Microchip Technology - DSPIC33CK256MP202T-I/SS Datasheet

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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	100MHz
Connectivity	I²C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, QEI, WDT
Number of I/O	21
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	24K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 12x12b; D/A 3x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ck256mp202t-i-ss

4.1.1 PROGRAM MEMORY ORGANIZATION

The program memory space is organized in word-addressable blocks. Although it is treated as 24 bits wide, it is more appropriate to think of each address of the program memory as a lower and upper word, with the upper byte of the upper word being unimplemented. The lower word always has an even address, while the upper word has an odd address (Figure 4-6).

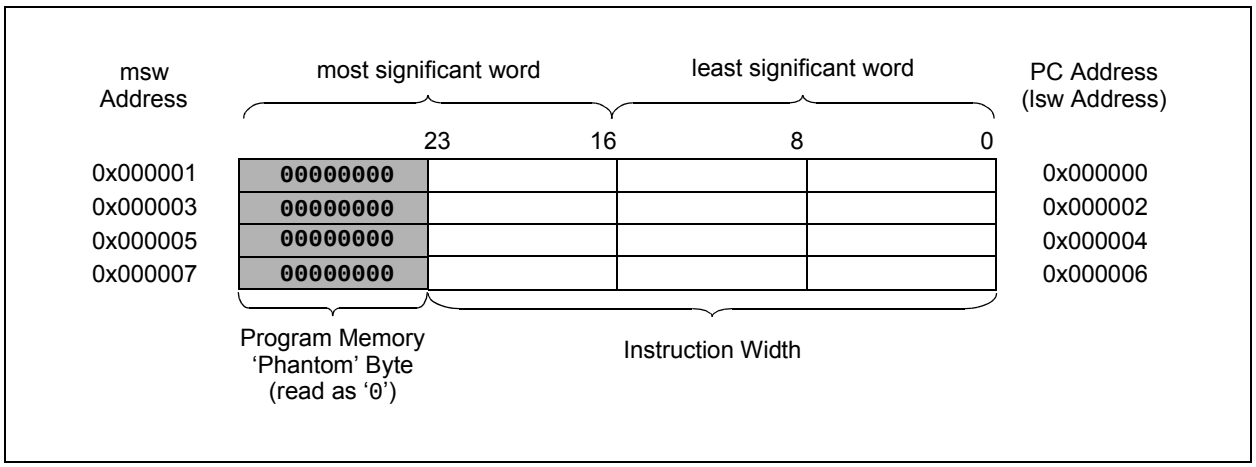
Program memory addresses are always word-aligned on the lower word, and addresses are incremented or decremented, by two, during code execution. This arrangement provides compatibility with data memory space addressing and makes data in the program memory space accessible.

4.1.2 INTERRUPT AND TRAP VECTORS

All dsPIC33CK256MP508 family devices reserve the addresses between 0x000000 and 0x000200 for hard-coded program execution vectors. A hardware Reset vector is provided to redirect code execution from the default value of the PC on device Reset to the actual start of code. A `GOTO` instruction is programmed by the user application at address, 0x000000, of Flash memory, with the actual address for the start of code at address, 0x000002, of Flash memory.

A more detailed discussion of the Interrupt Vector Tables (IVTs) is provided in **Section 7.0 "Interrupt Controller"**.

FIGURE 4-6: PROGRAM MEMORY ORGANIZATION



REGISTER 8-2: TRISx: OUTPUT ENABLE FOR PORTx REGISTER

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
TRISx<15:8>							
bit 15							bit 8

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
TRISx<7:0>							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 **TRISx<15:0>:** Output Enable for PORTx bits
1 = LATx[n] is not driven on the PORTx[n] pin
0 = LATx[n] is driven on the PORTx[n] pin

REGISTER 8-3: PORTx: INPUT DATA FOR PORTx REGISTER

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
PORTx<15:8>							
bit 15							bit 8

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
PORTx<7:0>							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 **PORTx<15:0>:** PORTx Data Input Value bits

TABLE 8-7: OUTPUT SELECTION FOR REMAPPABLE PINS (RPn) (CONTINUED)

Function	RPnR<5:0>	Output Name
MCCP9A	110010	RPn tied to MCCP9 Output A
MCCP9B	110011	RPn tied to MCCP9 Output B
MCCP9C	110100	RPn tied to MCCP9 Output C
MCCP9D	110101	RPn tied to MCCP9 Output D
MCCP9E	110110	RPn tied to MCCP9 Output E
MCCP9F	110111	RPn tied to MCCP9 Output F
CLC3OUT	111011	RPn tied to CLC4 Output
CLC4OUT	111100	RPn tied to CLC4 Output
$\overline{\text{U1DTR}}$	111101	RPn tied to UART1 DTR
$\overline{\text{U2DTR}}$	111110	RPn tied to UART2 DTR
$\overline{\text{U3DTR}}$	111111	RPn tied to UART3 DTR

REGISTER 8-58: RPOR4: PERIPHERAL PIN SELECT OUTPUT REGISTER 4

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP41R5	RP41R4	RP41R3	RP41R2	RP41R1	RP41R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP40R5	RP40R4	RP40R3	RP40R2	RP40R1	RP40R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **RP41R<5:0>:** Peripheral Output Function is Assigned to RP41 Output Pin bits (see Table 8-7 for peripheral function numbers)

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **RP40R<5:0>:** Peripheral Output Function is Assigned to RP40 Output Pin bits (see Table 8-7 for peripheral function numbers)

REGISTER 8-59: RPOR5: PERIPHERAL PIN SELECT OUTPUT REGISTER 5

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP43R5	RP43R4	RP43R3	RP43R2	RP43R1	RP43R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP42R5	RP42R4	RP42R3	RP42R2	RP42R1	RP42R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **RP43R<5:0>:** Peripheral Output Function is Assigned to RP43 Output Pin bits (see Table 8-7 for peripheral function numbers)

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **RP42R<5:0>:** Peripheral Output Function is Assigned to RP42 Output Pin bits (see Table 8-7 for peripheral function numbers)

REGISTER 11-37: C1TEFSTA: CAN TRANSMIT EVENT FIFO STATUS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	S/HC-0	R-0	R-0	R-0
—	—	—	—	TEFOVIF	TEFFIF(1)	TEFHIF(1)	TEFNEIF(1)
bit 7							bit 0

Legend:	HC = Hardware Clearable bit	S = Settable bit Can Set by ‘1’	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-4 **Unimplemented:** Read as ‘0’

bit 3 **TEFOVIF:** Transmit Event FIFO Overflow Interrupt Flag bit
1 = Overflow event has occurred
0 = No overflow event has occurred

bit 2 **TEFFIF:** Transmit Event FIFO Full Interrupt Flag bit(1)
1 = FIFO is full
0 = FIFO is not full

bit 1 **TEFHIF:** Transmit Event FIFO Half Full Interrupt Flag bit(1)
1 = FIFO is ≥ half full
0 = FIFO is < half full

bit 0 **TEFNEIF:** Transmit Event FIFO Not Empty Interrupt Flag bit(1)
1 = FIFO is not empty
0 = FIFO is empty

Note 1: These bits are read-only and reflect the status of the FIFO.

REGISTER 12-32: PGxCAP: PWM GENERATOR x CAPTURE REGISTER

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
PGxCAP<15:8>							
bit 15							bit 8

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
PGxCAP<7:0>(1)							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 **PGxCAP<15:0>:** PGx Time Base Capture bits(1)

Note 1: PGxCAP<1:0> will read as '0' in Standard Resolution mode. PGxCAP<4:0> will read as '0' in High-Resolution mode.

13.0 HIGH-SPEED, 12-BIT ANALOG-TO-DIGITAL CONVERTER (ADC)

Note 1: This data sheet summarizes the features of the dsPIC33CK256MP508 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **"12-Bit High-Speed, Multiple SARs A/D Converter (ADC)**" (DS70005213) in the *"dsPIC33/PIC24 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com).

2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The dsPIC33CK256MP508 devices have a high-speed, 12-bit Analog-to-Digital Converter (ADC) that features a low conversion latency, high resolution and over-sampling capabilities to improve performance in AC/DC, DC/DC power converters. The devices implement the ADC with three SAR cores, two dedicated and one shared.

13.1 ADC Features Overview

The High-Speed, 12-Bit Multiple SARs Analog-to-Digital Converter (ADC) includes the following features:

- Three ADC Cores: Two Dedicated Cores and One Shared (common) Core
- User-Configurable Resolution of up to 12 Bits for each Core
- Up to 3.5 Msps Conversion Rate per Channel at 12-Bit Resolution
- Low-Latency Conversion
- Up to 24 Analog Input Channels, with a Separate 16-Bit Conversion Result Register for each Input
- Conversion Result can be Formatted as Unsigned or Signed Data, on a per Channel Basis, for All Channels
- Simultaneous Sampling of up to 3 Analog Inputs
- Channel Scan Capability
- Multiple Conversion Trigger Options for each Core, including:
  - PWM triggers from CPU cores
  - MCCP/SCCP modules triggers
  - CLC modules triggers
  - External pin trigger event (ADTRG31)
  - Software trigger
- Four Integrated Digital Comparators with Dedicated Interrupts:
  - Multiple comparison options
  - Assignable to specific analog inputs
- Four Oversampling Filters with Dedicated Interrupts:
  - Provide increased resolution
  - Assignable to a specific analog input

The module consists of three independent SAR ADC cores. Simplified block diagrams of the Multiple SARs 12-Bit ADC are shown in Figure 13-1 and Figure 13-2.

The analog inputs (channels) are connected through multiplexers and switches to the Sample-and-Hold (S&H) circuit of each ADC core. The core uses the channel information (the output format, the Measurement mode and the input number) to process the analog sample. When conversion is complete, the result is stored in the result buffer for the specific analog input, and passed to the digital filter and digital comparator if they were configured to use data from this particular channel.

The ADC module can sample up to three inputs at a time (two inputs from the dedicated SAR cores and one from the shared SAR core). If multiple ADC inputs request conversion on the shared core, the module will convert them in a sequential manner, starting with the lowest order input.

The ADC provides each analog input the ability to specify its own trigger source. This capability allows the ADC to sample and convert analog inputs that are associated with PWM generators operating on independent time bases.

REGISTER 13-2: ADCON1H: ADC CONTROL REGISTER 1 HIGH

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-1	R/W-1	U-0	U-0	U-0	U-0	U-0
FORM	SHRRES1	SHRRES0	—	—	—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7 **FORM:** Fractional Data Output Format bit
1 = Fractional
0 = Integer

bit 6-5 **SHRRES<1:0>:** Shared ADC Core Resolution Selection bits
11 = 12-bit resolution
10 = 10-bit resolution
01 = 8-bit resolution
00 = 6-bit resolution

bit 4-0 **Unimplemented:** Read as '0'

REGISTER 14-5: DACxCONL: DACx CONTROL LOW REGISTER (CONTINUED)

bit 10 **CBE:** Comparator Blank Enable bit
1 = Enables the analog comparator output to be blanked (gated off) during the recovery transition following the completion of a slope operation
0 = Disables the blanking signal to the analog comparator; therefore, the analog comparator output is always active

bit 9 **DACOEN:** DACx Output Buffer Enable bit
1 = DACx analog voltage is connected to the DACOUT1 pin
0 = DACx analog voltage is not connected to the DACOUT1 pin

bit 8 **FLTREN:** Comparator Digital Filter Enable bit
1 = Digital filter is enabled
0 = Digital filter is disabled

bit 7 **CMPSTAT:** Comparator Status bits
The current state of the comparator output including the CMPPOL selection.

bit 6 **CMPPOL:** Comparator Output Polarity Control bit
1 = Output is inverted
0 = Output is non-inverted

bit 5-3 **INSEL<2:0>:** Comparator Input Source Select bits
111 = Reserved
110 = Reserved
101 = Reserved
100 = Reserved
011 = CMPxD input pin
010 = CMPxC input pin
001 = CMPxB input pin
000 = CMPxA input pin

bit 2 **HYSPOL:** Comparator Hysteresis Polarity Select bit
1 = Hysteresis is applied to the falling edge of the comparator output
0 = Hysteresis is applied to the rising edge of the comparator output

bit 1-0 **HYSSEL<1:0>:** Comparator Hysteresis Select bits
11 = 45 mv hysteresis
10 = 30 mv hysteresis
01 = 15 mv hysteresis
00 = No hysteresis is selected

Note 1: Changing these bits during operation may generate a spurious interrupt.
2: The edge selection is a post-polarity selection via the CMPPOL bit.

15.0 QUADRATURE ENCODER INTERFACE (QEI)

Note 1: This data sheet summarizes the features of the dsPIC33CK256MP508 family of devices. It is not intended to be a comprehensive resource. For more information, refer to **"Quadrature Encoder Interface (QEI)"** (DS70000601) in the *"dsPIC33/PIC24 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com).

The Quadrature Encoder Interface (QEI) module provides the interface to incremental encoders for obtaining mechanical position data. The dsPIC33CK256MP508 family implements 2 instances of the QEI. Quadrature Encoders, also known as incremental encoders or optical encoders, detect position and speed of rotating motion systems. Quadrature Encoders enable closed-loop control of motor control applications, such as Switched Reluctance (SR) and AC Induction Motors (ACIM).

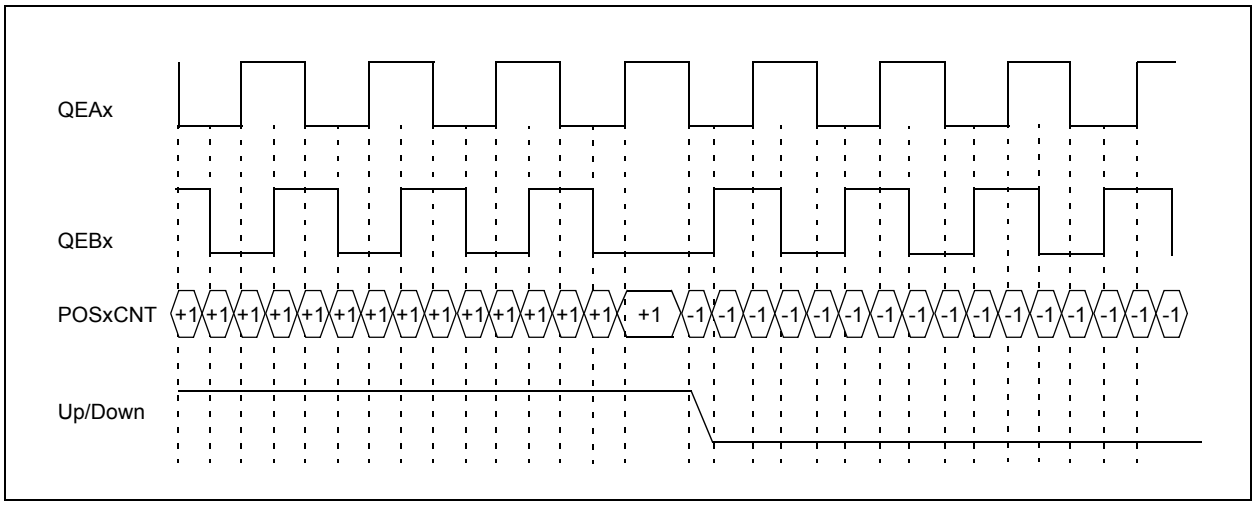
A typical Quadrature Encoder includes a slotted wheel attached to the shaft of the motor and an emitter/ detector module that senses the slots in the wheel. Typically, three output channels, Phase A (QEAx), Phase B (QEBx) and Index (INDXx), provide information on the movement of the motor shaft, including distance and direction.

The two channels, Phase A (QEAx) and Phase B (QEBx), are typically 90 degrees out of phase with respect to each other. The Phase A and Phase B channels have a unique relationship. If Phase A leads Phase B, the direction of the motor is deemed positive or forward. If Phase A lags Phase B, the direction of the motor is deemed negative or reverse. The Index pulse occurs once per mechanical revolution and is used as a reference to indicate an absolute position. Figure 15-1 illustrates the Quadrature Encoder Interface signals.

The Quadrature signals from the encoder can have four unique states ('01', '00', '10' and '11') that reflect the relationship between QEAx and QEBx. Figure 15-1 illustrates these states for one count cycle. The order of the states get reversed when the direction of travel changes.

The Quadrature Decoder increments or decrements the 32-bit up/down Position x Counter (POSxCNTH/L) registers for each Change-of-State (COS). The counter increments when QEAx leads QEBx and decrements when QEBx leads QEAx.

FIGURE 15-1: QUADRATURE ENCODER INTERFACE SIGNALS



17.0 SERIAL PERIPHERAL INTERFACE (SPI)

Note 1: This data sheet summarizes the features of the dsPIC33CK256MP508 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **"Serial Peripheral Interface (SPI) with Audio Codec Support"** (DS70005136) in the *"dsPIC33/PIC24 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com).

The Serial Peripheral Interface (SPI) module is a synchronous serial interface, useful for communicating with other peripheral or microcontroller devices. These peripheral devices may be serial EEPROMs, shift registers, display drivers, A/D Converters, etc. The SPI module is compatible with the Motorola® SPI and SIOP interfaces. All devices in the dsPIC33CK256MP508 family include three SPI modules. On 48, 64 and 80-pin devices, SPI instance SPI2 can work up to 50 MHz speed when selected as a non-PPS pin. The selection is done using the SPI2PIN bit (FDEVOPT<13>). If the bit for SPI2PIN is '1', the PPS pin will be used. When SPI2PIN is '0', the SPI signals are routed to dedicated pins.

The module supports operation in two Buffer modes. In Standard mode, data is shifted through a single serial buffer. In Enhanced Buffer mode, data is shifted through a FIFO buffer. The FIFO level depends on the configured mode.

Note: FIFO depth for this device is 4 (in 8-Bit Data mode).

Variable length data can be transmitted and received, from 2 to 32 bits.

Note: Do not perform Read-Modify-Write operations (such as bit-oriented instructions) on the SPIxBUF register in either Standard or Enhanced Buffer mode.

The module also supports a basic framed SPI protocol while operating in either Master or Slave mode. A total of four framed SPI configurations are supported.

The module also supports Audio modes. Four different Audio modes are available.

- I^2S mode
- Left Justified mode
- Right Justified mode
- PCM/DSP mode

In each of these modes, the serial clock is free-running and audio data is always transferred.

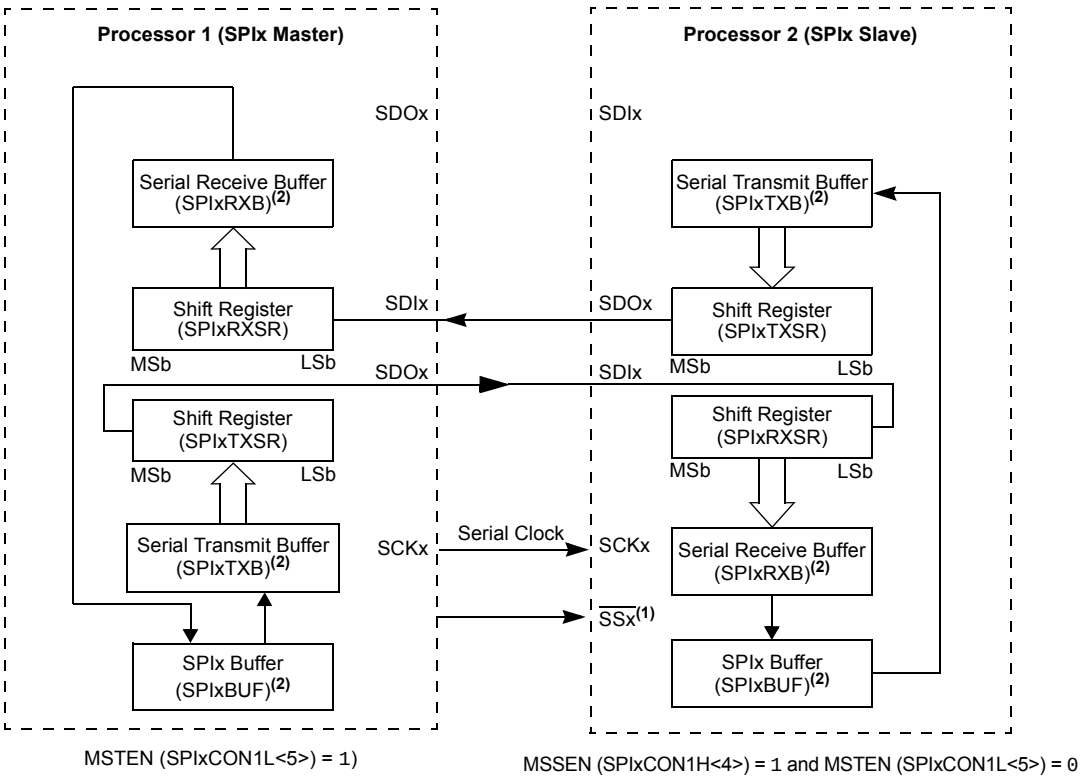
If an audio protocol data transfer takes place between two devices, then usually one device is the Master and the other is the Slave. However, audio data can be transferred between two Slaves. Because the audio protocols require free-running clocks, the Master can be a third-party controller. In either case, the Master generates two free-running clocks: SCKx and LRC (Left, Right Channel Clock/$\overline{SSx}$/FSYNC).

The SPI serial interface consists of four pins:

- SDIx: Serial Data Input
- SDOx: Serial Data Output
- SCKx: Shift Clock Input or Output
- $\overline{SSx}$: Active-Low Slave Select or Frame Synchronization I/O Pulse

The SPI module can be configured to operate using 2, 3 or 4 pins. In the 3-pin mode, $\overline{SSx}$ is not used. In the 2-pin mode, both SDOx and $\overline{SSx}$ are not used.

FIGURE 17-3: SPIx MASTER/SLAVE CONNECTION (STANDARD MODE)



Note 1: Using the $\overline{SSx}$ pin in Slave mode of operation is optional.

2: User must write transmit data to read the received data from SPIxBUF. The SPIxTXB and SPIxRXB registers are memory-mapped to SPIxBUF.

20.2 Receive Mode

The module can be configured for receive operation by setting the RCVEN (SENTxCON1<11>) bit. The time between each falling edge is compared to SYNCMIN<15:0> (SENTxCON3<15:0>) and SYNCMAX<15:0> (SENTxCON2<15:0>), and if the measured time lies between the minimum and maximum limits, the module begins to receive data. The validated Sync time is captured in the SENTxSYNC register and the tick time is calculated. Subsequent falling edges are verified to be within the valid data width and the data is stored in the SENTxDATL/H registers. An interrupt event is generated at the completion of the message and the user software should read the SENTx Data registers before the reception of the next nibble. The equation for SYNCMIN<15:0> and SYNCMAX<15:0> is shown in Equation 20-3.

EQUATION 20-3: SYNCMIN<15:0> AND SYNCMAX<15:0> CALCULATIONS

$$T_{TICK} = T_{CLK} \bullet (TICKTIME\langle 15:0\rangle + 1)$$

$$FRAMETIME\langle 15:0\rangle = T_{TICK}/T_{FRAME}$$

$$SyncCount = 8 \times F_{RCV} \times T_{TICK}$$

$$SYNCMIN\langle 15:0\rangle = 0.8 \times SyncCount$$

$$SYNCMAX\langle 15:0\rangle = 1.2 \times SyncCount$$

$$FRAMETIME\langle 15:0\rangle \geq 122 + 27N$$

$$FRAMETIME\langle 15:0\rangle \geq 848 + 12N$$

Where:

T_{FRAME} = Total time of the message from ms

N = The number of data nibbles in message, 1-6

F_{RCV} = FCY x Prescaler

T_{CLK} = FCY/Prescaler

For TTICK = 3.0 μs and FCLK = 4 MHz, SYNCMIN<15:0> = 76.

Note: To ensure a Sync period can be identified, the value written to SYNCMIN<15:0> must be less than the value written to SYNCMAX<15:0>.

20.2.1 RECEIVE MODE CONFIGURATION

20.2.1.1 Initializing the SENTx Module

Perform the following steps to initialize the module:

1. Write RCVEN (SENTxCON1<11>) = 1 for Receive mode.
2. Write NIBCNT<2:0> (SENTxCON1<2:0>) for the desired data frame length.
3. Write CRCEN (SENTxCON1<8>) for hardware or software CRC validation.
4. Write PPP (SENTxCON1<7>) = 1 if pause pulse is present.
5. Write SENTxCON2 with the value of SYNCMAXx (Nominal Sync Period + 20%).
6. Write SENTxCON3 with the value of SYNCMINx (Nominal Sync Period – 20%).
7. Enable interrupts and set interrupt priority.
8. Set the SNTEN (SENTxCON1<15>) bit to enable the module.

The data should be read from the SENTxDATL/H registers after the completion of the CRC and before the next message frame's status nibble. The recommended method is to use the message frame completion interrupt trigger.

REGISTER 20-3: SENTxDATL: SENTx RECEIVE DATA REGISTER LOW(1)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DATA4<3:0>				DATA5<3:0>			
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DATA6<3:0>				CRC<3:0>			
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-12 **DATA4<3:0>:** Data Nibble 4 Data bits

bit 11-8 **DATA5<3:0>:** Data Nibble 5 Data bits

bit 7-4 **DATA6<3:0>:** Data Nibble 6 Data bits

bit 3-0 **CRC<3:0>:** CRC Nibble Data bits

Note 1: Register bits are read-only in Receive mode (RCVEN = 1). In Transmit mode, the CRC<3:0> bits are read-only when automatic CRC calculation is enabled (RCVEN = 0, CRCEN = 1).

REGISTER 20-4: SENTxDATH: SENTx RECEIVE DATA REGISTER HIGH(1)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
STAT<3:0>				DATA1<3:0>			
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DATA2<3:0>				DATA3<3:0>			
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-12 **STAT<3:0>:** Status Nibble Data bits

bit 11-8 **DATA1<3:0>:** Data Nibble 1 Data bits

bit 7-4 **DATA2<3:0>:** Data Nibble 2 Data bits

bit 3-0 **DATA3<3:0>:** Data Nibble 3 Data bits

Note 1: Register bits are read-only in Receive mode (RCVEN = 1). In Transmit mode, the CRC<3:0> bits are read-only when automatic CRC calculation is enabled (RCVEN = 0, CRCEN = 1).

REGISTER 22-5: CCPxCON3L: CCPx CONTROL 3 LOW REGISTERS(1)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	DT<5:0>					
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-6 **Unimplemented:** Read as '0'

bit 5-0 **DT<5:0>:** CCPx Dead-Time Select bits

111111 = Inserts 63 dead-time delay periods between complementary output signals
111110 = Inserts 62 dead-time delay periods between complementary output signals
...
000010 = Inserts 2 dead-time delay periods between complementary output signals
000001 = Inserts 1 dead-time delay period between complementary output signals
000000 = Dead-time logic is disabled

Note 1: This register is implemented in the MCCP9 module only.

REGISTER 29-1: PMD1: PERIPHERAL MODULE DISABLE 1 CONTROL REGISTER

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	U-0
—	—	—	—	T1MD	QEI1MD	PWMMD	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
I2C1MD	U2MD	U1MD	SPI2MD	SPI1MD	—	C1MD	ADC1MD
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-12 **Unimplemented:** Read as '0'

bit 11 **T1MD:** Timer1 Module Disable bit
1 = Timer1 module is disabled
0 = Timer1 module is enabled

bit 10 **QEI1MD:** QEI1 Module Disable bit
1 = QEI1 module is disabled
0 = QEI1 module is enabled

bit 9 **PWMMD:** PWM Module Disable bit
1 = PWM module is disabled
0 = PWM module is enabled

bit 8 **Unimplemented:** Read as '0'

bit 7 **I2C1MD:** I2C1 Module Disable bit
1 = I2C1 module is disabled
0 = I2C1 module is enabled

bit 6 **U2MD:** UART2 Module Disable bit
1 = UART2 module is disabled
0 = UART2 module is enabled

bit 5 **U1MD:** UART1 Module Disable bit
1 = UART1 module is disabled
0 = UART1 module is enabled

bit 4 **SPI2MD:** SPI2 Module Disable bit
1 = SPI2 module is disabled
0 = SPI2 module is enabled

bit 3 **SPI1MD:** SPI1 Module Disable bit
1 = SPI1 module is disabled
0 = SPI1 module is enabled

bit 2 **Unimplemented:** Read as '0'

bit 1 **C1MD:** CAN1 Module Disable bit
1 = CAN1 module is disabled
0 = CAN1 module is enabled

bit 0 **ADC1MD:** ADC Module Disable bit
1 = ADC module is disabled
0 = ADC module is enabled

REGISTER 30-6: FWDT CONFIGURATION REGISTER

U-1	U-1	U-1	U-1	U-1	U-1	U-1	U-1
—	—	—	—	—	—	—	—
bit 23							bit 16

R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1
FWDTEN	SWDTPS4	SWDTPS3	SWDTPS2	SWDTPS1	SWDTPS0	WDTWIN1	WDTWIN0
bit 15							bit 8

R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1
WINDIS	RCLKSEL1	RCLKSEL0	RWDTPS4	RWDTPS3	RWDTPS2	RWDTPS1	RWDTPS0
bit 7							bit 0

Legend:	PO = Program Once bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 23-16 **Unimplemented:** Read as '1'

bit 15 **FWDTEN:** Watchdog Timer Enable bit
1 = WDT is enabled in hardware
0 = WDT controller via the ON bit (WDTCONL<15>)

bit 14-10 **SWDTPS<4:0>:** Sleep Mode Watchdog Timer Period Select bits
11111 = Divide by 2 ^ 30 = 1,073,741,824
11110 = Divide by 2 ^ 29 = 526,870,912
...
00001 = Divide by 2 ^ 2, 4
00000 = Divide by 2 ^ 1, 2

bit 9-8 **WDTWIN<1:0>:** Watchdog Timer Window Select bits
11 = WDT window is 25% of the WDT period
10 = WDT window is 37.5% of the WDT period
01 = WDT window is 50% of the WDT period
00 = WDT Window is 75% of the WDT period

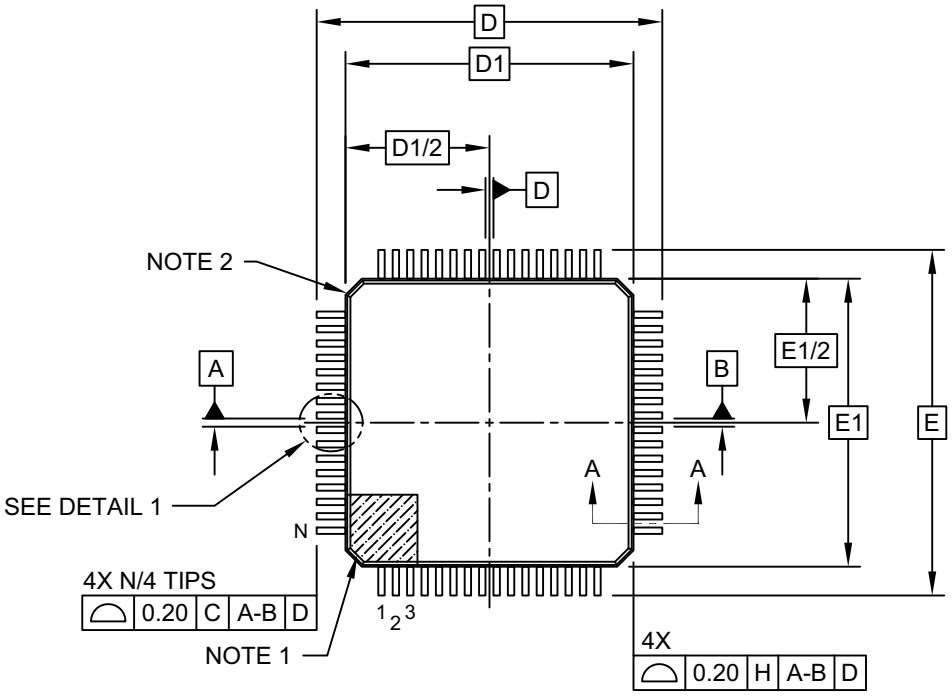
bit 7 **WINDIS:** Watchdog Timer Window Enable bit
1 = Watchdog Timer is in Non-Window mode
0 = Watchdog Timer is in Window mode

bit 6-5 **RCLKSEL<1:0>:** Watchdog Timer Clock Select bits
11 = LPRC clock
10 = Uses FRC when WINDIS = 0, system clock is not INTOSC/LPRC and device is not in Sleep; otherwise, uses INTOSC/LPRC
01 = Uses peripheral clock when system clock is not INTOSC/LPRC and device is not in Sleep; otherwise, uses INTOSC/LPRC
00 = Reserved

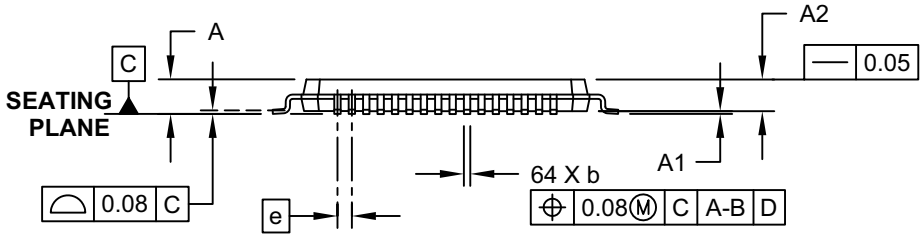
bit 4-0 **RWDTPS<4:0>:** Run Mode Watchdog Timer Period Select bits
11111 = Divide by 2 ^ 30 = 1,073,741,824
11110 = Divide by 2 ^ 29 = 526,870,912
...
00001 = Divide by 2 ^ 2, 4
00000 = Divide by 2 ^ 1, 2

64-Lead Plastic Thin Quad Flatpack (PT)-10x10x1 mm Body, 2.00 mm Footprint [TQFP]

Note:	For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



TOP VIEW



SIDE VIEW

Microchip Technology Drawing C04-085C Sheet 1 of 2

S

T

U

V

W

