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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	AVR
Core Size	8/16-Bit
Speed	32MHz
Connectivity	I²C, IrDA, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	50
Program Memory Size	256KB (128K x 16)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 3.6V
Data Converters	A/D 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atxmega256c3-mnr

13. Interrupts and Programmable Multilevel Interrupt Controller

13.1 Features

- Short and predictable interrupt response time
- Separate interrupt configuration and vector address for each interrupt
- Programmable multilevel interrupt controller
  - Interrupt prioritizing according to level and vector address
  - Three selectable interrupt levels for all interrupts: low, medium, and high
  - Selectable, round-robin priority scheme within low-level interrupts
  - Non-maskable interrupts for critical functions
- Interrupt vectors optionally placed in the application section or the boot loader section

13.2 Overview

Interrupts signal a change of state in peripherals, and this can be used to alter program execution. Peripherals can have one or more interrupts, and all are individually enabled and configured. When an interrupt is enabled and configured, it will generate an interrupt request when the interrupt condition is present. The programmable multilevel interrupt controller (PMIC) controls the handling and prioritizing of interrupt requests. When an interrupt request is acknowledged by the PMIC, the program counter is set to point to the interrupt vector, and the interrupt handler can be executed.

All peripherals can select between three different priority levels for their interrupts: low, medium, and high. Interrupts are prioritized according to their level and their interrupt vector address. Medium-level interrupts will interrupt low-level interrupt handlers. High-level interrupts will interrupt both medium- and low-level interrupt handlers. Within each level, the interrupt priority is decided from the interrupt vector address, where the lowest interrupt vector address has the highest interrupt priority. Low-level interrupts have an optional round-robin scheduling scheme to ensure that all interrupts are serviced within a certain amount of time.

Non-maskable interrupts (NMI) are also supported, and can be used for system critical functions.

13.3 Interrupt Vectors

The interrupt vector is the sum of the peripheral's base interrupt address and the offset address for specific interrupts in each peripheral. The base addresses for the Atmel AVR XMEGA C3 devices are shown in Table 13-1 on page 28. Offset addresses for each interrupt available in the peripheral are described for each peripheral in the XMEGA C manual. For peripherals or modules that have only one interrupt, the interrupt vector is shown in Table 13-1 on page 28. The program address is the word address.

Mnemonics	Operands	Description	Operation	Flags	#Clocks
RCALL	k	Relative Call Subroutine	PC ← PC + k + 1	None	2 / 3
ICALL		Indirect Call to (Z)	PC(15:0) ← Z, PC(21:16) ← 0	None	2 / 3
EICALL		Extended Indirect Call to (Z)	PC(15:0) ← Z, PC(21:16) ← EIND	None	3
CALL	k	call Subroutine	PC ← k	None	3 / 4
RET		Subroutine Return	PC ← STACK	None	4 / 5
RETI		Interrupt Return	PC ← STACK	I	4 / 5
CPSE	Rd,Rr	Compare, Skip if Equal	if (Rd = Rr) PC ← PC + 2 or 3	None	1 / 2 / 3
CP	Rd,Rr	Compare	Rd - Rr	Z,C,N,V,S,H	1
CPC	Rd,Rr	Compare with Carry	Rd - Rr - C	Z,C,N,V,S,H	1
CPI	Rd,K	Compare with Immediate	Rd - K	Z,C,N,V,S,H	1
SBRC	Rr, b	Skip if Bit in Register Cleared	if (Rr(b) = 0) PC ← PC + 2 or 3	None	1 / 2 / 3
SBRS	Rr, b	Skip if Bit in Register Set	if (Rr(b) = 1) PC ← PC + 2 or 3	None	1 / 2 / 3
SBIC	A, b	Skip if Bit in I/O Register Cleared	if (I/O(A,b) = 0) PC ← PC + 2 or 3	None	2 / 3 / 4
SBIS	A, b	Skip if Bit in I/O Register Set	If (I/O(A,b) =1) PC ← PC + 2 or 3	None	2 / 3 / 4
BRBS	s, k	Branch if Status Flag Set	if (SREG(s) = 1) then PC ← PC + k + 1	None	1 / 2
BRBC	s, k	Branch if Status Flag Cleared	if (SREG(s) = 0) then PC ← PC + k + 1	None	1 / 2
BREQ	k	Branch if Equal	if (Z = 1) then PC ← PC + k + 1	None	1 / 2
BRNE	k	Branch if Not Equal	if (Z = 0) then PC ← PC + k + 1	None	1 / 2
BRCS	k	Branch if Carry Set	if (C = 1) then PC ← PC + k + 1	None	1 / 2
BRCC	k	Branch if Carry Cleared	if (C = 0) then PC ← PC + k + 1	None	1 / 2
BRSH	k	Branch if Same or Higher	if (C = 0) then PC ← PC + k + 1	None	1 / 2
BRLO	k	Branch if Lower	if (C = 1) then PC ← PC + k + 1	None	1 / 2
BRMI	k	Branch if Minus	if (N = 1) then PC ← PC + k + 1	None	1 / 2
BRPL	k	Branch if Plus	if (N = 0) then PC ← PC + k + 1	None	1 / 2
BRGE	k	Branch if Greater or Equal, Signed	if (N ⊕ V= 0) then PC ← PC + k + 1	None	1 / 2
BRLT	k	Branch if Less Than, Signed	if (N ⊕ V= 1) then PC ← PC + k + 1	None	1 / 2
BRHS	k	Branch if Half Carry Flag Set	if (H = 1) then PC ← PC + k + 1	None	1 / 2
BRHC	k	Branch if Half Carry Flag Cleared	if (H = 0) then PC ← PC + k + 1	None	1 / 2
BRTS	k	Branch if T Flag Set	if (T = 1) then PC ← PC + k + 1	None	1 / 2
BRTC	k	Branch if T Flag Cleared	if (T = 0) then PC ← PC + k + 1	None	1 / 2
BRVS	k	Branch if Overflow Flag is Set	if (V = 1) then PC ← PC + k + 1	None	1 / 2
BRVC	k	Branch if Overflow Flag is Cleared	if (V = 0) then PC ← PC + k + 1	None	1 / 2
BRIE	k	Branch if Interrupt Enabled	if (I = 1) then PC ← PC + k + 1	None	1 / 2
BRID	k	Branch if Interrupt Disabled	if (I = 0) then PC ← PC + k + 1	None	1 / 2
Data transfer instructions					
MOV	Rd, Rr	Copy Register	Rd ← Rr	None	1

33.1.8 Bandgap and Internal 1.0V Reference Characteristics

Table 33-13. Bandgap and Internal 1.0V Reference Characteristics

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
	Startup time	As reference for ADC		1 Clk_{PER} + 2.5µs		µs
		As input voltage to ADC and AC		1.5		
	Bandgap voltage			1.1		V
INT1V	Internal 1.00V reference	T= 85°C, after calibration	0.99	1.0	1.01	
	Variation over voltage and temperature	Calibrated at T= 85°C		1.0		%

33.1.9 Brownout Detection Characteristics

Table 33-14. Brownout Detection Characteristics(1)

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
V_{BOT}	BOD level 0 falling V_{CC}		1.40	1.60	1.70	V
	BOD level 1 falling V_{CC}			1.8		
	BOD level 2 falling V_{CC}			2.0		
	BOD level 3 falling V_{CC}			2.2		
	BOD level 4 falling V_{CC}			2.4		
	BOD level 5 falling V_{CC}			2.6		
	BOD level 6 falling V_{CC}			2.8		
	BOD level 7 falling V_{CC}			3.0		
t_{BOD}	Detection time	Continuous mode		0.4		µs
		Sampled mode		1000		
V_{HYST}	Hysteresis			1.0		%

Note: 1. BOD is calibrated at 85°C within BOD level 0 values, and BOD level 0 is the default level.

33.1.10 External Reset Characteristics

Table 33-15. External Reset Characteristics

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
t_{EXT}	Minimum reset pulse width		1000	90		ns
V_{RST}	Reset threshold voltage	V_{CC} = 2.7 - 3.6V		0.45*V_{CC}		V
		V_{CC} = 1.6 - 2.7V		0.45*V_{CC}		
R_{RST}	Reset pin Pull-up Resistor			25		kΩ

33.1.13 Clock and Oscillator Characteristics

33.1.13.1 Calibrated 32.768kHz Internal Oscillator Characteristics

Table 33-19. 32.768kHz Internal Oscillator Characteristics

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
	Frequency			32.768		kHz
	Factory calibration accuracy	T = 85°C, V_{CC} = 3.0V	-0.5		0.5	%
	User calibration accuracy		-0.5		0.5	

33.1.13.2 Calibrated 2MHz RC Internal Oscillator Characteristics

Table 33-20. 2MHz Internal Oscillator Characteristics

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
	Frequency range	DFLL can tune to this frequency over voltage and temperature	1.8	2.0	2.2	MHz
	Factory calibrated frequency			2.0		
	Factory calibration accuracy	T = 85°C, V_{CC}= 3.0V	-1.5		1.5	%
	User calibration accuracy		-0.2		0.2	
	DFLL calibration stepsize			0.18		

33.1.13.3 Calibrated and Tunable 32MHz Internal Oscillator Characteristics

Table 33-21. 32MHz Internal Oscillator Characteristics

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
	Frequency range	DFLL can tune to this frequency over voltage and temperature	30	32	55	MHz
	Factory calibrated frequency			32		
	Factory calibration accuracy	T = 85°C, V_{CC}= 3.0V	-1.5		1.5	%
	User calibration accuracy		-0.2		0.2	
	DFLL calibration step size			0.19		

33.1.13.4 32kHz Internal ULP Oscillator Characteristics

Table 33-22. 32kHz internal ULP Oscillator Characteristics

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
	Factory calibrated frequency			32		kHz
	Factory calibration accuracy	T = 85°C, V_{CC}= 3.0V	-12		12	%
	Accuracy		-30		30	

33.2.3 Current Consumption

Table 33-33. Current Consumption for Active Mode and Sleep Modes

Symbol	Parameter	Condition		Min.	Typ.	Max.	Units
I_{CC}	Active power consumption(1)	32kHz, Ext. Clk	V_{CC} = 1.8V		50		µA
			V_{CC} = 3.0V		130		
		1MHz, Ext. Clk	V_{CC} = 1.8V		215		
			V_{CC} = 3.0V		475		
		2MHz, Ext. Clk	V_{CC} = 1.8V		445	600	
			V_{CC} = 3.0V		0.95	1.5	mA
		32MHz, Ext. Clk			7.8	12	
	Idle power consumption(2)	32kHz, Ext. Clk	V_{CC} = 1.8V		2.8		µA
			V_{CC} = 3.0V		3.0		
		1MHz, Ext. Clk	V_{CC} = 1.8V		46		
			V_{CC} = 3.0V		92		
		2MHz, Ext. Clk	V_{CC} = 1.8V		93	225	
			V_{CC} = 3.0V		184	350	
		32MHz, Ext. Clk			2.9	5.0	mA
	Power-down power consumption	T = 25°C	V_{CC} = 3.0V		0.07	1.0	µA
		T = 85°C			1.3	5.0	
		T = 105°C			4.0	8.0	
		WDT and sampled BOD enabled, T = 25°C	V_{CC} = 3.0V		1.4	2.0	
		WDT and sampled BOD enabled, T = 85°C			2.6	6.0	
		WDT and sampled BOD enabled, T = 105°C			5.0	10	
	Power-save power consumption(3)	RTC from ULP clock, WDT and sampled BOD enabled, T = 25°C	V_{CC} = 1.8V		1.7		
			V_{CC} = 3.0V		1.8		
		RTC from 1.024kHz low power 32.768kHz TOSC, T = 25°C	V_{CC} = 1.8V		0.7	2.0	
			V_{CC} = 3.0V		0.8	2.0	
		RTC from low power 32.768kHz TOSC, T = 25°C	V_{CC} = 1.8V		0.9	3.0	
			V_{CC} = 3.0V		1.2	3.0	
	Reset power consumption	Current through $\overline{\text{RESET}}$ pin substracted	V_{CC} = 3.0V		120		

Notes:
1. All Power Reduction Registers set including FPRM and EPRM.
2. All Power Reduction Registers set without FPRM and EPRM.
3. Maximum limits are based on characterization, and not tested in production.

Table 33-34. Current Consumption for Modules and Peripherals

Symbol	Parameter	Condition[1]		Min.	Typ.	Max.	Units
I_{CC}	ULP oscillator				0.9		µA
	32.768kHz int. oscillator				29		
	2MHz int. oscillator				82		
		DFLL enabled with 32.768kHz int. osc. as reference			114		
	32MHz int. oscillator				250		
		DFLL enabled with 32.768kHz int. osc. as reference			400		
	PLL	20x multiplication factor, 32MHz int. osc. DIV4 as reference			300		
	Watchdog timer				1.0		
	BOD	Continuous mode			140		
		Sampled mode, includes ULP oscillator			1.4		
	Internal 1.0V reference				180		
	Temperature sensor				175		
	ADC	16ksps V_{REF} = Ext. ref.			1.23		mA
			CURRLIMIT = LOW		1.1		
			CURRLIMIT = MEDIUM		0.98		
			CURRLIMIT = HIGH		0.87		
		75ksps V_{REF} = Ext. ref.	CURRLIMIT = LOW		1.7		
		300ksps V_{REF} = Ext. ref.			3.1		
	USART	Rx and Tx enabled, 9600 BAUD			9.7		µA
	Flash memory and EEPROM programming				5		mA

Note: 1. All parameters measured as the difference in current consumption between module enabled and disabled. All data at V_{CC} = 3.0V, Clk_{SYS} = 1MHz external clock without prescaling, T = 25°C unless other conditions are given.

33.2.6 ADC Characteristics

Table 33-37. Power Supply, Reference, and Input Range

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
AV_{CC}	Analog supply voltage		V_{CC}- 0.3		V_{CC}+ 0.3	V
V_{REF}	Reference voltage		1		AV_{CC}- 0.6	
R_{in}	Input resistance	Switched			4.5	kΩ
C_{in}	Input capacitance	Switched			5	pF
R_{AREF}	Reference input resistance	(leakage only)		>10		MΩ
C_{AREF}	Reference input capacitance	Static load		7		pF
Vin	Input range		0		V_{REF}	V
	Conversion range	Differential mode, Vinp - Vinn	-V_{REF}		V_{REF}	
	Conversion range	Single ended unsigned mode, Vinp	-ΔV		V_{REF}-ΔV	
ΔV	Fixed offset voltage			200		lsb

Table 33-38. Clock and Timing

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
Clk_{ADC}	ADC Clock frequency	Maximum is 1/4 of peripheral clock frequency	100		1800	kHz
		Measuring internal signals	100		125	
f_{ClkADC}	Sample rate		16		300	ksps
f_{ADC}	Sample rate	Current limitation (CURRLIMIT) off	16		300	
		CURRLIMIT = LOW	16		250	
		CURRLIMIT = MEDIUM	16		150	
		CURRLIMIT = HIGH	16		50	
	Sampling time	Configurable in steps of 1/2 Clk_{ADC} cycles up to 32 Clk_{ADC} cycles	0.28		320	µs
	Conversion time (latency)	(RES+2)/2+1+ GAIN RES (Resolution) = 8 or 12, GAIN=0 to 3	5.5		10	Clk_{ADC} cycles
	Start-up time	ADC clock cycles		12	24	
	ADC settling time	After changing reference or input mode		7	7	

Table 33-58. Two-wire Interface Characteristics

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
V_{IH}	Input high voltage		$0.7V_{CC}$		V_{CC}+0.5	V
V_{IL}	Input low voltage		-0.5		$0.3*V_{CC}$	
V_{hys}	Hysteresis of Schmitt trigger inputs		$0.05*V_{CC}$ (1)			
V_{OL}	Output low voltage	3mA, sink current	0		0.4	
t_r	Rise time for both SDA and SCL		$20+0.1C_b$ (1)(2)		300	ns
t_{of}	Output fall time from V_{IHmin} to V_{ILmax}	$10pF < C_b < 400pF$ (2)	$20+0.1C_b$ (1)(2)		250	
t_{SP}	Spikes suppressed by input filter		0		50	
I_I	Input current for each I/O Pin	$0.1V_{CC} < V_I < 0.9V_{CC}$	-10		10	µA
C_I	Capacitance for each I/O Pin				10	pF
f_{SCL}	SCL clock frequency	f_{PER} (3)>max($10f_{SCL}$, 250kHz)	0		400	kHz
R_P	Value of pull-up resistor	$f_{SCL} \leq 100kHz$	$\frac{V_{CC}-0.4V}{3mA}$		$\frac{100ns}{C_b}$	Ω
		$f_{SCL} > 100kHz$			$\frac{300ns}{C_b}$	
$t_{HD;STA}$	Hold time (repeated) START condition	$f_{SCL} \leq 100kHz$	4.0			µs
		$f_{SCL} > 100kHz$	0.6			
t_{LOW}	Low period of SCL clock	$f_{SCL} \leq 100kHz$	4.7			
		$f_{SCL} > 100kHz$	1.3			
t_{HIGH}	High period of SCL clock	$f_{SCL} \leq 100kHz$	4.0			
		$f_{SCL} > 100kHz$	0.6			
$t_{SU;STA}$	Setup time for a repeated START condition	$f_{SCL} \leq 100kHz$	4.7			
		$f_{SCL} > 100kHz$	0.6			
$t_{HD;DAT}$	Data hold time	$f_{SCL} \leq 100kHz$	0		3.45	
		$f_{SCL} > 100kHz$	0		0.9	
$t_{SU;DAT}$	Data setup time	$f_{SCL} \leq 100kHz$	250			ns
		$f_{SCL} > 100kHz$	100			
$t_{SU;STO}$	Setup time for STOP condition	$f_{SCL} \leq 100kHz$	4.0			µs
		$f_{SCL} > 100kHz$	0.6			
t_{BUF}	Bus free time between a STOP and START condition	$f_{SCL} \leq 100kHz$	4.7			
		$f_{SCL} > 100kHz$	1.3			

Notes:
1. Required only for $f_{SCL} > 100kHz$.
2. C_b = Capacitance of one bus line in pF.
3. f_{PER} = Peripheral clock frequency.

Table 33-127. Gain Stage Characteristics

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
R_{in}	Input resistance	Switched in normal mode		4.0		kΩ
C_{sample}	Input capacitance	Switched in normal mode		4.4		pF
	Signal range	Gain stage output	0		AV_{CC}- 0.6	V
	Propagation delay	ADC conversion rate	1/2	1	3	Clk_{ADC} cycles
	Clock frequency	Same as ADC	100		1800	kHz
	Gain error	0.5x gain, normal mode		-1		%
		1x gain, normal mode		-1		
		8x gain, normal mode		-1		
		64x gain, normal mode		5		
	Offset error, input referred	0.5x gain, normal mode		10		mV
		1x gain, normal mode		5		
		8x gain, normal mode		-20		
		64x gain, normal mode		-126		

33.5.7 Analog Comparator Characteristics

Table 33-128. Analog Comparator Characteristics

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
V_{off}	Input offset voltage			10		mV
I_{lk}	Input leakage current			<10	50	nA
	Input voltage range		-0.1		AV_{CC}	V
	AC startup time			50		µs
V_{hys1}	Hysteresis, none	V_{CC} = 1.6V - 3.6V		0		mV
V_{hys2}	Hysteresis, small	V_{CC} = 1.6V - 3.6V		15		
V_{hys3}	Hysteresis, large	V_{CC} = 1.6V - 3.6V		30		
t_{delay}	Propagation delay	V_{CC} = 3.0V, T= 85°C		20	40	ns
		V_{CC} = 3.0V		17		
	64-level voltage scaler	Integral non-linearity (INL)		0.3	0.5	lsb
	Current source accuracy after calibration			5		%
	Current source calibration range	Single mode	4		6	µA

Figure 34-3. Active Mode Supply Current vs. V_{CC}

f_{SYS} = 32.768kHz internal oscillator

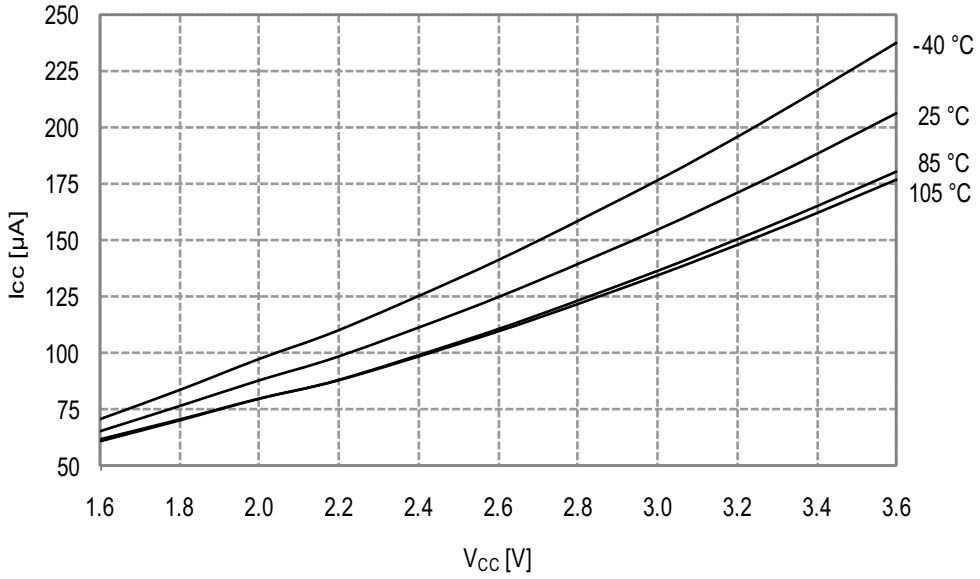
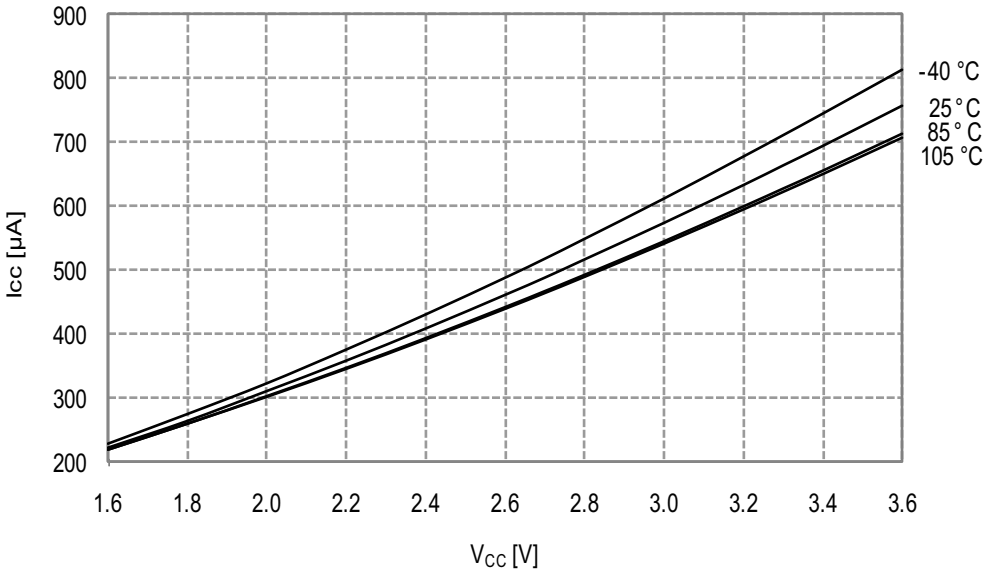


Figure 34-4. Active Mode Supply Current vs. V_{CC}

f_{SYS} = 1MHz external clock



34.3.2.3 Thresholds and Hysteresis

Figure 34-169. I/O Pin Input Threshold Voltage vs. V_{CC}

V_{IH} I/O pin read as "1"

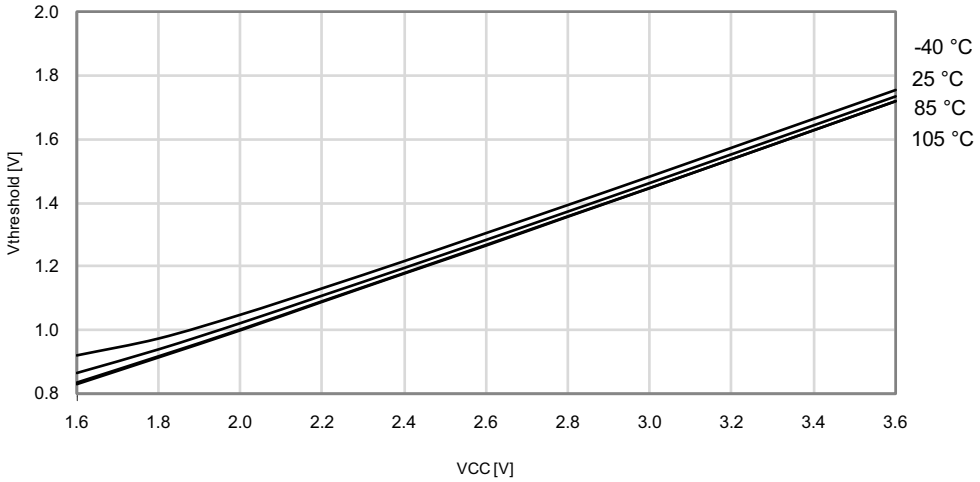


Figure 34-170. I/O Pin Input Threshold Voltage vs. V_{CC}

V_{IL} I/O pin read as "0"

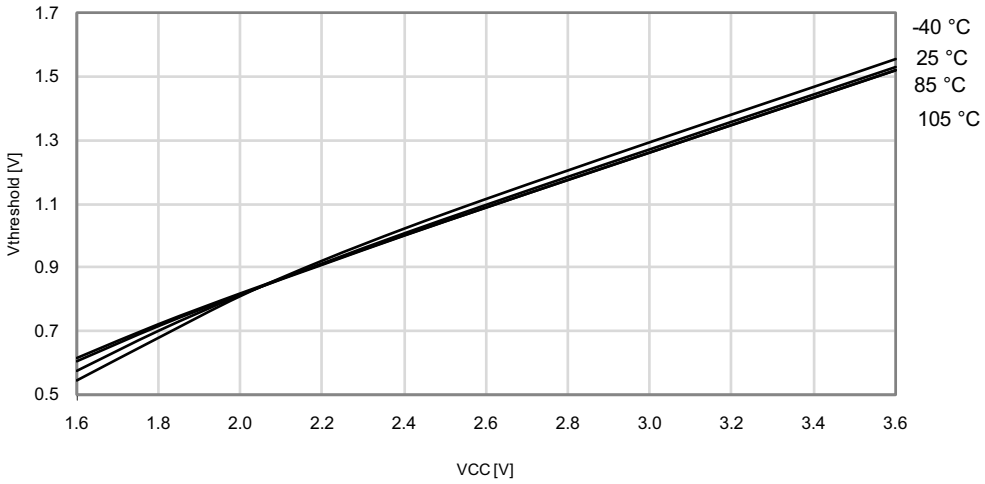


Figure 34-173. INL Error vs. Sample Rate

T = 25°C, V_{CC} = 3.6V, V_{REF} = 3.0V external

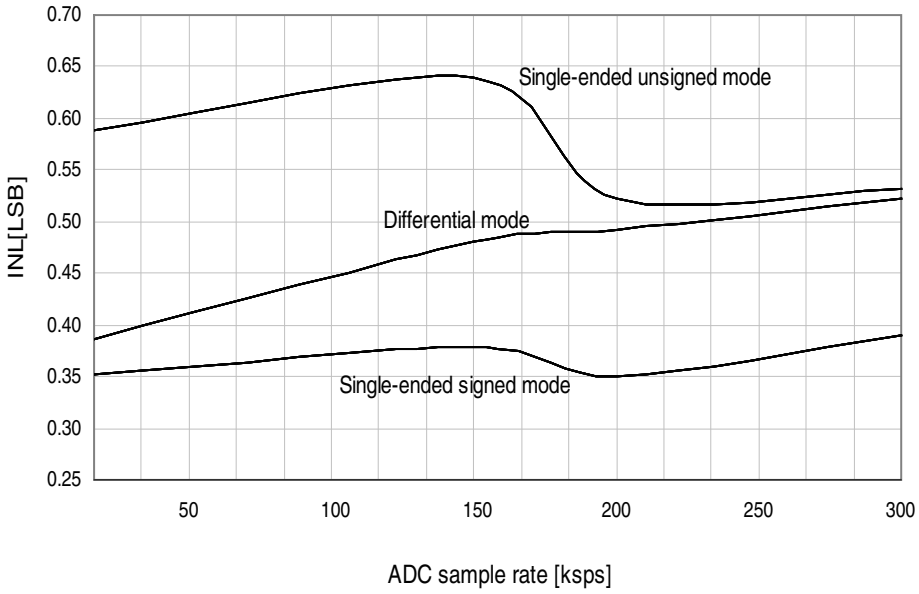


Figure 34-174. INL Error vs. Input Code

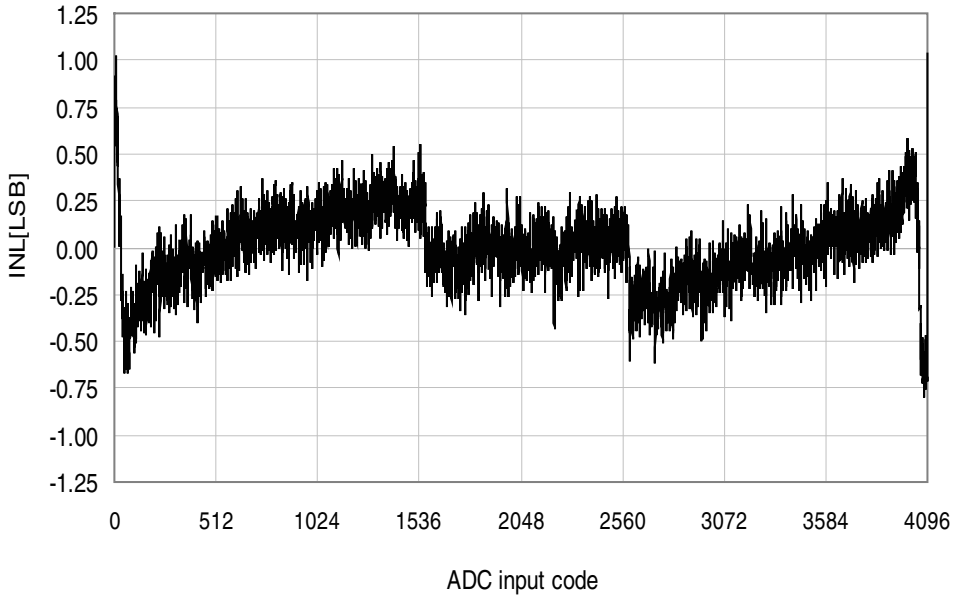


Figure 34-191. Reset Pin Pull-up Resistor Current vs. Reset Pin Voltage

V_{CC} = 1.8V

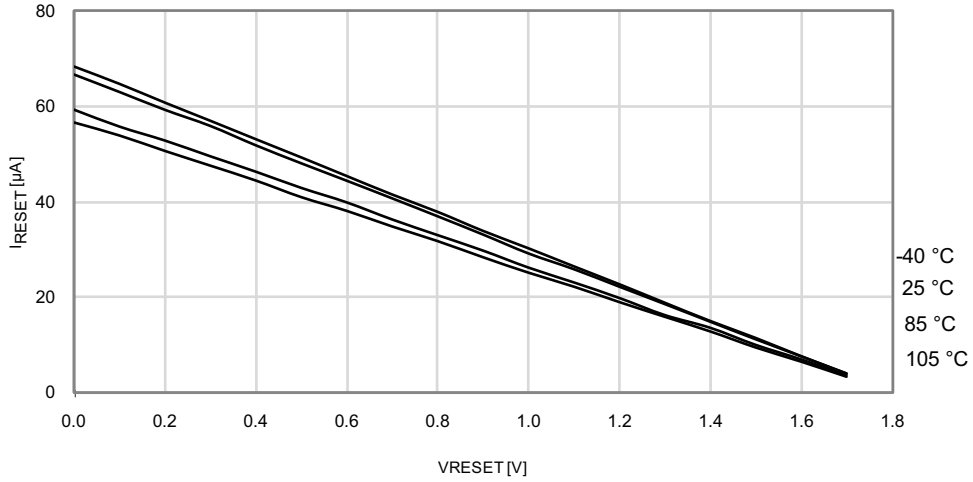
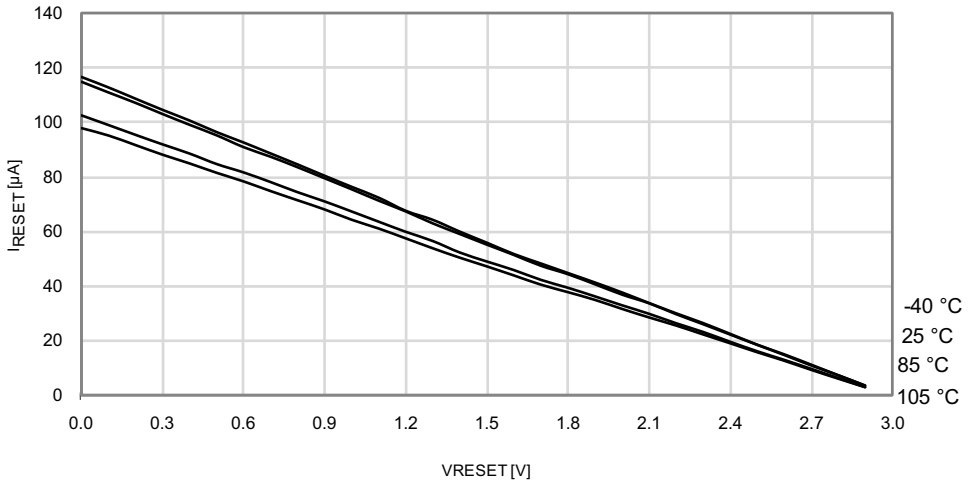


Figure 34-192. Reset Pin Pull-up Resistor Current vs. Reset Pin Voltage

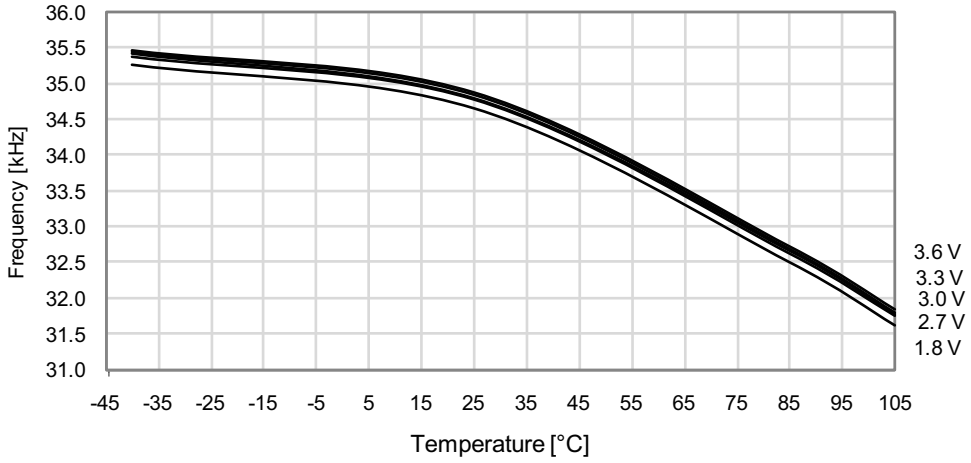
V_{CC} = 3.0V



34.3.8 Oscillator Characteristics

34.3.8.1 Ultra Low-Power Internal Oscillator

Figure 34-195. Ultra Low-Power Internal Oscillator Frequency vs. Temperature



34.3.8.2 32.768kHz Internal Oscillator

Figure 34-196. 32.768kHz Internal Oscillator Frequency vs. Temperature

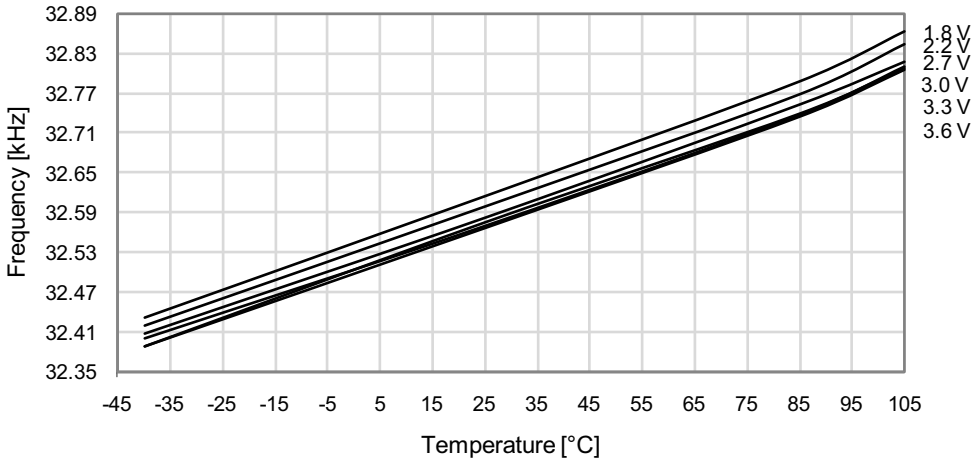


Figure 34-243. INL Error vs. Sample Rate

T = 25°C, V_{CC} = 3.6V, V_{REF} = 3.0V external

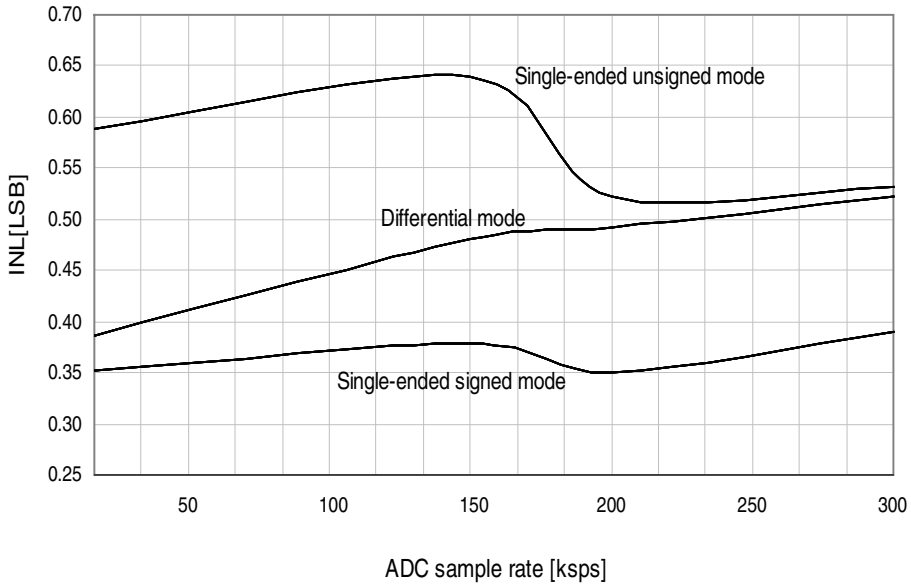


Figure 34-244. INL Error vs. Input Code

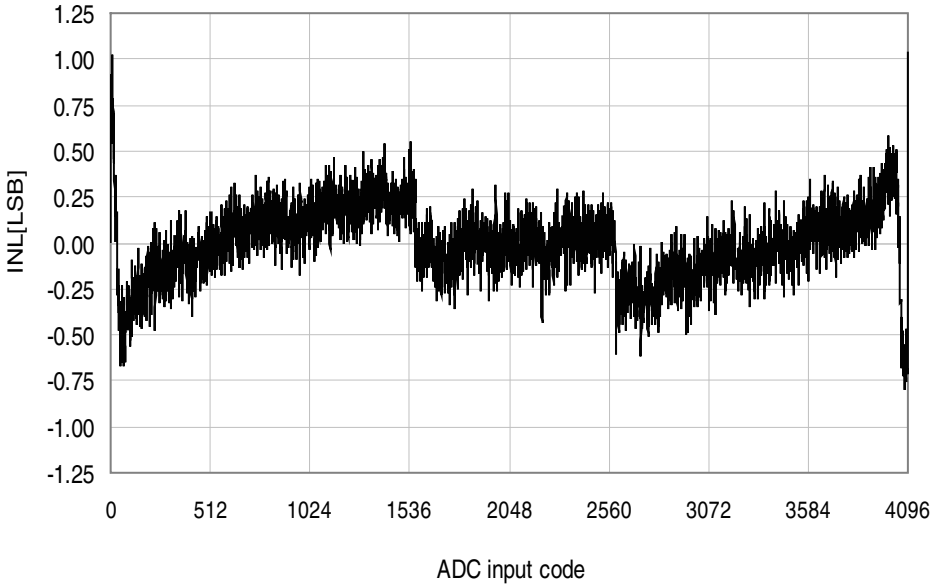
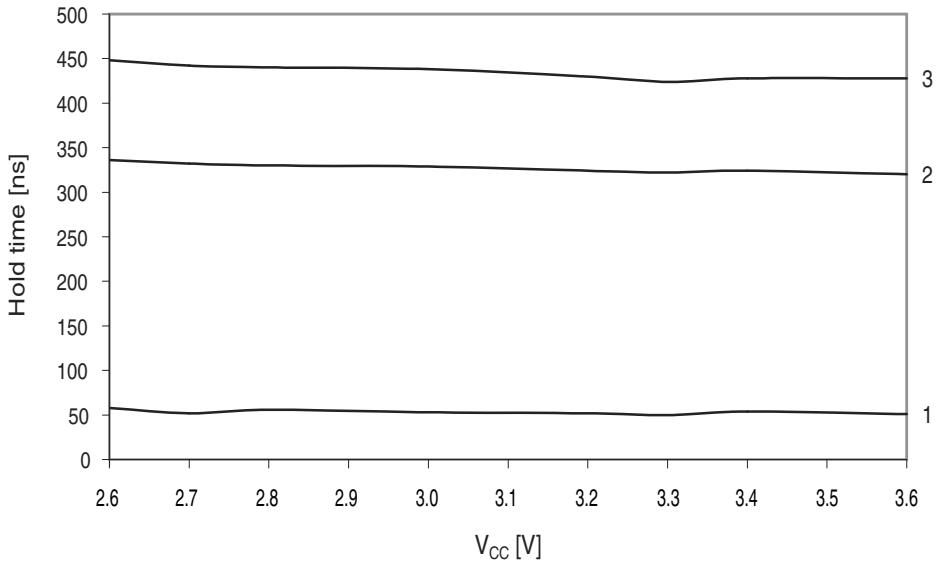
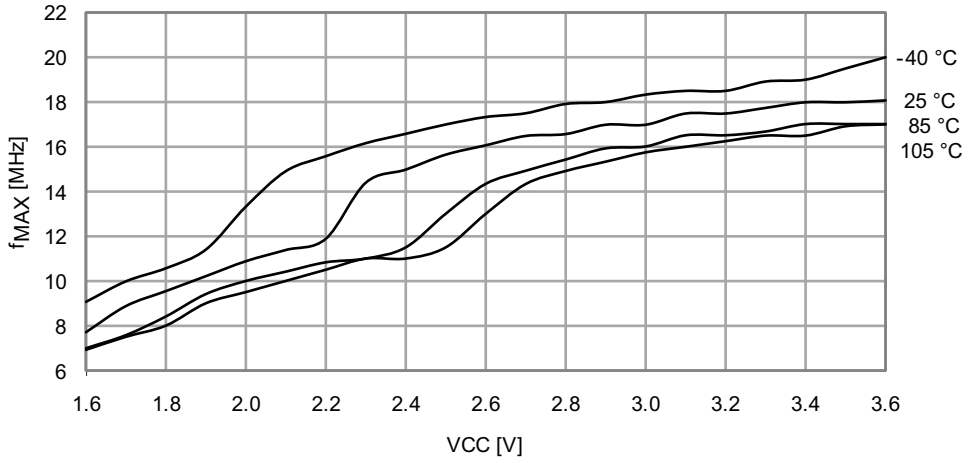


Figure 34-281. SDA Hold Time vs. Supply Voltage



34.4.10 PDI Characteristics

Figure 34-282. Maximum PDI Frequency vs. V_{CC}



34.5 Atmel ATxmega256C3

34.5.1 Current Consumption

34.5.1.1 Active Mode Supply Current

Figure 34-283. Active Supply Current vs. Frequency
f_{SYS} = 0 - 1MHz external clock, T = 25°C

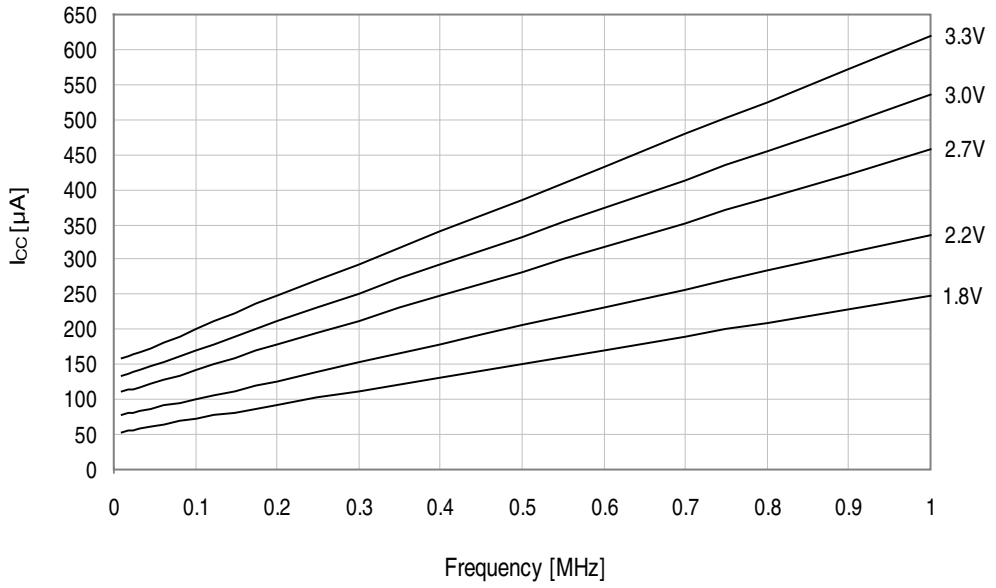


Figure 34-284. Active Supply Current vs. Frequency
f_{SYS} = 1 - 32MHz external clock, T = 25°C

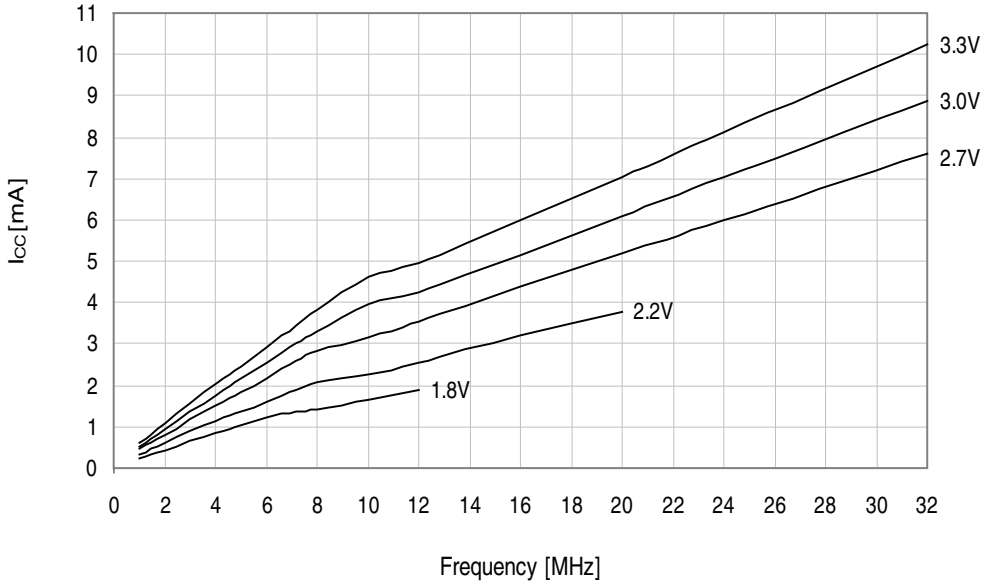
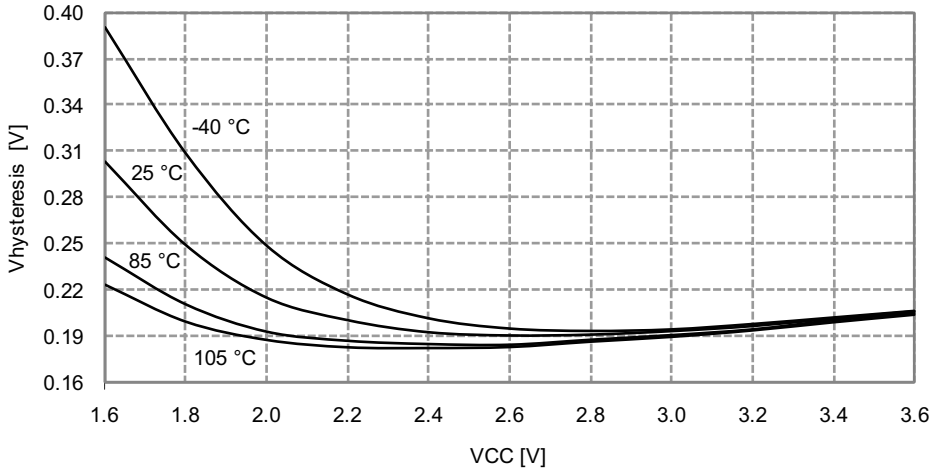


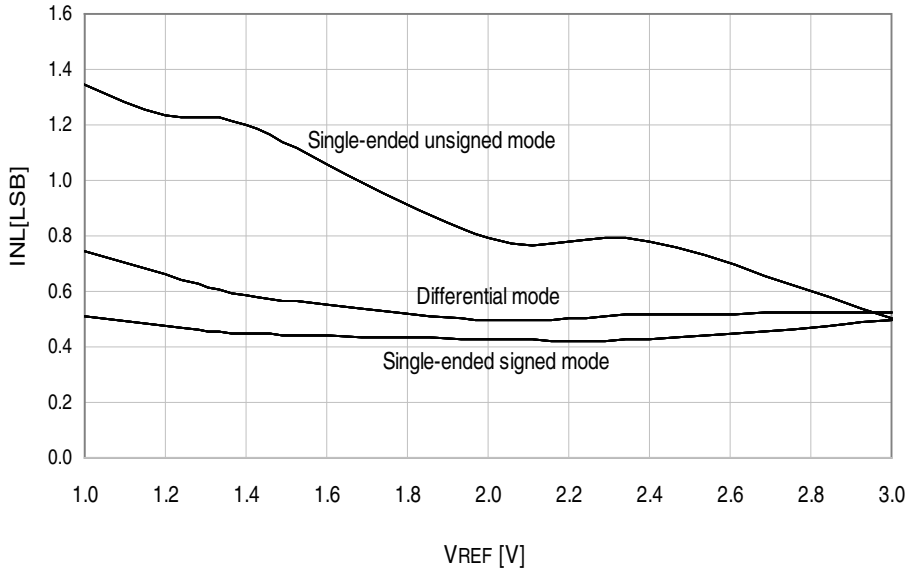
Figure 34-311. I/O Pin Input Hysteresis vs. V_{CC}



34.5.3 ADC Characteristics

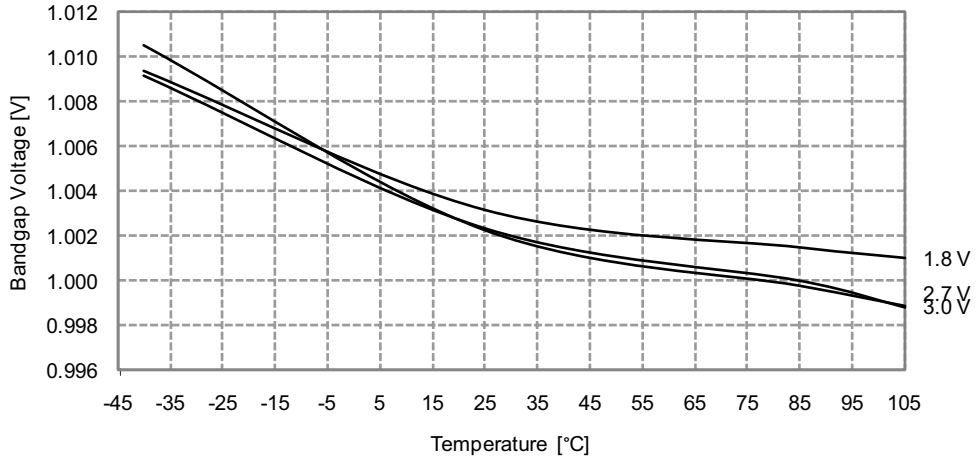
Figure 34-312. INL Error vs. External V_{REF}

T = 25°C, V_{CC} = 3.6V, external reference



34.5.5 Internal 1.0V Reference Characteristics

Figure 34-327. ADC Internal 1.0V Reference vs. Temperature



34.5.6 BOD Characteristics

Figure 34-328. BOD Thresholds vs. Temperature

BOD level = 1.6V

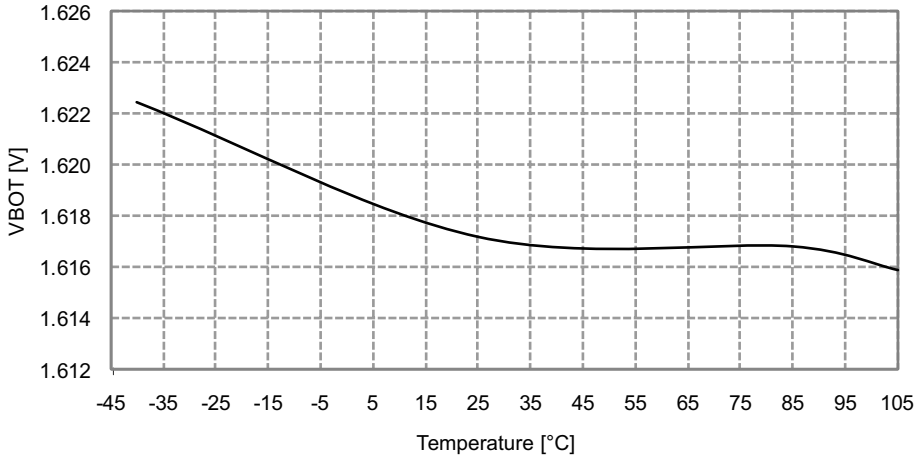


Figure 34-339. 2MHz Internal Oscillator Frequency vs. Temperature

DFLL enabled, from the 32.768kHz internal oscillator

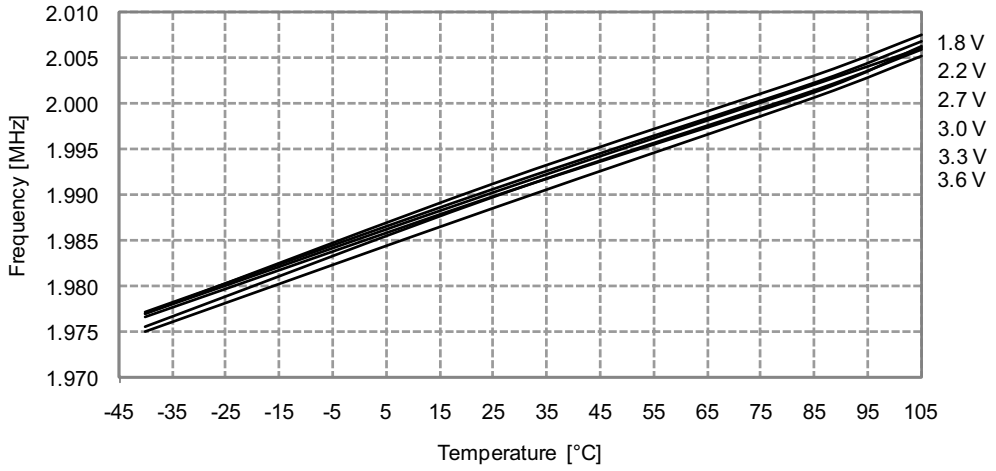


Figure 34-340. 2MHz Internal Oscillator Frequency vs. CALA Calibration Value

V_{CC} = 3V