

Welcome to E-XFL.COM

Understanding Embedded - Microprocessors

Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of **Embedded - Microprocessors**

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details

Obsolete
ARM926EJ-S
1 Core, 32-Bit
180MHz
-
SDRAM, SRAM
No
LCD, Touchscreen
10/100Mbps
-
USB 2.0 (3)
1.8V, 2.5V, 3.3V
-40°C ~ 85°C (TA)
-
217-LFBGA
217-LFBGA (15x15)
https://www.e-xfl.com/product-detail/microchip-technology/at91sam9xe512-cu

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



Table 3-1. Signal Description List (Continued)

Signal Name	Function	Туре	Active Level	Reference Voltage	Comments
	Co	ompactFlash S	Support	4	
CFCE1 - CFCE2	CompactFlash Chip Enable	Output	Low	VDDIOM	
CFOE	CompactFlash Output Enable	Output	Low	VDDIOM	
CFWE	CompactFlash Write Enable	Output	Low	VDDIOM	
CFIOR	CompactFlash IO Read	Output	Low	VDDIOM	
CFIOW	CompactFlash IO Write	Output	Low	VDDIOM	
CFRNW	CompactFlash Read Not Write	Output		VDDIOM	
CFCS0 - CFCS1	CompactFlash Chip Select Lines	Output	Low	VDDIOM	
	1	AND Flash Su	upport		
NANDCS	NAND Flash Chip Select	Output	Low	VDDIOM	
NANDOE	NAND Flash Output Enable	Output	Low	VDDIOM	
NANDWE	NAND Flash Write Enable	Output	Low	VDDIOM	
		SDRAM Cont	roller		
SDCK	SDRAM Clock	Output		VDDIOM	
SDCKE	SDRAM Clock Enable	Output	High	VDDIOM	
SDCS	SDRAM Controller Chip Select	Output	Low	VDDIOM	
BA0 - BA1	Bank Select	Output		VDDIOM	
SDWE	SDRAM Write Enable	Output	Low	VDDIOM	
RAS - CAS	Row and Column Signal	Output	Low	VDDIOM	
SDA10	SDRAM Address 10 Line	Output		VDDIOM	
	Multir	nedia Card Int	terface MCI	1	
МССК	Multimedia Card Clock	Output		VDDIOP0	
MCCDA	Multimedia Card Slot A Command	I/O		VDDIOP0	
MCDA0 - MCDA3	Multimedia Card Slot A Data	I/O		VDDIOP0	
MCCDB	Multimedia Card Slot B Command	I/O		VDDIOP0	
MCDB0 - MCDB3	Multimedia Card Slot B Data	I/O		VDDIOP0	
	Universal Synchronous A	synchronous	Receiver Tra	ansmitter USA	RTx
SCKx	USARTx Serial Clock	I/O		(2)	
TXDx	USARTx Transmit Data	I/O		(2)	
RXDx	USARTx Receive Data	Input		(2)	
RTSx	USARTx Request To Send Output			(2)	
CTSx	USARTx Clear To Send	Input		(2)	
DTR0	USART0 Data Terminal Ready	Output		(2)	
DSR0	USART0 Data Set Ready	Input		(2)	
DCD0	USART0 Data Carrier Detect	Input		(2)	
RI0	USART0 Ring Indicator	Input		(2)	

11. ARM926EJ-S Processor

11.1 Overview

The ARM926EJ-S processor is a member of the ARM9[™] family of general-purpose microprocessors. The ARM926EJ-S implements ARM architecture version 5TEJ and is targeted at multi-tasking applications where full memory management, high performance, low die size and low power are all important features.

The ARM926EJ-S processor supports the 32-bit ARM and 16-bit THUMB instruction sets, enabling the user to trade off between high performance and high code density. It also supports 8-bit Java instruction set and includes features for efficient execution of Java bytecode, providing a Java performance similar to a JIT (Just-In-Time compilers), for the next generation of Javapowered wireless and embedded devices. It includes an enhanced multiplier design for improved DSP performance.

The ARM926EJ-S processor supports the ARM debug architecture and includes logic to assist in both hardware and software debug.

The ARM926EJ-S provides a complete high performance processor subsystem, including:

- an ARM9EJ-S[™] integer core
- a Memory Management Unit (MMU)
- separate instruction and data AMBA AHB bus interfaces
- · separate instruction and data TCM interfaces

	Table 11-1.	Reference Document Table
--	-------------	--------------------------

Owner-Reference	Denomination
ARM Ltd DD10198B	ARM926EJS Technical Reference Manual
ARM Ltd DD10222B	ARM9EJ-S Technical Reference Manual



12.5 JTAG Port Pins

TMS, TDI and TCK are Schmitt trigger inputs and have no pull-up resistors.

TDO and RTCK are outputs, driven at up to VDDIOP0, and have no pull-up resistors.

The JTAGSEL pin is used to select the JTAG boundary scan when asserted at a high level (tied to VDDBU). It integrates a permanent pull-down resistor of about 15 k Ω to GNDBU, so that it can be left unconnected for normal operations.

All the JTAG signals are supplied with VDDIOP0.

12.6 Functional Description

12.6.1 Test Pin

One dedicated pin, TST, is used to define the device operating mode. The user must make sure that this pin is tied at low level to ensure normal operating conditions. Other values associated with this pin are reserved for manufacturing test.

12.6.2 Embedded In-circuit Emulator

The ARM9EJ-S Embedded In-Circuit Emulator-RT is supported via the ICE/JTAG port. It is connected to a host computer via an ICE interface. Debug support is implemented using an ARM9EJ-S core embedded within the ARM926EJ-S. The internal state of the ARM926EJ-S is examined through an ICE/JTAG port which allows instructions to be serially inserted into the pipeline of the core without using the external data bus. Therefore, when in debug state, a storemultiple (STM) can be inserted into the instruction pipeline. This exports the contents of the ARM9EJ-S registers. This data can be serially shifted out without affecting the rest of the system.

There are two scan chains inside the ARM9EJ-S processor which support testing, debugging, and programming of the Embedded ICE-RT. The scan chains are controlled by the ICE/JTAG port.

Embedded ICE mode is selected when JTAGSEL is low. It is not possible to switch directly between ICE and JTAG operations. A chip reset must be performed after JTAGSEL is changed.

For further details on the Embedded In-Circuit-Emulator-RT, see the ARM document:

ARM9EJ-S Technical Reference Manual (DDI 0222A).

12.6.3 Debug Unit

The Debug Unit provides a two-pin (DXRD and TXRD) USART that can be used for several debug and trace purposes and offers an ideal means for in-situ programming solutions and debug monitor communication. Moreover, the association with two peripheral data controller channels permits packet handling of these tasks with processor time reduced to a minimum.

The Debug Unit also manages the interrupt handling of the COMMTX and COMMRX signals that come from the ICE and that trace the activity of the Debug Communication Channel.The Debug Unit allows blockage of access to the system through the ICE interface.

A specific register, the Debug Unit Chip ID Register, gives information about the product version and its internal configuration.

The AT91SAM9XE Debug Unit Chip ID value is 0x0198 03A0 on 32-bit width.

For further details on the Debug Unit, see the Debug Unit section.





AT91SAM9XE128/256/512 Preliminary

6254C-ATARM-22-Jan-10

15.4.2 Reset Controller Status Register

Name:	RSTC_S	RSTC_SR						
Address:	0xFFFF	0xFFFFD04						
Access Type:	Read-or	ıly						
31	30	29	28	27	26	25	24	
_	-	-	-	-	-	-	-	
23	22	21	20	19	18	17	16	
_	—	-	-	—	-	SRCMP	NRSTL	
15	14	13	12	11	10	9	8	
_	-	-	-	—		RSTTYP		
7	6	5	4	3	2	. 1	0	
_	_	_	_	_	_	-BODSTS	URSTS	

• URSTS: User Reset Status

0 = No high-to-low edge on NRST happened since the last read of RSTC_SR.

1 = At least one high-to-low transition of NRST has been detected since the last read of RSTC_SR.

BODSTS: Brownout Detection Status

0 = No brownout high-to-low transition happened since the last read of RSTC_SR.

1 = A brownout high-to-low transition has been detected since the last read of RSTC_SR.

• RSTTYP: Reset Type

Reports the cause of the last processor reset. Reading this RSTC_SR does not reset this field.

	RSTTYP Reset Type		Reset Type	Comments
0	0	0	General Reset	Both VDDCORE and VDDBU rising
0	0	1	Wake Up Reset	VDDCORE rising
0	1	0	Watchdog Reset	Watchdog fault occurred
0	1	1	Software Reset	Processor reset required by the software
1	0	0	User Reset	NRST pin detected low
1	0	1	Brownout Reset	Brownout reset occurred

• NRSTL: NRST Pin Level

Registers the NRST Pin Level at Master Clock (MCK).

• SRCMP: Software Reset Command in Progress

0 = No software command is being performed by the reset controller. The reset controller is ready for a software command.

1 = A software reset command is being performed by the reset controller. The reset controller is busy.





22.6.6.1 I/O Mode, Common Memory Mode, Attribute Memory Mode and True IDE Mode

Within the NCS4 and/or NCS5 address space, the current transfer address is used to distinguish I/O mode, common memory mode, attribute memory mode and True IDE mode.

The different modes are accessed through a specific memory mapping as illustrated on Figure 22-3. A[23:21] bits of the transfer address are used to select the desired mode as described in Table 22-5 on page 178.





Note: The A22 pin is used to drive the REG signal of the CompactFlash Device (except in True IDE mode).

Table 22-5. CompactFlash Mode Selection

A[23:21]	Mode Base Address
000	Attribute Memory
010	Common Memory
100	I/O Mode
110	True IDE Mode
111	Alternate True IDE Mode

22.6.6.2 CFCE1 and CFCE2 Signals

To cover all types of access, the SMC must be alternatively set to drive 8-bit data bus or 16-bit data bus. The odd byte access on the D[7:0] bus is only possible when the SMC is configured to drive 8-bit memory devices on the corresponding NCS pin (NCS4 or NCS5). The Chip Select Register (DBW field in the corresponding Chip Select Register) of the NCS4 and/or NCS5 address space must be set as shown in Table 22-6 to enable the required access type.

NBS1 and NBS0 are the byte selection signals from SMC and are available when the SMC is set in Byte Select mode on the corresponding Chip Select.

178 AT91SAM9XE128/256/512 Preliminary



22.7.4 16-bit NAND FLASH

Hardware Configuration



22.7.4.1 Software Configuration

The software configuration is the same as for an 8-bit NAND Flash except the data bus width programmed in the mode register of the Static Memory Controller.

timings are identical. The pulse length of the first access to the page is defined with the NCS_RD_PULSE field of the SMC_PULSE register. The pulse length of subsequent accesses within the page are defined using the NRD_PULSE parameter.

In page mode, the programming of the read timings is described in Table 23-7:

Parameter	Value	Definition
READ_MODE	'x'	No impact
NCS_RD_SETUP	ʻx'	No impact
NCS_RD_PULSE	t _{pa}	Access time of first access to the page
NRD_SETUP	'x'	No impact
NRD_PULSE	t _{sa}	Access time of subsequent accesses in the page
NRD_CYCLE	'x'	No impact

Table 23-7. Programming of Read Timings in Page Mode

The SMC does not check the coherency of timings. It will always apply the NCS_RD_PULSE timings as page access timing (t_{pa}) and the NRD_PULSE for accesses to the page (t_{sa}), even if the programmed value for t_{pa} is shorter than the programmed value for t_{sa} .

23.13.2 Byte Access Type in Page Mode

The Byte Access Type configuration remains active in page mode. For 16-bit or 32-bit page mode devices that require byte selection signals, configure the BAT field of the SMC_REGISTER to 0 (byte select access type).

23.13.3 Page Mode Restriction

The page mode is not compatible with the use of the NWAIT signal. Using the page mode and the NWAIT signal may lead to unpredictable behavior.

23.13.4 Sequential and Non-sequential Accesses

If the chip select and the MSB of addresses as defined in Table 23-6 are identical, then the current access lies in the same page as the previous one, and no page break occurs.

Using this information, all data within the same page, sequential or not sequential, are accessed with a minimum access time (t_{sa}). Figure 23-35 illustrates access to an 8-bit memory device in page mode, with 8-byte pages. Access to D1 causes a page access with a long access time (t_{pa}). Accesses to D3 and D7, though they are not sequential accesses, only require a short access time (t_{sa}).

If the MSB of addresses are different, the SMC performs the access of a new page. In the same way, if the chip select is different from the previous access, a page break occurs. If two sequential accesses are made to the page mode memory, but separated by an other internal or external peripheral access, a page break occurs on the second access because the chip select of the device was deasserted between both accesses.



24.4 Product Dependencies

24.4.1 SDRAM Device Initialization

The initialization sequence is generated by software. The SDRAM devices are initialized by the following sequence:

- 1. SDRAM features must be set in the configuration register: asynchronous timings (TRC, TRAS, etc.), number of columns, rows, CAS latency, and the data bus width.
- 2. For mobile SDRAM, temperature-compensated self refresh (TCSR), drive strength (DS) and partial array self refresh (PASR) must be set in the Low Power Register.
- 3. The SDRAM memory type must be set in the Memory Device Register.
- 4. A minimum pause of 200 µs is provided to precede any signal toggle.
- 5. ⁽¹⁾A NOP command is issued to the SDRAM devices. The application must set Mode to 1 in the Mode Register and perform a write access to any SDRAM address.
- 6. An All Banks Precharge command is issued to the SDRAM devices. The application must set Mode to 2 in the Mode Register and perform a write access to any SDRAM address.
- 7. Eight auto-refresh (CBR) cycles are provided. The application must set the Mode to 4 in the Mode Register and perform a write access to any SDRAM location eight times.
- 8. A Mode Register set (MRS) cycle is issued to program the parameters of the SDRAM devices, in particular CAS latency and burst length. The application must set Mode to 3 in the Mode Register and perform a write access to the SDRAM. The write address must be chosen so that BA[1:0] are set to 0. For example, with a 16-bit 128 MB SDRAM (12 rows, 9 columns, 4 banks) bank address, the SDRAM write access should be done at the address 0x20000000.
- 9. For mobile SDRAM initialization, an Extended Mode Register set (EMRS) cycle is issued to program the SDRAM parameters (TCSR, PASR, DS). The application must set Mode to 5 in the Mode Register and perform a write access to the SDRAM. The write address must be chosen so that BA[1] or BA[0] are set to 1. For example, with a 16-bit 128 MB SDRAM, (12 rows, 9 columns, 4 banks) bank address the SDRAM write access should be done at the address 0x20800000 or 0x20400000.
- 10. The application must go into Normal Mode, setting Mode to 0 in the Mode Register and performing a write access at any location in the SDRAM.
- 11. Write the refresh rate into the count field in the SDRAMC Refresh Timer register. (Refresh rate = delay between refresh cycles). The SDRAM device requires a refresh every 15.625 μs or 7.81 μs. With a 100 MHz frequency, the Refresh Timer Counter Register must be set with the value 1562(15.652 μs x 100 MHz) or 781(7.81 μs x 100 MHz).

After initialization, the SDRAM devices are fully functional.

Note: 1. It is strongly recommended to respect the instructions stated in Step 5 of the initialization process in order to be certain that the subsequent commands issued by the SDRAMC will be taken into account.



mend to utilize either 1 ECC per 256 bytes of data, 1 ECC per 512 bytes of data or 1 ECC for all of the page.

The only configurations required for ECC are the NAND Flash or the SmartMedia page size (528/2112/4224) and the type of correction wanted (1 ECC for all the page/1 ECC per 256 bytes of data /1 ECC per 512 bytes of data). Page size is configured setting the PAGESIZE field in the ECC Mode Register (ECC_MR). Type of correction is configured setting the TYPCORRECT field in the ECC Mode Register (ECC_MR).

ECC is automatically computed as soon as a read (00h)/write (80h) command to the NAND Flash or the SmartMedia is detected. Read and write access must start at a page boundary.

ECC results are available as soon as the counter reaches the end of the main area. Values in the ECC Parity Registers (ECC_PR0 to ECC_PR15) are then valid and locked until a new start condition occurs (read/write command followed by address cycles).

25.3.1 Write Access

Once the Flash memory page is written, the computed ECC codes are available in the ECC Parity (ECC_PR0 to ECC_PR15) registers. The ECC code values must be written by the software application in the extra area used for redundancy. The number of write accesses in the extra area is a function of the value of the type of correction field. For example, for 1 ECC per 256 bytes of data for a page of 512 bytes, only the values of ECC_PR0 and ECC_PR1 must be written by the software application. Other registers are meaningless.

25.3.2 Read Access

After reading the whole data in the main area, the application must perform read accesses to the extra area where ECC code has been previously stored. Error detection is automatically performed by the ECC controller. Please note that it is mandatory to read consecutively the entire main area and the locations where Parity and NParity values have been previously stored to let the ECC controller perform error detection.

The application can check the ECC Status Registers (ECC_SR1/ECC_SR2) for any detected errors. It is up to the application to correct any detected error. ECC computation can detect four different circumstances:

- No error: XOR between the ECC computation and the ECC code stored at the end of the NAND Flash or SmartMedia page is equal to 0. No error flags in the ECC Status Registers (ECC_SR1/ECC_SR2).
- Recoverable error: Only the RECERR flags in the ECC Status registers (ECC_SR1/ECC_SR2) are set. The corrupted word offset in the read page is defined by the WORDADDR field in the ECC Parity Registers (ECC_PR0 to ECC_PR15). The corrupted bit position in the concerned word is defined in the BITADDR field in the ECC Parity Registers (ECC_PR0 to ECC_PR15).
- ECC error: The ECCERR flag in the ECC Status Registers (ECC_SR1/ECC_SR2) are set. An error has been detected in the ECC code stored in the Flash memory. The position of the corrupted bit can be found by the application performing an XOR between the Parity and the NParity contained in the ECC code stored in the Flash memory.
- Non correctable error: The MULERR flag in the ECC Status Registers (ECC_SR1/ECC_SR2) are set. Several unrecoverable errors have been detected in the Flash memory page.



 RECERR2: Recoverable Error in the page between the 512th and the 767th bytes or the 1024th and the 1535th bytes

Fixed to 0 if TYPECORREC = 0.

0 = No Errors Detected.

1 = Errors Detected. If MUL_ERROR is 0, a single correctable error was detected. Otherwise, multiple uncorrected errors were detected.

• ECCERR2: ECC Error in the page between the 512th and the 767th bytes or the 1024th and the 1535th bytes Fixed to 0 if TYPECORREC = 0.

0 = No Errors Detected.

1 = A single bit error occurred in the ECC bytes.

Read ECC Parity 2 register, the error occurred at the location which contains a 1 in the least significant 24 bits.

• MULERR2: Multiple Error in the page between the 512th and the 767th bytes or the 1024th and the 1535th bytes Fixed to 0 if TYPECORREC = 0.

0 = No Multiple Errors Detected.

1 = Multiple Errors Detected.

 RECERR3: Recoverable Error in the page between the 768th and the 1023rd bytes or the 1536th and the 2047th bytes

Fixed to 0 if TYPECORREC = 0.

0 = No Errors Detected.

1 = Errors Detected. If MUL_ERROR is 0, a single correctable error was detected. Otherwise multiple uncorrected errors were detected.

• ECCERR3: ECC Error in the page between the 768th and the 1023rd bytes or the 1536th and the 2047th bytes Fixed to 0 if TYPECORREC = 0.

0 = No Errors Detected.

1 = A single bit error occurred in the ECC bytes.

Read ECC Parity 3 register, the error occurred at the location which contains a 1 in the least significant 24 bits.

• MULERR3: Multiple Error in the page between the 768th and the 1023rd bytes or the 1536th and the 2047th bytes Fixed to 0 if TYPECORREC = 0.

0 = No Multiple Errors Detected.

1 = Multiple Errors Detected.

 RECERR4: Recoverable Error in the page between the 1024th and the 1279th bytes or the 2048th and the 2559th bytes

Fixed to 0 if TYPECORREC = 0.

0 = No Errors Detected.

1 = Errors Detected. If MUL_ERROR is 0, a single correctable error was detected. Otherwise multiple uncorrected errors were detected.

• ECCERR4: ECC Error in the page between the 1024th and the 1279th bytes or the 2048th and the 2559th bytes Fixed to 0 if TYPECORREC = 0.



26.4.5 Receive Next Pointer Register

Register Name:	PERIPF	PERIPH_RNPR					
Access Type:	Read-write						
31	30	29	28	27	26	25	24
			RXN	IPTR			
23	22	21	20	19	18	17	16
	RXNPTR						
15	14	13	12	11	10	9	8
RXNPTR							
7	6	5	4	3	2	1	0
	RXNPTR						

• RXNPTR: Receive Next Pointer

RXNPTR contains next receive buffer address.

When a half duplex peripheral is connected to the PDC, RXNPTR = TXNPTR.

26.4.6 Receive Next Counter Register

Register Name	: PERIPH	PERIPH_RNCR					
Access Type:	Read-w	Read-write					
31	30	29	28	27	26	25	24
-	-	-	-	-	-	-	-
23	22	21	20	19	18	17	16
-	-	-	-	-	-	—	-
15	14	13	12	11	10	9	8
RXNCTR							
7	6	5	4	3	2	1	0
	RXNCTR						

• RXNCTR: Receive Next Counter

RXNCTR contains next receive buffer size.

When a half duplex peripheral is connected to the PDC, RXNCTR = TXNCTR.



AT91SAM9XE128/256/512 Preliminary

30.5.2 Debug Unit Mode Register

Name: DBGU_MR

Address: 0xFFFF204

Access Type: Read-write

31	30	29	28	27	26	25	24
_	-	—	-	-	-	-	-
23	22	21	20	19	18	17	16
-	-	_	_	_	_	_	_
15	14	13	12	11	10	9	8
CHM	10DE	-	-		PAR		-
7	6	5	4	3	2	1	0
_	_	_	_	_	_	_	_

• PAR: Parity Type

PAR			Parity Type
0	0	0	Even parity
0	0	1	Odd parity
0	1	0	Space: parity forced to 0
0	1	1	Mark: parity forced to 1
1	х	х	No parity

• CHMODE: Channel Mode

CHM	IODE	Mode Description
0	0	Normal Mode
0	1	Automatic Echo
1	0	Local Loopback
1	1	Remote Loopback



33.10.1 TWI Control Register

Name: TWI_CR

Addresses: 0xFFFAC000 (0), 0xFFFD8000 (1)

Access: Write-only

Reset Value: 0x0000000

31	30	29	28	27	26	25	24
_	-	-	—	—	—	—	—
23	22	21	20	19	18	17	16
-	-	Ι	-	—	—	-	—
15	14	13	12	11	10	9	8
-	-	Ι	-	—	—	-	-
7	6	5	4	3	2	1	0
SWRST	QUICK	SVDIS	SVEN	MSDIS	MSEN	STOP	START

• START: Send a START Condition

0 = No effect.

1 = A frame beginning with a START bit is transmitted according to the features defined in the mode register.

This action is necessary when the TWI peripheral wants to read data from a slave. When configured in Master Mode with a write operation, a frame is sent as soon as the user writes a character in the Transmit Holding Register (TWI_THR).

• STOP: Send a STOP Condition

0 = No effect.

1 = STOP Condition is sent just after completing the current byte transmission in master read mode.

- In single data byte master read, the START and STOP must both be set.
- In multiple data bytes master read, the STOP must be set after the last data received but one.
- In master read mode, if a NACK bit is received, the STOP is automatically performed.
- In master data write operation, a STOP condition will be sent after the transmission of the current data is finished.

MSEN: TWI Master Mode Enabled

0 = No effect.

1 = If MSDIS = 0, the master mode is enabled.

Note: Switching from Slave to Master mode is only permitted when TXCOMP = 1.

• MSDIS: TWI Master Mode Disabled

0 = No effect.

1 = The master mode is disabled, all pending data is transmitted. The shifter and holding characters (if it contains data) are transmitted in case of write operation. In read operation, the character being transferred must be completely received before disabling.



33.10.3 TWI Slave Mode Register

Name: TWI_SMR

Addresses: 0xFFFAC008 (0), 0xFFFD8008 (1)

Access: Read-write

Reset Value: 0x0000000

31	30	29	28	27	26	25	24
-	-	-	-	-	-	—	-
23	22	21	20	19	18	17	16
-				SADR			
15	14	13	12	11	10	9	8
-	-	-	-	-	-		
7	6	5	4	3	2	1	0
_	_	_	—	_	—	_	—

• SADR: Slave Address

The slave device address is used in Slave mode in order to be accessed by master devices in read or write mode.

SADR must be programmed before enabling the Slave mode or after a general call. Writes at other times have no effect.

35.8.13 SSC Name:	Status Regist SSC_SI	er R					
Address:	0xFFFB	C040					
Access Type:	Read-or	nly					
31	30	29	28	27	26	25	24
-	-	-	-	—	-	-	-
23	22	21	20	19	18	17	16
-	Ι	-	-	-	-	RXEN	TXEN
15	14	13	12	11	10	9	8
-	Ι	-	-	RXSYN	TXSYN	CP1	CP0
7	6	5	4	3	2		0
HXBUFF	ENDRX	OVRUN	KXRDY	IXBUFE	ENDIX	IXEMPTY	TXRDY

• TXRDY: Transmit Ready

0 = Data has been loaded in SSC_THR and is waiting to be loaded in the Transmit Shift Register (TSR).

1 = SSC_THR is empty.

• TXEMPTY: Transmit Empty

0 = Data remains in SSC_THR or is currently transmitted from TSR.

1 = Last data written in SSC_THR has been loaded in TSR and last data loaded in TSR has been transmitted.

• ENDTX: End of Transmission

0 = The register SSC_TCR has not reached 0 since the last write in SSC_TCR or SSC_TNCR.

1 = The register SSC_TCR has reached 0 since the last write in SSC_TCR or SSC_TNCR.

• TXBUFE: Transmit Buffer Empty

0 = SSC_TCR or SSC_TNCR have a value other than 0.

1 = Both SSC_TCR and SSC_TNCR have a value of 0.

• RXRDY: Receive Ready

 $0 = SSC_RHR$ is empty.

1 = Data has been received and loaded in SSC_RHR.

OVRUN: Receive Overrun

0 = No data has been loaded in SSC_RHR while previous data has not been read since the last read of the Status Register.

1 = Data has been loaded in SSC_RHR while previous data has not yet been read since the last read of the Status Register.

• ENDRX: End of Reception

0 = Data is written on the Receive Counter Register or Receive Next Counter Register.

1 = End of PDC transfer when Receive Counter Register has arrived at zero.





39.6.6 UDP Interrupt Mask Register

Register Name	: UDP_IN	1R					
Address:	0xFFFA	4018					
Access Type:	Read-	only					
31	30	29	28	27	26	25	24
-	_	-	-	—	—	_	-
23	22	21	20	19	18	17	. 16
-	-	-	-	-	-	-	-
15	14	13	12	11	10	9	. 8
-	Ι	WAKEUP	BIT12	SOFINT	EXTRSM	RXRSM	RXSUSP
7	6	5	4	3	2	1	0
		EP5INT	EP4INT	EP3INT	EP2INT	EP1INT	EPOINT

- EP0INT: Mask Endpoint 0 Interrupt
- EP1INT: Mask Endpoint 1 Interrupt
- EP2INT: Mask Endpoint 2 Interrupt
- EP3INT: Mask Endpoint 3 Interrupt
- EP4INT: Mask Endpoint 4 Interrupt
- EP5INT: Mask Endpoint 5 Interrupt
- 0 = Corresponding Endpoint Interrupt is disabled.
- 1 = Corresponding Endpoint Interrupt is enabled.

• RXSUSP: Mask UDP Suspend Interrupt

- 0 = UDP Suspend Interrupt is disabled.
- 1 = UDP Suspend Interrupt is enabled.

• RXRSM: Mask UDP Resume Interrupt.

0 = UDP Resume Interrupt is disabled.

1 = UDP Resume Interrupt is enabled.

• EXTRSM: Mask External Resume Interrupt

- 0 = UDP External Resume Interrupt is disabled.
- 1 = UDP External Resume Interrupt is enabled.

• SOFINT: Mask Start Of Frame Interrupt

- 0 = Start of Frame Interrupt is disabled.
- 1 = Start of Frame Interrupt is enabled.

• BIT12: UDP_IMR Bit 12

Bit 12 of UDP_IMR cannot be masked and is always read at 1.

42.6.4 ADC Channel Disable Register

Register Name	e: ADC_CI	HDR					
Address:	0xFFFE	0014					
Access Type:	Write-or	nly					
31	30	29	28	27	26	25	24
—	-	-	-	-	—	-	—
23	22	21	20	19	18	17	16
—	-	-	-	-	—	-	-
15	14	13	12	11	10	9	8
—	-	-	-	-	—	-	-
7	6	5	4	3	2	1	0
_	_	—	—	CH3	CH2	CH1	CH0

• CHx: Channel x Disable

0 = No effect.

1 = Disables the corresponding channel.

Warning: If the corresponding channel is disabled during a conversion or if it is disabled then reenabled during a conversion, its associated data and its corresponding EOC and OVRE flags in ADC_SR are unpredictable.





Table 43-30. SMC Write Signals - NWE Controlled (Write_Mode = 1) (Continued)

		М	in	Мах				
Symbol	Parameter	1.8V Supply	3.3V Supply	1.8V Supply	3.3V Supply	Units		
	ŀ	IOLD SETTINGS (I	nwe hold …0)					
SMC ₁₉	NWE High to Data OUT, NBS0/A0 NBS1, NBS2/A1, NBS3, A2 - A25 change	nwe hold * t _{CPMCK} -2.8	nwe hold * t _{CPMCK} -5.6			ns		
SMC ₂₀	NWE High to NCS Inactive ⁽¹⁾	(nwe hold - ncs wr hold)* t _{CPMCK} -1.4	(nwe hold - ncs wr hold)* t _{CPMCK} -1.4			ns		
NO HOLD SETTINGS (nwe hold = 0)								
SMC ₂₁	NWE High to Data OUT, NBS0/A0 NBS1, NBS2/A1, NBS3, A2 - A25, NCS change ⁽¹⁾	3.3	3.2			ns		

Note: 1. hold length = total cycle duration - setup duration - pulse duration. "hold length" is for "ncs wr hold length" or "NWE hold length".

		M	lin	М		
Symbol	Parameter	1.8V Supply	3.3V Supply	1.8V Supply	3.3V Supply	Units
SMC ₂₂	Data Out Valid before NCS High	ncs wr pulse * t _{CPMCK} -1.2	ncs wr pulse * t _{CPMCK} -5.8			ns
SMC ₂₃	NCS Pulse Width	ncs wr pulse * t _{CPMCK} -1.13	ncs wr pulse * t _{CPMCK} -1.12			ns
SMC ₂₄	NBS0/A0 NBS1, NBS2/A1, NBS3, A2 - A25 valid before NCS low	ncs wr setup * t _{CPMCK} -1.7	ncs wr setup * t _{CPMCK} -3.0			ns
SMC ₂₅	NWE low before NCS high	(ncs wr setup - nwe setup + ncs pulse)* t _{CPMCK} -1.13	(ncs wr setup - nwe setup + ncs pulse)* t _{CPMCK} -1.12			ns
SMC ₂₆	NCS High to Data Out, NBS0/A0, NBS1, NBS2/A1, NBS3, A2 - A25, change	ncs wr hold * t _{CPMCK} -3.3	ncs wr hold * t _{CPMCK} -3.4			ns
SMC ₂₇	NCS High to NWE Inactive	(ncs wr hold - nwe hold)* t _{CPMCK} -0.91	(ncs wr hold - nwe hold)* t _{CPMCK} -0.88			ns

Table 43-31. SMC Write NCS Controlled (WRITE_MODE=0)

Consequence: After the failure condition, the Host controller stops sending the SOF. This causes the connected device to go into suspend state.

Problem Fix/Workaround

This problem can be avoided if the system can guarantee that no buffer underrun occurs during the transfer.

46.2.9.3 UHP: Remote Wakeup Event

Conditions:

When a Remote Wakeup event occurs on a downstream port, the OHCI Host controller begins sending resume signaling to the device. The Host controller is supposed to send this resume signaling for 20 ms. However, if the driver sets the HcControl, HCFS into USBOPERATIONAL state during the resume event, then the Host controller terminates sending the resume signal with an EOP to the device.

Consequence: If the Device does not recognize the resume (<20 ms) event, then the Device will remain in suspend state.

Problem Fix/Workaround

Host stack can do a port resume after it sets the HcControl, HCFS to USBOPERATIONAL.

46.2.10 Universal Synchronous Asycnchronous Receiver Transmitter (USART)

46.2.10.1 USART: Slave Synchronous Mode

Limitation on synchronous mode external clock is MCK/9.

Problem Fix/Workaround

None.

46.2.10.2 USART: Number of Errors Register (US_NER) ISO7816 error number

The Number of Errors Register always returns 0 instead of the ISO7816 error number.

It is not part of the ISO7816 protocol.

Problem Fix/Workaround

None.

