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### Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

### Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

#### Details

Product Status	Obsolete
Number of LABs/CLBs	3022
Number of Logic Elements/Cells	60440
Total RAM Bits	2544192
Number of I/O	334
Number of Gates	-
Voltage - Supply	1.15V ~ 1.25V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	484-BBGA
Supplier Device Package	484-FBGA (23x23)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/intel/ep2s60f484i4n">https://www.e-xfl.com/product-detail/intel/ep2s60f484i4n</a>

## Document Revision History

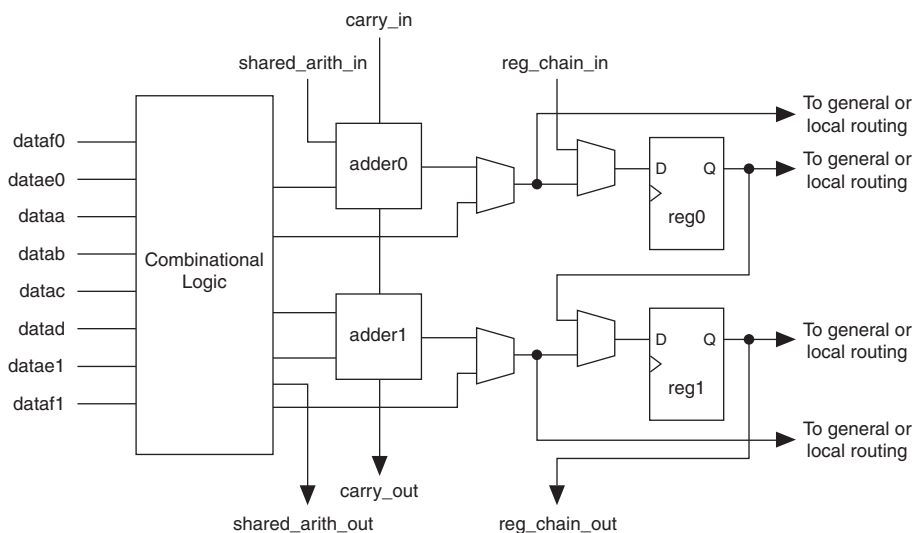
Table 1–6 shows the revision history for this chapter.

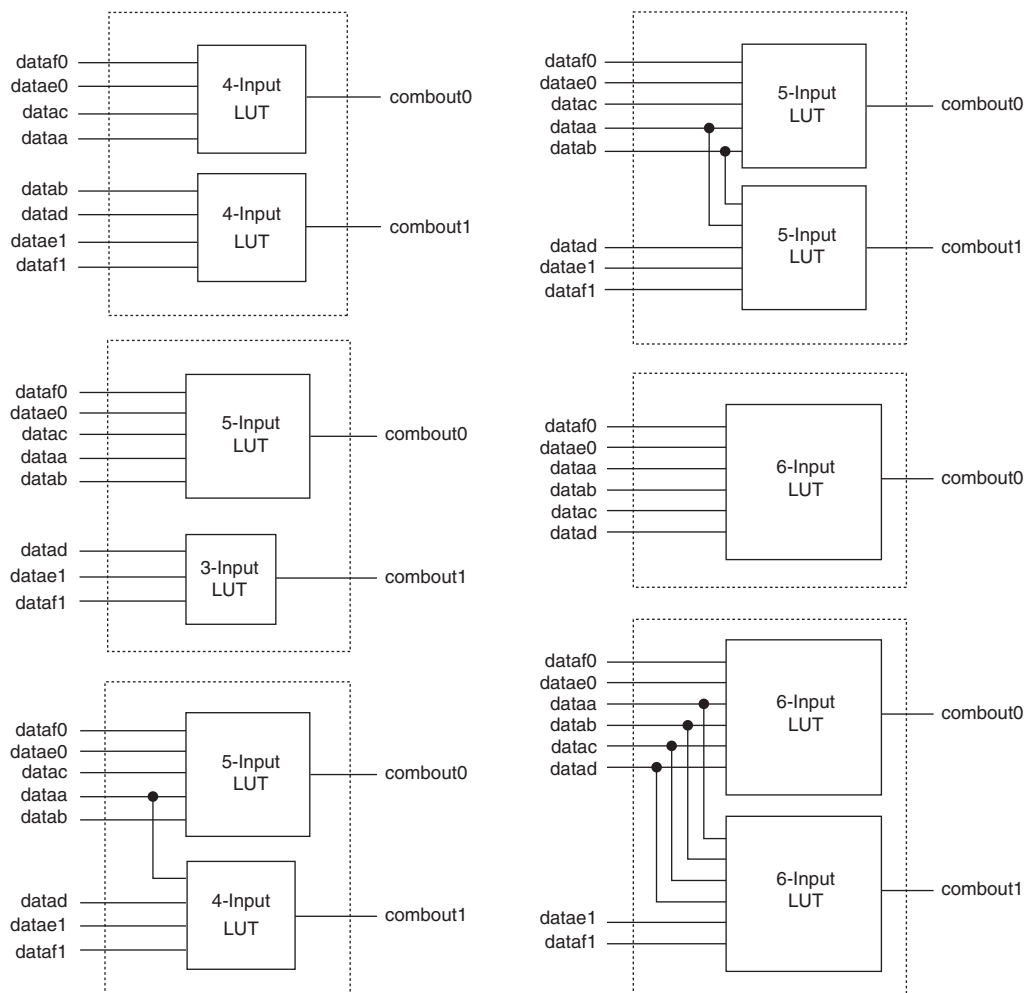
<b>Table 1–6. Document Revision History</b>		
<b>Date and Document Version</b>	<b>Changes Made</b>	<b>Summary of Changes</b>
May 2007, v4.2	Moved Document Revision History to the end of the chapter.	—
April 2006, v4.1	<ul style="list-style-type: none"> <li>• Updated “Features” section.</li> <li>• Removed Note 4 from Table 1–2.</li> <li>• Updated Table 1–4.</li> </ul>	—
December 2005, v4.0	<ul style="list-style-type: none"> <li>• Updated Tables 1–2, 1–4, and 1–5.</li> <li>• Updated Figure 2–43.</li> </ul>	—
July 2005, v3.1	<ul style="list-style-type: none"> <li>• Added vertical migration information, including Table 1–4.</li> <li>• Updated Table 1–5.</li> </ul>	—
May 2005, v3.0	<ul style="list-style-type: none"> <li>• Updated “Features” section.</li> <li>• Updated Table 1–2.</li> </ul>	—
March 2005, v2.1	Updated “Introduction” and “Features” sections.	—
January 2005, v2.0	Added note to Table 1–2.	—
October 2004, v1.2	Updated Tables 1–2, 1–3, and 1–5.	—
July 2004, v1.1	<ul style="list-style-type: none"> <li>• Updated Tables 1–1 and 1–2.</li> <li>• Updated “Features” section.</li> </ul>	—
February 2004, v1.0	Added document to the Stratix II Device Handbook.	—

completely backward-compatible with four-input LUT architectures. One ALM can also implement any function of up to six inputs and certain seven-input functions.

In addition to the adaptive LUT-based resources, each ALM contains two programmable registers, two dedicated full adders, a carry chain, a shared arithmetic chain, and a register chain. Through these dedicated resources, the ALM can efficiently implement various arithmetic functions and shift registers. Each ALM drives all types of interconnects: local, row, column, carry chain, shared arithmetic chain, register chain, and direct link interconnects. [Figure 2-5](#) shows a high-level block diagram of the Stratix II ALM while [Figure 2-6](#) shows a detailed view of all the connections in the ALM.

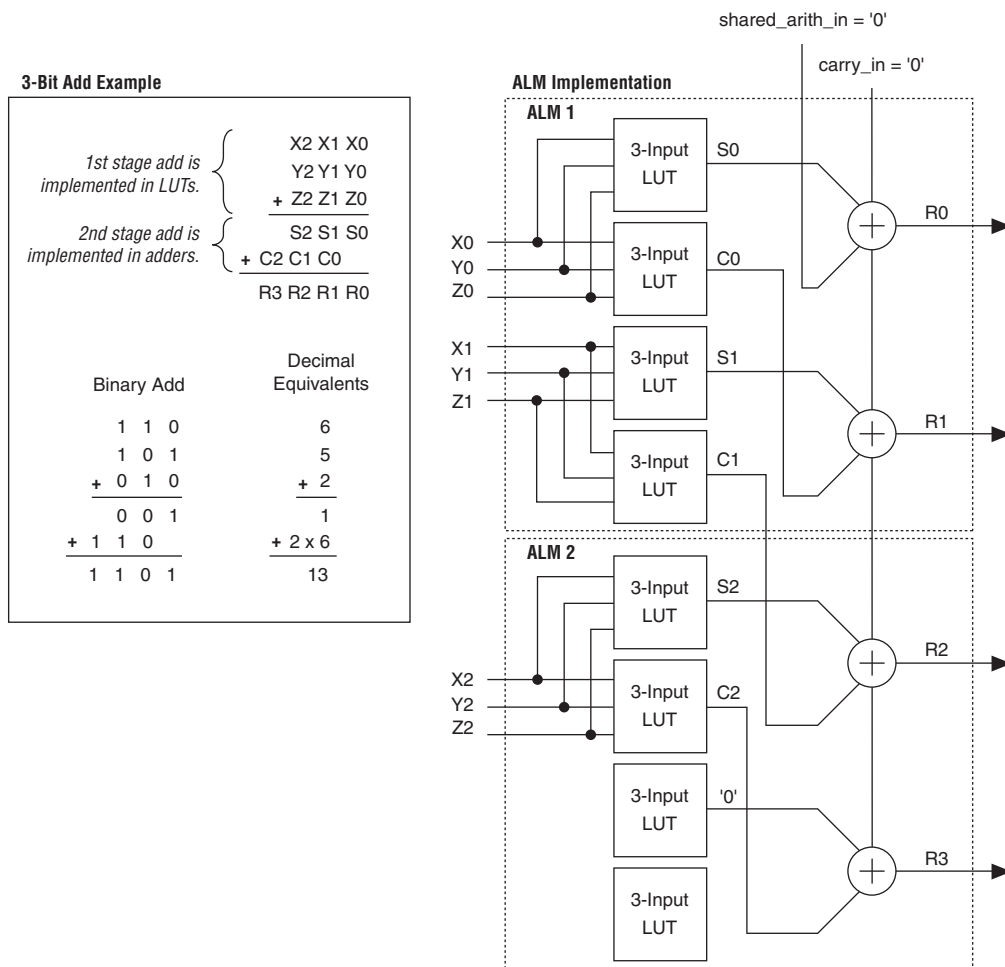
**Figure 2-5. High-Level Block Diagram of the Stratix II ALM**



**Figure 2–7. ALM in Normal Mode** *Note (1)***Note to Figure 2–7:**

- (1) Combinations of functions with fewer inputs than those shown are also supported. For example, combinations of functions with the following number of inputs are supported: 4 and 3, 3 and 3, 3 and 2, 5 and 2, etc.

The normal mode provides complete backward compatibility with four-input LUT architectures. Two independent functions of four inputs or less can be implemented in one Stratix II ALM. In addition, a five-input function and an independent three-input function can be implemented without sharing inputs.

**Figure 2–14. Example of a 3-bit Add Utilizing Shared Arithmetic Mode**

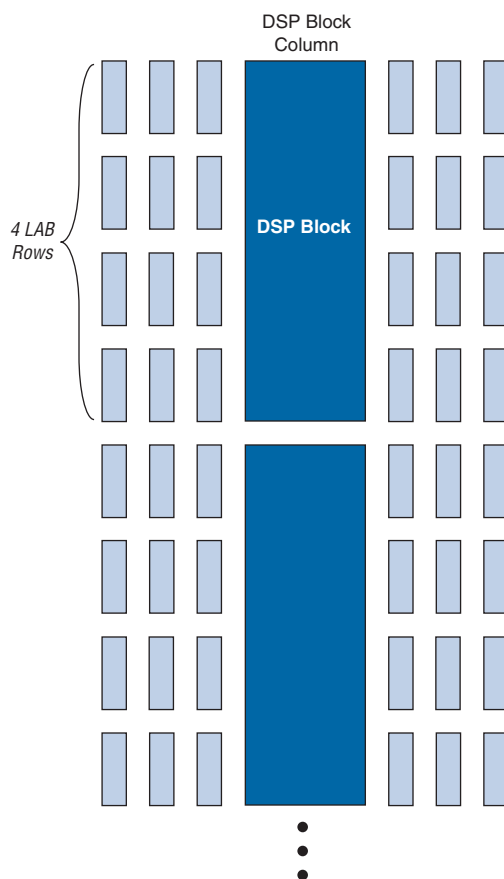
### Shared Arithmetic Chain

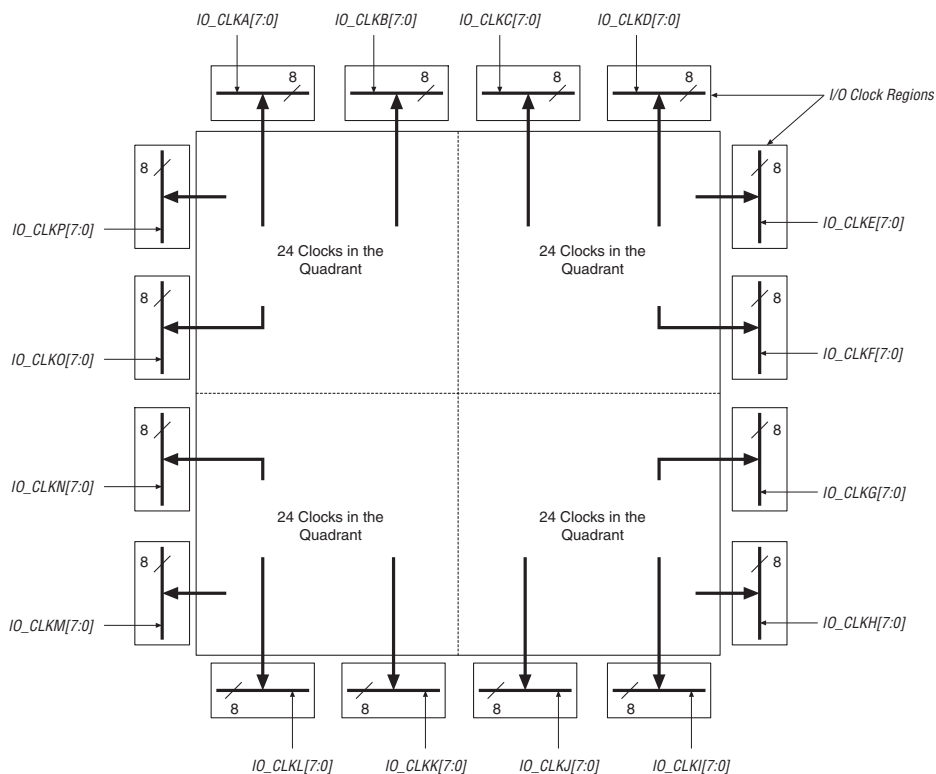
In addition to the dedicated carry chain routing, the shared arithmetic chain available in shared arithmetic mode allows the ALM to implement a three-input add. This significantly reduces the resources necessary to implement large adder trees or correlator functions.

The shared arithmetic chains can begin in either the first or fifth ALM in an LAB. The Quartus II Compiler creates shared arithmetic chains longer than 16 (8 ALMs in arithmetic or shared arithmetic mode) by linking LABs together automatically. For enhanced fitting, a long shared

Figure 2–27 shows one of the columns with surrounding LAB rows.

**Figure 2–27. DSP Blocks Arranged in Columns**



**Figure 2–36. EP2S60, EP2S90, EP2S130 & EP2S180 Device I/O Clock Groups**

You can use the Quartus II software to control whether a clock input pin drives either a global, regional, or dual-regional clock network. The Quartus II software automatically selects the clocking resources if not specified.

### *Clock Control Block*

Each global clock, regional clock, and PLL external clock output has its own clock control block. The control block has two functions:

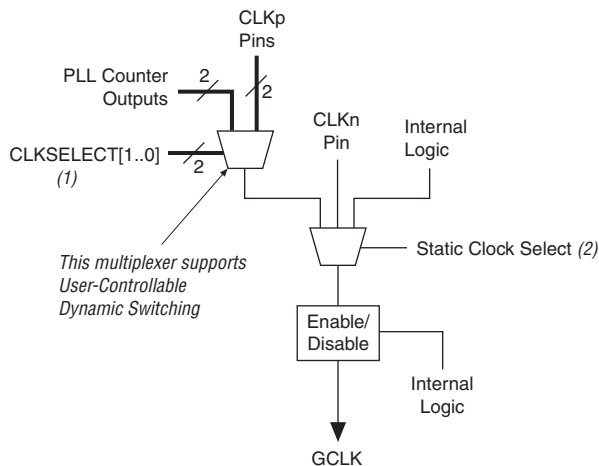
- Clock source selection (dynamic selection for global clocks)
- Clock power-down (dynamic clock enable/disable)



When using the global or regional clock control blocks in Stratix II devices to select between multiple clocks or to enable and disable clock networks, be aware of possible narrow pulses or glitches when switching from one clock signal to another. A glitch or runt pulse has a width that is less than the width of the highest frequency input clock signal. To prevent logic errors within the FPGA, Altera recommends that you build circuits that filter out glitches and runt pulses.

Figures 2–37 through 2–39 show the clock control block for the global clock, regional clock, and PLL external clock output, respectively.

**Figure 2–37. Global Clock Control Blocks**



**Notes to Figure 2–37:**

- (1) These clock select signals can be dynamically controlled through internal logic when the device is operating in user mode.
- (2) These clock select signals can only be set through a configuration file (.sof or .pof) and cannot be dynamically controlled during user mode operation.



The Stratix II clock networks can be disabled (powered down) by both static and dynamic approaches. When a clock net is powered down, all the logic fed by the clock net is in an off-state thereby reducing the overall power consumption of the device.

The global and regional clock networks can be powered down statically through a setting in the configuration (**.sof** or **.pof**) file. Clock networks that are not used are automatically powered down through configuration bit settings in the configuration file generated by the Quartus II software.

The dynamic clock enable/disable feature allows the internal logic to control power up/down synchronously on GCLK and RCLK nets and PLL\_OUT pins. This function is independent of the PLL and is applied directly on the clock network or PLL\_OUT pin, as shown in [Figures 2-37 through 2-39](#).



The following restrictions for the input clock pins apply:

- CLK0 pin -> inclk[0] of CLKCTRL
- CLK1 pin -> inclk[1] of CLKCTRL
- CLK2 pin -> inclk[0] of CLKCTRL
- CLK3 pin -> inclk[1] of CLKCTRL

In general, even CLK numbers connect to the inclk[0] port of CLKCTRL, and odd CLK numbers connect to the inclk[1] port of CLKCTRL.

Failure to comply with these restrictions will result in a no-fit error.

## Enhanced & Fast PLLs

Stratix II devices provide robust clock management and synthesis using up to four enhanced PLLs and eight fast PLLs. These PLLs increase performance and provide advanced clock interfacing and clock-frequency synthesis. With features such as clock switchover, spread-spectrum clocking, reconfigurable bandwidth, phase control, and reconfigurable phase shifting, the Stratix II device's enhanced PLLs provide you with complete control of clocks and system timing. The fast PLLs provide general purpose clocking with multiplication and phase shifting as well as high-speed outputs for high-speed differential I/O support. Enhanced and fast PLLs work together with the Stratix II high-speed I/O and advanced clock architecture to provide significant improvements in system performance and bandwidth.

**Table 2–16. Stratix II Supported I/O Standards (Part 2 of 2)**

I/O Standard	Type	Input Reference Voltage ( $V_{REF}$ ) (V)	Output Supply Voltage ( $V_{CCIO}$ ) (V)	Board Termination Voltage ( $V_{TT}$ ) (V)
SSTL-2 Class I and II	Voltage-referenced	1.25	2.5	1.25

**Notes to Table 2–16:**

- (1) This I/O standard is only available on input and output column clock pins.
- (2) This I/O standard is only available on input clock pins and DQS pins in I/O banks 3, 4, 7, and 8, and output clock pins in I/O banks 9, 10, 11, and 12.
- (3)  $V_{CCIO}$  is 3.3 V when using this I/O standard in input and output column clock pins (in I/O banks 9, 10, 11, and 12). The clock input pins supporting LVDS on banks 3, 4, 7, and 8 use  $V_{CCINT}$  for LVDS input operations and have no dependency on the  $V_{CCIO}$  level of the bank.
- (4) 1.2-V HSTL is only supported in I/O banks 4, 7, and 8.



For more information on I/O standards supported by Stratix II I/O banks, refer to the *Selectable I/O Standards in Stratix II & Stratix II GX Devices* chapter in volume 2 of the *Stratix II Device Handbook* or the *Stratix II GX Device Handbook*.

Stratix II devices contain eight I/O banks and four enhanced PLL external clock output banks, as shown in [Figure 2–57](#). The four I/O banks on the right and left of the device contain circuitry to support high-speed differential I/O for LVDS and HyperTransport inputs and outputs. These banks support all Stratix II I/O standards except PCI or PCI-X I/O pins, and SSTL-18 Class II and HSTL outputs. The top and bottom I/O banks support all single-ended I/O standards. Additionally, enhanced PLL external clock output banks allow clock output capabilities such as differential support for SSTL and HSTL.

**Table 3–5. Stratix II Configuration Features (Part 2 of 2)**

Configuration Scheme	Configuration Method	Design Security	Decompression	Remote System Upgrade
PPA	MAX II device or microprocessor and flash device			✓
JTAG	Download cable (4)			
	MAX II device or microprocessor and flash device			

**Notes for Table 3–5:**

- (1) In these modes, the host system must send a DCLK that is 4× the data rate.
- (2) The enhanced configuration device decompression feature is available, while the Stratix II decompression feature is not available.
- (3) Only remote update mode is supported when using the AS configuration scheme. Local update mode is not supported.
- (4) The supported download cables include the Altera USB Blaster universal serial bus (USB) port download cable, MasterBlaster serial/USB communications cable, ByteBlaster II parallel port download cable, and the ByteBlasterMV parallel port download cable.



See the *Configuring Stratix II & Stratix II GX Devices* chapter in volume 2 of the *Stratix II Device Handbook* or the *Stratix II GX Device Handbook* for more information about configuration schemes in Stratix II and Stratix II GX devices.

### *Device Security Using Configuration Bitstream Encryption*

Stratix II FPGAs are the industry's first FPGAs with the ability to decrypt a configuration bitstream using the Advanced Encryption Standard (AES) algorithm. When using the design security feature, a 128-bit security key is stored in the Stratix II FPGA. To successfully configure a Stratix II FPGA that has the design security feature enabled, it must be configured with a configuration file that was encrypted using the same 128-bit security key. The security key can be stored in non-volatile memory inside the Stratix II device. This non-volatile memory does not require any external devices, such as a battery back-up, for storage.

**Table 3–7. Document Revision History (Part 2 of 2)**

<b>Date and Document Version</b>	<b>Changes Made</b>	<b>Summary of Changes</b>
April 2006, v4.1	Updated “Device Security Using Configuration Bitstream Encryption” section.	—
December 2005, v4.0	Updated “Software Interface” section.	—
May 2005, v3.0	<ul style="list-style-type: none"> <li>• Updated “IEEE Std. 1149.1 JTAG Boundary-Scan Support” section.</li> <li>• Updated “Operating Modes” section.</li> </ul>	—
January 2005, v2.1	Updated JTAG chain device limits.	—
January 2005, v2.0	Updated Table 3–3.	—
July 2004, v1.1	<ul style="list-style-type: none"> <li>• Added “Automated Single Event Upset (SEU) Detection” section.</li> <li>• Updated “Device Security Using Configuration Bitstream Encryption” section.</li> <li>• Updated Figure 3–2.</li> </ul>	—
February 2004, v1.0	Added document to the Stratix II Device Handbook.	—

**Table 5–19. SSTL-2 Class I Specifications**

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
$V_{CCIO}$	Output supply voltage		2.375	2.500	2.625	V
$V_{TT}$	Termination voltage		$V_{REF} - 0.04$	$V_{REF}$	$V_{REF} + 0.04$	V
$V_{REF}$	Reference voltage		1.188	1.250	1.313	V
$V_{IH}$ (DC)	High-level DC input voltage		$V_{REF} + 0.18$		3.00	V
$V_{IL}$ (DC)	Low-level DC input voltage		-0.30		$V_{REF} - 0.18$	V
$V_{IH}$ (AC)	High-level AC input voltage		$V_{REF} + 0.35$			V
$V_{IL}$ (AC)	Low-level AC input voltage				$V_{REF} - 0.35$	V
$V_{OH}$	High-level output voltage	$I_{OH} = -8.1 \text{ mA}$ (1)	$V_{TT} + 0.57$			V
$V_{OL}$	Low-level output voltage	$I_{OL} = 8.1 \text{ mA}$ (1)			$V_{TT} - 0.57$	V

**Note to Table 5–19:**

- (1) This specification is supported across all the programmable drive settings available for this I/O standard as shown in the *Stratix II Architecture* chapter in volume 1 of the *Stratix II Device Handbook*.

**Table 5–20. SSTL-2 Class II Specifications**

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
$V_{CCIO}$	Output supply voltage		2.375	2.500	2.625	V
$V_{TT}$	Termination voltage		$V_{REF} - 0.04$	$V_{REF}$	$V_{REF} + 0.04$	V
$V_{REF}$	Reference voltage		1.188	1.250	1.313	V
$V_{IH}$ (DC)	High-level DC input voltage		$V_{REF} + 0.18$		$V_{CCIO} + 0.30$	V
$V_{IL}$ (DC)	Low-level DC input voltage		-0.30		$V_{REF} - 0.18$	V
$V_{IH}$ (AC)	High-level AC input voltage		$V_{REF} + 0.35$			V
$V_{IL}$ (AC)	Low-level AC input voltage				$V_{REF} - 0.35$	V
$V_{OH}$	High-level output voltage	$I_{OH} = -16.4 \text{ mA}$ (1)	$V_{TT} + 0.76$			V
$V_{OL}$	Low-level output voltage	$I_{OL} = 16.4 \text{ mA}$ (1)			$V_{TT} - 0.76$	V

**Note to Table 5–20:**

- (1) This specification is supported across all the programmable drive settings available for this I/O standard as shown in the *Stratix II Architecture* chapter in volume 1 of the *Stratix II Device Handbook*.

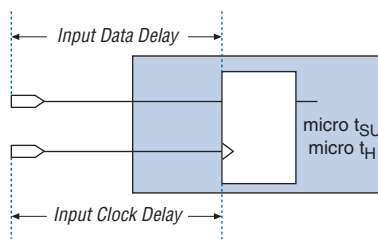
**Table 5–30. Series On-Chip Termination Specification for Top & Bottom I/O Banks (Part 2 of 2)**

*Notes (1), 2*

Symbol	Description	Conditions	Resistance Tolerance		
			Commercial Max	Industrial Max	Unit
50-Ω R <sub>S</sub> 3.3/2.5	Internal series termination with calibration (50-Ω setting)	V <sub>CCIO</sub> = 3.3/2.5 V	±5	±10	%
	Internal series termination without calibration (50-Ω setting)	V <sub>CCIO</sub> = 3.3/2.5 V	±30	±30	%
50-Ω R <sub>T</sub> 2.5	Internal parallel termination with calibration (50-Ω setting)	V <sub>CCIO</sub> = 1.8 V	±30	±30	%
25-Ω R <sub>S</sub> 1.8	Internal series termination with calibration (25-Ω setting)	V <sub>CCIO</sub> = 1.8 V	±5	±10	%
	Internal series termination without calibration (25-Ω setting)	V <sub>CCIO</sub> = 1.8 V	±30	±30	%
50-Ω R <sub>S</sub> 1.8	Internal series termination with calibration (50-Ω setting)	V <sub>CCIO</sub> = 1.8 V	±5	±10	%
	Internal series termination without calibration (50-Ω setting)	V <sub>CCIO</sub> = 1.8 V	±30	±30	%
50-Ω R <sub>T</sub> 1.8	Internal parallel termination with calibration (50-Ω setting)	V <sub>CCIO</sub> = 1.8 V	±10	±15	%
50-Ω R <sub>S</sub> 1.5	Internal series termination with calibration (50-Ω setting)	V <sub>CCIO</sub> = 1.5 V	±8	±10	%
	Internal series termination without calibration (50-Ω setting)	V <sub>CCIO</sub> = 1.5 V	±36	±36	%
50-Ω R <sub>T</sub> 1.5	Internal parallel termination with calibration (50-Ω setting)	V <sub>CCIO</sub> = 1.5 V	±10	±15	%
50-Ω R <sub>S</sub> 1.2	Internal series termination with calibration (50-Ω setting)	V <sub>CCIO</sub> = 1.2 V	±8	±10	%
	Internal series termination without calibration (50-Ω setting)	V <sub>CCIO</sub> = 1.2 V	±50	±50	%
50-Ω R <sub>T</sub> 1.2	Internal parallel termination with calibration (50-Ω setting)	V <sub>CCIO</sub> = 1.2 V	±10	±15	%

**Notes for Table 5–30:**

- (1) The resistance tolerances for calibrated SOCT and POCT are for the moment of calibration. If the temperature or voltage changes over time, the tolerance may also change.
- (2) On-chip parallel termination with calibration is only supported for input pins.

**Figure 5–3. Input Register Setup & Hold Timing Diagram**

For output timing, different I/O standards require different baseline loading techniques for reporting timing delays. Altera characterizes timing delays with the required termination for each I/O standard and with 0 pF (except for PCI and PCI-X which use 10 pF) loading and the timing is specified up to the output pin of the FPGA device. The Quartus II software calculates the I/O timing for each I/O standard with a default baseline loading as specified by the I/O standards.

The following measurements are made during device characterization. Altera measures clock-to-output delays ( $t_{CO}$ ) at worst-case process, minimum voltage, and maximum temperature (PVT) for default loading conditions shown in Table 5–34. Use the following equations to calculate clock pin to output pin timing for Stratix II devices.

$t_{CO}$  from clock pin to I/O pin = delay from clock pad to I/O output register + IOE output register clock-to-output delay + delay from output register to output pin + I/O output delay

$t_{xz}/t_{zx}$  from clock pin to I/O pin = delay from clock pad to I/O output register + IOE output register clock-to-output delay + delay from output register to output pin + I/O output delay + output enable pin delay

Simulation using IBIS models is required to determine the delays on the PCB traces in addition to the output pin delay timing reported by the Quartus II software and the timing model in the device handbook.

1. Simulate the output driver of choice into the generalized test setup, using values from Table 5–34.
2. Record the time to  $V_{MEAS}$ .
3. Simulate the output driver of choice into the actual PCB trace and load, using the appropriate IBIS model or capacitance value to represent the load.

*EP2S15 Clock Timing Parameters*

Tables 5–44 through 5–47 show the maximum clock timing parameters for EP2S15 devices.

**Table 5–44. EP2S15 Column Pins Regional Clock Timing Parameters**

Parameter	Minimum Timing		-3 Speed Grade	-4 Speed Grade	-5 Speed Grade	Unit
	Industrial	Commercial				
$t_{CIN}$	1.445	1.512	2.487	2.848	3.309	ns
$t_{COUT}$	1.288	1.347	2.245	2.570	2.985	ns
$t_{PLLCIN}$	0.104	0.102	0.336	0.373	0.424	ns
$t_{PLLCOUT}$	-0.053	-0.063	0.094	0.095	0.1	ns

**Table 5–45. EP2S15 Column Pins Global Clock Timing Parameters**

Parameter	Minimum Timing		-3 Speed Grade	-4 Speed Grade	-5 Speed Grade	Unit
	Industrial	Commercial				
$t_{CIN}$	1.419	1.487	2.456	2.813	3.273	ns
$t_{COUT}$	1.262	1.322	2.214	2.535	2.949	ns
$t_{PLLCIN}$	0.094	0.092	0.326	0.363	0.414	ns
$t_{PLLCOUT}$	-0.063	-0.073	0.084	0.085	0.09	ns

**Table 5–46. EP2S15 Row Pins Regional Clock Timing Parameters**

Parameter	Minimum Timing		-3 Speed Grade	-4 Speed Grade	-5 Speed Grade	Unit
	Industrial	Commercial				
$t_{CIN}$	1.232	1.288	2.144	2.454	2.848	ns
$t_{COUT}$	1.237	1.293	2.140	2.450	2.843	ns
$t_{PLLCIN}$	-0.109	-0.122	-0.007	-0.021	-0.037	ns
$t_{PLLCOUT}$	-0.104	-0.117	-0.011	-0.025	-0.042	ns



## I/O Delays

See [Tables 5-72 through 5-76](#) for I/O delays.

**Table 5-72. I/O Delay Parameters**

Symbol	Parameter
$t_{DIP}$	Delay from I/O datain to output pad
$t_{OP}$	Delay from I/O output register to output pad
$t_{PCOUT}$	Delay from input pad to I/O dataout to core
$t_{PI}$	Delay from input pad to I/O input register

**Table 5-73. Stratix II I/O Input Delay for Column Pins (Part 1 of 3)**

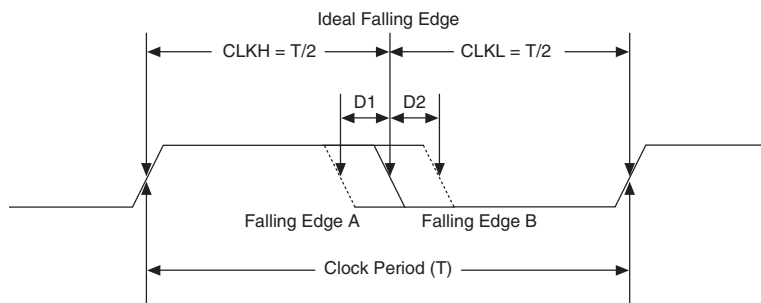
I/O Standard	Parameter	Minimum Timing		-3 Speed Grade (2)	-3 Speed Grade (3)	-4 Speed Grade	-5 Speed Grade	Unit
		Industrial	Commercial					
LVTTTL	$t_{PI}$	674	707	1223	1282	1405	1637	ps
	$t_{PCOUT}$	408	428	787	825	904	1054	ps
2.5 V	$t_{PI}$	684	717	1210	1269	1390	1619	ps
	$t_{PCOUT}$	418	438	774	812	889	1036	ps
1.8 V	$t_{PI}$	747	783	1366	1433	1570	1829	ps
	$t_{PCOUT}$	481	504	930	976	1069	1246	ps
1.5 V	$t_{PI}$	749	786	1436	1506	1650	1922	ps
	$t_{PCOUT}$	483	507	1000	1049	1149	1339	ps
LVCMOS	$t_{PI}$	674	707	1223	1282	1405	1637	ps
	$t_{PCOUT}$	408	428	787	825	904	1054	ps
SSTL-2 Class I	$t_{PI}$	507	530	818	857	939	1094	ps
	$t_{PCOUT}$	241	251	382	400	438	511	ps
SSTL-2 Class II	$t_{PI}$	507	530	818	857	939	1094	ps
	$t_{PCOUT}$	241	251	382	400	438	511	ps
SSTL-18 Class I	$t_{PI}$	543	569	898	941	1031	1201	ps
	$t_{PCOUT}$	277	290	462	484	530	618	ps
SSTL-18 Class II	$t_{PI}$	543	569	898	941	1031	1201	ps
	$t_{PCOUT}$	277	290	462	484	530	618	ps
1.5-V HSTL Class I	$t_{PI}$	560	587	993	1041	1141	1329	ps
	$t_{PCOUT}$	294	308	557	584	640	746	ps

Table 5–75. Stratix II I/O Output Delay for Column Pins (Part 3 of 8)

I/O Standard	Drive Strength	Parameter	Minimum Timing		-3 Speed Grade (3)	-3 Speed Grade (4)	-4 Speed Grade	-5 Speed Grade	Unit
			Industrial	Commercial					
1.8 V	2 mA	t <sub>OP</sub>	1042	1093	2904	3048	3338	3472	ps
		t <sub>DIP</sub>	1062	1115	2970	3118	3414	3562	ps
	4 mA	t <sub>OP</sub>	1047	1098	2248	2359	2584	2698	ps
		t <sub>DIP</sub>	1067	1120	2314	2429	2660	2788	ps
	6 mA	t <sub>OP</sub>	974	1022	2024	2124	2326	2434	ps
		t <sub>DIP</sub>	994	1044	2090	2194	2402	2524	ps
	8 mA	t <sub>OP</sub>	976	1024	1947	2043	2238	2343	ps
		t <sub>DIP</sub>	996	1046	2013	2113	2314	2433	ps
	10 mA	t <sub>OP</sub>	933	978	1882	1975	2163	2266	ps
		t <sub>DIP</sub>	953	1000	1948	2045	2239	2356	ps
	12 mA (1)	t <sub>OP</sub>	934	979	1833	1923	2107	2209	ps
		t <sub>DIP</sub>	954	1001	1899	1993	2183	2299	ps
1.5 V	2 mA	t <sub>OP</sub>	1023	1073	2505	2629	2879	3002	ps
		t <sub>DIP</sub>	1043	1095	2571	2699	2955	3092	ps
	4 mA	t <sub>OP</sub>	963	1009	2023	2123	2325	2433	ps
		t <sub>DIP</sub>	983	1031	2089	2193	2401	2523	ps
	6 mA	t <sub>OP</sub>	966	1012	1923	2018	2210	2315	ps
		t <sub>DIP</sub>	986	1034	1989	2088	2286	2405	ps
	8 mA (1)	t <sub>OP</sub>	926	971	1878	1970	2158	2262	ps
		t <sub>DIP</sub>	946	993	1944	2040	2234	2352	ps
SSTL-2 Class I	8 mA	t <sub>OP</sub>	913	957	1715	1799	1971	2041	ps
		t <sub>DIP</sub>	933	979	1781	1869	2047	2131	ps
	12 mA (1)	t <sub>OP</sub>	896	940	1672	1754	1921	1991	ps
		t <sub>DIP</sub>	916	962	1738	1824	1997	2081	ps
SSTL-2 Class II	16 mA	t <sub>OP</sub>	876	918	1609	1688	1849	1918	ps
		t <sub>DIP</sub>	896	940	1675	1758	1925	2008	ps
	20 mA	t <sub>OP</sub>	877	919	1598	1676	1836	1905	ps
		t <sub>DIP</sub>	897	941	1664	1746	1912	1995	ps
	24 mA (1)	t <sub>OP</sub>	872	915	1596	1674	1834	1903	ps
		t <sub>DIP</sub>	892	937	1662	1744	1910	1993	ps

**Table 5–75. Stratix II I/O Output Delay for Column Pins (Part 6 of 8)**

I/O Standard	Drive Strength	Parameter	Minimum Timing		-3 Speed Grade (3)	-3 Speed Grade (4)	-4 Speed Grade	-5 Speed Grade	Unit
			Industrial	Commercial					
Differential SSTL-2 Class I	8 mA	t <sub>OP</sub>	913	957	1715	1799	1971	2041	ps
		t <sub>DIP</sub>	933	979	1781	1869	2047	2131	ps
	12 mA	t <sub>OP</sub>	896	940	1672	1754	1921	1991	ps
		t <sub>DIP</sub>	916	962	1738	1824	1997	2081	ps
Differential SSTL-2 Class II	16 mA	t <sub>OP</sub>	876	918	1609	1688	1849	1918	ps
		t <sub>DIP</sub>	896	940	1675	1758	1925	2008	ps
	20 mA	t <sub>OP</sub>	877	919	1598	1676	1836	1905	ps
		t <sub>DIP</sub>	897	941	1664	1746	1912	1995	ps
	24 mA	t <sub>OP</sub>	872	915	1596	1674	1834	1903	ps
		t <sub>DIP</sub>	892	937	1662	1744	1910	1993	ps
Differential SSTL-18 Class I	4 mA	t <sub>OP</sub>	909	953	1690	1773	1942	2012	ps
		t <sub>DIP</sub>	929	975	1756	1843	2018	2102	ps
	6 mA	t <sub>OP</sub>	914	958	1656	1737	1903	1973	ps
		t <sub>DIP</sub>	934	980	1722	1807	1979	2063	ps
	8 mA	t <sub>OP</sub>	894	937	1640	1721	1885	1954	ps
		t <sub>DIP</sub>	914	959	1706	1791	1961	2044	ps
	10 mA	t <sub>OP</sub>	898	942	1638	1718	1882	1952	ps
		t <sub>DIP</sub>	918	964	1704	1788	1958	2042	ps
	12 mA	t <sub>OP</sub>	891	936	1626	1706	1869	1938	ps
		t <sub>DIP</sub>	911	958	1692	1776	1945	2028	ps
Differential SSTL-18 Class II	8 mA	t <sub>OP</sub>	883	925	1597	1675	1835	1904	ps
		t <sub>DIP</sub>	903	947	1663	1745	1911	1994	ps
	16 mA	t <sub>OP</sub>	894	937	1578	1655	1813	1882	ps
		t <sub>DIP</sub>	914	959	1644	1725	1889	1972	ps
	18 mA	t <sub>OP</sub>	890	933	1585	1663	1821	1890	ps
		t <sub>DIP</sub>	910	955	1651	1733	1897	1980	ps
	20 mA	t <sub>OP</sub>	890	933	1583	1661	1819	1888	ps
		t <sub>DIP</sub>	910	955	1649	1731	1895	1978	ps

**Figure 5–7. Duty Cycle Distortion**

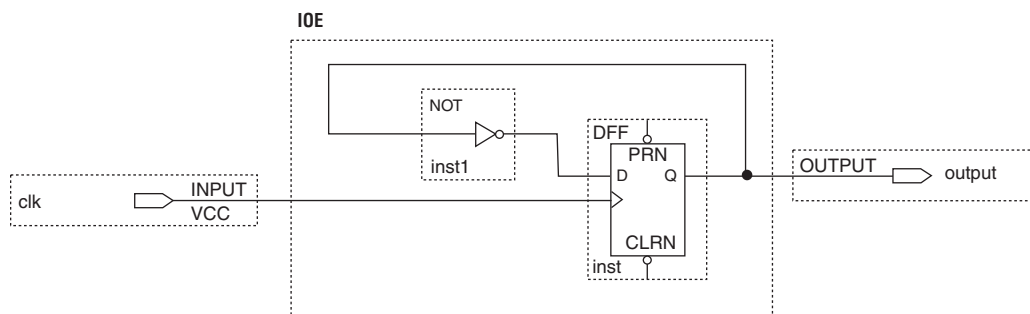
DCD expressed in absolute derivation, for example,  $D1$  or  $D2$  in [Figure 5–7](#), is clock-period independent. DCD can also be expressed as a percentage, and the percentage number is clock-period dependent. DCD as a percentage is defined as

$$(T/2 - D1) / T \text{ (the low percentage boundary)}$$

$$(T/2 + D2) / T \text{ (the high percentage boundary)}$$

## DCD Measurement Techniques

DCD is measured at an FPGA output pin driven by registers inside the corresponding I/O element (IOE) block. When the output is a single data rate signal (non-DDIO), only one edge of the register input clock (positive or negative) triggers output transitions ([Figure 5–8](#)). Therefore, any DCD present on the input clock signal or caused by the clock input buffer or different input I/O standard does not transfer to the output signal.

**Figure 5–8. DCD Measurement Technique for Non-DDIO (Single-Data Rate) Outputs**

**Table 5–85. Maximum DCD for DDIO Output on Column I/O Pins Without PLL in the Clock Path for -4 & -5 Devices (Part 2 of 2)** *Notes (1), (2)*

DDIO Column Output I/O Standard	Maximum DCD Based on I/O Standard of Input Feeding the DDIO Clock Port (No PLL in the Clock Path)				Unit
	TTL/CMOS		SSTL-2	SSTL/HSTL	
	3.3/2.5 V	1.8/1.5 V	2.5 V	1.8/1.5 V	
SSTL-18 Class I	335	390	65	65	ps
SSTL-18 Class II	320	375	70	80	ps
1.8-V HSTL Class I	330	385	60	70	ps
1.8-V HSTL Class II	330	385	60	70	ps
1.5-V HSTL Class I	330	390	60	70	ps
1.5-V HSTL Class II	330	360	90	100	ps
1.2-V HSTL	420	470	155	165	ps
LVPECL	180	180	180	180	ps

**Notes to Table 5–85:**

- (1) Table 5–85 assumes the input clock has zero DCD.  
 (2) The DCD specification is based on a no logic array noise condition.

**Table 5–86. Maximum DCD for DDIO Output on Row I/O Pins with PLL in the Clock Path (Part 1 of 2)** *Note (1)*

Row DDIO Output I/O Standard	Maximum DCD (PLL Output Clock Feeding DDIO Clock Port)		Unit
	-3 Device	-4 & -5 Device	
3.3-V LVTTTL	110	105	ps
3.3-V LVCMOS	65	75	ps
2.5V	75	90	ps
1.8V	85	100	ps
1.5-V LVCMOS	105	100	ps
SSTL-2 Class I	65	75	ps
SSTL-2 Class II	60	70	ps
SSTL-18 Class I	50	65	ps
1.8-V HSTL Class I	50	70	ps
1.5-V HSTL Class I	55	70	ps