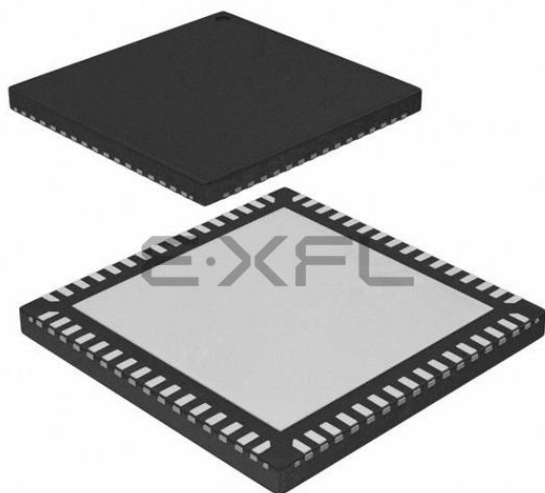




Welcome to [E-XFL.COM](https://www.e-xfl.com)

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	AVR
Core Size	8/16-Bit
Speed	32MHz
Connectivity	I ² C, IrDA, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	50
Program Memory Size	64KB (32K x 16)
Program Memory Type	FLASH
EEPROM Size	2K x 8
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 3.6V
Data Converters	A/D 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atxmega64c3-mn

3. Overview

The Atmel AVR XMEGA is a family of low power, high performance, and peripheral rich 8/16-bit microcontrollers based on the AVR enhanced RISC architecture. By executing instructions in a single clock cycle, the AVR XMEGA devices achieve CPU throughput approaching one million instructions per second (MIPS) per megahertz, allowing the system designer to optimize power consumption versus processing speed.

The AVR CPU combines a rich instruction set with 32 general purpose working registers. All 32 registers are directly connected to the arithmetic logic unit (ALU), allowing two independent registers to be accessed in a single instruction, executed in one clock cycle. The resulting architecture is more code efficient while achieving throughputs many times faster than conventional single-accumulator or CISC based microcontrollers.

The XMEGA C3 devices provide the following features: in-system programmable flash with read-while-write capabilities; internal EEPROM and SRAM; four-channel event system and programmable multilevel interrupt controller, 50 general purpose I/O lines, 16-bit real-time counter (RTC); five, 16-bit timer/counters with compare and PWM channels; three USARTs; two two-wire serial interfaces (TWIs); one full speed USB 2.0 interface; two serial peripheral interfaces (SPIs); one sixteen-channel, 12-bit ADC with programmable gain; two analog comparators (ACs) with window mode; programmable watchdog timer with separate internal oscillator; accurate internal oscillators with PLL and prescaler; and programmable brown-out detection.

The program and debug interface (PDI), a fast, two-pin interface for programming and debugging, is available.

The XMEGA C3 devices have five software selectable power saving modes. The idle mode stops the CPU while allowing the SRAM, event system, interrupt controller, and all peripherals to continue functioning. The power-down mode saves the SRAM and register contents, but stops the oscillators, disabling all other functions until the next TWI, USB resume, or pin-change interrupt, or reset. In power-save mode, the asynchronous real-time counter continues to run, allowing the application to maintain a timer base while the rest of the device is sleeping. In standby mode, the external crystal oscillator keeps running while the rest of the device is sleeping. This allows very fast startup from the external crystal, combined with low power consumption. In extended standby mode, both the main oscillator and the asynchronous timer continue to run. To further reduce power consumption, the peripheral clock to each individual peripheral can optionally be stopped in active mode and idle sleep mode.

Atmel offers a free QTouch library for embedding capacitive touch buttons, sliders and wheels functionality into AVR microcontrollers.

The devices are manufactured using Atmel high-density, nonvolatile memory technology. The program flash memory can be reprogrammed in-system through the PDI. A boot loader running in the device can use any interface to download the application program to the flash memory. The boot loader software in the boot flash section will continue to run while the application flash section is updated, providing true read-while-write operation. By combining an 8/16-bit RISC CPU with in-system, self-programmable flash, the AVR XMEGA is a powerful microcontroller family that provides a highly flexible and cost effective solution for many embedded applications.

All Atmel AVR XMEGA devices are supported with a full suite of program and system development tools, including: C compilers, macro assemblers, program debugger/simulators, programmers, and evaluation kits.

Mnemonics	Operands	Description	Operation	Flags	#Clocks
SEN		Set Negative Flag	N ← 1	N	1
CLN		Clear Negative Flag	N ← 0	N	1
SEZ		Set Zero Flag	Z ← 1	Z	1
CLZ		Clear Zero Flag	Z ← 0	Z	1
SEI		Global Interrupt Enable	I ← 1	I	1
CLI		Global Interrupt Disable	I ← 0	I	1
SES		Set Signed Test Flag	S ← 1	S	1
CLS		Clear Signed Test Flag	S ← 0	S	1
SEV		Set Two's Complement Overflow	V ← 1	V	1
CLV		Clear Two's Complement Overflow	V ← 0	V	1
SET		Set T in SREG	T ← 1	T	1
CLT		Clear T in SREG	T ← 0	T	1
SEH		Set Half Carry Flag in SREG	H ← 1	H	1
CLH		Clear Half Carry Flag in SREG	H ← 0	H	1
MCU control instructions					
BREAK		Break	(See specific descr. for BREAK)	None	1
NOP		No Operation		None	1
SLEEP		Sleep	(see specific descr. for Sleep)	None	1
WDR		Watchdog Reset	(see specific descr. for WDR)	None	1

Notes: 1. One extra cycle must be added when accessing internal SRAM.

33.2.13.5 Internal Phase Locked Loop (PLL) Characteristics

Table 33-52. Internal PLL Characteristics

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
f_{IN}	Input frequency	Output frequency must be within f_{OUT}	0.4		64	MHz
f_{OUT}	Output frequency ⁽¹⁾	$V_{CC} = 1.6 - 1.8V$	20		48	
		$V_{CC} = 2.7 - 3.6V$	20		128	
	Start-up time			25		μs
	Re-lock time			25		

Note: 1. The maximum output frequency vs. supply voltage is linear between 1.8V and 2.7V, and can never be higher than four times the maximum CPU frequency.

33.2.13.6 External Clock Characteristics

Figure 33-10. External Clock Drive Waveform

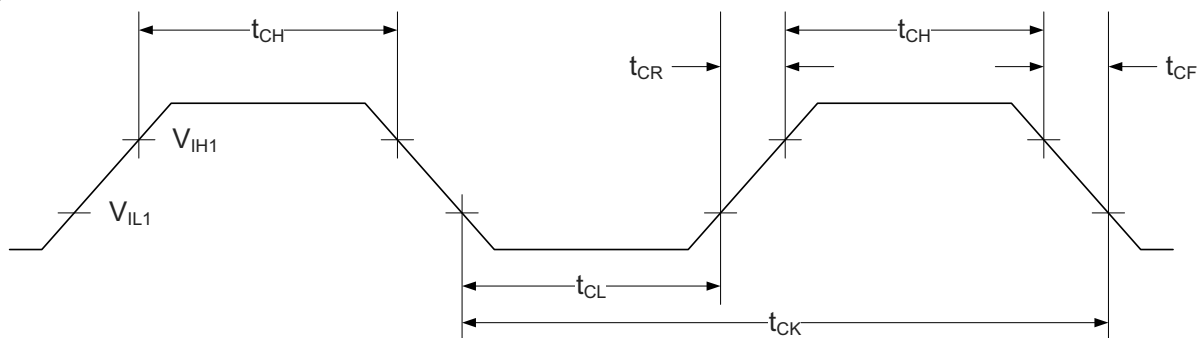


Table 33-53. External Clock used as System Clock without Prescaling

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
$1/t_{CK}$	Clock Frequency ⁽¹⁾	$V_{CC} = 1.6 - 1.8V$	0		12	MHz
		$V_{CC} = 2.7 - 3.6V$	0		32	
t_{CK}	Clock Period	$V_{CC} = 1.6 - 1.8V$	83.3			ns
		$V_{CC} = 2.7 - 3.6V$	31.5			
t_{CH}	Clock High Time	$V_{CC} = 1.6 - 1.8V$	30.0			
		$V_{CC} = 2.7 - 3.6V$	12.5			
t_{CL}	Clock Low Time	$V_{CC} = 1.6 - 1.8V$	30.0			
		$V_{CC} = 2.7 - 3.6V$	12.5			
t_{CR}	Rise Time (for maximum frequency)	$V_{CC} = 1.6 - 1.8V$			10	
		$V_{CC} = 2.7 - 3.6V$			3	
t_{CF}	Fall Time (for maximum frequency)	$V_{CC} = 1.6 - 1.8V$			10	
		$V_{CC} = 2.7 - 3.6V$			3	
Δt_{CK}	Change in period from one clock cycle to the next				10	%

Note: 1. The maximum frequency vs. supply voltage is linear between 1.6V and 2.7V, and the same applies for all other parameters with supply voltage conditions.

33.4.3 Current Consumption

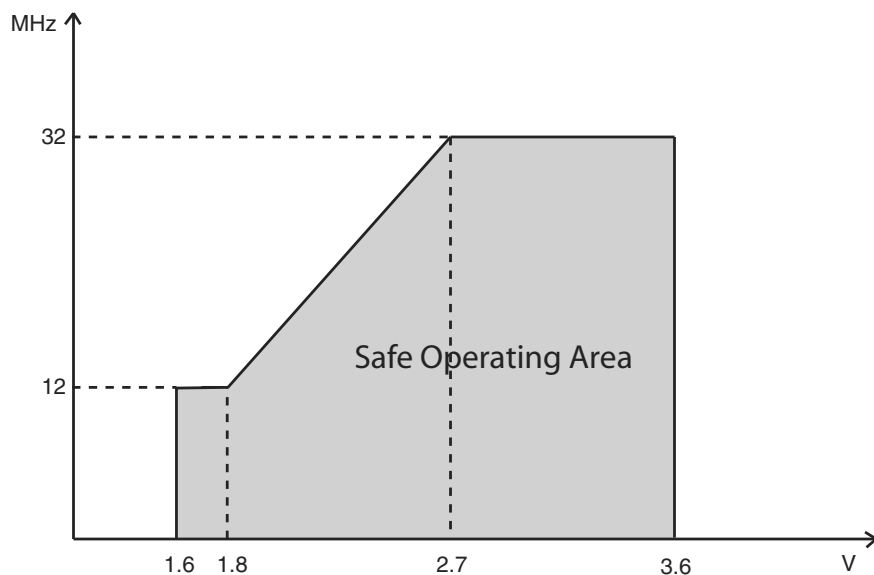
Table 33-91. Current Consumption for Active Mode and Sleep Mode

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
I_{CC}	Active power consumption ⁽¹⁾	32kHz, Ext. Clk	$V_{CC} = 1.8V$	60		μA
			$V_{CC} = 3.0V$	140		
		1MHz, Ext. Clk	$V_{CC} = 1.8V$	245		
			$V_{CC} = 3.0V$	550		
		2MHz, Ext. Clk	$V_{CC} = 1.8V$	440	700	mA
			$V_{CC} = 3.0V$	0.9	1.5	
		32MHz, Ext. Clk		9.0	15	
	Idle power consumption ⁽²⁾	32kHz, Ext. Clk	$V_{CC} = 1.8V$	3.0		μA
			$V_{CC} = 3.0V$	3.5		
		1MHz, Ext. Clk	$V_{CC} = 1.8V$	55		
			$V_{CC} = 3.0V$	110		
		2MHz, Ext. Clk	$V_{CC} = 1.8V$	105	350	mA
			$V_{CC} = 3.0V$	215	650	
		32MHz, Ext. Clk		3.4	8.0	
	Power-down power consumption	T = 25°C	$V_{CC} = 3.0V$	0.1	1.0	μA
		T = 85°C		3.5	6.0	
		T = 105°C		10.0	15	
		WDT and sampled BOD enabled, T = 25°C	$V_{CC} = 3.0V$	1.5	2.0	
		WDT and sampled BOD enabled, T = 85°C		5.8	10	
		WDT and sampled BOD enabled, T = 105°C		12	20	
	Power-save power consumption ⁽³⁾	RTC from ULP clock, WDT and sampled BOD enabled, T = 25°C	$V_{CC} = 1.8V$	1.3		
			$V_{CC} = 3.0V$	1.4		
		RTC from 1.024kHz low power 32.768kHz TOSC, T = 25°C	$V_{CC} = 1.8V$	0.7	2.0	
			$V_{CC} = 3.0V$	0.8	2.0	
		RTC from low power 32.768kHz TOSC, T = 25°C	$V_{CC} = 1.8V$	0.9	3.0	
			$V_{CC} = 3.0V$	1.1	3.0	
	Reset power consumption	Current through $\overline{RESET}$ pin subtracted	$V_{CC} = 3.0V$	170		

- Notes:
1. All Power Reduction Registers set including FPRM and EPRM.
 2. All Power Reduction Registers set without FPRM and EPRM.
 3. Maximum limits are based on characterization, and not tested in production.

The maximum CPU clock frequency depends on V_{CC} . As shown in Figure 33-29 the Frequency vs. V_{CC} curve is linear between $1.8V < V_{CC} < 2.7V$.

Figure 33-29. Maximum Frequency vs. V_{CC}



33.5.6 ADC Characteristics

Table 33-124. Power Supply, Reference, and Input Range

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
AV_{CC}	Analog supply voltage		$V_{CC} - 0.3$		$V_{CC} + 0.3$	V
V_{REF}	Reference voltage		1		$AV_{CC} - 0.6$	
R_{in}	Input resistance	Switched			4.5	k Ω
C_{in}	Input capacitance	Switched			5	pF
R_{AREF}	Reference input resistance	(leakage only)		>10		M Ω
C_{AREF}	Reference input capacitance	Static load		7		pF
V_{in}	Input range		0		V_{REF}	V
	Conversion range	Differential mode, $V_{inP} - V_{inN}$	$-V_{REF}$		V_{REF}	
	Conversion range	Single ended unsigned mode, V_{inP}	$-\Delta V$		$V_{REF} - \Delta V$	
ΔV	Fixed offset voltage			200		lsb

Table 33-125. Clock and Timing

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
Clk_{ADC}	ADC Clock frequency	Maximum is 1/4 of peripheral clock frequency	100		1800	kHz
		Measuring internal signals	100		125	
f_{ClkADC}	Sample rate		16		300	ksps
f_{ADC}	Sample rate	Current limitation (CURRLIMIT) off	16		300	
		CURRLIMIT = LOW	16		250	
		CURRLIMIT = MEDIUM	16		150	
		CURRLIMIT = HIGH	16		50	
	Sampling time	Configurable in steps of 1/2 Clk_{ADC} cycles up to 32 Clk_{ADC} cycles	0.28		320	μs
	Conversion time (latency)	(RES+2)/2+1+ GAIN RES (Resolution) = 8 or 12, GAIN=0 to 3	5.5		10	Clk_{ADC} cycles
	Start-up time	ADC clock cycles		12	24	
	ADC settling time	After changing reference or input mode		7	7	

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
R _Q	Negative impedance ⁽¹⁾	XOSCPWR=0, FRQRANGE=0	0.4MHz resonator, CL=100pF	44k		Ω
			1MHz crystal, CL=20pF	67k		
			2MHz crystal, CL=20pF	67k		
		XOSCPWR=0, FRQRANGE=1, CL=20pF	2MHz crystal	82k		
			8MHz crystal	1500		
			9MHz crystal	1500		
		XOSCPWR=0, FRQRANGE=2, CL=20pF	8MHz crystal	2700		
			9MHz crystal	2700		
			12MHz crystal	1000		
		XOSCPWR=0, FRQRANGE=3, CL=20pF	9MHz crystal	3600		
			12MHz crystal	1300		
			16MHz crystal	590		
		XOSCPWR=1, FRQRANGE=0, CL=20pF	9MHz crystal	390		
			12MHz crystal	50		
			16MHz crystal	10		
		XOSCPWR=1, FRQRANGE=1, CL=20pF	9MHz crystal	1500		
			12MHz crystal	650		
			16MHz crystal	270		
		XOSCPWR=1, FRQRANGE=2, CL=20pF	12MHz crystal	1000		
			16MHz crystal	440		
		XOSCPWR=1, FRQRANGE=3, CL=20pF	12MHz crystal	1300		
			16MHz crystal	590		
	ESR	SF = safety factor			min(R _Q)/SF	kΩ
	Startup time	XOSCPWR=0, FRQRANGE=0	0.4MHz resonator, CL=100pF	1.0		ms
		XOSCPWR=0, FRQRANGE=1	2MHz crystal, CL=20pF	2.6		
		XOSCPWR=0, FRQRANGE=2	8MHz crystal, CL=20pF	0.8		
		XOSCPWR=0, FRQRANGE=3	12MHz crystal, CL=20pF	1.0		
		XOSCPWR=1, FRQRANGE=3	16MHz crystal, CL=20pF	1.4		

Table 33-145. Two-wire Interface Characteristics

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
V_{IH}	Input high voltage		$0.7 \cdot V_{CC}$		$V_{CC} + 0.5$	V
V_{IL}	Input low voltage		-0.5		$0.3 \cdot V_{CC}$	
V_{hys}	Hysteresis of Schmitt trigger inputs		$0.05 V_{CC}^{(1)}$			
V_{OL}	Output low voltage	3mA, sink current	0		0.4	
t_r	Rise time for both SDA and SCL		$20 + 0.1 C_b^{(1)(2)}$		300	ns
t_{of}	Output fall time from V_{IHmin} to V_{ILmax}	$10pF < C_b < 400pF^{(2)}$	$20 + 0.1 C_b^{(1)(2)}$		250	
t_{SP}	Spikes suppressed by input filter		0		50	
I_I	Input current for each I/O Pin	$0.1 V_{CC} < V_I < 0.9 V_{CC}$	-10		10	μA
C_I	Capacitance for each I/O Pin				10	pF
f_{SCL}	SCL clock frequency	$f_{PER}^{(3)} > \max(10f_{SCL}, 250kHz)$	0		400	kHz
R_P	Value of pull-up resistor	$f_{SCL} \leq 100kHz$	$\frac{V_{CC} - 0.4V}{3mA}$		$\frac{100ns}{C_b}$	Ω
		$f_{SCL} > 100kHz$			$\frac{300ns}{C_b}$	
$t_{HD;STA}$	Hold time (repeated) START condition	$f_{SCL} \leq 100kHz$	4.0			μs
		$f_{SCL} > 100kHz$	0.6			
t_{LOW}	Low period of SCL clock	$f_{SCL} \leq 100kHz$	4.7			
		$f_{SCL} > 100kHz$	1.3			
t_{HIGH}	High period of SCL clock	$f_{SCL} \leq 100kHz$	4.0			
		$f_{SCL} > 100kHz$	0.6			
$t_{SU;STA}$	Setup time for a repeated START condition	$f_{SCL} \leq 100kHz$	4.7			
		$f_{SCL} > 100kHz$	0.6			
$t_{HD;DAT}$	Data hold time	$f_{SCL} \leq 100kHz$	0		3.45	
		$f_{SCL} > 100kHz$	0		0.9	
$t_{SU;DAT}$	Data setup time	$f_{SCL} \leq 100kHz$	250			ns
		$f_{SCL} > 100kHz$	100			
$t_{SU;STO}$	Setup time for STOP condition	$f_{SCL} \leq 100kHz$	4.0			μs
		$f_{SCL} > 100kHz$	0.6			
t_{BUF}	Bus free time between a STOP and START condition	$f_{SCL} \leq 100kHz$	4.7			
		$f_{SCL} > 100kHz$	1.3			

- Notes:
1. Required only for $f_{SCL} > 100kHz$.
 2. C_b = Capacitance of one bus line in pF.
 3. f_{PER} = Peripheral clock frequency.

Figure 34-13. Idle Mode Supply Current vs. V_{CC}
 $f_{SYS} = 32\text{MHz}$ internal oscillator prescaled to 8MHz

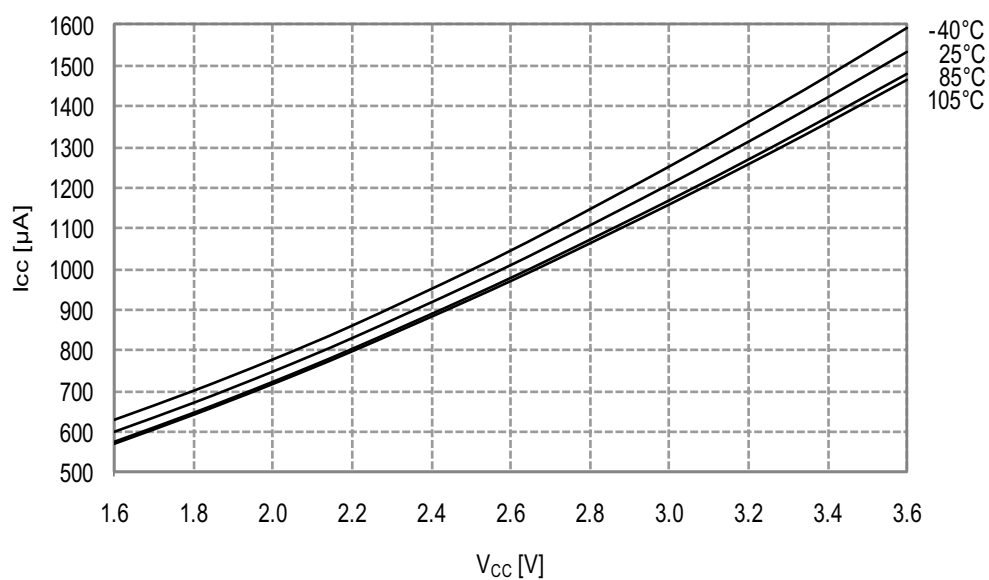


Figure 34-14. Idle Mode Current vs. V_{CC}
 $f_{SYS} = 32\text{MHz}$ internal oscillator

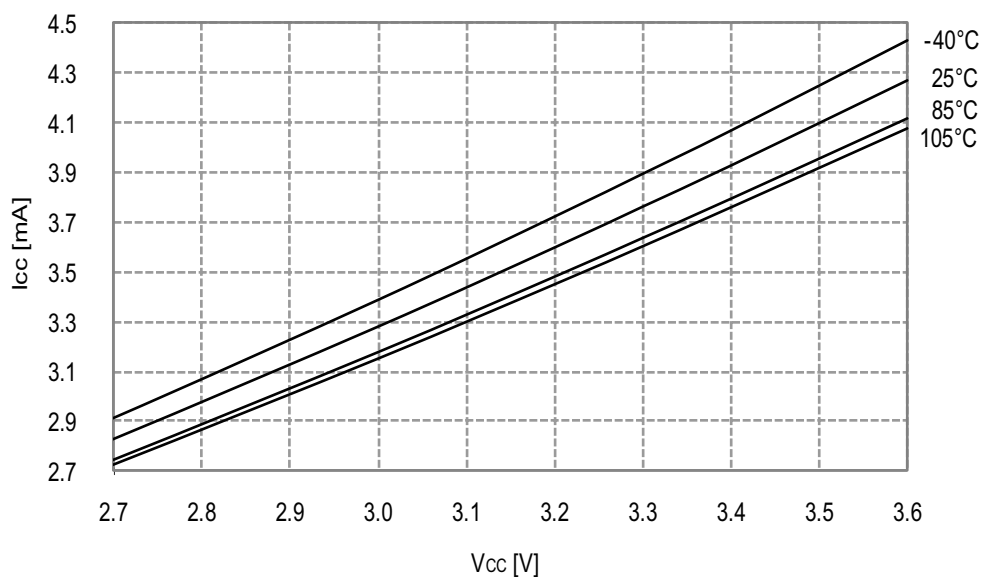


Figure 34-17. Power-down Mode Supply Current vs. Temperature
All functions disabled

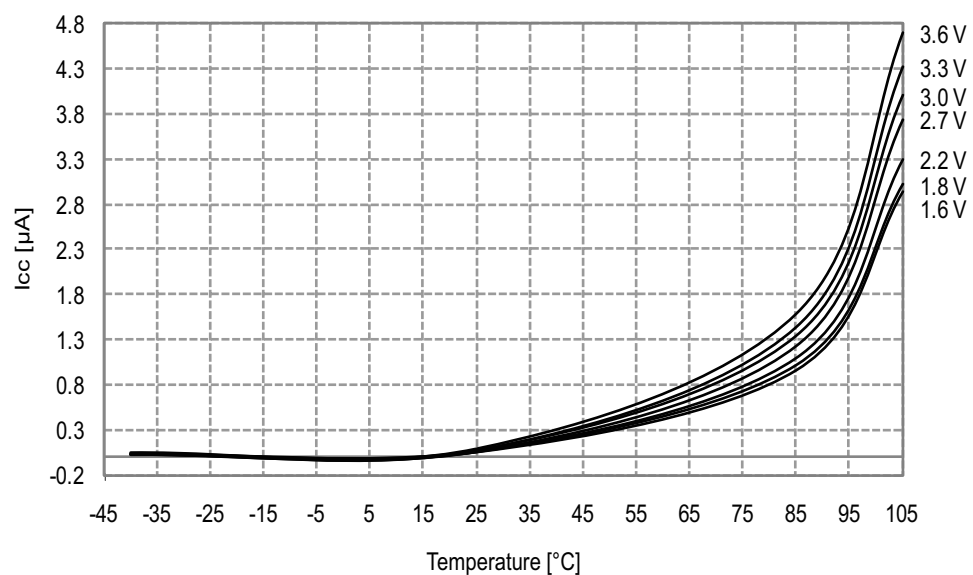


Figure 34-18. Power-down Mode Supply Current vs. Temperature
Watchdog and sampled BOD enabled and running from internal ULP oscillator

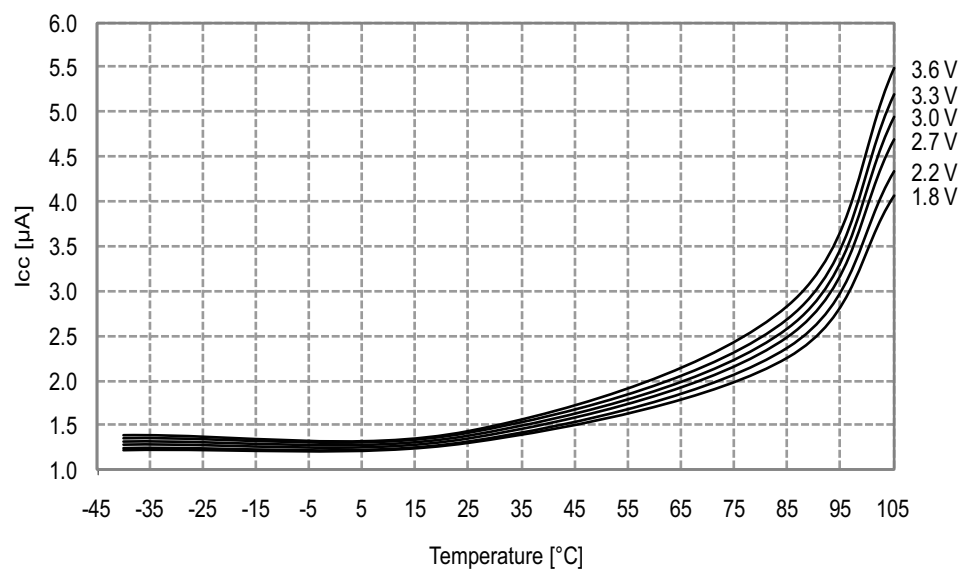


Figure 34-100. I/O Pin Input Threshold Voltage vs. V_{CC}

V_{IL} I/O pin read as "0"

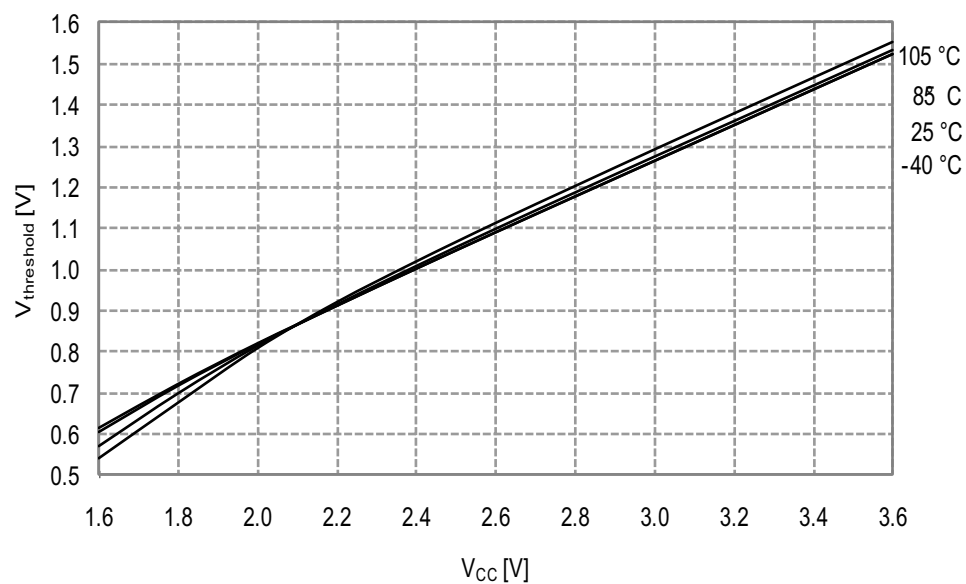


Figure 34-101. I/O Pin Input Hysteresis vs. V_{CC}

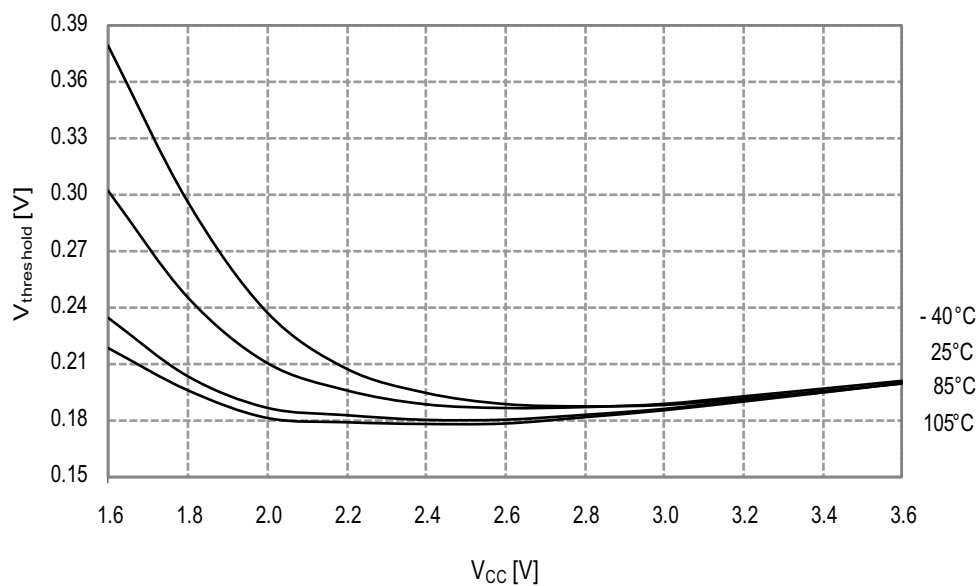


Figure 34-104. INL Error vs. Input Code

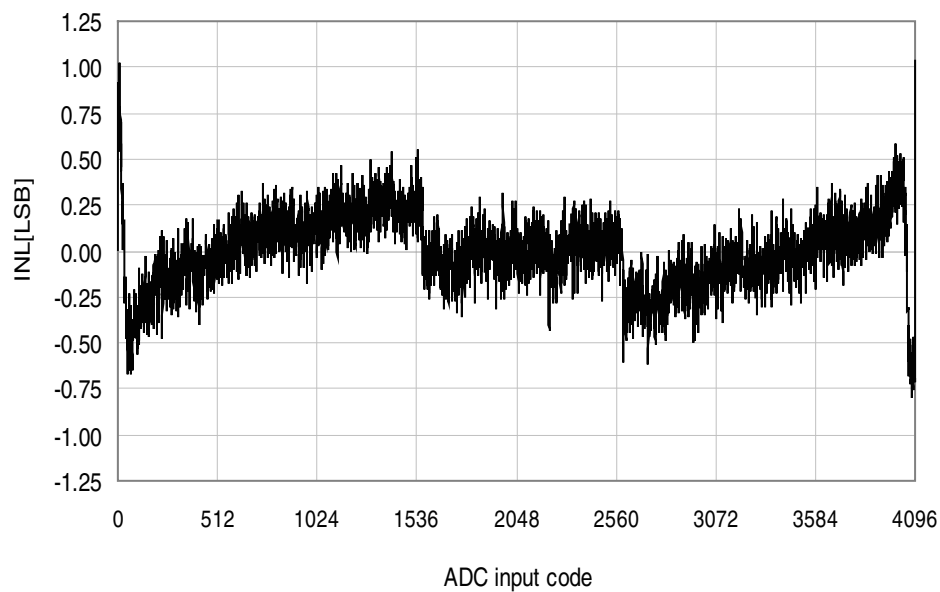


Figure 34-105. DNL Error vs. External V_{REF}
 $T = 25^{\circ}\text{C}$, $V_{CC} = 3.6\text{V}$, external reference

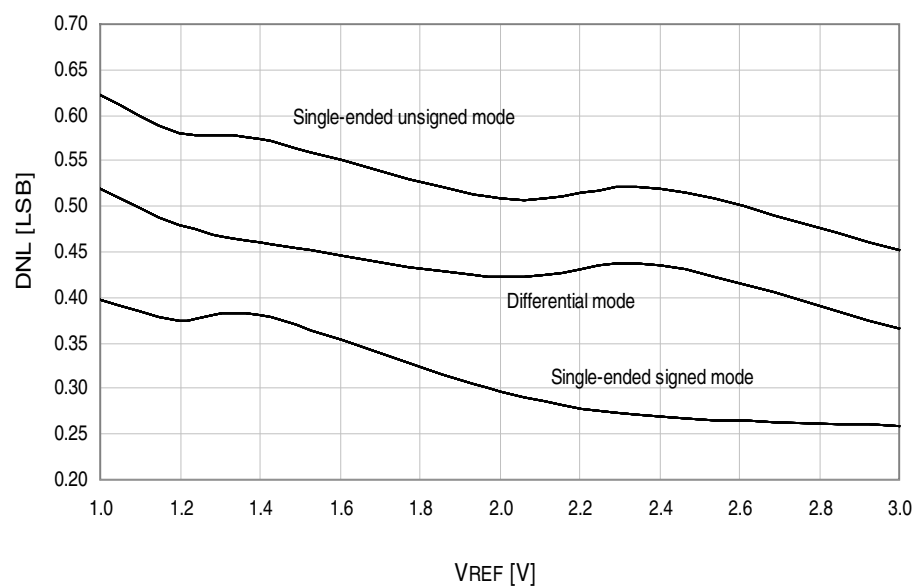


Figure 34-106. DNL Error vs. Sample Rate
 $T = 25^{\circ}\text{C}$, $V_{CC} = 3.6\text{V}$, $V_{REF} = 3.0\text{V external}$

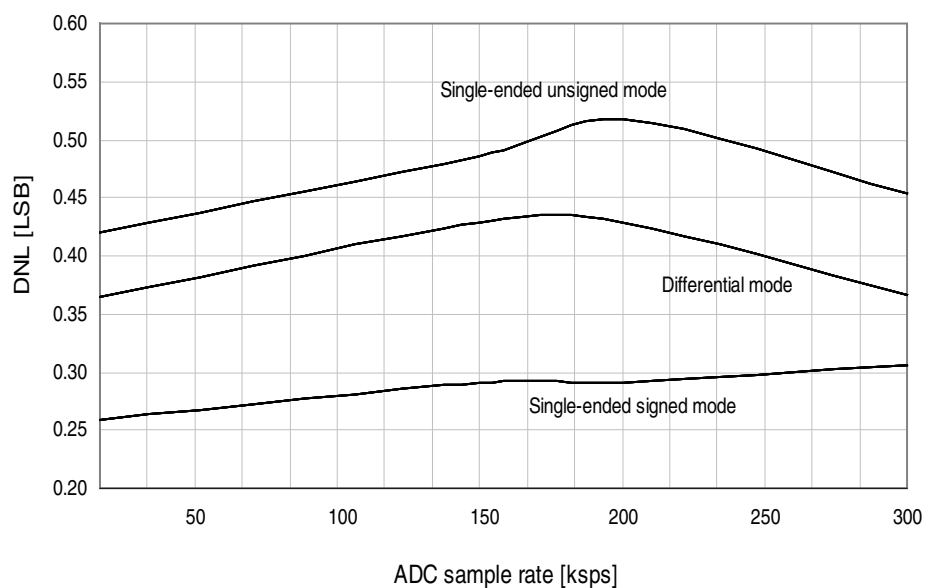


Figure 34-107. DNL Error vs. Input Code

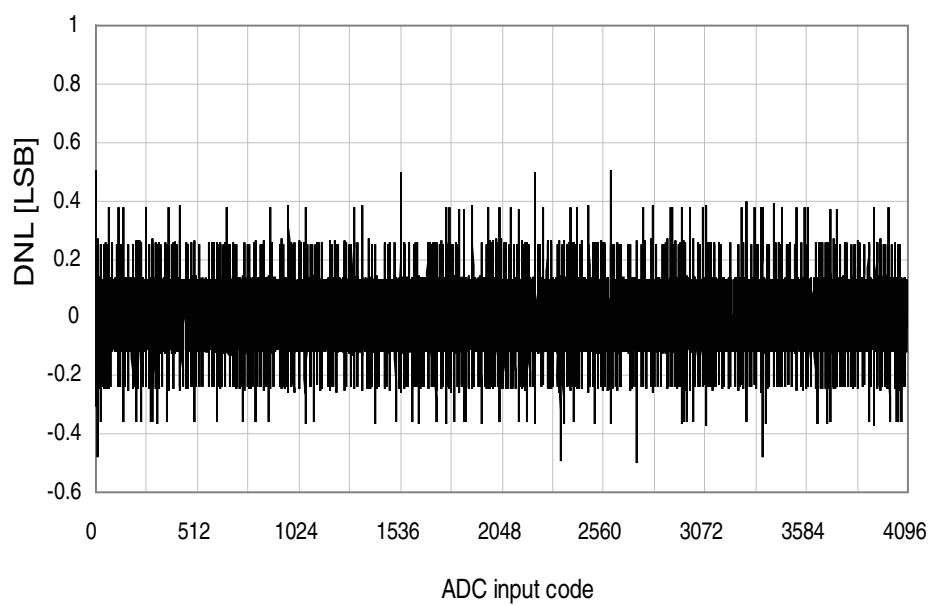
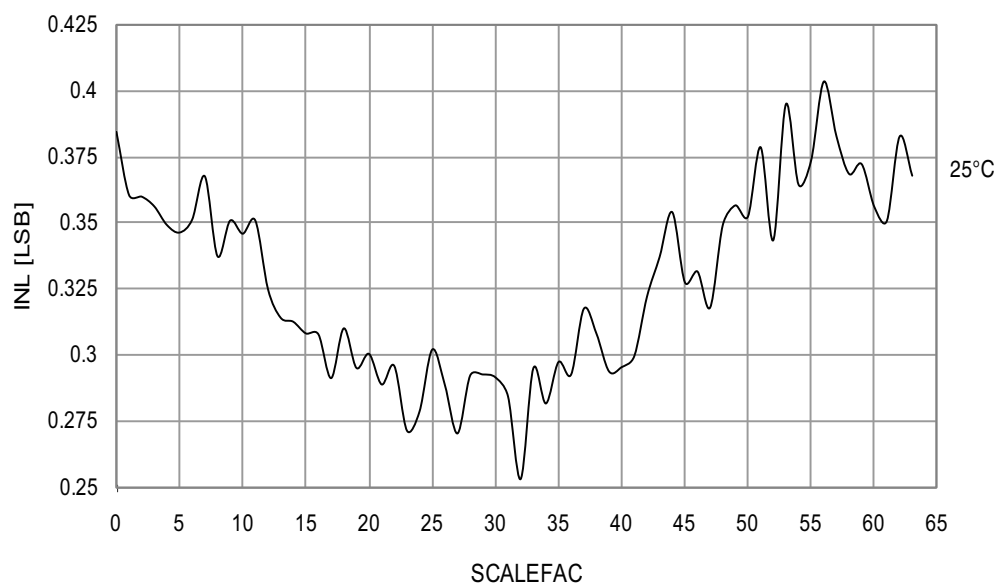


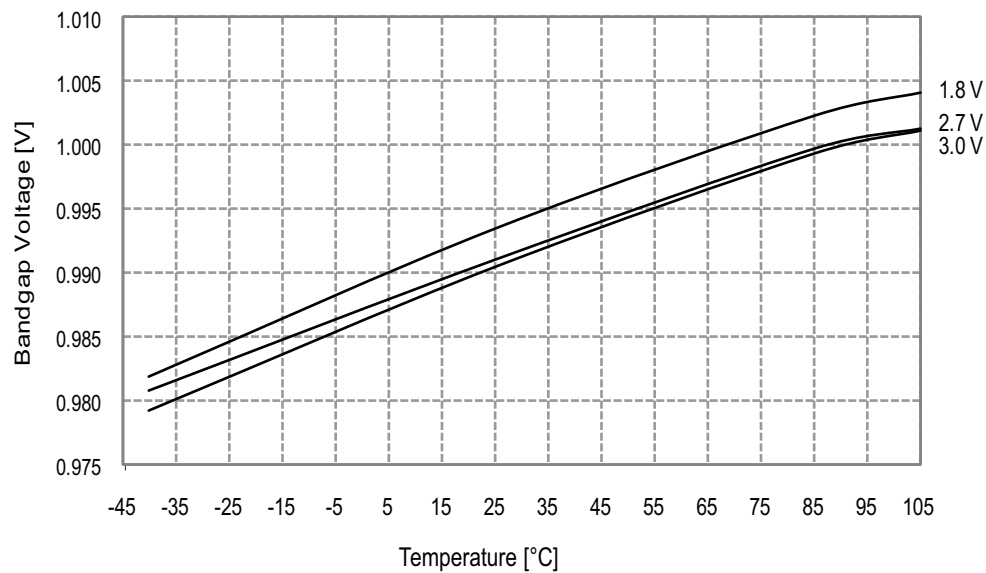
Figure 34-116. Voltage Scaler INL vs. SCALEFAC

$T = 25^{\circ}\text{C}$, $V_{CC} = 3.0\text{V}$



34.2.5 Internal 1.0V Reference Characteristics

Figure 34-117. ADC Internal 1.0V Reference vs. Temperature



34.2.6 BOD Characteristics

Figure 34-118. BOD Thresholds vs. Temperature
BOD level = 1.6V

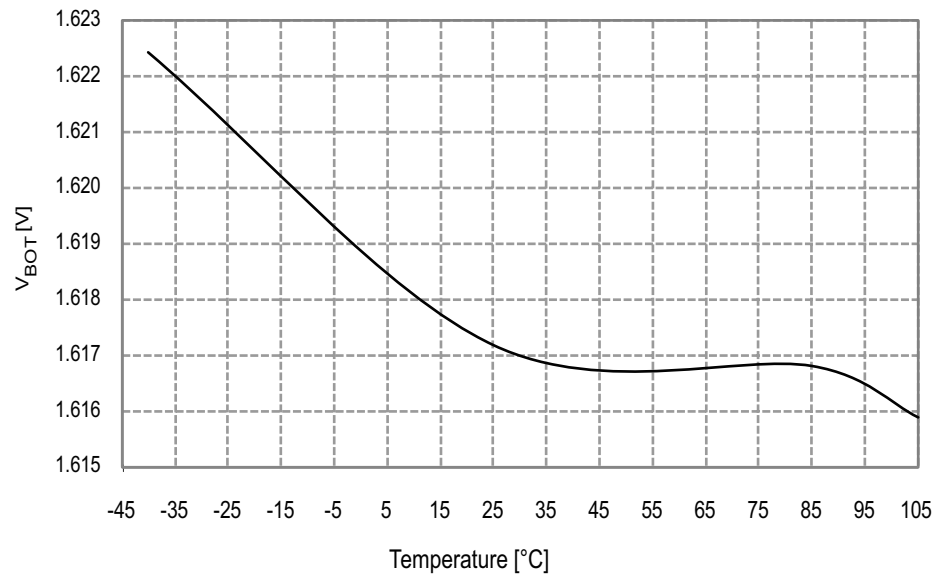


Figure 34-119. BOD Thresholds vs. Temperature
BOD level = 3.0V

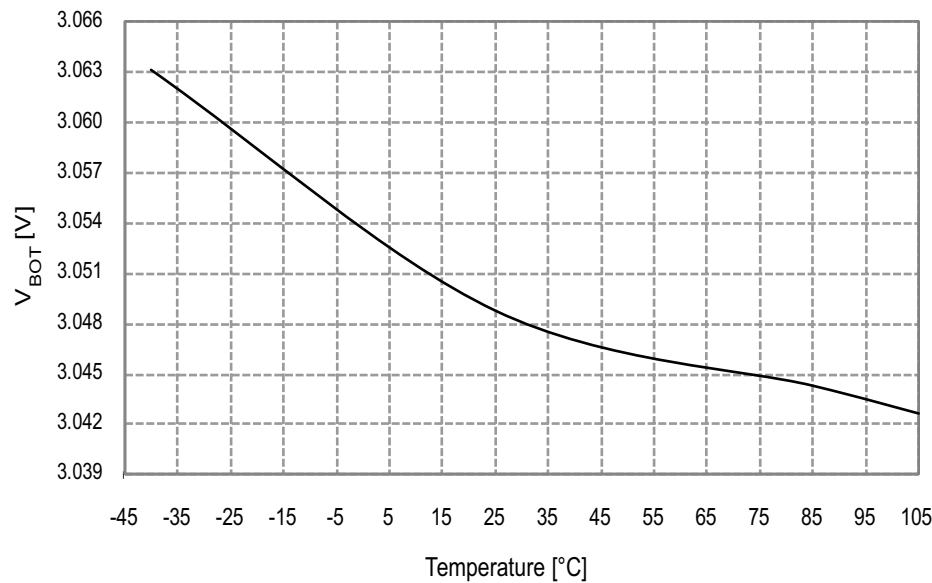


Figure 34-225. Idle Mode Supply Current vs. V_{CC}
 $f_{SYS} = 32\text{MHz}$ internal oscillator prescaled to 8MHz

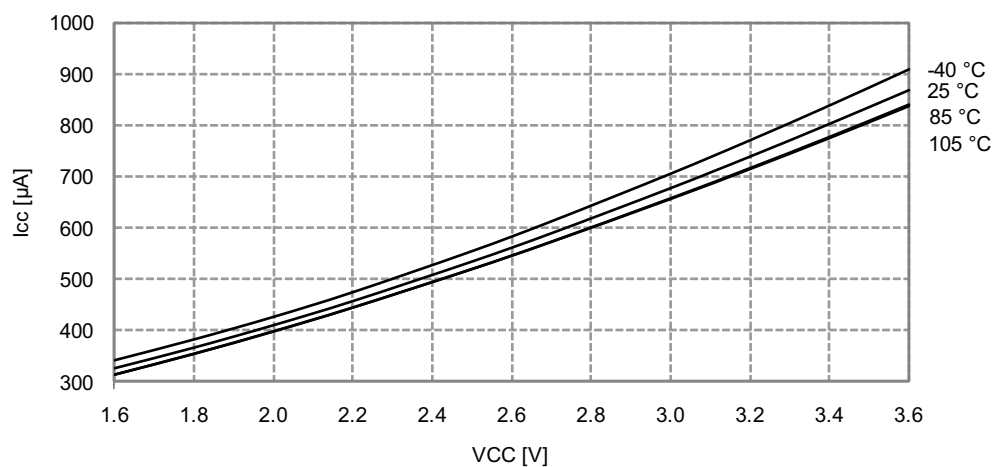


Figure 34-226. Idle Mode Current vs. V_{CC}
 $f_{SYS} = 32\text{MHz}$ internal oscillator

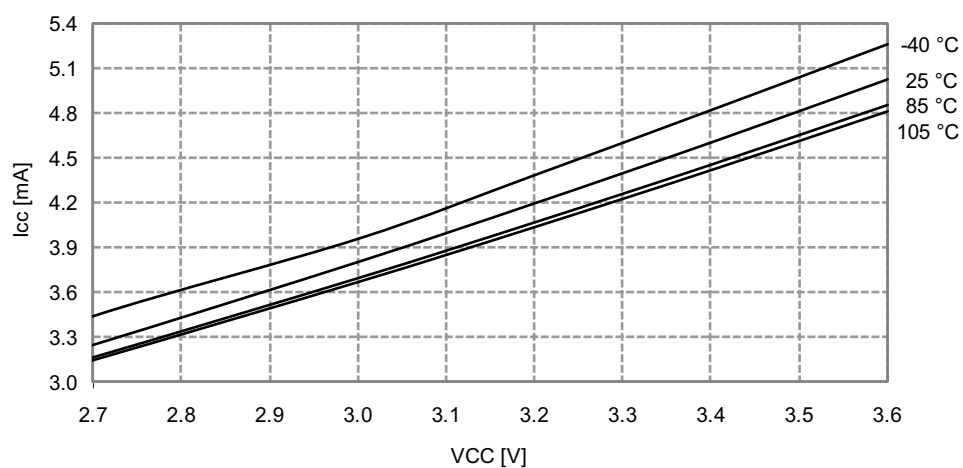


Figure 34-269. 2MHz Internal Oscillator Frequency vs. Temperature
DFLL enabled, from the 32.768kHz internal oscillator

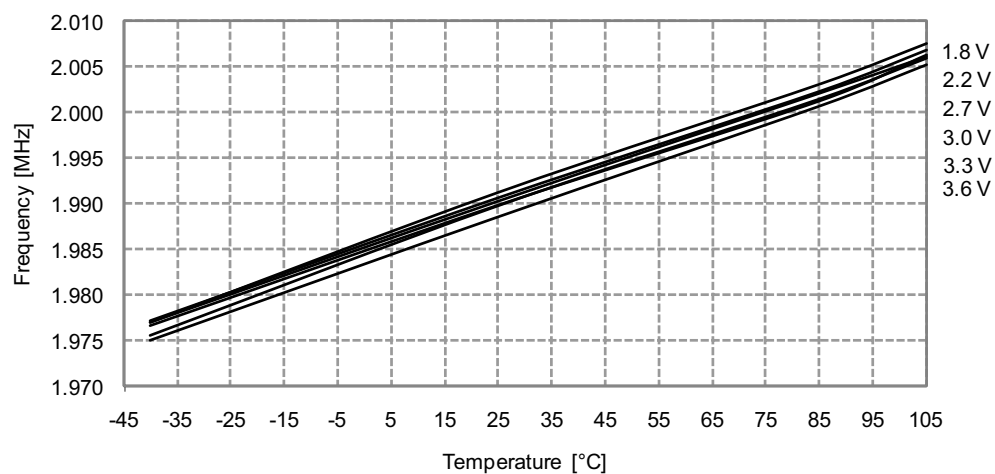


Figure 34-270. 2MHz Internal Oscillator Frequency vs. CALA Calibration Value
 $V_{CC} = 3V$

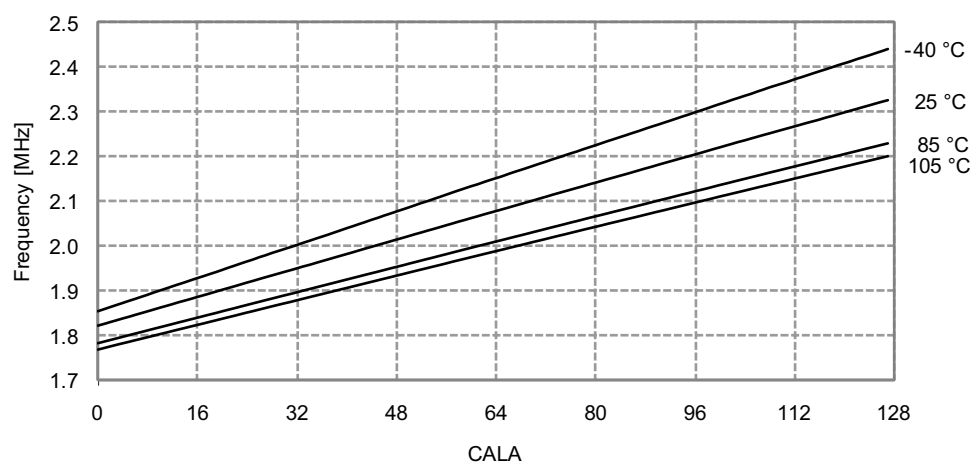


Figure 34-275. 32MHz Internal Oscillator CALA Calibration Step Size

$T = 85^{\circ}\text{C}$, $V_{CC} = 3.0\text{V}$

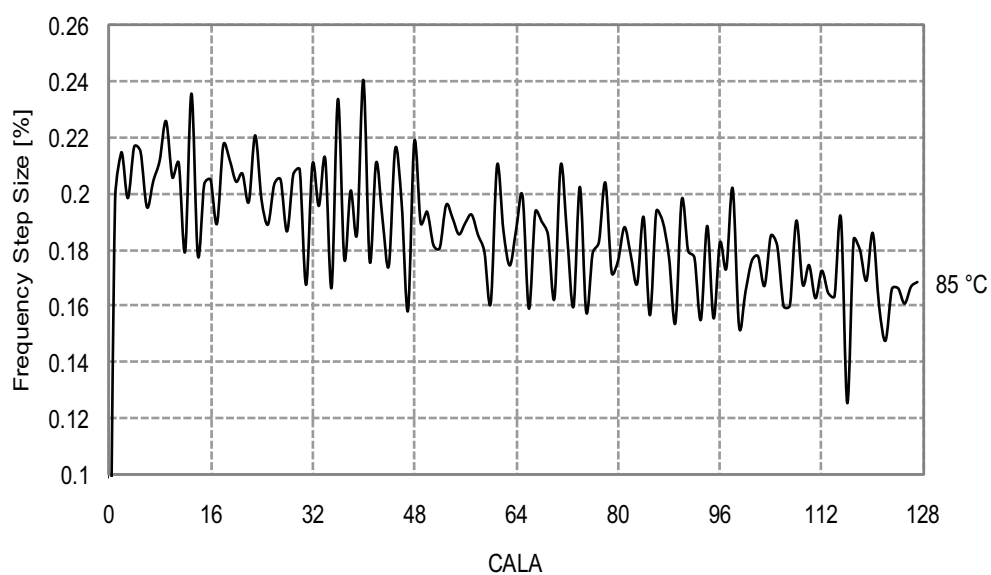
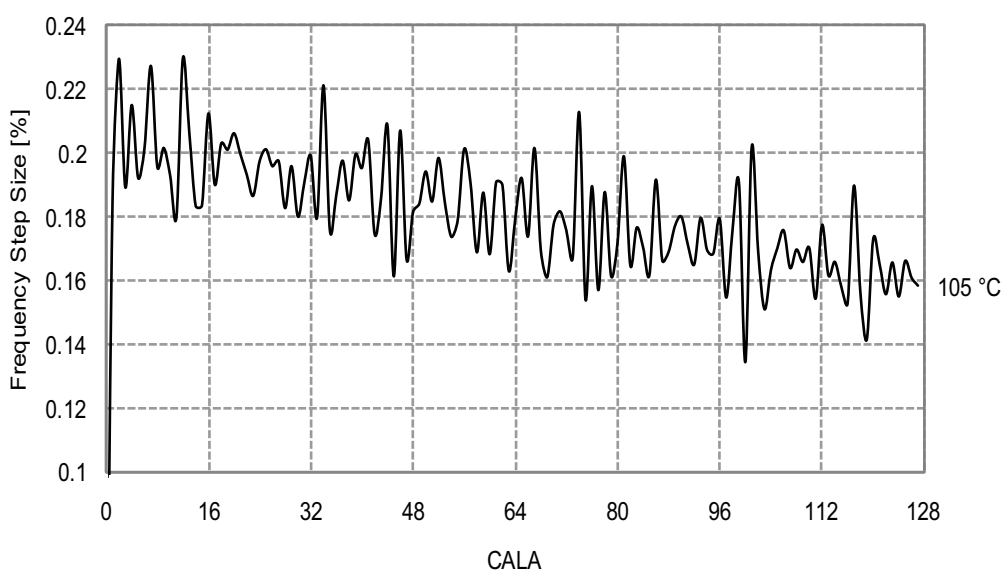


Figure 34-276. 32MHz Internal Oscillator CALA Calibration Step Size

$T = 105^{\circ}\text{C}$, $V_{CC} = 3.0\text{V}$



11. System Control and Reset	24
11.1 Features	24
11.2 Overview	24
11.3 Reset Sequence	24
11.4 Reset Sources	24
12. WDT – Watchdog Timer	26
12.1 Features	26
12.2 Overview	26
13. Interrupts and Programmable Multilevel Interrupt Controller	27
13.1 Features	27
13.2 Overview	27
13.3 Interrupt Vectors	27
14. I/O Ports	29
14.1 Features	29
14.2 Overview	29
14.3 Output Driver	30
14.4 Input Sensing	32
14.5 Alternate Port Functions	32
15. TC0/1 – 16-bit Timer/Counter Type 0 and 1	33
15.1 Features	33
15.2 Overview	33
16. TC2 – Timer/Counter Type 2	35
16.1 Features	35
16.2 Overview	35
17. AWeX – Advanced Waveform Extension	36
17.1 Features	36
17.2 Overview	36
18. Hi-Res – High Resolution Extension	37
18.1 Features	37
18.2 Overview	37
19. RTC – 16-bit Real-Time Counter	38
19.1 Features	38
19.2 Overview	38
20. USB – Universal Serial Bus Interface	39
20.1 Features	39
20.2 Overview	39
21. TWI – Two-Wire Interface	41
21.1 Features	41
21.2 Overview	41
22. SPI – Serial Peripheral Interface	42
22.1 Features	42
22.2 Overview	42

23. USART	43
23.1 Features	43
23.2 Overview	43
24. IRCOM – IR Communication Module	44
24.1 Features	44
24.2 Overview	44
25. CRC – Cyclic Redundancy Check Generator	45
25.1 Features	45
25.2 Overview	45
26. ADC – 12-bit Analog to Digital Converter	46
26.1 Features	46
26.2 Overview	46
27. AC – Analog Comparator	48
27.1 Features	48
27.2 Overview	48
28. Programming and Debugging	50
28.1 Features	50
28.2 Overview	50
29. Pinout and Pin Functions	51
29.1 Alternate Pin Function Description	51
29.2 Alternate Pin Functions	53
30. Peripheral Module Address Map	56
31. Instruction Set Summary	58
32. Packaging Information	63
32.1 64A	63
32.2 64M	64
33. Electrical Characteristics	65
33.1 Atmel ATxmega32C3	65
33.2 Atmel ATxmega64C3	84
33.3 Atmel ATxmega128C3	103
33.4 Atmel ATxmega192C3	122
33.5 Atmel ATxmega256C3	141
34. Typical Characteristics	160
34.1 Atmel ATxmega32C3	160
34.2 Atmel ATxmega64C3	196
34.3 Atmel ATxmega128C3	232
34.4 Atmel ATxmega192C3	267
34.5 Atmel ATxmega256C3	302
35. Errata	337
35.1 Atmel ATxmega256C3	337
35.2 Atmel ATxmega192C3	338
35.3 Atmel ATxmega128C3	339