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Details

| | |
|----------------------------|---|
| Product Status | Active |
| Core Processor | PIC |
| Core Size | 8-Bit |
| Speed | 40MHz |
| Connectivity | EBI/EMI, I ² C, SPI, UART/USART |
| Peripherals | Brown-out Detect/Reset, HLVD, POR, PWM, WDT |
| Number of I/O | 70 |
| Program Memory Size | 128KB (64K x 16) |
| Program Memory Type | FLASH |
| EEPROM Size | 1K x 8 |
| RAM Size | 3.8K x 8 |
| Voltage - Supply (Vcc/Vdd) | 2V ~ 5.5V |
| Data Converters | A/D 16x12b |
| Oscillator Type | Internal |
| Operating Temperature | -40°C ~ 85°C (TA) |
| Mounting Type | Surface Mount |
| Package / Case | 80-TQFP |
| Supplier Device Package | 80-TQFP (12x12) |
| Purchase URL | https://www.e-xfl.com/product-detail/microchip-technology/pic18lf8723-i-pt |

PIC18F8723

Table of Contents

| | | |
|--|---|----|
| 1.0 | Device Overview | 9 |
| 2.0 | 12-Bit Analog-to-Digital Converter (A/D) Module | 31 |
| 3.0 | Special Features of the CPU | 41 |
| 4.0 | Electrical Characteristics | 43 |
| 5.0 | Packaging Information..... | 49 |
| Appendix A: Revision History..... | | 51 |
| Appendix B: Device Differences..... | | 51 |
| Appendix C: Conversion Considerations | | 52 |
| Appendix D: Migration From Baseline to Enhanced Devices..... | | 52 |
| Appendix E: Migration From Mid-Range to Enhanced Devices | | 53 |
| Appendix F: Migration From High-End to Enhanced Devices | | 53 |
| Index | | 55 |
| The Microchip Web Site | | 57 |
| Customer Change Notification Service | | 57 |
| Customer Support | | 57 |
| Reader Response | | 58 |
| PIC18F8723 family Product Identification System | | 59 |

PIC18F8723 FAMILY

TABLE 1-1: DEVICE FEATURES

| Features | PIC18F6628 | PIC18F6723 | PIC18F8628 | PIC18F8723 |
|--------------------------------------|--|--|--|--|
| Operating Frequency | DC – 40 MHz | DC – 40 MHz | DC – 40 MHz | DC – 40 MHz |
| Program Memory (Bytes) | 96K | 128K | 96K | 128K |
| Program Memory (Instructions) | 49152 | 65536 | 49152 | 65536 |
| Data Memory (Bytes) | 3936 | 3936 | 3936 | 3936 |
| Data EEPROM Memory (Bytes) | 1024 | 1024 | 1024 | 1024 |
| Interrupt Sources | 28 | 28 | 29 | 29 |
| I/O Ports | Ports A, B, C, D, E, F, G | Ports A, B, C, D, E, F, G | Ports A, B, C, D, E, F, G, H, J | Ports A, B, C, D, E, F, G, H, J |
| Timers | 5 | 5 | 5 | 5 |
| Capture/Compare/PWM Modules | 2 | 2 | 2 | 2 |
| Enhanced Capture/Compare/PWM Modules | 3 | 3 | 3 | 3 |
| Enhanced USART | 2 | 2 | 2 | 2 |
| Serial Communications | MSSP, Enhanced USART | MSSP, Enhanced USART | MSSP, Enhanced USART | MSSP, Enhanced USART |
| Parallel Communications (PSP) | Yes | Yes | Yes | Yes |
| 12-Bit Analog-to-Digital Module | 12 Input Channels | 12 Input Channels | 16 Input Channels | 16 Input Channels |
| Resets (and Delays) | POR, BOR, RESET Instruction, Stack Full, Stack Underflow (PWRT, OST), MCLR (optional), WDT | POR, BOR, RESET Instruction, Stack Full, Stack Underflow (PWRT, OST), MCLR (optional), WDT | POR, BOR, RESET Instruction, Stack Full, Stack Underflow (PWRT, OST), MCLR (optional), WDT | POR, BOR, RESET Instruction, Stack Full, Stack Underflow (PWRT, OST), MCLR (optional), WDT |
| Programmable High/Low-Voltage Detect | Yes | Yes | Yes | Yes |
| Programmable Brown-out Reset | Yes | Yes | Yes | Yes |
| Instruction Set | 75 Instructions; 83 with Extended Instruction Set Enabled | 75 Instructions; 83 with Extended Instruction Set Enabled | 75 Instructions; 83 with Extended Instruction Set Enabled | 75 Instructions; 83 with Extended Instruction Set Enabled |
| Packages | 64-Pin TQFP | 64-Pin TQFP | 80-Pin TQFP | 80-Pin TQFP |

PIC18F8723 FAMILY

TABLE 1-2: PIC18F6628/6723 (64-PIN) PINOUT I/O DESCRIPTIONS

| Pin Name | Pin Number | Pin Type | Buffer Type | Description |
|--|------------|-------------------|-----------------------|---|
| | TQFP | | | |
| RG5/ <u>MCLR</u> /VPP RG5 <u>MCLR</u> VPP | 7 | I I P | ST ST | Master Clear (input) or programming voltage (input). Digital input. Master Clear (Reset) input. This pin is an active-low Reset to the device. Programming voltage input. |
| OSC1/CLKI/RA7 OSC1 CLKI RA7 | 39 | I I I/O | ST CMOS TTL | Oscillator crystal or external clock input. Oscillator crystal input or external clock source input. ST buffer when configured in RC mode, CMOS otherwise. External clock source input. Always associated with pin function OSC1. (See related OSC1/CLKI, OSC2/CLKO pins.) General purpose I/O pin. |
| OSC2/CLKO/RA6 OSC2 CLKO RA6 | 40 | O O I/O | — — TTL | Oscillator crystal or clock output. Oscillator crystal output. Connects to crystal or resonator in Crystal Oscillator mode. In RC mode, OSC2 pin outputs CLKO, which has 1/4 the frequency of OSC1 and denotes the instruction cycle rate. General purpose I/O pin. |

Legend: TTL = TTL compatible input CMOS = CMOS compatible input or output
ST = Schmitt Trigger input with CMOS levels Analog = Analog input
I = Input O = Output
P = Power I²C™ = I²C/SMBus input buffer

Note 1: Default assignment for ECCP2 when Configuration bit, CCP2MX, is set.

2: Alternate assignment for ECCP2 when Configuration bit, CCP2MX, is cleared.

PIC18F8723 FAMILY

TABLE 1-2: PIC18F6628/6723 (64-PIN) PINOUT I/O DESCRIPTIONS (CONTINUED)

| Pin Name | Pin Number | Pin Type | Buffer Type | Description |
|--|------------|-----------------|----------------|---|
| | TQFP | | | |
| RE0/ $\overline{\text{RD}}$ /P2D RE0 $\overline{\text{RD}}$ P2D | 2 | I/O I O | ST TTL — | <p>PORTE is a bidirectional I/O port.</p> <p>Digital I/O. Read control for Parallel Slave Port. ECCP2 PWM output D.</p> |
| RE1/ $\overline{\text{WR}}$ /P2C RE1 $\overline{\text{WR}}$ P2C | 1 | I/O I O | ST TTL — | <p>Digital I/O. Write control for Parallel Slave Port. ECCP2 PWM output C.</p> |
| RE2/ $\overline{\text{CS}}$ /P2B RE2 $\overline{\text{CS}}$ P2B | 64 | I/O I O | ST TTL — | <p>Digital I/O. Chip select control for Parallel Slave Port. ECCP2 PWM output B.</p> |
| RE3/P3C RE3 P3C | 63 | I/O O | ST — | <p>Digital I/O. ECCP3 PWM output C.</p> |
| RE4/P3B RE4 P3B | 62 | I/O O | ST — | <p>Digital I/O. ECCP3 PWM output B.</p> |
| RE5/P1C RE5 P1C | 61 | I/O O | ST — | <p>Digital I/O. ECCP1 PWM output C.</p> |
| RE6/P1B RE6 P1B | 60 | I/O O | ST — | <p>Digital I/O. ECCP1 PWM output B.</p> |
| RE7/ECCP2/P2A RE7 ECCP2 ⁽²⁾ P2A ⁽²⁾ | 59 | I/O I/O O | ST ST — | <p>Digital I/O. Enhanced Capture 2 input/Compare 2 output/ PWM2 output. ECCP2 PWM output A.</p> |

Legend: TTL = TTL compatible input CMOS = CMOS compatible input or output
ST = Schmitt Trigger input with CMOS levels Analog = Analog input
I = Input O = Output
P = Power I²C™ = I²C/SMBus input buffer

Note 1: Default assignment for ECCP2 when Configuration bit, CCP2MX, is set.

2: Alternate assignment for ECCP2 when Configuration bit, CCP2MX, is cleared.

PIC18F8723 FAMILY

TABLE 1-3: PIC18F8628/8723 (80-PIN) PINOUT I/O DESCRIPTIONS (CONTINUED)

| Pin Name | Pin Number | Pin Type | Buffer Type | Description |
|----------------------------|------------|----------|----------------------|--|
| | TQFP | | | |
| RD0/AD0/PSP0 | 72 | | | PORTD is a bidirectional I/O port. |
| RD0 | | I/O | ST | Digital I/O. |
| AD0 | | I/O | TTL | External memory address/data 0. |
| PSP0 | | I/O | TTL | Parallel Slave Port data. |
| RD1/AD1/PSP1 | 69 | | | |
| RD1 | | I/O | ST | Digital I/O. |
| AD1 | | I/O | TTL | External memory address/data 1. |
| PSP1 | | I/O | TTL | Parallel Slave Port data. |
| RD2/AD2/PSP2 | 68 | | | |
| RD2 | | I/O | ST | Digital I/O. |
| AD2 | | I/O | TTL | External memory address/data 2. |
| PSP2 | | I/O | TTL | Parallel Slave Port data. |
| RD3/AD3/PSP3 | 67 | | | |
| RD3 | | I/O | ST | Digital I/O. |
| AD3 | | I/O | TTL | External memory address/data 3. |
| PSP3 | | I/O | TTL | Parallel Slave Port data. |
| RD4/AD4/PSP4/SDO2 | 66 | | | |
| RD4 | | I/O | ST | Digital I/O. |
| AD4 | | I/O | TTL | External memory address/data 4. |
| PSP4 | | I/O | TTL | Parallel Slave Port data. |
| SDO2 | | O | — | SPI data out. |
| RD5/AD5/PSP5/ SDI2/SDA2 | 65 | | | |
| RD5 | | I/O | ST | Digital I/O. |
| AD5 | | I/O | TTL | External memory address/data 5. |
| PSP5 | | I/O | TTL | Parallel Slave Port data. |
| SDI2 | | I | ST | SPI data in. |
| SDA2 | | I/O | I ² C/SMB | I ² C™ data I/O. |
| RD6/AD6/PSP6/ SCK2/SCL2 | 64 | | | |
| RD6 | | I/O | ST | Digital I/O. |
| AD6 | | I/O | TTL | External memory address/data 6. |
| PSP6 | | I/O | TTL | Parallel Slave Port data. |
| SCK2 | | I/O | ST | Synchronous serial clock input/output for SPI mode. |
| SCL2 | | I/O | I ² C/SMB | Synchronous serial clock input/output for I ² C mode. |
| RD7/AD7/PSP7/SS2 | 63 | | | |
| RD7 | | I/O | ST | Digital I/O. |
| AD7 | | I/O | TTL | External memory address/data 7. |
| PSP7 | | I/O | TTL | Parallel Slave Port data. |
| SS2 | | I | TTL | SPI slave select input. |

Legend: TTL = TTL compatible input CMOS = CMOS compatible input or output
ST = Schmitt Trigger input with CMOS levels Analog = Analog input
I = Input O = Output
P = Power I²C™/SMB = I²C/SMBus input buffer

Note 1: Alternate assignment for ECCP2 when Configuration bit, CCP2MX, is cleared (all operating modes except Microcontroller mode).

2: Default assignment for ECCP2 in all operating modes (CCP2MX is set).

3: Alternate assignment for ECCP2 when CCP2MX is cleared (Microcontroller mode only).

4: Default assignment for P1B/P1C/P3B/P3C (ECCPMX is set).

5: Alternate assignment for P1B/P1C/P3B/P3C (ECCPMX is clear).

PIC18F8723 FAMILY

TABLE 1-3: PIC18F8628/8723 (80-PIN) PINOUT I/O DESCRIPTIONS (CONTINUED)

| Pin Name | Pin Number | Pin Type | Buffer Type | Description |
|---------------|------------|----------|-------------|--|
| | TQFP | | | |
| RG0/ECCP3/P3A | 5 | | | PORTG is a bidirectional I/O port. |
| RG0 | | I/O | ST | Digital I/O. |
| ECCP3 | | I/O | ST | Enhanced Capture 3 input/Compare 3 output/PWM3 output. |
| P3A | 6 | O | — | ECCP3 PWM output A. |
| RG1/TX2/CK2 | | | | |
| RG1 | | I/O | ST | Digital I/O. |
| TX2 | | O | — | EUSART2 asynchronous transmit. |
| CK2 | 7 | I/O | ST | EUSART2 synchronous clock (see related RX2/DT2). |
| RG2/RX2/DT2 | | | | |
| RG2 | | I/O | ST | Digital I/O. |
| RX2 | | I | ST | EUSART2 asynchronous receive. |
| DT2 | 8 | I/O | ST | EUSART2 synchronous data (see related TX2/CK2). |
| RG3/CCP4/P3D | | | | |
| RG3 | | I/O | ST | Digital I/O. |
| CCP4 | | I/O | ST | Capture 4 input/Compare 4 output/PWM4 output. |
| P3D | 10 | O | — | ECCP3 PWM output D. |
| RG4/CCP5/P1D | | | | |
| RG4 | | I/O | ST | Digital I/O. |
| CCP5 | | I/O | ST | Capture 5 input/Compare 5 output/PWM5 output. |
| P1D | 10 | O | — | ECCP1 PWM output D. |
| RG5 | | | | See RG5/MCLR/VPP pin. |

Legend: TTL = TTL compatible input CMOS = CMOS compatible input or output
ST = Schmitt Trigger input with CMOS levels Analog = Analog input
I = Input O = Output
P = Power I²C™/SMB = I²C/SMBus input buffer

- Note 1:** Alternate assignment for ECCP2 when Configuration bit, CCP2MX, is cleared (all operating modes except Microcontroller mode).
- 2:** Default assignment for ECCP2 in all operating modes (CCP2MX is set).
- 3:** Alternate assignment for ECCP2 when CCP2MX is cleared (Microcontroller mode only).
- 4:** Default assignment for P1B/P1C/P3B/P3C (ECCPMX is set).
- 5:** Alternate assignment for P1B/P1C/P3B/P3C (ECCPMX is clear).

PIC18F8723 FAMILY

REGISTER 2-2: ADCON1: A/D CONTROL REGISTER 1

| | | | | | | | |
|-------|-----|-------|-------|-------|-------|-------|-------|
| U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
| — | — | VCFG1 | VCFG0 | PCFG3 | PCFG2 | PCFG1 | PCFG0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-6

Unimplemented: Read as '0'

bit 5-4

VCFG1:VCFG0: Voltage Reference Configuration bits

| | A/D VREF+ | A/D VREF- |
|----|----------------|----------------|
| 00 | AVDD | AVSS |
| 01 | External VREF+ | AVSS |
| 10 | AVDD | External VREF- |
| 11 | External VREF+ | External VREF- |

bit 3-0

PCFG3:PCFG0: A/D Port Configuration Control bits:

| PCFG<3:0> | AN15 ⁽¹⁾ | AN14 ⁽¹⁾ | AN13 ⁽¹⁾ | AN12 ⁽¹⁾ | AN11 | AN10 | AN9 | AN8 | AN7 | AN6 | AN5 | AN4 | AN3 | AN2 | AN1 | AN0 |
|-----------|---------------------|---------------------|---------------------|---------------------|------|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| 0000 | A | A | A | A | A | A | A | A | A | A | A | A | A | A | A | A |
| 0001 | D | D | A | A | A | A | A | A | A | A | A | A | A | A | A | A |
| 0010 | D | D | D | A | A | A | A | A | A | A | A | A | A | A | A | A |
| 0011 | D | D | D | D | A | A | A | A | A | A | A | A | A | A | A | A |
| 0100 | D | D | D | D | D | A | A | A | A | A | A | A | A | A | A | A |
| 0101 | D | D | D | D | D | D | A | A | A | A | A | A | A | A | A | A |
| 0110 | D | D | D | D | D | D | D | A | A | A | A | A | A | A | A | A |
| 0111 | D | D | D | D | D | D | D | D | A | A | A | A | A | A | A | A |
| 1000 | D | D | D | D | D | D | D | D | D | A | A | A | A | A | A | A |
| 1001 | D | D | D | D | D | D | D | D | D | D | A | A | A | A | A | A |
| 1010 | D | D | D | D | D | D | D | D | D | D | D | A | A | A | A | A |
| 1011 | D | D | D | D | D | D | D | D | D | D | D | D | A | A | A | A |
| 1100 | D | D | D | D | D | D | D | D | D | D | D | D | D | A | A | A |
| 1101 | D | D | D | D | D | D | D | D | D | D | D | D | D | D | A | A |
| 1110 | D | D | D | D | D | D | D | D | D | D | D | D | D | D | D | A |
| 1111 | D | D | D | D | D | D | D | D | D | D | D | D | D | D | D | D |

A = Analog input

D = Digital I/O

Note 1: AN15 through AN12 are available only on PIC18F8628/8723 devices.

PIC18F8723 FAMILY

REGISTER 2-3: ADCON2: A/D CONTROL REGISTER 2

| R/W-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|-------|-----|-------|-------|-------|-------|-------|-------|
| ADFM | — | ACQT2 | ACQT1 | ACQT0 | ADCS2 | ADCS1 | ADCS0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **ADFM:** A/D Result Format Select bit

1 = Right justified

0 = Left justified

bit 6 **Unimplemented:** Read as '0'

bit 5-3 **ACQT2:ACQT0:** A/D Acquisition Time Select bits

111 = 20 TAD

110 = 16 TAD

101 = 12 TAD

100 = 8 TAD

011 = 6 TAD

010 = 4 TAD

001 = 2 TAD

000 = 0 TAD⁽¹⁾

bit 2-0 **ADCS2:ADCS0:** A/D Conversion Clock Select bits

111 = FRC (clock derived from A/D RC oscillator)⁽¹⁾

110 = FOSC/64

101 = FOSC/16

100 = FOSC/4

011 = FRC (clock derived from A/D RC oscillator)⁽¹⁾

010 = FOSC/32

001 = FOSC/8

000 = FOSC/2

Note 1: If the A/D FRC clock source is selected, a delay of one T_{CY} (instruction cycle) is added before the A/D clock starts. This allows the **SLEEP** instruction to be executed before starting a conversion.

PIC18F8723 FAMILY

The analog reference voltage is software selectable to either the device's positive and negative supply voltage (VDD and VSS), or the voltage level on the RA3/AN3/VREF+ and RA2/AN2/VREF-/CVREF pins.

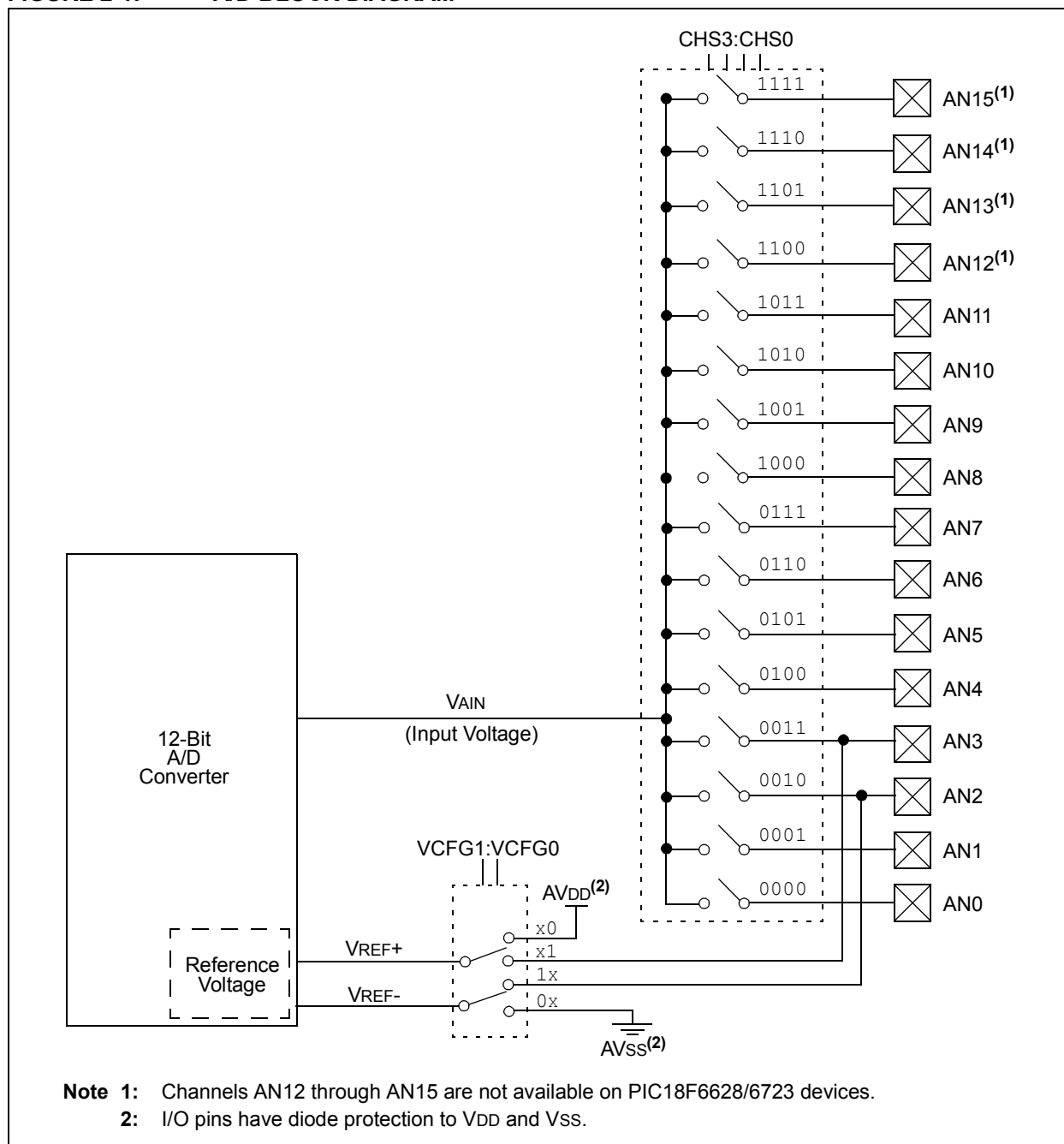
The A/D Converter has a unique feature of being able to operate while the device is in Sleep mode. To operate in Sleep, the A/D conversion clock must be derived from the A/D's internal RC oscillator.

The output of the sample and hold is the input into the converter, which generates the result via successive approximation.

A device Reset forces all registers to their Reset state. This forces the A/D module to be turned off and any conversion in progress is aborted.

Each port pin associated with the A/D Converter can be configured as an analog input or a digital I/O. The ADRESH and ADRESL registers contain the result of the A/D conversion. When the A/D conversion is complete, the result is loaded into the ADRESH:ADRESL register pair, the GO/DONE bit (ADCON0<1>) is cleared and the A/D Interrupt Flag bit, ADIF, is set. The block diagram of the A/D module is shown in Figure 2-1.

FIGURE 2-1: A/D BLOCK DIAGRAM



2.2 Selecting and Configuring Acquisition Time

The ADCON2 register allows the user to select an acquisition time that occurs each time the GO/DONE bit is set. It also gives users the option to use an automatically determined acquisition time.

Acquisition time may be set with the ACQT2:ACQT0 bits (ADCON2<5:3>), which provide a range of 2 to 20 TAD. When the GO/DONE bit is set, the A/D module continues to sample the input for the selected acquisition time, then automatically begins a conversion. Since the acquisition time is programmed, there may be no need to wait for an acquisition time between selecting a channel and setting the GO/DONE bit.

Manual acquisition is selected when ACQT2:ACQT0 = 000. When the GO/DONE bit is set, sampling is stopped and a conversion begins. The user is responsible for ensuring the required acquisition time has passed between selecting the desired input channel and setting the GO/DONE bit. This option is also the default Reset state of the ACQT2:ACQT0 bits and is compatible with devices that do not offer programmable acquisition times.

In either case, when the conversion is completed, the GO/DONE bit is cleared, the ADIF flag is set and the A/D begins sampling the currently selected channel again. If an acquisition time is programmed, there is nothing to indicate if the acquisition time has ended or if the conversion has begun.

2.3 Selecting the A/D Conversion Clock

The A/D conversion time per bit is defined as TAD. The A/D conversion requires 13 TAD per 12-bit conversion. The source of the A/D conversion clock is software selectable. There are seven possible options for TAD:

- 2 TOSC
- 4 TOSC
- 8 TOSC
- 16 TOSC
- 32 TOSC
- 64 TOSC
- Internal RC Oscillator

For correct A/D conversions, the A/D conversion clock (TAD) must be as short as possible, but greater than the minimum TAD (see parameter 130 for more information).

Table 2-1 shows the resultant TAD times derived from the device operating frequencies and the A/D clock source selected.

TABLE 2-1: TAD vs. DEVICE OPERATING FREQUENCIES

| A/D Clock Source (TAD) | | Assumes TAD Min. = 0.8 μ s |
|------------------------|-------------|--------------------------------|
| Operation | ADCS2:ADCS0 | Maximum Fosc |
| 2 TOSC | 000 | 2.50 MHz |
| 4 TOSC | 100 | 5.00 MHz |
| 8 TOSC | 001 | 10.00 MHz |
| 16 TOSC | 101 | 20.00 MHz |
| 32 TOSC | 010 | 40.00 MHz |
| 64 TOSC | 110 | 40.00 MHz |
| RC ⁽¹⁾ | x11 | 1.00 MHz ⁽²⁾ |

Note 1: The RC source has a typical TAD time of 2.5 μ s.

2: For device frequencies above 1 MHz, the device must be in Sleep for the entire conversion or a FOSC divider should be used instead; otherwise, the A/D accuracy specification may not be met.

2.6 A/D Conversions

Figure 2-4 shows the operation of the A/D Converter after the $\overline{\text{GO/DONE}}$ bit has been set and the ACQT2:ACQT0 bits are cleared. A conversion is started after the following instruction to allow entry into Sleep mode before the conversion begins.

Figure 2-5 shows the operation of the A/D Converter after the $\overline{\text{GO/DONE}}$ bit has been set, the ACQT2:ACQT0 bits are set to '010' and a 4 TAD acquisition time has been selected before the conversion starts.

Clearing the $\overline{\text{GO/DONE}}$ bit during a conversion will abort the current conversion. The A/D Result register pair will NOT be updated with the partially completed A/D conversion sample. This means the ADRESH:ADRESL registers will continue to contain the value of the last completed conversion (or the last value written to the ADRESH:ADRESL registers).

After the A/D conversion is completed or aborted, a 2 T_{CY} wait is required before the next acquisition can be started. After this wait, acquisition on the selected channel is automatically started.

Note: The $\overline{\text{GO/DONE}}$ bit should **NOT** be set in the same instruction that turns on the A/D. Code should wait at least 2 μs after enabling the A/D before beginning an acquisition and conversion cycle.

2.7 Discharge

The discharge phase is used to initialize the value of the holding capacitor. The array is discharged before every sample. This feature helps to optimize the unity gain amplifier, as the circuit always needs to charge the capacitor array, rather than charge/discharge based on previous measure values.

FIGURE 2-4: A/D CONVERSION TAD CYCLES (ACQT<2:0> = 000, TACQ = 0)

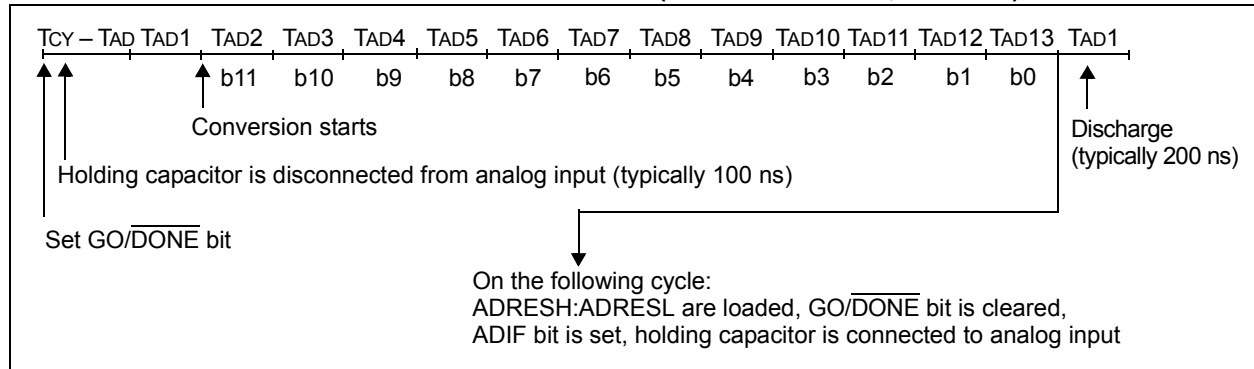
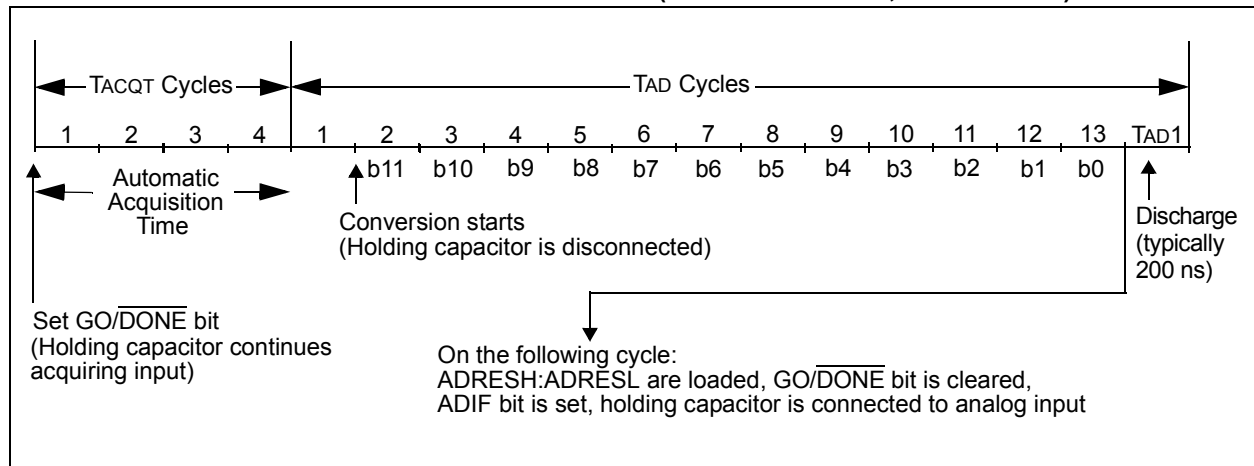


FIGURE 2-5: A/D CONVERSION TAD CYCLES (ACQT<2:0> = 010, TACQ = 4 TAD)



PIC18F8723 FAMILY

2.8 Use of the ECCP2 Trigger

An A/D conversion can be started by the Special Event Trigger of the ECCP2 module. This requires that the CCP2M3:CCP2M0 bits (CCP2CON<3:0>) be programmed as '1011' and that the A/D module is enabled (ADON bit is set). When the trigger occurs, the GO/DONE bit will be set, starting the A/D acquisition and conversion, and the Timer1 (or Timer3) counter will be reset to zero. Timer1 (or Timer3) is reset to automatically repeat the A/D acquisition period with minimal software overhead (moving ADRESH:ADRESL to the

desired location). The appropriate analog input channel must be selected and the minimum acquisition period is either timed by the user, or an appropriate TACQ time selected before the Special Event Trigger sets the GO/DONE bit (starts a conversion).

If the A/D module is not enabled (ADON is cleared), the Special Event Trigger will be ignored by the A/D module but will still reset the Timer1 (or Timer3) counter.

TABLE 2-2: REGISTERS ASSOCIATED WITH A/D OPERATION

| Name | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | Reset Values |
|----------------------|-------------------------------|-----------------------|--------|--------|--------|--------|---------|--------|--------------|
| INTCON | GIE/GIEH | PEIE/GIEL | TMR0IE | INT0IE | RBIE | TMR0IF | INT0IF | RBIF | (3) |
| PIR1 | PSPIF | ADIF | RC1IF | TX1IF | SSP1IF | CCP1IF | TMR2IF | TMR1IF | (3) |
| PIE1 | PSPIE | ADIE | RC1IE | TX1IE | SSP1IE | CCP1IE | TMR2IE | TMR1IE | (3) |
| IPR1 | PSPIP | ADIP | RC1IP | TX1IP | SSP1IP | CCP1IP | TMR2IP | TMR1IP | (3) |
| PIR2 | OSCFIF | CMIF | — | EEIF | BCL1IF | HLVDIF | TMR3IF | CCP2IF | (3) |
| PIE2 | OSCFIE | CMIE | — | EEIE | BCL1IE | HLVDIE | TMR3IE | CCP2IE | (3) |
| IPR2 | OSCFIP | CMIP | — | EEIP | BCL1IP | HLVDIP | TMR3IP | CCP2IP | (3) |
| ADRESH | A/D Result Register High Byte | | | | | | | | (3) |
| ADRESL | A/D Result Register Low Byte | | | | | | | | (3) |
| ADCON0 | — | — | CHS3 | CHS2 | CHS1 | CHS0 | GO/DONE | ADON | (3) |
| ADCON1 | — | — | VCFG1 | VCFG0 | PCFG3 | PCFG2 | PCFG1 | PCFG0 | (3) |
| ADCON2 | ADFM | — | ACQT2 | ACQT1 | ACQT0 | ADCS2 | ADCS1 | ADCS0 | (3) |
| TRISA | TRISA7 ⁽¹⁾ | TRISA6 ⁽¹⁾ | TRISA5 | TRISA4 | TRISA3 | TRISA2 | TRISA1 | TRISA0 | (3) |
| TRISF | TRISF7 | TRISF6 | TRISF5 | TRISF4 | TRISF3 | TRISF2 | TRISF1 | TRISF0 | (3) |
| TRISH ⁽²⁾ | TRISH7 | TRISH6 | TRISH5 | TRISH4 | TRISH3 | TRISH2 | TRISH1 | TRISH0 | (3) |

Legend: — = unimplemented, read as '0'. Shaded cells are not used for A/D conversion.

Note 1: PORTA<7:6> and their direction bits are individually configured as port pins based on various primary oscillator modes. When disabled, these bits read as '0'.

2: These registers are not implemented on PIC18F6628/6723 devices.

3: For these Reset values, see the "PIC18F8722 Family Data Sheet" (DS39646).

PIC18F8723 FAMILY

REGISTER 3-1: DEVID1: DEVICE ID REGISTER 1 FOR PIC18F8723 FAMILY DEVICES

| | | | | | | | |
|-------|------|------|------|------|------|------|-------|
| R | R | R | R | R | R | R | R |
| DEV2 | DEV1 | DEV0 | REV4 | REV3 | REV2 | REV1 | REV0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Read-only bit

P = Programmable bit

U = Unimplemented bit, read as '0'

-n = Value when device is unprogrammed

u = Unchanged from programmed state

bit 7-5 **DEV2:DEV0:** Device ID bits
See Register 3-2 for a complete listing.

bit 4-0 **REV4:REV0:** Revision ID bits
These bits are used to indicate the device revision.

REGISTER 3-2: DEVID2: DEVICE ID REGISTER 2 FOR PIC18F8723 FAMILY DEVICES

| | | | | | | | |
|-------|------|------|------|------|------|------|-------|
| R | R | R | R | R | R | R | R |
| DEV10 | DEV9 | DEV8 | DEV7 | DEV6 | DEV5 | DEV4 | DEV3 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Read-only bit

P = Programmable bit

U = Unimplemented bit, read as '0'

-n = Value when device is unprogrammed

u = Unchanged from programmed state

bit 7-0 **DEV10:DEV3:** Device ID bits

| DEV10:DEV3 (DEVID2<7:0>) | DEV2:DEV0 (DEVID1<7:5>) | Device |
|---|--|---------------|
| 0100 1001 | 110 | PIC18F6628 |
| 0100 1010 | 000 | PIC18F6723 |
| 0100 1001 | 111 | PIC18F8628 |
| 0100 1010 | 001 | PIC18F8723 |

PIC18F8723 FAMILY

FIGURE 4-1: PIC18F8723 FAMILY VOLTAGE-FREQUENCY GRAPH (INDUSTRIAL)

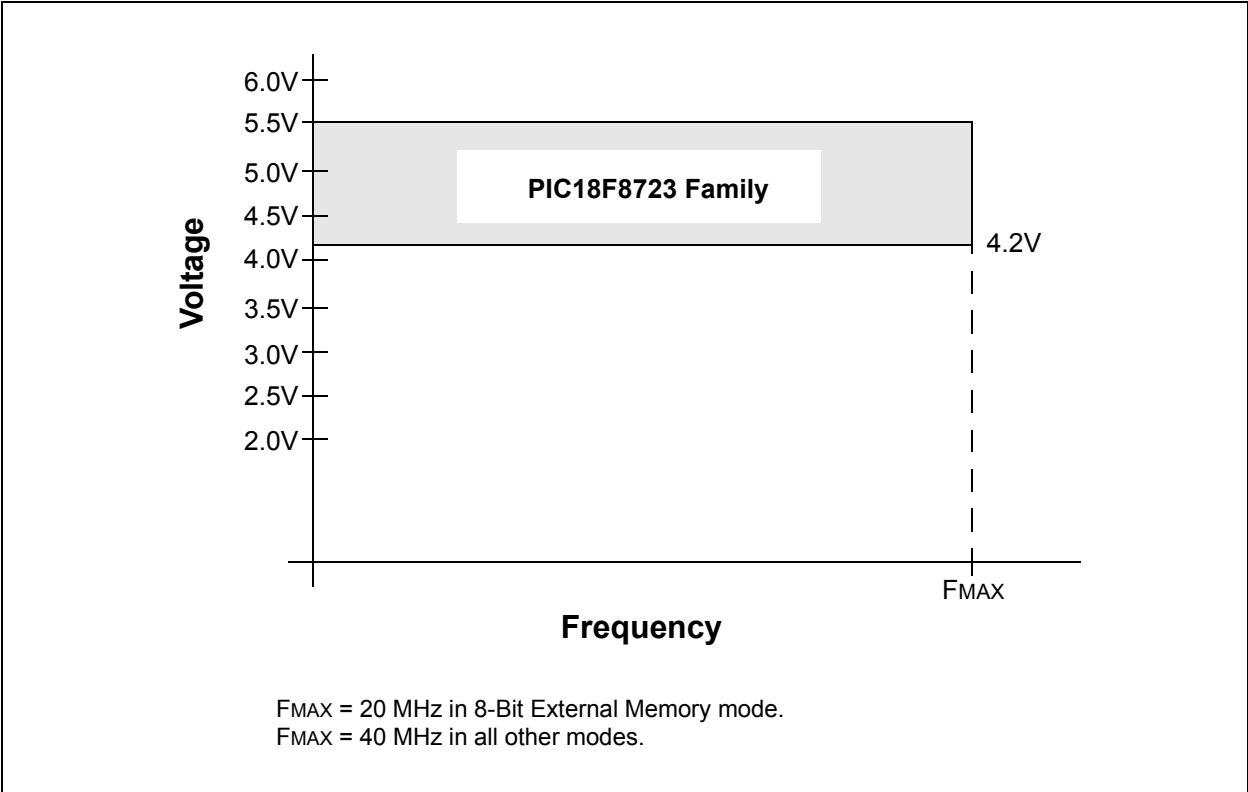
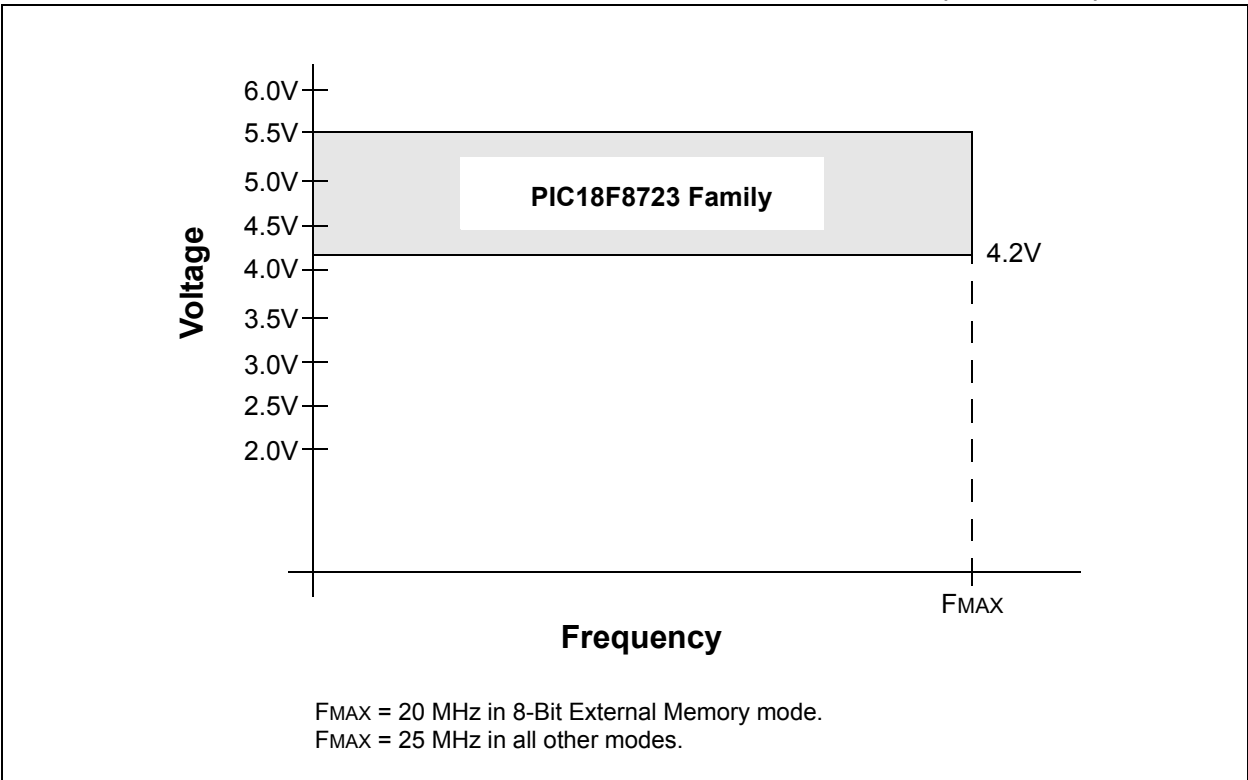
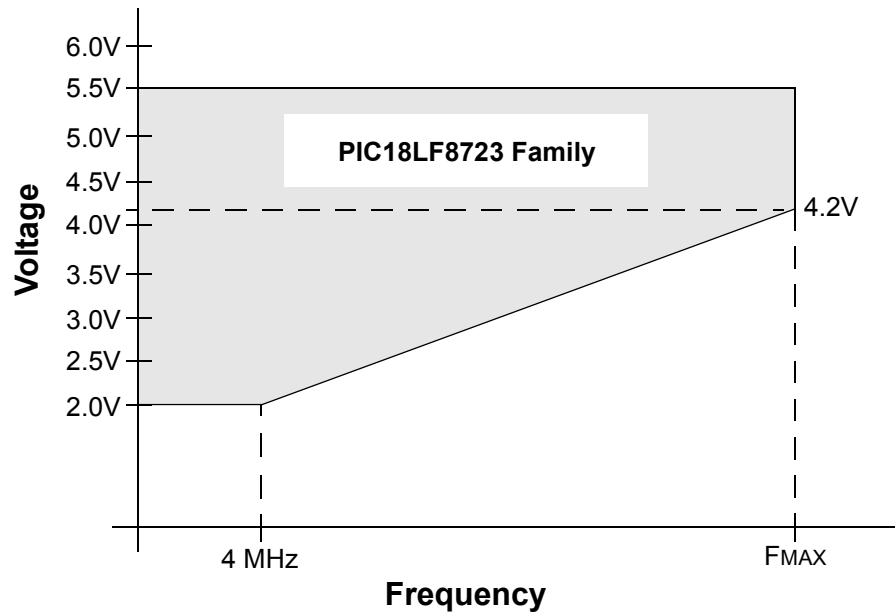


FIGURE 4-2: PIC18F8723 FAMILY VOLTAGE-FREQUENCY GRAPH (EXTENDED)



PIC18F8723 FAMILY

FIGURE 4-3: PIC18LF8723 FAMILY VOLTAGE-FREQUENCY GRAPH (INDUSTRIAL)



In 8-Bit External Memory mode:

$F_{MAX} = (9.55 \text{ MHz/V}) (V_{DDAPPMIN} - 2.0\text{V}) + 4 \text{ MHz}$, if $V_{DDAPPMIN} \leq 4.2\text{V}$;
 $F_{MAX} = 25 \text{ MHz}$, if $V_{DDAPPMIN} > 4.2\text{V}$.

In all other modes:

$F_{MAX} = (16.36 \text{ MHz/V}) (V_{DDAPPMIN} - 2.0\text{V}) + 4 \text{ MHz}$;
 $F_{MAX} = 40 \text{ MHz}$, if $V_{DDAPPMIN} > 4.2\text{V}$.

Note: $V_{DDAPPMIN}$ is the minimum voltage of the PIC[®] device in the application.

FIGURE 4-4: A/D CONVERSION TIMING

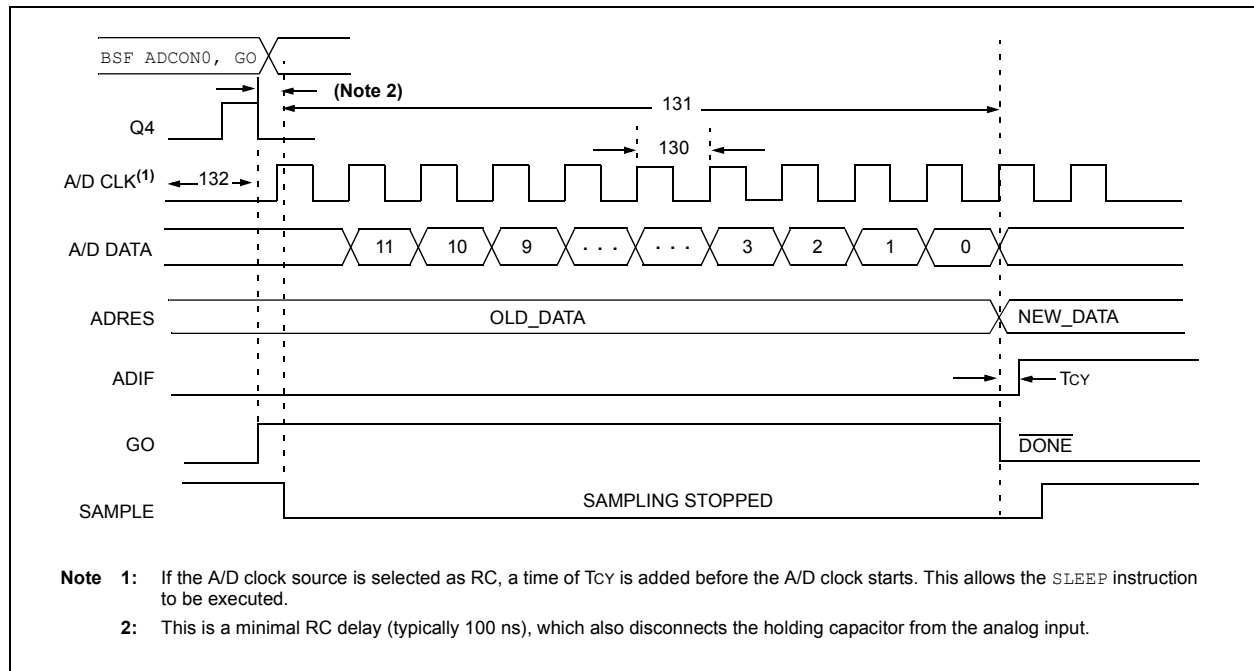


TABLE 4-2: A/D CONVERSION REQUIREMENTS

| Param No. | Symbol | Characteristic | Min | Max | Units | Conditions |
|-----------|--------|---|-------------|----------|---------------------|---|
| 130 | TAD | A/D Clock Period | PIC18FXXXX | 0.8 | 12.5 ⁽¹⁾ | μS TOSC based, $V_{REF} \geq 3.0\text{V}$ |
| | | | PIC18LFXXXX | 1.4 | 25.0 ⁽¹⁾ | μS $V_{DD} = 3.0\text{V}$; TOSC based, V_{REF} full range |
| | | | PIC18FXXXX | — | 1 | μS A/D RC mode |
| | | | PIC18LFXXXX | — | 3 | μS $V_{DD} = 3.0\text{V}$; A/D RC mode |
| 131 | TCNV | Conversion Time (not including acquisition time) ⁽²⁾ | 13 | 14 | TAD | |
| 132 | TACQ | Acquisition Time ⁽³⁾ | 1.4 | — | μS | |
| 135 | TSWC | Switching Time from Convert \rightarrow Sample | — | (Note 4) | | |
| 137 | TDIS | Discharge Time | 0.2 | — | μS | |

Note 1: The time of the A/D clock period is dependent on the device frequency and the TAD clock divider.

Note 2: ADRES registers may be read on the following T_{CY} cycle.

Note 3: The time for the holding capacitor to acquire the “New” input voltage when the voltage changes full scale after the conversion (V_{DD} to V_{SS} or V_{SS} to V_{DD}). The source impedance (R_s) on the input channels is 50Ω .

Note 4: On the following cycle of the device clock.

PIC18F8723 FAMILY

NOTES:

5.0 PACKAGING INFORMATION

For packaging information, see the “*PIC18F8722 Family Data Sheet*” (DS39646).

PIC18F8723 FAMILY

| | |
|------------------------------|--------|
| RD1/AD1/PSP1 | 25 |
| RD1/PSP1 | 17 |
| RD2/AD2/PSP2 | 25 |
| RD2/PSP2 | 17 |
| RD3/AD3/PSP3 | 25 |
| RD3/PSP3 | 17 |
| RD4/AD4/PSP4/SDO2 | 25 |
| RD4/PSP4/SDO2 | 17 |
| RD5/AD5/PSP5/SDI2/SDA2 | 25 |
| RD5/PSP5/SDI2/SDA2 | 17 |
| RD6/AD6/PSP6/SCK2/SCL2 | 25 |
| RD6/PSP6/SCK2/SCL2 | 17 |
| RD7/AD7/PSP7/SS2 | 25 |
| RD7/PSP7/SS2 | 17 |
| RE0/AD8/RD/P2D | 26 |
| RE0/RD/P2D | 18 |
| RE1/AD9/WR/P2C | 26 |
| RE1/WR/P2C | 18 |
| RE2/AD10/CS/P2B | 26 |
| RE2/CS/P2D | 18 |
| RE3/AD11/P3C | 26 |
| RE3/P3C | 18 |
| RE4/AD12/P3B | 26 |
| RE4/P3B | 18 |
| RE5/AD13/P1C | 26 |
| RE5/P1C | 18 |
| RE6/AD14/P1B | 26 |
| RE6/P1B | 18 |
| RE7/AD15/ECCP2/P2A | 26 |
| RE7/ECCP2/P2A | 18 |
| RF0/AN5 | 19, 27 |
| RF1/AN6/C2OUT | 19, 27 |
| RF2/AN7/C1OUT | 19, 27 |
| RF3/AN8 | 19, 27 |
| RF4/AN9 | 19, 27 |
| RF5/AN10/CVREF | 19, 27 |
| RF6/AN11 | 19, 27 |
| RF7/SS1 | 19, 27 |
| RG0/ECCP3/P3A | 20, 28 |
| RG1/TX2/CK2 | 20, 28 |
| RG2/RX2/DT2 | 20, 28 |
| RG3/CCP4/P3D | 20, 28 |
| RG4/CCP5/P1D | 20, 28 |
| RG5 | 20, 28 |
| RG5/MCLR/VPP | 13, 21 |
| RH0/A16 | 29 |
| RH1/A17 | 29 |
| RH2/A18 | 29 |
| RH3/A19 | 29 |
| RH4/AN12/P3C | 29 |
| RH5/AN13/P3B | 29 |
| RH6/AN14/P1C | 29 |
| RH7/AN15/P1B | 29 |
| RJ0/ALE | 30 |
| RJ1/OE | 30 |
| RJ2/WRL | 30 |
| RJ3/WRH | 30 |
| RJ4/BA0 | 30 |
| RJ5/CE | 30 |
| RJ6/LB | 30 |
| RJ7/UB | 30 |
| VDD | 20 |
| VDD | 30 |
| VSS | 20 |
| VSS | 30 |

| | |
|-------------------------------------|----|
| Pinout I/O Descriptions | 13 |
| PIC18F6628/6723 | 21 |
| PIC18F8628/8723 | 3 |
| Power-Managed Modes | 38 |
| and A/D Operation | 59 |
| Product Identification System | 59 |

R

| | |
|------------------------------|----|
| Reader Response | 58 |
| Registers | |
| ADCON0 (A/D Control 0) | 31 |
| ADCON1 (A/D Control 1) | 32 |
| ADCON2 (A/D Control 2) | 33 |
| DEVID1 (Device ID 1) | 42 |
| DEVID2 (Device ID 2) | 42 |
| Revision History | 51 |

S

| | |
|--|----|
| Special Features of the CPU | 41 |
| Device ID Registers | 41 |
| Special Microcontroller Features | 3 |

T

| | |
|--|----|
| Timing Diagrams | |
| A/D Conversion | 47 |
| Timing Diagrams and Specifications | |
| A/D Conversion Requirements | 47 |

V

| | |
|--------------------------------|----|
| Voltage-Frequency Graphs | |
| Extended (PIC18F8723) | 44 |
| Industrial (PIC18F8723) | 44 |
| Industrial (PIC18LF8723) | 45 |

W

| | |
|----------------------------|----|
| WWW Address | 57 |
| WWW, On-Line Support | 7 |

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