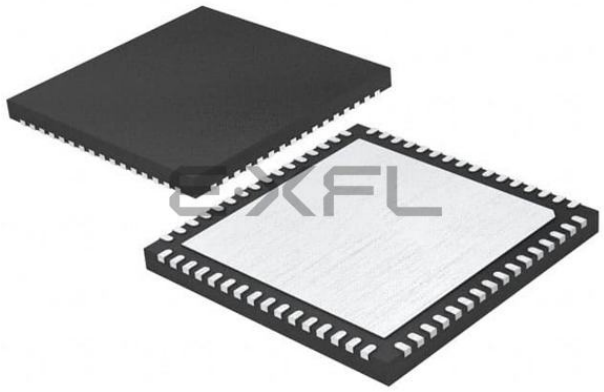

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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I²C, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	51
Program Memory Size	192KB (65.5K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-VQFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24fj192gb106-i-mr

TABLE 1-4: PIC24FJ256GB110 FAMILY PINOUT DESCRIPTIONS (CONTINUED)

Function	Pin Number			I/O	Input Buffer	Description
	64-Pin TQFP, QFN	80-Pin TQFP	100-Pin TQFP			
CN43	—	52	66	I	ST	Interrupt-on-Change Inputs.
CN44	—	53	67	I	ST	
CN45	—	4	6	I	ST	
CN46	—	—	7	I	ST	
CN47	—	5	8	I	ST	
CN48	—	—	9	I	ST	
CN49	46	58	72	I	ST	
CN50	49	61	76	I	ST	
CN51	50	62	77	I	ST	
CN52	51	63	78	I	ST	
CN53	42	54	68	I	ST	
CN54	43	55	69	I	ST	
CN55	44	56	70	I	ST	
CN56	45	57	71	I	ST	
CN57	—	64	79	I	ST	
CN58	60	76	93	I	ST	
CN59	61	77	94	I	ST	
CN60	62	78	98	I	ST	
CN61	63	79	99	I	ST	
CN62	64	80	100	I	ST	
CN63	1	1	3	I	ST	
CN64	2	2	4	I	ST	
CN65	3	3	5	I	ST	
CN66	—	13	18	I	ST	
CN67	—	14	19	I	ST	
CN68	58	72	87	I	ST	
CN69	59	73	88	I	ST	
CN70	—	42	52	I	ST	
CN71	33	41	51	I	ST	
CN74	—	43	53	I	ST	
CN75	—	—	40	I	ST	
CN76	—	—	39	I	ST	
CN77	—	75	90	I	ST	
CN78	—	74	89	I	ST	
CN79	—	—	96	I	ST	
CN80	—	—	97	I	ST	
CN81	—	—	95	I	ST	
CN82	—	—	1	I	ST	
CTED1	28	34	42	I	ANA	CTMU External Edge Input 1.
CTED2	27	33	41	I	ANA	CTMU External Edge Input 2.
CTPLS	29	35	43	O	—	CTMU Pulse Output.
CVREF	23	29	34	O	—	Comparator Voltage Reference Output.

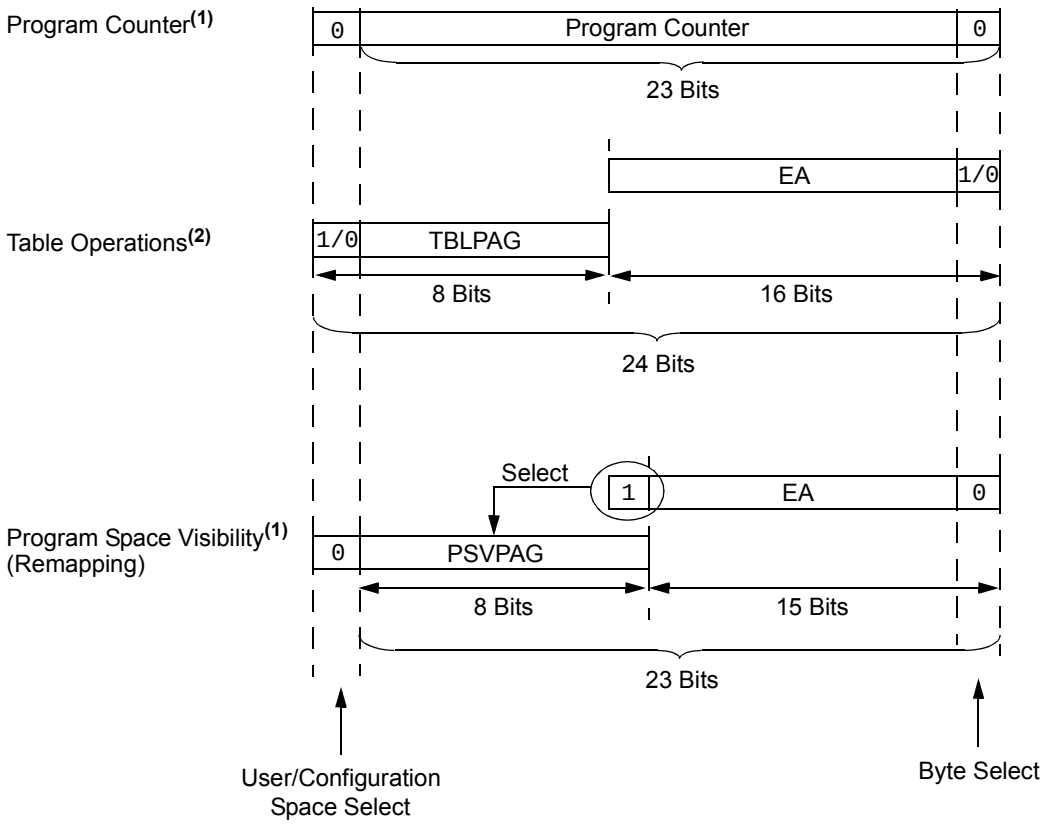
Legend: TTL = TTL input buffer
ANA = Analog level input/output
ST = Schmitt Trigger input buffer
I^2C™ = I^2C/SMBus input buffer

TABLE 4-31: PROGRAM SPACE ADDRESS CONSTRUCTION

Access Type	Access Space	Program Space Address				
		<23>	<22:16>	<15>	<14:1>	<0>
Instruction Access (Code Execution)	User	0	PC<22:1>			0
		0xx xxxx xxxx xxxx xxxx xxx0				
TBLRD/TBLWT (Byte/Word Read/Write)	User	TBLPAG<7:0>		Data EA<15:0>		
		0xxx xxxx		xxxx xxxx xxxx xxxx		
	Configuration	TBLPAG<7:0>		Data EA<15:0>		
		1xxx xxxx		xxxx xxxx xxxx xxxx		
Program Space Visibility (Block Remap/Read)	User	0	PSVPAG<7:0>		Data EA<14:0>(1)	
		0	xxxx xxxx		xxx xxxx xxxx xxxx	

Note 1: Data EA<15> is always '1' in this case, but is not used in calculating the program space address. Bit 15 of the address is PSVPAG<0>.

FIGURE 4-5: DATA ACCESS FROM PROGRAM SPACE ADDRESS GENERATION



Note 1: The LSb of program space addresses is always fixed as '0' in order to maintain word alignment of data in the program and data spaces.

2: Table operations are not required to be word-aligned. Table read operations are permitted in the configuration memory space.

5.6.2 PROGRAMMING A SINGLE WORD OF FLASH PROGRAM MEMORY

If a Flash location has been erased, it can be programmed using table write instructions to write an instruction word (24-bit) into the write latch. The TBLPAG register is loaded with the 8 Most Significant Bytes of the Flash address. The TBLWTL and TBLWTH instructions write the desired data into the write latches and specify the lower 16 bits of the program memory address to write to. To configure the NVMCON register for a word write, set the NVMOP bits (NVMCON<3:0>) to '0011'. The write is performed by executing the unlock sequence and setting the WR bit, as shown in Example 5-7. An equivalent procedure in C, using the MPLAB C30 compiler and built-in hardware functions, is shown in Example 5-8.

EXAMPLE 5-7: PROGRAMMING A SINGLE WORD OF FLASH PROGRAM MEMORY (ASSEMBLY LANGUAGE CODE)

```
; Setup a pointer to data Program Memory
    MOV     #tblpage(PROG_ADDR), W0       ;
    MOV     W0, TBLPAG                    ;Initialize PM Page Boundary SFR
    MOV     #tbloffset(PROG_ADDR), W0     ;Initialize a register with program memory address

    MOV     #LOW_WORD, W2                 ;
    MOV     #HIGH_BYTE, W3                ;
    TBLWTL  W2, [W0]                      ; Write PM low word into program latch
    TBLWTH  W3, [W0++]                    ; Write PM high byte into program latch

; Setup NVMCON for programming one word to data Program Memory
    MOV     #0x4003, W0                   ;
    MOV     W0, NVMCON                    ; Set NVMOP bits to 0011

    DISI    #5                            ; Disable interrupts while the KEY sequence is written
    MOV     #0x55, W0                     ; Write the key sequence
    MOV     W0, NVMKEY
    MOV     #0xAA, W0
    MOV     W0, NVMKEY
    BSET    NVMCON, #WR                   ; Start the write cycle
    NOP                                   ; Insert two NOPs after the erase
    NOP                                   ; Command is asserted
```

EXAMPLE 5-8: PROGRAMMING A SINGLE WORD OF FLASH PROGRAM MEMORY (C LANGUAGE CODE)

```
// C example using MPLAB C30

    unsigned int offset;
    unsigned long progAddr = 0xXXXXXX;          // Address of word to program
    unsigned int progDataL = 0xXXXX;            // Data to program lower word
    unsigned char progDataH = 0xXX;             // Data to program upper byte

//Set up NVMCON for word programming
    NVMCON = 0x4003;                            // Initialize NVMCON

//Set up pointer to the first memory location to be written
    TBLPAG = progAddr>>16;                      // Initialize PM Page Boundary SFR
    offset = progAddr & 0xFFFF;                 // Initialize lower word of address

//Perform TBLWT instructions to write latches
       __builtin_tblwtl(offset, progDataL);     // Write to address low word
       __builtin_tblwth(offset, progDataH);     // Write to upper byte
       asm("DISI #5");                          // Block interrupts with priority < 7
                                                // for next 5 instructions
       __builtin_write_NVM();                   // C30 function to perform unlock
                                                // sequence and set WR
```

NOTES:

7.0 INTERRUPT CONTROLLER

Note:	This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, **Section 8. "Interrupts"** (DS39707).

The PIC24F interrupt controller reduces the numerous peripheral interrupt request signals to a single interrupt request signal to the PIC24F CPU. It has the following features:

- Up to 8 processor exceptions and software traps
- 7 user-selectable priority levels
- Interrupt Vector Table (IVT) with up to 118 vectors
- A unique vector for each interrupt or exception source
- Fixed priority within a specified user priority level
- Alternate Interrupt Vector Table (AIVT) for debug support
- Fixed interrupt entry and return latencies

7.1 Interrupt Vector Table

The Interrupt Vector Table (IVT) is shown in Figure 7-1. The IVT resides in program memory, starting at location 000004h. The IVT contains 126 vectors, consisting of 8 non-maskable trap vectors, plus up to 118 sources of interrupt. In general, each interrupt source has its own vector. Each interrupt vector contains a 24-bit wide address. The value programmed into each interrupt vector location is the starting address of the associated Interrupt Service Routine (ISR).

Interrupt vectors are prioritized in terms of their natural priority; this is linked to their position in the vector table. All other things being equal, lower addresses have a higher natural priority. For example, the interrupt associated with vector 0 will take priority over interrupts at any other vector address.

PIC24FJ256GB110 family devices implement non-maskable traps and unique interrupts. These are summarized in Table 7-1 and Table 7-2.

7.1.1 ALTERNATE INTERRUPT VECTOR TABLE

The Alternate Interrupt Vector Table (AIVT) is located after the IVT, as shown in Figure 7-1. Access to the AIVT is provided by the ALTIVT control bit (INTCON2<15>). If the ALTIVT bit is set, all interrupt and exception processes will use the alternate vectors instead of the default vectors. The alternate vectors are organized in the same manner as the default vectors.

The AIVT supports emulation and debugging efforts by providing a means to switch between an application and a support environment without requiring the interrupt vectors to be reprogrammed. This feature also enables switching between applications for evaluation of different software algorithms at run time. If the AIVT is not needed, the AIVT should be programmed with the same addresses used in the IVT.

7.2 Reset Sequence

A device Reset is not a true exception because the interrupt controller is not involved in the Reset process. The PIC24F devices clear their registers in response to a Reset which forces the PC to zero. The microcontroller then begins program execution at location 000000h. The user programs a GOTO instruction at the Reset address, which redirects program execution to the appropriate start-up routine.

Note:	Any unimplemented or unused vector locations in the IVT and AIVT should be programmed with the address of a default interrupt handler routine that contains a RESET instruction.

REGISTER 7-20: IPC3: INTERRUPT PRIORITY CONTROL REGISTER 3

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	AD1IP2	AD1IP1	AD1IP0	—	U1TXIP2	U1TXIP1	U1TXIP0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-7 **Unimplemented:** Read as ‘0’

bit 6-4 **AD1IP<2:0>:** A/D Conversion Complete Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as ‘0’

bit 2-0 **U1TXIP<2:0>:** UART1 Transmitter Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

REGISTER 7-27: IPC10: INTERRUPT PRIORITY CONTROL REGISTER 10

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	OC7IP2	OC7IP1	OC7IP0	—	OC6IP2	OC6IP1	OC6IP0
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	OC5IP2	OC5IP1	OC5IP0	—	IC6IP2	IC6IP1	IC6IP0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15 **Unimplemented:** Read as ‘0’

bit 14-12 **OC7IP<2:0>:** Output Compare Channel 7 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as ‘0’

bit 10-8 **OC6IP<2:0>:** Output Compare Channel 6 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as ‘0’

bit 6-4 **OC5IP<2:0>:** Output Compare Channel 5 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as ‘0’

bit 2-0 **IC6IP<2:0>:** Input Capture Channel 6 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

REGISTER 10-5: RPINR4: PERIPHERAL PIN SELECT INPUT REGISTER 4

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	T5CKR5	T5CKR4	T5CKR3	T5CKR2	T5CKR1	T5CKR0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	T4CKR5	T4CKR4	T4CKR3	T4CKR2	T4CKR1	T4CKR0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as ‘0’

bit 13-8 **T5CKR<5:0>:** Assign Timer5 External Clock (T5CK) to Corresponding RPn or RPIn Pin bits

bit 7-6 **Unimplemented:** Read as ‘0’

bit 5-0 **T4CKR<5:0>:** Assign Timer4 External Clock (T4CK) to Corresponding RPn or RPIn Pin bits

REGISTER 10-6: RPINR7: PERIPHERAL PIN SELECT INPUT REGISTER 7

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	IC2R5	IC2R4	IC2R3	IC2R2	IC2R1	IC2R0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	IC1R5	IC1R4	IC1R3	IC1R2	IC1R1	IC1R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as ‘0’

bit 13-8 **IC2R<5:0>:** Assign Input Capture 2 (IC2) to Corresponding RPn or RPIn Pin bits

bit 7-6 **Unimplemented:** Read as ‘0’

bit 5-0 **IC1R<5:0>:** Assign Input Capture 1 (IC1) to Corresponding RPn or RPIn Pin bits

REGISTER 10-9: RPINR10: PERIPHERAL PIN SELECT INPUT REGISTER 10

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	IC8R5	IC8R4	IC8R3	IC8R2	IC8R1	IC8R0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	IC7R5	IC7R4	IC7R3	IC7R2	IC7R1	IC7R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as ‘0’

bit 13-8 **IC8R<5:0>:** Assign Input Capture 8 (IC8) to Corresponding RPn or RPIn Pin bits

bit 7-6 **Unimplemented:** Read as ‘0’

bit 5-0 **IC7R<5:0>:** Assign Input Capture 7 (IC7) to Corresponding RPn or RPIn Pin bits

REGISTER 10-10: RPINR11: PERIPHERAL PIN SELECT INPUT REGISTER 11

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	OCFBR5	OCFBR4	OCFBR3	OCFBR2	OCFBR1	OCFBR0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	OCFAR5	OCFAR4	OCFAR3	OCFAR2	OCFAR1	OCFAR0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as ‘0’

bit 13-8 **OCFBR<5:0>:** Assign Output Compare Fault B (OCFB) to Corresponding RPn or RPIn Pin bits

bit 7-6 **Unimplemented:** Read as ‘0’

bit 5-0 **OCFAR<5:0>:** Assign Output Compare Fault A (OCFA) to Corresponding RPn or RPIn Pin bits

REGISTER 12-2: TyCON: TIMER3 AND TIMER5 CONTROL REGISTER(3)

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
TON(1)	—	TSIDL(1)	—	—	—	—	—
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	U-0
—	TGATE(1)	TCKPS1(1)	TCKPS0(1)	—	—	TCS(1,2)	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **TON:** Timery On bit(1)
1 = Starts 16-bit Timery
0 = Stops 16-bit Timery

bit 14 **Unimplemented:** Read as '0'

bit 13 **TSIDL:** Stop in Idle Mode bit(1)
1 = Discontinue module operation when device enters Idle mode
0 = Continue module operation in Idle mode

bit 12-7 **Unimplemented:** Read as '0'

bit 6 **TGATE:** Timery Gated Time Accumulation Enable bit(1)
When TCS = 1:
This bit is ignored.
When TCS = 0:
1 = Gated time accumulation enabled
0 = Gated time accumulation disabled

bit 5-4 **TCKPS<1:0>:** Timery Input Clock Prescale Select bits(1)
11 = 1:256
10 = 1:64
01 = 1:8
00 = 1:1

bit 3-2 **Unimplemented:** Read as '0'

bit 1 **TCS:** Timery Clock Source Select bit(1,2)
1 = External clock from pin TyCK (on the rising edge)
0 = Internal clock (FOSC/2)

bit 0 **Unimplemented:** Read as '0'

Note 1: When 32-bit operation is enabled (T2CON<3> or T4CON<3> = 1), these bits have no effect on Timery operation; all timer functions are set through T2CON and T4CON.

2: If TCS = 1, RPINRx (TxCK) must be configured to an available RPn pin. See **Section 10.4 "Peripheral Pin Select"** for more information.

3: Changing the value of TyCON while the timer is running (TON = 1) causes the timer prescale counter to reset and is not recommended.

NOTES:

REGISTER 17-1: UxMODE: UARTx MODE REGISTER

R/W-0	U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
UARTEN(1)	—	USIDL	IREN(2)	RTSMD	—	UEN1	UEN0
bit 15							bit 8

R/C-0, HC	R/W-0	R/W-0, HC	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
WAKE	LPBACK	ABAUD	RXINV	BRGH	PDSEL1	PDSEL0	STSEL
bit 7							bit 0

Legend:	C = Clearable bit	HC = Hardware Clearable bit	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **UARTEN:** UARTx Enable bit(1)
- 1 = UARTx is enabled; all UARTx pins are controlled by UARTx as defined by UEN<1:0>
- 0 = UARTx is disabled; all UARTx pins are controlled by PORT latches; UARTx power consumption minimal

bit 14 **Unimplemented:** Read as '0'

bit 13 **USIDL:** Stop in Idle Mode bit
- 1 = Discontinue module operation when device enters Idle mode
- 0 = Continue module operation in Idle mode

bit 12 **IREN:** IrDA® Encoder and Decoder Enable bit(2)
- 1 = IrDA encoder and decoder enabled
- 0 = IrDA encoder and decoder disabled

bit 11 **RTSMD:** Mode Selection for $\overline{\text{UxRTS}}$ Pin bit
- 1 = $\overline{\text{UxRTS}}$ pin in Simplex mode
- 0 = $\overline{\text{UxRTS}}$ pin in Flow Control mode

bit 10 **Unimplemented:** Read as '0'

bit 9-8 **UEN1:UEN0:** UARTx Enable bits
- 11 = UxTX, UxRX and BCLKx pins are enabled and used; $\overline{\text{UxCTS}}$ pin controlled by port latches
- 10 = UxTX, UxRX, $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$ pins are enabled and used
- 01 = UxTX, UxRX and $\overline{\text{UxRTS}}$ pins are enabled and used; $\overline{\text{UxCTS}}$ pin controlled by port latches
- 00 = UxTX and UxRX pins are enabled and used; $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$/BCLKx pins controlled by port latches

bit 7 **WAKE:** Wake-up on Start Bit Detect During Sleep Mode Enable bit
- 1 = UARTx will continue to sample the UxRX pin; interrupt generated on falling edge, bit cleared in hardware on following rising edge
- 0 = No wake-up enabled

bit 6 **LPBACK:** UARTx Loopback Mode Select bit
- 1 = Enable Loopback mode
- 0 = Loopback mode is disabled

bit 5 **ABAUD:** Auto-Baud Enable bit
- 1 = Enable baud rate measurement on the next character – requires reception of a Sync field (55h); cleared in hardware upon completion
- 0 = Baud rate measurement disabled or completed

Note 1: If UARTEN = 1, the peripheral inputs and outputs must be configured to an available RPn pin. See **Section 10.4 "Peripheral Pin Select"** for more information.

2: This feature is only available for the 16x BRG mode (BRGH = 0).

REGISTER 17-2: UxSTA: UARTx STATUS AND CONTROL REGISTER (CONTINUED)

bit 5 **ADDEN:** Address Character Detect bit (bit 8 of received data = 1)
1 = Address Detect mode enabled. If 9-bit mode is not selected, this does not take effect.
0 = Address Detect mode disabled

bit 4 **RIDLE:** Receiver Idle bit (read-only)
1 = Receiver is Idle
0 = Receiver is active

bit 3 **PERR:** Parity Error Status bit (read-only)
1 = Parity error has been detected for the current character (character at the top of the receive FIFO)
0 = Parity error has not been detected

bit 2 **FERR:** Framing Error Status bit (read-only)
1 = Framing error has been detected for the current character (character at the top of the receive FIFO)
0 = Framing error has not been detected

bit 1 **OERR:** Receive Buffer Overrun Error Status bit (clear/read-only)
1 = Receive buffer has overflowed
0 = Receive buffer has not overflowed (clearing a previously set OERR bit (1 → 0 transition) will reset the receiver buffer and the RSR to the empty state

bit 0 **URXDA:** Receive Buffer Data Available bit (read-only)
1 = Receive buffer has data, at least one more character can be read
0 = Receive buffer is empty

Note 1: Value of bit only affects the transmit properties of the module when the IrDA encoder is enabled (IREN = 1).

2: If UARTEN = 1, the peripheral inputs and outputs must be configured to an available RPn pin. See **Section 10.4 "Peripheral Pin Select"** for more information.

REGISTER 18-5: U1PWRC: USB POWER CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0, HS	U-0	U-0	R/W-0	U-0	U-0	R/W-0, HC	R/W-0
UACTPND	—	—	USLPGRD	—	—	USUSPND	USBPWR
bit 7							bit 0

Legend:	HS = Hardware Settable bit	HC = Hardware Clearable bit	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7 **UACTPND:** USB Activity Pending bit
1 = Module should not be suspended at the moment (requires USLPGRD bit to be set)
0 = Module may be suspended or powered down

bit 6-5 **Unimplemented:** Read as '0'

bit 4 **USLPGRD:** Sleep/Suspend Guard bit
1 = Indicate to the USB module that it is about to be suspended or powered down
0 = No suspend

bit 3-2 **Unimplemented:** Read as '0'

bit 1 **USUSPND:** USB Suspend Mode Enable bit
1 = USB OTG module is in Suspend mode; USB clock is gated and the transceiver is placed in a low-power state
0 = Normal USB OTG operation

bit 0 **USBPWR:** USB Operation Enable bit
1 = USB OTG module is enabled
0 = USB OTG module is disabled(1)

Note 1: Do not clear this bit unless the HOSTEN, USBEN and OTGEN bits (U1CON<3,0> and U1OTGCON<2>) are all cleared.

REGISTER 19-1: PMCON: PARALLEL PORT CONTROL REGISTER

R/W-0	U-0	R/W-0	R/W-0(1)	R/W-0(1)	R/W-0	R/W-0	R/W-0
PMPEN	—	PSIDL	ADRMUX1	ADRMUX0	PTBEEN	PTWREN	PTRDEN
bit 15							bit 8

R/W-0	R/W-0	R/W-0(1)	R/W-0(1)	R/W-0(1)	R/W-0	R/W-0	R/W-0
CSF1	CSF0	ALP	CS2P	CS1P	BEP	WRSP	RDSP
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **PMPEN:** Parallel Master Port Enable bit
1 = PMP enabled
0 = PMP disabled, no off-chip access performed

bit 14 **Unimplemented:** Read as '0'

bit 13 **PSIDL:** Stop in Idle Mode bit
1 = Discontinue module operation when device enters Idle mode
0 = Continue module operation in Idle mode

bit 12-11 **ADRMUX<1:0>:** Address/Data Multiplexing Selection bits(1)
11 = Reserved
10 = All 16 bits of address are multiplexed on PMD<7:0> pins
01 = Lower 8 bits of address are multiplexed on PMD<7:0> pins, upper 3 bits are multiplexed on PMA<10:8>
00 = Address and data appear on separate pins

bit 10 **PTBEEN:** Byte Enable Port Enable bit (16-Bit Master mode)
1 = PMBE port enabled
0 = PMBE port disabled

bit 9 **PTWREN:** Write Enable Strobe Port Enable bit
1 = PMWR/PMENB port enabled
0 = PMWR/PMENB port disabled

bit 8 **PTRDEN:** Read/Write Strobe Port Enable bit
1 = PMRD/$\overline{\text{PMWR}}$ port enabled
0 = PMRD/$\overline{\text{PMWR}}$ port disabled

bit 7-6 **CSF1:CSF0:** Chip Select Function bits
11 = Reserved
10 = PMCS1 and PMCS2 function as chip select
01 = PMCS2 functions as chip select, PMCS1 functions as address bit 14
00 = PMCS1 and PMCS2 function as address bits 15 and 14

bit 5 **ALP:** Address Latch Polarity bit(1)
1 = Active-high ($\overline{\text{PMALL}}$ and $\overline{\text{PMALH}}$)
0 = Active-low (PMALL and PMALH)

bit 4 **CS2P:** Chip Select 2 Polarity bit(1)
1 = Active-high ($\overline{\text{PMCS2}}$/PMCS2)
0 = Active-low (PMCS2/$\overline{\text{PMCS2}}$)

bit 3 **CS1P:** Chip Select 1 Polarity bit(1)
1 = Active-high ($\overline{\text{PMCS1}}$/PMCS1)
0 = Active-low (PMCS1/$\overline{\text{PMCS1}}$)

Note 1: These bits have no effect when their corresponding pins are used as address lines.

20.0 REAL-TIME CLOCK AND CALENDAR (RTCC)

Note:	This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, **Section 29. "Real-Time Clock and Calendar (RTCC)"** (DS39696).

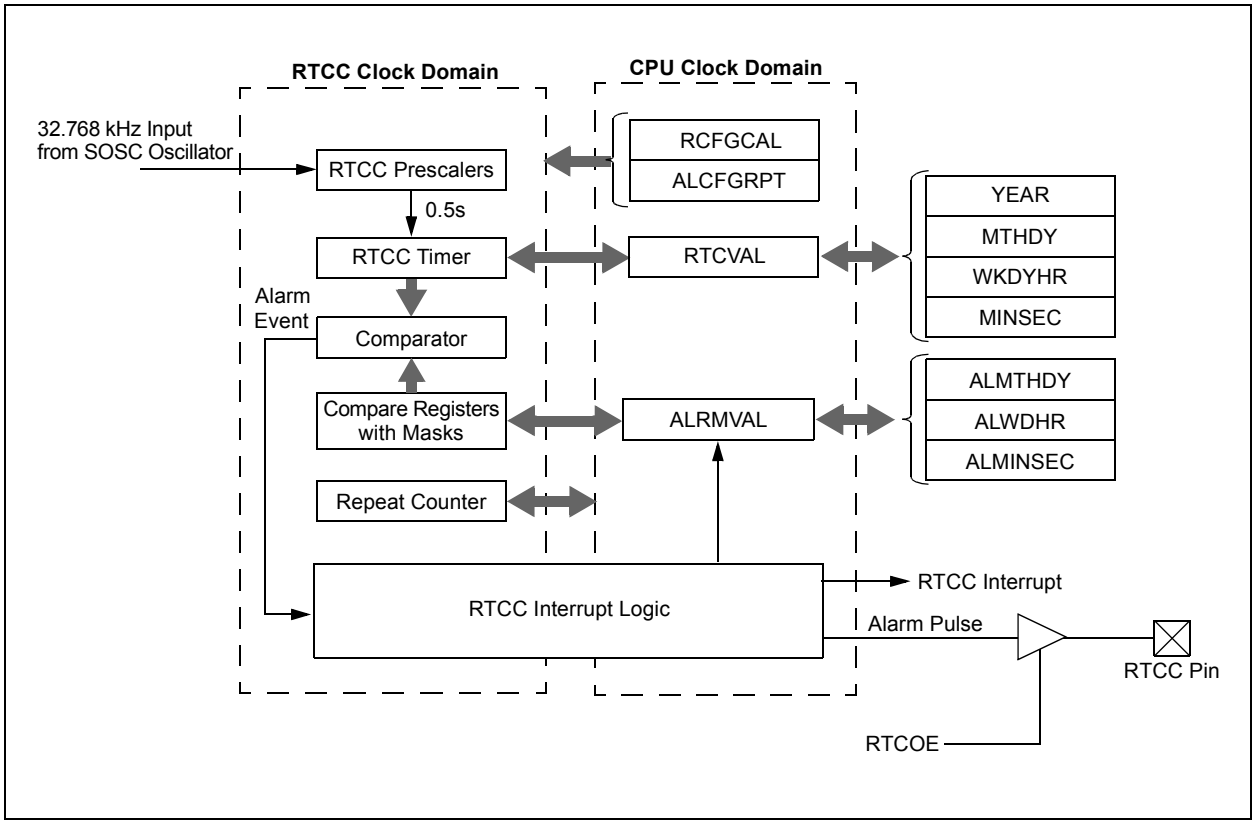
The Real-Time Clock and Calendar (RTCC) provides on-chip, hardware-based clock and calendar functionality with little or no CPU overhead. It is intended for applications where accurate time must be maintained for extended periods with minimal CPU activity and with limited power resources, such as battery-powered applications.

Key features include:

- Time data in hours, minutes and seconds, with a granularity of one-half second
- 24-hour format (Military Time) display option
- Calendar data as date, month and year
- Automatic, hardware-based day of the week and leap year calculations for dates from 2000 through 2099
- Time and calendar data in BCD format for _compact firmware
- Highly configurable alarm function
- External output pin with selectable alarm signal or seconds "tick" signal output
- User calibration feature with auto-adjust

A simplified block diagram of the module is shown in Figure 20-1. The SOSC and RTCC will both remain running while the device is held in Reset with $\overline{MCLR}$ and will continue running after $\overline{MCLR}$ is released.

FIGURE 20-1: RTCC BLOCK DIAGRAM



20.1.3 RTCC CONTROL REGISTERS

REGISTER 20-1: RCFGCAL: RTCC CALIBRATION AND CONFIGURATION REGISTER(1)

R/W-0	U-0	R/W-0	R-0	R-0	R/W-0	R/W-0	R/W-0
RTCEN(2)	—	RTCWREN	RTCSYNC	HALFSEC(3)	RTCOE	RTCPTR1	RTCPTR0
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CAL7	CAL6	CAL5	CAL4	CAL3	CAL2	CAL1	CAL0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **RTCEN:** RTCC Enable bit(2)
1 = RTCC module is enabled
0 = RTCC module is disabled

bit 14 **Unimplemented:** Read as '0'

bit 13 **RTCWREN:** RTCC Value Registers Write Enable bit
1 = RTCVALH and RTCVALL registers can be written to by the user
0 = RTCVALH and RTCVALL registers are locked out from being written to by the user

bit 12 **RTCSYNC:** RTCC Value Registers Read Synchronization bit
1 = RTCVALH, RTCVALL and ALCFGRPT registers can change while reading due to a rollover ripple resulting in an invalid data read. If the register is read twice and results in the same data, the data can be assumed to be valid.
0 = RTCVALH, RTCVALL or ALCFGRPT registers can be read without concern over a rollover ripple

bit 11 **HALFSEC:** Half-Second Status bit(3)
1 = Second half period of a second
0 = First half period of a second

bit 10 **RTCOE:** RTCC Output Enable bit
1 = RTCC output enabled
0 = RTCC output disabled

bit 9-8 **RTCPTR<1:0>:** RTCC Value Register Window Pointer bits
Points to the corresponding RTCC Value registers when reading RTCVALH and RTCVALL registers; the RTCPTR<1:0> value decrements on every read or write of RTCVALH until it reaches '00'.
RTCVAL<15:8>:
00 = MINUTES
01 = WEEKDAY
10 = MONTH
11 = Reserved
RTCVAL<7:0>:
00 = SECONDS
01 = HOURS
10 = DAY
11 = YEAR

Note 1: The RCFGCAL register is only affected by a POR.
2: A write to the RTCEN bit is only allowed when RTCWREN = 1.
3: This bit is read-only. It is cleared to '0' on a write to the lower half of the MINSEC register.

22.0 10-BIT HIGH-SPEED A/D CONVERTER

Note:	This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, **Section 17. "10-Bit A/D Converter"** (DS39705).

The 10-bit A/D Converter has the following key features:

- Successive Approximation (SAR) conversion
- Conversion speeds of up to 500 ksps
- 16 analog input pins
- External voltage reference input pins
- Internal band gap reference inputs
- Automatic Channel Scan mode
- Selectable conversion trigger source
- 16-word conversion result buffer
- Selectable Buffer Fill modes
- Four result alignment options
- Operation during CPU Sleep and Idle modes

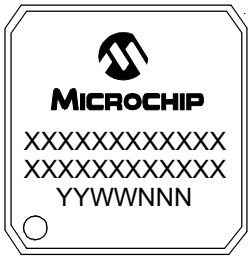
On all PIC24FJ256GB110 family devices, the 10-bit A/D Converter has 16 analog input pins, designated AN0 through AN15. In addition, there are two analog input pins for external voltage reference connections (V_{REF}+ and V_{REF}-). These voltage reference inputs may be shared with other analog input pins.

A block diagram of the A/D Converter is shown in Figure 22-1.

To perform an A/D conversion:

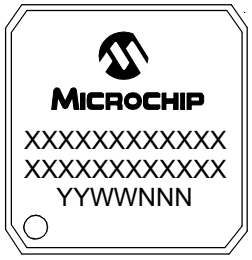
1. Configure the A/D module:
   a) Configure port pins as analog inputs and/or select band gap reference inputs (AD1PCFGL<15:0> and AD1PCFGH<1:0>).
   b) Select voltage reference source to match expected range on analog inputs (AD1CON2<15:13>).
   c) Select the analog conversion clock to match desired data rate with processor clock (AD1CON3<7:0>).
   d) Select the appropriate sample/conversion sequence (AD1CON1<7:5> and AD1CON3<12:8>).
   e) Select how conversion results are presented in the buffer (AD1CON1<9:8>).
   f) Select interrupt rate (AD1CON2<5:2>).
   g) Turn on A/D module (AD1CON1<15>).
2. Configure A/D interrupt (if required):
   a) Clear the AD1IF bit.
   b) Select A/D interrupt priority.

100-Lead TQFP (12x12x1 mm)

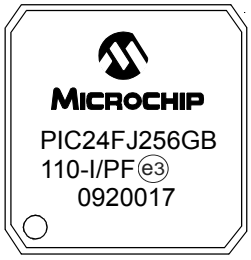


Example

100-Lead TQFP (14x14x1 mm)



Example

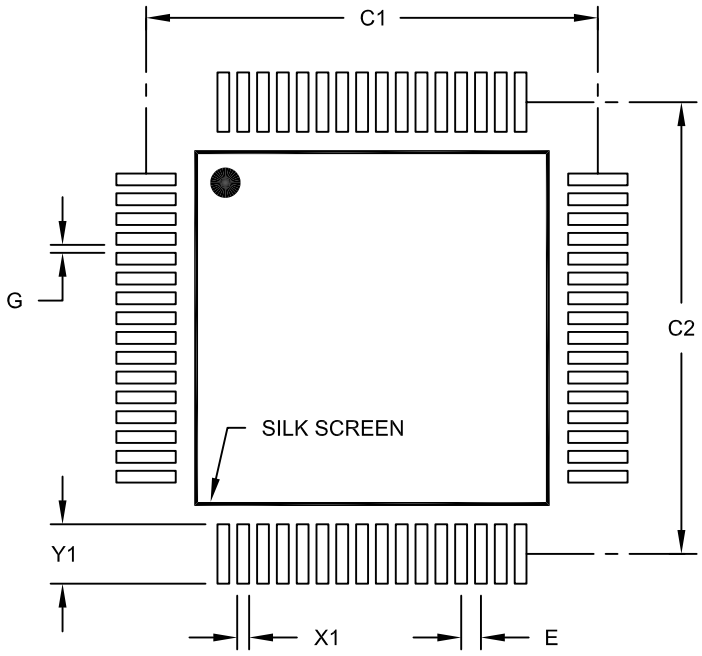


Legend:	XX...X	Customer-specific information
	Y	Year code (last digit of calendar year)
	YY	Year code (last 2 digits of calendar year)
	WW	Week code (week of January 1 is week '01')
	NNN	Alphanumeric traceability code
	(e3)	Pb-free JEDEC designator for Matte Tin (Sn)
	*	This package is Pb-free. The Pb-free JEDEC designator ((e3)) can be found on the outer packaging for this package.

Note: In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information.

64-Lead Plastic Thin Quad Flatpack (PT) – 10x10x1 mm Body, 2.00 mm [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E		0.50 BSC	
Contact Pad Spacing	C1		11.40	
Contact Pad Spacing	C2		11.40	
Contact Pad Width (X64)	X1			0.30
Contact Pad Length (X64)	Y1			1.50
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2085A