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#### What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

Product Status	Not For New Designs
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	32MHz
Connectivity	I <sup>2</sup> C, IrDA, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I <sup>2</sup> S, LCD, POR, PWM, WDT
Number of I/O	37
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	1.85V ~ 3.8V
Data Converters	A/D 4x12b; D/A 1x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-TQFP
Supplier Device Package	48-TQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32tg822f8-qfp48t

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

# 2.1.11 Universal Synchronous/Asynchronous Receiver/Transmitter (US-ART)

The Universal Synchronous Asynchronous serial Receiver and Transmitter (USART) is a very flexible serial I/O module. It supports full duplex asynchronous UART communication as well as RS-485, SPI, MicroWire and 3-wire. It can also interface with ISO7816 SmartCards, IrDA and I2S devices.

# 2.1.12 Pre-Programmed UART Bootloader

The bootloader presented in application note AN0003 is pre-programmed in the device at factory. Autobaud and destructive write are supported. The autobaud feature, interface and commands are described further in the application note.

# 2.1.13 Low Energy Universal Asynchronous Receiver/Transmitter (LEUART)

The unique LEUART<sup>TM</sup>, the Low Energy UART, is a UART that allows two-way UART communication on a strict power budget. Only a 32.768 kHz clock is needed to allow UART communication up to 9600 baud/s. The LEUART includes all necessary hardware support to make asynchronous serial communication possible with minimum of software intervention and energy consumption.

# 2.1.14 Timer/Counter (TIMER)

The 16-bit general purpose Timer has 3 compare/capture channels for input capture and compare/Pulse-Width Modulation (PWM) output.

# 2.1.15 Real Time Counter (RTC)

The Real Time Counter (RTC) contains a 24-bit counter and is clocked either by a 32.768 kHz crystal oscillator, or a 32.768 kHz RC oscillator. In addition to energy modes EM0 and EM1, the RTC is also available in EM2. This makes it ideal for keeping track of time since the RTC is enabled in EM2 where most of the device is powered down.

### 2.1.16 Low Energy Timer (LETIMER)

The unique LETIMER<sup>TM</sup>, the Low Energy Timer, is a 16-bit timer that is available in energy mode EM2 in addition to EM1 and EM0. Because of this, it can be used for timing and output generation when most of the device is powered down, allowing simple tasks to be performed while the power consumption of the system is kept at an absolute minimum. The LETIMER can be used to output a variety of waveforms with minimal software intervention. It is also connected to the Real Time Counter (RTC), and can be configured to start counting on compare matches from the RTC.

# 2.1.17 Pulse Counter (PCNT)

The Pulse Counter (PCNT) can be used for counting pulses on a single input or to decode quadrature encoded inputs. It runs off either the internal LFACLK or the PCNTn\_S0IN pin as external clock source. The module may operate in energy mode EM0 - EM3.

# 2.1.18 Analog Comparator (ACMP)

The Analog Comparator is used to compare the voltage of two analog inputs, with a digital output indicating which input voltage is higher. Inputs can either be one of the selectable internal references or from external pins. Response time and thereby also the current consumption can be configured by altering the current supply to the comparator.

# 2.1.19 Voltage Comparator (VCMP)

The Voltage Supply Comparator is used to monitor the supply voltage from software. An interrupt can be generated when the supply falls below or rises above a programmable threshold. Response time and thereby also the current consumption can be configured by altering the current supply to the comparator.

### 2.1.20 Analog to Digital Converter (ADC)

The ADC is a Successive Approximation Register (SAR) architecture, with a resolution of up to 12 bits at up to one million samples per second. The integrated input mux can select inputs from 4 external pins and 6 internal signals.

# 2.1.21 Digital to Analog Converter (DAC)

The Digital to Analog Converter (DAC) can convert a digital value to an analog output voltage. The DAC is fully differential rail-to-rail, with 12-bit resolution. It has one single ended output buffer connected to channel 0. The DAC may be used for a number of different applications such as sensor interfaces or sound output.

### 2.1.22 Operational Amplifier (OPAMP)

The EFM32TG822 features 3 Operational Amplifiers. The Operational Amplifier is a versatile general purpose amplifier with rail-to-rail differential input and rail-to-rail single ended output. The input can be set to pin, DAC or OPAMP, whereas the output can be pin, OPAMP or ADC. The current is programmable and the OPAMP has various internal configurations such as unity gain, programmable gain using internal resistors etc.

### 2.1.23 Low Energy Sensor Interface (LESENSE)

The Low Energy Sensor Interface (LESENSE<sup>TM</sup>), is a highly configurable sensor interface with support for up to 4 individually configurable sensors. By controlling the analog comparators and DAC, LESENSE is capable of supporting a wide range of sensors and measurement schemes, and can for instance measure LC sensors, resistive sensors and capacitive sensors. LESENSE also includes a programmable FSM which enables simple processing of measurement results without CPU intervention. LESENSE is available in energy mode EM2, in addition to EM0 and EM1, making it ideal for sensor monitoring in applications with a strict energy budget.

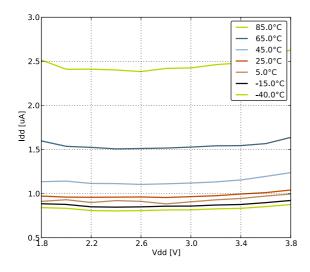
# 2.1.24 Advanced Encryption Standard Accelerator (AES)

The AES accelerator performs AES encryption and decryption with 128-bit or 256-bit keys. Encrypting or decrypting one 128-bit data block takes 52 HFCORECLK cycles with 128-bit keys and 75 HFCORECLK cycles with 256-bit keys. The AES module is an AHB slave which enables efficient access to the data and key registers. All write accesses to the AES module must be 32-bit operations, i.e. 8- or 16-bit operations are not supported.

### 2.1.25 General Purpose Input/Output (GPIO)

In the EFM32TG822, there are 37 General Purpose Input/Output (GPIO) pins, which are divided into ports with up to 16 pins each. These pins can individually be configured as either an output or input. More advanced configurations like open-drain, filtering and drive strength can also be configured individually for the pins. The GPIO pins can also be overridden by peripheral pin connections, like Timer PWM outputs or USART communication, which can be routed to several locations on the device. The GPIO supports up to 16 asynchronous external pin interrupts, which enables interrupts from any pin on the device. Also, the input value of a pin can be routed through the Peripheral Reflex System to other peripherals.

Figure 3.1. EM2 current consumption. RTC prescaled to 1kHz, 32.768 kHz LFRCO.



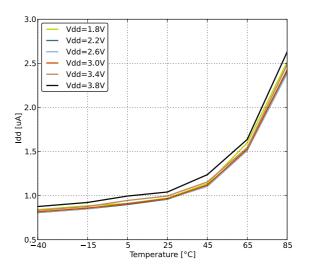


Figure 3.2. EM3 current consumption.

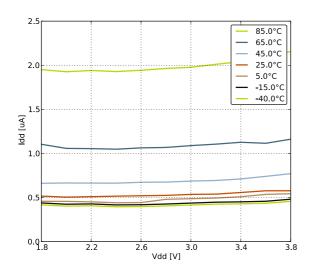
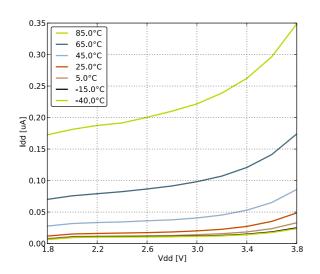
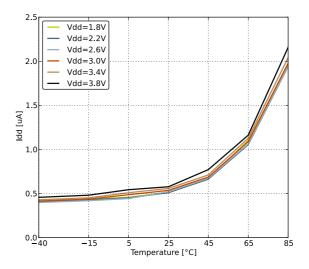
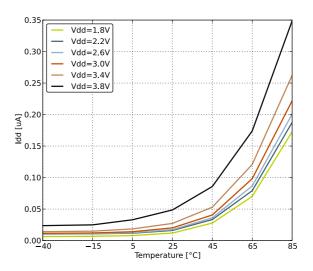


Figure 3.3. EM4 current consumption.







# 3.7 Flash

#### Table 3.6. Flash

Symbol	Parameter	Condition	Min	Тур	Max	Unit
EC <sub>FLASH</sub>	Flash erase cycles before failure		20000			cycles
		T <sub>AMB</sub> <150°C	10000			h
RET <sub>FLASH</sub>	Flash data retention	T <sub>AMB</sub> <85°C	10			years
		T <sub>AMB</sub> <70°C	20			years
t <sub>W_PROG</sub>	Word (32-bit) pro- gramming time		20			μs
t <sub>P_ERASE</sub>	Page erase time		20	20.4	20.8	ms
t <sub>D_ERASE</sub>	Device erase time		40	40.8	41.6	ms
I <sub>ERASE</sub>	Erase current				7 <sup>1</sup>	mA
I <sub>WRITE</sub>	Write current				7 <sup>1</sup>	mA
V <sub>FLASH</sub>	Supply voltage dur- ing flash erase and write		1.98		3.8	V

<sup>1</sup>Measured at 25°C

# **3.8 General Purpose Input Output**

#### Table 3.7. GPIO

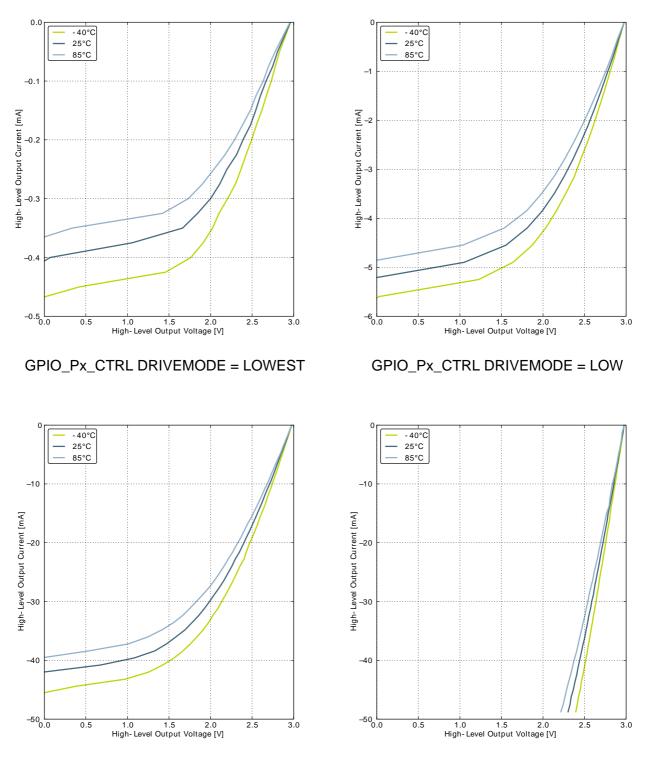
Symbol	Parameter	Condition	Min	Тур	Max	Unit
V <sub>IOIL</sub>	Input low voltage				0.30V <sub>DD</sub>	V
V <sub>IOIH</sub>	Input high voltage		0.70V <sub>DD</sub>			V
		Sourcing 0.1 mA, V <sub>DD</sub> =1.98 V, GPIO_Px_CTRL DRIVEMODE = LOWEST		0.80V <sub>DD</sub>		V
		Sourcing 0.1 mA, V <sub>DD</sub> =3.0 V, GPIO_Px_CTRL DRIVEMODE = LOWEST		0.90V <sub>DD</sub>		V
		Sourcing 1 mA, V <sub>DD</sub> =1.98 V, GPIO_Px_CTRL DRIVEMODE = LOW		0.85V <sub>DD</sub>		V
V <sub>IOOH</sub>	Output high volt- age (Production test condition = 3.0V, DRIVEMODE =	Sourcing 1 mA, V <sub>DD</sub> =3.0 V, GPIO_Px_CTRL DRIVEMODE = LOW		0.90V <sub>DD</sub>		V
	STANDARD)	Sourcing 6 mA, V <sub>DD</sub> =1.98 V, GPIO_Px_CTRL DRIVEMODE = STANDARD	0.75V <sub>DD</sub>			V
		Sourcing 6 mA, V <sub>DD</sub> =3.0 V, GPIO_Px_CTRL DRIVEMODE = STANDARD	0.85V <sub>DD</sub>			V
		Sourcing 20 mA, V <sub>DD</sub> =1.98 V, GPIO_Px_CTRL DRIVEMODE = HIGH	0.60V <sub>DD</sub>			V



Symbol	Parameter	Condition	Min	Тур	Max	Unit
		Sourcing 20 mA, V <sub>DD</sub> =3.0 V, GPIO_Px_CTRL DRIVEMODE = HIGH	0.80V <sub>DD</sub>			V
		Sinking 0.1 mA, V <sub>DD</sub> =1.98 V, GPIO_Px_CTRL DRIVEMODE = LOWEST		0.20V <sub>DD</sub>		V
		Sinking 0.1 mA, V <sub>DD</sub> =3.0 V, GPIO_Px_CTRL DRIVEMODE = LOWEST		0.10V <sub>DD</sub>		V
		Sinking 1 mA, V <sub>DD</sub> =1.98 V, GPIO_Px_CTRL DRIVEMODE = LOW		0.10V <sub>DD</sub>		V
View	Output low voltage (Production test condition = 3.0V,	Sinking 1 mA, V <sub>DD</sub> =3.0 V, GPIO_Px_CTRL DRIVEMODE = LOW		0.05V <sub>DD</sub>		V
V <sub>IOOL</sub>	DRIVEMODE = STANDARD)	Sinking 6 mA, V <sub>DD</sub> =1.98 V, GPIO_Px_CTRL DRIVEMODE = STANDARD			0.30V <sub>DD</sub>	V
		Sinking 6 mA, V <sub>DD</sub> =3.0 V, GPIO_Px_CTRL DRIVEMODE = STANDARD			0.20V <sub>DD</sub>	V
		Sinking 20 mA, V <sub>DD</sub> =1.98 V, GPIO_Px_CTRL DRIVEMODE = HIGH			0.35V <sub>DD</sub>	V
		Sinking 20 mA, V <sub>DD</sub> =3.0 V, GPIO_Px_CTRL DRIVEMODE = HIGH			0.20V <sub>DD</sub>	V
I <sub>IOLEAK</sub>	Input leakage cur- rent	High Impedance IO connected to GROUND or $V_{DD}$		±0.1	±100	nA
R <sub>PU</sub>	I/O pin pull-up resis- tor			40		kOhm
R <sub>PD</sub>	I/O pin pull-down re- sistor			40		kOhm
R <sub>IOESD</sub>	Internal ESD series resistor			200		Ohm
t <sub>IOGLITCH</sub>	Pulse width of puls- es to be removed by the glitch sup- pression filter		10		50	ns
t <sub>IOOF</sub>		$\begin{array}{c c} GPIO_{Px}CTRL DRIVEMODE \\ = LOWEST and load capaci- \\ tance C_{L}=12.5-25pF. \end{array}$		250	ns	
	Output fall time	GPIO_Px_CTRL DRIVEMODE = LOW and load capacitance $C_L$ =350-600pF	20+0.1C <sub>L</sub>		250	ns
V <sub>IOHYST</sub>	I/O pin hysteresis (V <sub>IOTHR+</sub> - V <sub>IOTHR-</sub> )	V <sub>DD</sub> = 1.98 - 3.8 V	0.1V <sub>DD</sub>			V



#### Figure 3.7. Typical High-Level Output Current, 3V Supply Voltage

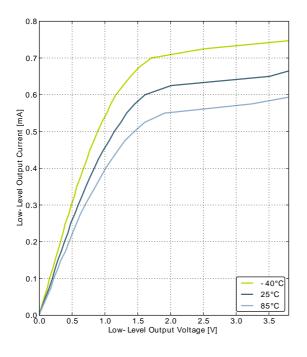


GPIO\_Px\_CTRL DRIVEMODE = STANDARD

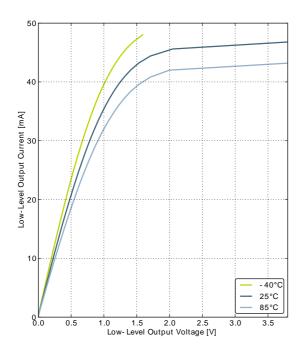
GPIO\_Px\_CTRL DRIVEMODE = HIGH



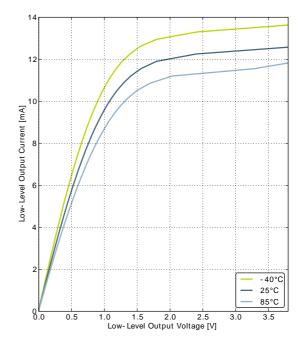
#### Figure 3.8. Typical Low-Level Output Current, 3.8V Supply Voltage



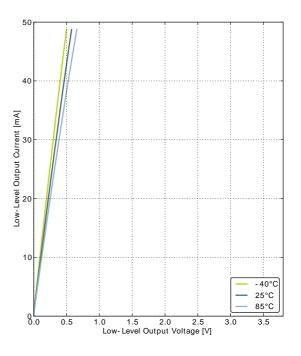
GPIO\_Px\_CTRL DRIVEMODE = LOWEST



GPIO\_Px\_CTRL DRIVEMODE = STANDARD



GPIO\_Px\_CTRL DRIVEMODE = LOW



GPIO\_Px\_CTRL DRIVEMODE = HIGH

# 3.9 Oscillators

### 3.9.1 LFXO

#### Table 3.8. LFXO

Symbol	Parameter	Condition	Min	Тур	Max	Unit
f <sub>LFXO</sub>	Supported nominal crystal frequency			32.768		kHz
ESR <sub>LFXO</sub>	Supported crystal equivalent series re- sistance (ESR)		30		120	kOhm
C <sub>LFXOL</sub>	Supported crystal external load range		X <sup>1</sup>		25	pF
I <sub>LFXO</sub>	Current consump- tion for core and buffer after startup.	ESR=30 kOhm, C <sub>L</sub> =10 pF, LFXOBOOST in CMU_CTRL is 1		190		nA
t <sub>LFXO</sub>	Start- up time.	ESR=30 kOhm, C <sub>L</sub> =10 pF, 40% - 60% duty cycle has been reached, LFXOBOOST in CMU_CTRL is 1		400		ms

<sup>1</sup>See Minimum Load Capacitance (C<sub>LFXOL</sub>) Requirement For Safe Crystal Startup in energyAware Designer in Simplicity Studio

For safe startup of a given crystal, the energyAware Designer in Simplicity Studio contains a tool to help users configure both load capacitance and software settings for using the LFXO. For details regarding the crystal configuration, the reader is referred to application note "AN0016 EFM32 Oscillator Design Consideration".

### 3.9.2 HFXO

#### Table 3.9. HFXO

Symbol	Parameter	Condition	Min	Тур	Max	Unit
f <sub>HFXO</sub>	Supported nominal crystal Frequency		4		32	MHz
FOD	Supported crystal	Crystal frequency 32 MHz		30	60	Ohm
ESR <sub>HFXO</sub>	equivalent series re- sistance (ESR)	Crystal frequency 4 MHz		400	1500	Ohm
<b>G</b> <sub>mHFXO</sub>	The transconduc- tance of the HFXO input transistor at crystal startup	HFXOBOOST in CMU_CTRL equals 0b11	20			mS
C <sub>HFXOL</sub>	Supported crystal external load range		5		25	pF
1	Current consump-	4 MHz: ESR=400 Ohm, C <sub>L</sub> =20 pF, HFXOBOOST in CMU_CTRL equals 0b11		85		μΑ
IHFXO	tion for HFXO after startup	32 MHz: ESR=30 Ohm, C <sub>L</sub> =10 pF, HFXOBOOST in CMU_CTRL equals $0b11$		165		μA
t <sub>HFXO</sub>	Startup time	32 MHz: ESR=30 Ohm, C <sub>L</sub> =10 pF, HFXOBOOST in CMU_CTRL equals 0b11		400		μs



Symbol	Parameter	Condition	Min	Тур	Max	Unit
		f <sub>HFRCO</sub> = 14 MHz		104	120	μA
		f <sub>HFRCO</sub> = 11 MHz		94	110	μA
		f <sub>HFRCO</sub> = 6.6 MHz		63	90	μA
		f <sub>HFRCO</sub> = 1.2 MHz		22	32	μA
TUNESTEP <sub>H-</sub> FRCO	Frequency step for LSB change in TUNING value			0.3 <sup>3</sup>		%

<sup>1</sup>For devices with prod. rev. < 19, Typ = 7MHz and Min/Max values not applicable.

 $^{2}$ For devices with prod. rev. < 19, Typ = 1MHz and Min/Max values not applicable.

<sup>3</sup>The TUNING field in the CMU\_HFRCOCTRL register may be used to adjust the HFRCO frequency. There is enough adjustment range to ensure that the frequency bands above 7 MHz will always have some overlap across supply voltage and temperature. By using a stable frequency reference such as the LFXO or HFXO, a firmware calibration routine can vary the TUNING bits and the frequency band to maintain the HFRCO frequency at any arbitrary value between 7 MHz and 28 MHz across operating conditions.

Figure 3.11. Calibrated HFRCO 1 MHz Band Frequency vs Supply Voltage and Temperature

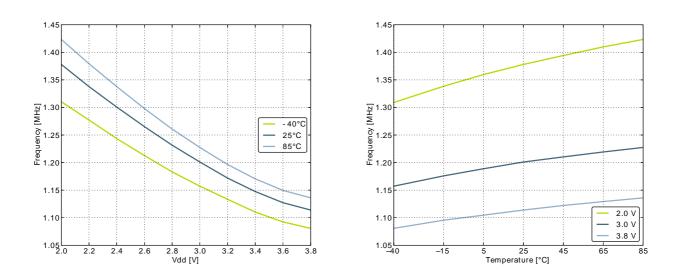
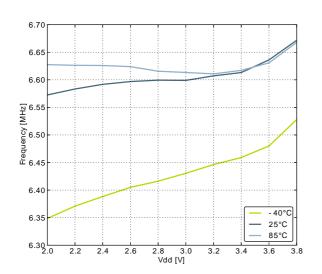
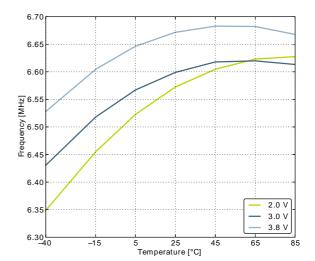
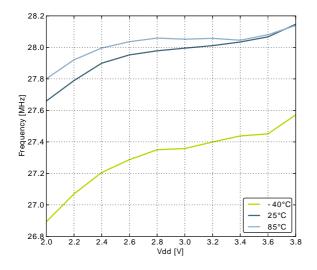


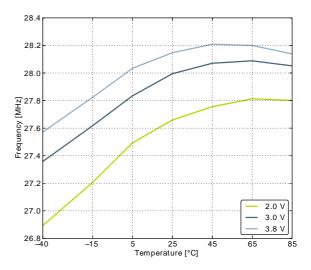
Figure 3.12. Calibrated HFRCO 7 MHz Band Frequency vs Supply Voltage and Temperature





#### Figure 3.16. Calibrated HFRCO 28 MHz Band Frequency vs Supply Voltage and Temperature





### 3.9.5 AUXHFRCO

#### Table 3.12. AUXHFRCO

Symbol	Parameter	Condition	Min	Тур	Max	Unit
		28 MHz frequency band	27.16	28.0	28.84	MHz
		21 MHz frequency band	20.37	21.0	21.63	MHz
£	Oscillation frequen-	14 MHz frequency band	13.58	14.0	14.42	MHz
<sup>†</sup> AUXHFRCO	cy, V <sub>DD</sub> = 3.0 V, T <sub>AMB</sub> =25°C	11 MHz frequency band	10.67	11.0	11.33	MHz
		7 MHz frequency band	6.40 <sup>1</sup>	6.60 <sup>1</sup>	6.80 <sup>1</sup>	MHz
		1 MHz frequency band	1.16 <sup>2</sup>	1.20 <sup>2</sup>	1.24 <sup>2</sup>	MHz
t <sub>AUXHFRCO_settlir</sub>	<sub>g</sub> Settling time after start-up	f <sub>AUXHFRCO</sub> = 14 MHz		0.6		Cycles
TUNESTEP <sub>AU&gt;</sub> HFRCO	Frequency step for LSB change in TUNING value			0.3 <sup>3</sup>		%

<sup>1</sup>For devices with prod. rev. < 19, Typ = 7MHz and Min/Max values not applicable.

 $^{2}$ For devices with prod. rev. < 19, Typ = 1MHz and Min/Max values not applicable.

<sup>3</sup>The TUNING field in the CMU\_AUXHFRCOCTRL register may be used to adjust the AUXHFRCO frequency. There is enough adjustment range to ensure that the frequency bands above 7 MHz will always have some overlap across supply voltage and temperature. By using a stable frequency reference such as the LFXO or HFXO, a firmware calibration routine can vary the TUNING bits and the frequency band to maintain the AUXHFRCO frequency at any arbitrary value between 7 MHz and 28 MHz across operating conditions.

### 3.9.6 ULFRCO

#### Table 3.13. ULFRCO

Symbol	Parameter	Condition	Min	Тур	Мах	Unit
fulfrco	Oscillation frequen- cy	25°C, 3V	0.70		1.75	kHz
TC <sub>ULFRCO</sub>	Temperature coeffi- cient			0.05		%/°C
VC <sub>ULFRCO</sub>	Supply voltage co- efficient			-18.2		%/V

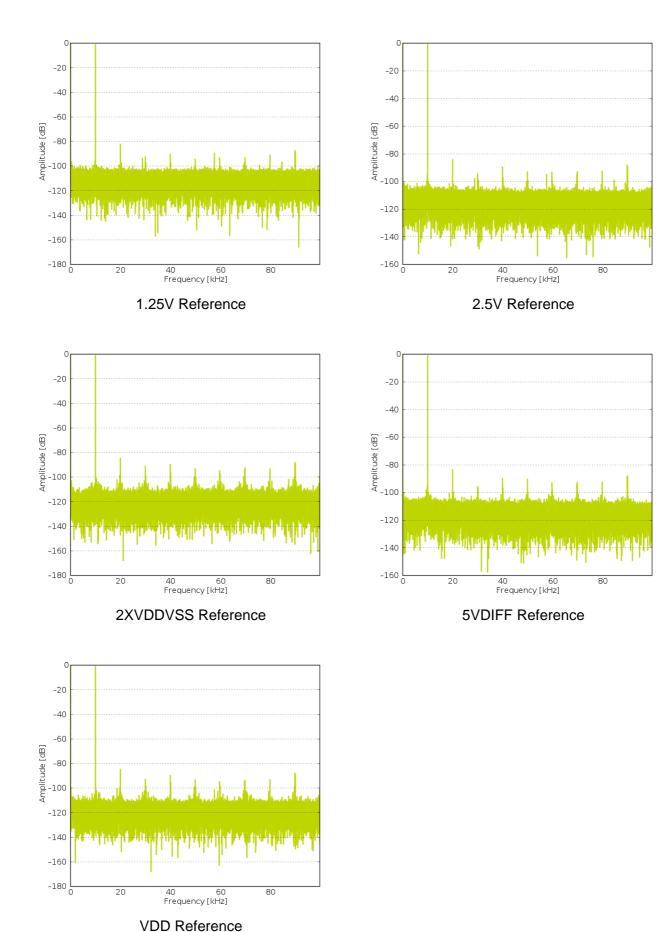
# 3.10 Analog Digital Converter (ADC)

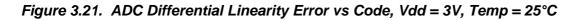
### Table 3.14. ADC

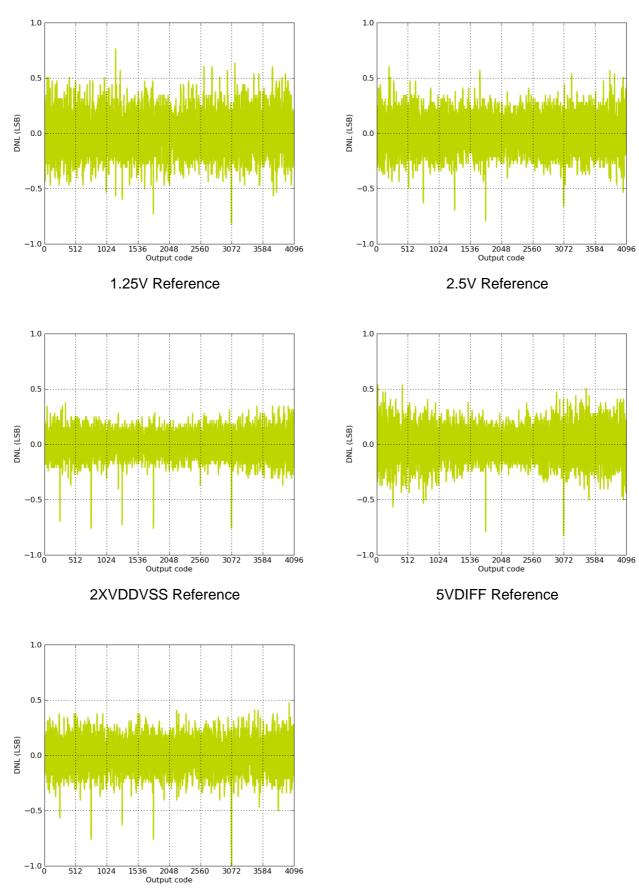
Symbol	Parameter	Condition	Min	Тур	Max	Unit
M		Single ended	0		V <sub>REF</sub>	V
V <sub>ADCIN</sub>	Input voltage range	Differential	-V <sub>REF</sub> /2		V <sub>REF</sub> /2	V
V <sub>ADCREFIN</sub>	Input range of exter- nal reference volt- age, single ended and differential			V <sub>DD</sub>	V	
V <sub>ADCREFIN_CH7</sub>	Input range of ex- ternal negative ref- erence voltage on channel 7	See V <sub>ADCREFIN</sub>	0		V <sub>DD</sub> - 1.1	V
VADCREFIN_CH6	Input range of ex- ternal positive ref- erence voltage on channel 6	See V <sub>ADCREFIN</sub> 0.625 V <sub>DD</sub>				
V <sub>ADCCMIN</sub>	Common mode in- put range		0		V <sub>DD</sub>	V
	Input current	2pF sampling capacitors		<100		nA
CMRR <sub>ADC</sub>	Analog input com- mon mode rejection ratio			65		dB
		1 MSamples/s, 12 bit, external reference		377		μA
	Average active cur- rent	10 kSamples/s 12 bit, internal 1.25 V reference, WARMUP- MODE in ADCn_CTRL set to 0b00		67		μΑ
I <sub>ADC</sub>		10 kSamples/s 12 bit, internal 1.25 V reference, WARMUP- MODE in ADCn_CTRL set to 0b01		68		μΑ
		10 kSamples/s 12 bit, internal 1.25 V reference, WARMUP- MODE in ADCn_CTRL set to 0b10		71		μΑ
		10 kSamples/s 12 bit, internal 1.25 V reference, WARMUP- MODE in ADCn_CTRL set to 0b11		244		μΑ
IADCREF	Current consump- tion of internal volt- age reference	Internal voltage reference	65			μA
C <sub>ADCIN</sub>	Input capacitance			2		pF
R <sub>ADCIN</sub>	Input ON resistance		1			MOhm
R <sub>ADCFILT</sub>	Input RC filter resis- tance		10			kOhm
C <sub>ADCFILT</sub>	Input RC filter/de- coupling capaci- tance			250		fF

### 3.10.1 Typical performance

#### Figure 3.19. ADC Frequency Spectrum, Vdd = 3V, Temp = 25°C







**VDD** Reference

Figure 3.22. ADC Absolute Offset, Common Mode = Vdd /2

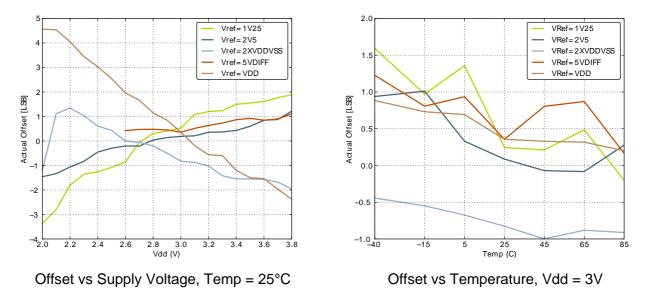
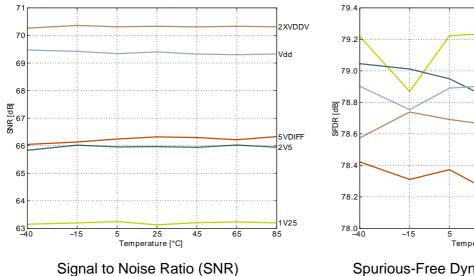
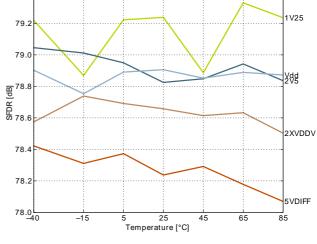


Figure 3.23. ADC Dynamic Performance vs Temperature for all ADC References, Vdd = 3V





Spurious-Free Dynamic Range (SFDR)

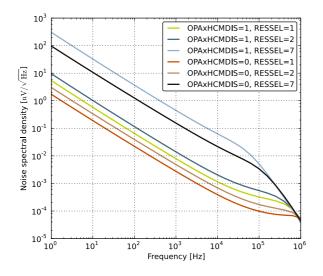
# 3.11 Digital Analog Converter (DAC)

#### Table 3.15. DAC

Symbol	Parameter	Condition	Min	Тур	Мах	Unit
V <sub>DACOUT</sub>	Output voltage range	VDD voltage reference, single ended	0		V <sub>DD</sub>	V
V <sub>DACCM</sub>	Output common mode voltage range		0		V <sub>DD</sub>	V
	Active current in-	500 kSamples/s, 12bit		400	650	μA
I <sub>DAC</sub>	cluding references	100 kSamples/s, 12 bit		200	250	μA
	for 2 channels	1 kSamples/s 12 bit NORMAL		17	25	μA
SR <sub>DAC</sub>	Sample rate				500	ksam- ples/s



Figure 3.28. OPAMP Voltage Noise Spectral Density (Non-Unity Gain)



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Alternate			L	OCATIO	N			
Functionality	0	1	2	3	4	5	6	Description
LES_CH15	PC15							LESENSE channel 15.
LETIM0_OUT0	PD6	PB11	PF0	PC4				Low Energy Timer LETIM0, output channel 0.
LETIM0_OUT1	PD7		PF1					Low Energy Timer LETIM0, output channel 1.
LEU0_RX	PD5	PB14		PF1	PA0			LEUART0 Receive input.
LEU0_TX	PD4	PB13		PF0	PF2			LEUART0 Transmit output. Also used as receive input in half duplex communication.
LFXTAL_N	PB8							Low Frequency Crystal (typically 32.768 kHz) negative pin. Also used as an optional external clock input pin.
LFXTAL_P	PB7							Low Frequency Crystal (typically 32.768 kHz) positive pin.
PCNT0_S0IN	PC13			PD6				Pulse Counter PCNT0 input number 0.
PCNT0_S1IN	PC14			PD7				Pulse Counter PCNT0 input number 1.
PRS_CH0	PA0	PF3						Peripheral Reflex System PRS, channel 0.
PRS_CH1	PA1	PF4						Peripheral Reflex System PRS, channel 1.
PRS_CH2		PF5						Peripheral Reflex System PRS, channel 2.
TIM0_CC0	PA0	PA0			PA0	PF0		Timer 0 Capture Compare input / output channel 0.
TIM0_CC1	PA1	PA1				PF1		Timer 0 Capture Compare input / output channel 1.
TIM0_CC2	PA2	PA2				PF2		Timer 0 Capture Compare input / output channel 2.
TIM1_CC0	PC13	PE10		PB7	PD6			Timer 1 Capture Compare input / output channel 0.
TIM1_CC1	PC14	PE11		PB8	PD7			Timer 1 Capture Compare input / output channel 1.
TIM1_CC2	PC15	PE12		PB11	PC13			Timer 1 Capture Compare input / output channel 2.
US0_CLK	PE12	PE5		PC15	PB13	PB13		USART0 clock input / output.
US0_CS	PE13	PE4		PC14	PB14	PB14		USART0 chip select input / output.
								USART0 Asynchronous Receive.
US0_RX	PE11	PE6		PE12	PB8			USART0 Synchronous mode Master Input / Slave Output (MISO).
US0_TX	PE10	PE7		PE13	PB7			USART0 Asynchronous Transmit.Also used as receive input in half duplex communication.
030_17	FLIU			FLIJ	F DI			USART0 Synchronous mode Master Output / Slave Input (MOSI).
US1_CLK	PB7		PF0					USART1 clock input / output.
US1_CS	PB8		PF1					USART1 chip select input / output.
								USART1 Asynchronous Receive.
US1_RX			PD6					USART1 Synchronous mode Master Input / Slave Output (MISO).
US1_TX			PD7					USART1 Asynchronous Transmit.Also used as receive input in half duplex communication. USART1 Synchronous mode Master Output / Slave Input (MOSI).

# 4.3 GPIO Pinout Overview

The specific GPIO pins available in *EFM32TG822* is shown in Table 4.3 (p. 52). Each GPIO port is organized as 16-bit ports indicated by letters A through F, and the individual pin on this port is indicated by a number from 15 down to 0.

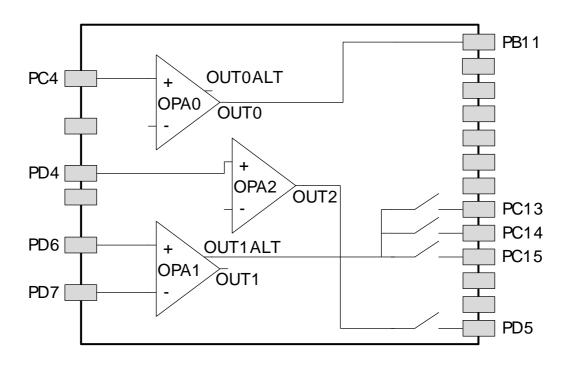
#### Table 4.3. GPIO Pinout

Port	Pin 15	Pin 14	Pin 13	Pin 12	Pin 11	Pin 10	Pin 9	Pin 8	Pin 7	Pin 6	Pin 5	Pin 4	Pin 3	Pin 2	Pin 1	Pin 0
Port A	-	PA14	PA13	PA12	-	-	-	-	-	-	-	-	-	PA2	PA1	PA0
Port B	-	PB14	PB13	-	PB11	-	-	PB8	PB7	PB6	PB5	PB4	PB3	-	-	-
Port C	PC15	PC14	PC13	-	-	-	-	-	-	-	-	PC4	-	-	-	-
Port D	-	-	-	-	-	-	-	-	PD7	PD6	PD5	PD4	-	-	-	-
Port E	-	-	PE13	PE12	PE11	PE10	-	-	PE7	PE6	PE5	PE4	-	-	-	-
Port F	-	-	-	-	-	-	-	-	-	-	PF5	PF4	PF3	PF2	PF1	PF0

# 4.4 Opamp Pinout Overview

The specific opamp terminals available in EFM32TG822 is shown in Figure 4.2 (p. 52).

#### Figure 4.2. Opamp Pinout





#### Figure 5.3. TQFP48 PCB Stencil Design

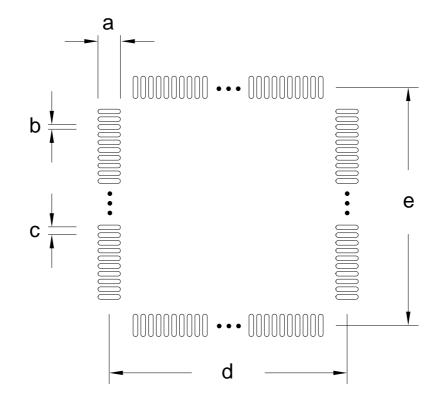


Table 5.3. QFP48 PCB Stencil Design Dimensions (Dimensions in mm)

Symbol	Dim. (mm)
а	1.50
b	0.20
с	0.50
d	8.50
e	8.50

- 1. The drawings are not to scale.
- 2. All dimensions are in millimeters.
- 3. All drawings are subject to change without notice.
- 4. The PCB Land Pattern drawing is in compliance with IPC-7351B.
- 5. Stencil thickness 0.125 mm.
- 6. For detailed pin-positioning, see Figure 4.3 (p. 53) .

# **5.2 Soldering Information**

The latest IPC/JEDEC J-STD-020 recommendations for Pb-Free reflow soldering should be followed.

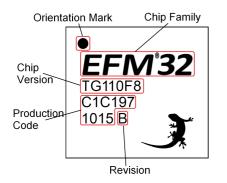
The packages have a Moisture Sensitivity Level rating of 3, please see the latest IPC/JEDEC J-STD-033 standard for MSL description and level 3 bake conditions.

# 6 Chip Marking, Revision and Errata

# 6.1 Chip Marking

In the illustration below package fields and position are shown.

#### Figure 6.1. Example Chip Marking (top view)



# 6.2 Revision

The revision of a chip can be determined from the "Revision" field in Figure 6.1 (p. 58).

# 6.3 Errata

Please see the errata document for EFM32TG822 for description and resolution of device erratas. This document is available in Simplicity Studio and online at: http://www.silabs.com/support/pages/document-library.aspx?p=MCUs--32-bit Added link to Environmental and Quality information.

Re-added missing DAC-data.

# 7.4 Revision 1.20

September 30th, 2013

Added I2C characterization data.

Corrected GPIO operating voltage from 1.8 V to 1.85 V.

Corrected the ADC gain and offset measurement reference voltage from 2.25 to 2.5V.

Corrected the ADC resolution from 12, 10 and 6 bit to 12, 8 and 6 bit.

Document changed status from "Preliminary".

Updated Environmental information.

Updated trademark, disclaimer and contact information.

Other minor corrections.

# 7.5 Revision 1.10

June 28th, 2013

Updated power requirements in the Power Management section.

Removed minimum load capacitance figure and table. Added reference to application note.

Other minor corrections.

# 7.6 Revision 1.00

September 11th, 2012

Updated the HFRCO 1 MHz band typical value to 1.2 MHz.

Updated the HFRCO 7 MHz band typical value to 6.6 MHz.

Added GPIO\_EM4WU3, GPIO\_EM4WU4 and GPIO\_EM4WU5 pins and removed GPIO\_EM4WU1 in the Alternate functionality overview table.

Other minor corrections.

# 7.7 Revision 0.96

May 4th, 2012

Corrected PCB footprint figures and tables.

# 7.8 Revision 0.95

February 27th, 2012

Corrected operating voltage from 1.8 V to 1.85 V.