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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Obsolete
Number of LABs/CLBs	1232
Number of Logic Elements/Cells	-
Total RAM Bits	-
Number of I/O	140
Number of Gates	8000
Voltage - Supply	4.5V ~ 5.5V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 70°C (TA)
Package / Case	172-CQFP with Tie Bar
Supplier Device Package	172-CQFP (63.37x63.37)
Purchase URL	https://www.e-xfl.com/product-detail/microsemi/a1280a-cq172c

Table 2-3 • Electrical Specifications

Symbol	Parameter	Commercial		Industrial		Military		Units
		Min.	Max.	Min.	Max.	Min.	Max.	
VOH ¹	(IOH = –10 mA) ²	2.4	–	–	–	–	–	V
	(IOH = –6 mA)	3.84	–	–	–	–	–	V
	(IOH = –4 mA)	–	–	3.7	–	3.7	–	V
VOL ¹	(IOL = 10 mA) ²	–	0.5	–	–	–	–	V
	(IOL = 6 mA)	–	0.33	–	0.40	–	0.40	V
VIL		–0.3	0.8	–0.3	0.8	–0.3	0.8	V
VIH		2.0	VCC + 0.3	2.0	VCC + 0.3	2.0	VCC + 0.3	V
Input Transition Time t _R , t _F ²		–	500	–	500	–	500	ns
C _{IO} I/O capacitance ^{2,3}		–	10	–	10	–	10	pF
Standby Current, ICC ⁴ (typical = 1 mA)		–	2	–	10	–	20	mA
Leakage Current ⁵		–10	+10	–10	+10	–10	+10	μA
ICC(D)	Dynamic VCC supply current. See the Power Dissipation section.							

Notes:

1. Only one output tested at a time. VCC = minimum.
2. Not tested, for information only.
3. Includes worst-case PG176 package capacitance. VOUT = 0 V, f = 1 MHz
4. All outputs unloaded. All inputs = VCC or GND, typical ICC = 1 mA. ICC limit includes IPP and ISV during normal operations.
5. VOUT, VIN = VCC or GND.

Package Thermal Characteristics

The device junction to case thermal characteristic is θ_{jc} , and the junction to ambient air characteristic is θ_{ja} . The thermal characteristics for θ_{ja} are shown with two different air flow rates.

Maximum junction temperature is 150°C.

A sample calculation of the absolute maximum power dissipation allowed for a PQ160 package at commercial temperature and still air is as follows:

$$\frac{\text{Max. junction temp. (°C)} - \text{Max. ambient temp. (°C)}}{\theta_{ja} \text{ °C/W}} = \frac{150^{\circ}\text{C} - 70^{\circ}\text{C}}{33^{\circ}\text{C/W}} = 2.4 \text{ W}$$

EQ 1

Table 2-4 • Package Thermal Characteristics

Package Type*	Pin Count	θ_{jc}	θ_{ja} Still Air	θ_{ja} 300 ft./min.	Units
Ceramic Pin Grid Array	100	5	35	17	°C/W
	132	5	30	15	°C/W
	176	8	23	12	°C/W
Ceramic Quad Flatpack	172	8	25	15	°C/W
Plastic Quad Flatpack ¹	100	13	48	40	°C/W
	144	15	40	32	°C/W
	160	15	38	30	°C/W
Plastic Leaded Chip Carrier	84	12	37	28	°C/W
Very Thin Quad Flatpack	100	12	43	35	°C/W
Thin Quad Flatpack	176	15	32	25	°C/W

Notes: (Maximum Power in Still Air)

1. Maximum power dissipation values for PQFP packages are 1.9 W (PQ100), 2.3 W (PQ144), and 2.4 W (PQ160).
2. Maximum power dissipation for PLCC packages is 2.7 W.
3. Maximum power dissipation for VQFP packages is 2.3 W.
4. Maximum power dissipation for TQFP packages is 3.1 W.

Power Dissipation

$$P = [\text{ICC standby} + \text{ICC active}] * V_{CC} + \text{IOL} * \text{VOL} * N + \text{IOH} * (V_{CC} - \text{VOH}) * M$$

EQ 2

where:

ICC standby is the current flowing when no inputs or outputs are changing

ICC active is the current flowing due to CMOS switching.

IOL and IOH are TTL sink/source currents.

VOL and VOH are TTL level output voltages.

N is the number of outputs driving TTL loads to VOL.

M is the number of outputs driving TTL loads to VOH.

An accurate determination of N and M is problematical because their values depend on the family type, design details, and on the system I/O. The power can be divided into two components: static and active.

To calculate the active power dissipated from the complete design, the switching frequency of each part of the logic must be known. EQ 4 shows a piece-wise linear summation over all components.

$$\begin{aligned}
 \text{Power} = & VCC^2 * [(m * C_{EQM} * f_m)_{\text{modules}} + (n * C_{EQI} * f_n)_{\text{inputs}} \\
 & + (p * (C_{EQO} + C_L) * f_p)_{\text{outputs}} \\
 & + 0.5 * (q1 * C_{EQCR} * f_{q1})_{\text{routed_Clk1}} + (r1 * f_{q1})_{\text{routed_Clk1}} \\
 & + 0.5 * (q2 * C_{EQCR} * f_{q2})_{\text{routed_Clk2}} + (r2 * f_{q2})_{\text{routed_Clk2}}
 \end{aligned}$$

EQ 4

Where:

m = Number of logic modules switching at f_m

n = Number of input buffers switching at f_n

p = Number of output buffers switching at f_p

q1 = Number of clock loads on the first routed array clock

q2 = Number of clock loads on the second routed array clock

r_1 = Fixed capacitance due to first routed array clock

r_2 = Fixed capacitance due to second routed array clock

C_{EQM} = Equivalent capacitance of logic modules in pF

C_{EQI} = Equivalent capacitance of input buffers in pF

C_{EQO} = Equivalent capacitance of output buffers in pF

C_{EQCR} = Equivalent capacitance of routed array clock in pF

C_L = Output lead capacitance in pF

f_m = Average logic module switching rate in MHz

f_n = Average input buffer switching rate in MHz

f_p = Average output buffer switching rate in MHz

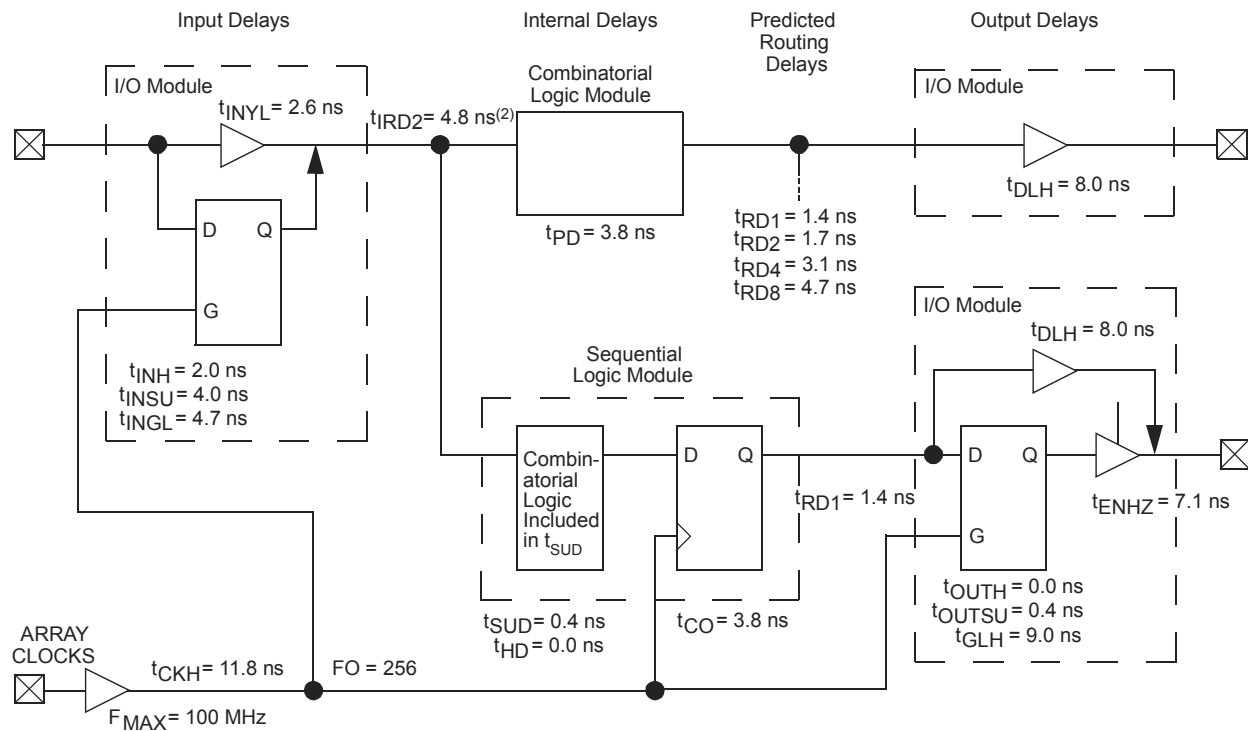
f_{q1} = Average first routed array clock rate in MHz

f_{q2} = Average second routed array clock rate in MHz

Table 2-7 • Fixed Capacitance Values for Microsemi FPGAs

Device Type	r_1 , routed_Clk1	r_2 , routed_Clk2
A1225A	106	106.0
A1240A	134	134.2
A1280A	168	167.8

ACT 2 Timing Model¹



Notes:

1. Values shown for A1240A-2 at worst-case commercial conditions.
2. Input module predicted routing delay

Figure 2-1 • Timing Model

Parameter Measurement

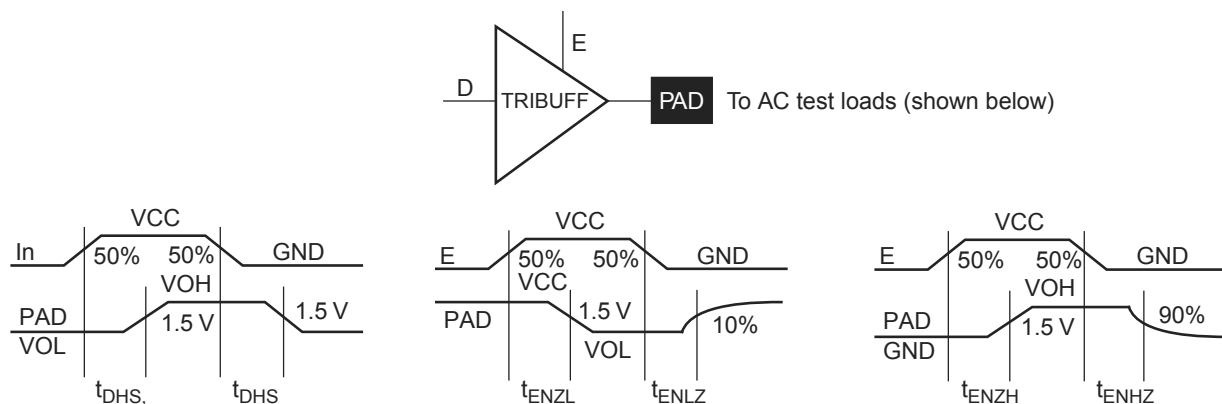


Figure 2-2 • Output Buffer Delays

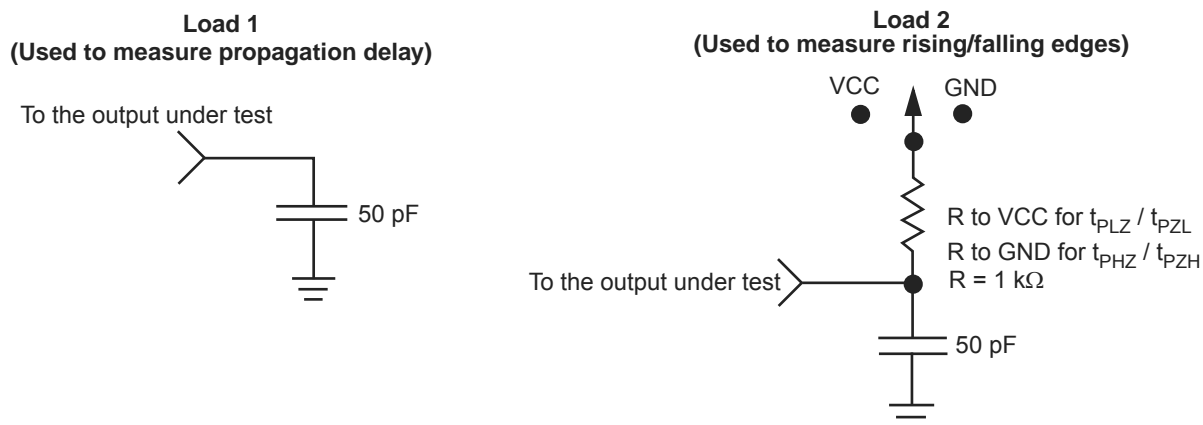


Figure 2-3 • AC Test Loads

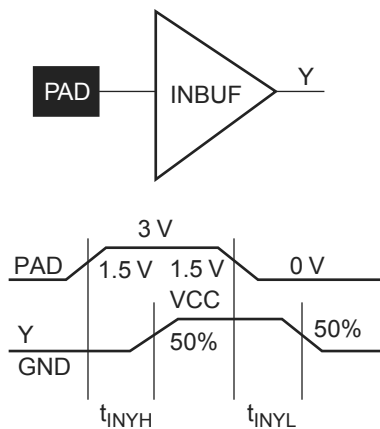


Figure 2-4 • Input Buffer Delays

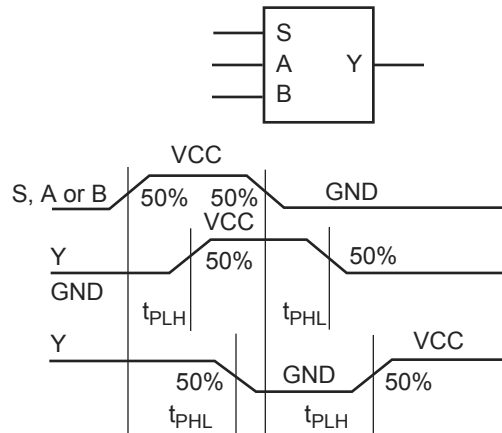
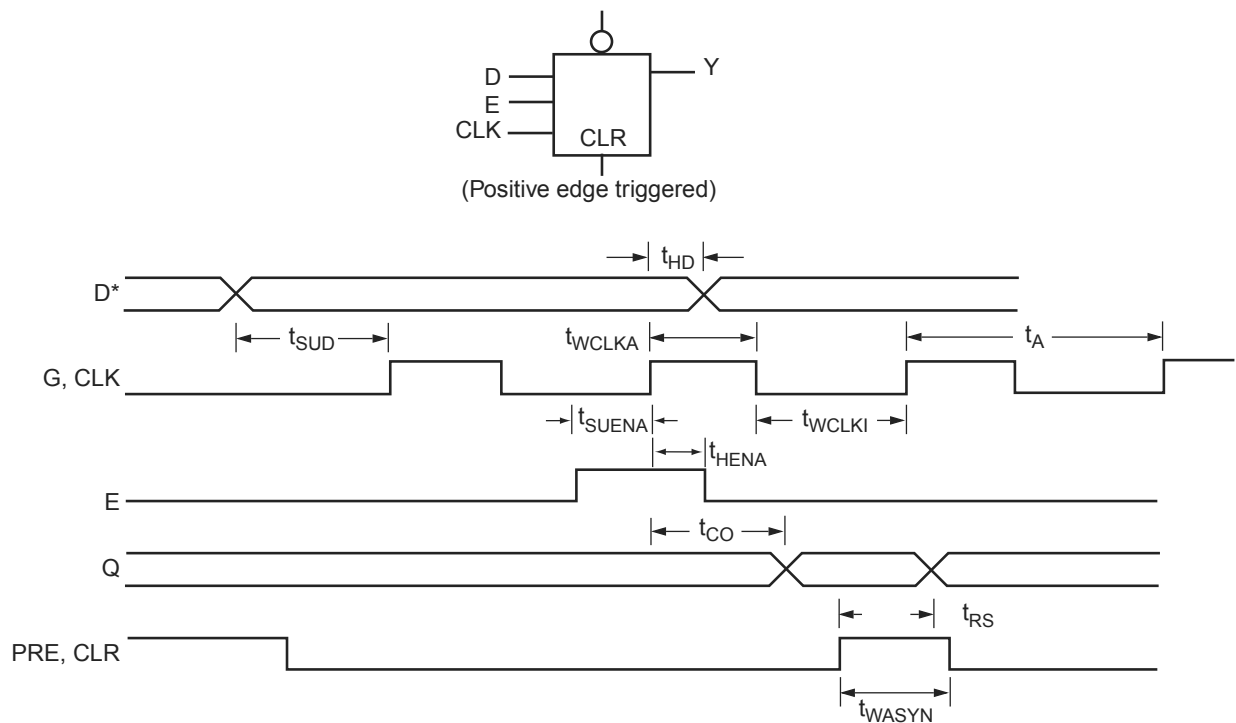


Figure 2-5 • Module Delays

Sequential Module Timing Characteristics



Note: D represents all data functions involving A, B, and S for multiplexed flip-flops.

Figure 2-6 • Flip-Flops and Latches

Timing Derating Factor (Temperature and Voltage)

Table 2-9 • Timing Derating Factor (Temperature and Voltage)

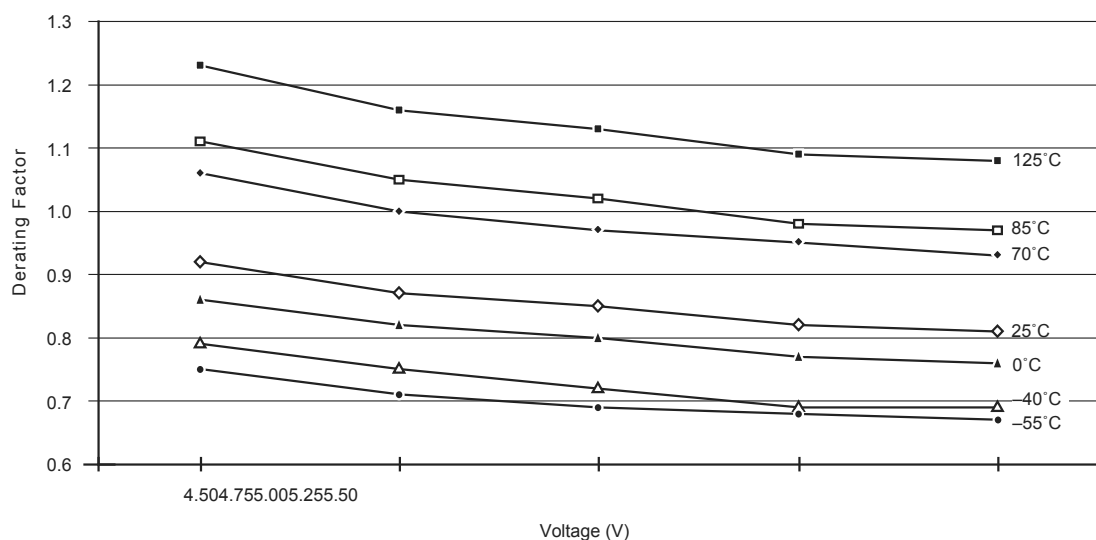
(Commercial Minimum/Maximum Specification) x	Industrial		Military	
	Min.	Max.	Min.	Max.
	0.69	1.11	0.67	1.23

Table 2-10 • Timing Derating Factor for Designs at Typical Temperature ($T_J = 25^\circ\text{C}$) and Voltage (5.0 V)

(Commercial Maximum Specification) x	0.85
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**Table 2-11 • Temperature and Voltage Derating Factors
(normalized to Worst-Case Commercial, $T_J = 4.75\text{ V}$, 70°C)**

	-55	-40	0	25	70	85	125
4.50	0.75	0.79	0.86	0.92	1.06	1.11	1.23
4.75	0.71	0.75	0.82	0.87	1.00	1.05	1.13
5.00	0.69	0.72	0.80	0.85	0.97	1.02	1.13
5.25	0.68	0.69	0.77	0.82	0.95	0.98	1.09
5.50	0.67	0.69	0.76	0.81	0.93	0.97	1.08



Note: This derating factor applies to all routing and propagation delays.

**Figure 2-9 • Junction Temperature and Voltage Derating Curves
(normalized to Worst-Case Commercial, $T_J = 4.75\text{ V}$, 70°C)**

A1225A Timing Characteristics (continued)

Table 2-14 • A1225A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

TTL Output Module Timing ¹		–2 Speed		–1 Speed		Std. Speed		Units
Parameter/Description		Min.	Max.	Min.	Max.	Min.	Max.	
t _{DLH}	Data to Pad High		8.0		9.0		10.6	ns
t _{DHL}	Data to Pad Low		10.1		11.4		13.4	ns
t _{ENZH}	Enable Pad Z to High		8.9		10.0		11.8	ns
t _{ENZL}	Enable Pad Z to Low		11.6		13.2		15.5	ns
t _{ENHZ}	Enable Pad High to Z		7.1		8.0		9.4	ns
t _{ENLZ}	Enable Pad Low to Z		8.3		9.5		11.1	ns
t _{GLH}	G to Pad High		8.9		10.2		11.9	ns
t _{GHL}	G to Pad Low		11.2		12.7		14.9	ns
d _{TLH}	Delta Low to High		0.07		0.08		0.09	ns/pF
d _{THL}	Delta High to Low		0.12		0.13		0.16	ns/pF
CMOS Output Module Timing ¹								
t _{DLH}	Data to Pad High		10.1		11.5		13.5	ns
t _{DHL}	Data to Pad Low		8.4		9.6		11.2	ns
t _{ENZH}	Enable Pad Z to High		8.9		10.0		11.8	ns
t _{ENZL}	Enable Pad Z to Low		11.6		13.2		15.5	ns
t _{ENHZ}	Enable Pad High to Z		7.1		8.0		9.4	ns
t _{ENLZ}	Enable Pad Low to Z		8.3		9.5		11.1	ns
t _{GLH}	G to Pad High		8.9		10.2		11.9	ns
t _{GHL}	G to Pad Low		11.2		12.7		14.9	ns
d _{TLH}	Delta Low to High		0.12		0.13		0.16	ns/pF
d _{THL}	Delta High to Low		0.09		0.10		0.12	ns/pF

Notes:

1. Delays based on 50 pF loading.
2. SSO information can be found at www.microsemi.com/soc/techdocs/appnotes/board_consideration.aspx.

A1240A Timing Characteristics

Table 2-15 • A1240A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

Logic Module Propagation Delays ¹		–2 Speed ³		–1 Speed		Std. Speed		Units
Parameter/Description		Min.	Max.	Min.	Max.	Min.	Max.	
t _{PD1}	Single Module		3.8		4.3		5.0	ns
t _{CO}	Sequential Clock to Q		3.8		4.3		5.0	ns
t _{GO}	Latch G to Q		3.8		4.3		5.0	ns
t _{RS}	Flip-Flop (Latch) Reset to Q		3.8		4.3		5.0	ns
Predicted Routing Delays²								
t _{RD1}	FO = 1 Routing Delay		1.4		1.5		1.8	ns
t _{RD2}	FO = 2 Routing Delay		1.7		2.0		2.3	ns
t _{RD3}	FO = 3 Routing Delay		2.3		2.6		3.0	ns
t _{RD4}	FO = 4 Routing Delay		3.1		3.5		4.1	ns
t _{RD8}	FO = 8 Routing Delay		4.7		5.4		6.3	ns
Sequential Timing Characteristics^{3,4}								
t _{SUD}	Flip-Flop (Latch) Data Input Setup	0.4		0.4		0.5		ns
t _{HD}	Flip-Flop (Latch) Data Input Hold	0.0		0.0		0.0		ns
t _{SUENA}	Flip-Flop (Latch) Enable Setup	0.8		0.9		1.0		ns
t _{HENA}	Flip-Flop (Latch) Enable Hold	0.0		0.0		0.0		ns
t _{WCLKA}	Flip-Flop (Latch) Clock Active Pulse Width	4.5		6.0		6.5		ns
t _{WASYN}	Flip-Flop (Latch) Clock Asynchronous Pulse Width	4.5		6.0		6.5		ns
t _A	Flip-Flop Clock Input Period	9.8		12.0		15.0		ns
t _{INH}	Input Buffer Latch Hold	0.0		0.0		0.0		ns
t _{INSU}	Input Buffer Latch Setup	0.4		0.4		0.5		ns
t _{OUTH}	Output Buffer Latch Hold	0.0		0.0		0.0		ns
t _{OUTSU}	Output Buffer Latch Setup	0.4		0.4		0.5		ns
f _{MAX}	Flip-Flop (Latch) Clock Frequency		100.0		80.0		66.0	MHz

Notes:

1. For dual-module macros, use t_{PD1} + t_{RD1} + t_{PDn}, t_{CO} + t_{RD1} + t_{PDn}, or t_{PD1} + t_{RD1} + t_{SUD}—whichever is appropriate.
2. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.
3. Data applies to macros based on the S-module. Timing parameters for sequential macros constructed from C-modules can be obtained from the DirectTime Analyzer utility.
4. Setup and hold timing parameters for the Input Buffer Latch are defined with respect to the PAD and the D input. External setup/hold timing parameters must account for delay from an external PAD signal to the G inputs. Delay from an external PAD signal to the G input subtracts (adds) to the internal setup (hold) time.

A1240A Timing Characteristics (continued)

Table 2-17 • A1240A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

TTL Output Module Timing ¹		–2 Speed		–1 Speed		Std. Speed		Units
Parameter/Description		Min.	Max.	Min.	Max.	Min.	Max.	
t _{DLH}	Data to Pad High		8.0		9.0		10.6	ns
t _{DHL}	Data to Pad Low		10.1		11.4		13.4	ns
t _{ENZH}	Enable Pad Z to High		8.9		10.0		11.8	ns
t _{ENZL}	Enable Pad Z to Low		11.7		13.2		15.5	ns
t _{ENHZ}	Enable Pad High to Z		7.1		8.0		9.4	ns
t _{ENLZ}	Enable Pad Low to Z		8.4		9.5		11.1	ns
t _{GLH}	G to Pad High		9.0		10.2		11.9	ns
t _{GHL}	G to Pad Low		11.2		12.7		14.9	ns
d _{TLH}	Delta Low to High		0.07		0.08		0.09	ns/pF
d _{THL}	Delta High to Low		0.12		0.13		0.16	ns/pF
CMOS Output Module Timing ¹								
t _{DLH}	Data to Pad High		10.2		11.5		13.5	ns
t _{DHL}	Data to Pad Low		8.4		9.6		11.2	ns
t _{ENZH}	Enable Pad Z to High		8.9		10.0		11.8	ns
t _{ENZL}	Enable Pad Z to Low		11.7		13.2		15.5	ns
t _{ENHZ}	Enable Pad High to Z		7.1		8.0		9.4	ns
t _{ENLZ}	Enable Pad Low to Z		8.4		9.5		11.1	ns
t _{GLH}	G to Pad High		9.0		10.2		11.9	ns
t _{GHL}	G to Pad Low		11.2		12.7		14.9	ns
d _{TLH}	Delta Low to High		0.12		0.13		0.16	ns/pF
d _{THL}	Delta High to Low		0.09		0.10		0.12	ns/pF

Notes:

1. Delays based on 50 pF loading.
2. SSO information can be found at www.microsemi.com/soc/techdocs/appnotes/board_consideration.aspx.

PL84			
Pin Number	A1225A Function	A1240A Function	A1280A Function
2	CLKB, I/O	CLKB, I/O	CLKB, I/O
4	PRB, I/O	PRB, I/O	PRB, I/O
6	GND	GND	GND
10	DCLK, I/O	DCLK, I/O	DCLK, I/O
12	MODE	MODE	MODE
22	VCC	VCC	VCC
23	VCC	VCC	VCC
28	GND	GND	GND
43	VCC	VCC	VCC
49	GND	GND	GND
52	SDO	SDO	SDO
63	GND	GND	GND
64	VCC	VCC	VCC
65	VCC	VCC	VCC
70	GND	GND	GND
76	SDI, I/O	SDI, I/O	SDI, I/O
81	PRA, I/O	PRA, I/O	PRA, I/O
83	CLKA, I/O	CLKA, I/O	CLKA, I/O
84	VCC	VCC	VCC

Notes:

1. All unlisted pin numbers are user I/Os.
2. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.

PQ100	
Pin Number	A1225A Function
2	DCLK, I/O
4	MODE
9	GND
16	VCC
17	VCC
22	GND
34	GND
40	VCC
46	GND
52	SDO
57	GND
64	GND

PQ100	
Pin Number	A1225A Function
65	VCC
66	VCC
67	VCC
72	GND
79	SDI, I/O
84	GND
87	PRA, I/O
89	CLKA, I/O
90	VCC
92	CLKB, I/O
94	PRB, I/O
96	GND

Notes:

1. All unlisted pin numbers are user I/Os.
2. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.

PQ144	
Pin Number	A1240A Function
2	MODE
9	GND
10	GND
11	GND
18	VCC
19	VCC
20	VCC
21	VCC
28	GND
29	GND
30	GND
44	GND
45	GND
46	GND
54	VCC
55	VCC
56	VCC
64	GND
65	GND
71	SDO
79	GND
80	GND
81	GND
88	GND

PQ144	
Pin Number	A1240A Function
89	VCC
90	VCC
91	VCC
92	VCC
93	VCC
100	GND
101	GND
102	GND
110	SDI, I/O
116	GND
117	GND
118	GND
123	PRA, I/O
125	CLKA, I/O
126	VCC
127	VCC
128	VCC
130	CLKB, I/O
132	PRB, I/O
136	GND
137	GND
138	GND
144	DCLK, I/O

Notes:

1. All unlisted pin numbers are user I/Os.
2. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.

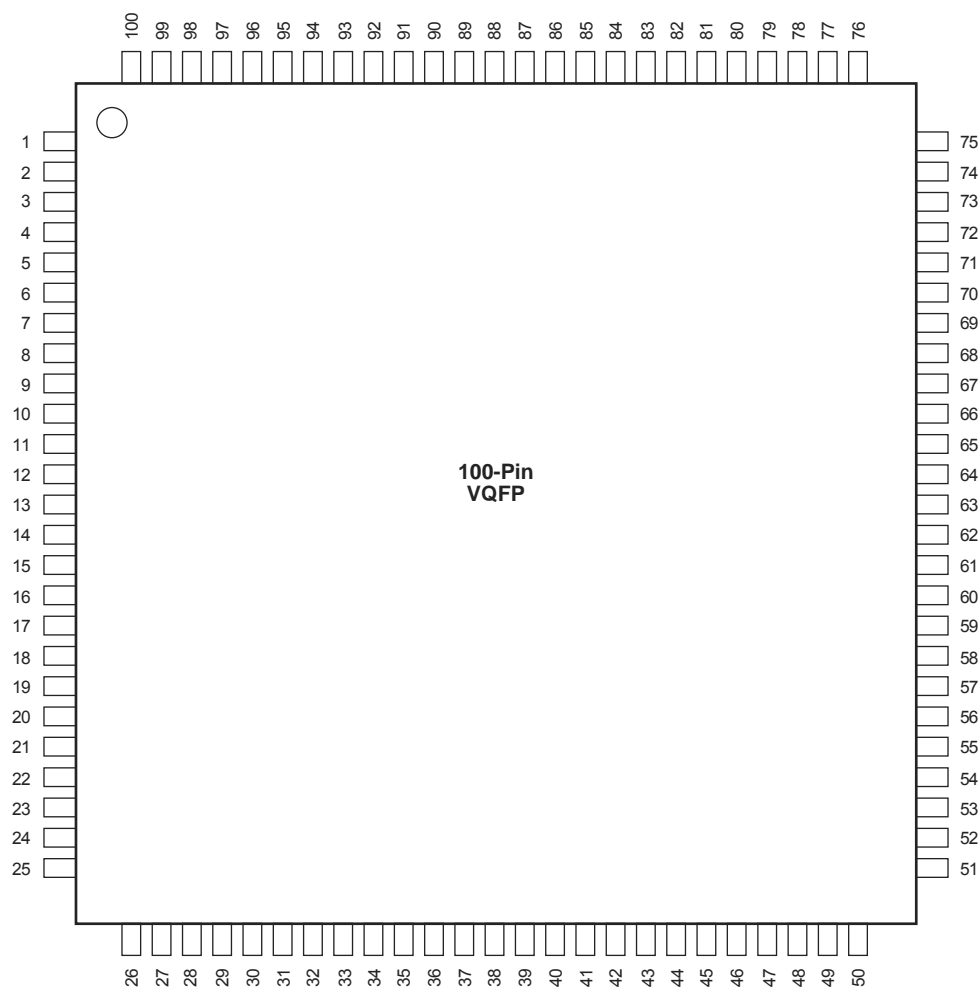
PQ160	
Pin Number	A1280A Function
2	DCLK, I/O
6	VCC
11	GND
16	PRB, I/O
18	CLKB, I/O
20	VCC
21	CLKA, I/O
23	PRA, I/O
30	GND
35	VCC
38	SDI, I/O
40	GND
44	GND
49	GND
54	VCC
57	VCC
58	VCC
59	GND
60	VCC
61	GND
64	GND

PQ160	
Pin Number	A1280A Function
69	GND
80	GND
82	SDO
86	VCC
89	GN
98	GND
99	GND
109	GND
114	VCC
120	GND
125	GND
130	GND
135	VCC
138	VCC
139	VCC
140	GND
145	GND
150	VCC
155	GND
159	MODE
160	GND

Notes:

1. All unlisted pin numbers are user I/Os.
2. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.

VQ100



Note

For Package Manufacturing and Environmental information, visit the Resource Center at <http://www.microsemi.com/soc/products/solutions/package/docs.aspx>

TQ176		
Pin Number	A1240A Function	A1280A Function
155	VCC	VCC
156	GND	GND
158	CLKB, I/O	CLKB, I/O
160	PRB, I/O	PRB, I/O
161	NC	I/O
165	NC	NC
166	NC	I/O
168	NC	I/O
170	NC	VCC
173	NC	I/O
175	DCLK, I/O	DCLK, I/O

Notes:

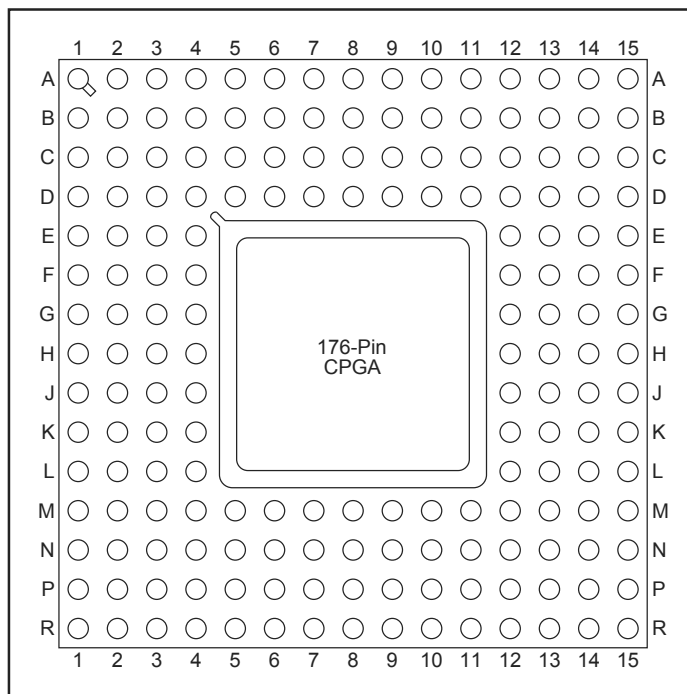
1. NC denotes no connection.
2. All unlisted pin numbers are user I/Os.
3. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.

PG100		PG100	
Pin Number	A1225A Function	Pin Number	A1225A Function
A4	PRB, I/O	E11	VCC
A7	PRA, I/O	F3	VCC
B6	VCC	F9	VCC
C2	MODE	F10	VCC
C3	DCLK, I/O	F11	GND
C5	GND	G1	VCC
C6	CLKA, I/O	G3	GND
C7	GND	G9	GND
C8	SDI, I/O	J5	GND
D6	CLKB, I/O	J7	GND
D10	GND	J9	SDO
E3	GND	K6	VCC

Notes:

1. All unlisted pin numbers are user I/Os.
2. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.

PG176



Note

For Package Manufacturing and Environmental information, visit the Resource Center at <http://www.microsemi.com/soc/products/solutions/package/docs.aspx>

PG176	
Pin Number	A1280A Function
A9	CLKA, I/O
B3	DCLK, I/O
B8	CLKB, I/O
B14	SDI, I/O
C3	MODE
C8	GND
C9	PRA, I/O
D4	GND
D5	VCC
D6	GND
D7	PRB, I/O
D8	VCC
D10	GND
D11	VCC
D12	GND
E4	GND
E12	GND
F4	VCC
F12	GND
G4	GND
G12	VCC
H2	VCC

PG176	
Pin Number	A1280A Function
H3	VCC
H4	GND
H12	GND
H13	VCC
H14	VCC
J4	VCC
J12	GND
J13	GND
J14	VCC
K4	GND
K12	GND
L4	GND
M4	GND
M5	VCC
M6	GND
M8	GND
M10	GND
M11	VCC
M12	GND
N8	VCC
P13	SDO

Notes:

1. All unlisted pin numbers are user I/Os.
2. MODE pin should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.

4 – Datasheet Information

List of Changes

The following table lists critical changes that were made in each version of the datasheet.

Revision	Changes	Page
Revision 8 (January 2012)	The ACT 2 datasheet was formatted newly in the style used for current datasheets. The same information is present (other than noted in the list of changes for this revision) but divided into chapters.	N/A
	Package names used in Table 1 • ACT 2 Product Family Profile and throughout the document were revised to match standards given in <i>Package Mechanical Drawings</i> (SAR 27395).	I
	The description for SDO pins had earlier been removed from the datasheet and has now been included again, in the "Pin Descriptions" section (SAR 35819).	2-21
	SDO pin numbers had earlier been removed from package pin assignment tables in the datasheet, and have now been restored to the pin tables (SAR 35819).	3-2
Revision 7 (June 2006)	The "Ordering Information" section was revised to include RoHS information.	II
Revision 6 (December 2000)	In the "PG176" package, pin A3 was incorrectly assigned as CLKA, I/O. A3 is a user I/O. Pin A9 is CLKA, I/O.	3-21