



Welcome to [E-XFL.COM](https://www.e-xfl.com)

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	PIC
Core Size	8-Bit
Speed	16MHz
Connectivity	UART/USART
Peripherals	POR, PWM, WDT
Number of I/O	33
Program Memory Size	4KB (2K x 16)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	232 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 6V
Data Converters	-
Oscillator Type	External
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Through Hole
Package / Case	40-DIP (0.600", 15.24mm)
Supplier Device Package	40-PDIP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic17c42a-16e-p

PIC17C4X

NOTES:

4.1.3 OSCILLATOR START-UP TIMER (OST)

The Oscillator Start-up Timer (OST) provides a 1024 oscillator cycle (1024Tosc) delay after $\overline{\text{MCLR}}$ is detected high or a wake-up from SLEEP event occurs.

The OST time-out is invoked only for XT and LF oscillator modes on a Power-on Reset or a Wake-up from SLEEP.

The OST counts the oscillator pulses on the OSC1/CLKIN pin. The counter only starts incrementing after the amplitude of the signal reaches the oscillator input thresholds. This delay allows the crystal oscillator or resonator to stabilize before the device exits reset. The length of time-out is a function of the crystal/resonator frequency.

4.1.4 TIME-OUT SEQUENCE

On power-up the time-out sequence is as follows: First the internal POR signal goes high when the POR trip point is reached. If $\overline{\text{MCLR}}$ is high, then both the OST and PWRT timers start. In general the PWRT time-out is longer, except with low frequency crystals/resonators. The total time-out also varies based on oscillator configuration. Table 4-1 shows the times that are associated with the oscillator configuration. Figure 4-2 and Figure 4-3 display these time-out sequences.

If the device voltage is not within electrical specification at the end of a time-out, the $\overline{\text{MCLR}}/\text{VPP}$ pin must be held low until the voltage is within the device specification. The use of an external RC delay is sufficient for many of these applications.

TABLE 4-1: TIME-OUT IN VARIOUS SITUATIONS

Oscillator Configuration	Power-up	Wake up from SLEEP	$\overline{\text{MCLR}}$ Reset
XT, LF	Greater of: 96 ms or 1024Tosc	1024Tosc	—
EC, RC	Greater of: 96 ms or 1024Tosc	—	—

The time-out sequence begins from the first rising edge of $\overline{\text{MCLR}}$.

Table 4-3 shows the reset conditions for some special registers, while Table 4-4 shows the initialization conditions for all the registers. The shaded registers (in Table 4-4) are for all devices except the PIC17C42. In the PIC17C42, the PRODH and PRODL registers are general purpose RAM.

TABLE 4-2: STATUS BITS AND THEIR SIGNIFICANCE

$\overline{\text{TO}}$	$\overline{\text{PD}}$	Event
1	1	Power-on Reset, $\overline{\text{MCLR}}$ Reset during normal operation, or CLRWDT instruction executed
1	0	$\overline{\text{MCLR}}$ Reset during SLEEP or interrupt wake-up from SLEEP
0	1	WDT Reset during normal operation
0	0	WDT Reset during SLEEP

In Figure 4-2, Figure 4-3 and Figure 4-4, $\text{TPWRT} > \text{TOST}$, as would be the case in higher frequency crystals. For lower frequency crystals, (i.e., 32 kHz) TOST would be greater.

TABLE 4-3: RESET CONDITION FOR THE PROGRAM COUNTER AND THE CPUSTA REGISTER

Event		PCH:PCL	CPUSTA	OST Active
Power-on Reset		0000h	--11 11--	Yes
$\overline{\text{MCLR}}$ Reset during normal operation		0000h	--11 11--	No
$\overline{\text{MCLR}}$ Reset during SLEEP		0000h	--11 10--	Yes ⁽²⁾
WDT Reset during normal operation		0000h	--11 01--	No
WDT Reset during SLEEP ⁽³⁾		0000h	--11 00--	Yes ⁽²⁾
Interrupt wake-up from SLEEP	GLINTD is set	PC + 1	--11 10--	Yes ⁽²⁾
	GLINTD is clear	PC + 1 ⁽¹⁾	--10 10--	Yes ⁽²⁾

Legend: u = unchanged, x = unknown, - = unimplemented read as '0'.

Note 1: On wake-up, this instruction is executed. The instruction at the appropriate interrupt vector is fetched and then executed.

2: The OST is only active when the Oscillator is configured for XT or LF modes.

3: The Program Counter = 0, that is the device branches to the reset vector. This is different from the mid-range devices.

PIC17C4X

NOTES:

PIC17C4X

6.2.2.3 TMR0 STATUS/CONTROL REGISTER (T0STA)

This register contains various control bits. Bit7 (INTEDG) is used to control the edge upon which a signal on the RA0/INT pin will set the RB0/INT interrupt flag. The other bits configure the Timer0 prescaler and clock source. (Figure 11-1).

FIGURE 6-9: T0STA REGISTER (ADDRESS: 05h, UNBANKED)

R/W - 0	R/W - 0	R/W - 0	R/W - 0	R/W - 0	R/W - 0	R/W - 0	U - 0
INTEDG	T0SE	T0CS	PS3	PS2	PS1	PS0	—
bit7							bit0

R = Readable bit
W = Writable bit
U = Unimplemented, reads as '0'
-n = Value at POR reset

bit 7: **INTEDG:** RA0/INT Pin Interrupt Edge Select bit
This bit selects the edge upon which the interrupt is detected.
1 = Rising edge of RA0/INT pin generates interrupt
0 = Falling edge of RA0/INT pin generates interrupt

bit 6: **T0SE:** Timer0 Clock Input Edge Select bit
This bit selects the edge upon which TMR0 will increment.
When T0CS = 0
1 = Rising edge of RA1/T0CKI pin increments TMR0 and/or generates a T0CKIF interrupt
0 = Falling edge of RA1/T0CKI pin increments TMR0 and/or generates a T0CKIF interrupt
When T0CS = 1
Don't care

bit 5: **T0CS:** Timer0 Clock Source Select bit
This bit selects the clock source for Timer0.
1 = Internal instruction clock cycle (TCY)
0 = T0CKI pin

bit 4-1: **PS3:PS0:** Timer0 Prescale Selection bits
These bits select the prescale value for Timer0.

PS3:PS0	Prescale Value
0000	1:1
0001	1:2
0010	1:4
0011	1:8
0100	1:16
0101	1:32
0110	1:64
0111	1:128
1xxx	1:256

bit 0: **Unimplemented:** Read as '0'

9.0 I/O PORTS

The PIC17C4X devices have five I/O ports, PORTA through PORTE. PORTB through PORTE have a corresponding Data Direction Register (DDR), which is used to configure the port pins as inputs or outputs. These five ports are made up of 33 I/O pins. Some of these ports pins are multiplexed with alternate functions.

PORTC, PORTD, and PORTE are multiplexed with the system bus. These pins are configured as the system bus when the device's configuration bits are selected to Microprocessor or Extended Microcontroller modes. In the two other microcontroller modes, these pins are general purpose I/O.

PORTA and PORTB are multiplexed with the peripheral features of the device. These peripheral features are:

- Timer modules
- Capture module
- PWM module
- USART/SCI module
- External Interrupt pin

When some of these peripheral modules are turned on, the port pin will automatically configure to the alternate function. The modules that do this are:

- PWM module
- USART/SCI module

When a pin is automatically configured as an output by a peripheral module, the pins data direction (DDR) bit is unknown. After disabling the peripheral module, the user should re-initialize the DDR bit to the desired configuration.

The other peripheral modules (which require an input) must have their data direction bit configured appropriately.

Note: A pin that is a peripheral input, can be configured as an output (DDRx<y> is cleared). The peripheral events will be determined by the action output on the port pin.

9.1 PORTA Register

PORTA is a 6-bit wide latch. PORTA does not have a corresponding Data Direction Register (DDR).

Reading PORTA reads the status of the pins.

The RA1 pin is multiplexed with TMR0 clock input, and RA4 and RA5 are multiplexed with the USART functions. The control of RA4 and RA5 as outputs is automatically configured by the USART module.

9.1.1 USING RA2, RA3 AS OUTPUTS

The RA2 and RA3 pins are open drain outputs. To use the RA2 or the RA3 pin(s) as output(s), simply write to the PORTA register the desired value. A '0' will cause the pin to drive low, while a '1' will cause the pin to float (hi-impedance). An external pull-up resistor should be used to pull the pin high. Writes to PORTA will not affect the other pins.

Note: When using the RA2 or RA3 pin(s) as output(s), read-modify-write instructions (such as BCF, BSF, BTG) on PORTA are not recommended. Such operations read the port pins, do the desired operation, and then write this value to the data latch. This may inadvertently cause the RA2 or RA3 pins to switch from input to output (or vice-versa). It is recommended to use a shadow register for PORTA. Do the bit operations on this shadow register and then move it to PORTA.

FIGURE 9-1: RA0 AND RA1 BLOCK DIAGRAM

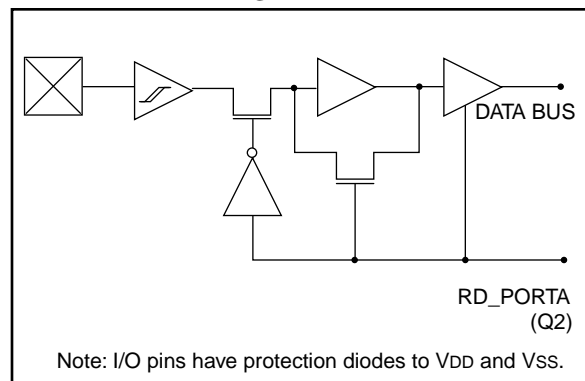


FIGURE 13-2: RCSTA REGISTER (ADDRESS: 13h, BANK 0)

R/W - 0	R/W - 0	R/W - 0	R/W - 0	U - 0	R - 0	R - 0	R - x
SPEN	RX9	SREN	CREN	—	FERR	OERR	RX9D
bit 7							bit 0

R = Readable bit
W = Writable bit
-n = Value at POR reset
(x = unknown)

bit 7: **SPEN**: Serial Port Enable bit
1 = Configures RA5/RX/DT and RA4/TX/CK pins as serial port pins
0 = Serial port disabled

bit 6: **RX9**: 9-bit Receive Enable bit
1 = Selects 9-bit reception
0 = Selects 8-bit reception

bit 5: **SREN**: Single Receive Enable bit
This bit enables the reception of a single byte. After receiving the byte, this bit is automatically cleared.
Synchronous mode:
1 = Enable reception
0 = Disable reception
Note: This bit is ignored in synchronous slave reception.
Asynchronous mode:
Don't care

bit 4: **CREN**: Continuous Receive Enable bit
This bit enables the continuous reception of serial data.
Asynchronous mode:
1 = Enable reception
0 = Disables reception
Synchronous mode:
1 = Enables continuous reception until CREN is cleared (CREN overrides SREN)
0 = Disables continuous reception

bit 3: **Unimplemented**: Read as '0'

bit 2: **FERR**: Framing Error bit
1 = Framing error (Updated by reading RCREG)
0 = No framing error

bit 1: **OERR**: Overrun Error bit
1 = Overrun (Cleared by clearing CREN)
0 = No overrun error

bit 0: **RX9D**: 9th bit of receive data (can be the software calculated parity bit)

13.1 USART Baud Rate Generator (BRG)

The BRG supports both the Asynchronous and Synchronous modes of the USART. It is a dedicated 8-bit baud rate generator. The SPBRG register controls the period of a free running 8-bit timer. Table 13-1 shows the formula for computation of the baud rate for different USART modes. These only apply when the USART is in synchronous master mode (internal clock) and asynchronous mode.

Given the desired baud rate and Fosc, the nearest integer value between 0 and 255 can be calculated using the formula below. The error in baud rate can then be determined.

TABLE 13-1: BAUD RATE FORMULA

SYNC	Mode	Baud Rate
0	Asynchronous	$F_{OSC}/(64(X+1))$
1	Synchronous	$F_{OSC}/(4(X+1))$

X = value in SPBRG (0 to 255)

Example 13-1 shows the calculation of the baud rate error for the following conditions:

Fosc = 16 MHz

Desired Baud Rate = 9600

SYNC = 0

EXAMPLE 13-1: CALCULATING BAUD RATE ERROR

Desired Baud rate = $F_{OSC} / (64 (X + 1))$

$9600 = 16000000 / (64 (X + 1))$

$X = 25.042 = 25$

Calculated Baud Rate = $16000000 / (64 (25 + 1))$

= 9615

Error = $\frac{(\text{Calculated Baud Rate} - \text{Desired Baud Rate})}{\text{Desired Baud Rate}}$

= $(9615 - 9600) / 9600$

= 0.16%

Writing a new value to the SPBRG, causes the BRG timer to be reset (or cleared), this ensures that the BRG does not wait for a timer overflow before outputting the new baud rate.

TABLE 13-2: REGISTERS ASSOCIATED WITH BAUD RATE GENERATOR

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on Power-on Reset	Value on all other resets (Note1)
13h, Bank 0	RCSTA	SPEN	RX9	SREN	CREN	—	FERR	OERR	RX9D	0000 -00x	0000 -00u
15h, Bank 0	TXSTA	CSRC	TX9	TXEN	SYNC	—	—	TRMT	TX9D	0000 --1x	0000 --1u
17h, Bank 0	SPBRG	Baud rate generator register								xxxx xxxx	uuuu uuuu

Legend: x = unknown, u = unchanged, - = unimplemented read as a '0', shaded cells are not used by the Baud Rate Generator.

Note 1: Other (non power-up) resets include: external reset through \overline{MCLR} and Watchdog Timer Reset.

FIGURE 14-3: CRYSTAL OPERATION, OVERTONE CRYSTALS (XT OSC CONFIGURATION)

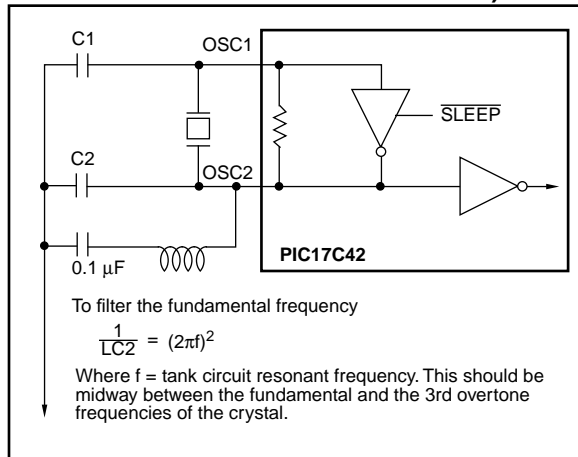


TABLE 14-2: CAPACITOR SELECTION FOR CERAMIC RESONATORS

Oscillator Type	Resonator Frequency	Capacitor Range C1 = C2
LF	455 kHz	15 - 68 pF
	2.0 MHz	10 - 33 pF
XT	4.0 MHz	22 - 68 pF
	8.0 MHz	33 - 100 pF
	16.0 MHz	33 - 100 pF

Higher capacitance increases the stability of the oscillator but also increases the start-up time. These values are for design guidance only. Since each resonator has its own characteristics, the user should consult the resonator manufacturer for appropriate values of external components.

Resonators Used:

455 kHz	Panasonic EFO-A455K04B	± 0.3%
2.0 MHz	Murata Erie CSA2.00MG	± 0.5%
4.0 MHz	Murata Erie CSA4.00MG	± 0.5%
8.0 MHz	Murata Erie CSA8.00MT	± 0.5%
16.0 MHz	Murata Erie CSA16.00MX	± 0.5%

Resonators used did not have built-in capacitors.

TABLE 14-3: CAPACITOR SELECTION FOR CRYSTAL OSCILLATOR

Osc Type	Freq	C1	C2
LF	32 kHz ⁽¹⁾	100-150 pF	100-150 pF
	1 MHz	10-33 pF	10-33 pF
	2 MHz	10-33 pF	10-33 pF
XT	2 MHz	47-100 pF	47-100 pF
	4 MHz	15-68 pF	15-68 pF
	8 MHz ⁽²⁾	15-47 pF	15-47 pF
	16 MHz	TBD	TBD
	25 MHz	15-47 pF	15-47 pF
	32 MHz ⁽³⁾	0 ⁽³⁾	0 ⁽³⁾

Higher capacitance increases the stability of the oscillator but also increases the start-up time and the oscillator current. These values are for design guidance only. Rs may be required in XT mode to avoid overdriving the crystals with low drive level specification. Since each crystal has its own characteristics, the user should consult the crystal manufacturer for appropriate values for external components.

Note 1: For VDD > 4.5V, C1 = C2 ≈ 30 pF is recommended.

2: Rs of 330Ω is required for a capacitor combination of 15/15 pF.

3: Only the capacitance of the board was present.

Crystals Used:

32.768 kHz	Epson C-001R32.768K-A	± 20 PPM
1.0 MHz	ECS-10-13-1	± 50 PPM
2.0 MHz	ECS-20-20-1	± 50 PPM
4.0 MHz	ECS-40-20-1	± 50 PPM
8.0 MHz	ECS ECS-80-S-4 ECS-80-18-1	± 50 PPM
16.0 MHz	ECS-160-20-1	TBD
25 MHz	CTS CTS25M	± 50 PPM
32 MHz	CRYSTEK HF-2	± 50 PPM

14.2.3 EXTERNAL CLOCK OSCILLATOR

In the EC oscillator mode, the OSC1 input can be driven by CMOS drivers. In this mode, the OSC1/CLKIN pin is hi-impedance and the OSC2/CLKOUT pin is the CLKOUT output (4 TOSC).

FIGURE 14-4: EXTERNAL CLOCK INPUT OPERATION (EC OSC CONFIGURATION)

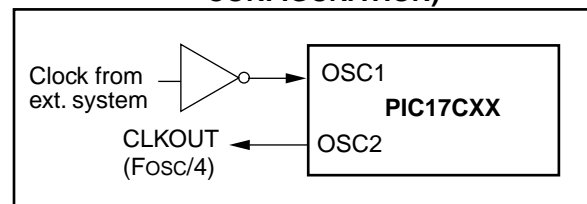


TABLE 15-2: PIC17CXX INSTRUCTION SET (Cont'd)

Mnemonic, Operands	Description	Cycles	16-bit Opcode		Status Affected	Notes
			MSb	LSb		
TABLWT t,i,f	Table Write	2	1010	11ti ffff ffff	None	5
TLRD t,f	Table Latch Read	1	1010	00tx ffff ffff	None	
TLWT t,f	Table Latch Write	1	1010	01tx ffff ffff	None	
TSTFSZ f	Test f, skip if 0	1 (2)	0011	0011 ffff ffff	None	6,8
XORWF f,d	Exclusive OR WREG with f	1	0000	110d ffff ffff	Z	
BIT-ORIENTED FILE REGISTER OPERATIONS						
BCF f,b	Bit Clear f	1	1000	1bbb ffff ffff	None	
BSF f,b	Bit Set f	1	1000	0bbb ffff ffff	None	
BTFSC f,b	Bit test, skip if clear	1 (2)	1001	1bbb ffff ffff	None	6,8
BTFSS f,b	Bit test, skip if set	1 (2)	1001	0bbb ffff ffff	None	6,8
BTG f,b	Bit Toggle f	1	0011	1bbb ffff ffff	None	
LITERAL AND CONTROL OPERATIONS						
ADDLW k	ADD literal to WREG	1	1011	0001 kkkk kkkk	OV,C,DC,Z	
ANDLW k	AND literal with WREG	1	1011	0101 kkkk kkkk	Z	
CALL k	Subroutine Call	2	111k	kkkk kkkk kkkk	None	7
CLRWDT —	Clear Watchdog Timer	1	0000	0000 0000 0100	$\overline{TO}, \overline{PD}$	
GOTO k	Unconditional Branch	2	110k	kkkk kkkk kkkk	None	7
IORLW k	Inclusive OR literal with WREG	1	1011	0011 kkkk kkkk	Z	
LCALL k	Long Call	2	1011	0111 kkkk kkkk	None	4,7
MOVLB k	Move literal to low nibble in BSR	1	1011	1000 uuuu kkkk	None	
MOVLR k	Move literal to high nibble in BSR	1	1011	101x kkkk uuuu	None	9
MOVLW k	Move literal to WREG	1	1011	0000 kkkk kkkk	None	
MULLW k	Multiply literal with WREG	1	1011	1100 kkkk kkkk	None	9
RETFIE —	Return from interrupt (and enable interrupts)	2	0000	0000 0000 0101	GLINTD	7
RETLW k	Return literal to WREG	2	1011	0110 kkkk kkkk	None	7
RETURN —	Return from subroutine	2	0000	0000 0000 0010	None	7
SLEEP —	Enter SLEEP Mode	1	0000	0000 0000 0011	$\overline{TO}, \overline{PD}$	
SUBLW k	Subtract WREG from literal	1	1011	0010 kkkk kkkk	OV,C,DC,Z	
XORLW k	Exclusive OR literal with WREG	1	1011	0100 kkkk kkkk	Z	

Legend: Refer to Table 15-1 for opcode field descriptions.

Note 1: 2's Complement method.

2: Unsigned arithmetic.

3: If s = '1', only the file is affected; If s = '0', both the WREG register and the file are affected; If only the Working register (WREG) is required to be affected, then f = WREG must be specified.

4: During an **LCALL**, the contents of PCLATH are loaded into the MSB of the PC and kkkk kkkk is loaded into the LSB of the PC (PCL)

5: Multiple cycle instruction for EPROM programming when table pointer selects internal EPROM. The instruction is terminated by an interrupt event. When writing to external program memory, it is a two-cycle instruction.

6: Two-cycle instruction when condition is true, else single cycle instruction.

7: Two-cycle instruction except for **TABLRD** to PCL (program counter low byte) in which case it takes 3 cycles.

8: A "skip" means that instruction fetched during execution of current instruction is not executed, instead an NOP is executed.

9: These instructions are not available on the PIC17C42.

ADDLW

ADD Literal to WREG

Syntax: [*label*] ADDLW k

Operands: $0 \leq k \leq 255$

Operation: (WREG) + k → (WREG)

Status Affected: OV, C, DC, Z

Encoding:

1011	0001	kkkk	kkkk
------	------	------	------

Description: The contents of WREG are added to the 8-bit literal 'k' and the result is placed in WREG.

Words: 1

Cycles: 1

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read literal 'k'	Execute	Write to WREG

Example: ADDLW 0x15

Before Instruction
WREG = 0x10

After Instruction
WREG = 0x25

ADDWF

ADD WREG to f

Syntax: [*label*] ADDWF f,d

Operands: $0 \leq f \leq 255$
 $d \in [0,1]$

Operation: (WREG) + (f) → (dest)

Status Affected: OV, C, DC, Z

Encoding:

0000	111d	ffff	ffff
------	------	------	------

Description: Add WREG to register 'f'. If 'd' is 0 the result is stored in WREG. If 'd' is 1 the result is stored back in register 'f'.

Words: 1

Cycles: 1

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read register 'f'	Execute	Write to destination

Example: ADDWF REG, 0

Before Instruction
WREG = 0x17
REG = 0xC2

After Instruction
WREG = 0xD9
REG = 0xC2

CPFSEQ Compare f with WREG, skip if f = WREG

Syntax: [*label*] CPFSEQ f

Operands: $0 \leq f \leq 255$

Operation: (f) – (WREG),
skip if (f) = (WREG)
(unsigned comparison)

Status Affected: None

Encoding:

0011	0001	ffff	ffff
------	------	------	------

Description: Compares the contents of data memory location 'f' to the contents of WREG by performing an unsigned subtraction.
If 'f' = WREG then the fetched instruction is discarded and an NOP is executed instead making this a two-cycle instruction.

Words: 1

Cycles: 1 (2)

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read register 'f'	Execute	NOP

If skip:

Q1	Q2	Q3	Q4
Forced NOP	NOP	Execute	NOP

Example:

```

HERE    CPFSEQ REG
NEQUAL  :
EQUAL   :
```

Before Instruction

```

PC Address = HERE
WREG       = ?
REG        = ?
```

After Instruction

```

If REG     = WREG;
PC         = Address (EQUAL)
If REG     ≠ WREG;
PC         = Address (NEQUAL)
```

CPFSGT Compare f with WREG, skip if f > WREG

Syntax: [*label*] CPFSGT f

Operands: $0 \leq f \leq 255$

Operation: (f) – (WREG),
skip if (f) > (WREG)
(unsigned comparison)

Status Affected: None

Encoding:

0011	0010	ffff	ffff
------	------	------	------

Description: Compares the contents of data memory location 'f' to the contents of the WREG by performing an unsigned subtraction.
If the contents of 'f' > the contents of WREG then the fetched instruction is discarded and an NOP is executed instead making this a two-cycle instruction.

Words: 1

Cycles: 1 (2)

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read register 'f'	Execute	NOP

If skip:

Q1	Q2	Q3	Q4
Forced NOP	NOP	Execute	NOP

Example:

```

HERE    CPFSGT REG
NGREATER :
GREATER  :
```

Before Instruction

```

PC       = Address (HERE)
WREG     = ?
```

After Instruction

```

If REG   > WREG;
PC       = Address (GREATER)
If REG   ≤ WREG;
PC       = Address (NGREATER)
```

DECF Decrement f

Syntax: [*label*] DECF f,d

Operands: $0 \leq f \leq 255$
 $d \in [0,1]$

Operation: $(f) - 1 \rightarrow (\text{dest})$

Status Affected: OV, C, DC, Z

Encoding:

0000	011d	ffff	ffff
------	------	------	------

Description: Decrement register 'f'. If 'd' is 0 the result is stored in WREG. If 'd' is 1 the result is stored back in register 'f'.

Words: 1

Cycles: 1

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read register 'f'	Execute	Write to destination

Example: DECF CNT, 1

Before Instruction

CNT = 0x01
Z = 0

After Instruction

CNT = 0x00
Z = 1

DECFSZ Decrement f, skip if 0

Syntax: [*label*] DECFSZ f,d

Operands: $0 \leq f \leq 255$
 $d \in [0,1]$

Operation: $(f) - 1 \rightarrow (\text{dest})$;
skip if result = 0

Status Affected: None

Encoding:

0001	011d	ffff	ffff
------	------	------	------

Description: The contents of register 'f' are decremented. If 'd' is 0 the result is placed in WREG. If 'd' is 1 the result is placed back in register 'f'.

If the result is 0, the next instruction, which is already fetched, is discarded, and an NOP is executed instead making it a two-cycle instruction.

Words: 1

Cycles: 1(2)

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read register 'f'	Execute	Write to destination

Example: HERE DECFSZ CNT, 1
GOTO LOOP

CONTINUE

Before Instruction

PC = Address (HERE)

After Instruction

CNT = CNT - 1
If CNT = 0;
PC = Address (CONTINUE)
If CNT \neq 0;
PC = Address (HERE+1)

IORWF		Inclusive OR WREG with f						
Syntax:	[<i>label</i>] IORWF f,d							
Operands:	$0 \leq f \leq 255$ $d \in [0,1]$							
Operation:	(WREG) .OR. (f) \rightarrow (dest)							
Status Affected:	Z							
Encoding:	<table><tr><td>0000</td><td>100d</td><td>ffff</td><td>ffff</td></tr></table>				0000	100d	ffff	ffff
0000	100d	ffff	ffff					
Description:	Inclusive OR WREG with register 'f'. If 'd' is 0 the result is placed in WREG. If 'd' is 1 the result is placed back in register 'f'.							
Words:	1							
Cycles:	1							
Q Cycle Activity:								
	Q1	Q2	Q3	Q4				
	Decode	Read register 'f'	Execute	Write to destination				

Example: IORWF RESULT, 0

Before Instruction

RESULT = 0x13
WREG = 0x91

After Instruction

RESULT = 0x13
WREG = 0x93

LCALL	Long Call												
Syntax:	[<i>label</i>] LCALL k												
Operands:	$0 \leq k \leq 255$												
Operation:	PC + 1 → TOS; k → PCL, (PCLATH) → PCH												
Status Affected:	None												
Encoding:	<table><tr><td>1011</td><td>0111</td><td>kkkk</td><td>kkkk</td></tr></table>	1011	0111	kkkk	kkkk								
1011	0111	kkkk	kkkk										
Description:	<p>LCALL allows an unconditional subroutine call to anywhere within the 64k program memory space.</p> <p>First, the return address (PC + 1) is pushed onto the stack. A 16-bit destination address is then loaded into the program counter. The lower 8-bits of the destination address is embedded in the instruction. The upper 8-bits of PC is loaded from PC high holding latch, PCLATH.</p>												
Words:	1												
Cycles:	2												
Q Cycle Activity:													
	<table><tr><th>Q1</th><th>Q2</th><th>Q3</th><th>Q4</th></tr><tr><td>Decode</td><td>Read literal 'k'</td><td>Execute</td><td>Write register PCL</td></tr><tr><td>Forced NOP</td><td>NOP</td><td>Execute</td><td>NOP</td></tr></table>	Q1	Q2	Q3	Q4	Decode	Read literal 'k'	Execute	Write register PCL	Forced NOP	NOP	Execute	NOP
Q1	Q2	Q3	Q4										
Decode	Read literal 'k'	Execute	Write register PCL										
Forced NOP	NOP	Execute	NOP										

Example: MOVLW HIGH(SUBROUTINE)
MOVWF WREG, PCLATH
LCALL LOW(SUBROUTINE)

Before Instruction

SUBROUTINE = 16-bit Address
PC = ?

After Instruction

PC = Address (SUBROUTINE)

TABLWT Table Write

Example1: TABLWT 0, 1, REG

Before Instruction

REG = 0x53
TBLATH = 0xAA
TBLATL = 0x55
TBLPTR = 0xA356
MEMORY(TBLPTR) = 0xFFFF

After Instruction (table write completion)

REG = 0x53
TBLATH = 0x53
TBLATL = 0x55
TBLPTR = 0xA357
MEMORY(TBLPTR - 1) = 0x5355

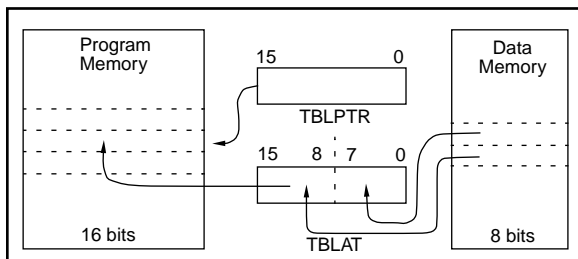
Example 2: TABLWT 1, 0, REG

Before Instruction

REG = 0x53
TBLATH = 0xAA
TBLATL = 0x55
TBLPTR = 0xA356
MEMORY(TBLPTR) = 0xFFFF

After Instruction (table write completion)

REG = 0x53
TBLATH = 0xAA
TBLATL = 0x53
TBLPTR = 0xA356
MEMORY(TBLPTR) = 0xAA53



TLRD Table Latch Read

Syntax: [label] TLRD t,f

Operands: $0 \leq f \leq 255$
 $t \in [0,1]$

Operation: If $t = 0$,
TBLATL \rightarrow f;
If $t = 1$,
TBLATH \rightarrow f

Status Affected: None

Encoding:

1010	00tx	ffff	ffff
------	------	------	------

Description: Read data from 16-bit table latch (TBLAT) into file register 'f'. Table Latch is unaffected.

If $t = 1$; high byte is read

If $t = 0$; low byte is read

This instruction is used in conjunction with TABLRD to transfer data from program memory to data memory.

Words: 1

Cycles: 1

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read register TBLATH or TBLATL	Execute	Write register 'f'

Example: TLRD t, RAM

Before Instruction

t = 0
RAM = ?
TBLAT = 0x00AF (TBLATH = 0x00)
(TBLATL = 0xAF)

After Instruction

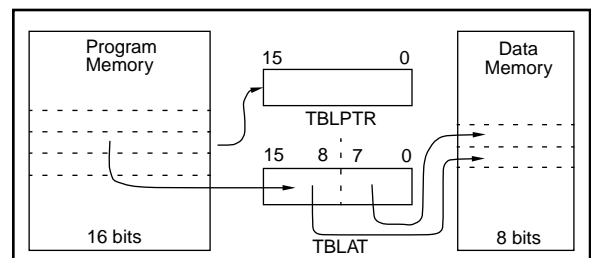
RAM = 0xAF
TBLAT = 0x00AF (TBLATH = 0x00)
(TBLATL = 0xAF)

Before Instruction

t = 1
RAM = ?
TBLAT = 0x00AF (TBLATH = 0x00)
(TBLATL = 0xAF)

After Instruction

RAM = 0x00
TBLAT = 0x00AF (TBLATH = 0x00)
(TBLATL = 0xAF)



PIC17C4X

Applicable Devices 42 R42 42A 43 R43 44

FIGURE 17-9: USART MODULE: SYNCHRONOUS TRANSMISSION (MASTER/SLAVE) TIMING

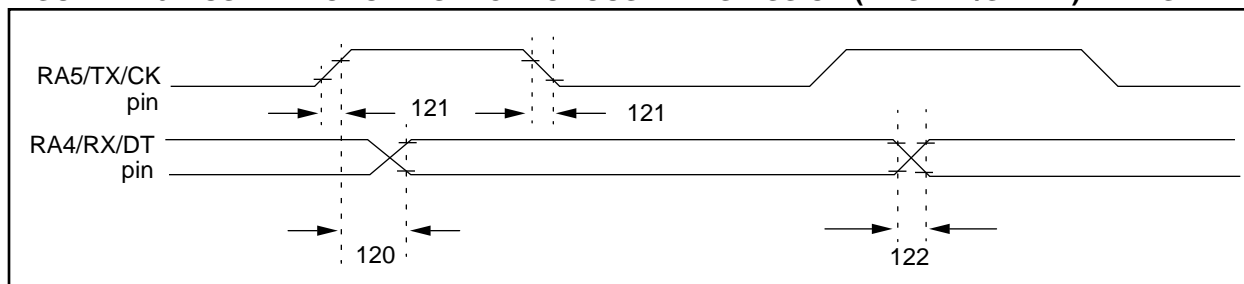


TABLE 17-9: SERIAL PORT SYNCHRONOUS TRANSMISSION REQUIREMENTS

Parameter No.	Sym	Characteristic	Min	Typ†	Max	Units	Conditions
120	TckH2dtV	<u>SYNC XMIT (MASTER & SLAVE)</u> Clock high to data out valid	—	—	65	ns	
121	TckRF	Clock out rise time and fall time (Master Mode)	—	10	35	ns	
122	TdtRF	Data out rise time and fall time	—	10	35	ns	

† Data in "Typ" column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

FIGURE 17-10: USART MODULE: SYNCHRONOUS RECEIVE (MASTER/SLAVE) TIMING

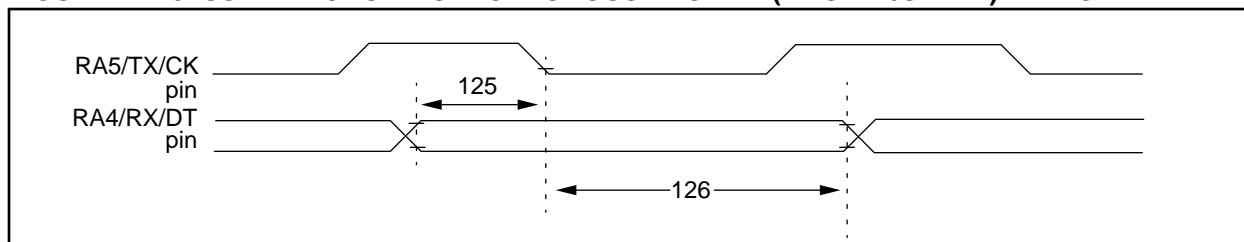


TABLE 17-10: SERIAL PORT SYNCHRONOUS RECEIVE REQUIREMENTS

Parameter No.	Sym	Characteristic	Min	Typ†	Max	Units	Conditions
125	TdtV2ckL	<u>SYNC RCV (MASTER & SLAVE)</u> Data hold before CK↓ (DT hold time)	15	—	—	ns	
126	TckL2dtl	Data hold after CK↓ (DT hold time)	15	—	—	ns	

† Data in "Typ" column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

PIC17C4X

Applicable Devices 42 R42 42A 43 R43 44

FIGURE 18-9: TYPICAL I_{PD} vs. V_{DD} WATCHDOG DISABLED 25°C

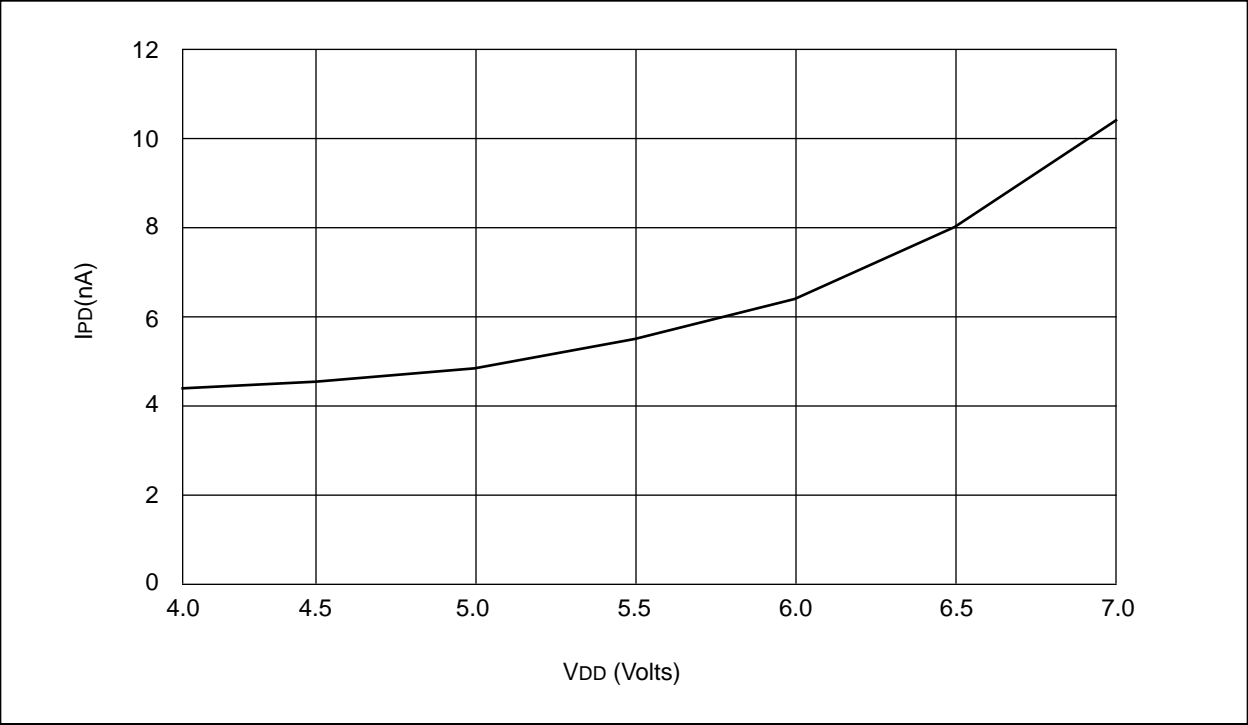


FIGURE 18-10: MAXIMUM I_{PD} vs. V_{DD} WATCHDOG DISABLED

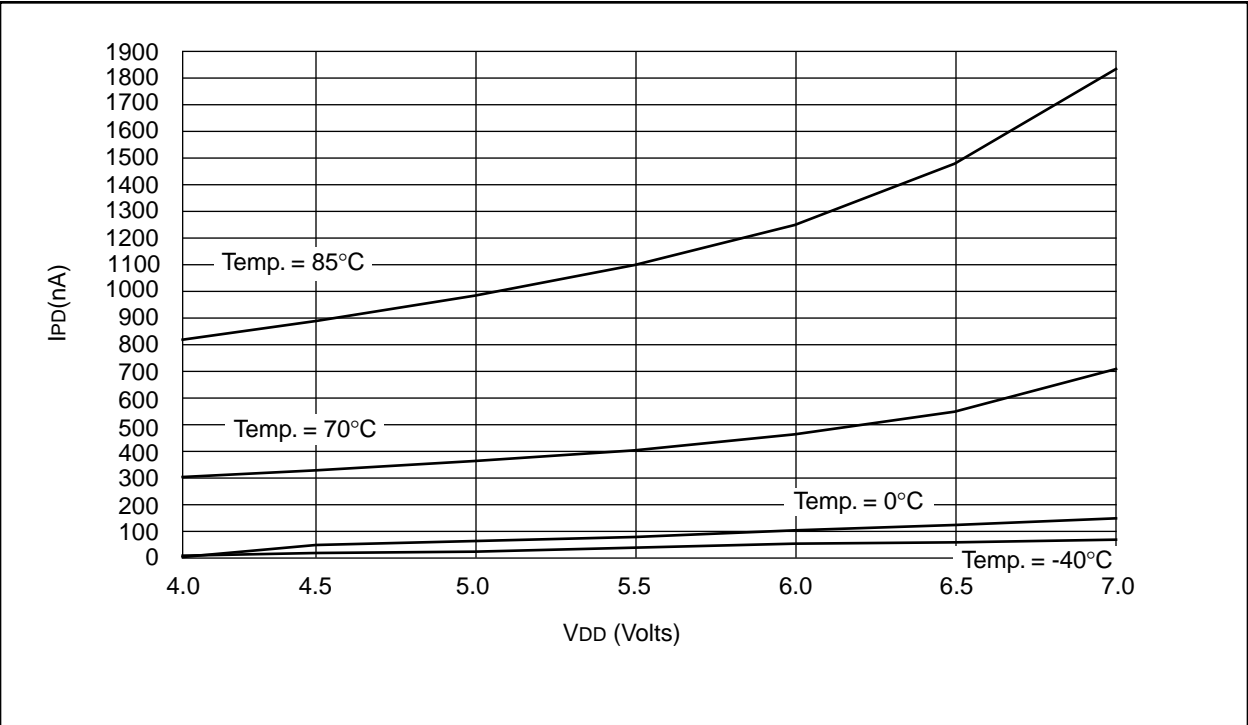


FIGURE 18-11: TYPICAL I_{PD} vs. V_{DD} WATCHDOG ENABLED 25°C

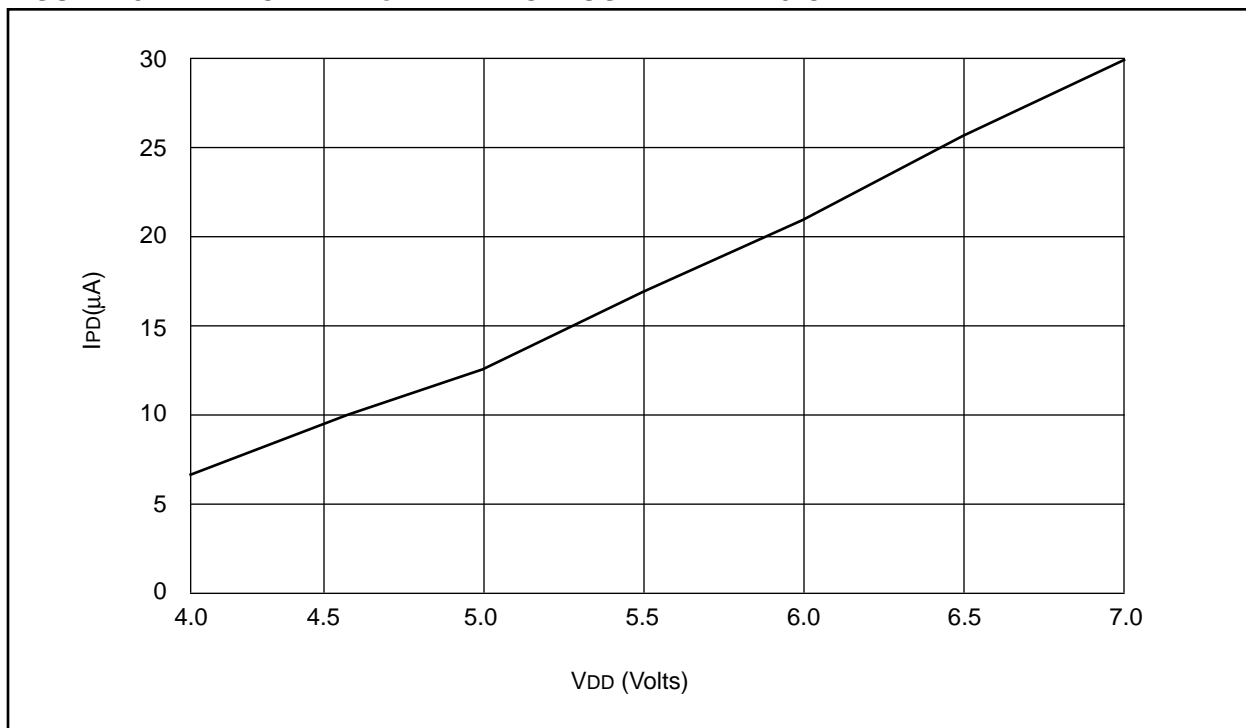
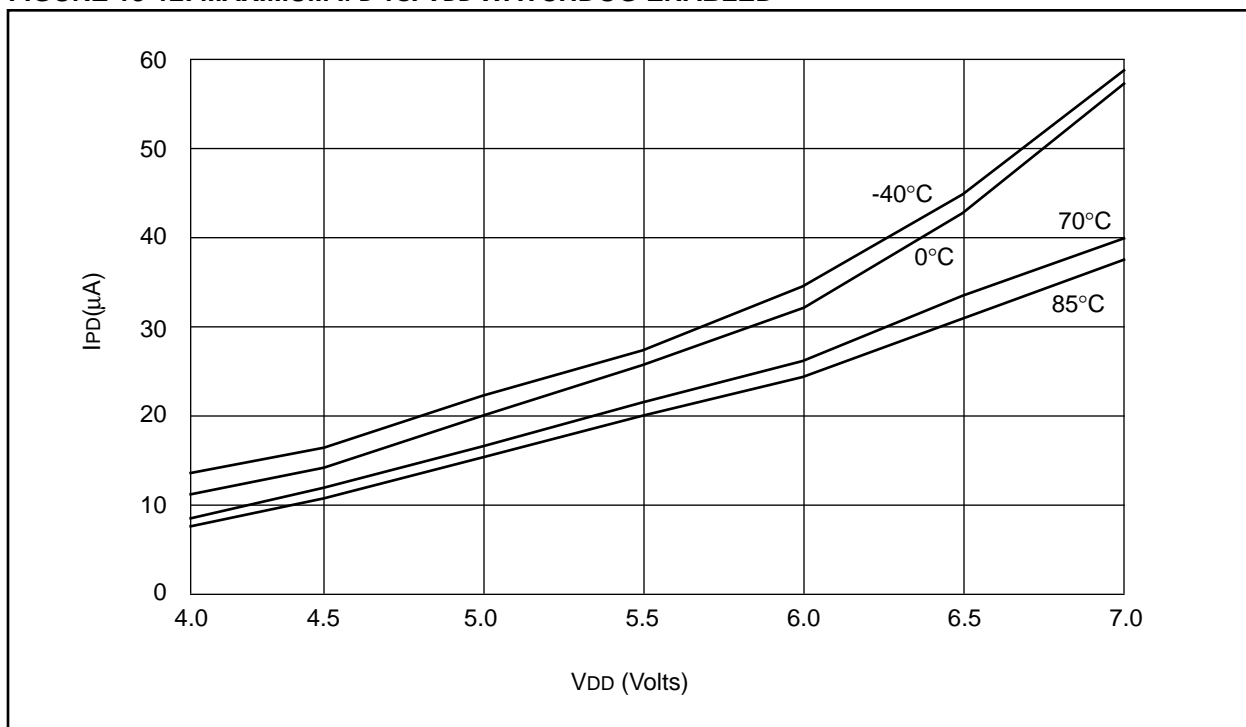


FIGURE 18-12: MAXIMUM I_{PD} vs. V_{DD} WATCHDOG ENABLED



PIC17C4X

Applicable Devices 42 R42 42A 43 R43 44

FIGURE 18-13: WDT TIMER TIME-OUT PERIOD vs. VDD

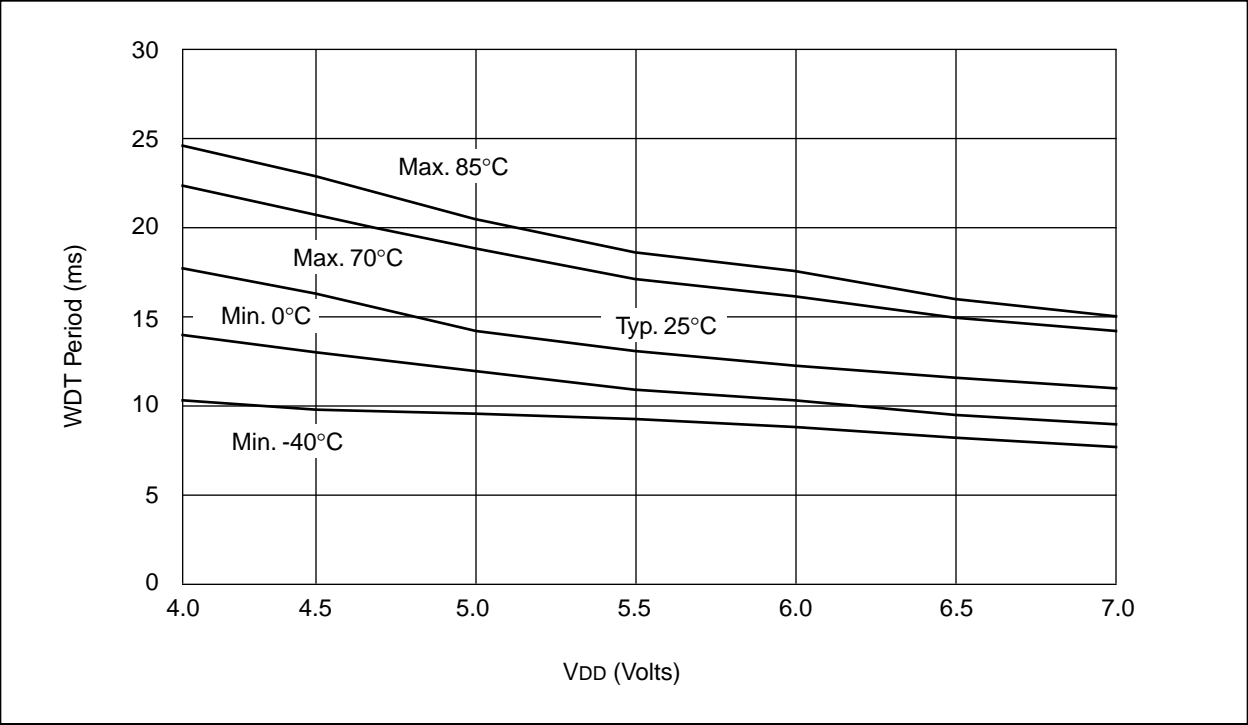
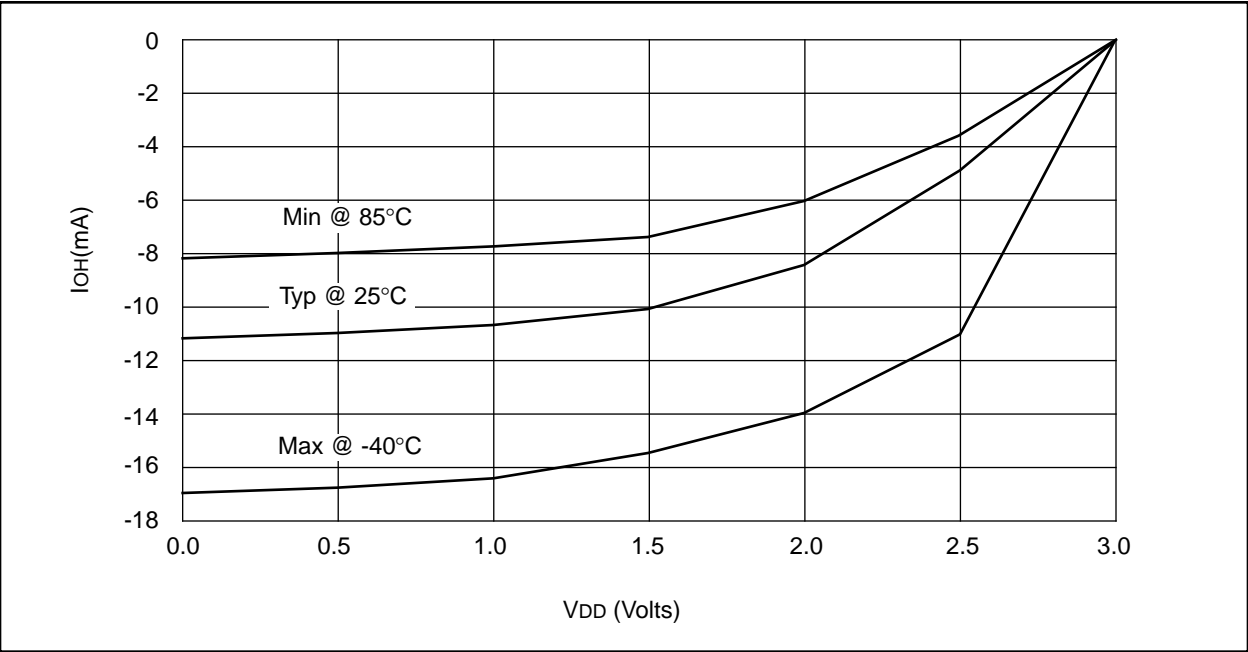


FIGURE 18-14: IOH vs. VOH, VDD = 3V



PIC17C4X

NOTES: