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Understanding Embedded - FPGAs (Field Programmable Gate Array)

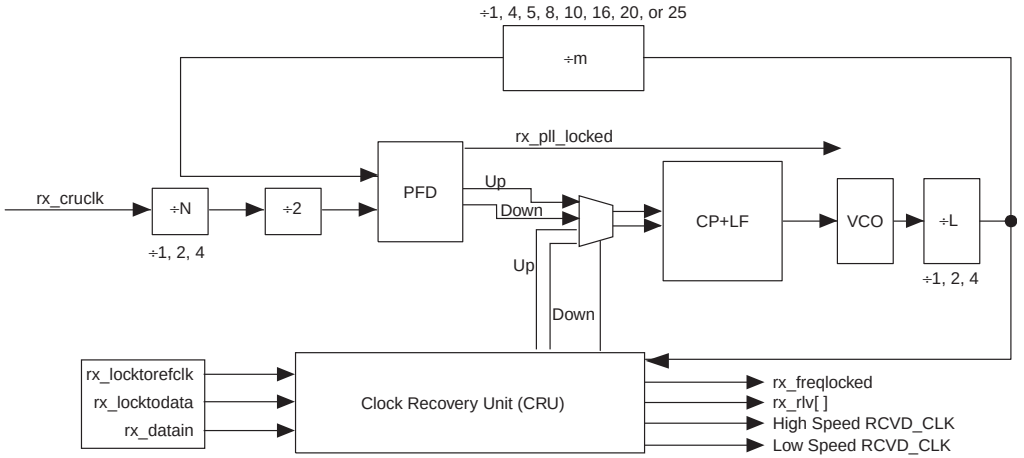
Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Obsolete
Number of LABs/CLBs	4548
Number of Logic Elements/Cells	90960
Total RAM Bits	4520448
Number of I/O	558
Number of Gates	-
Voltage - Supply	1.15V ~ 1.25V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	1152-BBGA
Supplier Device Package	1152-FBGA (35x35)
Purchase URL	https://www.e-xfl.com/product-detail/intel/ep2sgx90ef1152c4

Figure 2–16. Receiver PLL and CRU



The receiver PLLs and CRUs can support frequencies up to 6.375 Gbps. The input clock frequency is limited to the full clock range of 50 to 622 MHz but only when using `REFCLK0` or `REFCLK1`. An optional `RX_PLL_LOCKED` port is available to indicate whether the PLL is locked to the reference clock. The receiver PLL has a programmable loop bandwidth which can be set to low, medium, or high. The Quartus II software can statically set the loop bandwidth parameter.

All the parameters listed are programmable in the Quartus II software. The receiver PLL has the following features:

- Operates from 600 Mbps to 6.375 Gbps.
- Uses a reference clock between 50 MHz and 622.08 MHz.
- Programmable bandwidth settings: low, medium, and high.
- Programmable `rx_locktorefclk` (forces the receiver PLL to lock to the reference clock) and `rx_locktodata` (forces the receiver PLL to lock to the data).
- The voltage-controlled oscillator (VCO) operates at half rate and has two modes. These modes are for low or high frequency operation and provide optimized phase-noise performance.
- Programmable frequency multiplication *W* of 1, 4, 5, 8, 10, 16, 20, and 25. Not all settings are supported for any particular frequency.
- Two lock indication signals are provided. They are found in PFD mode (lock-to-reference clock), and PD (lock-to-data).

Programmable Run Length Violation

The word aligner supports a programmable run length violation counter. Whenever the number of the continuous '0' (or '1') exceeds a user programmable value, the `rx_rlv` signal goes high for a minimum pulse width of two recovered clock cycles. The maximum run values supported are shown in Table 2–7.

Table 2–7. Maximum Run Length (UI)

Mode	PMA Serialization			
	8 Bit	10 Bit	16 Bit	20 Bit
Single-Width	128	160	—	—
Double-Width	—	—	512	640

Running Disparity Check

The running disparity error `rx_disperr` and running disparity value `rx_runningdisp` are sent along with aligned data from the 8B/10B decoder to the FPGA. You can ignore or act on the reported running disparity value and running disparity error signals.

Bit-Slip Mode

The word aligner can operate in either pattern detection mode or in bit-slip mode.

The bit-slip mode provides the option to manually shift the word boundary through the FPGA. This feature is useful for:

- Longer synchronization patterns than the pattern detector can accommodate
- Scrambled data stream
- Input stream consisting of over-sampled data

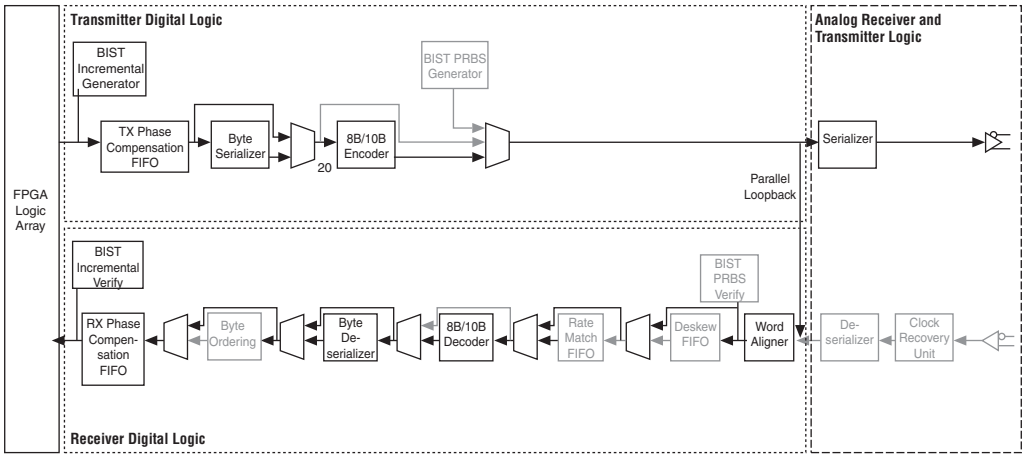
This feature can be applied at 10-bit and 16-bit data widths.

The word aligner outputs a word boundary as it is received from the analog receiver after reset. You can examine the word and search its boundary in the FPGA. To do so, assert the `rx_bitslip` signal. The `rx_bitslip` signal should be toggled and held constant for at least two FPGA clock cycles.

For every rising edge of the `rx_bitslip` signal, the current word boundary is slipped by one bit. Every time a bit is slipped, the bit received earliest is lost. If bit slipping shifts a complete round of bus width, the word boundary is back to the original boundary.

Figure 2–25 shows the data path in parallel loopback mode.

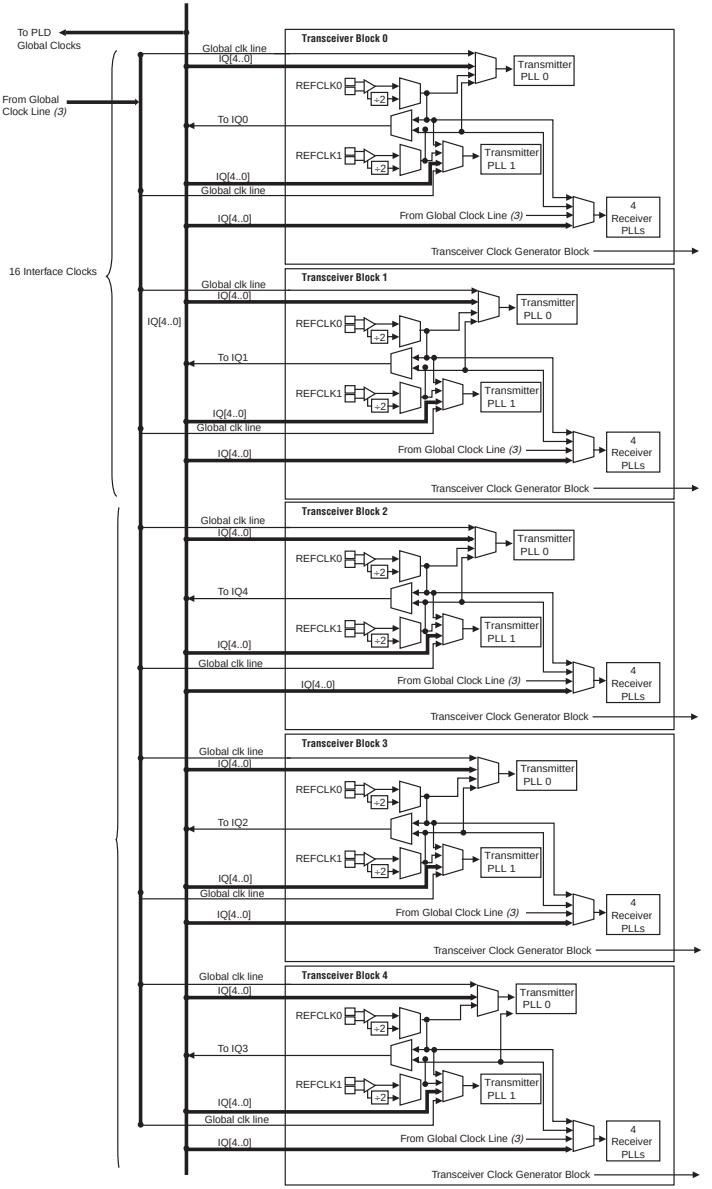
Figure 2–25. Stratix II GX Block in Parallel Loopback Mode



Reverse Serial Loopback

The reverse serial loopback mode uses the analog portion of the transceiver. An external source (pattern generator or transceiver) generates the source data. The high-speed serial source data arrives at the high-speed differential receiver input buffer, passes through the CRU unit, and the retimed serial data is looped back and transmitted though the high-speed differential transmitter output buffer.

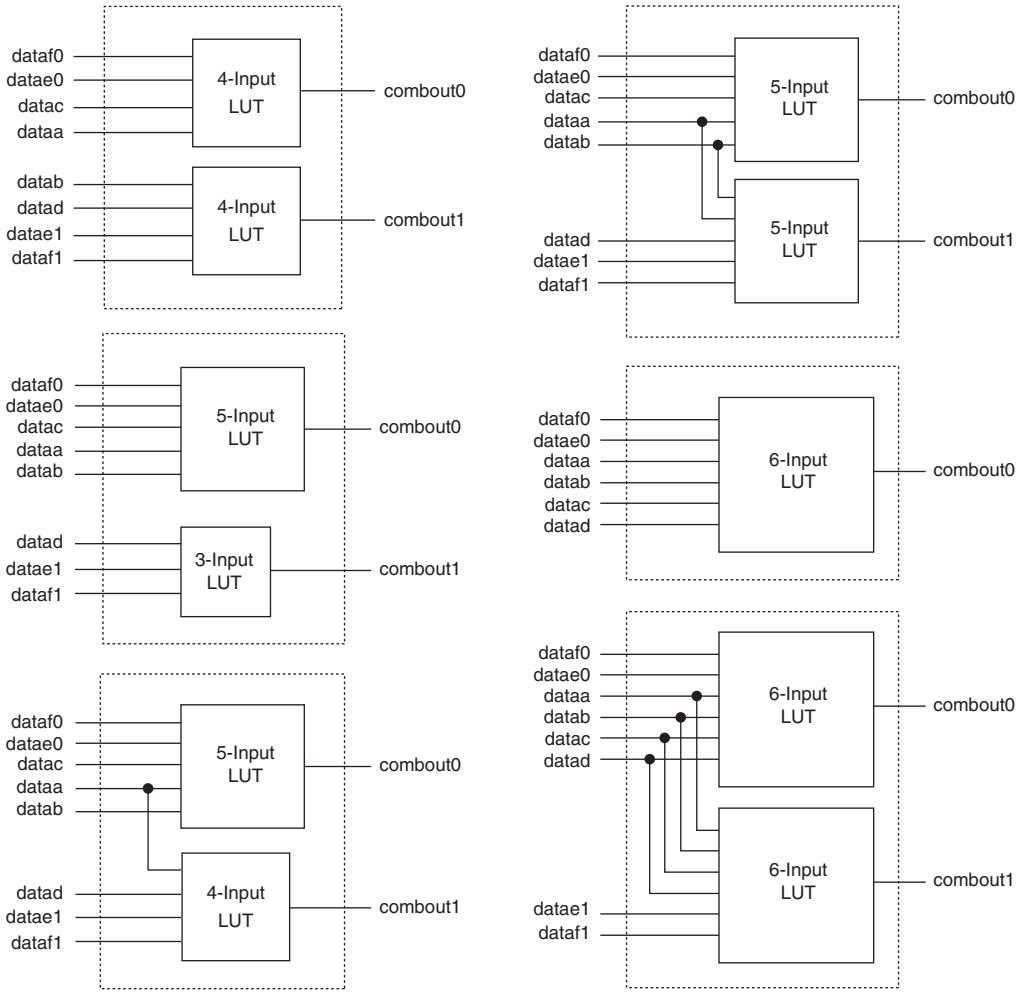
Figure 2–29. EP2SGX130 Device Inter-Transceiver and Global Clock Connections



Notes to Figure 2–29:

(1) There are two transmitter PLLs in each transceiver block.
(2) There are four receiver PLLs in each transceiver block.
(3) The Global Clock line must be driven by an input pin.

Figure 2–37. ALM in Normal Mode *Note (1)*

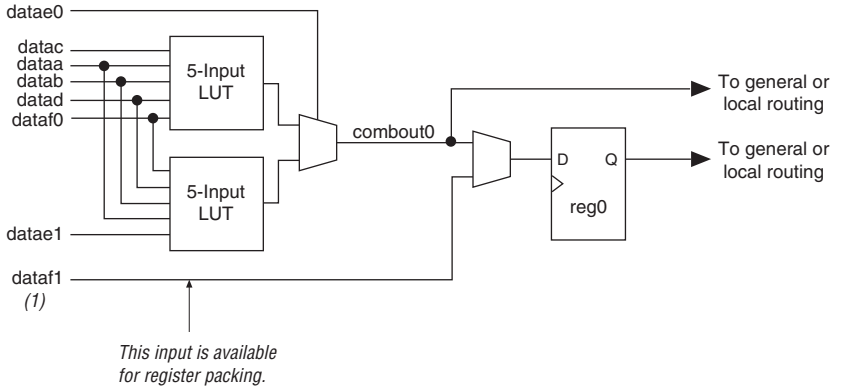


Note to Figure 2–37:

(1) Combinations of functions with less inputs than those shown are also supported. For example, combinations of functions with the following number of inputs are supported: 4 and 3, 3 and 3, 3 and 2, 5 and 2, etc.

The normal mode provides complete backward compatibility with four-input LUT architectures. Two independent functions of four inputs or less can be implemented in one Stratix II GX ALM. In addition, a five-input function and an independent three-input function can be implemented without sharing inputs.

Figure 2–40. Template for Supported Seven-Input Functions in Extended LUT Mode



Note to Figure 2–40:

(1) If the seven-input function is un-registered, the unused eighth input is available for register packing. The second register, `reg1`, is not available.

Arithmetic Mode

The arithmetic mode is ideal for implementing adders, counters, accumulators, wide parity functions, and comparators. An ALM in arithmetic mode uses two sets of two four-input LUTs along with two dedicated full adders. The dedicated adders allow the LUTs to be available to perform pre-adder logic; therefore, each adder can add the output of two four-input functions. The four LUTs share the `dataa` and `datab` inputs. As shown in Figure 2–41, the carry-in signal feeds to `adder0`, and the carry-out from `adder0` feeds to carry-in of `adder1`. The carry-out from `adder1` drives to `adder0` of the next ALM in the LAB. ALMs in arithmetic mode can drive out registered and/or un-registered versions of the adder outputs.

Table 2–18. Stratix II GX Device Routing Scheme (Part 2 of 2)

Source	Destination															
	Shared Arithmetic Chain	Carry Chain	Register Chain	Local Interconnect	Direct Link Interconnect	R4 Interconnect	R24 Interconnect	C4 Interconnect	C16 Interconnect	ALM	M512 RAM Block	M4K RAM Block	M-RAM Block	DSP Blocks	Column IOE	Row IOE
Column IOE					✓			✓	✓							
Row IOE					✓	✓	✓	✓								

TriMatrix Memory

TriMatrix memory consists of three types of RAM blocks: M512, M4K, and M-RAM. Although these memory blocks are different, they can all implement various types of memory with or without parity, including true dual-port, simple dual-port, and single-port RAM, ROM, and FIFO buffers. Table 2–19 shows the size and features of the different RAM blocks.

Table 2–19. TriMatrix Memory Features (Part 1 of 2)

Memory Feature	M512 RAM Block (32 × 18 Bits)	M4K RAM Block (128 × 36 Bits)	M-RAM Block (4K × 144 Bits)
Maximum performance	500 MHz	550 MHz	420 MHz
True dual-port memory		✓	✓
Simple dual-port memory	✓	✓	✓
Single-port memory	✓	✓	✓
Shift register	✓	✓	
ROM	✓	✓	*(1)*
FIFO buffer	✓	✓	✓
Pack mode		✓	✓
Byte enable	✓	✓	✓
Address clock enable		✓	✓
Parity bits	✓	✓	✓
Mixed clock mode	✓	✓	✓
Memory initialization (**.mif**)	✓	✓	

M4K RAM Blocks

The M4K RAM block includes support for true dual-port RAM. The M4K RAM block is used to implement buffers for a wide variety of applications such as storing processor code, implementing lookup schemes, and implementing larger memory applications. Each block contains 4,608 RAM bits (including parity bits). M4K RAM blocks can be configured in the following modes:

- True dual-port RAM
- Simple dual-port RAM
- Single-port RAM
- FIFO
- ROM
- Shift register

When configured as RAM or ROM, you can use an initialization file to pre-load the memory contents.

The M4K RAM blocks allow for different clocks on their inputs and outputs. Either of the two clocks feeding the block can clock M4K RAM block registers (`renwe`, `address`, `byte enable`, `datain`, and `output` registers). Only the `output` register can be bypassed. The six `labclk` signals or local interconnects can drive the control signals for the A and B ports of the M4K RAM block. ALMs can also control the `clock_a`, `clock_b`, `renwe_a`, `renwe_b`, `clr_a`, `clr_b`, `clocken_a`, and `clocken_b` signals, as shown in Figure 2–51.

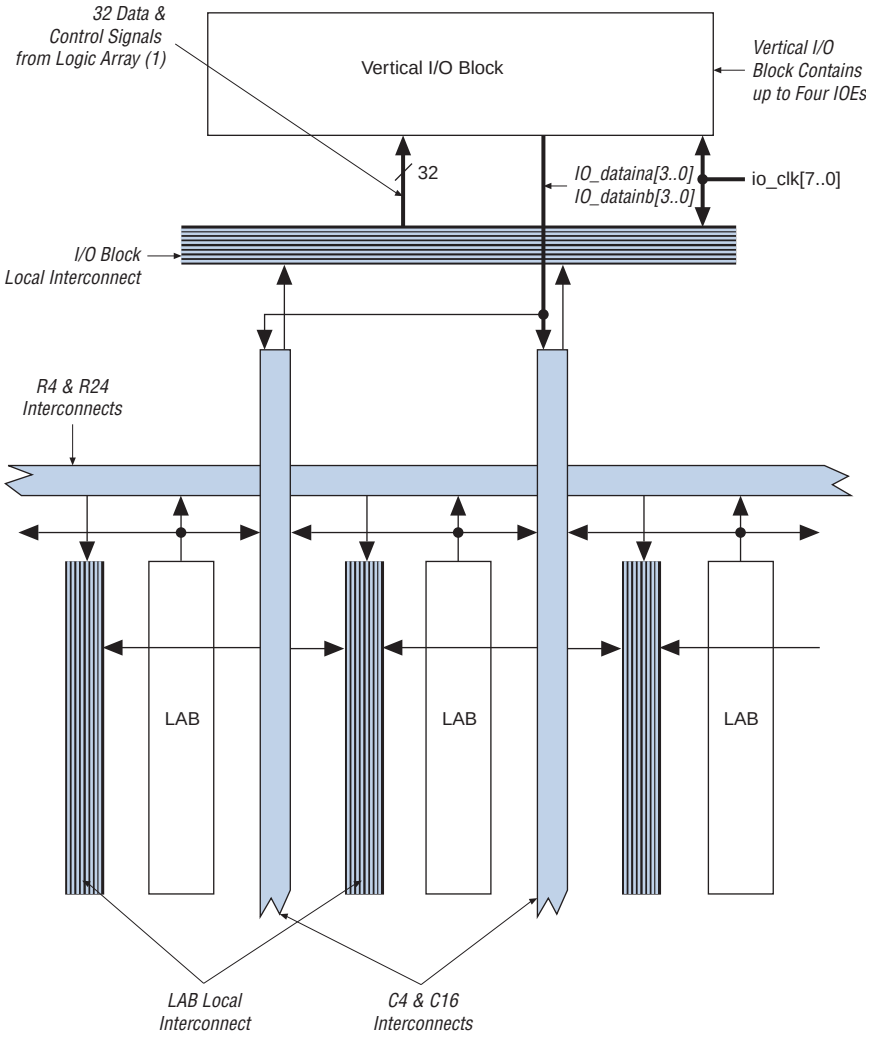
The Stratix II GX clock networks can be disabled (powered down) by both static and dynamic approaches. When a clock net is powered down, all the logic fed by the clock net is in an off-state, thereby reducing the overall power consumption of the device. The global and regional clock networks can be powered down statically through a setting in the configuration file (**.sof** or **.pof**). Clock networks that are not used are automatically powered down through configuration bit settings in the configuration file generated by the Quartus II software. The dynamic clock enable and disable feature allows the internal logic to control power up and down synchronously on GCLK and RCLK nets and PLL_OUT pins. This function is independent of the PLL and is applied directly on the clock network or PLL_OUT pin, as shown in Figures 2–67 through 2–69.

Enhanced and Fast PLLs

Stratix II GX devices provide robust clock management and synthesis using up to four enhanced PLLs and four fast PLLs. These PLLs increase performance and provide advanced clock interfacing and clock frequency synthesis. With features such as clock switchover, spread spectrum clocking, reconfigurable bandwidth, phase control, and reconfigurable phase shifting, the Stratix II GX device's enhanced PLLs provide you with complete control of clocks and system timing. The fast PLLs provide general purpose clocking with multiplication and phase shifting as well as high-speed outputs for high-speed differential I/O support. Enhanced and fast PLLs work together with the Stratix II GX high-speed I/O and advanced clock architecture to provide significant improvements in system performance and bandwidth.

Figure 2–78 shows how a column I/O block connects to the logic array.

Figure 2–78. Column I/O Block Connection to the Interconnect



Note to Figure 2–78:

(1) The 32 data and control signals consist of eight data out lines: four lines each for DDR applications `io_dataouta[3..0]` and `io_dataoutb[3..0]`, four output enables `io_oe[3..0]`, four input clock enables `io_ce_in[3..0]`, four output clock enables `io_ce_out[3..0]`, four clocks `io_clk[3..0]`, four asynchronous clear and preset signals `io_aclr/apreset[3..0]`, and four synchronous clear and preset signals `io_sclr/spreset[3..0]`.

These dedicated circuits combined, with enhanced PLL clocking and phase-shift ability, provide a complete hardware solution for interfacing to high-speed memory.

For more information on external memory interfaces, refer to the *External Memory Interfaces in Stratix II & Stratix II GX Devices* chapter in volume 2 of the *Stratix II GX Device Handbook*.

Programmable Drive Strength

The output buffer for each Stratix II GX device I/O pin has a programmable drive strength control for certain I/O standards. The LVTTL, LVCMOS, SSTL, and HSTL standards have several levels of drive strength that you can control. The default setting used in the Quartus II software is the maximum current strength setting that is used to achieve maximum I/O performance. For all I/O standards, the minimum setting is the lowest drive strength that guarantees the I_{OH}/I_{OL} of the standard. Using minimum settings provides signal slew rate control to reduce system noise and signal overshoot.

Table 2–42. Document Revision History (Part 5 of 6)

Date and Document Version	Changes Made	Summary of Changes
Previous Chapter 02 changes: June 2006, v1.2	• Updated notes 1 and 2 in Figure 2–1. • Updated "Byte Serializer" section. • Updated Tables 2–4, 2–7, and 2–16. • Updated "Programmable Output Driver" section. • Updated Figure 2–12. • Updated "Programmable Pre-Emphasis" section. • Added Table 2–11. • Added "Dynamic Reconfiguration" section. • Added "Calibration Block" section. • Updated "Programmable Equalizer" section, including addition of Figure 2–18.	Updated input frequency range in Table 2–4.
Previous Chapter 02 changes: April 2006, v1.1	• Updated Figure 2–3. • Updated Figure 2–7. • Updated Table 2–4. • Updated "Transmit Buffer" section.	Updated input frequency range in Table 2–4.
Previous Chapter 02 changes: October 2005 v1.0	Added chapter to the *Stratix II GX Device Handbook*.	
Previous Chapter 03 changes: August 2006, v1.4	• Updated Table 3–18 with note.	
Previous Chapter 03 changes: June 2006, v1.3	• Updated note 2 in Figure 3–41. • Updated column title in Table 3–21.	
Previous Chapter 03 changes: April 2006, v1.2	• Updated note 1 in Table 3–9. • Updated note 1 in Figure 3–40. • Updated note 2 in Figure 3–41. • Updated Table 3–16. • Updated Figure 3–56. • Updated Tables 3–19 through 3–22. • Updated Tables 3–25 and 3–26. • Updated "Fast PLL & Channel Layout" section.	Added 1,152-pin FineLine BGA package information for EP2SGX60 device in Table 3–16.

Table 4–19. Stratix II GX Transceiver Block AC Specification Notes (1), (2), (3) (Part 2 of 19)

Symbol/ Description	Conditions	-3 Speed Commercial Speed Grade			-4 Speed Commercial and Industrial Speed Grade			-5 Speed Commercial Speed Grade			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
SONET/SDH Receiver Jitter Tolerance *(7)*											
Jitter tolerance at 622.08 Mbps	Jitter frequency = 0.03 KHz Pattern = PRBS23 No Equalization DC Gain = 0 dB		> 15			> 15			> 15		UI
	Jitter frequency = 25 KHZ Pattern = PRBS23 No Equalization DC Gain = 0 dB		> 1.5			> 1.5			> 1.5		UI
	Jitter frequency = 250 KHz Pattern = PRBS23 No Equalization DC Gain = 0 dB		> 0.15			> 0.15			> 0.15		UI
Jitter tolerance at 2488.32 MBps	Jitter frequency = 0.06 KHz Pattern = PRBS23 No Equalization DC Gain = 0 dB		> 15			> 15			> 15		UI
	Jitter frequency = 100 KHZ Pattern = PRBS23 No Equalization DC Gain = 0 dB		> 1.5			> 1.5			> 1.5		UI
	Jitter frequency = 1 MHz Pattern = PRBS23 No Equalization DC Gain = 0 dB		> 0.15			> 0.15			> 0.15		UI
	Jitter frequency = 10 MHz Pattern = PRBS23 No Equalization DC Gain = 0 dB		> 0.15			> 0.15			> 0.15		UI

Table 4–19. Stratix II GX Transceiver Block AC Specification Notes (1), (2), (3) (Part 10 of 19)

Symbol/ Description	Conditions	-3 Speed Commercial Speed Grade			-4 Speed Commercial and Industrial Speed Grade			-5 Speed Commercial Speed Grade			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
Sinusoidal Jitter Tolerance (peak-to-peak)	Jitter Frequency = 1.875 MHz Data Rate = 3.75 Gbps REFCLK = 187.5 MHz Pattern = CJPAT No Equalization DC Gain = 3 dB	> 0.1			-			-			UI
	Jitter Frequency = 20 MHz Data Rate = 3.75 Gbps REFCLK = 187.5 MHz Pattern = CJPAT No Equalization DC Gain = 3 dB	> 0.1			-			-			UI
(OIF) CEI Transmitter Jitter Generation *(14)*											
Total Jitter (peak-to-peak)	Data Rate = 6.375 Gbps REFCLK = 318.75 MHz Pattern = PRBS15 Vod=1000 mV *(5)* No Pre-emphasis BER = 10^{-12}			0.3			N/A			N/A	UI
(OIF) CEI Receiver Jitter Tolerance *(14)*											
Deterministic Jitter Tolerance (peak-to-peak)	Data Rate = 6.375 Gbps Pattern = PRBS31 Equalizer Setting = 15 DC Gain = 0 dB BER = 10^{-12}	> 0.675			N/A			N/A			UI

Table 4–19. Stratix II GX Transceiver Block AC Specification Notes (1), (2), (3) (Part 16 of 19)

Symbol/ Description	Conditions	-3 Speed Commercial Speed Grade			-4 Speed Commercial and Industrial Speed Grade			-5 Speed Commercial Speed Grade			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
SDI Transmitter Jitter Generation *(16)*											
Alignment Jitter (peak-to-peak)	Data Rate = 1.485 Gbps (HD) REFCLK = 74.25 MHz Pattern = ColorBar Vod = 800 mV No Pre-emphasis Low-Frequency Roll-Off = 100 KHz		0.2			0.2			0.2		UI
	Data Rate = 2.97 Gbps (3G) REFCLK = 148.5 MHz Pattern = ColorBar Vod = 800 mV No Pre-emphasis Low-Frequency Roll-Off = 100 KHz		0.3			0.3			0.3		UI

DC Electrical Characteristics

Table 4–23 shows the Stratix II GX device family DC electrical characteristics.

Table 4–23. Stratix II GX Device DC Operating Conditions (Part 1 of 2) *Note (1)*

Symbol	Parameter	Conditions	Device	Minimum	Typical	Maximum	Unit
I_I	Input pin leakage current	$V_I = V_{CCIOmax}$ to 0 V *(2)*	All	–10		10	µA
I_{OZ}	Tri-stated I/O pin leakage current	$V_O = V_{CCIOmax}$ to 0 V *(2)*	All	–10		10	µA
I_{CCINT0}	V_{CCINT} supply current (standby)	V_I = ground, no load, no toggling inputs T_J = 25 °C	EP2SGX30		0.30	*(3)*	A
			EP2SGX60		0.50	*(3)*	A
			EP2SGX90		0.62	*(3)*	A
			EP2SGX130		0.82	*(3)*	A
I_{CCPD0}	V_{CCPD} supply current (standby)	V_I = ground, no load, no toggling inputs T_J = 25 °C, V_{CCPD} = 3.3V	EP2SGX30		2.7	*(3)*	mA
			EP2SGX60		3.6	*(3)*	mA
			EP2SGX90		4.3	*(3)*	mA
			EP2SGX130		5.4	*(3)*	mA
I_{CCIO0}	V_{CCIO} supply current (standby)	V_I = ground, no load, no toggling inputs T_J = 25 °C	EP2SGX30		4.0	*(3)*	mA
			EP2SGX60		4.0	*(3)*	mA
			EP2SGX90		4.0	*(3)*	mA
			EP2SGX130		4.0	*(3)*	mA

Table 4–86. Stratix II GX I/O Output Delay for Column Pins (Part 5 of 7)

I/O Standard	Drive Strength	Parameter	Fast Corner Industrial/ Commercial	-3 Speed Grade *(3)*	-3 Speed Grade *(4)*	-4 Speed Grade	-5 Speed Grade	Unit
1.5-V HSTL Class II	16 mA	t_{OP}	924	1431	1501	1596	1734	ps
		t_{DIP}	946	1497	1571	1670	1824	ps
	18 mA	t_{OP}	927	1439	1510	1605	1744	ps
		t_{DIP}	949	1505	1580	1679	1834	ps
	20 mA *(1)*	t_{OP}	929	1450	1521	1618	1757	ps
		t_{DIP}	951	1516	1591	1692	1847	ps
PCI	-	t_{OP}	1082	1956	2051	2176	2070	ps
		t_{DIP}	1104	2022	2121	2250	2160	ps
PCI-X	-	t_{OP}	1082	1956	2051	2176	2070	ps
		t_{DIP}	1104	2022	2121	2250	2160	ps
Differential SSTL-2 Class I *(2)*	8 mA	t_{OP}	957	1715	1799	1913	2041	ps
		t_{DIP}	979	1781	1869	1987	2131	ps
	12 mA	t_{OP}	940	1672	1754	1865	1991	ps
		t_{DIP}	962	1738	1824	1939	2081	ps
Differential SSTL-2 Class II *(2)*	16 mA	t_{OP}	918	1609	1688	1795	1918	ps
		t_{DIP}	940	1675	1758	1869	2008	ps
	20 mA	t_{OP}	919	1598	1676	1783	1905	ps
		t_{DIP}	941	1664	1746	1857	1995	ps
	24 mA	t_{OP}	915	1596	1674	1781	1903	ps
		t_{DIP}	937	1662	1744	1855	1993	ps
Differential SSTL-18 Class I *(2)*	4 mA	t_{OP}	953	1690	1773	1886	2012	ps
		t_{DIP}	975	1756	1843	1960	2102	ps
	6 mA	t_{OP}	958	1656	1737	1848	1973	ps
		t_{DIP}	980	1722	1807	1922	2063	ps
	8 mA	t_{OP}	937	1640	1721	1830	1954	ps
		t_{DIP}	959	1706	1791	1904	2044	ps
	10 mA	t_{OP}	942	1638	1718	1827	1952	ps
		t_{DIP}	964	1704	1788	1901	2042	ps
	12 mA	t_{OP}	936	1626	1706	1814	1938	ps
		t_{DIP}	958	1692	1776	1888	2028	ps

Tables 4–98 through 4–105 show the maximum DCD in absolution derivation for different I/O standards on Stratix II GX devices. Examples are also provided that show how to calculate DCD as a percentage.

Table 4–98. Maximum DCD for Non-DDIO Output on Row I/O Pins

Row I/O Output Standard	Maximum DCD (ps) for Non-DDIO Output		
	-3 Devices	-4 and -5 Devices	Unit
3.3-V LVTTTL	245	275	ps
3.3-V LVCMOS	125	155	ps
2.5 V	105	135	ps
1.8 V	180	180	ps
1.5-V LVCMOS	165	195	ps
SSTL-2 Class I	115	145	ps
SSTL-2 Class II	95	125	ps
SSTL-18 Class I	55	85	ps
1.8-V HSTL Class I	80	100	ps
1.5-V HSTL Class I	85	115	ps
LVDS	55	80	ps

Here is an example for calculating the DCD as a percentage for a non-DDIO output on a row I/O on a -3 device:

If the non-DDIO output I/O standard is SSTL-2 Class II, the maximum DCD is 95 ps (see Table 4–99). If the clock frequency is 267 MHz, the clock period T is:

T = 1/ f = 1 / 267 MHz = 3.745 ns = 3,745 ps

To calculate the DCD as a percentage:

(T/2 – DCD) / T = (3,745 ps/2 – 95 ps) / 3,745 ps = 47.5% (for low boundary)

(T/2 + DCD) / T = (3,745 ps/2 + 95 ps) / 3,745 ps = 52.5% (for high boundary)

5. Reference and Ordering Information

SIIGX51007-1.3

Software

Stratix® II GX devices are supported by the Altera® Quartus® II design software, which provides a comprehensive environment for system-on-a-programmable-chip (SOPC) design. The Quartus II software includes HDL and schematic design entry, compilation and logic synthesis, full simulation and advanced timing analysis, SignalTap® II logic analyzer, and device configuration.

Refer to the *Quartus II Development Software Handbook* for more information on the Quartus II software features.

The Quartus II software supports the Windows XP/2000/NT, Sun Solaris 8/9, Linux Red Hat v7.3, Linux Red Hat Enterprise 3, and HP-UX operating systems. It also supports seamless integration with industry-leading EDA tools through the NativeLink interface.

Device Pin-Outs

Stratix II GX device pin-outs (*Pin-Out Files for Altera Devices*) are available on the Altera web site at www.altera.com.

Ordering Information

Figure 5–1 describes the ordering codes for Stratix II GX devices.

For more information on a specific package, refer to the *Package Information for Stratix II & Stratix II GX Devices* chapter in volume 2 of the *Stratix II GX Device Handbook*.