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Understanding <u>Embedded - FPGAs (Field Programmable Gate Array)</u>

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Obsolete
Number of LABs/CLBs	684
Number of Logic Elements/Cells	-
Total RAM Bits	-
Number of I/O	72
Number of Gates	4000
Voltage - Supply	4.5V ~ 5.5V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 70°C (TA)
Package / Case	84-LCC (J-Lead)
Supplier Device Package	84-PLCC (29.31x29.31)
Purchase URL	https://www.e-xfl.com/product-detail/microsemi/a1240a-plg84c

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

Product Plan

	s	peed Grad	e ¹	Application ¹			
Device/Package	Std.	-1	-2	С	I	М	В
A1225A Device	•	•	•		•	•	
84-Pin Plastic Leaded Chip Carrier (PL)	✓	1	1	1	1	_	_
100-Pin Plastic Quad Flatpack (PQ)	1	1	1	1	1	_	_
100-Pin Very Thin Quad Flatpack (VQ)	1	✓	1	1	_	_	_
100-Pin Ceramic Pin Grid Array (PG)	1	1	1	1	_	_	_
A1240A Device	I				ı	ı	
84-Pin Plastic Leaded Chip Carrier (PL)	✓	1	✓	1	1	_	_
132-Pin Ceramic Pin Grid Array (PG)	1	1	1	1	_	1	✓
144-Pin Plastic Quad Flat Pack (PQ)	1	1	1	1	1	_	_
176-Pin Thin (1.4 mm) Quad Flat Pack (TQ)	1	1	1	1	_	_	_
A1280A Device	I				ı	ı	
160-Pin Plastic Quad Flatpack (PQ)	✓	1	✓	✓	1	_	_
172-Pin Ceramic Quad Flatpack (CQ)	1	✓	✓	✓	_	1	✓
176-Pin Ceramic Pin Grid Array (PG)	/	✓	✓	1	_	1	✓
176-Pin Thin (1.4 mm) Quad Flat Pack (TQ)	1	1	1	1	_	_	_
• • •		•		•	_	-	_

Notes:

Applications:
 C = Commercial
 I = Industrial
 M = Military
 B = MIL-STD-883

Availability: ✓ = Available P = Planned – = Not planned

Speed Grade:

-1 = Approx. 15% faster than Std. -2 = Approx. 25% faster than Std.

2. Contact your Microsemi SoC Products Group sales representative for product availability.

Device Resources

Device	Logic			User I/Os								
Series	Modules	Gates	PG176	PG132	PG100	PQ160	PQ144	PQ100	PL84	CQ172	TQ176	VQ100
A1225A	451	2,500	_	_	83	_	_	83	72	_	_	83
A1240A	684	4,000	_	104	_	_	104	_	72	_	104	_
A1280A	1,232	8,000	140	-	_	125	ı	-	72	140	140	_

Contact your local Microsemi SoC Products Group representative for device availability: http://www.microsemi.com/soc/contact/default.aspx.

Revision 8 III



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1 - ACT 2 Family Overview

General Description

The ACT 2 family represents Actel's second generation of field programmable gate arrays (FPGAs). The ACT 2 family presents a two-module architecture, consisting of C-modules and S-modules. These modules are optimized for both combinatorial and sequential designs. Based on Actel's patented channeled array architecture, the ACT 2 family provides significant enhancements to gate density and performance while maintaining downward compatibility with the ACT 1 design environment and upward compatibility with the ACT 3 design environment. The devices are implemented in silicon gate, 1.0-μm, two-level metal CMOS, and employ Actel's PLICE® antifuse technology. This revolutionary architecture offers gate array design flexibility, high performance, and fast time-to-production with user programming. The ACT 2 family is supported by the Designer and Designer Advantage Systems, which offers automatic pin assignment, validation of electrical and design rules, automatic placement and routing, timing analysis, user programming, and diagnostic probe capabilities. The systems are supported on the following platforms: 386/486™ PC, Sun™, and HP™ workstations. The systems provide CAE interfaces to the following design environments: Cadence, Viewlogic®, Mentor Graphics®, and OrCAD™.



Static Power Component

Microsemi FPGAs have small static power components that result in lower power dissipation than PALs or PLDs. By integrating multiple PALs/PLDs into one FPGA, an even greater reduction in board-level power dissipation can be achieved.

The power due to standby current is typically a small component of the overall power. Standby power is calculated in Table 2-5 for commercial, worst case conditions.

Table 2-5 • Standby Power Calculation

ICC	VCC	Power
2 mA	5.25 V	10.5 mW

The static power dissipated by TTL loads depends on the number of outputs driving high or low and the DC load current. Again, this value is typically small. For instance, a 32-bit bus sinking 4 mA at 0.33 V will generate 42 mW with all outputs driving low, and 140 mW with all outputs driving high. The actual dissipation will average somewhere between as I/Os switch states with time.

Active Power Component

Power dissipation in CMOS devices is usually dominated by the active (dynamic) power dissipation. This component is frequency dependent, a function of the logic and the external I/O. Active power dissipation results from charging internal chip capacitances of the interconnect, unprogrammed antifuses, module inputs, and module outputs, plus external capacitance due to PC board traces and load device inputs.

An additional component of the active power dissipation is the totem-pole current in CMOS transistor pairs. The net effect can be associated with an equivalent capacitance that can be combined with frequency and voltage to represent active power dissipation.

Equivalent Capacitance

The power dissipated by a CMOS circuit can be expressed by EQ 3.

Power (
$$\mu$$
W) = C_{EQ} * VCC² * F

EQ3

Where:

C_{EO} is the equivalent capacitance expressed in pF.

VCC is the power supply in volts.

F is the switching frequency in MHz.

Equivalent capacitance is calculated by measuring ICC active at a specified frequency and voltage for each circuit component of interest. Measurements have been made over a range of frequencies at a fixed value of VCC. Equivalent capacitance is frequency independent so that the results may be used over a wide range of operating conditions. Equivalent capacitance values are shown in Table 2-6.

Table 2-6 • CEQ Values for Microsemi FPGAs

Item	CEQ Value
Modules (C _{EQM})	5.8
Input Buffers (C _{EQI})	12.9
Output Buffers (C _{EQO})	23.8
Routed Array Clock Buffer Loads (C _{EQCR})	3.9

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Determining Average Switching Frequency

To determine the switching frequency for a design, you must have a detailed understanding of the data input values to the circuit. The following guidelines are meant to represent worst-case scenarios so that they can be generally used to predict the upper limits of power dissipation. These guidelines are given in Table 2-8.

Table 2-8 • Guidelines for Predicting Power Dissipation

Data	Value
Logic Modules (m)	80% of modules
Inputs switching (n)	# inputs/4
Outputs switching (p)	# output/4
First routed array clock loads (q1)	40% of sequential modules
Second routed array clock loads (q2)	40% of sequential modules
Load capacitance (C _L)	35 pF
Average logic module switching rate (f _m)	F/10
Average input switching rate (f _n)	F/5
Average output switching rate (f _p)	F/10
Average first routed array clock rate (f _{q1})	F
Average second routed array clock rate (f _{q2})	F/2

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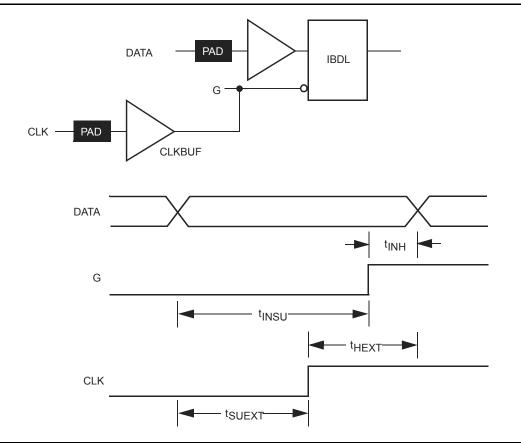


Figure 2-7 • Input Buffer Latches

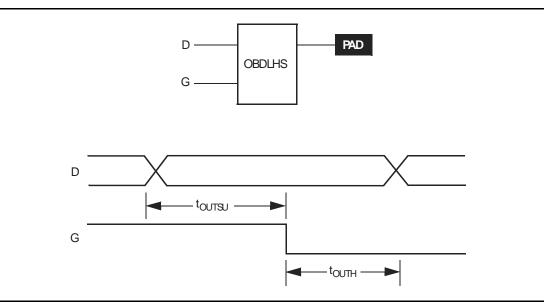


Figure 2-8 • Output Buffer Latches

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Timing Derating Factor (Temperature and Voltage)

Table 2-9 • Timing Derating Factor (Temperature and Voltage)

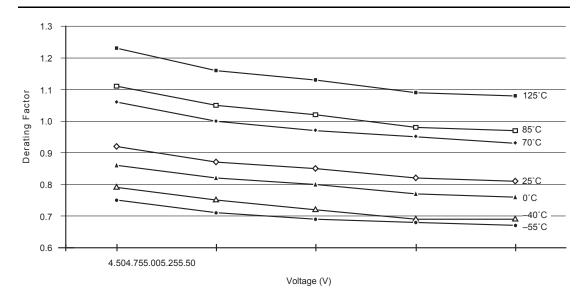
(Commercial Minimum/Maximum Specification) x	Indus	strial	Military		
	Min.	Max.	Min.	Max.	
	0.69	1.11	0.67	1.23	

Table 2-10 • Timing Derating Factor for Designs at Typical Temperature ($T_J = 25^{\circ}C$) and Voltage (5.0 V)

(Commercial Maximum Specification) x	0.85
--------------------------------------	------

Table 2-11 • Temperature and Voltage Derating Factors (normalized to Worst-Case Commercial, TJ = 4.75 V, 70°C)

	-55	-40	0	25	70	85	125
4.50	0.75	0.79	0.86	0.92	1.06	1.11	1.23
4.75	0.71	0.75	0.82	0.87	1.00	1.05	1.13
5.00	0.69	0.72	0.80	0.85	0.97	1.02	1.13
5.25	0.68	0.69	0.77	0.82	0.95	0.98	1.09
5.50	0.67	0.69	0.76	0.81	0.93	0.97	1.08



Note: This derating factor applies to all routing and propagation delays.

Figure 2-9 • Junction Temperature and Voltage Derating Curves (normalized to Worst-Case Commercial, T_J = 4.75 V, 70°C)



A1225A Timing Characteristics (continued)

Table 2-13 • A1225A Worst-Case Commercial Conditions, VCC = 4.75 V, $T_J = 70^{\circ}$ C

I/O Mod	ule Input Propagation Delays		-2 S	peed	-1 Speed		Std. Speed		Units
Paramet	ter/Description		Min.	Max.	Min.	Max.	Min.	Max.	
t _{INYH}	Pad to Y High			2.9		3.3		3.8	ns
t _{INYL}	Pad to Y Low			2.6		3.0		3.5	ns
t _{INGH}	G to Y High			5.0		5.7		6.6	ns
t _{INGL}	G to Y Low			4.7		5.4		6.3	ns
Input Mo	odule Predicted Input Routing Del	ays [*]							
t _{IRD1}	FO = 1 Routing Delay			4.1		4.6		5.4	ns
t _{IRD2}	FO = 2 Routing Delay			4.6		5.2		6.1	ns
t _{IRD3}	FO = 3 Routing Delay			5.3		6.0		7.1	ns
t _{IRD4}	FO = 4 Routing Delay			5.7		6.4		7.6	ns
t _{IRD8}	FO = 8 Routing Delay			7.4		8.3		9.8	ns
Global (Clock Network								
t _{CKH}	Input Low to High	FO = 32		10.2		11.0		12.8	ns
		FO = 256		11.8		13.0		15.7	
t _{CKL}	Input High to Low	FO = 32		10.2		11.0		12.8	ns
		FO = 256		12.0		13.2		15.9	
t _{PWH}	Minimum Pulse Width High	FO = 32	3.4		4.1		4.5		ns
		FO = 256	3.8		4.5		5.0		
t _{PWL}	Minimum Pulse Width Low	FO = 32	3.4		4.1		4.5		ns
		FO = 256	3.8		4.5		5.0		
t _{CKSW}	Maximum Skew	FO = 32		0.7		0.7		0.7	ns
		FO = 256		3.5		3.5		3.5	
t _{SUEXT}	Input Latch External Setup	FO = 32	0.0		0.0		0.0		ns
		FO = 256	0.0		0.0		0.0		
t _{HEXT}	Input Latch External Hold	FO = 32	7.0		7.0		7.0		ns
		FO = 256	11.2		11.2		11.2		
t _P	Minimum Period	FO = 32	7.7		8.3		9.1		ns
		FO = 256	8.1		8.8		10.0		
f _{MAX}	Maximum Frequency	FO = 32		130.0		120.0		110.0	ns
		FO = 256		125.0		115.0		100.0]

Note: *These parameters should be used for estimating device performance. Optimization techniques may further reduce delays by 0 to 4 ns. Routing delays are for typical designs across worst-case operating conditions. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.



A1240A Timing Characteristics

Table 2-15 • A1240A Worst-Case Commercial Conditions, VCC = 4.75 V, T, I = 70°C

Logic Module Propagation Delays ¹		-2 Speed ³		-1 Speed		Std. Speed	
er/Description	Min.	Max.	Min.	Max.	Min.	Max.	1
Single Module		3.8		4.3		5.0	ns
Sequential Clock to Q		3.8		4.3		5.0	ns
Latch G to Q		3.8		4.3		5.0	ns
Flip-Flop (Latch) Reset to Q		3.8		4.3		5.0	ns
d Routing Delays ²					I		L
FO = 1 Routing Delay		1.4		1.5		1.8	ns
FO = 2 Routing Delay		1.7		2.0		2.3	ns
FO = 3 Routing Delay		2.3		2.6		3.0	ns
FO = 4 Routing Delay		3.1		3.5		4.1	ns
FO = 8 Routing Delay		4.7		5.4		6.3	ns
al Timing Characteristics ^{3,4}		•		•	•		•
Flip-Flop (Latch) Data Input Setup	0.4		0.4		0.5		ns
Flip-Flop (Latch) Data Input Hold	0.0		0.0		0.0		ns
Flip-Flop (Latch) Enable Setup	0.8		0.9		1.0		ns
Flip-Flop (Latch) Enable Hold	0.0		0.0		0.0		ns
Flip-Flop (Latch) Clock Active Pulse Width	4.5		6.0		6.5		ns
Flip-Flop (Latch) Clock Asynchronous Pulse Width	4.5		6.0		6.5		ns
Flip-Flop Clock Input Period	9.8		12.0		15.0		ns
Input Buffer Latch Hold	0.0		0.0		0.0		ns
Input Buffer Latch Setup	0.4		0.4		0.5		ns
Output Buffer Latch Hold	0.0		0.0		0.0		ns
Output Buffer Latch Setup	0.4		0.4		0.5		ns
Flip-Flop (Latch) Clock Frequency		100.0		80.0		66.0	MHz
	Single Module Sequential Clock to Q Latch G to Q Flip-Flop (Latch) Reset to Q d Routing Delays² FO = 1 Routing Delay FO = 2 Routing Delay FO = 3 Routing Delay FO = 8 Routing Delay FO = 8 Routing Delay FO = 8 Routing Delay FIip-Flop (Latch) Data Input Setup Flip-Flop (Latch) Data Input Hold Flip-Flop (Latch) Enable Setup Flip-Flop (Latch) Enable Hold Flip-Flop (Latch) Clock Active Pulse Width Flip-Flop Clock Input Period Input Buffer Latch Hold Input Buffer Latch Hold Output Buffer Latch Hold Output Buffer Latch Setup	Single Module Sequential Clock to Q Latch G to Q Flip-Flop (Latch) Reset to Q Routing Delays FO = 1 Routing Delay FO = 2 Routing Delay FO = 3 Routing Delay FO = 8 Routing Delay FO = 8 Routing Delay FO = 8 Routing Delay FIp-Flop (Latch) Data Input Setup Flip-Flop (Latch) Data Input Hold Flip-Flop (Latch) Enable Setup Flip-Flop (Latch) Enable Hold Flip-Flop (Latch) Clock Active Pulse Width Flip-Flop Clock Input Period Input Buffer Latch Hold O.0 Input Buffer Latch Hold O.0 Output Buffer Latch Hold O.0 Output Buffer Latch Hold O.0 Output Buffer Latch Setup O.4	Single Module Sequential Clock to Q Latch G to Q Sequential Delays Flip-Flop (Latch) Reset to Q Sequential Delays FO = 1 Routing Delay FO = 2 Routing Delay FO = 3 Routing Delay FO = 4 Routing Delay FO = 8 Routing Delay Fo = 9 Routing Delay Fo = 1.7 Flip-Flop (Latch) Data Input Setup Flip-Flop (Latch) Data Input Hold Flip-Flop (Latch) Enable Setup Flip-Flop (Latch) Enable Hold Flip-Flop (Latch) Clock Active Pulse Width Flip-Flop (Latch) Clock Active Pulse Width Flip-Flop (Latch) Clock Asynchronous Pulse Width Flip-Flop Clock Input Period Input Buffer Latch Hold Input Buffer Latch Hold Output Buffer Latch Setup	Single Module Sequential Clock to Q Latch G to Q Sequential Place It o Q Sequential Clock to Q Sequential Clock Sequ	Min. Max. Min. Max. Min. Max. Single Module 3.8 4.3	Min. Max. Min. Max. Min. Max. Min. Min. Single Module	Min. Max. So. So. Sequential Clock to Q 3.8 4.3 5.0 Max. So. Max. Min. Min. Max. Min. Min. Max. Min. Max. Min. Min. Min. Max. Min. Max. Min. Max. Min. Max

Notes:

- $1. \quad \textit{For dual-module macros, use } t_{PD1} + t_{RD1} + t_{PDn}, \ t_{CO} + t_{RD1} + t_{PDn}, \ \textit{or } t_{PD1} + t_{RD1} + t_{SUD} \textit{whichever is appropriate.} \\$
- Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for
 estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case
 performance. Post-route timing is based on actual routing delay measurements performed on the device prior to
 shipment.
- 3. Data applies to macros based on the S-module. Timing parameters for sequential macros constructed from C-modules can be obtained from the DirectTime Analyzer utility.
- 4. Setup and hold timing parameters for the Input Buffer Latch are defined with respect to the PAD and the D input. External setup/hold timing parameters must account for delay from an external PAD signal to the G inputs. Delay from an external PAD signal to the G input subtracts (adds) to the internal setup (hold) time.



A1240A Timing Characteristics (continued)

Table 2-17 • A1240A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

TTL Output Module Timing ¹		-2 S	-2 Speed		-1 Speed		Std. Speed	
Parame	ter/Description	Min.	Max.	Min.	Max.	Min.	Max.	1
t _{DLH}	Data to Pad High		8.0		9.0		10.6	ns
t _{DHL}	Data to Pad Low		10.1		11.4		13.4	ns
t _{ENZH}	Enable Pad Z to High		8.9		10.0		11.8	ns
t _{ENZL}	Enable Pad Z to Low		11.7		13.2		15.5	ns
t _{ENHZ}	Enable Pad High to Z		7.1		8.0		9.4	ns
t _{ENLZ}	Enable Pad Low to Z		8.4		9.5		11.1	ns
t _{GLH}	G to Pad High		9.0		10.2		11.9	ns
t _{GHL}	G to Pad Low		11.2		12.7		14.9	ns
d_{TLH}	Delta Low to High		0.07		0.08		0.09	ns/pF
d_{THL}	Delta High to Low		0.12		0.13		0.16	ns/pF
CMOS (Output Module Timing ¹	•						
t _{DLH}	Data to Pad High		10.2		11.5		13.5	ns
t _{DHL}	Data to Pad Low		8.4		9.6		11.2	ns
t _{ENZH}	Enable Pad Z to High		8.9		10.0		11.8	ns
t _{ENZL}	Enable Pad Z to Low		11.7		13.2		15.5	ns
t _{ENHZ}	Enable Pad High to Z		7.1		8.0		9.4	ns
t _{ENLZ}	Enable Pad Low to Z		8.4		9.5		11.1	ns
t _{GLH}	G to Pad High		9.0		10.2		11.9	ns
t _{GHL}	G to Pad Low		11.2		12.7		14.9	ns
d_{TLH}	Delta Low to High		0.12		0.13		0.16	ns/pF
d _{THL}	Delta High to Low		0.09		0.10		0.12	ns/pF

Notes:

- 1. Delays based on 50 pF loading.
- 2. SSO information can be found at www.microsemi.com/soc/techdocs/appnotes/board_consideration.aspx.



Pin Descriptions

CLKA Clock A (Input)

TTL Clock input for clock distribution networks. The Clock input is buffered prior to clocking the logic modules. This pin can also be used as an I/O.

CLKB Clock B (Input)

TTL Clock input for clock distribution networks. The Clock input is buffered prior to clocking the logic modules. This pin can also be used as an I/O.

DCLK Diagnostic Clock (Input)

TTL Clock input for diagnostic probe and device programming. DCLK is active when the MODE pin is High. This pin functions as an I/O when the MODE pin is Low.

GND Ground

Low supply voltage.

I/O Input/Output (Input, Output)

The I/O pin functions as an input, output, three-state, or bidirectional buffer. Input and output levels are compatible with standard TTL and CMOS specifications. Unused I/O pins are automatically driven Low by the ALS software.

MODE Mode (Input)

The MODE pin controls the use of multifunction pins (DCLK, PRA, PRB, SDI). When the MODE pin is High, the special functions are active. When the MODE pin is Low, the pins function as I/Os. To provide Actionprobe capability, the MODE pin should be terminated to GND through a 10K resistor so that the MODE pin can be pulled High when required.

NC No Connection

This pin is not connected to circuitry within the device.

PRA Probe A (Output)

The Probe A pin is used to output data from any user-defined design node within the device. This independent diagnostic pin can be used in conjunction with the Probe B pin to allow real-time diagnostic output of any signal path within the device. The Probe A pin can be used as a user-defined I/O when debugging has been completed. The pin's probe capabilities can be permanently disabled to protect programmed design confidentiality. PRA is active when the MODE pin is High. This pin functions as an I/O when the MODE pin is Low.

PRB Probe B (Output)

The Probe B pin is used to output data from any user-defined design node within the device. This independent diagnostic pin can be used in conjunction with the Probe A pin to allow real-time diagnostic output of any signal path within the device. The Probe B pin can be used as a user-defined I/O when debugging has been completed. The pin's probe capabilities can be permanently disabled to protect programmed design confidentiality. PRB is active when the MODE pin is High. This pin functions as an I/O when the MODE pin is Low.

SDI Serial Data Input (Input)

Serial data input for diagnostic probe and device programming. SDI is active when the MODE pin is High. This pin functions as an I/O when the MODE pin is Low.

SDO Serial Data Output (Output)

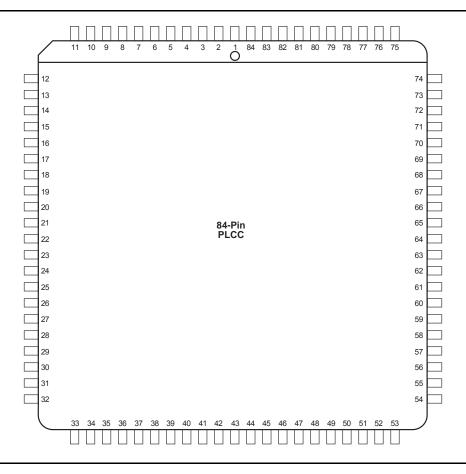
Serial data output for diagnostic probe. SDO is active when the MODE pin is High. This pin functions as an I/O when the MODE pin is Low.

VCC 5.0 V Supply Voltage

High supply voltage.



PL84



Note

For Package Manufacturing and Environmental information, visit the Resource Center at http://www.microsemi.com/soc/products/solutions/package/docs.aspx.



PQ100		
Pin Number	A1225A Function	
2	DCLK, I/O	
4	MODE	
9	GND	
16	VCC	
17	VCC	
22	GND	
34	GND	
40	VCC	
46	GND	
52	SDO	
57	GND	
64	GND	

PQ100		
Pin Number	A1225A Function	
65	VCC	
66	VCC	
67	VCC	
72	GND	
79	SDI, I/O	
84	GND	
87	PRA, I/O	
89	CLKA, I/O	
90	VCC	
92	CLKB, I/O	
94	PRB, I/O	
96	GND	

Notes:

- 1. All unlisted pin numbers are user I/Os.
- 2. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.

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PQ144			
Pin Number	A1240A Function		
2	MODE		
9	GND		
10	GND		
11	GND		
18	VCC		
19	VCC		
20	VCC		
21	VCC		
28	GND		
29	GND		
30	GND		
44	GND		
45	GND		
46	GND		
54	VCC		
55	VCC		
56	VCC		
64	GND		
65	GND		
71	SDO		
79	GND		
80	GND		
81	GND		
88	GND		

PQ144		
Pin Number	A1240A Function	
89	VCC	
90	VCC	
91	VCC	
92	VCC	
93	VCC	
100	GND	
101	GND	
102	GND	
110	SDI, I/O	
116	GND	
117	GND	
118	GND	
123	PRA, I/O	
125	CLKA, I/O	
126	VCC	
127	VCC	
128	VCC	
130	CLKB, I/O	
132	PRB, I/O	
136	GND	
137	GND	
138	GND	
144	DCLK, I/O	

Notes:

- 1. All unlisted pin numbers are user I/Os.
- 2. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.

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VQ100		
Pin Number	A1225A Function	
2	MODE	
7	GND	
14	VCC	
15	VCC	
20	GND	
32	GND	
38	VCC	
44	GND	
50	SDO	
55	GND	
62	GND	
63	VCC	

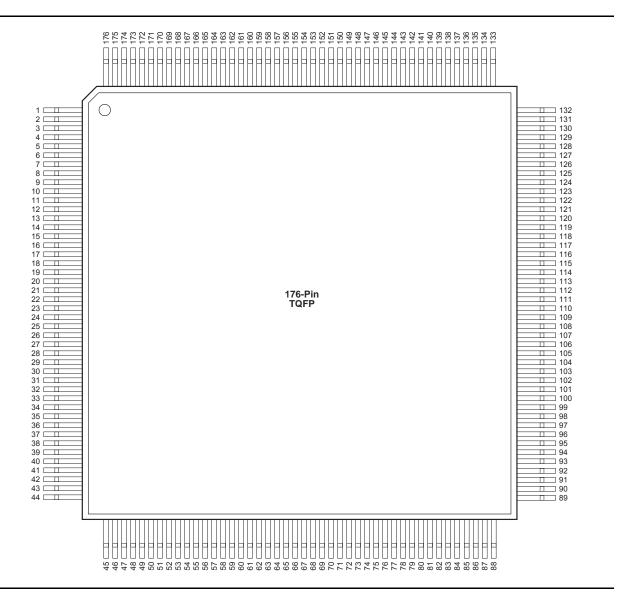
VQ100		
Pin Number	A1225A Function	
64	VCC	
65	VCC	
70	GND	
77	SDI, I/O	
82	GND	
85	PRA, I/O	
87	CLKA, I/O	
88	VCC	
90	CLKB, I/O	
92	PRB, I/O	
94	GND	
100	DCLK, I/O	

Notes:

- 1. All unlisted pin numbers are user I/Os.
- 2. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.

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TQ176

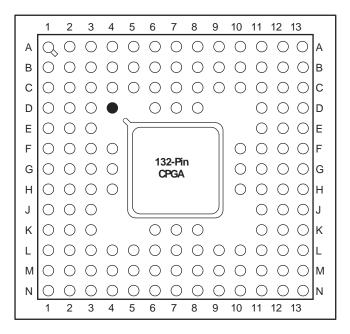


Note

For Package Manufacturing and Environmental information, visit the Resource Center at http://www.microsemi.com/soc/products/solutions/package/docs.aspx



PG132



Orientation Pin

Note

For Package Manufacturing and Environmental information, visit the Resource Center at http://www.microsemi.com/soc/products/solutions/package/docs.aspx

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Datasheet Information

Datasheet Categories

Categories

In order to provide the latest information to designers, some datasheet parameters are published before data has been fully characterized from silicon devices. The data provided for a given device is designated as either "Product Brief," "Advance," "Preliminary," or "Production." The definitions of these categories are as follows:

Product Brief

The product brief is a summarized version of a datasheet (advance or production) and contains general product information. This document gives an overview of specific device and family information.

Advance

This version contains initial estimated information based on simulation, other products, devices, or speed grades. This information can be used as estimates, but not for production. This label only applies to the DC and Switching Characteristics chapter of the datasheet and will only be used when the data has not been fully characterized.

Preliminary

The datasheet contains information based on simulation and/or initial characterization. The information is believed to be correct, but changes are possible.

Production

This version contains information that is considered to be final.

Export Administration Regulations (EAR)

The products described in this document are subject to the Export Administration Regulations (EAR). They could require an approved export license prior to export from the United States. An export includes release of product or disclosure of technology to a foreign national inside or outside the United States.

Safety Critical, Life Support, and High-Reliability Applications Policy

The products described in this advance status document may not have completed the Microsemi qualification process. Products may be amended or enhanced during the product introduction and qualification process, resulting in changes in device functionality or performance. It is the responsibility of each customer to ensure the fitness of any product (but especially a new product) for a particular purpose, including appropriateness for safety-critical, life-support, and other high-reliability applications. Consult the Microsemi SoC Products Group Terms and Conditions for specific liability exclusions relating to life-support applications. A reliability report covering all of the SoC Products Group's products is available at http://www.microsemi.com/soc/documents/ORT_Report.pdf. Microsemi also offers a variety of enhanced qualification and lot acceptance screening procedures. Contact your local sales office for additional reliability information.

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