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Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Obsolete
Number of LABs/CLBs	780
Number of Logic Elements/Cells	15600
Total RAM Bits	419328
Number of I/O	342
Number of Gates	-
Voltage - Supply	1.15V ~ 1.25V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	484-BBGA
Supplier Device Package	484-FBGA (23x23)
Purchase URL	https://www.e-xfl.com/product-detail/intel/ep2s15f484c4

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Chapter Revision Dates

The chapters in this book, *Stratix II Device Handbook, Volume 1*, were revised on the following dates. Where chapters or groups of chapters are available separately, part numbers are listed.

Chapter 1. Introduction

Revised: May 2007 Part number: SII51001-4.2

Chapter 2. Stratix II Architecture

Revised: *May* 2007 Part number: *SII5*1002-4.3

Chapter 3. Configuration & Testing

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Chapter 4. Hot Socketing & Power-On Reset

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Chapter 5. DC & Switching Characteristics

Revised: *April* 2011 Part number: *SII51005-4.5*

Chapter 6. Reference & Ordering Information

Revised: *April* 2011 Part number: *SII51006-2.2*

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About this Handbook

This handbook provides comprehensive information about the Altera® Stratix® II family of devices.

How to Contact Altera

For the most up-to-date information about Altera products, refer to the following table.

Contact (1)	Contact Method	Address
Technical support	Website	www.altera.com/support
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	Email	custrain@altera.com
Product literature	Email	www.altera.com/literature
Altera literature services	Website	literature@altera.com
Non-technical support (General)	Email	nacomp@altera.com
(Software Licensing)	Email	authorization@altera.com

Note to table:

(1) You can also contact your local Altera sales office or sales representative.

Typographic Conventions

This document uses the typographic conventions shown below.

Visual Cue	Meaning
Bold Type with Initial Capital Letters	Command names, dialog box titles, checkbox options, and dialog box options are shown in bold, initial capital letters. Example: Save As dialog box.
bold type	External timing parameters, directory names, project names, disk drive names, filenames, filename extensions, and software utility names are shown in bold type. Examples: f _{MAX} , \qdesigns directory, d: drive, chiptrip.gdf file.
Italic Type with Initial Capital Letters	Document titles are shown in italic type with initial capital letters. Example: AN 75: High-Speed Board Design.

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The direct link interconnect allows an LAB, DSP block, or TriMatrix memory block to drive into the local interconnect of its left and right neighbors and then back into itself. This provides fast communication between adjacent LABs and/or blocks without using row interconnect resources.

The R4 interconnects span four LABs, three LABs and one M512 RAM block, two LABs and one M4K RAM block, or two LABs and one DSP block to the right or left of a source LAB. These resources are used for fast row connections in a four-LAB region. Every LAB has its own set of R4 interconnects to drive either left or right. Figure 2-16 shows R4 interconnect connections from an LAB. R4 interconnects can drive and be driven by DSP blocks and RAM blocks and row IOEs. For LAB interfacing, a primary LAB or LAB neighbor can drive a given R4 interconnect. For R4 interconnects that drive to the right, the primary LAB and right neighbor can drive on to the interconnect. For R4 interconnects that drive to the left, the primary LAB and its left neighbor can drive on to the interconnect. R4 interconnects can drive other R4 interconnects to extend the range of LABs they can drive. R4 interconnects can also drive C4 and C16 interconnects for connections from one row to another. Additionally, R4 interconnects can drive R24 interconnects.

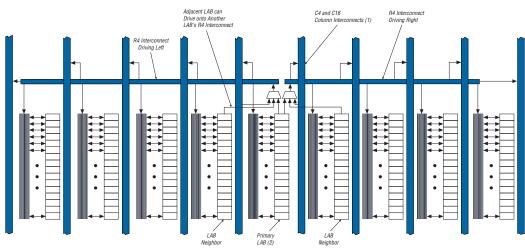


Figure 2–16. R4 Interconnect Connections Notes (1), (2), (3)

Notes to Figure 2–16:

- (1) C4 and C16 interconnects can drive R4 interconnects.
- (2) This pattern is repeated for every LAB in the LAB row.
- (3) The LABs in Figure 2–16 show the 16 possible logical outputs per LAB.

The M4K RAM blocks allow for different clocks on their inputs and outputs. Either of the two clocks feeding the block can clock M4K RAM block registers (renwe, address, byte enable, datain, and output registers). Only the output register can be bypassed. The six labclk signals or local interconnects can drive the control signals for the A and B ports of the M4K RAM block. ALMs can also control the clock_a, clock_b, renwe_a, renwe_b, clr_a, clr_b, clocken_a, and clocken_b signals, as shown in Figure 2–21.

The R4, C4, and direct link interconnects from adjacent LABs drive the M4K RAM block local interconnect. The M4K RAM blocks can communicate with LABs on either the left or right side through these row resources or with LAB columns on either the right or left with the column resources. Up to 16 direct link input connections to the M4K RAM Block are possible from the left adjacent LABs and another 16 possible from the right adjacent LAB. M4K RAM block outputs can also connect to left and right LABs through direct link interconnect. Figure 2–22 shows the M4K RAM block to logic array interface.

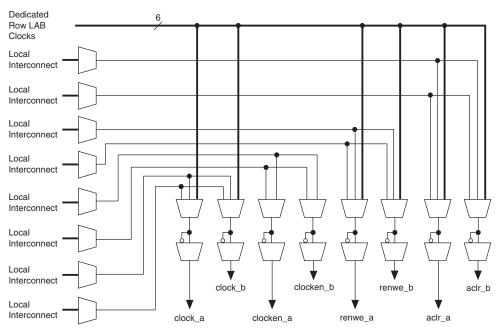


Figure 2-21. M4K RAM Block Control Signals

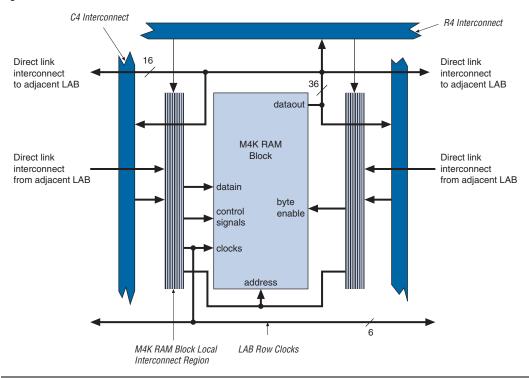


Figure 2-22. M4K RAM Block LAB Row Interface

M-RAM Block

The largest TriMatrix memory block, the M-RAM block, is useful for applications where a large volume of data must be stored on-chip. Each block contains 589,824 RAM bits (including parity bits). The M-RAM block can be configured in the following modes:

- True dual-port RAM
- Simple dual-port RAM
- Single-port RAM
- FIFO

You cannot use an initialization file to initialize the contents of an M-RAM block. All M-RAM block contents power up to an undefined value. Only synchronous operation is supported in the M-RAM block, so all inputs are registered. Output registers can be bypassed.

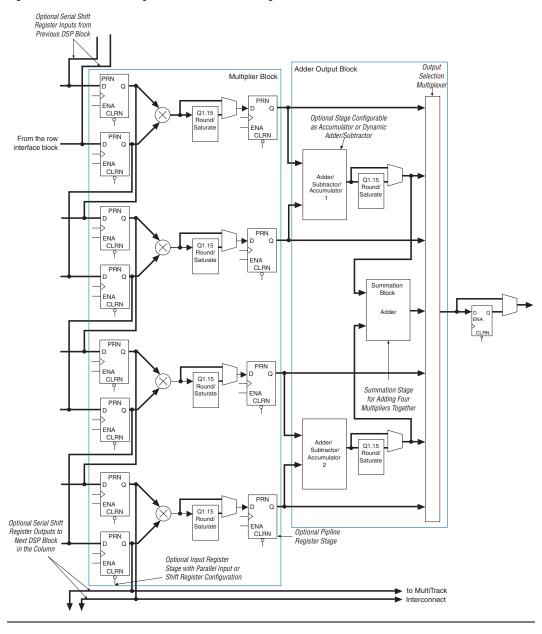


Figure 2-28. DSP Block Diagram for 18 x 18-Bit Configuration

PLLs & Clock Networks

Stratix II devices provide a hierarchical clock structure and multiple PLLs with advanced features. The large number of clocking resources in combination with the clock synthesis precision provided by enhanced and fast PLLs provides a complete clock management solution.

Global & Hierarchical Clocking

Stratix II devices provide 16 dedicated global clock networks and 32 regional clock networks (eight per device quadrant). These clocks are organized into a hierarchical clock structure that allows for up to 24 clocks per device region with low skew and delay. This hierarchical clocking scheme provides up to 48 unique clock domains in Stratix II devices.

There are 16 dedicated clock pins (CLK [15..0]) to drive either the global or regional clock networks. Four clock pins drive each side of the device, as shown in Figures 2–31 and 2–32. Internal logic and enhanced and fast PLL outputs can also drive the global and regional clock networks. Each global and regional clock has a clock control block, which controls the selection of the clock source and dynamically enables/disables the clock to reduce power consumption. Table 2–8 shows global and regional clock features.

Table 2–8. Global & Regional Clock Features								
Feature	Global Clocks	Regional Clocks						
Number per device	16	32						
Number available per quadrant	16	8						
Sources	CLK pins, PLL outputs, or internal logic	CLK pins, PLL outputs, or internal logic						
Dynamic clock source selection	√ (1)							
Dynamic enable/disable	✓	✓						

Note to Table 2–8:

 Dynamic source clock selection is supported for selecting between CLKp pins and PLL outputs only.

Global Clock Network

These clocks drive throughout the entire device, feeding all device quadrants. The global clock networks can be used as clock sources for all resources in the device-IOEs, ALMs, DSP blocks, and all memory blocks. These resources can also be used for control signals, such as clock enables and synchronous or asynchronous clears fed from the external pin. The

Table 2–11. Global & Regional Clock Connections from Top Clock Pins & Enhanced PLL Outputs (Part 1 of 2)									art 1				
Top Side Global & Regional Clock Network Connectivity	DLLCLK	CLK12	CLK13	CLK14	CLK15	RCLK24	RCLK25	RCLK26	RCLK27	RCLK28	RCLK29	RCLK30	RCLK31
Clock pins													
CLK12p	\	~	<			\				~			
CLK13p	✓	✓	\				~						~
CLK14p	✓			✓	✓			✓				✓	
CLK15p	✓			✓	✓				✓		✓		
CLK12n		✓				✓				✓			
CLK13n			✓				✓						✓
CLK14n				✓				✓				✓	
CLK15n					✓				✓		✓		
Drivers from internal logic		ı		ı		ı	ı		ı	ı		ı	
GCLKDRV0		~											
GCLKDRV1			✓										
GCLKDRV2				✓									
GCLKDRV3					✓								
RCLKDRV0						✓				✓			
RCLKDRV1							✓				✓		
RCLKDRV2								✓				✓	
RCLKDRV3									✓				✓
RCLKDRV4						✓				✓			
RCLKDRV5							✓				✓		
RCLKDRV6								✓				✓	
RCLKDRV7									✓				✓
Enhanced PLL 5 outputs	Enhanced PLL 5 outputs												
c0	✓	✓	✓			✓				✓			
c1	✓	✓	✓				✓				✓		
c2	✓			✓	✓			✓				✓	
c3	✓			✓	✓				✓				✓

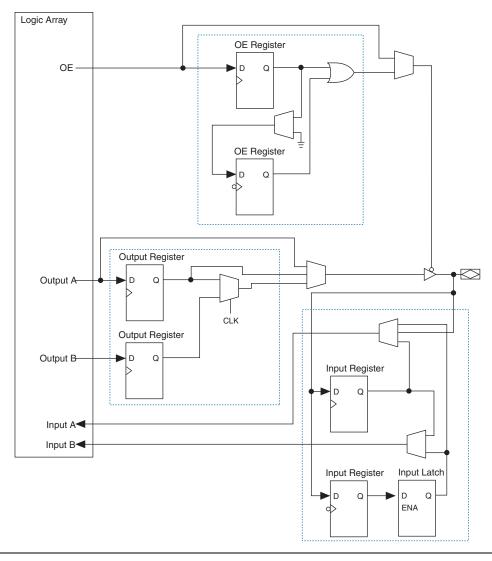


Figure 2-46. Stratix II IOE Structure

The IOEs are located in I/O blocks around the periphery of the Stratix II device. There are up to four IOEs per row I/O block and four IOEs per column I/O block. The row I/O blocks drive row, column, or direct link interconnects. The column I/O blocks drive column interconnects. Figure 2–47 shows how a row I/O block connects to the logic array. Figure 2–48 shows how a column I/O block connects to the logic array.

Table 2–19. Board Design Recommendations for nCEO									
nCF Innut Buffer Bower in I/O	S	tratix II nCEO V	_{ccio} Voltage Le	vel in I/O Bank 7	7				
nCE Input Buffer Power in I/O Bank 3	V _{CC10} = 3.3 V	V _{CC10} = 2.5 V	V _{CC10} = 1.8 V	V _{CC10} = 1.5 V	V _{CCIO} = 1.2 V				
VCCSEL high (V _{CCIO} Bank 3 = 1.5 V)	√ (1), (2)	✓ (3), (4)	√ (5)	✓	✓				
VCCSEL high (V _{CCIO} Bank 3 = 1.8 V)	√ (1), (2)	✓ (3), (4)	✓	✓	Level shifter required				
VCCSEL low (nCE Powered by V _{CCPD} = 3.3V)	√	√ (4)	√ (6)	Level shifter required	Level shifter required				

Notes to Table 2-19:

- (1) Input buffer is 3.3-V tolerant.
- (2) The nCEO output buffer meets V_{OH} (MIN) = 2.4 V.
- (3) Input buffer is 2.5-V tolerant.
- (4) The nCEO output buffer meets V_{OH} (MIN) = 2.0 V.
- (5) Input buffer is 1.8-V tolerant.
- (6) An external 250-Ω pull-up resistor is not required, but recommended if signal levels on the board are not optimal.

For JTAG chains, the TDO pin of the first device drives the TDI pin of the second device in the chain. The V_{CCSEL} input on JTAG input I/O cells (TCK, TMS, TDI, and TRST) is internally hardwired to GND selecting the 3.3-V/2.5-V input buffer powered by V_{CCPD} . The ideal case is to have the V_{CCIO} of the TDO bank from the first device to match the V_{CCSEL} settings for TDI on the second device, but that may not be possible depending on the application. Table 2–20 contains board design recommendations to ensure proper JTAG chain operation.

Table 2–20. Supported TDO/TDI Voltage Combinations (Part 1 of 2)										
Device	TDI Input Buffer Power	;	Stratix II TDO V _{CC10} Voltage Level in I/O Bank 4							
Device		V _{CC10} = 3.3 V	V _{CC10} = 2.5 V	V _{CC10} = 1.8 V	V _{CC10} = 1.5 V	V _{CC10} = 1.2 V				
Stratix II	Always V _{CCPD} (3.3V)	√ (1)	√ (2)	√ (3)	Level shifter required	Level shifter required				

Table 2-25. E	P2\$130 Differe	ential Chan	nels	Note (1)						
Dookono	Transmitter/	Total		Center F	ast PLLs		C	orner Fas	st PLLs ((4)
Package	Receiver	Channels	PLL 1	PLL 2	PLL 3	PLL 4	PLL 7	PLL 8	PLL 9	PLL 10
780-pin	Transmitter	64 (2)	16	16	16	16	-	-	-	
FineLine BGA		(3)	32	32	32	32	-	-	-	-
	Receiver	68 (2)	17	17	17	17	-	-	-	-
		(3)	34	34	34	34	-	-	-	
1,020-pin	Transmitter	88 (2)	22	22	22	22	22	22	22	22
FineLine BGA		(3)	44	44	44	44	-	-	-	-
	Receiver	92 (2)	23	23	23	23	23	23	23	23
		(3)	46	46	46	46	-	-	-	-
1,508-pin	Transmitter	156 <i>(2)</i>	37	41	41	37	37	41	41	37
FineLine BGA		(3)	78	78	78	78	-	-	-	-
	Receiver	156 <i>(2)</i>	37	41	41	37	37	41	41	37
		(3)	78	78	78	78	-	-	-	-

Table 2–26. E	Table 2–26. EP2S180 Differential Channels Note (1)										
Dookogo	Transmitter/	Total		Center F	ast PLLs	1	C	Corner Fast PLLs (4)			
Package	Receiver	Channels	PLL 1	PLL 2	PLL 3	PLL 4	PLL 7	PLL 8	PLL 9	PLL 10	
1,020-pin	Transmitter	88 (2)	22	22	22	22	22	22	22	22	
FineLine BGA		(3)	44	44	44	44	-	-	-	-	
	Receiver	92 (2)	23	23	23	23	23	23	23	23	
		(3)	46	46	46	46	-	-	-	-	
1,508-pin	Transmitter	156 <i>(2)</i>	37	41	41	37	37	41	41	37	
FineLine BGA		(3)	78	78	78	78	-	=	-	-	
	Receiver	156 <i>(2)</i>	37	41	41	37	37	41	41	37	
		(3)	78	78	78	78	-	-	-	-	

Notes to Tables 2-21 to 2-26:

- (1) The total number of receiver channels includes the four non-dedicated clock channels that can be optionally used as data channels.
- (2) This is the maximum number of channels the PLLs can directly drive.
- (3) This is the maximum number of channels if the device uses cross bank channels from the adjacent center PLL.
- (4) The channels accessible by the center fast PLL overlap with the channels accessible by the corner fast PLL. Therefore, the total number of channels is not the addition of the number of channels accessible by PLLs 1, 2, 3, and 4 with the number of channels accessible by PLLs 7, 8, 9, and 10.

The PLL_ENA pin and the configuration input pins (Table 3–4) have a dual buffer design: a 3.3-V/2.5-V input buffer and a 1.8-V/1.5-V input buffer. The VCCSEL input pin selects which input buffer is used. The 3.3-V/2.5-V input buffer is powered by $V_{CCPD_{\rm c}}$ while the 1.8-V/1.5-V input buffer is powered by $V_{\rm CCIO}$. Table 3–4 shows the pins affected by VCCSEL.

Table 3–4. Pins Ai	fected by the Voltage Level a	t VCCSEL		
Pin	VCCSEL = LOW (connected to GND)	VCCSEL = HIGH (connected to V _{CCPD})		
nSTATUS (when used as an input)				
nCONFIG				
CONF_DONE (when used as an input)				
DATA[70]				
nCE				
DCLK (when used as an input)	3.3/2.5-V input buffer is	1.8/1.5-V input buffer is selected. Input buffer is		
CS	selected. Input buffer is powered by V _{CCPD} .	powered by V _{CCIO} of the I/O		
nWS	, 5015	bank.		
nRS				
nCS				
CLKUSR				
DEV_OE				
DEV_CLRn				
RUnLU				
PLL_ENA				

VCCSEL is sampled during power-up. Therefore, the VCCSEL setting cannot change on the fly or during a reconfiguration. The VCCSEL input buffer is powered by V_{CCINT} and must be hardwired to V_{CCPD} or ground. A logic high VCCSEL connection selects the 1.8-V/1.5-V input buffer, and a logic low selects the 3.3-V/2.5-V input buffer. VCCSEL should be set to comply with the logic levels driven out of the configuration device or MAX^{\otimes} II/microprocessor.

If you need to support configuration input voltages of 3.3 V/2.5 V, you should set the VCCSEL to a logic low; you can set the V_{CCIO} of the I/O bank that contains the configuration inputs to any supported voltage. If

Devices Can Be Driven Before Power-Up

You can drive signals into the I/O pins, dedicated input pins and dedicated clock pins of Stratix II devices before or during power-up or power-down without damaging the device. Stratix II devices support any power-up or power-down sequence (V_{CCIO} , V_{CCINT} , and V_{CCPD}) in order to simplify system level design.

I/O Pins Remain Tri-Stated During Power-Up

A device that does not support hot-socketing may interrupt system operation or cause contention by driving out before or during power-up. In a hot socketing situation, Stratix II device's output buffers are turned off during system power-up or power-down. Stratix II device also does not drive out until the device is configured and has attained proper operating conditions.

Signal Pins Do Not Drive the $V_{\text{CCIO}},\,V_{\text{CCINT}}$ or V_{CCPD} Power Supplies

Devices that do not support hot-socketing can short power supplies together when powered-up through the device signal pins. This irregular power-up can damage both the driving and driven devices and can disrupt card power-up.

Stratix II devices do not have a current path from I/O pins, dedicated input pins, or dedicated clock pins to the V_{CCIO} , V_{CCINT} , or V_{CCPD} pins before or during power-up. A Stratix II device may be inserted into (or removed from) a powered-up system board without damaging or interfering with system-board operation. When hot-socketing, Stratix II devices may have a minimal effect on the signal integrity of the backplane.



You can power up or power down the $V_{\rm CCIO}$, $V_{\rm CCINT}$, and $V_{\rm CCPD}$ pins in any sequence. The power supply ramp rates can range from 100 μ s to 100 ms. All $V_{\rm CC}$ supplies must power down within 100 ms of each other to prevent I/O pins from driving out. During hot socketing, the I/O pin capacitance is less than 15 pF and the clock pin capacitance is less than 20 pF. Stratix II devices meet the following hot socketing specification.

- The hot socketing DC specification is: $|I_{IOPIN}| < 300 \,\mu\text{A}$.
- The hot socketing AC specification is: | I_{IOPIN} | < 8 mA for 10 ns or less.</p>

Table 5-	Table 5–3. Stratix II Device Recommended Operating Conditions (Part 2 of 2) Note (1)									
Symbol	Parameter Conditions Minimum Maximum U									
T_{J}	Operating junction temperature	For commercial use	0	85	°C					
		For industrial use	-40	100	°C					
		For military use (7)	- 55	125	°C					

Notes to Table 5-3:

- (1) Supply voltage specifications apply to voltage readings taken at the device pins, not at the power supply.
- (2) During transitions, the inputs may overshoot to the voltage shown in Table 5–2 based upon the input duty cycle. The DC case is equivalent to 100% duty cycle. During transitions, the inputs may undershoot to –2.0 V for input currents less than 100 mA and periods shorter than 20 ns.
- (3) Maximum V_{CC} rise time is 100 ms, and V_{CC} must rise monotonically from ground to V_{CC} .
- (4) V_{CCPD} must ramp-up from 0 V to 3.3 V within 100 μs to 100 ms. If V_{CCPD} is not ramped up within this specified time, your Stratix II device does not configure successfully. If your system does not allow for a V_{CCPD} ramp-up time of 100 ms or less, you must hold nCONFIG low until all power supplies are reliable.
- (5) All pins, including dedicated inputs, clock, I/O, and JTAG pins, may be driven before V_{CCINT}, V_{CCPD}, and V_{CCIO} are powered.
- (6) V_{CCIO} maximum and minimum conditions for PCI and PCI-X are shown in parentheses.
- (7) For more information, refer to the Stratix II Military Temperature Range Support technical brief.

DC Electrical Characteristics

Table 5–4 shows the Stratix II device family DC electrical characteristics.

Table 5-	4. Stratix II Device DC Op	erating Conditions	(Part 1 of 2)	Note (1)			
Symbol	Parameter	Conditio	Minimum	Typical	Maximum	Unit	
I _I	Input pin leakage current	V _I = V _{CCIOmax} to 0 \	<i>I (2)</i>	-10		10	μА
I _{OZ}	Tri-stated I/O pin leakage current	$V_O = V_{CCIOmax}$ to 0	$V_O = V_{CCIOmax}$ to 0 V (2)			10	μА
I _{CCINTO}	V _{CCINT} supply current	V _I = ground, no	EP2S15		0.25	(3)	Α
	$\begin{array}{c} \text{(standby)} & \text{load, no tog} \\ & \text{inputs} \\ & \text{T}_{\text{J}} = 25^{\circ} \text{ C} \end{array}$	load, no toggling	EP2S30		0.30	(3)	Α
			EP2S60		0.50	(3)	Α
			EP2S90		0.62	(3)	Α
		<u> </u>	EP2S130		0.82	(3)	Α
			EP2S180		1.12	(3)	Α
I _{CCPD0}	V _{CCPD} supply current	V _I = ground, no	EP2S15		2.2	(3)	mA
	(standby)	load, no toggling	EP2S30		2.7	(3)	mA
		inputs T _{.l} = 25° C,	EP2S60		3.6	(3)	mA
	, and the second	$V_{CCPD} = 3.3V$	EP2S90		4.3	(3)	mA
			EP2S130		5.4	(3)	mA
			EP2S180		6.8	(3)	mA

Table 5–5. LVTTL Specifications (Part 2 of 2)						
Symbol	Parameter	Conditions	Minimum	Maximum	Unit	
V_{OL}	Low-level output voltage	I _{OL} = 4 mA (2)		0.45	V	

Notes to Tables 5-5:

- Stratix II devices comply to the narrow range for the supply voltage as specified in the EIA/JEDEC Standard, JESD8-B.
- (2) This specification is supported across all the programmable drive strength settings available for this I/O standard as shown in the *Stratix II Architecture* chapter in volume 1 of the *Stratix II Device Handbook*.

Table 5–6. LVCMOS Specifications								
Symbol	Parameter	Conditions	Minimum	Maximum	Unit			
V _{CCIO} (1)	Output supply voltage		3.135	3.465	V			
V _{IH}	High-level input voltage		1.7	4.0	V			
V _{IL}	Low-level input voltage		-0.3	0.8	V			
V _{OH}	High-level output voltage	$V_{CCIO} = 3.0,$ $I_{OH} = -0.1 \text{ mA } (2)$	V _{CCIO} - 0.2		V			
V _{OL}	Low-level output voltage	V _{CCIO} = 3.0, I _{OL} = 0.1 mA (2)		0.2	V			

Notes to Table 5-6:

- (1) Stratix II devices comply to the narrow range for the supply voltage as specified in the EIA/JEDEC Standard, JESD8-B.
- (2) This specification is supported across all the programmable drive strength available for this I/O standard as shown in the *Stratix II Architecture* chapter in volume 1 of the *Stratix II Device Handbook*.

Table 5-7.	Table 5–7. 2.5-V I/O Specifications								
Symbol	Parameter	Conditions	Minimum	Maximum	Unit				
V _{CCIO} (1)	Output supply voltage		2.375	2.625	V				
V _{IH}	High-level input voltage		1.7	4.0	٧				
V _{IL}	Low-level input voltage		-0.3	0.7	V				
V _{OH}	High-level output voltage	I _{OH} = -1mA (2)	2.0		V				
V _{OL}	Low-level output voltage	I _{OL} = 1 mA (2)		0.4	V				

Notes to Table 5–7:

- (1) Stratix II devices V_{CCIO} voltage level support of $2.5 \pm .5\%$ is narrower than defined in the Normal Range of the EIA/JEDEC standard.
- (2) This specification is supported across all the programmable drive settings available for this I/O standard as shown in the *Stratix II Architecture* chapter in volume 1 of the *Stratix II Device Handbook*.

O. mahal	Davarratar	-3 Speed Grade (2)		-3 Speed Grade (3)		-4 Speed Grade		-5 Speed Grade		11:4
Symbol	Parameter	Min (4)	Max	Min (4)	Max	Min (5)	Max	Min (4)	Max	Unit
t _{MEGARC}	Synchronous read cycle time	1,866	2,774	1,866	2,911	1,777 1,866	3,189	1,777 1,866	3,716	ps
t _{MEGAWERESU}	Write or read enable setup time before clock	144		151		165 165		192		ps
t _{MEGAWEREH}	Write or read enable hold time after clock	39		40		44 44		52		ps
t _{MEGABESU}	Byte enable setup time before clock	50		52		57 57		67		ps
t _{MEGABEH}	Byte enable hold time after clock	39		40		44 44		52		ps
t _{MEGADATAASU}	A port data setup time before clock	50		52		57 57		67		ps
t _{MEGADATAAH}	A port data hold time after clock	243		255		279 279		325		ps
t _{MEGAADDRASU}	A port address setup time before clock	589		618		677 677		789		ps
t _{MEGAADDRAH}	A port address hold time after clock	241		253		277 277		322		ps
t _{MEGADATABSU}	B port setup time before clock	50		52		57 57		67		ps
t _{MEGADATABH}	B port hold time after clock	243		255		279 279		325		ps
t _{MEGAADDRBSU}	B port address setup time before clock	589		618		677 677		789		ps
t _{MEGAADDRBH}	B port address hold time after clock	241		253		277 277		322		ps
t _{MEGADATACO1}	Clock-to-output delay when using output registers	480	715	480	749	457 480	821	480	957	ps
t _{MEGADATACO2}	Clock-to-output delay without output registers	1,950	2,899	1,950	3,042	1,857 1,950	3,332	1,950	3,884	ps
t _{MEGACLKL}	Minimum clock low time	1,250		1,312		1,437 1,437		1,675		ps

Table 5–59. EP2S90 Row Pins Global Clock Timing Parameters								
Donomotor	Minimum Timing		-3 Speed	-4 Speed	-5 Speed	Unit		
Parameter	Industrial	Commercial	Grade	Grade	Grade	Ullit		
t _{CIN}	1.585	1.658	2.757	3.154	3.665	ns		
t _{COUT}	1.590	1.663	2.753	3.150	3.660	ns		
t _{PLLCIN}	-0.341	-0.341	-0.193	-0.235	-0.278	ns		
t _{PLLCOUT}	-0.336	-0.336	-0.197	-0.239	-0.283	ns		

EP2S130 Clock Timing Parameters

Tables 5–60 through 5–63 show the maximum clock timing parameters for EP2S130 devices.

Table 5–60. EP2S130 Column Pins Regional Clock Timing Parameters								
Parameter	Minimum Timing		-3 Speed	-4 Speed	-5 Speed	Unit		
Parameter	Industrial	Commercial	Grade	Grade	Grade	UIIII		
t _{CIN}	1.889	1.981	3.405	3.722	4.326	ns		
t _{COUT}	1.732	1.816	3.151	3.444	4.002	ns		
t _{PLLCIN}	0.105	0.106	0.226	0.242	0.277	ns		
t _{PLLCOUT}	-0.052	-0.059	-0.028	-0.036	-0.047	ns		

Table 5–61. EP2S130 Column Pins Global Clock Timing Parameters								
Parameter	Minimum Timing		-3 Speed	-4 Speed	-5 Speed	Unit		
	Industrial	Commercial	Grade	Grade	Grade	Ullit		
t _{CIN}	1.907	1.998	3.420	3.740	4.348	ns		
t _{COUT}	1.750	1.833	3.166	3.462	4.024	ns		
t _{PLLCIN}	0.134	0.136	0.276	0.296	0.338	ns		
t _{PLLCOUT}	-0.023	-0.029	0.022	0.018	0.014	ns		

			Minimu	m Timing	-3	-3	-4	-5	
I/O Standard	Drive Strength	Parameter	Industrial	Commercial	Speed Grade (3)	Speed Grade (4)	Speed Grade	Speed Grade	Unit
Differential	8 mA	t _{OP}	913	957	1715	1799	1971	2041	ps
SSTL-2 Class I		t _{DIP}	933	979	1781	1869	2047	2131	ps
	12 mA	t _{OP}	896	940	1672	1754	1921	1991	ps
		t _{DIP}	916	962	1738	1824	1997	2081	ps
Differential	16 mA	t _{OP}	876	918	1609	1688	1849	1918	ps
SSTL-2 Class II		t _{DIP}	896	940	1675	1758	1925	2008	ps
	20 mA	t _{OP}	877	919	1598	1676	1836	1905	ps
		t _{DIP}	897	941	1664	1746	1912	1995	ps
	24 mA	t _{OP}	872	915	1596	1674	1834	1903	ps
		t _{DIP}	892	937	1662	1744	1910	1993	ps
Differential	4 mA	t _{OP}	909	953	1690	1773	1942	2012	ps
SSTL-18 Class I		t _{DIP}	929	975	1756	1843	2018	2102	ps
0.000	6 mA	t _{OP}	914	958	1656	1737	1903	1973	ps
		t _{DIP}	934	980	1722	1807	1979	2063	ps
	8 mA	t _{OP}	894	937	1640	1721	1885	1954	ps
		t _{DIP}	914	959	1706	1791	1961	2044	ps
	10 mA	t _{OP}	898	942	1638	1718	1882	1952	ps
		t _{DIP}	918	964	1704	1788	1958	2042	ps
	12 mA	t _{OP}	891	936	1626	1706	1869	1938	ps
		t _{DIP}	911	958	1692	1776	1945	2028	ps
Differential	8 mA	t _{OP}	883	925	1597	1675	1835	1904	ps
SSTL-18 Class II		t _{DIP}	903	947	1663	1745	1911	1994	ps
J.200 II	16 mA	t _{OP}	894	937	1578	1655	1813	1882	ps
		t _{DIP}	914	959	1644	1725	1889	1972	ps
	18 mA	t _{OP}	890	933	1585	1663	1821	1890	ps
		t _{DIP}	910	955	1651	1733	1897	1980	ps
	20 mA	t _{OP}	890	933	1583	1661	1819	1888	ps
		t _{DIP}	910	955	1649	1731	1895	1978	ps

Table 5–97. DQS Phase Jitter Specifications for DLL-Delayed Clock (tDQS PHASE_JITTER) Note (1)						
Number of DQS Delay Buffer Stages (2)	DQS Phase Jitter	Unit				
1	30	ps				
2	60	ps				
3	90	ps				
4	120	ps				

Notes to Table 5–97:

- (1) Peak-to-peak phase jitter on the phase shifted DDS clock (digital jitter is caused by DLL tracking).
- (2) Delay stages used for requested DQS phase shift are reported in your project's Compilation Report in the Quartus II software.

Table 5–98. DQS Phase-Shift Error Specifications for DLL-Delayed Clock (tDQS_PSERR) (1)							
Number of DQS Delay Buffer Stages (2)	-3 Speed Grade	-4 Speed Grade	–5 Speed Grade	Unit			
1	25	30	35	ps			
2	50	60	70	ps			
3	75	90	105	ps			
4	100	120	140	ps			

Notes to Table 5–98:

- (1) This error specification is the absolute maximum and minimum error. For example, skew on three delay buffer stages in a C3 speed grade is 75 ps or \pm 37.5 ps.
- (2) Delay stages used for requested DQS phase shift are reported in your project's Compilation Report in the Quartus II software.

Table 5–99. DQS Bus Clock Skew Adder Specifications (tDQS_CLOCK_SKEW_ADDER)						
Mode	DQS Clock Skew Adder	Unit				
×4 DQ per DQS	40	ps				
×9 DQ per DQS	70	ps				
×18 DQ per DQS	75	ps				
×36 DQ per DQS	95	ps				

Note to Table 5-99:

(1) This skew specification is the absolute maximum and minimum skew. For example, skew on a $\times 4$ DQ group is 40 ps or ± 20 ps.