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Details

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Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I ² C, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	83
Program Memory Size	128KB (43K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-TQFP
Supplier Device Package	100-TQFP (12x12)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24fj128gb110-i-pt

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		Pin Number				
Function	64-Pin TQFP, QFN	80-Pin TQFP	100-Pin TQFP	I/O	Input Buffer	Description
RC1	_	4	6	I/O	ST	PORTC Digital I/O.
RC2	_		7	I/O	ST	
RC3	_	5	8	I/O	ST	
RC4	_	_	9	I/O	ST	
RC12	39	49	63	I/O	ST	
RC13	47	59	73	I/O	ST	
RC14	48	60	74	I/O	ST	
RC15	40	50	64	I/O	ST	
RCV	18	22	27	I	ST	USB Receive Input (from external transceiver).
RD0	46	58	72	I/O	ST	PORTD Digital I/O.
RD1	49	61	76	I/O	ST	
RD2	50	62	77	I/O	ST	
RD3	51	63	78	I/O	ST	
RD4	52	66	81	I/O	ST	
RD5	53	67	82	I/O	ST	
RD6	54	68	83	I/O	ST	
RD7	55	69	84	I/O	ST	
RD8	42	54	68	I/O	ST	
RD9	43	55	69	I/O	ST	
RD10	44	56	70	I/O	ST	
RD11	45	57	71	I/O	ST	
RD12	_	64	79	I/O	ST	
RD13	_	65	80	I/O	ST	
RD14	_	37	47	I/O	ST	
RD15	_	38	48	I/O	ST	
RE0	60	76	93	I/O	ST	PORTE Digital I/O.
RE1	61	77	94	I/O	ST	1
RE2	62	78	98	I/O	ST	1
RE3	63	79	99	I/O	ST	1
RE4	64	80	100	I/O	ST	1
RE5	1	1	3	I/O	ST	1
RE6	2	2	4	I/O	ST	1
RE7	3	3	5	I/O	ST	1
RE8	_	13	18	I/O	ST	1
RE9	_	14	19	I/O	ST	1
REFO	30	36	44	0	—	Reference Clock Output.
Legend:	TTL = TTL in	put buffer			ST = 5	Schmitt Trigger input buffer

TABLE 1-4: PIC24FJ256GB110 FAMILY PINOUT DESCRIPTIONS (CONTINUED)

Legend: TTL = TTL input buffer ANA = Analog level input/output ST = Schmitt Trigger input buffer

 $I^2C^{TM} = I^2C/SMBus$ input buffer

2.6 External Oscillator Pins

Many microcontrollers have options for at least two oscillators: a high-frequency primary oscillator and a low-frequency secondary oscillator (refer to **Section 8.0 "Oscillator Configuration**" for details).

The oscillator circuit should be placed on the same side of the board as the device. Place the oscillator circuit close to the respective oscillator pins with no more than 0.5 inch (12 mm) between the circuit components and the pins. The load capacitors should be placed next to the oscillator itself, on the same side of the board.

Use a grounded copper pour around the oscillator circuit to isolate it from surrounding circuits. The grounded copper pour should be routed directly to the MCU ground. Do not run any signal traces or power traces inside the ground pour. Also, if using a two-sided board, avoid any traces on the other side of the board where the crystal is placed.

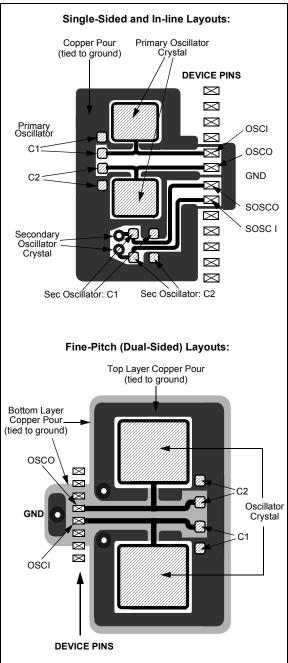
Layout suggestions are shown in Figure 2-4. In-line packages may be handled with a single-sided layout that completely encompasses the oscillator pins. With fine-pitch packages, it is not always possible to completely surround the pins and components. A suitable solution is to tie the broken guard sections to a mirrored ground layer. In all cases, the guard trace(s) must be returned to ground.

In planning the application's routing and I/O assignments, ensure that adjacent port pins and other signals in close proximity to the oscillator are benign (i.e., free of high frequencies, short rise and fall times and other similar noise).

For additional information and design guidance on oscillator circuits, please refer to these Microchip Application Notes, available at the corporate web site (www.microchip.com):

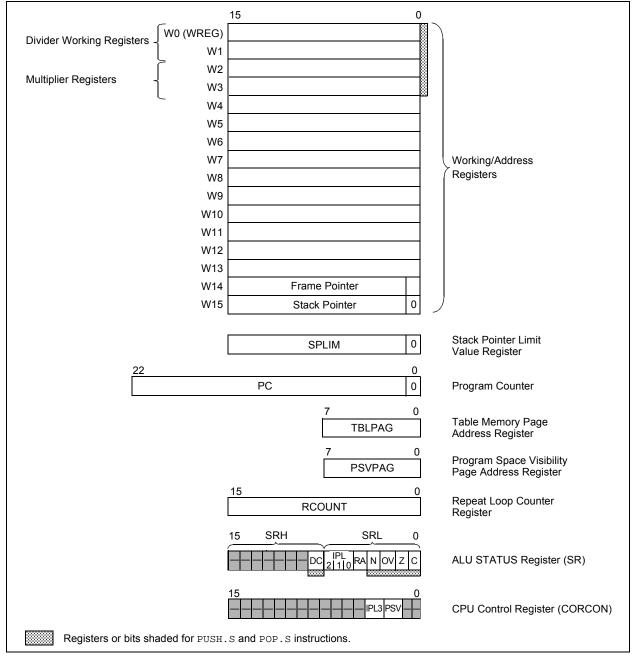
- AN826, "Crystal Oscillator Basics and Crystal Selection for rfPIC™ and PICmicro[®] Devices"
- AN849, "Basic PICmicro[®] Oscillator Design"
- AN943, "Practical PICmicro[®] Oscillator Analysis and Design"
- AN949, "Making Your Oscillator Work"

FIGURE 2-4: SUGGESTED PLACEMENT OF THE OSCILLATOR CIRCUIT



Register(s) Name	Description
W0 through W15	Working Register Array
PC	23-Bit Program Counter
SR	ALU STATUS Register
SPLIM	Stack Pointer Limit Value Register
TBLPAG	Table Memory Page Address Register
PSVPAG	Program Space Visibility Page Address Register
RCOUNT	Repeat Loop Counter Register
CORCON	CPU Control Register

FIGURE 3-2: PROGRAMMER'S MODEL



3.3.2 DIVIDER

The divide block supports signed and unsigned integer divide operations with the following data sizes:

- 1. 32-bit signed/16-bit signed divide
- 2. 32-bit unsigned/16-bit unsigned divide
- 3. 16-bit signed/16-bit signed divide
- 4. 16-bit unsigned/16-bit unsigned divide

The quotient for all divide instructions ends up in W0 and the remainder in W1. Sixteen-bit signed and unsigned DIV instructions can specify any W register for both the 16-bit divisor (Wn), and any W register (aligned) pair (W(m + 1):Wm) for the 32-bit dividend. The divide algorithm takes one cycle per bit of divisor, so both 32-bit/16-bit and 16-bit/16-bit instructions take the same number of cycles to execute.

3.3.3 MULTI-BIT SHIFT SUPPORT

The PIC24F ALU supports both single bit and single-cycle, multi-bit arithmetic and logic shifts. Multi-bit shifts are implemented using a shifter block, capable of performing up to a 15-bit arithmetic right shift, or up to a 15-bit left shift, in a single cycle. All multi-bit shift instructions only support Register Direct Addressing for both the operand source and result destination.

A full summary of instructions that use the shift operation is provided below in Table 3-2.

TABLE 3-2: INSTRUCTIONS THAT USE THE SINGLE AND MULTI-BIT SHIFT OPERATION

Instruction	Description
ASR	Arithmetic shift right source register by one or more bits.
SL	Shift left source register by one or more bits.
LSR	Logical shift right source register by one or more bits.

TABLE 4-12: PORTA REGISTER MAP⁽¹⁾

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7 ⁽²⁾	Bit 6 ⁽²⁾	Bit 5 ⁽²⁾	Bit 4 ⁽²⁾	Bit 3 ⁽²⁾	Bit2 ⁽²⁾	Bit 1 ⁽²⁾	Bit 0 ⁽²⁾	All Resets
TRISA	02C0	TRISA15	TRISA14	_	_	_	TRISA10	TRISA9	_	TRISA7	TRISA6	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	36FF
PORTA	02C2	RA15	RA14	-	_	—	RA10	RA9	—	RA7	RA6	RA5	RA4	RA3	RA2	RA1	RA0	xxxx
LATA	02C4	LATA15	LATA14		_	—	LATA10	LATA9	—	LATA7	LATA6	LATA5	LATA4	LATA3	LATA2	LATA1	LATA0	xxxx
ODCA	02C6	ODA15	ODA14	_	_	_	ODA10	ODA9	_	ODA7	ODA6	ODA5	ODA4	ODA3	ODA2	ODA1	ODA0	0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal. Reset values shown are for 100-pin devices.

Note 1: PORTA and all associated bits are unimplemented on 64-pin devices and read as '0'. Bits are available on 80-pin and 100-pin devices only, unless otherwise noted.

2: Bits are implemented on 100-pin devices only; otherwise read as '0'.

TABLE 4-13: PORTB REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISB	02C8	TRISB15	TRISB14	TRISB13	TRISB12	TRISB11	TRISB10	TRISB9	TRISB8	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	FFFF
PORTB	02CA	RB15	RB14	RB13	RB12	RB11	RB10	RB9	RB8	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	xxxx
LATB	02CC	LATB15	LATB14	LATB13	LATB12	LATB11	LATB10	LATB9	LATB8	LATB7	LATB6	LATB5	LATB4	LATB3	LATB2	LATB1	LATB0	xxxx
ODCB	02CE	ODB15	ODB14	ODB13	ODB12	ODB11	ODB10	ODB9	ODB8	ODB7	ODB6	ODB5	ODB4	ODB3	ODB2	ODB1	ODB0	0000

Legend: Reset values are shown in hexadecimal.

TABLE 4-14: PORTC REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4 ⁽¹⁾	Bit 3 ⁽²⁾	Bit 2 ⁽¹⁾	Bit 1 ⁽²⁾	Bit 0	All Resets
TRISC	02D0	TRISC15	TRISC14	TRISC13	TRISC12	—	_	-	_	_	—	-	TRISC4	TRISC3	TRISC2	TRISC1	_	F01E
PORTC	02D2	RC15 ^(3,4)	RC14	RC13	RC12 ⁽³⁾	_		_	_	_	_	_	RC4	RC3	RC2	RC1	_	xxxx
LATC	02D4	LATC15	LATC14	LATC13	LATC12	_	_		_	_	_		LATC4	LATC3	LATC2	LATC1		xxxx
ODCC	02D6	ODC15	ODC14	ODC13	ODC12	_	_	_	_	_	_	_	ODC4	ODC3	ODC2	ODC1		0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal. Reset values shown are for 100-pin devices.

Note 1: Bits are unimplemented on 64-pin and 80-pin devices; read as '0'.

2: Bits are unimplemented on 64-pin devices; read as '0'.

3: RC12 and RC15 are only available when the Primary Oscillator is disabled or when EC mode is selected (POSCMD<1:0> Configuration bits = 11 or 00); otherwise read as '0'.

4: RC15 is only available when the POSCMD<1:0> Configuration bits = 11 or 00 and the OSCIOFN Configuration bit = 1.

TABLE 4-15:PORTD REGISTER MAP

File Name	Addr	Bit 15 ⁽¹⁾	Bit 14 ⁽¹⁾	Bit 13 ⁽¹⁾	Bit 12 ⁽¹⁾	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISD	02D8	TRISD15	TRISD14	TRISD13	TRISD12	TRISD11	TRISD10	TRISD9	TRISD8	TRISD7	TRISD6	TRISD5	TRISD4	TRISD3	TRISD2	TRISD1	TRISD0	FFFF
PORTD	02DA	RD15	RD14	RD13	RD12	RD11	RD10	RD9	RD8	RD7	RD6	RD5	RD4	RD3	RD2	RD1	RD0	xxxx
LATD	02DC	LATD15	LATD14	LATD13	LATD12	LATD11	LATD10	LATD9	LATD8	LATD7	LATD6	LATD5	LATD4	LATD3	LATD2	LATD1	LATD0	xxxx
ODCD	02DE	ODD15	ODD14	ODD13	ODD12	ODD11	ODD10	ODD9	ODD8	ODD7	ODD6	ODD5	ODD4	ODD3	ODD2	ODD1	ODD0	0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal. Reset values shown are for 100-pin devices.

Note 1: Bits are unimplemented on 64-pin devices; read as '0'.

DS39897C-page 51

	Vector		AIVT	Inte	errupt Bit Locat	ions
Interrupt Source	Number	IVT Address	Address	Flag	Enable	Priority
Timer1	3	00001Ah	00011Ah	IFS0<3>	IEC0<3>	IPC0<14:12>
Timer2	7	000022h	000122h	IFS0<7>	IEC0<7>	IPC1<14:12>
Timer3	8	000024h	000124h	IFS0<8>	IEC0<8>	IPC2<2:0>
Timer4	27	00004Ah	00014Ah	IFS1<11>	IEC1<11>	IPC6<14:12>
Timer5	28	00004Ch	00014Ch	IFS1<12>	IEC1<12>	IPC7<2:0>
UART1 Error	65	000096h	000196h	IFS4<1>	IEC4<1>	IPC16<6:4>
UART1 Receiver	11	00002Ah	00012Ah	IFS0<11>	IEC0<11>	IPC2<14:12>
UART1 Transmitter	12	00002Ch	00012Ch	IFS0<12>	IEC0<12>	IPC3<2:0>
UART2 Error	66	000098h	000198h	IFS4<2>	IEC4<2>	IPC16<10:8>
UART2 Receiver	30	000050h	000150h	IFS1<14>	IEC1<14>	IPC7<10:8>
UART2 Transmitter	31	000052h	000152h	IFS1<15>	IEC1<15>	IPC7<14:12>
UART3 Error	81	0000B6h	0001B6h	IFS5<1>	IEC5<1>	IPC20<6:4>
UART3 Receiver	82	0000B8h	0001B8h	IFS5<2>	IEC5<2>	IPC20<10:8>
UART3 Transmitter	83	0000BAh	0001BAh	IFS5<3>	IEC5<3>	IPC20<14:12>
UART4 Error	87	0000C2h	0001C2h	IFS5<7>	IEC5<7>	IPC21<14:12>
UART4 Receiver	88	0000C4h	0001C4h	IFS5<8>	IEC5<8>	IPC22<2:0>
UART4 Transmitter	89	0000C6h	0001C6h	IFS5<9>	IEC5<9>	IPC22<6:4>
USB Interrupt	86	0000C0h	0001C0h	IFS5<6>	IEC5<6>	IPC21<10:8>

TABLE 7-2: IMPLEMENTED INTERRUPT VECTORS (CONTINUED)

7.3 Interrupt Control and Status Registers

The PIC24FJ256GB110 family of devices implements a total of 37 registers for the interrupt controller:

- INTCON1
- INTCON2
- IFS0 through IFS5
- IEC0 through IEC5
- IPC0 through IPC23 (except IPC14 and IPC17)
- INTTREG

Global interrupt control functions are controlled from INTCON1 and INTCON2. INTCON1 contains the Interrupt Nesting Disable (NSTDIS) bit, as well as the control and status flags for the processor trap sources. The INTCON2 register controls the external interrupt request signal behavior and the use of the Alternate Interrupt Vector Table.

The IFSx registers maintain all of the interrupt request flags. Each source of interrupt has a status bit which is set by the respective peripherals, or an external signal, and is cleared via software.

The IECx registers maintain all of the interrupt enable bits. These control bits are used to individually enable interrupts from the peripherals or external signals.

The IPCx registers are used to set the interrupt priority level for each source of interrupt. Each user interrupt source can be assigned to one of eight priority levels. The INTTREG register contains the associated interrupt vector number and the new CPU interrupt priority level, which are latched into the Vector Number (VECNUM<6:0>) and the Interrupt Level (ILR<3:0>) bit fields in the INTTREG register. The new interrupt priority level is the priority of the pending interrupt.

The interrupt sources are assigned to the IFSx, IECx and IPCx registers in the order of their vector numbers, as shown in Table 7-2. For example, the INT0 (External Interrupt 0) is shown as having a vector number and a natural order priority of 0. Thus, the INT0IF status bit is found in IFS0<0>, the INT0IE enable bit in IEC0<0> and the INT0IP<2:0> priority bits in the first position of IPC0 (IPC0<2:0>).

Although they are not specifically part of the interrupt control hardware, two of the CPU Control registers contain bits that control interrupt functionality. The ALU STATUS register (SR) contains the IPL<2:0> bits (SR<7:5>). These indicate the current CPU interrupt priority level. The user may change the current CPU priority level by writing to the IPL bits.

The CORCON register contains the IPL3 bit, which together with IPL<2:0>, indicates the current CPU priority level. IPL3 is a read-only bit so that trap events cannot be masked by the user software.

All interrupt registers are described in Register 7-1 through Register 7-39, in the following pages.

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	AD1IE	U1TXIE	U1RXIE	SPI1IE	SPF1IE	T3IE
bit 15							bit 8
R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
T2IE	OC2IE	IC2IE	—	T1IE	OC1IE	IC1IE	INT0IE
bit 7							bit (
Legend:							
R = Readab	le bit	W = Writable	bit	U = Unimplen	nented bit, read	d as '0'	
-n = Value a	t POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	own
bit 15-14	Unimplemen	ted: Read as ')'				
bit 13	AD1IE: A/D C 1 = Interrupt r	Conversion Con request enable	nplete Interrup d	t Enable bit			
bit 12	U1TXIE: UAF 1 = Interrupt r	request not ena RT1 Transmitter request enable request not ena	· Interrupt Enal	ble bit			
bit 11	U1RXIE: UAF 1 = Interrupt r	RT1 Receiver Ir equest enable equest not ena	nterrupt Enable d	e bit			
bit 10	SPI1IE: SPI1 1 = Interrupt r	Transfer Comp request enabled request not ena	blete Interrupt I d	Enable bit			
bit 9	SPF1IE: SPI1 1 = Interrupt r	Fault Interrup equest enable equest not ena	t Enable bit d				
bit 8	T3IE: Timer3 1 = Interrupt r	Interrupt Enable equest enable equest not ena	e bit d				
bit 7	T2IE: Timer2 1 = Interrupt r	Interrupt Enable request enable request not ena	e bit d				
bit 6	OC2IE: Outpu 1 = Interrupt r	ut Compare Ch equest enable equest not ena	annel 2 Interru ป	ipt Enable bit			
bit 5	IC2IE: Input C 1 = Interrupt r	Capture Channe request enable request not ena	el 2 Interrupt E d	nable bit			
bit 4	-	ted: Read as '					
bit 3	T1IE: Timer1 1 = Interrupt r	Interrupt Enable request enable request not ena	e bit d				
bit 2	1 = Interrupt r	ut Compare Ch equest enabled equest not ena	b	ipt Enable bit			
bit 1	1 = Interrupt r	Capture Channe request enable request not ena	d .	nable bit			
bit 0	1 = Interrupt r	nal Interrupt 0 equest enable equest not ena	b				

REGISTER 7-15: IEC4: INTERRUPT ENABLE CONTROL REGISTER 4

U-0	U-0	R/W-0	U-0	U-0	U-0	U-0	R/W-0
_	—	CTMUIE	_	—	—	—	LVDIE
bit 15							bit 8
U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	U-0
		—	—	CRCIE	U2ERIE	U1ERIE	
bit 7							bit C
Legend:							
R = Readabl		W = Writable b	bit		nented bit, read	d as '0'	
-n = Value at	t POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	own
bit 15-14	-	ted: Read as '0					
bit 13		MU Interrupt En					
		request enabled request not enal					
bit 12-9	Unimplemen	ted: Read as '0	,				
bit 8	LVDIE: Low-	Voltage Detect I	nterrupt Enab	le bit			
		request enabled request not enal					
bit 7-4		ted: Read as '0					
bit 3	CRCIE: CRC	Generator Inter	rupt Enable b	pit			
		request enabled request not enal					
bit 2	•	RT2 Error Interru					
		request enabled	•				
		request not enal					
	•		unt Enchla hit				
bit 1	U1ERIE: UA	RI1 Error Interru	ומנ בהמסופ סוו				
bit 1	1 = Interrupt	request enabled					
bit 1	1 = Interrupt						

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	—	RP27R5	RP27R4	RP27R3	RP27R2	RP27R1	RP27R0
bit 15							bit 8
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP26R5	RP26R4	RP26R3	RP26R2	RP26R1	RP26R0
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit			U = Unimplemented bit, read as '0'				
-n = Value at POR '1' = Bit is set			'0' = Bit is cleared x = Bit is unknow			iown	

REGISTER 10-35: RPOR13: PERIPHERAL PIN SELECT OUTPUT REGISTER 13

bit 15-14 Unimplemented: Read as '0'

- bit 13-8
 RP27R<5:0>: RP27 Output Pin Mapping bits

 Peripheral output number n is assigned to pin, RP27 (see Table 10-3 for peripheral function numbers)

 bit 7-6
 Unimplemented: Read as '0'
- bit 5-0 **RP26R<5:0>:** RP26 Output Pin Mapping bits Peripheral output number n is assigned to pin, RP26 (see Table 10-3 for peripheral function numbers)

REGISTER 10-36: RPOR14: PERIPHERAL PIN SELECT OUTPUT REGISTER 14

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	_	RP29R5	RP29R4	RP29R3	RP29R2	RP29R1	RP29R0
bit 15							bit 8
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	_	RP28R5	RP28R4	RP28R3	RP28R2	RP28R1	RP28R0
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit			U = Unimplemented bit, read as '0'				

'0' = Bit is cleared

bit 15-14 Unimplemented: Read as '0'

'1' = Bit is set

bit 13-8 **RP29R<5:0>:** RP29 Output Pin Mapping bits Peripheral output number n is assigned to pin, RP29 (see Table 10-3 for peripheral function numbers)

bit 7-6 Unimplemented: Read as '0'

bit 5-0 **RP28R<5:0>:** RP28 Output Pin Mapping bits Peripheral output number n is assigned to pin, RP28 (see Table 10-3 for peripheral function numbers)

-n = Value at POR

x = Bit is unknown

For 32-bit cascaded operation, these steps are also necessary:

- Set the OC32 bits for both registers (OCyCON2<8> and (OCxCON2<8>). Enable the even numbered module first to ensure the modules will start functioning in unison.
- Clear the OCTRIG bit of the even module (OCyCON2), so the module will run in Synchronous mode.
- 3. Configure the desired output and Fault settings for OCy.
- 4. Force the output pin for OCx to the output state by clearing the OCTRIS bit.
- If Trigger mode operation is required, configure the trigger options in OCx by using the OCTRIG (OCxCON2<7>), TRIGSTAT (OCxCON2<6>), and SYNCSEL (OCxCON2<4:0>) bits.
- Configure the desired compare or PWM mode of operation (OCM<2:0>) for OCy first, then for OCx.

Depending on the output mode selected, the module holds the OCx pin in its default state, and forces a transition to the opposite state when OCxR matches the timer. In Double Compare modes, OCx is forced back to its default state when a match with OCxRS occurs. The OCxIF interrupt flag is set after an OCxR match in Single Compare modes, and after each OCxRS match in Double Compare modes.

Single-shot pulse events only occur once, but may be repeated by simply rewriting the value of the OCxCON1 register. Continuous pulse events continue indefinitely until terminated.

14.3 Pulse-Width Modulation (PWM) Mode

In PWM mode, the output compare module can be configured for edge-aligned or center-aligned pulse waveform generation. All PWM operations are double-buffered (buffer registers are internal to the module and are not mapped into SFR space).

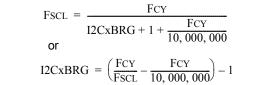
To configure the output compare module for PWM operation:

- 1. Configure the OCx output for one of the available Peripheral Pin Select pins.
- 2. Calculate the desired duty cycles and load them into the OCxR register.
- 3. Calculate the desired period and load it into the OCxRS register.
- Select the current OCx as the sync source by writing 0x1F to SYNCSEL<4:0> (OCxCON2<4:0>), and clearing OCTRIG (OCxCON2<7>).
- 5. Select a clock source by writing the OCTSEL<2:0> (OCxCON<12:10>) bits.
- 6. Enable interrupts, if required, for the timer and output compare modules. The output compare interrupt is required for PWM Fault pin utilization.
- 7. Select the desired PWM mode in the OCM<2:0> (OCxCON1<2:0>) bits.
- If a timer is selected as a clock source, set the TMRy prescale value and enable the time base by setting the TON (TxCON<15>) bit.
- Note: This peripheral contains input and output functions that may need to be configured by the Peripheral Pin Select. See Section 10.4 "Peripheral Pin Select" for more information.

16.2 Setting Baud Rate When Operating as a Bus Master

To compute the Baud Rate Generator reload value, use Equation 16-1.

EQUATION 16-1: COMPUTING BAUD RATE RELOAD VALUE^(1,2)



- **Note 1:** Based on Fcy = Fosc/2; Doze mode and PLL are disabled.
 - 2: These clock rate values are for guidance only. The actual clock rate can be affected by various system level parameters. The actual clock rate should be measured in its intended application.

TABLE 16-1: I²C[™] CLOCK RATES^(1,2)

16.3 Slave Address Masking

The I2CxMSK register (Register 16-3) designates address bit positions as "don't care" for both 7-Bit and 10-Bit Addressing modes. Setting a particular bit location (= 1) in the I2CxMSK register causes the slave module to respond whether the corresponding address bit value is a '0' or a '1'. For example, when I2CxMSK is set to '00100000', the slave module will detect both addresses, '0000000' and '0100000'.

To enable address masking, the IPMI (Intelligent Peripheral Management Interface) must be disabled by clearing the IPMIEN bit (I2CxCON<11>).

Note: As a result of changes in the I²C[™] protocol, the addresses in Table 16-2 are reserved and will not be Acknowledged in Slave mode. This includes any address mask settings that include any of these addresses.

Demained Queters Fact	Fair	I2CxB		
Required System FscL	Fcy	(Decimal)	(Hexadecimal)	Actual FSCL
100 kHz	16 MHz	157	9D	100 kHz
100 kHz	8 MHz	78	4E	100 kHz
100 kHz	4 MHz	39	27	99 kHz
400 kHz	16 MHz	37	25	404 kHz
400 kHz	8 MHz	18	12	404 kHz
400 kHz	4 MHz	9	9	385 kHz
400 kHz	2 MHz	4	4	385 kHz
1 MHz	16 MHz	13	D	1.026 MHz
1 MHz	8 MHz	6	6	1.026 MHz
1 MHz	4 MHz	3	3	0.909 MHz

Note 1: Based on FCY = FOSC/2, Doze mode and PLL are disabled.

2: These clock rate values are for guidance only. The actual clock rate can be affected by various system level parameters. The actual clock rate should be measured in its intended application.

TABLE 16-2: I²C[™] RESERVED ADDRESSES⁽¹⁾

Slave Address	R/W Bit	Description
0000 0000	0	General Call Address ⁽²⁾
0000 0000	1	Start Byte
0000 001	x	Cbus Address
0000 010	х	Reserved
0000 011	х	Reserved
0000 1xx	x	HS Mode Master Code
1111 1xx	х	Reserved
1111 Oxx	x	10-Bit Slave Upper Byte ⁽³⁾

Note 1: The address bits listed here will never cause an address match, independent of address mask settings.

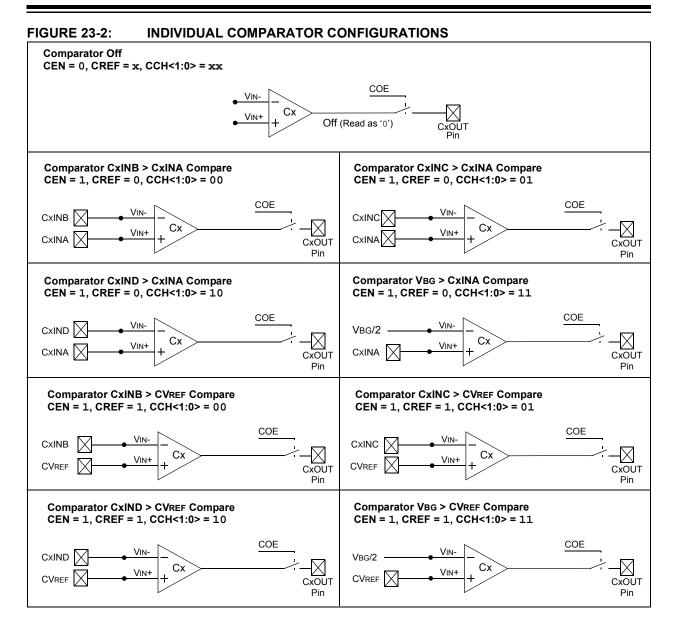
- 2: Address will be Acknowledged only if GCEN = 1.
- 3: Match on this address can only occur on the upper byte in 10-Bit Addressing mode.

REGISTER 17-1: UXMODE: UARTX MODE REGISTER (CONTINUED)

bit 4	RXINV: Receive Polarity Inversion bit 1 = UxRX Idle state is '0' 0 = UxRX Idle state is '1'
bit 3	BRGH: High Baud Rate Enable bit
	1 = High-Speed mode (baud clock generated from FcY/4)0 = Standard mode (baud clock generated from FcY/16)
bit 2-1	PDSEL<1:0>: Parity and Data Selection bits
	 11 = 9-bit data, no parity 10 = 8-bit data, odd parity 01 = 8-bit data, even parity 00 = 8-bit data, no parity
bit 0	STSEL: Stop Bit Selection bit
	1 = Two Stop bits 0 = One Stop bit

- **Note 1:** If UARTEN = 1, the peripheral inputs and outputs must be configured to an available RPn pin. See **Section 10.4 "Peripheral Pin Select"** for more information.
 - **2:** This feature is only available for the 16x BRG mode (BRGH = 0).

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0				
—	—	—	—	—	—	—					
bit 15							bit				
R-x, HSC	R-x, HSC	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
JSTATE	SE0	TOKBUSY	USBRST	HOSTEN	RESUME	PPBRST	SOFEN				
bit 7	320	TURBUST	USDROI	HUSTEN	RESUME	FFDROI	bit				
Legend:		U = Unimplem	ented bit, read	d as '0'							
R = Readab	ole bit	W = Writable t	bit	HSC = Hardw	are Settable/C	learable bit					
-n = Value a	it POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	iown				
bit 15-8	-	ited: Read as '0									
bit 7		e Differential Re		•			D				
	1 = J state (0 0 = No J stat	differential '0' in te detected	low speed, dif	terential '1' in fi	ull speed) dete	cted on the US	В				
oit 6	SE0: Live Single-Ended Zero Flag bit										
	1 = Single-ended zero active on the USB bus										
	0 = No single-ended zero detected										
bit 5		TOKBUSY: Token Busy Status bit									
	 1 = Token being executed by the USB module in On-The-Go state 0 = No token being executed 										
bit 4		•	•								
		USBRST: Module Reset bit 1 = USB Reset has been generated; for software Reset, application must set this bit for 50 ms, then									
	clear it										
	0 = USB Reset terminated										
bit 3		HOSTEN: Host Mode Enable bit									
	 1 = USB host capability enabled; pull-downs on D+ and D- are activated in hardware 0 = USB host capability disabled 										
bit 2		RESUME: Resume Signaling Enable bit									
		1 = Resume signaling activated; software must set bit for 10 ms and then clear to enable remote wake-up									
	0 = Resume signaling disabled										
bit 1		PPBRST: Ping-Pong Buffers Reset bit									
		Il Ping-Pong But ng Buffer Pointe		the EVEN BD	banks						
bit 0											
bit 0	SOFEN: Star	t-Of-Frame Ena Frame token se	ble bit	millisecond							



U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0			
_	—	_	—	—	_	—	—			
bit 15							bit 8			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
CVREN	CVROE	CVRR	CVRSS	CVR3	CVR2	CVR1	CVR0			
bit 7							bit (
Legend: R = Readab	lo hit	W = Writable	hit	II – Unimplom	onted hit read	d ac 'O'				
				U = Unimplem						
-n = Value a	IT POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	IOWN			
bit 15-8	Unimplemen	ted: Read as '	0'							
bit 7	CVREN: Comparator Voltage Reference Enable bit									
	1 = CVREF circuit powered on									
	0 = CVREF circuit powered down									
bit 6	CVROE: Comparator VREF Output Enable bit									
	1 = CVREF voltage level is output on CVREF pin									
	0 = CVREF voltage level is disconnected from CVREF pin									
bit 5	CVRR: Comparator VREF Range Selection bit									
	 1 = CVRSRC range should be 0 to 0.625 CVRSRC with CVRSRC/24 step size 0 = CVRSRC range should be 0.25 to 0.719 CVRSRC with CVRSRC/32 step size 									
		•			JVRSRC/32 ste	p size				
bit 4	CVRSS: Comparator VREF Source Selection bit									
	 1 = Comparator reference source CVRSRC = VREF+ – VREF- 0 = Comparator reference source CVRSRC = AVDD – AVSS 									
bit 3-0	CVR<3:0>: Comparator VREF Value Selection $0 \le \text{CVR3:CVR0} \le 15$ bits									
	When $CVRR = 1$:									
		 R<3:0>/24) ● (0	CVRSRC)							
	When CVRR		-							
	CVREF = 1/4									

REGISTER 24-1: CVRCON: COMPARATOR VOLTAGE REFERENCE CONTROL REGISTER

REGISTER 26-2: CW2: FLASH CONFIGURATION WORD 2 (CONTINUED)

- bit 4 **IOL1WAY:** IOLOCK One-Way Set Enable bit
 - 1 = The IOLOCK bit (OSCCON<6>)can be set once, provided the unlock sequence has been completed. Once set, the Peripheral Pin Select registers cannot be written to a second time.
 - 0 = The IOLOCK bit can be set and cleared as needed, provided the unlock sequence has been completed

bit 3 DISUVREG: Internal USB 3.3V Regulator Disable bit

- 1 = Regulator is disabled
- 0 = Regulator is enabled
- bit 2 Reserved: Always maintain as '1'
- bit 1-0 **POSCMD<1:0>:** Primary Oscillator Configuration bits
 - 11 = Primary Oscillator disabled
 - 10 = HS Oscillator mode selected
 - 01 = XT Oscillator mode selected
 - 00 = EC Oscillator mode selected

REGISTER 26-3: CW3: FLASH CONFIGURATION WORD 3

U-1	U-1	U-1	U-1	U-1	U-1	U-1	U-1			
—	—	—	—	—	—	—	—			
bit 23							bit 16			
R/PO-1	R/PO-1	R/PO-1	U-1	U-1	U-1	U-1	U-1			
WPEND	WPCFG	WPCFG WPDIS								
bit 15							bit 8			
	D (D 0 4	D / D 0_1	D (D 0, 4)	D / D 0_4	D / D 0_4	D / D 0_1				
R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1			
WPFP7	WPFP6	WPFP5	WPFP4	WPFP3	WPFP2	WPFP1	WPFP0			
bit 7							bit 0			
Legend:]			
R = Readable	a hit	PO = Prograr	n once hit		nented bit, read	las '0'				
	nen device is un	•		'1' = Bit is set		'0' = Bit is clea	ared			
		programmed		1 - Dit 13 Set			areu			
bit 23-16	Unimplement	ted: Read as '	1'							
bit 15	-		- otection End Pa	age Select bit						
	•			ary is at the bo	ttom of progra	m memory (00	0000h); upper			
	boundary	is the code pa	ige specified by	y WPFP<7:0>						
				ary is at the las	t page of progr	am memory; lo	ower boundary			
L:1 4 4			ed by WPFP<7		4 h:4					
bit 14		•	•	Protection Select		landa ana matin	a to a to d			
				ry) and Flash C ds are code pro		fords are not p	rolected			
bit 13			ection Disable	•	otootou					
211 10	•	ed code protec								
				; protected se	gment defined	by WPEND,	WPCFG and			
	WPFPx C	Configuration b	its							
bit 12-8	Unimplement	ted: Read as '	1'							
bit 7-0	WPFP<7:0>:	Protected Cod	e Segment Bo	undary Page bi	ts					
				ge that is the b	oundary of the	protected code	e segment,			
	•	•	ottom of progra	am memory.						
	$\frac{\text{If WPEND} = 1}{1}$		anda mana ia th		and of the access					
	If WPEND = '		soue page is th	e upper bound	ary of the segn					
			code page is th	e lower bounda	ary of the segm	ient.				
		5	. 0		. 0					

27.0 DEVELOPMENT SUPPORT

The PIC[®] microcontrollers and dsPIC[®] digital signal controllers are supported with a full range of software and hardware development tools:

- Integrated Development Environment
- MPLAB[®] IDE Software
- Compilers/Assemblers/Linkers
 - MPLAB C Compiler for Various Device Families
 - HI-TECH C for Various Device Families
 - MPASM[™] Assembler
 - MPLINK[™] Object Linker/ MPLIB[™] Object Librarian
 - MPLAB Assembler/Linker/Librarian for Various Device Families
- Simulators
 - MPLAB SIM Software Simulator
- Emulators
 - MPLAB REAL ICE™ In-Circuit Emulator
- In-Circuit Debuggers
 - MPLAB ICD 3
 - PICkit™ 3 Debug Express
- Device Programmers
 - PICkit[™] 2 Programmer
 - MPLAB PM3 Device Programmer
- Low-Cost Demonstration/Development Boards, Evaluation Kits, and Starter Kits

27.1 MPLAB Integrated Development Environment Software

The MPLAB IDE software brings an ease of software development previously unseen in the 8/16/32-bit microcontroller market. The MPLAB IDE is a Windows[®] operating system-based application that contains:

- A single graphical interface to all debugging tools
 - Simulator
 - Programmer (sold separately)
 - In-Circuit Emulator (sold separately)
 - In-Circuit Debugger (sold separately)
- A full-featured editor with color-coded context
- A multiple project manager
- Customizable data windows with direct edit of contents
- High-level source code debugging
- · Mouse over variable inspection
- Drag and drop variables from source to watch windows
- · Extensive on-line help
- Integration of select third party tools, such as IAR C Compilers

The MPLAB IDE allows you to:

- Edit your source files (either C or assembly)
- One-touch compile or assemble, and download to emulator and simulator tools (automatically updates all project information)
- Debug using:
 - Source files (C or assembly)
 - Mixed C and assembly
 - Machine code

MPLAB IDE supports multiple debugging tools in a single development paradigm, from the cost-effective simulators, through low-cost in-circuit debuggers, to full-featured emulators. This eliminates the learning curve when upgrading to tools with increased flexibility and power.

Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
ADD	ADD	f	f = f + WREG	1	1	C, DC, N, OV, Z
	ADD	f,WREG	WREG = f + WREG	1	1	C, DC, N, OV, Z
	ADD	#lit10,Wn	Wd = lit10 + Wd	1	1	C, DC, N, OV, Z
	ADD	Wb,Ws,Wd	Wd = Wb + Ws	1	1	C, DC, N, OV, Z
	ADD	Wb,#lit5,Wd	Wd = Wb + lit5	1	1	C, DC, N, OV, Z
ADDC	ADDC	f	f = f + WREG + (C)	1	1	C, DC, N, OV, Z
	ADDC	f,WREG	WREG = f + WREG + (C)	1	1	C, DC, N, OV, Z
	ADDC	#lit10,Wn	Wd = lit10 + Wd + (C)	1	1	C, DC, N, OV, Z
	ADDC	Wb,Ws,Wd	Wd = Wb + Ws + (C)	1	1	C, DC, N, OV, Z
	ADDC	Wb,#lit5,Wd	Wd = Wb + Iit5 + (C)	1	1	C, DC, N, OV, Z
AND	AND	f	f = f .AND. WREG	1	1	N, Z
	AND	f,WREG	WREG = f .AND. WREG	1	1	N, Z
	AND	#lit10,Wn	Wd = lit10 .AND. Wd	1	1	N, Z
	AND	Wb,Ws,Wd	Wd = Wb .AND. Ws	1	1	N, Z
	AND	Wb,#lit5,Wd	Wd = Wb .AND. lit5	1	1	N, Z
ASR	ASR	f	f = Arithmetic Right Shift f	1	1	C, N, OV, Z
	ASR	f,WREG	WREG = Arithmetic Right Shift f	1	1	C, N, OV, Z
	ASR	Ws,Wd	Wd = Arithmetic Right Shift Ws	1	1	C, N, OV, Z
	ASR	Wb,Wns,Wnd	Wnd = Arithmetic Right Shift Wb by Wns	1	1	N, Z
	ASR	Wb,#lit5,Wnd	Wnd = Arithmetic Right Shift Wb by lit5	1	1	N, Z
BCLR	BCLR	f,#bit4	Bit Clear f	1	1	None
Doni	BCLR	Ws,#bit4	Bit Clear Ws	1	1	None
BRA	BRA	C,Expr	Branch if Carry	1	1 (2)	None
	BRA	GE, Expr	Branch if Greater than or Equal	1	1 (2)	None
	BRA	GEU, Expr	Branch if Unsigned Greater than or Equal	1	1 (2)	None
	BRA	GT, Expr	Branch if Greater than	1	1 (2)	None
	BRA	GTU, Expr	Branch if Unsigned Greater than	1	1 (2)	None
	BRA	LE, Expr	Branch if Less than or Equal	1	1 (2)	None
	BRA	LEU, Expr	Branch if Unsigned Less than or Equal	1	1 (2)	None
	BRA	LT, Expr	Branch if Less than	1	1 (2)	None
	BRA	LTU, Expr	Branch if Unsigned Less than	1	1 (2)	None
	BRA	· · · · ·	Branch if Negative	1	1 (2)	None
		N, Expr	Branch if Not Carry	1	1 (2)	None
	BRA	NC, Expr	,		. ,	
	BRA	NN, Expr	Branch if Not Negative Branch if Not Overflow	1	1 (2)	None None
	BRA	NOV, Expr			1 (2)	
	BRA	NZ,Expr	Branch if Not Zero	1	1 (2)	None
	BRA	OV,Expr	Branch if Overflow	1	1 (2)	None
	BRA	Expr	Branch Unconditionally	1	2	None
	BRA	Z,Expr	Branch if Zero	1	1 (2)	None
	BRA	Wn	Computed Branch	1	2	None
BSET	BSET	f,#bit4	Bit Set f	1	1	None
	BSET	Ws,#bit4	Bit Set Ws	1	1	None
BSW	BSW.C	Ws,Wb	Write C bit to Ws <wb></wb>	1	1	None
	BSW.Z	Ws,Wb	Write Z bit to Ws <wb></wb>	1	1	None
BTG	BTG	f,#bit4	Bit Toggle f	1	1	None
	BTG	Ws,#bit4	Bit Toggle Ws	1	1	None
BTSC	BTSC	f,#bit4	Bit Test f, Skip if Clear	1	1 (2 or 3)	None
	BTSC	Ws,#bit4	Bit Test Ws, Skip if Clear	1	1 (2 or 3)	None

TABLE 28-2:	INSTRUCTION SET OVERVIEW

Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
GOTO	GOTO	Expr	Go to Address	2	2	None
	GOTO	Wn	Go to Indirect	1	2	None
INC	INC	f	f = f + 1	1	1	C, DC, N, OV, Z
	INC	f,WREG	WREG = f + 1	1	1	C, DC, N, OV, Z
	INC	Ws,Wd	Wd = Ws + 1	1	1	C, DC, N, OV, Z
INC2	INC2	f	f = f + 2	1	1	C, DC, N, OV, Z
	INC2	f,WREG	WREG = f + 2	1	1	C, DC, N, OV, Z
	INC2	Ws,Wd	Wd = Ws + 2	1	1	C, DC, N, OV, Z
IOR	IOR	f	f = f .IOR. WREG	1	1	N, Z
	IOR	f,WREG	WREG = f .IOR. WREG	1	1	N, Z
	IOR	#lit10,Wn	Wd = lit10 .IOR. Wd	1	1	N, Z
	IOR	Wb,Ws,Wd	Wd = Wb .IOR. Ws	1	1	N, Z
	IOR	Wb,#lit5,Wd	Wd = Wb .IOR. lit5	1	1	N, Z
LNK	LNK	#lit14	Link Frame Pointer	1	1	None
LSR	LSR	f	f = Logical Right Shift f	1	1	C, N, OV, Z
	LSR	f,WREG	WREG = Logical Right Shift f	1	1	C, N, OV, Z
	LSR	Ws,Wd	Wd = Logical Right Shift Ws	1	1	C, N, OV, Z
	LSR	Wb,Wns,Wnd	What = Logical Right Shift Wb by Whs	1	1	N, Z
	LSR	Wb,#lit5,Wnd	Wnd = Logical Right Shift Wb by lit5	1	1	N, Z
MOV	MOV	f,Wn	Move f to Wn	1	1	None
	MOV	[Wns+Slit10],Wnd	Move [Wns+Slit10] to Wnd	1	1	None
	MOV	f	Move f to f	1	1	N, Z
			Move f to WREG	1	1	
	MOV	f,WREG				N, Z
	MOV	#lit16,Wn	Move 16-bit Literal to Wn	1	1	None
	MOV.b	#lit8,Wn	Move 8-bit Literal to Wn	1	1	None
	MOV	Wn,f	Move Wn to f	1	1	None
	MOV	Wns,[Wns+Slit10]	Move Wns to [Wns+Slit10]	1	1	Next
	MOV	Wso,Wdo	Move Ws to Wd	1	1	None
	MOV	WREG, f	Move WREG to f	1	1	N, Z
	MOV.D	Wns,Wd	Move Double from W(ns):W(ns+1) to Wd	1	2	None
	MOV.D	Ws,Wnd	Move Double from Ws to W(nd+1):W(nd)	1	2	None
MUL	MUL.SS	Wb,Ws,Wnd	{Wnd+1, Wnd} = Signed(Wb) * Signed(Ws)	1	1	None
	MUL.SU	Wb,Ws,Wnd	{Wnd+1, Wnd} = Signed(Wb) * Unsigned(Ws)	1	1	None
	MUL.US	Wb,Ws,Wnd	{Wnd+1, Wnd} = Unsigned(Wb) * Signed(Ws)	1	1	None
	MUL.UU	Wb,Ws,Wnd	{Wnd+1, Wnd} = Unsigned(Wb) * Unsigned(Ws)	1	1	None
	MUL.SU	Wb,#lit5,Wnd	{Wnd+1, Wnd} = Signed(Wb) * Unsigned(lit5)	1	1	None
	MUL.UU	Wb,#lit5,Wnd	{Wnd+1, Wnd} = Unsigned(Wb) * Unsigned(lit5)	1	1	None
	MUL	f	W3:W2 = f * WREG	1	1	None
NEG	NEG	f	$f = \overline{f} + 1$	1	1	C, DC, N, OV, Z
	NEG	f,WREG	WREG = \overline{f} + 1	1	1	C, DC, N, OV, Z
	NEG	Ws,Wd	$Wd = \overline{Ws} + 1$	1	1	C, DC, N, OV, Z
NOP	NOP		No Operation	1	1	None
	NOPR		No Operation	1	1	None
POP	POP	f	Pop f from Top-of-Stack (TOS)	1	1	None
	POP	Wdo	Pop from Top-of-Stack (TOS) to Wdo	1	1	None
	POP.D	Wnd	Pop from Top-of-Stack (TOS) to W(nd):W(nd+1)	1	2	None
	POP.S		Pop Shadow Registers	1	1	All
PUSH	PUSH	f	Push f to Top-of-Stack (TOS)	1	1	None
	PUSH	Wso	Push Wso to Top-of-Stack (TOS)	1	1	None
	PUSH.D	Wns	Push W(ns):W(ns+1) to Top-of-Stack (TOS)	1	2	None
	PUSH.S	Gitn	Push Shadow Registers	1	1	None

TABLE 28-2: INSTRUCTION SET OVERVIEW (CONTINUED)