

Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Product Status	Obsolete
Core Processor	80C51
Core Size	8-Bit
Speed	40/20MHz
Connectivity	UART/USART
Peripherals	POR, PWM, WDT
Number of I/O	32
Program Memory Size	-
Program Memory Type	ROMIess
EEPROM Size	-
RAM Size	768 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	44-QFP
Supplier Device Package	44-VQFP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/ts80c51rd2-mce

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



4. SFR Mapping

The Special Function Registers (SFRs) of the TS80C51Rx2 fall into the following categories:

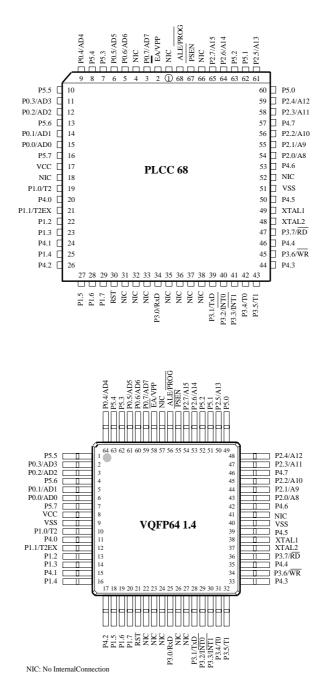
- C51 core registers: ACC, B, DPH, DPL, PSW, SP, AUXR1
- I/O port registers: P0, P1, P2, P3, P4, P5
- Timer registers: T2CON, T2MOD, TCON, TH0, TH1, TH2, TMOD, TL0, TL1, TL2, RCAP2L, RCAP2H
- Serial I/O port registers: SADDR, SADEN, SBUF, SCON
- Power and clock control registers: PCON
- HDW Watchdog Timer Reset: WDTRST, WDTPRG
- PCA registers: CL, CH, CCAPiL, CCAPiH, CCON, CMOD, CCAPMi
- Interrupt system registers: IE, IP, IPH
- Others: AUXR, CKCON

Table 1. All SFRs with their address and their reset value

	Bit addressable		Non Bit addressable										
	0/8	1/9	2/A	3/B	4/C	5/D	6/E	7/F					
F8h		CH 0000 0000	CCAP0H XXXX XXXX	CCAP1H XXXX XXXX	CCAPL2H XXXX XXXX	CCAPL3H XXXX XXXX	CCAPL4H XXXX XXXX		FFh				
F0h	B 0000 0000								F7h				
E8h	P5 bit addressable 1111 1111	CL 0000 0000	CCAP0L XXXX XXXX	CCAP1L XXXX XXXX	CCAPL2L XXXX XXXX	CCAPL3L XXXX XXXX	CCAPL4L XXXX XXXX		EFh				
E0h	ACC 0000 0000								E7h				
D8h	CCON 00X0 0000	CMOD 00XX X000	CCAPM0 X000 0000	CCAPM1 X000 0000	CCAPM2 X000 0000	CCAPM3 X000 0000	CCAPM4 X000 0000		DFh				
D0h	PSW 0000 0000								D7h				
C8h	T2CON 0000 0000	T2MOD XXXX XX00	RCAP2L 0000 0000	RCAP2H 0000 0000	TL2 0000 0000	TH2 0000 0000			CFh				
C0h	P4 bit addressable 1111 1111							P5 byte addressable 1111 1111	C7h				
B8h	IP X000 000	SADEN 0000 0000							BFh				
B0h	P3 1111 1111							IPH X000 0000	B7h				
A8h	IE 0000 0000	SADDR 0000 0000							AFh				
A0h	P2 1111 1111		AUXR1 XXXX0XX0				WDTRST XXXX XXXX	WDTPRG XXXX X000	A7h				
98h	SCON 0000 0000	SBUF XXXX XXXX							9Fh				
90h	P1 1111 1111								97h				
88h	TCON 0000 0000	TMOD 0000 0000	TL0 0000 0000	TL1 0000 0000	TH0 0000 0000	TH1 0000 0000	AUXR XXXXXX00	CKCON XXXX XXX0	8Fh				
80h	P0 1111 1111	SP 0000 0111	DPL 0000 0000	DPH 0000 0000				PCON 00X1 0000	87h				
	0/8	1/9	2/A	3/B	4/C	5/D	6/E	7/F					
	macaminad												

reserved







5.1. Pin Description for 64/68 pin Packages

Port 4 and Port 5 are 8-bit bidirectional I/O ports with internal pull-ups. Pins that have 1 written to them are pulled high by the internal pull ups and can be used as inputs.

As inputs, pins that are externally pulled low will source current because of the internal pull-ups.

Refer to the previous pin description for other pins.

	PLCC68	SQUARE VQFP64 1.4
VSS	51	9/40
VCC	17	8
P0.0	15	6
P0.1	14	5
P0.2	12	3
P0.3	11	2
P0.4	9	64
P0.5	6	61
P0.6	5	60
P0.7	3	59
P1.0	19	10
P1.1	21	12
P1.2	22	13
P1.3	23	14
P1.4	25	16
P1.5	27	18
P1.6	28	19
P1.7	29	20
P2.0	54	43
P2.1	55	44
P2.2	56	45
P2.3	58	47
P2.4	59	48
P2.5	61	50
P2.6	64	53
P2.7	65	54
P3.0	34	25
P3.1	39	28



	PLCC68	SQUARE VQFP64 1.4
P3.2	40	29
P3.3	41	30
P3.4	42	31
P3.5	43	32
P3.6	45	34
P3.7	47	36
RESET	30	21
ALE/PROG	68	56
PSEN	67	55
EA/VPP	2	58
XTAL1	49	38
XTAL2	48	37
P4.0	20	11
P4.1	24	15
P4.2	26	17
P4.3	44	33
P4.4	46	35
P4.5	50	39
P4.6	53	42
P4.7	57	46
P5.0	60	49
P5.1	62	51
P5.2	63	52
P5.3	7	62
P5.4	8	63
P5.5	10	1
P5.6	13	4
P5.7	16	7



Table 3. CKCON Register

CKCON - Clock Control Register (8Fh)

7	6	5	4	3	2	1	0
-	-	-	-	-	-	-	X2

Bit Number	Bit Mnemonic	Description
7	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
6	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
5	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
4	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
3	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
2	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
1	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
0	X2	CPU and peripheral clock bit Clear to select 12 clock periods per machine cycle (STD mode, $F_{OSC}=F_{XTAL}/2$). Set to select 6 clock periods per machine cycle (X2 mode, $F_{OSC}=F_{XTAL}$).

Reset Value = XXXX XXX0b Not bit addressable

For further details on the X2 feature, please refer to ANM072 available on the web (http://www.atmel-wm.com)



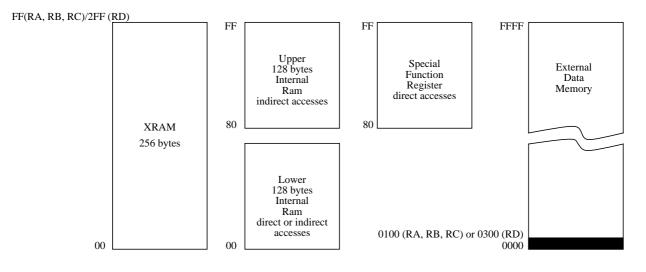


Figure 4. Internal and External Data Memory Address

Ad	AUXR Idress 08EH		-	-	-	-	-	-	EXTRA M	AO	
	Reset	value	Х	Х	Х	X	Х	Х	0	0	
	Symbol					Function	1				
	-	Not imple	mented, 1	eserved fo	or future u	se. ^a					
	AO	Disable/Enable ALE									
		AO	Ope	erating M	ode						
		0		E is emitte mode is u		istant rate	of 1/6 the	oscillator	frequency (o	r 1/3 if	
		1	ALI	E is active	only duri	ng a MOV	X or MO	VC instruc	tion		
	EXTRAM	Internal/E:	xternal R.	AM (00H-	FFH) acce	ess using N	AOVX @	Ri/@DP	TR		
		EXTRA	M Ope	Operating Mode							
		0	Inte	rnal XRA	M access 1	using MOV	/X @ Ri/	@ DPTR			
		1	Exte	External data memory access							

 Table 5. Auxiliary Register AUXR

a. User software should not write 1s to reserved bits. These bits may be used in future 8051 family products to invoke new features. In that case, the reset or inactive value of the new bit will be 0, and its active value will be 1. The value read from a reserved bit is indeterminate.



6.4. Timer 2

The timer 2 in the TS80C51RX2 is compatible with the timer 2 in the 80C52.

It is a 16-bit timer/counter: the count is maintained by two eight-bit timer registers, TH2 and TL2, connected in cascade. It is controlled by T2CON register (See Table 6) and T2MOD register (See Table 7). Timer 2 operation is similar to Timer 0 and Timer 1. C/T2 selects $F_{OSC}/12$ (timer operation) or external pin T2 (counter operation) as the timer clock input. Setting TR2 allows TL2 to be incremented by the selected input.

Timer 2 has 3 operating modes: capture, autoreload and Baud Rate Generator. These modes are selected by the combination of RCLK, TCLK and $CP/\overline{RL2}$ (T2CON), as described in the Atmel Wireless & Microcontrollers 8-bit Microcontroller Hardware description.

Refer to the Atmel Wireless & Microcontrollers 8-bit Microcontroller Hardware description for the description of Capture and Baud Rate Generator Modes.

In TS80C51RX2 Timer 2 includes the following enhancements:

- Auto-reload mode with up or down counter
- Programmable clock-output

6.4.1. Auto-Reload Mode

The auto-reload mode configures timer 2 as a 16-bit timer or event counter with automatic reload. If DCEN bit in T2MOD is cleared, timer 2 behaves as in 80C52 (refer to the Atmel Wireless & Microcontrollers 8-bit Microcontroller Hardware description). If DCEN bit is set, timer 2 acts as an Up/down timer/counter as shown in Figure 5. In this mode the T2EX pin controls the direction of count.

When T2EX is high, timer 2 counts up. Timer overflow occurs at FFFFh which sets the TF2 flag and generates an interrupt request. The overflow also causes the 16-bit value in RCAP2H and RCAP2L registers to be loaded into the timer registers TH2 and TL2.

When T2EX is low, timer 2 counts down. Timer underflow occurs when the count in the timer registers TH2 and TL2 equals the value stored in RCAP2H and RCAP2L registers. The underflow sets TF2 flag and reloads FFFFh into the timer registers.

The EXF2 bit toggles when timer 2 overflows or underflows according to the direction of the count. EXF2 does not generate any interrupt. This bit can be used to provide 17-bit resolution.



6.5.3. High Speed Output Mode

In this mode the CEX output (on port 1) associated with the PCA module will toggle each time a match occurs between the PCA counter and the module's capture registers. To activate this mode the TOG, MAT, and ECOM bits in the module's CCAPMn SFR must be set (See Figure 11).

A prior write must be done to CCAPnL and CCAPnH before writing the ECOMn bit.

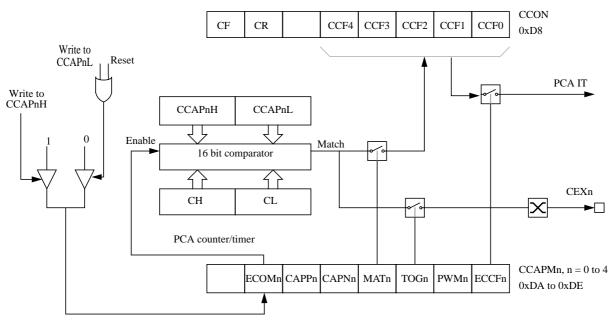


Figure 11. PCA High Speed Output Mode

Before enabling ECOM bit, CCAPnL and CCAPnH should be set with a non zero value, otherwise an unwanted match could happen.

Once ECOM set, writing CCAPnL will clear ECOM so that an unwanted match doesn't occur while modifying the compare value. Writing to CCAPnH will set ECOM. For this reason, user software should write CCAPnL first, and then CCAPnH. Of course, the ECOM bit can still be controlled by accessing to CCAPMn register.



6.5.4. Pulse Width Modulator Mode

All of the PCA modules can be used as PWM outputs. Figure 12 shows the PWM function. The frequency of the output depends on the source for the PCA timer. All of the modules will have the same frequency of output because they all share the PCA timer. The duty cycle of each module is independently variable using the module's capture register CCAPLn. When the value of the PCA CL SFR is less than the value in the module's CCAPLn SFR the output will be low, when it is equal to or greater than the output will be high. When CL overflows from FF to 00, CCAPLn is reloaded with the value in CCAPHn. This allows updating the PWM without glitches. The PWM and ECOM bits in the module's CCAPMn register must be set to enable the PWM mode.

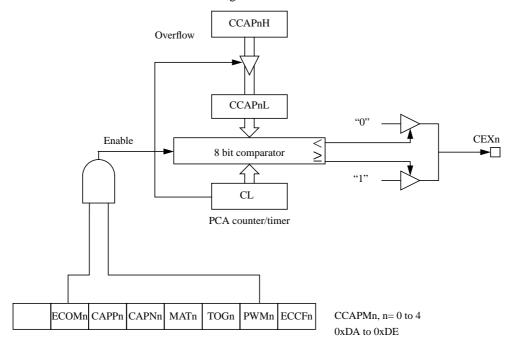


Figure 12. PCA PWM Mode

6.5.5. PCA Watchdog Timer

An on-board watchdog timer is available with the PCA to improve the reliability of the system without increasing chip count. Watchdog timers are useful for systems that are susceptible to noise, power glitches, or electrostatic discharge. Module 4 is the only PCA module that can be programmed as a watchdog. However, this module can still be used for other modes if the watchdog is not needed. Figure 10 shows a diagram of how the watchdog works. The user pre-loads a 16-bit value in the compare registers. Just like the other compare modes, this 16-bit value is compared to the PCA timer value. If a match is allowed to occur, an internal reset will be generated. This will not cause the RST pin to be driven high.

In order to hold off the reset, the user has three options:

- 1. periodically change the compare value so it will never match the PCA timer,
- 2. periodically change the PCA timer value so it will never match the compare values, or
- 3. disable the watchdog by clearing the WDTE bit before a match occurs and then re-enable it.

The first two options are more reliable because the watchdog timer is never disabled as in option #3. If the program counter ever goes astray, a match will eventually occur and cause an internal reset. The second option is also not recommended if other PCA modules are being used. Remember, the PCA timer is the time base for all modules; changing the time base for other modules would not be a good idea. Thus, in most applications the first solution is the best option.

This watchdog timer won't generate a reset out on the reset pin.



6.6.5. Reset Addresses

On reset, the SADDR and SADEN registers are initialized to 00h, i.e. the given and broadcast addresses are XXXX (all don't-care bits). This ensures that the serial port will reply to any address, and so, that it is backwards compatible with the 80C51 microcontrollers that do not support automatic address recognition.

SADEN - Slave Address Mask Register (B9h)

7	6	5	4	3	2	1	0

Reset Value = 0000 0000b Not bit addressable

SADDR - Slave Address Register (A9h)

7	6	5	4	3	2	1	0

Reset Value = 0000 0000b Not bit addressable



Table 16. SCON Register

SCON - Serial Control Register (98h)

7	6	5		4	3	2	1	0			
FE/SM0	SM1	SN	SM2 REN TB8 RB8 TI								
Bit Number	Bit Mnemonic				Descrip	tion	-	·			
7	FE	Set by h	reset the ardware v	error state, not cle	eared by a valid sto op bit is detected. ss to the FE bit	p bit.					
	SM0	Refer to	rial port Mode bit 0 Refer to SM1 for serial port mode selection. SMOD0 must be cleared to enable access to the SM0 bit								
		Serial port I <u>SM0</u>	Mode bit <u>SM1</u>		Descripti	on Baud Rate	2				
6	SM1	0 0 1 1	0 1 0 1	0 1 2 3	Shift Reg 8-bit UAI 9-bit UAI 9-bit UAI	RT Variable RT F _{XTAL} /6	4 or F _{XTAL} /32 (/32				
5	SM2	Clear to Set to en	disable n	nultiprocessor cor tiprocessor comm	cessor Communic nmunication featur unication feature ir	e.	l eventually mode	1. This bit should			
4	REN		disable s	t erial reception. al reception.							
3	TB8	Clear to	transmit	a logic 0 in the 9t		d 3.					
2	RB8	Cleared Set by h	Set to transmit a logic 1 in the 9th bit. Receiver Bit 8 / Ninth bit received in modes 2 and 3 Cleared by hardware if 9th bit received is a logic 0. Set by hardware if 9th bit received is a logic 1. In mode 1, if SM2 = 0, RB8 is the received stop bit. In mode 0 RB8 is not used.								
1	TI		acknowle	edge interrupt.	th bit time in mode	0 or at the beginn	ing of the stop bit	in the other			
0	RI		acknowle	edge interrupt.	th bit time in mode	0, see Figure 14.	and Figure 15. in	the other modes.			

Reset Value = 0000 0000b Bit addressable



Table 17. PCON Register

PCON - Power Control Register (87h)

7	6	5	4		3	2	1	0			
SMOD1	SMOD) -	POI	F	GF1	GF0	PD	IDL			
Bit Number	Bit Mnemonic	Description									
7	SMOD1	Serial port Mo Set to sele	de bit 1 ct double baud ra	te in m	ode 1, 2 or 3.						
6	SMOD0		de bit 0 ect SM0 bit in S0 lect FE bit in SC0								
5	-	Reserved The value	ead from this bit	is inde	terminate. Do not	set this bit.					
4	POF		cognize next reset		rom 0 to its nomin	al voltage. Can also	o be set by softwar	re.			
3	GF1		se Flag user for general j for general purp								
2	GF0		se Flag user for general j for general purp								
1	PD	Cleared by	Power-Down mode bit Cleared by hardware when reset occurs. Set to enter power-down mode.								
0	IDL		Idle mode bit Clear by hardware when interrupt or reset occurs. Set to enter idle mode.								

Reset Value = 00X1 0000b Not bit addressable

Power-off flag reset value will be 1 only after a power on (cold reset). A warm reset doesn't affect the value of this bit.



Table 18. Priority Level Bit Values

IPH.x	IP.x	Interrupt Level Priority
0	0	0 (Lowest)
0	1	1
1	0	2
1	1	3 (Highest)

A low-priority interrupt can be interrupted by a high priority interrupt, but not by another low-priority interrupt. A high-priority interrupt can't be interrupted by any other interrupt source.

If two interrupt requests of different priority levels are received simultaneously, the request of higher priority level is serviced. If interrupt requests of the same priority level are received simultaneously, an internal polling sequence determines which request is serviced. Thus within each priority level there is a second priority structure determined by the polling sequence.

Table 19. IE Register

IE - Interrupt Enable Register (A8h)

	7	6	5	4	3	2	1	0
E	ĊA	EC	ET2	ES	ET1	EX1	ЕТО	EX0

Bit Number	Bit Mnemonic	Description
7	EA	Enable All interrupt bit Clear to disable all interrupts. Set to enable all interrupts. If EA=1, each interrupt source is individually enabled or disabled by setting or clearing its own interrupt enable bit.
6	EC	PCA interrupt enable bit Clear to disable . Set to enable.
5	ET2	Timer 2 overflow interrupt Enable bit Clear to disable timer 2 overflow interrupt. Set to enable timer 2 overflow interrupt.
4	ES	Serial port Enable bit Clear to disable serial port interrupt. Set to enable serial port interrupt.
3	ET1	Timer 1 overflow interrupt Enable bit Clear to disable timer 1 overflow interrupt. Set to enable timer 1 overflow interrupt.
2	EX1	External interrupt 1 Enable bit Clear to disable external interrupt 1. Set to enable external interrupt 1.
1	ET0	Timer 0 overflow interrupt Enable bit Clear to disable timer 0 overflow interrupt. Set to enable timer 0 overflow interrupt.
0	EX0	External interrupt 0 Enable bit Clear to disable external interrupt 0. Set to enable external interrupt 0.

Reset Value = 0000 0000b Bit addressable



6.12. Power-Off Flag

The power-off flag allows the user to distinguish between a "cold start" reset and a "warm start" reset.

A cold start reset is the one induced by V_{CC} switch-on. A warm start reset occurs while V_{CC} is still applied to the device and could be generated for example by an exit from power-down.

The power-off flag (POF) is located in PCON register (See Table 26.). POF is set by hardware when V_{CC} rises from 0 to its nominal voltage. The POF can be set or cleared by software allowing the user to determine the type of reset.

The POF value is only relevant with a Vcc range from 4.5V to 5.5V. For lower Vcc value, reading POF bit will return indeterminate value.

Table 26. PCON Register

PCON - Power Control Register (87h)

7	6	5 4 3 2				1	0	
SMOD1	SMOD0	-	POF	GF1	GF0	PD	IDL	
Bit Number	Bit Mnemonic			Descrip	tion			
7	SMOD1	Serial port Mode bi Set to select dou	t 1 ble baud rate in m	ode 1, 2 or 3.				
6	SMOD0	Clear to select S	Serial port Mode bit 0 Clear to select SM0 bit in SCON register. Set to to select FE bit in SCON register.					
5	-	Reserved The value read fr	Reserved The value read from this bit is indeterminate. Do not set this bit.					
4	POF	Power-Off Flag Clear to recogniz Set by hardware	Power-Off Flag Clear to recognize next reset type. Set by hardware when V _{CC} rises from 0 to its nominal voltage. Can also be set by software.					
3	GF1	Cleared by user	General purpose Flag Cleared by user for general purpose usage. Set by user for general purpose usage.					
2	GF0	Cleared by user	General purpose Flag Cleared by user for general purpose usage. Set by user for general purpose usage.					
1	PD	Cleared by hardy	Power-Down mode bit Cleared by hardware when reset occurs. Set to enter power-down mode.					
0	IDL	Idle mode bit Clear by hardwa Set to enter idle	Idle mode bit Clear by hardware when interrupt or reset occurs. Set to enter idle mode.					

Reset Value = 00X1 0000b Not bit addressable



Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
I _{CC} operating	Power Supply Current Maximum values, X1 mode: ⁽⁷⁾			3 + 0.6 Freq (MHz) @12MHz 10.2 @16MHz 12.6	mA	$V_{CC} = 5.5 V^{(8)}$
I _{CC} idle	Power Supply Current Maximum values, X1 mode: ⁽⁷⁾			0.25+0.3Freq (MHz) @12MHz 3.9 @16MHz 5.1	mA	$V_{CC} = 5.5 V^{(2)}$

10.4. DC Parameters for Low Voltage

TA = 0°C to +70°C; V_{SS} = 0 V; V_{CC} = 2.7 V to 5.5 V \pm 10%; F = 0 to 30 MHz. TA = -40°C to +85°C; V_{SS} = 0 V; V_{CC} = 2.7 V to 5.5 V \pm 10%; F = 0 to 30 MHz.

Table 33.	DC Parameters	for Low	Voltage
-----------	----------------------	---------	---------

Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
V _{IL}	Input Low Voltage	-0.5		0.2 V _{CC} - 0.1	v	
V _{IH}	Input High Voltage except XTAL1, RST	0.2 V _{CC} + 0.9		V _{CC} + 0.5	v	
V _{IH1}	Input High Voltage, XTAL1, RST	0.7 V _{CC}		V _{CC} + 0.5	V	
V _{OL}	Output Low Voltage, ports 1, 2, 3, 4, 5 ⁽⁶⁾			0.45	V	$I_{OL} = 0.8 \text{ mA}^{(4)}$
V _{OL1}	Output Low Voltage, port 0, ALE, PSEN (6)			0.45	v	$I_{OL} = 1.6 \text{ mA}^{(4)}$
V _{OH}	Output High Voltage, ports 1, 2, 3, 4, 5	0.9 V _{CC}			V	$I_{OH} = -10 \ \mu A$
V _{OH1}	Output High Voltage, port 0, ALE, PSEN	0.9 V _{CC}			V	$I_{OH} = -40 \ \mu A$
I _{IL}	Logical 0 Input Current ports 1, 2, 3, 4, 5			-50	μΑ	Vin = 0.45 V
I _{LI}	Input Leakage Current			±10	μΑ	0.45 V < Vin < V _{CC}
I _{TL}	Logical 1 to 0 Transition Current, ports 1, 2, 3, 4, 5			-650	μΑ	Vin = 2.0 V
R _{RST}	RST Pulldown Resistor	50	90 ⁽⁵⁾	200	kΩ	
CIO	Capacitance of I/O Buffer			10	pF	$Fc = 1 MHz$ $TA = 25^{\circ}C$
I _{PD}	Power Down Current		20 ⁽⁵⁾ 10 ⁽⁵⁾	50 30	μΑ	$V_{CC} = 2.0 \text{ V to } 5.5 \text{ V}^{(3)}$ $V_{CC} = 2.0 \text{ V to } 3.3 \text{ V}^{(3)}$
I _{CC} under RESET	Power Supply Current Maximum values, X1 mode: ⁽⁷⁾			1 + 0.2 Freq (MHz) @12MHz 3.4 @16MHz 4.2	mA	$V_{\rm CC} = 3.3 \ V^{(1)}$
I _{CC} operating	Power Supply Current Maximum values, X1 mode: ⁽⁷⁾			1 + 0.3 Freq (MHz) @12MHz 4.6 @16MHz 5.8	mA	$V_{\rm CC} = 3.3 \ V^{(8)}$



10.5. AC Parameters

10.5.1. Explanation of the AC Symbols

Each timing symbol has 5 characters. The first character is always a "T" (stands for time). The other characters, depending on their positions, stand for the name of a signal or the logical status of that signal. The following is a list of all the characters and what they stand for.

Example: T_{AVLL} = Time for Address Valid to ALE Low. T_{LLPL} = Time for ALE Low to PSEN Low.

TA = 0 to +70°C (commercial temperature range); $V_{SS} = 0$ V; $V_{CC} = 5$ V ± 10%; -M and -V ranges. TA = -40°C to +85°C (industrial temperature range); $V_{SS} = 0$ V; $V_{CC} = 5$ V ± 10%; -M and -V ranges. TA = 0 to +70°C (commercial temperature range); $V_{SS} = 0$ V; 2.7 V < $V_{CC} < 5.5$ V; -L range. TA = -40°C to +85°C (industrial temperature range); $V_{SS} = 0$ V; 2.7 V < $V_{CC} < 5.5$ V; -L range.

Table 34. gives the maximum applicable load capacitance for Port 0, Port 1, 2 and 3, and ALE and $\overline{\text{PSEN}}$ signals. Timings will be guaranteed if these capacitances are respected. Higher capacitance values can be used, but timings will then be degraded.

	-M	-V	-L
Port 0	100	50	100
Port 1, 2, 3	80	50	80
ALE / PSEN	100	30	100

Table 34	. Load	Capacitance	versus	speed	range.	in	рF
		Capacitanee		peed			r-

Table 36., Table 39. and Table 42. give the description of each AC symbols.

Table 37., Table 40. and Table 43. give for each range the AC parameter.

Table 38., Table 41. and Table 44. give the frequency derating formula of the AC parameter. To calculate each AC symbols, take the x value corresponding to the speed grade you need (-M, -V or -L) and replace this value in the formula. Values of the frequency must be limited to the corresponding speed grade:

Table 35. Max frequency for derating formula regarding the speed grade

	-M X1 mode	-M X2 mode	-V X1 mode	-V X2 mode	-L X1 mode	-L X2 mode
Freq (MHz)	40	20	40	30	30	20
T (ns)	25	50	25	33.3	33.3	50

Example:

 T_{LLIV} in X2 mode for a -V part at 20 MHz (T = $1/20^{E6}$ = 50 ns):

x= 22 (Table 38.)

T=50ns

 T_{LLIV} = 2T - x = 2 x 50 - 22 = 78ns



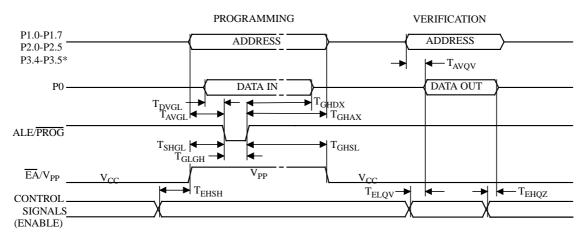
10.5.9. EPROM Programming and Verification Characteristics

TA = 21°C to 27°C; $V_{SS} = 0V$; $V_{CC} = 5V \pm 10\%$ while programming. V_{CC} = operating range while verifying

Symbol	Parameter	Min	Max	Units
V _{PP}	Programming Supply Voltage	12.5	13	v
I _{PP}	Programming Supply Current		75	mA
1/T _{CLCL}	Oscillator Frquency	4	6	MHz
T _{AVGL}	Address Setup to PROG Low	48 T _{CLCL}		
T _{GHAX}	Adress Hold after PROG	48 T _{CLCL}		
T _{DVGL}	Data Setup to PROG Low	48 T _{CLCL}		
T _{GHDX}	Data Hold after PROG	48 T _{CLCL}		
T _{EHSH}	(Enable) High to V _{PP}	48 T _{CLCL}		
T _{SHGL}	V _{PP} Setup to PROG Low	10		μs
T _{GHSL}	V _{PP} Hold after PROG	10		μs
T _{GLGH}	PROG Width	90	110	μs
T _{AVQV}	Address to Valid Data		48 T _{CLCL}	
T _{ELQV}	ENABLE Low to Data Valid		48 T _{CLCL}	
T _{EHQZ}	Data Float after ENABLE	0	48 T _{CLCL}	1

Table 45. EPROM Programming Parameters

10.5.10. EPROM Programming and Verification Waveforms



* 8KB: up to P2.4, 16KB: up to P2.5, 32KB: up to P3.4, 64KB: up to P3.5

Figure 29. EPROM Programming and Verification Waveforms



10.5.11. External Clock Drive Characteristics (XTAL1)

Table	46.	AC	Parameters
-------	-----	----	------------

Symbol	Parameter	Min	Max	Units
T _{CLCL}	Oscillator Period	25		ns
T _{CHCX}	High Time	5		ns
T _{CLCX}	Low Time	5		ns
T _{CLCH}	Rise Time		5	ns
T _{CHCL}	Fall Time		5	ns
T _{CHCX} /T _{CLCX}	Cyclic ratio in X2 mode	40	60	%

10.5.12. External Clock Drive Waveforms

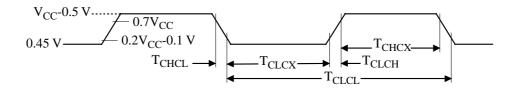


Figure 30. External Clock Drive Waveforms

10.5.13. AC Testing Input/Output Waveforms

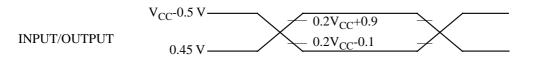


Figure 31. AC Testing Input/Output Waveforms

AC inputs during testing are driven at V_{CC} - 0.5 for a logic "1" and 0.45V for a logic "0". Timing measurement are made at V_{IH} min for a logic "1" and V_{IL} max for a logic "0".

10.5.14. Float Waveforms

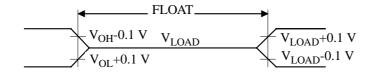
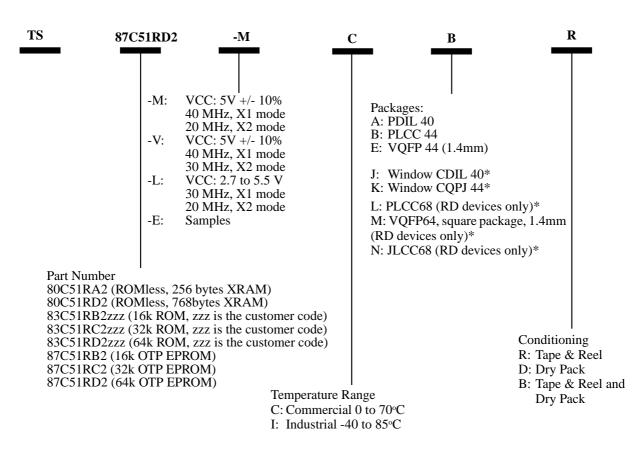


Figure 32. Float Waveforms



11. Ordering Information



(*) Check with Atmel Wireless & Microcontrollers Sales Office for availability. Ceramic packages (J, K, N) are available for proto typing, not for volume production. Ceramic packages are available for OTP only.

Code	-M	-V	-L	Unit
Standard Mode, oscillator frequency	40	40	30	MHz
Standard Mode, internal frequency	40	40	30	
X2 Mode, oscillator frequency	20	30	20	MHz
X2 Mode, internal equivalent frequency	40	60	40	



	TS80C51RA2/RD2 ROMless	TS83C51RB2/RC2/RD2zzz ROM	TS87C51RB2/RC2/RD2 OTP
-MCA	X	Х	X
-MCB	X	Х	X
-MCE	X	Х	X
-MCL	RD2 only	RD2 only	RD2 only
-MCM	RD2 only	RD2 only	RD2 only
-VCA	Х	Х	X
-VCB	X	Х	X
-VCE	Х	X	X
-VCL	RD2 only	RD2 only	RD2 only
-VCM	RD2 only	RD2 only	RD2 only
-LCA	Х	Х	X
-LCB	X	Х	X
-LCE	Х	X	X
-LCL	RD2 only	RD2 only	RD2 only
-LCM	RD2 only	RD2 only	RD2 only
-MIA	Х	Х	X
-MIB	X	Х	X
-MIE	Х	X	X
-MIL	RD2 only	RD2 only	RD2 only
-MIM	RD2 only	RD2 only	RD2 only
-VIA	Х	Х	X
-VIB	X	Х	X
-VIE	X	X	X
-VIL	RD2 only	RD2 only	RD2 only
-VIM	RD2 only	RD2 only	RD2 only
-LIA	Х	Х	X
-LIB	X	Х	X
-LIE	X	Х	X
-LIL	RD2 only	RD2 only	RD2 only
-LIM	RD2 only	RD2 only	RD2 only
-EA	Х		X
-EB	X		X
-EE	X		X
-EL	RD2 only		RD2 only
-EM	RD2 only		RD2 only
-EJ			RC2 and RD2 only
-EK			RC2 and RD2 only
-EN			RD2 only

Table 48. Possible Ordering Entries

• -Ex for samples

- Tape and Reel available for B, E, L and M packages
- Dry pack mandatory for E and M packages