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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Not For New Designs
Core Processor	M16C/60
Core Size	16-Bit
Speed	32MHz
Connectivity	EBI/EMI, I ² C, SIO, UART/USART
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	85
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	8K x 8
RAM Size	31K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 26x10b; D/A 2x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LFQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f3650mdfb-30

1.3 Product List

Table 1.5 and Table 1.6 list product information. Figure 1.1 shows the Part No., with Memory Size and Package, and Figure 1.2 shows the Marking Diagram (Top View).

Table 1.5 Product List (1/2)

As of July 2012

Part No.	ROM Capacity			RAM Capacity	Package Code	Remarks
	Program ROM 1	Program ROM 2	Data flash			
R5F36506NFA	128 KB	16 KB	4 KB x 2 blocks	12 KB	PRQP0100JD-B	Operating temperature -20°C to 85°C
R5F36506NFB					PLQP0100KB-A	
R5F36506DFA					PRQP0100JD-B	Operating temperature -40°C to 85°C
R5F36506DFB					PLQP0100KB-A	
R5F3651ENFC	256 KB	16 KB	4 KB x 2 blocks	20 KB	PLQP0128KB-A	Operating temperature -20°C to 85°C
R5F3650ENFA					PRQP0100JD-B	
R5F3650ENFB					PLQP0100KB-A	Operating temperature -40°C to 85°C
R5F3651EDFC					PLQP0128KB-A	
R5F3650EDFA					PRQP0100JD-B	
R5F3650EDFB					PLQP0100KB-A	
R5F3651KNFC	384 KB	16 KB	4 KB x 2 blocks	31 KB	PLQP0128KB-A	Operating temperature -20°C to 85°C
R5F3650KNFA					PRQP0100JD-B	
R5F3650KNFB					PLQP0100KB-A	Operating temperature -40°C to 85°C
R5F3651KDFC					PLQP0128KB-A	
R5F3650KDFA					PRQP0100JD-B	
R5F3650KDFB					PLQP0100KB-A	
R5F3651MNFC	512 KB	16 KB	4 KB x 2 blocks	31 KB	PLQP0128KB-A	Operating temperature -20°C to 85°C
R5F3650MNFA					PRQP0100JD-B	
R5F3650MNFB					PLQP0100KB-A	Operating temperature -40°C to 85°C
R5F3651MDFC					PLQP0128KB-A	
R5F3650MDFA					PRQP0100JD-B	
R5F3650MDFB					PLQP0100KB-A	
R5F3651NNFC	512 KB	16 KB	4 KB x 2 blocks	47 KB	PLQP0128KB-A	Operating temperature -20°C to 85°C
R5F3650NNFA					PRQP0100JD-B	
R5F3650NNFB					PLQP0100KB-A	Operating temperature -40°C to 85°C
R5F3651NDFC					PLQP0128KB-A	
R5F3650NDFA					PRQP0100JD-B	
R5F3650NDFB					PLQP0100KB-A	
R5F3651RNFC	640 KB	16 KB	4 KB x 2 blocks	47 KB	PLQP0128KB-A	Operating temperature -20°C to 85°C
R5F3650RNFA					PRQP0100JD-B	
R5F3650RNFB					PLQP0100KB-A	Operating temperature -40°C to 85°C
R5F3651RDFA					PLQP0128KB-A	
R5F3650RDFA					PRQP0100JD-B	
R5F3650RDFB					PLQP0100KB-A	

(D): Under development

(P): Planning

Previous package codes are as follows:

PLQP0128KB-A: 128P6Q-A

PRQP0100JD-B: 100P6F-A

PLQP0100KB-A: 100P6Q-A

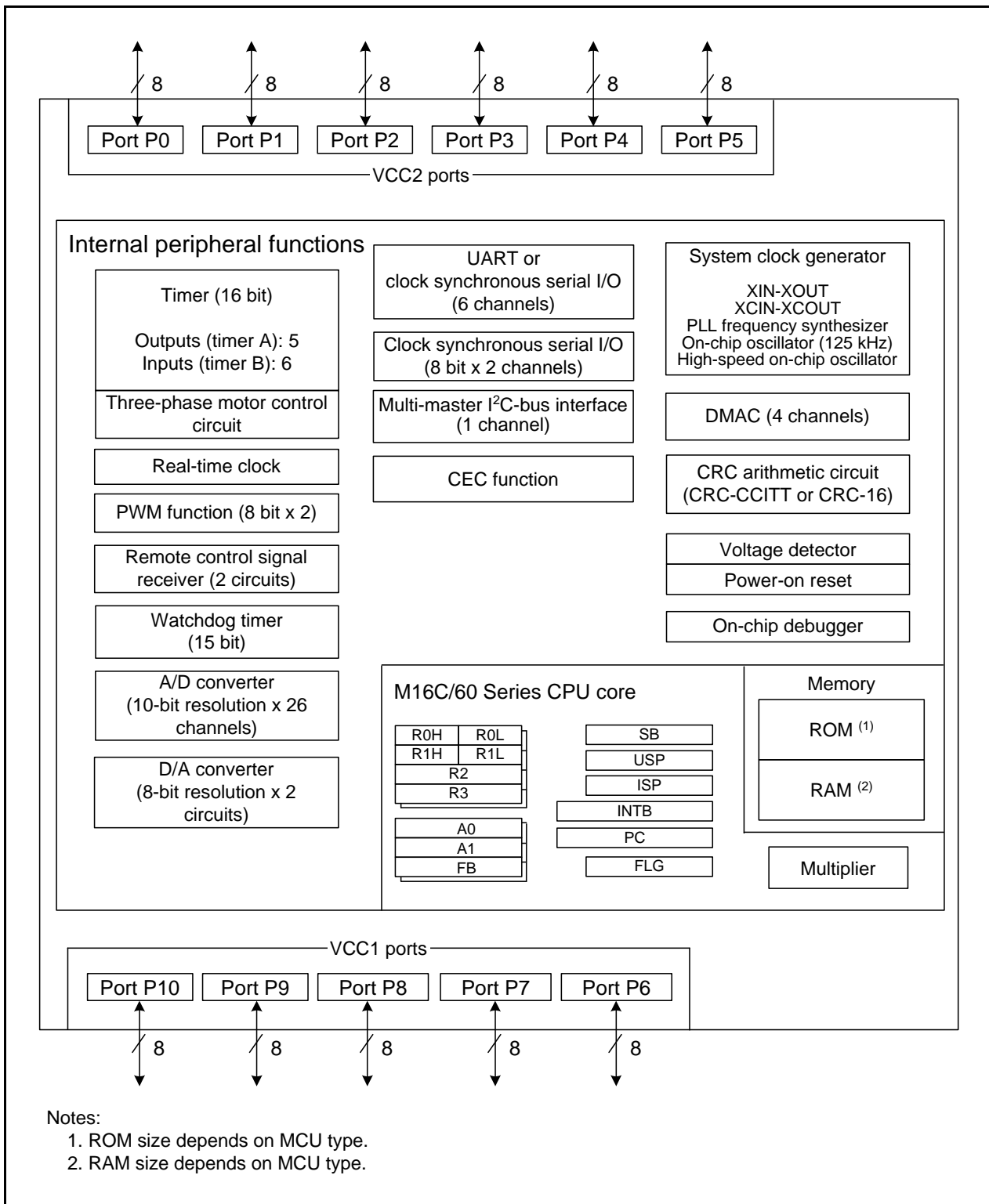


Figure 1.4 Block Diagram for the 100-Pin Package

Table 1.10 Pin Names for the 100-Pin Package (1/2)

Pin No.		Control Pin	Port	I/O Pin for Peripheral Function				Bus Control Pin
FA	FB			Interrupt	Timer	Serial interface	A/D converter, D/A converter	
1	99		P9_6			SOUT4	ANEX1	
2	100		P9_5			CLK4	ANEX0	
3	1		P9_4		TB4IN/PWM1		DA1	
4	2		P9_3		TB3IN/PWM0		DA0	
5	3		P9_2		TB2IN/PMC0	SOUT3		
6	4		P9_1		TB1IN/PMC1	SIN3		
7	5		P9_0		TB0IN	CLK3		
8	6	BYTE						
9	7	CNVSS						
10	8	XCIN	P8_7					
11	9	XCOUT	P8_6					
12	10	RESET						
13	11	XOUT						
14	12	VSS						
15	13	XIN						
16	14	VCC1						
17	15		P8_5	NMI	SD	CEC		
18	16		P8_4	INT2	ZP			
19	17		P8_3	INT1				
20	18		P8_2	INT0				
21	19		P8_1		TA4IN/U	CTS5/RTS5		
22	20		P8_0		TA4OUT/U	RXD5/SCL5		
23	21		P7_7		TA3IN	CLK5		
24	22		P7_6		TA3OUT	TXD5/SDA5		
25	23		P7_5		TA2IN/W			
26	24		P7_4		TA2OUT/W			
27	25		P7_3		TA1IN/V	CTS2/RTS2		
28	26		P7_2		TA1OUT/V	CLK2		
29	27		P7_1		TA0IN/TB5IN	RXD2/SCL2/SCLMM		
30	28		P7_0		TA0OUT	TXD2/SDA2/SDAMM		
31	29		P6_7			TXD1/SDA1		
32	30		P6_6			RXD1/SCL1		
33	31		P6_5			CLK1		
34	32		P6_4			CTS1/RTS1/CTS0/ CLKS1		
35	33		P6_3			TXD0/SDA0		
36	34		P6_2			RXD0/SCL0		
37	35		P6_1			CLK0		
38	36		P6_0		RTCOUT	CTS0/RTS0		
39	37	CLKOUT	P5_7					RDY
40	38		P5_6					ALE
41	39		P5_5					HOLD
42	40		P5_4					HLDA
43	41		P5_3					BCLK
44	42		P5_2					RD
45	43		P5_1					WRH/BHE
46	44		P5_0					WRL/WR
47	45		P4_7		PWM1	TXD7/SDA7		CS3
48	46		P4_6		PWM0	RXD7/SCL7		CS2
49	47		P4_5			CLK7		CS1
50	48		P4_4			CTS7/RTS7		CS0

1.6 Pin Functions

Table 1.12 Pin Functions for the 128-Pin Package (1/3)

Signal Name	Pin Name	I/O	Power Supply	Description
Power supply input	VCC1, VCC2, VSS	I	-	Apply 2.7 to 5.5 V to pins VCC1 and VCC2 ($VCC1 \geq VCC2$), and 0 V to the VSS pin.
Analog power supply input	AVCC, AVSS	I	VCC1	This is the power supply for the A/D and D/A converters. Connect the AVCC pin to VCC1, and connect the AVSS pin to VSS.
Reset input	$\overline{\text{RESET}}$	I	VCC1	Driving this pin low resets the MCU.
CNVSS	CNVSS	I	VCC1	Input pin to switch processor modes. After a reset, to start operating in single-chip mode, connect the CNVSS pin to VSS via a resistor. To start operating in microprocessor mode, connect the pin to VCC1.
External data bus width select input	BYTE	I	VCC1	Input pin to select the data bus of the external area. The data bus is 16 bits when it is low and 8 bits when it is high. This pin must be fixed either high or low. Connect the BYTE pin to VSS in single-chip mode.
Bus control pins	D0 to D7	I/O	VCC2	Inputs or outputs data (D0 to D7) while accessing an external area with a separate bus.
	D8 to D15	I/O	VCC2	Inputs or outputs data (D8 to D15) while accessing an external area with a 16-bit separate bus.
	A0 to A19	O	VCC2	Outputs address bits A0 to A19.
	A0/D0 to A7/D7	I/O	VCC2	Inputs or outputs data (D0 to D7) and outputs address bits (A0 to A7) by timesharing, while accessing an external area with an 8-bit multiplexed bus.
	A1/D0 to A8/D7	I/O	VCC2	Inputs or outputs data (D0 to D7) and outputs address bits (A1 to A8) by timesharing, while accessing an external area with a 16-bit multiplexed bus.
	$\overline{\text{CS0}}$ to $\overline{\text{CS3}}$	O	VCC2	Outputs chip-select signals $\overline{\text{CS0}}$ to $\overline{\text{CS3}}$ to specify an external area.
	$\overline{\text{WRL}}/\overline{\text{WRH}}$ $\overline{\text{WRH}}/\overline{\text{BHE}}$ $\overline{\text{RD}}$	O	VCC2	Outputs $\overline{\text{WRL}}$, $\overline{\text{WRH}}$, ($\overline{\text{WR}}$, $\overline{\text{BHE}}$), and $\overline{\text{RD}}$ signals. $\overline{\text{WRL}}$ and $\overline{\text{WRH}}$ can be switched with $\overline{\text{BHE}}$ and $\overline{\text{WR}}$. <ul style="list-style-type: none"> • $\overline{\text{WRL}}$, $\overline{\text{WRH}}$, and $\overline{\text{RD}}$ selected If the external data bus is 16 bits, data is written to an even address in an external area when $\overline{\text{WRL}}$ is driven low. Data is written to an odd address when $\overline{\text{WRH}}$ is driven low. Data is read when $\overline{\text{RD}}$ is driven low. • $\overline{\text{WR}}$, $\overline{\text{BHE}}$, and $\overline{\text{RD}}$ selected Data is written to an external area when $\overline{\text{WR}}$ is driven low. Data in an external area is read when $\overline{\text{RD}}$ is driven low. An odd address is accessed when $\overline{\text{BHE}}$ is driven low. Select $\overline{\text{WR}}$, $\overline{\text{BHE}}$, and $\overline{\text{RD}}$ when using an 8-bit external data bus.
	ALE	O	VCC2	Outputs an ALE signal to latch the address.
	$\overline{\text{HOLD}}$	I	VCC2	$\overline{\text{HOLD}}$ input is unavailable. Connect the $\overline{\text{HOLD}}$ pin to VCC2 via a resistor (pull-up).
	$\overline{\text{HLDA}}$	O	VCC2	In a hold state, $\overline{\text{HLDA}}$ outputs a low-level signal.
	$\overline{\text{RDY}}$	I	VCC2	The MCU bus is placed in wait state while the $\overline{\text{RDY}}$ pin is driven low.

Power supply: VCC2 is used to supply power to the external bus associated pins. The dual power supply configuration allows VCC2 to interface at a different voltage than VCC1.

3.3 Accessible Area in Each Mode

Areas that can be accessed vary depending on processor mode and the status of each control bit. Figure 3.3 shows the Accessible Area in Each Mode.

In single-chip mode, the SFRs, internal RAM, and internal ROM can be accessed.

In memory expansion mode, the SFRs, internal RAM, internal ROM, and external areas can be accessed. Address space is expandable to 4 MB with the memory area expansion function.

In microprocessor mode, the SFRs, internal RAM, and external areas can be accessed. Address space is expandable to 4 MB with the memory area expansion function. Allocate ROM to the fixed vector table from FFFDCh to FFFFFh.

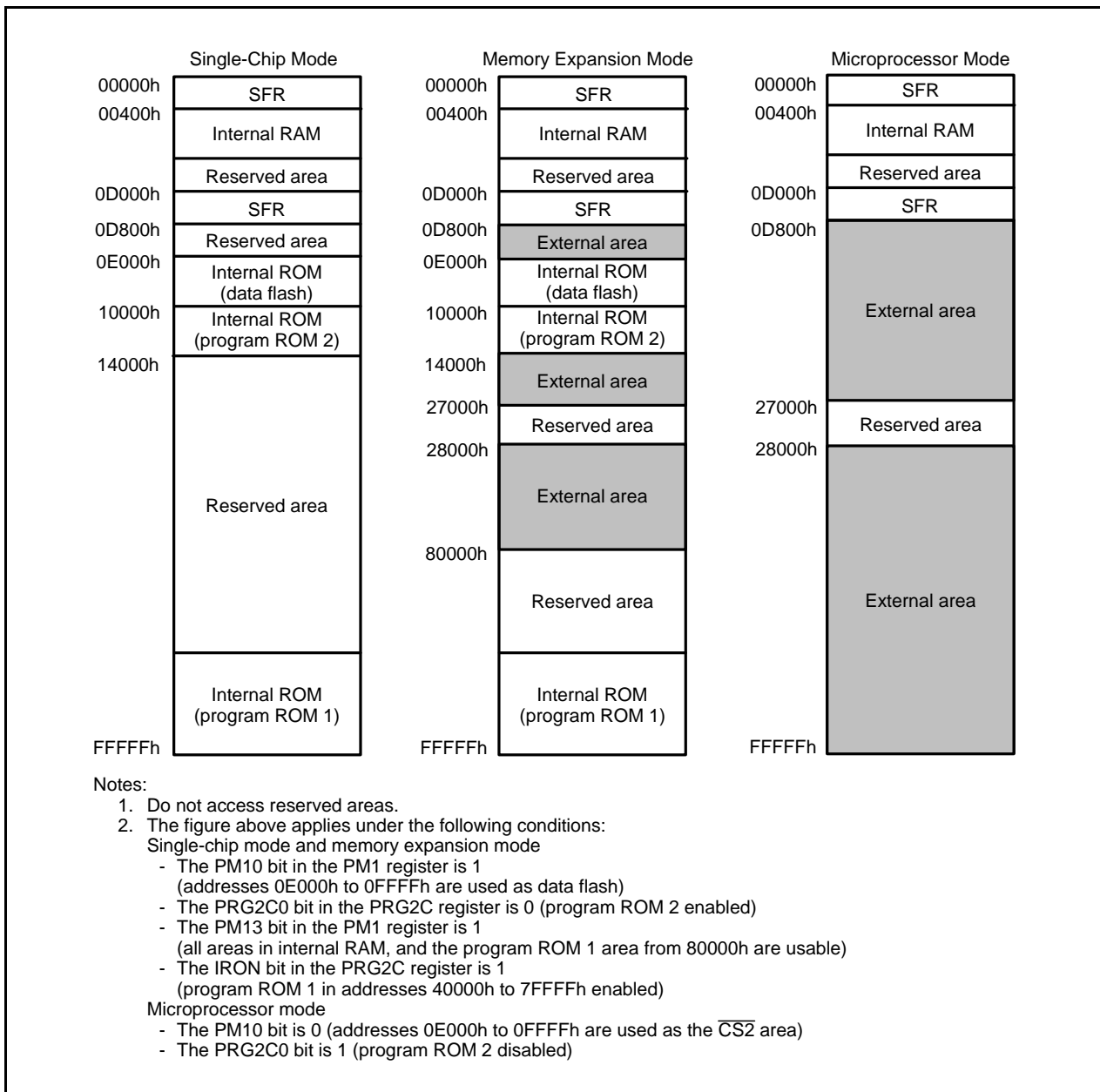


Figure 3.3 Accessible Area in Each Mode

Table 4.9 SFR Information (9) ⁽¹⁾

Address	Register	Symbol	Reset Value
0240h			
0241h			
0242h			
0243h			
0244h	UART0 Special Mode Register 4	U0SMR4	00h
0245h	UART0 Special Mode Register 3	U0SMR3	000X 0X0Xb
0246h	UART0 Special Mode Register 2	U0SMR2	X000 0000b
0247h	UART0 Special Mode Register	U0SMR	X000 0000b
0248h	UART0 Transmit/Receive Mode Register	U0MR	00h
0249h	UART0 Bit Rate Register	U0BRG	XXh
024Ah	UART0 Transmit Buffer Register	U0TB	XXh
024Bh			XXh
024Ch	UART0 Transmit/Receive Control Register 0	U0C0	0000 1000b
024Dh	UART0 Transmit/Receive Control Register 1	U0C1	00XX 0010b
024Eh	UART0 Receive Buffer Register	U0RB	XXh
024Fh			XXh
0250h	UART Transmit/Receive Control Register 2	U0CON	X000 0000b
0251h			
0252h	UART Clock Select Register	UCLKSELO	X0h
0253h			
0254h	UART1 Special Mode Register 4	U1SMR4	00h
0255h	UART1 Special Mode Register 3	U1SMR3	000X 0X0Xb
0256h	UART1 Special Mode Register 2	U1SMR2	X000 0000b
0257h	UART1 Special Mode Register	U1SMR	X000 0000b
0258h	UART1 Transmit/Receive Mode Register	U1MR	00h
0259h	UART1 Bit Rate Register	U1BRG	XXh
025Ah	UART1 Transmit Buffer Register	U1TB	XXh
025Bh			XXh
025Ch	UART1 Transmit/Receive Control Register 0	U1C0	0000 1000b
025Dh	UART1 Transmit/Receive Control Register 1	U1C1	00XX 0010b
025Eh	UART1 Receive Buffer Register	U1RB	XXh
025Fh			XXh
0260h			
0261h			
0262h			
0263h			
0264h	UART2 Special Mode Register 4	U2SMR4	00h
0265h	UART2 Special Mode Register 3	U2SMR3	000X 0X0Xb
0266h	UART2 Special Mode Register 2	U2SMR2	X000 0000b
0267h	UART2 Special Mode Register	U2SMR	X000 0000b
0268h	UART2 Transmit/Receive Mode Register	U2MR	00h
0269h	UART2 Bit Rate Register	U2BRG	XXh
026Ah	UART2 Transmit Buffer Register	U2TB	XXh
026Bh			XXh
026Ch	UART2 Transmit/Receive Control Register 0	U2C0	0000 1000b
026Dh	UART2 Transmit/Receive Control Register 1	U2C1	0000 0010b
026Eh	UART2 Receive Buffer Register	U2RB	XXh
026Fh			XXh

X: Undefined

Note:

1. The blank areas are reserved. No access is allowed.

Table 4.12 SFR Information (12) ⁽¹⁾

Address	Register	Symbol	Reset Value
0300h	Timer B3/B4/B5 Count Start Flag	TBSR	000X XXXXb
0301h			
0302h	Timer A1-1 Register	TA11	XXh
0303h			XXh
0304h	Timer A2-1 Register	TA21	XXh
0305h			XXh
0306h	Timer A4-1 Register	TA41	XXh
0307h			XXh
0308h	Three-Phase PWM Control Register 0	INVC0	00h
0309h	Three-Phase PWM Control Register 1	INVC1	00h
030Ah	Three-Phase Output Buffer Register 0	IDB0	XX11 1111b
030Bh	Three-Phase Output Buffer Register 1	IDB1	XX11 1111b
030Ch	Dead Time Timer	DTT	XXh
030Dh	Timer B2 Interrupt Generation Frequency Set Counter	ICTB2	XXh
030Eh	Position-Data-Retain Function Control Register	PDRF	XXXX 0000b
030Fh			
0310h	Timer B3 Register	TB3	XXh
0311h			XXh
0312h	Timer B4 Register	TB4	XXh
0313h			XXh
0314h	Timer B5 Register	TB5	XXh
0315h			XXh
0316h			
0317h			
0318h	Port Function Control Register	PFCR	0011 1111b
0319h			
031Ah			
031Bh	Timer B3 Mode Register	TB3MR	00XX 0000b
031Ch	Timer B4 Mode Register	TB4MR	00XX 0000b
031Dh	Timer B5 Mode Register	TB5MR	00XX 0000b
031Eh			
031Fh			
0320h	Count Start Flag	TABSR	00h
0321h			
0322h	One-Shot Start Flag	ONSF	00h
0323h	Trigger Select Register	TRGSR	00h
0324h	Increment/Decrement Flag	UDF	00h
0325h			
0326h	Timer A0 Register	TA0	XXh
0327h			XXh
0328h	Timer A1 Register	TA1	XXh
0329h			XXh
032Ah	Timer A2 Register	TA2	XXh
032Bh			XXh
032Ch	Timer A3 Register	TA3	XXh
032Dh			XXh
032Eh	Timer A4 Register	TA4	XXh
032Fh			XXh

X: Undefined

Note:

1. The blank areas are reserved. No access is allowed.

Table 5.4 Recommended Operating Conditions (3/3) (1)

$V_{CC1} = 2.7$ to 5.5 V, $V_{SS} = 0$ V, and $T_{opr} = -20^{\circ}\text{C}$ to $85^{\circ}\text{C}/-40^{\circ}\text{C}$ to 85°C unless otherwise specified.

The ripple voltage must not exceed $V_{r(VCC1)}$ and/or $dV_{r(VCC1)}/dt$.

Symbol	Parameter	Standard			Unit
		Min.	Typ.	Max.	
$V_{r(VCC1)}$	Allowable ripple voltage	$V_{CC1} = 5.0$ V		0.5	Vp-p
		$V_{CC1} = 3.0$ V		0.3	Vp-p
$dV_{r(VCC1)}/dt$	Ripple voltage falling gradient	$V_{CC1} = 5.0$ V		0.3	V/ms
		$V_{CC1} = 3.0$ V		0.3	V/ms

Note:

- The device is operationally guaranteed under these operating conditions.

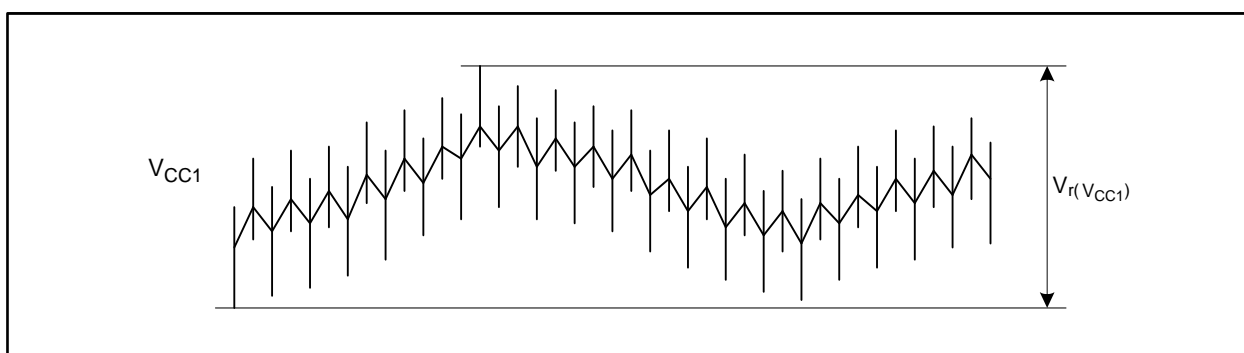


Figure 5.1 Ripple Waveform

5.2 Electrical Characteristics ($V_{CC1} = V_{CC2} = 5\text{ V}$)

5.2.1 Electrical Characteristics

$$V_{CC1} = V_{CC2} = 5\text{ V}$$

Table 5.19 Electrical Characteristics (1) (1)

$V_{CC1} = V_{CC2} = 4.2$ to 5.5 V , $V_{SS} = 0\text{ V}$ at $T_{opr} = -20^{\circ}\text{C}$ to $85^{\circ}\text{C}/-40^{\circ}\text{C}$ to 85°C , $f_{(BCLK)} = 32\text{ MHz}$ unless otherwise specified.

Symbol	Parameter		Measuring Condition	Standard			Unit	
				Min.	Typ.	Max.		
V_{OH}	High output voltage	P6_0 to P6_7, P7_2 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P14_0, P14_1	$I_{OH} = -5\text{ mA}$	$V_{CC1} - 2.0$		V_{CC1}	V	
		P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P12_0 to P12_7, P13_0 to P13_7	$I_{OH} = -5\text{ mA}$	$V_{CC2} - 2.0$		V_{CC2}		
V_{OH}	High output voltage	P6_0 to P6_7, P7_2 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P14_0, P14_1	$I_{OH} = -200\text{ }\mu\text{A}$	$V_{CC1} - 0.3$		V_{CC1}	V	
		P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P12_0 to P12_7, P13_0 to P13_7	$I_{OH} = -200\text{ }\mu\text{A}$	$V_{CC2} - 0.3$		V_{CC2}		
V_{OH}	High output voltage	XOUT	HIGH POWER	$I_{OH} = -1\text{ mA}$	$V_{CC1} - 2.0$		V_{CC1}	V
			LOW POWER	$I_{OH} = -0.5\text{ mA}$	$V_{CC1} - 2.0$		V_{CC1}	
	High output voltage	XCOUT	HIGH POWER	With no load applied		2.6		V
			LOW POWER	With no load applied		2.2		
V_{OL}	Low output voltage	P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P14_0, P14_1	$I_{OL} = 5\text{ mA}$			2.0	V	
		P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P12_0 to P12_7, P13_0 to P13_7	$I_{OL} = 5\text{ mA}$			2.0		
V_{OL}	Low output voltage	P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P14_0, P14_1	$I_{OL} = 200\text{ }\mu\text{A}$			0.45	V	
		P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P12_0 to P12_7, P13_0 to P13_7	$I_{OL} = 200\text{ }\mu\text{A}$			0.45		
V_{OL}	Low output voltage	XOUT	HIGH POWER	$I_{OL} = 1\text{ mA}$			2.0	V
			LOW POWER	$I_{OL} = 0.5\text{ mA}$			2.0	
	Low output voltage	XCOUT	HIGH POWER	With no load applied		0		V
			LOW POWER	With no load applied		0		

Note:

- When $V_{CC1} \neq V_{CC2}$, refer to 5 V or 3 V standard depending on the voltage.

$$V_{CC1} = V_{CC2} = 5 V$$

Timing Requirements

($V_{CC1} = V_{CC2} = 5 V$, $V_{SS} = 0 V$, at $T_{opr} = -20^{\circ}C$ to $85^{\circ}C$ / $-40^{\circ}C$ to $85^{\circ}C$ unless otherwise specified)

5.2.2.3 Timer A Input

Table 5.26 Timer A Input (Counter Input in Event Counter Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiIN input cycle time	100		ns
$t_{w(TAH)}$	TAiIN input high pulse width	40		ns
$t_{w(TAL)}$	TAiIN input low pulse width	40		ns

Table 5.27 Timer A Input (Gating Input in Timer Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiIN input cycle time	400		ns
$t_{w(TAH)}$	TAiIN input high pulse width	200		ns
$t_{w(TAL)}$	TAiIN input low pulse width	200		ns

Table 5.28 Timer A Input (External Trigger Input in One-Shot Timer Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiIN input cycle time	200		ns
$t_{w(TAH)}$	TAiIN input high pulse width	100		ns
$t_{w(TAL)}$	TAiIN input low pulse width	100		ns

Table 5.29 Timer A Input (External Trigger Input in Pulse Width Modulation Mode and Programmable Output Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{w(TAH)}$	TAiIN input high pulse width	100		ns
$t_{w(TAL)}$	TAiIN input low pulse width	100		ns

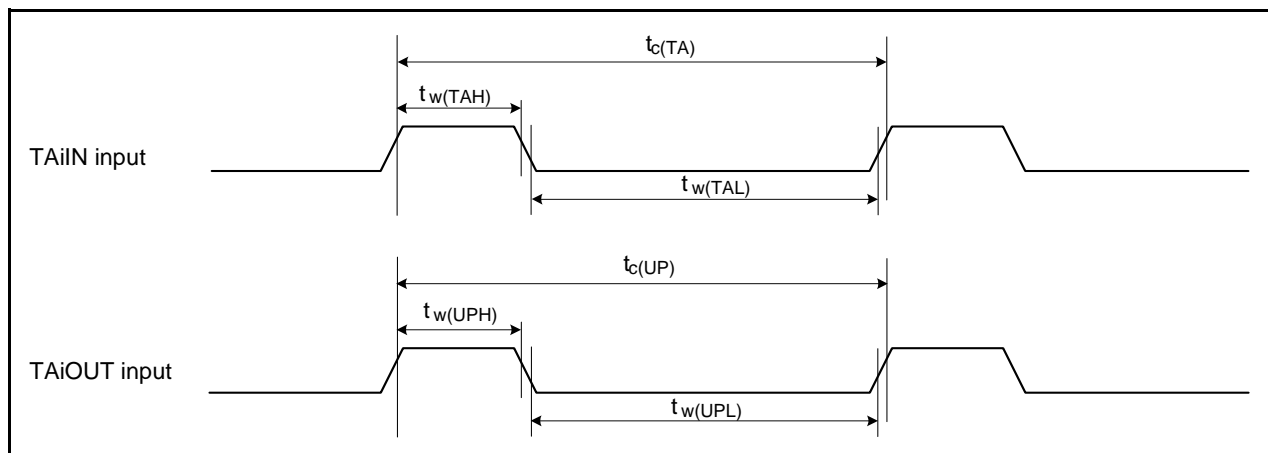


Figure 5.7 Timer A Input

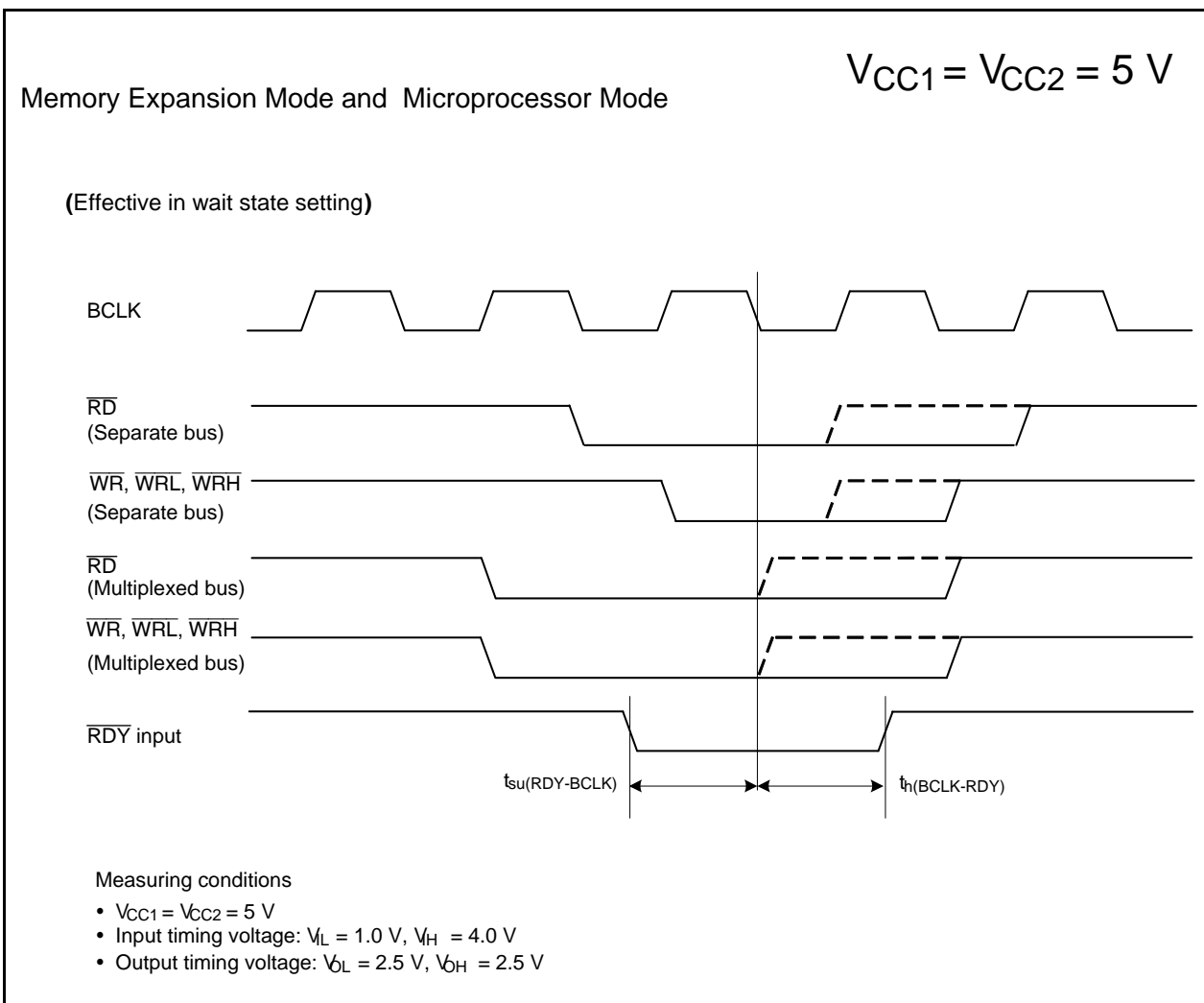


Figure 5.13 Timing Diagram

$$V_{CC1} = V_{CC2} = 5 \text{ V}$$

Switching Characteristics

($V_{CC1} = V_{CC2} = 5 \text{ V}$, $V_{SS} = 0 \text{ V}$, at $T_{opr} = -20^\circ\text{C}$ to $85^\circ\text{C}/-40^\circ\text{C}$ to 85°C unless otherwise specified)

5.2.4.2 In 1 to 3 Waits Setting and When Accessing External Area

Table 5.39 Memory Expansion Mode and Microprocessor Mode (in 1 to 3 Waits Setting and When Accessing External Area)

Symbol	Parameter	Measuring Condition	Standard		Unit
			Min.	Max.	
$t_{d(BCLK-AD)}$	Address output delay time	See Figure 5.14		25	ns
$t_{h(BCLK-AD)}$	Address output hold time (in relation to BCLK)		0		ns
$t_{h(RD-AD)}$	Address output hold time (in relation to RD)		0		ns
$t_{h(WR-AD)}$	Address output hold time (in relation to WR)		(Note 2)		ns
$t_{d(BCLK-CS)}$	Chip select output delay time			25	ns
$t_{h(BCLK-CS)}$	Chip select output hold time (in relation to BCLK)		0		ns
$t_{d(BCLK-ALE)}$	ALE signal output delay time			15	ns
$t_{h(BCLK-ALE)}$	ALE signal output hold time		-4		ns
$t_{d(BCLK-RD)}$	RD signal output delay time			25	ns
$t_{h(BCLK-RD)}$	RD signal output hold time		0		ns
$t_{d(BCLK-WR)}$	WR signal output delay time			25	ns
$t_{h(BCLK-WR)}$	WR signal output hold time		0		ns
$t_{d(BCLK-DB)}$	Data output delay time (in relation to BCLK)			40	ns
$t_{h(BCLK-DB)}$	Data output hold time (in relation to BCLK) ⁽³⁾		0		ns
$t_{d(DB-WR)}$	Data output delay time (in relation to WR)		(Note 1)		ns
$t_{h(WR-DB)}$	Data output hold time (in relation to WR) ⁽³⁾		(Note 2)		ns

Notes:

1. Calculated according to the BCLK frequency as follows:

$$\frac{(n-0.5) \times 10^9}{f_{(BCLK)}} - 40 [ns] \quad \begin{array}{l} n \text{ is 1 for 1 wait setting, 2 for 2 waits setting and 3 for 3 waits setting.} \\ \text{When } n = 1, f_{(BCLK)} \text{ is 12.5 MHz or less.} \end{array}$$

2. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f_{(BCLK)}} - 10 [ns]$$

3. This standard value shows the timing when the output is off, and does not show hold time of data bus. Hold time of data bus varies with capacitor volume and pull-up (pull-down) resistance value.

Hold time of data bus is expressed in

$$t = -CR \times \ln(1 - V_{OL}/V_{CC2})$$

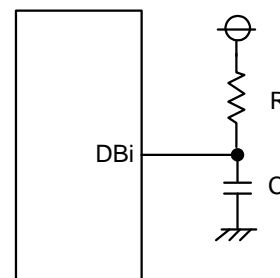
by a circuit of the right figure.

For example, when $V_{OL} = 0.2V_{CC2}$, $C = 30 \text{ pF}$, $R = 1 \text{ k}\Omega$, hold

time of output low level is

$$t = -30 \text{ pF} \times 1 \text{ k}\Omega \times \ln(1 - 0.2V_{CC2}/V_{CC2})$$

$$= 6.7 \text{ ns.}$$



5.3 Electrical Characteristics ($V_{CC1} = V_{CC2} = 3\text{ V}$)

5.3.1 Electrical Characteristics

 $V_{CC1} = V_{CC2} = 3\text{ V}$
Table 5.43 Electrical Characteristics (1) (1)
 $V_{CC1} = V_{CC2} = 2.7\text{ to }3.3\text{ V}$, $V_{SS} = 0\text{ V}$ at $T_{opr} = -20^\circ\text{C to }85^\circ\text{C}/-40^\circ\text{C to }85^\circ\text{C}$, $f_{(BCLK)} = 32\text{ MHz}$ unless otherwise specified.

Symbol	Parameter		Measuring Condition	Standard			Unit
				Min.	Typ.	Max.	
V_{OH}	High output voltage	P6_0 to P6_7, P7_2 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P14_0, P14_1	$I_{OH} = -1\text{ mA}$	$V_{CC1} - 0.5$		V_{CC1}	V
		P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P12_0 to P12_7, P13_0 to P13_7	$I_{OH} = -1\text{ mA}$	$V_{CC2} - 0.5$		V_{CC2}	
V_{OH}	High output voltage XOUT	HIGH POWER	$I_{OH} = -0.1\text{ mA}$	$V_{CC1} - 0.5$		V_{CC1}	V
		LOW POWER	$I_{OH} = -50\text{ }\mu\text{A}$	$V_{CC1} - 0.5$		V_{CC1}	
	High output voltage XCOUT	HIGH POWER	With no load applied		2.6		V
		LOW POWER	With no load applied		2.2		
V_{OL}	Low output voltage	P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P14_0, P14_1	$I_{OL} = 1\text{ mA}$			0.5	V
		P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P12_0 to P12_7, P13_0 to P13_7	$I_{OL} = 1\text{ mA}$			0.5	
		CEC	$I_{OL} = 1\text{ mA}$		0	0.5	V
V_{OL}	Low output voltage XOUT	HIGH POWER	$I_{OL} = 0.1\text{ mA}$			0.5	V
		LOW POWER	$I_{OL} = 50\text{ }\mu\text{A}$			0.5	
	Low output voltage XCOUT	HIGH POWER	With no load applied		0		V
		LOW POWER	With no load applied		0		
$V_{T+}-V_{T-}$	Hysteresis	HOLD, RDY, TA0IN to TA4IN, TB0IN to TB5IN, INT0 to INT7, NMI, ADTRG, CTS0 to CTS2, CTS5 to CTS7, SCL0 to SCL2, SCL5 to SCL7, SDA0 to SDA2, SDA5 to SDA7, CLK0 to CLK7, TA0OUT to TA4OUT, K10 to K13, RXD0 to RXD2, RXD5 to RXD7, SIN3, SIN4, SD, PMC0, PMC1, SCLMM, SDAMM, ZP, IDU, IDV, IDW		0.2		1.0	V
		CEC		0.2	0.5	1.0	
		RESET		0.2		1.8	
I_{IH}	High input current	P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P12_0 to P12_7, P13_0 to P13_7, P14_0, P14_1 XIN, RESET, CNVSS, BYTE	$V_I = 3\text{ V}$			4.0	μA
–	Leakage current in powered-off state CEC		$V_{CC1} = 0\text{ V}$			1.8	μA
I_{IL}	Low input current	P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P12_0 to P12_7, P13_0 to P13_7, P14_0, P14_1 XIN, RESET, CNVSS, BYTE	$V_I = 0\text{ V}$			-4.0	μA
R_{PULLUP}	Pull-up resistance	P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_2 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7, P11_0 to P11_7, P12_0 to P12_7, P13_0 to P13_7, P14_0, P14_1	$V_I = 0\text{ V}$	50	80	150	$\text{k}\Omega$
R_{FXIN}	Feedback resistance XIN				3.0		$\text{M}\Omega$
V_{RAM}	RAM retention voltage		In stop mode	1.8			V

Note:

- When $V_{CC1} \neq V_{CC2}$, refer to 5 V or 3 V standard depending on the voltage.

$$V_{CC1} = V_{CC2} = 3 \text{ V}$$

Timing Requirements

($V_{CC1} = V_{CC2} = 3 \text{ V}$, $V_{SS} = 0 \text{ V}$, at $T_{opr} = -20^\circ\text{C}$ to $85^\circ\text{C}/-40^\circ\text{C}$ to 85°C unless otherwise specified)

5.3.2.4 Timer B Input

Table 5.54 Timer B Input (Counter Input in Event Counter Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN input cycle time (counted on one edge)	150		ns
$t_{w(TBH)}$	TBiIN input high pulse width (counted on one edge)	60		ns
$t_{w(TBL)}$	TBiIN input low pulse width (counted on one edge)	60		ns
$t_{c(TB)}$	TBiIN input cycle time (counted on both edges)	300		ns
$t_{w(TBH)}$	TBiIN input high pulse width (counted on both edges)	120		ns
$t_{w(TBL)}$	TBiIN input low pulse width (counted on both edges)	120		ns

Table 5.55 Timer B Input (Pulse Period Measurement Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN input cycle time	600		ns
$t_{w(TBH)}$	TBiIN input high pulse width	300		ns
$t_{w(TBL)}$	TBiIN input low pulse width	300		ns

Table 5.56 Timer B Input (Pulse Width Measurement Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN input cycle time	600		ns
$t_{w(TBH)}$	TBiIN input high pulse width	300		ns
$t_{w(TBL)}$	TBiIN input low pulse width	300		ns

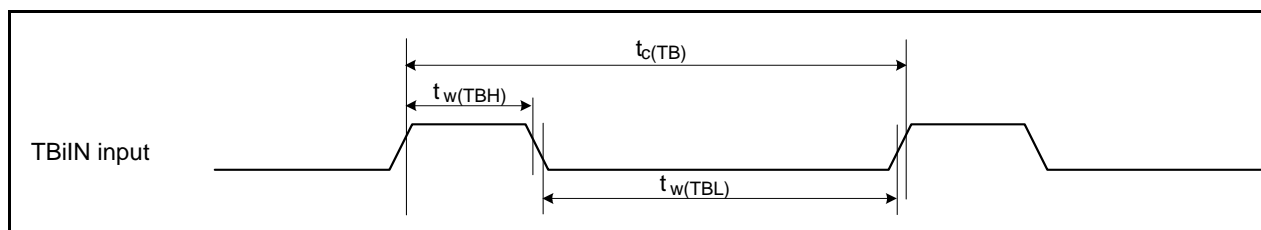


Figure 5.24 Timer B Input

$$V_{CC1} = V_{CC2} = 3\text{ V}$$

Timing Requirements

($V_{CC1} = V_{CC2} = 3\text{ V}$, $V_{SS} = 0\text{ V}$, at $T_{opr} = -20^{\circ}\text{C}$ to $85^{\circ}\text{C}/-40^{\circ}\text{C}$ to 85°C unless otherwise specified)

5.3.2.5 Serial Interface

Table 5.57 Serial Interface

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_c(\text{CK})$	CLKi input cycle time	300		ns
$t_w(\text{CKH})$	CLKi input high pulse width	150		ns
$t_w(\text{CKL})$	CLKi input low pulse width	150		ns
$t_d(\text{C-Q})$	TXDi output delay time		160	ns
$t_h(\text{C-Q})$	TXDi hold time	0		ns
$t_{su}(\text{D-C})$	RXDi input setup time	100		ns
$t_h(\text{C-D})$	RXDi input hold time	90		ns

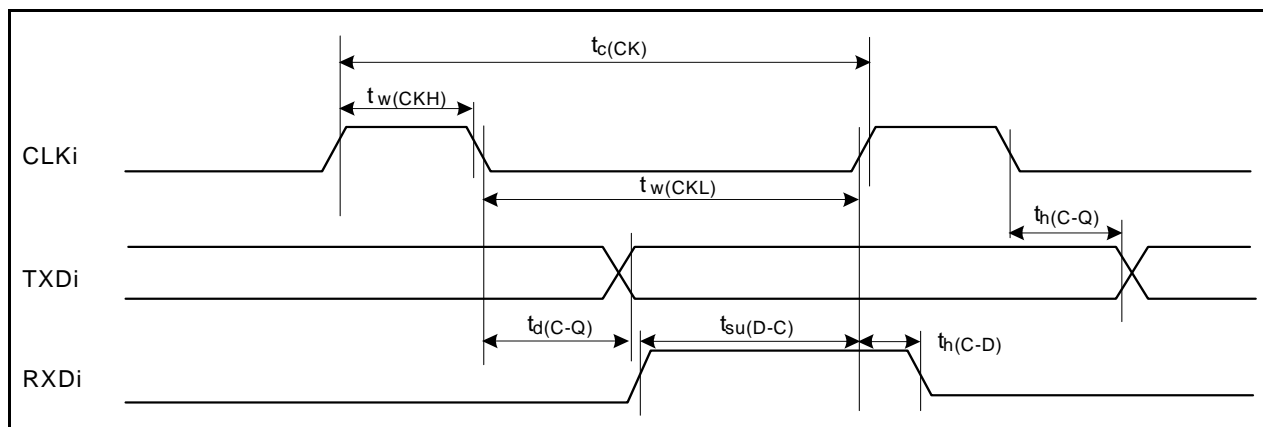


Figure 5.25 Serial Interface

5.3.2.6 External Interrupt $\overline{\text{INTi}}$ Input

Table 5.58 External Interrupt $\overline{\text{INTi}}$ Input

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_w(\text{INH})$	INTi input high pulse width	380		ns
$t_w(\text{INL})$	$\overline{\text{INTi}}$ input low pulse width	380		ns

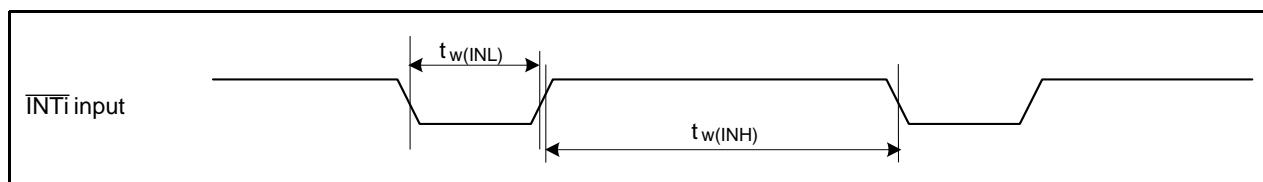


Figure 5.26 External Interrupt $\overline{\text{INTi}}$ Input

$$V_{CC1} = V_{CC2} = 3 V$$

Timing Requirements

($V_{CC1} = V_{CC2} = 3 V$, $V_{SS} = 0 V$, at $T_{opr} = -20^{\circ}C$ to $85^{\circ}C$ / $-40^{\circ}C$ to $85^{\circ}C$ unless otherwise specified)

5.3.3 Timing Requirements (Memory Expansion Mode and Microprocessor Mode)

Table 5.60 Memory Expansion Mode and Microprocessor Mode

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{ac1(RD-DB)}$	Data input access time (for setting with no wait)		(Note 1)	ns
$t_{ac2(RD-DB)}$	Data input access time (for setting with wait)		(Note 2)	ns
$t_{ac3(RD-DB)}$	Data input access time (when accessing multiplex bus area)		(Note 3)	ns
$t_{ac4(RD-DB)}$	Data input access time (for setting with 2 ϕ + 3 ϕ or more)		(Note 4)	ns
$t_{su(DB-RD)}$	Data input setup time	50		ns
$t_{su(RDY-BCLK)}$	\overline{RDY} input setup time	85		ns
$t_h(RD-DB)$	Data input hold time	0		ns
$t_h(BCLK-RDY)$	\overline{RDY} input hold time	0		ns

Notes:

1. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f_{(BCLK)}} - 60 [ns]$$

2. Calculated according to the BCLK frequency as follows:

$$\frac{(n + 0.5) \times 10^9}{f_{(BCLK)}} - 60 [ns] \quad n \text{ is 1 for 1 wait setting, 2 for 2 waits setting and 3 for 3 waits setting.}$$

3. Calculated according to the BCLK frequency as follows:

$$\frac{(n - 0.5) \times 10^9}{f_{(BCLK)}} - 60 [ns] \quad n \text{ is 2 for 2 waits setting, 3 for 3 waits setting.}$$

4. Calculated according to the BCLK frequency as follows:

$$\frac{n \times 10^9}{f_{(BCLK)}} - 60 [ns] \quad n \text{ is 3 for } 2\phi + 3\phi, 4 \text{ for } 2\phi + 4\phi, 4 \text{ for } 3\phi + 4\phi, 5 \text{ for } 4\phi + 5\phi, .$$

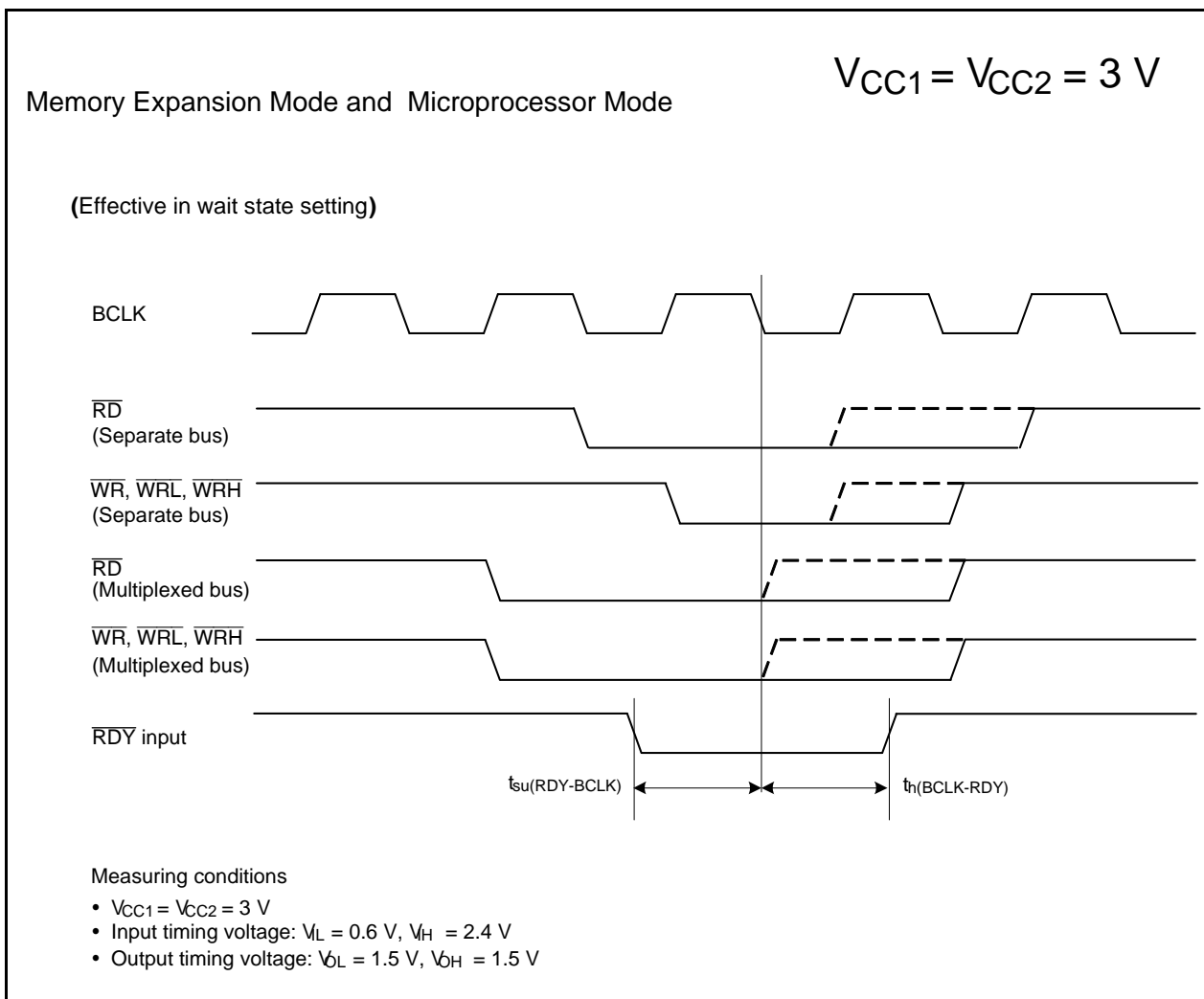


Figure 5.28 Timing Diagram

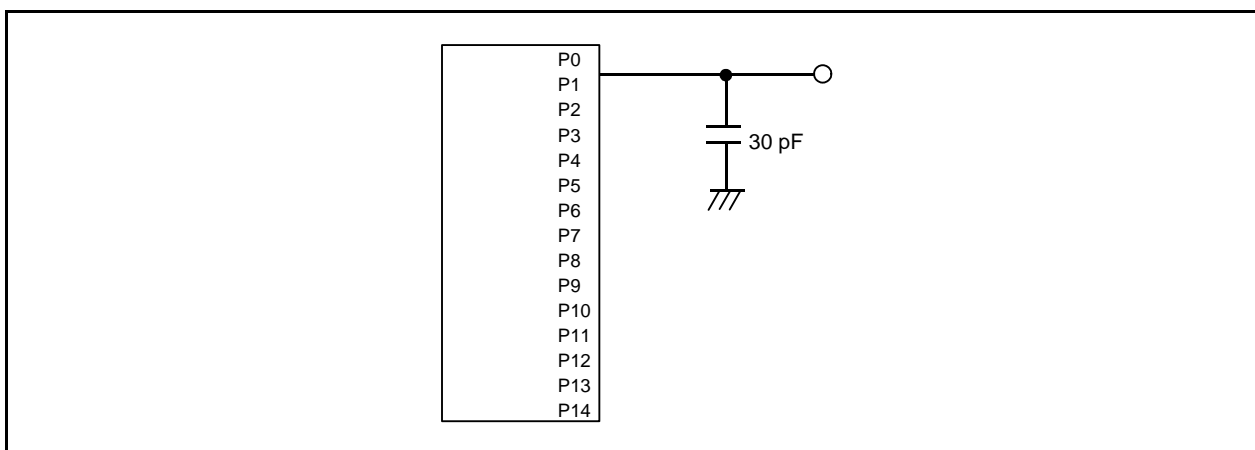


Figure 5.29 Ports P0 to P14 Measurement Circuit

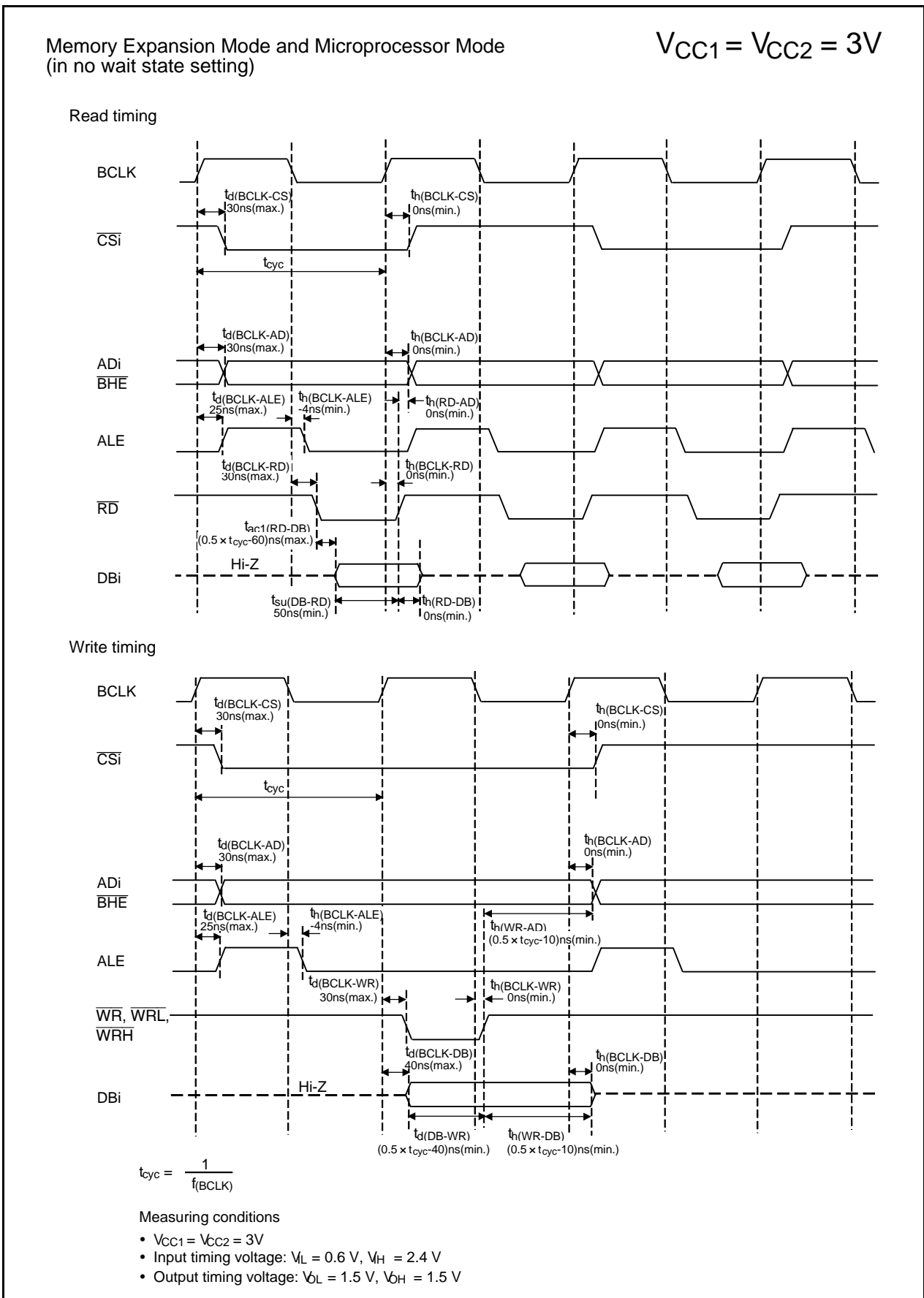


Figure 5.30 Timing Diagram

Appendix 1. Package Dimensions

The information on the latest package dimensions or packaging may be obtained from "Packages" on the Renesas Electronics website.

