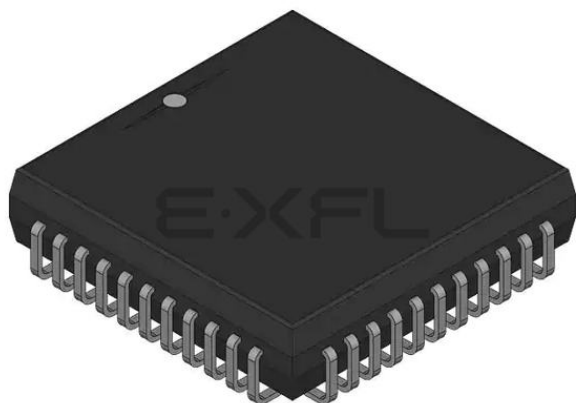




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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	80C51
Core Size	8-Bit
Speed	40MHz
Connectivity	SPI, UART/USART
Peripherals	POR, PWM, WDT
Number of I/O	32
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1.25K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 3.6V
Data Converters	-
Oscillator Type	External
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-LCC (J-Lead)
Supplier Device Package	44-PLCC (16.6x16.6)
Purchase URL	https://www.e-xfl.com/product-detail/atmel/at89c51rc2-slsul

Table 6. Timer SFRs

Mnemonic	Add	Name	7	6	5	4	3	2	1	0
TCON	88h	Timer/Counter 0 and 1 Control	TF1	TR1	TF0	TR0	IE1	IT1	IE0	IT0
TMOD	89h	Timer/Counter 0 and 1 Modes	GATE1	C/T1#	M11	M01	GATE0	C/T0#	M10	M00
TL0	8Ah	Timer/Counter 0 Low Byte								
TH0	8Ch	Timer/Counter 0 High Byte								
TL1	8Bh	Timer/Counter 1 Low Byte								
TH1	8Dh	Timer/Counter 1 High Byte								
WDRST	A6h	Watchdog Timer Reset								
WDTPRG	A7h	Watchdog Timer Program	-	-	-	-	-	WTO2	WTO1	WTO0
T2CON	C8h	Timer/Counter 2 control	TF2	EXF2	RCLK	TCLK	EXEN2	TR2	C/T2#	CP/RL2#
T2MOD	C9h	Timer/Counter 2 Mode	-	-	-	-	-	-	T2OE	DCEN
RCAP2H	CBh	Timer/Counter 2 Reload/Capture High Byte								
RCAP2L	CAh	Timer/Counter 2 Reload/Capture Low Byte								
TH2	CDh	Timer/Counter 2 High Byte								
TL2	CCh	Timer/Counter 2 Low Byte								

Table 7. PCA SFRs

Mnemonic	Add	Name	7	6	5	4	3	2	1	0
CCON	D8h	PCA Timer/Counter Control	CF	CR	-	CCF4	CCF3	CCF2	CCF1	CCF0
CMOD	D9h	PCA Timer/Counter Mode	CIDL	WDTE	-	-	-	CPS1	CPS0	ECF
CL	E9h	PCA Timer/Counter Low Byte								
CH	F9h	PCA Timer/Counter High Byte								
CCAPM0	DAh	PCA Timer/Counter Mode 0	-	ECOM0	CAPP0	CAPN0	MAT0	TOG0	PWM0	ECCF0
CCAPM1	DBh	PCA Timer/Counter Mode 1		ECOM1	CAPP1	CAPN1	MAT1	TOG1	PWM1	ECCF1
CCAPM2	DCh	PCA Timer/Counter Mode 2		ECOM2	CAPP2	CAPN2	MAT2	TOG2	PWM2	ECCF2
CCAPM3	DDh	PCA Timer/Counter Mode 3		ECOM3	CAPP3	CAPN3	MAT3	TOG3	PWM3	ECCF3
CCAPM4	DEh	PCA Timer/Counter Mode 4		ECOM4	CAPP4	CAPN4	MAT4	TOG4	PWM4	ECCF4
CCAP0H	FAh	PCA Compare Capture Module 0 H	CCAP0H7	CCAP0H6	CCAP0H5	CCAP0H4	CCAP0H3	CCAP0H2	CCAP0H1	CCAP0H0
CCAP1H	FBh	PCA Compare Capture Module 1 H	CCAP1H7	CCAP1H6	CCAP1H5	CCAP1H4	CCAP1H3	CCAP1H2	CCAP1H1	CCAP1H0
CCAP2H	FCh	PCA Compare Capture Module 2 H	CCAP2H7	CCAP2H6	CCAP2H5	CCAP2H4	CCAP2H3	CCAP2H2	CCAP2H1	CCAP2H0
CCAP3H	FDh	PCA Compare Capture Module 3 H	CCAP3H7	CCAP3H6	CCAP3H5	CCAP3H4	CCAP3H3	CCAP3H2	CCAP3H1	CCAP3H0
CCAP4H	FEh	PCA Compare Capture Module 4 H	CCAP4H7	CCAP4H6	CCAP4H5	CCAP4H4	CCAP4H3	CCAP4H2	CCAP4H1	CCAP4H0
CCAP0L	EAh	PCA Compare Capture Module 0 L	CCAP0L7	CCAP0L6	CCAP0L5	CCAP0L4	CCAP0L3	CCAP0L2	CCAP0L1	CCAP0L0
CCAP1L	EBh	PCA Compare Capture Module 1 L	CCAP1L7	CCAP1L6	CCAP1L5	CCAP1L4	CCAP1L3	CCAP1L2	CCAP1L1	CCAP1L0
CCAP2L	ECh	PCA Compare Capture Module 2 L	CCAP2L7	CCAP2L6	CCAP2L5	CCAP2L4	CCAP2L3	CCAP2L2	CCAP2L1	CCAP2L0
CCAP3L	EDh	PCA Compare Capture Module 3 L	CCAP3L7	CCAP3L6	CCAP3L5	CCAP3L4	CCAP3L3	CCAP3L2	CCAP3L1	CCAP3L0
CCAP4L	EEh	PCA Compare Capture Module 4 L	CCAP4L7	CCAP4L6	CCAP4L5	CCAP4L4	CCAP4L3	CCAP4L2	CCAP4L1	CCAP4L0

Expanded RAM (XRAM)

The AT89C51RB2/RC2 provides additional bytes of random access memory (RAM) space for increased data parameter handling and high-level language usage.

AT89C51RB2/RC2 devices have expanded RAM in external data space; maximum size and location are described in Table 18.

Table 18. Expanded RAM

Part Number	XRAM Size	Address	
		Start	End
AT89C51RB2/RC2	1024	00h	3FFh

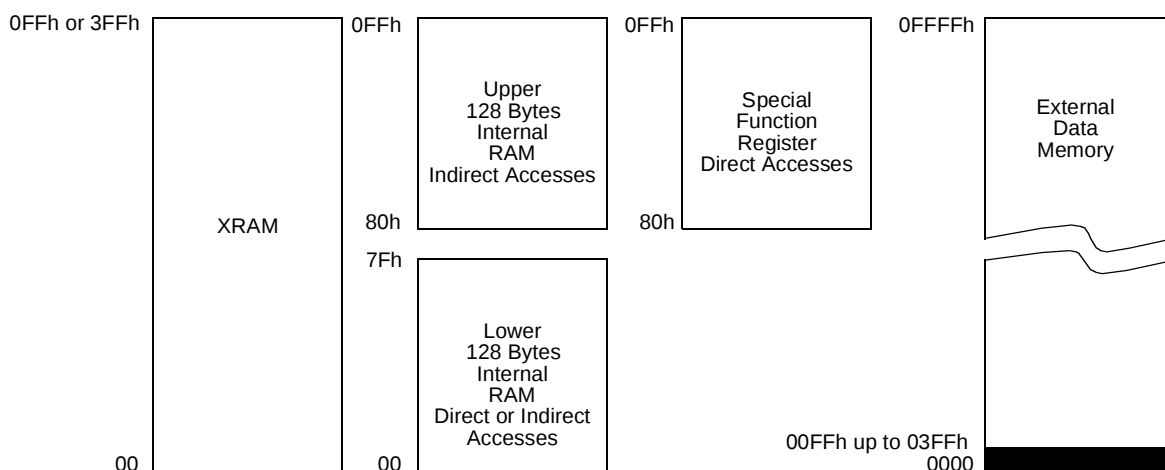
The AT89C51RB2/RC2 has internal data memory that is mapped into four separate segments.

The four segments are:

1. The Lower 128 Bytes of RAM (addresses 00h to 7Fh) are directly and indirectly addressable.
2. The Upper 128 Bytes of RAM (addresses 80h to FFh) are indirectly addressable only.
3. The Special Function Registers, SFRs, (addresses 80h to FFh) are directly addressable only.
4. The expanded RAM Bytes are indirectly accessed by MOVX instructions, and with the EXTRAM bit cleared in the AUXR register (see Table 18).

The lower 128 Bytes can be accessed by either direct or indirect addressing. The Upper 128 Bytes can be accessed by indirect addressing only. The Upper 128 Bytes occupy the same address space as the SFR. That means they have the same address, but are physically separate from SFR space.

Figure 8. Internal and External Data Memory Address



When an instruction accesses an internal location above address 7Fh, the CPU knows whether the access is to the upper 128 Bytes of data RAM or to SFR space by the addressing mode used in the instruction.

- Instructions that use direct addressing access SFR space. For example: `MOV 0A0H, # data`, accesses the SFR at location 0A0h (which is P2).

- Instructions that use indirect addressing access the Upper 128 Bytes of data RAM. For example: `MOV @R0, # data` where R0 contains 0A0h, accesses the data Byte at address 0A0h, rather than P2 (whose address is 0A0h).
- The XRAM Bytes can be accessed by indirect addressing, with EXTRAM bit cleared and MOVX instructions. This part of memory that is physically located on-chip, logically occupies the first Bytes of external data memory. The bits XRS0 and XRS1 are used to hide a part of the available XRAM as explained in Table 18. This can be useful if external peripherals are mapped at addresses already used by the internal XRAM.
- With EXTRAM = 0, the XRAM is indirectly addressed, using the MOVX instruction in combination with any of the registers R0, R1 of the selected bank or DPTR. An access to XRAM will not affect ports P0, P2, P3.6 (WR) and P3.7 (RD). For example, with EXTRAM = 0, `MOVX @R0, # data` where R0 contains 0A0H, accesses the XRAM at address 0A0H rather than external memory. An access to external data memory locations higher than the accessible size of the XRAM will be performed with the MOVX DPTR instructions in the same way as in the standard 80C51, with P0 and P2 as data/address busses, and P3.6 and P3.7 as write and read timing signals. Accesses to XRAM above 0FFH can only be done by the use of DPTR.
- With EXTRAM = 1, MOVX @RI and MOVX @DPTR will be similar to the standard 80C51. MOVX @ Ri will provide an eight-bit address multiplexed with data on Port0 and any output port pins can be used to output higher order address bits. This is to provide the external paging capability. MOVX @DPTR will generate a sixteen-bit address. Port2 outputs the high-order eight address bits (the contents of DPH) while Port0 multiplexes the low-order eight address bits (DPL) with data. MOVX @ RI and MOVX @DPTR will generate either read or write signals on P3.6 (WR) and P3.7 (RD).

The stack pointer (SP) may be located anywhere in the 256 Bytes RAM (lower and upper RAM) internal data memory. The stack may not be located in the XRAM.

The M0 bit allows to stretch the XRAM timings; if M0 is set, the read and write pulses are extended from 6 to 30 clock periods. This is useful to access external slow peripherals.

Programmable Counter Array (PCA)

The PCA provides more timing capabilities with less CPU intervention than the standard timer/counters. Its advantages include reduced software overhead and improved accuracy. The PCA consists of a dedicated timer/counter which serves as the time base for an array of five compare/capture Modules. Its clock input can be programmed to count any one of the following signals:

- Peripheral clock frequency ($F_{CLK\ PERIPH} \div 6$)
- Peripheral clock frequency ($F_{CLK\ PERIPH} \div 2$)
- Timer 0 overflow
- External input on ECI (P1.2)

Each compare/capture Modules can be programmed in any one of the following modes:

- Rising and/or falling edge capture
- Software timer
- High-speed output
- Pulse width modulator

Module 4 can also be programmed as a watchdog timer (see Section "PCA Watchdog Timer", page 42).

When the compare/capture Modules are programmed in the capture mode, software timer, or high speed output mode, an interrupt can be generated when the Module executes its function. All five Modules plus the PCA timer overflow share one interrupt vector.

The PCA timer/counter and compare/capture modules share Port 1 for external I/O. These pins are listed below. If one or several bits in the port are not used for the PCA, they can still be used for standard I/O.

PCA Component	External I/O Pin
16-bit Counter	P1.2/ECI
16-bit Module 0	P1.3/CEX0
16-bit Module 1	P1.4/CEX1
16-bit Module 2	P1.5/CEX2
16-bit Module 3	P1.6/CEX3

The PCA timer is a common time base for all five Modules (see Figure 11). The timer count source is determined from the CPS1 and CPS0 bits in the CMOD register (Table 22) and can be programmed to run at:

- 1/6 the peripheral clock frequency ($F_{CLK\ PERIPH}$)
- 1/2 the peripheral clock frequency ($F_{CLK\ PERIPH}$)
- The Timer 0 overflow
- The input on the ECI pin (P1.2)

PCA Capture Mode

To use one of the PCA Modules in the capture mode either one or both of the CCAPM bits CAPN and CAPP for that Module must be set. The external CEX input for the Module (on port 1) is sampled for a transition. When a valid transition occurs the PCA hardware loads the value of the PCA counter registers (CH and CL) into the Module's capture registers (CCAPnL and CCAPnH). If the CCFn bit for the Module in the CCON SFR and the ECCFn bit in the CCAPMn SFR are set then an interrupt will be generated (see Figure 13).

Figure 13. PCA Capture Mode

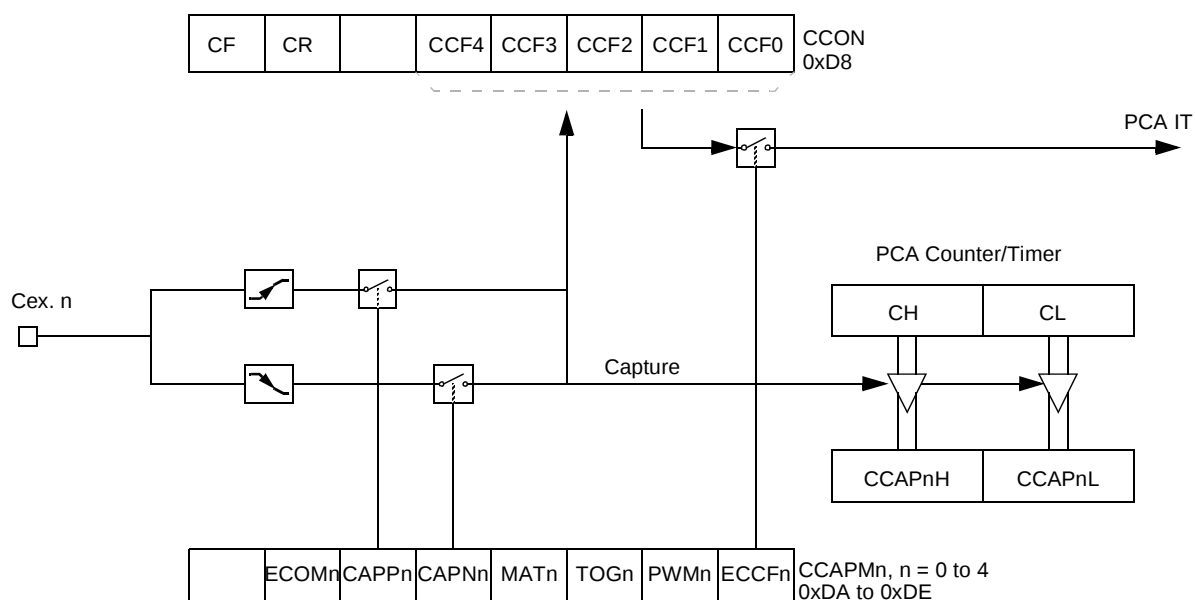


Table 38. SBUF Register
SBUF - Serial Buffer Register for UART (99h)

7	6	5	4	3	2	1	0

Reset Value = XXXX XXXXb

Table 39. BRL Register
BRL - Baud Rate Reload Register for the internal baud rate generator, UART (9Ah)

7	6	5	4	3	2	1	0

Reset Value = 0000 0000b



Table 45. IPL0 Register

IPL0 - Interrupt Priority Register (B8h)

7	6	5	4	3	2	1	0
-	PPCL	PT2L	PSL	PT1L	PX1L	PT0L	PX0L

Bit Number	Bit Mnemonic	Description
7	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
6	PPCL	PCA Interrupt Priority Bit see PPCH for priority level.
5	PT2L	Timer 2 Overflow Interrupt Priority Bit see PT2H for priority level.
4	PSL	Serial Port Priority Bit see PSH for priority level.
3	PT1L	Timer 1 Overflow Interrupt Priority Bit see PT1H for priority level.
2	PX1L	External Interrupt 1 Priority Bit see PX1H for priority level.
1	PT0L	Timer 0 Overflow Interrupt Priority Bit see PT0H for priority level.
0	PX0L	External Interrupt 0 Priority Bit see PX0H for priority level.

Reset Value = X000 0000b

Bit addressable

Table 46. IPH0 Register

IPH0 - Interrupt Priority High Register (B7h)

7	6	5	4	3	2	1	0
-	PPCH	PT2H	PSH	PT1H	PX1H	PT0H	PX0H

Bit Number	Bit Mnemonic	Description															
7	-	Reserved The value read from this bit is indeterminate. Do not set this bit.															
6	PPCH	PCA Interrupt Priority High Bit <table> <tr> <td><u>PPCH</u></td><td><u>PPCL</u></td><td><u>Priority Level</u></td></tr> <tr> <td>0</td><td>0</td><td>Lowest</td></tr> <tr> <td>0</td><td>1</td><td></td></tr> <tr> <td>1</td><td>0</td><td></td></tr> <tr> <td>1</td><td>1</td><td>Highest</td></tr> </table>	<u>PPCH</u>	<u>PPCL</u>	<u>Priority Level</u>	0	0	Lowest	0	1		1	0		1	1	Highest
<u>PPCH</u>	<u>PPCL</u>	<u>Priority Level</u>															
0	0	Lowest															
0	1																
1	0																
1	1	Highest															
5	PT2H	Timer 2 Overflow Interrupt Priority High Bit <table> <tr> <td><u>PT2H</u></td><td><u>PT2L</u></td><td><u>Priority Level</u></td></tr> <tr> <td>0</td><td>0</td><td>Lowest</td></tr> <tr> <td>0</td><td>1</td><td></td></tr> <tr> <td>1</td><td>0</td><td></td></tr> <tr> <td>1</td><td>1</td><td>Highest</td></tr> </table>	<u>PT2H</u>	<u>PT2L</u>	<u>Priority Level</u>	0	0	Lowest	0	1		1	0		1	1	Highest
<u>PT2H</u>	<u>PT2L</u>	<u>Priority Level</u>															
0	0	Lowest															
0	1																
1	0																
1	1	Highest															
4	PSH	Serial Port Priority High Bit <table> <tr> <td><u>PSH</u></td><td><u>PSL</u></td><td><u>Priority Level</u></td></tr> <tr> <td>0</td><td>0</td><td>Lowest</td></tr> <tr> <td>0</td><td>1</td><td></td></tr> <tr> <td>1</td><td>0</td><td></td></tr> <tr> <td>1</td><td>1</td><td>Highest</td></tr> </table>	<u>PSH</u>	<u>PSL</u>	<u>Priority Level</u>	0	0	Lowest	0	1		1	0		1	1	Highest
<u>PSH</u>	<u>PSL</u>	<u>Priority Level</u>															
0	0	Lowest															
0	1																
1	0																
1	1	Highest															
3	PT1H	Timer 1 Overflow Interrupt Priority High Bit <table> <tr> <td><u>PT1H</u></td><td><u>PT1L</u></td><td><u>Priority Level</u></td></tr> <tr> <td>0</td><td>0</td><td>Lowest</td></tr> <tr> <td>0</td><td>1</td><td></td></tr> <tr> <td>1</td><td>0</td><td></td></tr> <tr> <td>1</td><td>1</td><td>Highest</td></tr> </table>	<u>PT1H</u>	<u>PT1L</u>	<u>Priority Level</u>	0	0	Lowest	0	1		1	0		1	1	Highest
<u>PT1H</u>	<u>PT1L</u>	<u>Priority Level</u>															
0	0	Lowest															
0	1																
1	0																
1	1	Highest															
2	PX1H	External Interrupt 1 Priority High Bit <table> <tr> <td><u>PX1H</u></td><td><u>PX1L</u></td><td><u>Priority Level</u></td></tr> <tr> <td>0</td><td>0</td><td>Lowest</td></tr> <tr> <td>0</td><td>1</td><td></td></tr> <tr> <td>1</td><td>0</td><td></td></tr> <tr> <td>1</td><td>1</td><td>Highest</td></tr> </table>	<u>PX1H</u>	<u>PX1L</u>	<u>Priority Level</u>	0	0	Lowest	0	1		1	0		1	1	Highest
<u>PX1H</u>	<u>PX1L</u>	<u>Priority Level</u>															
0	0	Lowest															
0	1																
1	0																
1	1	Highest															
1	PT0H	Timer 0 Overflow Interrupt Priority High Bit <table> <tr> <td><u>PT0H</u></td><td><u>PT0L</u></td><td><u>Priority Level</u></td></tr> <tr> <td>0</td><td>0</td><td>Lowest</td></tr> <tr> <td>0</td><td>1</td><td></td></tr> <tr> <td>1</td><td>0</td><td></td></tr> <tr> <td>1</td><td>1</td><td>Highest</td></tr> </table>	<u>PT0H</u>	<u>PT0L</u>	<u>Priority Level</u>	0	0	Lowest	0	1		1	0		1	1	Highest
<u>PT0H</u>	<u>PT0L</u>	<u>Priority Level</u>															
0	0	Lowest															
0	1																
1	0																
1	1	Highest															
0	PX0H	External Interrupt 0 Priority High Bit <table> <tr> <td><u>PX0H</u></td><td><u>PX0L</u></td><td><u>Priority Level</u></td></tr> <tr> <td>0</td><td>0</td><td>Lowest</td></tr> <tr> <td>0</td><td>1</td><td></td></tr> <tr> <td>1</td><td>0</td><td></td></tr> <tr> <td>1</td><td>1</td><td>Highest</td></tr> </table>	<u>PX0H</u>	<u>PX0L</u>	<u>Priority Level</u>	0	0	Lowest	0	1		1	0		1	1	Highest
<u>PX0H</u>	<u>PX0L</u>	<u>Priority Level</u>															
0	0	Lowest															
0	1																
1	0																
1	1	Highest															

Reset Value = X000 0000b

Not bit addressable

Table 47. IEN1 Register

IEN1 - Interrupt Enable Register (B1h)

7	6	5	4	3	2	1	0
-	-	-	-	-	ESPI	-	KBD

Bit Number	Bit Mnemonic	Description
7	-	Reserved
6	-	Reserved
5	-	Reserved
4	-	Reserved
3	-	Reserved
2	ESPI	SPI Interrupt Enable Bit Cleared to disable SPI interrupt. Set to enable SPI interrupt.
1	-	Reserved
0	KBD	Keyboard Interrupt Enable Bit Cleared to disable keyboard interrupt. Set to enable keyboard interrupt.

Reset Value = XXXX X000b

Bit addressable

Registers

Table 51. KBF Register

KBF - Keyboard Flag Register (9Eh)

7	6	5	4	3	2	1	0
KBF7	KBF6	KBF5	KBF4	KBF3	KBF2	KBF1	KBF0
Bit Number	Bit Mnemonic	Description					
7	KBF7	Keyboard Line 7 Flag Set by hardware when the Port line 7 detects a programmed level. It generates a Keyboard interrupt request if the KBKIE. 7 bit in KBIE register is set. Must be cleared by software.					
6	KBF6	Keyboard Line 6 Flag Set by hardware when the Port line 6 detects a programmed level. It generates a Keyboard interrupt request if the KBIE. 6 bit in KBIE register is set. Must be cleared by software.					
5	KBF5	Keyboard Line 5 Flag Set by hardware when the Port line 5 detects a programmed level. It generates a Keyboard interrupt request if the KBIE. 5 bit in KBIE register is set. Must be cleared by software.					
4	KBF4	Keyboard Line 4 Flag Set by hardware when the Port line 4 detects a programmed level. It generates a Keyboard interrupt request if the KBIE. 4 bit in KBIE register is set. Must be cleared by software.					
3	KBF3	Keyboard Line 3 Flag Set by hardware when the Port line 3 detects a programmed level. It generates a Keyboard interrupt request if the KBIE. 3 bit in KBIE register is set. Must be cleared by software.					
2	KBF2	Keyboard Line 2 Flag Set by hardware when the Port line 2 detects a programmed level. It generates a Keyboard interrupt request if the KBIE. 2 bit in KBIE register is set. Must be cleared by software.					
1	KBF1	Keyboard Line 1 Flag Set by hardware when the Port line 1 detects a programmed level. It generates a Keyboard interrupt request if the KBIE. 1 bit in KBIE register is set. Must be cleared by software.					
0	KBF0	Keyboard Line 0 Flag Set by hardware when the Port line 0 detects a programmed level. It generates a Keyboard interrupt request if the KBIE. 0 bit in KBIE register is set. Must be cleared by software.					

Reset Value = 0000 0000b

This register is read only access, all flags are automatically cleared by reading the register.

Bit Number	Bit Mnemonic	Description
1	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
0	-	Reserved The value read from this bit is indeterminate. Do not set this bit.

Reset Value = 00X0 XXXXb

Not Bit addressable

Serial Peripheral DATa Register (SPDAT)

The Serial Peripheral Data Register (Table 58) is a read/write buffer for the receive data register. A write to SPDAT places data directly into the shift register. No transmit buffer is available in this model.

A Read of the SPDAT returns the value located in the receive buffer and not the content of the shift register.

Table 58. SPDAT Register

SPDAT - Serial Peripheral Data Register (0C5H)

7	6	5	4	3	2	1	0
R7	R6	R5	R4	R3	R2	R1	R0

Reset Value = Indeterminate

R7:R0: Receive data bits

SPCON, SPSTA and SPDAT registers may be read and written at any time while there is no on-going exchange. However, special care should be taken when writing to them while a transmission is on-going:

- Do not change SPR2, SPR1 and SPR0
- Do not change CPHA and CPOL
- Do not change MSTR
- Clearing SPEN would immediately disable the peripheral
- Writing to the SPDAT will cause an overflow.

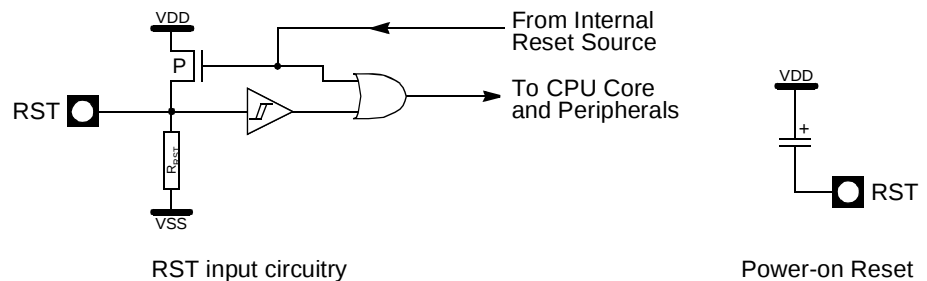
Power Management

Two power reduction modes are implemented in the AT89C51RB2/RC2: the Idle mode and the Power-down mode. These modes are detailed in the following sections. In addition to these power reduction modes, the clocks of the core and peripherals can be dynamically divided by 2 using the X2 mode detailed in Section “X2 Feature”.

Reset

In order to start-up (cold reset) or to restart (warm reset) properly the microcontroller, a high level has to be applied on the RST pin. A bad level leads to a wrong initialization of the internal registers like SFRs, Program Counter... and to unpredictable behavior of the microcontroller. A proper device reset initializes the AT89C51RB2/RC2 and vectors the CPU to address 0000h. RST input has a pull-down resistor allowing power-on reset by simply connecting an external capacitor to V_{DD} as shown in Figure 32. A warm reset can be applied either directly on the RST pin or indirectly by an internal reset source such as the watchdog timer. Resistor value and input characteristics are discussed in the Section “DC Characteristics” of the AT89C51RB2/RC2 datasheet.

Figure 32. Reset Circuitry and Power-On Reset



Cold Reset

2 conditions are required before enabling a CPU start-up:

- V_{DD} must reach the specified V_{DD} range
- The level on X1 input pin must be outside the specification (V_{IH} , V_{IL})

If one of these 2 conditions are not met, the microcontroller does not start correctly and can execute an instruction fetch from anywhere in the program space. An active level applied on the RST pin must be maintained till both of the above conditions are met. A reset is active when the level V_{IH1} is reached and when the pulse width covers the period of time where V_{DD} and the oscillator are not stabilized. 2 parameters have to be taken into account to determine the reset pulse width:

- V_{DD} rise time,
- Oscillator startup time.

To determine the capacitor value to implement, the highest value of these 2 parameters has to be chosen. Table 1 gives some capacitor values examples for a minimum R_{RST} of 50 K Ω and different oscillator startup and V_{DD} rise times.

Table 1. Minimum Reset Capacitor Value for a 50 k Ω Pull-down Resistor⁽¹⁾

Oscillator Start-Up Time	VDD Rise Time		
	1 ms	10 ms	100 ms
5 ms	820 nF	1.2 μ F	12 μ F
20 ms	2.7 μ F	3.9 μ F	12 μ F

Note: These values assume V_{DD} starts from 0V to the nominal value. If the time between 2 on/off sequences is too fast, the power-supply de-coupling capacitors may not be fully discharged, leading to a bad reset sequence.

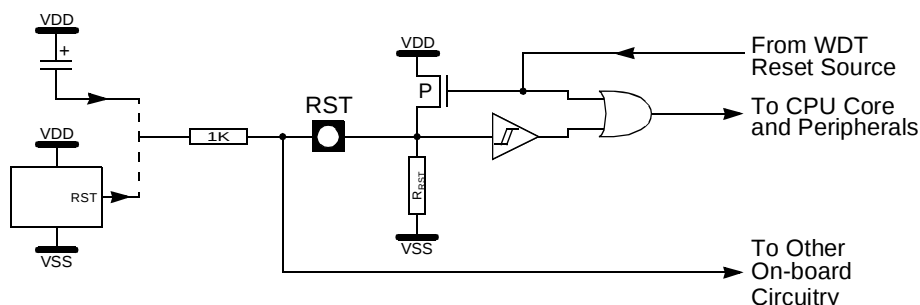
Warm Reset

To achieve a valid reset, the reset signal must be maintained for at least 2 machine cycles (24 oscillator clock periods) while the oscillator is running. The number of clock periods is mode independent (X2 or X1).

Watchdog Reset

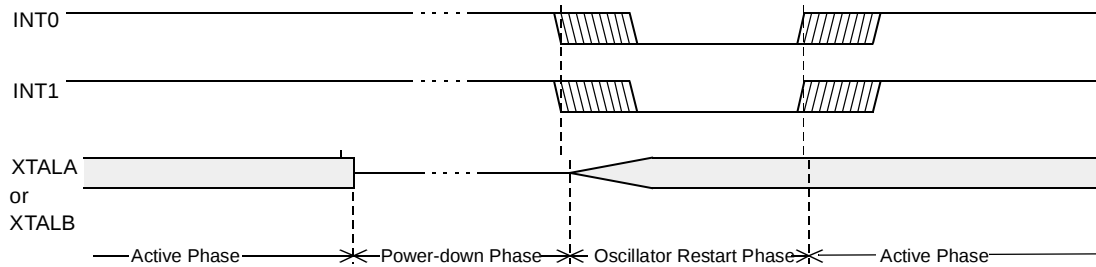
As detailed in Section “Hardware Watchdog Timer”, page 77, the WDT generates a 96-clock period pulse on the RST pin. In order to properly propagate this pulse to the rest of the application in case of external capacitor or power-supply supervisor circuit, a 1 k Ω resistor must be added as shown Figure 33.

Figure 33. Reset Circuitry for WDT Reset-out Usage



be the one following the instruction that puts the AT89C51RB2/RC2 into Power-down mode.

Figure 34. Power-down Exit Waveform



Exit from Power-down by reset redefines all the SFRs, exit from Power-down by external interrupt does not affect the SFRs.

Exit from Power-down by either reset or external interrupt or keyboard interrupt does not affect the internal RAM content.

Note: If idle mode is activated with Power-down mode (IDL and PD bits set), the exit sequence is unchanged, when execution is vectored to interrupt, PD and IDL bits are cleared and idle mode is not entered.

Table 62 shows the state of ports during idle and power-down modes.

Table 62. State of Ports

Mode	Program Memory	ALE	PSEN	PORT0	PORT1	PORT2	PORT3
Idle	Internal	1	1	Port Data ⁽¹⁾	Port Data	Port Data	Port Data
Idle	External	1	1	Floating	Port Data	Address	Port Data
Power Down	Internal	0	0	Port Data ⁽¹⁾	Port Data	Port Data	Port Data
Power Down	External	0	0	Floating	Port Data	Port Data	Port Data

Port 0 can force a 0 level. A "one" will leave port floating.

Functional Description

Software Security Bits (SSB)

The SSB protects any Flash access from ISP command.
The command "Program Software Security bit" can only write a higher priority level.

There are three levels of security:

- level 0: **NO_SECURITY** (FFh)

This is the default level.

From level 0, one can write level 1 or level 2.

- level 1: **WRITE_SECURITY** (FEh)

For this level it is impossible to write in the Flash memory, BSB and SBV.

The Bootloader returns 'P' on write access.

From level 1, one can write only level 2.

- level 2: **RD_WR_SECURITY** (FCh)

The level 2 forbids all read and write accesses to/from the Flash/EEPROM memory.

The Bootloader returns 'L' on read or write access.

Only a full chip erase in parallel mode (using a programmer) or ISP command can reset the software security bits.

From level 2, one cannot read and write anything.

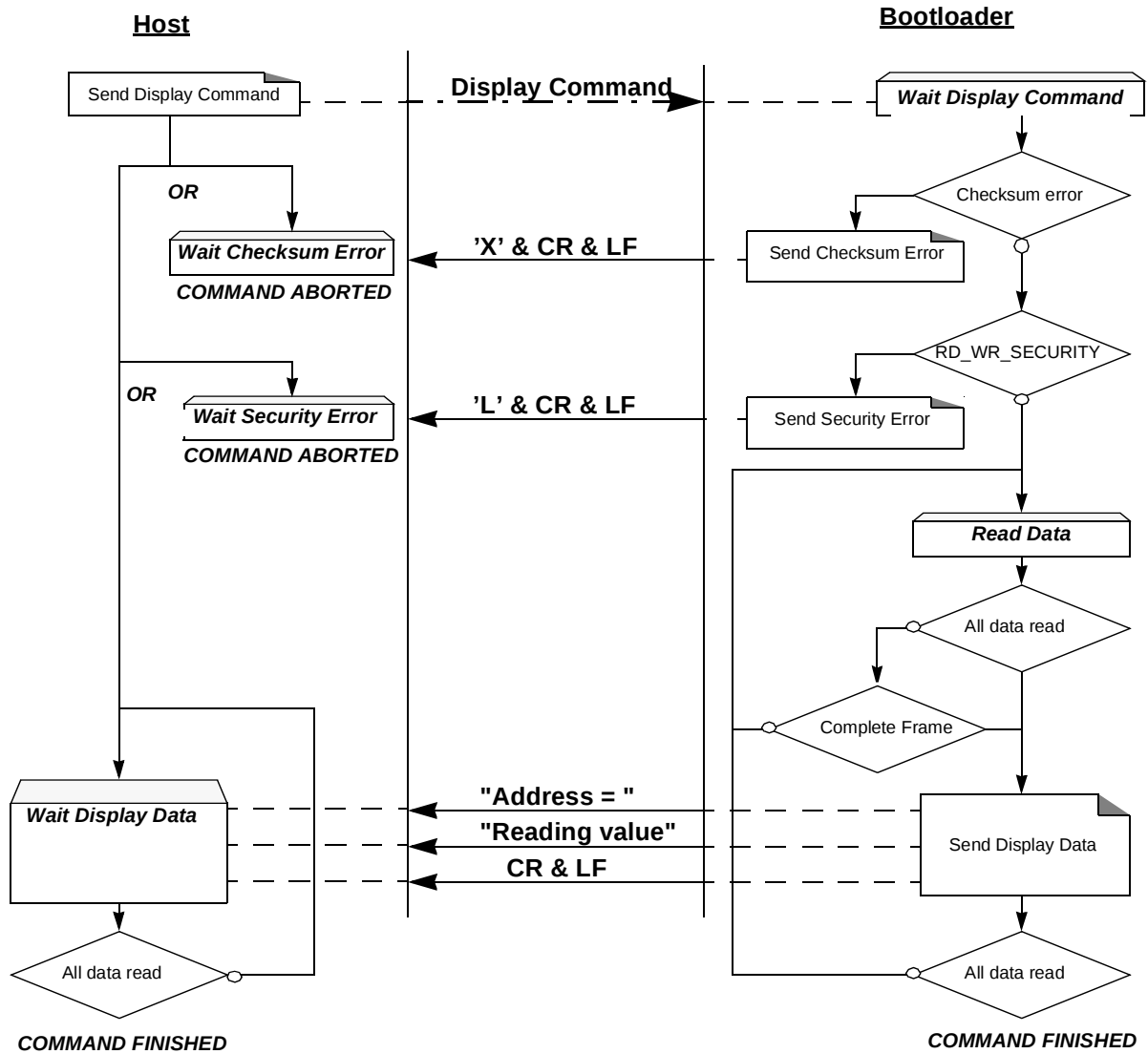
Table 71. Software Security Byte Behavior

	Level 0	Level 1	Level 2
Flash/EEPROM	Any access allowed	Read only access allowed	Any access not allowed
Fuse Bit	Any access allowed	Read only access allowed	Any access not allowed
BSB & SBV	Any access allowed	Read only access allowed	Any access not allowed
SSB	Any access allowed	Write level 2 allowed	Read only access allowed
Manufacturer Info	Read only access allowed	Read only access allowed	Read only access allowed
Bootloader Info	Read only access allowed	Read only access allowed	Read only access allowed
Erase Block	Allowed	Not allowed	Not allowed
Full-chip Erase	Allowed	Allowed	Allowed
Blank Check	Allowed	Allowed	Allowed

Display Data

Description

Figure 44. Display Flow



Note: The maximum size of block is 400h. To read more than 400h Bytes, the Host must send a new command.

Electrical Characteristics

Absolute Maximum Ratings

C = commercial.....0°C to 70°C I = industrial-40°C to 85°C Storage Temperature -65°C to + 150°C Voltage on V _{CC} to V _{SS} (standard voltage)-0.5V to + 6.5V Voltage on V _{CC} to V _{SS} (low voltage).....-0.5V to + 4.5V Voltage on Any Pin to V _{SS}-0.5V to V _{CC} + 0.5V Power Dissipation 1 W	Note: Stresses at or above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions may affect device reliability. Power dissipation value is based on the maximum allowable die temperature and the thermal resistance of the package.
--	--

DC Parameters for Standard Voltage

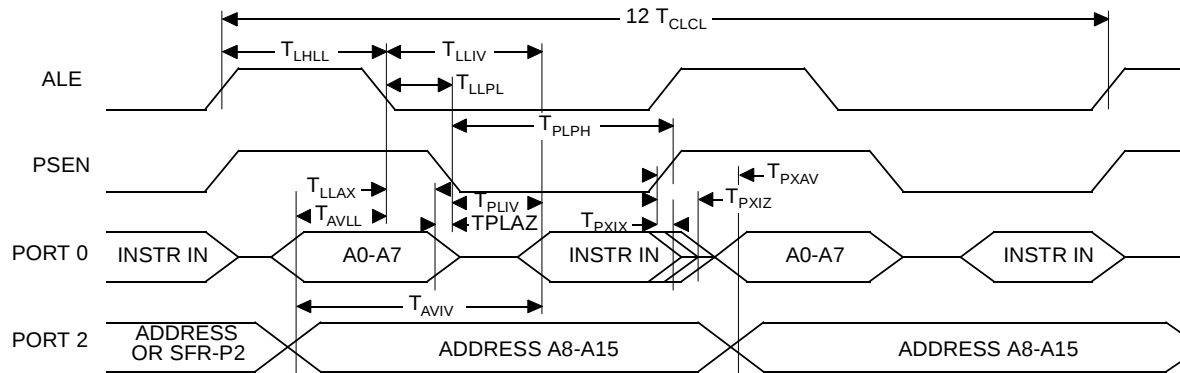
T_A = -40°C to +85°C; V_{SS} = 0V;

V_{CC} = 2.7V to 5.5V and F = 0 to 40 MHz (both internal and external code execution)

V_{CC} = 4.5V to 5.5V and F = 0 to 60 MHz (internal code execution only)

Symbol	Parameter	Min	Typ	Max	Unit	Test Conditions
V _{IL}	Input Low Voltage	-0.5		0.2 V _{CC} - 0.1	V	
V _{IH}	Input High Voltage except RST, XTAL1	0.2 V _{CC} + 0.9		V _{CC} + 0.5	V	
V _{IH1} ⁽⁹⁾	Input High Voltage RST, XTAL1	0.7 V _{CC}		V _{CC} + 0.5	V	
V _{OL}	Output Low Voltage, ports 1, 2, 3, 4 ⁽⁶⁾			0.3	V	VCC = 4.5V to 5.5V I _{OL} = 100 μA ⁽⁴⁾
				0.45	V	I _{OL} = 1.6 mA ⁽⁴⁾
				1.0	V	I _{OL} = 3.5 mA ⁽⁴⁾
V _{OL1}	Output Low Voltage, port 0, ALE, $\overline{\text{PSEN}}$ ⁽⁶⁾			0.45	V	VCC = 2.7V to 5.5V I _{OL} = 0.8 mA ⁽⁴⁾
				0.3	V	VCC = 4.5V to 5.5V I _{OL} = 200 μA ⁽⁴⁾
				0.45	V	I _{OL} = 3.2 mA ⁽⁴⁾
V _{OH}	Output High Voltage, ports 1, 2, 3, 4	V _{CC} - 0.3 V _{CC} - 0.7 V _{CC} - 1.5		1.0	V	I _{OH} = 7.0 mA ⁽⁴⁾
				0.45	V	VCC = 2.7V to 5.5V I _{OH} = 1.6 mA ⁽⁴⁾
					V	V _{CC} = 5V ± 10% I _{OH} = -10 μA
		0.9 V _{CC}			V	VCC = 2.7V to 5.5V I _{OH} = -10 μA

External Program Memory Read Cycle

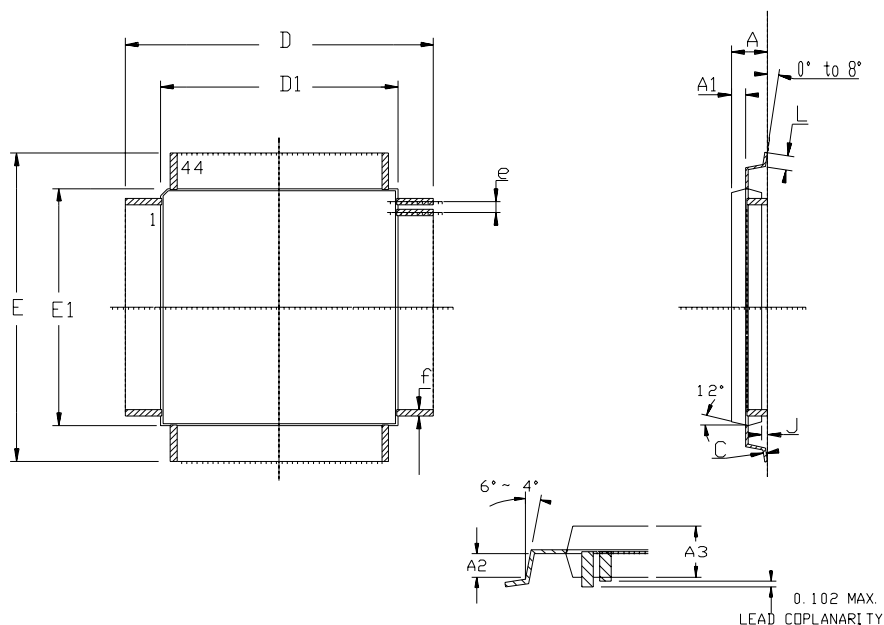


External Data Memory Characteristics

Table 78. Symbol Description

Symbol	Parameter
T_{RLRH}	$\overline{RD}$ Pulse Width
T_{WLWH}	$\overline{WR}$ Pulse Width
T_{RLDV}	$\overline{RD}$ to Valid Data In
T_{RHDZ}	Data Hold After $\overline{RD}$
T_{RHDZ}	Data Float After $\overline{RD}$
T_{LLDV}	ALE to Valid Data In
T_{AVDV}	Address to Valid Data In
T_{LLWL}	ALE to $\overline{WR}$ or $\overline{RD}$
T_{AVWL}	Address to $\overline{WR}$ or $\overline{RD}$
T_{QVWX}	Data Valid to $\overline{WR}$ Transition
T_{QVWH}	Data set-up to $\overline{WR}$ High
T_{WHQX}	Data Hold After $\overline{WR}$
T_{RLAZ}	$\overline{RD}$ Low to Address Float
T_{WHLH}	$\overline{RD}$ or $\overline{WR}$ High to ALE high

VQFP44



	MM		INCH	
	Min	Max	Min	Max
A	-	1.60	-	.063
A1	0.64 REF		.025 REF	
A2	0.64 REF		.025 REF	
A3	1.35	1.45	.053	.057
D	11.90	12.10	.468	.476
D1	9.90	10.10	.390	.398
E	11.90	12.10	.468	.476
E1	9.90	10.10	.390	.398
J	0.05	-	.002	-
L	0.45	0.75	.018	.030
e	0.80 BSC		.0315 BSC	
f	0.35 BSC		.014 BSC	



Atmel Corporation

2325 Orchard Parkway
San Jose, CA 95131, USA
Tel: 1(408) 441-0311
Fax: 1(408) 487-2600

Regional Headquarters

Europe

Atmel Sarl
Route des Arsenaux 41
Case Postale 80
CH-1705 Fribourg
Switzerland
Tel: (41) 26-426-5555
Fax: (41) 26-426-5500

Asia

Room 1219
Chinachem Golden Plaza
77 Mody Road Tsimshatsui
East Kowloon
Hong Kong
Tel: (852) 2721-9778
Fax: (852) 2722-1369

Japan

9F, Tonetsu Shinkawa Bldg.
1-24-8 Shinkawa
Chuo-ku, Tokyo 104-0033
Japan
Tel: (81) 3-3523-3551
Fax: (81) 3-3523-7581

Atmel Operations

Memory

2325 Orchard Parkway
San Jose, CA 95131, USA
Tel: 1(408) 441-0311
Fax: 1(408) 436-4314

Microcontrollers

2325 Orchard Parkway
San Jose, CA 95131, USA
Tel: 1(408) 441-0311
Fax: 1(408) 436-4314

La Chantrerie
BP 70602
44306 Nantes Cedex 3, France
Tel: (33) 2-40-18-18-18
Fax: (33) 2-40-18-19-60

ASIC/ASSP/Smart Cards

Zone Industrielle
13106 Rousset Cedex, France
Tel: (33) 4-42-53-60-00
Fax: (33) 4-42-53-60-01

1150 East Cheyenne Mtn. Blvd.
Colorado Springs, CO 80906, USA
Tel: 1(719) 576-3300
Fax: 1(719) 540-1759

Scottish Enterprise Technology Park
Maxwell Building
East Kilbride G75 0QR, Scotland
Tel: (44) 1355-803-000
Fax: (44) 1355-242-743

RF/Automotive

Theresienstrasse 2
Postfach 3535
74025 Heilbronn, Germany
Tel: (49) 71-31-67-0
Fax: (49) 71-31-67-2340

1150 East Cheyenne Mtn. Blvd.
Colorado Springs, CO 80906, USA
Tel: 1(719) 576-3300
Fax: 1(719) 540-1759

Biometrics/Imaging/Hi-Rel MPU/ High Speed Converters/RF Datacom

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Tel: (33) 4-76-58-30-00
Fax: (33) 4-76-58-34-80

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