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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Not For New Designs
Core Processor	M16C/60
Core Size	16-Bit
Speed	32MHz
Connectivity	EBI/EMI, I <sup>2</sup> C, SIO, UART/USART
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	85
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	8K x 8
RAM Size	20K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 26x10b; D/A 2x8b
Oscillator Type	Internal
Operating Temperature	-20°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-BQFP
Supplier Device Package	100-QFP (14x20)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f3650enfa-u0">https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f3650enfa-u0</a>

## 1.4 Block Diagram

Figure 1.3 to Figure 1.4 show block diagrams.

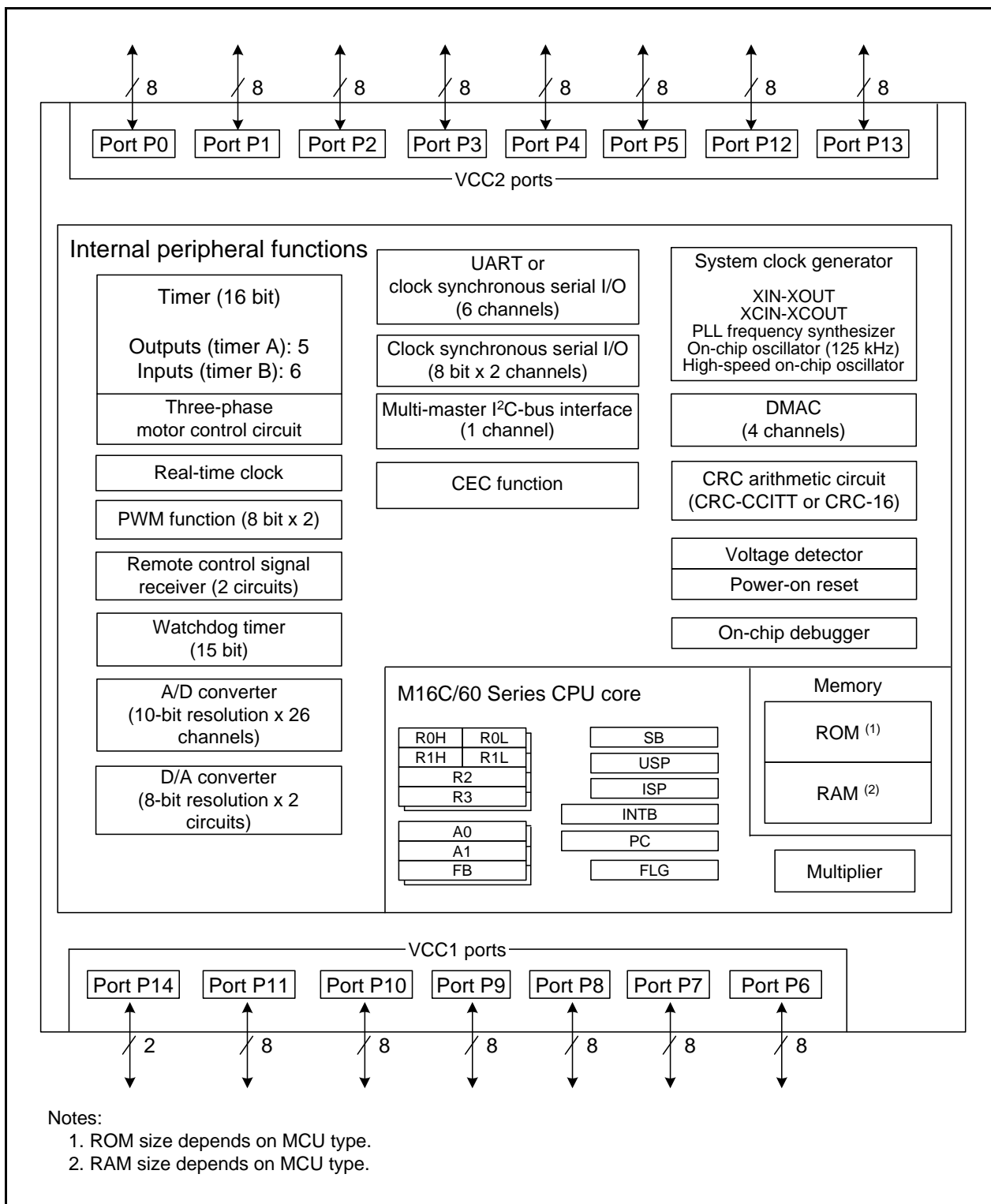


Figure 1.3 Block Diagram for the 128-Pin Package

**Table 1.11 Pin Names for the 100-Pin Package (2/2)**

Pin No.		Control Pin	Port	I/O Pin for Peripheral Function				Bus Control Pin
FA	FB			Interrupt	Timer	Serial interface	A/D converter, D/A converter	
51	49		P4_3					A19
52	50		P4_2					A18
53	51		P4_1					A17
54	52		P4_0					A16
55	53		P3_7					A15
56	54		P3_6					A14
57	55		P3_5					A13
58	56		P3_4					A12
59	57		P3_3					A11
60	58		P3_2					A10
61	59		P3_1					A9
62	60	VCC2						
63	61		P3_0					A8, [A8/D7]
64	62	VSS						
65	63		P2_7				AN2_7	A7, [A7/D7], [A7/D6]
66	64		P2_6				AN2_6	A6, [A6/D6], [A6/D5]
67	65		P2_5	INT7			AN2_5	A5, [A5/D5], [A5/D4]
68	66		P2_4	INT6			AN2_4	A4, [A4/D4], [A4/D3]
69	67		P2_3				AN2_3	A3, [A3/D3], [A3/D2]
70	68		P2_2				AN2_2	A2, [A2/D2], [A2/D1]
71	69		P2_1				AN2_1	A1, [A1/D1], [A1/D0]
72	70		P2_0				AN2_0	A0, [A0/D0], A0
73	71		P1_7	INT5	IDU			D15
74	72		P1_6	INT4	IDW			D14
75	73		P1_5	INT3	IDV			D13
76	74		P1_4					D12
77	75		P1_3			TXD6/SDA6		D11
78	76		P1_2			RXD6/SCL6		D10
79	77		P1_1			CLK6		D9
80	78		P1_0			CTS6/RTS6		D8
81	79		P0_7				AN0_7	D7
82	80		P0_6				AN0_6	D6
83	81		P0_5				AN0_5	D5
84	82		P0_4				AN0_4	D4
85	83		P0_3				AN0_3	D3
86	84		P0_2				AN0_2	D2
87	85		P0_1				AN0_1	D1
88	86		P0_0				AN0_0	D0
89	87		P10_7	KI3			AN7	
90	88		P10_6	KI2			AN6	
91	89		P10_5	KI1			AN5	
92	90		P10_4	KI0			AN4	
93	91		P10_3				AN3	
94	92		P10_2				AN2	
95	93		P10_1				AN1	
96	94	AVSS						
97	95		P10_0				AN0	
98	96	VREF						
99	97	AVCC						
100	98		P9_7			SIN4	ADTRG	

**Table 1.13 Pin Functions for the 128-Pin Package (2/3)**

Signal Name	Pin Name	I/O	Power Supply	Description
Main clock input	XIN	I	VCC1	I/O for the main clock oscillator. Connect a ceramic resonator or crystal between pins XIN and XOUT. <sup>(1)</sup> Input an external clock to XIN pin and leave XOUT pin open.
Main clock output	XOUT	O	VCC1	
Sub clock input	XCIN	I	VCC1	I/O for a sub clock oscillator. Connect a crystal between pins XCIN and XOUT. <sup>(1)</sup> Input an external clock to XCIN pin and leave XOUT pin open.
Sub clock output	XCOUT	O	VCC1	
BCLK output	BCLK	O	VCC2	Outputs the BCLK signal.
Clock output	CLKOUT	O	VCC2	Outputs a clock with the same frequency as f <sub>C</sub> , f <sub>1</sub> , f <sub>8</sub> , or f <sub>32</sub> .
INT interrupt input	INT0 to INT2	I	VCC1	Input for the INT interrupt.
	INT3 to INT7	I	VCC2	
NMI interrupt input	NMI	I	VCC1	Input for the NMI interrupt.
Key input interrupt input	KI0 to KI3	I	VCC1	Input for the key input interrupt.
Timer A	TA0OUT to TA4OUT	I/O	VCC1	I/O for timers A0 to A4 (TA0OUT is N-channel open drain output).
	TA0IN to TA4IN	I	VCC1	Input for timers A0 to A4.
	ZP	I	VCC1	Input for Z-phase.
Timer B	TB0IN to TB5IN	I	VCC1	Input for timers B0 to B5.
Three-phase motor control timer	U, $\bar{U}$ , V, $\bar{V}$ , W, $\bar{W}$	O	VCC1	Output for the three-phase motor control timer.
	SD	I	VCC1	Forced cutoff input.
	IDU, IDV, IDW	I	VCC2	Input for the position data.
Real-time clock output	RTCOUT	O	VCC1	Output for the real-time clock.
PWM output	PWM0, PWM1	O	VCC1, VCC2	PWM output.
Remote control signal receiver input	PMC0, PMC1	I	VCC1	Input for the remote control signal receiver.
Serial interface UART0 to UART2, UART5 to UART7	CTS0 to CTS2, $\bar{CTS5}$	I	VCC1	Input pins to control data transmission.
	CTS6, CTS7	I	VCC2	
	RTS0 to RTS2, $\bar{RTS5}$	O	VCC1	Output pins to control data reception.
	RTS6, RTS7	O	VCC2	
	CLK0 to CLK2, CLK5	I/O	VCC1	Transmit/receive clock I/O.
	CLK6, CLK7	I/O	VCC2	
	RXD0 to RXD2, RXD5	I	VCC1	Serial data input.
	RXD6, RXD7	I	VCC2	
	TXD0 to TXD2, TXD5	O	VCC1	Serial data output. <sup>(2)</sup>
	TXD6, TXD7	O	VCC2	
	CLKS1	O	VCC1	Output for the transmit/receive clock multiple-pin output function.

**Notes:**

1. Contact the manufacturer of crystal/ceramic resonator regarding the oscillation characteristics.
2. TXD2, SDA2, and SCL2 are N-channel open drain output pins. TXDi (i = 0, 1, 5 to 7), SDAi, and SCLi can be selected as CMOS output pins or N-channel open drain output pins.

**Table 1.14 Pin Functions for the 128-Pin Package (3/3)**

Signal Name	Pin Name	I/O	Power Supply	Description
UART0 to UART2, UART5 to UART7 I <sup>2</sup> C mode	SDA0 to SDA2, SDA5	I/O	VCC1	Serial data I/O.
	SDA6, SDA7	I/O	VCC2	
	SCL0 to SCL2, SCL5	I/O	VCC1	Transmit/receive clock I/O.
	SCL6, SCL7	I/O	VCC2	
Serial interface SI/O3, SI/O4	CLK3, CLK4	I/O	VCC1	Transmit/receive clock I/O.
	SIN3, SIN4	I	VCC1	Serial data input.
	SOUT3, SOUT4	O	VCC1	Serial data output.
Multi-master I <sup>2</sup> C- bus interface	SDAMM	I/O	VCC1	Serial data I/O (N-channel open drain output).
	SCLMM	I/O	VCC1	Transmit/receive clock I/O (N-channel open drain output).
CEC I/O	CEC	I/O	VCC1	CEC I/O (N-channel open drain output).
Reference voltage input	VREF	I	VCC1	Reference voltage input for the A/D and D/A converters.
A/D converter	AN0 to AN7	I	VCC1	Analog input.
	AN0_0 to AN0_7 AN2_0 to AN2_7	I	VCC2	
	$\overline{\text{ADTRG}}$	I	VCC1	External trigger input.
	ANEX0, ANEX1	I	VCC1	Extended analog input.
D/A converter	DA0, DA1	O	VCC1	Output pin the D/A converter.
I/O ports	P0_0 to P0_7 P1_0 to P1_7 P2_0 to P2_7 P3_0 to P3_7 P4_0 to P4_7 P5_0 to P5_7 P12_0 to P12_7 P13_0 to P13_7	I/O	VCC2	8-bit CMOS I/O ports. A direction register determines whether each pin is used as an input port or an output port. A pull-up resistor may be enabled or disabled for input ports in 4-bit units.
	P6_0 to P6_7 P7_0 to P7_7 P8_0 to P8_7 P9_0 to P9_7 P10_0 to P10_7 P11_0 to P11_7	I/O	VCC1	8-bit I/O ports having equivalent functions to P0. However, P7_0, P7_1, and P8_5 are N-channel open drain output ports. No pull-up resistor is provided. P8_5 is an input port for verifying the NMI pin level and shares a pin with NMI.
	P14_0, P14_1	I/O	VCC1	I/O ports having equivalent functions to P0.

**Table 1.16 Pin Functions for the 100-Pin Package (2/3)**

Signal Name	Pin Name	I/O	Power Supply	Description
Main clock input	XIN	I	VCC1	I/O for the main clock oscillator. Connect a ceramic resonator or crystal between pins XIN and XOUT. <sup>(1)</sup> Input an external clock to XIN pin and leave XOUT pin open.
Main clock output	XOUT	O	VCC1	
Sub clock input	XCIN	I	VCC1	I/O for a sub clock oscillator. Connect a crystal between XCIN pin and XCOU pin. <sup>(1)</sup> Input an external clock to XCIN pin and leave XCOU pin open.
Sub clock output	XCOU	O	VCC1	
BCLK output	BCLK	O	VCC2	Outputs the BCLK signal.
Clock output	CLKOUT	O	VCC2	Outputs a clock with the same frequency as f <sub>C</sub> , f <sub>1</sub> , f <sub>8</sub> , or f <sub>32</sub> .
$\overline{\text{INT}}$ interrupt input	$\overline{\text{INT0}}$ to $\overline{\text{INT2}}$	I	VCC1	Input for the $\overline{\text{INT}}$ interrupt.
	$\overline{\text{INT3}}$ to $\overline{\text{INT7}}$	I	VCC2	
$\overline{\text{NMI}}$ interrupt input	$\overline{\text{NMI}}$	I	VCC1	Input for the $\overline{\text{NMI}}$ interrupt.
Key input interrupt input	$\overline{\text{KI0}}$ to $\overline{\text{KI3}}$	I	VCC1	Input for the key input interrupt.
Timer A	TA0OUT to TA4OUT	I/O	VCC1	I/O for timers A0 to A4 (TA0OUT is N-channel open drain output).
	TA0IN to TA4IN	I	VCC1	Input for timers A0 to A4.
	ZP	I	VCC1	Input for Z-phase.
Timer B	TB0IN to TB5IN	I	VCC1	Input for timers B0 to B5.
Three-phase motor control timer	U, $\overline{\text{U}}$ , V, $\overline{\text{V}}$ , W, $\overline{\text{W}}$	O	VCC1	Output for the three-phase motor control timer.
	$\overline{\text{SD}}$	I	VCC1	Forced cutoff input.
	IDU, IDV, IDW	I	VCC2	Input for the position data.
Real-time clock output	RTCOUT	O	VCC1	Output for the real-time clock.
PWM output	PWM0, PWM1	O	VCC1, VCC2	PWM output.
Remote control signal receiver input	PMC0, PMC1	I	VCC1	Input for the remote control signal receiver.
Serial interface UART0 to UART2, UART5 to UART7	CTS0 to CTS2, CTS5	I	VCC1	Input pins to control data transmission.
	CTS6, CTS7	I	VCC2	
	RTS0 to RTS2, RTS5	O	VCC1	Output pins to control data reception.
	RTS6, RTS7	O	VCC2	
	CLK0 to CLK2, CLK5	I/O	VCC1	Transmit/receive clock I/O.
	CLK6, CLK7	I/O	VCC2	
	RXD0 to RXD2, RXD5	I	VCC1	Serial data input.
	RXD6, RXD7	I	VCC2	
	TXD0 to TXD2, TXD5	O	VCC1	Serial data output. <sup>(2)</sup>
	TXD6, TXD7	O	VCC2	
	CLKS1	O	VCC1	Output for the transmit/receive clock multiple-pin output function.

**Notes:**

1. Contact the manufacturer of crystal/ceramic resonator regarding the oscillation characteristics.
2. TXD2, SDA2, and SCL2 are N-channel open drain output pins. TXDi (i = 0, 1, 5 to 7), SDAi, and SCLi can be selected as CMOS output pins or N-channel open drain output pins.

**Table 4.14 SFR Information (14) <sup>(1)</sup>**

Address	Register	Symbol	Reset Value
0360h	Pull-Up Control Register 0	PUR0	00h
0361h	Pull-Up Control Register 1	PUR1	0000 0000b <sup>(2)</sup> 0000 0010b
0362h	Pull-Up Control Register 2	PUR2	00h
0363h	Pull-Up Control Register 3	PUR3	00h
0364h			
0365h			
0366h	Port Control Register	PCR	0000 0XX0b
0367h			
0368h			
0369h	NMI/SD Digital Filter Register	NMIDF	XXXX X000b
036Ah			
036Bh			
036Ch			
036Dh			
036Eh			
036Fh			
0370h	PWM Control Register 0	PWMCON0	00h
0371h			
0372h	PWM0 Prescaler	PWMPRE0	00h
0373h	PWM0 Register	PWMREG0	00h
0374h	PWM1 Prescaler	PWMPRE1	00h
0375h	PWM1 Register	PWMREG1	00h
0376h	PWM Control Register 1	PWMCON1	00h
0377h			
0378h			
0379h			
037Ah			
037Bh			
037Ch	Count Source Protection Mode Register	CSPR	00h <sup>(3)</sup>
037Dh	Watchdog Timer Refresh Register	WDTR	XXh
037Eh	Watchdog Timer Start Register	WDTS	XXh
037Fh	Watchdog Timer Control Register	WDC	00XX XXXXb
0380h to 038Fh			

X: Undefined

**Notes:**

- The blank areas are reserved. No access is allowed.
- Values after hardware reset, power-on reset, or voltage monitor 0 reset are as follows:
  - 00000000b when a low-level signal is input to the CNVSS pin
  - 00000010b when a high-level signal is input to the CNVSS pin
 Values after voltage monitor 1 reset, voltage monitor 2 reset, software reset, watchdog timer reset, or oscillation stop detect reset are as follows:
  - 00000000b when bits PM01 and PM00 in the PM0 register are 00b (single-chip mode).
  - 00000010b when bits PM01 and PM00 in the PM0 register are 01b (memory expansion mode) or 11b (microprocessor mode).
- When the CSPROINI bit in the OFS1 address is 0, the reset value is 1000 0000b.

**Table 4.15 SFR Information (15) <sup>(1)</sup>**

Address	Register	Symbol	Reset Value
0390h	DMA2 Source Select Register	DM2SL	00h
0391h			
0392h	DMA3 Source Select Register	DM3SL	00h
0393h			
0394h			
0395h			
0396h			
0397h			
0398h	DMA0 Source Select Register	DM0SL	00h
0399h			
039Ah	DMA1 Source Select Register	DM1SL	00h
039Bh			
039Ch			
039Dh			
039Eh			
039Fh			
03A0h			
03A1h			
03A2h	Open-Circuit Detection Assist Function Register	AINRST	XX00 XXXXb
03A3h			
03A4h			
03A5h			
03A6h			
03A7h			
03A8h			
03A9h			
03AAh			
03ABh			
03ACh			
03ADh			
03AEh			
03AFh			
03B0h			
03B1h			
03B2h			
03B3h			
03B4h	SFR Snoop Address Register	CRCSAR	XXXX XXXXb
03B5h			00XX XXXXb
03B6h	CRC Mode Register	CRCMR	0XXX XXX0b
03B7h			
03B8h			
03B9h			
03BAh			
03BBh			
03BCh	CRC Data Register	CRCD	XXh
03BDh			XXh
03BEh	CRC Input Register	CRCIN	XXh
03BFh			

X: Undefined

Note:

1. The blank areas are reserved. No access is allowed.



**Table 4.20 Read-Modify-Write Instructions**

Function	Mnemonic
Transfer	<i>MOVDir</i>
Bit processing	BCLR, BMCnd, BNOT, BSET, BTSTC, and BTSTS
Shifting	ROL, ROR, ROT, SHA, and SHL
Arithmetic operation	ABS, ADC, ADCF, ADD, DEC, DIV, DIVU, DIVX, EXTS, INC, MUL, MULU, NEG, SBB, and SUB
Decimal operation	DADC, DADD, DSBB, and DSUB
Logical operation	AND, NOT, OR, and XOR
Jump	ADJNZ, SBJNZ

### 5.1.2 Recommended Operating Conditions

**Table 5.2 Recommended Operating Conditions (1/3)**
 $V_{CC1} = V_{CC2} = 2.7$  to  $5.5$  V at  $T_{opr} = -20^{\circ}\text{C}$  to  $85^{\circ}\text{C}/-40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$  unless otherwise specified.

Symbol	Parameter		Standard			Unit
			Min.	Typ.	Max.	
$V_{CC1}$ , $V_{CC2}$	Supply voltage ( $V_{CC1} \geq V_{CC2}$ )	CEC function is not used	2.7	5.0	5.5	V
		CEC function is used	2.7		3.63	V
$AV_{CC}$	Analog supply voltage			$V_{CC1}$		V
$V_{SS}$	Supply voltage			0		V
$AV_{SS}$	Analog supply voltage			0		V
$V_{IH}$	High input voltage	P3_1 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P12_0 to P12_7, P13_0 to P13_7	$0.8V_{CC2}$		$V_{CC2}$	V
		P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 (in single-chip mode)	$0.8V_{CC2}$		$V_{CC2}$	V
		P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 (data input in memory expansion and microprocessor modes)	$0.5V_{CC2}$		$V_{CC2}$	V
		P6_0 to P6_7, P7_2 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P14_0, P14_1 XIN, RESET, CNVSS, BYTE	$0.8V_{CC1}$		$V_{CC1}$	V
		P7_0, P7_1, P8_5	$0.8V_{CC1}$		6.5	V
		CEC	$0.7V_{CC1}$			V
$V_{IL}$	Low input voltage	P3_1 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P12_0 to P12_7, P13_0 to P13_7	0		$0.2V_{CC2}$	V
		P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 (in single-chip mode)	0		$0.2V_{CC2}$	V
		P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 (data input in memory expansion and microprocessor mode)	0		$0.16V_{CC2}$	V
		P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P14_0, P14_1 XIN, RESET, CNVSS, BYTE	0		$0.2V_{CC1}$	V
		CEC			$0.26V_{CC1}$	V
$I_{OH(sum)}$	High peak output current	Sum of $I_{OH(peak)}$ at P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7			-40.0	mA
		Sum of $I_{OH(peak)}$ at P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P12_0 to P12_7, and P13_0 to P13_7			-40.0	mA
		Sum of $I_{OH(peak)}$ at P6_0 to P6_7, P7_2 to P7_7, P8_0 to P8_4			-40.0	mA
		Sum of $I_{OH(peak)}$ at P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P14_0 to P14_1			-40.0	mA
$I_{OH(peak)}$	High peak output current	P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_2 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P12_0 to P12_7, P13_0 to P13_7, P14_0, P14_1			-10.0	mA
$I_{OH(avg)}$	High average output current (1)	P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_2 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P12_0 to P12_7, P13_0 to P13_7, P14_0, P14_1			-5.0	mA

Note:

- The average output current is the mean value within 100 ms.

### 5.1.5 Flash Memory Electrical Characteristics

**Table 5.8 CPU Clock When Operating Flash Memory ( $f_{\text{BLK}}$ )**

$V_{\text{CC1}} = 2.7$  to  $5.5$  V,  $T_{\text{opr}} = -20^{\circ}\text{C}$  to  $85^{\circ}\text{C}/-40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$  unless otherwise specified.

Symbol	Parameter	Conditions	Standard			Unit
			Min.	Typ.	Max.	
-	CPU rewrite mode				10 (1)	MHz
$f(\text{SLOW\_R})$	Slow read mode				5 (3)	MHz
-	Low current consumption read mode			$f\text{C}(32.768)$	35	kHz
-	Data flash read	$2.7\text{ V} \leq V_{\text{CC1}} \leq 3.0\text{ V}$			16 (2)	MHz
		$3.0\text{ V} < V_{\text{CC1}} \leq 5.5\text{ V}$			20 (2)	MHz

Notes:

1. Set the PM17 bit in the PM1 register to 1 (one wait).
2. When the frequency is over this value, set the FMR17 bit in the FMR1 register to 0 (one wait) or the PM17 bit in the PM1 register to 1 (one wait).
3. Set the PM17 bit in the PM1 register to 1 (one wait). When using 125 kHz on-chip oscillator clock or sub clock as the CPU clock source, a wait is not necessary.

**Table 5.9 Flash Memory (Program ROM 1, 2) Electrical Characteristics**

$V_{\text{CC1}} = 2.7$  to  $5.5$  V at  $T_{\text{opr}} = 0^{\circ}\text{C}$  to  $60^{\circ}\text{C}$  (option:  $-40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ), unless otherwise specified.

Symbol	Parameter	Conditions	Standard			Unit
			Min.	Typ.	Max.	
-	Program and erase cycles (1), (3), (4)	$V_{\text{CC1}} = 3.3\text{ V}$ , $T_{\text{opr}} = 25^{\circ}\text{C}$	1,000 (2)			times
-	2 word program time	$V_{\text{CC1}} = 3.3\text{ V}$ , $T_{\text{opr}} = 25^{\circ}\text{C}$		150	4000	$\mu\text{s}$
-	Lock bit program time	$V_{\text{CC1}} = 3.3\text{ V}$ , $T_{\text{opr}} = 25^{\circ}\text{C}$		70	3000	$\mu\text{s}$
-	Block erase time	$V_{\text{CC1}} = 3.3\text{ V}$ , $T_{\text{opr}} = 25^{\circ}\text{C}$		0.2	3.0	s
-	Program, erase voltage		2.7		5.5	V
-	Read voltage	$T_{\text{opr}} = -20^{\circ}\text{C}$ to $85^{\circ}\text{C}/-40^{\circ}\text{C}$ to $85^{\circ}\text{C}$	2.7		5.5	V
-	Program, erase temperature		0		60	$^{\circ}\text{C}$
$t_{\text{PS}}$	Flash memory circuit stabilization wait time				50	$\mu\text{s}$
-	Data hold time (6)	Ambient temperature = $55^{\circ}\text{C}$	20			year

Notes:

1. Definition of program and erase cycles:  
The program and erase cycles refer to the number of per-block erasures. If the program and erase cycles are  $n$  ( $n = 1,000$ ), each block can be erased  $n$  times. For example, if a block is erased after writing 2 word data 16,384 times, each to a different address, this counts as one program and erase cycles. Data cannot be written to the same address more than once without erasing the block (rewrite prohibited).
2. Cycles to guarantee all electrical characteristics after program and erase. (1 to Min. value can be guaranteed).
3. In a system that executes multiple programming operations, the actual erasure count can be reduced by writing to sequential addresses in turn so that as much of the block as possible is used up before performing an erase operation. It is advisable to retain data on the erasure cycles of each block and limit the number of erase operations to a certain number.
4. If an error occurs during block erase, attempt to execute the clear status register command, then execute the block erase command at least three times until the erase error does not occur.
5. Customers desiring program/erase failure rate information should contact a Renesas Electronics sales office.
6. The data hold time includes time that the power supply is off or the clock is not supplied.

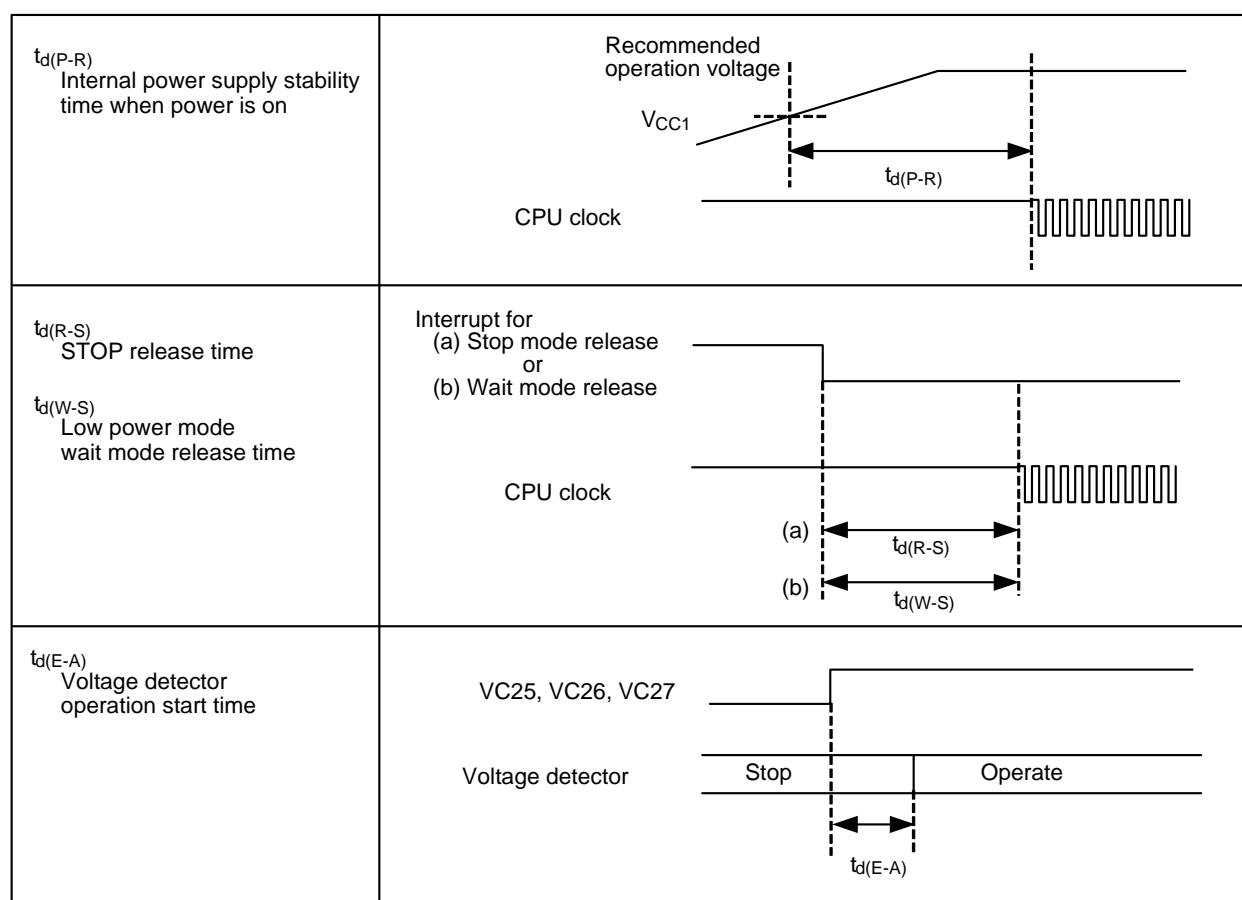
**Table 5.15 Power Supply Circuit Timing Characteristics**

The measurement condition is  $V_{CC1} = 2.7$  to  $5.5$  V and  $T_{opr} = 25^{\circ}\text{C}$ , unless otherwise specified.

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
$t_{d(P-R)}$	Internal power supply stability time when power is on <sup>(1)</sup>				5	ms
$t_{d(R-S)}$	STOP release time				150	$\mu\text{s}$
$t_{d(W-S)}$	Low power mode wait mode release time				150	$\mu\text{s}$

Note:

- Waiting time until the internal power supply generator stabilizes when power is on.

**Figure 5.4 Power Supply Circuit Timing Diagram**

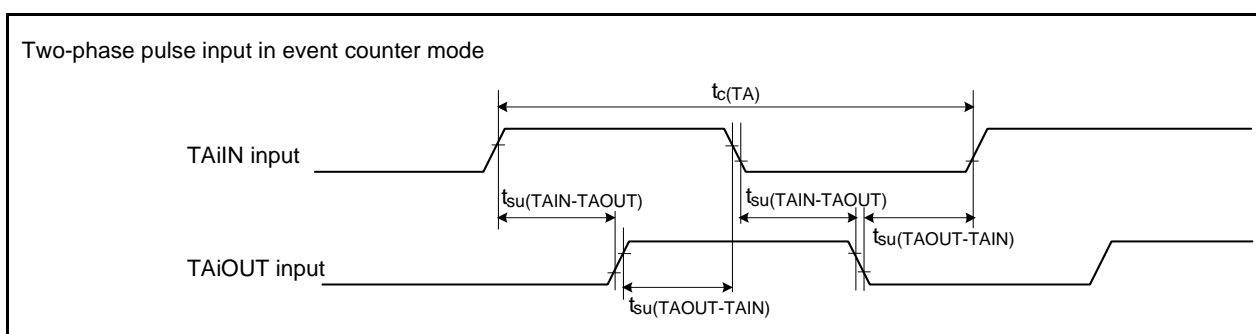
$$V_{CC1} = V_{CC2} = 5\text{ V}$$

**Timing Requirements**

( $V_{CC1} = V_{CC2} = 5\text{ V}$ ,  $V_{SS} = 0\text{ V}$ , at  $T_{opr} = -20^{\circ}\text{C}$  to  $85^{\circ}\text{C}$  /  $-40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$  unless otherwise specified)

**Table 5.30 Timer A Input (Two-Phase Pulse Input in Event Counter Mode)**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiIN input cycle time	800		ns
$t_{su(TAIN-TAOUT)}$	TAiOUT input setup time	200		ns
$t_{su(TAOUT-TAIN)}$	TAiIN input setup time	200		ns

**Figure 5.8 Timer A Input (Two-Phase Pulse Input in Event Counter Mode)**

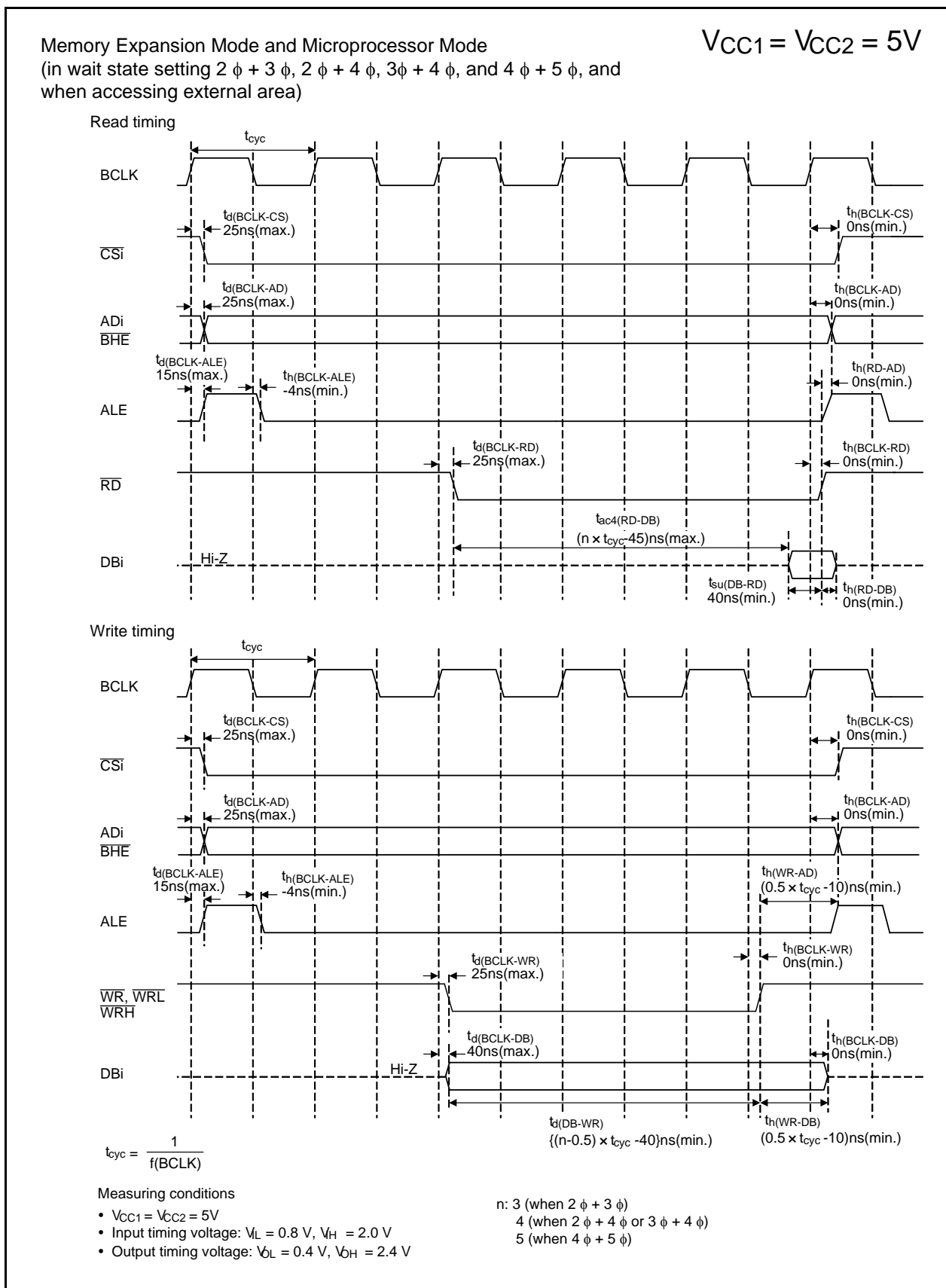


Figure 5.18 Timing Diagram

$$V_{CC1} = V_{CC2} = 3 \text{ V}$$

**Table 5.45 Electrical Characteristics (3)**

R5F3651ENFC, R5F3651EDFC, R5F3651KNFC, R5F3650KNFA, R5F3650KNFB, R5F3651KDFC, R5F3650KDFA, R5F3650KDFB, R5F3651MNFC, R5F3650MNFA, R5F3650MNFB, R5F3651MDFC, R5F3650MDFA, R5F3650MDFB, R5F3651NNFC, R5F3650NNFA, R5F3650NNFB, R5F3651NDFC, R5F3650NDFA, R5F3650NDFB  
 $V_{CC1} = V_{CC2} = 2.7 \text{ to } 3.3 \text{ V}$ ,  $V_{SS} = 0 \text{ V}$  at  $T_{opr} = -20^\circ\text{C to } 85^\circ\text{C} / -40^\circ\text{C to } 85^\circ\text{C}$ ,  $f_{(BCLK)} = 32 \text{ MHz}$  unless otherwise specified.

Symbol	Parameter	Measuring Condition	Standard			Unit
			Min.	Typ.	Max.	
$R_{fXCIN}$	Feedback resistance XCIN			16		$M\Omega$
$I_{CC}$	Power supply current  In single-chip, mode, the output pin are open and other pins are $V_{SS}$	High-speed mode	$f_{(BCLK)} = 32 \text{ MHz}$ XIN = 4 MHz (square wave), PLL multiplied by 8 125 kHz on-chip oscillator stopped	26.0		mA
			$f_{(BCLK)} = 32 \text{ MHz}$ , A/D conversion XIN = 4 MHz (square wave), PLL multiplied by 8 125 kHz on-chip oscillator stopped	27.0		mA
			$f_{(BCLK)} = 20 \text{ MHz}$ XIN = 20 MHz (square wave) 125 kHz on-chip oscillator stopped	17.0		mA
		40 MHz on-chip oscillator mode	Main clock stopped 40 MHz on-chip oscillator on, divide-by-4 ( $f_{(BCLK)} = 10 \text{ MHz}$ ) 125 kHz on-chip oscillator stopped	18.0		mA
		125 kHz on-chip oscillator mode	Main clock stopped 40 MHz on-chip oscillator stopped 125 kHz on-chip oscillator on, no division FMR22 = 1 (slow read mode)	500.0		$\mu\text{A}$
		Low-power mode	$f_{(BCLK)} = 32 \text{ MHz}$ In low-power mode, FMR 22 = FMR23 = 1 on flash memory <sup>(1)</sup>	170.0		$\mu\text{A}$
			$f_{(BCLK)} = 32 \text{ MHz}$ In low-power mode, on RAM <sup>(1)</sup>	40.0		$\mu\text{A}$
		Wait mode	Main clock stopped 40 MHz on-chip oscillator stopped 125 kHz on-chip oscillator on Peripheral clock operating $T_{opr} = 25^\circ\text{C}$	20.0		$\mu\text{A}$
			$f_{(BCLK)} = 32 \text{ MHz}$ (oscillation capacity High) 40 MHz on-chip oscillator stopped 125 kHz on-chip oscillator stopped Peripheral clock operating $T_{opr} = 25^\circ\text{C}$	8.0		$\mu\text{A}$
			$f_{(BCLK)} = 32 \text{ kHz}$ (oscillation capacity Low) 40 MHz on-chip oscillator stopped 125 kHz on-chip oscillator stopped Peripheral clock operating $T_{opr} = 25^\circ\text{C}$	4.0		$\mu\text{A}$
		Stop mode	Main clock stopped 40 MHz on-chip oscillator stopped 125 kHz on-chip oscillator stopped Peripheral clock stopped $T_{opr} = 25^\circ\text{C}$	1.6		$\mu\text{A}$
		During flash memory program	$f_{(BCLK)} = 10 \text{ MHz}$ , PM17 = 1 (one wait) $V_{CC1} = 3.0 \text{ V}$	20.0		mA
		During flash memory erase	$f_{(BCLK)} = 10 \text{ MHz}$ , PM17 = 1 (one wait) $V_{CC1} = 3.0 \text{ V}$	30.0		mA

Note:

- This indicates the memory in which the program to be executed exists.

$$V_{CC1} = V_{CC2} = 3\text{ V}$$

**Timing Requirements**

( $V_{CC1} = V_{CC2} = 3\text{ V}$ ,  $V_{SS} = 0\text{ V}$ , at  $T_{opr} = -20^{\circ}\text{C}$  to  $85^{\circ}\text{C}$  /  $-40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$  unless otherwise specified)

**5.3.2.4 Timer B Input****Table 5.54 Timer B Input (Counter Input in Event Counter Mode)**

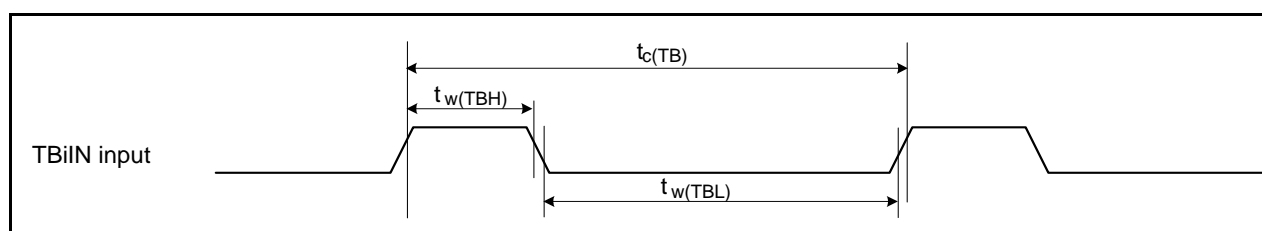
Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN input cycle time (counted on one edge)	150		ns
$t_{w(TBH)}$	TBiIN input high pulse width (counted on one edge)	60		ns
$t_{w(TBL)}$	TBiIN input low pulse width (counted on one edge)	60		ns
$t_{c(TB)}$	TBiIN input cycle time (counted on both edges)	300		ns
$t_{w(TBH)}$	TBiIN input high pulse width (counted on both edges)	120		ns
$t_{w(TBL)}$	TBiIN input low pulse width (counted on both edges)	120		ns

**Table 5.55 Timer B Input (Pulse Period Measurement Mode)**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN input cycle time	600		ns
$t_{w(TBH)}$	TBiIN input high pulse width	300		ns
$t_{w(TBL)}$	TBiIN input low pulse width	300		ns

**Table 5.56 Timer B Input (Pulse Width Measurement Mode)**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN input cycle time	600		ns
$t_{w(TBH)}$	TBiIN input high pulse width	300		ns
$t_{w(TBL)}$	TBiIN input low pulse width	300		ns

**Figure 5.24 Timer B Input**



$$V_{CC1} = V_{CC2} = 3 \text{ V}$$

### 5.3.4 Switching Characteristics (Memory Expansion Mode and Microprocessor Mode)

( $V_{CC1} = V_{CC2} = 3 \text{ V}$ ,  $V_{SS} = 0 \text{ V}$ , at  $T_{opr} = -20^{\circ}\text{C}$  to  $85^{\circ}\text{C}/-40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$  unless otherwise specified)

#### 5.3.4.1 In No Wait State Setting

**Table 5.61 Memory Expansion and Microprocessor Modes (in No Wait State Setting)**

Symbol	Parameter	Measuring Condition	Standard		Unit
			Min.	Max.	
$t_{d(BCLK-AD)}$	Address output delay time	See Figure 5.29		30	ns
$t_{h(BCLK-AD)}$	Address output hold time (in relation to BCLK)		0		ns
$t_{h(RD-AD)}$	Address output hold time (in relation to RD)		0		ns
$t_{h(WR-AD)}$	Address output hold time (in relation to WR)		(Note 2)		ns
$t_{d(BCLK-CS)}$	Chip select output delay time			30	ns
$t_{h(BCLK-CS)}$	Chip select output hold time (in relation to BCLK)		0		ns
$t_{d(BCLK-ALE)}$	ALE signal output delay time			25	ns
$t_{h(BCLK-ALE)}$	ALE signal output hold time		-4		ns
$t_{d(BCLK-RD)}$	RD signal output delay time			30	ns
$t_{h(BCLK-RD)}$	RD signal output hold time		0		ns
$t_{d(BCLK-WR)}$	WR signal output delay time			30	ns
$t_{h(BCLK-WR)}$	WR signal output hold time		0		ns
$t_{d(BCLK-DB)}$	Data output delay time (in relation to BCLK)			40	ns
$t_{h(BCLK-DB)}$	Data output hold time (in relation to BCLK) <sup>(3)</sup>		0		ns
$t_{d(DB-WR)}$	Data output delay time (in relation to WR)		(Note 1)		ns
$t_{h(WR-DB)}$	Data output hold time (in relation to WR) <sup>(3)</sup>		(Note 2)		ns

Notes:

1. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f_{(BCLK)}} - 40[\text{ns}] \quad f_{(BCLK)} \text{ is } 12.5 \text{ MHz or less.}$$

2. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f_{(BCLK)}} - 10[\text{ns}]$$

3. This standard value shows the timing when the output is off, and does not show hold time of data bus.

Hold time of data bus varies with capacitor volume and pull-up (pull-down) resistance value.

Hold time of data bus is expressed in

$$t = -CR \times \ln(1 - V_{OL}/V_{CC2})$$

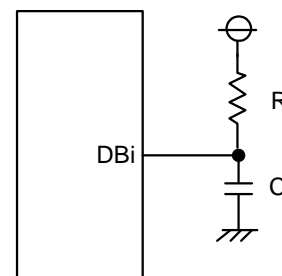
by a circuit of the right figure.

For example, when  $V_{OL} = 0.2V_{CC2}$ ,  $C = 30 \text{ pF}$ ,  $R = 1 \text{ k}\Omega$ ,

hold time of output low level is

$$t = -30 \text{ pF} \times 1 \text{ k}\Omega \times \ln(1 - 0.2V_{CC2}/V_{CC2})$$

= 6.7 ns.



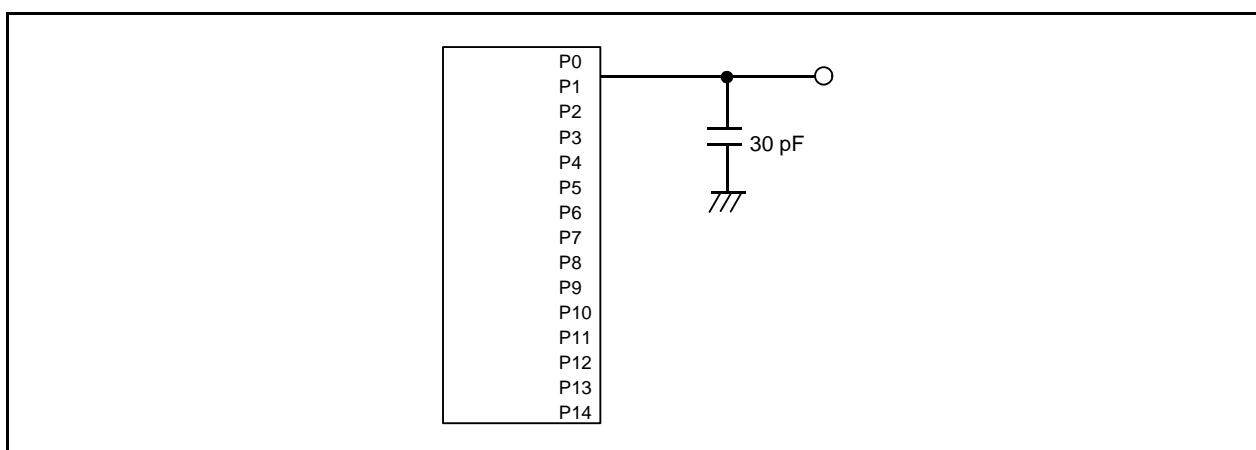


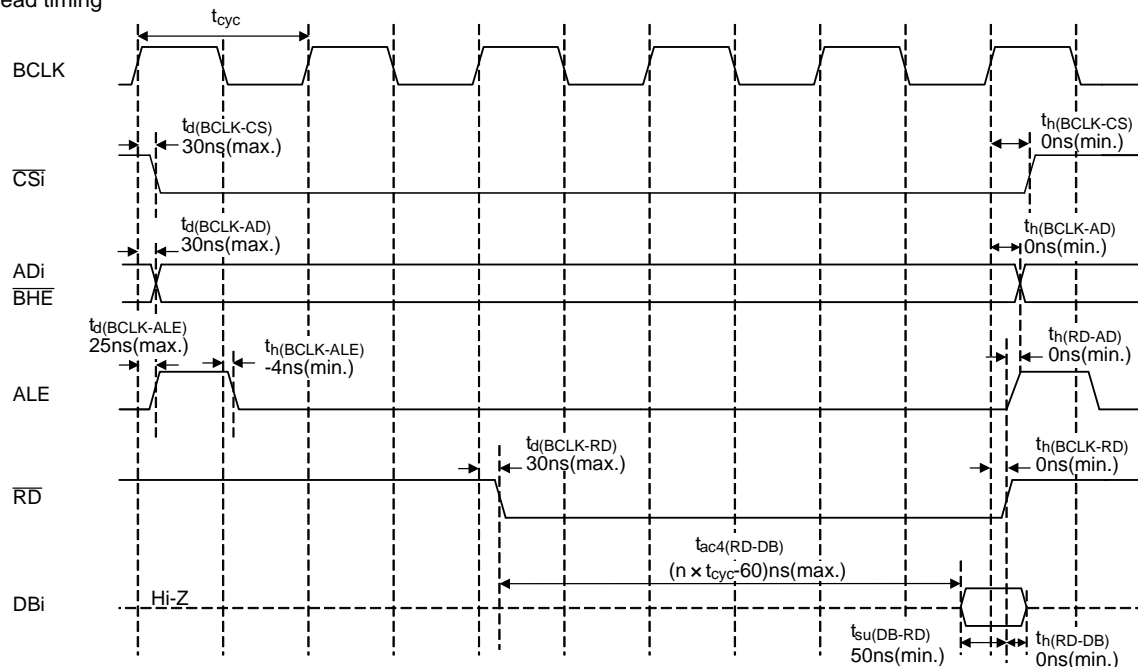
Figure 5.29 Ports P0 to P14 Measurement Circuit

## Memory Expansion Mode, Microprocessor Mode

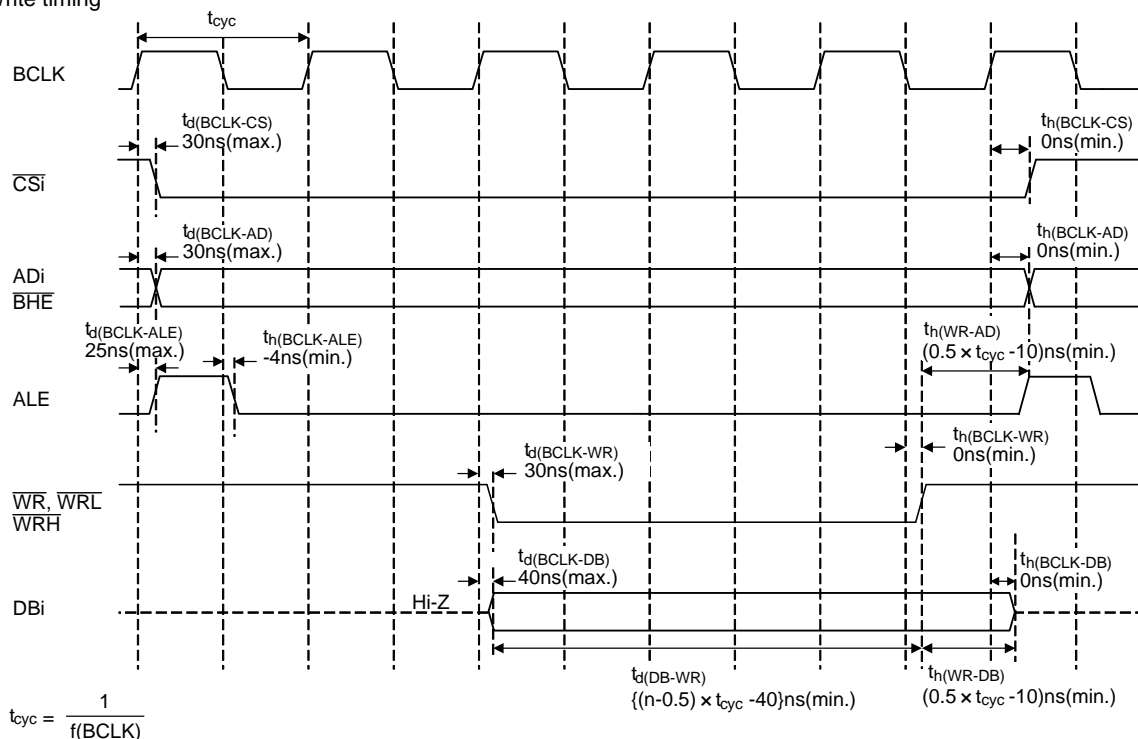
(in wait state setting  $2\phi + 3\phi$ ,  $2\phi + 4\phi$ ,  $3\phi + 4\phi$ , and  $4\phi + 5\phi$ , and when accessing external area)

$$V_{CC1} = V_{CC2} = 3V$$

## Read timing



## Write timing



## Measuring conditions

- $V_{CC1} = V_{CC2} = 3V$
- Input timing voltage:  $V_L = 0.6V$ ,  $V_H = 2.4V$
- Output timing voltage:  $V_L = 1.5V$ ,  $V_H = 1.5V$

- n: 3 (when  $2\phi + 3\phi$ )  
 4 (when  $2\phi + 4\phi$  or  $3\phi + 4\phi$ )  
 5 (when  $4\phi + 5\phi$ )

Figure 5.33 Timing Diagram

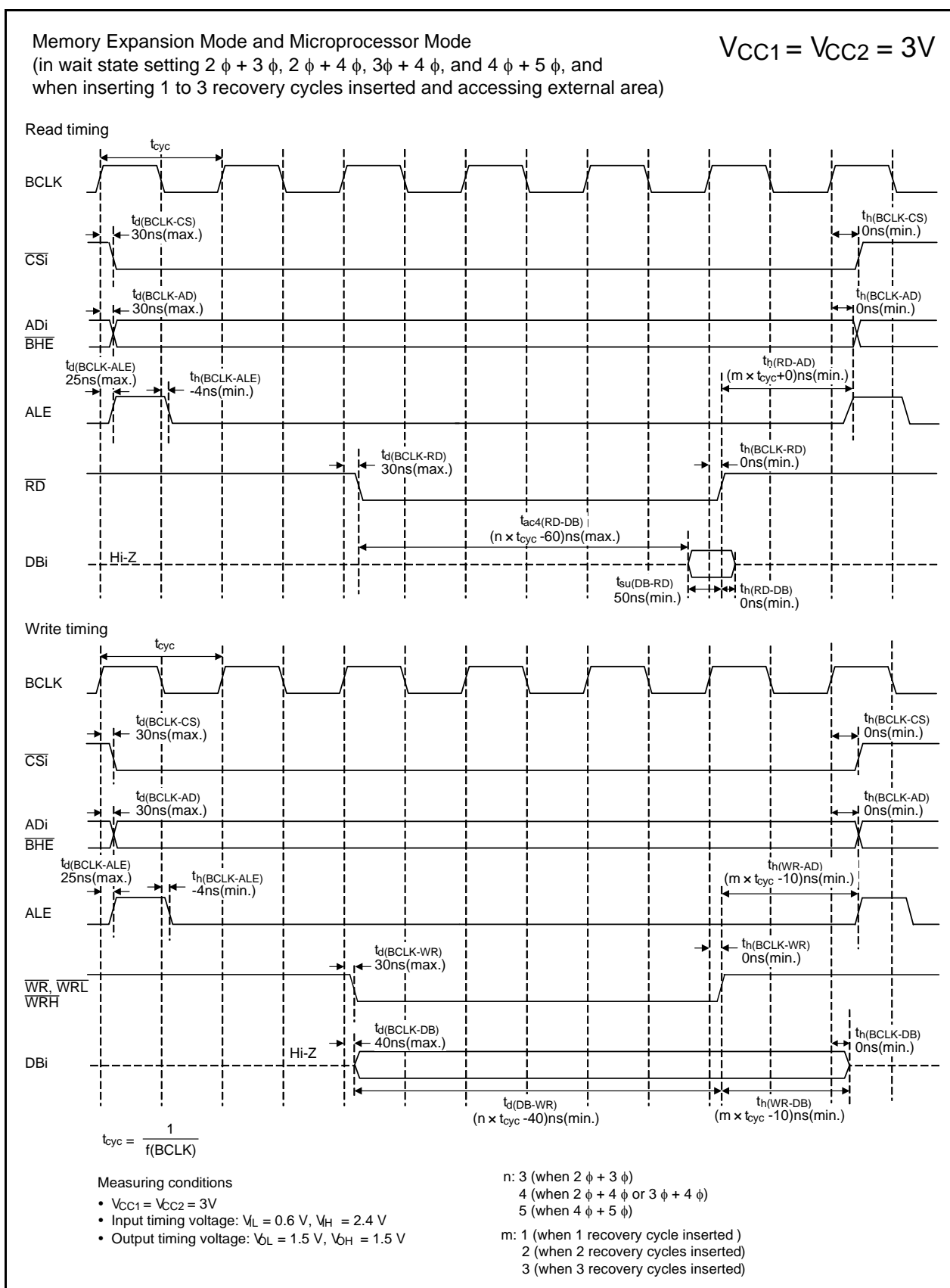


Figure 5.34 Timing Diagram

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