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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	I²C, LINbus, SPI, UART/USART, USB, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I²S, LVD, POR, PWM, WDT
Number of I/O	80
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 3.6V
Data Converters	A/D - 16bit; D/A - 12bit
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	121-LFBGA
Supplier Device Package	121-MAPBGA (8x8)
Purchase URL	https://www.e-xfl.com/pro/item?MUrl=&PartUrl=mkl26z256vmc4

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2.2 Nonswitching electrical specifications

2.2.1 Voltage and current operating requirements

Table 5. Voltage and current operating requirements

Symbol	Description	Min.	Max.	Unit	Notes
V_{DD}	Supply voltage	1.71	3.6	V	
V_{DDA}	Analog supply voltage	1.71	3.6	V	
$V_{DD} - V_{DDA}$	V_{DD} -to- V_{DDA} differential voltage	-0.1	0.1	V	
$V_{SS} - V_{SSA}$	V_{SS} -to- V_{SSA} differential voltage	-0.1	0.1	V	
V_{IH}	Input high voltage • $2.7 \text{ V} \leq V_{DD} \leq 3.6 \text{ V}$ • $1.7 \text{ V} \leq V_{DD} \leq 2.7 \text{ V}$	$0.7 \times V_{DD}$ $0.75 \times V_{DD}$	— —	V V	
V_{IL}	Input low voltage • $2.7 \text{ V} \leq V_{DD} \leq 3.6 \text{ V}$ • $1.7 \text{ V} \leq V_{DD} \leq 2.7 \text{ V}$	— —	$0.35 \times V_{DD}$ $0.3 \times V_{DD}$	V V	
V_{HYS}	Input hysteresis	$0.06 \times V_{DD}$	—	V	
I_{ICIO}	IO pin negative DC injection current — single pin • $V_{IN} < V_{SS}-0.3\text{V}$	-3	—	mA	1
I_{ICcont}	Contiguous pin DC injection current —regional limit, includes sum of negative injection currents of 16 contiguous pins • Negative current injection	-25	—	mA	
V_{ODPU}	Open drain pullup voltage level	V_{DD}	V_{DD}	V	2
V_{RAM}	V_{DD} voltage required to retain RAM	1.2	—	V	

- All I/O pins are internally clamped to V_{SS} through a ESD protection diode. There is no diode connection to V_{DD} . If V_{IN} greater than V_{IO_MIN} ($= V_{SS}-0.3 \text{ V}$) is observed, then there is no need to provide current limiting resistors at the pads. If this limit cannot be observed then a current limiting resistor is required. The negative DC injection current limiting resistor is calculated as $R = (V_{IO_MIN} - V_{IN})/I_{ICIO}$.
- Open drain outputs must be pulled to V_{DD} .

2.2.2 LVD and POR operating requirements

Table 6. V_{DD} supply LVD and POR operating requirements

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V_{POR}	Falling V_{DD} POR detect voltage	0.8	1.1	1.5	V	—

Table continues on the next page...

Table 9. Power consumption operating behaviors (continued)

Symbol	Description	Typ.	Max	Unit	Note
		at 85 °C	29.60	47.30	μA
		at 105 °C	69.13	106.04	μA
I _{DD_LLS}	Low leakage stop mode current at 3.0 V	at 25 °C	2.00	2.7	μA
		at 50 °C	3.96	5.14	μA
		at 70 °C	7.77	10.71	μA
		at 85 °C	14.15	18.79	μA
		at 105 °C	33.20	43.67	μA
I _{DD_VLLS3}	Very low-leakage stop mode 3 current at 3.0 V	at 25 °C	1.5	2.2	μA
		at 50 °C	2.83	3.55	μA
		at 70 °C	5.53	7.26	μA
		at 85 °C	9.92	12.71	μA
		at 105 °C	22.90	29.23	μA
I _{DD_VLLS1}	Very low-leakage stop mode 1 current at 3.0V	at 25 °C	0.71	1.2	μA
		at 50 °C	1.27	1.9	μA
		at 70 °C	2.48	3.51	μA
		at 85 °C	4.65	6.29	μA
		at 105 °C	11.55	14.34	μA
I _{DD_VLLS0}	Very low-leakage stop mode 0 current (SMC_STOPCTRL[PORPO] = 0) at 3.0 V	at 25 °C	0.41	0.9	μA
		at 50 °C	0.96	1.56	μA
		at 70 °C	2.17	3.1	μA
		at 85 °C	4.35	5.32	μA
		at 105 °C	11.24	14.00	μA
I _{DD_VLLS0}	Very low-leakage stop mode 0 current (SMC_STOPCTRL[PORPO] = 1) at 3.0 V	at 25 °C	0.23	0.69	μA
		at 50 °C	0.77	1.35	μA
		at 70 °C	1.98	2.52	μA
		at 85 °C	4.16	5.14	μA
		at 105 °C	11.05	13.80	μA

1. The analog supply current is the sum of the active or disabled current for each of the analog modules on the device. See each module's specification for its supply current.
2. MCG configured for PEE mode. CoreMark benchmark compiled using IAR 6.40 with optimization level high, optimized for balanced.
3. MCG configured for FEI mode.
4. Incremental current consumption from peripheral activity is not included.
5. MCG configured for BLPI mode. CoreMark benchmark compiled using IAR 6.40 with optimization level high, optimized for balanced.
6. MCG configured for BLPI mode.
7. No brownout.

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Table 10. Low power mode peripheral adders — typical value

Symbol	Description	Temperature (°C)						Unit	
		-40	25	50	70	85	105		
$I_{IREFSTEN4MHz}$	4 MHz internal reference clock (IRC) adder. Measured by entering STOP or VLPS mode with 4 MHz IRC enabled.	56	56	56	56	56	56	μA	
$I_{IREFSTEN32KHz}$	32 kHz internal reference clock (IRC) adder. Measured by entering STOP mode with the 32 kHz IRC enabled.	52	52	52	52	52	52	μA	
$I_{EREFSTEN4MHz}$	External 4 MHz crystal clock adder. Measured by entering STOP or VLPS mode with the crystal enabled.	206	228	237	245	251	258	μA	
$I_{EREFSTEN32KHz}$	External 32 kHz crystal clock adder by means of the OSC0_CR[EREFSTEN and EREFSTEN] bits. Measured by entering all modes with the crystal enabled.	VLLS1	440	490	540	560	570	580	nA
		VLLS3	440	490	540	560	570	580	
		LLS	490	490	540	560	570	680	
		VLPS	510	560	560	560	610	680	
		STOP	510	560	560	560	610	680	
I_{CMP}	CMP peripheral adder measured by placing the device in VLLS1 mode with CMP enabled using the 6-bit DAC and a single external input for compare. Includes 6-bit DAC power consumption.	22	22	22	22	22	22	μA	
I_{RTC}	RTC peripheral adder measured by placing the device in VLLS1 mode with external 32 kHz crystal enabled by means of the RTC_CR[OSCE] bit and the RTC ALARM set for 1 minute. Includes ERCLK32K (32 kHz external crystal) power consumption.	432	357	388	475	532	810	nA	
I_{UART}	UART peripheral adder measured by placing the device in STOP or VLPS mode with selected clock source waiting for RX data at 115200 baud rate. Includes selected clock source power consumption.	MCGIRCLK (4 MHz internal reference clock)	66	66	66	66	66	66	μA
		OSCERCLK (4 MHz external crystal)	214	237	246	254	260	268	
I_{TPM}	TPM peripheral adder measured by placing the device in STOP or VLPS mode with selected clock source configured for output compare generating 100 Hz clock signal. No load is placed on the I/O generating the clock signal. Includes selected clock source and I/O switching currents.	MCGIRCLK (4 MHz internal reference clock)	86	86	86	86	86	86	μA
		OSCERCLK (4 MHz external crystal)	235	256	265	274	280	287	

Table continues on the next page...

2.2.7 Designing with radiated emissions in mind

To find application notes that provide guidance on designing your system to minimize interference from radiated emissions:

1. Go to www.freescale.com.
2. Perform a keyword search for “EMC design.”

2.2.8 Capacitance attributes

Table 12. Capacitance attributes

Symbol	Description	Min.	Max.	Unit
C_{IN}	Input capacitance	—	7	pF

2.3 Switching specifications

2.3.1 Device clock specifications

Table 13. Device clock specifications

Symbol	Description	Min.	Max.	Unit
Normal run mode				
f_{SYS}	System and core clock	—	48	MHz
f_{BUS}	Bus clock	—	24	MHz
f_{FLASH}	Flash clock	—	24	MHz
f_{SYS_USB}	System and core clock when Full Speed USB in operation	20	—	MHz
f_{LPTMR}	LPTMR clock	—	24	MHz
VLPR and VLPS modes ¹				
f_{SYS}	System and core clock	—	4	MHz
f_{BUS}	Bus clock	—	1	MHz
f_{FLASH}	Flash clock	—	1	MHz
f_{LPTMR}	LPTMR clock ²	—	24	MHz
f_{ERCLK}	External reference clock	—	16	MHz
f_{LPTMR_ERCLK}	LPTMR external reference clock	—	16	MHz
$f_{osc_hi_2}$	Oscillator crystal or resonator frequency — high frequency mode (high range) (MCG_C2[RANGE]=1x)	—	16	MHz
f_{TPM}	TPM asynchronous clock	—	8	MHz
f_{UART0}	UART0 asynchronous clock	—	8	MHz

1. The frequency limitations in VLPR and VLPS modes here override any frequency specification listed in the timing specification for any other module. These same frequency limits apply to VLPS, whether VLPS was entered from RUN or from VLPR.
2. The LPTMR can be clocked at this speed in VLPR or VLPS only when the source is an external pin.

2.3.2 General switching specifications

These general-purpose specifications apply to all signals configured for GPIO and UART signals.

Table 14. General switching specifications

Description	Min.	Max.	Unit	Notes
GPIO pin interrupt pulse width (digital glitch filter disabled) — Synchronous path	1.5	—	Bus clock cycles	1
External RESET and NMI pin interrupt pulse width — Asynchronous path	100	—	ns	2
GPIO pin interrupt pulse width — Asynchronous path	16	—	ns	2
Port rise and fall time	—	36	ns	3

1. The greater synchronous and asynchronous timing must be met.
2. This is the shortest pulse that is guaranteed to be recognized.
3. 75 pF load

2.4 Thermal specifications

2.4.1 Thermal operating requirements

Table 15. Thermal operating requirements

Symbol	Description	Min.	Max.	Unit
T _J	Die junction temperature	-40	125	°C
T _A	Ambient temperature	-40	105	°C

Table 18. MCG specifications (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
J _{acc_pll}	PLL accumulated jitter over 1μs (RMS) <ul style="list-style-type: none"> • f_{VCO} = 48 MHz • f_{VCO} = 100 MHz 	—	1350	—	ps	10
D _{lock}	Lock entry frequency tolerance	± 1.49	—	± 2.98	%	
D _{unl}	Lock exit frequency tolerance	± 4.47	—	± 5.97	%	
t _{pll_lock}	Lock detector detection time	—	—	150 × 10 ⁻⁶ + 1075(1/ f _{pll_ref})	s	11

1. This parameter is measured with the internal reference (slow clock) being used as a reference to the FLL (FEI clock mode).
2. The deviation is relative to the factory trimmed frequency at nominal V_{DD} and 25 °C, f_{ints_ft}.
3. These typical values listed are with the slow internal reference clock (FEI) using factory trim and DMX32 = 0.
4. The resulting system clock frequencies must not exceed their maximum specified values. The DCO frequency deviation ($\Delta f_{dco,t}$) over voltage and temperature must be considered.
5. These typical values listed are with the slow internal reference clock (FEI) using factory trim and DMX32 = 1.
6. The resulting clock frequency must not exceed the maximum specified clock frequency of the device.
7. This specification is based on standard deviation (RMS) of period or frequency.
8. This specification applies to any time the FLL reference source or reference divider is changed, trim value is changed, DMX32 bit is changed, DRS bits are changed, or changing from FLL disabled (BLPE, BLPI) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.
9. Excludes any oscillator currents that are also consuming power while PLL is in operation.
10. This specification was obtained using a Freescale developed PCB. PLL jitter is dependent on the noise characteristics of each PCB and results will vary.
11. This specification applies to any time the PLL VCO divider or reference divider is changed, or changing from PLL disabled (BLPE, BLPI) to PLL enabled (PBE, PEE). If a crystal/resonator is being used as the reference, this specification assumes it is already running.

3.3.2 Oscillator electrical specifications

3.3.2.1 Oscillator DC electrical specifications

Table 19. Oscillator DC electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V _{DD}	Supply voltage	1.71	—	3.6	V	
I _{DDOSC}	Supply current — low-power mode (HGO=0) <ul style="list-style-type: none"> • 32 kHz • 4 MHz • 8 MHz (RANGE=01) • 16 MHz 	—	500	—	nA	1
		—	200	—	μA	
		—	300	—	μA	
		—	950	—	μA	
		—	1.2	—	mA	

Table continues on the next page...

3. C_x, C_y can be provided by using the integrated capacitors when the low frequency oscillator (RANGE = 00) is used. For all other cases external capacitors must be used.
4. When low power mode is selected, R_F is integrated and must not be attached externally.
5. The EXTAL and XTAL pins should only be connected to required oscillator components and must not be connected to any other devices.

3.3.2.2 Oscillator frequency specifications

Table 20. Oscillator frequency specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
f_{osc_lo}	Oscillator crystal or resonator frequency — low-frequency mode (MCG_C2[RANGE]=00)	32	—	40	kHz	
$f_{osc_hi_1}$	Oscillator crystal or resonator frequency — high-frequency mode (low range) (MCG_C2[RANGE]=01)	3	—	8	MHz	
$f_{osc_hi_2}$	Oscillator crystal or resonator frequency — high frequency mode (high range) (MCG_C2[RANGE]=1x)	8	—	32	MHz	
f_{ec_extal}	Input clock frequency (external clock mode)	—	—	48	MHz	1, 2
t_{dc_extal}	Input clock duty cycle (external clock mode)	40	50	60	%	
t_{cst}	Crystal startup time — 32 kHz low-frequency, low-power mode (HGO=0)	—	750	—	ms	3, 4
	Crystal startup time — 32 kHz low-frequency, high-gain mode (HGO=1)	—	250	—	ms	
	Crystal startup time — 8 MHz high-frequency (MCG_C2[RANGE]=01), low-power mode (HGO=0)	—	0.6	—	ms	
	Crystal startup time — 8 MHz high-frequency (MCG_C2[RANGE]=01), high-gain mode (HGO=1)	—	1	—	ms	

1. Other frequency limits may apply when external clock is being used as a reference for the FLL or PLL.
2. When transitioning from FEI or FBI to FBE mode, restrict the frequency of the input clock so that, when it is divided by FRDIV, it remains within the limits of the DCO input clock frequency.
3. Proper PC board layout procedures must be followed to achieve specifications.
4. Crystal startup time is defined as the time between the oscillator being enabled and the OSCINIT bit in the MCG_S register being set.

3.4 Memories and memory interfaces

3.4.1 Flash electrical specifications

This section describes the electrical characteristics of the flash memory module.

3.4.1.1 Flash timing specifications — program and erase

The following specifications represent the amount of time the internal charge pumps are active and do not include command overhead.

Table 21. NVM program/erase timing specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
t_{hvpgm4}	Longword Program high-voltage time	—	7.5	18	μs	—
$t_{hversscr}$	Sector Erase high-voltage time	—	13	113	ms	1
$t_{hversblk128k}$	Erase Block high-voltage time for 128 KB	—	52	452	ms	1
$t_{hversall}$	Erase All high-voltage time	—	52	452	ms	1

1. Maximum time based on expectations at cycling end-of-life.

3.4.1.2 Flash timing specifications — commands

Table 22. Flash command timing specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$t_{rd1blk128k}$	Read 1s Block execution time • 128 KB program flash	—	—	1.7	ms	—
$t_{rd1sec1k}$	Read 1s Section execution time (flash sector)	—	—	60	μs	1
t_{pgmchk}	Program Check execution time	—	—	45	μs	1
t_{rdrsrc}	Read Resource execution time	—	—	30	μs	1
t_{pgm4}	Program Longword execution time	—	65	145	μs	—
$t_{ersblk128k}$	Erase Flash Block execution time • 128 KB program flash	—	88	600	ms	2
t_{ersscr}	Erase Flash Sector execution time	—	14	114	ms	2
t_{rd1all}	Read 1s All Blocks execution time	—	—	1.8	ms	—
t_{rdonce}	Read Once execution time	—	—	25	μs	1
$t_{pgmonce}$	Program Once execution time	—	65	—	μs	—
t_{ersall}	Erase All Blocks execution time	—	175	1300	ms	2
t_{vfykey}	Verify Backdoor Access Key execution time	—	—	30	μs	1

1. Assumes 25 MHz flash clock frequency.
2. Maximum times for erase parameters based on expectations at cycling end-of-life.

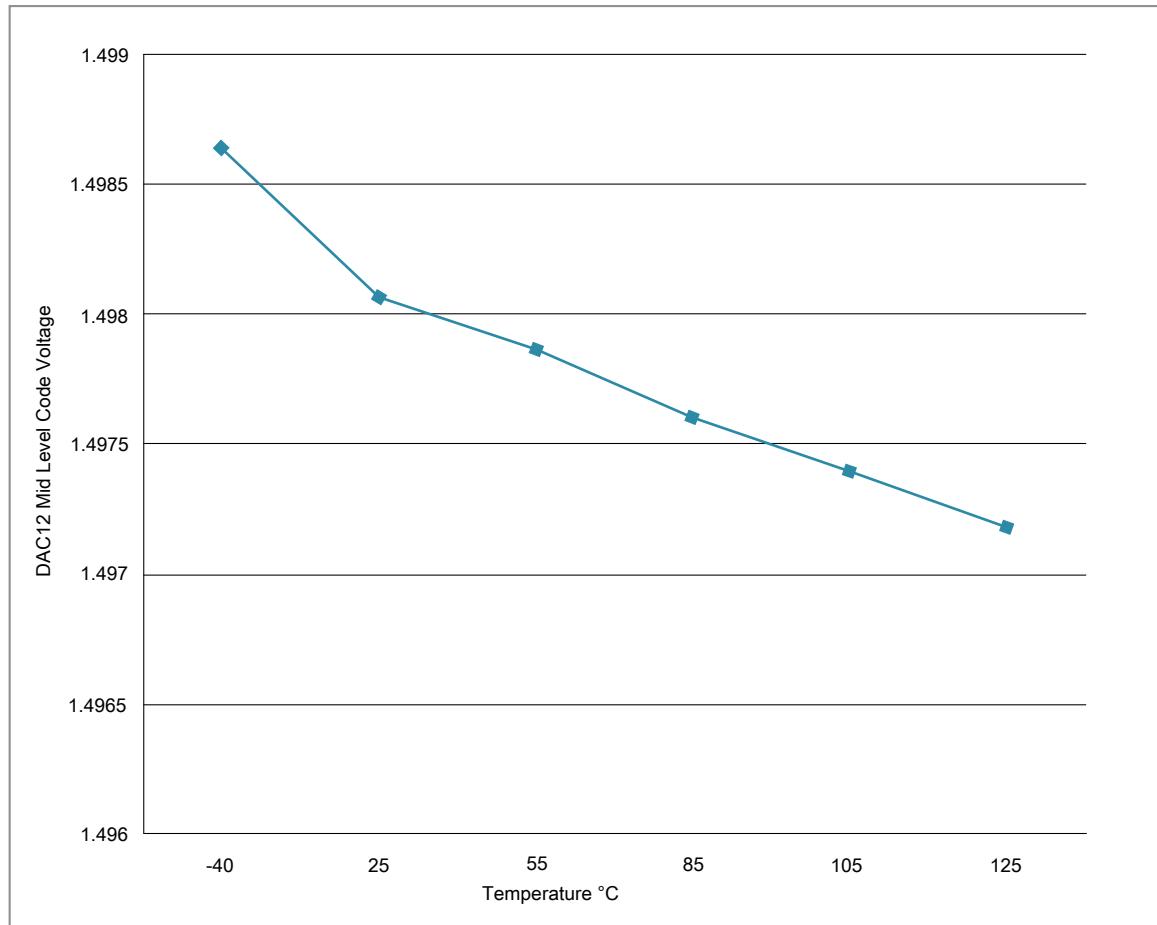


Figure 13. Offset at half scale vs. temperature

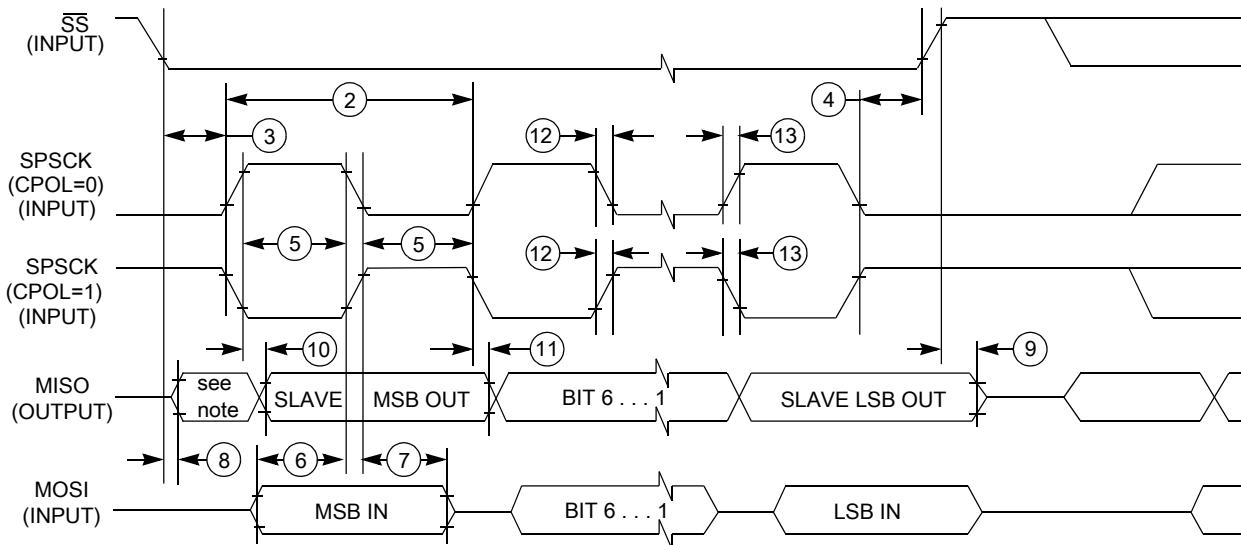
3.7 Timers

See [General switching specifications](#).

3.8 Communication interfaces

3.8.1 USB electrical specifications

The USB electricals for the USB On-the-Go module conform to the standards documented by the Universal Serial Bus Implementers Forum. For the most up-to-date standards, visit [usb.org](#).



NOTE: Not defined

Figure 17. SPI slave mode timing (CPHA = 1)

3.8.4 Inter-Integrated Circuit Interface (I²C) timing

Table 35. I²C timing

Characteristic	Symbol	Standard Mode		Fast Mode		Unit
		Minimum	Maximum	Minimum	Maximum	
SCL Clock Frequency	f _{SCL}	0	100	0	400 ¹	kHz
Hold time (repeated) START condition. After this period, the first clock pulse is generated.	t _{HD} ; STA	4	—	0.6	—	μs
LOW period of the SCL clock	t _{LOW}	4.7	—	1.3	—	μs
HIGH period of the SCL clock	t _{HIGH}	4	—	0.6	—	μs
Set-up time for a repeated START condition	t _{SU} ; STA	4.7	—	0.6	—	μs
Data hold time for I ² C bus devices	t _{HD} ; DAT	0 ²	3.45 ³	0 ⁴	0.9 ²	μs
Data set-up time	t _{SU} ; DAT	250 ⁵	—	100 ^{3, 6}	—	ns
Rise time of SDA and SCL signals	t _r	—	1000	20 + 0.1C _b ⁷	300	ns
Fall time of SDA and SCL signals	t _f	—	300	20 + 0.1C _b ⁶	300	ns
Set-up time for STOP condition	t _{SU} ; STO	4	—	0.6	—	μs
Bus free time between STOP and START condition	t _{BUF}	4.7	—	1.3	—	μs
Pulse width of spikes that must be suppressed by the input filter	t _{SP}	N/A	N/A	0	50	ns

1. The maximum SCL Clock Frequency in Fast mode with maximum bus loading can only be achieved when using the High drive pins (see [Voltage and current operating behaviors](#)) or when using the Normal drive pins and VDD ≥ 2.7 V

2. The master mode I²C deasserts ACK of an address byte simultaneously with the falling edge of SCL. If no slaves acknowledge this address byte, then a negative hold time can result, depending on the edge rates of the SDA and SCL lines.
3. The maximum tHD; DAT must be met only if the device does not stretch the LOW period (tLOW) of the SCL signal.
4. Input signal Slew = 10 ns and Output Load = 50 pF
5. Set-up time in slave-transmitter mode is 1 IPBus clock period, if the TX FIFO is empty.
6. A Fast mode I²C bus device can be used in a Standard mode I²C bus system, but the requirement $t_{SU; DAT} \geq 250$ ns must then be met. This is automatically the case if the device does not stretch the LOW period of the SCL signal. If such a device does stretch the LOW period of the SCL signal, then it must output the next data bit to the SDA line $t_{rmax} + t_{SU; DAT} = 1000 + 250 = 1250$ ns (according to the Standard mode I²C bus specification) before the SCL line is released.
7. C_b = total capacitance of the one bus line in pF.

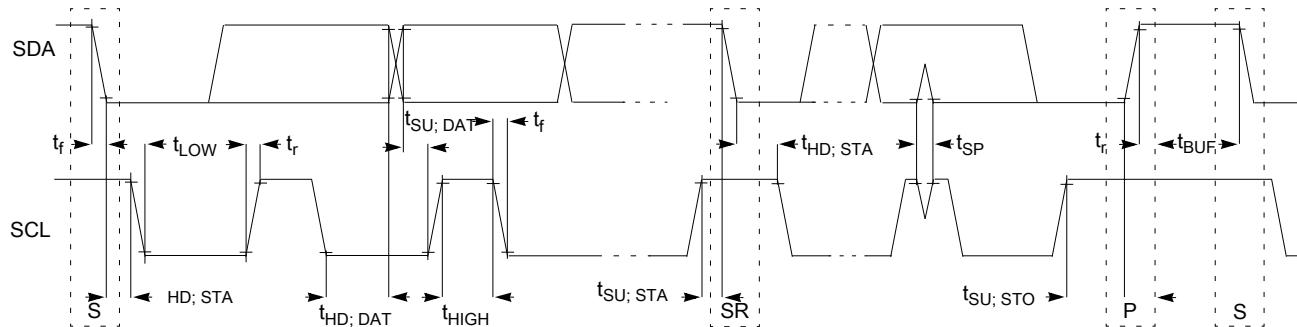


Figure 18. Timing definition for fast and standard mode devices on the I²C bus

3.8.5 UART

See [General switching specifications](#).

3.8.6 I2S/SAI switching specifications

This section provides the AC timing for the I2S/SAI module in master mode (clocks are driven) and slave mode (clocks are input). All timing is given for noninverted serial clock polarity (TCR2[BCP] is 0, RCR2[BCP] is 0) and a noninverted frame sync (TCR4[FSP] is 0, RCR4[FSP] is 0). If the polarity of the clock and/or the frame sync have been inverted, all the timing remains valid by inverting the bit clock signal (BCLK) and/or the frame sync (FS) signal shown in the following figures.

121 BGA	100 LQFP	64 BGA	64 LQFP	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7
E4	1	A1	1	PTE0	DISABLED		PTE0	SPI1_MISO	UART1_TX	RTC_CLKOUT	CMP0_OUT	I2C1_SDA	
E3	2	B1	2	PTE1	DISABLED		PTE1	SPI1_MOSI	UART1_RX		SPI1_MISO	I2C1_SCL	
E2	3	—	—	PTE2	DISABLED		PTE2	SPI1_SCK					
F4	4	—	—	PTE3	DISABLED		PTE3	SPI1_MISO			SPI1_MOSI		
H7	5	—	—	PTE4	DISABLED		PTE4	SPI1_PCS0					
G4	6	—	—	PTE5	DISABLED		PTE5						
F3	7	—	—	PTE6	DISABLED		PTE6			I2S0_MCLK	audioUSB_SOF_OUT		
E6	8	—	3	VDD	VDD	VDD							
G7	9	C4	4	VSS	VSS	VSS							
L6	—	—	—	VSS	VSS	VSS							
F1	10	E1	5	USBO_DP	USBO_DP	USBO_DP							
F2	11	D1	6	USBO_DM	USBO_DM	USBO_DM							
G1	12	E2	7	VOUT33	VOUT33	VOUT33							
G2	13	D2	8	VREGIN	VREGIN	VREGIN							
H1	14	—	—	PTE16	ADC0_DP1/ ADC0_SE1	ADC0_DP1/ ADC0_SE1	PTE16	SPI0_PCS0	UART2_TX	TPM_CLKIN0			
H2	15	—	—	PTE17	ADC0_DM1/ ADC0_SE5a	ADC0_DM1/ ADC0_SE5a	PTE17	SPI0_SCK	UART2_RX	TPM_CLKIN1		LPTMR0_ALT3	
J1	16	—	—	PTE18	ADC0_DP2/ ADC0_SE2	ADC0_DP2/ ADC0_SE2	PTE18	SPI0_MOSI		I2C0_SDA	SPI0_MISO		
J2	17	—	—	PTE19	ADC0_DM2/ ADC0_SE6a	ADC0_DM2/ ADC0_SE6a	PTE19	SPI0_MISO		I2C0_SCL	SPI0_MOSI		
K1	18	G1	9	PTE20	ADC0_DP0/ ADC0_SE0	ADC0_DP0/ ADC0_SE0	PTE20		TPM1_CH0	UART0_TX			
K2	19	F1	10	PTE21	ADC0_DM0/ ADC0_SE4a	ADC0_DM0/ ADC0_SE4a	PTE21		TPM1_CH1	UART0_RX			
L1	20	G2	11	PTE22	ADC0_DP3/ ADC0_SE3	ADC0_DP3/ ADC0_SE3	PTE22		TPM2_CH0	UART2_TX			
L2	21	F2	12	PTE23	ADC0_DM3/ ADC0_SE7a	ADC0_DM3/ ADC0_SE7a	PTE23		TPM2_CH1	UART2_RX			
F5	22	F4	13	VDDA	VDDA	VDDA							
G5	23	G4	14	VREFH	VREFH	VREFH							
G6	24	G3	15	VREFL	VREFL	VREFL							
F6	25	F3	16	VSSA	VSSA	VSSA							
L3	26	H1	17	PTE29	CMP0_IN5/ ADC0_SE4b	CMP0_IN5/ ADC0_SE4b	PTE29		TPM0_CH2	TPM_CLKIN0			
K5	27	H2	18	PTE30	DAC0_OUT/ ADC0_SE23/ CMP0_IN4	DAC0_OUT/ ADC0_SE23/ CMP0_IN4	PTE30		TPM0_CH3	TPM_CLKIN1			
L4	28	H3	19	PTE31	DISABLED		PTE31		TPM0_CH4				
L5	29	—	—	VSS	VSS	VSS							

Pinout

121 BGA	100 LQFP	64 BGA	64 LQFP	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7
K6	30	—	—	VDD	VDD	VDD							
H5	31	H4	20	PTE24	DISABLED		PTE24		TPM0_CH0		I2C0_SCL		
J5	32	H5	21	PTE25	DISABLED		PTE25		TPM0_CH1		I2C0_SDA		
H6	33	—	—	PTE26	DISABLED		PTE26		TPM0_CH5			RTC_CLKOUT	USB_CLKIN
J6	34	D3	22	PTA0	SWD_CLK	TSI0_CH1	PTA0		TPM0_CH5				SWD_CLK
H8	35	D4	23	PTA1	DISABLED	TSI0_CH2	PTA1	UART0_RX	TPM2_CH0				
J7	36	E5	24	PTA2	DISABLED	TSI0_CH3	PTA2	UART0_TX	TPM2_CH1				
H9	37	D5	25	PTA3	SWD_DIO	TSI0_CH4	PTA3	I2C1_SCL	TPM0_CH0				SWD_DIO
J8	38	G5	26	PTA4	NMI_b	TSI0_CH5	PTA4	I2C1_SDA	TPM0_CH1				NMI_b
K7	39	F5	27	PTA5	DISABLED		PTA5	USB_CLKIN	TPM0_CH2				I2S0_TX_BCLK
E5	—	—	—	VDD	VDD	VDD							
G3	—	—	—	VSS	VSS	VSS							
K3	40	—	—	PTA6	DISABLED		PTA6		TPM0_CH3				
H4	41	—	—	PTA7	DISABLED		PTA7		TPM0_CH4				
K8	42	H6	28	PTA12	DISABLED		PTA12		TPM1_CH0				I2S0_TXD0
L8	43	G6	29	PTA13	DISABLED		PTA13		TPM1_CH1				I2S0_TX_FS
K9	44	—	—	PTA14	DISABLED		PTA14	SPI0_PCS0	UART0_TX				I2S0_RX_BCLK
L9	45	—	—	PTA15	DISABLED		PTA15	SPI0_SCK	UART0_RX				I2S0_RXD0
J10	46	—	—	PTA16	DISABLED		PTA16	SPI0_MOSI			SPI0_MISO	I2S0_RX_FS	I2S0_RXD0
H10	47	—	—	PTA17	DISABLED		PTA17	SPI0_MISO			SPI0_MOSI	I2S0_MCLK	
L10	48	G7	30	VDD	VDD	VDD							
K10	49	H7	31	VSS	VSS	VSS							
L11	50	H8	32	PTA18	EXTAL0	EXTAL0	PTA18		UART1_RX	TPM_CLKIN0			
K11	51	G8	33	PTA19	XTAL0	XTAL0	PTA19		UART1_TX	TPM_CLKIN1			LPTMR0_ALT1
J11	52	F8	34	PTA20	RESET_b		PTA20						RESET_b
G11	53	F7	35	PTB0/ LLWU_P5	ADC0_SE8/ TSI0_CH0	ADC0_SE8/ TSI0_CH0	PTB0/ LLWU_P5	I2C0_SCL	TPM1_CH0				
G10	54	F6	36	PTB1	ADC0_SE9/ TSI0_CH6	ADC0_SE9/ TSI0_CH6	PTB1	I2C0_SDA	TPM1_CH1				
G9	55	E7	37	PTB2	ADC0_SE12/ TSI0_CH7	ADC0_SE12/ TSI0_CH7	PTB2	I2C0_SCL	TPM2_CH0				
G8	56	E8	38	PTB3	ADC0_SE13/ TSI0_CH8	ADC0_SE13/ TSI0_CH8	PTB3	I2C0_SDA	TPM2_CH1				
E11	57	—	—	PTB7	DISABLED		PTB7						
D11	58	—	—	PTB8	DISABLED		PTB8	SPI1_PCS0	EXTRG_IN				
E10	59	—	—	PTB9	DISABLED		PTB9	SPI1_SCK					
D10	60	—	—	PTB10	DISABLED		PTB10	SPI1_PCS0					

121 BGA	100 LQFP	64 BGA	64 LQFP	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7
C10	61	—	—	PTB11	DISABLED		PTB11	SPI1_SCK					
B10	62	E6	39	PTB16	TSI0_CH9	TSI0_CH9	PTB16	SPI1_MOSI	UART0_RX	TPM_CLKIN0	SPI1_MISO		
E9	63	D7	40	PTB17	TSI0_CH10	TSI0_CH10	PTB17	SPI1_MISO	UART0_TX	TPM_CLKIN1	SPI1_MOSI		
D9	64	D6	41	PTB18	TSI0_CH11	TSI0_CH11	PTB18		TPM2_CH0	I2S0_TX_BCLK			
C9	65	C7	42	PTB19	TSI0_CH12	TSI0_CH12	PTB19		TPM2_CH1	I2S0_TX_FS			
F10	66	—	—	PTB20	DISABLED		PTB20					CMP0_OUT	
F9	67	—	—	PTB21	DISABLED		PTB21						
F8	68	—	—	PTB22	DISABLED		PTB22						
E8	69	—	—	PTB23	DISABLED		PTB23						
B9	70	D8	43	PTC0	ADC0_SE14/ TSI0_CH13	ADC0_SE14/ TSI0_CH13	PTC0		EXTRG_IN	audioUSB_SOF_OUT	CMP0_OUT	I2S0_TXD0	
D8	71	C6	44	PTC1/ LLWU_P6/ RTC_CLKIN	ADC0_SE15/ TSI0_CH14	ADC0_SE15/ TSI0_CH14	PTC1/ LLWU_P6/ RTC_CLKIN	I2C1_SCL		TPM0_CH0		I2S0_TXD0	
C8	72	B7	45	PTC2	ADC0_SE11/ TSI0_CH15	ADC0_SE11/ TSI0_CH15	PTC2	I2C1_SDA		TPM0_CH1		I2S0_TX_FS	
B8	73	C8	46	PTC3/ LLWU_P7	DISABLED		PTC3/ LLWU_P7		UART1_RX	TPM0_CH2	CLKOUT	I2S0_TX_BCLK	
F7	74	E3	47	VSS	VSS	VSS							
E7	75	E4	48	VDD	VDD	VDD							
A10	—	—	—	PTC20	DISABLED		PTC20						
A9	—	—	—	PTC21	DISABLED		PTC21						
B11	—	—	—	PTC22	DISABLED		PTC22						
C11	—	—	—	PTC23	DISABLED		PTC23						
A8	76	B8	49	PTC4/ LLWU_P8	DISABLED		PTC4/ LLWU_P8	SPI0_PCS0	UART1_TX	TPM0_CH3	I2S0_MCLK		
D7	77	A8	50	PTC5/ LLWU_P9	DISABLED		PTC5/ LLWU_P9	SPI0_SCK	LPTMR0_ALT2	I2S0_RXD0		CMP0_OUT	
C7	78	A7	51	PTC6/ LLWU_P10	CMP0_IN0	CMP0_IN0	PTC6/ LLWU_P10	SPI0_MOSI	EXTRG_IN	I2S0_RX_BCLK	SPI0_MISO	I2S0_MCLK	
B7	79	B6	52	PTC7	CMP0_IN1	CMP0_IN1	PTC7	SPI0_MISO	audioUSB_SOF_OUT	I2S0_RX_FS	SPI0_MOSI		
A7	80	A6	53	PTC8	CMP0_IN2	CMP0_IN2	PTC8	I2C0_SCL	TPM0_CH4	I2S0_MCLK			
D6	81	B5	54	PTC9	CMP0_IN3	CMP0_IN3	PTC9	I2C0_SDA	TPM0_CH5	I2S0_RX_BCLK			
C6	82	B4	55	PTC10	DISABLED		PTC10	I2C1_SCL		I2S0_RX_FS			
C5	83	A5	56	PTC11	DISABLED		PTC11	I2C1_SDA		I2S0_RXD0			
B6	84	—	—	PTC12	DISABLED		PTC12			TPM_CLKIN0			
A6	85	—	—	PTC13	DISABLED		PTC13			TPM_CLKIN1			

	1	2	3	4	5	6	7	8	9	10	11	
A	PTD7	PTD5	PTD4/ LLWU_P14	NC	NC	PTC13	PTC8	PTC4/ LLWU_P8	PTC21	PTC20	NC	A
B	NC	PTD6/ LLWU_P15	PTD3	PTC18	NC	PTC12	PTC7	PTC3/ LLWU_P7	PTC0	PTB16	PTC22	B
C	NC	NC	PTD2	PTC17	PTC11	PTC10	PTC6/ LLWU_P10	PTC2	PTB19	PTB11	PTC23	C
D	NC	NC	PTD1	PTD0	PTC16	PTC9	PTC5/ LLWU_P9	PTC1/ LLWU_P6/ RTC_CLKIN	PTB18	PTB10	PTB8	D
E	NC	PTE2	PTE1	PTE0	VDD	VDD	VDD	PTB23	PTB17	PTB9	PTB7	E
F	USB0_DP	USB0_DM	PTE6	PTE3	VDDA	VSSA	VSS	PTB22	PTB21	PTB20	NC	F
G	VOUT33	VREGIN	VSS	PTE5	VREFH	VREFL	VSS	PTB3	PTB2	PTB1	PTB0/ LLWU_P5	G
H	PTE16	PTE17	NC	PTA7	PTE24	PTE26	PTE4	PTA1	PTA3	PTA17	NC	H
J	PTE18	PTE19	NC	NC	PTE25	PTA0	PTA2	PTA4	NC	PTA16	PTA20	J
K	PTE20	PTE21	PTA6	NC	PTE30	VDD	PTA5	PTA12	PTA14	VSS	PTA19	K
L	PTE22	PTE23	PTE29	PTE31	VSS	VSS	NC	PTA13	PTA15	VDD	PTA18	L
	1	2	3	4	5	6	7	8	9	10	11	

Figure 23. KL26 121-pin BGA pinout diagram

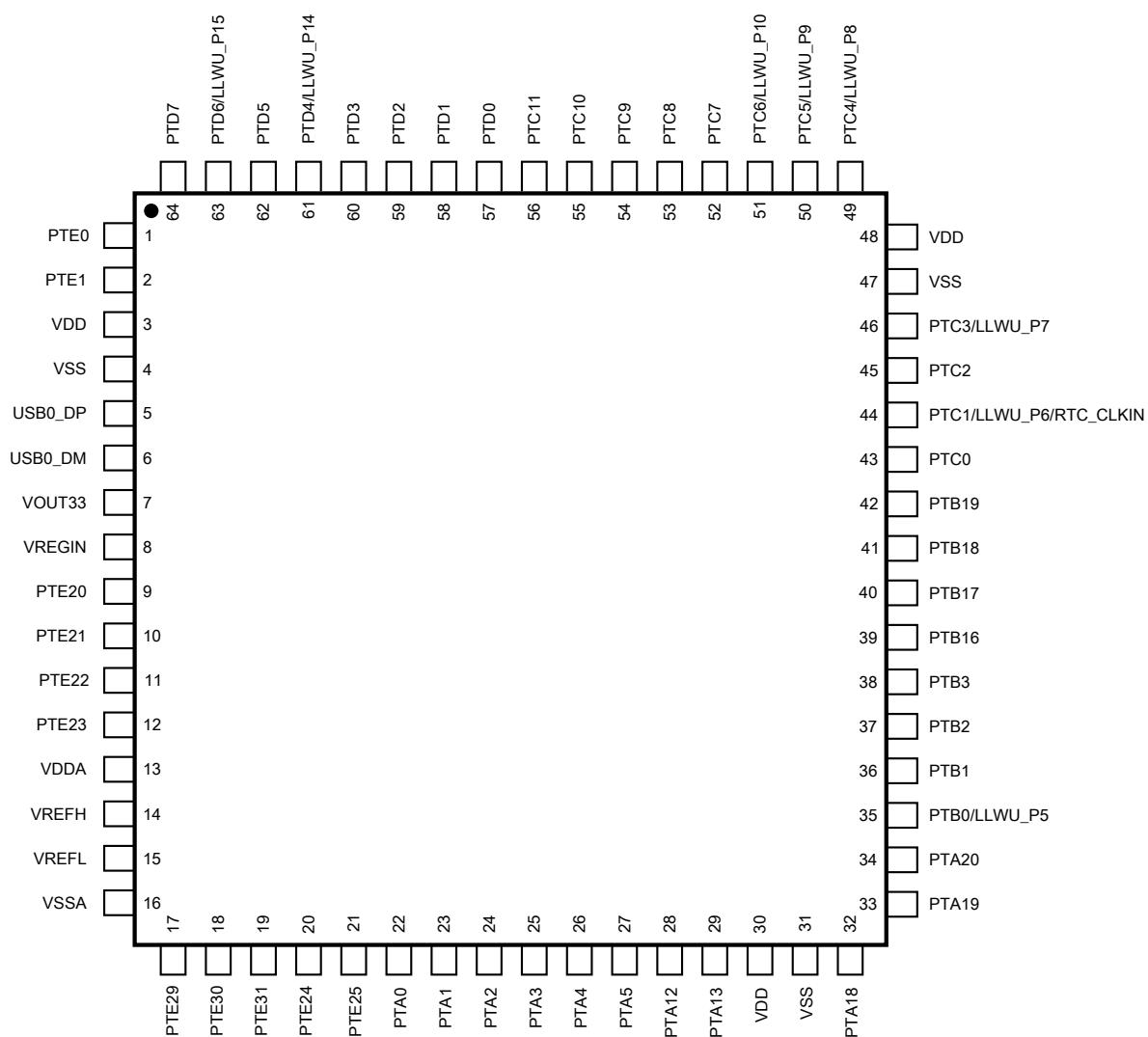


Figure 25. KL26 64-pin LQFP pinout diagram

	1	2	3	4	5	6	7	8	
A	PTE0	PTD7	PTD4 /LLWU_P14	PTD1	PTC11	PTC8	PTC6 /LLWU_P10	PTC5 /LLWU_P9	A
B	PTE1	PTD6 /LLWU_P15	PTD3	PTC10	PTC9	PTC7	PTC2	PTC4 /LLWU_P8	B
C	PTD5	PTD2	PTD0	VSS	NC	PTC1 /LLWU_P6 /RTC _CLKIN	PTB19	PTC3 /LLWU_P7	C
D	USB0_DM	VREGIN	PTA0	PTA1	PTA3	PTB18	PTB17	PTC0	D
E	USB0_DP	VOUT33	VSS	VDD	PTA2	PTB16	PTB2	PTB3	E
F	PTE21	PTE23	VSSA	VDDA	PTA5	PTB1	PTB0 /LLWU_P5	PTA20	F
G	PTE20	PTE22	VREFL	VREFH	PTA4	PTA13	VDD	PTA19	G
H	PTE29	PTE30	PTE31	PTE24	PTE25	PTA12	VSS	PTA18	H
	1	2	3	4	5	6	7	8	

Figure 26. KL26 64-pin MAPBGA pinout diagram

6 Ordering parts

6.1 Determining valid orderable parts

Valid orderable part numbers are provided on the web. To determine the orderable part numbers for this device, go to freescale.com and perform a part number search for the following device numbers: PKL26 and MKL26

7 Part identification

7.1 Description

Part numbers for the chip have fields that identify the specific part. You can use the values of these fields to determine the specific part you have received.

7.2 Format

Part numbers for this device have the following format:

Q KL## A FFF R T PP CC N

7.3 Fields

This table lists the possible values for each field in the part number (not all combinations are valid):

Table 41. Part number fields descriptions

Field	Description	Values
Q	Qualification status	<ul style="list-style-type: none"> M = Fully qualified, general market flow P = Prequalification
KL##	Kinetis family	• KL26
A	Key attribute	• Z = Cortex-M0+
FFF	Program flash memory size	<ul style="list-style-type: none"> 128 = 128 KB 256 = 256 KB
R	Silicon revision	<ul style="list-style-type: none"> (Blank) = Main A = Revision after main
T	Temperature range (°C)	• V = -40 to 105
PP	Package identifier	<ul style="list-style-type: none"> LH = 64 LQFP (10 mm x 10 mm) MP = 64 MAPBGA (5 mm x 5 mm) LL = 100 LQFP (14 mm x 14 mm) MC = 121 MAPBGA (8 mm x 8 mm)
CC	Maximum CPU frequency (MHz)	• 4 = 48 MHz
N	Packaging type	• R = Tape and reel

7.4 Example

This is an example part number:

MKL26Z256VLH4

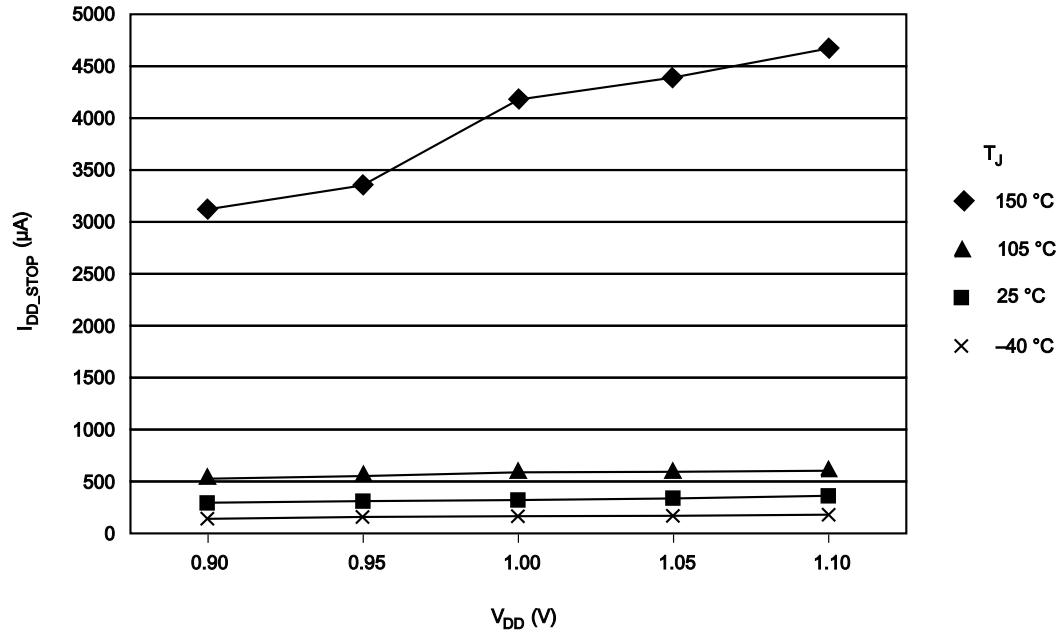
8.8.1 Example 1

This is an example of an operating behavior that includes a typical value:

Symbol	Description	Min.	Typ.	Max.	Unit
I_{WP}	Digital I/O weak pullup/pulldown current	10	70	130	μA

8.8.2 Example 2

This is an example of a chart that shows typical values for various voltage and temperature conditions:



8.9 Typical value conditions

Typical values assume you meet the following conditions (or other conditions as specified):