



Welcome to **E-XFL.COM** 

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Product Status         Active           Core Processor         PIC           Core Size         8-Bit           Speed         64MHz           Connectivity         P*C, SPI, UART/USART           Peripherals         Brown-out Detect/Reset, HLVD, POR, PWM, WDT           Number of I/O         24           Program Memory Size         32KB (16K x 16)           Program Memory Type         FLASH           EEPROM Size         256 x 8           RAM Size         1.5K x 8           Voltage - Supply (Vcc/Vdd)         1.8V ~ 3.6V           Data Converters         A/D 11x10b           Oscillator Type         Internal           Operating Temperature         -40°C ~ 85°C (TA)           Mounting Type         Through Hole           Package / Case         28-DIP (0.300", 7.62mm)           Supplier Device Package         28-SPDIP           Purchase URL         https://www.e-xfl.com/product-detail/microchip-technology/pic18f25k20-i-sp	Dataila	
Core Processor  Core Size  8-Bit  Speed  64MHz  Connectivity  1°C, SPI, UART/USART  Peripherals  Brown-out Detect/Reset, HLVD, POR, PWM, WDT  Number of I/O  24  Program Memory Size  32KB (16K x 16)  Program Memory Type  FLASH  EEPROM Size  256 x 8  RAM Size  1.5K x 8  Voltage - Supply (Vcc/Vdd)  1.8V ~ 3.6V  Data Converters  A/D 11x10b  Oscillator Type  Internal  Operating Temperature  -40°C ~ 85°C (TA)  Mounting Type  Through Hole  Package / Case  28-DIP (0.300", 7.62mm)  Supplier Device Package	Details	
Core Size         8-Bit           Speed         64MHz           Connectivity         PC, SPI, UART/USART           Peripherals         Brown-out Detect/Reset, HLVD, POR, PWM, WDT           Number of I/O         24           Program Memory Size         32KB (16K x 16)           Program Memory Type         FLASH           EEPROM Size         256 x 8           RAM Size         1.5K x 8           Voltage - Supply (Vcc/Vdd)         1.8V ~ 3.6V           Data Converters         A/D 11x10b           Oscillator Type         Internal           Operating Temperature         -40°C ~ 85°C (TA)           Mounting Type         Through Hole           Package / Case         28-DIP (0.300", 7.62mm)           Supplier Device Package         28-SPDIP	Product Status	Active
Speed 64MHz  Connectivity   PC, SPI, UART/USART  Peripherals Brown-out Detect/Reset, HLVD, POR, PWM, WDT  Number of I/O 24  Program Memory Size 32KB (16K x 16)  Program Memory Type FLASH  EEPROM Size 256 x 8  RAM Size 1.5K x 8  Voltage - Supply (Vcc/Vdd) 1.8V ~ 3.6V  Data Converters A/D 11x10b  Oscillator Type Internal  Operating Temperature -40°C ~ 85°C (TA)  Mounting Type Through Hole  Package / Case 28-DIP (0.300", 7.62mm)  Supplier Device Package   Pthrough Hole   Package   Pthrough Hole   Package   Package	Core Processor	PIC
Connectivity   PC, SPI, UART/USART   Peripherals   Brown-out Detect/Reset, HLVD, POR, PWM, WDT   Number of I/O   24   Program Memory Size   32KB (16K x 16)   Program Memory Type   FLASH   EEPROM Size   256 x 8   RAM Size   1.5K x 8   Voltage - Supply (Vcc/Vdd)   1.8V ~ 3.6V   Data Converters   A/D 11x10b   Oscillator Type   Internal   Operating Temperature   -40°C ~ 85°C (TA)   Mounting Type   Through Hole   Package / Case   28-DIP (0.300", 7.62mm)   Supplier Device Package   28-SPDIP	Core Size	8-Bit
Peripherals  Brown-out Detect/Reset, HLVD, POR, PWM, WDT  Number of I/O  24  Program Memory Size  32KB (16K x 16)  Program Memory Type  FLASH  EEPROM Size  256 x 8  RAM Size  1.5K x 8  Voltage - Supply (Vcc/Vdd)  1.8V ~ 3.6V  Data Converters  A/D 11x10b  Oscillator Type  Internal  Operating Temperature  -40°C ~ 85°C (TA)  Mounting Type  Through Hole  Package / Case  28-DIP (0.300", 7.62mm)  Supplier Device Package  Pttps://www.e.a.xfl.com/product.detail/microschip.techpology/pic18f25k20 i.sp.	Speed	64MHz
Number of I/O 24  Program Memory Size 32KB (16K x 16)  Program Memory Type FLASH  EEPROM Size 256 x 8  RAM Size 1.5K x 8  Voltage - Supply (Vcc/Vdd) 1.8V ~ 3.6V  Data Converters A/D 11x10b  Oscillator Type Internal  Operating Temperature -40°C ~ 85°C (TA)  Mounting Type Through Hole  Package / Case 28-DIP (0.300", 7.62mm)  Supplier Device Package 28-SPDIP	Connectivity	I <sup>2</sup> C, SPI, UART/USART
Program Memory Size 32KB (16K x 16)  Program Memory Type FLASH  EEPROM Size 256 x 8  RAM Size 1.5K x 8  Voltage - Supply (Vcc/Vdd) 1.8V ~ 3.6V  Data Converters A/D 11x10b  Oscillator Type Internal  Operating Temperature -40°C ~ 85°C (TA)  Mounting Type Through Hole  Package / Case 28-DIP (0.300", 7.62mm)  Supplier Device Package 28-SPDIP	Peripherals	Brown-out Detect/Reset, HLVD, POR, PWM, WDT
Program Memory Type FLASH  EEPROM Size 256 x 8  RAM Size 1.5K x 8  Voltage - Supply (Vcc/Vdd) 1.8V ~ 3.6V  Data Converters A/D 11x10b  Oscillator Type Internal  Operating Temperature -40°C ~ 85°C (TA)  Mounting Type Through Hole  Package / Case 28-DIP (0.300", 7.62mm)  Supplier Device Package 28-SPDIP	Number of I/O	24
EEPROM Size  256 x 8  RAM Size  1.5K x 8  Voltage - Supply (Vcc/Vdd)  1.8V ~ 3.6V  Data Converters  A/D 11x10b  Oscillator Type  Internal  Operating Temperature  -40°C ~ 85°C (TA)  Mounting Type  Through Hole  Package / Case  28-DIP (0.300", 7.62mm)  Supplier Device Package  Pather://wwww.o.xfl.com/product.detail/microchip.technology/pic18f25k20.i.sp.	Program Memory Size	32KB (16K x 16)
RAM Size  1.5K x 8  Voltage - Supply (Vcc/Vdd)  1.8V ~ 3.6V  Data Converters  A/D 11x10b  Oscillator Type  Internal  Operating Temperature  -40°C ~ 85°C (TA)  Mounting Type  Through Hole  Package / Case  28-DIP (0.300", 7.62mm)  Supplier Device Package  28-SPDIP	Program Memory Type	FLASH
Voltage - Supply (Vcc/Vdd)  1.8V ~ 3.6V  Data Converters  A/D 11x10b  Oscillator Type  Internal  Operating Temperature  -40°C ~ 85°C (TA)  Mounting Type  Through Hole  Package / Case  28-DIP (0.300", 7.62mm)  Supplier Device Package  28-SPDIP	EEPROM Size	256 x 8
Data Converters  A/D 11x10b  Oscillator Type  Internal  Operating Temperature  -40°C ~ 85°C (TA)  Mounting Type  Through Hole  Package / Case  28-DIP (0.300", 7.62mm)  Supplier Device Package  28-SPDIP	RAM Size	1.5K x 8
Oscillator Type Internal  Operating Temperature -40°C ~ 85°C (TA)  Mounting Type Through Hole  Package / Case 28-DIP (0.300", 7.62mm)  Supplier Device Package 28-SPDIP	Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Operating Temperature  -40°C ~ 85°C (TA)  Mounting Type  Through Hole  Package / Case  28-DIP (0.300", 7.62mm)  Supplier Device Package  28-SPDIP  https://www.e.yfl.com/product.detail/microchip.technology/pic18f25k20.i.sp	Data Converters	A/D 11x10b
Mounting Type Through Hole Package / Case 28-DIP (0.300", 7.62mm) Supplier Device Package 28-SPDIP	Oscillator Type	Internal
Package / Case 28-DIP (0.300", 7.62mm)  Supplier Device Package 28-SPDIP  https://www.e.yfl.com/product_detail/microchip_technology/pic18f25k20_i.sp.	Operating Temperature	-40°C ~ 85°C (TA)
Supplier Device Package 28-SPDIP  https://www.e.xfl.com/product_detail/microchip_technology/pic18f25k20_i.sp.	Mounting Type	Through Hole
https://www.a.yfl.com/product_datail/microship_toshnology/pic18f25k20_i.sn	Package / Case	28-DIP (0.300", 7.62mm)
Purchase URL https://www.e-xfl.com/product-detail/microchip-technology/pic18f25k20-i-sp	Supplier Device Package	28-SPDIP
	Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18f25k20-i-sp

# PIC18F24K20/25K20/44K20/45K20 Silicon Errata and Data Sheet Clarification

The PIC18F24K20/25K20/44K20/45K20 devices that you have received conform functionally to the current Device Data Sheet (DS41303**H**), except for the anomalies described in this document.

The silicon issues discussed in the following pages are for silicon revisions with the Device and Revision IDs listed in Table 1. The silicon issues are summarized in Table 2.

The errata described in this document will be addressed in future revisions of the PIC18F24K20/25K20/44K20/45K20 silicon.

Note: This document summarizes all silicon errata issues from all revisions of silicon, previous as well as current. Only the issues indicated in the last column of Table 2 apply to the current silicon revision (AF).

Data Sheet clarifications and corrections start on page 13, following the discussion of silicon issues.

The silicon revision level can be identified using the current version of MPLAB<sup>®</sup> IDE and Microchip's programmers, debuggers, and emulation tools, which are available at the Microchip corporate web site (www.microchip.com).

For example, to identify the silicon revision level using MPLAB IDE in conjunction with a hardware debugger:

- 1. Using the appropriate interface, connect the device to the hardware debugger.
- 2. Open an MPLAB IDE project.
- 3. Configure the MPLAB IDE project for the appropriate device and hardware debugger.
- 4. Based on the version of MPLAB IDE you are using, do one of the following:
  - a) For MPLAB IDE 8, select <u>Programmer ></u> Reconnect.
  - b) For MPLAB X IDE, select <u>Window > Dashboard</u> and click the **Refresh Debug Tool Status** icon ( ).
- 5. Depending on the development tool used, the part number *and* Device Revision ID value appear in the **Output** window.

**Note:** If you are unable to extract the silicon revision level, please contact your local Microchip sales office for assistance.

The DEVREV values for the various PIC18F24K20/25K20/44K20/45K20 silicon revisions are shown in Table 1.

TABLE 1:	SILICON DEVR	EV VALUES
----------	--------------	-----------

Part Number	Device ID <sup>(1)</sup> (11-bit)		Revision ID for Silicon Revision <sup>(2)</sup> (5-bit)								
Fait Number	Device ID( / (11-bit)	A4	A7	A9	AB	A4	A7	A8	AE	AF	
PIC18F24K20	105h	0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C	
PIC18F25K20	103h	0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C	
PIC18F44K20	104h	0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C	
PIC18F45K20	102h	0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C	

- **Note 1:** The Device IDs (DEVID and DEVREV) are located at the last two implemented addresses of configuration memory space. They are shown in hexadecimal in the format "DEVID:DEVREV".
  - 2: Refer to the "PIC18F2XK20/4XK20 Flash Memory Programming Specification" (DS41297) for detailed information on Device and Revision IDs for your specific device.
  - 3: Shaded cells in this table indicate older device revisions that are no longer in production.

TABLE 2: SILICON ISSUE SUMMARY

					Δ	ffec	ted	Rev	/isic	ns <sup>(</sup>	1)	
Module	Feature	Item	Issue Summary	<b>A4</b>	A7	<b>A9</b>	AB	<b>A4</b>	A7	A8	AE	ΑF
modulo	i outuro	Number	locae cummary	0xA	0xC	0xE	0x11	0x16	0x18	0×19	0x1B	0x1C
ECCP	CCP1CON	1.	Changing CCP1M bits may cause capture of Timer1 value.	Х	Х	Х	Х					
ECCP	Full-Bridge mode	2.	Direction change issue.	Х	Х	Х	Х					
MSSP SPI	SPI Clock	3.	Shortened SPI high time.	Х	Х	Х	Х					
MSSP I <sup>2</sup> C	Slew Rate	4.	Slow slew rate when SLRCON<2> is set.	Х	Х	Х	Х					
ADC	Offset	5.	Time dependent on offset.	Х	Χ	Х	Х					
MSSP I <sup>2</sup> C	Receiving	6.	Address may be received as data.	Х	Х	Х	Х					
MSSP I <sup>2</sup> C	Master mode	7.	Master mode not functional.	Χ								
MSSP SPI	SPI Master	8.	Improper sampling of last bit.	Х	Х	Х	Х					
MSSP SPI	SPI Master	9.	SSPBUF improperly reloads on SS pin transitions.	Х	Х	Х	Х					
MSSP SPI	SPI Master	10.	Improper extra pulse on SCK pin.	Х	Х	Х	Х					
EUSART	Synchronous Master mode	11.	Duty cycle of CK output is skewed when SPBRG is odd.	Х	Х	Х	Х					
EUSART	Synchronous Master mode	12.	LS bit corruption during transmission when SPBRG = 3.	Х	Х	Х	Х					
EUSART	Synchronous Master mode	13.	Clock fails to stop at end of character transmission when SPBRG = 0.	Х	Х	Х	Х					
Internal Fixed Voltage Refer- ence (FVR)	_	14.	FVRST bit activates prematurely.	Х	Х							
High Low Voltage Detect (HLVD)	_	15.	IVRST bit activates prematurely.	Х	Х							
BOR	FVR	16.	Unexpected BOR occurrence.	Х	Х							
System Clocks	_	17.	HFINTOSC output accuracy.	Х	Х	Х	Х					
POR/BOR	_	18.	Unexpected code execution at low VDD.	Х	Х	Х	Х					
POR	_	19.	Premature POR release.	Х	Х	Х	Х					
POR	_	20.	POR may become stuck.	Х	Х	Х	Х					
Clocks	EC mode	21.	48 MHz maximum frequency.	Х	Х							
Comparators	Interrupt-on- Change	22.	Presetting interrupt-on-change issue.	Х	Х	Х	Х					
Data EEPROM Memory	Endurance	23.	Endurance is limited to 10K cycles.	Х	Х	Х	Х	Х	Χ	Х		
Program Flash Memory	Endurance	24.	Endurance is limited to 1K cycles.	Х	Х	Х	Х	Χ	Χ	Χ		
Configuration Bits	CONFIG3H	25.	HFOFST bit erases to '0' instead of '1'.	Х	Х	Х	Х					

Note 1: Only those issues indicated in the last column apply to the current silicon revision.

**<sup>2:</sup>** Shaded cells in this table indicate older device revisions that are no longer in production.

TABLE 2: SILICON ISSUE SUMMARY (CONTINUED)

				Affected Revisions				1)				
Module	Feature	Item	Issue Summary	A4	A7	A9	AB	<b>A4</b>	A7	<b>A8</b>	AE	AF
		Number	,	0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
EUSART	Asynchronous Receive mode	26.	RCIDL bit may stay low improperly.	Х	Х	Х	Х					
PORTB Interrupts	Interrupt-on- Change	27.	False interrupt when setting interrupt enable.	Х	Х	Х	Х	Х	Х	X	X	Х
ADC	ADC Conversion	28.	ADC conversion may be limited to half scale.	Х	Х	Х	Х	Х	Χ	Х		
ECCP	Full-Bridge mode	29.	Wrong dead-band time.	Х	Х	Х	Х	Х	Χ	Х	Х	Х
ECCP	Full-Bridge mode	30.	Wrong signal start time.	Х	Х	Х	Х	Х	Х	Х	Х	Х
MSSP SPI	SPI Clock	31.	Improper SCK output.	Х	Х	Х	Х	Х	Χ	Χ	Χ	Х
MSSP SPI	SPI Master	32.	Improper sampling of last bit.	Х	Х	Х	Х	Х	Χ	Χ	Χ	Χ
MSSP SPI	SPI Master	33.	Improper handling of write collision.	Х	Х	Х	Х	Х	Х	Х	Х	Х
MSSP I <sup>2</sup> C	I <sup>2</sup> C Master	34.	Improper handling of Stop event.	Χ	Х	Χ	Х	Х	Χ	Χ	Χ	Χ
EUSART	OERR Flag	35.	Clearing SPEN bit does not clear OERR flag.	Х	Х	Х	Х	Х	Х	Х	Х	Х
EUSART	BAUDCTL	36.	RCIDL bit may stay low improperly.	Х	Х	Х	Х	Х	Х	Х	Х	Х
PORTB Interrupts	Interrupt-on- Change	37.	False interrupt when waking from Sleep.	Х	Х	Х	Х	Х	Χ	Х	Х	Х
BOR	Reset	38.	Reset on configuring the analog comparators to the FVR.	Х	Х	Х	Х	Х	Х	Х	Х	Х
Wake-up from Low-Power Sleep mode	Wake-up Sources	39.	Device may not wake-up under specific conditions.	Х	Х	Х	Х	Х	X	Х	X	Х
Low-Voltage Detect	LVD in Sleep	40.	LVD erroneously triggers upon wake-up from Sleep if band gap is disabled in Sleep mode.	Х	Х	Х	Х	Х	X	X	X	Х
Timer1/3	Interrupt	41.	When the timer is operated in Asynchronous External Input mode, unexpected interrupt flag generation may occur.	Х	Х	Х	Х	Х	X	X	X	Х

**Note 1:** Only those issues indicated in the last column apply to the current silicon revision.

**<sup>2:</sup>** Shaded cells in this table indicate older device revisions that are no longer in production.

## Silicon Errata Issues

**Note 1:** This document summarizes all silicon errata issues from all specified revisions of silicon

**2:** Shaded cells in this section indicate latest silicon in production.

## 1. Module: ECCP

Changing the CCP1M<3:0> bits of CCP1CON may cause the CCPR1H and CCPR1L registers to capture the value of Timer1.

#### Work around

Halt Timer1 before changing ECCP mode. Reload Timer1 with desired value after ECCP is setup and before Timer1 is restarted.

#### **Affected Silicon Revisions**

0xA	0xC	3×0	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Х	Χ	Χ					

## 2. Module: ECCP

Changing direction in Full-Bridge mode does not insert dead time between changing the active drivers in common legs of the bridge.

#### Work around

None.

## Affected Silicon Revisions

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Χ					

## 3. Module: MSSP SPI

When the SPI clock is configured for Timer2/2 (SSPCON1<3:0> = 0011), the first SPI high time may be short.

#### Work around

Option 1: Ensure TMR2 value rolls over to zero immediately before writing to SSPBUF.

Option 2: Turn Timer2 off and clear TMR2 before writing SSPBUF. Enable TMR2 after SSPBUF is written.

#### **Affected Silicon Revisions**

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Х	Χ					

# 4. Module: MSSP I<sup>2</sup>C

Slew rate is slower than I<sup>2</sup>C specifications when the SLRCON<2> bit is set.

#### Work around

Clear SLRCON<2> bit when using the I<sup>2</sup>C peripheral.

#### **Affected Silicon Revisions**

0xA	OX0	3×0	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Χ					

#### 5. Module: ADC

Offset error is 3 LSb typical, 7 LSb maximum, including an acquisition time-dependent component (~2 LSb).

## Work around

The time dependent error is insignificant when the time between conversions is less than 100 ms. When the time since the previous conversion is greater than 100 ms then take two ADC conversions and discard the first.

#### **Affected Silicon Revisions**

0xA	Ox0	3×0	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Χ					

# 6. Module: MSSP I<sup>2</sup>C

If a new address byte is received while the BF flag is set, the SSPOV bit is properly set and an ACK is not properly generated. If only the SSPOV bit is set (BF flag was cleared) and a matching address is clocked in, that received byte will be improperly loaded into the SSPBUF register and an ACK will be improperly generated.

#### Work around

None.

	0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
I	Χ	Χ	Χ	Χ					

# 7. Module: MSSP I<sup>2</sup>C

I<sup>2</sup>C Master mode is not functional (Rev. A4 only).

#### Work around

Use software to emulate Master mode.

#### **Affected Silicon Revisions**

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
X								

# 8. Module: MSSP SPI

In SPI Master mode, when the CKE bit is cleared and the SMP bit is set, the last bit of the incoming data stream (bit 0) at the SDI pin will not be sampled properly.

#### Work around

None.

#### **Affected Silicon Revisions**

0xA	OX0	3×0	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Χ					

#### 9. Module: MSSP SPI

In SPI Master mode, when CKE bit is set, the SSPBUF will reload the SSPSR output shift register on every high-to-low transition of the  $\overline{\text{SS}}$  pin.

# Work around

Avoid using the  $\overline{SS}$  pin when the CKE bit is set and the MSSP is configured for SPI Master mode.

## **Affected Silicon Revisions**

0xA	OX0	3×0	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Χ					

## 10. Module: MSSP SPI

When SPI is enabled in Master mode with CKE = 1 and CKP = 0, a 1/Fosc wide pulse will occur on the SCK pin.

#### Work around

Configure SCK pin as an input until after the MSSP is setup.

#### **Affected Silicon Revisions**

0xA	Ox0	0×E	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Χ					

#### 11. Module: EUSART

In Synchronous Master mode, when the SPBRG is set to an odd number, the duty cycle of the CK output will be skewed by one baud clock count.

## Work around

High values of SPBRG will minimize the effect of this anomaly.

#### **Affected Silicon Revisions**

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Χ					

# 12. Module: EUSART

In Synchronous Master mode, when the SPBRG is set to 3 and the TXREG is written while the previous character is still in the TX shift register, the LS bit of the TXREG character may be corrupted during transmission.

#### Work around

When SPBRG is set to 3, wait until the TRMT bit of the TXSTA register is set before loading TXREG with the next character to be transmitted.

#### **Affected Silicon Revisions**

0xA	0xC	3×0	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Х	Χ	Χ					

#### 13. Module: EUSART

In Synchronous Master mode, if the SPBRG register is equal to 0 when the TXEN bit is set, then writing to TXREG will properly start transmission. However, the clock will be improperly out of phase with the data bits and the clock will not stop at the end of the character transmission.

#### Work around

Set SPBRG register to non-zero value before setting the TXEN bit.

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Х	Χ	Χ					

# 14. Module: Internal Fixed Voltage Reference (FVR)

The FVRST bit of the CVRCON2 register activates prematurely (Rev. A4 and A7 only).

#### Work around

Wait an additional 20  $\mu s$  after FVRST is sensed high before using the fixed voltage reference. Enable the FVR by setting the FVREN bit of the CVRCON2 register before activating any peripheral that automatically enables the FVR. Peripherals that automatically enable the FVR include the Brown-out Reset, the High/Low-Voltage Detect, and the HFINTOSC.

#### **Affected Silicon Revisions**

0xA	OX0	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ							

# 15. Module: High Low Voltage Detect (HLVD)

The IVRST bit of the HLVDCON register activates prematurely (Rev. A4 and A7 only).

#### Work around

Wait an additional 20 µs after IVRST is sensed high before using the fixed voltage reference. Enable the FVR by setting the FVREN bit of the CVRCON2 register before activating any peripheral that automatically enables the FVR. Peripherals that automatically enable the FVR include the Brown-out Reset, the High/Low-Voltage Detect, and the HFINTOSC.

# **Affected Silicon Revisions**

	0xA	Ox0	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
I	Χ	Χ							

#### 16. Module: BOR

An unexpected Brown-out Reset may occur when the fixed voltage reference is inactive and BOR is activated, thereby activating the fixed voltage reference simultaneously. This error is caused by a premature FVRST stable flag (Rev. A4 and A7 only) and only affects Brown-out disable in Sleep and software enabled BOR modes.

#### Work around

Enable the FVR by setting the FVREN bit of the CVRCON2 register and then wait an additional 20 µs after FVRST is sensed high before enabling BOR. Brown-out disable in Sleep mode with automatic enable on wake-up cannot be used.

#### **Affected Silicon Revisions**

0xA	Ox0	3×0	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ							

# 17. Module: System Clocks

HFINTOSC output frequency is 16 MHz ±3%, 25°C to 85°C.

#### Work around

None.

#### Affected Silicon Revisions

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Х	Х	Χ					

#### 18. Module: POR/BOR

The POR rearm voltage may be below the low end of the BOR range, causing unexpected code execution below the BOR range.

## Work around

Use external power monitor to hold the device in Reset below 1.1V.

0xA	Ox0	3×0	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Χ					

#### 19. Module: POR

The POR may release around 0.8V (below the POR rearm voltage of 1.2V, nominal) when VDD rises from below 0.60V (when BOR is not enabled) or 0.33V (when BOR is enabled).

#### Work around

Use Power-up Timer when operating with the EC, EXTRC or HFINTOSC oscillator modes. Ensure that VDD rise time is less than the Power-up Timer time.

#### **Affected Silicon Revisions**

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Х					

#### 20. Module: POR

The part may hang in the Reset state when VDD rises to the operating range at a rate faster than 7500V per second. Recovery from the hung state is possible only by first lowering VDD to below 0.3V, followed by raising VDD to the operating range.

#### Work around

Slow VDD rise time by adding series resistance between the voltage supply and the VDD pin and increasing the VDD bypass capacitance. VDD bypassing should remain on the pin side of the series resistor.

# **Affected Silicon Revisions**

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Χ					

#### 21. Module: Clocks

EC mode operation is limited to a maximum of 48 MHz (Rev. A4 and A7 only).

#### Work around

Divide external clock by 4 and use HS-PLL Clock mode for external clocking above 48 MHz.

## **Affected Silicon Revisions**

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Х	Х							

#### 22. Module: Comparators

When the CxON bit is clear, the output from the comparator will be properly forced to zero, but the CxPOL bit will improperly have no effect on the CxOUT bit. This prevents presetting the comparator change-on-interrupt mismatch latches as described in the data sheet.

#### Work around

Configure one of the unused comparator input channels as a digital output. Use that digital output to manipulate the comparator output to the desired CxOUT non-interrupt level. When the comparator is then set to the desired inputs, the mismatch latches will be preset to the non-interrupt level and the CxIF flag can then be cleared.

#### **Affected Silicon Revisions**

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Х	Х	Х	Χ					

## 23. Module: Data EEPROM Memory

The write/erase endurance of Data EE Memory is limited to 10K cycles.

#### Work around

Use error correction method that stores data in multiple locations.

#### **Affected Silicon Revisions**

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Х	Χ	Χ	Χ	Х	Χ		

# 24. Module: Program Flash Memory

The write/erase endurance of the PFM is limited to 1K cycles when VDD is above 3V. Endurance degrades when VDD is below 3V.

# Work around

For data tables in Program Flash Memory use error correction method that stores data in multiple locations.

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Χ	Χ	Χ	Χ		

## 25. Module: Configuration Bits

Bit 3 of CONFIG3H defaults to '0' after a Bulk Erase instead of '1' as specified in the data sheet.

#### Work around

Program the HFOFST bit to the desired state after a Bulk Erase. All MPLAB® IDE programming tools currently perform this way.

# **Affected Silicon Revisions**

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Χ					

#### 26. Module: EUSART

In Asynchronous Receive mode, the RCIDL bit of the BAUDCON register will properly go low when an invalid Start bit less than 1/8th of a bit time is received. The RCIDL bit will then stay low improperly until a valid Start bit is received.

#### Work around

When monitoring the RCIDL bit, measure the length of time between the RCIDL going low and the RCIF flag going high. If this time is greater than one character time, then restore the RCIDL bit by resetting the EUSART module. The EUSART module is reset when the SPEN bit of the RCSTA register is cleared.

#### **Affected Silicon Revisions**

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Х	Х	Х	Х					

#### 27. Module: PORTB

Setting a PORTB interrupt-on-change enable bit of the IOCB register while the corresponding PORTB input is high will cause an RBIF interrupt.

#### **Work around**

Set the IOCB bits to the desired configuration, then read PORTB to clear the mismatch latches. Finally, clear the RBIF bit before setting the RBIE bit.

#### Affected Silicon Revisions

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Х	Χ	Χ	Χ	Х	Χ	Χ

#### 28. Module: ADC

After extended stress, the Most Significant bit (MSb) of the ADC conversion result can become stuck at '0'. Conversions resulting in code 511 or less are still accurate, but conversions that should result in codes greater than 511 are, instead, pinned at 511.

The potential for failures is a function of several factors:

- The potential for failures increases over the life of the part. No failures have ever been seen for accelerated stress estimated to be equivalent to 34 years at room temperature. The failure rate after accelerated stress estimated to be equivalent to 146 years at room temperature can be as high as 10% for VDD = 1.8V. The time to failure will decrease as the operating temperature increases.
- The potential for failures is highest at low VDD and decreases as VDD increases.

#### Work around

- Restrict the input voltage to less than 1/2 of the ADC voltage reference so that the expected result is always a code less than or equal to 511.
- 2. Use manual acquisition time (ACQT<2:0> = 000) and put the part to Sleep after each conversion.

## **Affected Silicon Revisions**

	ОхА	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
I	Χ	Χ	Χ	Χ	Χ	Χ	Χ		

## 29. Module: ECCP

Changing direction in Full-Bridge mode inserts a dead-band time of 4/Fosc \* TMR2 Prescale instead of 1/Fosc \* TMR2 Prescale as specified in the data sheet.

# Work around

None.

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Х	Х	Χ	Х	Х	X	Х	Х

#### 30. Module: ECCP

ECCP – In Full-Bridge mode when PR2 = CCPR1L and DC1B[1:0] <>'00' and the direction is changed, then the dead time before the modulated output starts is compromised. The modulated signal improperly starts immediately with the direction change and stays on for Tosc \* TMR2 Prescale \* DC1B[1:0].

#### Work around

Avoid changing direction when the duty cycle is within three Least Significant steps of 100% duty cycle. Instead, clear the DC1B[1:0] bits before the direction change and then set them to the desired value after the direction change is complete.

#### **Affected Silicon Revisions**

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Χ	Χ	Х	Χ	Χ	Х

#### 31. Module: MSSP SPI

When the SPI clock is configured for Timer2/2 (SSPCON1<3:0> = 0011) and the CKE bit of the SSPSTAT register is '1', then when SSPBUF is written, the SCK output is improperly immediately driven to the non-Idle state together with the MSb value of the SSPBUF. The duration at which SDO and SCK remain at these levels may be shorter than a full half-bit period. The remaining bits in the byte are output properly.

#### Work around

None.

#### **Affected Silicon Revisions**

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Х	Х	Х	Χ	Х	Х	Χ	Х	Х

#### 32. Module: MSSP SPI

In SPI Master mode, when the CKE bit of the SSPSTAT register is cleared and the SMP bit of the SSPSTAT register is set, then the last bit of the incoming data stream (bit 0) at the SDI pin will not be sampled properly.

# Work around

None.

#### **Affected Silicon Revisions**

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Х	Χ	Χ	Х	Х	Х	Х	Χ

#### 33. Module: MSSP SPI

In SPI Master mode, if the SSPBUF register is written while a byte is actively being transmitted, an extra clock pulse will be improperly generated at the end of the transmission. Further writes to the SSPBUF register will be inhibited although 8 or 9 clock pulses will be generated for each attempted write. The WCON bit of the SSPCON register is properly set indicating that a write collision occurred. However, the write collision condition can only be cleared by resetting the MSSP module. Clear the MSSP by clearing the SSPEN bit of the SSPCON1 register.

#### Work around

Use the SSPIF bit of the PIR1 register or the BF bit of the SSPSTAT register to determine that the transmission is complete before writing the SSPBUF register. In the event that a write collision does occur, use the slave select feature to resynchronize the slave clock.

#### **Affected Silicon Revisions**

	0xA	Ox0	3×0	0x11	0x16	0x18	0x19	0x1B	0x1C
ĺ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ

#### 34. Module: MSSP I<sup>2</sup>C

In Master I<sup>2</sup>C Receive mode if a Stop condition occurs in the middle of an address or data reception, then the SCL clock stream will continue endlessly and the RCEN bit of the SSPCON2 register will remain set improperly. If a Start condition occurs after the improper Stop condition then nine additional clocks will be generated followed by the RCEN bit going low.

#### Work around

Use low-impedance pull-ups on the SDA line to reduce the possibility of noise glitches which may trigger an improper Stop event. Use a time-out event timer to detect the unexpected Stop condition and resulting stuck RCEN bit. Clear the stuck RCEN bit by clearing the SSPEN bit of SSPCON1.

0xA	0xC	0×E	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ

#### 35. Module: EUSART

The OERR flag of the RCSTA register is reset only by clearing the CREN bit of the RCSTA register or by a device Reset. Clearing the SPEN bit of the RCSTA register does not clear the OERR flag.

#### **Work around**

Clear the OERR flag by clearing the CREN bit instead of clearing the SPEN bit.

## **Affected Silicon Revisions**

0xA	Ox0	3×0	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Χ	Χ	Χ	Χ	Х	Χ

#### 36. Module: EUSART

In Asynchronous Receive mode, the RCIDL bit of the BAUDCON register will properly go low when an invalid Start bit less than 1/16th of a bit time is received. The RCIDL bit will then properly go high 1/8th of a bit time later. However, if another invalid Start bit occurs less than 1 bit time after the leading edge of the first invalid Start bit, then the RCIDL bit will improperly stay high then improperly go low one bit time later. The RCIDL bit will then stay low improperly until a valid Start bit is received.

#### Work around

When monitoring the RCIDL bit, measure the length of time between the RCIDL going low and the RCIF flag going high. If this time is greater than one character time, then restore the RCIDL bit by resetting the EUSART module. The EUSART module is reset when the SPEN bit of the RCSTA register is cleared.

#### **Affected Silicon Revisions**

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Χ	Χ	Х	Χ	Х	Х

# 37. Module: Interrupt-on-Change

When any interrupt-on-change is enabled and the corresponding input is high, then waking from Sleep by a source other than interrupt-on-change may cause the RBIF interrupt flag bit to become set improperly.

#### Work around

 Use the INTx interrupt in lieu of interrupt-onchange.

Or

 Store the state of the PORTB inputs before entering Sleep. Upon waking, if an RBIF is detected, then compare the PORTB levels with those stored. If they are the same, then clear and ignore the RBIF interrupt.

#### **Affected Silicon Revisions**

0xA	Ox0	3×0	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Χ	Χ	Х	Х	Х	Х

#### 38. Module: BOR

An unexpected Brown-out Reset may occur when enabling the comparator with the Fixed Voltage Reference (FVR) selected as the VIN+ input.

#### Work around

Disconnect the FVR from the VIN+ comparator inputs prior to enabling the comparator and then reconnect it after enabling the comparator.

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Х	Χ	Χ	Χ	Χ	Χ	Χ

# 39. Module: Wake-up from Low-Power Sleep mode

The device may not wake from Sleep when both of the following conditions are met:

- 1. The device is in Sleep mode for <1 ms;
- 2. On waking, the device executes a SLEEP instruction within 100 µs.

Under these conditions, the oscillator may stop before completing execution of the SLEEP instruction. The device will enter Sleep mode but will not wake-up on any enabled wake-up event, including the Watchdog Timer.

#### Work around

1. Disable High-Speed Start-up

Disabling High-Speed Start-up in the Configuration Word will delay the device executing code on wake-up by 250 µs, nominally, allowing the oscillator to stabilize.

The wake-up time from Sleep will increase by about 250 µs, nominally.

2. BOR enabled during Sleep

Configuring the device for hardware only BOR or software-controlled BOR and enabling SBOREN, the voltage reference is on during Sleep.

The device will wake-up and the oscillator will be stable. This will add 20  $\mu A$  (nominal) to the Sleep current.

3. Enable the FVR during Sleep

In the same manner as the BOR, the FVR will keep the voltage reference on during Sleep, causing the oscillator to be stable on wake-up.

4. Avoid executing SLEEP within 100  $\mu s$  of any wake-up event

This can be achieved by adding more instructions (NOP) before executing the SLEEP instruction. This minimizes the probability of the SLEEP instruction only partially executing.

#### **Affected Silicon Revisions**

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Х

#### 40. Module: Low-Voltage Detect

If Low-Voltage Detect is enabled, the band gap is disabled in Sleep, and the part is put to Sleep for a short period of time, the LVD will trigger immediately upon waking-up from Sleep.

#### Work around

Do not disable the band gap in Sleep when using the LVD.

#### **Affected Silicon Revisions**

0xA	Ox0	0×E	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Х	Χ	Х	Χ	Χ	Χ	Χ

#### 41. Module: Timer1/3

When Timer1 or Timer3 is operated in Asynchronous External Input mode, unexpected interrupt flag generation may occur if an external clock edge arrives too soon following a firmware write to the TMRxH:TMRxL registers. An unexpected interrupt flag event may also occur when enabling the module or switching from Synchronous to Asynchronous mode.

#### Work around

This issue only applies when operating the timer in Asynchronous mode. Whenever possible, operate the timer module in Synchronous mode to avoid spurious timer interrupts.

If Asynchronous mode must be used in the application, potential strategies to mitigate the issue may include any of the following:

- Design the firmware so it does not rely on the TMRxIF flag or keep the respective interrupt disabled. The timer still counts normally and does not reset to 0x0000 when the spurious interrupt flag event is generated.
- Design the firmware so that it does not write to the TMRxH:TMRxL registers or does not periodically disable/enable the timer, or switch modes. Reading from the timer does not trigger the spurious interrupt flag events.
- If the firmware must use the timer interrupts and must write to the timer (or disable/enable, or mode switch the timer), implement code to suppress the spurious interrupt event, should it occur. This can be achieved by following the process shown in Example 1.

# EXAMPLE 1: ASYNCHRONOUS TIMER MODE WORK AROUND TO AVOID SPURIOUS INTERRUPT

```
/Timer1 update procedure in asynchronous mode
//The code below uses Timer1 as example
T1CONbits.TMR1ON = 0;
                              //Stop timer from incrementing
PIE1bits.TMR1IE = 0;
                              //Temporarily disable Timer1 interrupt vectoring
TMR1H = 0x00;
                              //Update timer value
TMR1L = 0x00;
T1CONbits.TMR1ON = 1;
                             //Turn on timer
//Now wait at least two full T1CKI periods + 2T_{\mathrm{CY}} before re-enabling Timer1 interrupts.
^{\prime}/Depending upon clock edge timing relative to TMR1H/TMR1L firmware write operation,
/a spurious TMR1IF flag event may sometimes assert. If this happens, to suppress
//the actual interrupt vectoring, the TMR1IE bit should be kept clear until
//after the "window of opportunity" (for the spurious interrupt flag event has passed).
//After the window is passed, no further spurious interrupts occur, at least
//until the next timer write (or mode switch/enable event).
while(TMR1L < 0 \times 02);
                              //Wait for 2 timer increments more than the Updated Timer
                              //value (indicating more than 2 full T1CKI clock periods elapsed)
NOP();
                              //Wait two more instruction cycles
NOP();
PIR1bits.TMR1IF = 0;
                              //Clear TMR1IF flag, in case it was spuriously set
PIE1bits.TMR1IE = 1;
                              //Now re-enable interrupt vectoring for timer 1
```

0xA	0xC	0xE	0x11	0x16	0x18	0x19	0x1B	0x1C
Χ	Χ	Χ	Х	Х	Χ	Χ	Χ	Χ

#### **Data Sheet Clarifications**

The following typographic corrections and clarifications are to be noted for the latest version of the device data sheet (DS41303**H**):

Note: Corrections are shown in bold. Where

possible, the original bold text formatting

has been removed for clarity.

# 1. Module: Product Identification System

The temperature range values have been corrected.

# PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

PART NO.	ĪΧΊ	(1)	<u>X</u>		<u>/XX</u>	<u>XXX</u>
Device	Tape an Optio	d Reel on	Temper Ranç		Package	Pattern
Device:					F44K20; PIC18 F45K20; PIC1	
Tape and Reel Option:		= Standar = Tape ar	rd packagin nd Reel <sup>(1)</sup>	g (tube o	or tray)	
Temperature Range:			o +85°C o +125°C			
Package:	SS SO SP P ML	<ul> <li>SSOF</li> <li>SOIC</li> </ul>	P (Skinny P	•	,	
Pattern:		TP, Code	or Special I	Require	ments	

#### **Examples:**

- a) PIC18F45K20 E/P 301 = Industrial temp., PDIP package, QTP pattern #301.
- PIC18F24K20 I/SO = Industrial temp., SOIC package.
- PIC18F44K20 E/P = Extended temp., PDIP package.
- PIC18F46K20 I/PT = Industrial temp., TQFP package, tape and reel.

Note 1: Tape and Reel identifier only appears in the catalog part number description. This identifier is used for ordering purposes and is not printed on the device package. Check with your Microchip Sales Office for package availability with the Tape and Reel option.

# APPENDIX A: DOCUMENT REVISION HISTORY

# Rev A Document (12/2008)

Initial release of this document.

# **Rev B Document (05/2009)**

Updated Errata to new format; Added Module 11: PORTB and Module 12: ADC; minor edits.

Clarifications/Corrections to the Data Sheet: Added Module 1: MSSP; Module 2: Electrical Specifications; Module 3: Electrical Specifications.

# **Rev C Document (06/2009)**

Clarifications/Corrections to the Data Sheet:

Deleted Module 1: MSSP: Figure 17-17 Baud Rate Generator Block Diagram, updating subsequent numbering. Added Module 3 MSSP: Register 17-3 SSPADD; Added Module 4 MSSP: Section 17.4.2 Operation; Added Module 5 MSSP: Figure 17-16 MSSP Block Diagram; Added Module 6 MSSP: Sections 17.4.7.1, 17.4.8, 17.4.9, 17.4.17.1, 17.4.17.2, 17.4.17.3: SSPADD, changing <6:0> to <7:0>.

# **Rev D Document (11/2009)**

Updated to add revision 0x1B.

Data Sheet Clarifications: Deleted Modules 1, 2, 3, 4, 5, 6.

## Rev E Document (04/2010)

Updated to include early revisions of silicon, revision IDs 0xA through 0x11. These early revisions were described in DS80366 errata, which is now obsolete.

#### Rev F Document (05/2010)

Updated Table 1.

# Rev G Document (07/2010)

Removed ADC Work around #2 and changed #3 to #2 (Module 28).

## **Rev H Document (07/2011)**

Updated errata to the new format; Updated Module 16; Added Modules 38 and 39; Updated Table 2 to include the new modules.

Data Sheet Clarifications: Added Module 1.

#### Rev J Document (07/2012)

Added Silicon revision AF.

# Rev K Document (05/2013)

Added MPLAB X IDE; Added Module 40, Low-Voltage Detect.

Data Sheet Clarifications: Added Module 2, Electrical Characteristics.

# Rev L Document (12/2013)

Data Sheet Clarification: Updated Module 2 (Electrical Characteristics, Table 26-8).

## Rev M Document (4/2014)

Data Sheet Clarifications: Added Modules 3, 4, 5, 6, 7, 8.

## Rev N Document (7/2014)

Added Module 41, Timer1/3 to Silicon Errata Issues section.

# Rev P Document (9/2015)

**Data Sheet Clarifications:** 

Removed modules 1-8. Added Module 1, Product Identification System.

#### Note the following details of the code protection feature on Microchip devices:

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the
  intended manner and under normal conditions.
- There are dishonest and possibly illegal methods used to breach the code protection feature. All of these methods, to our knowledge, require using the Microchip products in a manner outside the operating specifications contained in Microchip's Data Sheets. Most likely, the person doing so is engaged in theft of intellectual property.
- Microchip is willing to work with the customer who is concerned about the integrity of their code.
- Neither Microchip nor any other semiconductor manufacturer can guarantee the security of their code. Code protection does not mean that we are guaranteeing the product as "unbreakable."

Code protection is constantly evolving. We at Microchip are committed to continuously improving the code protection features of our products. Attempts to break Microchip's code protection feature may be a violation of the Digital Millennium Copyright Act. If such acts allow unauthorized access to your software or other copyrighted work, you may have a right to sue for relief under that Act.

Information contained in this publication regarding device applications and the like is provided only for your convenience and may be superseded by updates. It is your responsibility to ensure that your application meets with your specifications. MICROCHIP MAKES NO REPRESENTATIONS OR WARRANTIES OF ANY KIND WHETHER EXPRESS OR IMPLIED, WRITTEN OR ORAL, STATUTORY OR OTHERWISE, RELATED TO THE INFORMATION, INCLUDING BUT NOT LIMITED TO ITS CONDITION, QUALITY, PERFORMANCE, MERCHANTABILITY OR FITNESS FOR PURPOSE. Microchip disclaims all liability arising from this information and its use. Use of Microchip devices in life support and/or safety applications is entirely at the buyer's risk, and the buyer agrees to defend, indemnify and hold harmless Microchip from any and all damages, claims, suits, or expenses resulting from such use. No licenses are conveyed, implicitly or otherwise, under any Microchip intellectual property rights unless otherwise stated.

#### **Trademarks**

The Microchip name and logo, the Microchip logo, dsPIC, FlashFlex, flexPWR, JukeBlox, KEELOQ, KEELOQ logo, Kleer, LANCheck, MediaLB, MOST, MOST logo, MPLAB, OptoLyzer, PIC, PICSTART, PIC<sup>32</sup> logo, RightTouch, SpyNIC, SST, SST Logo, SuperFlash and UNI/O are registered trademarks of Microchip Technology Incorporated in the U.S.A. and other countries.

The Embedded Control Solutions Company and mTouch are registered trademarks of Microchip Technology Incorporated in the U.S.A.

Analog-for-the-Digital Age, BodyCom, chipKIT, chipKIT logo, CodeGuard, dsPICDEM, dsPICDEM.net, ECAN, In-Circuit Serial Programming, ICSP, Inter-Chip Connectivity, KleerNet, KleerNet logo, MiWi, motorBench, MPASM, MPF, MPLAB Certified logo, MPLIB, MPLINK, MultiTRAK, NetDetach, Omniscient Code Generation, PICDEM, PICDEM.net, PICkit, PICtail, RightTouch logo, REAL ICE, SQI, Serial Quad I/O, Total Endurance, TSHARC, USBCheck, VariSense, ViewSpan, WiperLock, Wireless DNA, and ZENA are trademarks of Microchip Technology Incorporated in the U.S.A. and other countries.

 $\ensuremath{\mathsf{SQTP}}$  is a service mark of Microchip Technology Incorporated in the U.S.A.

Silicon Storage Technology is a registered trademark of Microchip Technology Inc. in other countries.

GestIC is a registered trademark of Microchip Technology Germany II GmbH & Co. KG, a subsidiary of Microchip Technology Inc., in other countries.

All other trademarks mentioned herein are property of their respective companies.

© 2008-2015, Microchip Technology Incorporated, Printed in the U.S.A., All Rights Reserved.

ISBN: 978-1-63277-796-6

# QUALITY MANAGEMENT SYSTEM CERTIFIED BY DNV = ISO/TS 16949=

Microchip received ISO/TS-16949:2009 certification for its worldwide headquarters, design and wafer fabrication facilities in Chandler and Tempe, Arizona; Gresham, Oregon and design centers in California and India. The Company's quality system processes and procedures are for its PIC® MCUs and dsPIC® DSCs, KEELOQ® code hopping devices, Serial EEPROMs, microperipherals, nonvolatile memory and analog products. In addition, Microchip's quality system for the design and manufacture of development systems is ISO 9001:2000 certified.

# Worldwide Sales and Service

#### **AMERICAS**

**Corporate Office** 

2355 West Chandler Blvd. Chandler, AZ 85224-6199 Tel: 480-792-7200 Fax: 480-792-7277

**Technical Support:** http://www.microchip.com/

support Web Address:

www.microchip.com

Atlanta Duluth, GA

Tel: 678-957-9614 Fax: 678-957-1455

Austin, TX Tel: 512-257-3370

**Boston** 

Westborough, MA Tel: 774-760-0087 Fax: 774-760-0088

Chicago Itasca, IL

Tel: 630-285-0071 Fax: 630-285-0075

Cleveland

Independence, OH Tel: 216-447-0464 Fax: 216-447-0643

**Dallas** 

Addison, TX Tel: 972-818-7423 Fax: 972-818-2924

**Detroit** Novi, MI

Tel: 248-848-4000

Houston, TX Tel: 281-894-5983

Indianapolis

Noblesville, IN Tel: 317-773-8323 Fax: 317-773-5453

Los Angeles

Mission Viejo, CA Tel: 949-462-9523 Fax: 949-462-9608

New York, NY Tel: 631-435-6000

San Jose, CA Tel: 408-735-9110

Canada - Toronto Tel: 905-673-0699 Fax: 905-673-6509

#### ASIA/PACIFIC

**Asia Pacific Office** 

Suites 3707-14, 37th Floor Tower 6, The Gateway Harbour City, Kowloon

Hong Kong

Tel: 852-2943-5100 Fax: 852-2401-3431

Australia - Sydney

Tel: 61-2-9868-6733 Fax: 61-2-9868-6755

China - Beijing

Tel: 86-10-8569-7000 Fax: 86-10-8528-2104

China - Chengdu Tel: 86-28-8665-5511

Fax: 86-28-8665-7889

China - Chongqing Tel: 86-23-8980-9588

Fax: 86-23-8980-9500 China - Dongguan

Tel: 86-769-8702-9880

China - Hangzhou Tel: 86-571-8792-8115 Fax: 86-571-8792-8116

China - Hong Kong SAR Tel: 852-2943-5100

Fax: 852-2401-3431 China - Nanjing

Tel: 86-25-8473-2460 Fax: 86-25-8473-2470

China - Qingdao Tel: 86-532-8502-7355

Fax: 86-532-8502-7205

China - Shanghai Tel: 86-21-5407-5533

Fax: 86-21-5407-5066

China - Shenyang Tel: 86-24-2334-2829

Fax: 86-24-2334-2393

China - Shenzhen Tel: 86-755-8864-2200

Fax: 86-755-8203-1760

China - Wuhan Tel: 86-27-5980-5300 Fax: 86-27-5980-5118

China - Xian Tel: 86-29-8833-7252 Fax: 86-29-8833-7256

# ASIA/PACIFIC

China - Xiamen

Tel: 86-592-2388138 Fax: 86-592-2388130

China - Zhuhai

Tel: 86-756-3210040 Fax: 86-756-3210049

India - Bangalore

Tel: 91-80-3090-4444 Fax: 91-80-3090-4123

India - New Delhi

Tel: 91-11-4160-8631 Fax: 91-11-4160-8632

India - Pune

Tel: 91-20-3019-1500

Japan - Osaka

Tel: 81-6-6152-7160 Fax: 81-6-6152-9310

Japan - Tokyo

Tel: 81-3-6880- 3770 Fax: 81-3-6880-3771

Korea - Daegu

Tel: 82-53-744-4301 Fax: 82-53-744-4302

Korea - Seoul

Tel: 82-2-554-7200 Fax: 82-2-558-5932 or 82-2-558-5934

Malaysia - Kuala Lumpur

Tel: 60-3-6201-9857 Fax: 60-3-6201-9859

Malaysia - Penang

Tel: 60-4-227-8870 Fax: 60-4-227-4068

Philippines - Manila

Tel: 63-2-634-9065 Fax: 63-2-634-9069

Singapore

Tel: 65-6334-8870 Fax: 65-6334-8850

Taiwan - Hsin Chu

Tel: 886-3-5778-366 Fax: 886-3-5770-955

Taiwan - Kaohsiung

Tel: 886-7-213-7828

Taiwan - Taipei

Tel: 886-2-2508-8600 Fax: 886-2-2508-0102

Thailand - Bangkok

Tel: 66-2-694-1351 Fax: 66-2-694-1350

# **EUROPE**

Austria - Wels

Tel: 43-7242-2244-39 Fax: 43-7242-2244-393

Denmark - Copenhagen

Tel: 45-4450-2828 Fax: 45-4485-2829

France - Paris

Tel: 33-1-69-53-63-20 Fax: 33-1-69-30-90-79

**Germany - Dusseldorf** Tel: 49-2129-3766400

Germany - Karlsruhe

Tel: 49-721-625370 Germany - Munich

Tel: 49-89-627-144-0 Fax: 49-89-627-144-44

Italy - Milan

Tel: 39-0331-742611 Fax: 39-0331-466781

Italy - Venice

Tel: 39-049-7625286

Netherlands - Drunen

Tel: 31-416-690399

Fax: 31-416-690340

Poland - Warsaw

Tel: 48-22-3325737

Spain - Madrid Tel: 34-91-708-08-90 Fax: 34-91-708-08-91

Sweden - Stockholm Tel: 46-8-5090-4654

**UK - Wokingham** 

Tel: 44-118-921-5800 Fax: 44-118-921-5820

07/14/15