDR7)
- Port 7 direction register (DDR7)
- Port 7 pull-up register (PUL7)

17.5.2 Block diagrams of port 7

P70/TO00 pin

This pin has the following peripheral function:

• 8/16-bit composite time ch. 0 output pin (TO00)

• P71/TO01 pin

This pin has the following peripheral function:

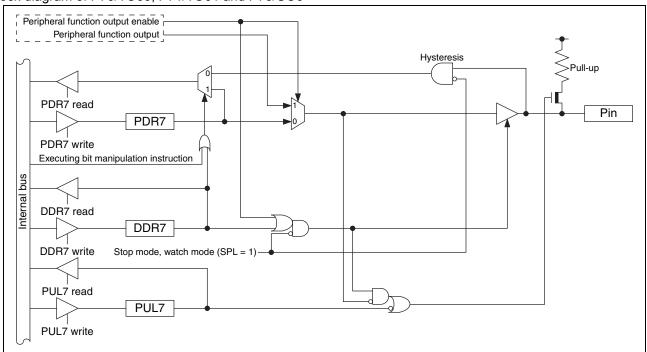
• 8/16-bit composite timer ch. 0 output pin (TO01)

• P76/UO0 pin

This pin has the following peripheral function:

• UART/SIO ch. 0 data output pin (UO0)

Block diagram of P70/TO00, P71/TO01 and P76/UO0





• P72/SCL pin

This pin has the following peripheral function:

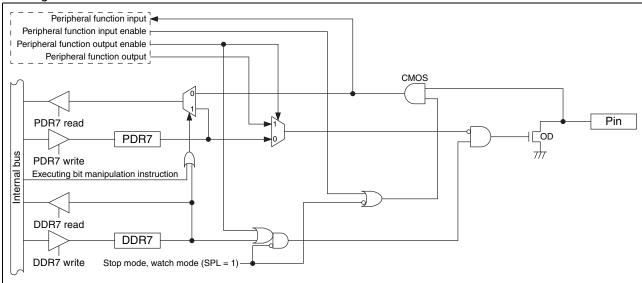
• I²C bus interface ch. 0 clock I/O pin (SCL)

• P73/SDA pin

This pin has the following peripheral function:

• I²C bus interface ch. 0 data I/O pin (SDA)

• Block diagram of P72/SCL and P73/SDA



• P74/EC0 pin

This pin has the following peripheral functions:

• 8/16-bit composite timer ch. 0 clock input pin (EC0)



(Continued)

Din nama	Normal	Clean made	Stop	mode	Watch	mode	On rocat	
Pin name	operation	Sleep mode	SPL=0 SPL=1		SPL=0	SPL=1	On reset	
P72/SCL	I/O port/ peripheral	I/O port/ peripheral	- Previous state kept	- Hi-Z - Input	- Previous state kept	- Hi-Z - Input	- Hi-Z - Input enabled* ³	
P73/SDA	function I/O	function I/O	- Input blocked* ^{2,*9}	blocked*2, *9	- Input blocked* ^{2,*9}	blocked*2, *9	(However, it does not function.)	
P70/TO00	I/O port/	I/O port/	Provious state		- Previous state		- Hi-Z - Input	
P71/TO01	peripheral function I/O	I/O port/ peripheral function I/O	 Previous state kept Input blocked*2 	- HI-Z*°	kent	- Hi-Z*5 - Input blocked*2	,	
P76/UO0							does not function.)	
P74/EC0	I/O port/	I/O port/	- Previous state	- Hi-Z* ⁵	- Previous state	- Hi-Z* ⁵	- Hi-Z - Input	
P75/UCK0 peripheral		peripheral function I/O	kept - Input	- Input blocked*2,*7	kept - Input	- Input blocked*2, *7	enabled* ³ (However, it	
P77/UI0			blocked*2,*7		blocked*2,*7		does not function.)	

SPL: Pin state setting bit in the standby control register (STBC:SPL)

Hi-Z: High impedance

- *1: The pin stays at the state shown when configured as a general-purpose I/O port.
- *2: "Input blocked" means direct input gate operation from the pin is disabled.
- *3: "Input enabled" means that the input function is enabled. While the input function is enabled, execute a pull-up or pull-down operation in order to prevent leaks due to external input. If a pin is used as an output port, its pin state is the same as that of other ports.
- *4: The PF2/RST pin stays at the state shown when configured as a reset pin.
- *5: The pull-up control setting is still effective.
- *6: Though input is blocked, an external interrupt can be input when the external interrupt request is enabled, and an analog signal can also be input to generate a comparator interrupt when the comparator interrupt is enabled.
- *7: Though input is blocked, an external interrupt can be input when the external interrupt request is enabled.
- *8: The output function of the comparator is still in operation in stop mode and watch mode.
- *9: The I²C bus interface can wake up the MCU in stop mode or watch mode when its MCU standby mode wakeup function is enabled. For details of the MCU standby mode wakeup function, refer to "New 8FX MB95690K Series Hardware Manual".



20. Electrical Characteristics

20.1 Absolute Maximum Ratings

Dama wa atau	Ob. a.l	Rating		11	Domonto.		
Parameter	Symbol	Min	Max	Unit	Remarks		
Power supply voltage*1	Vcc	Vss - 0.3	Vss + 6	V			
Input voltage*1	Vı	Vss - 0.3	Vss + 6	V	*2		
Output voltage*1	Vo	Vss - 0.3	Vss + 6	V	*2		
Maximum clamp current	I CLAMP	-2	+2	mA	Applicable to specific pins*3		
Total maximum clamp current	Σ Iclamp	_	20	mA	Applicable to specific pins*3		
"L" level maximum output current	lol	_	15	mA			
"L" level average current	lolav1		4	mA	Other than P60 to P67 Average output current = operating current × operating ratio (1 pin)		
L level average current	lolav2	_	12	IIIA	P60 to P67 Average output current = operating current × operating ratio (1 pin)		
"L" level total maximum output current	Σ loL	_	100	mA			
"L" level total average output current	Σ lolav	_	37	mA	Total average output current = operating current × operating ratio (Total number of pins)		
"H" level maximum output current	Іон	_	-15	mA			
"H" level average	Iонаv1		-4	mA	Other than P60 to P67 Average output current = operating current × operating ratio (1 pin)		
current	Iohav2		-8	ША	P60 to P67 Average output current = operating current × operating ratio (1 pin)		
"H" level total maximum output current	Σ Іон	_	-100	mA			
"H" level total average output current	Σ Iohav	_	-47	mA	Total average output current = operating current × operating ratio (Total number of pins)		
Power consumption	Pd		320	mW			
Operating temperature	Та	-40	+85	°C			
Storage temperature	Tstg	-55	+150	°C			

^{*1:} These parameters are based on the condition that Vss is 0.0 V.

^{*2:} V₁ and V₀ must not exceed Vcc + 0.3 V. V₁ must not exceed the rated voltage. However, if the maximum current to/from an input is limited by means of an external component, the Iclamp rating is used instead of the V₁ rating.

^{*3:} Specific pins: P00 to P07, P10, P11, P13 to P17, P40 to P47, P60 to P67, P70, P71, P74 to P77, PF0, PF1, PG1, PG2

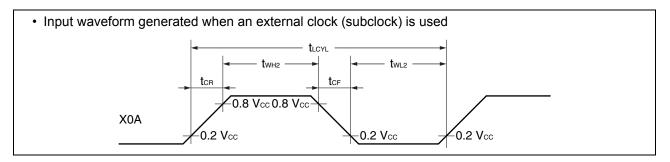


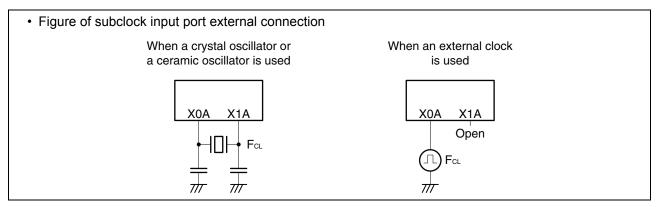
20.3 DC Characteristics

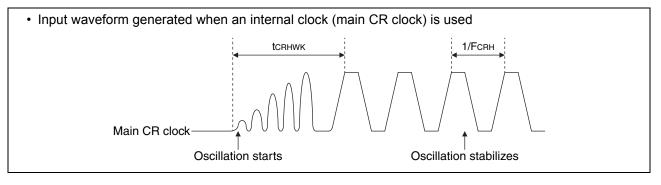
(Vcc = 5.0 V \pm 10%, Vss = 0.0 V, TA = -40 °C to +85 °C)

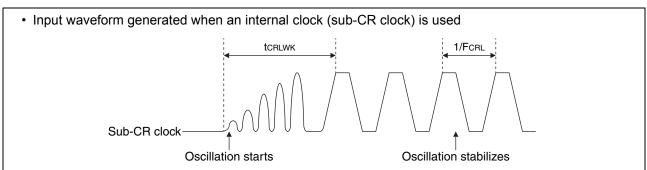
Danamatan	Ols al	Din nome	O a maliti a m		Value		11:4	Remarks	
Parameter	Symbol	Pin name	Condition	Min	Тур	Max	Unit		
61 12 1 1	VIHI	P47, P72, P73, P77	_	0.7 Vcc	_	Vcc + 0.3	V	CMOS input level	
"H" level input voltage	Vihs	Other than P47, P72, P73, P77, PF2	_	0.8 Vcc		Vcc + 0.3	V	Hysteresis input	
	Vінм	PF2	_	0.8 Vcc	_	Vcc + 0.3	V	Hysteresis input	
61 7 L	VILI	P47, P72, P73, P77	_	Vss - 0.3		0.3 Vcc	V	CMOS input level	
"L" level input voltage	VILS	Other than P47, P72, P73, P77, PF2	_	Vss - 0.3		0.2 Vcc	V	Hysteresis input	
	VILM	PF2	_	Vss - 0.3	_	0.2 Vcc	V	Hysteresis input	
Open-drain output application voltage	VD	P12, P72, P73, PF2	_	Vss - 0.3	_	Vss + 5.5	V		
"H" level VoHoutput		Output pins other than P12, P60 to P67, PF2	Iон = − 4 mA	Vcc – 0.5	_	_	V		
	V _{OH2}	P60 to P67	Iон = -8 mA	Vcc - 0.5	_	_	V		
"L" level output voltage	V _{OL1}	Output pins other than P60 to P67	IoL = 4 mA	_	_	0.4	V		
voitage	V _{OL2}	P60 to P67	IoL = 12 mA	_	_	0.4	V		
Input leak current(Hi-Z output leak current)	lu	All input pins	0.0 V < Vı < Vcc	-5	_	+5	μA	When the internal pull-up resistor is disabled	
Internal pull-up resistor	Rpull	Other than P12, P72, P73, PF0, PF1, PF2	V _I = 0 V	25	50	100	kΩ	When the internal pull-up resistor is enabled	
Input capacitance	Cin	Other than Vcc and Vss	f = 1 MHz	_	5	15	pF		



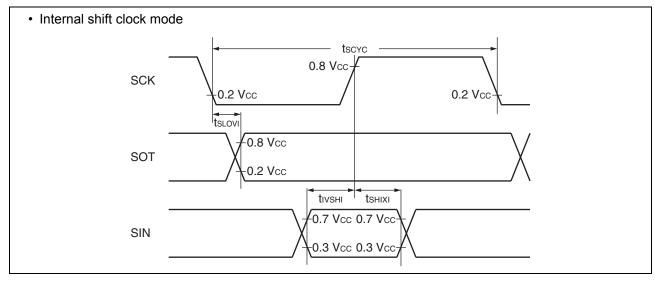


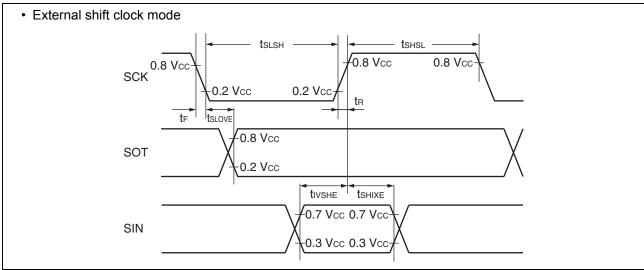




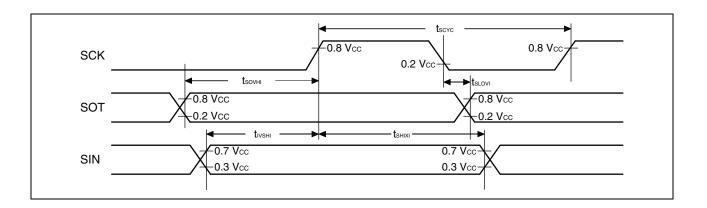












20.4.7 Low-voltage Detection

 $(V_{SS} = 0.0 \text{ V}, T_A = -40 ^{\circ}\text{C to } +85 ^{\circ}\text{C})$

Doromotor	Symbol		Value		Unit	Domarka
Parameter	Symbol	Min	Тур	Max	Unit	Remarks
		2.52	2.7	2.88		
Release voltage*	V _{DL+}	2.61	2.8	2.99	V	At power supply rise
Telease voltage	V DLT	2.89	3.1	3.31]	At power supply rise
		3.08	3.3	3.52		
		2.43	2.6	2.77		
Detection voltage*	V _{DL} -	2.52	2.7	2.88	V	At power supply fall
Detection voltage	V DL—	2.80	3	3.20	T *	At power supply fall
		2.99	3.2	3.41		
Hysteresis width	VHYS	_		100	mV	
Power supply start	Voff			2.3	V	
voltage	ν οπ	_		2.3	V	
Power supply end	Von	4.9			V	
voltage	v on	4.9		_	V	
Power supply voltage						Slope of power supply that the reset
change time	tr	650		_	μs	release signal generates within the
(at power supply rise)						rating (V _{DL+})
Power supply voltage						Slope of power supply that the reset
change time	t f	650		_	μs	release signal generates within the
(at power supply fall)						rating (V _{DL-})
Reset release delay	t d1			30		
time	L a1	_		30	μs	
Reset detection delay	4			30		
time	t d2	_		30	μs	
LVD reset threshold						
voltage transition	t stb	10	_	_	μs	
stabilization time						

^{*:} After the LVD reset is enabled by the LVD reset circuit control register (LVDCC), the release voltage and the detection voltage can be selected by using the LVD reset voltage selection ID register (LVDR) in the low-voltage detection reset circuit. For details of the LVDCC register and the LVDR register, refer to "CHAPTER 16 LOW-VOLTAGE DETECTION RESET CIRCUIT" in "New 8FX MB95690K Series Hardware Manual".



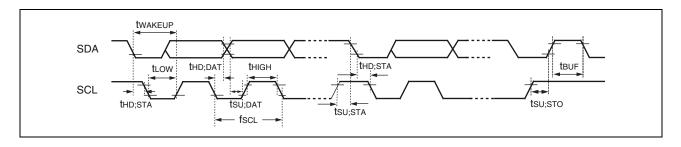
20.4.8 I2C Bus Interface Timing

 $(Vcc = 5.0 V\pm 10\%, Vss = 0.0 V, T_A = -40 °C to +85 °C)$

				Value				
Parameter	Symbol	Pin name	Condition	Standard- mode		Fast-mode		Unit
				Min	Max	Min	Max	
SCL clock frequency	fscL	SCL		0	100	0	400	kHz
(Repeated) START condition hold time SDA $\downarrow \rightarrow$ SCL \downarrow	thd;sta	SCL, SDA		4.0	_	0.6	_	μs
SCL clock "L" width	tLOW	SCL		4.7	_	1.3	_	μs
SCL clock "H" width	t HIGH	SCL		4.0	_	0.6	_	μs
(Repeated) START condition setup time SCL $\uparrow \rightarrow$ SDA \downarrow	tsu;sta	SCL, SDA	R = 1.7 kΩ, C = 50 pF*1	4.7	_	0.6	_	μs
Data hold time SCL \downarrow \rightarrow SDA \downarrow \uparrow	thd;dat	SCL, SDA	00 pi	0	3.45*2	0	0.9*3	μs
Data setup time SDA $\downarrow\uparrow$ \rightarrow SCL \uparrow	tsu;dat	SCL, SDA		0.25		0.1	_	μs
STOP condition setup time SCL $\uparrow \rightarrow$ SDA \uparrow	t su;sто	SCL, SDA		4	_	0.6	_	μs
Bus free time between STOP condition and START condition	t BUF	SCL, SDA		4.7	_	1.3	_	μs

^{*1:} R represents the pull-up resistor of the SCL and SDA lines, and C the load capacitor of the SCL and SDA lines.

^{*3:} A Fast-mode I²C-bus device can be used in a Standard-mode I²C-bus system, provided that the condition of tsu;DAT ≥ 250 ns is fulfilled.



^{*2:} The maximum thd; DAT in the Standard-mode is applicable only when the time during which the device is holding the SCL signal at "L" (tLow) does not extend.



20.5 A/D Converter

20.5.1 A/D Converter Electrical Characteristics

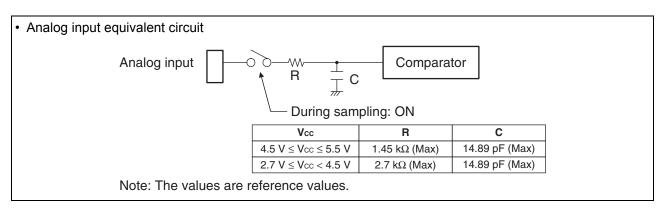
 $(Vcc = 2.7 \text{ V to } 5.5 \text{ V}, Vss = 0.0 \text{ V}, T_A = -40 ^{\circ}\text{C to } +85 ^{\circ}\text{C})$

Doromotor	Parameter Symbol		Value	Unit	Remarks		
Parameter	Syllibol	Min	Тур	Max	5	Remarks	
Resolution		_	_	10	bit		
Total error		-3	_	+3	LSB		
Linearity error	_	-2.5	_	+2.5	LSB		
Differential linearity error		-1.9	_	+1.9	LSB		
Zero transition voltage	Vот	Vss – 7.2 LSB	Vss + 0.5 LSB	Vss + 8.2 LSB	V		
Full-scale transition voltage	VFST	Vcc – 6.2 LSB	Vcc – 1.5 LSB	Vcc + 9.2 LSB	V		
Compare time	_	3	_	10	μs	$2.7 \text{ V} \leq \text{Vcc} \leq 5.5 \text{ V}$	
Sampling time	_	0.941	_	∞	μs	$2.7 \text{ V} \le \text{Vcc} \le 5.5 \text{ V},$ with external impedance $< 3.3 \text{ k}\Omega$ and external capacitance = 10 pF	
Analog input current	lain	-0.3	_	+0.3	μΑ		
Analog input voltage	Vain	Vss	_	Vcc	V		

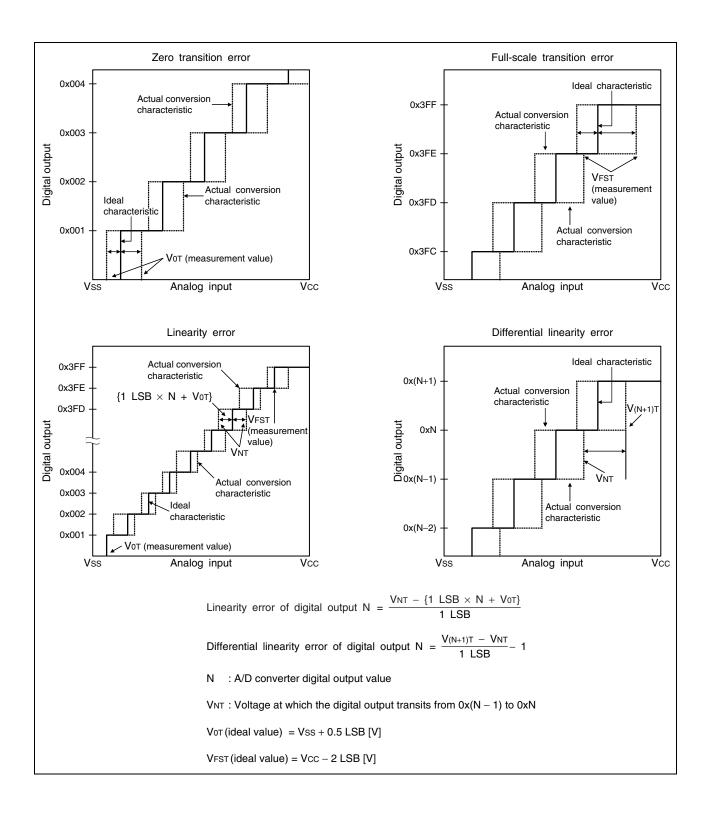
20.5.2 Notes on Using A/D Converter

External impedance of analog input and its sampling time

The A/D converter of the MB95690K Series has a sample and hold circuit. If the external impedance is too high to keep sufficient sampling time, the analog voltage charged to the capacitor of the internal sample and hold circuit is insufficient, adversely affecting A/D conversion precision. Therefore, to satisfy the A/D conversion precision standard, considering the relationship between the external impedance and minimum sampling time, either adjust the register value and operating frequency or decrease the external impedance so that the sampling time is longer than the minimum value. In addition, if sufficient sampling time cannot be secured, connect a capacitor of about 0.1 μ F to the analog input pin.







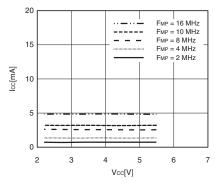


21. Sample Characteristics

Power supply current temperature characteristics

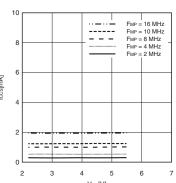
Icc - Vcc

 $T_A = +25$ °C, $F_{MP} = 2, 4, 8, 10, 16$ MHz (divided by 2) Main clock mode with the external clock operating



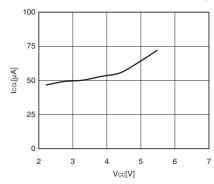
Iccs - Vcc

 $T_A = +25$ °C, $F_{MP} = 2, 4, 8, 10, 16$ MHz (divided by 2) Main sleep mode with the external clock operating



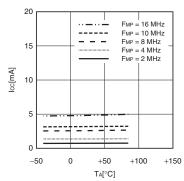
Iccl – Vcc

 $T_A = +25$ °C, $F_{MPL} = 16$ kHz (divided by 2) Subclock mode with the external clock operating



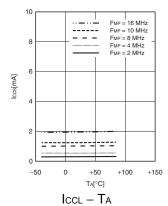
Icc - Ta

 $V_{CC} = 5.5 \text{ V}$, $F_{MP} = 2, 4, 8, 10, 16 \text{ MHz}$ (divided by 2) Main clock mode with the external clock operating

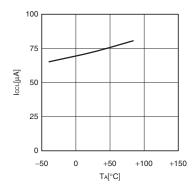


Iccs - Ta

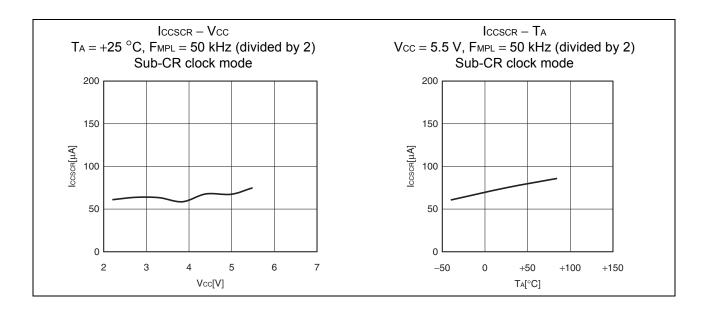
Vcc = 5.5 V, Fmp = 2, 4, 8, 10, 16 MHz (divided by 2) Main sleep mode with the external clock operating



 $V_{CC} = 5.5 \text{ V}$, $F_{MPL} = 16 \text{ kHz}$ (divided by 2) Subclock mode with the external clock operating

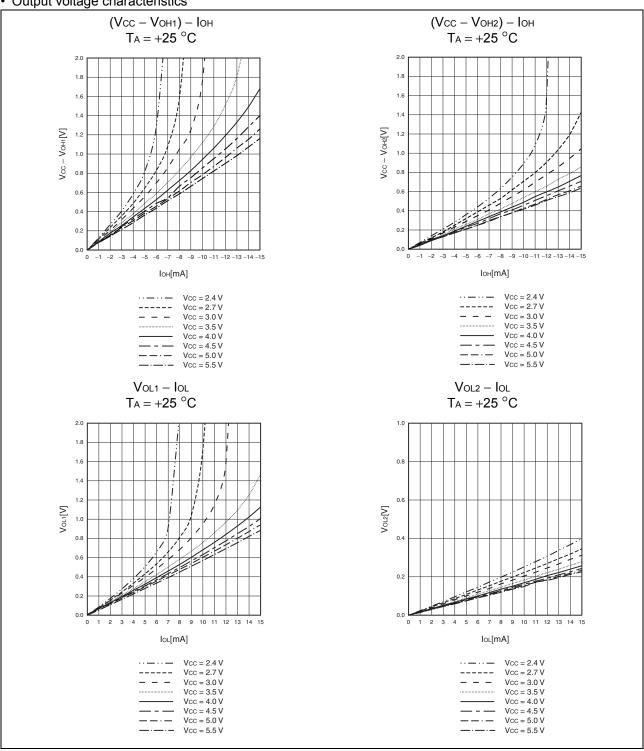








Output voltage characteristics





24. Major Changes In This Edition

Spansion Publication Number: DS702-00014-2v0-E

Page	Section	Details
2	■ FEATURES	Added information on FPT-44P-M25.
4	■ PRODUCT LINE-UP	Added information on FPT-44P-M25 to the parameters "General-purpose I/O" and "8/10-bit A/D converter".
5		Added information on FPT-44P-M25 to the parameter "External interrupt".
6		Added FPT-44P-M25 to the parameter "Package".
7	■ PACKAGES AND CORRESPONDING PRODUCTS	Added information on FPT-44P-M25.
9	■ PIN ASSIGNMENT	Added the pin assignment diagram of FPT-44P-M25.
13 to 16	■ PIN FUNCTIONS (FPT-44P-M25)	New section
17	■ PIN FUNCTIONS (FPT-48P-M49, FPT-52P-M02, LCC-48P-M11)	Renamed the section "■ PIN FUNCTIONS" to "■ PIN FUNCTIONS (FPT-48P-M49, FPT-52P-M02, LCC-48P-M11).
29	■ PIN CONNECTION • DBG pin	Revised details of "• DBG pin".
	RST pin	Revised details of "• RST pin".
30	• C pin	Corrected the following statement. The bypass capacitor for the Vcc pin must have a capacitance larger than Cs. → The decoupling capacitor for the Vcc pin must have a capacitance equal to or larger than the capacitance of Cs.
31	■ BLOCK DIAGRAM (FPT-44P-M25)	New section
32	■ BLOCK DIAGRAM (FPT-48P-M49, FPT-52P-M02, LCC-48P-M11)	Renamed the section "■ BLOCK DIAGRAM" to "■ BLOCK DIAGRAM (FPT-48P-M49, FPT-52P-M02, LCC-48P-M11).
75	I/O PORTS6. Port F(4) Port F operationsOperation as an input port	Added the following statement. For a pin shared with other peripheral functions, disable the output of such peripheral functions.
78	7. Port G(4) Port G operationsOperation as an input port	Added the following statement. For a pin shared with other peripheral functions, disable the output of such peripheral functions.