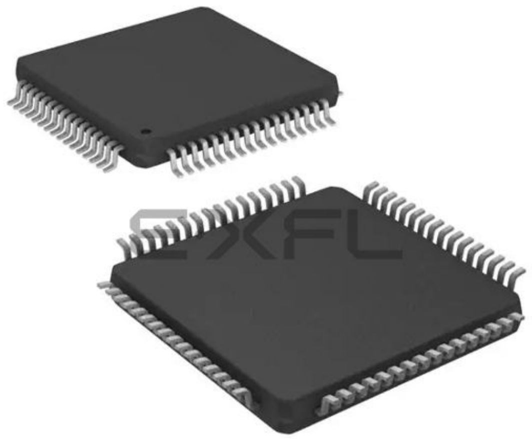

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I²C, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	51
Program Memory Size	192KB (65.5K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24fj192gb106t-i-pt

1.2 USB On-The-Go

With the PIC24FJ256GB110 family of devices, Microchip introduces USB On-The-Go functionality on a single chip to its product line. This new module provides on-chip functionality as a target device compatible with the USB 2.0 standard, as well as limited stand-alone functionality as a USB embedded host. By implementing USB Host Negotiation Protocol (HNP), the module can also dynamically switch between device and host operation, allowing for a much wider range of versatile USB-enabled applications on a microcontroller platform.

In addition to USB host functionality, PIC24FJ256GB110 family devices provide a true single-chip USB solution, including an on-chip transceiver and voltage regulator, and a voltage boost generator for sourcing bus power during host operations.

1.3 Other Special Features

- **Peripheral Pin Select:** The Peripheral Pin Select (PPS) feature allows most digital peripherals to be mapped over a fixed set of digital I/O pins. Users may independently map the input and/or output of any one of the many digital peripherals to any one of the I/O pins.
- **Communications:** The PIC24FJ256GB110 family incorporates a range of serial communication peripherals to handle a range of application requirements. There are three independent I^2C modules that support both Master and Slave modes of operation. Devices also have, through the Peripheral Pin Select feature, four independent UARTs with built-in IrDA encoder/decoders and three SPI modules.
- **Analog Features:** All members of the PIC24FJ256GB110 family include a 10-bit A/D Converter module and a triple comparator module. The A/D module incorporates programmable acquisition time, allowing for a channel to be selected and a conversion to be initiated without waiting for a sampling period, as well as faster sampling speeds. The comparator module includes three analog comparators that are configurable for a wide range of operations.
- **CTMU Interface:** In addition to their other analog features, members of the PIC24FJ256GB110 family include the brand new CTMU interface module. This provides a convenient method for precision time measurement and pulse generation, and can serve as an interface for capacitive sensors.
- **Parallel Master/Enhanced Parallel Slave Port:** One of the general purpose I/O ports can be reconfigured for enhanced parallel data communications. In this mode, the port can be configured for both master and slave operations, and supports 8-bit and 16-bit data transfers with up to 16 external address lines in Master modes.
- **Real-Time Clock/Calendar:** This module implements a full-featured clock and calendar with alarm functions in hardware, freeing up timer resources and program memory space for use of the core application.

1.4 Details on Individual Family Members

Devices in the PIC24FJ256GB110 family are available in 64-pin, 80-pin and 100-pin packages. The general block diagram for all devices is shown in Figure 1-1.

The devices are differentiated from each other in four ways:

1. Flash program memory (64 Kbytes for PIC24FJ64GB1 devices, 128 Kbytes for PIC24FJ128GB1 devices, 192 Kbytes for PIC24FJ192GB1 devices and 256 Kbytes for PIC24FJ256GB1 devices).
2. Available I/O pins and ports (51 pins on 6 ports for 64-pin devices, 65 pins on 7 ports for 80-pin devices and 83 pins on 7 ports for 100-pin devices).
3. Available Interrupt-on-Change Notification (ICN) inputs (49 on 64-pin devices, 63 on 80-pin devices and 81 on 100-pin devices).
4. Available remappable pins (29 pins on 64-pin devices, 40 pins on 80-pin devices and 44 pins on 100-pin devices)

All other features for devices in this family are identical. These are summarized in Table 1-1.

A list of the pin features available on the PIC24FJ256GB110 family devices, sorted by function, is shown in Table 1-4. Note that this table shows the pin location of individual peripheral features and not how they are multiplexed on the same pin. This information is provided in the pinout diagrams in the beginning of the data sheet. Multiplexed features are sorted by the priority given to a feature, with the highest priority peripheral being listed first.

TABLE 1-4: PIC24FJ256GB110 FAMILY PINOUT DESCRIPTIONS (CONTINUED)

Function	Pin Number			I/O	Input Buffer	Description
	64-Pin TQFP, QFN	80-Pin TQFP	100-Pin TQFP			
D+	37	47	57	I/O	—	USB Differential Plus line (internal transceiver).
D-	36	46	56	I/O	—	USB Differential Minus line (internal transceiver).
DMH	46	58	72	O	—	D- External Pull-up Control Output.
DMLN	42	54	68	O	—	D- External Pull-down Control Output.
DPH	50	62	77	O	—	D+ External Pull-up Control Output.
DPLN	43	55	69	O	—	D+ External Pull-down Control Output.
ENVREG	57	71	86	I	ST	Voltage Regulator Enable.
INT0	46	58	72	I	ST	External Interrupt Input.
$\overline{\text{MCLR}}$	7	9	13	I	ST	Master Clear (device Reset) Input. This line is brought low to cause a Reset.
OSCI	39	49	63	I	ANA	Main Oscillator Input Connection.
OSCO	40	50	64	O	ANA	Main Oscillator Output Connection.
PGEC1	15	19	24	I/O	ST	In-Circuit Debugger/Emulator/ICSP™ Programming Clock.
PGED1	16	20	25	I/O	ST	In-Circuit Debugger/Emulator/ICSP Programming Data.
PGEC2	17	21	26	I/O	ST	In-Circuit Debugger/Emulator/ICSP Programming Clock.
PGED2	18	22	27	I/O	ST	In-Circuit Debugger/Emulator/ICSP Programming Data.
PGEC3	11	15	20	I/O	ST	In-Circuit Debugger/Emulator/ICSP Programming Clock.
PGED3	12	16	21	I/O	ST	In-Circuit Debugger/Emulator/ICSP Programming Data.
PMA0	30	36	44	I/O	ST	Parallel Master Port Address Bit 0 Input (Buffered Slave modes) and Output (Master modes).
PMA1	29	35	43	I/O	ST	Parallel Master Port Address Bit 1 Input (Buffered Slave modes) and Output (Master modes).
PMA2	8	10	14	O	—	Parallel Master Port Address (Demultiplexed Master modes).
PMA3	6	8	12	O	—	
PMA4	5	7	11	O	—	
PMA5	4	6	10	O	—	
PMA6	16	24	29	O	—	
PMA7	22	23	28	O	—	
PMA8	32	40	50	O	—	
PMA9	31	39	49	O	—	
PMA10	28	34	42	O	—	
PMA11	27	33	41	O	—	
PMA12	24	30	35	O	—	
PMA13	23	29	34	O	—	
PMCS1	45	57	71	I/O	ST/TTL	Parallel Master Port Chip Select 1 Strobe/Address Bit 15.
PMCS2	44	56	70	O	ST	Parallel Master Port Chip Select 2 Strobe/Address Bit 14.
PMBE	51	63	78	O	—	Parallel Master Port Byte Enable Strobe.

Legend: TTL = TTL input buffer; ST = Schmitt Trigger input buffer; ANA = Analog level input/output; I^2C™ = I^2C/SMBus input buffer

NOTES:

TABLE 4-20: ADC REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
ADC1BUF0	0300	ADC Data Buffer 0																xxxx
ADC1BUF1	0302	ADC Data Buffer 1																xxxx
ADC1BUF2	0304	ADC Data Buffer 2																xxxx
ADC1BUF3	0306	ADC Data Buffer 3																xxxx
ADC1BUF4	0308	ADC Data Buffer 4																xxxx
ADC1BUF5	030A	ADC Data Buffer 5																xxxx
ADC1BUF6	030C	ADC Data Buffer 6																xxxx
ADC1BUF7	030E	ADC Data Buffer 7																xxxx
ADC1BUF8	0310	ADC Data Buffer 8																xxxx
ADC1BUF9	0312	ADC Data Buffer 9																xxxx
ADC1BUFA	0314	ADC Data Buffer 10																xxxx
ADC1BUFB	0316	ADC Data Buffer 11																xxxx
ADC1BUFC	0318	ADC Data Buffer 12																xxxx
ADC1BUFD	031A	ADC Data Buffer 13																xxxx
ADC1BUFE	031C	ADC Data Buffer 14																xxxx
ADC1BUFF	031E	ADC Data Buffer 15																xxxx
AD1CON1	0320	ADON	—	ADSIDL	—	—	—	FORM1	FORM0	SSRC2	SSRC1	SSRC0	—	—	ASAM	SAMP	DONE	0000
AD1CON2	0322	VCFG2	VCFG1	VCFG0	r	—	CSCNA	—	—	BUFS	—	SMPI3	SMPI2	SMPI1	SMPI0	BUFM	ALTS	0000
AD1CON3	0324	ADRC	r	r	SAMC4	SAMC3	SAMC2	SAMC1	SAMC0	ADCS7	ADCS6	ADCS5	ADCS4	ADCS3	ADCS2	ADCS1	ADCS0	0000
AD1CHS	0328	CH0NB	—	—	CH0SB4	CH0SB3	CH0SB2	CH0SB1	CH0SB0	CH0NA	—	—	CH0SA4	CH0SA3	CH0SA2	CH0SA1	CH0SA0	0000
AD1PCFGH	032A	—	—	—	—	—	—	—	—	—	—	—	—	—	—	PCFG17	PCFG16	0000
AD1PCFGL	032C	PCFG15	PCFG14	PCFG13	PCFG12	PCFG11	PCFG10	PCFG9	PCFG8	PCFG7	PCFG6	PCFG5	PCFG4	PCFG3	PCFG2	PCFG1	PCFG0	0000
AD1CSSL	0330	CSSL15	CSSL14	CSSL13	CSSL12	CSSL11	CSSL10	CSSL9	CSSL8	CSSL7	CSSL6	CSSL5	CSSL4	CSSL3	CSSL2	CSSL1	CSSL0	0000

Legend: — = unimplemented, read as ‘0’, r = reserved, maintain as ‘0’. Reset values are shown in hexadecimal.

TABLE 4-21: CTMU REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
CTMUCON	033C	CTMUEN	—	CTMUSIDL	TGEN	EDGEN	EDGSEQEN	IDISSEN	CTTRIG	EDG2POL	EDG2SEL1	EDG2SEL0	EDG1POL	EDG1SEL1	EDG1SEL0	EDG2STAT	EDG1STAT	0000
CTMUICON	033E	ITRIM5	ITRIM4	ITRIM3	ITRIM2	ITRIM1	ITRIM0	IRNG1	IRNG0	—	—	—	—	—	—	—	—	0000

Legend: — = unimplemented, read as ‘0’. Reset values are shown in hexadecimal.

EXAMPLE 5-2: ERASING A PROGRAM MEMORY BLOCK (C LANGUAGE CODE)

```
// C example using MPLAB C30
    unsigned long progAddr = 0xXXXXXX;       // Address of row to write
    unsigned int offset;

//Set up pointer to the first memory location to be written
    TBLPAG = progAddr>>16;                   // Initialize PM Page Boundary SFR
    offset = progAddr & 0xFFFF;              // Initialize lower word of address

    __builtin_tblwtl(offset, 0x0000);        // Set base address of erase block
                                             // with dummy latch write

    NVMCON = 0x4042;                         // Initialize NVMCON

    asm("DISI #5");                          // Block all interrupts with priority <7
                                             // for next 5 instructions
    __builtin_write_NVM();                   // C30 function to perform unlock
                                             // sequence and set WR
```

EXAMPLE 5-3: LOADING THE WRITE BUFFERS (ASSEMBLY LANGUAGE CODE)

```
; Set up NVMCON for row programming operations
       MOV     #0x4001, W0                  ;
       MOV     W0, NVMCON                   ; Initialize NVMCON
; Set up a pointer to the first program memory location to be written
; program memory selected, and writes enabled
       MOV     #0x0000, W0                  ;
       MOV     W0, TBLPAG                   ; Initialize PM Page Boundary SFR
       MOV     #0x6000, W0                  ; An example program memory address
; Perform the TBLWT instructions to write the latches
; 0th_program_word
       MOV     #LOW_WORD_0, W2              ;
       MOV     #HIGH_BYTE_0, W3             ;
       TBLWTL  W2, [W0]                     ; Write PM low word into program latch
       TBLWTH  W3, [W0++]                   ; Write PM high byte into program latch
; 1st_program_word
       MOV     #LOW_WORD_1, W2              ;
       MOV     #HIGH_BYTE_1, W3             ;
       TBLWTL  W2, [W0]                     ; Write PM low word into program latch
       TBLWTH  W3, [W0++]                   ; Write PM high byte into program latch
;  2nd_program_word
       MOV     #LOW_WORD_2, W2              ;
       MOV     #HIGH_BYTE_2, W3             ;
       TBLWTL  W2, [W0]                     ; Write PM low word into program latch
       TBLWTH  W3, [W0++]                   ; Write PM high byte into program latch
       •
       •
       •
; 63rd_program_word
       MOV     #LOW_WORD_31, W2             ;
       MOV     #HIGH_BYTE_31, W3            ;
       TBLWTL  W2, [W0]                     ; Write PM low word into program latch
       TBLWTH  W3, [W0]                     ; Write PM high byte into program latch
```

TABLE 6-3: RESET DELAY TIMES FOR VARIOUS DEVICE RESETS

Reset Type	Clock Source	$\overline{SYSRST}$ Delay	System Clock Delay	Notes
POR(6)	EC	TPOR + TPWRT	—	**1, 2**
	FRC, FRCDIV	TPOR + TPWRT	TFRC	**1, 2, 3, 6**
	LPRC	TPOR + TPWRT	TLPRC	**1, 2, 3**
	ECPLL	TPOR + TPWRT	TLOCK	**1, 2, 4**
	FRCPLL	TPOR + TPWRT	TFRC + TLOCK	**1, 2, 3, 4**
	XT, HS, SOSC	TPOR+ TPWRT	TOST	**1, 2, 5**
	XTPLL, HSPLL	TPOR + TPWRT	TOST + TLOCK	**1, 2, 4, 5**
BOR	EC	TPWRT	—	**2**
	FRC, FRCDIV	TPWRT	TFRC	**2, 3, 6**
	LPRC	TPWRT	TLPRC	**2, 3**
	ECPLL	TPWRT	TLOCK	**2, 4**
	FRCPLL	TPWRT	TFRC + TLOCK	**2, 3, 4**
	XT, HS, SOSC	TPWRT	TOST	**2, 5**
	XTPLL, HSPLL	TPWRT	TFRC + TLOCK	**2, 3, 4**
All Others	Any Clock	—	—	—

Note 1: TPOR = Power-on Reset delay.
2: TPWRT = 64 ms nominal if regulator is disabled (ENVREG tied to VSS).
3: TFRC and TLPRC = RC Oscillator start-up times.
4: TLOCK = PLL lock time.
5: TOST = Oscillator Start-up Timer (OST). A 10-bit counter waits 1024 oscillator periods before releasing oscillator clock to the system.
6: If Two-Speed Start-up is enabled, regardless of the Primary Oscillator selected, the device starts with FRC, and in such cases, FRC start-up time is valid.

Note: For detailed operating frequency and timing specifications, see **Section 29.0 “Electrical Characteristics”**.

REGISTER 7-5: IFS0: INTERRUPT FLAG STATUS REGISTER 0

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	AD1IF	U1TXIF	U1RXIF	SPI1IF	SPF1IF	T3IF
bit 15							bit 8

R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
T2IF	OC2IF	IC2IF	—	T1IF	OC1IF	IC1IF	INT0IF
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **AD1IF:** A/D Conversion Complete Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 12 **U1TXIF:** UART1 Transmitter Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 11 **U1RXIF:** UART1 Receiver Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 10 **SPI1IF:** SPI1 Event Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 9 **SPF1IF:** SPI1 Fault Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 8 **T3IF:** Timer3 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 7 **T2IF:** Timer2 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 6 **OC2IF:** Output Compare Channel 2 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 5 **IC2IF:** Input Capture Channel 2 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 4 **Unimplemented:** Read as '0'

bit 3 **T1IF:** Timer1 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 2 **OC1IF:** Output Compare Channel 1 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 1 **IC1IF:** Input Capture Channel 1 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 0 **INT0IF:** External Interrupt 0 Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

REGISTER 7-26: IPC9: INTERRUPT PRIORITY CONTROL REGISTER 9

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	IC5IP2	IC5IP1	IC5IP0	—	IC4IP2	IC4IP1	IC4IP0
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—	IC3IP2	IC3IP1	IC3IP0	—	—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15 **Unimplemented:** Read as ‘0’

bit 14-12 **IC5IP<2:0>:** Input Capture Channel 5 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as ‘0’

bit 10-8 **IC4IP<2:0>:** Input Capture Channel 4 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as ‘0’

bit 6-4 **IC3IP<2:0>:** Input Capture Channel 3 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as ‘0’

REGISTER 7-36: IPC21: INTERRUPT PRIORITY CONTROL REGISTER 21

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	U4ERIP2	U4ERIP1	U4ERIP0	—	USB1IP2	USB1IP1	USB1IP0
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	MI2C3P2	MI2C3P1	MI2C3P0	—	SI2C3P2	SI2C3P1	SI2C3P0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15 **Unimplemented:** Read as ‘0’

bit 14-12 **U4ERIP<2:0>:** UART4 Error Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as ‘0’

bit 10-8 **USB1IP<2:0>:** USB1 (USB OTG) Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as ‘0’

bit 6-4 **MI2C3P<2:0>:** Master I2C3 Event Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as ‘0’

bit 2-0 **SI2C3P<2:0>:** Slave I2C3 Event Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

REGISTER 8-2: CLKDIV: CLOCK DIVIDER REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-1
ROI	DOZE2	DOZE1	DOZE0	DOZEN(1)	RCDIV2	RCDIV1	RCDIV0
bit 15							bit 8

R/W-0	R/W-0	U-0	U-0	U-0	U-0	U-0	U-0
CPDIV1	CPDIV0	—	—	—	—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15 **ROI:** Recover on Interrupt bit
1 = Interrupts clear the DOZEN bit and reset the CPU peripheral clock ratio to 1:1
0 = Interrupts have no effect on the DOZEN bit

bit 14-12 **DOZE<2:0>:** CPU Peripheral Clock Ratio Select bits
111 = 1:128
110 = 1:64
101 = 1:32
100 = 1:16
011 = 1:8
010 = 1:4
001 = 1:2
000 = 1:1

bit 11 **DOZEN:** DOZE Enable bit(1)
1 = DOZE<2:0> bits specify the CPU peripheral clock ratio
0 = CPU peripheral clock ratio is set to 1:1

bit 10-8 **RCDIV<2:0>:** FRC Postscaler Select bits
111 = 31.25 kHz (divide-by-256)
110 = 125 kHz (divide-by-64)
101 = 250 kHz (divide-by-32)
100 = 500 kHz (divide-by-16)
011 = 1 MHz (divide-by-8)
010 = 2 MHz (divide-by-4)
001 = 4 MHz (divide-by-2)
000 = 8 MHz (divide-by-1)

bit 7-6 **CPDIV<1:0>:** USB System Clock Select bits (postscaler select from 32 MHz clock branch)
11 = 4 MHz (divide-by-8)(2)
10 = 8 MHz (divide-by-4)(2)
01 = 16 MHz (divide-by-2)
00 = 32 MHz (divide-by-1)

bit 5-0 **Unimplemented:** Read as ‘0’

Note 1: This bit is automatically cleared when the ROI bit is set and an interrupt occurs.
2: This setting is not allowed while the USB module is enabled.

REGISTER 10-15: RPINR20: PERIPHERAL PIN SELECT INPUT REGISTER 20

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SCK1R5	SCK1R4	SCK1R3	SCK1R2	SCK1R1	SCK1R0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SDI1R5	SDI1R4	SDI1R3	SDI1R2	SDI1R1	SDI1R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as ‘0’
bit 13-8 **SCK1R<5:0>:** Assign SPI1 Clock Input (SCK1IN) to Corresponding RPn or RPIn Pin bits
bit 7-6 **Unimplemented:** Read as ‘0’
bit 5-0 **SDI1R<5:0>:** Assign SPI1 Data Input (SDI1) to Corresponding RPn or RPIn Pin bits

REGISTER 10-16: RPINR21: PERIPHERAL PIN SELECT INPUT REGISTER 21

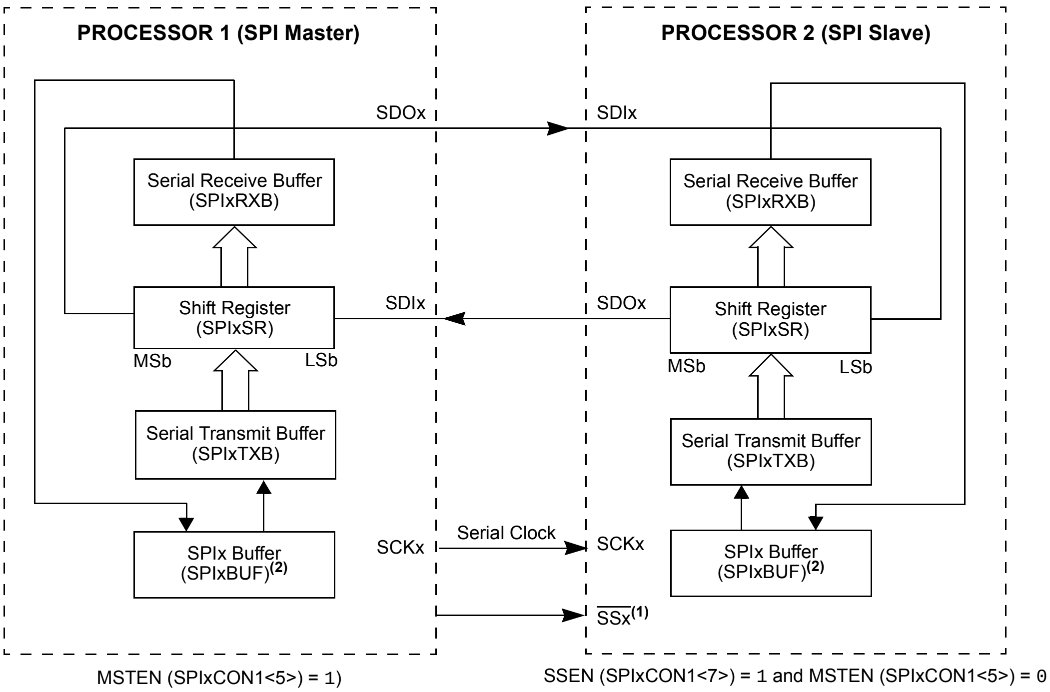
U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	U3CTSR5	U3CTSR4	U3CTSR3	U3CTSR2	U3CTSR1	U3CTSR0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SS1R5	SS1R4	SS1R3	SS1R2	SS1R1	SS1R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

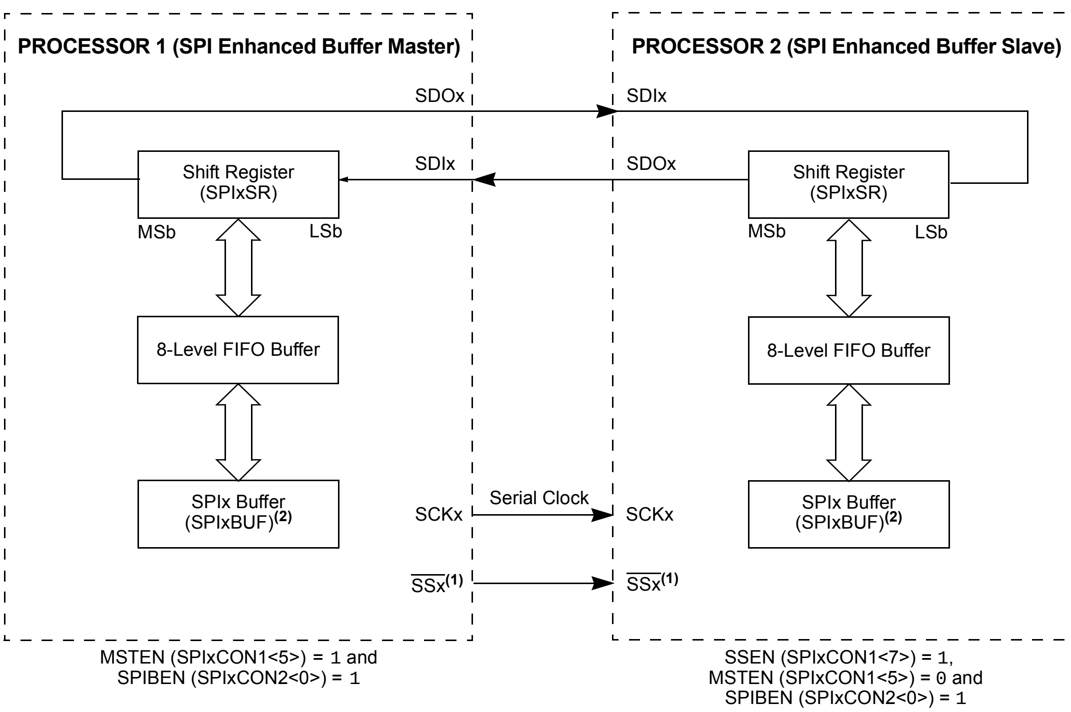
bit 15-14 **Unimplemented:** Read as ‘0’
bit 13-8 **U3CTSR<5:0>:** Assign UART3 Clear to Send ($\overline{\text{U3CTS}}$) to Corresponding RPn or RPIn Pin bits
bit 7-6 **Unimplemented:** Read as ‘0’
bit 5-0 **SS1R<5:0>:** Assign SPI1 Slave Select Input (SS1IN) to Corresponding RPn or RPIn Pin bits

FIGURE 15-3: SPI MASTER/SLAVE CONNECTION (STANDARD MODE)



Note 1: Using the $\overline{\text{SSx}}$ pin in Slave mode of operation is optional.
2: User must write transmit data to read received data from SPIxBUF. The SPIxTXB and SPIxRXB registers are memory mapped to SPIxBUF.

FIGURE 15-4: SPI MASTER/SLAVE CONNECTION (ENHANCED BUFFER MODES)



Note 1: Using the $\overline{\text{SSx}}$ pin in Slave mode of operation is optional.
2: User must write transmit data to read received data from SPIxBUF. The SPIxTXB and SPIxRXB registers are memory mapped to SPIxBUF.

EQUATION 15-1: RELATIONSHIP BETWEEN DEVICE AND SPI CLOCK SPEED[(1)]

$$F_{SCK} = \frac{F_{CY}}{\text{Primary Prescaler} * \text{Secondary Prescaler}}$$

Note 1: Based on $F_{CY} = F_{OSC}/2$, Doze mode and PLL are disabled.

TABLE 15-1: SAMPLE SCK FREQUENCIES[(1,2)]

FCY = 16 MHz		**Secondary Prescaler Settings**				
		1:1	**2:1**	**4:1**	**6:1**	**8:1**
Primary Prescaler Settings	1:1	Invalid	8000	4000	2667	2000
	4:1	4000	2000	1000	667	500
	16:1	1000	500	250	167	125
	64:1	250	125	63	42	31
FCY = 5 MHz						
Primary Prescaler Settings	1:1	5000	2500	1250	833	625
	4:1	1250	625	313	208	156
	16:1	313	156	78	52	39
	64:1	78	39	20	13	10

Note 1: Based on $F_{CY} = F_{OSC}/2$, Doze mode and PLL are disabled.
2: SCKx frequencies shown in kHz.

REGISTER 16-1: I2CxCON: I2Cx CONTROL REGISTER

R/W-0	U-0	R/W-0	R/W-1, HC	R/W-0	R/W-0	R/W-0	R/W-0
I2CEN	—	I2CSIDL	SCLREL	IPMIEN	A10M	DISSLW	SMEN
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0, HC	R/W-0, HC	R/W-0, HC	R/W-0, HC	R/W-0, HC
GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN
bit 7							bit 0

Legend:	HC = Hardware Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **I2CEN:** I2Cx Enable bit
1 = Enables the I2Cx module and configures the SDAx and SCLx pins as serial port pins
0 = Disables I2Cx module. All I^2C pins are controlled by port functions.

bit 14 **Unimplemented:** Read as '0'

bit 13 **I2CSIDL:** Stop in Idle Mode bit
1 = Discontinues module operation when device enters an Idle mode
0 = Continues module operation in Idle mode

bit 12 **SCLREL:** SCLx Release Control bit (when operating as I^2C Slave)
1 = Releases SCLx clock
0 = Holds SCLx clock low (clock stretch)
If STREN = 1:
Bit is R/$\overline{W}$ (i.e., software may write '0' to initiate stretch and write '1' to release clock).
Hardware clear at beginning of slave transmission.
Hardware clear at end of slave reception.
If STREN = 0:
Bit is R/S (i.e., software may only write '1' to release clock).
Hardware clear at beginning of slave transmission.

bit 11 **IPMIEN:** Intelligent Platform Management Interface (IPMI) Enable bit
1 = IPMI Support mode is enabled; all addresses Acknowledged
0 = IPMI mode disabled

bit 10 **A10M:** 10-Bit Slave Addressing bit
1 = I2CxADD is a 10-bit slave address
0 = I2CxADD is a 7-bit slave address

bit 9 **DISSLW:** Disable Slew Rate Control bit
1 = Slew rate control disabled
0 = Slew rate control enabled

bit 8 **SMEN:** SMBus Input Levels bit
1 = Enables I/O pin thresholds compliant with SMBus specification
0 = Disables SMBus input thresholds

bit 7 **GCEN:** General Call Enable bit (when operating as I^2C slave)
1 = Enables interrupt when a general call address is received in the I2CxRSR (module is enabled for reception)
0 = General call address disabled

bit 6 **STREN:** SCLx Clock Stretch Enable bit (when operating as I^2C slave)
Used in conjunction with SCLREL bit.
1 = Enables software or receive clock stretching
0 = Disables software or receive clock stretching

BDs have a fixed relationship to a particular endpoint, depending on the buffering configuration. Table 18-2 provides the mapping of BDs to endpoints. This relationship also means that gaps may occur in the BDT if endpoints are not enabled contiguously. This theoretically means that the BDs for disabled endpoints could be used as buffer space. In practice, users should avoid using such spaces in the BDT unless a method of validating BD addresses is implemented.

18.2.1 BUFFER OWNERSHIP

Because the buffers and their BDs are shared between the CPU and the USB module, a simple semaphore mechanism is used to distinguish which is allowed to update the BD and associated buffers in memory. This is done by using the UOWN bit as a semaphore to distinguish which is allowed to update the BD and associated buffers in memory. UOWN is the only bit that is shared between the two configurations of BDnSTAT.

When UOWN is clear, the BD entry is “owned” by the microcontroller core. When the UOWN bit is set, the BD entry and the buffer memory are “owned” by the USB peripheral. The core should not modify the BD or its corresponding data buffer during this time. Note that the microcontroller core can still read BDnSTAT while the SIE owns the buffer and vice versa.

The buffer descriptors have a different meaning based on the source of the register update. Register 18-1 and Register 18-2 show the differences in BDnSTAT depending on its current “ownership”.

When UOWN is set, the user can no longer depend on the values that were written to the BDs. From this point, the USB module updates the BDs as necessary, overwriting the original BD values. The BDnSTAT register is updated by the SIE with the token PID and the transfer count is updated.

18.2.2 DMA INTERFACE

The USB OTG module uses a dedicated DMA to access both the BDT and the endpoint data buffers. Since part of the address space of the DMA is dedicated to the Buffer Descriptors, a portion of the memory connected to the DMA must comprise a contiguous address space properly mapped for the access by the module.

TABLE 18-2: ASSIGNMENT OF BUFFER DESCRIPTORS FOR THE DIFFERENT BUFFERING MODES

Endpoint	BDs Assigned to Endpoint							
	Mode 0 (No Ping-Pong)		Mode 1 (Ping-Pong on EP0 Out)		Mode 2 (Ping-Pong on all EPs)		Mode 3 (Ping-Pong on all other EPs, except EP0)	
	Out	In	Out	In	Out	In	Out	In
0	0	1	0 (E), 1 (O)	2	0 (E), 1 (O)	2 (E), 3 (O)	0	1
1	2	3	3	4	4 (E), 5 (O)	6 (E), 7 (O)	2 (E), 3 (O)	4 (E), 5 (O)
2	4	5	5	6	8 (E), 9 (O)	10 (E), 11 (O)	6 (E), 7 (O)	8 (E), 9 (O)
3	6	7	7	8	12 (E), 13 (O)	14 (E), 15 (O)	10 (E), 11 (O)	12 (E), 13 (O)
4	8	9	9	10	16 (E), 17 (O)	18 (E), 19 (O)	14 (E), 15 (O)	16 (E), 17 (O)
5	10	11	11	12	20 (E), 21 (O)	22 (E), 23 (O)	18 (E), 19 (O)	20 (E), 21 (O)
6	12	13	13	14	24 (E), 25 (O)	26 (E), 27 (O)	22 (E), 23 (O)	24 (E), 25 (O)
7	14	15	15	16	28 (E), 29 (O)	30 (E), 31 (O)	26 (E), 27 (O)	28 (E), 29 (O)
8	16	17	17	18	32 (E), 33 (O)	34 (E), 35 (O)	30 (E), 31 (O)	32 (E), 33 (O)
9	18	19	19	20	36 (E), 37 (O)	38 (E), 39 (O)	34 (E), 35 (O)	36 (E), 37 (O)
10	20	21	21	22	40 (E), 41 (O)	42 (E), 43 (O)	38 (E), 39 (O)	40 (E), 41 (O)
11	22	23	23	24	44 (E), 45 (O)	46 (E), 47 (O)	42 (E), 43 (O)	44 (E), 45 (O)
12	24	25	25	26	48 (E), 49 (O)	50 (E), 51 (O)	46 (E), 47 (O)	48 (E), 49 (O)
13	26	27	27	28	52 (E), 53 (O)	54 (E), 55 (O)	50 (E), 51 (O)	52 (E), 53 (O)
14	28	29	29	30	56 (E), 57 (O)	58 (E), 59 (O)	54 (E), 55 (O)	56 (E), 57 (O)
15	30	31	31	32	60 (E), 61 (O)	62 (E), 63 (O)	58 (E), 59 (O)	60 (E), 61 (O)

Legend: (E) = Even transaction buffer, (O) = Odd transaction buffer

18.5.3 SEND A FULL-SPEED BULK DATA TRANSFER TO A TARGET DEVICE

1. Follow the procedure described in **Section 18.5.1 "Enable Host Mode and Discover a Connected Device"** and **Section 18.5.2 "Complete a Control Transaction to a Connected Device"** to discover and configure a device.
2. To enable transmit and receive transfers with handshaking enabled, write 1Dh to U1EP0. If the target device is a low-speed device, also set the LSPD bit (U1EP0<7>). If you want the hardware to automatically retry indefinitely if the target device asserts a NAK on the transfer, clear the Retry Disable bit, RETRYDIS (U1EP0<6>).
3. Set up the BD for the current (EVEN or ODD) Tx EP0 to transfer up to 64 bytes.
4. Set the USB device address of the target device in the address register (U1ADDR<6:0>).
5. Write an OUT token to the desired endpoint to U1TOK. This triggers the module's transmit state machines to begin transmitting the token and the data.
6. Wait for the Transfer Done Interrupt Flag, TRNIF. This indicates that the BD has been released back to the microprocessor, and the transfer has completed. If the retry disable bit is set, the handshake (ACK, NAK, STALL or ERROR (0Fh)) is returned in the BD PID field. If a STALL interrupt occurs, the pending packet must be dequeued and the error condition in the target device cleared. If a detach interrupt occurs (SE0 for more than 2.5 μs), then the target has detached (U1IR<0> is set).
7. Once the transfer done interrupt occurs (TRNIF is set), the BD can be examined and the next data packet queued by returning to step 2.

Note:	USB speed, transceiver and pull-ups should only be configured during the module setup phase. It is not recommended to change these settings while the module is enabled.

18.6 OTG Operation

18.6.1 SESSION REQUEST PROTOCOL (SRP)

An OTG A-device may decide to power down the VBUS supply when it is not using the USB link through the Session Request Protocol (SRP). Software may do this by clearing VBUSON (U1OTGCON<3>). When the VBUS supply is powered down, the A-device is said to have ended a USB session.

An OTG A-device or Embedded Host may repower the VBUS supply at any time (initiate a new session). An OTG B-device may also request that the OTG A-device repower the VBUS supply (initiate a new session). This is accomplished via Session Request Protocol (SRP).

Prior to requesting a new session, the B-device must first check that the previous session has definitely ended. To do this, the B-device must check for two conditions:

1. VBUS supply is below the Session Valid voltage and
2. Both D+ and D- have been low for at least 2 ms.

The B-device will be notified of condition 1 by the SESENDIF (U1OTGIR<2>) interrupt. Software will have to manually check for condition 2.

Note:	When the A-device powers down the VBUS supply, the B-device must disconnect its pull-up resistor from power. If the device is self-powered, it can do this by clearing DPPULUP (U1OTGCON<7>) and DMPULUP (U1OTGCON<6>).

The B-device may aid in achieving condition 1 by discharging the VBUS supply through a resistor. Software may do this by setting VBUSDIS (U1OTGCON<0>).

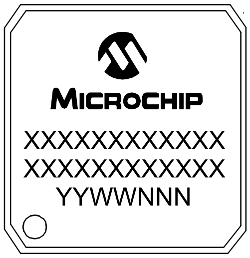
After these initial conditions are met, the B-device may begin requesting the new session. The B-device begins by pulsing the D+ data line. Software should do this by setting DPPULUP (U1OTGCON<7>). The data line should be held high for 5 to 10 ms.

The B-device then proceeds by pulsing the VBUS supply. Software should do this by setting PUVBUS (U1CNFG2<4>). When an A-device detects SRP signaling (either via the ATTACHIF (U1IR<6>) interrupt or via the SESVDIF (U1OTGIR<3>) interrupt), the A-device must restore the VBUS supply by either setting VBUSON (U1OTGCON<3>), or by setting the I/O port controlling the external power source.

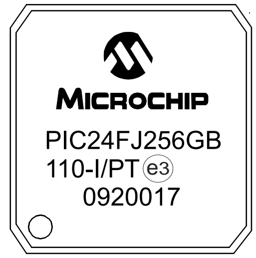
The B-device should not monitor the state of the VBUS supply while performing VBUS supply pulsing. When the B-device does detect that the VBUS supply has been restored (via the SESVDIF (U1OTGIR<3>) interrupt), the B-device must re-connect to the USB link by pulling up D+ or D- (via the DPPULUP or DMPULUP).

The A-device must complete the SRP by driving USB Reset signaling.

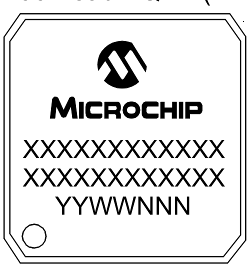
100-Lead TQFP (12x12x1 mm)



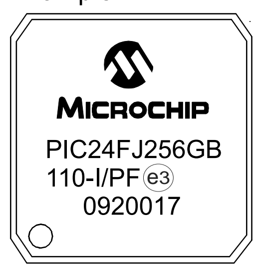
Example



100-Lead TQFP (14x14x1 mm)



Example

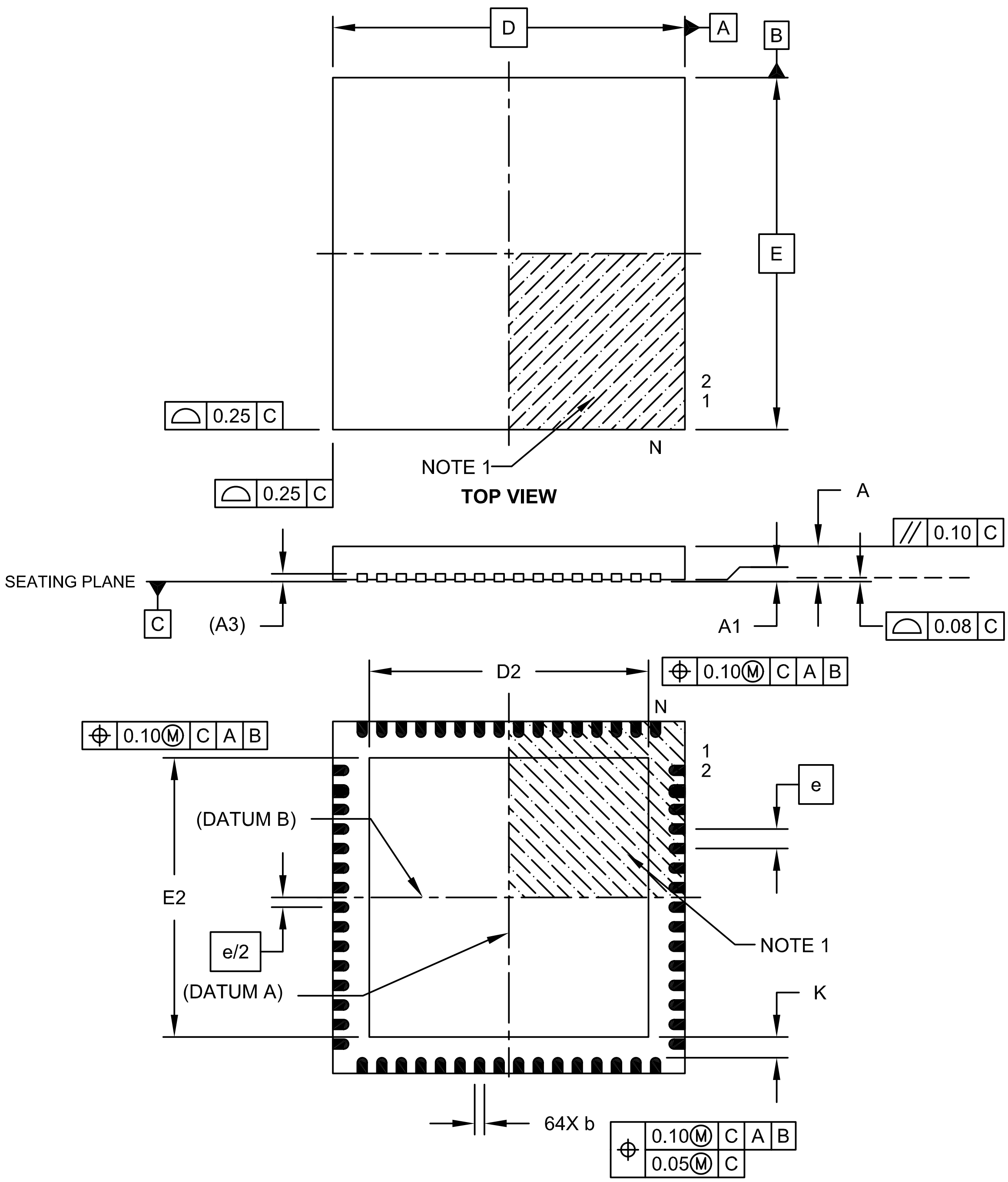


Legend:	XX...X	Customer-specific information
	Y	Year code (last digit of calendar year)
	YY	Year code (last 2 digits of calendar year)
	WW	Week code (week of January 1 is week ‘01’)
	NNN	Alphanumeric traceability code
	(e3)	Pb-free JEDEC designator for Matte Tin (Sn)
	*	This package is Pb-free. The Pb-free JEDEC designator (e3) can be found on the outer packaging for this package.

Note: In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information.

64-Lead Plastic Quad Flat, No Lead Package (MR) – 9x9x0.9 mm Body [QFN]

Note:	For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



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