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Understanding <u>Embedded - FPGAs (Field</u> <u>Programmable Gate Array)</u>

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Details	
Product Status	Obsolete
Number of LABs/CLBs	1232
Number of Logic Elements/Cells	•
Total RAM Bits	•
Number of I/O	125
Number of Gates	8000
Voltage - Supply	4.5V ~ 5.5V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 85°C (TA)
Package / Case	160-BQFP
Supplier Device Package	160-PQFP (28x28)
Purchase URL	https://www.e-xfl.com/product-detail/microsemi/a1280a-1pqg160i

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

Product Plan

	S	peed Grad	e ¹		Application ¹			
Device/Package	Std.	-1	-2	С	I	М	В	
A1225A Device				•		•		
84-Pin Plastic Leaded Chip Carrier (PL)	1	1	✓	1	1	-	-	
100-Pin Plastic Quad Flatpack (PQ)	1	1	✓	1	1	-	-	
100-Pin Very Thin Quad Flatpack (VQ)	1	~	✓	1	_	-	_	
100-Pin Ceramic Pin Grid Array (PG)	1	1	1	1	-	-	_	
A1240A Device								
84-Pin Plastic Leaded Chip Carrier (PL)	1	~	✓	1	1	-	-	
132-Pin Ceramic Pin Grid Array (PG)	1	1	<i>✓</i>	1	_	1	1	
144-Pin Plastic Quad Flat Pack (PQ)	1	1	✓	1	1	-	-	
176-Pin Thin (1.4 mm) Quad Flat Pack (TQ)	1	1	1	1	-	-	_	
A1280A Device								
160-Pin Plastic Quad Flatpack (PQ)	1	1	✓	1	1	-	-	
172-Pin Ceramic Quad Flatpack (CQ)	1	~	✓	1	_	1	1	
176-Pin Ceramic Pin Grid Array (PG)	1	1	1	1	_	1	1	
176-Pin Thin (1.4 mm) Quad Flat Pack (TQ)	1	1	1	1	_	-	-	
Notes:	Availa	hility:	1	Sneed	d Grade:	1		

1. Applications: C = Commercial I = Industrial M = Military B = MIL-STD-883 Availability: $\checkmark = Available$ P = Planned- = Not planned Speed Grade: -1 = Approx. 15% faster than Std.

-2 = Approx. 25% faster than Std.

2. Contact your Microsemi SoC Products Group sales representative for product availability.

Device Resources

Device	Logic			User I/Os								
Series	Modules	Gates	PG176	PG132	PG100	PQ160	PQ144	PQ100	PL84	CQ172	TQ176	VQ100
A1225A	451	2,500	-	-	83	-	_	83	72	-	-	83
A1240A	684	4,000	-	104	-	-	104	-	72	-	104	_
A1280A	1,232	8,000	140	_	-	125	_	-	72	140	140	-

Contact your local Microsemi SoC Products Group representative for device availability: http://www.microsemi.com/soc/contact/default.aspx.

Package Thermal Characteristics

The device junction to case thermal characteristic is θ jc, and the junction to ambient air characteristic is θ ja. The thermal characteristics for θ ja are shown with two different air flow rates.

Maximum junction temperature is 150°C.

A sample calculation of the absolute maximum power dissipation allowed for a PQ160 package at commercial temperature and still air is as follows:

$$\frac{\text{Max. junction temp. (°C)} - \text{Max. ambient temp. (°C)}}{\theta_{ja} °C/W} = \frac{150°C - 70°C}{33°C/W} = 2.4 \text{ W}$$

EQ 1

Package Type∗	Pin Count	θ _{jc}	^θ ja Still Air	θ _{ja} 300 ft./min.	Units
Ceramic Pin Grid Array	100	5	35	17	°C/W
	132	5	30	15	°C/W
	176	8	23	12	°C/W
Ceramic Quad Flatpack	172	8	25	15	°C/W
Plastic Quad Flatpack ¹	100	13	48	40	°C/W
	144	15	40	32	°C/W
	160	15	38	30	°C/W
Plastic Leaded Chip Carrier	84	12	37	28	°C/W
Very Thin Quad Flatpack	100	12	43	35	°C/W
Thin Quad Flatpack	176	15	32	25	°C/W

Table 2-4 • Package Thermal Characteristics

Notes: (Maximum Power in Still Air)

1. Maximum power dissipation values for PQFP packages are 1.9 W (PQ100), 2.3 W (PQ144), and 2.4 W (PQ160).

2. Maximum power dissipation for PLCC packages is 2.7 W.

3. Maximum power dissipation for VQFP packages is 2.3 W.

4. Maximum power dissipation for TQFP packages is 3.1 W.

Power Dissipation

P = [ICC standby + ICCactive] * VCC + IOL * VOL * N + IOH* (VCC – VOH) * M

EQ 2

where:

ICC standby is the current flowing when no inputs or outputs are changing

ICCactive is the current flowing due to CMOS switching.

IOL and IOH are TTL sink/source currents.

VOL and VOH are TTL level output voltages.

N is the number of outputs driving TTL loads to VOL.

M is the number of outputs driving TTL loads to VOH.

An accurate determination of N and M is problematical because their values depend on the family type, design details, and on the system I/O. The power can be divided into two components: static and active.



Static Power Component

Microsemi FPGAs have small static power components that result in lower power dissipation than PALs or PLDs. By integrating multiple PALs/PLDs into one FPGA, an even greater reduction in board-level power dissipation can be achieved.

The power due to standby current is typically a small component of the overall power. Standby power is calculated in Table 2-5 for commercial, worst case conditions.

Table 2-5 • Standby Power Calculation

ICC	VCC	Power
2 mA	5.25 V	10.5 mW

The static power dissipated by TTL loads depends on the number of outputs driving high or low and the DC load current. Again, this value is typically small. For instance, a 32-bit bus sinking 4 mA at 0.33 V will generate 42 mW with all outputs driving low, and 140 mW with all outputs driving high. The actual dissipation will average somewhere between as I/Os switch states with time.

Active Power Component

Power dissipation in CMOS devices is usually dominated by the active (dynamic) power dissipation. This component is frequency dependent, a function of the logic and the external I/O. Active power dissipation results from charging internal chip capacitances of the interconnect, unprogrammed antifuses, module inputs, and module outputs, plus external capacitance due to PC board traces and load device inputs.

An additional component of the active power dissipation is the totem-pole current in CMOS transistor pairs. The net effect can be associated with an equivalent capacitance that can be combined with frequency and voltage to represent active power dissipation.

EQ 3

Equivalent Capacitance

The power dissipated by a CMOS circuit can be expressed by EQ 3.

Power (μ W) = C_{EQ} * VCC² * F

Where:

C_{EQ} is the equivalent capacitance expressed in pF.

VCC is the power supply in volts.

F is the switching frequency in MHz.

Equivalent capacitance is calculated by measuring ICC active at a specified frequency and voltage for each circuit component of interest. Measurements have been made over a range of frequencies at a fixed value of VCC. Equivalent capacitance is frequency independent so that the results may be used over a wide range of operating conditions. Equivalent capacitance values are shown in Table 2-6.

Table 2-6 • CEQ Values for Microsemi FPGAs

Item	CEQ Value
Modules (C _{EQM})	5.8
Input Buffers (C _{EQI})	12.9
Output Buffers (C _{EQO})	23.8
Routed Array Clock Buffer Loads (C _{EQCR})	3.9



2-5

To calculate the active power dissipated from the complete design, the switching frequency of each part of the logic must be known. EQ 4 shows a piece-wise linear summation over all components.

Power =VCC² * [(m * C_{EQM} * f_m)_{modules} + (n * C_{EQI} * f_n)_{inputs}

+ (p * (C_{EQO} + C_L) * fp)outputs

+ 0.5 * (q1 * C_{EQCR} * f_{q1})_{routed_Clk1} + (r1 * f_{q1})_{routed_Clk1}

+ 0.5 * (q2 * C_{EQCR} * f_{q2})_{routed Clk2} + (r₂ * f_{q2})_{routed Clk2}

Where:

m = Number of logic modules switching at fm

n = Number of input buffers switching at fn

p = Number of output buffers switching at f_p

q1 = Number of clock loads on the first routed array clock

q2 = Number of clock loads on the second routed array clock

r₁ = Fixed capacitance due to first routed array clock

r₂ = Fixed capacitance due to second routed array clock

C_{EOM} = Equivalent capacitance of logic modules in pF

C_{EOI} = Equivalent capacitance of input buffers in pF

C_{FOO} = Equivalent capacitance of output buffers in pF

C_{EQCR} = Equivalent capacitance of routed array clock in pF

C₁ = Output lead capacitance in pF

f_m = Average logic module switching rate in MHz

fn = Average input buffer switching rate in MHz

fp = Average output buffer switching rate in MHz

 f_{q1} = Average first routed array clock rate in MHz

f_{g2} = Average second routed array clock rate in MHz

Table 2-7 • Fixed Capacitance Values for Microsemi FPGAs

Device Type	r1, routed_Clk1	r2, routed_Clk2
A1225A	106	106.0
A1240A	134	134.2
A1280A	168	167.8

EQ 4





Detailed Specifications

Parameter Measurement

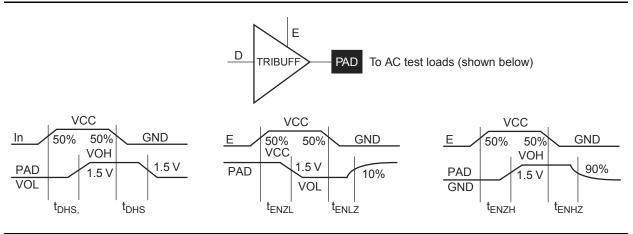


Figure 2-2 • Output Buffer Delays

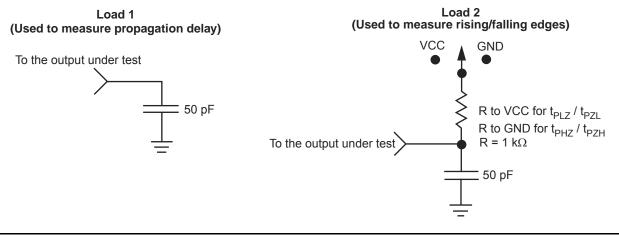


Figure 2-3 • AC Test Loads

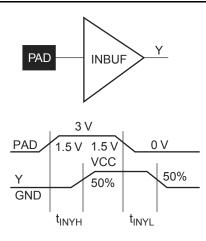
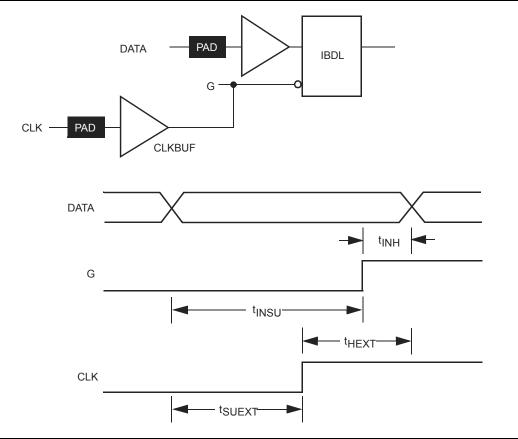
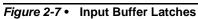
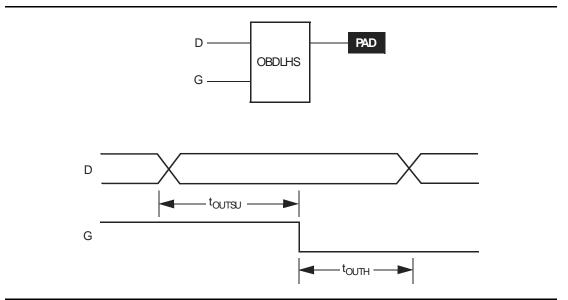


Figure 2-4 • Input Buffer Delays













Detailed Specifications

A1225A Timing Characteristics

Table 2-12 • A1225A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

Logic Mo	odule Propagation Delays ¹	–2 Sj	beed ³	–1 S	peed	Std. S	Units	
Paramet	er/Description	Min.	Max.	Min.	Max.	Min.	Max.	1
t _{PD1}	Single Module		3.8		4.3		5.0	ns
t _{CO}	Sequential Clock to Q		3.8		4.3		5.0	ns
t _{GO}	Latch G to Q		3.8		4.3		5.0	ns
t _{RS}	Flip-Flop (Latch) Reset to Q		3.8		4.3		5.0	ns
Predicte	d Routing Delays ²							
t _{RD1}	FO = 1 Routing Delay		1.1		1.2		1.4	ns
t _{RD2}	FO = 2 Routing Delay		1.7		1.9		2.2	ns
t _{RD3}	FO = 3 Routing Delay		2.3		2.6		3.0	ns
t _{RD4}	FO = 4 Routing Delay		2.8		3.1		3.7	ns
t _{RD8}	FO = 8 Routing Delay		4.4		4.9		5.8	ns
Sequent	ial Timing Characteristics ^{3,4}							
t _{SUD}	Flip-Flop (Latch) Data Input Setup	0.4		0.4		0.5		ns
t _{HD}	Flip-Flop (Latch) Data Input Hold	0.0		0.0		0.0		ns
t _{SUENA}	Flip-Flop (Latch) Enable Setup	0.8		0.9		1.0		ns
t _{HENA}	Flip-Flop (Latch) Enable Hold	0.0		0.0		0.0		ns
t _{WCLKA}	Flip-Flop (Latch) Clock Active Pulse Width	4.5		5.0		6.0		ns
t _{WASYN}	Flip-Flop (Latch) Clock Asynchronous Pulse Width	4.5		5.0		6.0		ns
t _A	Flip-Flop Clock Input Period	9.4		11.0		13.0		ns
t _{INH}	Input Buffer Latch Hold	0.0		0.0		0.0		ns
t _{INSU}	Input Buffer Latch Setup	0.4		0.4		0.5		ns
t _{оитн}	Output Buffer Latch Hold	0.0		0.0		0.0		ns
t _{outsu}	Output Buffer Latch Setup	0.4		0.4		0.5		ns
f _{MAX}	Flip-Flop (Latch) Clock Frequency		105.0		90.0		75.0	MHz

Notes:

1. For dual-module macros, use $t_{PD1} + t_{RD1} + t_{PDn}$, $t_{CO} + t_{RD1} + t_{PDn}$, or $t_{PD1} + t_{RD1} + t_{SUD}$ —whichever is appropriate.

 Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.

3. Data applies to macros based on the S-module. Timing parameters for sequential macros constructed from C-modules can be obtained from the DirectTime Analyzer utility.

4. Setup and hold timing parameters for the Input Buffer Latch are defined with respect to the PAD and the D input. External setup/hold timing parameters must account for delay from an external PAD signal to the G inputs. Delay from an external PAD signal to the G input subtracts (adds) to the internal setup (hold) time.

A1240A Timing Characteristics

Logic M	odule Propagation Delays ¹	–2 Sj	beed ³	–1 S	peed	Std. Speed		Units
Paramet	er/Description	Min.	Max.	Min.	Max.	Min.	Max.	
t _{PD1}	Single Module		3.8		4.3		5.0	ns
t _{CO}	Sequential Clock to Q		3.8		4.3		5.0	ns
t _{GO}	Latch G to Q		3.8		4.3		5.0	ns
t _{RS}	Flip-Flop (Latch) Reset to Q		3.8		4.3		5.0	ns
Predicte	d Routing Delays ²					1		
t _{RD1}	FO = 1 Routing Delay		1.4		1.5		1.8	ns
t _{RD2}	FO = 2 Routing Delay		1.7		2.0		2.3	ns
t _{RD3}	FO = 3 Routing Delay		2.3		2.6		3.0	ns
t _{RD4}	FO = 4 Routing Delay		3.1		3.5		4.1	ns
t _{RD8}	FO = 8 Routing Delay		4.7		5.4		6.3	ns
Sequent	ial Timing Characteristics ^{3,4}							
t _{SUD}	Flip-Flop (Latch) Data Input Setup	0.4		0.4		0.5		ns
t _{HD}	Flip-Flop (Latch) Data Input Hold	0.0		0.0		0.0		ns
t _{SUENA}	Flip-Flop (Latch) Enable Setup	0.8		0.9		1.0		ns
t _{HENA}	Flip-Flop (Latch) Enable Hold	0.0		0.0		0.0		ns
t _{WCLKA}	Flip-Flop (Latch) Clock Active Pulse Width	4.5		6.0		6.5		ns
t _{WASYN}	Flip-Flop (Latch) Clock Asynchronous Pulse Width	4.5		6.0		6.5		ns
t _A	Flip-Flop Clock Input Period	9.8		12.0		15.0		ns
t _{INH}	Input Buffer Latch Hold	0.0		0.0		0.0		ns
t _{INSU}	Input Buffer Latch Setup	0.4		0.4		0.5		ns
t _{OUTH}	Output Buffer Latch Hold	0.0		0.0		0.0		ns
t _{outsu}	Output Buffer Latch Setup	0.4		0.4		0.5		ns
f _{MAX}	Flip-Flop (Latch) Clock Frequency		100.0		80.0		66.0	MHz

Notes:

1. For dual-module macros, use $t_{PD1} + t_{RD1} + t_{PDn}$, $t_{CO} + t_{RD1} + t_{PDn}$, or $t_{PD1} + t_{RD1} + t_{SUD}$ —whichever is appropriate.

 Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.

3. Data applies to macros based on the S-module. Timing parameters for sequential macros constructed from C-modules can be obtained from the DirectTime Analyzer utility.

4. Setup and hold timing parameters for the Input Buffer Latch are defined with respect to the PAD and the D input. External setup/hold timing parameters must account for delay from an external PAD signal to the G inputs. Delay from an external PAD signal to the G input subtracts (adds) to the internal setup (hold) time.

Pin Descriptions

CLKA Clock A (Input)

TTL Clock input for clock distribution networks. The Clock input is buffered prior to clocking the logic modules. This pin can also be used as an I/O.

CLKB Clock B (Input)

TTL Clock input for clock distribution networks. The Clock input is buffered prior to clocking the logic modules. This pin can also be used as an I/O.

DCLK Diagnostic Clock (Input)

TTL Clock input for diagnostic probe and device programming. DCLK is active when the MODE pin is High. This pin functions as an I/O when the MODE pin is Low.

GND Ground

Low supply voltage.

I/O Input/Output (Input, Output)

The I/O pin functions as an input, output, three-state, or bidirectional buffer. Input and output levels are compatible with standard TTL and CMOS specifications. Unused I/O pins are automatically driven Low by the ALS software.

MODE Mode (Input)

The MODE pin controls the use of multifunction pins (DCLK, PRA, PRB, SDI). When the MODE pin is High, the special functions are active. When the MODE pin is Low, the pins function as I/Os. To provide Actionprobe capability, the MODE pin should be terminated to GND through a 10K resistor so that the MODE pin can be pulled High when required.

NC No Connection

This pin is not connected to circuitry within the device.

PRA Probe A (Output)

The Probe A pin is used to output data from any user-defined design node within the device. This independent diagnostic pin can be used in conjunction with the Probe B pin to allow real-time diagnostic output of any signal path within the device. The Probe A pin can be used as a user-defined I/O when debugging has been completed. The pin's probe capabilities can be permanently disabled to protect programmed design confidentiality. PRA is active when the MODE pin is High. This pin functions as an I/O when the MODE pin is Low.

PRB Probe B (Output)

The Probe B pin is used to output data from any user-defined design node within the device. This independent diagnostic pin can be used in conjunction with the Probe A pin to allow real-time diagnostic output of any signal path within the device. The Probe B pin can be used as a user-defined I/O when debugging has been completed. The pin's probe capabilities can be permanently disabled to protect programmed design confidentiality. PRB is active when the MODE pin is High. This pin functions as an I/O when the MODE pin is Low.

SDI Serial Data Input (Input)

Serial data input for diagnostic probe and device programming. SDI is active when the MODE pin is High. This pin functions as an I/O when the MODE pin is Low.

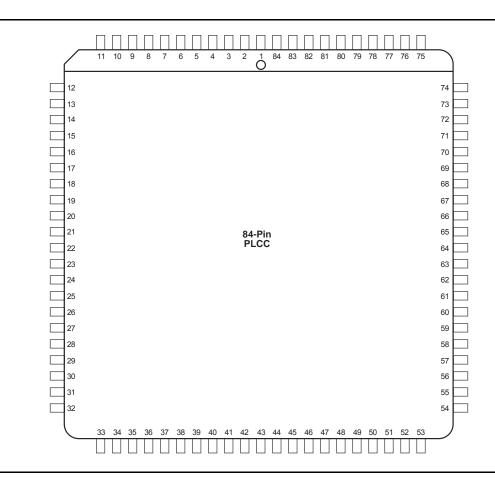
SDO Serial Data Output (Output)

Serial data output for diagnostic probe. SDO is active when the MODE pin is High. This pin functions as an I/O when the MODE pin is Low.

VCC 5.0 V Supply Voltage

High supply voltage.

PL84



Note

For Package Manufacturing and Environmental information, visit the Resource Center at http://www.microsemi.com/soc/products/solutions/package/docs.aspx.



PL84						
Pin Number	A1225A Function	A1240A Function	A1280A Function			
2	CLKB, I/O	CLKB, I/O	CLKB, I/O			
4	PRB, I/O	PRB, I/O	PRB, I/O			
6	GND	GND	GND			
10	DCLK, I/O	DCLK, I/O	DCLK, I/O			
12	MODE	MODE	MODE			
22	VCC	VCC	VCC			
23	VCC	VCC	VCC			
28	GND	GND	GND			
43	VCC	VCC	VCC			
49	GND	GND	GND			
52	SDO	SDO	SDO			
63	GND	GND	GND			
64	VCC	VCC	VCC			
65	VCC	VCC	VCC			
70	GND	GND	GND			
76	SDI, I/O	SDI, I/O	SDI, I/O			
81	PRA, I/O	PRA, I/O	PRA, I/O			
83	CLKA, I/O	CLKA, I/O	CLKA, I/O			
84	VCC	VCC	VCC			

Notes:

1. All unlisted pin numbers are user I/Os.

2. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.



	PQ144	PQ144				
Pin Number	A1240A Function	Pin Number	A1240A Function			
2	MODE	89	VCC			
9	GND	90	VCC			
10	GND	91	VCC			
11	GND	92	VCC			
18	VCC	93	VCC			
19	VCC	100	GND			
20	VCC	101	GND			
21	VCC	102	GND			
28	GND	110	SDI, I/O			
29	GND	116	GND			
30	GND	117	GND			
44	GND	118	GND			
45	GND	123	PRA, I/O			
46	GND	125	CLKA, I/O			
54	VCC	126	VCC			
55	VCC	127	VCC			
56	VCC	128	VCC			
64	GND	130	CLKB, I/O			
65	GND	132	PRB, I/O			
71	SDO	136	GND			
79	GND	137	GND			
80	GND	138	GND			
81	GND	144	DCLK, I/O			
88	GND	-	-			

Notes:

- 1. All unlisted pin numbers are user I/Os.
- 2. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.

CQ172		CQ172	
Pin Number	A1280A Function	Pin Number	A1280A Function
1	MODE	107	VCC
7	GND	108	GND
12	VCC	109	VCC
17	GND	110	VCC
22	GND	113	VCC
23	VCC	118	GND
24	VCC	123	GND
27	VCC	131	SDI, I/O
32	GND	136	VCC
37	GND	141	GND
50	VCC	148	PRA, I/O
55	GND	150	CLKA, I/O
65	GND	151	VCC
66	VCC	152	GND
75	GND	154	CLKB, I/O
80	VCC	156	PRB, I/O
85	SDO	161	GND
98	GND	166	VCC
103	GND	171	DCLK, I/O
106	GND	L L	

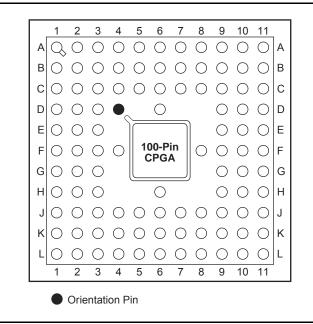
Notes:

1. All unlisted pin numbers are user I/Os.

2. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.



PG100



Note

For Package Manufacturing and Environmental information, visit the Resource Center at http://www.microsemi.com/soc/products/solutions/package/docs.aspx

PG132				
Pin Number	A1240A Function			
A1	MODE			
B5	GND			
B6	CLKB, I/O			
B7	CLKA, I/O			
B8	PRA, I/O			
B9	GND			
B12	SDI, I/O			
C3	DCLK, I/O			
C5	GND			
C6	PRB, I/O			
C7	VCC			
C9	GND			
D7	VCC			
E3	GND			
E11	GND			
E12	GND			
F4	GND			
G2	VCC			

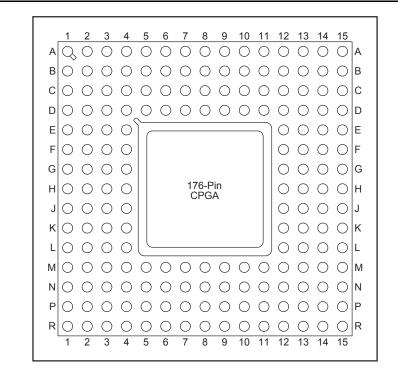
PG132				
Pin Number	A1240A Function			
G3	VCC			
G4	VCC			
G10	VCC			
G11	VCC			
G12	VCC			
G13	VCC			
H13	GND			
J2	GND			
J3	GND			
J11	GND			
K7	VCC			
K12	GND			
L5	GND			
L7	VCC			
L9	GND			
M9	GND			
N12	SDO			

Notes:

- 1. All unlisted pin numbers are user I/Os.
- 2. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.



PG176



Note

For Package Manufacturing and Environmental information, visit the Resource Center at http://www.microsemi.com/soc/products/solutions/package/docs.aspx

4 – Datasheet Information

List of Changes

The following table lists critical changes that were made in each version of the datasheet.

Revision	Changes	
Revision 8 (January 2012)	The ACT 2 datasheet was formatted newly in the style used for current datasheets. The same information is present (other than noted in the list of changes for this revision) but divided into chapters.	N/A
	Package names used in Table 1 • ACT 2 Product Family Profile and throughout the document were revised to match standards given in <i>Package Mechanical Drawings</i> (SAR 27395).	Ι
	The description for SDO pins had earlier been removed from the datasheet and has now been included again, in the "Pin Descriptions" section (SAR 35819).	2-21
	SDO pin numbers had earlier been removed from package pin assignment tables in the datasheet, and have now been restored to the pin tables (SAR 35819).	3-2
Revision 7 (June 2006)	The "Ordering Information" section was revised to include RoHS information.	II
Revision 6 (December 2000)	In the "PG176" package, pin A3 was incorrectly assigned as CLKA, I/O. A3 is a user I/O. Pin A9 is CLKA, I/O.	3-21



Datasheet Information

Datasheet Categories

Categories

In order to provide the latest information to designers, some datasheet parameters are published before data has been fully characterized from silicon devices. The data provided for a given device is designated as either "Product Brief," "Advance," "Preliminary," or "Production." The definitions of these categories are as follows:

Product Brief

The product brief is a summarized version of a datasheet (advance or production) and contains general product information. This document gives an overview of specific device and family information.

Advance

This version contains initial estimated information based on simulation, other products, devices, or speed grades. This information can be used as estimates, but not for production. This label only applies to the DC and Switching Characteristics chapter of the datasheet and will only be used when the data has not been fully characterized.

Preliminary

The datasheet contains information based on simulation and/or initial characterization. The information is believed to be correct, but changes are possible.

Production

This version contains information that is considered to be final.

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