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Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	100MHz
Connectivity	I ² C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, QEI, WDT
Number of I/O	53
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 20x12b; D/A 3x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ck128mp206t-i-pt

dsPIC33CK256MP508 FAMILY

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TABLE 4-7: SFR BLOCK 500h

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
CAN			C1TSCONL	5D4	-----0000000000	C1RXOVIFH	5EA	0000000000000000
C1CONL	5C0	--00011101100000	C1TSCONH	5D6	-----000	C1TXATIFL	5EC	0000000000000000
C1CONH	5C2	0000010010011000	C1VECL	5D8	---00000-100000	C1TXATIFH	5EE	0000000000000000
C1NBTCFGL	5C4	00001111-0001111	C1VECH	5DA	11000000-100000	C1TXREQL	5F0	0000000000000000
C1NBTCFGH	5C6	0000000000111110	C1INTL	5DC	000000----0000	C1TXREQH	5F2	0000000000000000
C1DBTCFGL	5C8	----0011----0011	C1INTH	5DE	000000----0000	C1TRECL	5F4	0000000000000000
C1DBTCFGH	5CA	00000000--01110	C1RXIFL	5E0	0000000000000000	C1TRECH	5F6	-----100000
C1TDCL	5CC	00010000--00000	C1RXIFH	5E2	0000000000000000	C1BDIAG0L	5F8	0000000000000000
C1TDCH	5CE	-----00-----10	C1TXIFL	5E4	000000000000000-	C1BDIAG0H	5FA	0000000000000000
C1TBCL	5D0	0000000000000000	C1TXIFH	5E6	0000000000000000	C1BDIAG1L	5FC	0000000000000000
C1TBCH	5D2	0000000000000000	C1RXOVIFL	5E8	000000000000000-	C1BDIAG1H	5FE	0000-000-00000

Legend: x = unknown or indeterminate value; “-” = unimplemented bits. Address values are in hexadecimal. Reset values are in binary.

5.3.2 ERROR CORRECTING CODE (ECC)

In order to improve program memory performance and durability, these devices include Error Correcting Code (ECC) functionality as an integral part of the Flash memory controller. ECC can determine the presence of single bit errors in program data, including which bit is in error, and correct the data automatically without user intervention. ECC cannot be disabled.

When data is written to program memory, ECC generates a 7-bit Hamming code parity value for every two (24-bit) instruction words. The data is stored in blocks of 48 data bits and 7 parity bits; parity data is not memory-mapped and is inaccessible. When the data is read back, the ECC calculates the parity on it and compares it to the previously stored parity value. If a parity mismatch occurs, there are two possible outcomes:

- Single bit error has occurred and has been automatically corrected on readback.
- Double-bit error has occurred and the read data is not changed.

Single bit error occurrence can be identified by the state of the ECCSBEIF (IFS0<13>) bit. An interrupt can be generated when the corresponding interrupt enable bit is set, ECCSBEIE (IEC0<13>). The ECCSTATL register contains the parity information for single bit errors. The SECOUT<7:0> bits field contains the expected calculated SEC parity and the SECIN<7:0> bits contain the actual value from a Flash read operation. The SECSYNDx bits (ECCSTATH<7:0>) indicate the bit position of the single bit error within the 48-bit pair of instruction words. When no error is present, SECINx equals SECOUTx and SECSYNDx is zero.

Double-bit errors result in a generic hard trap. The ECCDBE bit (INTCON4<1>) will be set to identify the source of the hard trap. If no Interrupt Service Routine is implemented for the hard trap, a device Reset will also occur. The ECCSTATH register contains double-bit error status information. The DEDOUT bit is the expected calculated DED parity and DEDIN is the actual value from a Flash read operation. When no error is present, DEDIN equals DEDOUT.

5.3.3 ECC FAULT INJECTION

To test Fault handling, an EEC error can be generated. Both single and double-bit errors can be generated in both the read and write data paths. Read path Fault injection first reads the Flash data and then modifies it prior to entering the ECC logic. Write path Fault injection modifies the actual data prior to it being written into the target Flash and will cause an EEC error on a subsequent Flash read. The following procedure is used to inject a Fault:

1. Load the Flash target address into the ECCADDR register.
2. Select 1st Fault bit determined by FLT1PTRx (ECCCONH<7:0>). The target bit is inverted to create the Fault.
3. If a double Fault is desired, select the 2nd Fault bit determined by FLT2PTRx (ECCCONH<15:8>), otherwise set to all '1's.
4. Write the NVMKEY unlock sequence (see [Section 5.5.3 “Program Flash Memory Control Registers”](#)).
5. Enable the ECC Fault injection logic by setting the FLTINJ bit (ECCCONL<0>).
6. Perform a read or write to the Flash target address.

6.0 RESETS

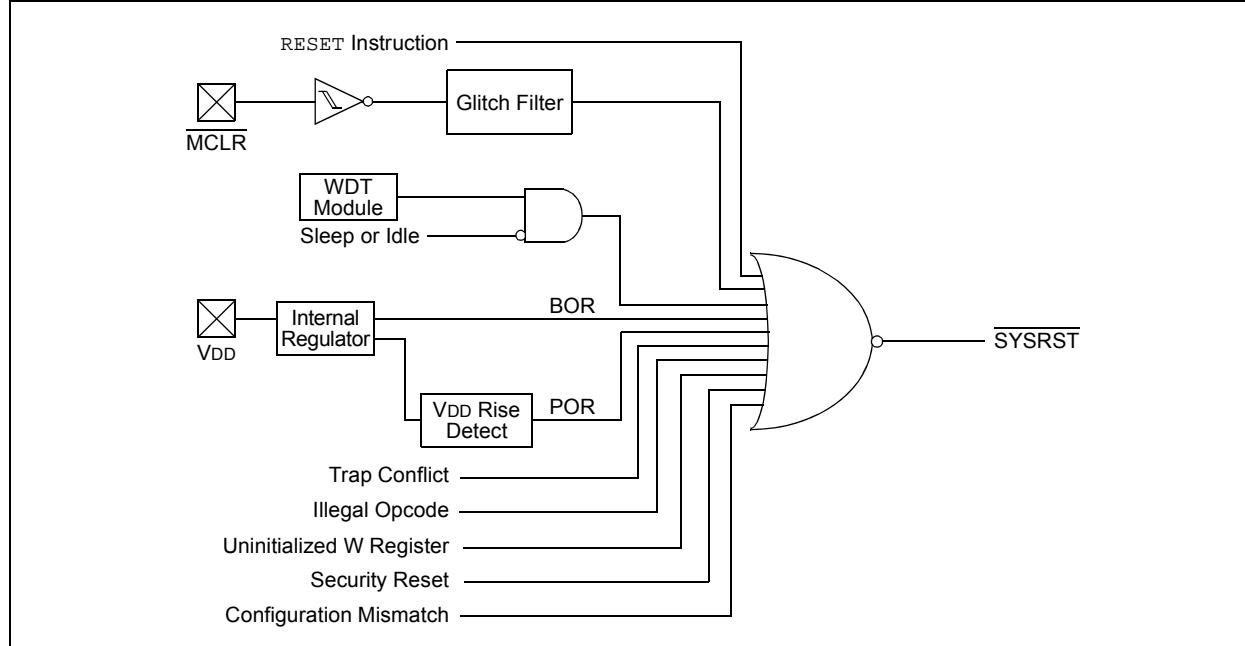
- Note 1:** This data sheet summarizes the features of the dsPIC33CK256MP508 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “Reset” (DS70602) in the “dsPIC33/PIC24 Family Reference Manual”, which is available from the Microchip web site (www.microchip.com).
- 2:** Some registers and associated bits described in this section may not be available on all devices.

The Reset module combines all Reset sources and controls the device Master Reset Signal, SYSRST. The following is a list of device Reset sources:

- POR: Power-on Reset
- BOR: Brown-out Reset
- MCLR: Master Clear Pin Reset
- SWR: RESET Instruction
- WDTO: Watchdog Timer Time-out Reset
- CM: Configuration Mismatch Reset
- TRAPR: Trap Conflict Reset
- IOPUWR: Illegal Condition Device Reset
 - Illegal Opcode Reset
 - Uninitialized W Register Reset
 - Security Reset

A simplified block diagram of the Reset module is shown in Figure 6-1.

FIGURE 6-1: RESET SYSTEM BLOCK DIAGRAM



Any active source of Reset will make the SYSRST signal active. On system Reset, some of the registers associated with the CPU and peripherals are forced to a known Reset state, and some are unaffected.

Note: Refer to the specific peripheral section or **Section 4.0 “Memory Organization”** of this data sheet for register Reset states.

All types of device Reset set a corresponding status bit in the RCON register to indicate the type of Reset (see Register 6-1).

A POR clears all the bits, except for the BOR and POR bits (RCON<1:0>) that are set. The user application can set or clear any bit, at any time, during code execution. The RCON bits only serve as status bits. Setting a particular Reset status bit in software does not cause a device Reset to occur.

The RCON register also has other bits associated with the Watchdog Timer and device power-saving states. The function of these bits is discussed in other sections of this data sheet.

Note: The status bits in the RCON register should be cleared after they are read so that the next RCON register value after a device Reset is meaningful.

For all Resets, the default clock source is determined by the FNOSC<2:0> bits in the FOSCSEL Configuration register. The value of the FNOSCx bits is loaded into the NOSC<2:0> (OSCCON<10:8>) bits on Reset, which in turn, initializes the system clock.

TABLE 7-4: INTERRUPT PRIORITY REGISTERS

Register	Address	Bit 15	Bit14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
IPC0	840h	—	CNBIP2	CNBIP1	CNBIP0	—	CNAIP2	CNAIP1	CNAIP0	—	T1IP2	T1IP1	T1IP0	—	INT0IP2	INT0IP1	INT0IP0
IPC1	842h	—	CCT1IP2	CCT1IP1	CCT1IP0	—	CCP1IP2	CCP1IP1	CCP1IP0	—	—	—	—	—	DMA0IP2	DMA0IP1	DMA0IP0
IPC2	844h	—	U1RXIP2	U1RXIP1	U1RXIP0	—	SPI1TXIP2	SPI1TXIP1	SPI1TXIP0	—	SPI1RXIP2	SPI1RXIP1	SPI1RXIP0	—	DMA1IP2	DMA1IP1	DMA1IP0
IPC3	846h	—	INT1IP2	INT1IP1	INT1IP0	—	NVMIP2	NVMIP1	NVMIP0	—	ECCSBEIP2	ECCSBEIP1	ECCSBEIP0	—	U1TXIP2	U1TXIP1	U1TXIP0
IPC4	848h	—	CNCIP2	CNCIP1	CNCIP0	—	DMA2IP2	DMA2IP1	DMA2IP0	—	MI2C1IP2	MI2C1IP1	MI2C1IP0	—	SI2C1IP2	SI2C1IP1	SI2C1IP0
IPC5	84Ah	—	CCP2IP2	CCP2IP1	CCP2IP0	—	—	—	—	—	DMA3IP2	DMA3IP1	DMA3IP20	—	INT2IP2	INT2IP1	INT2IP0
IPC6	84Ch	—	U2RXIP2	U2RXIP1	U2RXIP0	—	INT3IP2	INT3IP1	INT3IP0	—	C1IP2	C1IP1	C1IP0	—	CCT2IP2	CCT2IP1	CCT2IP0
IPC7	84Eh	—	C1RXIP2	C1RXIP1	C1RXIP0	—	SPI2TXIP2	SPI2TXIP1	SPI2TXIP0	—	SPI2RXIP2	SPI2RXIP1	SPI2RXIP0	—	U2TXIP2	U2TXIP1	U2TXIP0
IPC8	850h	—	CCP3IP2	CCP3IP1	CCP3IP0	—	—	—	—	—	—	—	—	—	—	—	—
IPC9	852h	—	—	—	—	—	MI2C2IP2	MI2C2IP1	MI2C2IP0	—	SI2C2IP2	SI2C2IP1	SI2C2IP0	—	CCT3IP2	CCT3IP1	CCT3IP0
IPC10	854h	—	CCP5IP2	CCP5IP1	CCP5IP0	—	—	—	—	—	CCT4IP2	CCT4IP1	CCT4IP0	—	CCP4IP2	CCP4IP1	CCP4IP0
IPC11	856h	—	CCT6IP2	CCT6IP1	CCT6IP0	—	CCP6IP2	CCP6IP1	CCP6IP0	—	DMTIP2	DMTIP1	DMTIP0	—	CCT5IP2	CCT5IP1	CCT5IP0
IPC12	858h	—	CRCIP2	CRCIP1	CRCIP0	—	U2EIP2	U2EIP1	U2EIP0	—	U1EIP2	U1EIP1	U1EIP0	—	QE1IP2	QE1IP1	QE1IP0
IPC13	85Ah	—	—	—	—	—	QE1IP2	QE1IP1	QE1IP0	—	—	—	—	—	C1TXIP2	C1TXIP1	C1TXIP0
IPC14	85Ch	—	SPI3RXIP2	SPI3RXIP1	SPI3RXIP0	—	U3TXIP2	U3TXIP1	U3TXIP0	—	U3RXIP2	U3RXIP1	U3RXIP0	—	U3EIP2	U3EIP1	U3EIP0
IPC15	85Eh	—	PTGSTEIP2	PTGSTEIP1	PTGSTEIP0	—	JTAGIP2	JTAGIP1	JTAGIP0	—	ICDIP2	ICDIP1	ICDIP0	—	SPI3TXIP2	SPI3TXIP1	SPI3TXIP0
IPC16	860h	—	PWM1IP2	PWM1IP1	PWM1IP0	—	—	—	—	—	I2C2BCIP2	I2C2BCIP1	I2C2BCIP0	—	I2C1BCIP2	I2C1BCIP1	I2C1BCIP0
IPC17	862h	—	PWM5IP2	PWM5IP1	PWM5IP0	—	PWM4IP2	PWM4IP1	PWM4IP0	—	PWM3IP2	PWM3IP1	PWM3IP0	—	PWM2IP2	PWM2IP1	PWM2IP0
IPC18	864h	—	CNDIP2	CNDIP1	CNDIP0	—	PWM8IP2	PWM8IP1	PWM8IP0	—	PWM7IP2	PWM7IP1	PWM7IP0	—	PWM6IP2	PWM6IP1	PWM6IP0
IPC19	866h	—	CMP3IP2	CMP3IP1	CMP3IP0	—	CMP2IP2	CMP2IP1	CMP2IP0	—	CMP1IP2	CMP1IP1	CMP1IP0	—	CNEIP2	CNEIP1	CNEIP0
IPC20	868h	—	PTG1IP2	PTG1IP1	PTG1IP0	—	PTG0IP2	PTG0IP1	PTG0IP0	—	PTGWDTIP2	PTGWDTIP1	PTGWDTIP0	—	—	—	—
IPC21	86Ah	—	SENT1EIP2	SENT1EIP1	SENT1EIP0	—	SENT1IP2	SENT1IP1	SENT1IP0	—	PTG3IP2	PTG3IP1	PTG3IP0	—	PTG2IP2	PTG2IP1	PTG2IP0
IPC22	86Ch	—	ADCAN0IP2	ADCAN0IP1	ADCAN0IP0	—	ADCIP2	ADCIP1	ADCIP0	—	SENT2EIP2	SENT2EIP1	SENT2EIP0	—	SENT2IP2	SENT2IP1	SENT2IP0
IPC23	86Eh	—	ADCAN4IP2	ADCAN4IP1	ADCAN4IP0	—	ADCAN3IP2	ADCAN3IP1	ADCAN3IP0	—	ADCAN2IP2	ADCAN2IP1	ADCAN2IP0	—	ADCAN1IP2	ADCAN1IP1	ADCAN1IP0
IPC24	870h	—	ADCAN8IP2	ADCAN8IP1	ADCAN8IP0	—	ADCAN7IP2	ADCAN7IP1	ADCAN7IP0	—	ADCAN6IP2	ADCAN6IP1	ADCAN6IP0	—	ADCAN5IP2	ADCAN5IP1	ADCAN5IP0
IPC25	872h	—	ADCAN12IP2	ADCAN12IP1	ADCAN12IP0	—	ADCAN11IP2	ADCAN11IP1	ADCAN11IP0	—	ADCAN10IP2	ADCAN10IP1	ADCAN10IP0	—	ADCAN9IP2	ADCAN9IP1	ADCAN9IP0
IPC26	874h	—	ADCAN16IP2	ADCAN16IP1	ADCAN16IP0	—	ADCAN15IP2	ADCAN15IP1	ADCAN15IP0	—	ADCAN14IP2	ADCAN14IP1	ADCAN14IP0	—	ADCAN13IP2	ADCAN13IP1	ADCAN13IP0
IPC27	876h	—	ADCAN20IP2	ADCAN20IP1	ADCAN20IP0	—	ADCAN19IP2	ADCAN19IP1	ADCAN19IP0	—	ADCAN18IP2	ADCAN18IP1	ADCAN18IP0	—	ADCAN17IP2	ADCAN17IP1	ADCAN17IP0
IPC28	878h	—	ADFLTIP2	ADFLTIP1	ADFLTIP0	—	ADCAN23IP2	ADCAN23IP1	ADCAN23IP0	—	ADCAN22IP2	ADCAN22IP1	ADCAN22IP0	—	ADCAN21IP2	ADCAN21IP1	ADCAN21IP0
IPC29	87Ah	—	ADCM3IP2	ADCM3IP1	ADCM3IP0	—	ADCM2IP2	ADCM2IP1	ADCM2IP0	—	ADCM1IP2	ADCM1IP1	ADCM1IP0	—	ADCM0IP2	ADCM0IP1	ADCM0IP0
IPC30	87Ch	—	ADFLTR3IP2	ADFLTR3IP1	ADFLTR3IP0	—	ADFLTR2IP2	ADFLTR2IP1	ADFLTR2IP0	—	ADFLTR1IP2	ADFLTR1IP1	ADFLTR1IP0	—	ADFLTR0IP2	ADFLTR0IP1	ADFLTR0IP0
IPC31	87Eh	—	SPI2GIP0	SPI2GIP1	SPI2GIP0	—	SPI1GIP2	SPI1GIP1	SPI1GIP0	—	CLC2PIP2	CLC2PIP1	CLC2PIP0	—	CLC1PIP2	CLC1PIP1	CLC1PIP0
IPC32	880h	—	—	—	—	—	—	—	—	—	—	—	—	—	SPI3GIP2	SPI3GIP1	SPI3GIP0
IPC33	882h	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—
IPC34	884h	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—

Legend: — = Unimplemented.

TABLE 7-4: INTERRUPT PRIORITY REGISTERS (CONTINUED)

Register	Address	Bit 15	Bit14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	
IPC35	886h	—	MI2C3IP2	MI2C3IP1	MI2C3IP1	—	SI2C3IP2	SI2C3IP1	SI2C3IP0	—	—	—	—	—	—	—	—	
IPC36	888h	—	—	—	—	—	—	—	—	—	—	—	—	I2C3BCIP2	I2C3BCIP1	I2C3BCIP0		
IPC37	88Ah	—	—	—	—	—	CCT7IP2	CCT7IP1	CCT7IP0	—	CCP7IP2	CCP7IP1	CCP7IP0	—	—	—	—	
IPC38	88Ch	—	—	—	—	—	—	—	—	—	CCT8IP2	CCT8IP1	CCT8IP0	—	CCP8IP2	CCP8IP1	CCP8IP0	
IPC39	88Eh	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	
IPC40	890h	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	
IPC41	892h	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	
IPC42	894h	—	PEVTCIP2	PEVTCIP1	PEVTCIP0	—	PEVTBIP2	PEVTBIP1	PEVTBIP0	—	PEVTAIP2	PEVTAIP1	PEVTAIP0	—	AD FIFOIP2	AD FIFOIP1	AD FIFOIP0	
IPC43	896h	—	CLC3PIP2	CLC3PIP1	CLC3PIP0	—	PEVTFIP2	PEVTFIP1	PEVTFIP0	—	PEVTEIP2	PEVTEIP1	PEVTEIP0	—	PEVTDIP2	PEVTDIP1	PEVTDIP0	
IPC44	898h	—	CLC3NIP2	CLC3NIP1	CLC3NIP0	—	CLC2NIP2	CLC2NIP1	CLC2NIP0	—	CLC1NIP2	CLC1NIP1	CLC1NIP0	—	CLC4PIP2	CLC4PIP1	CLC4PIP0	
IPC45	89Ah	—	—	—	—	—	CCT9IP2	CCT9IP1	CCT9IP0	—	CCP9IP2	CCP9IP1	CCP9IP0	—	CLC4NIP2	CLC4NIP1	CLC4NIP0	
IPC46	89Ch	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	
IPC47	89Eh	—	U3EVTIP2	U3EVTIP1	U3EVTIP0	—	U2EVTIP2	U2EVTIP1	U2EVTIP0	—	U1EVTIP2	U1EVTIP1	U1EVTIP0	—	—	—	—	—
IPC48	900h	—	PMPEIP2	PMPEIP1	PMPEIP0	—	PMPIP2	PMPIP1	PMPIP0	—	ADCAN25IP2	ADCAN25IP1	ADCAN25IP0	—	ADCAN24IP2	ADCAN24IP1	ADCAN24IP0	

Legend: — = Unimplemented.

7.3 Interrupt Resources

Many useful resources are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page contains the latest updates and additional information.

7.3.1 KEY RESOURCES

- “**Interrupts**” (DS70000600) in the “*dsPIC33/PIC24 Family Reference Manual*”
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related “*dsPIC33/PIC24 Family Reference Manual*” Sections
- Development Tools

7.4 Interrupt Control and Status Registers

The dsPIC33CK256MP508 family devices implement the following registers for the interrupt controller:

- INTCON1
- INTCON2
- INTCON3
- INTCON4
- INTTREG

7.4.0.1 INTCON1 through INTCON4

Global interrupt control functions are controlled from INTCON1, INTCON2, INTCON3 and INTCON4.

INTCON1 contains the Interrupt Nesting Disable bit (NSTDIS), as well as the control and status flags for the processor trap sources.

The INTCON2 register controls external interrupt request signal behavior, contains the Global Interrupt Enable bit (GIE) and the Alternate Interrupt Vector Table Enable bit (AIVTEN).

INTCON3 contains the status flags for the Auxiliary PLL and DO stack overflow status trap sources.

The INTCON4 register contains the Software Generated Hard Trap Status bit (SGHT).

7.4.0.2 IFSx

The IFSx registers maintain all of the interrupt request flags. Each source of interrupt has a status bit, which is set by the respective peripherals or external signal and is cleared via software.

7.4.0.3 IECx

The IECx registers maintain all of the interrupt enable bits. These control bits are used to individually enable interrupts from the peripherals or external signals.

7.4.0.4 IPCx

The IPCx registers are used to set the Interrupt Priority Level (IPL) for each source of interrupt. Each user interrupt source can be assigned to one of seven priority levels.

7.4.0.5 INTTREG

The INTTREG register contains the associated interrupt vector number and the new CPU Interrupt Priority Level, which are latched into the Vector Number (VECNUM<7:0>) and Interrupt Level bits (ILR<3:0>) fields in the INTTREG register. The new Interrupt Priority Level is the priority of the pending interrupt.

The interrupt sources are assigned to the IFSx, IECx and IPCx registers in the same sequence as they are listed in Table 7-1. For example, INT0 (External Interrupt 0) is shown as having Vector Number 8 and a natural order priority of 0. Thus, the INT0IF bit is found in IFS0<0>, the INT0IE bit in IEC0<0> and the INT0IP<2:0> bits in the first position of IPC0 (IPC0<2:0>).

7.4.0.6 Status/Control Registers

Although these registers are not specifically part of the interrupt control hardware, two of the CPU Control registers contain bits that control interrupt functionality. For more information on these registers, refer to “**dsPIC33E Enhanced CPU**” (DS70005158) in the “*dsPIC33/PIC24 Family Reference Manual*”.

- The CPU STATUS Register, SR, contains the IPL<2:0> bits (SR<7:5>). These bits indicate the current CPU Interrupt Priority Level. The user software can change the current CPU Interrupt Priority Level by writing to the IPLx bits.
- The CORCON register contains the IPL3 bit, which together with IPL<2:0>, also indicates the current CPU priority level. IPL3 is a read-only bit so that trap events cannot be masked by the user software.

All Interrupt registers are described in Register 7-3 through Register 7-7 in the following pages.

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REGISTER 10-1: DMACON: DMA ENGINE CONTROL REGISTER

R/W-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
DMAEN	—	—	—	—	—	—	—
bit 15	bit 8						

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—	—	PRSSEL
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **DMAEN:** DMA Module Enable bit

1 = Enables module

0 = Disables module and terminates all active DMA operation(s)

bit 14-1 **Unimplemented:** Read as '0'

bit 0 **PRSSEL:** Channel Priority Scheme Selection bit

1 = Round robin scheme

0 = Fixed priority scheme

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REGISTER 11-42: C1TXQUAH: CAN TRANSMIT QUEUE USER ADDRESS REGISTER HIGH⁽¹⁾

R-x	R-x	R-x	R-x	R-x	R-x	R-x	R-x
TXQUA<31:24>							
bit 15							bit 8

R-x	R-x	R-x	R-x	R-x	R-x	R-x	R-x
TXQUA<23:16>							
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **TXQUA<31:16>: TXQ User Address bits**

A read of this register will return the address where the next message is to be written (TXQ head).

Note 1: This register is not ensured to read correctly in Configuration mode and should only be accessed when the module is not in Configuration mode.

REGISTER 11-43: C1TXQUAL: CAN TRANSMIT QUEUE USER ADDRESS REGISTER LOW⁽¹⁾

R-x	R-x	R-x	R-x	R-x	R-x	R-x	R-x
TXQUA<15:8>							
bit 15							bit 8

R-x	R-x	R-x	R-x	R-x	R-x	R-x	R-x
TXQUA<7:0>							
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **TXQUA<15:0>: TXQ User Address bits**

A read of this register will return the address where the next message is to be written (TXQ head).

Note 1: This register is not ensured to read correctly in Configuration mode and should only be accessed when the module is not in Configuration mode.

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REGISTER 11-44: C1TRECH: CAN TRANSMIT/RECEIVE ERROR COUNT REGISTER HIGH

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	R-1	R-0	R-0	R-0	R-0	R-0
—	—	TXBO	TXBP	RXBP	TXWARN	RXWARN	EWARN
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-6 **Unimplemented:** Read as '0'

bit 5 **TXBO:** Transmitter in Error State Bus Off bit (TERRCNT<7:0> > 255)

In Configuration mode, TXBO is set since the module is not on the bus.

bit 4 **TXBP:** Transmitter in Error State Bus Passive bit (TERRCNT<7:0> > 127)

bit 3 **RXBP:** Receiver in Error State Bus Passive bit (RERRCNT<7:0> > 127)

bit 2 **TXWARN:** Transmitter in Error State Warning bit (128 > TERRCNT<7:0> > 95)

bit 1 **RXWARN:** Receiver in Error State Warning bit (128 > RERRCNT<7:0> > 95)

bit 0 **EWARN:** Transmitter or Receiver in Error State Warning bit

REGISTER 11-45: C1TRECL: CAN TRANSMIT/RECEIVE ERROR COUNT REGISTER LOW

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
TERRCNT<7:0>							
bit 15							bit 8

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
RERRCNT<7:0>							
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8 **TERRCNT<7:0>:** Transmit Error Counter bits

bit 7-0 **RERRCNT<7:0>:** Receive Error Counter bits

12.0 HIGH-RESOLUTION PWM WITH FINE EDGE PLACEMENT

Note 1: This data sheet summarizes the features of the dsPIC33CK256MP508 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**High-Resolution PWM with Fine Edge Placement**” (DS70005320) in the “*dsPIC33/PIC24 Family Reference Manual*”, which is available from the Microchip web site (www.microchip.com).

The High-Speed PWM (HSPWM) module is a Pulse-Width Modulated (PWM) module to support both motor control and power supply applications. This flexible module provides features to support many types of Motor Control (MC) and Power Control (PC) applications, including:

- AC-to-DC Converters
- DC-to-DC Converters
- AC and DC Motors: BLDC, PMSM, ACIM, SRM, etc.
- Inverters
- Battery Chargers
- Digital Lighting
- Power Factor Correction (PFC)

12.1 Features

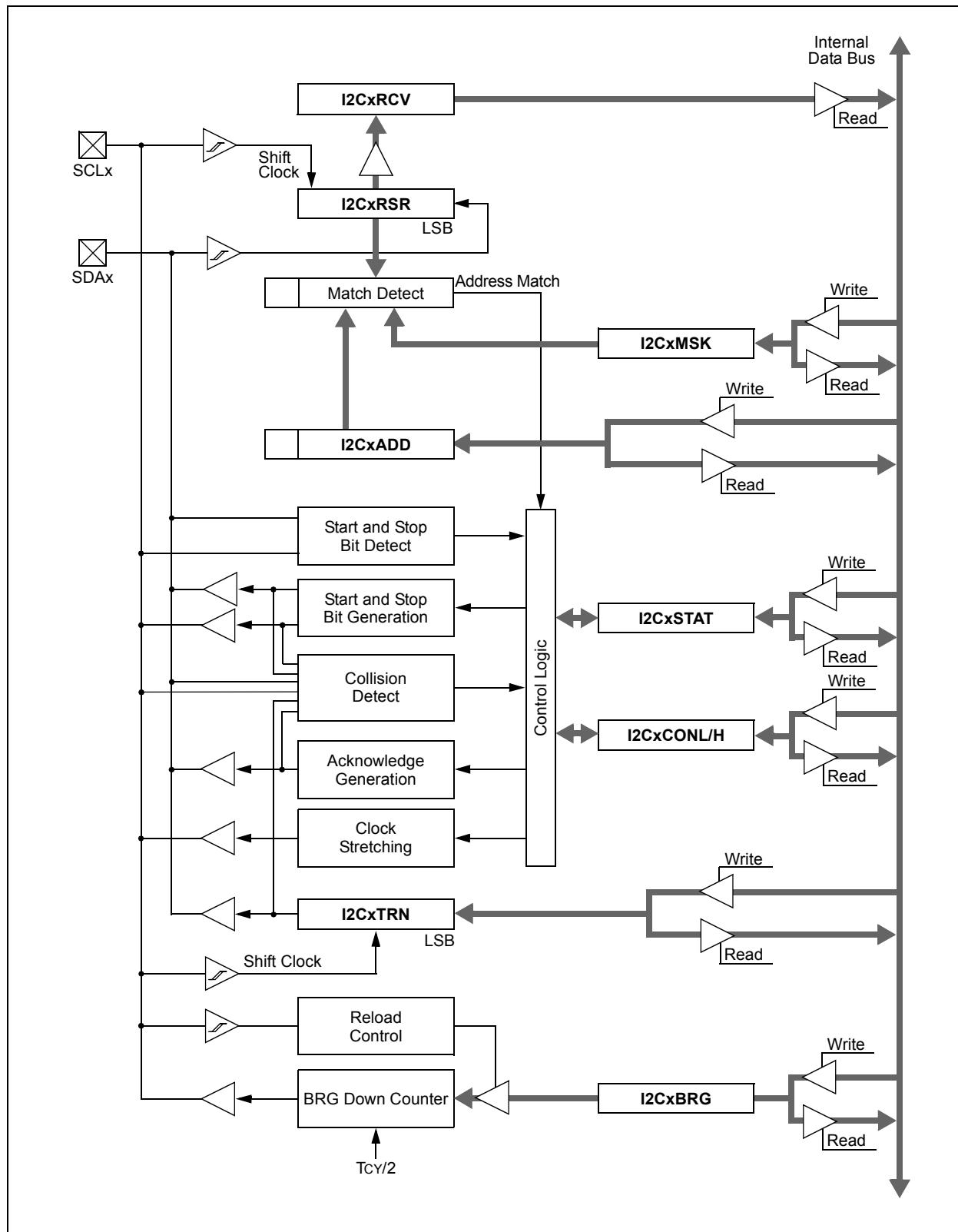
- 8 Independent PWM Generators, each with Dual Outputs
- Operating modes:
 - Independent Edge mode
 - Variable Phase PWM mode
 - Center-Aligned mode
 - Double Update Center-Aligned mode
 - Dual Edge Center-Aligned mode
 - Dual PWM mode
- Output modes:
 - Complementary
 - Independent
 - Push-Pull
- Dead-Time Generator
- Leading-Edge Blanking (LEB)
- Output Override for Fault Handling
- Flexible Period/Duty Cycle Updating Options
- Programmable Control Inputs (PCI)
- Advanced Triggering Options
- 6 Combinatorial Logic Outputs
- 6 PWM Event Outputs

REGISTER 16-3: UxSTA: UARTx STATUS REGISTER (CONTINUED)

bit 5	ABDOVF: Auto-Baud Rate Acquisition Interrupt Flag bit (must be cleared by software) 1 = BRG rolled over during the auto-baud rate acquisition sequence (must be cleared in software) 0 = BRG has not rolled over during the auto-baud rate acquisition sequence
bit 4	CERIF: Checksum Error Interrupt Flag bit (must be cleared by software) 1 = Checksum error 0 = No checksum error
bit 3	FERR: Framing Error Interrupt Flag bit 1 = Framing Error: Inverted level of the Stop bit corresponding to the topmost character in the buffer; propagates through the buffer with the received character 0 = No framing error
bit 2	RXBKIF: Receive Break Interrupt Flag bit (must be cleared by software) 1 = A Break was received 0 = No Break was detected
bit 1	OERR: Receive Buffer Overflow Interrupt Flag bit (must be cleared by software) 1 = Receive buffer has overflowed 0 = Receive buffer has not overflowed
bit 0	TXCIF: Transmit Collision Interrupt Flag bit (must be cleared by software) 1 = Transmitted word is not equal to the received word 0 = Transmitted word is equal to the received word

dsPIC33CK256MP508 FAMILY

FIGURE 18-1: I²Cx BLOCK DIAGRAM



dsPIC33CK256MP508 FAMILY

REGISTER 19-12: PMRADDR: PARALLEL MASTER PORT READ ADDRESS REGISTER⁽²⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
RCS2 ⁽¹⁾	RCS1 ⁽¹⁾				RADDR<13:8>		
RADDR15 ⁽¹⁾	RADDR14 ⁽¹⁾						
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
				RADDR<7:0>			
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **RCS2:** Chip Select 2 bit⁽¹⁾
 1 = Chip Select 2 is active
 0 = Chip Select 2 is inactive (RADDR15 function is selected)
bit 15 **RADDR15:** Target Read Address bit 15⁽¹⁾
bit 14 **RCS1:** Chip Select 1 bit⁽¹⁾
 1 = Chip Select 1 is active
 0 = Chip Select 1 is inactive (RADDR14 function is selected)
bit 14 **RADDR14:** Target Read Address bit 14⁽¹⁾
bit 13-0 **RADDR<13:0>:** Target Read Address bits

Note 1: The use of these pins as PMA15/PMA14 or RCS2/RCS1 is selected by the CSF<1:0> bits (PMCON<7:6>).

2: This register is only used when the DUALBUF bit (PMCONH<1>) is set to '1'.

dsPIC33CK256MP508 FAMILY

REGISTER 30-8: FICD CONFIGURATION REGISTER

U-1	U-1	U-1	U-1	U-1	U-1	U-1	U-1
—	—	—	—	—	—	—	—
bit 23							bit 16

R/PO-1	U-1						
NOBTSWP	—	—	—	—	—	—	—
bit 15							bit 8

r-1	U-1	R/PO-1	U-1	U-1	U-1	R/PO-1	R/PO-1
—	—	JTAGEN	—	—	—	ICS1	ICS0
bit 7							bit 0

Legend:

PO = Program Once bit

r = Reserved bit

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 23-16 **Unimplemented:** Read as '1'bit 15 **NOBTSWP:** BOOTSWP Instruction Disable bit

1 = BOOTSWP instruction is disabled

0 = BOOTSWP instruction is enabled

bit 14-8 **Unimplemented:** Read as '1'bit 7 **Reserved:** Maintain as '1'bit 6 **Unimplemented:** Read as '1'bit 5 **JTAGEN:** JTAG Enable bit

1 = JTAG port is enabled

0 = JTAG port is disabled

bit 4-2 **Unimplemented:** Read as '1'bit 1-0 **ICS<1:0>:** ICD Communication Channel Select bits

11 = Communicates on PGC1 and PGD1

10 = Communicates on PGC2 and PGD2

01 = Communicates on PGC3 and PGD3

00 = Reserved, do not use

dsPIC33CK256MP508 FAMILY

**TABLE 33-31: SPI_x SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = x, SMP = 0)
TIMING REQUIREMENTS**

Operating Conditions: 3.0V to 3.6V (unless otherwise stated)							
Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended							
Param No.	Symbol	Characteristic ⁽¹⁾	Min.	Typ. ⁽²⁾	Max.	Units	Conditions
SP10	FscP	Maximum SCK _x Input Frequency	—	—	15	MHz	Using PPS pins
			—	—	40	MHz	SPI _x dedicated pins
SP72	TscF	SCK _x Input Fall Time	—	—	—	ns	See Parameter DO32
SP73	TscR	SCK _x Input Rise Time	—	—	—	ns	See Parameter DO31
SP30	TdoF	SDO _x Data Output Fall Time	—	—	—	ns	See Parameter DO32
SP31	TdoR	SDO _x Data Output Rise Time	—	—	—	ns	See Parameter DO31
SP35	TscH2doV, TscL2doV	SDO _x Data Output Valid After SCK _x Edge	—	6	20	ns	
SP36	TdoV2scH, TdoV2scL	SDO _x Data Output Setup to First SCK _x Edge	30	—	—	ns	Using PPS pins
			20	—	—	ns	SPI _x dedicated pins
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCK _x Edge	30	—	—	ns	Using PPS pins
			10	—	—	ns	SPI _x dedicated pins
SP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCK _x Edge	30	—	—	ns	Using PPS pins
			15	—	—	ns	SPI _x dedicated pins
SP50	TssL2scH, TssL2scL	SS _x ↓ to SCK _x ↑ or SCK _x ↓ Input	120	—	—	ns	
SP51	TssH2doZ	SS _x ↑ to SDO _x Output High-Z	8	—	50	ns	
SP52	TscH2ssH, TscL2ssH	SS _x ↑ After SCK _x Edge	1.5 T _{CY} + 40	—	—	ns	

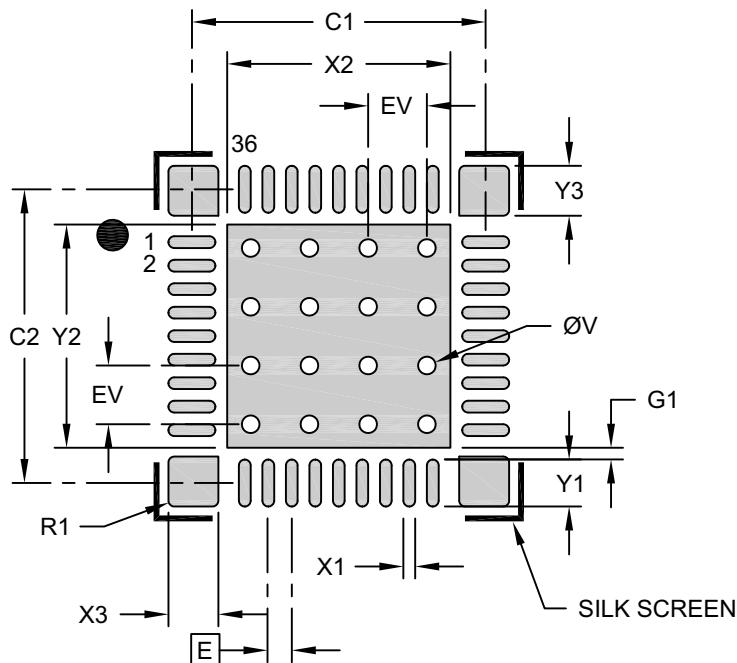
Note 1: These parameters are characterized but not tested in manufacturing.

2: Data in "Typ." column is at 3.3V, +25°C unless otherwise stated.

dsPIC33CK256MP508 FAMILY

36-Lead Ultra Thin Plastic Quad Flat, No Lead Package (M5) - 5x5 mm Body [UQFN] With Corner Anchors

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	0.40 BSC		
Optional Center Pad Width	X2			3.80
Optional Center Pad Length	Y2			3.80
Contact Pad Spacing	C1		5.00	
Contact Pad Spacing	C2		5.00	
Contact Pad Width (X36)	X1			0.20
Contact Pad Length (X36)	Y1			0.80
Corner Pad Width (X4)	X3			0.20
Corner Pad Length (X36)	Y3			0.85
Corner Pad Radius	R1		0.10	
Contact Pad to Center Pad (X36)	G1	0.20		
Thermal Via Diameter	V		0.30	
Thermal Via Pitch	EV		1.00	

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

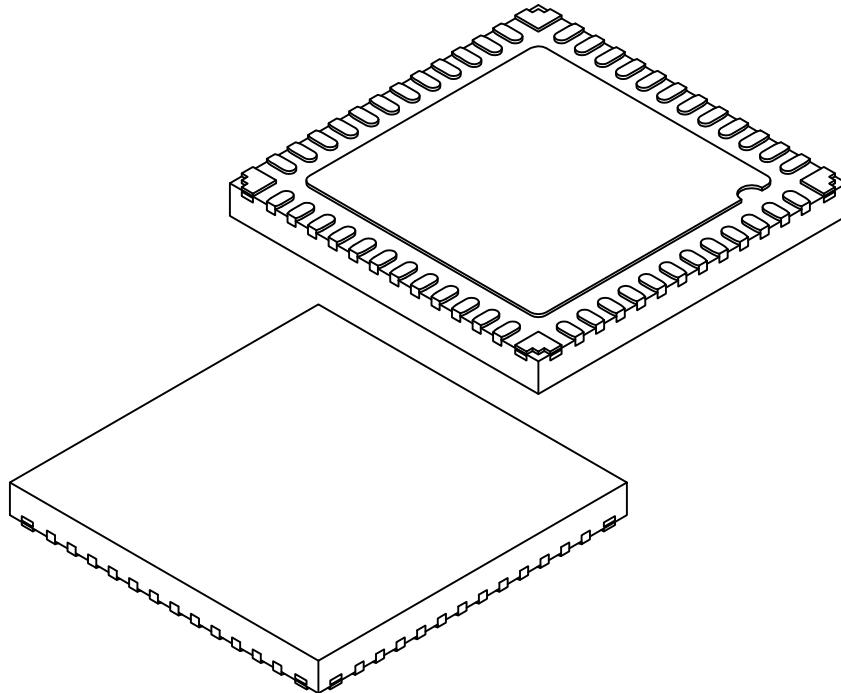
2. For best soldering results, thermal vias, if used, should be filled or tented to avoid solder loss during reflow process

Microchip Technology Drawing C04-2436A-M5

dsPIC33CK256MP508 FAMILY

48-Lead Ultra Thin Plastic Quad Flat, No Lead Package (M4) - 6x6 mm Body [UQFN] With Corner Anchors and 4.6x4.6 mm Exposed Pad

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Dimension Limits		MILLIMETERS		
		MIN	NOM	MAX
Number of Terminals	N		48	
Pitch	e		0.40 BSC	
Overall Height	A	0.50	0.55	0.60
Standoff	A1	0.00	0.02	0.05
Terminal Thickness	A3		0.15 REF	
Overall Length	D		6.00 BSC	
Exposed Pad Length	D2	4.50	4.60	4.70
Overall Width	E		6.00 BSC	
Exposed Pad Width	E2	4.50	4.60	4.70
Terminal Width	b	0.15	0.20	0.25
Corner Anchor Pad	b1		0.45 REF	
Corner Anchor Pad, Metal-free Zone	b2		0.23 REF	
Terminal Length	L	0.35	0.40	0.45
Terminal-to-Exposed-Pad	K		0.30 REF	

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. Package is saw singulated

3. Dimensioning and tolerancing per ASME Y14.5M

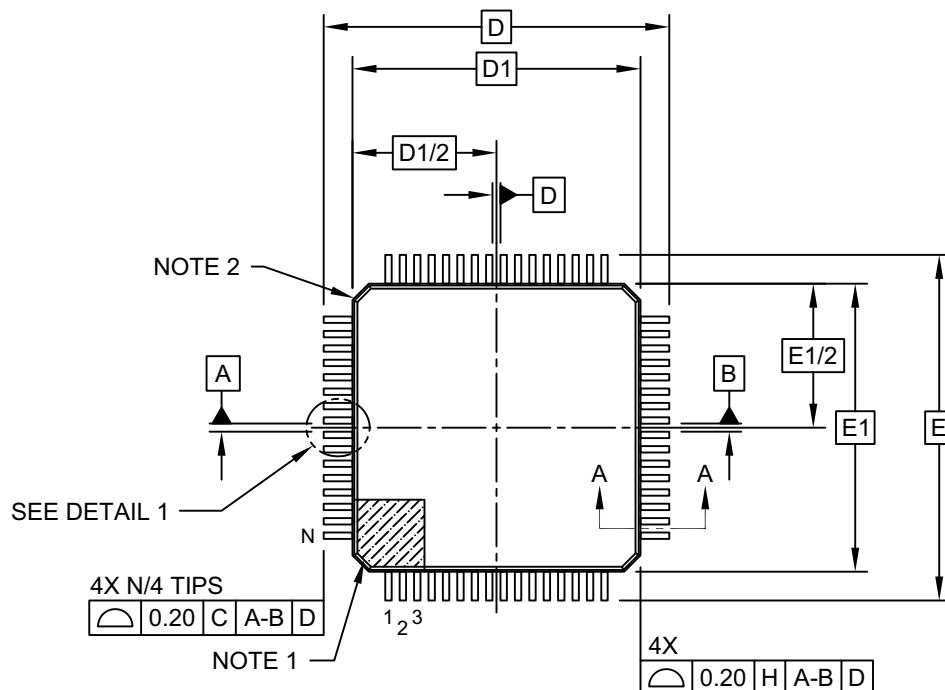
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

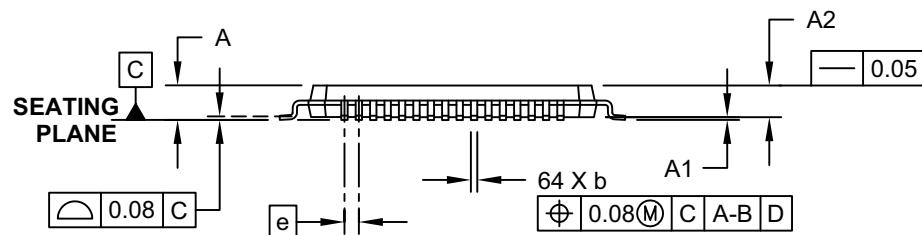
dsPIC33CK256MP508 FAMILY

64-Lead Plastic Thin Quad Flatpack (PT)-10x10x1 mm Body, 2.00 mm Footprint [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



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