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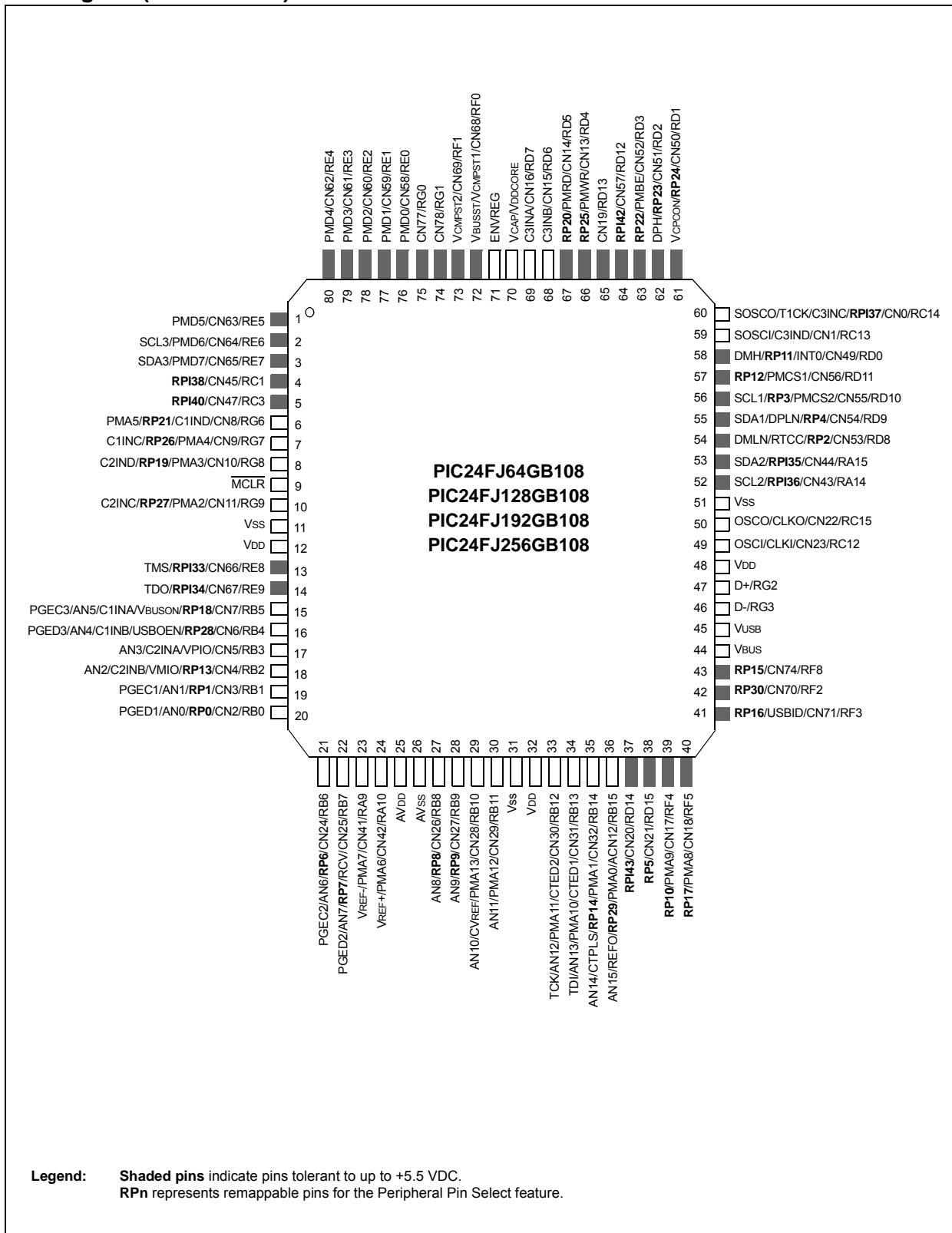
"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

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Details

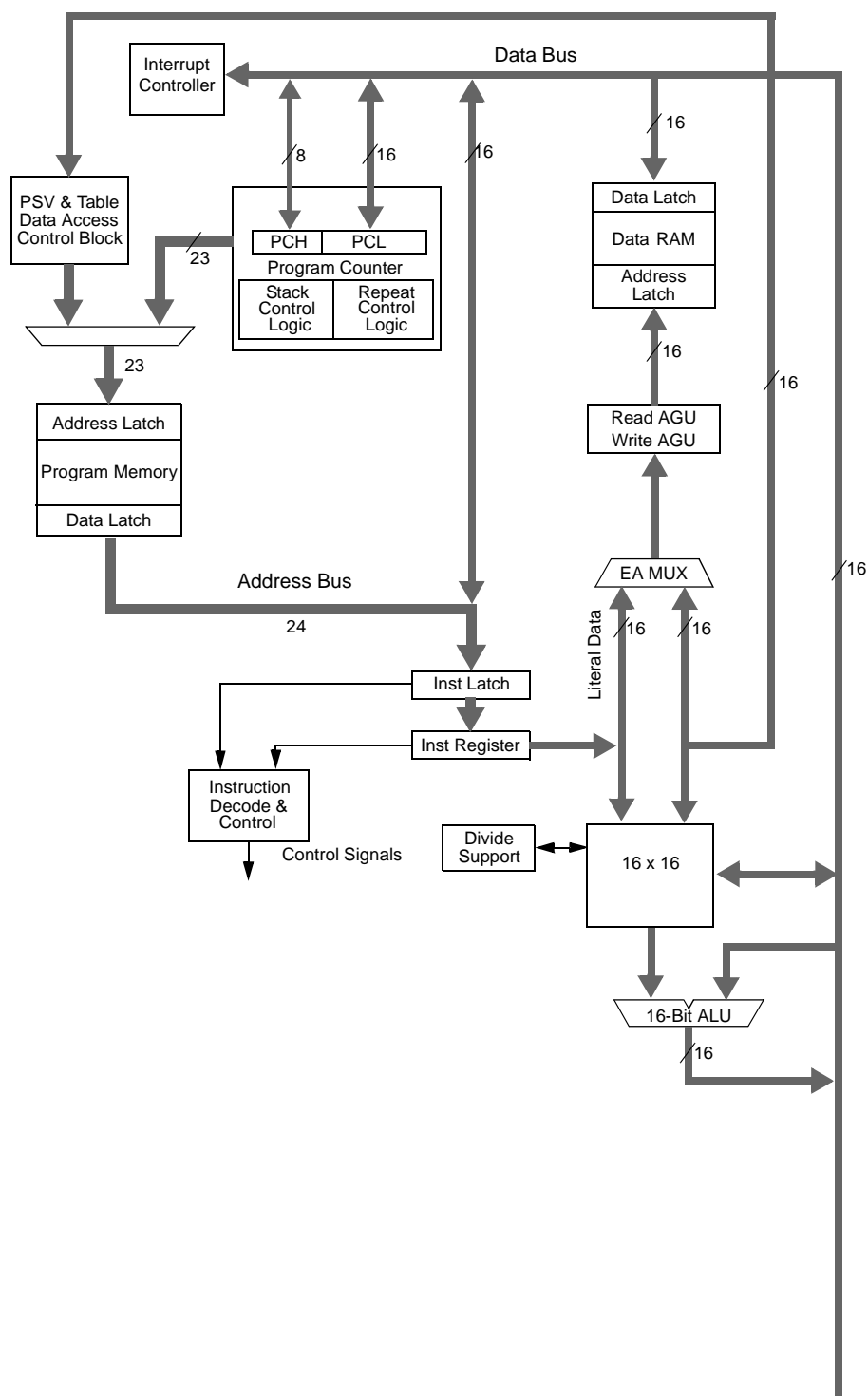
Product Status	Obsolete
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I ² C, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	83
Program Memory Size	128KB (43K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-TQFP
Supplier Device Package	100-TQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24fj128gb110t-i-pf

Pin Diagram (80-Pin TQFP)



PIC24FJ256GB110 FAMILY

FIGURE 1-1: PIC24FJ256GB110 FAMILY GENERAL BLOCK DIAGRAM



PIC24FJ256GB110 FAMILY

TABLE 1-4: PIC24FJ256GB110 FAMILY PINOUT DESCRIPTIONS

Function	Pin Number			I/O	Input Buffer	Description
	64-Pin TQFP, QFN	80-Pin TQFP	100-Pin TQFP			
AN0	16	20	25	I	ANA	A/D Analog Inputs.
AN1	15	19	24	I	ANA	
AN2	14	18	23	I	ANA	
AN3	13	17	22	I	ANA	
AN4	12	16	21	I	ANA	
AN5	11	15	20	I	ANA	
AN6	17	21	26	I	ANA	
AN7	18	22	27	I	ANA	
AN8	21	27	32	I	ANA	
AN9	22	28	33	I	ANA	
AN10	23	29	34	I	ANA	
AN11	24	30	35	I	ANA	
AN12	27	33	41	I	ANA	
AN13	28	34	42	I	ANA	
AN14	29	35	43	I	ANA	
AN15	30	36	44	I	ANA	
AVDD	19	25	30	P	—	Positive Supply for Analog modules.
AVSS	20	26	31	P	—	Ground Reference for Analog modules.
C1INA	11	15	20	I	ANA	Comparator 1 Input A.
C1INB	12	16	21	I	ANA	Comparator 1 Input B.
C1INC	5	7	11	I	ANA	Comparator 1 Input C.
C1IND	4	6	10	I	ANA	Comparator 1 Input D.
C2INA	13	17	22	I	ANA	Comparator 2 Input A.
C2INB	14	18	23	I	ANA	Comparator 2 Input B.
C2INC	8	10	14	I	ANA	Comparator 2 Input C.
C2IND	6	8	12	I	ANA	Comparator 2 Input D.
C3INA	55	69	84	I	ANA	Comparator 3 Input A.
C3INB	54	68	83	I	ANA	Comparator 3 Input B.
C3INC	48	60	74	I	ANA	Comparator 3 Input C.
C3IND	47	59	73	I	ANA	Comparator 3 Input D.
CLKI	39	49	63	I	ANA	Main Clock Input Connection.
CLKO	40	50	64	O	—	System Clock Output.

Legend: TTL = TTL input buffer
ANA = Analog level input/output

ST = Schmitt Trigger input buffer
I²C™ = I²C/SMBus input buffer

PIC24FJ256GB110 FAMILY

REGISTER 7-12: IEC1: INTERRUPT ENABLE CONTROL REGISTER 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
U2TXIE	U2RXIE	INT2IE ⁽¹⁾	T5IE	T4IE	OC4IE	OC3IE	—
bit 15							bit 8

R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
IC8IE	IC7IE	—	INT1IE ⁽¹⁾	CNIE	CMIE	MI2C1IE	SI2C1IE
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **U2TXIE:** UART2 Transmitter Interrupt Enable bit
 1 = Interrupt request enabled
 0 = Interrupt request not enabled
- bit 14 **U2RXIE:** UART2 Receiver Interrupt Enable bit
 1 = Interrupt request enabled
 0 = Interrupt request not enabled
- bit 13 **INT2IE:** External Interrupt 2 Enable bit⁽¹⁾
 1 = Interrupt request enabled
 0 = Interrupt request not enabled
- bit 12 **T5IE:** Timer5 Interrupt Enable bit
 1 = Interrupt request enabled
 0 = Interrupt request not enabled
- bit 11 **T4IE:** Timer4 Interrupt Enable bit
 1 = Interrupt request enabled
 0 = Interrupt request not enabled
- bit 10 **OC4IE:** Output Compare Channel 4 Interrupt Enable bit
 1 = Interrupt request enabled
 0 = Interrupt request not enabled
- bit 9 **OC3IE:** Output Compare Channel 3 Interrupt Enable bit
 1 = Interrupt request enabled
 0 = Interrupt request not enabled
- bit 8 **Unimplemented:** Read as '0'
- bit 7 **IC8IE:** Input Capture Channel 8 Interrupt Enable bit
 1 = Interrupt request enabled
 0 = Interrupt request not enabled
- bit 6 **IC7IE:** Input Capture Channel 7 Interrupt Enable bit
 1 = Interrupt request enabled
 0 = Interrupt request not enabled
- bit 5 **Unimplemented:** Read as '0'
- bit 4 **INT1IE:** External Interrupt 1 Enable bit⁽¹⁾
 1 = Interrupt request enabled
 0 = Interrupt request not enabled
- bit 3 **CNIE:** Input Change Notification Interrupt Enable bit
 1 = Interrupt request enabled
 0 = Interrupt request not enabled
- bit 2 **CMIE:** Comparator Interrupt Enable bit
 1 = Interrupt request enabled
 0 = Interrupt request not enabled

Note 1: If an external interrupt is enabled, the interrupt input must also be configured to an available RPN or RPI pin. See **Section 10.4 “Peripheral Pin Select”** for more information.

PIC24FJ256GB110 FAMILY

REGISTER 7-16: IEC5: INTERRUPT ENABLE CONTROL REGISTER 5

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	IC9IE	OC9IE	SPI3IE	SPF3IE	U4TXIE	U4RXIE
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
U4ERIE	USB1IE	MI2C3IE	SI2C3IE	U3TXIE	U3RXIE	U3ERIE	—
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13 **IC9IE:** Input Capture Channel 9 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled
- bit 12 **OC9IE:** Output Compare Channel 9 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled
- bit 11 **SPI3IE:** SPI3 Event Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled
- bit 10 **SPF3IE:** SPI3 Fault Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled
- bit 9 **U4TXIE:** UART4 Transmitter Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled
- bit 8 **U4RXIE:** UART4 Receiver Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled
- bit 7 **U4ERIE:** UART4 Error Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled
- bit 6 **USB1IE:** USB1 (USB OTG) Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled
- bit 5 **MI2C3IE:** Master I2C3 Event Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled
- bit 4 **SI2C3IE:** Slave I2C3 Event Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled
- bit 3 **U3TXIE:** UART3 Transmitter Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled
- bit 2 **U3RXIE:** UART3 Receiver Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled
- bit 1 **U3ERIE:** UART3 Error Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled
- bit 0 **Unimplemented:** Read as '0'

PIC24FJ256GB110 FAMILY

REGISTER 7-17: IPC0: INTERRUPT PRIORITY CONTROL REGISTER 0

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	T1IP2	T1IP1	T1IP0	—	OC1IP2	OC1IP1	OC1IP0
bit 15				bit 8			

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	IC1IP2	IC1IP1	IC1IP0	—	INT0IP2	INT0IP1	INT0IP0
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **Unimplemented:** Read as '0'
- bit 14-12 **T1IP<2:0>:** Timer1 Interrupt Priority bits
 111 = Interrupt is priority 7 (highest priority interrupt)
 •
 •
 •
 001 = Interrupt is priority 1
 000 = Interrupt source is disabled
- bit 11 **Unimplemented:** Read as '0'
- bit 10-8 **OC1IP<2:0>:** Output Compare Channel 1 Interrupt Priority bits
 111 = Interrupt is priority 7 (highest priority interrupt)
 •
 •
 •
 001 = Interrupt is priority 1
 000 = Interrupt source is disabled
- bit 7 **Unimplemented:** Read as '0'
- bit 6-4 **IC1IP<2:0>:** Input Capture Channel 1 Interrupt Priority bits
 111 = Interrupt is priority 7 (highest priority interrupt)
 •
 •
 •
 001 = Interrupt is priority 1
 000 = Interrupt source is disabled
- bit 3 **Unimplemented:** Read as '0'
- bit 2-0 **INT0IP<2:0>:** External Interrupt 0 Priority bits
 111 = Interrupt is priority 7 (highest priority interrupt)
 •
 •
 •
 001 = Interrupt is priority 1
 000 = Interrupt source is disabled

10.3 Input Change Notification

The input change notification function of the I/O ports allows the PIC24FJ256GB110 family of devices to generate interrupt requests to the processor in response to a Change-Of-State (COS) on selected input pins. This feature is capable of detecting input Change-Of-States even in Sleep mode, when the clocks are disabled. Depending on the device pin count, there are up to 81 external inputs that may be selected (enabled) for generating an interrupt request on a Change-Of-State.

Registers, CNEN1 through CNEN6, contain the interrupt enable control bits for each of the CN input pins. Setting any of these bits enables a CN interrupt for the corresponding pins.

Each CN pin has both a weak pull-up and a weak pull-down connected to it. The pull-ups act as a current source that is connected to the pin, while the pull-downs act as a current sink that is connected to the pin. These eliminate the need for external resistors when push button or keypad devices are connected. The pull-ups and pull-downs are separately enabled using the CNPU1 through CNPU6 registers (for pull-ups) and the CNPD1 through CNPD6 registers (for pull-downs). Each CN pin has individual control bits for its pull-up and pull-down. Setting a control bit enables the weak pull-up or pull-down for the corresponding pin.

When the internal pull-up is selected, the pin pulls up to $V_{DD} - 0.7V$ (typical). Make sure that there is no external pull-up source when the internal pull-ups are enabled, as the voltage difference can cause a current path.

Note: Pull-ups on change notification pins should always be disabled whenever the port pin is configured as a digital output.

10.4 Peripheral Pin Select

A major challenge in general purpose devices is providing the largest possible set of peripheral features while minimizing the conflict of features on I/O pins. In an application that needs to use more than one peripheral multiplexed on a single pin, inconvenient workarounds in application code or a complete redesign may be the only option.

The Peripheral Pin Select (PPS) feature provides an alternative to these choices by enabling the user's peripheral set selection and their placement on a wide range of I/O pins. By increasing the pinout options available on a particular device, users can better tailor the microcontroller to their entire application, rather than trimming the application to fit the device.

The Peripheral Pin Select feature operates over a fixed subset of digital I/O pins. Users may independently map the input and/or output of any one of many digital peripherals to any one of these I/O pins. Peripheral Pin Select is performed in software and generally does not require the device to be reprogrammed. Hardware safeguards are included that prevent accidental or spurious changes to the peripheral mapping once it has been established.

10.4.1 AVAILABLE PINS

The Peripheral Pin Select feature is used with a range of up to 44 pins, depending on the particular device and its pin count. Pins that support the Peripheral Pin Select feature include the designation, "RPn" or "RPI n", in their full pin designation, where "n" is the remappable pin number. "RP" is used to designate pins that support both remappable input and output functions, while "RPI" indicates pins that support remappable input functions only.

PIC24FJ256GB110 family devices support a larger number of remappable input only pins than remappable input/output pins. In this device family, there are up to 32 remappable input/output pins, depending on the pin count of the particular device selected; these are numbered, RP0 through RP31. Remappable input only pins are numbered above this range, from RPI32 to RPI43 (or the upper limit for that particular device).

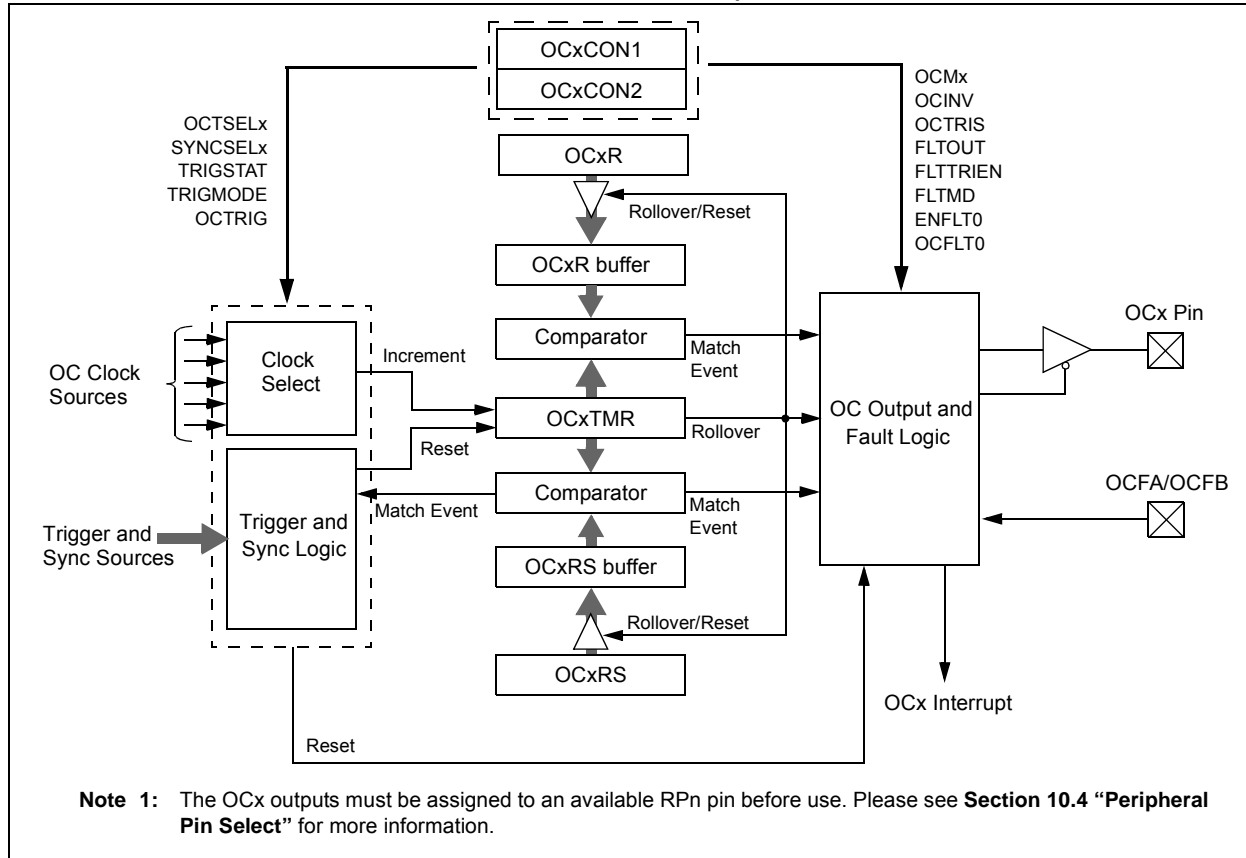
See Table 1-4 for a summary of pinout options in each package offering.

PIC24FJ256GB110 FAMILY

NOTES:

PIC24FJ256GB110 FAMILY

FIGURE 14-2: OUTPUT COMPARE BLOCK DIAGRAM (DOUBLE-BUFFERED, 16-BIT PWM MODE)



14.3.1 PWM PERIOD

The PWM period is specified by writing to PRy, the Timer Period register. The PWM period can be calculated using Equation 14-1.

EQUATION 14-1: CALCULATING THE PWM PERIOD⁽¹⁾

$$\text{PWM Period} = [(PRy) + 1] \cdot TCY \cdot (\text{Timer Prescale Value})$$

where: PWM Frequency = 1/[PWM Period]

Note 1: Based on $TCY = TOSC \cdot 2$, Doze mode and PLL are disabled.

Note: A PRy value of N will produce a PWM period of N + 1 time base count cycles. For example, a value of 7 written into the PRy register will yield a period consisting of 8 time base cycles.

14.3.2 PWM DUTY CYCLE

The PWM duty cycle is specified by writing to the OCxRS and OCxR registers. The OCxRS and OCxR registers can be written to at any time, but the duty cycle value is not latched until a match between PRy and TMRy occurs (i.e., the period is complete). This provides a double buffer for the PWM duty cycle and is essential for glitchless PWM operation.

Some important boundary parameters of the PWM duty cycle include:

- If OCxR, OCxRS, and PRy are all loaded with 0000h, the OCx pin will remain low (0% duty cycle).
- If OCxRS is greater than PRy, the pin will remain high (100% duty cycle).

See Example 14-1 for PWM mode timing details. Table 14-1 and Table 14-2 show example PWM frequencies and resolutions for a device operating at 4 MIPS and 10 MIPS, respectively.

PIC24FJ256GB110 FAMILY

REGISTER 14-2: OCxCON2: OUTPUT COMPARE x CONTROL REGISTER 2

bit 4-0 **SYNCSEL<4:0>**: Trigger/Synchronization Source Selection bits

11111 = This OC module⁽¹⁾
11110 = Input Capture 9⁽²⁾
11101 = Input Capture 6⁽²⁾
11100 = CTMU⁽²⁾
11011 = A/D⁽²⁾
11010 = Comparator 3⁽²⁾
11001 = Comparator 2⁽²⁾
11000 = Comparator 1⁽²⁾
10111 = Input Capture 4⁽²⁾
10110 = Input Capture 3⁽²⁾
10101 = Input Capture 2⁽²⁾
10100 = Input Capture 1⁽²⁾
10011 = Input Capture 8⁽²⁾
10010 = Input Capture 7⁽²⁾
1000x = reserved
01111 = Timer 5
01110 = Timer 4
01101 = Timer 3
01100 = Timer 2
01011 = Timer 1
01010 = Input Capture 5⁽²⁾
01001 = Output Compare 9⁽¹⁾
01000 = Output Compare 8⁽¹⁾
00111 = Output Compare 7⁽¹⁾
00110 = Output Compare 6⁽¹⁾
00101 = Output Compare 5⁽¹⁾
00100 = Output Compare 4⁽¹⁾
00011 = Output Compare 3⁽¹⁾
00010 = Output Compare 2⁽¹⁾
00001 = Output Compare 1⁽¹⁾
00000 = Not synchronized to any other module

Note 1: Never use an OC module as its own trigger source, either by selecting this mode or another equivalent SYNCSEL setting.

2: Use these inputs as trigger sources only and never as sync sources.

PIC24FJ256GB110 FAMILY

REGISTER 16-2: I2CxSTAT: I2Cx STATUS REGISTER

R-0, HSC	R-0, HSC	U-0	U-0	U-0	R/C-0, HS	R-0, HSC	R-0, HSC
ACKSTAT	TRSTAT	—	—	—	BCL	GCSTAT	ADD10
bit 15							bit 8

R/C-0, HS	R/C-0, HS	R-0, HSC	R/C-0, HSC	R/C-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC
IWCOL	I2COV	D \bar{A}	P	S	R \bar{W}	RBF	TBF
bit 7							bit 0

Legend:	C = Clearable bit	HS = Hardware Settable bit	HSC = Hardware Settable/Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15 **ACKSTAT:** Acknowledge Status bit
1 = NACK was detected last
0 = ACK was detected last
Hardware set or clear at end of Acknowledge.
- bit 14 **TRSTAT:** Transmit Status bit
(When operating as I²C master. Applicable to master transmit operation.)
1 = Master transmit is in progress (8 bits + ACK)
0 = Master transmit is not in progress
Hardware set at beginning of master transmission. Hardware clear at end of slave Acknowledge.
- bit 13-11 **Unimplemented:** Read as '0'
- bit 10 **BCL:** Master Bus Collision Detect bit
1 = A bus collision has been detected during a master operation
0 = No collision
Hardware set at detection of bus collision.
- bit 9 **GCSTAT:** General Call Status bit
1 = General call address was received
0 = General call address was not received
Hardware set when address matches general call address. Hardware clear at Stop detection.
- bit 8 **ADD10:** 10-Bit Address Status bit
1 = 10-bit address was matched
0 = 10-bit address was not matched
Hardware set at match of 2nd byte of matched 10-bit address. Hardware clear at Stop detection.
- bit 7 **IWCOL:** Write Collision Detect bit
1 = An attempt to write the I2CxTRN register failed because the I²C module is busy
0 = No collision
Hardware set at occurrence of write to I2CxTRN while busy (cleared by software).
- bit 6 **I2COV:** Receive Overflow Flag bit
1 = A byte was received while the I2CxRCV register is still holding the previous byte
0 = No overflow
Hardware set at attempt to transfer I2CxRSR to I2CxRCV (cleared by software).
- bit 5 **D \bar{A} :** Data/Address bit (when operating as I²C slave)
1 = Indicates that the last byte received was data
0 = Indicates that the last byte received was device address
Hardware clear at device address match. Hardware set by after transmission finishes, or by reception of slave byte.

PIC24FJ256GB110 FAMILY

REGISTER 17-2: UxSTA: UARTx STATUS AND CONTROL REGISTER

R/W-0	R/W-0	R/W-0	U-0	R/W-0 HC	R/W-0	R-0	R-1
UTXISEL1	UTXINV ⁽¹⁾	UTXISEL0	—	UTXBRK	UTXEN ⁽²⁾	UTXBF	TRMT
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R-1	R-0	R-0	R/C-0	R-0
URXISEL1	URXISEL0	ADDEN	RIDLE	PERR	FERR	OERR	URXDA
bit 7							bit 0

Legend:	C = Clearable bit	HC = Hardware Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared x = Bit is unknown

- bit 15,13 **UTXISEL<1:0>:** Transmission Interrupt Mode Selection bits
 11 = Reserved; do not use
 10 = Interrupt when a character is transferred to the Transmit Shift Register (TSR), and as a result, the transmit buffer becomes empty
 01 = Interrupt when the last character is shifted out of the Transmit Shift Register; all transmit operations are completed
 00 = Interrupt when a character is transferred to the Transmit Shift Register (this implies there is at least one character open in the transmit buffer)
- bit 14 **UTXINV:** IrDA[®] Encoder Transmit Polarity Inversion bit⁽¹⁾
IREN = 0:
 1 = UxTX Idle '0'
 0 = UxTX Idle '1'
IREN = 1:
 1 = UxTX Idle '1'
 0 = UxTX Idle '0'
- bit 12 **Unimplemented:** Read as '0'
- bit 11 **UTXBRK:** Transmit Break bit
 1 = Send Sync Break on next transmission – Start bit, followed by twelve '0' bits, followed by Stop bit; cleared by hardware upon completion
 0 = Sync Break transmission disabled or completed
- bit 10 **UTXEN:** Transmit Enable bit⁽²⁾
 1 = Transmit enabled, UxTX pin controlled by UARTx
 0 = Transmit disabled, any pending transmission is aborted and buffer is reset. UxTX pin controlled by port.
- bit 9 **UTXBF:** Transmit Buffer Full Status bit (read-only)
 1 = Transmit buffer is full
 0 = Transmit buffer is not full, at least one more character can be written
- bit 8 **TRMT:** Transmit Shift Register Empty bit (read-only)
 1 = Transmit Shift Register is empty and transmit buffer is empty (the last transmission has completed)
 0 = Transmit Shift Register is not empty, a transmission is in progress or queued
- bit 7-6 **URXISEL<1:0>:** Receive Interrupt Mode Selection bits
 11 = Interrupt is set on RSR transfer, making the receive buffer full (i.e., has 4 data characters)
 10 = Interrupt is set on RSR transfer, making the receive buffer 3/4 full (i.e., has 3 data characters)
 0x = Interrupt is set when any character is received and transferred from the RSR to the receive buffer. Receive buffer has one or more characters.

Note 1: Value of bit only affects the transmit properties of the module when the IrDA encoder is enabled (IREN = 1).

2: If UARTEN = 1, the peripheral inputs and outputs must be configured to an available RPN pin. See Section 10.4 “Peripheral Pin Select” for more information.

PIC24FJ256GB110 FAMILY

18.7.2 USB INTERRUPT REGISTERS

REGISTER 18-14: U1OTGIR: USB OTG INTERRUPT STATUS REGISTER (HOST MODE ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15						bit 8	

R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	U-0	R/K-0, HS
IDIF	T1MSECIF	LSTATEIF	ACTVIF	SESVDIF	SESENDIF	—	VBUSVDIF
bit 7						bit 0	

Legend:	U = Unimplemented bit, read as '0'		
R = Readable bit	K = Write '1' to clear bit	HS = Hardware Settable bit	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15-8 **Unimplemented:** Read as '0'
- bit 7 **IDIF:** ID State Change Indicator bit
 1 = Change in ID state detected
 0 = No ID state change
- bit 6 **T1MSECIF:** 1 Millisecond Timer bit
 1 = The 1 millisecond timer has expired
 0 = The 1 millisecond timer has not expired
- bit 5 **LSTATEIF:** Line State Stable Indicator bit
 1 = USB line state (as defined by the SE0 and JSTATE bits) has been stable for 1 ms, but different from last time
 0 = USB line state has not been stable for 1 ms
- bit 4 **ACTVIF:** Bus Activity Indicator bit
 1 = Activity on the D+/D- lines or VBUS detected
 0 = No activity on the D+/D- lines or VBUS detected
- bit 3 **SESVDIF:** Session Valid Change Indicator bit
 1 = VBUS has crossed VA_SESS_END (as defined in the USB OTG Specification)⁽¹⁾
 0 = VBUS has not crossed VA_SESS_END
- bit 2 **SESENDIF:** B-Device VBUS Change Indicator bit
 1 = VBUS change on B-device detected; VBUS has crossed VB_SESS_END (as defined in the USB OTG Specification)⁽¹⁾
 0 = VBUS has not crossed VA_SESS_END
- bit 1 **Unimplemented:** Read as '0'
- bit 0 **VBUSVDIF:** A-Device VBUS Change Indicator bit
 1 = VBUS change on A-device detected; VBUS has crossed VA_VBUS_VLD (as defined in the USB OTG Specification)⁽¹⁾
 0 = No VBUS change on A-device detected

Note 1: VBUS threshold crossings may be either rising or falling.

Note: Individual bits can only be cleared by writing a '1' to the bit position as part of a word write operation on the entire register. Using Boolean instructions or bitwise operations to write to a single bit position will cause all set bits at the moment of the write to become cleared.

PIC24FJ256GB110 FAMILY

REGISTER 18-16: U1IR: USB INTERRUPT STATUS REGISTER (DEVICE MODE ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/K-0, HS	U-0	R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	R-0	R/K-0, HS
STALLIF	—	RESUMEIF	IDLEIF	TRNIF	SOFIF	UERRIF	URSTIF
bit 7							bit 0

Legend:	U = Unimplemented bit, read as '0'		
R = Readable bit	K = Write '1' to clear bit	HS = Hardware Settable bit	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15-8 **Unimplemented:** Read as '0'
- bit 7 **STALLIF:** STALL Handshake Interrupt bit
 1 = A STALL handshake was sent by the peripheral during the handshake phase of the transaction in Device mode
 0 = A STALL handshake has not been sent
- bit 6 **Unimplemented:** Read as '0'
- bit 5 **RESUMEIF:** Resume Interrupt bit
 1 = A K-state is observed on the D+ or D- pin for 2.5 μ s (differential '1' for low speed, differential '0' for full speed)
 0 = No K-state observed
- bit 4 **IDLEIF:** Idle Detect Interrupt bit
 1 = Idle condition detected (constant Idle state of 3 ms or more)
 0 = No Idle condition detected
- bit 3 **TRNIF:** Token Processing Complete Interrupt bit
 1 = Processing of current token is complete; read U1STAT register for endpoint information
 0 = Processing of current token not complete; clear U1STAT register or load next token from STAT (clearing this bit causes the STAT FIFO to advance)
- bit 2 **SOFIF:** Start-Of-Frame Token Interrupt bit
 1 = A Start-Of-Frame token received by the peripheral or the Start-Of-Frame threshold reached by the host
 0 = No Start-Of-Frame token received or threshold reached
- bit 1 **UERRIF:** USB Error Condition Interrupt bit (read-only)
 1 = An unmasked error condition has occurred; only error states enabled in the U1EIE register can set this bit
 0 = No unmasked error condition has occurred
- bit 0 **URSTIF:** USB Reset Interrupt bit
 1 = Valid USB Reset has occurred for at least 2.5 μ s; Reset state must be cleared before this bit can be reasserted
 0 = No USB Reset has occurred. Individual bits can only be cleared by writing a '1' to the bit position as part of a word write operation on the entire register. Using Boolean instructions or bitwise operations to write to a single bit position will cause all set bits at the moment of the write to become cleared.

Note: Individual bits can only be cleared by writing a '1' to the bit position as part of a word write operation on the entire register. Using Boolean instructions or bitwise operations to write to a single bit position will cause all set bits at the moment of the write to become cleared.

PIC24FJ256GB110 FAMILY

18.7.4 USB V_{Bus} POWER CONTROL REGISTER

REGISTER 18-22: U1PWMCON: USB V_{Bus} PWM GENERATOR CONTROL REGISTER

R/W-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
PWMEN	—	—	—	—	—	PWMPOL	CNTEN
bit 15						bit 8	

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7						bit 0	

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **PWMEN:** PWM Enable bit
1 = PWM generator is enabled
0 = PWM generator is disabled; output is held in Reset state specified by PWMPOL
- bit 14-10 **Unimplemented:** Read as '0'
- bit 9 **PWMPOL:** PWM Polarity bit
1 = PWM output is active-low and resets high
0 = PWM output is active-high and resets low
- bit 8 **CNTEN:** PWM Counter Enable bit
1 = Counter is enabled
0 = Counter is disabled
- bit 7-0 **Unimplemented:** Read as '0'

PIC24FJ256GB110 FAMILY

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	0.40 BSC		
Contact Pad Spacing	C1		13.40	
Contact Pad Spacing	C2		13.40	
Contact Pad Width (X100)	X1			0.20
Contact Pad Length (X100)	Y1			1.50
Distance Between Pads	G	0.20		

BSC: Basic Dimension. Theoretically exact value shown with no tolerance.
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PIC24FJ256GB110 FAMILY

PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

	PIC	24	FJ	256	GB1	10	T	-	I	/	PT	-	XXX
Microchip Trademark	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Architecture	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Flash Memory Family	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Program Memory Size (KB)	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Product Group	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Pin Count	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Tape and Reel Flag (if applicable)	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Temperature Range	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Package	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Pattern	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____

Architecture	24	= 16-bit modified Harvard without DSP
Flash Memory Family	FJ	= Flash program memory
Product Group	GB1	= General purpose microcontrollers with USB On-The-Go
Pin Count	06	= 64-pin
	08	= 80-pin
	10	= 100-pin
Temperature Range	I	= -40°C to +85°C (Industrial)
Package	PF	= 100-lead (14x14x1 mm) TQFP (Thin Quad Flatpack)
	PT	= 64-lead, 80-lead, 100-lead (12x12x1 mm) TQFP (Thin Quad Flatpack)
	MR	= 64-lead (9x9x0.9 mm) QFN (Quad Flatpack No Leads)
Pattern		Three-digit QTP, SQTP, Code or Special Requirements (blank otherwise)
	ES	= Engineering Sample

Examples:
a) PIC24FJ64GB106-I/PT:
PIC24F device with USB On-The-Go, 64-Kbyte program memory, 64-pin, Industrial temp., TQFP package.
b) PIC24FJ256GB110-I/PT:
PIC24F device with USB On-The-Go, 256-Kbyte program memory, 100-pin, Industrial temp., TQFP package.