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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	20MHz
Connectivity	-
Peripherals	Brown-out Detect/Reset, POR, WDT
Number of I/O	12
Program Memory Size	1.75KB (1K x 14)
Program Memory Type	FLASH
EEPROM Size	128 x 8
RAM Size	64 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Through Hole
Package / Case	14-DIP (0.300", 7.62mm)
Supplier Device Package	14-PDIP
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic16f630-i-p">https://www.e-xfl.com/product-detail/microchip-technology/pic16f630-i-p</a>

# PIC16F630/676

**TABLE 1-1: PIC16F630/676 PINOUT DESCRIPTION**

Name	Function	Input Type	Output Type	Description
RA0/AN0/CIN+/ICSPDAT	RA0	TTL	CMOS	Bidirectional I/O w/ programmable pull-up and interrupt-on-change.
	AN0	AN	—	A/D Channel 0 input.
	CIN+	AN	—	Comparator input.
	ICSPDAT	TTL	CMOS	Serial Programming Data I/O.
RA1/AN1/CIN-/VREF/ICSPCLK	RA1	TTL	CMOS	Bidirectional I/O w/ programmable pull-up and interrupt-on-change.
	AN1	AN	—	A/D Channel 1 input.
	CIN-	AN	—	Comparator input.
	VREF	AN	—	External Voltage reference.
RA2/AN2/COU/T0CKI/INT	RA2	ST	CMOS	Bidirectional I/O w/ programmable pull-up and interrupt-on-change.
	AN2	AN	—	A/D Channel 2 input.
	COU	—	CMOS	Comparator output.
	T0CKI	ST	—	Timer0 clock input.
RA3/MCLR/VPP	INT	ST	—	External Interrupt.
	RA3	TTL	—	Input port with interrupt-on-change.
	MCLR	ST	—	Master Clear.
RA4/T1G/AN3/OSC2/CLKOUT	VPP	HV	—	Programming voltage.
	RA4	TTL	CMOS	Bidirectional I/O w/ programmable pull-up and interrupt-on-change.
	T1G	ST	—	Timer1 gate.
	AN3	AN3	—	A/D Channel 3 input.
RA5/T1CKI/OSC1/CLKIN	OSC2	—	XTAL	Crystal/Resonator.
	CLKOUT	—	CMOS	Fosc/4 output.
	RA5	TTL	CMOS	Bidirectional I/O w/ programmable pull-up and interrupt-on-change.
	T1CKI	ST	—	Timer1 clock.
RC0/AN4	OSC1	XTAL	—	Crystal/Resonator.
	CLKIN	ST	—	External clock input/RC oscillator connection.
RC1/AN5	RC0	TTL	CMOS	Bidirectional I/O.
	AN4	AN4	—	A/D Channel 4 input.
RC2/AN6	RC1	TTL	CMOS	Bidirectional I/O.
	AN5	AN5	—	A/D Channel 5 input.
RC3/AN7	RC2	TTL	CMOS	Bidirectional I/O.
	AN6	AN6	—	A/D Channel 6 input.
RC4	RC3	TTL	CMOS	Bidirectional I/O.
	AN7	AN7	—	A/D Channel 7 input.
RC5	RC4	TTL	CMOS	Bidirectional I/O.
VSS	RC5	TTL	CMOS	Bidirectional I/O.
VDD	VSS	Power	—	Ground reference.
	VDD	Power	—	Positive supply.

**Legend:** Shade = PIC16F676 only  
TTL = TTL input buffer  
ST = Schmitt Trigger input buffer

# PIC16F630/676

## 2.2.2.2 OPTION Register

The OPTION register is a readable and writable register, which contains various control bits to configure:

- TMR0/WDT prescaler
- External RA2/INT interrupt
- TMR0
- Weak pull-ups on PORTA

**Note:** To achieve a 1:1 prescaler assignment for TMR0, assign the prescaler to the WDT by setting PSA bit to '1' (OPTION<3>). See **Section 4.4 "Prescaler"**.

### REGISTER 2-2: OPTION\_REG — OPTION REGISTER (ADDRESS: 81h)

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
RAPU	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0
bit 7							bit 0

- bit 7 **RAPU:** PORTA Pull-up Enable bit  
1 = PORTA pull-ups are disabled  
0 = PORTA pull-ups are enabled by individual PORT latch values
- bit 6 **INTEDG:** Interrupt Edge Select bit  
1 = Interrupt on rising edge of RA2/INT pin  
0 = Interrupt on falling edge of RA2/INT pin
- bit 5 **T0CS:** TMR0 Clock Source Select bit  
1 = Transition on RA2/T0CKI pin  
0 = Internal instruction cycle clock (CLKOUT)
- bit 4 **T0SE:** TMR0 Source Edge Select bit  
1 = Increment on high-to-low transition on RA2/T0CKI pin  
0 = Increment on low-to-high transition on RA2/T0CKI pin
- bit 3 **PSA:** Prescaler Assignment bit  
1 = Prescaler is assigned to the WDT  
0 = Prescaler is assigned to the Timer0 module
- bit 2-0 **PS2:PS0:** Prescaler Rate Select bits

Bit Value	TMR0 Rate	WDT Rate
000	1 : 2	1 : 1
001	1 : 4	1 : 2
010	1 : 8	1 : 4
011	1 : 16	1 : 8
100	1 : 32	1 : 16
101	1 : 64	1 : 32
110	1 : 128	1 : 64
111	1 : 256	1 : 128

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

- n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

\_\_\_\_\_

Each PORTA pin is multiplexed with other functions. The pins and their combined functions are briefly described here. For specific information about individual functions such as the comparator or the A/D, refer to the appropriate section in this Data Sheet.

Figure 3-1 shows the diagram for this pin. The RA0 pin is configurable to function as one of the following:

- ### 3.2.3.2 RA1/AN1/CIN-/VREF

Figure 3-1 shows the diagram for this pin. The RA1 pin is configurable to function as one of the following:

- as a general purpose I/O
- an analog input for the A/D (PIC16F676 only)
- an analog input to the comparator
- a voltage reference input for the A/D (PIC16F676 only)

[illegible]

# PIC16F630/676

## REGISTER 5-1: T1CON — TIMER1 CONTROL REGISTER (ADDRESS: 10h)

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	TMR1GE	T1CKPS1	T1CKPS0	T1OSCEN	T1SYNC	TMR1CS	TMR1ON
bit 7							bit 0

- bit 7 **Unimplemented:** Read as '0'
- bit 6 **TMR1GE:** Timer1 Gate Enable bit  
If TMR1ON = 0:  
 This bit is ignored  
If TMR1ON = 1:  
 1 = Timer1 is on if T1G pin is low  
 0 = Timer1 is on
- bit 5-4 **T1CKPS1:T1CKPS0:** Timer1 Input Clock Prescale Select bits  
 11 = 1:8 Prescale Value  
 10 = 1:4 Prescale Value  
 01 = 1:2 Prescale Value  
 00 = 1:1 Prescale Value
- bit 3 **T1OSCEN:** LP Oscillator Enable Control bit  
If INTOSC without CLKOUT oscillator is active:  
 1 = LP oscillator is enabled for Timer1 clock  
 0 = LP oscillator is off  
Else:  
 This bit is ignored
- bit 2 **T1SYNC:** Timer1 External Clock Input Synchronization Control bit  
TMR1CS = 1:  
 1 = Do not synchronize external clock input  
 0 = Synchronize external clock input  
TMR1CS = 0:  
 This bit is ignored. Timer1 uses the internal clock.
- bit 1 **TMR1CS:** Timer1 Clock Source Select bit  
 1 = External clock from T1OSO/T1CKI pin (on the rising edge)  
 0 = Internal clock (Fosc/4)
- bit 0 **TMR1ON:** Timer1 On bit  
 1 = Enables Timer1  
 0 = Stops Timer1

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
- n = Value at POR	'1' = Bit is set	'0' = Bit is cleared    x = Bit is unknown

6.1 Comparator Operation

A single comparator is shown in Figure 6-1, along with the relationship between the analog input levels and the digital output. When the analog input at VIN+ is less than the analog input VIN-, the output of the comparator is a digital low level. When the analog input at VIN+ is greater than the analog input VIN-, the output of the comparator is a digital high level. The shaded areas of the output of the comparator in Figure 6-1 represent the uncertainty due to input offsets and response time.

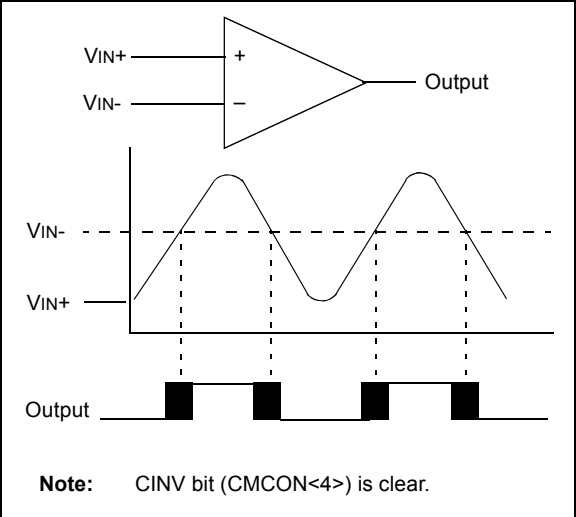
**Note:** To use CIN+ and CIN- pins as analog inputs, the appropriate bits must be programmed in the CMCON (19h) register.

The polarity of the comparator output can be inverted by setting the CINV bit (CMCON<4>). Clearing CINV results in a non-inverted output. A complete table showing the output state versus input conditions and the polarity bit is shown in Table 6-1.

TABLE 6-1: OUTPUT STATE VS. INPUT CONDITIONS

Input Conditions	CINV	COUT
VIN- > VIN+	0	0
VIN- < VIN+	0	1
VIN- > VIN+	1	1
VIN- < VIN+	1	0

FIGURE 6-1: SINGLE COMPARATOR



# PIC16F630/676

REGISTER 7-3:   **ANSEL — ANALOG SELECT REGISTER (ADDRESS: 91h) (PIC16F676 ONLY)**

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
ANS7	ANS6	ANS5	ANS4	ANS3	ANS2	ANS1	ANS0
bit 7				bit 0			

bit 7-0:   **ANS<7:0>**: Analog Select between analog or digital function on pins AN<7:0>, respectively.  
1 = Analog input. Pin is assigned as analog input.<sup>(1)</sup>  
0 = Digital I/O. Pin is assigned to port or special function.

**Note 1:** Setting a pin to an analog input automatically disables the digital input circuitry, weak pull-ups, and interrupt-on-change if available. The corresponding TRIS bit must be set to Input mode in order to allow external control of the voltage on the pin.

<b>Legend:</b>			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
- n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

# PIC16F630/676

## 9.1 Configuration Bits

The Configuration bits can be programmed (read as '0'), or left unprogrammed (read as '1') to select various device configurations, as shown in Register 9-1. These bits are mapped in program memory location 2007h.

**Note:** Address 2007h is beyond the user program memory space. It belongs to the special configuration memory space (2000h-3FFFh), which can be accessed only during programming. See PIC16F630/676 Programming Specification for more information.

**REGISTER 9-1: CONFIG — CONFIGURATION WORD (ADDRESS: 2007h)**

R/P-1	R/P-1	U-0	U-0	U-0	R/P-1	R/P-1	R/P-1	R/P-1	R/P-1	R/P-1	R/P-1	R/P-1	R/P-1	R/P-1
BG1	BG0	—	—	—	CPD	CP	BODEN	MCLRE	PWRT	WDTE	FOSC2	FOSC1	FOSC0	
bit 13														bit 0

bit 13-12 **BG1:BG0:** Bandgap Calibration bits for BOD and POR voltage<sup>(1)</sup>

00 = Lowest bandgap voltage  
11 = Highest bandgap voltage

bit 11-9 **Unimplemented:** Read as '0'

bit 8 **CPD:** Data Code Protection bit<sup>(2)</sup>

1 = Data memory code protection is disabled  
0 = Data memory code protection is enabled

bit 7 **CP:** Code Protection bit<sup>(3)</sup>

1 = Program Memory code protection is disabled  
0 = Program Memory code protection is enabled

bit 6 **BODEN:** Brown-out Detect Enable bit<sup>(4)</sup>

1 = BOD enabled  
0 = BOD disabled

bit 5 **MCLRE:** RA3/MCLR pin function select bit<sup>(5)</sup>

1 = RA3/MCLR pin function is MCLR  
0 = RA3/MCLR pin function is digital I/O, MCLR internally tied to VDD

bit 4 **PWRT:** Power-up Timer Enable bit

1 = PWRT disabled  
0 = PWRT enabled

bit 3 **WDTE:** Watchdog Timer Enable bit

1 = WDT enabled  
0 = WDT disabled

bit 2-0 **FOSC2:FOSC0:** Oscillator Selection bits

111 = RC oscillator: CLKOUT function on RA4/OSC2/CLKOUT pin, RC on RA5/OSC1/CLKIN  
110 = RC oscillator: I/O function on RA4/OSC2/CLKOUT pin, RC on RA5/OSC1/CLKIN  
101 = INTOSC oscillator: CLKOUT function on RA4/OSC2/CLKOUT pin, I/O function on RA5/OSC1/CLKIN  
100 = INTOSC oscillator: I/O function on RA4/OSC2/CLKOUT pin, I/O function on RA5/OSC1/CLKIN  
011 = EC: I/O function on RA4/OSC2/CLKOUT pin, CLKIN on RA5/OSC1/CLKIN  
010 = HS oscillator: High speed crystal/resonator on RA4/OSC2/CLKOUT and RA5/OSC1/CLKIN  
001 = XT oscillator: Crystal/resonator on RA4/OSC2/CLKOUT and RA5/OSC1/CLKIN  
000 = LP oscillator: Low power crystal on RA4/OSC2/CLKOUT and RA5/OSC1/CLKIN

**Note 1:** The Bandgap Calibration bits are factory programmed and must be read and saved prior to erasing the device as specified in the PIC16F630/676 Programming Specification. These bits are reflected in an export of the Configuration Word. Microchip Development Tools maintain all calibration bits to factory settings.

**2:** The entire data EEPROM will be erased when the code protection is turned off.

**3:** The entire program memory will be erased, including OSCCAL value, when the code protection is turned off.

**4:** Enabling Brown-out Detect does not automatically enable Power-up Timer.

**5:** When MCLR is asserted in INTOSC or RC mode, the internal clock oscillator is disabled.

### Legend:

P = Programmed using ICSP™

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

1 = bit is set

0 = bit is cleared

x = bit is unknown



## 9.3 Reset

The PIC16F630/676 differentiates between various kinds of Reset:

- Power-on Reset (POR)
- WDT Reset during normal operation
- WDT Reset during Sleep
- $\overline{\text{MCLR}}$  Reset during normal operation
- $\overline{\text{MCLR}}$  Reset during Sleep
- Brown-out Detect (BOD)

Some registers are not affected in any Reset condition; their status is unknown on POR and unchanged in any other Reset. Most other registers are reset to a "Reset state" on:

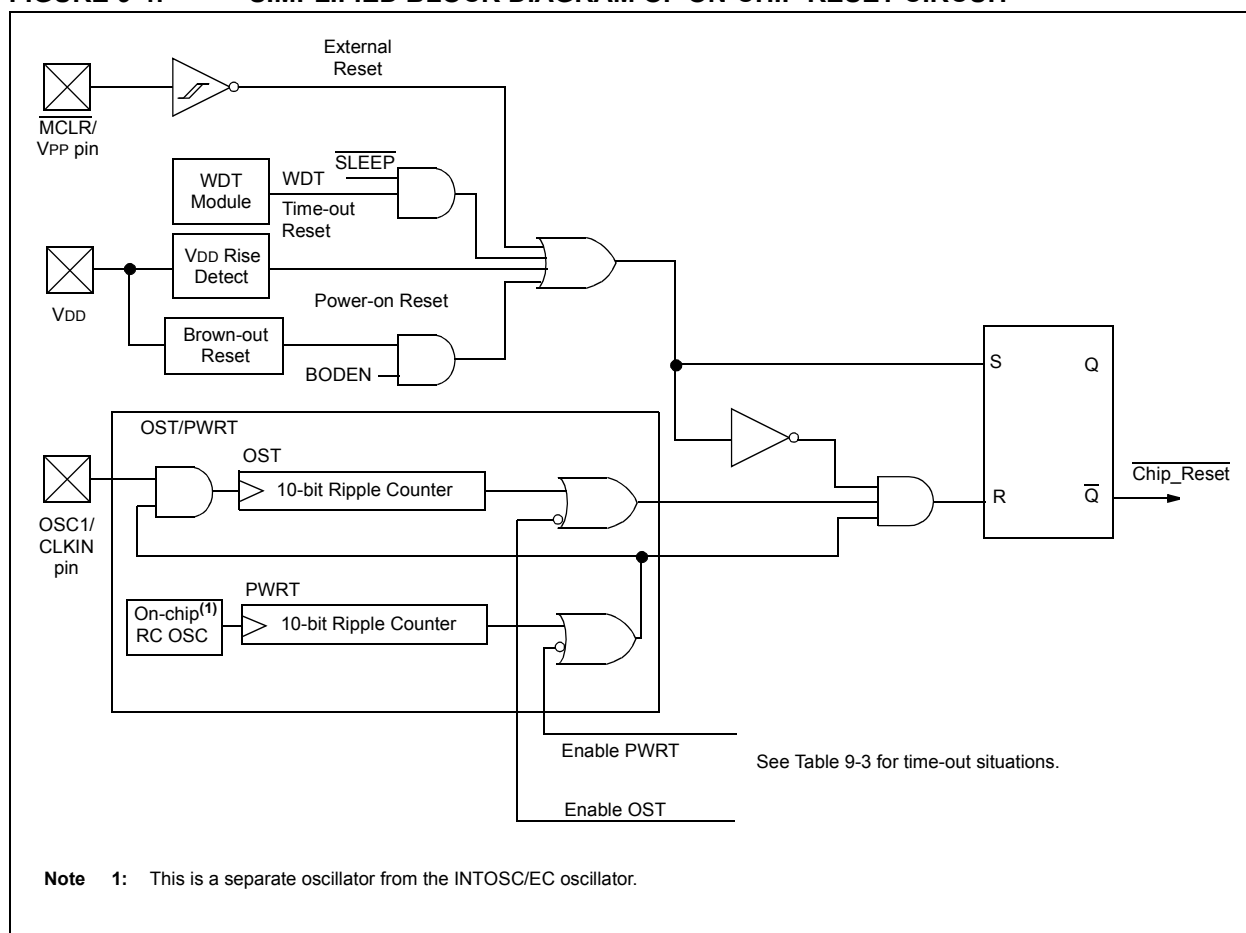
- Power-on Reset
- $\overline{\text{MCLR}}$  Reset
- WDT Reset
- WDT Reset during Sleep
- Brown-out Detect (BOD)

They are not affected by a WDT wake-up, since this is viewed as the resumption of normal operation.  $\overline{\text{TO}}$  and  $\overline{\text{PD}}$  bits are set or cleared differently in different Reset situations as indicated in Table 9-4. These bits are used in software to determine the nature of the Reset. See Table 9-7 for a full description of Reset states of all registers.

A simplified block diagram of the On-Chip Reset Circuit is shown in Figure 9-4.

The  $\overline{\text{MCLR}}$  Reset path has a noise filter to detect and ignore small pulses. See Table 12-4 in Electrical Specifications Section for pulse-width specification.

**FIGURE 9-4: SIMPLIFIED BLOCK DIAGRAM OF ON-CHIP RESET CIRCUIT**



## 9.3.5 BROWN-OUT DETECT (BOD)

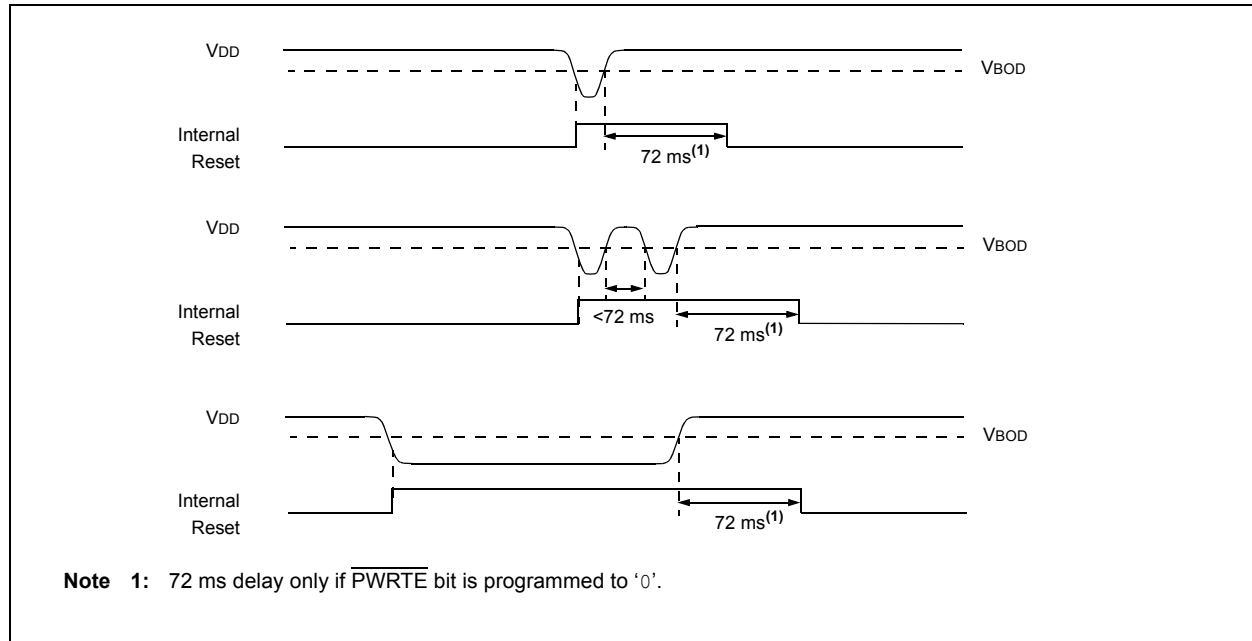
The PIC16F630/676 members have on-chip Brown-out Detect circuitry. A Configuration bit, BODEN, can disable (if clear/programmed) or enable (if set) the Brown-out Detect circuitry. If VDD falls below VBOD for greater than parameter (TBOD) in Table 12-4 (see **Section 12.0 “Electrical Specifications”**), the Brown-out situation will reset the device. This will occur regardless of VDD slew-rate. A Reset is not guaranteed to occur if VDD falls below VBOD for less than parameter (TBOD).

On any Reset (Power-on, Brown-out Detect, Watchdog, etc.), the chip will remain in Reset until VDD rises above BVDD (see Figure 9-6). The Power-up Timer will now be invoked, if enabled, and will keep the chip in Reset an additional 72 ms.

**Note:** A Brown-out Detect does not enable the Power-up Timer if the PWRTE bit in the Configuration Word is set.

If VDD drops below BVDD while the Power-up Timer is running, the chip will go back into a Brown-out Detect and the Power-up Timer will be re-initialized. Once VDD rises above BVDD, the Power-up Timer will execute a 72 ms Reset.

**FIGURE 9-6: BROWN-OUT SITUATIONS**



## 9.3.6 TIME-OUT SEQUENCE

On power-up, the time-out sequence is as follows: first, PWRT time-out is invoked after POR has expired. Then, OST is activated. The total time-out will vary based on oscillator configuration and PWRTE bit status. For example, in EC mode with PWRTE bit erased (PWRT disabled), there will be no time-out at all. Figure 9-7, Figure 9-8 and Figure 9-9 depict time-out sequences.

Since the time-outs occur from the POR pulse, if MCLR is kept low long enough, the time-outs will expire. Then bringing MCLR high will begin execution immediately (see Figure 9-8). This is useful for testing purposes or to synchronize more than one PIC16F630/676 device operating in parallel.

Table 9-6 shows the Reset conditions for some special registers, while Table 9-7 shows the Reset conditions for all the registers.

## 9.3.7 POWER CONTROL (PCON) STATUS REGISTER

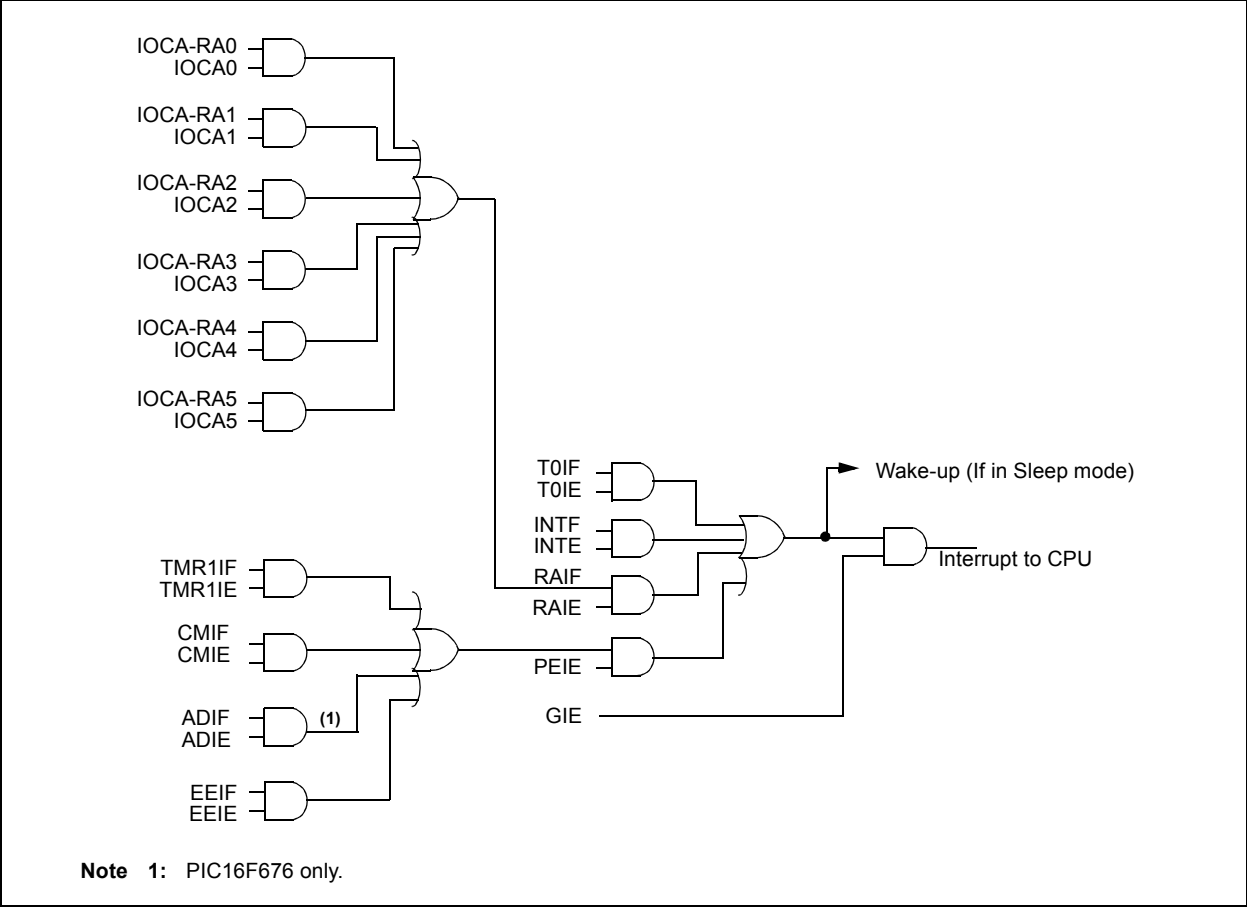
The power CONTROL/STATUS register, PCON (address 8Eh) has two bits.

Bit 0 is BOD (Brown-out). BOD is unknown on Power-on Reset. It must then be set by the user and checked on subsequent Resets to see if BOD = 0, indicating that a brown-out has occurred. The BOD Status bit is a “don’t care” and is not necessarily predictable if the brown-out circuit is disabled (by setting BODEN bit = 0 in the Configuration Word).

Bit 1 is POR (Power-on Reset). It is a ‘0’ on Power-on Reset and unaffected otherwise. The user must write a ‘1’ to this bit following a Power-on Reset. On a subsequent Reset, if POR is ‘0’, it will indicate that a Power-on Reset must have occurred (i.e., VDD may have gone too low).

# PIC16F630/676

FIGURE 9-10: INTERRUPT LOGIC



## DECFSZ      Decrement f, Skip if 0

**Syntax:**      `[label] DECFSZ f,d`

**Operands:**       $0 \leq f \leq 127$   
 $d \in [0,1]$

**Operation:**       $(f) - 1 \rightarrow (\text{destination});$   
skip if result = 0

**Status Affected:**      None

**Description:**      The contents of register 'f' are decremented. If 'd' is 0, the result is placed in the W register. If 'd' is 1, the result is placed back in register 'f'.  
If the result is 1, the next instruction is executed. If the result is 0, then a NOP is executed instead, making it a 2-cycle instruction.

## INCFSZ      Increment f, Skip if 0

**Syntax:**      `[label] INCFSZ f,d`

**Operands:**       $0 \leq f \leq 127$   
 $d \in [0,1]$

**Operation:**       $(f) + 1 \rightarrow (\text{destination}),$   
skip if result = 0

**Status Affected:**      None

**Description:**      The contents of register 'f' are incremented. If 'd' is 0, the result is placed in the W register. If 'd' is 1, the result is placed back in register 'f'.  
If the result is 1, the next instruction is executed. If the result is 0, a NOP is executed instead, making it a 2-cycle instruction.

## GOTO      Unconditional Branch

**Syntax:**      `[label] GOTO k`

**Operands:**       $0 \leq k \leq 2047$

**Operation:**       $k \rightarrow \text{PC}<10:0>$   
 $\text{PCLATH}<4:3> \rightarrow \text{PC}<12:11>$

**Status Affected:**      None

**Description:**      GOTO is an unconditional branch. The eleven-bit immediate value is loaded into PC bits <10:0>. The upper bits of PC are loaded from PCLATH<4:3>. GOTO is a two-cycle instruction.

## IORLW      Inclusive OR Literal with W

**Syntax:**      `[label] IORLW k`

**Operands:**       $0 \leq k \leq 255$

**Operation:**       $(W) .\text{OR. } k \rightarrow (W)$

**Status Affected:**      Z

**Description:**      The contents of the W register are OR'ed with the eight-bit literal 'k'. The result is placed in the W register.

## INCF      Increment f

**Syntax:**      `[label] INCF f,d`

**Operands:**       $0 \leq f \leq 127$   
 $d \in [0,1]$

**Operation:**       $(f) + 1 \rightarrow (\text{destination})$

**Status Affected:**      Z

**Description:**      The contents of register 'f' are incremented. If 'd' is 0, the result is placed in the W register. If 'd' is 1, the result is placed back in register 'f'.

## IORWF      Inclusive OR W with f

**Syntax:**      `[label] IORWF f,d`

**Operands:**       $0 \leq f \leq 127$   
 $d \in [0,1]$

**Operation:**       $(W) .\text{OR. } (f) \rightarrow (\text{destination})$

**Status Affected:**      Z

**Description:**      Inclusive OR the W register with register 'f'. If 'd' is 0, the result is placed in the W register. If 'd' is 1, the result is placed back in register 'f'.

## 11.11 PICKit 2 Development Programmer/Debugger and PICKit 2 Debug Express

The PICKit™ 2 Development Programmer/Debugger is a low-cost development tool with an easy to use interface for programming and debugging Microchip's Flash families of microcontrollers. The full featured Windows® programming interface supports baseline (PIC10F, PIC12F5xx, PIC16F5xx), midrange (PIC12F6xx, PIC16F), PIC18F, PIC24, dsPIC30, dsPIC33, and PIC32 families of 8-bit, 16-bit, and 32-bit microcontrollers, and many Microchip Serial EEPROM products. With Microchip's powerful MPLAB Integrated Development Environment (IDE) the PICKit™ 2 enables in-circuit debugging on most PIC® microcontrollers. In-Circuit-Debugging runs, halts and single steps the program while the PIC microcontroller is embedded in the application. When halted at a breakpoint, the file registers can be examined and modified.

The PICKit 2 Debug Express include the PICKit 2, demo board and microcontroller, hookup cables and CDROM with user's guide, lessons, tutorial, compiler and MPLAB IDE software.

## 11.12 MPLAB PM3 Device Programmer

The MPLAB PM3 Device Programmer is a universal, CE compliant device programmer with programmable voltage verification at VDDMIN and VDDMAX for maximum reliability. It features a large LCD display (128 x 64) for menus and error messages and a modular, detachable socket assembly to support various package types. The ICSP™ cable assembly is included as a standard item. In Stand-Alone mode, the MPLAB PM3 Device Programmer can read, verify and program PIC devices without a PC connection. It can also set code protection in this mode. The MPLAB PM3 connects to the host PC via an RS-232 or USB cable. The MPLAB PM3 has high-speed communications and optimized algorithms for quick programming of large memory devices and incorporates an MMC card for file storage and data applications.

## 11.13 Demonstration/Development Boards, Evaluation Kits, and Starter Kits

A wide variety of demonstration, development and evaluation boards for various PIC MCUs and dsPIC DSCs allows quick application development on fully functional systems. Most boards include prototyping areas for adding custom circuitry and provide application firmware and source code for examination and modification.

The boards support a variety of features, including LEDs, temperature sensors, switches, speakers, RS-232 interfaces, LCD displays, potentiometers and additional EEPROM memory.

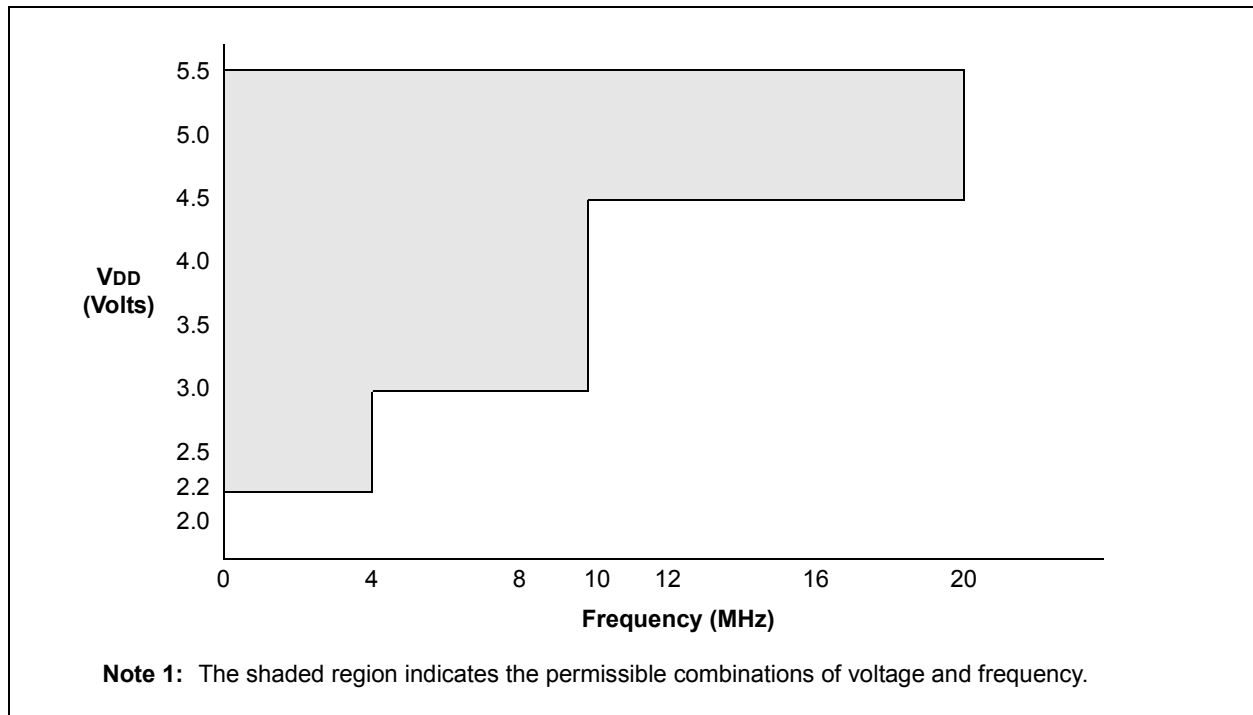
The demonstration and development boards can be used in teaching environments, for prototyping custom circuits and for learning about various microcontroller applications.

In addition to the PICDEM™ and dsPICDEM™ demonstration/development board series of circuits, Microchip has a line of evaluation kits and demonstration software for analog filter design, KEELOQ® security ICs, CAN, IrDA®, PowerSmart battery management, SEEVAL® evaluation system, Sigma-Delta ADC, flow rate sensing, plus many more.

Also available are starter kits that contain everything needed to experience the specified device. This usually includes a single application and debug capability, all on one board.

Check the Microchip web page ([www.microchip.com](http://www.microchip.com)) for the complete list of demonstration, development and evaluation kits.

**FIGURE 12-3: PIC16F676 WITH A/D ENABLED VOLTAGE-FREQUENCY GRAPH,  
 $0^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$**



# PIC16F630/676

## 12.1 DC Characteristics: PIC16F630/676-I (Industrial), PIC16F630/676-E (Extended)

DC CHARACTERISTICS			Standard Operating Conditions (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for industrial -40°C ≤ TA ≤ +125°C for extended				
Param No.	Sym	Characteristic	Min	Typ†	Max	Units	Conditions
D001 D001A D001B D001C D001D	VDD	Supply Voltage	2.0 2.2 2.5 3.0 4.5	— — — — —	5.5 5.5 5.5 5.5 5.5	V V V V V	FOSC ≤ 4 MHz: PIC16F630/676 with A/D off PIC16F676 with A/D on, 0°C to +125°C PIC16F676 with A/D on, -40°C to +125°C 4 MHz < FOSC ≤ 10 MHz
D002	VDR	RAM Data Retention Voltage <sup>(1)</sup>	1.5*	—	—	V	Device in Sleep mode
D003	VPOR	VDD Start Voltage to ensure internal Power-on Reset signal	—	VSS	—	V	See section on Power-on Reset for details
D004	SVDD	VDD Rise Rate to ensure internal Power-on Reset signal	0.05*	—	—	V/ms	See section on Power-on Reset for details
D005	VBOD		—	2.1	—	V	

\* These parameters are characterized but not tested.

† Data in "Typ" column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

**Note 1:** This is the limit to which VDD can be lowered in Sleep mode without losing RAM data.

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**TABLE 12-6: COMPARATOR SPECIFICATIONS**

Comparator Specifications		Standard Operating Conditions -40°C to +125°C (unless otherwise stated)				
Sym	Characteristics	Min	Typ	Max	Units	Comments
VOS	Input Offset Voltage	—	± 5.0	± 10	mV	
VCM	Input Common Mode Voltage	0	—	VDD - 1.5	V	
CMRR	Common Mode Rejection Ratio	+55*	—	—	db	
TRT	Response Time <sup>(1)</sup>	—	150	400*	ns	
TMC2COV	Comparator Mode Change to Output Valid	—	—	10*	µs	

\* These parameters are characterized but not tested.

**Note 1:** Response time measured with one comparator input at (VDD - 1.5)/2 while the other input transitions from VSS to VDD - 1.5V.

**TABLE 12-7: COMPARATOR VOLTAGE REFERENCE SPECIFICATIONS**

Voltage Reference Specifications		Standard Operating Conditions -40°C to +125°C (unless otherwise stated)				
Sym	Characteristics	Min	Typ	Max	Units	Comments
	Resolution	—	VDD/24*	—	LSb	Low Range (VRR = 1)
		—	VDD/32	—	LSb	High Range (VRR = 0)
	Absolute Accuracy	—	—	± 1/2*	LSb	Low Range (VRR = 1)
		—	—	± 1/2*	LSb	High Range (VRR = 0)
	Unit Resistor Value (R)	—	2k*	—	Ω	
	Settling Time <sup>(1)</sup>	—	—	10*	µs	

\* These parameters are characterized but not tested.

**Note 1:** Settling time measured while VRR = 1 and VR<3:0> transitions from 0000 to 1111.



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NOTES:

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FIGURE 13-3: TYPICAL IPD vs. VDD OVER TEMP (+125°C)

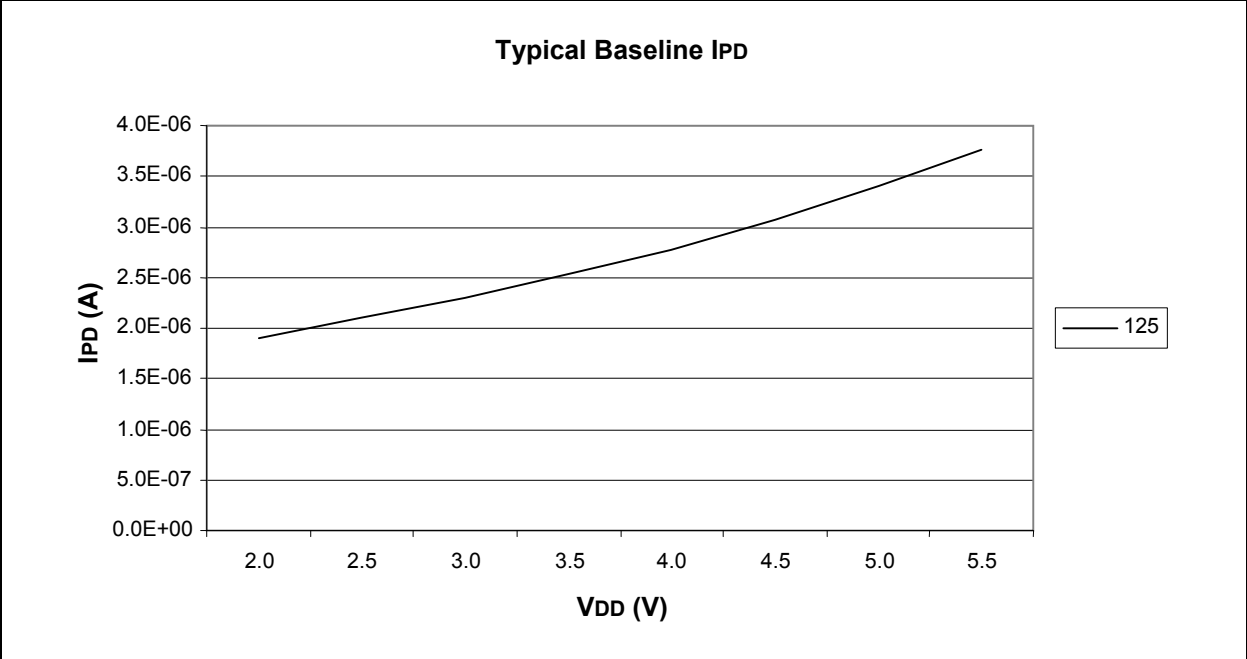
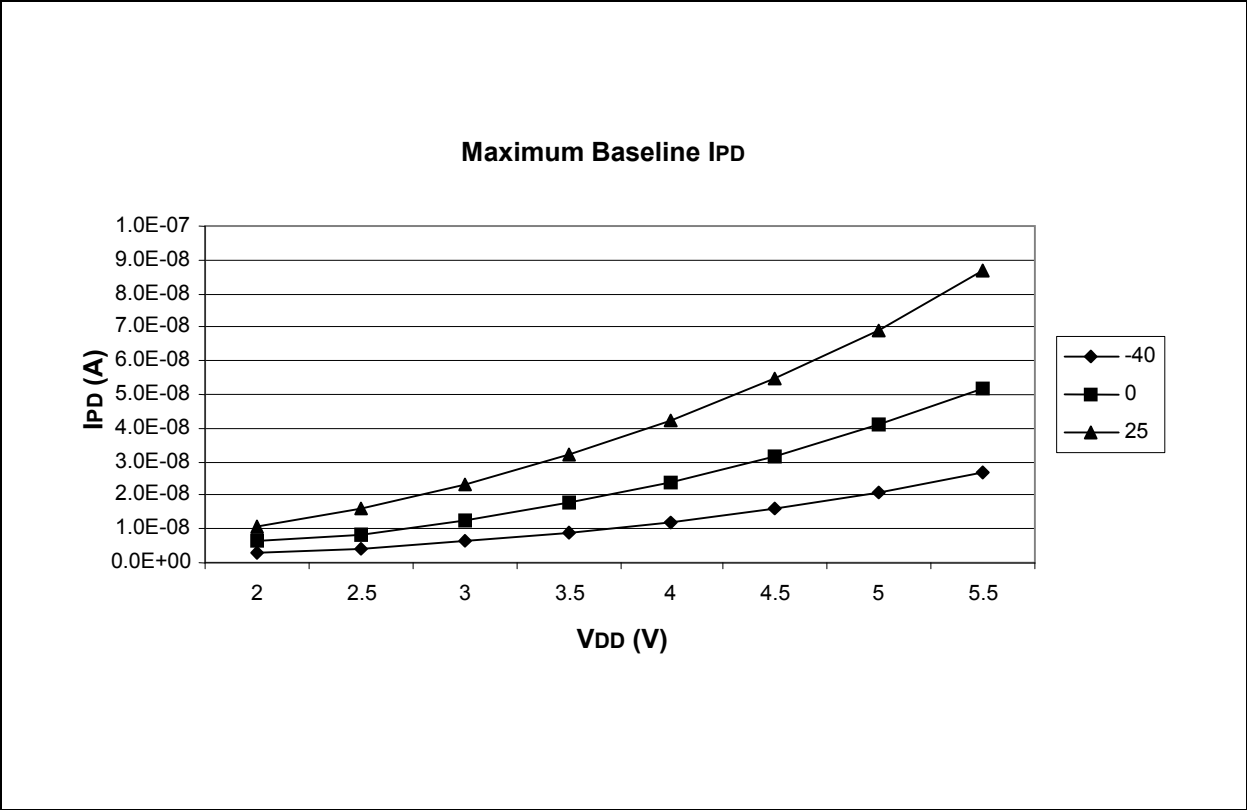
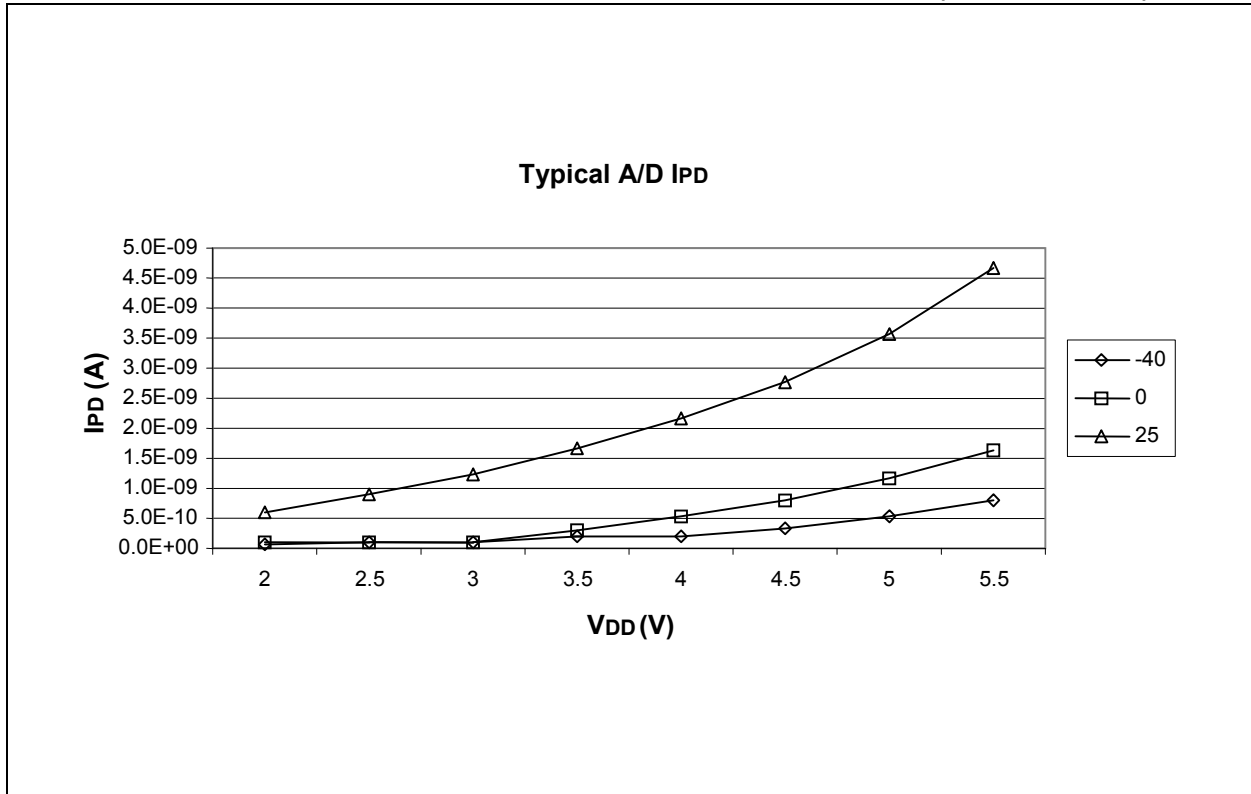


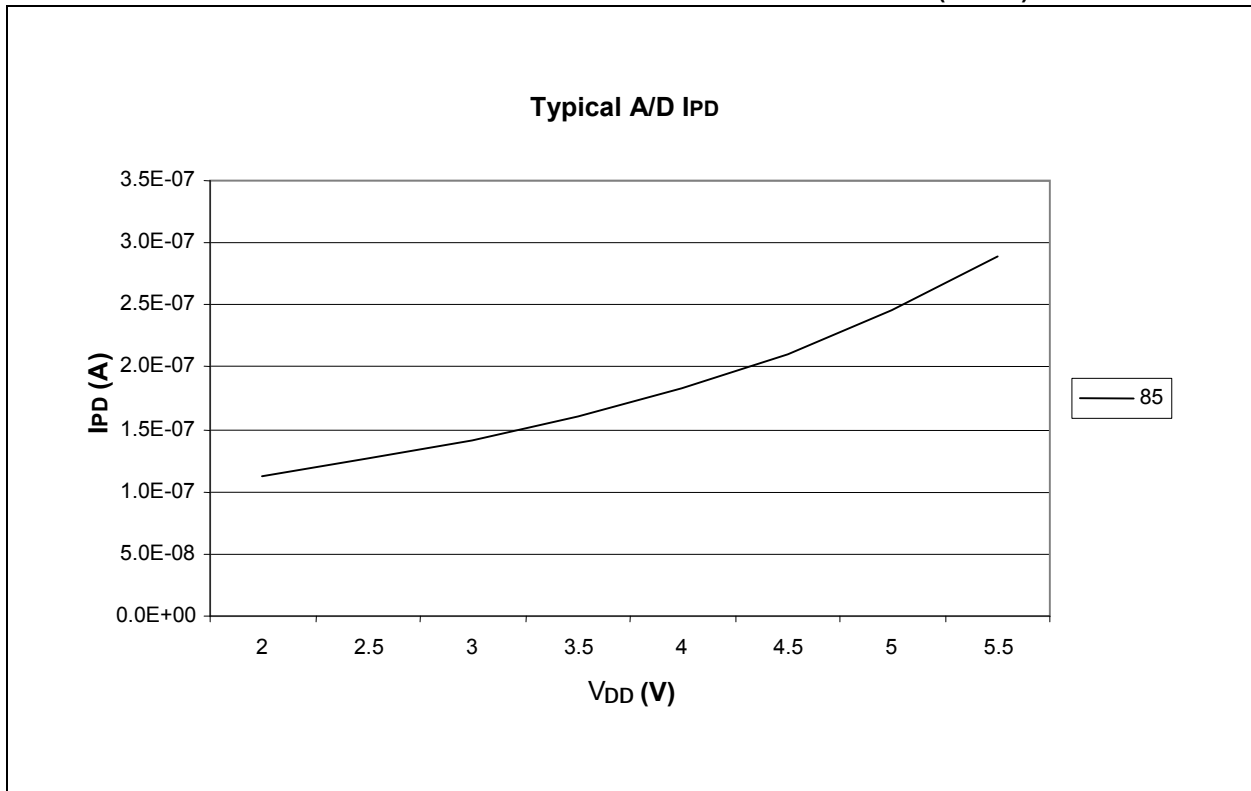
FIGURE 13-4: MAXIMUM IPD vs. VDD OVER TEMP (-40°C TO +25°C)



**FIGURE 13-9: TYPICAL  $I_{PD}$  WITH A/D ENABLED vs.  $V_{DD}$  OVER TEMP (-40°C TO +25°C)**



**FIGURE 13-10: TYPICAL  $I_{PD}$  WITH A/D ENABLED vs.  $V_{DD}$  OVER TEMP (+85°C)**



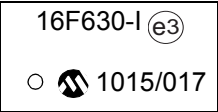
14.0 PACKAGING INFORMATION

14.1 Package Marking Information

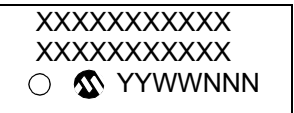
14-Lead PDIP (Skinny DIP)



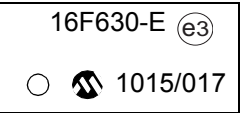
Example



14-Lead SOIC



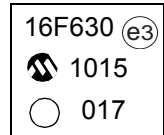
Example



14-Lead TSSOP



Example

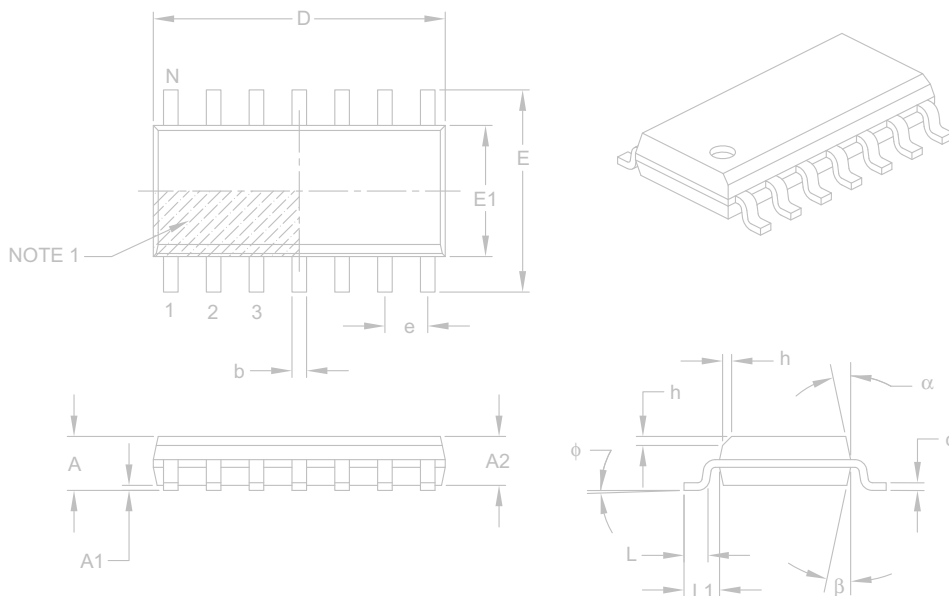


<b>Legend:</b>	XX...X	Customer-specific information
	Y	Year code (last digit of calendar year)
	YY	Year code (last 2 digits of calendar year)
	WW	Week code (week of January 1 is week '01')
	NNN	Alphanumeric traceability code
	(e3)	Pb-free JEDEC designator for Matte Tin (Sn)
	*	This package is Pb-free. The Pb-free JEDEC designator (e3) can be found on the outer packaging for this package.

**Note:** In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information.

## 14-Lead Plastic Small Outline (SL) – Narrow, 3.90 mm Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N	14		
Pitch	e	1.27 BSC		
Overall Height	A	–	–	1.75
Molded Package Thickness	A2	1.25	–	–
Standoff §	A1	0.10	–	0.25
Overall Width	E	6.00 BSC		
Molded Package Width	E1	3.90 BSC		
Overall Length	D	8.65 BSC		
Chamfer (optional)	h	0.25	–	0.50
Foot Length	L	0.40	–	1.27
Footprint	L1	1.04 REF		
Foot Angle	φ	0°	–	8°
Lead Thickness	c	0.17	–	0.25
Lead Width	b	0.31	–	0.51
Mold Draft Angle Top	α	5°	–	15°
Mold Draft Angle Bottom	β	5°	–	15°

**Notes:**

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- § Significant Characteristic.
- Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15 mm per side.
- Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-065B