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#### Details

Product Status	Obsolete
Core Processor	80C51
Core Size	8-Bit
Speed	40/20MHz
Connectivity	UART/USART
Peripherals	POR, PWM, WDT
Number of I/O	32
Program Memory Size	-
Program Memory Type	ROMIess
EEPROM Size	-
RAM Size	768 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-LCC (J-Lead)
Supplier Device Package	44-PLCC (16.6x16.6)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/ts80c51rd2-mib

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



Reset	9	10	4	Ι	Reset: A high on this pin for two machine cycles while the oscillator is running,
					resets the device. An internal diffused resistor to $V_{\mbox{\scriptsize SS}}$ permits a power-on reset
					using only an external capacitor to $V_{CC}$ . If the hardware watchdog reaches its
					time-out, the reset pin becomes an output during the time the internal reset is
					activated.



# 6. TS80C51Rx2 Enhanced Features

In comparison to the original 80C52, the TS80C51Rx2 implements some new features, which are:

- The X2 option.
- The Dual Data Pointer.
- The extended RAM.
- The Programmable Counter Array (PCA).
- The Watchdog.
- The 4 level interrupt priority system.
- The power-off flag.
- The ONCE mode.
- The ALE disabling.
- Some enhanced features are also located in the UART and the timer 2.

### 6.1. X2 Feature

The TS80C51Rx2 core needs only 6 clock periods per machine cycle. This feature called "X2" provides the following advantages:

- Divide frequency crystals by 2 (cheaper crystals) while keeping same CPU power.
- Save power consumption while keeping same CPU power (oscillator power saving).
- Save power consumption by dividing dynamically operating frequency by 2 in operating and idle modes.
- Increase CPU power by 2 while keeping same crystal frequency.

In order to keep the original C51 compatibility, a divider by 2 is inserted between the XTAL1 signal and the main clock input of the core (phase generator). This divider may be disabled by software.

#### 6.1.1. Description

The clock for the whole circuit and peripheral is first divided by two before being used by the CPU core and peripherals. This allows any cyclic ratio to be accepted on XTAL1 input. In X2 mode, as this divider is bypassed, the signals on XTAL1 must have a cyclic ratio between 40 to 60%. Figure 1. shows the clock generation block diagram. X2 bit is validated on XTAL1÷2 rising edge to avoid glitches when switching from X2 to STD mode. Figure 2. shows the mode switching waveforms.



Figure 1. Clock Generation Diagram







The X2 bit in the CKCON register (See Table 3.) allows to switch from 12 clock cycles per instruction to 6 clock cycles and vice versa. At reset, the standard speed is activated (STD mode). Setting this bit activates the X2 feature (X2 mode).

#### CAUTION

In order to prevent any incorrect operation while operating in X2 mode, user must be aware that all peripherals using clock frequency as time reference (UART, timers, PCA...) will have their time reference divided by two. For example a free running timer generating an interrupt every 20 ms will then generate an interrupt every 10 ms. UART with 4800 baud rate will have 9600 baud rate.



#### Table 3. CKCON Register

#### CKCON - Clock Control Register (8Fh)

7	6	5	4	3	2	1	0		
-	-	-	-	-	-	-	X2		

Bit Number	Bit Mnemonic	Description
7	-	<b>Reserved</b> The value read from this bit is indeterminate. Do not set this bit.
6	-	<b>Reserved</b> The value read from this bit is indeterminate. Do not set this bit.
5	-	<b>Reserved</b> The value read from this bit is indeterminate. Do not set this bit.
4	-	<b>Reserved</b> The value read from this bit is indeterminate. Do not set this bit.
3	-	<b>Reserved</b> The value read from this bit is indeterminate. Do not set this bit.
2	-	<b>Reserved</b> The value read from this bit is indeterminate. Do not set this bit.
1	-	<b>Reserved</b> The value read from this bit is indeterminate. Do not set this bit.
0	X2	<b>CPU and peripheral clock bit</b> Clear to select 12 clock periods per machine cycle (STD mode, $F_{OSC}=F_{XTAL}/2$ ). Set to select 6 clock periods per machine cycle (X2 mode, $F_{OSC}=F_{XTAL}$ ).

Reset Value = XXXX XXX0b Not bit addressable

For further details on the X2 feature, please refer to ANM072 available on the web (http://www.atmel-wm.com)



## ASSEMBLY LANGUAGE

; Block move using dual data pointers ; Destroys DPTR0, DPTR1, A and PSW ; note: DPS exits opposite of entry state ; unless an extra INC AUXR1 is added

00A2	AUXR1 EQU 0A2H	
; 0000 909000 0003 05A2 0005 004000	MOV DPTR,#SOURCE INC AUXR1 MOV DPTR #DEST	; address of SOURCE ; switch data pointers : address of DEST
0003 90A000 0008 0008 05A2	LOOP: INC AUXR1	; switch data pointers
000A E0	MOVX A, @DPTR	; get a byte from SOURCE
000B A3	INC DPTR	; increment SOURCE address
000C 05A2	INC AUXRI	; switch data pointers
000E F0	MOVX @DPTR,A	; write the byte to DEST
000F A3	INC DPTR	: increment DEST address
0010 70F6	JNZ LOOP	; check for 0 terminator
0012 05A2	INC AUXR1	; (optional) restore DPS

INC is a short (2 bytes) and fast (12 clocks) way to manipulate the DPS bit in the AUXR1 SFR. However, note that the INC instruction does not directly force the DPS bit to a particular state, but simply toggles it. In simple routines, such as the block move example, only the fact that DPS is toggled in the proper sequence matters, not its actual value. In other words, the block move routine works the same whether DPS is '0' or '1' on entry. Observe that without the last instruction (INC AUXR1), the routine will exit with DPS in the opposite state.



• The ECF bit which when set causes an interrupt and the PCA overflow flag CF (in the CCON SFR) to be set when the PCA timer overflows.



## 6.5.4. Pulse Width Modulator Mode

All of the PCA modules can be used as PWM outputs. Figure 12 shows the PWM function. The frequency of the output depends on the source for the PCA timer. All of the modules will have the same frequency of output because they all share the PCA timer. The duty cycle of each module is independently variable using the module's capture register CCAPLn. When the value of the PCA CL SFR is less than the value in the module's CCAPLn SFR the output will be low, when it is equal to or greater than the output will be high. When CL overflows from FF to 00, CCAPLn is reloaded with the value in CCAPHn. This allows updating the PWM without glitches. The PWM and ECOM bits in the module's CCAPMn register must be set to enable the PWM mode.



Figure 12. PCA PWM Mode

## 6.5.5. PCA Watchdog Timer

An on-board watchdog timer is available with the PCA to improve the reliability of the system without increasing chip count. Watchdog timers are useful for systems that are susceptible to noise, power glitches, or electrostatic discharge. Module 4 is the only PCA module that can be programmed as a watchdog. However, this module can still be used for other modes if the watchdog is not needed. Figure 10 shows a diagram of how the watchdog works. The user pre-loads a 16-bit value in the compare registers. Just like the other compare modes, this 16-bit value is compared to the PCA timer value. If a match is allowed to occur, an internal reset will be generated. This will not cause the RST pin to be driven high.

In order to hold off the reset, the user has three options:

- 1. periodically change the compare value so it will never match the PCA timer,
- 2. periodically change the PCA timer value so it will never match the compare values, or
- 3. disable the watchdog by clearing the WDTE bit before a match occurs and then re-enable it.

The first two options are more reliable because the watchdog timer is never disabled as in option #3. If the program counter ever goes astray, a match will eventually occur and cause an internal reset. The second option is also not recommended if other PCA modules are being used. Remember, the PCA timer is the time base for all modules; changing the time base for other modules would not be a good idea. Thus, in most applications the first solution is the best option.

This watchdog timer won't generate a reset out on the reset pin.



## 6.6. TS80C51Rx2 Serial I/O Port

The serial I/O port in the TS80C51Rx2 is compatible with the serial I/O port in the 80C52. It provides both synchronous and asynchronous communication modes. It operates as an Universal Asynchronous

Receiver and Transmitter (UART) in three full-duplex modes (Modes 1, 2 and 3). Asynchronous transmission and reception can occur simultaneously and at different baud rates

Serial I/O port includes the following enhancements:

- Framing error detection
- Automatic address recognition

#### 6.6.1. Framing Error Detection

Framing bit error detection is provided for the three asynchronous modes (modes 1, 2 and 3). To enable the framing bit error detection feature, set SMOD0 bit in PCON register (See Figure 13).



#### Figure 13. Framing Error Block Diagram

When this feature is enabled, the receiver checks each incoming data frame for a valid stop bit. An invalid stop bit may result from noise on the serial lines or from simultaneous transmission by two CPUs. If a valid stop bit is not found, the Framing Error bit (FE) in SCON register (See Table 16.) bit is set.



Software may examine FE bit after each reception to check for data errors. Once set, only software or a reset can clear FE bit. Subsequently received frames with valid stop bits cannot clear FE bit. When FE feature is enabled, RI rises on stop bit instead of the last data bit (See Figure 14. and Figure 15.).







Figure 15. UART Timings in Modes 2 and 3

#### 6.6.2. Automatic Address Recognition

The automatic address recognition feature is enabled when the multiprocessor communication feature is enabled (SM2 bit in SCON register is set).

Implemented in hardware, automatic address recognition enhances the multiprocessor communication feature by allowing the serial port to examine the address of each incoming command frame. Only when the serial port recognizes its own address, the receiver sets RI bit in SCON register to generate an interrupt. This ensures that the CPU is not interrupted by command frames addressed to other devices.

If desired, you may enable the automatic address recognition feature in mode 1. In this configuration, the stop bit takes the place of the ninth data bit. Bit RI is set only when the received command frame address matches the device's address and is terminated by a valid stop bit.

To support automatic address recognition, a device is identified by a given address and a broadcast address.

NOTE: The multiprocessor communication and automatic address recognition features cannot be enabled in mode 0 (i.e. setting SM2 bit in SCON register in mode 0 has no effect).



#### 6.6.5. Reset Addresses

On reset, the SADDR and SADEN registers are initialized to 00h, i.e. the given and broadcast addresses are XXXX (all don't-care bits). This ensures that the serial port will reply to any address, and so, that it is backwards compatible with the 80C51 microcontrollers that do not support automatic address recognition.

#### SADEN - Slave Address Mask Register (B9h)

7	6	5	4	3	2	1	0

Reset Value = 0000 0000b Not bit addressable

#### SADDR - Slave Address Register (A9h)

7	6	5	4	3	2	1	0

Reset Value = 0000 0000b Not bit addressable



### Table 17. PCON Register

#### PCON - Power Control Register (87h)

7	6	5	4	3	2	1	0		
SMOD1	SMOD	) -	POF	GF1	GF0	PD	IDL		
Bit Number	Bit Mnemonic		Description						
7	SMOD1	Serial port Mode bi Set to select dou	t <b>1</b> ble baud rate in m	ode 1, 2 or 3.					
6	SMOD0	Serial port Mode bi Clear to select S Set to to select F	erial port Mode bit 0 Clear to select SM0 bit in SCON register. Set to to select FE bit in SCON register.						
5	-	Reserved The value read fr	Reserved The value read from this bit is indeterminate. Do not set this bit.						
4	POF	Power-Off Flag Clear to recogniz Set by hardware	Power-Off Flag Clear to recognize next reset type. Set by hardware when VCC rises from 0 to its nominal voltage. Can also be set by software.						
3	GF1	General purpose Fla Cleared by user for g	General purpose Flag Cleared by user for general purpose usage. Set by user for general purpose usage.						
2	GF0	General purpose Fla Cleared by user for g	General purpose Flag Cleared by user for general purpose usage. Set by user for general purpose usage.						
1	PD	Power-Down mode Cleared by hardy Set to enter powe	Power-Down mode bit Cleared by hardware when reset occurs. Set to enter power-down mode.						
0	IDL	Idle mode bit Clear by hardwar Set to enter idle	e when interrupt on node.	or reset occurs.					

Reset Value = 00X1 0000b Not bit addressable

Power-off flag reset value will be 1 only after a power on (cold reset). A warm reset doesn't affect the value of this bit.



#### Table 24. WDTPRG Register

7	6		5	4	3	2	1	0	
T4	Т3		T2	T1	TO	S2	S1	<b>S0</b>	
Bit Number	Bit Mnemonic	Description							
7	T4								
6	T3								
5	T2	Reserve Do 1	d not try to set	or clear this bit.					
4	T1								
3	TO								
2	S2	WDT Ti	ime-out sele	et bit 2					
1	S1	WDT Ti	ime-out sele	et bit 1					
0	SO	WDT Ti	ime-out sele	et bit 0					
			<u>S1</u> 0 1 1 0 0 1 1	$\begin{array}{c cccc} \underline{S0} & \underline{Selecter} \\ 0 & (2^{14} - 1) \\ 1 & (2^{15} - 1) \\ 0 & (2^{16} - 1) \\ 1 & (2^{17} - 1) \\ 0 & (2^{18} - 1) \\ 1 & (2^{19} - 1) \\ 0 & (2^{20} - 1) \\ 1 & (2^{21} - 1) \end{array}$	1 Time-out 9 machine cycles, 10 9 machine cycles, 32 9 machine cycles, 63 9 machine cycles, 12 9 machine cycles, 20 9 machine cycles, 55 9 machine cycles, 1 9 machine cycles, 1 9 machine cycles, 2	5.3 ms @ 12 MHz 2.7 ms @ 12 MHz 5.5 ms @ 12 MHz 31 ms @ 12 MHz 62 ms @ 12 MHz 42 ms @ 12 MHz 05 s @ 12 MHz 09 s @ 12 MHz			

Reset value XXXX X000

## 6.10.2. WDT during Power Down and Idle

In Power Down mode the oscillator stops, which means the WDT also stops. While in Power Down mode the user does not need to service the WDT. There are 2 methods of exiting Power Down mode: by a hardware reset or via a level activated external interrupt which is enabled prior to entering Power Down mode. When Power Down is exited with hardware reset, servicing the WDT should occur as it normally should whenever the TS80C51Rx2 is reset. Exiting Power Down with an interrupt is significantly different. The interrupt is held low long enough for the oscillator to stabilize. When the interrupt is brought high, the interrupt is serviced. To prevent the WDT from resetting the device while the interrupt pin is held low, the WDT is not started until the interrupt is pulled high. It is suggested that the WDT be reset during the interrupt service routine.

To ensure that the WDT does not overflow within a few states of exiting of powerdown, it is best to reset the WDT just before entering powerdown.

In the Idle mode, the oscillator continues to run. To prevent the WDT from resetting the TS80C51Rx2 while in Idle mode, the user should always set up a timer that will periodically exit Idle, service the WDT, and re-enter Idle mode.

## WDTPRG Address (0A7h)



### 6.13. Reduced EMI Mode

The ALE signal is used to demultiplex address and data buses on port 0 when used with external program or data memory. Nevertheless, during internal code execution, ALE signal is still generated. In order to reduce EMI, ALE signal can be disabled by setting AO bit.

The AO bit is located in AUXR register at bit location 0. As soon as AO is set, ALE is no longer output but remains active during MOVX and MOVC instructions and external fetches. During ALE disabling, ALE pin is weakly pulled high.

#### Table 27. AUXR Register

#### AUXR - Auxiliary Register (8Eh)

7	6	5	4	3	2	1	0	
-	-	-	-	-	-	EXTRAM	AO	
Bit Number	Bit Mnemonic			tion				
7	-	<b>Reserved</b> The value read fr	om this bit is inde	terminate. Do not s	set this bit.			
6	-	<b>Reserved</b> The value read fr	om this bit is inde	terminate. Do not s	set this bit.			
5	-	<b>Reserved</b> The value read fr	om this bit is inde	terminate. Do not s	set this bit.			
4	-	<b>Reserved</b> The value read fr	om this bit is inde	terminate. Do not s	set this bit.			
3	-	<b>Reserved</b> The value read fr	om this bit is inde	terminate. Do not s	set this bit.			
2	-	<b>Reserved</b> The value read fr	om this bit is inde	terminate. Do not s	set this bit.			
1	EXTRAM	EXTRAM bit See Table 5.	EXTRAM bit See Table 5.					
0	AO	ALE Output bit Clear to restore A Set to disable AL	LE operation dur E operation durin	ing internal fetches g internal fetches.	i.			

Reset Value = XXXX XX00b Not bit addressable



# 7. TS83C51RB2/RC2/RD2 ROM

## 7.1. ROM Structure

The TS83C51RB2/RC2/RD2 ROM memory is divided in three different arrays:

•	the code array:	es.
•	the encryption array:	s.
•	the signature array:	es.

## 7.2. ROM Lock System

The program Lock system, when programmed, protects the on-chip program against software piracy.

## 7.2.1. 7.2.1. Encryption Array

Within the ROM array are 64 bytes of encryption array that are initially unprogrammed (all FF's). Every time a byte is addressed during program verify, 6 address lines are used to select a byte of the encryption array. This byte is then exclusive-NOR'ed (XNOR) with the code byte, creating an encrypted verify byte. The algorithm, with the encryption array in the unprogrammed state, will return the code in its original, unmodified form.

When using the encryption array, one important factor needs to be considered. If a byte has the value FFh, verifying the byte will produce the encryption byte value. If a large block (>64 bytes) of code is left unprogrammed, a verification routine will display the content of the encryption array. For this reason all the unused code bytes should be programmed with random values. This will ensure program protection.

## 7.2.2. Program Lock Bits

The lock bits when programmed according to Table 28. will provide different level of protection for the on-chip code and data.

Program Lock Bits					
Security level	LB1	LB2	LB3	Protection description	
1	U	U	U	No program lock features enabled. Code verify will still be encrypted by the encryption array if programmed. MOVC instruction executed from external program memory returns non encrypted data.	
2	Р	U	U	MOVC instruction executed from external program memory are disabled from fetching code bytes from internal memory, $\overline{EA}$ is sampled and latched on reset.	
3	U	Р	U	Same as level 1+ Verify disable. This security level is only available for 51RDX2 devices.	

Table	28.	Program	Lock	bits
-------	-----	---------	------	------

U: unprogrammed

P: programmed

## 7.2.3. Signature bytes

The TS83C51RB2/RC2/RD2 contains 4 factory programmed signatures bytes. To read these bytes, perform the process described in section 8.3.

#### 7.2.4. Verify Algorithm

Refer to 8.3.4.



## **8.3. EPROM Programming**

#### 8.3.1. Set-up modes

In order to program and verify the EPROM or to read the signature bytes, the TS87C51RB2/RC2/RD2 is placed in specific set-up modes (See Figure 18.).

Control and program signals must be held at the levels indicated in Table 30.

#### **8.3.2.** Definition of terms

Address Lines: P1.0-P1.7, P2.0-P2.5, P3.4, P3.5 respectively for A0-A15 (P2.5 (A13) for RB, P3.4 (A14) for RC, P3.5 (A15) for RD)

Data Lines: P0.0-P0.7 for D0-D7

**Control Signals:** RST, <u>PSEN</u>, P2.6, P2.7, P3.3, P3.6, P3.7.

Program Signals: ALE/PROG, EA/VPP.

Mode	RST	PSEN	ALE/ PROG	<b>EA</b> /VPP	P2.6	P2.7	P3.3	P3.6	P3.7
Program Code data	1	0	Г	12.75V	0	1	1	1	1
Verify Code data	1	0	1	1	0		0	1	1
Program Encryption Array Address 0-3Fh	1	0	Г	12.75V	0	1	1	0	1
Read Signature Bytes	1	0	1	1	0		0	0	0
Program Lock bit 1	1	0	Г	12.75V	1	1	1	1	1
Program Lock bit 2	1	0	ப	12.75V	1	1	1	0	0
Program Lock bit 3	1	0	Г	12.75V	1	0	1	1	0

Table 30. EPROM Set-Up Modes



## 10.3. DC Parameters for Standard Voltage

TA = 0°C to +70°C; V<sub>SS</sub> = 0 V; V<sub>CC</sub> = 5 V ± 10%; F = 0 to 40 MHz. TA = -40°C to +85°C; V<sub>SS</sub> = 0 V; V<sub>CC</sub> = 5 V ± 10%; F = 0 to 40 MHz.

#### Table 32. DC Parameters in Standard Voltage

Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
V <sub>IL</sub>	Input Low Voltage	-0.5		0.2 V <sub>CC</sub> - 0.1	V	
V <sub>IH</sub>	Input High Voltage except XTAL1, RST	$0.2 V_{CC} + 0.9$		V <sub>CC</sub> + 0.5	V	
V <sub>IH1</sub>	Input High Voltage, XTAL1, RST	0.7 V <sub>CC</sub>		V <sub>CC</sub> + 0.5	V	
V <sub>OL</sub>	Output Low Voltage, ports 1, 2, 3, 4, 5 <sup>(6)</sup>			0.3 0.45 1.0	V V V	$I_{OL} = 100 \ \mu A^{(4)}$ $I_{OL} = 1.6 \ m A^{(4)}$ $I_{OL} = 3.5 \ m A^{(4)}$
V <sub>OL1</sub>	Output Low Voltage, port 0 <sup>(6)</sup>			0.3 0.45 1.0	V V V	$I_{OL} = 200 \ \mu A^{(4)}$ $I_{OL} = 3.2 \ m A^{(4)}$ $I_{OL} = 7.0 \ m A^{(4)}$
V <sub>OL2</sub>	Output Low Voltage, ALE, PSEN			0.3 0.45 1.0	V V V	$\begin{split} I_{OL} &= 100 \; \mu A^{(4)} \\ I_{OL} &= 1.6 \; m A^{(4)} \\ I_{OL} &= 3.5 \; m A^{(4)} \end{split}$
V <sub>OH</sub>	Output High Voltage, ports 1, 2, 3, 4, 5	V <sub>CC</sub> - 0.3 V <sub>CC</sub> - 0.7 V <sub>CC</sub> - 1.5			V V V	$\begin{split} I_{OH} &= -10 \; \mu A \\ I_{OH} &= -30 \; \mu A \\ I_{OH} &= -60 \; \mu A \\ V_{CC} &= 5 \; V \pm 10\% \end{split}$
V <sub>OH1</sub>	Output High Voltage, port 0	V <sub>CC</sub> - 0.3 V <sub>CC</sub> - 0.7 V <sub>CC</sub> - 1.5			V V V	$I_{OH} = -200 \ \mu A$ $I_{OH} = -3.2 \ m A$ $I_{OH} = -7.0 \ m A$ $V_{CC} = 5 \ V \pm 10\%$
V <sub>OH2</sub>	Output High Voltage, ALE, PSEN	V <sub>CC</sub> - 0.3 V <sub>CC</sub> - 0.7 V <sub>CC</sub> - 1.5			V V V	$I_{OH} = -100 \ \mu A$ $I_{OH} = -1.6 \ m A$ $I_{OH} = -3.5 \ m A$ $V_{CC} = 5 \ V \pm 10\%$
R <sub>RST</sub>	RST Pulldown Resistor	50	90 <sup>(5)</sup>	200	kΩ	
I <sub>IL</sub>	Logical 0 Input Current ports 1, 2, 3, 4, 5			-50	μΑ	Vin = 0.45 V
I <sub>LI</sub>	Input Leakage Current			±10	μΑ	0.45 V < Vin < V <sub>CC</sub>
I <sub>TL</sub>	Logical 1 to 0 Transition Current, ports 1, 2, 3, 4, 5			-650	μA	Vin = 2.0 V
C <sub>IO</sub>	Capacitance of I/O Buffer			10	pF	$Fc = 1 MHz$ $TA = 25^{\circ}C$
I <sub>PD</sub>	Power Down Current		20 (5)	50	μΑ	$2.0 \ V < V_{CC} < 5.5 \ V^{(3)}$
I <sub>CC</sub> under RESET	Power Supply Current Maximum values, X1 mode: <sup>(7)</sup>			1 + 0.4 Freq (MHz) @12MHz 5.8 @16MHz 7.4	mA	$V_{CC} = 5.5 V^{(1)}$



Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
I <sub>CC</sub> idle	Power Supply Current Maximum values, X1 mode: <sup>(7)</sup>			0.15 Freq (MHz) + 0.2 @12MHz 2 @16MHz 2.6	mA	$V_{CC} = 3.3 V^{(2)}$

NOTES

1.  $I_{CC}$  under reset is measured with all output pins disconnected; XTAL1 driven with  $T_{CLCH}$ ,  $T_{CHCL} = 5$  ns (see Figure 24.),  $V_{IL} = V_{SS} + 0.5$  V,  $V_{IH} = V_{CC} - 0.5$ V; XTAL2 N.C.;  $\overline{EA} = RST = Port \ 0 = V_{CC}$ .  $I_{CC}$  would be slightly higher if a crystal oscillator used.

2. Idle  $I_{CC}$  is measured with all output pins disconnected; XTAL1 driven with  $T_{CLCH}$ ,  $T_{CHCL} = 5$  ns,  $V_{IL} = V_{SS} + 0.5$  V,  $V_{IH} = V_{CC} - 0.5$  V; XTAL2 N.C; Port  $0 = V_{CC}$ ;  $\overline{EA} = RST = V_{SS}$  (see Figure 22.).

3. Power Down  $I_{CC}$  is measured with all output pins disconnected;  $\overline{EA} = V_{SS}$ , PORT  $0 = V_{CC}$ ; XTAL2 NC.; RST =  $V_{SS}$  (see Figure 23.).

4. Capacitance loading on Ports 0 and 2 may cause spurious noise pulses to be superimposed on the  $V_{OL}s$  of ALE and Ports 1 and 3. The noise is due to external bus capacitance discharging into the Port 0 and Port 2 pins when these pins make 1 to 0 transitions during bus operation. In the worst cases (capacitive loading 100pF), the noise pulse on the ALE line may exceed 0.45V with maxi  $V_{OL}$  peak 0.6V. A Schmitt Trigger use is not necessary.

5. Typicals are based on a limited number of samples and are not guaranteed. The values listed are at room temperature and 5V.

6. Under steady state (non-transient) conditions, I<sub>OL</sub> must be externally limited as follows:

Maximum I<sub>OL</sub> per port pin: 10 mA Maximum I<sub>OL</sub> per 8-bit port:

Port 0: 26 mA

Ports 1, 2, 3 and 4 and 5 when available: 15 mA

Maximum total I<sub>OL</sub> for all output pins: 71 mA

If  $I_{OL}$  exceeds the test condition,  $V_{OL}$  may exceed the related specification. Pins are not guaranteed to sink current greater than the listed test conditions. 7. For other values, please contact your sales office.

8. Operating  $I_{CC}$  is measured with all output pins disconnected; XTAL1 driven with  $T_{CLCH}$ ,  $T_{CHCL} = 5$  ns (see Figure 24.),  $V_{IL} = V_{SS} + 0.5$  V,

 $V_{IH} = V_{CC} - 0.5V$ ; XTAL2 N.C.;  $\overline{EA} = Port 0 = V_{CC}$ ; RST =  $V_{SS}$ . The internal ROM runs the code 80 FE (label: SJMP label).  $I_{CC}$  would be slightly higher if a crystal oscillator is used. Measurements are made with OTP products when possible, which is the worst case.



All other pins are disconnected.

Figure 20. I<sub>CC</sub> Test Condition, under reset



Speed	-] 40 M	M MHz	X2 1 30 M 60 MH	V node MHz z equiv.	- standar 40 M	V °d mode MHz		L node MHz z equiv.	- standar 30 M	L rd mode MHz	Units
Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
T <sub>RLRH</sub>	130		85		135		125		175		ns
T <sub>WLWH</sub>	130		85		135		125		175		ns
T <sub>RLDV</sub>		100		60		102		95		137	ns
T <sub>RHDX</sub>	0		0		0		0		0		ns
T <sub>RHDZ</sub>		30		18		35		25		42	ns
T <sub>LLDV</sub>		160		98		165		155		222	ns
T <sub>AVDV</sub>		165		100		175		160		235	ns
T <sub>LLWL</sub>	50	100	30	70	55	95	45	105	70	130	ns
T <sub>AVWL</sub>	75		47		80		70		103		ns
T <sub>QVWX</sub>	10		7		15		5		13		ns
T <sub>QVWH</sub>	160		107		165		155		213		ns
T <sub>WHQX</sub>	15		9		17		10		18		ns
T <sub>RLAZ</sub>		0		0		0		0		0	ns
T <sub>WHLH</sub>	10	40	7	27	15	35	5	45	13	53	ns

Table 40. AC Parameters for a Fix Clock



### **10.5.9. EPROM Programming and Verification Characteristics**

TA = 21°C to 27°C;  $V_{SS} = 0V$ ;  $V_{CC} = 5V \pm 10\%$  while programming.  $V_{CC}$  = operating range while verifying

Symbol	Parameter	Min	Max	Units
V <sub>PP</sub>	Programming Supply Voltage	12.5	13	V
I <sub>PP</sub>	Programming Supply Current		75	mA
1/T <sub>CLCL</sub>	Oscillator Frquency	4	6	MHz
T <sub>AVGL</sub>	Address Setup to PROG Low	48 T <sub>CLCL</sub>		
T <sub>GHAX</sub>	Adress Hold after PROG	48 T <sub>CLCL</sub>		
T <sub>DVGL</sub>	Data Setup to PROG Low	48 T <sub>CLCL</sub>		
T <sub>GHDX</sub>	Data Hold after PROG	48 T <sub>CLCL</sub>		
T <sub>EHSH</sub>	(Enable) High to V <sub>PP</sub>	48 T <sub>CLCL</sub>		
T <sub>SHGL</sub>	V <sub>PP</sub> Setup to PROG Low	10		μs
T <sub>GHSL</sub>	V <sub>PP</sub> Hold after PROG	10		μs
T <sub>GLGH</sub>	PROG Width	90	110	μs
T <sub>AVQV</sub>	Address to Valid Data		48 T <sub>CLCL</sub>	
T <sub>ELQV</sub>	ENABLE Low to Data Valid		48 T <sub>CLCL</sub>	
T <sub>EHQZ</sub>	Data Float after ENABLE	0	48 T <sub>CLCL</sub>	

#### Table 45. EPROM Programming Parameters

#### 10.5.10. EPROM Programming and Verification Waveforms



\* 8KB: up to P2.4, 16KB: up to P2.5, 32KB: up to P3.4, 64KB: up to P3.5

#### Figure 29. EPROM Programming and Verification Waveforms



	TS80C51RA2/RD2 ROMless	TS83C51RB2/RC2/RD2zzz ROM	TS87C51RB2/RC2/RD2 OTP
-MCA	Х	Х	X
-MCB	Х	Х	X
-MCE	Х	Х	X
-MCL	RD2 only	RD2 only	RD2 only
-MCM	RD2 only	RD2 only	RD2 only
-VCA	Х	Х	X
-VCB	Х	Х	X
-VCE	Х	Х	X
-VCL	RD2 only	RD2 only	RD2 only
-VCM	RD2 only	RD2 only	RD2 only
-LCA	Х	Х	X
-LCB	Х	Х	X
-LCE	Х	Х	X
-LCL	RD2 only	RD2 only	RD2 only
-LCM	RD2 only	RD2 only	RD2 only
-MIA	Х	Х	X
-MIB	Х	Х	X
-MIE	Х	Х	X
-MIL	RD2 only	RD2 only	RD2 only
-MIM	RD2 only	RD2 only	RD2 only
-VIA	Х	Х	X
-VIB	Х	Х	X
-VIE	Х	Х	X
-VIL	RD2 only	RD2 only	RD2 only
-VIM	RD2 only	RD2 only	RD2 only
-LIA	Х	Х	X
-LIB	Х	Х	X
-LIE	Х	Х	X
-LIL	RD2 only	RD2 only	RD2 only
-LIM	RD2 only	RD2 only	RD2 only
-EA	Х		X
-EB	Х		X
-EE	Х		X
-EL	RD2 only		RD2 only
-EM	RD2 only		RD2 only
-EJ			RC2 and RD2 only
-EK			RC2 and RD2 only
-EN			RD2 only

#### Table 48. Possible Ordering Entries

• -Ex for samples

- Tape and Reel available for B, E, L and M packages
- Dry pack mandatory for E and M packages