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Intel - EP2SGX90EF1152C3 Datasheet



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Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Detuns	
Product Status	Obsolete
Number of LABs/CLBs	4548
Number of Logic Elements/Cells	90960
Total RAM Bits	4520448
Number of I/O	558
Number of Gates	-
Voltage - Supply	1.15V ~ 1.25V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	1152-BBGA
Supplier Device Package	1152-FBGA (35x35)
Purchase URL	https://www.e-xfl.com/product-detail/intel/ep2sgx90ef1152c3

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Transmit State Machine

The transmit state machine operates in either PCI Express mode, XAUI mode, or GIGE mode, depending on the protocol used. The state machine is not utilized for certain protocols, such as SONET.

GIGE Mode

In GIGE mode, the transmit state machine converts all idle ordered sets (/K28.5/, /Dx.y/) to either /I1/ or /I2/ ordered sets. /I1/ consists of a negative-ending disparity /K28.5/ (denoted by /K28.5/-) followed by a neutral /D5.6/. /I2/ consists of a positive-ending disparity /K28.5/ (denoted by /K28.5/+) and a negative-ending disparity /D16.2/ (denoted by /D16.2/-). The transmit state machines do not convert any of the ordered sets to match /C1/ or /C2/, which are the configuration ordered sets. (/C1/ and /C2/ are defined by [/K28.5/, /D21.5/] and [/K28.5/, /D2.2/], respectively). Both the /I1/ and /I2/ ordered sets guarantee a negative-ending disparity after each ordered set.

XAUI Mode

The transmit state machine translates the XAUI XGMII code group to the XAUI PCS code group. Table 2–5 shows the code conversion.

Table 2–5.	Table 2–5. Code Conversion							
XGMII TXC	XGMII TXD	PCS Code-Group	Description					
0	00 through FF	Dxx.y	Normal data					
1	07	K28.0 or K28.3 or K28.5	Idle in 					
1	07	K28.5	Idle in T					
1	9C	K28.4	Sequence					
1	FB	K27.7	Start					
1	FD	K29.7	Terminate					
1	FE	K30.7	Error					
1	See IEEE 802.3 reserved code groups	See IEEE 802.3 reserved code groups	Reserved code groups					
1	Other value	K30.7	Invalid XGMII character					

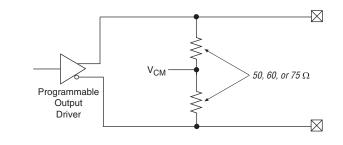
The XAUI PCS idle code groups, /K28.0/ (/R/) and /K28.5/ (/K/), are automatically randomized based on a PRBS7 pattern with an $x^7 + x^6 + 1$ polynomial. The /K28.3/ (/A/) code group is automatically generated between 16 and 31 idle code groups. The idle randomization on the /A/, /K/, and /R/ code groups is done automatically by the transmit state machine.

Pre-emphasis percentage is defined as $(V_{MAX}/V_{MIN}-1) \times 100$, where V_{MAX} is the differential emphasized voltage (peak-to-peak) and V_{MIN} is the differential steady-state voltage (peak-to-peak).

Programmable Termination

The programmable termination can be statically set in the Quartus II software. The values are 100Ω , 120Ω , 150Ω , and external termination. Figure 2–11 shows the setup for programmable termination.





PCI Express Receiver Detect

The Stratix II GX transmitter buffer has a built-in receiver detection circuit for use in PIPE mode. This circuit provides the ability to detect if there is a receiver downstream by sending out a pulse on the channel and monitoring the reflection. This mode requires the transmitter buffer to be tri-stated (in electrical idle mode).

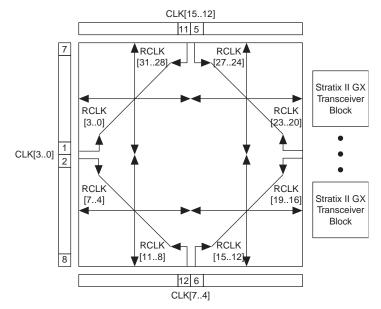
PCI Express Electric Idles (or Individual Transmitter Tri-State)

The Stratix II GX transmitter buffer supports PCI Express electrical idles. This feature is only active in PIPE mode. The tx_forceelecidle port puts the transmitter buffer in electrical idle mode. This port is available in all PCI Express power-down modes and has specific usage in each mode.

Receiver Path

This section describes the data path through the Stratix II GX receiver. The Stratix II GX receiver consists of the following blocks:

- Receiver differential input buffer
- Receiver PLL lock detector, signal detector, and run length checker
- Clock/data recovery (CRU) unit
- Deserializer
- Pattern detector
- Word aligner





Notes to Figure 2–31:

- (1) CLK# pins are clock pins and their associated number. These are pins for global and local clocks.
- (2) RCLK# pins are regional clock pins.

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	Clock R	Clock Resource Transceiver			
Region	Global Clock	Regional Clock	Bank 13 8 Clock I/O	Bank 14 8 Clock I/O	Bank 15 8 Clock I/O
Region0 8 LRIO clock	~	RCLK 20-27	\checkmark		
Region1 8 LRIO clock	~	RCLK 20-27	~	\checkmark	
Region2 8 LRIO clock	~	RCLK 12-19		\checkmark	~
Region3 8 LRIO clock	~	RCLK 12-19			\checkmark

Table 2–14. Available Clocking Connections for Transceivers in 2SGX90F								
	Clock	Resource		Transceiver				
Region	Global Clock	Regional Clock	Bank 13 8 Clock I/O	Bank 14 8 Clock I/O	Bank 15 8 clock I/O	Bank 16 8 Clock I/O		
Region0 8 LRIO clock	\checkmark	RCLK 20-27	~					
Region1 8 LRIO clock	\checkmark	RCLK 20-27		\checkmark				
Region2 8 LRIO clock	\checkmark	RCLK 12-19			~			
Region3 8 LRIO clock	\checkmark	RCLK 12-19				~		

Table 2–15. Available Clocking Connections for Transceivers in 2SGX130G										
	Clock	Resource		Transceiver						
Region	Global Clock	Regional Clock	Bank 13 8 Clock I/O	Bank 14 8 Clock I/O	Bank 15 8 clock I/O	Bank 16 8 Clock I/O	Bank 17 8 Clock I/O			
Region0 8 LRIO clock	~	RCLK 20-27	\checkmark							
Region1 8 LRIO clock	~	RCLK 20-27		\checkmark						
Region2 8 LRIO clock	~	RCLK 12-19			~	~				
Region3 8 LRIO clock	~	RCLK 12-19				~	~			

Other Transceiver Features

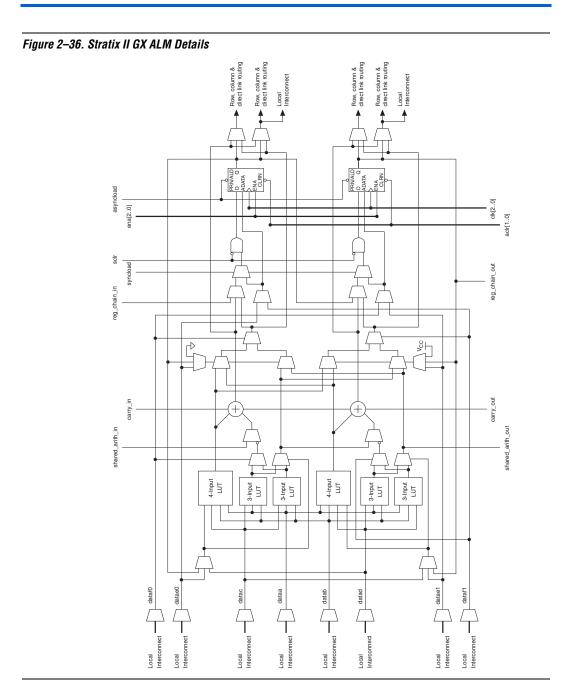
Other important features of the Stratix II GX transceivers are the power down and reset capabilities, external voltage reference and bias circuitry, and hot swapping.

Calibration Block

The Stratix II GX device uses the calibration block to calibrate the on-chip termination for the PLLs and their associated output buffers and the terminating resistors on the transceivers. The calibration block counters the effects of process, voltage, and temperature (PVT). The calibration block references a derived voltage across an external reference resistor to calibrate the on-chip termination resistors on the Stratix II GX device. The calibration block can be powered down. However, powering down the calibration block during operations may yield transmit and receive data errors.

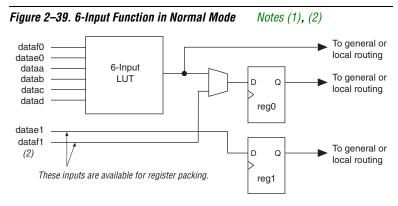
Dynamic Reconfiguration

This feature allows you to dynamically reconfigure the PMA portion and the channel parameters, such as data rate and functional mode, of the Stratix II GX transceiver. The PMA reconfiguration allows you to quickly optimize the settings for the transceiver's PMA to achieve the intended bit error rate (BER).



Altera Corporation October 2007

using the bottom set of output drivers. The Quartus II Compiler automatically selects the inputs to the LUT. Asynchronous load data for the register comes from the datae or dataf input of the ALM. ALMs in normal mode support register packing.



Notes to Figure 2-39:

- (1) If datae1 and dataf1 are used as inputs to the six-input function, datae0 and dataf0 are available for register packing.
- (2) The dataf1 input is available for register packing only if the six-input function is un-registered.

Extended LUT Mode

The extended LUT mode is used to implement a specific set of seven-input functions. The set must be a 2-to-1 multiplexer fed by two arbitrary five-input functions sharing four inputs. Figure 2–40 shows the template of supported seven-input functions utilizing extended LUT mode. In this mode, if the seven-input function is unregistered, the unused eighth input is available for register packing. Functions that fit into the template shown in Figure 2–40 occur naturally in designs. These functions often appear in designs as "if-else" statements in Verilog HDL or VHDL code.

Clear and Preset Logic Control

LAB-wide signals control the logic for the register's clear and load/preset signals. The ALM directly supports an asynchronous clear and preset function. The register preset is achieved through the asynchronous load of a logic high. The direct asynchronous preset does not require a NOT gate push-back technique. Stratix II GX devices support simultaneous asynchronous load/preset and clear signals. An asynchronous clear signal takes precedence if both signals are asserted simultaneously. Each LAB supports up to two clears and one load/preset signal.

In addition to the clear and load/preset ports, Stratix II GX devices provide a device-wide reset pin (DEV_CLRn) that resets all registers in the device. An option set before compilation in the Quartus II software controls this pin. This device-wide reset overrides all other control signals.

MultiTrack Interconnect

In the Stratix II GX architecture, the MultiTrack interconnect structure with DirectDrive technology provides connections between ALMs, TriMatrix memory, DSP blocks, and device I/O pins. The MultiTrack interconnect consists of continuous, performance-optimized routing lines of different lengths and speeds used for inter- and intra-design block connectivity. The Quartus II Compiler automatically places critical design paths on faster interconnects to improve design performance.

DirectDrive technology is a deterministic routing technology that ensures identical routing resource usage for any function regardless of placement in the device. The MultiTrack interconnect and DirectDrive technology simplify the integration stage of block-based designing by eliminating the re-optimization cycles that typically follow design changes and additions.

The MultiTrack interconnect consists of row and column interconnects that span fixed distances. A routing structure with fixed length resources for all devices allows predictable and repeatable performance when migrating through different device densities. Dedicated row interconnects route signals to and from LABs, DSP blocks, and TriMatrix memory in the same row.

These row resources include:

- Direct link interconnects between LABs and adjacent blocks
- R4 interconnects traversing four blocks to the right or left
- R24 row interconnects for high-speed access across the length of the device

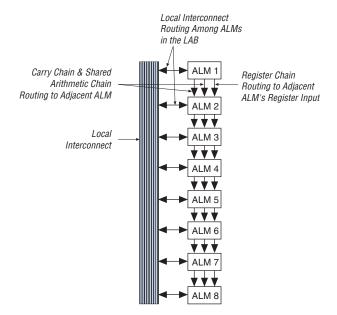
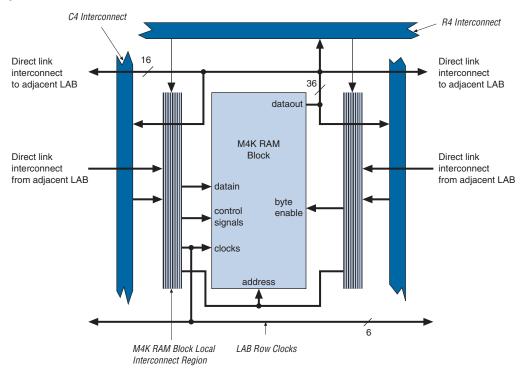


Figure 2–47. Shared Arithmetic Chain, Carry Chain and Register Chain Interconnects

The C4 interconnects span four LABs, M512, or M4K blocks up or down from a source LAB. Every LAB has its own set of C4 interconnects to drive either up or down. Figure 2–48 shows the C4 interconnect connections from a LAB in a column. The C4 interconnects can drive and be driven by all types of architecture blocks, including DSP blocks, TriMatrix memory blocks, and column and row IOEs. For LAB interconnection, a primary LAB or its LAB neighbor can drive a given C4 interconnect. C4 interconnects can drive each other to extend their range as well as drive row interconnects for column-to-column connections. The RAM blocks in Stratix II GX devices have local interconnects to allow ALMs and interconnects to drive into RAM blocks. The M512 RAM block local interconnect is driven by the R4, C4, and direct link interconnects from adjacent LABs. The M512 RAM blocks can communicate with LABs on either the left or right side through these row interconnects or with LAB columns on the left or right side with the column interconnects. The M512 RAM block has up to 16 direct link input connections from the left adjacent LABs and another 16 from the right adjacent LAB. M512 RAM outputs can also connect to left and right LABs through direct link interconnect. The M512 RAM block has equal opportunity for access and performance to and from LABs on either its left or right side. Figure 2–50 shows the M512 RAM block to logic array interface.

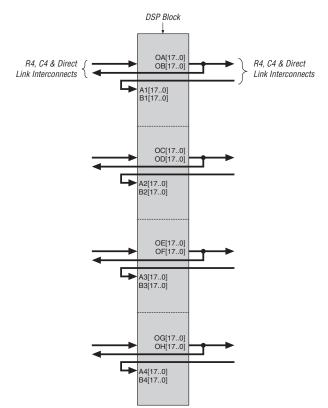




The DSP block is divided into four block units that interface with four LAB rows on the left and right. Each block unit can be considered one complete 18 × 18-bit multiplier with 36 inputs and 36 outputs. A local interconnect region is associated with each DSP block. Like a LAB, this interconnect region can be fed with 16 direct link interconnects from the LAB to the left or right of the DSP block in the same row. R4 and C4 routing resources can access the DSP block's local interconnect region. The outputs also work similarly to LAB outputs. Eighteen outputs from the DSP block can drive to the left LAB through direct link interconnects and 18 can drive to the right LAB through direct link interconnects. All 36 outputs can drive to R4 and C4 routing interconnects. Outputs can drive right- or left-column routing.

Figures 2–59 and 2–60 show the DSP block interfaces to LAB rows.

Figure 2–59. DSP Block Interconnect Interface



There are 32 control and data signals that feed each row or column I/O block. These control and data signals are driven from the logic array. The row or column IOE clocks, io_clk[7..0], provide a dedicated routing resource for low-skew, high-speed clocks. I/O clocks are generated from global or regional clocks. Refer to "PLLs and Clock Networks" on page 2-89 for more information.

Figure 2–79 illustrates the signal paths through the I/O block.

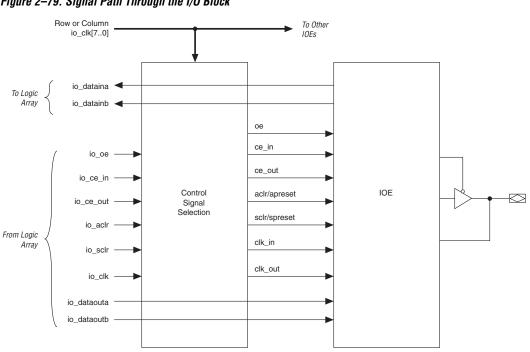


Figure 2–79. Signal Path Through the I/O Block

Each IOE contains its own control signal selection for the following control signals: oe, ce_in, ce_out, aclr/apreset, sclr/spreset, clk in, and clk out. Figure 2-80 illustrates the control signal selection.

A path in which a pin directly drives a register can require the delay to ensure zero hold time, whereas a path in which a pin drives a register through combinational logic may not require the delay. Programmable delays exist for decreasing input-pin-to-logic-array and IOE input register delays. The Quartus II Compiler can program these delays to automatically minimize setup time while providing a zero hold time. Programmable delays can increase the register-to-pin delays for output and/or output enable registers. Programmable delays are no longer required to ensure zero hold times for logic array register-to-IOE register transfers. The Quartus II Compiler can create the zero hold time for these transfers. Table 2–30 shows the programmable delays for Stratix II GX devices.

Programmable Delays	Quartus II Logic Option
Input pin to logic array delay	Input delay from pin to internal cells
Input pin to input register delay	Input delay from pin to input register
Output pin delay	Delay from output register to output pin
Output enable register t_{CO} delay	Delay to output enable pin

Table 2–30. Stratix II GX Programmable Delay Ch	ain
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The IOE registers in Stratix II GX devices share the same source for clear or preset. You can program preset or clear for each individual IOE. You can also program the registers to power up high or low after configuration is complete. If programmed to power up low, an asynchronous clear can control the registers. If programmed to power up high, an asynchronous preset can control the registers. This feature prevents the inadvertent activation of another device's active-low input upon power-up. If one register in an IOE uses a preset or clear signal, all registers in the IOE must use that same signal if they require preset or clear. Additionally, a synchronous reset signal is available for the IOE registers.

Double Data Rate I/O Pins

Stratix II GX devices have six registers in the IOE, which support DDR interfacing by clocking data on both positive and negative clock edges. The IOEs in Stratix II GX devices support DDR inputs, DDR outputs, and bidirectional DDR modes. When using the IOE for DDR inputs, the two input registers clock double rate input data on alternating edges. An input latch is also used in the IOE for DDR input acquisition. The latch holds the data that is present during the clock high times, allowing both bits of data to be synchronous with the same clock edge (either rising or falling). Figure 2–82 shows an IOE configured for DDR input. Figure 2–83 shows the DDR input timing diagram.

On-Chip Parallel Termination with Calibration

Stratix II GX devices support on-chip parallel termination with calibration for column I/O pins only. There is one calibration circuit for the top I/O banks and one circuit for the bottom I/O banks. Each on-chip parallel termination calibration circuit compares the total impedance of each I/O buffer to the external 50- Ω resistors connected to the RUP and RDN pins and dynamically enables or disables the transistors until they match. Calibration occurs at the end of device configuration. Once the calibration circuit finds the correct impedance, it powers down and stops changing the characteristics of the drivers.

On-chip parallel termination with calibration is only supported for input pins.



For more information about on-chip termination supported by Stratix II devices, refer to the *Selectable I/O Standards in Stratix II & Stratix II GX Devices* chapter in volume 2 of the *Stratix II GX Device Handbook*.

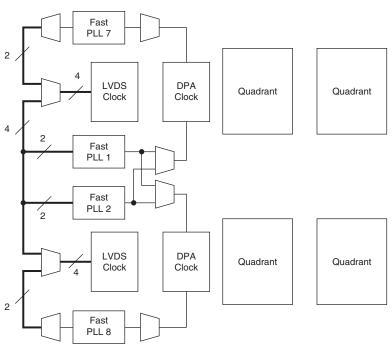


For more information about tolerance specifications for on-chip termination with calibration, refer to the *DC* & *Switching Characteristics* chapter in volume 1 of the *Stratix II GX Device Handbook*.

MultiVolt I/O Interface

The Stratix II GX architecture supports the MultiVolt I/O interface feature that allows Stratix II GX devices in all packages to interface with systems of different supply voltages. The Stratix II GX VCCINT pins must always be connected to a 1.2-V power supply. With a 1.2-V V_{CCINT} level, input pins are 1.2-, 1.5-, 1.8-, 2.5-, and 3.3-V tolerant. The VCCIO pins can be connected to either a 1.2-, 1.5-, 1.8-, 2.5-, or 3.3-V power supply, depending on the output requirements. The output levels are compatible with systems of the same voltage as the power supply (for example, when VCCIO pins are connected to a 1.5-V power supply, the output levels are compatible with 1.5-V systems). The Stratix II GX VCCPD power pins must be connected to a 3.3-V power supply. These power pins are used to supply the pre-driver power to the output buffers, which increases the performance of the output pins. The VCCPD pins also power configuration input pins and JTAG input pins.





Note to Figure 2–91: (1) See Tables 2–39 through Tables 2–41 for the number of channels each device supports.

Referenced Documents

This chapter references the following documents:

- DC & Switching Characteristics chapter in volume 1 of the Stratix II GX Handbook
- DSP Blocks in Stratix II GX Devices chapter in Volume 2 of the Stratix II GX Device Handbook
- External Memory Interfaces in Stratix II & Stratix II GX Devices chapter in volume 2 of the Stratix II GX Device Handbook
- High-Speed Differential I/O Interfaces with DPA in Stratix II & Stratix II
 GX Devices chapter in volume 2 of the Stratix II GX Handbook
- PLLs in Stratix II & Stratix II GX Devices chapter in volume 2 of the Stratix II GX Device Handbook
- Selectable I/O Standards in Stratix II & Stratix II GX Devices chapter in volume 2 of the Stratix II GX Handbook
- *Stratix II GX Device Handbook,* volume 2
- Stratix II GX Transceiver Architecture Overview chapter in volume 2 of the Stratix II GX Handbook

considerable flexibility for frequency synthesis, allowing real-time variation of the PLL frequency and delay. The rest of the device is functional while reconfiguring the PLL.



See the *PLLs in Stratix II & Stratix II GX Devices* chapter in volume 2 of the *Stratix II GX Device Handbook* for more information on Stratix II GX PLLs.

Temperature Sensing Diode (TSD)

Stratix II GX devices include a diode-connected transistor for use as a temperature sensor in power management. This diode is used with an external digital thermometer device. These devices steer bias current through the Stratix II GX diode, measuring forward voltage and converting this reading to temperature in the form of an 8-bit signed number (7 bits plus 1 sign bit). The external device's output represents the junction temperature of the Stratix II GX device and can be used for intelligent power management.

The diode requires two pins (tempdiodep and tempdioden) on the Stratix II GX device to connect to the external temperature-sensing device, as shown in Figure 3–1. The temperature sensing diode is a passive element and therefore can be used before the Stratix II GX device is powered.

Figure 3–1. External Temperature-Sensing Diode

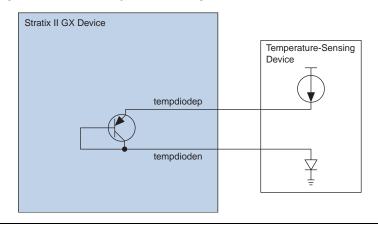
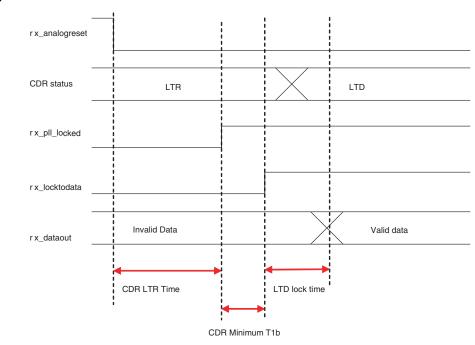


Figure 4–1 shows the lock time parameters in manual mode, Figure 4–2 shows the lock time parameters in automatic mode.

LTD = Lock to data LTR = Lock to reference clock



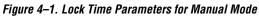


Table 4–4	6. 1.8-V HSTL Class II Specif	ications				
Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
V _{CCIO}	Output supply voltage		1.71	1.80	1.89	V
V _{REF}	Input reference voltage		0.85	0.90	0.95	V
V _{TT}	Termination voltage		0.85	0.90	0.95	V
V _{IH} (DC)	DC high-level input voltage		V _{REF} + 0.1			V
V _{IL} (DC)	DC low-level input voltage		-0.3		V _{REF} – 0.1	V
V _{IH} (AC)	AC high-level input voltage		V _{REF} + 0.2			V
V _{IL} (AC)	AC low-level input voltage				V _{REF} - 0.2	V
V _{OH}	High-level output voltage	I _{OH} = 16 mA <i>(1)</i>	$V_{\text{CCIO}} - 0.4$			V
V _{OL}	Low-level output voltage	I _{OH} = -16 mA <i>(1)</i>			0.4	V

Note to Table 4–46:

(1) This specification is supported across all the programmable drive settings available for this I/O standard as shown in the *Stratix II GX Architecture* chapter in volume 1 of the *Stratix II GX Device Handbook*.

Table 4–4	Table 4–47. 1.8-V HSTL Class I and II Differential Specifications								
Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit			
V _{CCIO}	I/O supply voltage		1.71	1.80	1.89	V			
V _{DIF} (DC)	DC input differential voltage		0.2			V			
V _{CM} (DC)	DC common mode input voltage		0.78		1.12	V			
V_{DIF} (AC)	AC differential input voltage		0.4			V			
V _{OX} (AC)	AC differential cross point voltage		0.68		0.9	V			

I/O Standard	Drive Strength	Parameter	Fast Corner Industrial/ Commercial	-3 Speed Grade (3)	-3 Speed Grade (4)	-4 Speed Grade	-5 Speed Grade	Unit
SSTL-18	4 mA	t _{OP}	1038	1709	1793	1906	2046	ps
Class I		t _{DIP}	995	1654	1736	1846	1973	ps
	6 mA	t _{OP}	1042	1648	1729	1838	1975	ps
		t _{DIP}	999	1593	1672	1778	1902	ps
	8 mA	t _{OP}	1018	1633	1713	1821	1958	ps
		t _{DIP}	975	1578	1656	1761	1885	ps
	10 mA (1)	t _{OP}	1021	1615	1694	1801	1937	ps
		t _{DIP}	978	1560	1637	1741	1864	ps
1.8-V HSTL	4 mA	t _{OP}	1019	1610	1689	1795	1956	ps
Class I		t _{DIP}	976	1555	1632	1735	1883	ps
	6 mA	t _{OP}	1022	1580	1658	1762	1920	ps
		t _{DIP}	979	1525	1601	1702	1847	ps
	8 mA	t _{OP}	1004	1576	1653	1757	1916	ps
		t _{DIP}	961	1521	1596	1697	1843	ps
	10 mA	t _{OP}	1008	1567	1644	1747	1905	ps
		t _{DIP}	965	1512	1587	1687	1832	ps
	12 mA (1)	t _{OP}	999	1566	1643	1746	1904	ps
		t _{DIP}	956	1511	1586	1686	1831	ps
1.5-V HSTL	4 mA	t _{OP}	1018	1591	1669	1774	1933	ps
Class I		t _{DIP}	975	1536	1612	1714	1860	ps
	6 mA	t _{OP}	1021	1579	1657	1761	1919	ps
		t _{DIP}	978	1524	1600	1701	1846	ps
	8 mA (1)	t _{OP}	1006	1572	1649	1753	1911	ps
		t _{DIP}	963	1517	1592	1693	1838	ps
Differential	8 mA	t _{OP}	1050	1759	1846	1962	2104	ps
SSTL-2 Class I		t _{DIP}	1007	1704	1789	1902	2031	ps
	12 mA	t _{OP}	1026	1694	1777	1889	2028	ps
		t _{DIP}	983	1639	1720	1829	1955	ps
Differential	16 mA	t _{OP}	992	1581	1659	1763	1897	ps
SSTL-2 Class II		t _{DIP}	949	1526	1602	1703	1824	ps

Figure 4–14. Stratix II GX JTAG Waveforms.

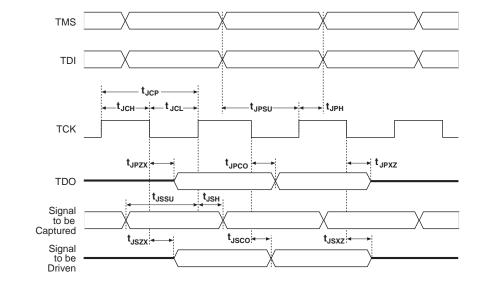


Table 4–117 shows the JTAG timing parameters and values for Stratix II GX devices.

Table 4–117. Stratix II GX JTAG Timing Parameters and Values								
Symbol	Parameter	Min	Max	Unit				
t _{JCP}	TCK clock period	30		ns				
t _{JCH}	TCK clock high time	12		ns				
t _{JCL}	TCK clock low time	12		ns				
t _{JPSU}	JTAG port setup time	4		ns				
t _{JPH}	JTAG port hold time	5		ns				
t _{JPCO}	JTAG port clock to output		9	ns				
t _{JPZX}	JTAG port high impedance to valid output		9	ns				
t _{JPXZ}	JTAG port valid output to high impedance		9	ns				
t _{JSSU}	Capture register setup time	4		ns				
t _{JSH}	Capture register hold time	5		ns				
t _{JSCO}	Update register clock to output		12	ns				
t _{JSZX}	Update register high impedance to valid output		12	ns				
t _{JSXZ}	Update register valid output to high impedance		12	ns				