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### Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

### Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

#### Details

Product Status	Obsolete
Number of LABs/CLBs	1232
Number of Logic Elements/Cells	-
Total RAM Bits	-
Number of I/O	72
Number of Gates	8000
Voltage - Supply	4.5V ~ 5.5V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 70°C (TA)
Package / Case	84-LCC (J-Lead)
Supplier Device Package	84-PLCC (29.31x29.31)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microsemi/a1280a-1plg84c">https://www.e-xfl.com/product-detail/microsemi/a1280a-1plg84c</a>

# 1 – ACT 2 Family Overview

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## General Description

The ACT 2 family represents Actel's second generation of field programmable gate arrays (FPGAs). The ACT 2 family presents a two-module architecture, consisting of C-modules and S-modules. These modules are optimized for both combinatorial and sequential designs. Based on Actel's patented channeled array architecture, the ACT 2 family provides significant enhancements to gate density and performance while maintaining downward compatibility with the ACT 1 design environment and upward compatibility with the ACT 3 design environment. The devices are implemented in silicon gate, 1.0- $\mu\text{m}$ , two-level metal CMOS, and employ Actel's PLICE® antifuse technology. This revolutionary architecture offers gate array design flexibility, high performance, and fast time-to-production with user programming. The ACT 2 family is supported by the Designer and Designer Advantage Systems, which offers automatic pin assignment, validation of electrical and design rules, automatic placement and routing, timing analysis, user programming, and diagnostic probe capabilities. The systems are supported on the following platforms: 386/486™ PC, Sun™, and HP™ workstations. The systems provide CAE interfaces to the following design environments: Cadence, Viewlogic®, Mentor Graphics®, and OrCAD™.



## 2 – Detailed Specifications

### Operating Conditions

**Table 2-1 • Absolute Maximum Ratings<sup>1</sup>**

Symbol	Parameter	Limits	Units
VCC	DC supply voltage	–0.5 to +7.0	V
VI	Input voltage	–0.5 to VCC + 0.5	V
VO	Output voltage	–0.5 to VCC + 0.5	V
IIO	I/O source sink current <sup>2</sup>	±20	mA
T <sub>STG</sub>	Storage temperature	–65 to +150	°C

Notes:

1. Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. Exposure to absolute maximum rated conditions for extended periods may affect device reliability. Device should not be operated outside the recommended operating conditions.
2. Device inputs are normally high impedance and draw extremely low current. However, when input voltage is greater than VCC + 0.5 V for less than GND –0.5 V, the internal protection diodes will be forward biased and can draw excessive current.

**Table 2-2 • Recommended Operating Conditions**

Parameter	Commercial	Industrial	Military	Units
Temperature range*	0 to +70	–40 to +85	–55 to +125	°C
Power supply tolerance	±5	±10	±10	%VCC

Note: \*Ambient temperature ( $T_A$ ) is used for commercial and industrial; case temperature ( $T_C$ ) is used for military.

**Table 2-3 • Electrical Specifications**

Symbol	Parameter	Commercial		Industrial		Military		Units
		Min.	Max.	Min.	Max.	Min.	Max.	
VOH <sup>1</sup>	(IOH = –10 mA) <sup>2</sup>	2.4	–	–	–	–	–	V
	(IOH = –6 mA)	3.84	–	–	–	–	–	V
	(IOH = –4 mA)	–	–	3.7	–	3.7	–	V
VOL <sup>1</sup>	(IOL = 10 mA) <sup>2</sup>	–	0.5	–	–	–	–	V
	(IOL = 6 mA)	–	0.33	–	0.40	–	0.40	V
VIL		–0.3	0.8	–0.3	0.8	–0.3	0.8	V
VIH		2.0	VCC + 0.3	2.0	VCC + 0.3	2.0	VCC + 0.3	V
Input Transition Time t <sub>R</sub> , t <sub>F</sub> <sup>2</sup>		–	500	–	500	–	500	ns
C <sub>IO</sub> I/O capacitance <sup>2,3</sup>		–	10	–	10	–	10	pF
Standby Current, ICC <sup>4</sup> (typical = 1 mA)		–	2	–	10	–	20	mA
Leakage Current <sup>5</sup>		–10	+10	–10	+10	–10	+10	μA
ICC(D)	Dynamic VCC supply current. See the Power Dissipation section.							

**Notes:**

1. Only one output tested at a time. VCC = minimum.
2. Not tested, for information only.
3. Includes worst-case PG176 package capacitance. VOUT = 0 V, f = 1 MHz
4. All outputs unloaded. All inputs = VCC or GND, typical ICC = 1 mA. ICC limit includes IPP and ISV during normal operations.
5. VOUT, VIN = VCC or GND.

To calculate the active power dissipated from the complete design, the switching frequency of each part of the logic must be known. EQ 4 shows a piece-wise linear summation over all components.

$$\begin{aligned}
 \text{Power} = & VCC^2 * [(m * C_{EQM} * f_m)_{\text{modules}} + (n * C_{EQI} * f_n)_{\text{inputs}} \\
 & + (p * (C_{EQO} + C_L) * f_p)_{\text{outputs}} \\
 & + 0.5 * (q1 * C_{EQCR} * f_{q1})_{\text{routed\_Clk1}} + (r1 * f_{q1})_{\text{routed\_Clk1}} \\
 & + 0.5 * (q2 * C_{EQCR} * f_{q2})_{\text{routed\_Clk2}} + (r2 * f_{q2})_{\text{routed\_Clk2}}
 \end{aligned}$$

EQ 4

Where:

m = Number of logic modules switching at  $f_m$

n = Number of input buffers switching at  $f_n$

p = Number of output buffers switching at  $f_p$

q1 = Number of clock loads on the first routed array clock

q2 = Number of clock loads on the second routed array clock

$r_1$  = Fixed capacitance due to first routed array clock

$r_2$  = Fixed capacitance due to second routed array clock

$C_{EQM}$  = Equivalent capacitance of logic modules in pF

$C_{EQI}$  = Equivalent capacitance of input buffers in pF

$C_{EQO}$  = Equivalent capacitance of output buffers in pF

$C_{EQCR}$  = Equivalent capacitance of routed array clock in pF

$C_L$  = Output lead capacitance in pF

$f_m$  = Average logic module switching rate in MHz

$f_n$  = Average input buffer switching rate in MHz

$f_p$  = Average output buffer switching rate in MHz

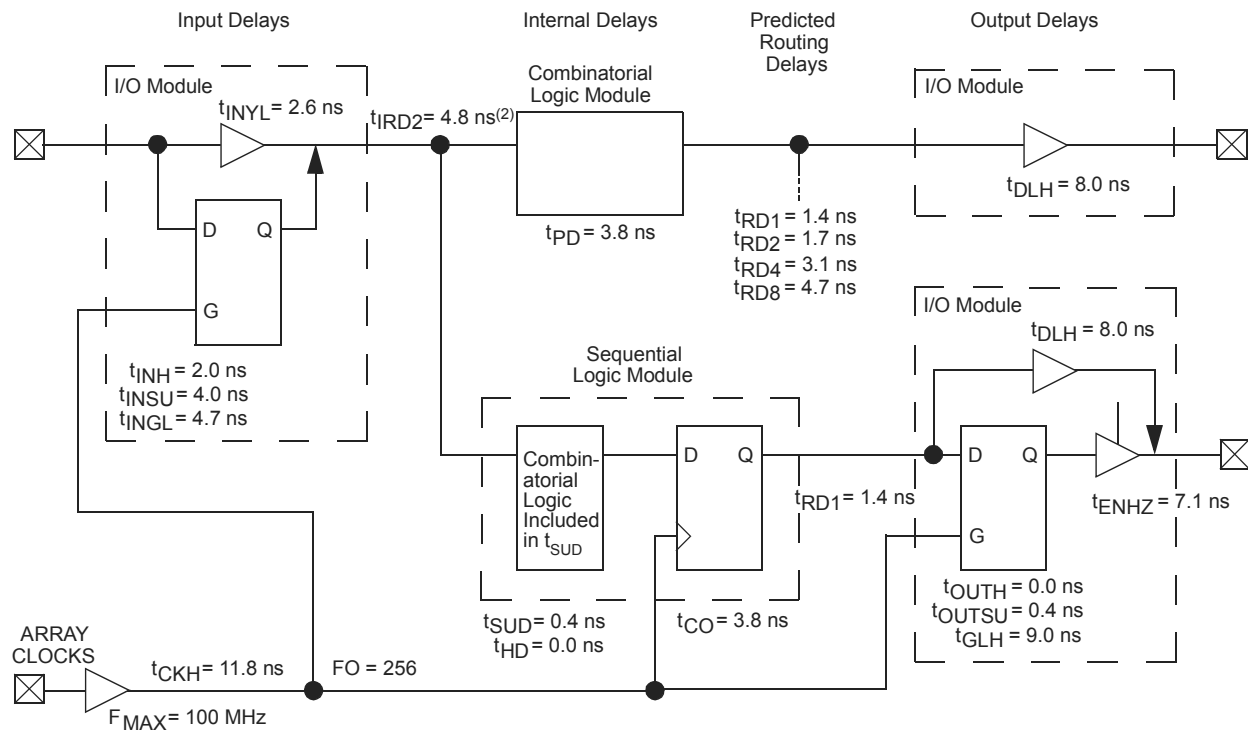
$f_{q1}$  = Average first routed array clock rate in MHz

$f_{q2}$  = Average second routed array clock rate in MHz

**Table 2-7 • Fixed Capacitance Values for Microsemi FPGAs**

Device Type	$r_1$ , routed_Clk1	$r_2$ , routed_Clk2
A1225A	106	106.0
A1240A	134	134.2
A1280A	168	167.8

## ACT 2 Timing Model<sup>1</sup>

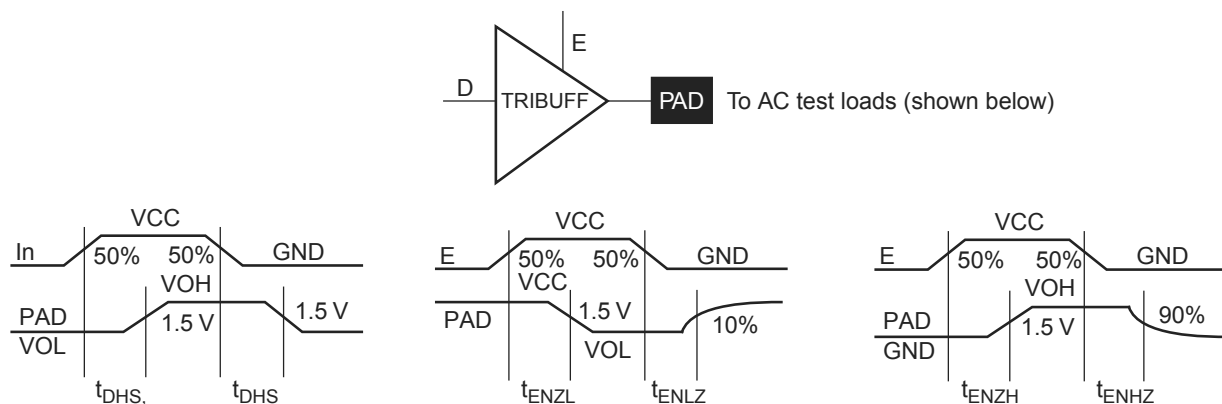


Notes:

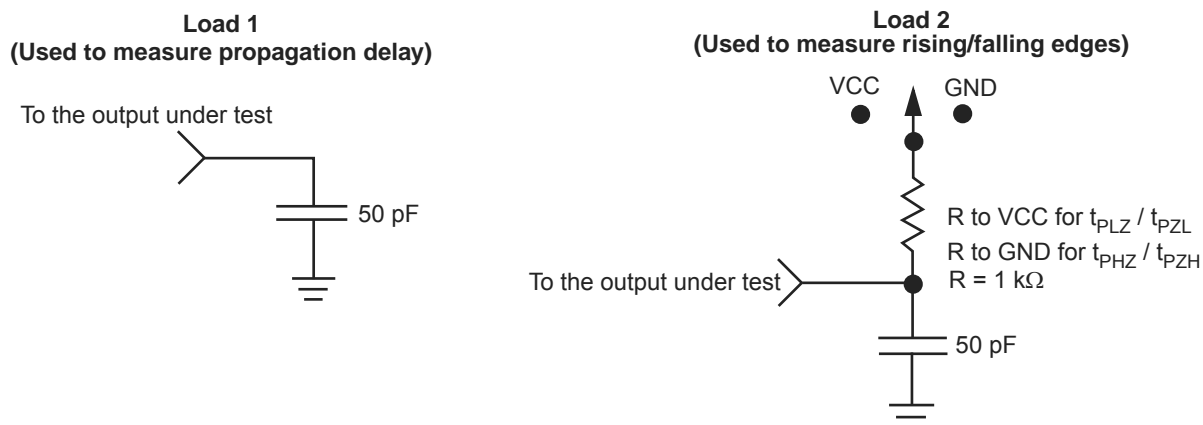
1. Values shown for A1240A-2 at worst-case commercial conditions.
2. Input module predicted routing delay

**Figure 2-1 • Timing Model**

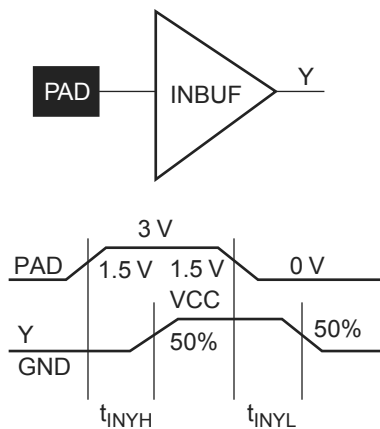
## Parameter Measurement



**Figure 2-2 • Output Buffer Delays**



**Figure 2-3 • AC Test Loads**



**Figure 2-4 • Input Buffer Delays**



## Timing Derating Factor (Temperature and Voltage)

**Table 2-9 • Timing Derating Factor (Temperature and Voltage)**

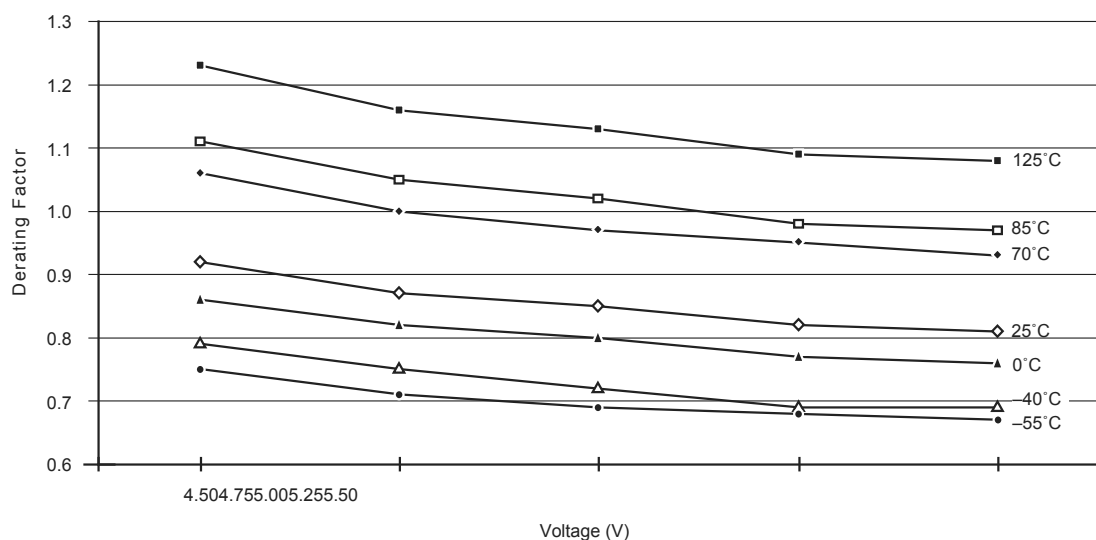
(Commercial Minimum/Maximum Specification) x	Industrial		Military	
	Min.	Max.	Min.	Max.
	0.69	1.11	0.67	1.23

**Table 2-10 • Timing Derating Factor for Designs at Typical Temperature ( $T_J = 25^\circ\text{C}$ ) and Voltage (5.0 V)**

(Commercial Maximum Specification) x	0.85
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**Table 2-11 • Temperature and Voltage Derating Factors  
(normalized to Worst-Case Commercial,  $T_J = 4.75\text{ V}$ ,  $70^\circ\text{C}$ )**

	-55	-40	0	25	70	85	125
<b>4.50</b>	0.75	0.79	0.86	0.92	1.06	1.11	1.23
<b>4.75</b>	0.71	0.75	0.82	0.87	1.00	1.05	1.13
<b>5.00</b>	0.69	0.72	0.80	0.85	0.97	1.02	1.13
<b>5.25</b>	0.68	0.69	0.77	0.82	0.95	0.98	1.09
<b>5.50</b>	0.67	0.69	0.76	0.81	0.93	0.97	1.08



*Note: This derating factor applies to all routing and propagation delays.*

**Figure 2-9 • Junction Temperature and Voltage Derating Curves  
(normalized to Worst-Case Commercial,  $T_J = 4.75\text{ V}$ ,  $70^\circ\text{C}$ )**

## A1225A Timing Characteristics

**Table 2-12 • A1225A Worst-Case Commercial Conditions, VCC = 4.75 V, T<sub>J</sub> = 70°C**

Logic Module Propagation Delays <sup>1</sup>		–2 Speed <sup>3</sup>		–1 Speed		Std. Speed		Units
Parameter/Description		Min.	Max.	Min.	Max.	Min.	Max.	
t <sub>PD1</sub>	Single Module		3.8		4.3		5.0	ns
t <sub>CO</sub>	Sequential Clock to Q		3.8		4.3		5.0	ns
t <sub>GO</sub>	Latch G to Q		3.8		4.3		5.0	ns
t <sub>RS</sub>	Flip-Flop (Latch) Reset to Q		3.8		4.3		5.0	ns
<b>Predicted Routing Delays<sup>2</sup></b>								
t <sub>RD1</sub>	FO = 1 Routing Delay		1.1		1.2		1.4	ns
t <sub>RD2</sub>	FO = 2 Routing Delay		1.7		1.9		2.2	ns
t <sub>RD3</sub>	FO = 3 Routing Delay		2.3		2.6		3.0	ns
t <sub>RD4</sub>	FO = 4 Routing Delay		2.8		3.1		3.7	ns
t <sub>RD8</sub>	FO = 8 Routing Delay		4.4		4.9		5.8	ns
<b>Sequential Timing Characteristics<sup>3,4</sup></b>								
t <sub>SUD</sub>	Flip-Flop (Latch) Data Input Setup	0.4		0.4		0.5		ns
t <sub>HD</sub>	Flip-Flop (Latch) Data Input Hold	0.0		0.0		0.0		ns
t <sub>SUENA</sub>	Flip-Flop (Latch) Enable Setup	0.8		0.9		1.0		ns
t <sub>HENA</sub>	Flip-Flop (Latch) Enable Hold	0.0		0.0		0.0		ns
t <sub>WCLKA</sub>	Flip-Flop (Latch) Clock Active Pulse Width	4.5		5.0		6.0		ns
t <sub>WASYN</sub>	Flip-Flop (Latch) Clock Asynchronous Pulse Width	4.5		5.0		6.0		ns
t <sub>A</sub>	Flip-Flop Clock Input Period	9.4		11.0		13.0		ns
t <sub>INH</sub>	Input Buffer Latch Hold	0.0		0.0		0.0		ns
t <sub>INSU</sub>	Input Buffer Latch Setup	0.4		0.4		0.5		ns
t <sub>OUTH</sub>	Output Buffer Latch Hold	0.0		0.0		0.0		ns
t <sub>OUTSU</sub>	Output Buffer Latch Setup	0.4		0.4		0.5		ns
f <sub>MAX</sub>	Flip-Flop (Latch) Clock Frequency		105.0		90.0		75.0	MHz

**Notes:**

1. For dual-module macros, use t<sub>PD1</sub> + t<sub>RD1</sub> + t<sub>PDn</sub>, t<sub>CO</sub> + t<sub>RD1</sub> + t<sub>PDn</sub>, or t<sub>PD1</sub> + t<sub>RD1</sub> + t<sub>SUD</sub>—whichever is appropriate.
2. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.
3. Data applies to macros based on the S-module. Timing parameters for sequential macros constructed from C-modules can be obtained from the DirectTime Analyzer utility.
4. Setup and hold timing parameters for the Input Buffer Latch are defined with respect to the PAD and the D input. External setup/hold timing parameters must account for delay from an external PAD signal to the G inputs. Delay from an external PAD signal to the G input subtracts (adds) to the internal setup (hold) time.

## A1240A Timing Characteristics (continued)

Table 2-17 • A1240A Worst-Case Commercial Conditions, VCC = 4.75 V, T<sub>J</sub> = 70°C

TTL Output Module Timing <sup>1</sup>		–2 Speed		–1 Speed		Std. Speed		Units
Parameter/Description		Min.	Max.	Min.	Max.	Min.	Max.	
t <sub>DLH</sub>	Data to Pad High		8.0		9.0		10.6	ns
t <sub>DHL</sub>	Data to Pad Low		10.1		11.4		13.4	ns
t <sub>ENZH</sub>	Enable Pad Z to High		8.9		10.0		11.8	ns
t <sub>ENZL</sub>	Enable Pad Z to Low		11.7		13.2		15.5	ns
t <sub>ENHZ</sub>	Enable Pad High to Z		7.1		8.0		9.4	ns
t <sub>ENLZ</sub>	Enable Pad Low to Z		8.4		9.5		11.1	ns
t <sub>GLH</sub>	G to Pad High		9.0		10.2		11.9	ns
t <sub>GHL</sub>	G to Pad Low		11.2		12.7		14.9	ns
d <sub>TLH</sub>	Delta Low to High		0.07		0.08		0.09	ns/pF
d <sub>THL</sub>	Delta High to Low		0.12		0.13		0.16	ns/pF
CMOS Output Module Timing <sup>1</sup>								
t <sub>DLH</sub>	Data to Pad High		10.2		11.5		13.5	ns
t <sub>DHL</sub>	Data to Pad Low		8.4		9.6		11.2	ns
t <sub>ENZH</sub>	Enable Pad Z to High		8.9		10.0		11.8	ns
t <sub>ENZL</sub>	Enable Pad Z to Low		11.7		13.2		15.5	ns
t <sub>ENHZ</sub>	Enable Pad High to Z		7.1		8.0		9.4	ns
t <sub>ENLZ</sub>	Enable Pad Low to Z		8.4		9.5		11.1	ns
t <sub>GLH</sub>	G to Pad High		9.0		10.2		11.9	ns
t <sub>GHL</sub>	G to Pad Low		11.2		12.7		14.9	ns
d <sub>TLH</sub>	Delta Low to High		0.12		0.13		0.16	ns/pF
d <sub>THL</sub>	Delta High to Low		0.09		0.10		0.12	ns/pF

Notes:

1. Delays based on 50 pF loading.
2. SSO information can be found at [www.microsemi.com/soc/techdocs/appnotes/board\\_consideration.aspx](http://www.microsemi.com/soc/techdocs/appnotes/board_consideration.aspx).

## Pin Descriptions

**CLKA                      Clock A (Input)**

TTL Clock input for clock distribution networks. The Clock input is buffered prior to clocking the logic modules. This pin can also be used as an I/O.

**CLKB                      Clock B (Input)**

TTL Clock input for clock distribution networks. The Clock input is buffered prior to clocking the logic modules. This pin can also be used as an I/O.

**DCLK                      Diagnostic Clock (Input)**

TTL Clock input for diagnostic probe and device programming. DCLK is active when the MODE pin is High. This pin functions as an I/O when the MODE pin is Low.

**GND                      Ground**

Low supply voltage.

**I/O                      Input/Output (Input, Output)**

The I/O pin functions as an input, output, three-state, or bidirectional buffer. Input and output levels are compatible with standard TTL and CMOS specifications. Unused I/O pins are automatically driven Low by the ALS software.

**MODE                      Mode (Input)**

The MODE pin controls the use of multifunction pins (DCLK, PRA, PRB, SDI). When the MODE pin is High, the special functions are active. When the MODE pin is Low, the pins function as I/Os. To provide Actionprobe capability, the MODE pin should be terminated to GND through a 10K resistor so that the MODE pin can be pulled High when required.

**NC                      No Connection**

This pin is not connected to circuitry within the device.

**PRA                      Probe A (Output)**

The Probe A pin is used to output data from any user-defined design node within the device. This independent diagnostic pin can be used in conjunction with the Probe B pin to allow real-time diagnostic output of any signal path within the device. The Probe A pin can be used as a user-defined I/O when debugging has been completed. The pin's probe capabilities can be permanently disabled to protect programmed design confidentiality. PRA is active when the MODE pin is High. This pin functions as an I/O when the MODE pin is Low.

**PRB                      Probe B (Output)**

The Probe B pin is used to output data from any user-defined design node within the device. This independent diagnostic pin can be used in conjunction with the Probe A pin to allow real-time diagnostic output of any signal path within the device. The Probe B pin can be used as a user-defined I/O when debugging has been completed. The pin's probe capabilities can be permanently disabled to protect programmed design confidentiality. PRB is active when the MODE pin is High. This pin functions as an I/O when the MODE pin is Low.

**SDI                      Serial Data Input (Input)**

Serial data input for diagnostic probe and device programming. SDI is active when the MODE pin is High. This pin functions as an I/O when the MODE pin is Low.

**SDO                      Serial Data Output (Output)**

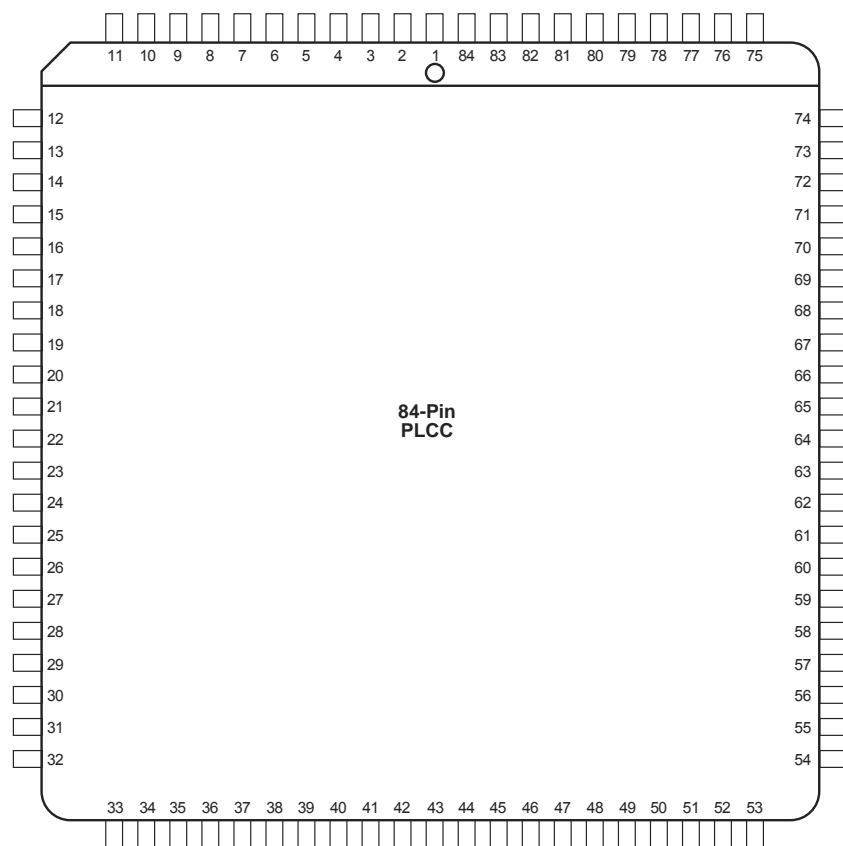
Serial data output for diagnostic probe. SDO is active when the MODE pin is High. This pin functions as an I/O when the MODE pin is Low.

**VCC                      5.0 V Supply Voltage**

High supply voltage.

## 3 – Package Pin Assignments

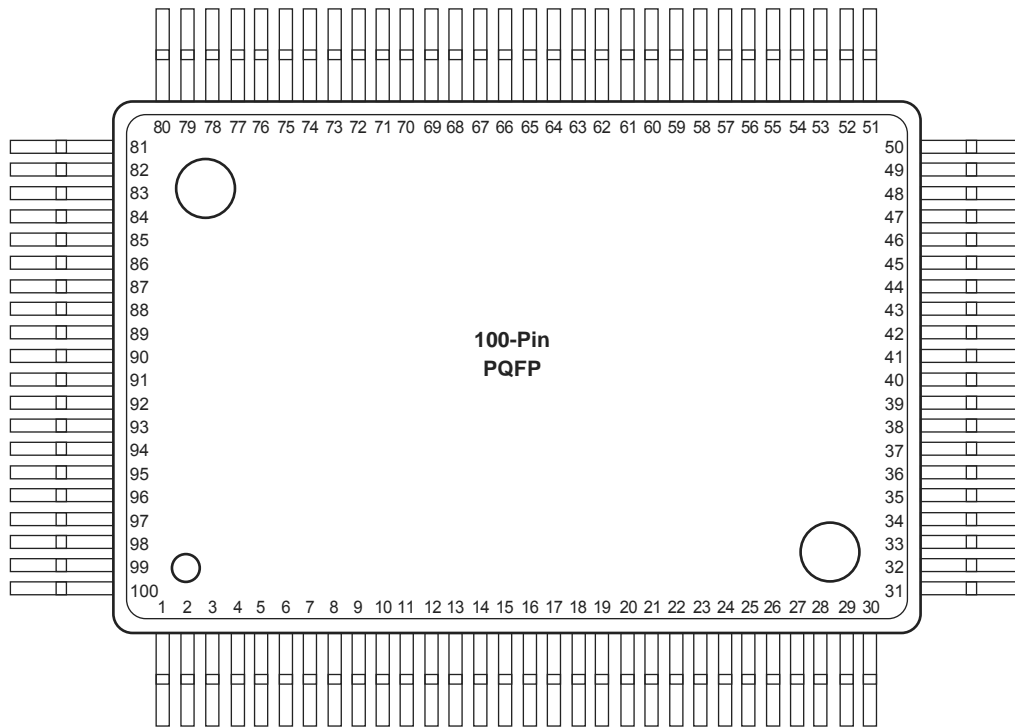
### PL84



#### **Note**

For Package Manufacturing and Environmental information, visit the Resource Center at <http://www.microsemi.com/soc/products/solutions/package/docs.aspx>.

## PQ100

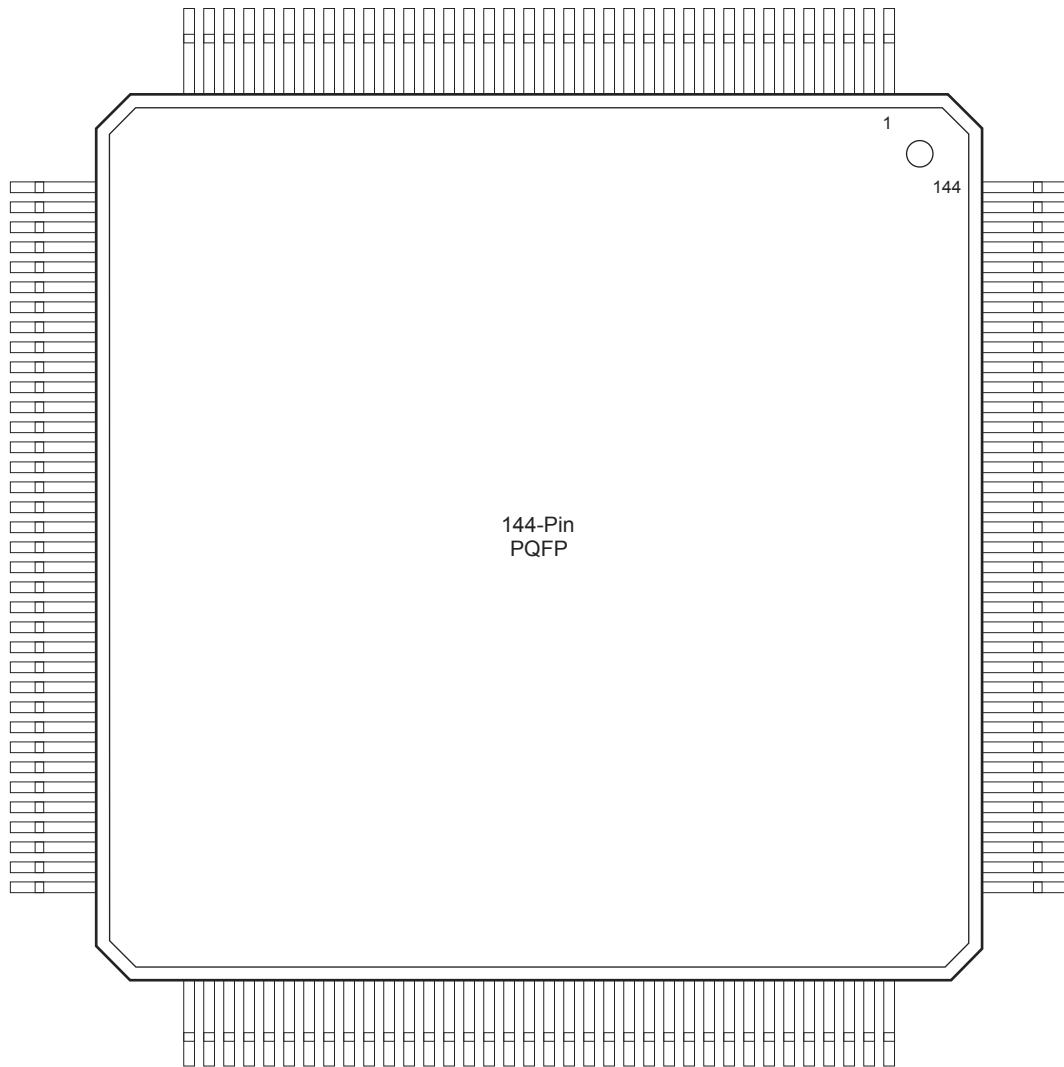


### Note

For Package Manufacturing and Environmental information, visit the Resource Center at <http://www.microsemi.com/soc/products/solutions/package/docs.aspx>

## PQ144

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### **Note**

For Package Manufacturing and Environmental information, visit the Resource Center at <http://www.microsemi.com/soc/products/solutions/package/docs.aspx>

PQ160	
Pin Number	A1280A Function
2	DCLK, I/O
6	VCC
11	GND
16	PRB, I/O
18	CLKB, I/O
20	VCC
21	CLKA, I/O
23	PRA, I/O
30	GND
35	VCC
38	SDI, I/O
40	GND
44	GND
49	GND
54	VCC
57	VCC
58	VCC
59	GND
60	VCC
61	GND
64	GND

PQ160	
Pin Number	A1280A Function
69	GND
80	GND
82	SDO
86	VCC
89	GN
98	GND
99	GND
109	GND
114	VCC
120	GND
125	GND
130	GND
135	VCC
138	VCC
139	VCC
140	GND
145	GND
150	VCC
155	GND
159	MODE
160	GND

*Notes:*

1. All unlisted pin numbers are user I/Os.
2. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.



TQ176		
Pin Number	A1240A Function	A1280A Function
155	VCC	VCC
156	GND	GND
158	CLKB, I/O	CLKB, I/O
160	PRB, I/O	PRB, I/O
161	NC	I/O
165	NC	NC
166	NC	I/O
168	NC	I/O
170	NC	VCC
173	NC	I/O
175	DCLK, I/O	DCLK, I/O

*Notes:*

1. NC denotes no connection.
2. All unlisted pin numbers are user I/Os.
3. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.

CQ172	
Pin Number	A1280A Function
1	MODE
7	GND
12	VCC
17	GND
22	GND
23	VCC
24	VCC
27	VCC
32	GND
37	GND
50	VCC
55	GND
65	GND
66	VCC
75	GND
80	VCC
85	SDO
98	GND
103	GND
106	GND

CQ172	
Pin Number	A1280A Function
107	VCC
108	GND
109	VCC
110	VCC
113	VCC
118	GND
123	GND
131	SDI, I/O
136	VCC
141	GND
148	PRA, I/O
150	CLKA, I/O
151	VCC
152	GND
154	CLKB, I/O
156	PRB, I/O
161	GND
166	VCC
171	DCLK, I/O

*Notes:*

1. All unlisted pin numbers are user I/Os.
2. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.

PG100		PG100	
Pin Number	A1225A Function	Pin Number	A1225A Function
A4	PRB, I/O	E11	VCC
A7	PRA, I/O	F3	VCC
B6	VCC	F9	VCC
C2	MODE	F10	VCC
C3	DCLK, I/O	F11	GND
C5	GND	G1	VCC
C6	CLKA, I/O	G3	GND
C7	GND	G9	GND
C8	SDI, I/O	J5	GND
D6	CLKB, I/O	J7	GND
D10	GND	J9	SDO
E3	GND	K6	VCC

*Notes:*

1. All unlisted pin numbers are user I/Os.
2. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.



