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#### Details

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Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	40 MIPs
Connectivity	I <sup>2</sup> C, IrDA, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	13
Program Memory Size	12KB (12K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 6x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	18-SOIC (0.295", 7.50mm Width)
Supplier Device Package	18-SOIC
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33fj12gp201-e-so

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Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

### **Pin Diagrams (Continued)**



### 1.1 Referenced Sources

This device data sheet is based on the following individual chapters of the *"dsPIC33F/PIC24H Family Reference Manual"*. These documents should be considered as the general reference for the operation of a particular module or device feature.

Note 1: To access the documents listed below, browse to the documentation section of the dsPIC33FJ12GP202 product page of the Microchip web site (www.microchip.com) or select a family reference manual section from the following list.

In addition to parameters, features, and other documentation, the resulting page provides links to the related family reference manual sections.

- Section 1. "Introduction" (DS70197)
- Section 2. "CPU" (DS70204)
- Section 3. "Data Memory" (DS70202)
- Section 4. "Program Memory" (DS70202)
- Section 5. "Flash Programming" (DS70191)
- Section 6. "Interrupts" (DS70184)
- Section 7. "Oscillator" (DS70186)
- Section 8. "Reset" (DS70192)
- Section 9. "Watchdog Timer and Power-saving Modes" (DS70196)
- Section 10. "I/O Ports" (DS70193)
- Section 11. "Timers" (DS70205)
- Section 12. "Input Capture" (DS70198)
- Section 13. "Output Compare" (DS70209)
- Section 14. "Motor Control PWM" (DS70187)
- Section 15. "Quadrature Encoder Interface (QEI)" (DS70208)
- Section 16. "Analog-to-Digital Converter (ADC)" (DS70183)
- Section 17. "UART" (DS70188)
- Section 18. "Serial Peripheral Interface (SPI)" (DS70206)
- Section 19. "Inter-Integrated Circuit™ (I<sup>2</sup>C™)" (DS70195)





#### 3.6.2.4 Data Space Write Saturation

In addition to adder/subtracter saturation, writes to data space can also be saturated, but without affecting the contents of the source accumulator. The data space write saturation logic block accepts a 16-bit, 1.15 fractional value from the round logic block as its input, together with overflow status from the original source (accumulator) and the 16-bit round adder. These inputs are combined and used to select the appropriate 1.15 fractional value as output to write to data space memory.

If the SATDW bit in the CORCON register is set, data (after rounding or truncation) is tested for overflow and adjusted accordingly:

- For input data greater than 0x007FFF, data written to memory is forced to the maximum positive 1.15 value, 0x7FFF
- For input data less than 0xFF8000, data written to memory is forced to the maximum negative 1.15 value, 0x8000

The MSb of the source (bit 39) is used to determine the sign of the operand being tested.

If the SATDW bit in the CORCON register is not set, the input data is always passed through unmodified under all conditions.

### 3.6.3 BARREL SHIFTER

The barrel shifter can perform up to 16-bit arithmetic or logic right shifts, or up to 16-bit left shifts in a single cycle. The source can be either of the two DSP accumulators or the X bus (to support multi-bit shifts of register or memory data).

The shifter requires a signed binary value to determine both the magnitude (number of bits) and direction of the shift operation. A positive value shifts the operand right. A negative value shifts the operand left. A value of '0' does not modify the operand.

The barrel shifter is 40 bits wide, thereby obtaining a 40-bit result for DSP shift operations and a 16-bit result for MCU shift operations. Data from the X bus is presented to the barrel shifter between bit positions 16 and 31 for right shifts, and between bit positions 0 and 16 for left shifts.

	Reset – GOTO Instruction	0x000000	
	Reset – GOTO Address	0x000002	
	Reserved	0x000002	
	Oscillator Fail Tran Vector	0,000004	
	Address Error Tran Vector		
	Stack Error Tran Vector	_	
	Math Error Tran Vector		
	Reserved		
	Reserved	_	
	Reserved	_	
	Interrupt Vector 0	0x000014	
	Interrupt Vector 1		
	~		
	~		
	~		
	Interrupt Vector 52	0x00007C	· · · · · · · · · · · · · · · · · · ·
	Interrupt Vector 53	0x00007E	Interrupt Vector Table (IVT)(")
ity	Interrupt Vector 54	0x000080	
ior	~		
<u>r</u>	~		
der	~		
ō	Interrupt Vector 116	0x0000FC	
a	Interrupt Vector 117	0x0000FE	
atu	Reserved	0x000100	
ž	Reserved	0x000102	
ing	Reserved	-	
sas	Oscillator Fail Trap Vector		
SCLE	Address Error Trap Vector		
ĕ	Stack Error Trap Vector		
	Math Error Trap Vector		
	Reserved		
	Reserved		
	Reserved		
	Interrupt Vector 0	0x000114	
	Interrupt Vector 1		
	~		
	~		
	~		Alternate Interrupt Vector Table (AIVT) <sup>(1)</sup>
	Interrupt Vector 52	0x00017C	
	Interrupt Vector 53	0x00017E	
	Interrupt Vector 54	0x000180	
	~		
	~		
	~		
	Interrupt Vector 116		
1	Interrupt Vector 117	0x0001FE	
4	Start of Code	0x000200	

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
—	—	AD1IE	U1TXIE	U1RXIE	SPI1IE	SPI1EIE	T3IE				
bit 15							bit 8				
R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0				
T2IE	OC2IE	IC2IE	—	T1IE	OC1IE	IC1IE	INT0IE				
bit 7							bit 0				
Г											
Legend:											
R = Readable	bit	W = Writable	bit	U = Unimpler	nented bit, read	l as '0'					
-n = Value at F	POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown				
			o.'								
DIT 15-14	Unimplement	ted: Read as	0.								
DIT 13	ADTIE: ADC1	Conversion C	complete inter	rupt Enable bit							
	0 = Interrupt r	equest enable	abled								
bit 12	U1TXIE: UAR	RT1 Transmitte	r Interrupt Ena	able bit							
	1 = Interrupt r	equest enable	d								
	0 = Interrupt r	equest not ena	abled								
bit 11	U1RXIE: UAF	RT1 Receiver I	nterrupt Enabl	le bit							
	1 = Interrupt r	equest enable	d								
bit 10		Event Interrun	ableu at Enable bit								
bit 10	1 = Interrupt r	equest enable	d								
	0 = Interrupt r	equest not en	abled								
bit 9	SPI1EIE: SPI	1 Error Interru	pt Enable bit								
	1 = Interrupt r	equest enable	d								
	0 = Interrupt r	equest not ena	abled								
bit 8	T3IE: Timer3	Interrupt Enab	le bit								
	1 = Interrupt r 0 = Interrupt r	equest enable	0 abled								
bit 7	T2IE: Timer2	Interrupt Fnab	le bit								
2	1 = Interrupt r	equest enable	d								
	0 = Interrupt r	equest not ena	abled								
bit 6	OC2IE: Outpu	ut Compare Ch	nannel 2 Interr	upt Enable bit							
	1 = Interrupt r	1 = Interrupt request enabled									
		equest not ena	abled								
DIT 5		apture Chann	ei 2 Interrupt i	Enable bit							
	0 = Interrupt r	equest enable	abled								
bit 4	Unimplemen	ted: Read as '	0'								
bit 3	T1IE: Timer1	Interrupt Enab	le bit								
	1 = Interrupt r	equest enable	d								
	0 = Interrupt r	equest not ena	abled								
bit 2	OC1IE: Outpu	ut Compare Ch	nannel 1 Interr	upt Enable bit							
	1 = Interrupt r	equest enable	d abled								

### REGISTER 7-8: IEC0: INTERRUPT ENABLE CONTROL REGISTER 0

### TABLE 8-1: CONFIGURATION BIT VALUES FOR CLOCK SELECTION

Oscillator Mode	Oscillator Source	POSCMD<1:0>	FNOSC<2:0>	Note
Fast RC Oscillator with Divide-by-N (FRCDIVN)	Internal	xx	111	1, 2
Fast RC Oscillator with Divide-by-16 (FRCDIV16)	Internal	xx	110	1
Low-Power RC Oscillator (LPRC)	Internal	xx	101	1
Secondary (Timer1) Oscillator (SOSC)	Secondary	xx	100	1
Primary Oscillator (HS) with PLL (HSPLL)	Primary	10	011	
Primary Oscillator (XT) with PLL (XTPLL)	Primary	01	011	
Primary Oscillator (EC) with PLL (ECPLL)	Primary	00	011	1
Primary Oscillator (HS)	Primary	10	010	
Primary Oscillator (XT)	Primary	01	010	
Primary Oscillator (EC)	Primary	00	010	1
Fast RC Oscillator with PLL (FRCPLL)	Internal	xx	001	1
Fast RC Oscillator (FRC)	Internal	xx	000	1

Note 1: OSC2 pin function is determined by the OSCIOFNC Configuration bit.

**2:** This is the default oscillator mode for an unprogrammed (erased) device.

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0 <sup>(1)</sup>
	_		—	—	_	_	PLLDIV<8>
bit 15	·				·		bit 8
R/W-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0
			PLLDI	V<7:0>			
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable	bit	U = Unimpler	mented bit, read	l as '0'	
-n = Value at I	POR	'1' = Bit is set	'0' = Bit is cleared		ared	x = Bit is unknown	
bit 15-9	Unimplemen	ted: Read as '	כ'				
bit 8-0	PLLDIV<8:0>	PLL Feedbac	k Divisor bits	(also denoted	as 'M', PLL mu	ltiplier)	
	111111111	= 513					
	•						
	•						
	•						
	000110000=	= 50 (default)					
	•						
	•						
	•						
	000000010 =	= 4					
	000000001 =	= 3 = 2					
	- 000000000	- 2					

## REGISTER 8-3: PLLFBD: PLL FEEDBACK DIVISOR REGISTER<sup>(1)</sup>

Note 1: This register is reset only on a Power-on Reset (POR).

## 9.0 POWER-SAVING FEATURES

- Note 1: This data sheet summarizes the features of the dsPIC33FJ12GP201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to Section 9. "Watchdog Timer and Power Savings Modes" (DS70196) of the "dsPIC33F/PIC24H Family Reference Manual", which is available from the Microchip website (www.microchip.com).
  - 2: Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The dsPIC33FJ12GP201/202 devices provide the ability to manage power consumption by selectively managing clocking to the CPU and the peripherals. In general, a lower clock frequency and a reduction in the number of circuits being clocked constitutes lower consumed power. dsPIC33FJ12GP201/202 devices can manage power consumption in four different ways:

- Clock frequency
- Instruction-based Sleep and Idle modes
- Software-controlled Doze mode
- Selective peripheral control in software

Combinations of these methods can be used to selectively tailor an application's power consumption while still maintaining critical application features, such as timing-sensitive communications.

### 9.1 Clock Frequency and Clock Switching

dsPIC33FJ12GP201/202 devices allow a wide range of clock frequencies to be selected under application control. If the system clock configuration is not locked, users can choose low-power or high-precision oscillators by simply changing the NOSC bits (OSCCON<10:8>). The process of changing a system clock during operation, as well as limitations to the process, are discussed in more detail in **Section 8.0 "Oscillator Configuration"**.

#### 9.2 Instruction-Based Power-Saving Modes

dsPIC33FJ12GP201/202 devices have two special power-saving modes that are entered through the execution of a special PWRSAV instruction. Sleep mode stops clock operation and halts all code execution. Idle mode halts the CPU and code execution, but allows peripheral modules to continue operation. The Assembler syntax of the PWRSAV instruction is shown in Example 9-1.

Note: SLEEP\_MODE and IDLE\_MODE are constants defined in the assembler include file for the selected device.

Sleep and Idle modes can be exited as a result of an enabled interrupt, WDT time-out, or a device Reset. When the device exits these modes, it is said to wake-up.

#### 9.2.1 SLEEP MODE

The following occur in Sleep mode:

- The system clock source is shut down. If an on-chip oscillator is used, it is turned off.
- The device current consumption is reduced to a minimum, provided that no I/O pin is sourcing current
- The Fail-Safe Clock Monitor does not operate, since the system clock source is disabled
- The LPRC clock continues to run if the WDT is enabled
- The WDT, if enabled, is automatically cleared prior to entering Sleep mode
- Some device features or peripherals may continue to operate. This includes items such as the input change notification on the I/O ports, or peripherals that use an external clock input.
- Any peripheral that requires the system clock source for its operation is disabled

The device will wake-up from Sleep mode on any of the these events:

- · Any interrupt source that is individually enabled
- · Any form of device Reset
- A WDT time-out

On wake-up from Sleep mode, the processor restarts with the same clock source that was active when Sleep mode was entered.

### EXAMPLE 9-1: PWRSAV INSTRUCTION SYNTAX

PWRSAV #SLEEP\_MODE ; Put the device into Sleep mode PWRSAV #IDLE\_MODE ; Put the device into Idle mode

#### REGISTER 10-8: RPINR20: PERIPHERAL PIN SELECT INPUT REGISTER 20

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—			SCK1R<4:0	>	
bit 15							bit 8
U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
		<u> </u>			SDI1R<4:0>	>	
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable	bit	U = Unimpler	nented bit, rea	id as '0'	
-n = Value at F	POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown
bit 15-13 bit 12-8 bit 7-5	Unimplement SCK1R<4:0> 11111 = Inpu 01111 = Inpu	ted: Read as ' : Assign SPI1 ( t tied to Vss t tied to RP15 t tied to RP1 t tied to RP1 t tied to RP0	<sub>D</sub> , Clock Input (S	SCK1IN) to the	corresponding	RPn pin bits	
bit 4-0	SDI1R<4.0>	Assign SPI1 D	ο lata Input (SΓ	)11) to the corre	sponding RPr	nin hits	
	11111 = Inpu 01111 = Inpu • • • 00001 = Inpu 00000 = Inpu	t tied to RP15 t tied to RP15 t tied to RP1				. pin 010	

#### REGISTER 10-11: RPOR1: PERIPHERAL PIN SELECT OUTPUT REGISTERS 1

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
_					RP3R<4:0>			
bit 15							bit 8	
U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
—	—	—			RP2R<4:0>			
bit 7							bit 0	
Legend:								
R = Readable I	oit	W = Writable I	bit	U = Unimpler	U = Unimplemented bit, read as '0'			
-n = Value at P	OR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown	
bit 15-13	Unimplemen	ted: Read as 'd	)'					
bit 12-8 <b>RP3R&lt;4:0&gt;:</b> Peripheral Output Function is Assigned to RP3 Output Pin bits (see Table 10-2 for peripheral function numbers)								
bit 7-5	Unimplemen	ted: Read as 'd	)'					

bit 4-0 **RP2R<4:0>:** Peripheral Output Function is Assigned to RP2 Output Pin bits (see Table 10-2 for peripheral function numbers)

#### REGISTER 10-12: RPOR2: PERIPHERAL PIN SELECT OUTPUT REGISTERS 2

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—			RP5R<4:0>		
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—			RP4R<4:0>		
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-13 Unimplemented: Read as '0'

bit 12-8 **RP5R<4:0>:** Peripheral Output Function is Assigned to RP5 Output Pin bits (see Table 10-2 for peripheral function numbers)

bit 7-5 Unimplemented: Read as '0'

bit 4-0 **RP4R<4:0>:** Peripheral Output Function is Assigned to RP4 Output Pin bits (see Table 10-2 for peripheral function numbers)

## 13.0 INPUT CAPTURE

- Note 1: This data sheet summarizes the features of the dsPIC33FJ12GP201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to Section 12. "Input Capture" (DS70198) of the "dsPIC33F/ PIC24H Family Reference Manual", which is available from the Microchip website (www.microchip.com).
  - 2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The Input Capture module is useful in applications requiring frequency (period) and pulse measurement. The dsPIC33FJ12GP201/202 devices support up to eight input capture channels.

The Input Capture module captures the 16-bit value of the selected Time Base register when an event occurs at the ICx pin. The events that cause a capture event are listed below in three categories:

- Simple Capture Event modes:
  - Capture timer value on every falling edge of input at ICx pin
  - Capture timer value on every rising edge of input at ICx pin
- Capture timer value on every edge (rising and falling)
- Prescaler Capture Event modes:
  - Capture timer value on every 4th rising edge of input at ICx pin
  - Capture timer value on every 16th rising edge of input at ICx pin

Each Input Capture channel can select one of two 16-bit timers (Timer2 or Timer3) for the time base. The selected timer can use either an internal or external clock.

Other operational features include:

- Device wake-up from capture pin during CPU Sleep and Idle modes
- · Interrupt on Input Capture event
- · 4-word FIFO buffer for capture values
  - Interrupt optionally generated after 1, 2, 3, or 4 buffer locations are filled
- · Use of Input Capture to provide additional



#### FIGURE 13-1: INPUT CAPTURE BLOCK DIAGRAM

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
SPIEN		SPISIDL	_			_	_
bit 15		•				•	bit 8
U-0	R/C-0	U-0	U-0	U-0	U-0	R-0	R-0
—	SPIROV	—	_	—	—	SPITBF	SPIRBF
bit 7							bit 0
Legend:		C = Clearable	bit				
R = Readable	bit	W = Writable	bit	U = Unimple	mented bit, read	as '0'	
-n = Value at F	POR	'1' = Bit is set		'0' = Bit is cle	eared	x = Bit is unkr	iown
bit 15	SPIEN: SPIx	Enable bit					
	1 = Enables n	nodule and cor	ifigures SCKx	, SDOx, SDIx,	and SSx as ser	ial port pins	
1.11.4.4		module	.1				
DIT 14	Unimplemen	ted: Read as "	).				
bit 13	SPISIDL: Sto	p in Idle Mode	bit				
	1 = Discontinu 0 = Continue	ue module opel module operati	on in Idle mo	evice enters ic de	die mode		
bit 12-7	Unimplemen	ted: Read as '	)'				
bit 6	SPIROV: Rec	eive Overflow I	Flag bit				
	1 = A new by	rte/word is com	pletely receive	ed and discard	led. The user so	oftware has not	read the
	previous	data in the SPI	xBUF register				
<b>h</b> # <b>F</b> 0		ow has occurre	a.				
DIL D-Z		Teo: Read as		L :4			
DIT	SPITEF: SPIX	C I ransmit Buffe		DIC			
	$\perp$ = Transmit	started SPIxT	Brix I AB IS II				
	Automatically	set in hardwar	e when CPU	writes SPIxBU	F location, loadi	ng SPIxTXB	
	Automatically	cleared in hard	lware when S	Plx module tra	ansfers data fror	n SPIxTXB to S	SPIxSR
bit 0	SPIRBF: SPI	x Receive Buffe	er Full Status I	bit			
	1 = Receive c	complete, SPIx	RXB is full				
	0 = Receive is	s not complete,	SPIxRXB is e	empty			
	Automatically	cleared in hard	e when SPIX I Iware when o	nansiers data	RUF location in	SMIXKAB eading SPIvRX	(B
	, atomatically						

#### REGISTER 15-1: SPIxSTAT: SPIx STATUS AND CONTROL REGISTER

## 19.2 On-Chip Voltage Regulator

The dsPIC33FJ12GP201/202 devices power their core digital logic at a nominal 2.5V. This can create a conflict for designs that are required to operate at a higher typical voltage, such as 3.3V. To simplify system design, both devices in the dsPIC33FJ12GP201/202 family incorporate an on-chip regulator that allows the device to run its core logic from VDD.

The regulator provides power to the core from the other VDD pins. When the regulator is enabled, a low ESR (less than 5 ohms) capacitor (such as tantalum or ceramic) must be connected to the VCAP pin (Figure 19-1). This helps to maintain the stability of the regulator. The recommended value for the filter capacitor is provided in Table 22-13 located in **Section 22.1** "**DC Characteristics**".

Note:	It is important for low-ESR capacitors to
	be placed as close as possible to the VCAP
	pin.

On a POR, it takes approximately 20 µs for the on-chip voltage regulator to generate an output voltage. During this time, designated as TSTARTUP, code execution is disabled. TSTARTUP is applied every time the device resumes operation after any power-down.

#### FIGURE 19-1: CONNECTIONS FOR THE ON-CHIP VOLTAGE REGULATOR<sup>(1,2,3)</sup>



### 19.3 BOR Module

The BOR module is based on an internal voltage reference circuit that monitors the regulated voltage VCAP. The main purpose of the BOR module is to generate a device Reset when a brown-out condition occurs. Brown-out conditions are generally caused by glitches on the AC mains (for example, missing portions of the AC cycle waveform due to bad power transmission lines, or voltage sags due to excessive current draw when a large inductive load is turned on).

A BOR generates a Reset pulse, which resets the device. The BOR selects the clock source, based on the device Configuration bit values (FNOSC<2:0> and POSCMD<1:0>).

If an oscillator mode is selected, the BOR activates the Oscillator Start-up Timer (OST). The system clock is held until OST expires. If the PLL is used, the clock is held until the LOCK bit (OSCCON<5>) is '1'.

Concurrently, the PWRT time-out (TPWRT) will be applied before the internal Reset is released. If TPWRT = 0 and a crystal oscillator is being used, a nominal delay of TFSCM = 100 is applied. The total delay in this case is TFSCM.

The BOR Status bit (RCON<1>) is set to indicate that a BOR has occurred. The BOR circuit continues to operate while in Sleep or Idle modes and resets the device should VDD fall below the BOR threshold voltage.

TABLE 22-4:	DC TEMPERATURE AND VOLTAGE SPECIFICATIONS

DC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V         (unless otherwise stated)         Operating temperature       -40°C ≤TA ≤+85°C for Industrial         -40°C ≤TA ≤+125°C for Extended					
Param No.	Symbol Characteristic		Min	Тур <sup>(1)</sup>	Max	Units	Conditions
Operati	Operating Voltage						
DC10	Supply V	/oltage					
	Vdd		3.0	-	3.6	V	Industrial and Extended
DC12	Vdr	RAM Data Retention Voltage <sup>(2)</sup>	1.8	_	—	V	
DC16	VPOR	VDD <b>Start Voltage<sup>(3)</sup></b> to ensure internal Power-on Reset signal	_	_	Vss	V	
DC17	Svdd	VDD Rise Rate to ensure internal Power-on Reset signal	0.03	_	—	V/ms	0-3.0V in 0.1s

Note 1: Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

2: This is the limit to which VDD can be lowered without losing RAM data.

3: VDD voltage must remain at Vss for a minimum of 200 µs to ensure POR.



## FIGURE 22-11: SPIx MASTER MODE (FULL-DUPLEX, CKE = 1, CKP = x, SMP = 1) TIMING CHARACTERISTICS

## TABLE 22-30:SPIX MASTER MODE (FULL-DUPLEX, CKE = 1, CKP = x, SMP = 1) TIMING<br/>REQUIREMENTS

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V         (unless otherwise stated)         Operating temperature       -40°C ≤TA ≤+85°C for Industrial         -40°C ≤TA ≤+125°C for Extended					
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Тур <sup>(2)</sup>	Max	Units	Conditions
SP10	TscP	Maximum SCK Frequency	_	—	9	MHz	See Note 3
SP20	TscF	SCKx Output Fall Time	_	—	_	ns	See parameter DO32 and <b>Note 4</b>
SP21	TscR	SCKx Output Rise Time	—	—	_	ns	See parameter DO31 and <b>Note 4</b>
SP30	TdoF	SDOx Data Output Fall Time	—	—	_	ns	See parameter DO32 and <b>Note 4</b>
SP31	TdoR	SDOx Data Output Rise Time	_	_		ns	See parameter DO31 and <b>Note 4</b>
SP35	TscH2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	6	20	ns	—
SP36	TdoV2sc, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	30	_		ns	
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	30	_	_	ns	_
SP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	30	_	_	ns	

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

- **3:** The minimum clock period for SCKx is 111 ns. The clock generated in Master mode must not violate this specification.
- **4:** Assumes 50 pF load on all SPIx pins.



## **FIGURE 22-21:** ADC CONVERSION (12-BIT MODE) TIMING CHARACTERISTICS

### TABLE 22-41: ADC CONVERSION (12-BIT MODE) TIMING REQUIREMENTS

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V         (unless otherwise stated)         Operating temperature       -40°C ≤TA ≤+85°C for Industrial         -40°C ≤TA ≤+125°C for Extended					
Param No.	Symbol	Characteristic	Min.	Min. Typ Max. Units Conditions			Conditions
		Clock	Paramete	ers <sup>(1)</sup>			
AD50	TAD	ADC Clock Period	117.6		—	ns	
AD51	tRC	ADC Internal RC Oscillator Period	—	250	—	ns	
Conversion Rate							
AD55	tCONV	Conversion Time	—	14 Tad		ns	
AD56	FCNV	Throughput Rate			500	Ksps	
AD57	TSAMP	Sample Time	3.0 Tad		—	—	
Timing Parameters							
AD60	tPCS	Conversion Start from Sample Trigger <sup>(2)</sup>	2.0 Tad	_	3.0 Tad	_	Auto Convert Trigger not selected
AD61	tpss	Sample Start from Setting Sample (SAMP) bit <sup>(2)</sup>	2.0 Tad	—	3.0 Tad	—	—
AD62	tcss	Conversion Completion to Sample Start (ASAM = $1$ ) <sup>(2)</sup>	—	0.5 Tad	—	_	—
AD63	tDPU	Time to Stabilize Analog Stage from ADC Off to ADC On <sup>(2)</sup>		—	20	μs	—

Note 1: Because the sample caps will eventually lose charge, clock rates below 10 kHz can affect linearity performance, especially at elevated temperatures.

2: These parameters are characterized but not tested in manufacturing.

### 28-Lead Skinny Plastic Dual In-Line (SP) – 300 mil Body [SPDIP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units	INCHES			
Dimensio	n Limits	MIN	NOM	MAX	
Number of Pins	Ν	28			
Pitch	е		.100 BSC		
Top to Seating Plane	А	—	—	.200	
Molded Package Thickness	A2	.120	.135	.150	
Base to Seating Plane	A1	.015	-	—	
Shoulder to Shoulder Width	E	.290	.310	.335	
Molded Package Width	E1	.240	.285	.295	
Overall Length	D	1.345	1.365	1.400	
Tip to Seating Plane	L	.110	.130	.150	
Lead Thickness	С	.008	.010	.015	
Upper Lead Width	b1	.040	.050	.070	
Lower Lead Width	b	.014	.018	.022	
Overall Row Spacing §	eB	_	_	.430	

#### Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. § Significant Characteristic.

3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" per side.

4. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-070B

#### TABLE 23-1: MAJOR SECTION UPDATES

Section Name	Update Description
Section 22.0 "Electrical Characteristics"	Updated Max MIPS value for -40°C to +125°C temperature range in Operating MIPS vs. Voltage (see Table 22-1).
	Added 28-pin SSOP package information to Thermal Packaging Characteristics and updated Typical values for all devices (see Table 22-3).
	Removed Typ value for parameter DC12 (see Table 22-4).
	Updated Note 2 in Table 22-7: DC Characteristics: Power-Down Current (IPD).
	Updated MIPS conditions for parameters DC24c, DC44c, DC72a, DC72f, and DC72g (see Table 22-5, Table 22-6, and Table 22-8).
	Added Note 4 (reference to new table containing digital-only and analog pin information to I/O Pin Input Specifications (see Table 22-9).
	Updated Program Memory parameters (D136a, D136b, D137a, D137b, D138a, and D138b) and added Note 2 (see Table 22-12).
	Updated Max value for Internal RC Accuracy parameter F21 for -40°C $\leq$ TA $\leq$ +125°C condition and added Note 2 (see Table 22-19).
	Removed all values for Reset, Watchdog Timer, Oscillator Start-up Timer, and Power-up Timer parameter SY20 and updated conditions, which now refers to <b>Section 19.4 "Watchdog Timer (WDT)</b> " and LPRC parameter F21 (see Table 22-21).
	The following changes were made to the ADC Module Specifications (Table 22-34):
	Updated Min value for ADC Module Specification parameter AD07
	Updated Typ value for parameter AD08
	Removed parameter AD10     Added references to Note 1 for parameters AD12 and AD12
	Removed Note 2
	The following changes were made to the ADC Module Specifications (12-bit Mode) (Table 22-35):
	<ul> <li>Updated Min and Max values for both AD21a parameters (measurements with <i>internal</i> and <i>external</i> VREF+/VREF-).</li> </ul>
	<ul> <li>Updated Min, Typ, and Max values for parameter AD24a.</li> </ul>
	Updated Max value for parameter AD32a.
	Removed Note 1.     Demoved Variations for necessary AD21a, AD22a
	• Removed VREFL from Conditions for parameters AD21a, AD22a, AD23a, and AD24a (measurements with <i>internal</i> VREF+/VREF-).
	The following changes were made to the ADC Module Specifications (10-bit Mode) (Table 22-36):
	<ul> <li>Updated Min and Max values for parameter AD21b (measurements with <i>external</i> VREF+/VREF-).</li> </ul>
	<ul> <li>Removed ± symbol from Min, Typ, and Max values for parameters AD23b and AD24b (measurements with <i>internal</i> VREF+/VREF-).</li> </ul>
	Updated Typ and Max values for parameter AD32b.
	Kemoved Note 1.     Bemoved VEEEL from Conditions for personators AD045, AD025
	AD23a, and AD24a (measurements with <i>internal</i> VREF+/VREF-).
	Updated Min and Typ values for parameters AD60, AD61, AD62, and AD63 and removed Note 3 (see Table 22-37 and Table 22-38).

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