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Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Obsolete
Number of LABs/CLBs	4548
Number of Logic Elements/Cells	90960
Total RAM Bits	4520488
Number of I/O	902
Number of Gates	-
Voltage - Supply	1.15V ~ 1.25V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	1508-BBGA, FCBGA
Supplier Device Package	1508-FBGA, FC (40x40)
Purchase URL	https://www.e-xfl.com/product-detail/intel/ep2s90f1508c5

Stratix II devices are available in space-saving FineLine BGA® packages (see Tables 1–2 and 1–3).

Table 1–2. Stratix II Package Options & I/O Pin Counts *Notes (1), (2)*

Device	484-Pin FineLine BGA	484-Pin Hybrid FineLine BGA	672-Pin FineLine BGA	780-Pin FineLine BGA	1,020-Pin FineLine BGA	1,508-Pin FineLine BGA
EP2S15	342		366			
EP2S30	342		500			
EP2S60 *(3)*	334		492		718	
EP2S90 *(3)*		308		534	758	902
EP2S130 *(3)*				534	742	1,126
EP2S180 *(3)*					742	1,170

Notes to Table 1–2:

(1) All I/O pin counts include eight dedicated clock input pins (`clk1p`, `clk1n`, `clk3p`, `clk3n`, `clk9p`, `clk9n`, `clk11p`, and `clk11n`) that can be used for data inputs.

(2) The Quartus II software I/O pin counts include one additional pin, `PLL_ENA`, which is not available as general-purpose I/O pins. The `PLL_ENA` pin can only be used to enable the PLLs within the device.

(3) The I/O pin counts for the EP2S60, EP2S90, EP2S130, and EP2S180 devices in the 1020-pin and 1508-pin packages include eight dedicated fast PLL clock inputs (`FPLL7CLKp/n`, `FPLL8CLKp/n`, `FPLL9CLKp/n`, and `FPLL10CLKp/n`) that can be used for data inputs.

Table 1–3. Stratix II FineLine BGA Package Sizes

Dimension	484 Pin	484-Pin Hybrid	672 Pin	780 Pin	1,020 Pin	1,508 Pin
Pitch (mm)	1.00	1.00	1.00	1.00	1.00	1.00
Area (mm2)	529	729	729	841	1,089	1,600
Length × width (mm × mm)	23 × 23	27 × 27	27 × 27	29 × 29	33 × 33	40 × 40

All Stratix II devices support vertical migration within the same package (for example, you can migrate between the EP2S15, EP2S30, and EP2S60 devices in the 672-pin FineLine BGA package). Vertical migration means that you can migrate to devices whose dedicated pins, configuration pins, and power pins are the same for a given package across device densities.

To ensure that a board layout supports migratable densities within one package offering, enable the applicable vertical migration path within the Quartus II software (Assignments menu > Device > Migration Devices).

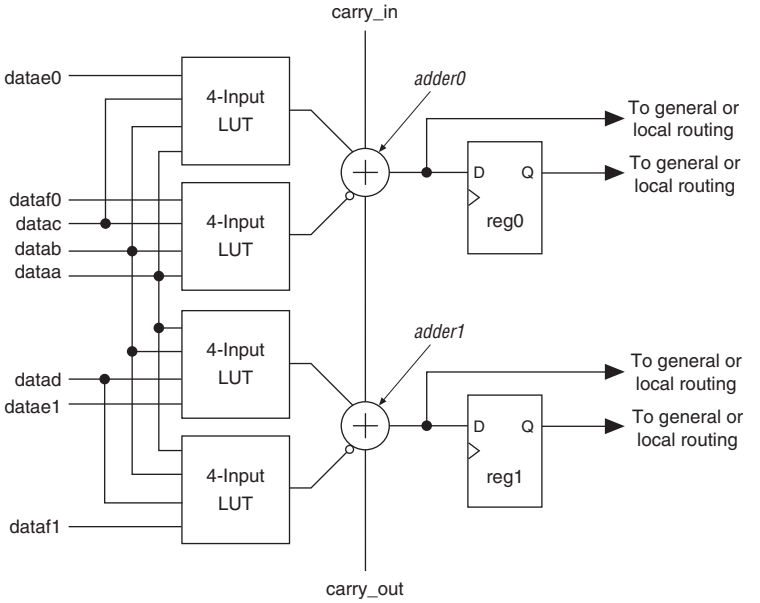
Document Revision History

Table 1–6 shows the revision history for this chapter.

Table 1–6. Document Revision History

Date and Document Version	Changes Made	Summary of Changes
May 2007, v4.2	Moved Document Revision History to the end of the chapter.	—
April 2006, v4.1	• Updated "Features" section. • Removed Note 4 from Table 1–2. • Updated Table 1–4.	—
December 2005, v4.0	• Updated Tables 1–2, 1–4, and 1–5. • Updated Figure 2–43.	—
July 2005, v3.1	• Added vertical migration information, including Table 1–4. • Updated Table 1–5.	—
May 2005, v3.0	• Updated "Features" section. • Updated Table 1–2.	—
March 2005, v2.1	Updated "Introduction" and "Features" sections.	—
January 2005, v2.0	Added note to Table 1–2.	—
October 2004, v1.2	Updated Tables 1–2, 1–3, and 1–5.	—
July 2004, v1.1	• Updated Tables 1–1 and 1–2. • Updated "Features" section.	—
February 2004, v1.0	Added document to the Stratix II Device Handbook.	—

Figure 2–11. ALM in Arithmetic Mode



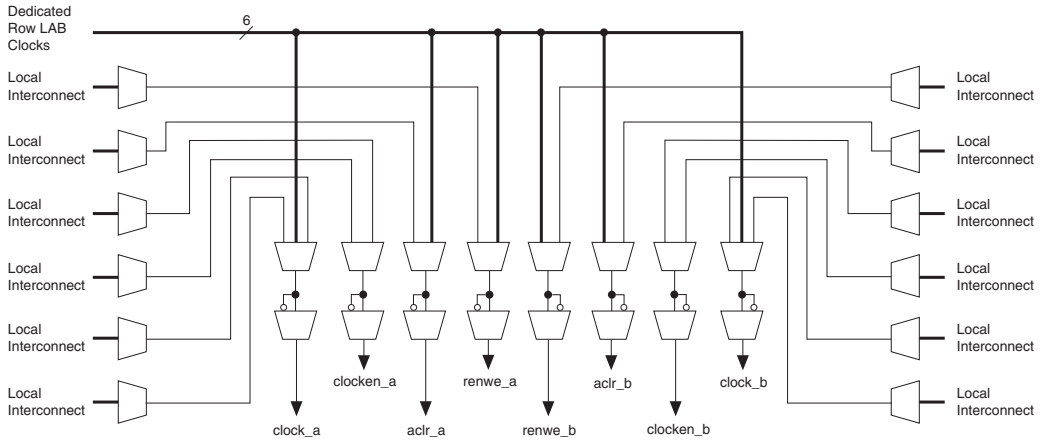
While operating in arithmetic mode, the ALM can support simultaneous use of the adder's carry output along with combinational logic outputs. In this operation, the adder output is ignored. This usage of the adder with the combinational logic output provides resource savings of up to 50% for functions that can use this ability. An example of such functionality is a conditional operation, such as the one shown in Figure 2–12. The equation for this example is:

$$R = (X < Y) ? Y : X$$

To implement this function, the adder is used to subtract 'Y' from 'X.' If 'X' is less than 'Y,' the `carry_out` signal is '1.' The `carry_out` signal is fed to an adder where it drives out to the LAB local interconnect. It then feeds to the LAB-wide `syncload` signal. When asserted, `syncload` selects the `syncdata` input. In this case, the data 'Y' drives the `syncdata` inputs to the registers. If 'X' is greater than or equal to 'Y,' the `syncload` signal is de-asserted and 'X' drives the data port of the registers.

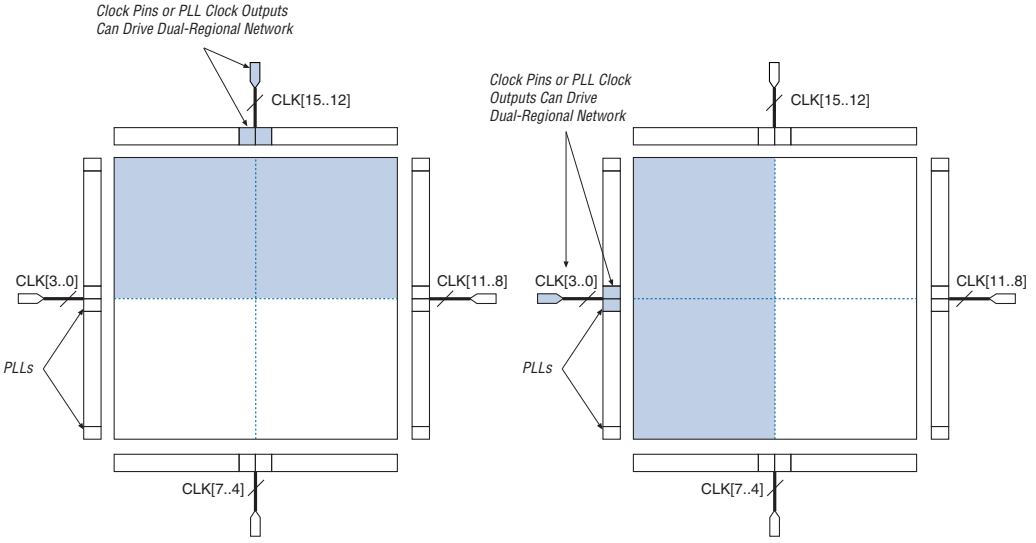
Similar to all RAM blocks, M-RAM blocks can have different clocks on their inputs and outputs. Either of the two clocks feeding the block can clock M-RAM block registers (renwe, address, byte enable, datain, and output registers). The output register can be bypassed. The six `labclk` signals or local interconnect can drive the control signals for the A and B ports of the M-RAM block. ALMs can also control the `clock_a`, `clock_b`, `renwe_a`, `renwe_b`, `clr_a`, `clr_b`, `clocken_a`, and `clocken_b` signals as shown in Figure 2–23.

Figure 2–23. M-RAM Block Control Signals



The R4, R24, C4, and direct link interconnects from adjacent LABs on either the right or left side drive the M-RAM block local interconnect. Up to 16 direct link input connections to the M-RAM block are possible from the left adjacent LABs and another 16 possible from the right adjacent LAB. M-RAM block outputs can also connect to left and right LABs through direct link interconnect. Figure 2–24 shows an example floorplan for the EP2S130 device and the location of the M-RAM interfaces. Figures 2–25 and 2–26 show the interface between the M-RAM block and the logic array.

Figure 2–33. Dual-Regional Clocks



Combined Resources

Within each quadrant, there are 24 distinct dedicated clocking resources consisting of 16 global clock lines and eight regional clock lines. Multiplexers are used with these clocks to form busses to drive LAB row clocks, column IOE clocks, or row IOE clocks. Another multiplexer is used at the LAB level to select three of the six row clocks to feed the ALM registers in the LAB (see Figure 2–34).

Figure 2–34. Hierarchical Clock Networks Per Quadrant

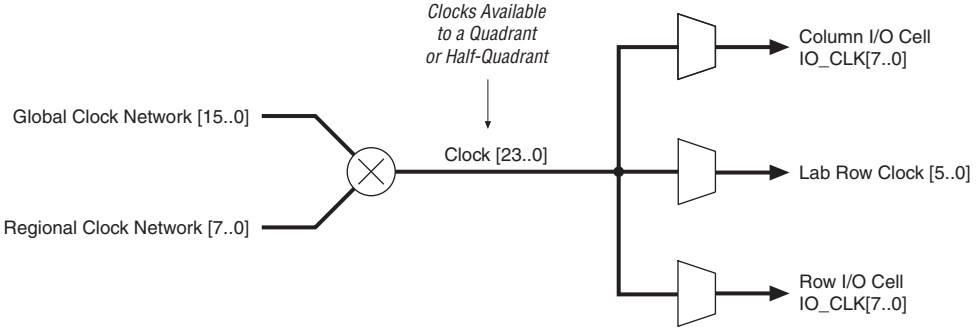


Table 2–14. DQS & DQ Bus Mode Support (Part 2 of 2) *Note (1)*

Device	Package	Number of ×4 Groups	Number of ×8/×9 Groups	Number of ×16/×18 Groups	Number of ×32/×36 Groups
EP2S90	484-pin Hybrid FineLine BGA	8	4	0	0
	780-pin FineLine BGA	18	8	4	0
	1,020-pin FineLine BGA	36	18	8	4
	1,508-pin FineLine BGA	36	18	8	4
EP2S130	780-pin FineLine BGA	18	8	4	0
	1,020-pin FineLine BGA	36	18	8	4
	1,508-pin FineLine BGA	36	18	8	4
EP2S180	1,020-pin FineLine BGA	36	18	8	4
	1,508-pin FineLine BGA	36	18	8	4

Notes to Table 2–14:
(1) Check the pin table for each DQS/DQ group in the different modes.

A compensated delay element on each DQS pin automatically aligns input DQS synchronization signals with the data window of their corresponding DQ data signals. The DQS signals drive a local DQS bus in the top and bottom I/O banks. This DQS bus is an additional resource to the I/O clocks and is used to clock DQ input registers with the DQS signal.

The Stratix II device has two phase-shifting reference circuits, one on the top and one on the bottom of the device. The circuit on the top controls the compensated delay elements for all DQS pins on the top. The circuit on the bottom controls the compensated delay elements for all DQS pins on the bottom.

Each phase-shifting reference circuit is driven by a system reference clock, which must have the same frequency as the DQS signal. Clock pins `CLK[15..12]p` feed the phase circuitry on the top of the device and clock pins `CLK[7..4]p` feed the phase circuitry on the bottom of the device. In addition, PLL clock outputs can also feed the phase-shifting reference circuits.

Figure 2–56 illustrates the phase-shift reference circuit control of each DQS delay shift on the top of the device. This same circuit is duplicated on the bottom of the device.

Table 2–27. Document Revision History (Part 2 of 2)

Date and Document Version	Changes Made	Summary of Changes
January 2005, v2.0	• Updated the "MultiVolt I/O Interface" and "TriMatrix Memory" sections. • Updated Tables 2–3, 2–17, and 2–19.	—
October 2004, v1.2	• Updated Tables 2–9, 2–16, 2–26, and 2–27.	—
July 2004, v1.1	• Updated note to Tables 2–9 and 2–16. • Updated Tables 2–16, 2–17, 2–18, 2–19, and 2–20. • Updated Figures 2–41, 2–42, and 2–57. • Removed 3 from list of SERDES factor *J*. • Updated "High-Speed Differential I/O with DPA Support" section. • In "Dedicated Circuitry with DPA Support" section, removed XSBI and changed RapidIO to Parallel RapidIO.	—
February 2004, v1.0	Added document to the Stratix II Device Handbook.	—

the Device & Pin Options dialog box in the Quartus II software uses a 32-bit CRC circuit to ensure data reliability and is one of the best options for mitigating SEU.

You can implement the error detection CRC feature with existing circuitry in Stratix II devices, eliminating the need for external logic. For Stratix II devices, CRC is computed by the device during configuration and checked against an automatically computed CRC during normal operation. The CRC_ERROR pin reports a soft error when configuration SRAM data is corrupted, triggering device reconfiguration.

Custom-Built Circuitry

Dedicated circuitry is built in the Stratix II devices to perform error detection automatically. This error detection circuitry in Stratix II devices constantly checks for errors in the configuration SRAM cells while the device is in user mode. You can monitor one external pin for the error and use it to trigger a re-configuration cycle. You can select the desired time between checks by adjusting a built-in clock divider.

Software Interface

In the Quartus II software version 4.1 and later, you can turn on the automated error detection CRC feature in the Device & Pin Options dialog box. This dialog box allows you to enable the feature and set the internal frequency of the CRC between 400 kHz to 50 MHz. This controls the rate that the CRC circuitry verifies the internal configuration SRAM bits in the FPGA device.

For more information on CRC, refer to *AN 357: Error Detection Using CRC in Altera FPGA Devices*.

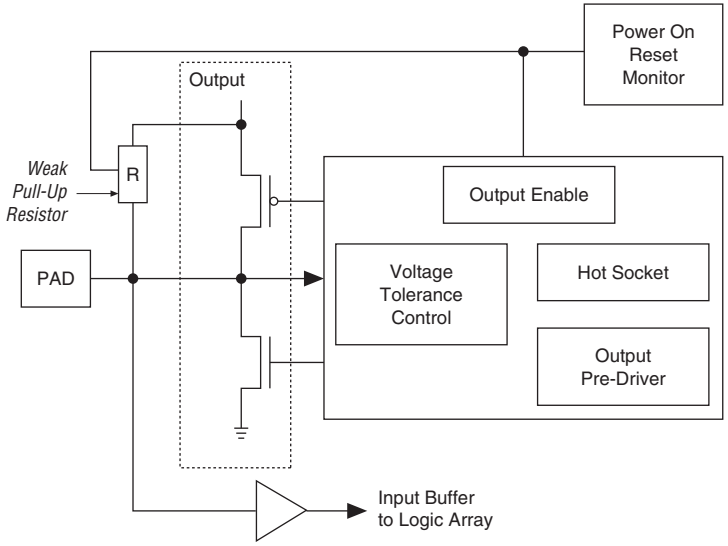
Document Revision History

Table 3–7 shows the revision history for this chapter.

Table 3–7. Document Revision History (Part 1 of 2)

Date and Document Version	Changes Made	Summary of Changes
May 2007, v4.2	Moved Document Revision History section to the end of the chapter.	—
	Updated the "Temperature Sensing Diode (TSD)" section.	—

Figure 4–1. Hot Socketing Circuit Block Diagram for Stratix II Devices



The POR circuit monitors V_{CCINT} voltage level and keeps I/O pins tri-stated until the device is in user mode. The weak pull-up resistor (R) from the I/O pin to V_{CCIO} is present to keep the I/O pins from floating. The 3.3-V tolerance control circuit permits the I/O pins to be driven by 3.3 V before V_{CCIO} and/or V_{CCINT} and/or V_{CCPD} are powered, and it prevents the I/O pins from driving out when the device is not in user mode. The hot socket circuit prevents I/O pins from internally powering V_{CCIO}, V_{CCINT}, and V_{CCPD} when driven by external signals before the device is powered.

Figure 4–2 shows a transistor level cross section of the Stratix II device I/O buffers. This design ensures that the output buffers do not drive when V_{CCIO} is powered before V_{CCINT} or if the I/O pad voltage is higher than V_{CCIO}. This also applies for sudden voltage spikes during hot insertion. There is no current path from signal I/O pins to V_{CCINT} or V_{CCIO} or V_{CCPD} during hot insertion. The V_{PAD} leakage current charges the 3.3-V tolerant circuit capacitance.

Table 5–2. Maximum Duty Cycles in Voltage Transitions				
Symbol	**Parameter**	**Condition**	**Maximum Duty Cycles**	**Unit**
V_I	Maximum duty cycles in voltage transitions	V_I = 4.0 V	100	%
		V_I = 4.1 V	90	%
		V_I = 4.2 V	50	%
		V_I = 4.3 V	30	%
		V_I = 4.4 V	17	%
		V_I = 4.5 V	10	%

Recommended Operating Conditions

Table 5–3 contains the Stratix II device family recommended operating conditions.

Table 5–3. Stratix II Device Recommended Operating Conditions (Part 1 of 2) Note (1)					
Symbol	**Parameter**	**Conditions**	**Minimum**	**Maximum**	**Unit**
V_{CCINT}	Supply voltage for internal logic	100 µs ≤ risetime ≤ 100 ms *(3)*	1.15	1.25	V
V_{CCIO}	Supply voltage for input and output buffers, 3.3-V operation	100 µs ≤ risetime ≤ 100 ms *(3)*, *(6)*	3.135 (3.00)	3.465 (3.60)	V
	Supply voltage for input and output buffers, 2.5-V operation	100 µs ≤ risetime ≤ 100 ms *(3)*	2.375	2.625	V
	Supply voltage for input and output buffers, 1.8-V operation	100 µs ≤ risetime ≤ 100 ms *(3)*	1.71	1.89	V
	Supply voltage for output buffers, 1.5-V operation	100 µs ≤ risetime ≤ 100 ms *(3)*	1.425	1.575	V
	Supply voltage for input and output buffers, 1.2-V operation	100 µs ≤ risetime ≤ 100 ms *(3)*	1.14	1.26	V
V_{CCPD}	Supply voltage for pre-drivers as well as configuration and JTAG I/O buffers.	100 µs ≤ risetime ≤ 100 ms *(4)*	3.135	3.465	V
V_{CCA}	Analog power supply for PLLs	100 µs ≤ risetime ≤ 100 ms *(3)*	1.15	1.25	V
V_{CCD}	Digital power supply for PLLs	100 µs ≤ risetime ≤ 100 ms *(3)*	1.15	1.25	V
V_I	Input voltage (see Table 5–2)	*(2)*, *(5)*	–0.5	4.0	V
V_O	Output voltage		0	V_{CCIO}	V

Table 5–3. Stratix II Device Recommended Operating Conditions (Part 2 of 2) Note (1)					
Symbol	**Parameter**	**Conditions**	**Minimum**	**Maximum**	**Unit**
T_J	Operating junction temperature	For commercial use	0	85	°C
		For industrial use	–40	100	°C
		For military use *(7)*	–55	125	°C

Notes to Table 5–3:

(1) Supply voltage specifications apply to voltage readings taken at the device pins, not at the power supply.

(2) During transitions, the inputs may overshoot to the voltage shown in Table 5–2 based upon the input duty cycle. The DC case is equivalent to 100% duty cycle. During transitions, the inputs may undershoot to –2.0 V for input currents less than 100 mA and periods shorter than 20 ns.

(3) Maximum V_{CC} rise time is 100 ms, and V_{CC} must rise monotonically from ground to V_{CC}.

(4) V_{CCPD} must ramp-up from 0 V to 3.3 V within 100 µs to 100 ms. If V_{CCPD} is not ramped up within this specified time, your Stratix II device does not configure successfully. If your system does not allow for a V_{CCPD} ramp-up time of 100 ms or less, you must hold `nCONFIG` low until all power supplies are reliable.

(5) All pins, including dedicated inputs, clock, I/O, and JTAG pins, may be driven before V_{CCINT}, V_{CCPD}, and V_{CCIO} are powered.

(6) V_{CCIO} maximum and minimum conditions for PCI and PCI-X are shown in parentheses.

(7) For more information, refer to the *Stratix II Military Temperature Range Support* technical brief.

DC Electrical Characteristics

Table 5–4 shows the Stratix II device family DC electrical characteristics.

Table 5–4. Stratix II Device DC Operating Conditions (Part 1 of 2) Note (1)							
Symbol	**Parameter**	**Conditions**		**Minimum**	**Typical**	**Maximum**	**Unit**
I_I	Input pin leakage current	$V_I = V_{CCIOmax}$ to 0 V *(2)*		–10		10	µA
I_{OZ}	Tri-stated I/O pin leakage current	$V_O = V_{CCIOmax}$ to 0 V *(2)*		–10		10	µA
I_{CCINT0}	V_{CCINT} supply current (standby)	V_I = ground, no load, no toggling inputs T_J = 25° C	EP2S15		0.25	*(3)*	A
			EP2S30		0.30	*(3)*	A
			EP2S60		0.50	*(3)*	A
			EP2S90		0.62	*(3)*	A
			EP2S130		0.82	*(3)*	A
			EP2S180		1.12	*(3)*	A
I_{CCPD0}	V_{CCPD} supply current (standby)	V_I = ground, no load, no toggling inputs T_J = 25° C, V_{CCPD} = 3.3V	EP2S15		2.2	*(3)*	mA
			EP2S30		2.7	*(3)*	mA
			EP2S60		3.6	*(3)*	mA
			EP2S90		4.3	*(3)*	mA
			EP2S130		5.4	*(3)*	mA
			EP2S180		6.8	*(3)*	mA

Table 5–34. Output Timing Measurement Methodology for Output Pins *Notes (1), (2), (3)*

I/O Standard	Loading and Termination						Measurement Point
	R_S (Ω)	R_D (Ω)	R_T (Ω)	V_{CCIO} (V)	V_{TT} (V)	C_L (pF)	V_{MEAS} (V)
LVTTL *(4)*				3.135		0	1.5675
LVCMOS *(4)*				3.135		0	1.5675
2.5 V *(4)*				2.375		0	1.1875
1.8 V *(4)*				1.710		0	0.855
1.5 V *(4)*				1.425		0	0.7125
PCI *(5)*				2.970		10	1.485
PCI-X *(5)*				2.970		10	1.485
SSTL-2 Class I	25		50	2.325	1.123	0	1.1625
SSTL-2 Class II	25		25	2.325	1.123	0	1.1625
SSTL-18 Class I	25		50	1.660	0.790	0	0.83
SSTL-18 Class II	25		25	1.660	0.790	0	0.83
1.8-V HSTL Class I	50		50	1.660	0.790	0	0.83
1.8-V HSTL Class II	25		25	1.660	0.790	0	0.83
1.5-V HSTL Class I	50		50	1.375	0.648	0	0.6875
1.5-V HSTL Class II			25	1.375	0.648	0	0.6875
1.2-V HSTL with OCT	50			1.140		0	0.570
Differential SSTL-2 Class I	50		50	2.325	1.123	0	1.1625
Differential SSTL-2 Class II	25		25	2.325	1.123	0	1.1625
Differential SSTL-18 Class I	50		50	1.660	0.790	0	0.83
Differential SSTL-18 Class II	25		25	1.660	0.790	0	0.83
1.5-V Differential HSTL Class I	50		50	1.375	0.648	0	0.6875
1.5-V Differential HSTL Class II			25	1.375	0.648	0	0.6875
1.8-V Differential HSTL Class I	50		50	1.660	0.790	0	0.83
1.8-V Differential HSTL Class II	25		25	1.660	0.790	0	0.83
LVDS		100		2.325		0	1.1625
HyperTransport		100		2.325		0	1.1625
LVPECL		100		3.135		0	1.5675

Notes to Table 5–34:

(1) Input measurement point at internal node is $0.5 \times V_{CCINT}$.

(2) Output measuring point for V_{MEAS} at buffer output is $0.5 \times V_{CCIO}$.

(3) Input stimulus edge rate is 0 to V_{CC} in 0.2 ns (internal signal) from the driver preceding the I/O buffer.

(4) Less than 50-mV ripple on V_{CCIO} and V_{CCPD}, V_{CCINT} = 1.15 V with less than 30-mV ripple

(5) V_{CCPD} = 2.97 V, less than 50-mV ripple on V_{CCIO} and V_{CCPD}, V_{CCINT} = 1.15 V

Table 5–36. Stratix II Performance Notes (Part 3 of 6) *Note (1)*

Applications		Resources Used			Performance				
		ALUTs	TriMatrix Memory Blocks	DSP Blocks	-3 Speed Grade *(2)*	-3 Speed Grade *(3)*	-4 Speed Grade	-5 Speed Grade	Unit
DSP block	9 × 9-bit multiplier *(5)*	0	0	1	430.29	409.16	373.13	320.10	MHz
	18 × 18-bit multiplier *(5)*	0	0	1	410.17	390.01	356.12	305.06	MHz
	18 × 18-bit multiplier *(7)*	0	0	1	450.04	428.08	391.23	335.12	MHz
	36 × 36-bit multiplier *(5)*	0	0	1	250.00	238.15	217.48	186.60	MHz
	36 × 36-bit multiplier *(6)*	0	0	1	410.17	390.01	356.12	305.06	MHz
	18-bit, four-tap FIR filter	0	0	1	410.17	390.01	356.12	305.06	MHz
Larger designs	8-bit,16-tap parallel FIR filter	58	0	4	259.06	240.61	217.15	185.01	MHz
	8-bit, 1024-point, streaming, three multipliers and five adders FFT function	2976	22	9	398.72	364.03	355.23	306.37	MHz
	8-bit, 1024-point, streaming, four multipliers and two adders FFT function	2781	22	12	398.56	409.16	347.22	311.13	MHz
	8-bit, 1024-point, single output, one parallel FFT engine, burst, three multipliers and five adders FFT function	984	5	3	425.17	365.76	346.98	292.39	MHz
	8-bit, 1024-point, single output, one parallel FFT engine, burst, four multipliers and two adders FFT function	919	5	4	427.53	378.78	357.14	307.59	MHz

Table 5–42. M-RAM Block Internal Timing Microparameters (Part 1 of 2) *Note (1)*

Symbol	Parameter	-3 Speed Grade (2)		-3 Speed Grade (3)		-4 Speed Grade		-5 Speed Grade		Unit
		Min (4)	Max	Min (4)	Max	Min (5)	Max	Min (4)	Max	
t_{MEGARC}	Synchronous read cycle time	1,866	2,774	1,866	2,911	1,777 1,866	3,189	1,777 1,866	3,716	ps
$t_{MEGAWERESU}$	Write or read enable setup time before clock	144		151		165 165		192		ps
$t_{MEGAWEREH}$	Write or read enable hold time after clock	39		40		44 44		52		ps
$t_{MEGABESU}$	Byte enable setup time before clock	50		52		57 57		67		ps
$t_{MEGABEH}$	Byte enable hold time after clock	39		40		44 44		52		ps
$t_{MEGADATAASU}$	A port data setup time before clock	50		52		57 57		67		ps
$t_{MEGADATAAH}$	A port data hold time after clock	243		255		279 279		325		ps
$t_{MEGAADDRASU}$	A port address setup time before clock	589		618		677 677		789		ps
$t_{MEGAADDRAH}$	A port address hold time after clock	241		253		277 277		322		ps
$t_{MEGADATABSU}$	B port setup time before clock	50		52		57 57		67		ps
$t_{MEGADATABH}$	B port hold time after clock	243		255		279 279		325		ps
$t_{MEGAADDRBSU}$	B port address setup time before clock	589		618		677 677		789		ps
$t_{MEGAADDRBH}$	B port address hold time after clock	241		253		277 277		322		ps
$t_{MEGADATACO1}$	Clock-to-output delay when using output registers	480	715	480	749	457 480	821	480	957	ps
$t_{MEGADATACO2}$	Clock-to-output delay without output registers	1,950	2,899	1,950	3,042	1,857 1,950	3,332	1,950	3,884	ps
$t_{MEGACLKL}$	Minimum clock low time	1,250		1,312		1,437 1,437		1,675		ps

Table 5–75. Stratix II I/O Output Delay for Column Pins (Part 4 of 8)

I/O Standard	Drive Strength	Parameter	Minimum Timing		-3 Speed Grade (3)	-3 Speed Grade (4)	-4 Speed Grade	-5 Speed Grade	Unit
			Industrial	Commercial					
SSTL-18 Class I	4 mA	t_{OP}	909	953	1690	1773	1942	2012	ps
		t_{DIP}	929	975	1756	1843	2018	2102	ps
	6 mA	t_{OP}	914	958	1656	1737	1903	1973	ps
		t_{DIP}	934	980	1722	1807	1979	2063	ps
	8 mA	t_{OP}	894	937	1640	1721	1885	1954	ps
		t_{DIP}	914	959	1706	1791	1961	2044	ps
	10 mA	t_{OP}	898	942	1638	1718	1882	1952	ps
		t_{DIP}	918	964	1704	1788	1958	2042	ps
	12 mA (1)	t_{OP}	891	936	1626	1706	1869	1938	ps
		t_{DIP}	911	958	1692	1776	1945	2028	ps
SSTL-18 Class II	8 mA	t_{OP}	883	925	1597	1675	1835	1904	ps
		t_{DIP}	903	947	1663	1745	1911	1994	ps
	16 mA	t_{OP}	894	937	1578	1655	1813	1882	ps
		t_{DIP}	914	959	1644	1725	1889	1972	ps
	18 mA	t_{OP}	890	933	1585	1663	1821	1890	ps
		t_{DIP}	910	955	1651	1733	1897	1980	ps
	20 mA (1)	t_{OP}	890	933	1583	1661	1819	1888	ps
		t_{DIP}	910	955	1649	1731	1895	1978	ps
1.8-V HSTL Class I	4 mA	t_{OP}	912	956	1608	1687	1848	1943	ps
		t_{DIP}	932	978	1674	1757	1924	2033	ps
	6 mA	t_{OP}	917	962	1595	1673	1833	1928	ps
		t_{DIP}	937	984	1661	1743	1909	2018	ps
	8 mA	t_{OP}	896	940	1586	1664	1823	1917	ps
		t_{DIP}	916	962	1652	1734	1899	2007	ps
	10 mA	t_{OP}	900	944	1591	1669	1828	1923	ps
		t_{DIP}	920	966	1657	1739	1904	2013	ps
	12 mA (1)	t_{OP}	892	936	1585	1663	1821	1916	ps
		t_{DIP}	912	958	1651	1733	1897	2006	ps

Table 5–77. Maximum Input Toggle Rate on Stratix II Devices (Part 2 of 2)

Input I/O Standard	Column I/O Pins (MHz)			Row I/O Pins (MHz)			Dedicated Clock Inputs (MHz)		
	-3	-4	-5	-3	-4	-5	-3	-4	-5
1.8-V HSTL Class II	500	500	500	500	500	500	500	500	500
PCI *(1)*	500	500	450	-	-	-	500	500	400
PCI-X *(1)*	500	500	450	-	-	-	500	500	400
1.2-V HSTL *(2)*	280	-	-	-	-	-	280	-	-
Differential SSTL-2 Class I *(1)*, *(3)*	500	500	500	-	-	-	500	500	500
Differential SSTL-2 Class II *(1)*, *(3)*	500	500	500	-	-	-	500	500	500
Differential SSTL-18 Class I *(1)*, *(3)*	500	500	500	-	-	-	500	500	500
Differential SSTL-18 Class II *(1)*, *(3)*	500	500	500	-	-	-	500	500	500
1.8-V Differential HSTL Class I *(1)*, *(3)*	500	500	500	-	-	-	500	500	500
1.8-V Differential HSTL Class II *(1)*, *(3)*	500	500	500	-	-	-	500	500	500
1.5-V Differential HSTL Class I *(1)*, *(3)*	500	500	500	-	-	-	500	500	500
1.5-V Differential HSTL Class II *(1)*, *(3)*	500	500	500	-	-	-	500	500	500
HyperTransport technology *(4)*	-	-	-	520	520	420	717	717	640
LVPECL *(1)*	-	-	-	-	-	-	450	450	400
LVDS *(5)*	-	-	-	520	520	420	717	717	640
LVDS *(6)*	-	-	-	-	-	-	450	450	400

Notes to Table 5–77:

(1) Row clock inputs don't support PCI, PCI-X, LVPECL, and differential HSTL and SSTL standards.
(2) 1.2-V HSTL is only supported on column I/O pins.
(3) Differential HSTL and SSTL standards are only supported on column clock and DQS inputs.
(4) HyperTransport technology is only supported on row I/O and row dedicated clock input pins.
(5) These numbers apply to I/O pins and dedicated clock pins in the left and right I/O banks.
(6) These numbers apply to dedicated clock pins in the top and bottom I/O banks.

Table 5–78. Maximum Output Toggle Rate on Stratix II Devices (Part 1 of 5) *Note (1)*

I/O Standard	Drive Strength	Column I/O Pins (MHz)			Row I/O Pins (MHz)			Clock Outputs (MHz)		
		-3	-4	-5	-3	-4	-5	-3	-4	-5
3.3-V LVTTL	4 mA	270	225	210	270	225	210	270	225	210
	8 mA	435	355	325	435	355	325	435	355	325
	12 mA	580	475	420	580	475	420	580	475	420
	16 mA	720	594	520	-	-	-	720	594	520
	20 mA	875	700	610	-	-	-	875	700	610
	24 mA	1,030	794	670	-	-	-	1,030	794	670
3.3-V LVCMOS	4 mA	290	250	230	290	250	230	290	250	230
	8 mA	565	480	440	565	480	440	565	480	440
	12 mA	790	710	670	-	-	-	790	710	670
	16 mA	1,020	925	875	-	-	-	1,020	925	875
	20 mA	1,066	985	935	-	-	-	1,066	985	935
	24 mA	1,100	1,040	1,000	-	-	-	1,100	1,040	1,000
2.5-V LVTTL/LVCMOS	4 mA	230	194	180	230	194	180	230	194	180
	8 mA	430	380	380	430	380	380	430	380	380
	12 mA	630	575	550	630	575	550	630	575	550
	16 mA	930	845	820	-	-	-	930	845	820
1.8-V LVTTL/LVCMOS	2 mA	120	109	104	120	109	104	120	109	104
	4 mA	285	250	230	285	250	230	285	250	230
	6 mA	450	390	360	450	390	360	450	390	360
	8 mA	660	570	520	660	570	520	660	570	520
	10 mA	905	805	755	-	-	-	905	805	755
	12 mA	1,131	1,040	990	-	-	-	1,131	1,040	990
1.5-V LVTTL/LVCMOS	2 mA	244	200	180	244	200	180	244	200	180
	4 mA	470	370	325	470	370	325	470	370	325
	6 mA	550	430	375	-	-	-	550	430	375
	8 mA	625	495	420	-	-	-	625	495	420
SSTL-2 Class I	8 mA	400	300	300	-	-	-	400	300	300
	12 mA	400	400	350	400	350	350	400	400	350
SSTL-2 Class II	16 mA	350	350	300	350	350	300	350	350	300
	20 mA	400	350	350	-	-	-	400	350	350
	24 mA	400	400	350	-	-	-	400	400	350

Table 5–82. Maximum DCD for DDIO Output on Row I/O Pins Without PLL in the Clock Path for -3 Devices *Notes (1), (2)*

Row DDIO Output I/O Standard	Maximum DCD Based on I/O Standard of Input Feeding the DDIO Clock Port (No PLL in Clock Path)					Unit
	TTL/CMOS		SSTL-2	SSTL/HSTL	LVDS/ HyperTransport Technology	
	3.3 & 2.5 V	1.8 & 1.5 V	2.5 V	1.8 & 1.5 V	3.3 V	
3.3-V LVTTL	260	380	145	145	110	ps
3.3-V LVCMOS	210	330	100	100	65	ps
2.5 V	195	315	85	85	75	ps
1.8 V	150	265	85	85	120	ps
1.5-V LVCMOS	255	370	140	140	105	ps
SSTL-2 Class I	175	295	65	65	70	ps
SSTL-2 Class II	170	290	60	60	75	ps
SSTL-18 Class I	155	275	55	50	90	ps
1.8-V HSTL Class I	150	270	60	60	95	ps
1.5-V HSTL Class I	150	270	55	55	90	ps
LVDS/ HyperTransport technology	180	180	180	180	180	ps

Notes to Table 5–82:
(1) The information in Table 5–82 assumes the input clock has zero DCD.
(2) The DCD specification is based on a no logic array noise condition.

Here is an example for calculating the DCD in percentage for a DDIO output on a row I/O on a -3 device:

If the input I/O standard is SSTL-2 and the DDIO output I/O standard is SSTL-2 Class II, the maximum DCD is 60 ps (see Table 5–82). If the clock frequency is 267 MHz, the clock period T is:

$$T = 1/f = 1 / 267\ \text{MHz} = 3.745\ \text{ns} = 3745\ \text{ps}$$

Calculate the DCD as a percentage:

$(T/2 - DCD) / T = (3745\text{ps}/2 - 60\text{ps}) / 3745\text{ps} = 48.4\%$ (for low boundary)

$(T/2 + DCD) / T = (3745\ \text{ps}/2 + 60\ \text{ps}) / 3745\text{ps} = 51.6\%$ (for high boundary)

External Memory Interface Specifications

Tables 5–94 through 5–101 contain Stratix II device specifications for the dedicated circuitry used for interfacing with external memory devices.

Table 5–94. DLL Frequency Range Specifications

Frequency Mode	Frequency Range	Resolution (Degrees)
0	100 to 175	30
1	150 to 230	22.5
2	200 to 310	30
3	240 to 400 (–3 speed grade)	36
	240 to 350 (–4 and –5 speed grades)	36

Table 5–95 lists the maximum delay in the fast timing model for the Stratix II DQS delay buffer. Multiply the number of delay buffers that you are using in the DQS logic block to get the maximum delay achievable in your system. For example, if you implement a 90° phase shift at 200 MHz, you use three delay buffers in mode 2. The maximum achievable delay from the DQS block is then 3 × .416 ps = 1.248 ns.

Table 5–95. DQS Delay Buffer Maximum Delay in Fast Timing Model

Frequency Mode	Maximum Delay Per Delay Buffer (Fast Timing Model)	Unit
0	0.833	ns
1, 2, 3	0.416	ns

Table 5–96. DQS Period Jitter Specifications for DLL-Delayed Clock (tDQS_JITTER) *Note (1)*

Number of DQS Delay Buffer Stages *(2)*	Commercial	Industrial	Unit
1	80	110	ps
2	110	130	ps
3	130	180	ps
4	160	210	ps

Notes to Table 5–96:
(1) Peak-to-peak period jitter on the phase shifted DQS clock.
(2) Delay stages used for requested DQS phase shift are reported in your project's Compilation Report in the Quartus II software.