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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	25MHz
Connectivity	EBI/EMI, I²C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, HLVD, POR, PWM, WDT
Number of I/O	70
Program Memory Size	128KB (64K x 16)
Program Memory Type	FLASH
EEPROM Size	1K x 8
RAM Size	3.8K x 8
Voltage - Supply (Vcc/Vdd)	4.2V ~ 5.5V
Data Converters	A/D 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	80-TQFP
Supplier Device Package	80-TQFP (12x12)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18f8723-e-pt

NOTES:

1.0 DEVICE OVERVIEW

This document contains device-specific information for the following devices:

- PIC18F6628
- PIC18F6723
- PIC18F8628
- PIC18F8723
- PIC18LF6628
- PIC18LF6723
- PIC18LF8628
- PIC18LF8723

Note: This data sheet documents only the devices' features and specifications that are in addition to the features and specifications of the PIC18F8722 family devices. For information on the features and specifications shared by the PIC18F8723 family and PIC18F8722 family devices, see the *"PIC18F8722 Family Data Sheet"* (DS39646).

The PIC18F8723 family of devices offers the advantages of all PIC18 microcontrollers – namely, high computational performance at an economical price – with the addition of high-endurance, Enhanced Flash program memory. In addition to these features, the PIC18F8723 introduces design enhancements that make these microcontrollers a logical choice for many high-performance, power-sensitive applications.

1.1 Special Features

- **12-Bit A/D Converter:** The PIC18F8723 family implements a 12-bit A/D Converter. A/D Converters in both families incorporate programmable acquisition time. This allows for a channel to be selected and a conversion to be initiated, without waiting for a sampling period and thus, reducing code overhead.

1.2 Details on Individual Family Members

Devices in the PIC18F8723 family are available in 64-pin and 80-pin packages. Block diagrams for the two groups are shown in Figure 1-1 and Figure 1-2.

The devices are differentiated from each other in the following ways:

- Flash program memory (96 Kbytes for PIC18FX628 devices and 128 Kbytes for PIC18FX723).
- A/D channels (12 for PIC18F6628/6723 devices and 16 for PIC18F8628/8723 devices).
- I/O ports (seven bidirectional ports on PIC18F6628/6723 devices and nine bidirectional ports on PIC18F8628/8723 devices).
- External Memory Bus, configurable for 8 and 16-bit operation

All other features for devices in this family are identical. These are summarized in Table 1-1.

The pinouts for all devices are listed in Table 1-2 and Table 1-3.

Like all Microchip PIC18 devices, members of the PIC18F8723 family are available as both standard and low-voltage devices. Standard devices with Enhanced Flash memory, designated with an "F" in the part number (such as PIC18**F**6628), accommodate an operating VDD range of 4.2V to 5.5V. Low-voltage parts, designated by "LF" (such as PIC18**LF**6628), function over an extended VDD range of 2.0V to 5.5V.

TABLE 1-2: PIC18F6628/6723 (64-PIN) PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number	Pin Type	Buffer Type	Description
	TQFP			
				PORTB is a bidirectional I/O port. PORTB can be software programmed for internal weak pull-ups on all inputs.
RB0/INT0/FLT0	48			
RB0		I/O	TTL	Digital I/O.
INT0		I	ST	External interrupt 0.
FLT0		I	ST	PWM Fault input for ECCPx.
RB1/INT1	47			
RB1		I/O	TTL	Digital I/O.
INT1		I	ST	External interrupt 1.
RB2/INT2	46			
RB2		I/O	TTL	Digital I/O.
INT2		I	ST	External interrupt 2.
RB3/INT3	45			
RB3		I/O	TTL	Digital I/O.
INT3		I	ST	External interrupt 3.
RB4/KBI0	44			
RB4		I/O	TTL	Digital I/O.
KBI0		I	TTL	Interrupt-on-change pin.
RB5/KBI1/PGM	43			
RB5		I/O	TTL	Digital I/O.
KBI1		I	TTL	Interrupt-on-change pin.
PGM		I/O	ST	Low-Voltage ICSP™ Programming enable pin.
RB6/KBI2/PGC	42			
RB6		I/O	TTL	Digital I/O.
KBI2		I	TTL	Interrupt-on-change pin.
PGC		I/O	ST	In-Circuit Debugger and ICSP programming clock pin.
RB7/KBI3/PGD	37			
RB7		I/O	TTL	Digital I/O.
KBI3		I	TTL	Interrupt-on-change pin.
PGD		I/O	ST	In-Circuit Debugger and ICSP programming data pin.

Legend: TTL = TTL compatible input; CMOS = CMOS compatible input or output; ST = Schmitt Trigger input with CMOS levels; Analog = Analog input; I = Input; O = Output; P = Power; I^2C™ = I^2C/SMBus input buffer

Note 1: Default assignment for ECCP2 when Configuration bit, CCP2MX, is set.

2: Alternate assignment for ECCP2 when Configuration bit, CCP2MX, is cleared.

TABLE 1-2: PIC18F6628/6723 (64-PIN) PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number	Pin Type	Buffer Type	Description
	TQFP			
				PORTD is a bidirectional I/O port.
RD0/PSP0	58			
RD0		I/O	ST	Digital I/O.
PSP0		I/O	TTL	Parallel Slave Port data.
RD1/PSP1	55			
RD1		I/O	ST	Digital I/O.
PSP1		I/O	TTL	Parallel Slave Port data.
RD2/PSP2	54			
RD2		I/O	ST	Digital I/O.
PSP2		I/O	TTL	Parallel Slave Port data.
RD3/PSP3	53			
RD3		I/O	ST	Digital I/O.
PSP3		I/O	TTL	Parallel Slave Port data.
RD4/PSP4/SDO2	52			
RD4		I/O	ST	Digital I/O.
PSP4		I/O	TTL	Parallel Slave Port data.
SDO2		O	—	SPI data out.
RD5/PSP5/SDI2/ SDA2	51			
RD5		I/O	ST	Digital I/O.
PSP5		I/O	TTL	Parallel Slave Port data.
SDI2		I	ST	SPI data in.
SDA2		I/O	I^2C/SMB	I^2C™ data I/O.
RD6/PSP6/SCK2/ SCL2	50			
RD6		I/O	ST	Digital I/O.
PSP6		I/O	TTL	Parallel Slave Port data.
SCK2		I/O	ST	Synchronous serial clock input/output for SPI mode.
SCL2		I/O	I^2C/SMB	Synchronous serial clock input/output for I^2C mode.
RD7/PSP7/$\overline{SS2}$	49			
RD7		I/O	ST	Digital I/O.
PSP7		I/O	TTL	Parallel Slave Port data.
$\overline{SS2}$		I	TTL	SPI slave select input.

Legend: TTL = TTL compatible input; CMOS = CMOS compatible input or output; ST = Schmitt Trigger input with CMOS levels; Analog = Analog input; I = Input; O = Output; P = Power; I^2C™ = I^2C/SMBus input buffer

Note 1: Default assignment for ECCP2 when Configuration bit, CCP2MX, is set.

2: Alternate assignment for ECCP2 when Configuration bit, CCP2MX, is cleared.

TABLE 1-2: PIC18F6628/6723 (64-PIN) PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number	Pin Type	Buffer Type	Description
	TQFP			
				PORTF is a bidirectional I/O port.
RF0/AN5	18			
RF0		I/O	ST	Digital I/O.
AN5		I	Analog	Analog input 5.
RF1/AN6/C2OUT	17			
RF1		I/O	ST	Digital I/O.
AN6		I	Analog	Analog input 6.
C2OUT		O	—	Comparator 2 output.
RF2/AN7/C1OUT	16			
RF2		I/O	ST	Digital I/O.
AN7		I	Analog	Analog input 7.
C1OUT		O	—	Comparator 1 output.
RF3/AN8	15			
RF3		I/O	ST	Digital I/O.
AN8		I	Analog	Analog input 8.
RF4/AN9	14			
RF4		I/O	ST	Digital I/O.
AN9		I	Analog	Analog input 9.
RF5/AN10/CVREF	13			
RF5		I/O	ST	Digital I/O.
AN10		I	Analog	Analog input 10.
CVREF		O	Analog	Comparator reference voltage output.
RF6/AN11	12			
RF6		I/O	ST	Digital I/O.
AN11		I	Analog	Analog input 11.
RF7/$\overline{SS1}$	11			
RF7		I/O	ST	Digital I/O.
$\overline{SS1}$		I	TTL	SPI slave select input.

Legend: TTL = TTL compatible input; CMOS = CMOS compatible input or output; ST = Schmitt Trigger input with CMOS levels; Analog = Analog input; I = Input; O = Output; P = Power; I^2C™ = I^2C/SMBus input buffer

Note 1: Default assignment for ECCP2 when Configuration bit, CCP2MX, is set.

2: Alternate assignment for ECCP2 when Configuration bit, CCP2MX, is cleared.

TABLE 1-3: PIC18F8628/8723 (80-PIN) PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number	Pin Type	Buffer Type	Description
	TQFP			
				PORTA is a bidirectional I/O port.
RA0/AN0	30			
RA0		I/O	TTL	Digital I/O.
AN0		I	Analog	Analog input 0.
RA1/AN1	29			
RA1		I/O	TTL	Digital I/O.
AN1		I	Analog	Analog input 1.
RA2/AN2/VREF-	28			
RA2		I/O	TTL	Digital I/O.
AN2		I	Analog	Analog input 2.
VREF-		I	Analog	A/D reference voltage (low) input.
RA3/AN3/VREF+	27			
RA3		I/O	TTL	Digital I/O.
AN3		I	Analog	Analog input 3.
VREF+		I	Analog	A/D reference voltage (high) input.
RA4/T0CKI	34			
RA4		I/O	ST	Digital I/O.
T0CKI		I	ST	Timer0 external clock input.
RA5/AN4/HLVDIN	33			
RA5		I/O	TTL	Digital I/O.
AN4		I	Analog	Analog input 4.
HLVDIN		I	Analog	High/Low-Voltage Detect input.
RA6				See the OSC2/CLKO/RA6 pin.
RA7				See the OSC1/CLKI/RA7 pin.

Legend: TTL = TTL compatible input; CMOS = CMOS compatible input or output; ST = Schmitt Trigger input with CMOS levels; Analog = Analog input; I = Input; O = Output; P = Power; I^2C™/SMB = I^2C/SMBus input buffer

Note 1: Alternate assignment for ECCP2 when Configuration bit, CCP2MX, is cleared (all operating modes except Microcontroller mode).

2: Default assignment for ECCP2 in all operating modes (CCP2MX is set).

3: Alternate assignment for ECCP2 when CCP2MX is cleared (Microcontroller mode only).

4: Default assignment for P1B/P1C/P3B/P3C (ECCPMX is set).

5: Alternate assignment for P1B/P1C/P3B/P3C (ECCPMX is clear).

TABLE 1-3: PIC18F8628/8723 (80-PIN) PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number	Pin Type	Buffer Type	Description
	TQFP			
				PORTF is a bidirectional I/O port.
RF0/AN5	24			
RF0		I/O	ST	Digital I/O.
AN5		I	Analog	Analog input 5.
RF1/AN6/C2OUT	23			
RF1		I/O	ST	Digital I/O.
AN6		I	Analog	Analog input 6.
C2OUT		O	—	Comparator 2 output.
RF2/AN7/C1OUT	18			
RF2		I/O	ST	Digital I/O.
AN7		I	Analog	Analog input 7.
C1OUT		O	—	Comparator 1 output.
RF3/AN8	17			
RF3		I/O	ST	Digital I/O.
AN8		I	Analog	Analog input 8.
RF4/AN9	16			
RF4		I/O	ST	Digital I/O.
AN9		I	Analog	Analog input 9.
RF5/AN10/CVREF	15			
RF5		I/O	ST	Digital I/O.
AN10		I	Analog	Analog input 10.
CVREF		O	Analog	Comparator reference voltage output.
RF6/AN11	14			
RF6		I/O	ST	Digital I/O.
AN11		I	Analog	Analog input 11.
RF7/$\overline{SS1}$	13			
RF7		I/O	ST	Digital I/O.
$\overline{SS1}$		I	TTL	SPI slave select input.

Legend: TTL = TTL compatible input; CMOS = CMOS compatible input or output; ST = Schmitt Trigger input with CMOS levels; Analog = Analog input; I = Input; O = Output; P = Power; I^2C™/SMB = I^2C/SMBus input buffer

Note 1: Alternate assignment for ECCP2 when Configuration bit, CCP2MX, is cleared (all operating modes except Microcontroller mode).

2: Default assignment for ECCP2 in all operating modes (CCP2MX is set).

3: Alternate assignment for ECCP2 when CCP2MX is cleared (Microcontroller mode only).

4: Default assignment for P1B/P1C/P3B/P3C (ECCPMX is set).

5: Alternate assignment for P1B/P1C/P3B/P3C (ECCPMX is clear).

TABLE 1-3: PIC18F8628/8723 (80-PIN) PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number	Pin Type	Buffer Type	Description
	TQFP			
				PORTG is a bidirectional I/O port.
RG0/ECCP3/P3A	5			
RG0		I/O	ST	Digital I/O.
ECCP3		I/O	ST	Enhanced Capture 3 input/Compare 3 output/ PWM3 output.
P3A		O	—	ECCP3 PWM output A.
RG1/TX2/CK2	6			
RG1		I/O	ST	Digital I/O.
TX2		O	—	EUSART2 asynchronous transmit.
CK2		I/O	ST	EUSART2 synchronous clock (see related RX2/DT2).
RG2/RX2/DT2	7			
RG2		I/O	ST	Digital I/O.
RX2		I	ST	EUSART2 asynchronous receive.
DT2		I/O	ST	EUSART2 synchronous data (see related TX2/CK2).
RG3/CCP4/P3D	8			
RG3		I/O	ST	Digital I/O.
CCP4		I/O	ST	Capture 4 input/Compare 4 output/PWM4 output.
P3D		O	—	ECCP3 PWM output D.
RG4/CCP5/P1D	10			
RG4		I/O	ST	Digital I/O.
CCP5		I/O	ST	Capture 5 input/Compare 5 output/PWM5 output.
P1D		O	—	ECCP1 PWM output D.
RG5				See RG5/$\overline{\text{MCLR}}$/V_{PP} pin.

Legend: TTL = TTL compatible input; CMOS = CMOS compatible input or output; ST = Schmitt Trigger input with CMOS levels; Analog = Analog input; I = Input; O = Output; P = Power; I^2C™/SMB = I^2C/SMBus input buffer

Note 1: Alternate assignment for ECCP2 when Configuration bit, CCP2MX, is cleared (all operating modes except Microcontroller mode).

2: Default assignment for ECCP2 in all operating modes (CCP2MX is set).

3: Alternate assignment for ECCP2 when CCP2MX is cleared (Microcontroller mode only).

4: Default assignment for P1B/P1C/P3B/P3C (ECCPMX is set).

5: Alternate assignment for P1B/P1C/P3B/P3C (ECCPMX is clear).

TABLE 1-3: PIC18F8628/8723 (80-PIN) PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number	Pin Type	Buffer Type	Description
	TQFP			
				PORTH is a bidirectional I/O port.
RH0/A16	79			
RH0		I/O	ST	Digital I/O.
A16		I/O	TTL	External memory address/data 16.
RH1/A17	80			
RH1		I/O	ST	Digital I/O.
A17		I/O	TTL	External memory address/data 17.
RH2/A18	1			
RH2		I/O	ST	Digital I/O.
A18		I/O	TTL	External memory address/data 18.
RH3/A19	2			
RH3		I/O	ST	Digital I/O.
A19		I/O	TTL	External memory address/data 19.
RH4/AN12/P3C	22			
RH4		I/O	ST	Digital I/O.
AN12		I	Analog	Analog input 12.
P3C(5)		O	—	ECCP3 PWM output C.
RH5/AN13/P3B	21			
RH5		I/O	ST	Digital I/O.
AN13		I	Analog	Analog input 13.
P3B(5)		O	—	ECCP3 PWM output B.
RH6/AN14/P1C	20			
RH6		I/O	ST	Digital I/O.
AN14		I	Analog	Analog input 14.
P1C(5)		O	—	ECCP1 PWM output C.
RH7/AN15/P1B	19			
RH7		I/O	ST	Digital I/O.
AN15		I	Analog	Analog input 15.
P1B(5)		O	—	ECCP1 PWM output B.

Legend: TTL = TTL compatible input; CMOS = CMOS compatible input or output; ST = Schmitt Trigger input with CMOS levels; Analog = Analog input; I = Input; O = Output; P = Power; I^2C™/SMB = I^2C/SMBus input buffer

Note 1: Alternate assignment for ECCP2 when Configuration bit, CCP2MX, is cleared (all operating modes except Microcontroller mode).

2: Default assignment for ECCP2 in all operating modes (CCP2MX is set).

3: Alternate assignment for ECCP2 when CCP2MX is cleared (Microcontroller mode only).

4: Default assignment for P1B/P1C/P3B/P3C (ECCPMX is set).

5: Alternate assignment for P1B/P1C/P3B/P3C (ECCPMX is clear).

2.0 12-BIT ANALOG-TO-DIGITAL CONVERTER (A/D) MODULE

The Analog-to-Digital (A/D) Converter module has 12 inputs for the 64-pin devices (PIC18F6628/6723) and 16 for the 80-pin devices (PIC18F8628/8723). This module allows conversion of an analog input signal to a corresponding 12-bit digital number.

The module has five registers:

- A/D Result High Register (ADRESH)
- A/D Result Low Register (ADRESL)
- A/D Control Register 0 (ADCON0)
- A/D Control Register 1 (ADCON1)
- A/D Control Register 2 (ADCON2)

The ADCON0 register, shown in Register 2-1, controls the operation of the A/D module. The ADCON1 register, shown in Register 2-2, configures the functions of the port pins. The ADCON2 register, shown in Register 2-3, configures the A/D clock source, programmed acquisition time and justification.

REGISTER 2-1: ADCON0: A/D CONTROL REGISTER 0

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	CHS3	CHS2	CHS1	CHS0	GO/$\overline{\text{DONE}}$	ADON
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7-6 **Unimplemented:** Read as '0'

bit 5-2 **CHS3:CHS0:** Analog Channel Select bits
0000 = Channel 0 (AN0)
0001 = Channel 1 (AN1)
0010 = Channel 2 (AN2)
0011 = Channel 3 (AN3)
0100 = Channel 4 (AN4)
0101 = Channel 5 (AN5)
0110 = Channel 6 (AN6)
0111 = Channel 7 (AN7)
1000 = Channel 8 (AN8)
1001 = Channel 9 (AN9)
1010 = Channel 10 (AN10)
1011 = Channel 11 (AN11)
1100 = Channel 12 (AN12)**(1,2)**
1101 = Channel 13 (AN13)**(1,2)**
1110 = Channel 14 (AN14)**(1,2)**
1111 = Channel 15 (AN15)**(1,2)**

bit 1 **GO/$\overline{\text{DONE}}$:** A/D Conversion Status bit
When ADON = 1:
1 = A/D conversion in progress
0 = A/D Idle

bit 0 **ADON:** A/D On bit
1 = A/D Converter module is enabled
0 = A/D Converter module is disabled

Note 1: These channels are not implemented on PIC18F6628/6723 devices.
2: Performing a conversion on unimplemented channels will return a floating input measurement.

2.1 A/D Acquisition Requirements

For the A/D Converter to meet its specified accuracy, the charge holding capacitor (CHOLD) must be allowed to fully charge to the input channel voltage level. The analog input model is shown in Figure 2-3. The source impedance (RS) and the internal sampling switch (RSS) impedance directly affect the time required to charge the capacitor, CHOLD. The sampling switch (RSS) impedance varies over the device voltage (VDD). The source impedance affects the offset voltage at the analog input (due to pin leakage current). **The maximum recommended impedance for analog sources is 2.5 kΩ**. After the analog input channel is selected (changed), the channel must be sampled for at least the minimum acquisition time before starting a conversion.

Note:	When the conversion is started, the holding capacitor is disconnected from the input pin.

To calculate the minimum acquisition time, Equation 2-1 may be used. This equation assumes that 1/2 LSb error is used (4096 steps for the 12-bit A/D). The 1/2 LSb error is the maximum error allowed for the A/D to meet its specified resolution.

Example 2-3 shows the calculation of the minimum required acquisition time, TACQ. This calculation is based on the following application system assumptions:

CHOLD	=	25 pF
Rs	=	2.5 kΩ
Conversion Error	≤	1/2 LSb
VDD	=	3V → Rss = 4 kΩ
Temperature	=	85°C (system max.)

EQUATION 2-1: ACQUISITION TIME

$$T_{ACQ} = \text{Amplifier Settling Time} + \text{Holding Capacitor Charging Time} + \text{Temperature Coefficient}$$
$$= T_{AMP} + T_C + T_{COFF}$$

EQUATION 2-2: A/D MINIMUM CHARGING TIME

$$V_{HOLD} = (V_{REF} - (V_{REF}/4096)) \cdot (1 - e^{(-T_C/C_{HOLD}(R_{IC} + R_{SS} + R_S))})$$
or
$$T_C = -(C_{HOLD})(R_{IC} + R_{SS} + R_S) \ln(1/4096)$$

EQUATION 2-3: CALCULATING THE MINIMUM REQUIRED ACQUISITION TIME

$$T_{ACQ} = T_{AMP} + T_C + T_{COFF}$$
$$T_{AMP} = 0.2\ \mu s$$
$$T_{COFF} = (\text{Temp} - 25°C)(0.02\ \mu s/°C)$$
$$(85°C - 25°C)(0.02\ \mu s/°C)$$
$$1.2\ \mu s$$

Temperature coefficient is only required for temperatures > 25°C. Below 25°C, $T_{COFF} = 0\ \mu s$.

$$T_C = -(C_{HOLD})(R_{IC} + R_{SS} + R_S) \ln(1/4096)\ \mu s$$
$$-(25\ pF)\ (1\ k\Omega + 4\ k\Omega + 2.5\ k\Omega) \ln(0.0002441)\ \mu s$$
$$1.56\ \mu s$$

$$T_{ACQ} = 0.2\ \mu s + 1.56\ \mu s + 1.2\ \mu s$$
$$2.96\ \mu s$$

2.2 Selecting and Configuring Acquisition Time

The ADCON2 register allows the user to select an acquisition time that occurs each time the GO/DONE bit is set. It also gives users the option to use an automatically determined acquisition time.

Acquisition time may be set with the ACQT2:ACQT0 bits (ADCON2<5:3>), which provide a range of 2 to 20 TAD. When the GO/DONE bit is set, the A/D module continues to sample the input for the selected acquisition time, then automatically begins a conversion. Since the acquisition time is programmed, there may be no need to wait for an acquisition time between selecting a channel and setting the GO/DONE bit.

Manual acquisition is selected when ACQT2:ACQT0 = 000. When the GO/DONE bit is set, sampling is stopped and a conversion begins. The user is responsible for ensuring the required acquisition time has passed between selecting the desired input channel and setting the GO/DONE bit. This option is also the default Reset state of the ACQT2:ACQT0 bits and is compatible with devices that do not offer programmable acquisition times.

In either case, when the conversion is completed, the GO/DONE bit is cleared, the ADIF flag is set and the A/D begins sampling the currently selected channel again. If an acquisition time is programmed, there is nothing to indicate if the acquisition time has ended or if the conversion has begun.

2.3 Selecting the A/D Conversion Clock

The A/D conversion time per bit is defined as TAD. The A/D conversion requires 13 TAD per 12-bit conversion. The source of the A/D conversion clock is software selectable. There are seven possible options for TAD:

- 2 TOSC
- 4 TOSC
- 8 TOSC
- 16 TOSC
- 32 TOSC
- 64 TOSC
- Internal RC Oscillator

For correct A/D conversions, the A/D conversion clock (TAD) must be as short as possible, but greater than the minimum TAD (see parameter 130 for more information).

Table 2-1 shows the resultant TAD times derived from the device operating frequencies and the A/D clock source selected.

TABLE 2-1: TAD vs. DEVICE OPERATING FREQUENCIES

A/D Clock Source (TAD)		Assumes TAD Min. = 0.8 μs
Operation	**ADCS2:ADCS0**	**Maximum FOSC**
2 TOSC	000	2.50 MHz
4 TOSC	100	5.00 MHz
8 TOSC	001	10.00 MHz
16 TOSC	101	20.00 MHz
32 TOSC	010	40.00 MHz
64 TOSC	110	40.00 MHz
RC(1)	x11	1.00 MHz(2)

Note 1: The RC source has a typical TAD time of 2.5 μs.

2: For device frequencies above 1 MHz, the device must be in Sleep for the entire conversion or a FOSC divider should be used instead; otherwise, the A/D accuracy specification may not be met.

2.4 Operation in Power-Managed Modes

The selection of the automatic acquisition time and A/D conversion clock is determined in part by the clock source and frequency while in a power-managed mode.

If the A/D is expected to operate while the device is in a power-managed mode, the ADCS2:ADCS0 bits in ADCON2 should be updated in accordance with the clock source to be used. The ACQT2:ACQT0 bits do not need to be adjusted as the ADCS2:ADCS0 bits adjust the TAD time for the new clock speed. After entering the mode, an A/D acquisition or conversion may be started. Once started, the device should continue to be clocked by the same clock source until the conversion has been completed.

If desired, the device may be placed into the corresponding Idle mode during the conversion. If the device clock frequency is less than 1 MHz, the A/D RC clock source should be selected.

Operation in Sleep mode requires the A/D FRC clock to be selected. If the ACQT2:ACQT0 bits are set to '000' and a conversion is started, the conversion will be delayed one instruction cycle to allow execution of the SLEEP instruction and entry to Sleep mode. The IDLEN bit (OSCCON<7>) must have already been cleared prior to starting the conversion.

2.5 Configuring Analog Port Pins

The ADCON1, TRISA, TRISF and TRISH registers all configure the A/D port pins. The port pins needed as analog inputs must have their corresponding TRIS bits set (input). If the TRIS bit is cleared (output), the digital output level (VOH or VOL) will be converted.

The A/D operation is independent of the state of the CHS3:CHS0 bits and the TRIS bits.

Note 1:	When reading the PORT register, all pins configured as analog input channels will read as cleared (a low level). Analog conversion on pins configured as digital pins can be performed. The voltage on the pin will be accurately converted.
2:	Analog levels on any pin defined as a digital input may cause the digital input buffer to consume current out of the device's specification limits.

2.6 A/D Conversions

Figure 2-4 shows the operation of the A/D Converter after the GO/$\overline{\text{DONE}}$ bit has been set and the ACQT2:ACQT0 bits are cleared. A conversion is started after the following instruction to allow entry into Sleep mode before the conversion begins.

Figure 2-5 shows the operation of the A/D Converter after the GO/$\overline{\text{DONE}}$ bit has been set, the ACQT2:ACQT0 bits are set to '010' and a 4 TAD acquisition time has been selected before the conversion starts.

Clearing the GO/$\overline{\text{DONE}}$ bit during a conversion will abort the current conversion. The A/D Result register pair will NOT be updated with the partially completed A/D conversion sample. This means the ADRESH:ADRESL registers will continue to contain the value of the last completed conversion (or the last value written to the ADRESH:ADRESL registers).

After the A/D conversion is completed or aborted, a 2 TCY wait is required before the next acquisition can be started. After this wait, acquisition on the selected channel is automatically started.

Note: The GO/$\overline{\text{DONE}}$ bit should **NOT** be set in the same instruction that turns on the A/D. Code should wait at least 2 μs after enabling the A/D before beginning an acquisition and conversion cycle.

2.7 Discharge

The discharge phase is used to initialize the value of the holding capacitor. The array is discharged before every sample. This feature helps to optimize the unity gain amplifier, as the circuit always needs to charge the capacitor array, rather than charge/discharge based on previous measure values.

FIGURE 2-4: A/D CONVERSION TAD CYCLES (ACQT<2:0> = 000, TACQ = 0)

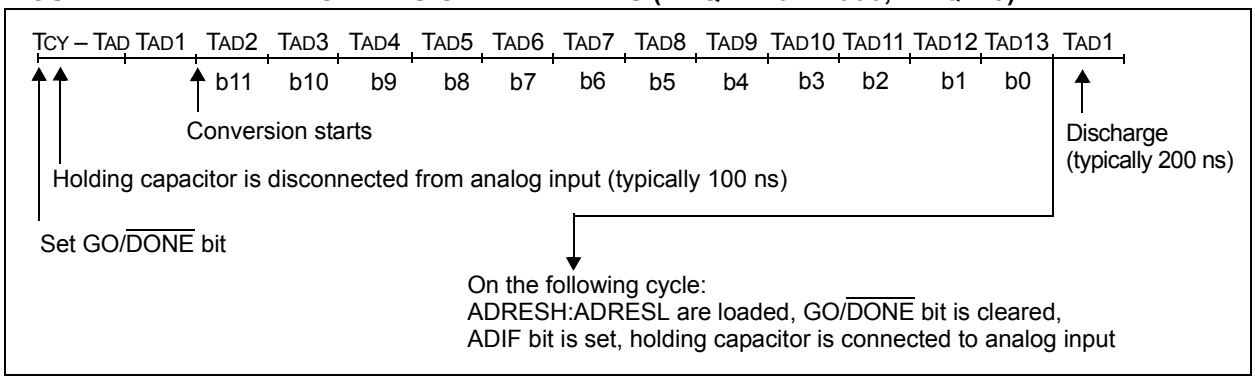


FIGURE 2-5: A/D CONVERSION TAD CYCLES (ACQT<2:0> = 010, TACQ = 4 TAD)

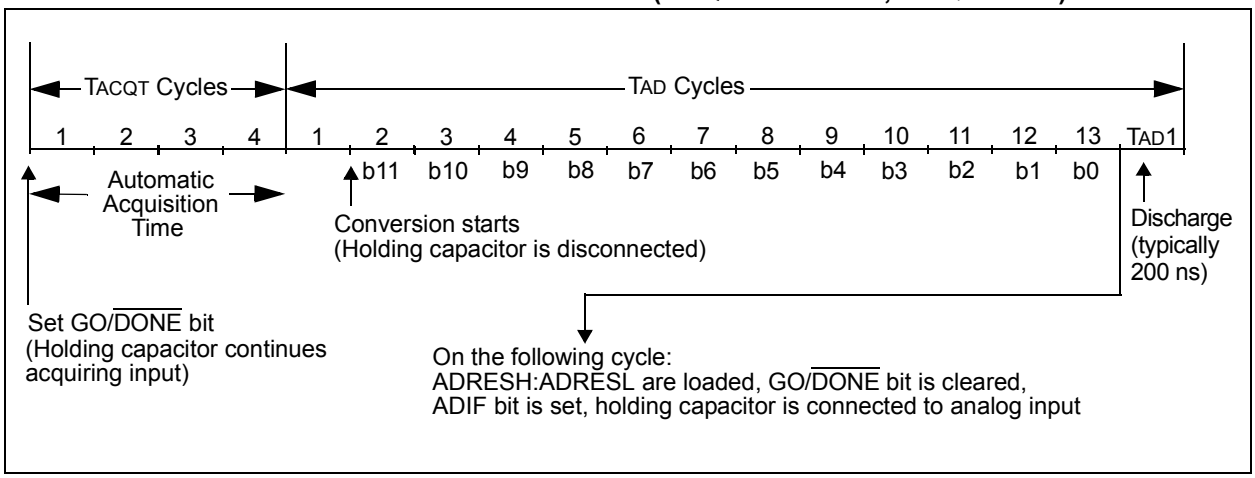
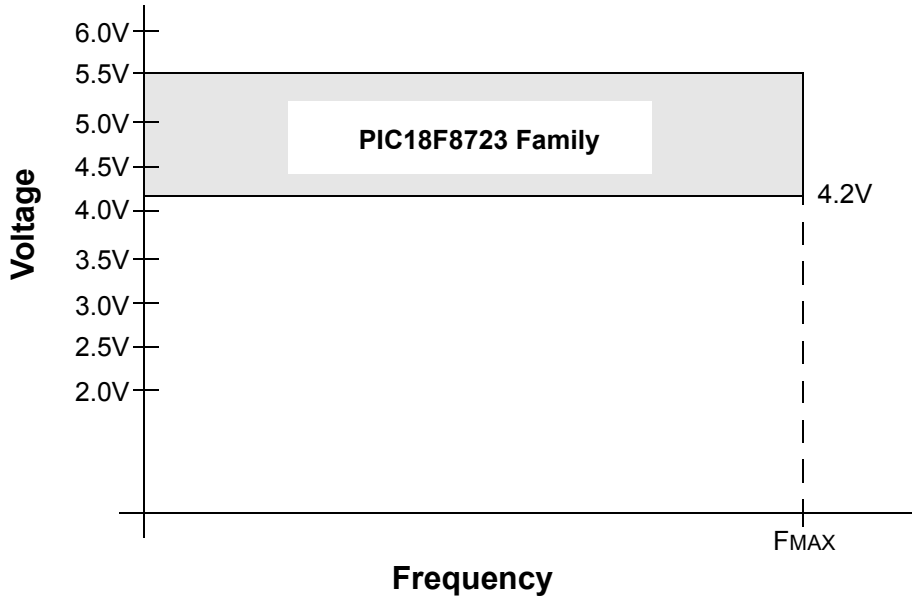
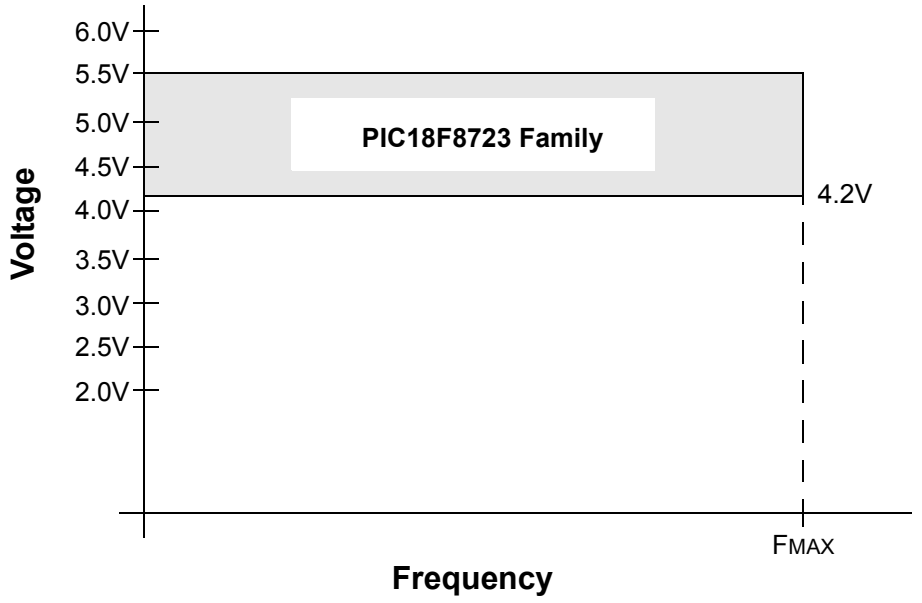


FIGURE 4-1: PIC18F8723 FAMILY VOLTAGE-FREQUENCY GRAPH (INDUSTRIAL)



FMAX = 20 MHz in 8-Bit External Memory mode.
FMAX = 40 MHz in all other modes.

FIGURE 4-2: PIC18F8723 FAMILY VOLTAGE-FREQUENCY GRAPH (EXTENDED)



FMAX = 20 MHz in 8-Bit External Memory mode.
FMAX = 25 MHz in all other modes.

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APPENDIX A: REVISION HISTORY

Revision A (August 2007)

Original data sheet for the PIC18F8723 family of devices.

Revision B (October 2009)

Updated to remove Preliminary status.

APPENDIX B: DEVICE DIFFERENCES

The differences between the devices listed in this data sheet are shown in Table B-1.

TABLE B-1: PIC18F8723 FAMILY DEVICE DIFFERENCES

Features	PIC18F6628	PIC18F6723	PIC18F8628	PIC18F8723
Program Memory (Bytes)	96K	128K	96K	128K
Program Memory (Instructions)	49152	65536	49152	65536
Interrupt Sources	28	28	29	29
I/O Ports	Ports A, B, C, D, E, F, G	Ports A, B, C, D, E, F, G	Ports A, B, C, D, E, F, G, H, J	Ports A, B, C, D, E, F, G, H, J
Capture/Compare/PWM Modules	2	2	2	2
Enhanced Capture/Compare/PWM Modules	3	3	3	3
Parallel Communications (PSP)	Yes	Yes	Yes	Yes
External Memory Bus	No	No	Yes	Yes
12-Bit Analog-to-Digital Module	12 Input Channels	12 Input Channels	16 Input Channels	16 Input Channels
Packages	64-Pin TQFP	64-Pin TQFP	80-Pin TQFP	80-Pin TQFP

APPENDIX E: MIGRATION FROM MID-RANGE TO ENHANCED DEVICES

A detailed discussion of the differences between the mid-range MCU devices (i.e., PIC16CXXX) and the enhanced devices (i.e., PIC18FXXX) is provided in *AN716, "Migrating Designs from PIC16C74A/74B to PIC18C442*". The changes discussed, while device specific, are generally applicable to all mid-range to enhanced device migrations.

This Application Note is available on our web site, www.microchip.com, as Literature Number DS00716.

APPENDIX F: MIGRATION FROM HIGH-END TO ENHANCED DEVICES

A detailed discussion of the migration pathway and differences between the high-end MCU devices (i.e., PIC17CXXX) and the enhanced devices (i.e., PIC18FXXX) is provided in *AN726, "PIC17CXXX to PIC18CXXX Migration*".

This Application Note is available on our web site, www.microchip.com, as Literature Number DS00726.

PIC18F8723 FAMILY PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

PART NO.	X	/XX	XXX
Device	Temperature Range	Package	Pattern

Device[1) (2)]	PIC18F6628/6723, PIC18F8628/8723, VDD range 4.2V to 5.5V PIC18LF6628/6723, PIC18LF6628/6723(VDD range 2.0V to 5.5V
Temperature Range	I = -40°C to +85°C (Industrial) E = -40°C to +125°C (Extended)
Package	PT = TQFP (Thin Quad Flatpack)
Pattern	QTP, SQTP, Code or Special Requirements (blank otherwise)

Examples:

a) PIC18LF6723-I/PT 301 = Industrial temp., TQFP package, Extended VDD limits, QTP pattern #301.

b) PIC18F6723-E/PT = Extended temp., TQFP package, standard VDD limits.

Note 1: F = Standard Voltage Range
LF = Wide Voltage Range
2: T = in tape and reel TQFP packages only.