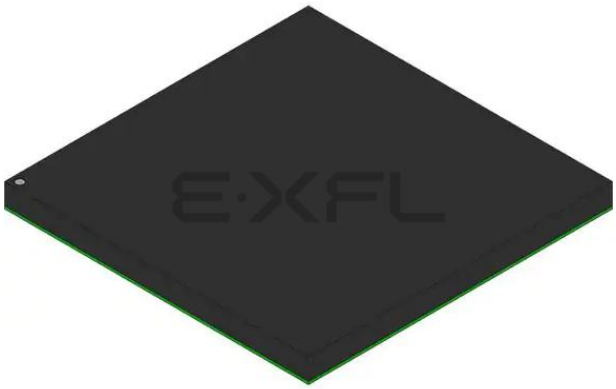

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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Active
Number of LABs/CLBs	8970
Number of Logic Elements/Cells	179400
Total RAM Bits	9383040
Number of I/O	1170
Number of Gates	-
Voltage - Supply	1.15V ~ 1.25V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	1508-BBGA, FCBGA
Supplier Device Package	1508-FBGA (40x40)
Purchase URL	https://www.e-xfl.com/pro/item?MUrl=&PartUrl=ep2s180f1508c5n

Section I. Stratix II Device Family Data Sheet

This section provides the data sheet specifications for Stratix® II devices. This section contains feature definitions of the internal architecture, configuration and JTAG boundary-scan testing information, DC operating conditions, AC timing parameters, a reference to power consumption, and ordering information for Stratix II devices.

This section contains the following chapters:

Revision History

Refer to each chapter for its own specific revision history. For information on when each chapter was updated, refer to the Chapter Revision Dates section, which appears in the full handbook.

1. Introduction

SII51001-4.2

Introduction

The Stratix® II FPGA family is based on a 1.2-V, 90-nm, all-layer copper SRAM process and features a new logic structure that maximizes performance, and enables device densities approaching 180,000 equivalent logic elements (LEs). Stratix II devices offer up to 9 Mbits of on-chip, TriMatrix™ memory for demanding, memory intensive applications and has up to 96 DSP blocks with up to 384 (18-bit × 18-bit) multipliers for efficient implementation of high performance filters and other DSP functions. Various high-speed external memory interfaces are supported, including double data rate (DDR) SDRAM and DDR2 SDRAM, RLDRAM II, quad data rate (QDR) II SRAM, and single data rate (SDR) SDRAM. Stratix II devices support various I/O standards along with support for 1-gigabit per second (Gbps) source synchronous signaling with DPA circuitry. Stratix II devices offer a complete clock management solution with internal clock frequency of up to 550 MHz and up to 12 phase-locked loops (PLLs). Stratix II devices are also the industry's first FPGAs with the ability to decrypt a configuration bitstream using the Advanced Encryption Standard (AES) algorithm to protect designs.

Features

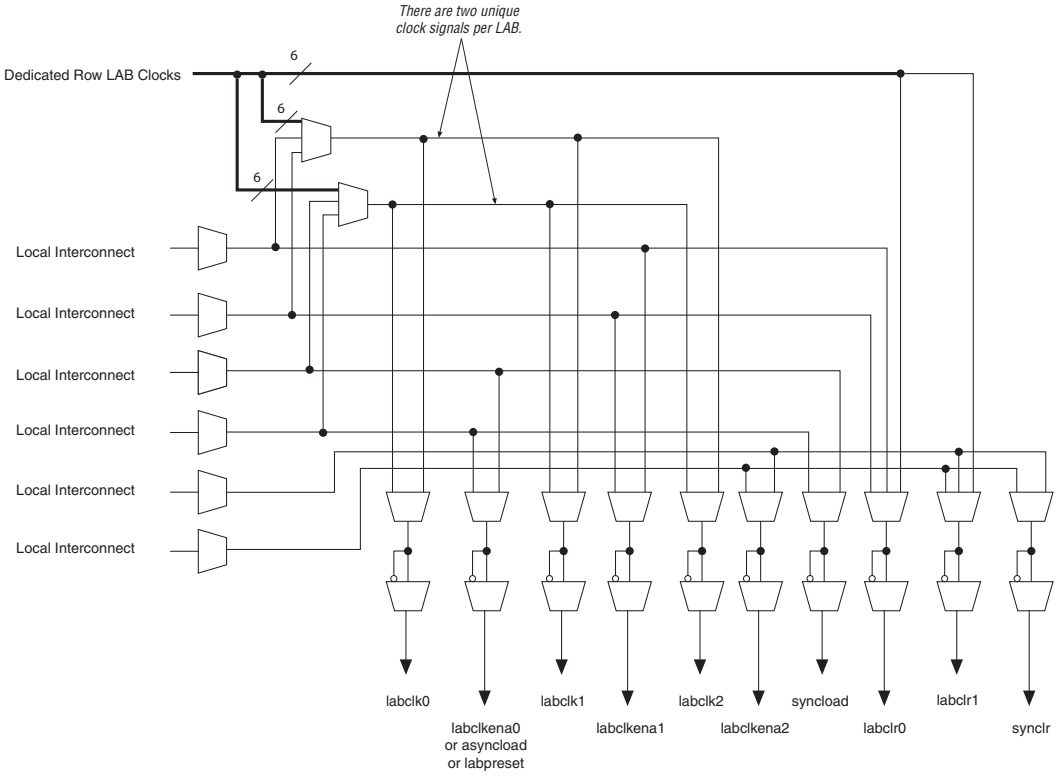
The Stratix II family offers the following features:

- 15,600 to 179,400 equivalent LEs; see Table 1–1
- New and innovative adaptive logic module (ALM), the basic building block of the Stratix II architecture, maximizes performance and resource usage efficiency
- Up to 9,383,040 RAM bits (1,172,880 bytes) available without reducing logic resources
- TriMatrix memory consisting of three RAM block sizes to implement true dual-port memory and first-in first-out (FIFO) buffers
- High-speed DSP blocks provide dedicated implementation of multipliers (at up to 450 MHz), multiply-accumulate functions, and finite impulse response (FIR) filters
- Up to 16 global clocks with 24 clocking resources per device region
- Clock control blocks support dynamic clock network enable/disable, which allows clock networks to power down to reduce power consumption in user mode
- Up to 12 PLLs (four enhanced PLLs and eight fast PLLs) per device provide spread spectrum, programmable bandwidth, clock switch-over, real-time PLL reconfiguration, and advanced multiplication and phase shifting

signal with asynchronous load data input tied high. When the asynchronous load/preset signal is used, the `labclkena0` signal is no longer available.

The LAB row clocks `[5..0]` and LAB local interconnect generate the LAB-wide control signals. The MultiTrack™ interconnect's inherent low skew allows clock and control signal distribution in addition to data. Figure 2–4 shows the LAB control signal generation circuit.

Figure 2–4. LAB-Wide Control Signals



Adaptive Logic Modules

The basic building block of logic in the Stratix II architecture, the adaptive logic module (ALM), provides advanced features with efficient logic utilization. Each ALM contains a variety of look-up table (LUT)-based resources that can be divided between two adaptive LUTs (ALUTs). With up to eight inputs to the two ALUTs, one ALM can implement various combinations of two functions. This adaptability allows the ALM to be

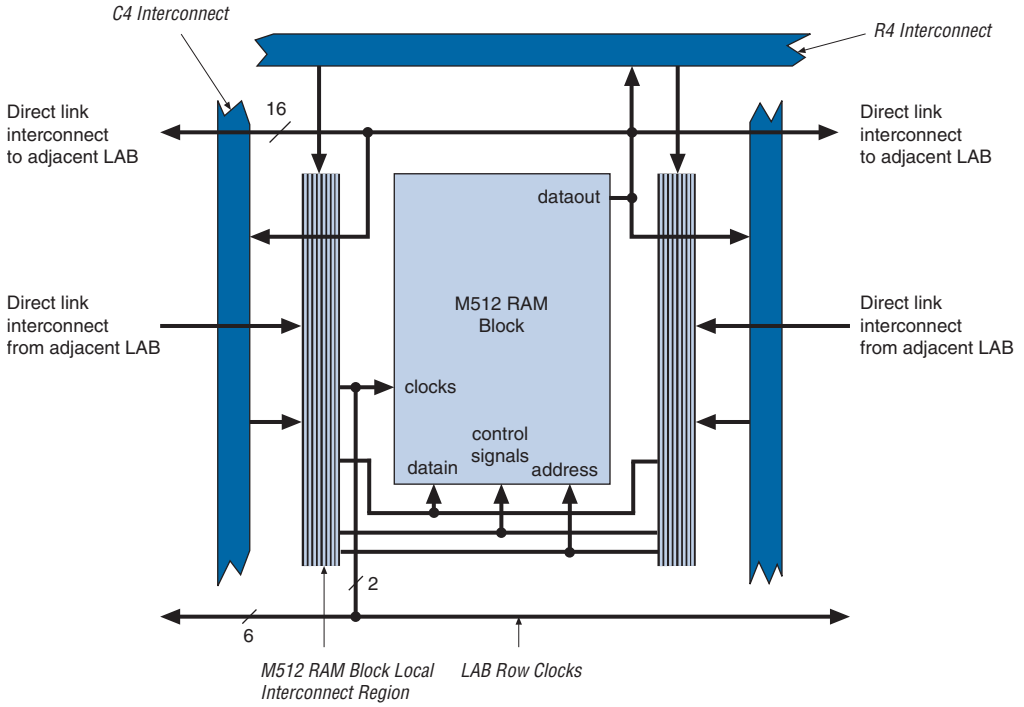
R24 row interconnects span 24 LABs and provide the fastest resource for long row connections between LABs, TriMatrix memory, DSP blocks, and Row IOEs. The R24 row interconnects can cross M-RAM blocks. R24 row interconnects drive to other row or column interconnects at every fourth LAB and do not drive directly to LAB local interconnects. R24 row interconnects drive LAB local interconnects via R4 and C4 interconnects. R24 interconnects can drive R24, R4, C16, and C4 interconnects.

The column interconnect operates similarly to the row interconnect and vertically routes signals to and from LABs, TriMatrix memory, DSP blocks, and IOEs. Each column of LABs is served by a dedicated column interconnect. These column resources include:

- Shared arithmetic chain interconnects in an LAB
- Carry chain interconnects in an LAB and from LAB to LAB
- Register chain interconnects in an LAB
- C4 interconnects traversing a distance of four blocks in up and down direction
- C16 column interconnects for high-speed vertical routing through the device

Stratix II devices include an enhanced interconnect structure in LABs for routing shared arithmetic chains and carry chains for efficient arithmetic functions. The register chain connection allows the register output of one ALM to connect directly to the register input of the next ALM in the LAB for fast shift registers. These ALM to ALM connections bypass the local interconnect. The Quartus II Compiler automatically takes advantage of these resources to improve utilization and performance. Figure 2–17 shows the shared arithmetic chain, carry chain and register chain interconnects.

Figure 2–20. M512 RAM Block LAB Row Interface



M4K RAM Blocks

The M4K RAM block includes support for true dual-port RAM. The M4K RAM block is used to implement buffers for a wide variety of applications such as storing processor code, implementing lookup schemes, and implementing larger memory applications. Each block contains 4,608 RAM bits (including parity bits). M4K RAM blocks can be configured in the following modes:

- True dual-port RAM
- Simple dual-port RAM
- Single-port RAM
- FIFO
- ROM
- Shift register

When configured as RAM or ROM, you can use an initialization file to pre-load the memory contents.

The M4K RAM blocks allow for different clocks on their inputs and outputs. Either of the two clocks feeding the block can clock M4K RAM block registers (renwe, address, byte enable, datain, and output registers). Only the output register can be bypassed. The six `labclk` signals or local interconnects can drive the control signals for the A and B ports of the M4K RAM block. ALMs can also control the `clock_a`, `clock_b`, `renwe_a`, `renwe_b`, `clr_a`, `clr_b`, `clocken_a`, and `clocken_b` signals, as shown in Figure 2–21.

The R4, C4, and direct link interconnects from adjacent LABs drive the M4K RAM block local interconnect. The M4K RAM blocks can communicate with LABs on either the left or right side through these row resources or with LAB columns on either the right or left with the column resources. Up to 16 direct link input connections to the M4K RAM Block are possible from the left adjacent LABs and another 16 possible from the right adjacent LAB. M4K RAM block outputs can also connect to left and right LABs through direct link interconnect. Figure 2–22 shows the M4K RAM block to logic array interface.

Figure 2–21. M4K RAM Block Control Signals

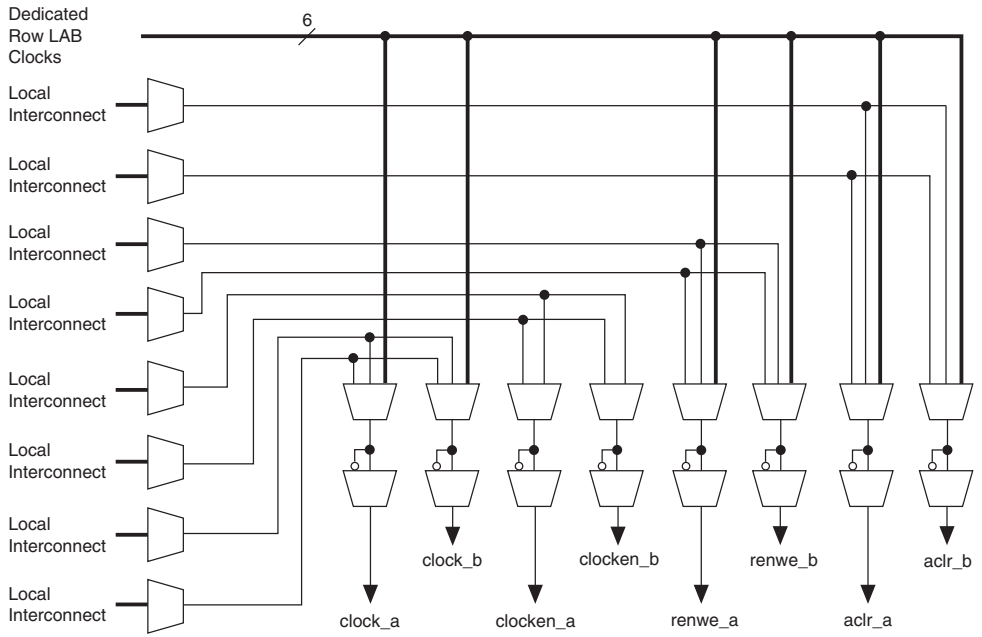
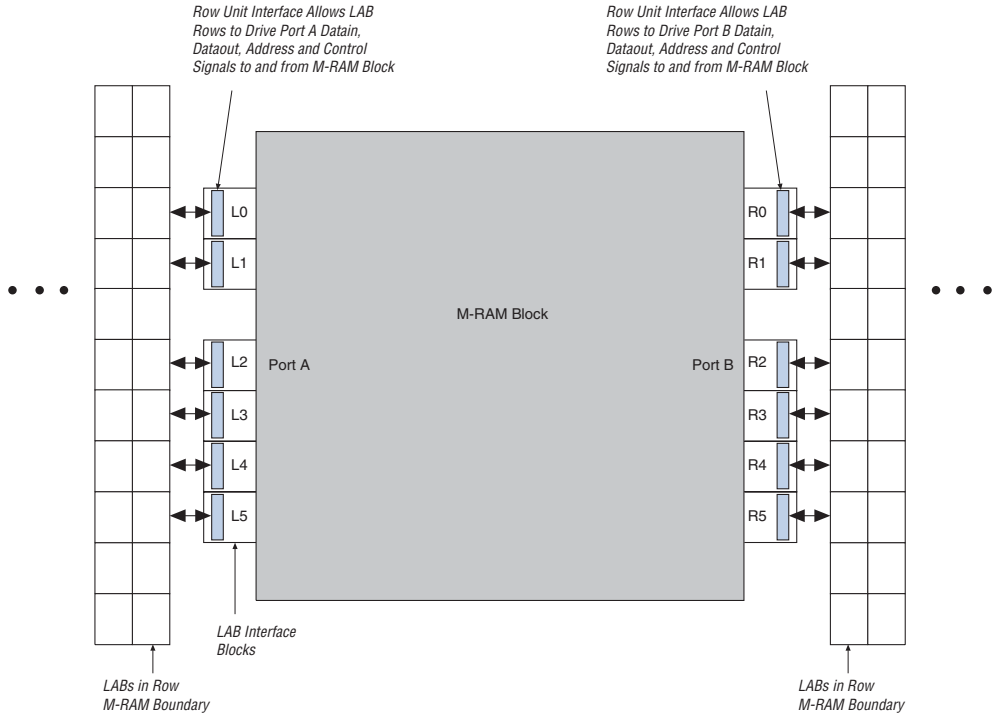


Figure 2–25. M-RAM Block LAB Row Interface *Note (1)*



Note to Figure 2–25:
(1) Only R24 and C16 interconnects cross the M-RAM block boundaries.

Figure 2–26. M-RAM Row Unit Interface to Interconnect

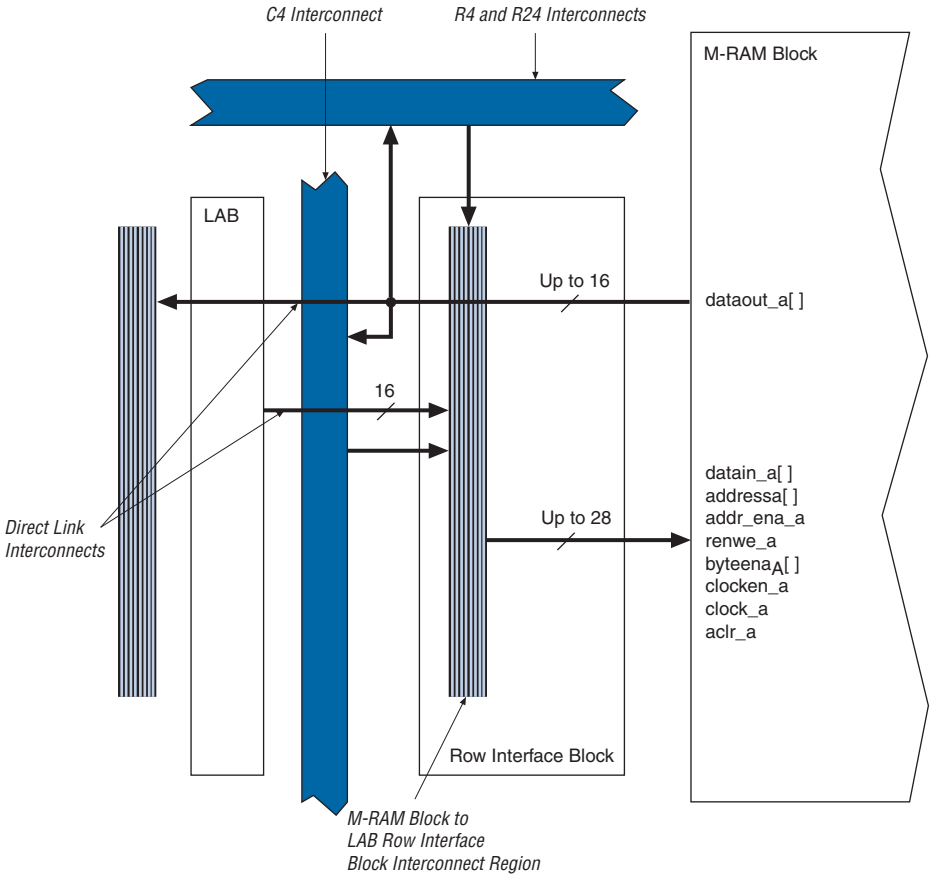


Table 2–4 shows the input and output data signal connections along with the address and control signal input connections to the row unit interfaces (L0 to L5 and R0 to R5).

PLLs & Clock Networks

Stratix II devices provide a hierarchical clock structure and multiple PLLs with advanced features. The large number of clocking resources in combination with the clock synthesis precision provided by enhanced and fast PLLs provides a complete clock management solution.

Global & Hierarchical Clocking

Stratix II devices provide 16 dedicated global clock networks and 32 regional clock networks (eight per device quadrant). These clocks are organized into a hierarchical clock structure that allows for up to 24 clocks per device region with low skew and delay. This hierarchical clocking scheme provides up to 48 unique clock domains in Stratix II devices.

There are 16 dedicated clock pins (CLK[15..0]) to drive either the global or regional clock networks. Four clock pins drive each side of the device, as shown in Figures 2–31 and 2–32. Internal logic and enhanced and fast PLL outputs can also drive the global and regional clock networks. Each global and regional clock has a clock control block, which controls the selection of the clock source and dynamically enables/disables the clock to reduce power consumption. Table 2–8 shows global and regional clock features.

Table 2–8. Global & Regional Clock Features

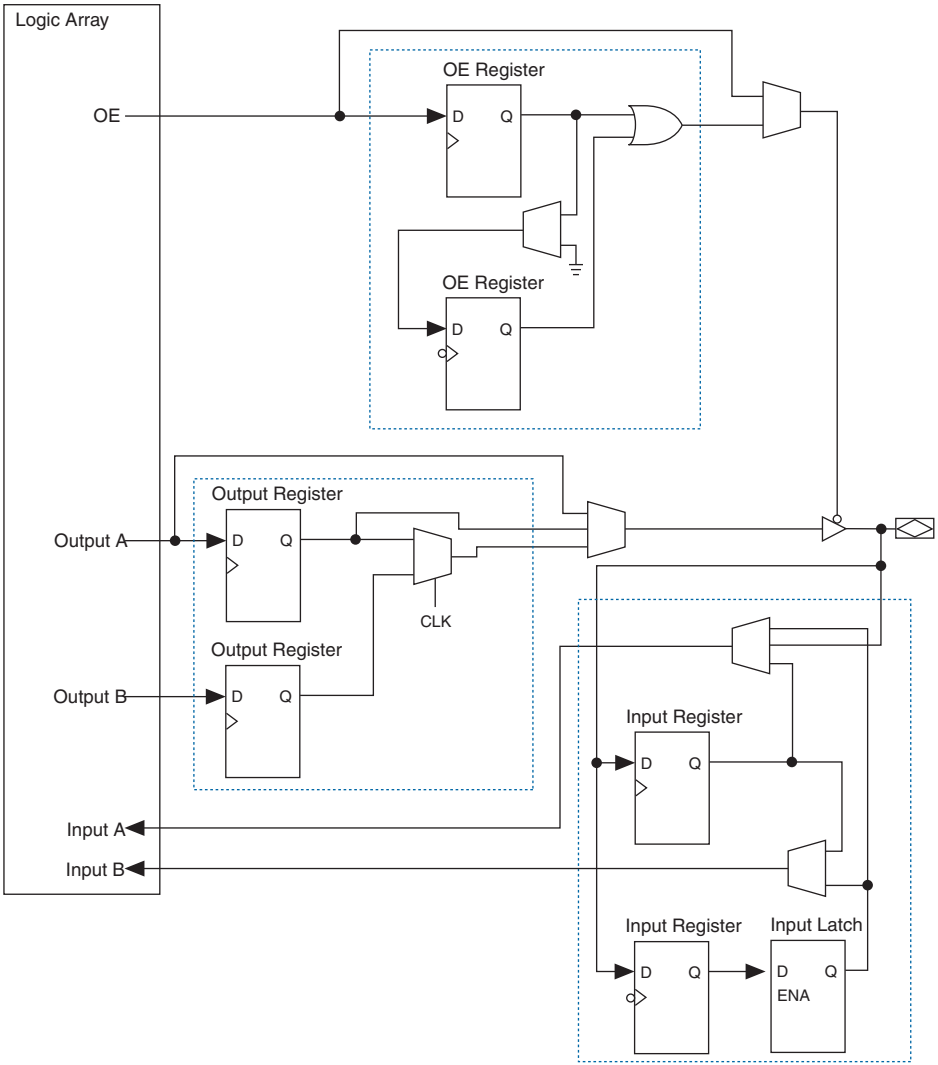
Feature	Global Clocks	Regional Clocks
Number per device	16	32
Number available per quadrant	16	8
Sources	CLK pins, PLL outputs, or internal logic	CLK pins, PLL outputs, or internal logic
Dynamic clock source selection	✓ (1)	
Dynamic enable/disable	✓	✓

Note to Table 2–8:
(1) Dynamic source clock selection is supported for selecting between CLKp pins and PLL outputs only.

Global Clock Network

These clocks drive throughout the entire device, feeding all device quadrants. The global clock networks can be used as clock sources for all resources in the device-IOEs, ALMs, DSP blocks, and all memory blocks. These resources can also be used for control signals, such as clock enables and synchronous or asynchronous clears fed from the external pin. The

Figure 2–46. Stratix II IOE Structure



The IOEs are located in I/O blocks around the periphery of the Stratix II device. There are up to four IOEs per row I/O block and four IOEs per column I/O block. The row I/O blocks drive row, column, or direct link interconnects. The column I/O blocks drive column interconnects. Figure 2–47 shows how a row I/O block connects to the logic array. Figure 2–48 shows how a column I/O block connects to the logic array.

Preliminary status means the timing model is subject to change. Initially, timing numbers are created using simulation results, process data, and other known parameters. These tests are used to make the preliminary numbers as close to the actual timing parameters as possible.

Final timing numbers are based on actual device operation and testing. These numbers reflect the actual performance of the device under worst-case voltage and junction temperature conditions.

Table 5–33. Stratix II Device Timing Model Status

Device	Preliminary	Final
EP2S15		✓
EP2S30		✓
EP2S60		✓
EP2S90		✓
EP2S130		✓
EP2S180		✓

I/O Timing Measurement Methodology

Altera characterizes timing delays at the worst-case process, minimum voltage, and maximum temperature for input register setup time (t_{SU}) and hold time (t_H). The Quartus II software uses the following equations to calculate t_{SU} and t_H timing for Stratix II devices input signals.

t_{SU} = + data delay from input pin to input register
+ micro setup time of the input register
– clock delay from input pin to input register

t_H = – data delay from input pin to input register
+ micro hold time of the input register
+ clock delay from input pin to input register

Figure 5–3 shows the setup and hold timing diagram for input registers.

Table 5–36. Stratix II Performance Notes (Part 3 of 6) *Note (1)*

Applications		Resources Used			Performance				
		ALUTs	TriMatrix Memory Blocks	DSP Blocks	-3 Speed Grade *(2)*	-3 Speed Grade *(3)*	-4 Speed Grade	-5 Speed Grade	Unit
DSP block	9 × 9-bit multiplier *(5)*	0	0	1	430.29	409.16	373.13	320.10	MHz
	18 × 18-bit multiplier *(5)*	0	0	1	410.17	390.01	356.12	305.06	MHz
	18 × 18-bit multiplier *(7)*	0	0	1	450.04	428.08	391.23	335.12	MHz
	36 × 36-bit multiplier *(5)*	0	0	1	250.00	238.15	217.48	186.60	MHz
	36 × 36-bit multiplier *(6)*	0	0	1	410.17	390.01	356.12	305.06	MHz
	18-bit, four-tap FIR filter	0	0	1	410.17	390.01	356.12	305.06	MHz
Larger designs	8-bit,16-tap parallel FIR filter	58	0	4	259.06	240.61	217.15	185.01	MHz
	8-bit, 1024-point, streaming, three multipliers and five adders FFT function	2976	22	9	398.72	364.03	355.23	306.37	MHz
	8-bit, 1024-point, streaming, four multipliers and two adders FFT function	2781	22	12	398.56	409.16	347.22	311.13	MHz
	8-bit, 1024-point, single output, one parallel FFT engine, burst, three multipliers and five adders FFT function	984	5	3	425.17	365.76	346.98	292.39	MHz
	8-bit, 1024-point, single output, one parallel FFT engine, burst, four multipliers and two adders FFT function	919	5	4	427.53	378.78	357.14	307.59	MHz

Table 5–39. DSP Block Internal Timing Microparameters (Part 1 of 2)

Symbol	Parameter	-3 Speed Grade *(1)*		-3 Speed Grade *(2)*		-4 Speed Grade		-5 Speed Grade		Unit
		Min *(3)*	Max	Min *(3)*	Max	Min *(4)*	Max	Min *(3)*	Max	
t_{SU}	Input, pipeline, and output register setup time before clock	50		52		57 57		67		ps
t_{H}	Input, pipeline, and output register hold time after clock	180		189		206 206		241		ps
t_{CO}	Input, pipeline, and output register clock-to-output delay	0	0	0	0	0 0	0	0	0	ps
$t_{INREG2PIPE9}$	Input register to DSP block pipeline register in 9 × 9-bit mode	1,312	2,030	1,312	2,030	1,250 1,312	2,334	1,312	2,720	ps
$t_{INREG2PIPE18}$	Input register to DSP block pipeline register in 18 × 18-bit mode	1,302	2,010	1,302	2,110	1,240 1,302	2,311	1,302	2,693	ps
$t_{INREG2PIPE36}$	Input register to DSP block pipeline register in 36 × 36-bit mode	1,302	2,010	1,302	2,110	1,240 1,302	2,311	1,302	2,693	ps
$t_{PIPE2OUTREG2ADD}$	DSP block pipeline register to output register delay in two-multipliers adder mode	924	1,450	924	1,522	880 924	1,667	924	1,943	ps
$t_{PIPE2OUTREG4ADD}$	DSP block pipeline register to output register delay in four-multipliers adder mode	1,134	1,850	1,134	1,942	1,080 1,134	2,127	1,134	2,479	ps
t_{PD9}	Combinational input to output delay for 9 × 9	2,100	2,880	2,100	3,024	2,000 2,100	3,312	2,100	3,859	ps
t_{PD18}	Combinational input to output delay for 18 × 18	2,110	2,990	2,110	3,139	2,010 2,110	3,438	2,110	4,006	ps
t_{PD36}	Combinational input to output delay for 36 × 36	2,939	4,450	2,939	4,672	2,800 2,939	5,117	2,939	5,962	ps
t_{CLR}	Minimum clear pulse width	2,212		2,322		2,543 2,543		2,964		ps

Table 5–40. M512 Block Internal Timing Microparameters (Part 2 of 2) *Note (1)*

Symbol	Parameter	-3 Speed Grade (2)		-3 Speed Grade (3)		-4 Speed Grade		-5 Speed Grade		Unit
		Min (4)	Max	Min (4)	Max	Min (5)	Max	Min (4)	Max	
$t_{M512DATACO1}$	Clock-to-output delay when using output registers	298	478	298	501	284 298	548	298	640	ps
$t_{M512DATACO2}$	Clock-to-output delay without output registers	2,102	2,345	2,102	2,461	2,003 2,102	2,695	2,102	3,141	ps
$t_{M512CLKL}$	Minimum clock low time	1,315		1,380		1,512 1,512		1,762		ps
$t_{M512CLKH}$	Minimum clock high time	1,315		1,380		1,512 1,512		1,762		ps
$t_{M512CLR}$	Minimum clear pulse width	144		151		165 165		192		ps

Notes to Table 5–40:

(1) F_{MAX} of M512 block obtained using the Quartus II software does not necessarily equal to 1/TM512RC.
(2) These numbers apply to -3 speed grade EP2S15, EP2S30, EP2S60, and EP2S90 devices.
(3) These numbers apply to -3 speed grade EP2S130 and EP2S180 devices.
(4) For the -3 and -5 speed grades, the minimum timing is for the commercial temperature grade. Only -4 speed grade devices offer the industrial temperature grade.
(5) For the -4 speed grade, the first number is the minimum timing parameter for industrial devices. The second number is the minimum timing parameter for commercial devices.

Table 5–41. M4K Block Internal Timing Microparameters (Part 1 of 2) *Note (1)*

Symbol	Parameter	-3 Speed Grade (2)		-3 Speed Grade (3)		-4 Speed Grade		-5 Speed Grade		Unit
		Min (4)	Max	Min (4)	Max	Min (5)	Max	Min (4)	Max	
t_{M4KRC}	Synchronous read cycle time	1,462	2,240	1,462	2,351	1,393 1,462	2,575	1,462	3,000	ps
$t_{M4KWERESU}$	Write or read enable setup time before clock	22		23		25 25		29		ps
$t_{M4KWEREH}$	Write or read enable hold time after clock	203		213		233 233		272		ps
$t_{M4KBESU}$	Byte enable setup time before clock	22		23		25 25		29		ps
t_{M4KBEH}	Byte enable hold time after clock	203		213		233 233		272		ps

Table 5–42. M-RAM Block Internal Timing Microparameters (Part 1 of 2) *Note (1)*

Symbol	Parameter	-3 Speed Grade (2)		-3 Speed Grade (3)		-4 Speed Grade		-5 Speed Grade		Unit
		Min (4)	Max	Min (4)	Max	Min (5)	Max	Min (4)	Max	
t_{MEGARC}	Synchronous read cycle time	1,866	2,774	1,866	2,911	1,777 1,866	3,189	1,777 1,866	3,716	ps
$t_{MEGAWERESU}$	Write or read enable setup time before clock	144		151		165 165		192		ps
$t_{MEGAWEREH}$	Write or read enable hold time after clock	39		40		44 44		52		ps
$t_{MEGABESU}$	Byte enable setup time before clock	50		52		57 57		67		ps
$t_{MEGABEH}$	Byte enable hold time after clock	39		40		44 44		52		ps
$t_{MEGADATAASU}$	A port data setup time before clock	50		52		57 57		67		ps
$t_{MEGADATAAH}$	A port data hold time after clock	243		255		279 279		325		ps
$t_{MEGAADDRASU}$	A port address setup time before clock	589		618		677 677		789		ps
$t_{MEGAADDRAH}$	A port address hold time after clock	241		253		277 277		322		ps
$t_{MEGADATABSU}$	B port setup time before clock	50		52		57 57		67		ps
$t_{MEGADATABH}$	B port hold time after clock	243		255		279 279		325		ps
$t_{MEGAADDRBSU}$	B port address setup time before clock	589		618		677 677		789		ps
$t_{MEGAADDRBH}$	B port address hold time after clock	241		253		277 277		322		ps
$t_{MEGADATACO1}$	Clock-to-output delay when using output registers	480	715	480	749	457 480	821	480	957	ps
$t_{MEGADATACO2}$	Clock-to-output delay without output registers	1,950	2,899	1,950	3,042	1,857 1,950	3,332	1,950	3,884	ps
$t_{MEGACLKL}$	Minimum clock low time	1,250		1,312		1,437 1,437		1,675		ps

Table 5–73. Stratix II I/O Input Delay for Column Pins (Part 2 of 3)

I/O Standard	Parameter	Minimum Timing		-3 Speed Grade (2)	-3 Speed Grade (3)	-4 Speed Grade	-5 Speed Grade	Unit
		Industrial	Commercial					
1.5-V HSTL Class II	t_{PI}	560	587	993	1041	1141	1329	ps
	t_{PCOUT}	294	308	557	584	640	746	ps
1.8-V HSTL Class I	t_{PI}	543	569	898	941	1031	1201	ps
	t_{PCOUT}	277	290	462	484	530	618	ps
1.8-V HSTL Class II	t_{PI}	543	569	898	941	1031	1201	ps
	t_{PCOUT}	277	290	462	484	530	618	ps
PCI	t_{PI}	679	712	1214	1273	1395	1625	ps
	t_{PCOUT}	413	433	778	816	894	1042	ps
PCI-X	t_{PI}	679	712	1214	1273	1395	1625	ps
	t_{PCOUT}	413	433	778	816	894	1042	ps
Differential SSTL-2 Class I (1)	t_{PI}	507	530	818	857	939	1094	ps
	t_{PCOUT}	241	251	382	400	438	511	ps
Differential SSTL-2 Class II (1)	t_{PI}	507	530	818	857	939	1094	ps
	t_{PCOUT}	241	251	382	400	438	511	ps
Differential SSTL-18 Class I (1)	t_{PI}	543	569	898	941	1031	1201	ps
	t_{PCOUT}	277	290	462	484	530	618	ps
Differential SSTL-18 Class II (1)	t_{PI}	543	569	898	941	1031	1201	ps
	t_{PCOUT}	277	290	462	484	530	618	ps
1.8-V Differential HSTL Class I (1)	t_{PI}	543	569	898	941	1031	1201	ps
	t_{PCOUT}	277	290	462	484	530	618	ps
1.8-V Differential HSTL Class II (1)	t_{PI}	543	569	898	941	1031	1201	ps
	t_{PCOUT}	277	290	462	484	530	618	ps
1.5-V Differential HSTL Class I (1)	t_{PI}	560	587	993	1041	1141	1329	ps
	t_{PCOUT}	294	308	557	584	640	746	ps
1.5-V Differential HSTL Class II (1)	t_{PI}	560	587	993	1041	1141	1329	ps
	t_{PCOUT}	294	308	557	584	640	746	ps

Table 5–78. Maximum Output Toggle Rate on Stratix II Devices (Part 2 of 5) *Note (1)*

I/O Standard	Drive Strength	Column I/O Pins (MHz)			Row I/O Pins (MHz)			Clock Outputs (MHz)		
		-3	-4	-5	-3	-4	-5	-3	-4	-5
SSTL-18 Class I	4 mA	200	150	150	200	150	150	200	150	150
	6 mA	350	250	200	350	250	200	350	250	200
	8 mA	450	300	300	450	300	300	450	300	300
	10 mA	500	400	400	500	400	400	500	400	400
	12 mA	700	550	400	-	-	-	650	550	400
SSTL-18 Class II	8 mA	200	200	150	-	-	-	200	200	150
	16 mA	400	350	350	-	-	-	400	350	350
	18 mA	450	400	400	-	-	-	450	400	400
	20 mA	550	500	450	-	-	-	550	500	450
1.8-V HSTL Class I	4 mA	300	300	300	300	300	300	300	300	300
	6 mA	500	450	450	500	450	450	500	450	450
	8 mA	650	600	600	650	600	600	650	600	600
	10 mA	700	650	600	700	650	600	700	650	600
	12 mA	700	700	650	700	700	650	700	700	650
1.8-V HSTL Class II	16 mA	500	500	450	-	-	-	500	500	450
	18 mA	550	500	500	-	-	-	550	500	500
	20 mA	650	550	550	-	-	-	550	550	550
1.5-V HSTL Class I	4 mA	350	300	300	350	300	300	350	300	300
	6 mA	500	500	450	500	500	450	500	500	450
	8 mA	700	650	600	700	650	600	700	650	600
	10 mA	700	700	650	-	-	-	700	700	650
	12 mA	700	700	700	-	-	-	700	700	700
1.5-V HSTL Class II	16 mA	600	600	550	-	-	-	600	600	550
	18 mA	650	600	600	-	-	-	650	600	600
	20 mA	700	650	600	-	-	-	700	650	600
Differential SSTL-2 Class I *(3)*	8 mA	400	300	300	400	300	300	400	300	300
	12 mA	400	400	350	400	400	350	400	400	350
Differential SSTL-2 Class II *(3)*	16 mA	350	350	300	350	350	300	350	350	300
	20 mA	400	350	350	350	350	297	400	350	350
	24 mA	400	400	350	-	-	-	400	400	350

Table 5–78. Maximum Output Toggle Rate on Stratix II Devices (Part 3 of 5) *Note (1)*

I/O Standard	Drive Strength	Column I/O Pins (MHz)			Row I/O Pins (MHz)			Clock Outputs (MHz)		
		-3	-4	-5	-3	-4	-5	-3	-4	-5
Differential SSTL-18 Class I *(3)*	4 mA	200	150	150	200	150	150	200	150	150
	6 mA	350	250	200	350	250	200	350	250	200
	8 mA	450	300	300	450	300	300	450	300	300
	10 mA	500	400	400	500	400	400	500	400	400
	12 mA	700	550	400	350	350	297	650	550	400
Differential SSTL-18 Class II *(3)*	8 mA	200	200	150	-	-	-	200	200	150
	16 mA	400	350	350	-	-	-	400	350	350
	18 mA	450	400	400	-	-	-	450	400	400
	20 mA	550	500	450	-	-	-	550	500	450
1.8-V Differential HSTL Class I *(3)*	4 mA	300	300	300	-	-	-	300	300	300
	6 mA	500	450	450	-	-	-	500	450	450
	8 mA	650	600	600	-	-	-	650	600	600
	10 mA	700	650	600	-	-	-	700	650	600
	12 mA	700	700	650	-	-	-	700	700	650
1.8-V Differential HSTL Class II *(3)*	16 mA	500	500	450	-	-	-	500	500	450
	18 mA	550	500	500	-	-	-	550	500	500
	20 mA	650	550	550	-	-	-	550	550	550
1.5-V Differential HSTL Class I *(3)*	4 mA	350	300	300	-	-	-	350	300	300
	6 mA	500	500	450	-	-	-	500	500	450
	8 mA	700	650	600	-	-	-	700	650	600
	10 mA	700	700	650	-	-	-	700	700	650
	12 mA	700	700	700	-	-	-	700	700	700
1.5-V Differential HSTL Class II *(3)*	16 mA	600	600	550	-	-	-	600	600	550
	18 mA	650	600	600	-	-	-	650	600	600
	20 mA	700	650	600	-	-	-	700	650	600
3.3-V PCI		1,000	790	670	-	-	-	1,000	790	670
3.3-V PCI-X		1,000	790	670	-	-	-	1,000	790	670
LVDS *(6)*		-	-	-	500	500	500	450	400	300
HyperTransport technology *(4)*, *(6)*					500	500	500	-	-	-
LVPECL *(5)*		-	-	-	-	-	-	450	400	300
3.3-V LVTTL	OCT 50 Ω	400	400	350	400	400	350	400	400	350
2.5-V LVTTL	OCT 50 Ω	350	350	300	350	350	300	350	350	300

High-Speed I/O Specifications

Table 5–88 provides high-speed timing specifications definitions.

Table 5–88. High-Speed Timing Specifications & Definitions

High-Speed Timing Specifications	Definitions
t_C	High-speed receiver/transmitter input and output clock period.
f_{HSCLK}	High-speed receiver/transmitter input and output clock frequency.
J	Deserialization factor (width of parallel data bus).
W	PLL multiplication factor.
t_{RISE}	Low-to-high transmission time.
t_{FALL}	High-to-low transmission time.
Timing unit interval (TUI)	The timing budget allowed for skew, propagation delays, and data sampling window. (TUI = 1/(Receiver Input Clock Frequency × Multiplication Factor) = t_C/w).
f_{HSDR}	Maximum/minimum LVDS data transfer rate (f_{HSDR} = 1/TUI), non-DPA.
$f_{HSDRDPA}$	Maximum/minimum LVDS data transfer rate ($f_{HSDRDPA}$ = 1/TUI), DPA.
Channel-to-channel skew (TCCS)	The timing difference between the fastest and slowest output edges, including t_{CO} variation and clock skew. The clock is included in the TCCS measurement.
Sampling window (SW)	The period of time during which the data must be valid in order to capture it correctly. The setup and hold times determine the ideal strobe position within the sampling window.
Input jitter	Peak-to-peak input jitter on high-speed PLLs.
Output jitter	Peak-to-peak output jitter on high-speed PLLs.
t_{DUTY}	Duty cycle on high-speed transmitter output clock.
t_{LOCK}	Lock time for high-speed transmitter and receiver PLLs.

Table 5–89 shows the high-speed I/O timing specifications for -3 speed grade Stratix II devices.

Table 5–89. High-Speed I/O Specifications for -3 Speed Grade (Part 1 of 2) *Notes (1), (2)*

Symbol	Conditions	-3 Speed Grade			Unit
		Min	Typ	Max	
f_{HSCLK} (clock frequency) $f_{HSCLK} = f_{HSDR} / W$	W = 2 to 32 (LVDS, HyperTransport technology) *(3)*	16		520	MHz
	W = 1 (SERDES bypass, LVDS only)	16		500	MHz
	W = 1 (SERDES used, LVDS only)	150		717	MHz

Table 5–103. Document Revision History (Part 2 of 3)

Date and Document Version	Changes Made	Summary of Changes
August, 2006, v4.2	Updated Table 5–73, Table 5–75, Table 5–77, Table 5–78, Table 5–79, Table 5–81, Table 5–85, and Table 5–87.	—
April 2006, v4.1	• Updated Table 5–3. • Updated Table 5–11. • Updated Figures 5–8 and 5–9. • Added parallel on-chip termination information to "On-Chip Termination Specifications" section. • Updated Tables 5–28, 5–30,5–31, and 5–34. • Updated Table 5–78, Tables 5–81 through 5–90, and Tables 5–92, 5–93, and 5–98. • Updated "PLL Timing Specifications" section. • Updated "External Memory Interface Specifications" section. • Added Tables 5–95 and 5–101. • Updated "JTAG Timing Specifications" section, including Figure 5–10 and Table 5–102.	• Changed 0.2 MHz to 2 MHz in Table 5–93. • Added new spec for half period jitter (Table 5–101). • Added support for PLL clock switchover for industrial temperature range. • Changed f_{INPFD} (min) spec from 4 MHz to 2 MHz in Table 5–92. • Fixed typo in $t_{OUTJITTER}$ specification in Table 5–92. • Updated V_{DIF} AC & DC max specifications in Table 5–28. • Updated minimum values for t_{JCH}, t_{JCL}, and t_{JPSU} in Table 5–102. • Update maximum values for t_{JPCO}, t_{JPZX}, and t_{JPXZ} in Table 5–102.
December 2005, v4.0	• Updated "External Memory Interface Specifications" section. • Updated timing numbers throughout chapter.	—
July 2005, v3.1	• Updated HyperTransport technology information in Table 5–13. • Updated "Timing Model" section. • Updated "PLL Timing Specifications" section. • Updated "External Memory Interface Specifications" section.	—
May 2005, v3.0	• Updated tables throughout chapter. • Updated "Power Consumption" section. • Added various tables. • Replaced "Maximum Input & Output Clock Rate" section with "Maximum Input & Output Clock Toggle Rate" section. • Added "Duty Cycle Distortion" section. • Added "External Memory Interface Specifications" section.	—
March 2005, v2.2	Updated tables in "Internal Timing Parameters" section.	—
January 2005, v2.1	Updated input rise and fall time.	—