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Understanding <u>Embedded - FPGAs (Field Programmable Gate Array)</u>

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Obsolete
Number of LABs/CLBs	3022
Number of Logic Elements/Cells	60440
Total RAM Bits	2544192
Number of I/O	334
Number of Gates	-
Voltage - Supply	1.15V ~ 1.25V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	484-BBGA
Supplier Device Package	484-FBGA (23x23)
Purchase URL	https://www.e-xfl.com/product-detail/intel/ep2s60f484c4n

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

signal with asynchronous load data input tied high. When the asynchronous load/preset signal is used, the labclkena0 signal is no longer available.

The LAB row clocks [5..0] and LAB local interconnect generate the LAB-wide control signals. The MultiTrackTM interconnect's inherent low skew allows clock and control signal distribution in addition to data. Figure 2–4 shows the LAB control signal generation circuit.

There are two unique clock signals per LAB. Dedicated Row LAB Clocks Local Interconnect Local Interconnect Local Interconnect Local Interconnect Local Interconnect Local Interconnect labclr1 labclk0 labclk1 labclkena0 labclkena1 labclkena2 labclr0 synclr or asyncload or labpreset

Figure 2-4. LAB-Wide Control Signals

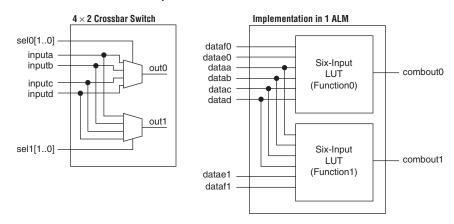
Adaptive Logic Modules

The basic building block of logic in the Stratix II architecture, the adaptive logic module (ALM), provides advanced features with efficient logic utilization. Each ALM contains a variety of look-up table (LUT)-based resources that can be divided between two adaptive LUTs (ALUTs). With up to eight inputs to the two ALUTs, one ALM can implement various combinations of two functions. This adaptability allows the ALM to be

For the packing of two five-input functions into one ALM, the functions must have at least two common inputs. The common inputs are dataa and datab. The combination of a four-input function with a five-input function requires one common input (either dataa or datab).

In the case of implementing two six-input functions in one ALM, four inputs must be shared and the combinational function must be the same. For example, a 4×2 crossbar switch (two 4-to-1 multiplexers with common inputs and unique select lines) can be implemented in one ALM, as shown in Figure 2–8. The shared inputs are dataa, datab, datac, and datad, while the unique select lines are datae0 and dataf0 for function0, and datae1 and dataf1 for function1. This crossbar switch consumes four LUTs in a four-input LUT-based architecture.

Figure 2-8. 4 × 2 Crossbar Switch Example



In a sparsely used device, functions that could be placed into one ALM may be implemented in separate ALMs. The Quartus II Compiler spreads a design out to achieve the best possible performance. As a device begins to fill up, the Quartus II software automatically utilizes the full potential of the Stratix II ALM. The Quartus II Compiler automatically searches for functions of common inputs or completely independent functions to be placed into one ALM and to make efficient use of the device resources. In addition, you can manually control resource usage by setting location assignments.

Any six-input function can be implemented utilizing inputs dataa, datab, datac, datad, and either datae0 and dataf0 or datae1 and dataf1. If datae0 and dataf0 are utilized, the output is driven to register0, and/or register0 is bypassed and the data drives out to the interconnect using the top set of output drivers (see Figure 2–9). If

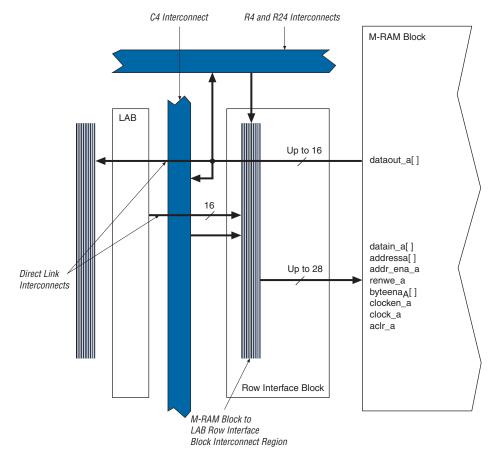


Figure 2–26. M-RAM Row Unit Interface to Interconnect

Table 2–4 shows the input and output data signal connections along with the address and control signal input connections to the row unit interfaces (L0 to L5 and R0 to R5).

The DSP block is divided into four block units that interface with four LAB rows on the left and right. Each block unit can be considered one complete 18×18 -bit multiplier with 36 inputs and 36 outputs. A local interconnect region is associated with each DSP block. Like an LAB, this interconnect region can be fed with 16 direct link interconnects from the LAB to the left or right of the DSP block in the same row. R4 and C4 routing resources can access the DSP block's local interconnect region. The outputs also work similarly to LAB outputs as well. Eighteen outputs from the DSP block can drive to the left LAB through direct link interconnects and eighteen can drive to the right LAB though direct link interconnects. All 36 outputs can drive to R4 and C4 routing interconnects. Outputs can drive right- or left-column routing. Figures 2–29 and 2–30 show the DSP block interfaces to LAB rows.

DSP Block OA[17..0] R4, C4 & Direct R4, C4 & Direct OB[17..0] Link Interconnects \(\) Link Interconnects A1[17..0] B1[17..0] OC[17..0] OD[17..0] A2[17..0] B2[17..0] OE[17..0] OF[17..0] A3[17..0] B3[17..0] OG[17..0] OH[17..0] A4[17..0] B4[17..0]

Figure 2-29. DSP Block Interconnect Interface

PLLs & Clock Networks

Stratix II devices provide a hierarchical clock structure and multiple PLLs with advanced features. The large number of clocking resources in combination with the clock synthesis precision provided by enhanced and fast PLLs provides a complete clock management solution.

Global & Hierarchical Clocking

Stratix II devices provide 16 dedicated global clock networks and 32 regional clock networks (eight per device quadrant). These clocks are organized into a hierarchical clock structure that allows for up to 24 clocks per device region with low skew and delay. This hierarchical clocking scheme provides up to 48 unique clock domains in Stratix II devices.

There are 16 dedicated clock pins (CLK [15..0]) to drive either the global or regional clock networks. Four clock pins drive each side of the device, as shown in Figures 2–31 and 2–32. Internal logic and enhanced and fast PLL outputs can also drive the global and regional clock networks. Each global and regional clock has a clock control block, which controls the selection of the clock source and dynamically enables/disables the clock to reduce power consumption. Table 2–8 shows global and regional clock features.

Table 2–8. Global & Regional Clock Features						
Feature	Global Clocks	Regional Clocks				
Number per device	16	32				
Number available per quadrant	16	8				
Sources	CLK pins, PLL outputs, or internal logic	CLK pins, PLL outputs, or internal logic				
Dynamic clock source selection	√ (1)					
Dynamic enable/disable	✓	✓				

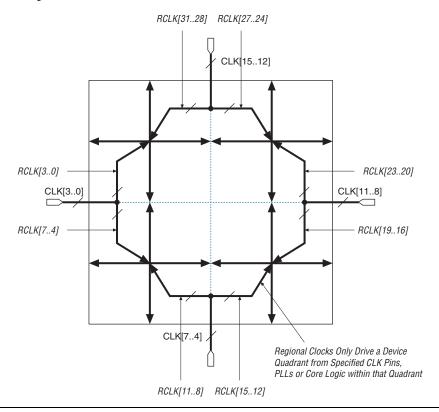
Note to Table 2–8:

 Dynamic source clock selection is supported for selecting between CLKp pins and PLL outputs only.

Global Clock Network

These clocks drive throughout the entire device, feeding all device quadrants. The global clock networks can be used as clock sources for all resources in the device-IOEs, ALMs, DSP blocks, and all memory blocks. These resources can also be used for control signals, such as clock enables and synchronous or asynchronous clears fed from the external pin. The

Figure 2-32. Regional Clocks



Dual-Regional Clock Network

A single source (CLK pin or PLL output) can generate a dual-regional clock by driving two regional clock network lines in adjacent quadrants (one from each quadrant). This allows logic that spans multiple quadrants to utilize the same low skew clock. The routing of this clock signal on an entire side has approximately the same speed but slightly higher clock skew when compared with a clock signal that drives a single quadrant. Internal logic-array routing can also drive a dual-regional clock. Clock pins and enhanced PLL outputs on the top and bottom can drive horizontal dual-regional clocks. Clock pins and fast PLL outputs on the left and right can drive vertical dual-regional clocks, as shown in Figure 2–33. Corner PLLs cannot drive dual-regional clocks.

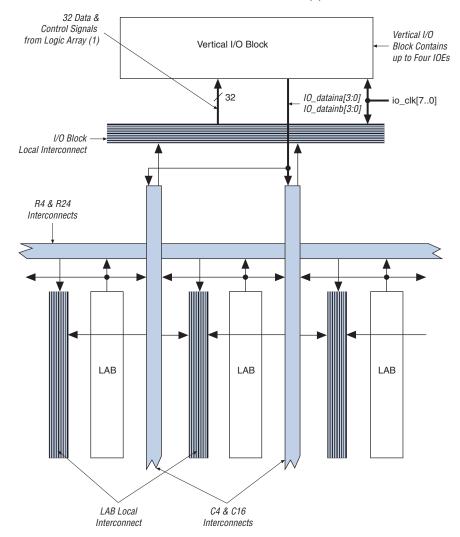


Figure 2–48. Column I/O Block Connection to the Interconnect Note (1)

Note to Figure 2-48:

(1) The 32 data and control signals consist of eight data out lines: four lines each for DDR applications io_dataouta[3..0] and io_dataoutb[3..0], four output enables io_oe[3..0], four input clock enables io_ce_in[3..0], four output clock enables io_ce_out[3..0], four clocks io_clk[3..0], four asynchronous clear and preset signals io_aclr/apreset[3..0], and four synchronous clear and preset signals io sclr/spreset[3..0].

When using the IOE for DDR inputs, the two input registers clock double rate input data on alternating edges. An input latch is also used in the IOE for DDR input acquisition. The latch holds the data that is present during the clock high times. This allows both bits of data to be synchronous with the same clock edge (either rising or falling). Figure 2–52 shows an IOE configured for DDR input. Figure 2–53 shows the DDR input timing diagram.

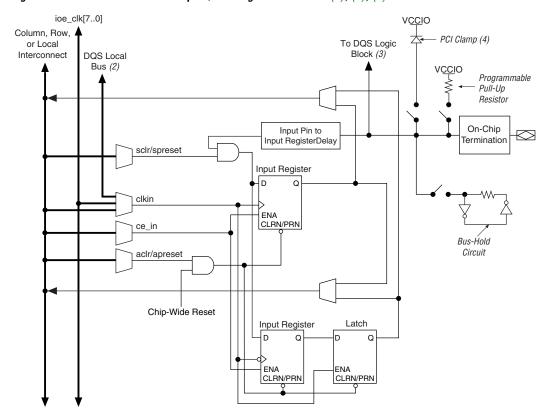


Figure 2–52. Stratix II IOE in DDR Input I/O Configuration Notes (1), (2), (3)

Notes to Figure 2–52:

- (1) All input signals to the IOE can be inverted at the IOE.
- (2) This signal connection is only allowed on dedicated DQ function pins.
- (3) This signal is for dedicated DQS function pins only.
- (4) The optional PCI clamp is only available on column I/O pins.

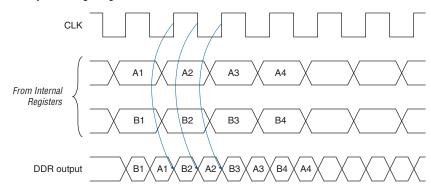


Figure 2-55. Output Timing Diagram in DDR Mode

The Stratix II IOE operates in bidirectional DDR mode by combining the DDR input and DDR output configurations. The negative-edge-clocked OE register holds the OE signal inactive until the falling edge of the clock. This is done to meet DDR SDRAM timing requirements.

External RAM Interfacing

In addition to the six I/O registers in each IOE, Stratix II devices also have dedicated phase-shift circuitry for interfacing with external memory interfaces. Stratix II devices support DDR and DDR2 SDRAM, QDR II SRAM, RLDRAM II, and SDR SDRAM memory interfaces. In every Stratix II device, the I/O banks at the top (banks 3 and 4) and bottom (banks 7 and 8) of the device support DQ and DQS signals with DQ bus modes of $\times 4$, $\times 8/\times 9$, $\times 16/\times 18$, or $\times 32/\times 36$. Table 2–14 shows the number of DQ and DQS buses that are supported per device.

Table 2-	Table 2–14. DQS & DQ Bus Mode Support (Part 1 of 2) Note (1)						
Device	Package	Number of ×4 Groups	Number of ×8/×9 Groups	Number of ×16/×18 Groups	Number of ×32/×36 Groups		
EP2S15	484-pin FineLine BGA	8	4	0	0		
	672-pin FineLine BGA	18	8	4	0		
EP2S30	484-pin FineLine BGA	8	4	0	0		
	672-pin FineLine BGA	18	8	4	0		
EP2S60	484-pin FineLine BGA	8	4	0	0		
	672-pin FineLine BGA	18	8	4	0		
	1,020-pin FineLine BGA	36	18	8	4		

Table 2–16. Stratix II Supp	oorted I/O Standards	(Part 2 of 2)				
I/O Standard	I/O Standard Type Input Reference Voltage (V _{REF}) (V) Voltage (V _{CCIO}) (V) Board Terminatio Voltage (V _{TT}) (V					
SSTL-2 Class I and II	Voltage-referenced 1.25 2.5 1.25					

Notes to Table 2–16:

- (1) This I/O standard is only available on input and output column clock pins.
- (2) This I/O standard is only available on input clock pins and DQS pins in I/O banks 3, 4, 7, and 8, and output clock pins in I/O banks 9,10, 11, and 12.
- (3) V_{CCIO} is 3.3 V when using this I/O standard in input and output column clock pins (in I/O banks 9, 10, 11, and 12). The clock input pins supporting LVDS on banks 3, 4, 7, and 8 use V_{CCINT} for LVDS input operations and have no dependency on the V_{CCIO} level of the bank.
- (4) 1.2-V HSTL is only supported in I/O banks 4,7, and 8.



For more information on I/O standards supported by Stratix II I/O banks, refer to the *Selectable I/O Standards in Stratix II & Stratix II GX Devices* chapter in volume 2 of the *Stratix II Device Handbook* or the *Stratix II GX Device Handbook*.

Stratix II devices contain eight I/O banks and four enhanced PLL external clock output banks, as shown in Figure 2–57. The four I/O banks on the right and left of the device contain circuitry to support high-speed differential I/O for LVDS and HyperTransport inputs and outputs. These banks support all Stratix II I/O standards except PCI or PCI-X I/O pins, and SSTL-18 Class II and HSTL outputs. The top and bottom I/O banks support all single-ended I/O standards. Additionally, enhanced PLL external clock output banks allow clock output capabilities such as differential support for SSTL and HSTL.

Each I/O bank has its own VCCIO pins. A single device can support 1.5-, 1.8-, 2.5-, and 3.3-V interfaces; each bank can support a different $V_{\rm CCIO}$ level independently. Each bank also has dedicated VREF pins to support the voltage-referenced standards (such as SSTL-2). The PLL banks utilize the adjacent VREF group when voltage-referenced standards are implemented. For example, if an SSTL input is implemented in PLL bank 10, the voltage level at VREFB7 is the reference voltage level for the SSTL input.

I/O pins that reside in PLL banks 9 through 12 are powered by the VCC_PLL<5, 6, 11, or 12>_OUT pins, respectively. The EP2S60F484, EP2S60F780, EP2S90H484, EP2S90F780, and EP2S130F780 devices do not support PLLs 11 and 12. Therefore, any I/O pins that reside in bank 11 are powered by the VCCIO3 pin, and any I/O pins that reside in bank 12 are powered by the VCCIO8 pin.

Each I/O bank can support multiple standards with the same $V_{\rm CCIO}$ for input and output pins. Each bank can support one $V_{\rm REF}$ voltage level. For example, when $V_{\rm CCIO}$ is 3.3 V, a bank can support LVTTL, LVCMOS, and 3.3-V PCI for inputs and outputs.

On-Chip Termination

Stratix II devices provide differential (for the LVDS or HyperTransport technology I/O standard), series, and parallel on-chip termination to reduce reflections and maintain signal integrity. On-chip termination simplifies board design by minimizing the number of external termination resistors required. Termination can be placed inside the package, eliminating small stubs that can still lead to reflections.

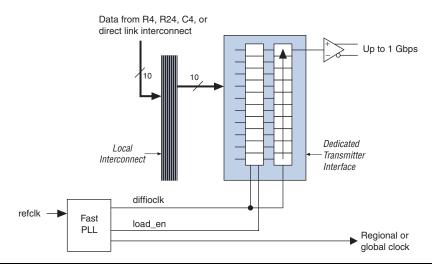
Stratix II devices provide four types of termination:

- Differential termination (R_D)
- Series termination (R_s) without calibration
- Series termination (R_S) with calibration
- Parallel termination (R_T) with calibration

Dedicated Circuitry with DPA Support

Stratix II devices support source-synchronous interfacing with LVDS or HyperTransport signaling at up to 1 Gbps. Stratix II devices can transmit or receive serial channels along with a low-speed or high-speed clock. The receiving device PLL multiplies the clock by an integer factor W = 1 through 32. For example, a HyperTransport technology application where the data rate is 1,000 Mbps and the clock rate is 500 MHz would require that W be set to 2. The SERDES factor *J* determines the parallel data width to deserialize from receivers or to serialize for transmitters. The SERDES factor *J* can be set to 4, 5, 6, 7, 8, 9, or 10 and does not have to equal the PLL clock-multiplication W value. A design using the dynamic phase aligner also supports all of these *J* factor values. For a *J* factor of 1, the Stratix II device bypasses the SERDES block. For a *J* factor of 2, the Stratix II device bypasses the SERDES block, and the DDR input and output registers are used in the IOE. Figure 2–58 shows the block diagram of the Stratix II transmitter channel.

Figure 2-58. Stratix II Transmitter Channel



Each Stratix II receiver channel features a DPA block for phase detection and selection, a SERDES, a synchronizer, and a data realigner circuit. You can bypass the dynamic phase aligner without affecting the basic source-synchronous operation of the channel. In addition, you can dynamically switch between using the DPA block or bypassing the block via a control signal from the logic array. Figure 2–59 shows the block diagram of the Stratix II receiver channel.

The temperature-sensing diode works for the entire operating range, as shown in Figure 3–2.

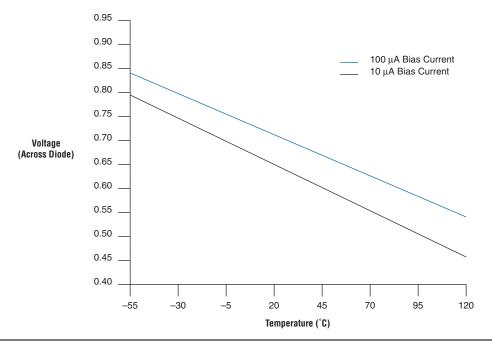


Figure 3–2. Temperature vs. Temperature-Sensing Diode Voltage

The temperature sensing diode is a very sensitive circuit which can be influenced by noise coupled from other traces on the board, and possibly within the device package itself, depending on device usage. The interfacing device registers temperature based on milivolts of difference as seen at the TSD. Switching I/O near the TSD pins can affect the temperature reading. Altera recommends you take temperature readings during periods of no activity in the device (for example, standby mode where no clocks are toggling in the device), such as when the nearby I/Os are at a DC state, and disable clock networks in the device.

Automated Single Event Upset (SEU) Detection Stratix II devices offer on-chip circuitry for automated checking of single event upset (SEU) detection. Some applications that require the device to operate error free at high elevations or in close proximity to Earth's North or South Pole require periodic checks to ensure continued data integrity. The error detection cyclic redundancy check (CRC) feature controlled by

Devices Can Be Driven Before Power-Up

You can drive signals into the I/O pins, dedicated input pins and dedicated clock pins of Stratix II devices before or during power-up or power-down without damaging the device. Stratix II devices support any power-up or power-down sequence (V_{CCIO} , V_{CCINT} , and V_{CCPD}) in order to simplify system level design.

I/O Pins Remain Tri-Stated During Power-Up

A device that does not support hot-socketing may interrupt system operation or cause contention by driving out before or during power-up. In a hot socketing situation, Stratix II device's output buffers are turned off during system power-up or power-down. Stratix II device also does not drive out until the device is configured and has attained proper operating conditions.

Signal Pins Do Not Drive the $V_{\text{CCIO}},\,V_{\text{CCINT}}$ or V_{CCPD} Power Supplies

Devices that do not support hot-socketing can short power supplies together when powered-up through the device signal pins. This irregular power-up can damage both the driving and driven devices and can disrupt card power-up.

Stratix II devices do not have a current path from I/O pins, dedicated input pins, or dedicated clock pins to the V_{CCIO} , V_{CCINT} , or V_{CCPD} pins before or during power-up. A Stratix II device may be inserted into (or removed from) a powered-up system board without damaging or interfering with system-board operation. When hot-socketing, Stratix II devices may have a minimal effect on the signal integrity of the backplane.



You can power up or power down the $V_{\rm CCIO}$, $V_{\rm CCINT}$, and $V_{\rm CCPD}$ pins in any sequence. The power supply ramp rates can range from 100 μ s to 100 ms. All $V_{\rm CC}$ supplies must power down within 100 ms of each other to prevent I/O pins from driving out. During hot socketing, the I/O pin capacitance is less than 15 pF and the clock pin capacitance is less than 20 pF. Stratix II devices meet the following hot socketing specification.

- The hot socketing DC specification is: $|I_{IOPIN}| < 300 \,\mu\text{A}$.
- The hot socketing AC specification is: | I_{IOPIN} | < 8 mA for 10 ns or less.</p>

Table 5–34. Output Timing Measurement Methodology for Output Pins Notes (1), (2), (3)							?)
I/O Standard		Measurement Point					
	R _δ (Ω)	$R_D(\Omega)$	$R_T(\Omega)$	V _{CCIO} (V)	V _{TT} (V)	C _L (pF)	V _{MEAS} (V)
LVTTL (4)				3.135		0	1.5675
LVCMOS (4)				3.135		0	1.5675
2.5 V (4)				2.375		0	1.1875
1.8 V (4)				1.710		0	0.855
1.5 V (4)				1.425		0	0.7125
PCI (5)				2.970		10	1.485
PCI-X (5)				2.970		10	1.485
SSTL-2 Class I	25		50	2.325	1.123	0	1.1625
SSTL-2 Class II	25		25	2.325	1.123	0	1.1625
SSTL-18 Class I	25		50	1.660	0.790	0	0.83
SSTL-18 Class II	25		25	1.660	0.790	0	0.83
1.8-V HSTL Class I	50		50	1.660	0.790	0	0.83
1.8-V HSTL Class II	25		25	1.660	0.790	0	0.83
1.5-V HSTL Class I	50		50	1.375	0.648	0	0.6875
1.5-V HSTL Class II			25	1.375	0.648	0	0.6875
1.2-V HSTL with OCT	50			1.140		0	0.570
Differential SSTL-2 Class I	50		50	2.325	1.123	0	1.1625
Differential SSTL-2 Class II	25		25	2.325	1.123	0	1.1625
Differential SSTL-18 Class I	50		50	1.660	0.790	0	0.83
Differential SSTL-18 Class II	25		25	1.660	0.790	0	0.83
1.5-V Differential HSTL Class I	50		50	1.375	0.648	0	0.6875
1.5-V Differential HSTL Class II			25	1.375	0.648	0	0.6875
1.8-V Differential HSTL Class I	50		50	1.660	0.790	0	0.83
1.8-V Differential HSTL Class II	25		25	1.660	0.790	0	0.83
LVDS		100		2.325		0	1.1625
HyperTransport		100		2.325		0	1.1625
LVPECL		100		3.135		0	1.5675

Notes to Table 5–34:

- (1) Input measurement point at internal node is $0.5 \times V_{CCINT}$.
- (2) Output measuring point for V_{MEAS} at buffer output is $0.5 \times V_{\text{CCIO}}.$
- (3) Input stimulus edge rate is 0 to V_{CC} in 0.2 ns (internal signal) from the driver preceding the I/O buffer.
- (4) Less than 50-mV ripple on V_{CCIO} and V_{CCPD} , V_{CCINT} = 1.15 V with less than 30-mV ripple
- (5) $V_{CCPD} = 2.97 \text{ V}$, less than 50-mV ripple on V_{CCIO} and V_{CCPD} , $V_{CCINT} = 1.15 \text{ V}$

Table 5–65. EP2S180 Column Pins Global Clock Timing Parameters						
Parameter	Minimu	Minimum Timing		-4 Speed	-5 Speed	Unit
rarameter	Industrial	Commercial	Grade	Grade	Grade	Unit
t _{CIN}	2.003	2.100	3.652	3.993	4.648	ns
t _{COUT}	1.846	1.935	3.398	3.715	4.324	ns
t _{PLLCIN}	-0.3	-0.29	0.053	0.054	0.058	ns
t _{PLLCOUT}	-0.457	-0.455	-0.201	-0.224	-0.266	ns

Table 5-66. EP2S	Table 5–66. EP2S180 Row Pins Regional Clock Timing Parameters						
Parameter	Minimu	m Timing	-3 Speed	-4 Speed	-5 Speed	Unit	
raiaillelei	Industrial	Commercial	Grade	Grade	Grade	Unit	
t _{CIN}	1.759	1.844	3.273	3.577	4.162	ns	
t _{COUT}	1.764	1.849	3.269	3.573	4.157	ns	
t _{PLLCIN}	-0.542	-0.541	-0.317	-0.353	-0.414	ns	
t _{PLLCOUT}	-0.537	-0.536	-0.321	-0.357	-0.419	ns	

Table 5–67. EP2S180 Row Pins Global Clock Timing Parameters						
Parameter	Minimu	m Timing	-3 Speed	-4 Speed	-5 Speed	Unit
Farameter	Industrial	Commercial	Grade	Grade	Grade	Ullit
t _{CIN}	1.763	1.850	3.285	3.588	4.176	ns
t _{COUT}	1.768	1.855	3.281	3.584	4.171	ns
t _{PLLCIN}	-0.542	-0.542	-0.319	-0.355	-0.42	ns
t _{PLLCOUT}	-0.537	-0.537	-0.323	-0.359	-0.425	ns

Table 5–73. Stratix II I/O Input Delay for Column Pins (Part 3 of 3)								
I/O Ctondovd	Davamatav	Minimur	Minimum Timing		-3 Speed	-4 Speed	-5 Speed	11!4
I/O Standard	Parameter	Industrial	Commercial	Grade (2)	Grade (3)	Grade	Grade	Unit
1.2-V HSTL	t _{P1}	645	677	1194	1252	-	-	ps
	t _{PCOUT}	379	398	758	795	-	-	ps

Notes for Table 5-73:

- (1) These I/O standards are only supported on DQS pins.
- (2) These numbers apply to -3 speed grade EP2S15, EP2S30, EP2S60, and EP2S90 devices.
- (3) These numbers apply to -3 speed grade EP2S130 and EP2S180 devices.

Table 5–74. Stratix II I/O Input Delay for Row Pins (Part 1 of 2)								
I/O Standard	Parameter	Minimu	m Timing	-3 Speed Grade	-3 Speed Grade	-4 Speed	-5 Speed	Unit
i/O Stanuaru	i arameter	Industrial	Commercial	(1)	<i>(2)</i>	Grade	Grade	Ullit
LVTTL	t _{Pl}	715	749	1287	1350	1477	1723	ps
	t _{PCOUT}	391	410	760	798	873	1018	ps
2.5 V	t _{Pl}	726	761	1273	1335	1461	1704	ps
	t _{PCOUT}	402	422	746	783	857	999	ps
1.8 V	t _{PI}	788	827	1427	1497	1639	1911	ps
	t _{PCOUT}	464	488	900	945	1035	1206	ps
1.5 V	t _{Pl}	792	830	1498	1571	1720	2006	ps
	t _{PCOUT}	468	491	971	1019	1116	1301	ps
LVCMOS	t _{Pl}	715	749	1287	1350	1477	1723	ps
	t _{PCOUT}	391	410	760	798	873	1018	ps
SSTL-2 Class I	t _{Pl}	547	573	879	921	1008	1176	ps
	t _{PCOUT}	223	234	352	369	404	471	ps
SSTL-2 Class II	t _{Pl}	547	573	879	921	1008	1176	ps
	t _{PCOUT}	223	234	352	369	404	471	ps
SSTL-18 Class I	t _{Pl}	577	605	960	1006	1101	1285	ps
	t _{PCOUT}	253	266	433	454	497	580	ps
SSTL-18 Class II	t _{Pl}	577	605	960	1006	1101	1285	ps
	t _{PCOUT}	253	266	433	454	497	580	ps
1.5-V HSTL	t _{Pl}	602	631	1056	1107	1212	1413	ps
Class I	t _{PCOUT}	278	292	529	555	608	708	ps

Table 5–79. Max	Table 5–79. Maximum Output Clock Toggle Rate Derating Factors (Part 3 of 5)										
		Maximum Output Clock Toggle Rate Derating Factors (ps/pF)									
I/O Standard	Drive Strength	Column I/O Pins			Row I/O Pins			Dedicated Clock Outputs			
	3.	-3	-4	-5	-3	-4	-5	-3	-4	-5	
SSTL-18 Class I	4 mA	458	570	570	458	570	570	505	570	570	
	6 mA	305	380	380	305	380	380	336	380	380	
	8 mA	225	282	282	225	282	282	248	282	282	
	10 mA	167	220	220	167	220	220	190	220	220	
	12 mA	129	175	175	-	-	-	148	175	175	
SSTL-18 Class II	8 mA	173	206	206	-	-	-	155	206	206	
	16 mA	150	160	160	-	-	-	140	160	160	
	18 mA	120	130	130	-	-	-	110	130	130	
	20 mA	109	127	127	-	-	-	94	127	127	
1.8-V HSTL	4 mA	245	282	282	245	282	282	229	282	282	
Class I	6 mA	164	188	188	164	188	188	153	188	188	
	8 mA	123	140	140	123	140	140	114	140	140	
	10 mA	110	124	124	110	124	124	108	124	124	
	12 mA	97	110	110	97	110	110	104	110	110	
1.8-V HSTL	16 mA	101	104	104	-	-	-	99	104	104	
Class II	18 mA	98	102	102	-	-	-	93	102	102	
	20 mA	93	99	99	-	-	-	88	99	99	
1.5-V HSTL	4 mA	168	196	196	168	196	196	188	196	196	
Class I	6 mA	112	131	131	112	131	131	125	131	131	
	8 mA	84	99	99	84	99	99	95	99	99	
	10 mA	87	98	98	-	-	-	90	98	98	
	12 mA	86	98	98	-	-	-	87	98	98	
1.5-V HSTL	16 mA	95	101	101	-	-	-	96	101	101	
Class II	18 mA	95	100	100	-	-	-	101	100	100	
	20 mA	94	101	101	-	-	-	104	101	101	
Differential	8 mA	364	680	680	-	-	-	350	680	680	
SSTL-2 Class II	12 mA	163	207	207	-	-	-	188	207	207	
(3)	16 mA	118	147	147	-	-	-	94	147	147	
	20 mA	99	122	122	-	-	-	87	122	122	
	24 mA	91	116	116	-	-	-	85	116	116	

High-Speed I/O Specifications

Table 5–88 provides high-speed timing specifications definitions.

Table 5–88. High-Speed Timing Specifications & Definitions					
High-Speed Timing Specifications	Definitions				
t _C	High-speed receiver/transmitter input and output clock period.				
f _{HSCLK}	High-speed receiver/transmitter input and output clock frequency.				
J	Deserialization factor (width of parallel data bus).				
W	PLL multiplication factor.				
t _{RISE}	Low-to-high transmission time.				
t _{FALL}	High-to-low transmission time.				
Timing unit interval (TUI)	The timing budget allowed for skew, propagation delays, and data sampling window. (TUI = $1/(\text{Receiver Input Clock Frequency} \times \text{Multiplication Factor}) = t_{\text{C}}/w$).				
f _{HSDR}	Maximum/minimum LVDS data transfer rate (f _{HSDR} = 1/TUI), non-DPA.				
f _{HSDRDPA}	Maximum/minimum LVDS data transfer rate (f _{HSDRDPA} = 1/TUI), DPA.				
Channel-to-channel skew (TCCS)	The timing difference between the fastest and slowest output edges, including t_{CO} variation and clock skew. The clock is included in the TCCS measurement.				
Sampling window (SW)	The period of time during which the data must be valid in order to capture it correctly. The setup and hold times determine the ideal strobe position within the sampling window.				
Input jitter	Peak-to-peak input jitter on high-speed PLLs.				
Output jitter	Peak-to-peak output jitter on high-speed PLLs.				
t _{DUTY}	Duty cycle on high-speed transmitter output clock.				
t _{LOCK}	Lock time for high-speed transmitter and receiver PLLs.				

Table 5–89 shows the high-speed I/O timing specifications for -3 speed grade Stratix II devices.

Table 5–89. High-Speed I/O Specifications for -3 Speed Grade (Part 1 of 2) Notes (1), (2)							
Symbol	Conditions	-3 Speed Grade			Unit		
		Min	Тур	Max	Uiill		
f_{HSCLK} (clock frequency) $f_{HSCLK} = f_{HSDR} / W$	W = 2 to 32 (LVDS, HyperTransport technology) (3)	16		520	MHz		
	W = 1 (SERDES bypass, LVDS only)	16		500	MHz		
	W = 1 (SERDES used, LVDS only)	150		717	MHz		

Table 5–103. Document Revision History (Part 2 of 3)						
Date and Document Version	Changes Made	Summary of Changes				
August, 2006, v4.2	Updated Table 5–73, Table 5–75, Table 5–77, Table 5–78, Table 5–79, Table 5–81, Table 5–85, and Table 5–87.	_				
April 2006, v4.1	 Updated Table 5–3. Updated Table 5–11. Updated Figures 5–8 and 5–9. Added parallel on-chip termination information to "On-Chip Termination Specifications" section. Updated Tables 5–28, 5–30,5–31, and 5–34. Updated Table 5–78, Tables 5–81 through 5–90, and Tables 5–92, 5–93, and 5–98. Updated "PLL Timing Specifications" section. Updated "External Memory Interface Specifications" section. Added Tables 5–95 and 5–101. Updated "JTAG Timing Specifications" section, including Figure 5–10 and Table 5–102. 	 Changed 0.2 MHz to 2 MHz in Table 5–93. Added new spec for half period jitter (Table 5–101). Added support for PLL clock switchover for industrial temperature range. Changed f_{INPFD} (min) spec from 4 MHz to 2 MHz in Table 5–92. Fixed typo in t_{OUTJITTER} specification in Table 5–92. Updated V_{DIF} AC & DC max specifications in Table 5–28. Updated minimum values for t_{JCH}, t_{JCL}, and t_{JPSU} in Table 5–102. Update maximum values for t_{JPCO}, t_{JPZX}, and t_{JPXZ} in Table 5–102. 				
December 2005, v4.0	 Updated "External Memory Interface Specifications" section. Updated timing numbers throughout chapter. 	_				
July 2005, v3.1	 Updated HyperTransport technology information in Table 5–13. Updated "Timing Model" section. Updated "PLL Timing Specifications" section. Updated "External Memory Interface Specifications" section. 	_				
May 2005, v3.0	 Updated tables throughout chapter. Updated "Power Consumption" section. Added various tables. Replaced "Maximum Input & Output Clock Rate" section with "Maximum Input & Output Clock Toggle Rate" section. Added "Duty Cycle Distortion" section. Added "External Memory Interface Specifications" section. 	_				
March 2005, v2.2	Updated tables in "Internal Timing Parameters" section.	_				
January 2005, v2.1	Updated input rise and fall time.	_				