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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
roduct Status	Active
Core Processor	dsPIC
Core Size	16-Bit
peed	100MHz
Connectivity	CANbus, I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART
eripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, QEI, WDT
lumber of I/O	21
rogram Memory Size	128KB (128K x 8)
rogram Memory Type	FLASH
EPROM Size	-
AM Size	16K x 8
oltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Oata Converters	A/D 12x12b; D/A 3x12b
Oscillator Type	Internal
perating Temperature	-40°C ~ 85°C (TA)
Nounting Type	Surface Mount
ackage / Case	28-UQFN Exposed Pad
upplier Device Package	28-UQFN (6x6)
urchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ck128mp502t-i-2n



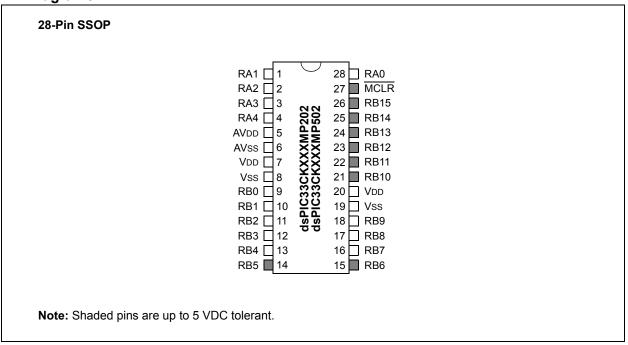


TABLE 3: 28-PIN SSOP

Pin#	Function	Pin#	Function
1	OA1IN-/ANA1/RA1	15	PGC3/RP38/SCL2/RB6
2	OA1IN+/AN9/RA2	16	TDO/AN2/CMP3A/RP39/SDA3/RB7
3	DACOUT1/AN3/CMP1C/RA3	17	PGD1/AN10/ <b>RP40</b> /SCL1/RB8
4	AN4/CMP3B/IBIAS3/RA4	18	PGC1/AN11/ <b>RP41</b> /SDA1/RB9
5	AVDD	19	Vss
6	AVss	20	VDD
7	VDD	21	TMS/ <b>RP42</b> /PWM3H/RB10
8	Vss	22	TCK/RP43/PWM3L/RB11
9	OSCI/CLKI/AN5/RP32/RB0	23	TDI/ <b>RP44</b> /PWM2H/RB12
10	OSCO/CLKO/AN6/RP33/RB1	24	RP45/PWM2L/RB13
11	OA2OUT/AN1/AN7/ANA0/CMP1D/CMP2D/CMP3D/ <b>RP34</b> / SCL3/INT0/RB2	25	RP46/PWM1H/RB14
12	PGD2/OA2IN-/AN8/ <b>RP35</b> /RB3	26	RP47/PWM1L/RB15
13	PGC2/OA2IN+/ <b>RP36</b> /RB4	27	MCLR
14	PGD3/ <b>RP37</b> /SDA2/RB5	28	OA1OUT/AN0/CMP1A/IBIAS0/RA0

Note: RPn represents remappable peripheral functions.

### 3.4.2 CPU RESOURCES

Many useful resources are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page contains the latest updates and additional information.

### 3.4.2.1 Key Resources

- "dsPIC33E Enhanced CPU" (DS70005158) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- · Application Notes
- · Software Libraries
- Webinars
- All related "dsPIC33/PIC24 Family Reference Manual" Sections
- · Development Tools

### 3.4.4 ARITHMETIC LOGIC UNIT (ALU)

The dsPIC33CK256MP508 family ALU is 16 bits wide and is capable of addition, subtraction, bit shifts and logic operations. Unless otherwise mentioned, arithmetic operations are two's complement in nature. Depending on the operation, the ALU can affect the values of the Carry (C), Zero (Z), Negative (N), Overflow (OV) and Digit Carry (DC) Status bits in the SR register. The C and DC Status bits operate as Borrow and Digit Borrow bits, respectively, for subtraction operations.

The ALU can perform 8-bit or 16-bit operations, depending on the mode of the instruction that is used. Data for the ALU operation can come from the W register array or data memory, depending on the addressing mode of the instruction. Likewise, output data from the ALU can be written to the W register array or a data memory location.

Refer to the "16-bit MCU and DSC Programmer's Reference Manual" (DS70000157) for information on the SR bits affected by each instruction.

The core CPU incorporates hardware support for both multiplication and division. This includes a dedicated hardware multiplier and support hardware for 16-bit divisor division.

### 3.4.4.1 Multiplier

Using the high-speed, 17-bit x 17-bit multiplier, the ALU supports unsigned, signed or mixed-sign operation in several MCU multiplication modes:

- · 16-bit x 16-bit signed
- 16-bit x 16-bit unsigned
- 16-bit signed x 5-bit (literal) unsigned
- 16-bit signed x 16-bit unsigned
- 16-bit unsigned x 5-bit (literal) unsigned
- 16-bit unsigned x 16-bit signed
- · 8-bit unsigned x 8-bit unsigned

### 3.4.4.2 Divider

The divide block supports 32-bit/16-bit and 16-bit/16-bit signed and unsigned integer divide operations with the following data sizes:

- · 32-bit signed/16-bit signed divide
- · 32-bit unsigned/16-bit unsigned divide
- 16-bit signed/16-bit signed divide
- 16-bit unsigned/16-bit unsigned divide

The 16-bit signed and unsigned DIV instructions can specify any W register for both the 16-bit divisor (Wn) and any W register (aligned) pair (W(m + 1):Wm) for the 32-bit dividend. The divide algorithm takes one cycle per bit of divisor, so both 32-bit/16-bit and 16-bit/16-bit instructions take the same number of cycles to execute. There are additional instructions: DIV2 and DIVF2. Divide instructions will complete in 6 cycles.

#### 3.4.5 DSP ENGINE

The DSP engine consists of a high-speed 17-bit x 17-bit multiplier, a 40-bit barrel shifter and a 40-bit adder/subtracter (with two target accumulators, round and saturation logic).

The DSP engine can also perform inherent accumulator-to-accumulator operations that require no additional data. These instructions are, ADD, SUB, NEG, MIN and MAX.

The DSP engine has options selected through bits in the CPU Core Control register (CORCON), as listed below:

- Fractional or integer DSP multiply (IF)
- Signed, unsigned or mixed-sign DSP multiply (USx)
- Conventional or convergent rounding (RND)
- Automatic saturation on/off for ACCA (SATA)
- Automatic saturation on/off for ACCB (SATB)
- Automatic saturation on/off for writes to data memory (SATDW)
- Accumulator Saturation mode selection (ACCSAT)

TABLE 3-2: DSP INSTRUCTIONS SUMMARY

Instruction	Algebraic Operation	ACC Write-Back						
CLR	A = 0	Yes						
ED	$A = (x - y)^2$	No						
EDAC	$A = A + (x - y)^2$	No						
MAC	$A = A + (x \bullet y)$	Yes						
MAC	$A = A + x^2$	No						
MOVSAC	No change in A	Yes						
MPY	$A = x \cdot y$	No						
MPY	$A = x^2$	No						
MPY.N	$A = -x \bullet y$	No						
MSC	$A = A - x \bullet y$	Yes						

TABLE 7-1: INTERRUPT VECTOR DETAILS

_	Vector	IRQ		In	Interrupt Bit Location			
Interrupt Source	Interrupt Source # # IVT Address		IVT Address	Flag	Enable	Priority		
INT0 – External Interrupt 0	8	0	0x000014	IFS0<0>	IEC0<0>	IPC0<2:0>		
T1 – Timer1	9	1	0x000016	IFS0<1>	IEC0<1>	IPC0<6:4>		
CNA – Change Notice Interrupt A	10	2	0x000018	IFS0<2>	IEC0<2>	IPC0<10:8>		
CNB – Change Notice Interrupt B	11	3	0x00001A	IFS0<3>	IEC0<3>	IPC0<14:12>		
DMA0 – DMA Channel 0	12	4	0x00001C	IFS0<4>	IEC0<4>	IPC1<2:0>		
Reserved	13	5	0x00001E	_	_	_		
CCP1 – Input Capture/Output Compare 1	14	6	0x000020	IFS0<6>	IEC0<6>	IPC1<10:8>		
CCT1 – CCP1 Timer	15	7	0x000022	IFS0<7>	IEC0<7>	IPC1<14:12>		
DMA1 – DMA Channel 1	16	8	0x000024	IFS0<8>	IEC0<8>	IPC2<2:0>		
SPI1RX – SPI1 Receiver	17	9	0x000026	IFS0<9>	IEC0<9>	IPC2<6:4>		
SPI1TX – SPI1 Transmitter	18	10	0x000028	IFS0<10>	IEC0<10>	IPC2<10:8>		
U1RX – UART1 Receiver	19	11	0x00002A	IFS0<11>	IEC0<11>	IPC2<14:12>		
U1TX – UART1 Transmitter	20	12	0x00002C	IFS0<12>	IEC0<12>	IPC3<2:0>		
ECCSBE – ECC Single Bit Error	21	13	0x00002E	IFS0<13>	IEC0<13>	IPC3<6:4>		
NVM – NVM Write Complete	22	14	0x000030	IFS0<14>	IEC0<14>	IPC3<10:8>		
INT1 – External Interrupt 1	23	15	0x000032	IFS0<15>	IEC0<15>	IPC3<14:12>		
SI2C1 – I2C1 Slave Event	24	16	0x000034	IFS1<0>	IEC1<0>	IPC4<2:0>		
MI2C1 – I2C1 Master Event	25	17	0x000036	IFS1<1>	IEC1<1>	IPC4<6:4>		
DMA2 – DMA Channel 2	26	18	0x000038	IFS1<2>	IEC1<2>	IPC4<10:8>		
CNC – Change Notice Interrupt C	27	19	0x00003A	IFS1<3>	IEC1<3>	IPC4<14:12>		
INT2 – External Interrupt 2	28	20	0x00003C	IFS1<4>	IEC1<4>	IPC5<2:0>		
DMA3 – DMA Channel 3	29	21	0x00003E	IFS1<5>	IEC1<5>	IPC5<6:4>		
Reserved	30	22	0x000040	_	1	_		
CCP2 – Input Capture/Output Compare 2	31	23	0x000042	IFS1<7>	IEC1<7>	IPC5<14:12>		
CCT2 – CCP2 Timer	32	24	0x000044	IFS1<8>	IEC1<8>	IPC6<2:0>		
CAN1 – CAN1 Combined Error	33	25	0x000046	IFS1<9>	IEC1<9>	IPC6<6:4>		
INT3 – External Interrupt 3	34	26	0x000048	IFS1<10>	IEC1<10>	IPC6<10:8>		
U2RX – UART2 Receiver	35	27	0x00004A	IFS1<11>	IEC1<11>	IPC6<14:12>		
U2TX – UART2 Transmitter	36	28	0x00004C	IFS1<12>	IEC1<12>	IPC7<2:0>		
SPI2RX – SPI2 Receiver	37	29	0x00004E	IFS1<13>	IEC1<13>	IPC7<6:4>		
SPI2TX – SPI2 Transmitter	38	30	0x000050	IFS1<14>	IEC1<14>	IPC7<10:8>		
C1RX – CAN1 RX Data Ready	39	31	0x000052	IFS1<15>	IEC1<15>	IPC7<14:12>		
Reserved	40-42	32-34	0x000054-0x000058	_	-	_		
CCP3 – Input Capture/Output Compare 3	43	35	0x00005A	IFS2<3>	IEC2<3>	IPC8<14:12>		
CCT3 – CCP3 Timer	44	36	0x00005C	IFS2<4>	IEC2<4>	IPC9<2:0>		
SI2C2 - I2C2 Slave Event	45	37	0x00005E	IFS2<5>	IEC2<5>	IPC9<6:4>		
MI2C2 – I2C2 Master Event	46	38	0x000060	IFS2<6>	IEC2<6>	IPC9<10:8>		
Reserved	47	39	0x000062	_	_	_		
CCP4 – Input Capture/Output Compare 4	48	40	0x000064	IFS2<8>	IEC2<8>	IPC10<2:0>		
CCT4 – CCP4 Timer	49	41	0x000066	IFS2<9>	IEC2<9>	IPC10<6:4>		
Reserved	50	42	0x000068	_	_	_		
CCP5 – Input Capture/Output Compare 5	51	43	0x00006A	IFS2<11>	IEC2<11>	IPC10<14:12>		
CCT5 – CCP5 Timer	52	44	0x00006C	IFS2<12>	IEC2<12>	IPC11<2:0>		
DMT – Deadman Timer	53	45	0x00006E	IFS2<13>	IEC2<13>	IPC11<6:4>		
CCP6 - Input Capture/Output Compare 6	54	46	0x000070	IFS2<14>	IEC2<14>	IPC11<10:8>		
CCT6 – CCP6 Timer	55	47	0x000072	IFS2<15>	IEC2<15>	IPC11<14:12>		

### REGISTER 7-3: INTCON1: INTERRUPT CONTROL REGISTER 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NSTDIS	OVAERR	OVBERR	COVAERR	COVBERR	OVATE	OVBTE	COVTE
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
SFTACERR	DIV0ERR	DMACERR	MATHERR	ADDRERR	STKERR	OSCFAIL	_
bit 7							bit 0

Legend	
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R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15 **NSTDIS:** Interrupt Nesting Disable bit

1 = Interrupt nesting is disabled0 = Interrupt nesting is enabled

bit 14 **OVAERR:** Accumulator A Overflow Trap Flag bit

1 = Trap was caused by an overflow of Accumulator A

0 = Trap was not caused by an overflow of Accumulator A

bit 13 OVBERR: Accumulator B Overflow Trap Flag bit

1 = Trap was caused by an overflow of Accumulator B

0 = Trap was not caused by an overflow of Accumulator B

bit 12 COVAERR: Accumulator A Catastrophic Overflow Trap Flag bit

1 = Trap was caused by a catastrophic overflow of Accumulator A

0 = Trap was not caused by a catastrophic overflow of Accumulator A

bit 11 COVBERR: Accumulator B Catastrophic Overflow Trap Flag bit

1 = Trap was caused by a catastrophic overflow of Accumulator B

0 = Trap was not caused by a catastrophic overflow of Accumulator B

bit 10 **OVATE:** Accumulator A Overflow Trap Enable bit

1 = Trap overflow of Accumulator A

0 = Trap is disabled

bit 9 **OVBTE:** Accumulator B Overflow Trap Enable bit

1 = Trap overflow of Accumulator B

0 = Trap is disabled

bit 8 **COVTE**: Catastrophic Overflow Trap Enable bit

1 = Trap catastrophic overflow of Accumulator A or B is enabled

0 = Trap is disabled

bit 7 SFTACERR: Shift Accumulator Error Status bit

1 = Math error trap was caused by an invalid accumulator shift

0 = Math error trap was not caused by an invalid accumulator shift

bit 6 **DIV0ERR:** Divide-by-Zero Error Status bit

1 = Math error trap was caused by a divide-by-zero

0 = Math error trap was not caused by a divide-by-zero

bit 5 DMACERR: DMA Controller Trap Status bit

1 = DMAC error trap has occurred

0 = DMAC error trap has not occurred

bit 4 MATHERR: Math Error Status bit

1 = Math error trap has occurred

0 = Math error trap has not occurred

### REGISTER 9-5: PLLDIV: PLL OUTPUT DIVIDER REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
_	_	_	_	_	_	VCODIV1	VCODIV0
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-1
_	POST1DIV2 <sup>(1,2)</sup>	POST1DIV1 <sup>(1,2)</sup>	POST1DIV0 <sup>(1,2)</sup>	_	POST2DIV2 <sup>(1,2)</sup>	POST2DIV1 <sup>(1,2)</sup>	POST2DIV0 <sup>(1,2)</sup>
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-10 Unimplemented: Read as '0'

bit 9-8 VCODIV<1:0>: PLL VCO Output Divider Select bits

11 **=** Fvco

10 = Fvco/2

01 = Fvco/3

00 = Fvco/4

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **POST1DIV<2:0>:** PLL Output Divider #1 Ratio bits<sup>(1,2)</sup>

POST1DIV<2:0> can have a valid value, from 1 to 7 (POST1DIVx value should be greater than or equal to the POST2DIVx value). The POST1DIVx divider is designed to operate at higher clock rates than the POST2DIVx divider.

bit 3 Unimplemented: Read as '0'

bit 2-0 POST2DIV<2:0>: PLL Output Divider #2 Ratio bits<sup>(1,2)</sup>

POST2DIV<2:0> can have a valid value, from 1 to 7 (POST2DIVx value should be less than or equal to the POST1DIVx value). The POST1DIVx divider is designed to operate at higher clock rates than the POST2DIVx divider.

- Note 1: The POST1DIVx and POST2DIVx divider values must not be changed while the PLL is operating.
  - 2: The default values for POST1DIVx and POST2DIVx are 4 and 1, respectively, yielding a 150 MHz system source clock.

### REGISTER 11-37: C1TEFSTA: CAN TRANSMIT EVENT FIFO STATUS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_	_	_	_	_	_	_	_
bit 15							bit 8

U-0	U-0	U-0	U-0	S/HC-0	R-0	R-0	R-0
_	_	_	_	TEFOVIF	TEFFIF <sup>(1)</sup>	TEFHIF <sup>(1)</sup>	TEFNEIF <sup>(1)</sup>
bit 7							bit 0

Legend:	HC = Hardware Clearable bit	S = Settable bit Can Set by '1'	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-4 Unimplemented: Read as '0'

bit 3 **TEFOVIF:** Transmit Event FIFO Overflow Interrupt Flag bit

1 = Overflow event has occurred0 = No overflow event has occurred

bit 2 **TEFFIF:** Transmit Event FIFO Full Interrupt Flag bit<sup>(1)</sup>

1 = FIFO is full 0 = FIFO is not full

bit 1 **TEFHIF:** Transmit Event FIFO Half Full Interrupt Flag bit<sup>(1)</sup>

1 = FIFO is ≥ half full 0 = FIFO is < half full

bit 0 **TEFNEIF:** Transmit Event FIFO Not Empty Interrupt Flag bit<sup>(1)</sup>

1 = FIFO is not empty 0 = FIFO is empty

Note 1: These bits are read-only and reflect the status of the FIFO.

### REGISTER 12-13: PGxCONH: PWM GENERATOR x CONTROL REGISTER HIGH (CONTINUED)

- bit 6

  TRGMOD: PWM Generator Trigger Mode Selection bit

  1 = PWM Generator operates in Retriggerable mode

  0 = PWM Generator operates in Single Trigger mode

  bit 5-4

  Unimplemented: Read as '0'

  bit 3-0

  SOCS<3:0>: Start-of-Cycle Selection bits(1,2,3)

  1111 = TRIG bit or PCI Sync function only (no hardware trigger source is selected)

  1110-0101 = Reserved

  0100 = Trigger output selected by PG4 or PG8 PGTRGSEL<2:0> bits (PGxEVTL<2:0>)

  0011 = Trigger output selected by PG3 or PG7 PGTRGSEL<2:0> bits (PGxEVTL<2:0>)

  0010 = Trigger output selected by PG2 or PG6 PGTRGSEL<2:0> bits (PGxEVTL<2:0>)

  0001 = Trigger output selected by PG1 or PG5 PGTRGSEL<2:0> bits (PGxEVTL<2:0>)

  0000 = Local EOC PWM Generator is self-triggered
- **Note 1:** The PCI selected Sync signal is always available to be OR'd with the selected SOC signal per the SOCS<3:0> bits if the PCI Sync function is enabled.
  - 2: The source selected by the SOCS<3:0> bits MUST operate from the same clock source as the local PWM Generator. If not, the source must be routed through the PCI Sync logic so the trigger signal may be synchronized to the PWM Generator clock domain.
  - **3:** PWM Generators are grouped into groups of four: PG1-PG4 and PG5-PG8, if available. Any generator within a group of four may be used to trigger another generator within the same group.

#### REGISTER 12-30: PGxDTL: PWM GENERATOR x DEAD-TIME REGISTER LOW

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	_			DTL<1	13:8> <sup>(1)</sup>		
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DTL<7:0>							
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-14 Unimplemented: Read as '0'

bit 13-0 DTL<13:0>: PWMxL Dead-Time Delay bits<sup>(1)</sup>

**Note 1:** DTL<13:11> bits are not available when HREN (PGxCONL<7>) = 0.

### REGISTER 12-31: PGxDTH: PWM GENERATOR x DEAD-TIME REGISTER HIGH

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	_			DTH<1	13:8> <sup>(1)</sup>		
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			DTH	l<7:0>			
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-14 Unimplemented: Read as '0'

bit 13-0 **DTH<13:0>:** PWMxH Dead-Time Delay bits<sup>(1)</sup>

**Note 1:** DTH<13:11> bits are not available when HREN (PGxCONL<7>) = 0.

### REGISTER 16-13: UxTXCHK: UARTx TRANSMIT CHECKSUM REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_	_	_	_	_	_	_	_
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
	TXCHK<7:0>									
bit 7							bit 0			

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7-0 **TXCHK<7:0>:** Transmit Checksum bits (calculated from TX words)

LIN Modes:

C0EN = 1: Sum of all transmitted data + addition carries, including PID. C0EN = 0: Sum of all transmitted data + addition carries, excluding PID.

LIN Slave:

Cleared when Break is detected.

LIN Master/Slave:

Cleared when Break is detected.

Other Modes:

C0EN = 1: Sum of every byte transmitted + addition carries.

C0EN = 0: Value remains unchanged.

#### REGISTER 16-16: UXSCINT: UARTX SMART CARD INTERRUPT REGISTER

U-0	U-0	R/W-0, HS	R/W-0, HS	U-0	R/W-0, HS	R/W-0, HS	R/W-0, HS
_	_	RXRPTIF	TXRPTIF	_	BTCIF	WTCIF	GTCIF
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
_	_	RXRPTIE	TXRPTIE	_	BTCIE	WTCIE	GTCIE
bit 7							bit 0

Legend:HS = Hardware Settable bitR = Readable bitW = Writable bitU = Unimplemented bit, read as '0'-n = Value at POR'1' = Bit is set'0' = Bit is clearedx = Bit is unknown

bit 15-14 Unimplemented: Read as '0'

bit 13 RXRPTIF: Receive Repeat Interrupt Flag bit

1 = Parity error has persisted after the same character has been received five times (four retransmits)

0 = Flag is cleared

bit 12 **TXRPTIF:** Transmit Repeat Interrupt Flag bit

1 = Line error has been detected after the last retransmit per TXRPT<1:0>

0 = Flag is cleared

bit 11 **Unimplemented:** Read as '0'

bit 9

bit 10 **BTCIF:** Block Time Counter Interrupt Flag bit

1 = Block Time Counter has reached 00 = Block Time Counter has not reached 0

WTCIF: Waiting Time Counter Interrupt Flag bit

1 = Waiting Time Counter has reached 00 = Waiting Time Counter has not reached 0

bit 8 GTCIF: Guard Time Counter Interrupt Flag bit

1 = Guard Time Counter has reached 0

0 = Guard Time Counter has not reached 0

bit 7-6 Unimplemented: Read as '0'

bit 5 RXRPTIE: Receive Repeat Interrupt Enable bit

1 = An interrupt is invoked when a parity error has persisted after the same character has been

received five times (four retransmits)

0 = Interrupt is disabled

bit 4 **TXRPTIE:** Transmit Repeat Interrupt Enable bit

1 = An interrupt is invoked when a line error is detected after the last retransmit per TXRPT<1:0> has

been completed

0 = Interrupt is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2 BTCIE: Block Time Counter Interrupt Enable bit

1 = Block Time Counter interrupt is enabled

0 = Block Time Counter interrupt is disabled

bit 1 WTCIE: Waiting Time Counter Interrupt Enable bit

1 = Waiting Time Counter interrupt is enabled

0 = Waiting Time Counter Interrupt is disabled

bit 0 GTCIE: Guard Time Counter interrupt enable bit

1 = Guard Time Counter interrupt is enabled

0 = Guard Time Counter interrupt is disabled

**NOTES:** 

### REGISTER 20-3: SENTxDATL: SENTx RECEIVE DATA REGISTER LOW(1)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	DATA4<3:0> DATA5<3:0>						
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
	DATA6	<3:0>		CRC<3:0>				
bit 7							bit 0	

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-12 DATA4<3:0>: Data Nibble 4 Data bits
bit 11-8 DATA5<3:0>: Data Nibble 5 Data bits
bit 7-4 DATA6<3:0>: Data Nibble 6 Data bits
bit 3-0 CRC<3:0>: CRC Nibble Data bits

**Note 1:** Register bits are read-only in Receive mode (RCVEN = 1). In Transmit mode, the CRC<3:0> bits are read-only when automatic CRC calculation is enabled (RCVEN = 0, CRCEN = 1).

### REGISTER 20-4: SENTxDATH: SENTx RECEIVE DATA REGISTER HIGH<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
	STAT<	<3:0>		DATA1<3:0>				
bit 15							bit 8	

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
	DATA2	<3:0>		DATA3<3:0>				
bit 7							bit 0	

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-12 STAT<3:0>: Status Nibble Data bits
bit 11-8 DATA1<3:0>: Data Nibble 1 Data bits
bit 7-4 DATA2<3:0>: Data Nibble 2 Data bits
bit 3-0 DATA3<3:0>: Data Nibble 3 Data bits

**Note 1:** Register bits are read-only in Receive mode (RCVEN = 1). In Transmit mode, the CRC<3:0> bits are read-only when automatic CRC calculation is enabled (RCVEN = 0, CRCEN = 1).

### REGISTER 24-11: PTGADJ: PTG ADJUST REGISTER<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
	PTGADJ<15:8>									
bit 15							bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
	PTGADJ<7:0>								
bit 7							bit 0		

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

#### bit 15-0 **PTGADJ<15:0>:** PTG Adjust Register bits

This register holds the user-supplied data to be added to the PTGTxLIM, PTGCxLIM, PTGSDLIM or PTGL0 register using the PTGADD command.

Note 1: These bits are read-only when the module is executing Step commands.

### REGISTER 24-12: PTGL0: PTG LITERAL 0 REGISTER<sup>(1,2)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
	PTGL0<15:8>									
bit 15							bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
PTGL0<7:0>									
bit 7									

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

### bit 15-0 PTGL0<15:0>: PTG Literal 0 Register bits

This register holds the 6-bit value to be written to the CNVCHSEL<5:0> bits (ADCON3L<5:0>) with the PTGCTRL Step command.

- **Note 1:** These bits are read-only when the module is executing Step commands.
  - 2: The PTG strobe output is typically connected to the ADC Channel Select register. This allows the PTG to directly control ADC channel switching. See the specific device data sheet for connections of the PTG output.

### TABLE 33-5: OPERATING CURRENT (IDD)(2)

Operating Conditions: 3.0V to 3.6V (unless otherwise stated)

Operating temperature  $-40^{\circ}\text{C} \le \text{Ta} \le +85^{\circ}\text{C}$  for Industrial  $-40^{\circ}\text{C} \le \text{Ta} \le +125^{\circ}\text{C}$  for Extended

-40°C ≤ TA ≤ +125°C for Extended									
Parameter No.	Typ. <sup>(1)</sup>	Max.	Units			Conditions			
DC20	7.76	10.7	mA	-40°C					
	7.49	10	mA	+25°C	3.3V	10 MIPS (N1 = 1, N2 = 5, N3 = 2, M = 50, Fvco = 400 MHz,			
	7.82	12.2	mA	+85°C	3.34	FPLLO = 40 MHz)			
	10.32	20.45	mA	+125°C		,			
DC21	10.36	13.1	mA	-40°C					
	10.09	12.45	mA	+25°C	3.3V	20 MIPS (N1 = 1, N2 = 5, N3 = 1,			
	10.42	14.5	mA	+85°C	3.30	M = 50, Fvco = 400 MHz, FPLLO = 80 MHz)			
	12.89	23.45	mA	+125°C					
DC22	14.54	17.45	mA	-40°C					
	14.26	16.7	mA	+25°C	3.3V	40 MIPS (N1 = 1, N2 = 3, N3 = 1, M = 60, Fvco = 480 MHz,			
	14.58	18.9	mA	+85°C		FPLLO = 160 MHz)			
	17.06	27.4	mA	+125°C		<u>,                                      </u>			
DC23	22.2	25.4	mA	-40°C					
	21.91	24.9	mA	+25°C	3.3V	70 MIPS (N1 = 1, N2 = 2, N3 = 1,			
	22.21	27	mA	+85°C	3.30	M = 70, Fvco = 560 MHz, Fpllo = 280 MHz)			
	24.65	35.1	mA	+125°C		200 1011 127			
DC24	27.36	30.7	mA	-40°C					
	26.96	30.5	mA	+25°C	2 2)/	90 MIPS (N1 = 1, N2 = 2, N3 = 1,			
	26.68	31.7	mA	+85°C	3.3V	M = 90, Fvco = 720 MHz, Fpllo = 360 MHz)			
	29.01	39.9	mA	+125°C		11228 300 1111 127			
DC25	27.14	30.9	mA	-40°C					
	26.54	30.1	mA	+25°C	2 2)/	100 MIPS (N1 = 1, N2 = 1,			
	26.79	31.7	mA	+85°C	3.3V	N3 = 1, M = 50, Fvco = 400 MHz, FPLLO = 400 MHz)			
	29.23	40	mA	+125°C					

Note 1: Data in the "Typ." column are for design guidance only and are not tested.

- 2: Base Run current (IDD) is measured as follows:
  - · Oscillator is switched to EC+PLL mode in software
  - OSC1 pin is driven with external 8 MHz square wave with levels from 0.3V to VDD 0.3V
  - OSC2 is configured as an I/O in the Configuration Words (OSCIOFCN (FOSC<2>) = 0)
  - FSCM is disabled (FCKSM<1:0> (FOSC<7:6>) = 01)
  - Watchdog Timer is disabled (FWDT<15> = 0 and WDTCONL<15> = 0)
  - · All I/O pins (except OSC1) are configured as outputs and driving low
  - No peripheral modules are operating or being clocked (defined PMDx bits are all '1's)
  - JTAG is disabled (JTAGEN (FICD<5>) = 0)
  - NOP instructions are executed in while(1) loop

### TABLE 33-16: I/O PIN INPUT INJECTION CURRENT SPECIFICATIONS

Operating Conditions: 3.0V to 3.6V (unless otherwise stated)

Operating temperature  $-40^{\circ}\text{C} \le \text{TA} \le +85^{\circ}\text{C}$  for Industrial

 $-40^{\circ}C \le TA \le +125^{\circ}C$  for Extended

Param No.	Symbol	Characteristic	Min.	Max.	Units	Conditions
DI60a	licl	Input Low Injection Current	0	-5 <sup>(1,4)</sup>	mA	All pins
DI60b	lich	Input High Injection Current	0	+5(2,3,4)	mA	All pins, excepting all 5V tolerant pins and SOSCI
DI60c	∑lict	Total Input Injection Current (sum of all I/O and control pins) <sup>(5)</sup>	-20	+20	mA	Absolute instantaneous sum of all $\pm$ input injection currents from all I/O pins (   IICL   +   IICH   ) $\leq \sum$ IICT

Note 1: VIL Source < (VSS - 0.3).

- 2: VIH Source > (VDD + 0.3) for non-5V tolerant pins only.
- **3:** 5V tolerant pins do not have an internal high-side diode to VDD, and therefore, cannot tolerate any "positive" input injection current.
- 4: Injection currents can affect the ADC results.
- 5: Any number and/or combination of I/O pins, not excluded under IICL or IICH conditions, are permitted in the sum.

### TABLE 33-17: I/O PIN OUTPUT SPECIFICATIONS

Operating Conditions: 3.0V to 3.6V (unless otherwise stated)

Operating temperature  $-40^{\circ}C \le TA \le +85^{\circ}C$  for Industrial

-40°C ≤ TA ≤ +125°C for Extended

		40 0 3 IA 3 1 IZO 0 II	OI EXICII	aca			
Param.	Symbol	Characteristic	Min.	Тур.	Max.	Units	Conditions
DO10	Vol	Output Low Voltage 4x Sink Driver Pins	_	_	0.42	V	VDD = 3.6V, IOL < 9 mA
		Output Low Voltage 8x Sink Driver Pins <sup>(1)</sup>	_	_	0.4	V	VDD = 3.6V, IOL < 11 mA
DO20	Vон	Output High Voltage 4x Source Driver Pins	2.4	_	_	V	VDD = 3.6V, IOH > -8 mA
		Output High Voltage 8x Source Driver Pins <sup>(1)</sup>	2.4	_	_	V	VDD = 3.6V, IOH > -12 mA

Note 1: 8x sink/source pins are RB1, RC8, RC9 and RD8.

### TABLE 33-34: I2Cx BUS DATA TIMING REQUIREMENTS (SLAVE MODE)

Operating Conditions: 3.0V to 3.6V (unless otherwise stated)

Operating temperature  $-40^{\circ}\text{C} \le \text{TA} \le +85^{\circ}\text{C}$  for Industrial  $-40^{\circ}\text{C} \le \text{TA} \le +125^{\circ}\text{C}$  for Extended

Param No.	Symbol	Characte	eristic <sup>(3)</sup>	Min.	Max.	Units	Conditions
IS10	TLO:SCL	Clock Low Time	100 kHz mode	4.7	_	μs	
			400 kHz mode	1.3	_	μs	
			1 MHz mode <sup>(1)</sup>	0.5	_	μs	
IS11	THI:SCL	Clock High Time	100 kHz mode	4.0	_	μs	Device must operate at a minimum of 1.5 MHz
			400 kHz mode	0.6	_	μs	Device must operate at a minimum of 10 MHz
			1 MHz mode <sup>(1)</sup>	0.26	_	μs	
IS20	TF:SCL	SDAx and SCLx	100 kHz mode	_	300	ns	CB is specified to be from
		Fall Time	400 kHz mode	20 x (VDD/5.5V)	300	ns	10 to 400 pF
			1 MHz mode <sup>(1)</sup>	20 x (VDD/5.5V)	120	ns	
IS21	TR:SCL	SDAx and SCLx	100 kHz mode	_	1000	ns	CB is specified to be from
		Rise Time	400 kHz mode	20 + 0.1 CB	300	ns	10 to 400 pF
			1 MHz mode <sup>(1)</sup>	_	120	ns	
IS25	TSU:DAT	Data Input	100 kHz mode	250		ns	
		Setup Time	400 kHz mode	100		ns	
			1 MHz mode <sup>(1)</sup>	50	_	ns	
IS26 THD:DA	THD:DAT	Data Input	100 kHz mode	0		μs	
		Hold Time	400 kHz mode	0	0.9	μs	
			1 MHz mode <sup>(1)</sup>	0	0.3	μs	
IS30	Tsu:sta	Start Condition Setup Time	100 kHz mode	4.7	_	μs	Only relevant for Repeated
			400 kHz mode	0.6	_	μs	Start condition
			1 MHz mode <sup>(1)</sup>	0.26	_	μs	
IS31	THD:STA	Start Condition	100 kHz mode	4.0	_	μs	After this period, the first
		Hold Time	400 kHz mode	0.6	_	μs	clock pulse is generated
			1 MHz mode <sup>(1)</sup>	0.26	_	μs	
IS33	Tsu:sto	Stop Condition	100 kHz mode	4.0	_	μs	
		Setup Time	400 kHz mode	0.6	_	μs	
			1 MHz mode <sup>(1)</sup>	0.26		μs	
IS34	THD:STO	Stop Condition	100 kHz mode	>0	_	μs	
		Hold Time	400 kHz mode	>0	_	μs	
			1 MHz mode <sup>(1)</sup>	>0		μs	
IS40	TAA:SCL	Output Valid from	100 kHz mode	0	3450	ns	
		Clock	400 kHz mode	0	900	ns	
			1 MHz mode <sup>(1)</sup>	0	450	ns	
IS45	TBF:SDA	Bus Free Time	100 kHz mode	4.7		μs	Time the bus must be free
			400 kHz mode	1.3	_	μs	before a new transmission
			1 MHz mode <sup>(1)</sup>	0.5	_	μs	can start
IS50	Св	Bus Capacitive Lo	ading	_	400	pF	
IS51	TPGD	Pulse Gobbler Del	ay	65	390	ns	(Note 2)

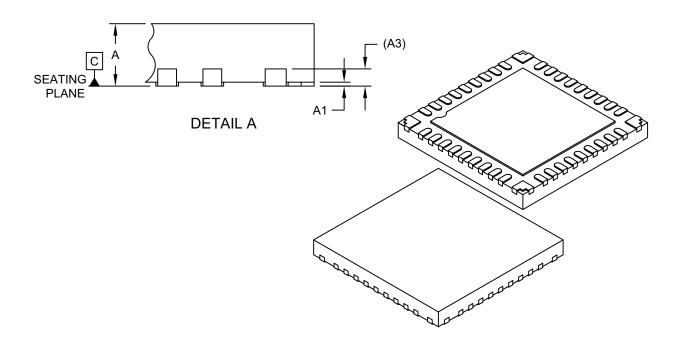
Note 1: Maximum Pin Capacitance = 10 pF for all I2Cx pins (for 1 MHz mode only).

**<sup>2:</sup>** Typical value for this parameter is 130 ns.

<sup>3:</sup> These parameters are characterized but not tested in manufacturing.

# 36-Lead Ultra Thin Plastic Quad Flat, No Lead Package (M5) - 5x5 mm Body [UQFN] With Corner Anchors

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units	MILLIMETERS			
Dimension	Limits	MIN	NOM	MAX	
Number of Terminals	N		36		
Pitch	е		0.40 BSC		
Overall Height	Α	0.50	0.55	0.60	
Standoff	A1	0.00	0.02	0.05	
Terminal Thickness	A3	0.152 REF			
Overall Length	D	5.00 BSC			
Exposed Pad Length	D2	3.60	3.70	3.80	
Overall Width	E	5.00 BSC			
Exposed Pad Width	E2	3.60	3.70	3.80	
Terminal Width	b	0.15	0.20	0.25	
Terminal Length	L	0.30	0.40	0.50	
Terminal-to-Exposed-Pad	K		0.25 REF		

#### Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Package is saw singulated
- 3. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-436A-M5 Sheet 2 of 2

# 64-Lead Plastic Quad Flat, No Lead Package (MR) – 9x9x0.9 mm Body with 5.40 x 5.40 Exposed Pad [QFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging D Ε 0.25 C NOTE 1 0.25 C **TOP VIEW** 0.10 C SEATING PLANE C (A3) ○ 0.08 C ◆ 0.10M C A B D2 ⊕ 0.10M C A B (DATUM B) E2 NOTE 1 e/2 (DATUM A) Κ 0.10M C A B 0.05(M) C **BOTTOM VIEW** 

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