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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	40MHz
Connectivity	I²C, IrDA, LINbus, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I²S, POR, PWM, WDT
Number of I/O	33
Program Memory Size	1MB (1M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D - 12b SAR
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-VQFN Exposed Pad
Supplier Device Package	48-QFN (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32jg12b500f1024gm48-cr

2. Ordering Information

Table 2.1. Ordering Information

Ordering Code	Flash (kB)	RAM (kB)	DC-DC Con-verter	GPIO	Package	Temp Range
EFM32JG12B500F1024GL125-B	1024	256	Yes	65	BGA125	-40 to +85
EFM32JG12B500F1024IL125-B	1024	256	Yes	65	BGA125	-40 to +125
EFM32JG12B500F1024GM48-B	1024	256	Yes	33	QFN48	-40 to +85
EFM32JG12B500F1024IM48-B	1024	256	Yes	33	QFN48	-40 to +125

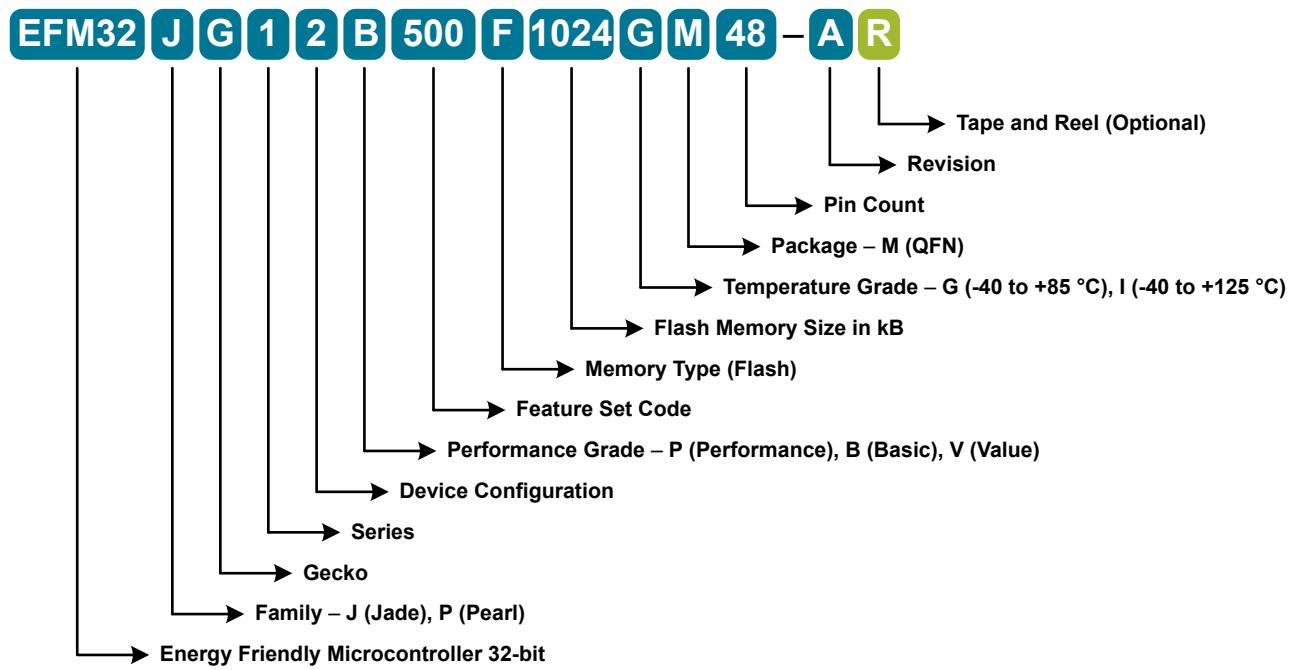


Figure 2.1. OPN Decoder

3.2 Power

The EFM32JG12 has an Energy Management Unit (EMU) and efficient integrated regulators to generate internal supply voltages. Only a single external supply voltage is required, from which all internal voltages are created. An optional integrated DC-DC buck regulator can be utilized to further reduce the current consumption. The DC-DC regulator requires one external inductor and one external capacitor.

The EFM32JG12 device family includes support for internal supply voltage scaling, as well as two different power domains groups for peripherals. These enhancements allow for further supply current reductions and lower overall power consumption.

AVDD and VREGVDD need to be 1.8 V or higher for the MCU to operate across all conditions; however the rest of the system will operate down to 1.62 V, including the digital supply and I/O. This means that the device is fully compatible with 1.8 V components. Running from a sufficiently high supply, the device can use the DC-DC to regulate voltage not only for itself, but also for other PCB components, supplying up to a total of 200 mA.

3.2.1 Energy Management Unit (EMU)

The Energy Management Unit manages transitions of energy modes in the device. Each energy mode defines which peripherals and features are available and the amount of current the device consumes. The EMU can also be used to turn off the power to unused RAM blocks, and it contains control registers for the DC-DC regulator and the Voltage Monitor (VMON). The VMON is used to monitor multiple supply voltages. It has multiple channels which can be programmed individually by the user to determine if a sensed supply has fallen below a chosen threshold.

3.2.2 DC-DC Converter

The DC-DC buck converter covers a wide range of load currents and provides up to 90% efficiency in energy modes EM0, EM1, EM2 and EM3, and can supply up to 200 mA to the device and surrounding PCB components. Protection features include programmable current limiting, short-circuit protection, and dead-time protection. The DC-DC converter may also enter bypass mode when the input voltage is too low for efficient operation. In bypass mode, the DC-DC input supply is internally connected directly to its output through a low resistance switch. Bypass mode also supports in-rush current limiting to prevent input supply voltage drops due to excessive output current transients.

3.2.3 Power Domains

The EFM32JG12 has two peripheral power domains for operation in EM2 and lower. If all of the peripherals in a peripheral power domain are configured as unused, the power domain for that group will be powered off in the low-power mode, reducing the overall current consumption of the device.

Table 3.1. Peripheral Power Subdomains

Peripheral Power Domain 1	Peripheral Power Domain 2
ACMP0	ACMP1
PCNT0	PCNT1
ADC0	PCNT2
LETIMER0	CSEN
LESENSE	DAC0
APORT	LEUART0
-	I2C0
-	I2C1
-	IDAC

3.11 Memory Map

The EFM32JG12 memory map is shown in the figures below. RAM and flash sizes are for the largest memory configuration.

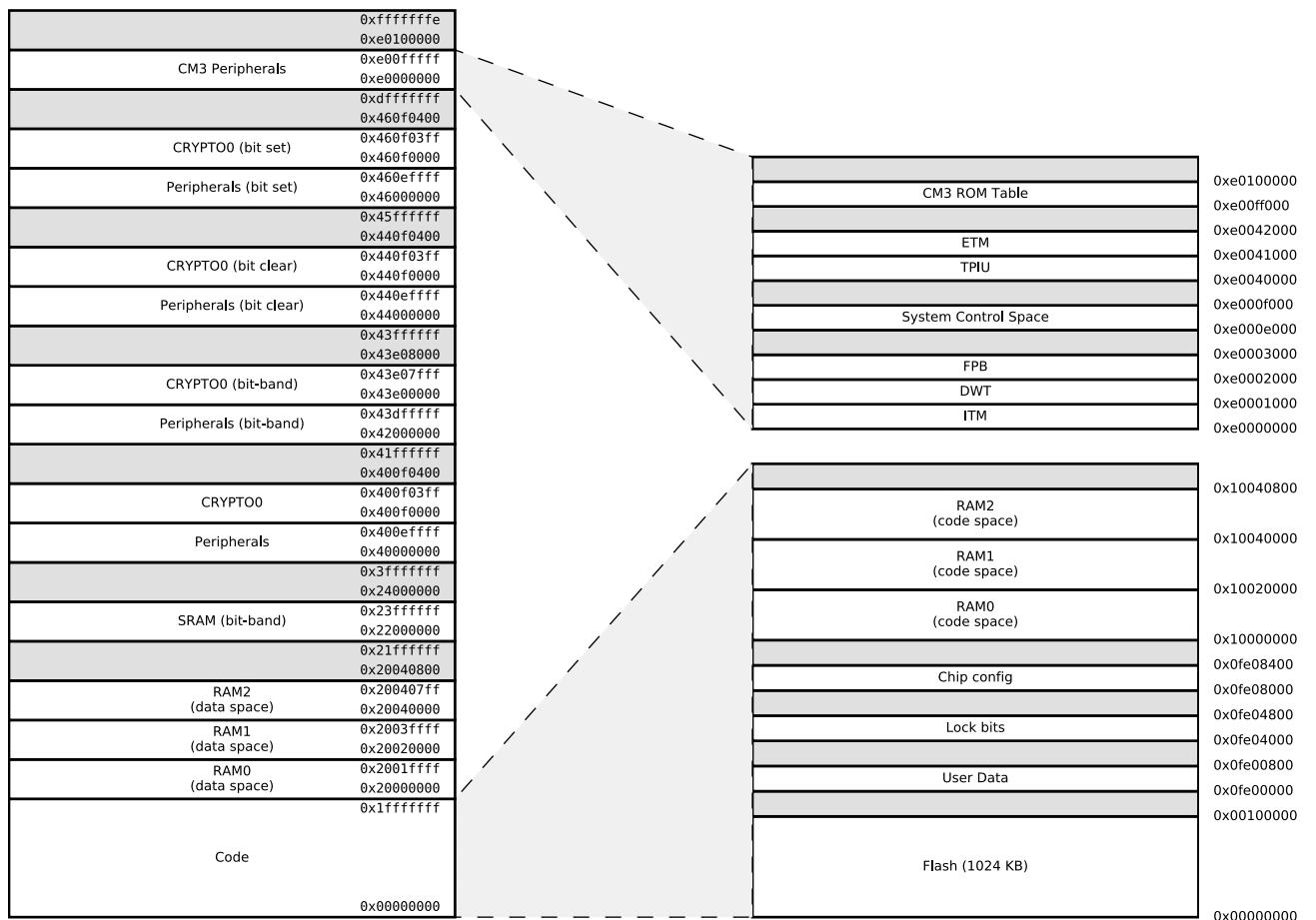


Figure 3.2. EFM32JG12 Memory Map — Core Peripherals and Code Space

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Max load current	I_{LOAD_MAX}	Low noise (LN) mode, Heavy Drive ² , $T_{amb} \leq 85^{\circ}\text{C}$	—	—	TBD	mA
		Low noise (LN) mode, Heavy Drive ² , $T_{amb} > 85^{\circ}\text{C}$	—	—	TBD	mA
		Low noise (LN) mode, Medium Drive ²	—	—	TBD	mA
		Low noise (LN) mode, Light Drive ²	—	—	TBD	mA
		Low power (LP) mode, $LPCMPBIASEMxx^3 = 0$	—	—	TBD	μA
		Low power (LP) mode, $LPCMPBIASEMxx^3 = 3$	—	—	TBD	mA
DCDC nominal output capacitor ⁵	C_{DCDC}	25% tolerance	1	4.7	4.7	μF
DCDC nominal output inductor	L_{DCDC}	20% tolerance	4.7	4.7	4.7	μH
Resistance in Bypass mode	R_{BYP}		—	1.2	TBD	Ω

Note:

1. Due to internal dropout, the DC-DC output will never be able to reach its input voltage, V_{REGVDD} .
2. Drive levels are defined by configuration of the PFETCNT and NFETCNT registers. Light Drive: PFETCNT=NFETCNT=3; Medium Drive: PFETCNT=NFETCNT=7; Heavy Drive: PFETCNT=NFETCNT=15.
3. In EMU_DCDCMISCCTRL register.
4. LP mode controller is a hysteretic controller that maintains the output voltage within the specified limits.
5. Output voltage under/over-shoot and regulation are specified with C_{DCDC} 4.7 μF . Different control loop settings must be used if C_{DCDC} is lower than 4.7 μF .

4.1.8.5 Auxiliary High-Frequency RC Oscillator (AUXHFRCO)

Table 4.14. Auxiliary High-Frequency RC Oscillator (AUXHFRCO)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Frequency accuracy	$f_{AUXHFRCO_ACC}$	At production calibrated frequencies, across supply voltage and temperature	TBD	—	TBD	%
Start-up time	$t_{AUXHFRCO}$	$f_{AUXHFRCO} \geq 19 \text{ MHz}$	—	400	—	ns
		$4 < f_{AUXHFRCO} < 19 \text{ MHz}$	—	1.4	—	μs
		$f_{AUXHFRCO} \leq 4 \text{ MHz}$	—	2.5	—	μs
Current consumption on all supplies	$I_{AUXHFRCO}$	$f_{AUXHFRCO} = 38 \text{ MHz}$	—	193	TBD	μA
		$f_{AUXHFRCO} = 32 \text{ MHz}$	—	157	TBD	μA
		$f_{AUXHFRCO} = 26 \text{ MHz}$	—	135	TBD	μA
		$f_{AUXHFRCO} = 19 \text{ MHz}$	—	108	TBD	μA
		$f_{AUXHFRCO} = 16 \text{ MHz}$	—	100	TBD	μA
		$f_{AUXHFRCO} = 13 \text{ MHz}$	—	77	TBD	μA
		$f_{AUXHFRCO} = 7 \text{ MHz}$	—	53	TBD	μA
		$f_{AUXHFRCO} = 4 \text{ MHz}$	—	29	TBD	μA
		$f_{AUXHFRCO} = 2 \text{ MHz}$	—	28	TBD	μA
		$f_{AUXHFRCO} = 1 \text{ MHz}$	—	27	TBD	μA
Coarse trim step size (% of period)	$SS_{AUXHFR-CO_COARSE}$		TBD	0.8	TBD	%
Fine trim step size (% of period)	$SS_{AUXHFR-CO_FINE}$		TBD	0.1	TBD	%
Period jitter	$PJ_{AUXHFRCO}$		—	0.2	—	% RMS

4.1.8.6 Ultra-low Frequency RC Oscillator (ULFRCO)

Table 4.15. Ultra-low Frequency RC Oscillator (ULFRCO)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Oscillation frequency	f_{ULFRCO}		TBD	1	TBD	kHz

4.1.10 General-Purpose I/O (GPIO)

Table 4.17. General-Purpose I/O (GPIO)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Input low voltage	V _{IL}	GPIO pins	—	—	IOVDD*0.3	V
Input high voltage	V _{IH}	GPIO pins	IOVDD*0.7	—	—	V
Output high voltage relative to IOVDD	V _{OH}	Sourcing 3 mA, IOVDD \geq 3 V, DRIVESTRENGTH ¹ = WEAK	IOVDD*0.8	—	—	V
		Sourcing 1.2 mA, IOVDD \geq 1.62 V, DRIVESTRENGTH ¹ = WEAK	IOVDD*0.6	—	—	V
		Sourcing 20 mA, IOVDD \geq 3 V, DRIVESTRENGTH ¹ = STRONG	IOVDD*0.8	—	—	V
		Sourcing 8 mA, IOVDD \geq 1.62 V, DRIVESTRENGTH ¹ = STRONG	IOVDD*0.6	—	—	V
Output low voltage relative to IOVDD	V _{OL}	Sinking 3 mA, IOVDD \geq 3 V, DRIVESTRENGTH ¹ = WEAK	—	—	IOVDD*0.2	V
		Sinking 1.2 mA, IOVDD \geq 1.62 V, DRIVESTRENGTH ¹ = WEAK	—	—	IOVDD*0.4	V
		Sinking 20 mA, IOVDD \geq 3 V, DRIVESTRENGTH ¹ = STRONG	—	—	IOVDD*0.2	V
		Sinking 8 mA, IOVDD \geq 1.62 V, DRIVESTRENGTH ¹ = STRONG	—	—	IOVDD*0.4	V
Input leakage current	I _{IOLEAK}	All GPIO except LFXO pins, GPIO \leq IOVDD, T _{amb} \leq 85 °C	—	0.1	TBD	nA
		LFXO Pins, GPIO \leq IOVDD, T _{amb} \leq 85 °C	—	0.1	TBD	nA
		All GPIO except LFXO pins, GPIO \leq IOVDD, T _{AMB} > 85 °C	—	—	TBD	nA
		LFXO Pins, GPIO \leq IOVDD, T _{AMB} > 85 °C	—	—	TBD	nA
Input leakage current on 5VTOL pads above IOVDD	I _{5VTOLLEAK}	IOVDD < GPIO \leq IOVDD + 2 V	—	3.3	15	µA
I/O pin pull-up/pull-down resistor	R _{PUD}		TBD	43	TBD	kΩ
Pulse width of pulses removed by the glitch suppression filter	t _{IOGLITCH}		TBD	25	TBD	ns

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Note:						
1.	ACMPVDD	is a supply chosen by the setting in ACMPn_CTRL_PWRSEL and may be IOVDD, AVDD or DVDD.				
2.		The total ACMP current is the sum of the contributions from the ACMP and its internal voltage reference. $I_{ACMPTOTAL} = I_{ACMP} + I_{ACMPREF}$.				
3.		± 100 mV differential drive.				
4.		In ACMPn_CTRL register.				
5.		In ACMPn_HYSTERESIS register.				
6.		In ACMPn_INPUTSEL register.				

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Slew rate ⁵	SR	DRIVESTRENGTH = 3, INCBW=1 ³	—	4.7	—	V/ μ s
		DRIVESTRENGTH = 3, INCBW=0	—	1.5	—	V/ μ s
		DRIVESTRENGTH = 2, INCBW=1 ³	—	1.27	—	V/ μ s
		DRIVESTRENGTH = 2, INCBW=0	—	0.42	—	V/ μ s
		DRIVESTRENGTH = 1, INCBW=1 ³	—	0.17	—	V/ μ s
		DRIVESTRENGTH = 1, INCBW=0	—	0.058	—	V/ μ s
		DRIVESTRENGTH = 0, INCBW=1 ³	—	0.044	—	V/ μ s
		DRIVESTRENGTH = 0, INCBW=0	—	0.015	—	V/ μ s
Startup time ⁶	T _{START}	DRIVESTRENGTH = 3	—	—	TBD	μ s
		DRIVESTRENGTH = 2	—	—	TBD	μ s
		DRIVESTRENGTH = 1	—	—	TBD	μ s
		DRIVESTRENGTH = 0	—	—	TBD	μ s
Input offset voltage	V _{OIS}	DRIVESTRENGTH = 2 or 3, T _J = 25 °C	TBD	—	TBD	mV
		DRIVESTRENGTH = 1 or 0, T _J = 25 °C	TBD	—	TBD	mV
		DRIVESTRENGTH = 2 or 3, across operating temperature range	TBD	—	TBD	mV
		DRIVESTRENGTH = 1 or 0, across operating temperature range	TBD	—	TBD	mV
DC power supply rejection ratio ⁹	PSRR _{DC}	Input referred	—	70	—	dB
DC common-mode rejection ratio ⁹	CMRR _{DC}	Input referred	—	70	—	dB
Total harmonic distortion	THD _{OPA}	DRIVESTRENGTH = 2, 3x Gain connection, 1 kHz, V _{OUT} = 0.1 V to V _{OPA} - 0.1 V	—	90	—	dB
		DRIVESTRENGTH = 0, 3x Gain connection, 0.1 kHz, V _{OUT} = 0.1 V to V _{OPA} - 0.1 V	—	90	—	dB

Pin		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
J13	PA5	VDAC0_OUT0ALT / OPA0_OUTALT #0 BUSCY BUSDX	TIM0_CC0 #5 TIM0_CC1 #4 TIM0_CC2 #3 TIM0_CDTI0 #2 TIM0_CDTI1 #1 TIM0_CDTI2 #0 TIM1_CC0 #5 TIM1_CC1 #4 TIM1_CC2 #3 TIM1_CC3 #2 WTIM0_CC0 #5 WTIM0_CC1 #3 WTIM0_CC2 #1 LE-TIM0_OUT0 #5 LE-TIM0_OUT1 #4 PCNT0_S0IN #5 PCNT0_S1IN #4	US0_TX #5 US0_RX #4 US0_CLK #3 US0_CS #2 US0_CTS #1 US0_RTS #0 US1_TX #5 US1_RX #4 US1_CLK #3 US1_CS #2 US1_CTS #1 US1_RTS #0 US2_TX #0 US2_RX #31 US2_CLK #30 US2_CS #29 US2_CTS #28 US2_RTS #27 LEU0_TX #5 LEU0_RX #4 I2C0_SDA #5 I2C0_SCL #4	CMU_CLKI0 #4 PRS_CH6 #5 PRS_CH7 #4 PRS_CH8 #3 PRS_CH9 #2 ACMP0_O #5 ACMP1_O #5 LES_CH13 ETM_TCLK #1
K1	HFXTAL_N	High Frequency Crystal input pin.			
K2	VSS	Ground			
K12	PA4	VDAC0_OUT1ALT / OPA1_OUTALT #2 BUSDY BUSCX OPA0_N	TIM0_CC0 #4 TIM0_CC1 #3 TIM0_CC2 #2 TIM0_CDTI0 #1 TIM0_CDTI1 #0 TIM0_CDTI2 #31 TIM1_CC0 #4 TIM1_CC1 #3 TIM1_CC2 #2 TIM1_CC3 #1 WTIM0_CC0 #4 WTIM0_CC1 #2 WTIM0_CC2 #0 LE-TIM0_OUT0 #4 LE-TIM0_OUT1 #3 PCNT0_S0IN #4 PCNT0_S1IN #3	US0_TX #4 US0_RX #3 US0_CLK #2 US0_CS #1 US0_CTS #0 US0_RTS #31 US1_TX #4 US1_RX #3 US1_CLK #2 US1_CS #1 US1_CTS #0 US1_RTS #31 LEU0_TX #4 LEU0_RX #3 I2C0_SDA #4 I2C0_SCL #3	PRS_CH6 #4 PRS_CH7 #3 PRS_CH8 #2 PRS_CH9 #1 ACMP0_O #4 ACMP1_O #4 LES_CH12
K13	PA3	BUSCY BUSDX VDAC0_OUT0 / OPA0_OUT	TIM0_CC0 #3 TIM0_CC1 #2 TIM0_CC2 #1 TIM0_CDTI0 #0 TIM0_CDTI1 #31 TIM0_CDTI2 #30 TIM1_CC0 #3 TIM1_CC1 #2 TIM1_CC2 #1 TIM1_CC3 #0 WTIM0_CC0 #3 WTIM0_CC1 #1 LE-TIM0_OUT0 #3 LE-TIM0_OUT1 #2 PCNT0_S0IN #3 PCNT0_S1IN #2	US0_TX #3 US0_RX #2 US0_CLK #1 US0_CS #0 US0_CTS #31 US0_RTS #30 US1_TX #3 US1_RX #2 US1_CLK #1 US1_CS #0 US1_CTS #31 US1_RTS #30 LEU0_TX #3 LEU0_RX #2 I2C0_SDA #3 I2C0_SCL #2	PRS_CH6 #3 PRS_CH7 #2 PRS_CH8 #1 PRS_CH9 #0 ACMP0_O #3 ACMP1_O #3 LES_CH11 GPIO_EM4WU8
L1	HFXTAL_P	High Frequency Crystal output pin.			
L2	VSS	Ground			
L10	BODEN	Brown-Out Detector Enable. This pin may be left disconnected or tied to AVDD.			

Pin		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
3	PF2	BUSBY BUSAX	TIM0_CC0 #26 TIM0_CC1 #25 TIM0_CC2 #24 TIM0_CDTI0 #23 TIM0_CDTI1 #22 TIM0_CDTI2 #21 TIM1_CC0 #26 TIM1_CC1 #25 TIM1_CC2 #24 TIM1_CC3 #23 WTIM0_CDTI2 #30 WTIM1_CC0 #26 WTIM1_CC1 #24 WTIM1_CC2 #22 WTIM1_CC3 #20 LE-TIM0_OUT0 #26 LE-TIM0_OUT1 #25 PCNT0_S0IN #26 PCNT0_S1IN #25	US0_TX #26 US0_RX #25 US0_CLK #24 US0_CS #23 US0_CTS #22 US0_RTS #21 US1_TX #26 US1_RX #25 US1_CLK #24 US1_CS #23 US1_CTS #22 US1_RTS #21 LEU0_TX #26 LEU0_RX #25 I2C0_SDA #26 I2C0_SCL #25	CMU_CLK0 #6 PRS_CH0 #2 PRS_CH1 #1 PRS_CH2 #0 PRS_CH3 #7 ACMP0_O #26 ACMP1_O #26 DBG_TDO DBG_SWO #0 GPIO_EM4WU0
4	PF3	BUSAY BUSBX	TIM0_CC0 #27 TIM0_CC1 #26 TIM0_CC2 #25 TIM0_CDTI0 #24 TIM0_CDTI1 #23 TIM0_CDTI2 #22 TIM1_CC0 #27 TIM1_CC1 #26 TIM1_CC2 #25 TIM1_CC3 #24 WTIM0_CDTI2 #31 WTIM1_CC0 #27 WTIM1_CC1 #25 WTIM1_CC2 #23 WTIM1_CC3 #21 LE-TIM0_OUT0 #27 LE-TIM0_OUT1 #26 PCNT0_S0IN #27 PCNT0_S1IN #26	US0_TX #27 US0_RX #26 US0_CLK #25 US0_CS #24 US0_CTS #23 US0_RTS #22 US1_TX #27 US1_RX #26 US1_CLK #25 US1_CS #24 US1_CTS #23 US1_RTS #22 US2_TX #16 US2_RX #15 US2_CLK #14 US2_CS #13 US2_CTS #12 US2_RTS #11 LEU0_TX #27 LEU0_RX #26 I2C0_SDA #27 I2C0_SCL #26	CMU_CLK1 #6 PRS_CH0 #3 PRS_CH1 #2 PRS_CH2 #1 PRS_CH3 #0 ACMP0_O #27 ACMP1_O #27 DBG_TDI
5	PF4	BUSBY BUSAX	TIM0_CC0 #28 TIM0_CC1 #27 TIM0_CC2 #26 TIM0_CDTI0 #25 TIM0_CDTI1 #24 TIM0_CDTI2 #23 TIM1_CC0 #28 TIM1_CC1 #27 TIM1_CC2 #26 TIM1_CC3 #25 WTIM1_CC0 #28 WTIM1_CC1 #26 WTIM1_CC2 #24 WTIM1_CC3 #22 LE-TIM0_OUT0 #28 LE-TIM0_OUT1 #27 PCNT0_S0IN #28 PCNT0_S1IN #27	US0_TX #28 US0_RX #27 US0_CLK #26 US0_CS #25 US0_CTS #24 US0_RTS #23 US1_TX #28 US1_RX #27 US1_CLK #26 US1_CS #25 US1_CTS #24 US1_RTS #23 US2_TX #17 US2_RX #16 US2_CLK #15 US2_CS #14 US2_CTS #13 US2_RTS #12 LEU0_TX #28 LEU0_RX #27 I2C0_SDA #28 I2C0_SCL #27	PRS_CH0 #4 PRS_CH1 #3 PRS_CH2 #2 PRS_CH3 #1 ACMP0_O #28 ACMP1_O #28

Pin		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
26	PA1	BUSCY BUSDX ADC0_EXTP VDAC0_EXT	TIM0_CC0 #1 TIM0_CC1 #0 TIM0_CC2 #31 TIM0_CDTI0 #30 TIM0_CDTI1 #29 TIM0_CDTI2 #28 TIM1_CC0 #1 TIM1_CC1 #0 TIM1_CC2 #31 TIM1_CC3 #30 WTIM0_CC0 #1 LE- TIM0_OUT0 #1 LE- TIM0_OUT1 #0 PCNT0_S0IN #1 PCNT0_S1IN #0	US0_TX #1 US0_RX #0 US0_CLK #31 US0_CS #30 US0_CTS #29 US0_RTS #28 US1_TX #1 US1_RX #0 US1_CLK #31 US1_CS #30 US1_CTS #29 US1_RTS #28 LEU0_TX #1 LEU0_RX #0 I2C0_SDA #1 I2C0_SCL #0	CMU_CLK0 #0 PRS_CH6 #1 PRS_CH7 #0 PRS_CH8 #10 PRS_CH9 #9 ACMP0_O #1 ACMP1_O #1 LES_CH9
27	PA2	VDAC0_OUT1ALT / OPA1_OUTALT #1 BUSDY BUSCX OPA0_P	TIM0_CC0 #2 TIM0_CC1 #1 TIM0_CC2 #0 TIM0_CDTI0 #31 TIM0_CDTI1 #30 TIM0_CDTI2 #29 TIM1_CC0 #2 TIM1_CC1 #1 TIM1_CC2 #0 TIM1_CC3 #31 WTIM0_CC0 #2 WTIM0_CC1 #0 LE- TIM0_OUT0 #2 LE- TIM0_OUT1 #1 PCNT0_S0IN #2 PCNT0_S1IN #1	US0_TX #2 US0_RX #1 US0_CLK #0 US0_CS #31 US0_CTS #30 US0_RTS #29 US1_TX #2 US1_RX #1 US1_CLK #0 US1_CS #31 US1_CTS #30 US1_RTS #29 LEU0_TX #2 LEU0_RX #1 I2C0_SDA #2 I2C0_SCL #1	PRS_CH6 #2 PRS_CH7 #1 PRS_CH8 #0 PRS_CH9 #10 ACMP0_O #2 ACMP1_O #2 LES_CH10
28	PA3	BUSCY BUSDX VDAC0_OUT0 / OPA0_OUT	TIM0_CC0 #3 TIM0_CC1 #2 TIM0_CC2 #1 TIM0_CDTI0 #0 TIM0_CDTI1 #31 TIM0_CDTI2 #30 TIM1_CC0 #3 TIM1_CC1 #2 TIM1_CC2 #1 TIM1_CC3 #0 WTIM0_CC0 #3 WTIM0_CC1 #1 LE- TIM0_OUT0 #3 LE- TIM0_OUT1 #2 PCNT0_S0IN #3 PCNT0_S1IN #2	US0_TX #3 US0_RX #2 US0_CLK #1 US0_CS #0 US0_CTS #31 US0_RTS #30 US1_TX #3 US1_RX #2 US1_CLK #1 US1_CS #0 US1_CTS #31 US1_RTS #30 LEU0_TX #3 LEU0_RX #2 I2C0_SDA #3 I2C0_SCL #2	PRS_CH6 #3 PRS_CH7 #2 PRS_CH8 #1 PRS_CH9 #0 ACMP0_O #3 ACMP1_O #3 LES_CH11 GPIO_EM4WU8

Pin		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
29	PA4	VDAC0_OUT1ALT / OPA1_OUTALT #2 BUSDY BUSCX OPA0_N	TIM0_CC0 #4 TIM0_CC1 #3 TIM0_CC2 #2 TIM0_CDTI0 #1 TIM0_CDTI1 #0 TIM0_CDTI2 #31 TIM1_CC0 #4 TIM1_CC1 #3 TIM1_CC2 #2 TIM1_CC3 #1 WTIM0_CC0 #4 WTIM0_CC1 #2 WTIM0_CC2 #0 LE- TIM0_OUT0 #4 LE- TIM0_OUT1 #3 PCNT0_S0IN #4 PCNT0_S1IN #3	US0_TX #4 US0_RX #3 US0_CLK #2 US0_CS #1 US0_CTS #0 US0_RTS #31 US1_TX #4 US1_RX #3 US1_CLK #2 US1_CS #1 US1_CTS #0 US1_RTS #31 LEU0_TX #4 LEU0_RX #3 I2C0_SDA #4 I2C0_SCL #3	PRS_CH6 #4 PRS_CH7 #3 PRS_CH8 #2 PRS_CH9 #1 ACMP0_O #4 ACMP1_O #4 LES_CH12
30	PA5	VDAC0_OUT0ALT / OPA0_OUTALT #0 BUSCY BUSDX	TIM0_CC0 #5 TIM0_CC1 #4 TIM0_CC2 #3 TIM0_CDTI0 #2 TIM0_CDTI1 #1 TIM0_CDTI2 #0 TIM1_CC0 #5 TIM1_CC1 #4 TIM1_CC2 #3 TIM1_CC3 #2 WTIM0_CC0 #5 WTIM0_CC1 #3 WTIM0_CC2 #1 LE- TIM0_OUT0 #5 LE- TIM0_OUT1 #4 PCNT0_S0IN #5 PCNT0_S1IN #4	US0_TX #5 US0_RX #4 US0_CLK #3 US0_CS #2 US0_CTS #1 US0_RTS #0 US1_TX #5 US1_RX #4 US1_CLK #3 US1_CS #2 US1_CTS #1 US1_RTS #0 US2_TX #0 US2_RX #31 US2_CLK #30 US2_CS #29 US2_CTS #28 US2_RTS #27 LEU0_TX #5 LEU0_RX #4 I2C0_SDA #5 I2C0_SCL #4	CMU_CLKI0 #4 PRS_CH6 #5 PRS_CH7 #4 PRS_CH8 #3 PRS_CH9 #2 ACMP0_O #5 ACMP1_O #5 LES_CH13 ETM_TCLK #1
31	PB11	BUSCY BUSDX OPA2_P	TIM0_CC0 #6 TIM0_CC1 #5 TIM0_CC2 #4 TIM0_CDTI0 #3 TIM0_CDTI1 #2 TIM0_CDTI2 #1 TIM1_CC0 #6 TIM1_CC1 #5 TIM1_CC2 #4 TIM1_CC3 #3 WTIM0_CC0 #15 WTIM0_CC1 #13 WTIM0_CC2 #11 WTIM0_CDTI0 #7 WTIM0_CDTI1 #5 WTIM0_CDTI2 #3 LE- TIM0_OUT0 #6 LE- TIM0_OUT1 #5 PCNT0_S0IN #6 PCNT0_S1IN #5	US0_TX #6 US0_RX #5 US0_CLK #4 US0_CS #3 US0_CTS #2 US0_RTS #1 US1_TX #6 US1_RX #5 US1_CLK #4 US1_CS #3 US1_CTS #2 US1_RTS #1 US3_TX #15 US3_RX #14 US3_CLK #13 US3_CS #12 US3_CTS #11 US3_RTS #10 LEU0_TX #6 LEU0_RX #5 I2C0_SDA #6 I2C0_SCL #5	PRS_CH6 #6 PRS_CH7 #5 PRS_CH8 #4 PRS_CH9 #3 ACMP0_O #6 ACMP1_O #6

6.3 Alternate Functionality Overview

A wide selection of alternate functionality is available for multiplexing to various pins. The following table shows the name of the alternate functionality in the first column, followed by columns showing the possible LOCATION bitfield settings.

Note: Some functionality, such as analog interfaces, do not have alternate settings or a LOCATION bitfield. In these cases, the pinout is shown in the column corresponding to LOCATION 0.

Table 6.5. Alternate Functionality Overview

Alternate	LOCATION								
Functionality	0 - 3	4 - 7	8 - 11	12 - 15	16 - 19	20 - 23	24 - 27	28 - 31	Description
ACMP0_O	0: PA0 1: PA1 2: PA2 3: PA3	4: PA4 5: PA5 6: PB11 7: PB12	8: PB13 9: PB14 10: PB15 11: PC6	12: PC7 13: PC8 14: PC9 15: PC10	16: PC11 17: PD9 18: PD10 19: PD11	20: PD12 21: PD13 22: PD14 23: PD15	24: PF0 25: PF1 26: PF2 27: PF3	28: PF4 29: PF5 30: PF6 31: PF7	Analog comparator ACMP0, digital output.
ACMP1_O	0: PA0 1: PA1 2: PA2 3: PA3	4: PA4 5: PA5 6: PB11 7: PB12	8: PB13 9: PB14 10: PB15 11: PC6	12: PC7 13: PC8 14: PC9 15: PC10	16: PC11 17: PD9 18: PD10 19: PD11	20: PD12 21: PD13 22: PD14 23: PD15	24: PF0 25: PF1 26: PF2 27: PF3	28: PF4 29: PF5 30: PF6 31: PF7	Analog comparator ACMP1, digital output.
ADC0_EXTN	0: PA0								Analog to digital converter ADC0 external reference input negative pin.
ADC0_EXTP	0: PA1								Analog to digital converter ADC0 external reference input positive pin.
BOOT_RX	0: PF1								Bootloader RX.
BOOT_TX	0: PF0								Bootloader TX.
CMU_CLK0	0: PA1 1: PB15 2: PC6 3: PC11	4: PD9 5: PD14 6: PF2 7: PF7							Clock Management Unit, clock output number 0.
CMU_CLK1	0: PA0 1: PB14 2: PC7 3: PC10	4: PD10 5: PD15 6: PF3 7: PF6							Clock Management Unit, clock output number 1.
CMU_CLKIO	0: PB13 1: PF7 2: PC6 3: PB6	4: PA5							Clock Management Unit, clock output number IO.

Alternate	LOCATION								
Functionality	0 - 3	4 - 7	8 - 11	12 - 15	16 - 19	20 - 23	24 - 27	28 - 31	Description
LEU0_RX	0: PA1 1: PA2 2: PA3 3: PA4	4: PA5 5: PB11 6: PB12 7: PB13	8: PB14 9: PB15 10: PC6 11: PC7	12: PC8 13: PC9 14: PC10 15: PC11	16: PD9 17: PD10 18: PD11 19: PD12	20: PD13 21: PD14 22: PD15 23: PF0	24: PF1 25: PF2 26: PF3 27: PF4	28: PF5 29: PF6 30: PF7 31: PA0	LEUART0 Receive input.
LEU0_TX	0: PA0 1: PA1 2: PA2 3: PA3	4: PA4 5: PA5 6: PB11 7: PB12	8: PB13 9: PB14 10: PB15 11: PC6	12: PC7 13: PC8 14: PC9 15: PC10	16: PC11 17: PD9 18: PD10 19: PD11	20: PD12 21: PD13 22: PD14 23: PD15	24: PF0 25: PF1 26: PF2 27: PF3	28: PF4 29: PF5 30: PF6 31: PF7	LEUART0 Transmit output. Also used as receive input in half duplex communication.
LFXTAL_N	0: PB14								Low Frequency Crystal (typically 32.768 kHz) negative pin. Also used as an optional external clock input pin.
LFXTAL_P	0: PB15								Low Frequency Crystal (typically 32.768 kHz) positive pin.
OPA0_N	0: PA4								Operational Amplifier 0 external negative input.
OPA0_P	0: PA2								Operational Amplifier 0 external positive input.
OPA1_N	0: PD15								Operational Amplifier 1 external negative input.
OPA1_P	0: PD13								Operational Amplifier 1 external positive input.
OPA2_N	0: PB13								Operational Amplifier 2 external negative input.
OPA2_OUT	0: PB12								Operational Amplifier 2 output.
OPA2_OUTALT	0: PB9 1: PB10								Operational Amplifier 2 alternative output.
OPA2_P	0: PB11								Operational Amplifier 2 external positive input.

Alternate	LOCATION									
Functionality	0 - 3	4 - 7	8 - 11	12 - 15	16 - 19	20 - 23	24 - 27	28 - 31	Description	
US3_CLK	0: PD10 1: PD11 2: PD12 3: PD13	4: PD14 5: PD15 6: PI2 7: PI3	8: PB6 9: PB7 10: PB8 11: PB9	12: PB10 13: PB11 14: PJ14 15: PJ15	16: PC0 17: PC1 18: PC2 19: PC3	20: PC4 21: PC5 22: PF11 23: PF12	24: PF13 25: PF14 26: PF15 27: PK0	28: PK1 29: PK2 30: PD8 31: PD9	USART3 clock input / output.	
US3_CS	0: PD11 1: PD12 2: PD13 3: PD14	4: PD15 5: PI2 6: PI3 7: PB6	8: PB7 9: PB8 10: PB9 11: PB10	12: PB11 13: PJ14 14: PJ15 15: PC0	16: PC1 17: PC2 18: PC3 19: PC4	20: PC5 21: PF11 22: PF12 23: PF13	24: PF14 25: PF15 26: PK0 27: PK1	28: PK2 29: PD8 30: PD9 31: PD10	USART3 chip select input / output.	
US3_CTS	0: PD12 1: PD13 2: PD14 3: PD15	4: PI2 5: PI3 6: PB6 7: PB7	8: PB8 9: PB9 10: PB10 11: PB11	12: PJ14 13: PJ15 14: PC0 15: PC1	16: PC2 17: PC3 18: PC4 19: PC5	20: PF11 21: PF12 22: PF13 23: PF14	24: PF15 25: PK0 26: PK1 27: PK2	28: PD8 29: PD9 30: PD10 31: PD11	USART3 Clear To Send hardware flow control input.	
US3_RTS	0: PD13 1: PD14 2: PD15 3: PI2	4: PI3 5: PB6 6: PB7 7: PB8	8: PB9 9: PB10 10: PB11 11: PJ14	12: PJ15 13: PC0 14: PC1 15: PC2	16: PC3 17: PC4 18: PC5 19: PF11	20: PF12 21: PF13 22: PF14 23: PF15	24: PK0 25: PK1 26: PK2 27: PD8	28: PD9 29: PD10 30: PD11 31: PD12	USART3 Request To Send hardware flow control output.	
US3_RX	0: PD9 1: PD10 2: PD11 3: PD12	4: PD13 5: PD14 6: PD15 7: PI2	8: PI3 9: PB6 10: PB7 11: PB8	12: PB9 13: PB10 14: PB11 15: PJ14	16: PJ15 17: PC0 18: PC1 19: PC2	20: PC3 21: PC4 22: PC5 23: PF11	24: PF12 25: PF13 26: PF14 27: PF15	28: PK0 29: PK1 30: PK2 31: PD8	USART3 Asynchronous Receive. USART3 Synchronous mode Master Input / Slave Output (MISO).	
US3_TX	0: PD8 1: PD9 2: PD10 3: PD11	4: PD12 5: PD13 6: PD14 7: PD15	8: PI2 9: PI3 10: PB6 11: PB7	12: PB8 13: PB9 14: PB10 15: PB11	16: PJ14 17: PJ15 18: PC0 19: PC1	20: PC2 21: PC3 22: PC4 23: PC5	24: PF11 25: PF12 26: PF13 27: PF14	28: PF15 29: PK0 30: PK1 31: PK2	USART3 Asynchronous Transmit. Also used as receive input in half duplex communication. USART3 Synchronous mode Master Output / Slave Input (MOSI).	
VDAC0_EXT	0: PA1								Digital to analog converter VDAC0 external reference input pin.	
VDAC0_OUT0 / OPA0_OUT	0: PA3								Digital to Analog Converter DAC0 output channel number 0.	
VDAC0_OUT0ALT / OPA0_OUT-ALT	0: PA5 1: PD13 2: PD15								Digital to Analog Converter DAC0 alternative output for channel 0.	
VDAC0_OUT1 / OPA1_OUT	0: PD14								Digital to Analog Converter DAC0 output channel number 1.	
VDAC0_OUT1ALT / OPA1_OUT-ALT	0: PD12 1: PA2 2: PA4								Digital to Analog Converter DAC0 alternative output for channel 1.	

Table 6.8. ADC0 Bus and Pin Mapping

APORT4Y	APORT4X	APORT3Y	APORT3X	APORT2Y	APORT2X	APORT1Y	APORT1X	APORT0Y	APORT0X	Port
BUSDY	BUSDX	BUSCY	BUSCX	BUSBY	BUSBX	BUSA Y	BUSA X	BUSADC0 Y	BUSADC0 X	Bus
PB15	PB15			PF15	PF15					CH31
PB14	PB13	PB13	PB14	PF14		PF14				CH30
PB12	PB11	PB11	PB12	PF12		PF13				CH29
PB10	PB9	PB9	PB10	PF10		PF11				CH28
PB8	PB7	PB7	PB8	PF8		PF9				CH27
PB6			PB6	PF6		PF7				CH26
				PF4		PF5				CH25
				PF2		PF3				CH24
				PF0		PF1				CH23
						PF6				CH22
						PF5				CH21
						PF4				CH20
						PF3				CH19
						PF2				CH18
						PF1				CH17
						PF0				CH16
										CH15
PA6	PA5	PA5	PA6							CH14
PA4	PA3	PA3	PA4							CH13
PA2	PA1	PA1	PA2	PC10		PC11				CH12
PA0	PD15	PD15	PA0	PC8		PC9				CH11
PD14	PD13	PD13	PD14	PC6		PC7				CH10
PD12	PD11	PD11	PD12	PC4		PC5				CH9
PD10	PD9	PD9	PD10	PC2		PC3				CH8
PD8			PD8	PC0		PC1				CH7
						PC0				CH6
										CH5
										CH4
										CH3
										CH2
										CH1
										CH0

APORT4Y	APORT3Y	APORT2Y	APORT1Y	APORT1X	APORT3X	APORT2X	APORT1X	APORT4Y	APORT3Y	APORT2Y	APORT1Y	Port
BUSDY	BUSCY	BUSBY	BUSAY	BUSDX	BUSCX	BUSBX	BUSAX	BUSDY	BUSCY	BUSBY	BUSAY	Bus
PB15		PF15		PB15		PF15		PB15		PF15		CH31
PB14		PF14		PB14		PF14		PB14		PF14		CH30
PB13		PF13		PB13		PF13		PB13		PF13		CH29
PB12		PF12		PB12		PF12		PB12		PF12		CH28
PB11		PF11		PB11		PF11		PB11		PF11		CH27
PB10		PF10		PB10		PF10		PB10		PF10		CH26
PB9		PF9		PB9		PF9		PB9		PF9		CH25
PB8		PF8		PB8		PF8		PB8		PF8		CH24
PB7		PF7		PB7		PF7		PB7		PF7		CH23
PB6		PF6		PB6		PF6		PB6		PF6		CH22
		PF5				PF5				PF5		CH21
		PF4				PF4				PF4		CH20
		PF3				PF3				PF3		CH19
		PF2				PF2				PF2		CH18
		PF1				PF1				PF1		CH17
		PF0				PF0				PF0		CH16
		PA7				PA7				PA7		CH15
PA6		PA5				PA6				PA6		CH14
PA4		PA3				PA4				PA5		CH13
PA2		PC10				PA3	PC11			PA4		CH12
PA1		PC9				PA2	PC10			PA3		CH11
PA0		PC8				PA1	PC9			PA2		CH10
PD14		PC6				PD15	PC7			PA1		CH9
PD13		PC5					PD14	PC6		PA0		CH8
PD12		PC4						PD13	PC5		PC8	CH7
PD11		PC3							PD12	PC4		CH6
PD10		PC2								PD11	PC3	CH5
PD9		PC1									PD10	CH4
PD8		PC0										CH3
												CH2
												CH1
												CH0

8. QFN48 Package Specifications

8.1 QFN48 Package Dimensions

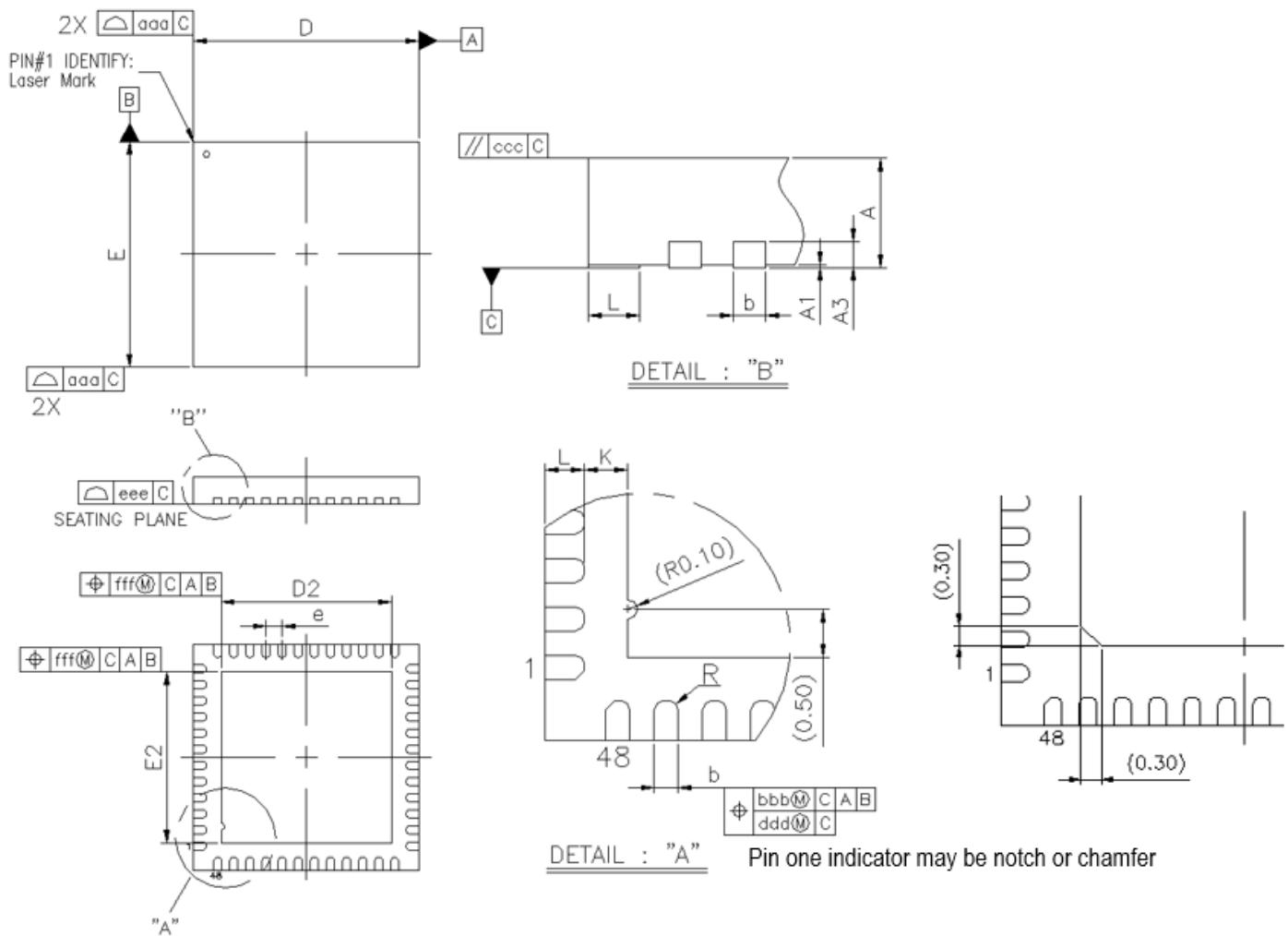


Figure 8.1. QFN48 Package Drawing

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