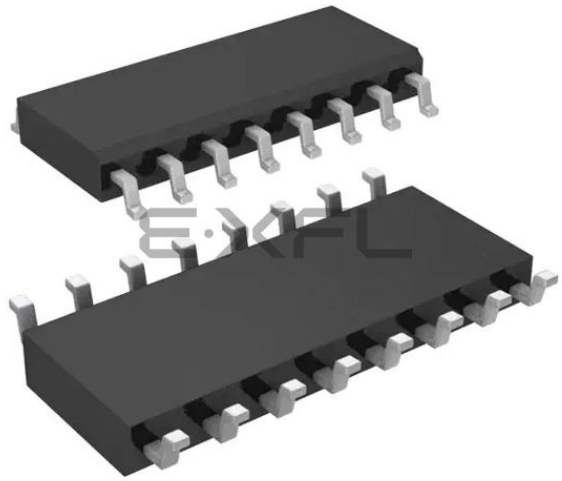


Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M0
Core Size	32-Bit Single-Core
Speed	16MHz
Connectivity	I²C
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	13
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 5.5V
Data Converters	D/A 1x7b, 1x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	16-SOIC (0.154", 3.90mm Width)
Supplier Device Package	16-SOIC
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/cy8c4014sxi-421t

More Information

Cypress provides a wealth of data at www.cypress.com to help you to select the right PSoC device for your design, and to help you to quickly and effectively integrate the device into your design. For a comprehensive list of resources, see the knowledge base article KBA86521, How to Design with PSoC 3, PSoC 4, and PSoC 5LP. Following is an abbreviated list for PSoC 4:

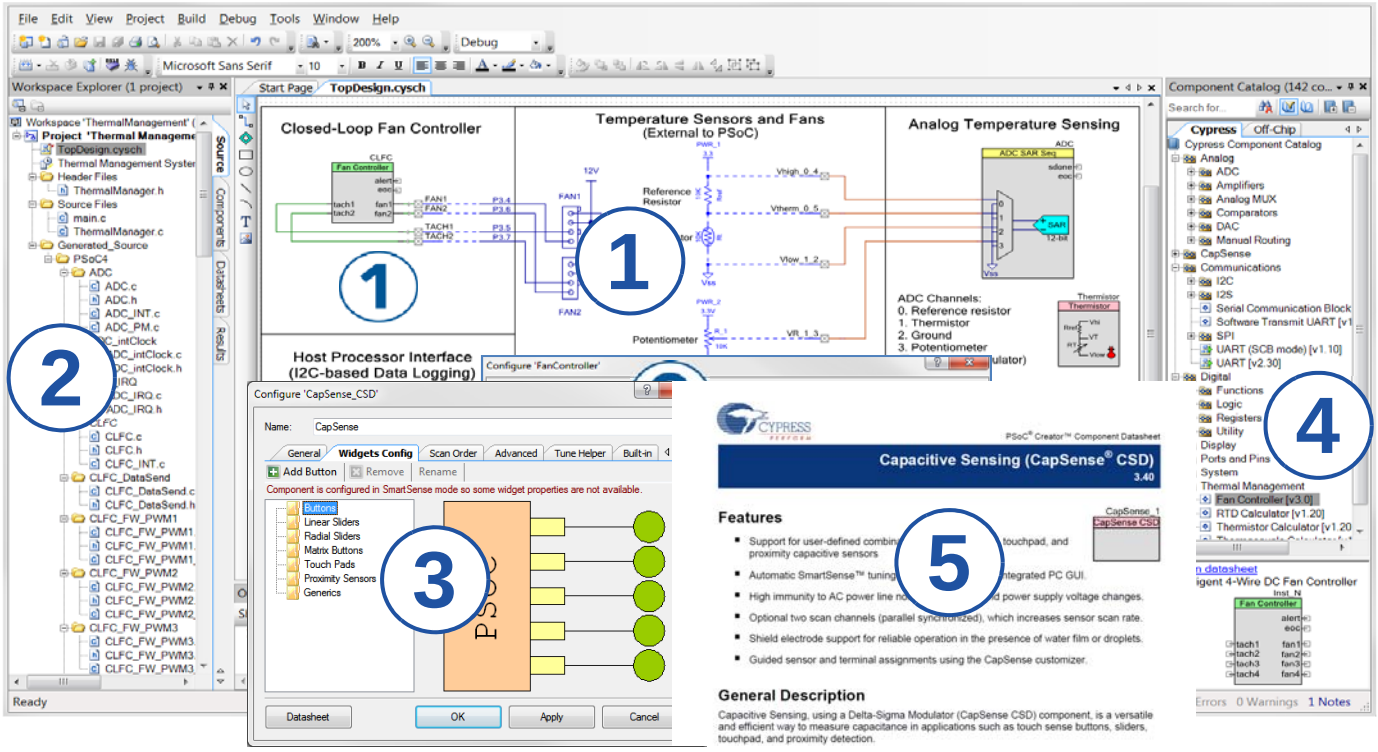
- Overview: PSoC Portfolio, PSoC Roadmap
- Product Selectors: PSoC 1, PSoC 3, PSoC 4, PSoC 5LP
  In addition, PSoC Creator includes a device selection tool.
- Application notes: Cypress offers a large number of PSoC application notes covering a broad range of topics, from basic to advanced level. Recommended application notes for getting started with PSoC 4 are:
  - AN79953: Getting Started With PSoC 4
  - AN88619: PSoC 4 Hardware Design Considerations
  - AN86439: Using PSoC 4 GPIO Pins
  - AN57821: Mixed Signal Circuit Board Layout
  - AN81623: Digital Design Best Practices
  - AN73854: Introduction To Bootloaders
  - AN89610: ARM Cortex Code Optimization
- Technical Reference Manual (TRM) is in two documents:
  - Architecture TRM details each PSoC 4 functional block.
  - Registers TRM describes each of the PSoC 4 registers.
- Development Kits:
  - CY8CKIT-040, PSoC 4000 Pioneer Kit, is an easy-to-use and inexpensive development platform with debugging capability. This kit includes connectors for Arduino™ compatible shields and Digilent® Pmod™ daughter cards.
  - The MiniProg3 device provides an interface for flash programming and debug.

PSoC Creator

PSoC Creator is a free Windows-based Integrated Design Environment (IDE). It enables concurrent hardware and firmware design of PSoC 3, PSoC 4, and PSoC 5LP based systems. Create designs using classic, familiar schematic capture supported by over 100 pre-verified, production-ready PSoC Components; see the list of component datasheets. With PSoC Creator, you can:

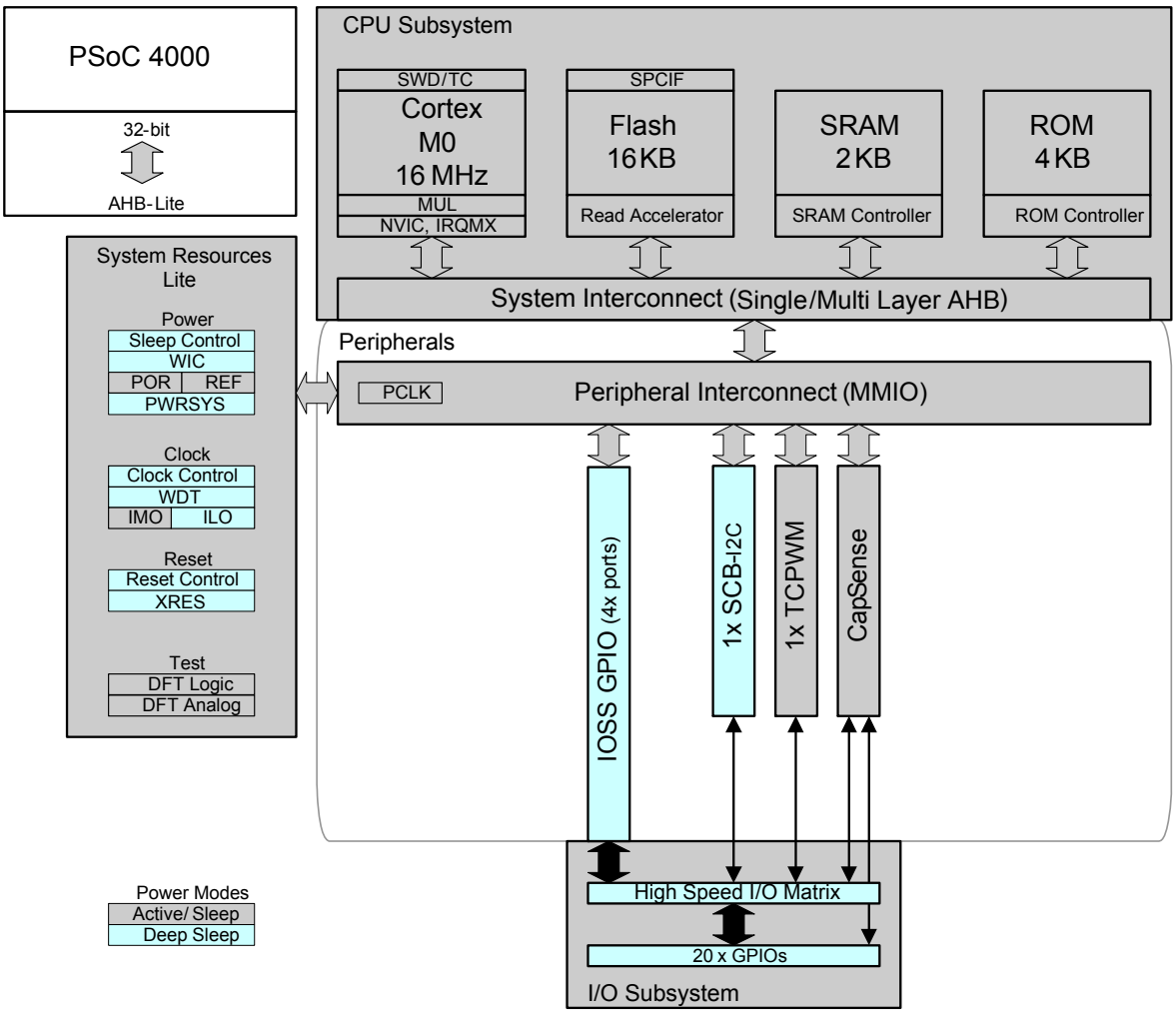
1. Drag and drop component icons to build your hardware system design in the main design workspace
2. Codesign your application firmware with the PSoC hardware, using the PSoC Creator IDE C compiler
3. Configure components using the configuration tools
4. Explore the library of 100+ components
5. Review component datasheets

Figure 1. CapSense Example Project in PSoC Creator



Contents

Figure 2. Block Diagram



PSoC 4000 devices include extensive support for programming, testing, debugging, and tracing both hardware and firmware.

The ARM Serial-Wire Debug (SWD) interface supports all programming and debug features of the device.

Complete debug-on-chip functionality enables full-device debugging in the final system using the standard production device. It does not require special interfaces, debugging pods, simulators, or emulators. Only the standard programming connections are required to fully support debug.

The PSoC Creator IDE provides fully integrated programming and debug support for the PSoC 4000 devices. The SWD interface is fully compatible with industry-standard third-party tools. The PSoC 4000 family provides a level of security not possible with multi-chip application solutions or with microcontrollers. It has the following advantages:

- Allows disabling of debug features
- Robust flash protection
- Allows customer-proprietary functionality to be implemented in on-chip programmable blocks

The debug circuits are enabled by default and can only be disabled in firmware. If they are not enabled, the only way to re-enable them is to erase the entire device, clear flash protection, and reprogram the device with new firmware that enables debugging.

Additionally, all device interfaces can be permanently disabled (device security) for applications concerned about phishing attacks due to a maliciously reprogrammed device or attempts to defeat security by starting and interrupting flash programming sequences. All programming, debug, and test interfaces are disabled when maximum device security is enabled. Therefore, PSoC 4000, with device security enabled, may not be returned for failure analysis. This is a trade-off the PSoC 4000 allows the customer to make.

Functional Definition

CPU and Memory Subsystem

CPU

The Cortex-M0 CPU in the PSoC 4000 is part of the 32-bit MCU subsystem, which is optimized for low-power operation with extensive clock gating. Most instructions are 16 bits in length and the CPU executes a subset of the Thumb-2 instruction set. This enables fully compatible, binary, upward migration of the code to higher performance processors, such as the Cortex-M3 and M4. It includes a nested vectored interrupt controller (NVIC) block with eight interrupt inputs and also includes a Wakeup Interrupt Controller (WIC). The WIC can wake the processor from the Deep Sleep mode, allowing power to be switched off to the main processor when the chip is in the Deep Sleep mode. The CPU subsystem also includes a 24-bit timer called SYSTICK, which can generate an interrupt.

The CPU also includes a debug interface, the serial wire debug (SWD) interface, which is a 2-wire form of JTAG. The debug configuration used for PSoC 4000 has four breakpoint (address) comparators and two watchpoint (data) comparators.

Flash

The PSoC 4000 device has a flash module with a flash accelerator, tightly coupled to the CPU to improve average access times from the flash block. The low-power flash block is designed to deliver zero wait-state (WS) access time at 16 MHz.

SRAM

Two KB of SRAM are provided with zero wait-state access at 16 MHz.

SROM

A supervisory ROM that contains boot and configuration routines is provided.

System Resources

Power System

The power system is described in detail in the section on Power on page 12. It provides an assurance that voltage levels are as required for each respective mode and either delays mode entry (for example, on power-on reset (POR)) until voltage levels are as required for proper functionality, or generates resets (for example, on brown-out detection). The PSoC 4000 operates with a single external supply over the range of either 1.8 V ±5% (externally regulated) or 1.8 to 5.5 V (internally regulated) and has three different power modes, transitions between which are managed by the power system. The PSoC 4000 provides Active, Sleep, and Deep Sleep low-power modes.

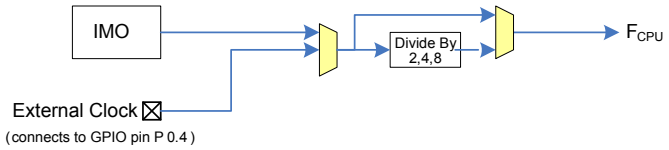
All subsystems are operational in Active mode. The CPU subsystem (CPU, flash, and SRAM) is clock-gated off in Sleep mode, while all peripherals and interrupts are active with instantaneous wake-up on a wake-up event. In Deep Sleep mode, the high-speed clock and associated circuitry is switched off; wake-up from this mode takes 35 µS.

Clock System

The PSoC 4000 clock system is responsible for providing clocks to all subsystems that require clocks and for switching between different clock sources without glitching. In addition, the clock system ensures that there are no metastable conditions.

The clock system for the PSoC 4000 consists of the internal main oscillator (IMO) and the internal low-frequency oscillator (ILO) and provision for an external clock.

Figure 3. PSoC 4000 MCU Clocking Architecture



The F_{CPU} signal can be divided down to generate synchronous clocks for the analog and digital peripherals. There are four clock dividers for the PSoC 4000, each with 16-bit divide capability The 16-bit capability allows flexible generation of fine-grained frequency values and is fully supported in PSoC Creator.

IMO Clock Source

The IMO is the primary source of internal clocking in the PSoC 4000. It is trimmed during testing to achieve the specified accuracy.The IMO default frequency is 24 MHz and it can be adjusted from 24 to 48 MHz in steps of 4 MHz. The IMO tolerance with Cypress-provided calibration settings is ±2% (24 and 32 MHz).

ILO Clock Source

The ILO is a very low power, 40-kHz oscillator, which is primarily used to generate clocks for the watchdog timer (WDT) and peripheral operation in Deep Sleep mode. ILO-driven counters can be calibrated to the IMO to improve accuracy.

Watchdog Timer

A watchdog timer is implemented in the clock block running from the ILO; this allows watchdog operation during Deep Sleep and generates a watchdog reset if not serviced before the set timeout occurs. The watchdog reset is recorded in a Reset Cause register, which is firmware readable.

Reset

The PSoC 4000 can be reset from a variety of sources including a software reset. Reset events are asynchronous and guarantee reversion to a known state. The reset cause is recorded in a register, which is sticky through reset and allows software to determine the cause of the reset. An XRES pin is reserved for external reset on the 24-pin package. An internal POR is provided on the 16-pin and 8-pin packages. The XRES pin has an internal pull-up resistor that is always enabled. Reset is Active Low.

Voltage Reference

The PSoC 4000 reference system generates all internally required references. A 1.2-V voltage reference is provided for the comparator. The IDACs are based on a ±5% reference.

Power

The following power system diagrams (Figure 9 and Figure 10) show the set of power supply pins as implemented for the PSoC 4000. The system has one regulator in Active mode for the digital circuitry. There is no analog regulator; the analog circuits run directly from the V_{DD} input. There is a separate regulator for the Deep Sleep mode. The supply voltage range is either 1.8 V ±5% (externally regulated) or 1.8 V to 5.5 V (unregulated externally; regulated internally) with all functions and circuits operating over that range.

The V_{DDIO} pin, available in the 16-pin QFN package, provides a separate voltage domain for the following pins: P3.0, P3.1, and P3.2. P3.0 and P3.1 can be I^2C pins and the chip can thus communicate with an I^2C system, running at a different voltage (where $V_{DDIO} \leq V_{DD}$). For example, V_{DD} can be 3.3 V and V_{DDIO} can be 1.8 V.

The PSoC 4000 family allows two distinct modes of power supply operation: Unregulated External Supply and Regulated External Supply.

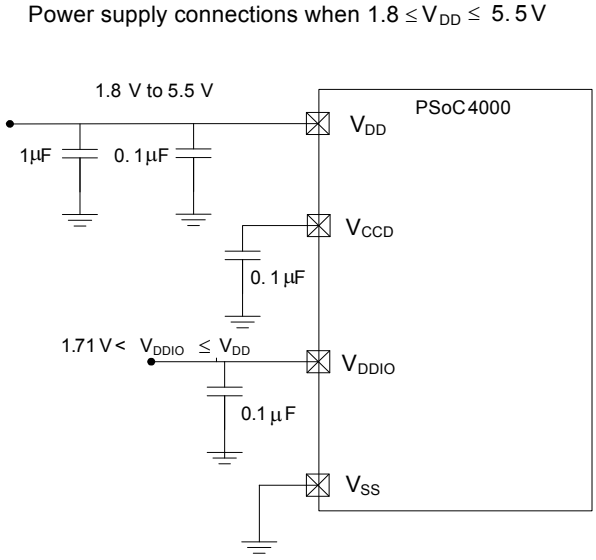
Unregulated External Supply

In this mode, the PSoC 4000 is powered by an external power supply that can be anywhere in the range of 1.8 to 5.5 V. This range is also designed for battery-powered operation. For example, the chip can be powered from a battery system that starts at 3.5 V and works down to 1.8 V. In this mode, the internal regulator of the PSoC 4000 supplies the internal logic and the V_{CCD} output of the PSoC 4000 must be bypassed to ground via an external capacitor (0.1 µF; X5R ceramic or better).

Bypass capacitors must be used from V_{DD} to ground. The typical practice for systems in this frequency range is to use a capacitor in the 1-µF range, in parallel with a smaller capacitor (0.1 µF, for example). Note that these are simply rules of thumb and that, for critical applications, the PCB layout, lead inductance, and the bypass capacitor parasitic should be simulated to design and obtain optimal bypassing.

An example of a bypass scheme follows (V_{DDIO} is available on the 16-QFN package).

Figure 9. 16-pin QFN Bypass Scheme Example - Unregulated External Supply



Regulated External Supply

In this mode, the PSoC 4000 is powered by an external power supply that must be within the range of 1.71 to 1.89 V; note that this range needs to include the power supply ripple too. In this mode, the V_{DD} and V_{CCD} pins are shorted together and bypassed. The internal regulator should be disabled in the firmware. Note that in this mode VDD (VCCD) should never exceed 1.89 in any condition, including flash programming.

An example of a bypass scheme follows (V_{DDIO} is available on the 16-QFN package).

Figure 10. 16-pin QFN Bypass Scheme Example - Regulated External Supply

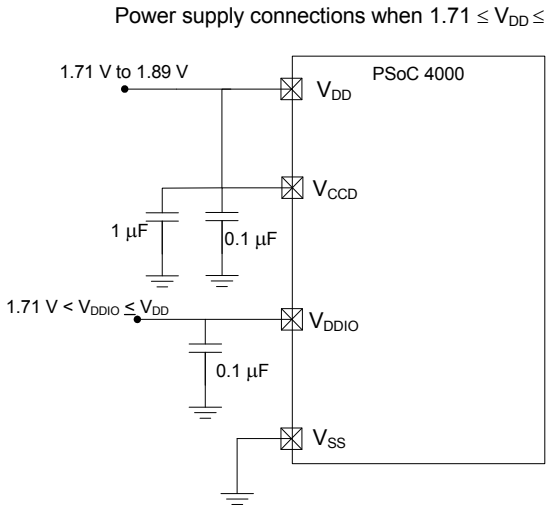


Table 4. DC Specifications *(continued)*

Typical values measured at V_{DD} = 3.3 V and 25 °C.

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
Deep Sleep Mode, V_{DD} = 3.6 to 5.5 V (Regulator on)							
SID34	I_{DD29}	I^2C wakeup and WDT on	–	2.5	12	µA	
Deep Sleep Mode, V_{DD} = V_{CCD} = 1.71 to 1.89 V (Regulator bypassed)							
SID37	I_{DD32}	I^2C wakeup and WDT on	–	2.5	9.2	µA	
XRES Current							
SID307	I_{DD_XR}	Supply current while XRES asserted	–	2	5	mA	

Table 5. AC Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID48	F_{CPU}	CPU frequency	DC	–	16	MHz	$1.71 \le V_{DD} \le 5.5$
SID49[5]	T_{SLEEP}	Wakeup from Sleep mode	–	0	–	µs	
SID50[5]	$T_{DEEPSLEEP}$	Wakeup from Deep Sleep mode	–	35	–	µs	

GPIO

Table 6. GPIO DC Specifications (referenced to V_{DDIO} for 16-Pin QFN V_{DDIO} pins)

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID57	V_{IH}[6]	Input voltage high threshold	0.7 × V_{DD}	–	–	V	CMOS Input
SID58	V_{IL}	Input voltage low threshold	–	–	0.3 × V_{DD}	V	CMOS Input
SID241	V_{IH}[6]	LVTTL input, V_{DD} < 2.7 V	0.7× V_{DD}	–	–	V	
SID242	V_{IL}	LVTTL input, V_{DD} < 2.7 V	–	–	0.3 × V_{DD}	V	
SID243	V_{IH}[6]	LVTTL input, $V_{DD} \ge$ 2.7 V	2.0	–	–	V	
SID244	V_{IL}	LVTTL input, $V_{DD} \ge$ 2.7 V	–	–	0.8	V	
SID59	V_{OH}	Output voltage high level	V_{DD} –0.6	–	–	V	I_{OH} = 4 mA at 3 V V_{DD}
SID60	V_{OH}	Output voltage high level	V_{DD} –0.5	–	–	V	I_{OH} = 1 mA at 1.8 V V_{DD}
SID61	V_{OL}	Output voltage low level	–	–	0.6	V	I_{OL} = 4 mA at 1.8 V V_{DD}
SID62	V_{OL}	Output voltage low level	–	–	0.6	V	I_{OL} = 10 mA at 3 V V_{DD}
SID62A	V_{OL}	Output voltage low level	–	–	0.4	V	I_{OL} = 3 mA at 3 V V_{DD}
SID63	R_{PULLUP}	Pull-up resistor	3.5	5.6	8.5	kΩ	
SID64	$R_{PULLDOWN}$	Pull-down resistor	3.5	5.6	8.5	kΩ	
SID65	I_{IL}	Input leakage current (absolute value)	–	–	2	nA	25 °C, V_{DD} = 3.0 V
SID66	C_{IN}	Input capacitance	–	3	7	pF	

Notes
5. Guaranteed by characterization.
6. V_{IH} must not exceed V_{DD} + 0.2 V.

Table 6. GPIO DC Specifications (referenced to V_{DDIO} for 16-Pin QFN V_{DDIO} pins) *(continued)*

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID67[7]	V_{HYSTTL}	Input hysteresis LVTTL	15	40	–	mV	$V_{DD} \geq 2.7$ V
SID68[7]	$V_{HYSCMOS}$	Input hysteresis CMOS	0.05 × V_{DD}	–	–	mV	$V_{DD} < 4.5$ V
SID68A[7]	$V_{HYSCMOS5V5}$	Input hysteresis CMOS	200	–	–	mV	$V_{DD} > 4.5$ V
SID69[7]	I_{DIODE}	Current through protection diode to V_{DD}/V_{SS}	–	–	100	µA	
SID69A[7]	I_{TOT_GPIO}	Maximum total source or sink chip current	–	–	85	mA	

Table 7. GPIO AC Specifications

(Guaranteed by Characterization)

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID70	T_{RISEF}	Rise time in fast strong mode	2	–	12	ns	3.3 V V_{DD}, Cload = 25 pF
SID71	T_{FALLF}	Fall time in fast strong mode	2	–	12	ns	3.3 V V_{DD}, Cload = 25 pF
SID72	T_{RISES}	Rise time in slow strong mode	10	–	60	–	3.3 V V_{DD}, Cload = 25 pF
SID73	T_{FALLS}	Fall time in slow strong mode	10	–	60	–	3.3 V V_{DD}, Cload = 25 pF
SID74	$F_{GPIOUT1}$	GPIO F_{OUT}; 3.3 V ≤ V_{DD} ≤ 5.5 V. Fast strong mode.	–	–	16	MHz	90/10%, 25 pF load, 60/40 duty cycle
SID75	$F_{GPIOUT2}$	GPIO F_{OUT}; 1.71 V≤ V_{DD}≤ 3.3 V. Fast strong mode.	–	–	16	MHz	90/10%, 25 pF load, 60/40 duty cycle
SID76	$F_{GPIOUT3}$	GPIO F_{OUT}; 3.3 V ≤ V_{DD} ≤ 5.5 V. Slow strong mode.	–	–	7	MHz	90/10%, 25 pF load, 60/40 duty cycle
SID245	$F_{GPIOUT4}$	GPIO F_{OUT}; 1.71 V ≤ V_{DD} ≤ 3.3 V. Slow strong mode.	–	–	3.5	MHz	90/10%, 25 pF load, 60/40 duty cycle
SID246	F_{GPIOIN}	GPIO input operating frequency; 1.71 V ≤ V_{DD} ≤ 5.5 V	–	–	16	MHz	90/10% V_{IO}

Note
7. Guaranteed by characterization.

XRES

Table 8. XRES DC Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID77	V_{IH}	Input voltage high threshold	0.7 × V_{DD}	–	–	V	CMOS Input
SID78	V_{IL}	Input voltage low threshold	–	–	0.3 × V_{DD}	V	CMOS Input
SID79	R_{PULLUP}	Pull-up resistor	3.5	5.6	8.5	kΩ	
SID80	C_{IN}	Input capacitance	–	3	7	pF	
SID81[8]	$V_{HYSXRES}$	Input voltage hysteresis	–	0.05* V_{DD}	–	mV	Typical hysteresis is 200 mV for V_{DD} > 4.5V

Table 9. XRES AC Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID83[8]	$T_{RESETWIDTH}$	Reset pulse width	5	–	–	µs	
BID#194[8]	$T_{RESETWAKE}$	Wake-up time from reset release	–	–	3	ms	

Analog Peripherals

Comparator

Table 10. Comparator DC Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID330[8]	I_{CMP1}	Block current, High Bandwidth mode	–	–	110	µA	
SID331[8]	I_{CMP2}	Block current, Low Power mode	–	–	85	µA	
SID332[8]	$V_{OFFSET1}$	Offset voltage, High Bandwidth mode	–	10	30	mV	
SID333[8]	$V_{OFFSET2}$	Offset voltage, Low Power mode	–	10	30	mV	
SID334[8]	Z_{CMP}	DC input impedance of comparator	35	–	–	MΩ	
SID338[8]	VINP_COMP	Comparator input range	0	–	3.6	V	Max input voltage is lower of 3.6 V or V_{DD}
SID339	VREF_COMP	Comparator internal voltage reference	1.188	1.2	1.212	V	

Note
8. Guaranteed by characterization.

Table 11. Comparator AC Specifications (Guaranteed by Characterization)

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID336[8]	T_{COMP1}	Response Time High Bandwidth mode, 50-mV overdrive	–	–	90	ns	
SID337[8]	T_{COMP2}	Response Time Low Power mode, 50-mV overdrive	–	–	110	ns	

CSD

Table 12. CSD and IDAC Block Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
CSD and IDAC Specifications							
SYS.PER#3	VDD_RIPPLE	Max allowed ripple on power supply, DC to 10 MHz	–	–	±50	mV	VDD > 2V (with ripple), 25 °C T_A, Sensitivity = 0.1 pF
SYS.PER#16	VDD_RIPPLE_1.8	Max allowed ripple on power supply, DC to 10 MHz	–	–	±25	mV	VDD > 1.75V (with ripple), 25 C T_A, Parasitic Capacitance (C_P) < 20 pF, Sensitivity ≥ 0.4 pF
SID.CSD#15	VREFHI	Reference Buffer Output	1.1	1.2	1.3	V	
SID.CSD#16	IDAC1IDD	IDAC1 (8-bits) block current	–	–	1125	µA	
SID.CSD#17	IDAC2IDD	IDAC2 (7-bits) block current	–	–	1125	µA	
SID308	V_{CSD}	Voltage range of operation	1.71	–	5.5	V	1.8 V ±5% or 1.8 V to 5.5 V
SID308A	VCOMPIDAC	Voltage compliance range of IDAC	0.8	–	V_{DD} –0.8	V	
SID309	$IDAC1_{DNL}$	DNL for 8-bit resolution	–1	–	1	LSB	
SID310	$IDAC1_{INL}$	INL for 8-bit resolution	–3	–	3	LSB	
SID311	$IDAC2_{DNL}$	DNL for 7-bit resolution	–1	–	1	LSB	
SID312	$IDAC2_{INL}$	INL for 7-bit resolution	–3	–	3	LSB	
SID313	SNR	Ratio of counts of finger to noise. Guaranteed by characterization	5	–	–	Ratio	Capacitance range of 9 to 35 pF, 0.1 pF sensitivity
SID314	$IDAC1_{CRT1}$	Output current of IDAC1 (8 bits) in high range	–	612	–	µA	
SID314A	$IDAC1_{CRT2}$	Output current of IDAC1(8 bits) in low range	–	306	–	µA	
SID315	$IDAC2_{CRT1}$	Output current of IDAC2 (7 bits) in high range	–	304.8	–	µA	
SID315A	$IDAC2_{CRT2}$	Output current of IDAC2 (7 bits) in low range	–	152.4	–	µA	
SID320	$IDAC_{OFFSET}$	All zeroes input	–	–	±1	LSB	
SID321	$IDAC_{GAIN}$	Full-scale error less offset	–	–	±10	%	
SID322	$IDAC_{MISMATCH}$	Mismatch between IDACs	–	–	7	LSB	
SID323	$IDAC_{SET8}$	Settling time to 0.5 LSB for 8-bit IDAC	–	–	10	µs	Full-scale transition. No external load.
SID324	$IDAC_{SET7}$	Settling time to 0.5 LSB for 7-bit IDAC	–	–	10	µs	Full-scale transition. No external load.
SID325	CMOD	External modulator capacitor.	–	2.2	–	nF	5-V rating, X7R or NP0 cap.

Digital Peripherals

Timer Counter Pulse-Width Modulator (TCPWM)

Table 13. TCPWM Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID.TCPWM.1	ITCPWM1	Block current consumption at 3 MHz	–	–	45	µA	All modes (TCPWM)
SID.TCPWM.2	ITCPWM2	Block current consumption at 8 MHz	–	–	145	µA	All modes (TCPWM)
SID.TCPWM.2A	ITCPWM3	Block current consumption at 16 MHz	–	–	160	µA	All modes (TCPWM)
SID.TCPWM.3	$TCPWM_{FREQ}$	Operating frequency	–	–	Fc	MHz	Fc max = CLK_SYS. Maximum = 16 MHz
SID.TCPWM.4	$TPWM_{ENEXT}$	Input trigger pulse width	2/Fc	–	–	ns	For all trigger events[9]
SID.TCPWM.5	$TPWM_{EXT}$	Output trigger pulse widths	2/Fc	–	–	ns	Minimum possible width of Overflow, Underflow, and CC (Counter equals Compare value) outputs
SID.TCPWM.5A	TC_{RES}	Resolution of counter	1/Fc	–	–	ns	Minimum time between successive counts
SID.TCPWM.5B	PWM_{RES}	PWM resolution	1/Fc	–	–	ns	Minimum pulse width of PWM Output
SID.TCPWM.5C	Q_{RES}	Quadrature inputs resolution	1/Fc	–	–	ns	Minimum pulse width between Quadrature phase inputs.

I^2C

Table 14. Fixed I^2C DC Specifications[10]

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID149	I_{I2C1}	Block current consumption at 100 kHz	–	–	25	µA	
SID150	I_{I2C2}	Block current consumption at 400 kHz	–	–	135	µA	
SID.PWR#5	ISBI2C	I^2C enabled in Deep Sleep mode	–	–	2.5	µA	

Table 15. Fixed I^2C AC Specifications[10]

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID153	F_{I2C1}	Bit rate	–	–	400	Kbps	

Note
9. Trigger events can be Stop, Start, Reload, Count, Capture, or Kill depending on which mode of operation is selected.
10. Guaranteed by characterization.

SWD Interface

Table 20. SWD Interface Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID213	F_SWDCLK1	3.3 V ≤ V_{DD} ≤ 5.5 V	–	–	14	MHz	SWDCLK ≤ 1/3 CPU clock frequency
SID214	F_SWDCLK2	1.71 V ≤ V_{DD} ≤ 3.3 V	–	–	7	MHz	SWDCLK ≤ 1/3 CPU clock frequency
SID215[13]	T_SWDI_SETUP	T = 1/f SWDCLK	0.25*T	–	–	ns	
SID216[13]	T_SWDI_HOLD	T = 1/f SWDCLK	0.25*T	–	–	ns	
SID217[13]	T_SWDO_VALID	T = 1/f SWDCLK	–	–	0.5*T	ns	
SID217A[13]	T_SWDO_HOLD	T = 1/f SWDCLK	1	–	–	ns	

Internal Main Oscillator

Table 21. IMO DC Specifications

(Guaranteed by Design)

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID218	I_{IMO1}	IMO operating current at 48 MHz	–	–	250	µA	
SID219	I_{IMO2}	IMO operating current at 24 MHz	–	–	180	µA	

Table 22. IMO AC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID223	$F_{IMOTOL1}$	Frequency variation at 24 and 32 MHz (trimmed)	–	–	±2	%	2 V ≤ V_{DD} ≤ 5.5 V, and –25 °C ≤ T_A ≤ 85 °C
SID223A	$F_{IMOTOLVCCD}$	Frequency variation at 24 and 32 MHz (trimmed)	–	–	±4	%	All other conditions
SID226	$T_{STARTIMO}$	IMO startup time	–	–	7	µs	
SID228	$T_{JITRMSIMO2}$	RMS jitter at 24 MHz	–	145	–	ps	

Internal Low-Speed Oscillator

Table 23. ILO DC Specifications

(Guaranteed by Design)

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID231[13]	I_{ILO1}	ILO operating current	–	0.3	1.05	µA	
SID233[13]	$I_{ILOLEAK}$	ILO leakage current	–	2	15	nA	

Table 24. ILO AC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID234[13]	$T_{STARTILO1}$	ILO startup time	–	–	2	ms	
SID236[13]	$T_{ILODUTY}$	ILO duty cycle	40	50	60	%	
SID237	$F_{ILOTRIM1}$	ILO frequency range	20	40	80	kHz	

Note
13. Guaranteed by characterization.

Table 25. External Clock Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID305[14]	ExtClkFreq	External clock input frequency	0	–	16	MHz	
SID306[14]	ExtClkDuty	Duty cycle; measured at $V_{DD/2}$	45	–	55	%	

Table 26. Block Specs

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID262[14]	$T_{CLKSWITCH}$	System clock source switching time	3	–	4	Periods	

Note
14. Guaranteed by characterization.

The Field Values are listed in the following table:

Field	Description	Values	Meaning
CY8C	Cypress prefix		
4	Architecture	4	PSoC 4
A	Family	0	4000 Family
B	CPU speed	1	16 MHz
		4	48 MHz
C	Flash capacity	3	8 KB
		4	16 KB
		5	32 KB
		6	64 KB
		7	128 KB
DE	Package code	SX	SOIC
		LQ	QFN
		PV	SSOP
		FN	WLCSP
F	Temperature range	I	Industrial
XYZ	Attributes code	000-999	Code of feature set in specific family

Packaging

Table 27. Package List

Spec ID#	Package	Description
BID#47A	28-Pin SSOP	28-pin 5 × 10 × 1.65mm SSOP with 0.65-mm pitch
BID#26	24-Pin QFN	24-pin 4 × 4 × 0.6 mm QFN with 0.5-mm pitch
BID#33	16-Pin QFN	16-pin 3 × 3 × 0.6 mm QFN with 0.5-mm pitch
BID#40	16-Pin SOIC	16-pin (150 Mil) SOIC
BID#47	8-Pin SOIC	8-pin (150 Mil) SOIC
BID#147A	16-Ball WLCSP	16-Ball 1.47 × 1.58 × 0.4 mm

Table 28. Package Characteristics

Parameter	Description	Conditions	Min	Typ	Max	Units
T_A	Operating ambient temperature		–40	25	85	°C
T_J	Operating junction temperature		–40	–	100	°C
T_{JA}	Package θ_{JA} (28-pin SSOP)		–	66.6	–	°C/Watt
T_{JC}	Package θ_{JC} (28-pin SSOP)		–	34	–	°C/Watt
T_{JA}	Package θ_{JA} (24-pin QFN)		–	38	–	°C/Watt
T_{JC}	Package θ_{JC} (24-pin QFN)		–	5.6	–	°C/Watt
T_{JA}	Package θ_{JA} (16-pin QFN)		–	49.6	–	°C/Watt
T_{JC}	Package θ_{JC} (16-pin QFN)		–	5.9	–	°C/Watt
T_{JA}	Package θ_{JA} (16-pin SOIC)		–	142	–	°C/Watt
T_{JC}	Package θ_{JC} (16-pin SOIC)		–	49.8	–	°C/Watt
T_{JA}	Package θ_{JA} (16-ball WLCSP)		–	90	–	°C/Watt
T_{JC}	Package θ_{JC} (16-ball WLCSP)		–	0.9	–	°C/Watt
T_{JA}	Package θ_{JA} (8-pin SOIC)		–	198	–	°C/Watt
T_{JC}	Package θ_{JC} (8-pin SOIC)		–	56.9	–	°C/Watt

Table 29. Solder Reflow Peak Temperature

Package	Maximum Peak Temperature	Maximum Time at Peak Temperature
All	260 °C	30 seconds

Table 30. Package Moisture Sensitivity Level (MSL), IPC/JEDEC J-STD-020

Package	MSL
All except WLCSP	MSL 3
16-ball WLCSP	MSL1

Package Outline Drawings

Figure 11. 28-Pin SSOP Package Outline

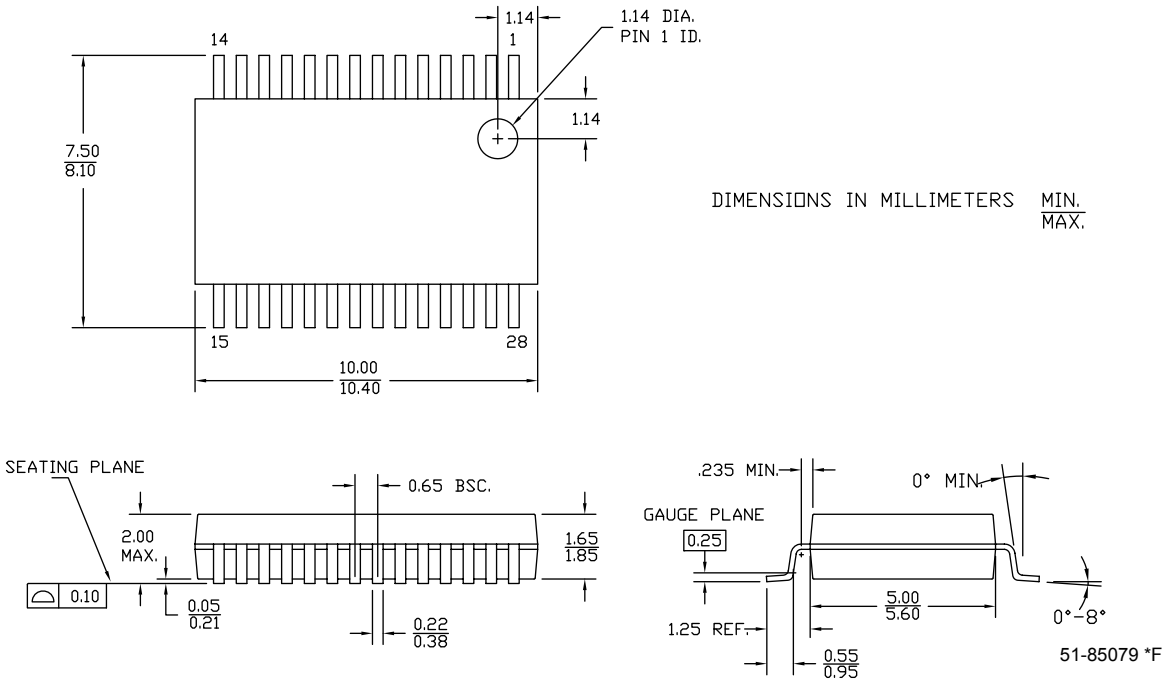
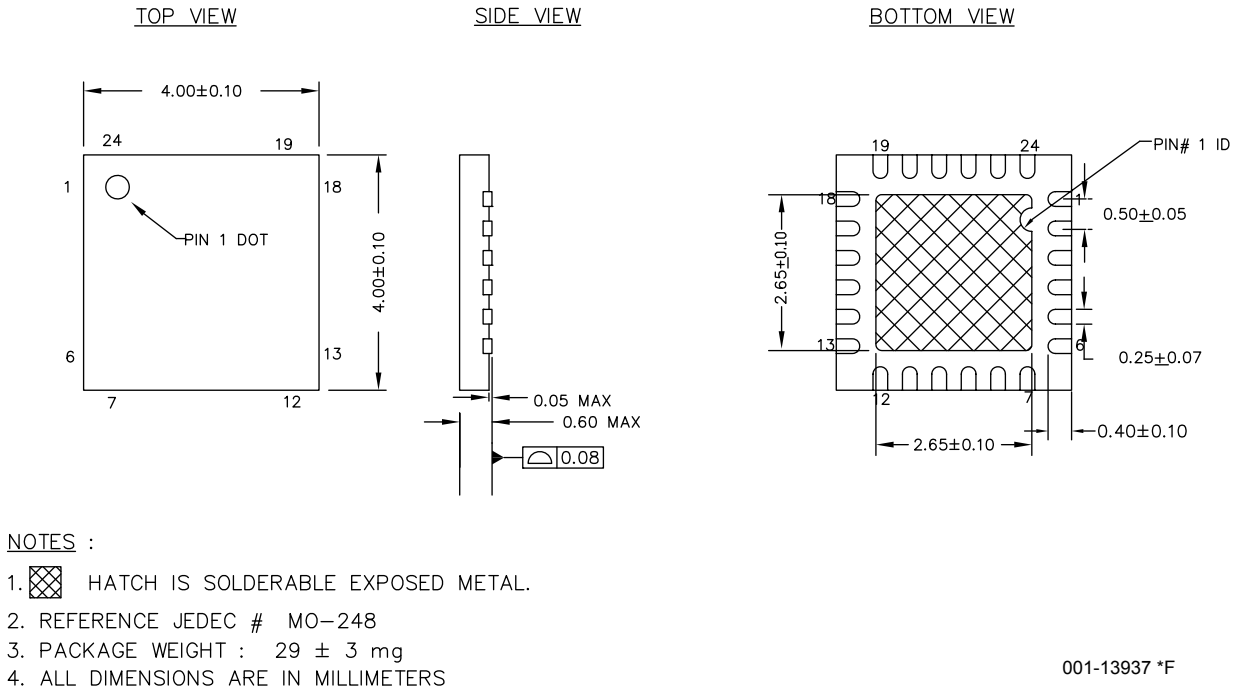


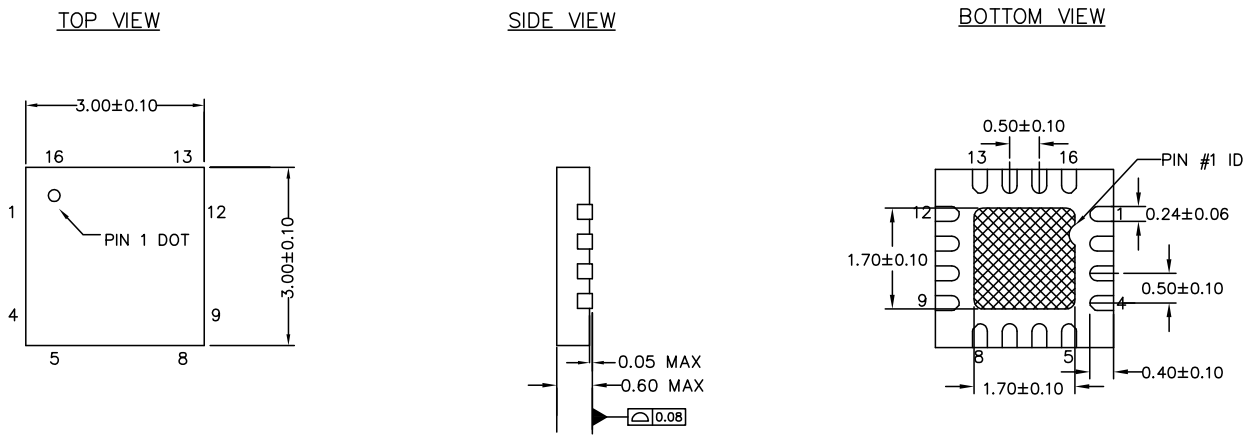
Figure 12. 24-pin QFN EPAD (Sawn) Package Outline



Note
15. Dimensions of the QFN package drawings are in millimeters.

The center pad on the QFN package should be connected to ground (VSS) for best mechanical, thermal, and electrical performance. If not connected to ground, it should be electrically floating and not connected to any other signal.

Figure 13. 16-pin QFN Package EPAD (Sawn)

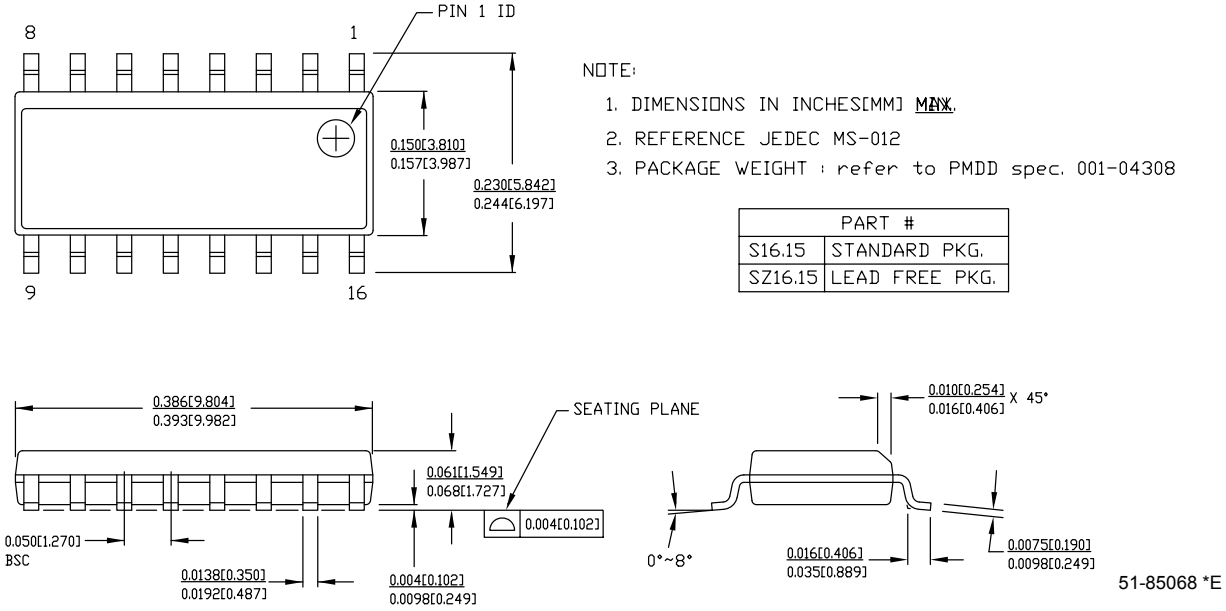


NOTES

1. HATCH AREA IS SOLDERABLE EXPOSED PAD
2. REFERENCE JEDEC # MO-248
3. ALL DIMENSIONS ARE IN MILLIMETERS
4. PACKAGE WEIGHT: See Cypress Package Material Declaration Datasheet (PMDD) posted on the Cypress web

001-87187 *A

Figure 14. 16-pin (150-mil) SOIC Package Outline



51-85068 *E

Note
16. Dimensions of the QFN package drawings are in inches [millimeters].

Acronyms

Table 31. Acronyms Used in this Document

Acronym	Description
abus	analog local bus
ADC	analog-to-digital converter
AG	analog global
AHB	AMBA (advanced microcontroller bus architecture) high-performance bus, an ARM data transfer bus
ALU	arithmetic logic unit
AMUXBUS	analog multiplexer bus
API	application programming interface
APSR	application program status register
ARM®	advanced RISC machine, a CPU architecture
ATM	automatic thump mode
BW	bandwidth
CAN	Controller Area Network, a communications protocol
CMRR	common-mode rejection ratio
CPU	central processing unit
CRC	cyclic redundancy check, an error-checking protocol
DAC	digital-to-analog converter, see also IDAC, VDAC
DFB	digital filter block
DIO	digital input/output, GPIO with only digital capabilities, no analog. See GPIO.
DMIPS	Dhrystone million instructions per second
DMA	direct memory access, see also TD
DNL	differential nonlinearity, see also INL
DNU	do not use
DR	port write data registers
DSI	digital system interconnect
DWT	data watchpoint and trace
ECC	error correcting code
ECO	external crystal oscillator
EEPROM	electrically erasable programmable read-only memory
EMI	electromagnetic interference
EMIF	external memory interface
EOC	end of conversion
EOF	end of frame
EPSR	execution program status register
ESD	electrostatic discharge

Table 31. Acronyms Used in this Document *(continued)*

Acronym	Description
ETM	embedded trace macrocell
FIR	finite impulse response, see also IIR
FPB	flash patch and breakpoint
FS	full-speed
GPIO	general-purpose input/output, applies to a PSoC pin
HVI	high-voltage interrupt, see also LVI, LVD
IC	integrated circuit
IDAC	current DAC, see also DAC, VDAC
IDE	integrated development environment
I^2C, or IIC	Inter-Integrated Circuit, a communications protocol
IIR	infinite impulse response, see also FIR
ILO	internal low-speed oscillator, see also IMO
IMO	internal main oscillator, see also ILO
INL	integral nonlinearity, see also DNL
I/O	input/output, see also GPIO, DIO, SIO, USBIO
IPOR	initial power-on reset
IPSR	interrupt program status register
IRQ	interrupt request
ITM	instrumentation trace macrocell
LCD	liquid crystal display
LIN	Local Interconnect Network, a communications protocol.
LR	link register
LUT	lookup table
LVD	low-voltage detect, see also LVI
LVI	low-voltage interrupt, see also HVI
LVTTL	low-voltage transistor-transistor logic
MAC	multiply-accumulate
MCU	microcontroller unit
MISO	master-in slave-out
NC	no connect
NMI	nonmaskable interrupt
NRZ	non-return-to-zero
NVIC	nested vectored interrupt controller
NVL	nonvolatile latch, see also WOL
opamp	operational amplifier
PAL	programmable array logic, see also PLD

Table 31. Acronyms Used in this Document *(continued)*

Acronym	Description
PC	program counter
PCB	printed circuit board
PGA	programmable gain amplifier
PHUB	peripheral hub
PHY	physical layer
PICU	port interrupt control unit
PLA	programmable logic array
PLD	programmable logic device, see also PAL
PLL	phase-locked loop
PMDD	package material declaration data sheet
POR	power-on reset
PRES	precise power-on reset
PRS	pseudo random sequence
PS	port read data register
PSoC®	Programmable System-on-Chip™
PSRR	power supply rejection ratio
PWM	pulse-width modulator
RAM	random-access memory
RISC	reduced-instruction-set computing
RMS	root-mean-square
RTC	real-time clock
RTL	register transfer language
RTR	remote transmission request
RX	receive
SAR	successive approximation register
SC/CT	switched capacitor/continuous time
SCL	I^2C serial clock
SDA	I^2C serial data
S/H	sample and hold
SINAD	signal to noise and distortion ratio
SIO	special input/output, GPIO with advanced features. See GPIO.
SOC	start of conversion
SOF	start of frame
SPI	Serial Peripheral Interface, a communications protocol
SR	slew rate
SRAM	static random access memory
SRES	software reset
SWD	serial wire debug, a test protocol

Table 31. Acronyms Used in this Document *(continued)*

Acronym	Description
SWV	single-wire viewer
TD	transaction descriptor, see also DMA
THD	total harmonic distortion
TIA	transimpedance amplifier
TRM	technical reference manual
TTL	transistor-transistor logic
TX	transmit
UART	Universal Asynchronous Transmitter Receiver, a communications protocol
UDB	universal digital block
USB	Universal Serial Bus
USBIO	USB input/output, PSoC pins used to connect to a USB port
VDAC	voltage DAC, see also DAC, IDAC
WDT	watchdog timer
WOL	write once latch, see also NVL
WRES	watchdog timer reset
XRES	external reset I/O pin
XTAL	crystal

Document Conventions

Units of Measure

Table 32. Units of Measure

Symbol	Unit of Measure
°C	degrees Celsius
dB	decibel
fF	femto farad
Hz	hertz
KB	1024 bytes
kbps	kilobits per second
Khr	kilohour
kHz	kilohertz
kΩ	kilo ohm
ksps	kilosamples per second
LSB	least significant bit
Mbps	megabits per second
MHz	megahertz
MΩ	mega-ohm
Msps	megasamples per second
µA	microampere
µF	microfarad
µH	microhenry
µs	microsecond
µV	microvolt
µW	microwatt
mA	milliampere
ms	millisecond
mV	millivolt
nA	nanoampere
ns	nanosecond
nV	nanovolt
Ω	ohm
pF	picofarad
ppm	parts per million
ps	picosecond
s	second
sps	samples per second
sqrtHz	square root of hertz
V	volt

Revision History

Description Title: PSoC® 4: PSoC 4000 Family Datasheet Programmable System-on-Chip (PSoC®) Document Number: 001-89638				
Revision	**ECN**	**Orig. of Change**	**Submission Date**	**Description of Change**
*B	4348760	WKA	05/16/2014	New PSoC 4000 datasheet.
*C	4514139	WKA	10/27/2014	Added 28-pin SSOP pin and package details. Updated V_{REF} spec values. Updated conditions for SID174. Updated SID.CSD#15 values and description. Added spec SID339.
*D	4617283	WKA	01/09/2015	Corrected Development Kits information and PSoC Creator Example Project figure. Corrected typo in the ordering information table. Updated 28-pin SSOP package diagram.
*E	4735762	WKA	05/26/2015	Added 16-ball WLCSP pin and package details.
*F	5466193	WKA	10/07/2016	Updated Table 30. Updated 8-pin SOIC package diagram. Updated the template.
*G	5685079	TSEN	04/05/2017	Updated 16-ball WLCSP package details.