Intel - EP2S90F1508C3N Datasheet

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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

Details	
Product Status	Obsolete
Number of LABs/CLBs	4548
Number of Logic Elements/Cells	90960
Total RAM Bits	4520488
Number of I/O	902
Number of Gates	-
Voltage - Supply	1.15V ~ 1.25V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	1508-BBGA, FCBGA
Supplier Device Package	1508-FBGA, FC (40x40)
Purchase URL	https://www.e-xfl.com/product-detail/intel/ep2s90f1508c3n

Email: info@E-XFL.COM Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

About this Handbook

This handbook provides comprehensive information about the Altera® Stratix® II family of devices.

How to Contact Altera

For the most up-to-date information about Altera products, refer to the following table.

Contact *(1)*	Contact Method	Address
Technical support	Website	www.altera.com/support
Technical training	Website	www.altera.com/training
	Email	custrain@altera.com
Product literature	Email	www.altera.com/literature
Altera literature services	Website	literature@altera.com
Non-technical support (General)	Email	nacomp@altera.com
(Software Licensing)	Email	authorization@altera.com

Note to table:

(1) You can also contact your local Altera sales office or sales representative.

Typographic Conventions

This document uses the typographic conventions shown below.

Visual Cue	Meaning
Bold Type with Initial Capital Letters	Command names, dialog box titles, checkbox options, and dialog box options are shown in bold, initial capital letters. Example: **Save As** dialog box.
bold type	External timing parameters, directory names, project names, disk drive names, filenames, filename extensions, and software utility names are shown in bold type. Examples: $\mathbf{f_{MAX}}$, **\qdesigns** directory, **d:** drive, **chiptrip.gdf** file.
Italic Type with Initial Capital Letters	Document titles are shown in italic type with initial capital letters. Example: *AN 75: High-Speed Board Design.*

- Support for numerous single-ended and differential I/O standards
- High-speed differential I/O support with DPA circuitry for 1-Gbps performance
- Support for high-speed networking and communications bus standards including Parallel RapidIO, SPI-4 Phase 2 (POS-PHY Level 4), HyperTransport™ technology, and SFI-4
- Support for high-speed external memory, including DDR and DDR2 SDRAM, RLDRAM II, QDR II SRAM, and SDR SDRAM
- Support for multiple intellectual property megafunctions from Altera MegaCore® functions and Altera Megafunction Partners Program (AMPP℠) megafunctions
- Support for design security using configuration bitstream encryption
- Support for remote configuration updates

Table 1–1. Stratix II FPGA Family Features

Feature	EP2S15	EP2S30	EP2S60	EP2S90	EP2S130	EP2S180
ALMs	6,240	13,552	24,176	36,384	53,016	71,760
Adaptive look-up tables (ALUTs) *(1)*	12,480	27,104	48,352	72,768	106,032	143,520
Equivalent LEs *(2)*	15,600	33,880	60,440	90,960	132,540	179,400
M512 RAM blocks	104	202	329	488	699	930
M4K RAM blocks	78	144	255	408	609	768
M-RAM blocks	0	1	2	4	6	9
Total RAM bits	419,328	1,369,728	2,544,192	4,520,488	6,747,840	9,383,040
DSP blocks	12	16	36	48	63	96
18-bit × 18-bit multipliers *(3)*	48	64	144	192	252	384
Enhanced PLLs	2	2	4	4	4	4
Fast PLLs	4	4	8	8	8	8
Maximum user I/O pins	366	500	718	902	1,126	1,170

Notes to Table 1–1:

(1) One ALM contains two ALUTs. The ALUT is the cell used in the Quartus® II software for logic synthesis.

(2) This is the equivalent number of LEs in a Stratix device (four-input LUT-based architecture).

(3) These multipliers are implemented using the DSP blocks.

Clear & Preset Logic Control

LAB-wide signals control the logic for the register's clear and load/preset signals. The ALM directly supports an asynchronous clear and preset function. The register preset is achieved through the asynchronous load of a logic high. The direct asynchronous preset does not require a NOT-gate push-back technique. Stratix II devices support simultaneous asynchronous load/preset, and clear signals. An asynchronous clear signal takes precedence if both signals are asserted simultaneously. Each LAB supports up to two clears and one load/preset signal.

In addition to the clear and load/preset ports, Stratix II devices provide a device-wide reset pin (`DEV_CLRn`) that resets all registers in the device. An option set before compilation in the Quartus II software controls this pin. This device-wide reset overrides all other control signals.

MultiTrack Interconnect

In the Stratix II architecture, connections between ALMs, TriMatrix memory, DSP blocks, and device I/O pins are provided by the MultiTrack interconnect structure with DirectDrive™ technology. The MultiTrack interconnect consists of continuous, performance-optimized routing lines of different lengths and speeds used for inter- and intra-design block connectivity. The Quartus II Compiler automatically places critical design paths on faster interconnects to improve design performance.

DirectDrive technology is a deterministic routing technology that ensures identical routing resource usage for any function regardless of placement in the device. The MultiTrack interconnect and DirectDrive technology simplify the integration stage of block-based designing by eliminating the re-optimization cycles that typically follow design changes and additions.

The MultiTrack interconnect consists of row and column interconnects that span fixed distances. A routing structure with fixed length resources for all devices allows predictable and repeatable performance when migrating through different device densities. Dedicated row interconnects route signals to and from LABs, DSP blocks, and TriMatrix memory in the same row. These row resources include:

- Direct link interconnects between LABs and adjacent blocks
- R4 interconnects traversing four blocks to the right or left
- R24 row interconnects for high-speed access across the length of the device

Digital Signal Processing Block

The most commonly used DSP functions are FIR filters, complex FIR filters, IIR filters, fast Fourier transform (FFT) functions, direct cosine transform (DCT) functions, and correlators. All of these use the multiplier as the fundamental building block. Additionally, some applications need specialized operations such as multiply-add and multiply-accumulate operations. Stratix II devices provide DSP blocks to meet the arithmetic requirements of these functions.

Each Stratix II device has from two to four columns of DSP blocks to efficiently implement DSP functions faster than ALM-based implementations. Stratix II devices have up to 24 DSP blocks per column (see Table 2–5). Each DSP block can be configured to support up to:

- Eight 9 × 9-bit multipliers
- Four 18 × 18-bit multipliers
- One 36 × 36-bit multiplier

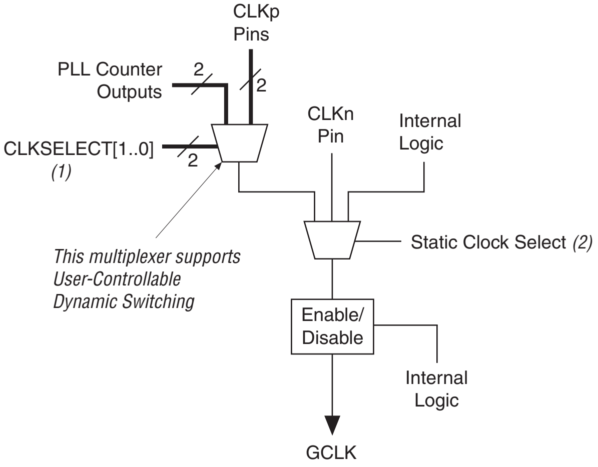
As indicated, the Stratix II DSP block can support one 36 × 36-bit multiplier in a single DSP block. This is true for any combination of signed, unsigned, or mixed sign multiplications.

☞ This list only shows functions that can fit into a single DSP block. Multiple DSP blocks can support larger multiplication functions.

When using the global or regional clock control blocks in Stratix II devices to select between multiple clocks or to enable and disable clock networks, be aware of possible narrow pulses or glitches when switching from one clock signal to another. A glitch or runt pulse has a width that is less than the width of the highest frequency input clock signal. To prevent logic errors within the FPGA, Altera recommends that you build circuits that filter out glitches and runt pulses.

Figures 2–37 through 2–39 show the clock control block for the global clock, regional clock, and PLL external clock output, respectively.

Figure 2–37. Global Clock Control Blocks



Notes to Figure 2–37:

(1) These clock select signals can be dynamically controlled through internal logic when the device is operating in user mode.

(2) These clock select signals can only be set through a configuration file (**.sof** or **.pof**) and cannot be dynamically controlled during user mode operation.

The Stratix II clock networks can be disabled (powered down) by both static and dynamic approaches. When a clock net is powered down, all the logic fed by the clock net is in an off-state thereby reducing the overall power consumption of the device.

The global and regional clock networks can be powered down statically through a setting in the configuration (**.sof** or **.pof**) file. Clock networks that are not used are automatically powered down through configuration bit settings in the configuration file generated by the Quartus II software.

The dynamic clock enable/disable feature allows the internal logic to control power up/down synchronously on `GCLK` and `RCLK` nets and `PLL_OUT` pins. This function is independent of the PLL and is applied directly on the clock network or `PLL_OUT` pin, as shown in Figures 2–37 through 2–39.

The following restrictions for the input clock pins apply:

- `CLK0 pin -> inclk[0] of CLKCTRL`
- `CLK1 pin -> inclk[1] of CLKCTRL`
- `CLK2 pin -> inclk[0] of CLKCTRL`
- `CLK3 pin -> inclk[1] of CLKCTRL`

In general, even CLK numbers connect to the `inclk[0]` port of `CLKCTRL`, and odd CLK numbers connect to the `inclk[1]` port of `CLKCTRL`.

Failure to comply with these restrictions will result in a no-fit error.

Enhanced & Fast PLLs

Stratix II devices provide robust clock management and synthesis using up to four enhanced PLLs and eight fast PLLs. These PLLs increase performance and provide advanced clock interfacing and clock-frequency synthesis. With features such as clock switchover, spread-spectrum clocking, reconfigurable bandwidth, phase control, and reconfigurable phase shifting, the Stratix II device's enhanced PLLs provide you with complete control of clocks and system timing. The fast PLLs provide general purpose clocking with multiplication and phase shifting as well as high-speed outputs for high-speed differential I/O support. Enhanced and fast PLLs work together with the Stratix II high-speed I/O and advanced clock architecture to provide significant improvements in system performance and bandwidth.

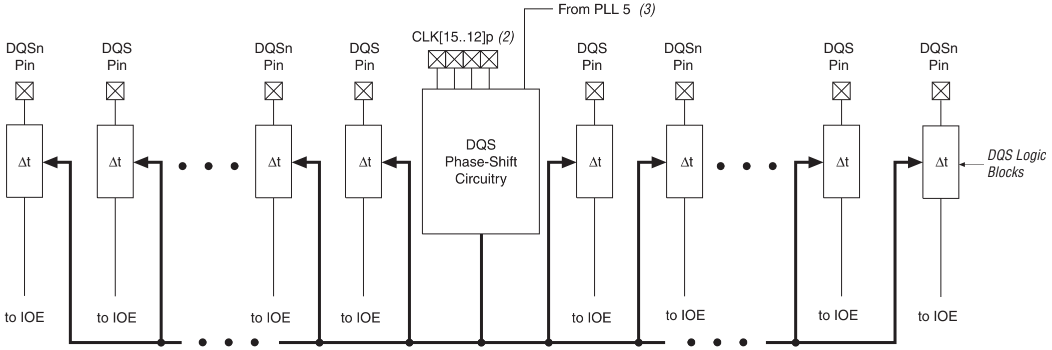
Table 2–11. Global & Regional Clock Connections from Top Clock Pins & Enhanced PLL Outputs (Part 2 of 2)

Top Side Global & Regional Clock Network Connectivity	DLLCLK	CLK12	CLK13	CLK14	CLK15	RCLK24	RCLK25	RCLK26	RCLK27	RCLK28	RCLK29	RCLK30	RCLK31
c4	✓					✓		✓		✓		✓	
c5	✓						✓		✓		✓		✓
Enhanced PLL 11 outputs													
c0		✓	✓			✓				✓			
c1		✓	✓				✓				✓		
c2				✓	✓			✓				✓	
c3				✓	✓				✓				✓
c4						✓		✓		✓		✓	
c5							✓		✓		✓		✓

Table 2–12. Global & Regional Clock Connections from Bottom Clock Pins & Enhanced PLL Outputs (Part 1 of 2)

Bottom Side Global & Regional Clock Network Connectivity	DLLCLK	CLK4	CLK5	CLK6	CLK7	RCLK8	RCLK9	RCLK10	RCLK11	RCLK12	RCLK13	RCLK14	RCLK15
Clock pins													
CLK4p	✓	✓	✓			✓				✓			
CLK5p	✓	✓	✓				✓				✓		
CLK6p	✓			✓	✓			✓				✓	
CLK7p	✓			✓	✓				✓				✓
CLK4n		✓				✓				✓			
CLK5n			✓				✓				✓		
CLK6n				✓				✓				✓	
CLK7n					✓				✓				✓
Drivers from internal logic													
GCLKDRV0		✓											
GCLKDRV1			✓										
GCLKDRV2				✓									

Figure 2–56. DQS Phase-Shift Circuitry *Notes (1), (2), (3), (4)*



Notes to Figure 2–56:

(1) There are up to 18 pairs of DQS and DQSn pins available on the top or the bottom of the Stratix II device. There are up to 10 pairs on the right side and 8 pairs on the left side of the DQS phase-shift circuitry.
(2) The Δt module represents the DQS logic block.
(3) Clock pins `CLK[15..12]p` feed the phase-shift circuitry on the top of the device and clock pins `CLK[7..4]p` feed the phase circuitry on the bottom of the device. You can also use a PLL clock output as a reference clock to the phase-shift circuitry.
(4) You can only use PLL 5 to feed the DQS phase-shift circuitry on the top of the device and PLL 6 to feed the DQS phase-shift circuitry on the bottom of the device.

These dedicated circuits combined with enhanced PLL clocking and phase-shift ability provide a complete hardware solution for interfacing to high-speed memory.

For more information on external memory interfaces, refer to the *External Memory Interfaces in Stratix II & Stratix II GX Devices* chapter in volume 2 of the *Stratix II Device Handbook* or the *Stratix II GX Device Handbook*.

Programmable Drive Strength

The output buffer for each Stratix II device I/O pin has a programmable drive strength control for certain I/O standards. The LVTTL, LVCMOS, SSTL, and HSTL standards have several levels of drive strength that the user can control. The default setting used in the Quartus II software is the maximum current strength setting that is used to achieve maximum I/O performance. For all I/O standards, the minimum setting is the lowest drive strength that guarantees the I_{OH}/I_{OL} of the standard. Using minimum settings provides signal slew rate control to reduce system noise and signal overshoot.

Table 2–17 shows the Stratix II on-chip termination support per I/O bank.

Table 2–17. On-Chip Termination Support by I/O Banks (Part 1 of 2)

On-Chip Termination Support	I/O Standard Support	Top & Bottom Banks	Left & Right Banks
Series termination without calibration	3.3-V LVTTL	✓	✓
	3.3-V LVCMOS	✓	✓
	2.5-V LVTTL	✓	✓
	2.5-V LVCMOS	✓	✓
	1.8-V LVTTL	✓	✓
	1.8-V LVCMOS	✓	✓
	1.5-V LVTTL	✓	✓
	1.5-V LVCMOS	✓	✓
	SSTL-2 Class I and II	✓	✓
	SSTL-18 Class I	✓	✓
	SSTL-18 Class II	✓	
	1.8-V HSTL Class I	✓	✓
	1.8-V HSTL Class II	✓	
	1.5-V HSTL Class I	✓	✓
	1.2-V HSTL	✓	

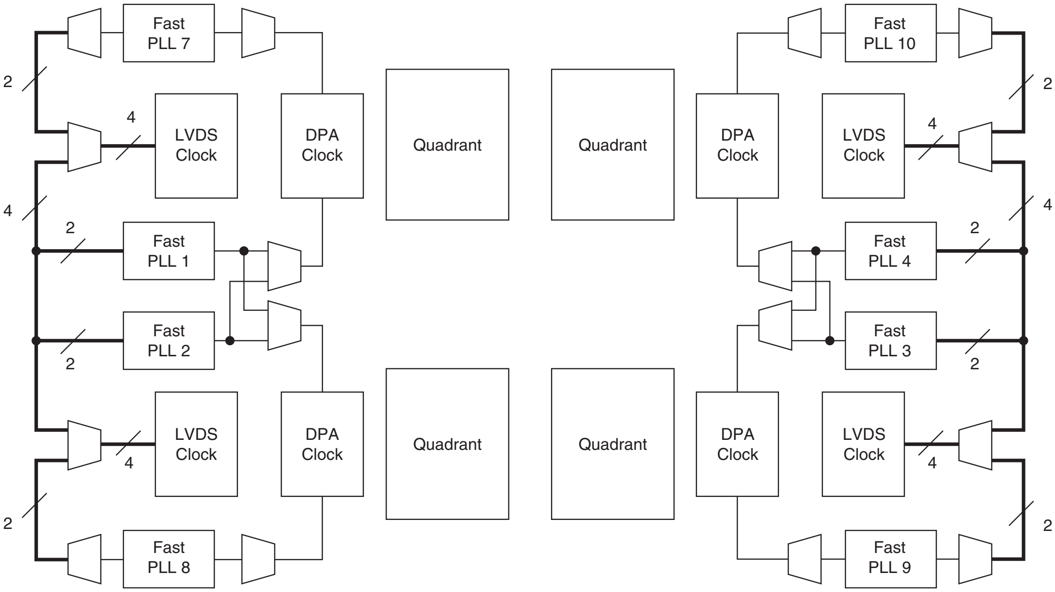
Table 2–17. On-Chip Termination Support by I/O Banks (Part 2 of 2)

On-Chip Termination Support	I/O Standard Support	Top & Bottom Banks	Left & Right Banks
Series termination with calibration	3.3-V LVTTL	✓	
	3.3-V LVCMOS	✓	
	2.5-V LVTTL	✓	
	2.5-V LVCMOS	✓	
	1.8-V LVTTL	✓	
	1.8-V LVCMOS	✓	
	1.5-V LVTTL	✓	
	1.5-V LVCMOS	✓	
	SSTL-2 Class I and II	✓	
	SSTL-18 Class I and II	✓	
	1.8-V HSTL Class I	✓	
	1.8-V HSTL Class II	✓	
	1.5-V HSTL Class I	✓	
	1.2-V HSTL	✓	
Parallel termination with calibration	SSTL-2 Class I and II	✓	
	SSTL-18 Class I and II	✓	
	1.8-V HSTL Class I	✓	
	1.8-V HSTL Class II	✓	
	1.5-V HSTL Class I and II	✓	
	1.2-V HSTL	✓	
Differential termination *(1)*	LVDS		✓
	HyperTransport technology		✓

Note to Table 2–17:

(1) Clock pins `CLK1`, `CLK3`, `CLK9`, `CLK11`, and pins `FPLL[7..10]CLK` do not support differential on-chip termination. Clock pins `CLK0`, `CLK2`, `CLK8`, and `CLK10` do support differential on-chip termination. Clock pins in the top and bottom banks (`CLK[4..7, 12..15]`) do not support differential on-chip termination.

Figure 2–61. Fast PLL & Channel Layout in the EP2S60 to EP2S180 Devices Note (1)



Note to Figure 2–61:

(1) See Tables 2–22 through 2–26 for the number of channels each device supports.

Table 5–14. 3.3-V PCI Specifications (Part 2 of 2)

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
V_{IL}	Low-level input voltage		–0.3		0.3 × V_{CCIO}	V
V_{OH}	High-level output voltage	I_{OUT} = –500 µA	0.9 × V_{CCIO}			V
V_{OL}	Low-level output voltage	I_{OUT} = 1,500 µA			0.1 × V_{CCIO}	V

Table 5–15. PCI-X Mode 1 Specifications

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
V_{CCIO}	Output supply voltage		3.0		3.6	V
V_{IH}	High-level input voltage		0.5 × V_{CCIO}		V_{CCIO} + 0.5	V
V_{IL}	Low-level input voltage		–0.30		0.35 × V_{CCIO}	V
V_{IPU}	Input pull-up voltage		0.7 × V_{CCIO}			V
V_{OH}	High-level output voltage	I_{OUT} = –500 µA	0.9 × V_{CCIO}			V
V_{OL}	Low-level output voltage	I_{OUT} = 1,500 µA			0.1 × V_{CCIO}	V

Table 5–16. SSTL-18 Class I Specifications

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
V_{CCIO}	Output supply voltage		1.71	1.80	1.89	V
V_{REF}	Reference voltage		0.855	0.900	0.945	V
V_{TT}	Termination voltage		V_{REF} – 0.04	V_{REF}	V_{REF} + 0.04	V
V_{IH} (DC)	High-level DC input voltage		V_{REF} + 0.125			V
V_{IL} (DC)	Low-level DC input voltage				V_{REF} – 0.125	V
V_{IH} (AC)	High-level AC input voltage		V_{REF} + 0.25			V
V_{IL} (AC)	Low-level AC input voltage				V_{REF} – 0.25	V
V_{OH}	High-level output voltage	I_{OH} = –6.7 mA *(1)*	V_{TT} + 0.475			V
V_{OL}	Low-level output voltage	I_{OL} = 6.7 mA *(1)*			V_{TT} – 0.475	V

Note to Table 5–16:

(1) This specification is supported across all the programmable drive settings available for this I/O standard as shown in the *Stratix II Architecture* chapter in volume 1 of the *Stratix II Device Handbook*.

Table 5–27. 1.8-V HSTL Class II Specifications

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
V_{CCIO}	Output supply voltage		1.71	1.80	1.89	V
V_{REF}	Input reference voltage		0.85	0.90	0.95	V
V_{TT}	Termination voltage		0.85	0.90	0.95	V
V_{IH} (DC)	DC high-level input voltage		$V_{REF} + 0.1$			V
V_{IL} (DC)	DC low-level input voltage		–0.3		$V_{REF} – 0.1$	V
V_{IH} (AC)	AC high-level input voltage		$V_{REF} + 0.2$			V
V_{IL} (AC)	AC low-level input voltage				$V_{REF} – 0.2$	V
V_{OH}	High-level output voltage	I_{OH} = 16 mA *(1)*	$V_{CCIO} – 0.4$			V
V_{OL}	Low-level output voltage	I_{OH} = –16 mA *(1)*			0.4	V

Note to Table 5–27:

(1) This specification is supported across all the programmable drive settings available for this I/O standard as shown in the *Stratix II Architecture* chapter in volume 1 of the *Stratix II Device Handbook*.

Table 5–28. 1.8-V HSTL Class I & II Differential Specifications

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
V_{CCIO}	I/O supply voltage		1.71	1.80	1.89	V
V_{DIF} (DC)	DC input differential voltage		0.2		V_{CCIO} + 0.6 V	V
V_{CM} (DC)	DC common mode input voltage		0.78		1.12	V
V_{DIF} (AC)	AC differential input voltage		0.4		V_{CCIO} + 0.6 V	V
V_{OX} (AC)	AC differential cross point voltage		0.68		0.90	V

Table 5–53. EP2S60 Column Pins Global Clock Timing Parameters

Parameter	Minimum Timing		-3 Speed Grade	-4 Speed Grade	-5 Speed Grade	Unit
	Industrial	Commercial				
t_{CIN}	1.658	1.739	2.920	3.350	3.899	ns
t_{COUT}	1.501	1.574	2.678	3.072	3.575	ns
t_{PLLCIN}	0.06	0.057	0.278	0.304	0.355	ns
$t_{PLLCOUT}$	-0.097	-0.108	0.036	0.026	0.031	ns

Table 5–54. EP2S60 Row Pins Regional Clock Timing Parameters

Parameter	Minimum Timing		-3 Speed Grade	-4 Speed Grade	-5 Speed Grade	Unit
	Industrial	Commercial				
t_{CIN}	1.463	1.532	2.591	2.972	3.453	ns
t_{COUT}	1.468	1.537	2.587	2.968	3.448	ns
t_{PLLCIN}	-0.153	-0.167	-0.079	-0.099	-0.128	ns
$t_{PLLCOUT}$	-0.148	-0.162	-0.083	-0.103	-0.133	ns

Table 5–55. EP2S60 Row Pins Global Clock Timing Parameters

Parameter	Minimum Timing		-3 Speed Grade	-4 Speed Grade	-5 Speed Grade	Unit
	Industrial	Commercial				
t_{CIN}	1.439	1.508	2.562	2.940	3.421	ns
t_{COUT}	1.444	1.513	2.558	2.936	3.416	ns
t_{PLLCIN}	-0.161	-0.174	-0.083	-0.107	-0.126	ns
$t_{PLLCOUT}$	-0.156	-0.169	-0.087	-0.111	-0.131	ns

Table 5–78. Maximum Output Toggle Rate on Stratix II Devices (Part 3 of 5) *Note (1)*

I/O Standard	Drive Strength	Column I/O Pins (MHz)			Row I/O Pins (MHz)			Clock Outputs (MHz)		
		-3	-4	-5	-3	-4	-5	-3	-4	-5
Differential SSTL-18 Class I *(3)*	4 mA	200	150	150	200	150	150	200	150	150
	6 mA	350	250	200	350	250	200	350	250	200
	8 mA	450	300	300	450	300	300	450	300	300
	10 mA	500	400	400	500	400	400	500	400	400
	12 mA	700	550	400	350	350	297	650	550	400
Differential SSTL-18 Class II *(3)*	8 mA	200	200	150	-	-	-	200	200	150
	16 mA	400	350	350	-	-	-	400	350	350
	18 mA	450	400	400	-	-	-	450	400	400
	20 mA	550	500	450	-	-	-	550	500	450
1.8-V Differential HSTL Class I *(3)*	4 mA	300	300	300	-	-	-	300	300	300
	6 mA	500	450	450	-	-	-	500	450	450
	8 mA	650	600	600	-	-	-	650	600	600
	10 mA	700	650	600	-	-	-	700	650	600
	12 mA	700	700	650	-	-	-	700	700	650
1.8-V Differential HSTL Class II *(3)*	16 mA	500	500	450	-	-	-	500	500	450
	18 mA	550	500	500	-	-	-	550	500	500
	20 mA	650	550	550	-	-	-	550	550	550
1.5-V Differential HSTL Class I *(3)*	4 mA	350	300	300	-	-	-	350	300	300
	6 mA	500	500	450	-	-	-	500	500	450
	8 mA	700	650	600	-	-	-	700	650	600
	10 mA	700	700	650	-	-	-	700	700	650
	12 mA	700	700	700	-	-	-	700	700	700
1.5-V Differential HSTL Class II *(3)*	16 mA	600	600	550	-	-	-	600	600	550
	18 mA	650	600	600	-	-	-	650	600	600
	20 mA	700	650	600	-	-	-	700	650	600
3.3-V PCI		1,000	790	670	-	-	-	1,000	790	670
3.3-V PCI-X		1,000	790	670	-	-	-	1,000	790	670
LVDS *(6)*		-	-	-	500	500	500	450	400	300
HyperTransport technology *(4)*, *(6)*					500	500	500	-	-	-
LVPECL *(5)*		-	-	-	-	-	-	450	400	300
3.3-V LVTTL	OCT 50 Ω	400	400	350	400	400	350	400	400	350
2.5-V LVTTL	OCT 50 Ω	350	350	300	350	350	300	350	350	300

Therefore, the DCD percentage for the 267 MHz SSTL-2 Class II DDIO row output clock on a –3 device ranges from 48.4% to 51.6%.

Table 5–83. Maximum DCD for DDIO Output on Row I/O Pins Without PLL in the Clock Path for -4 & -5 Devices *Notes (1), (2)*

Row DDIO Output I/O Standard	Maximum DCD Based on I/O Standard of Input Feeding the DDIO Clock Port (No PLL in the Clock Path)					Unit
	TTL/CMOS		SSTL-2	SSTL/HSTL	LVDS/ HyperTransport Technology	
	3.3/2.5 V	1.8/1.5 V	2.5 V	1.8/1.5 V	3.3 V	
3.3-V LVTTL	440	495	170	160	105	ps
3.3-V LVCMOS	390	450	120	110	75	ps
2.5 V	375	430	105	95	90	ps
1.8 V	325	385	90	100	135	ps
1.5-V LVCMOS	430	490	160	155	100	ps
SSTL-2 Class I	355	410	85	75	85	ps
SSTL-2 Class II	350	405	80	70	90	ps
SSTL-18 Class I	335	390	65	65	105	ps
1.8-V HSTL Class I	330	385	60	70	110	ps
1.5-V HSTL Class I	330	390	60	70	105	ps
LVDS/ HyperTransport technology	180	180	180	180	180	ps

Notes to Table 5–83:

(1) Table 5–83 assumes the input clock has zero DCD.

(2) The DCD specification is based on a no logic array noise condition.

Table 5–84. Maximum DCD for DDIO Output on Column I/O Pins Without PLL in the Clock Path for -3 Devices (Part 1 of 2) *Notes (1), (2)*

DDIO Column Output I/O Standard	Maximum DCD Based on I/O Standard of Input Feeding the DDIO Clock Port (No PLL in the Clock Path)					Unit
	TTL/CMOS		SSTL-2	SSTL/HSTL	1.2-V HSTL	
	3.3/2.5 V	1.8/1.5 V	2.5 V	1.8/1.5 V	1.2 V	
3.3-V LVTTL	260	380	145	145	145	ps
3.3-V LVCMOS	210	330	100	100	100	ps
2.5 V	195	315	85	85	85	ps

Table 5–89. High-Speed I/O Specifications for -3 Speed Grade (Part 2 of 2) Notes (1), (2)

<table>
<tr><th rowspan="2">Symbol</th><th rowspan="2" colspan="3">Conditions</th><th colspan="3">-3 Speed Grade</th><th rowspan="2">Unit</th></tr>
<tr><th>Min</th><th>Typ</th><th>Max</th></tr>
<tr><td rowspan="3">f_{HSDR} (data rate)</td><td colspan="3">J = 4 to 10 (LVDS, HyperTransport technology)</td><td>150</td><td></td><td>1,040</td><td>Mbps</td></tr>
<tr><td colspan="3">J = 2 (LVDS, HyperTransport technology)</td><td>(4)</td><td></td><td>760</td><td>Mbps</td></tr>
<tr><td colspan="3">J = 1 (LVDS only)</td><td>(4)</td><td></td><td>500</td><td>Mbps</td></tr>
<tr><td>$f_{HSDRDPA}$ (DPA data rate)</td><td colspan="3">J = 4 to 10 (LVDS, HyperTransport technology)</td><td>150</td><td></td><td>1,040</td><td>Mbps</td></tr>
<tr><td>TCCS</td><td colspan="3">All differential standards</td><td>-</td><td></td><td>200</td><td>ps</td></tr>
<tr><td>SW</td><td colspan="3">All differential standards</td><td>330</td><td></td><td>-</td><td>ps</td></tr>
<tr><td>Output jitter</td><td colspan="3"></td><td></td><td></td><td>190</td><td>ps</td></tr>
<tr><td>Output t_{RISE}</td><td colspan="3">All differential I/O standards</td><td></td><td></td><td>160</td><td>ps</td></tr>
<tr><td>Output t_{FALL}</td><td colspan="3">All differential I/O standards</td><td></td><td></td><td>180</td><td>ps</td></tr>
<tr><td>t_{DUTY}</td><td colspan="3"></td><td>45</td><td>50</td><td>55</td><td>%</td></tr>
<tr><td>DPA run length</td><td colspan="3"></td><td></td><td></td><td>6,400</td><td>UI</td></tr>
<tr><td>DPA jitter tolerance</td><td colspan="3">Data channel peak-to-peak jitter</td><td>0.44</td><td></td><td></td><td>UI</td></tr>
<tr><td rowspan="6">DPA lock time</td><td>Standard</td><td>Training Pattern</td><td>Transition Density</td><td></td><td></td><td></td><td rowspan="6">Number of repetitions</td></tr>
<tr><td>SPI-4</td><td>0000000000
1111111111</td><td>10%</td><td>256</td><td></td><td></td></tr>
<tr><td rowspan="2">Parallel Rapid I/O</td><td>00001111</td><td>25%</td><td>256</td><td></td><td></td></tr>
<tr><td>10010000</td><td>50%</td><td>256</td><td></td><td></td></tr>
<tr><td rowspan="2">Miscellaneous</td><td>10101010</td><td>100%</td><td>256</td><td></td><td></td></tr>
<tr><td>01010101</td><td></td><td>256</td><td></td><td></td></tr>
</table>

Notes to Table 5–89:

(1) When J = 4 to 10, the SERDES block is used.

(2) When J = 1 or 2, the SERDES block is bypassed.

(3) The input clock frequency and the W factor must satisfy the following fast PLL VCO specification: $150 \leq$ input clock frequency $\times W \leq 1{,}040$.

(4) The minimum specification is dependent on the clock source (fast PLL, enhanced PLL, clock pin, and so on) and the clock routing resource (global, regional, or local) utilized. The I/O differential buffer and input register do not have a minimum toggle rate.

Table 5–103. Document Revision History (Part 2 of 3)

Date and Document Version	Changes Made	Summary of Changes
August, 2006, v4.2	Updated Table 5–73, Table 5–75, Table 5–77, Table 5–78, Table 5–79, Table 5–81, Table 5–85, and Table 5–87.	—
April 2006, v4.1	● Updated Table 5–3. ● Updated Table 5–11. ● Updated Figures 5–8 and 5–9. ● Added parallel on-chip termination information to “On-Chip Termination Specifications” section. ● Updated Tables 5–28, 5–30,5–31, and 5–34. ● Updated Table 5–78, Tables 5–81 through 5–90, and Tables 5–92, 5–93, and 5–98. ● Updated “PLL Timing Specifications” section. ● Updated “External Memory Interface Specifications” section. ● Added Tables 5–95 and 5–101. ● Updated “JTAG Timing Specifications” section, including Figure 5–10 and Table 5–102.	● Changed 0.2 MHz to 2 MHz in Table 5–93. ● Added new spec for half period jitter (Table 5–101). ● Added support for PLL clock switchover for industrial temperature range. ● Changed f_{INPFD} (min) spec from 4 MHz to 2 MHz in Table 5–92. ● Fixed typo in $t_{OUTJITTER}$ specification in Table 5–92. ● Updated V_{DIF} AC & DC max specifications in Table 5–28. ● Updated minimum values for t_{JCH}, t_{JCL}, and t_{JPSU} in Table 5–102. ● Update maximum values for t_{JPCO}, t_{JPZX}, and t_{JPXZ} in Table 5–102.
December 2005, v4.0	● Updated “External Memory Interface Specifications” section. ● Updated timing numbers throughout chapter.	—
July 2005, v3.1	● Updated HyperTransport technology information in Table 5–13. ● Updated “Timing Model” section. ● Updated “PLL Timing Specifications” section. ● Updated “External Memory Interface Specifications” section.	—
May 2005, v3.0	● Updated tables throughout chapter. ● Updated “Power Consumption” section. ● Added various tables. ● Replaced “Maximum Input & Output Clock Rate” section with “Maximum Input & Output Clock Toggle Rate” section. ● Added “Duty Cycle Distortion” section. ● Added “External Memory Interface Specifications” section.	—
March 2005, v2.2	Updated tables in “Internal Timing Parameters” section.	—
January 2005, v2.1	Updated input rise and fall time.	—