

Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

E·XFI

Details	
Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I ² C, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	65
Program Memory Size	256КВ (85.5К х 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	80-TQFP
Supplier Device Package	80-TQFP (12x12)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24fj256gb108t-i-pt

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

1.2 USB On-The-Go

With the PIC24FJ256GB110 family of devices, Microchip introduces USB On-The-Go functionality on a single chip to its product line. This new module provides on-chip functionality as a target device compatible with the USB 2.0 standard, as well as limited stand-alone functionality as a USB embedded host. By implementing USB Host Negotiation Protocol (HNP), the module can also dynamically switch between device and host operation, allowing for a much wider range of versatile USB-enabled applications on a microcontroller platform.

In addition to USB host functionality, PIC24FJ256GB110 family devices provide a true single-chip USB solution, including an on-chip transceiver and voltage regulator, and a voltage boost generator for sourcing bus power during host operations.

1.3 Other Special Features

- Peripheral Pin Select: The Peripheral Pin Select (PPS) feature allows most digital peripherals to be mapped over a fixed set of digital I/O pins. Users may independently map the input and/or output of any one of the many digital peripherals to any one of the I/O pins.
- **Communications:** The PIC24FJ256GB110 family incorporates a range of serial communication peripherals to handle a range of application requirements. There are three independent I²C modules that support both Master and Slave modes of operation. Devices also have, through the Peripheral Pin Select feature, four independent UARTs with built-in IrDA encoder/decoders and three SPI modules.
- Analog Features: All members of the PIC24FJ256GB110 family include a 10-bit A/D Converter module and a triple comparator module. The A/D module incorporates programmable acquisition time, allowing for a channel to be selected and a conversion to be initiated without waiting for a sampling period, as well as faster sampling speeds. The comparator module includes three analog comparators that are configurable for a wide range of operations.
- **CTMU Interface:** In addition to their other analog features, members of the PIC24FJ256GB110 family include the brand new CTMU interface module. This provides a convenient method for precision time measurement and pulse generation, and can serve as an interface for capacitive sensors.

- Parallel Master/Enhanced Parallel Slave Port: One of the general purpose I/O ports can be reconfigured for enhanced parallel data communications. In this mode, the port can be configured for both master and slave operations, and supports 8-bit and 16-bit data transfers with up to 16 external address lines in Master modes.
- Real-Time Clock/Calendar: This module implements a full-featured clock and calendar with alarm functions in hardware, freeing up timer resources and program memory space for use of the core application.

1.4 Details on Individual Family Members

Devices in the PIC24FJ256GB110 family are available in 64-pin, 80-pin and 100-pin packages. The general block diagram for all devices is shown in Figure 1-1.

The devices are differentiated from each other in four ways:

- Flash program memory (64 Kbytes for PIC24FJ64GB1 devices, 128 Kbytes for PIC24FJ128GB1 devices, 192 Kbytes for PIC24FJ192GB1 devices and 256 Kbytes for PIC24FJ256GB1 devices).
- Available I/O pins and ports (51 pins on 6 ports for 64-pin devices, 65 pins on 7 ports for 80-pin devices and 83 pins on 7 ports for 100-pin devices).
- 3. Available Interrupt-on-Change Notification (ICN) inputs (49 on 64-pin devices, 63 on 80-pin devices and 81 on 100-pin devices).
- 4. Available remappable pins (29 pins on 64-pin devices, 40 pins on 80-pin devices and 44 pins on 100-pin devices)

All other features for devices in this family are identical. These are summarized in Table 1-1.

A list of the pin features available on the PIC24FJ256GB110 family devices, sorted by function, is shown in Table 1-4. Note that this table shows the pin location of individual peripheral features and not how they are multiplexed on the same pin. This information is provided in the pinout diagrams in the beginning of the data sheet. Multiplexed features are sorted by the priority given to a feature, with the highest priority peripheral being listed first.

4.1.1 PROGRAM MEMORY ORGANIZATION

The program memory space is organized in word-addressable blocks. Although it is treated as 24 bits wide, it is more appropriate to think of each address of the program memory as a lower and upper word, with the upper byte of the upper word being unimplemented. The lower word always has an even address, while the upper word has an odd address (Figure 4-2).

Program memory addresses are always word-aligned on the lower word and addresses are incremented or decremented by two during code execution. This arrangement also provides compatibility with data memory space addressing and makes it possible to access data in the program memory space.

4.1.2 HARD MEMORY VECTORS

All PIC24F devices reserve the addresses between 00000h and 000200h for hard coded program execution vectors. A hardware Reset vector is provided to redirect code execution from the default value of the PC on device Reset to the actual start of code. A GOTO instruction is programmed by the user at 000000h, with the actual address for the start of code at 000002h.

PIC24F devices also have two interrupt vector tables, located from 000004h to 0000FFh and 000100h to 0001FFh. These vector tables allow each of the many device interrupt sources to be handled by separate ISRs. A more detailed discussion of the interrupt vector tables is provided in **Section 7.1 "Interrupt Vector Table"**.

4.1.3 FLASH CONFIGURATION WORDS

In PIC24FJ256GB110 family devices, the top three words of on-chip program memory are reserved for configuration information. On device Reset, the configuration information is copied into the appropriate Configuration registers. The addresses of the Flash Configuration Word for devices in the PIC24FJ256GB110 family are shown in Table 4-1. Their location in the memory map is shown with the other memory vectors in Figure 4-1.

The Configuration Words in program memory are a compact format. The actual Configuration bits are mapped in several different registers in the configuration memory space. Their order in the Flash Configuration Words does not reflect a corresponding arrangement in the configuration space. Additional details on the device Configuration Words are provided in **Section 26.1** "Configuration Bits".

TABLE 4-1:	FLASH CONFIGURATION
	WORDS FOR
	PIC24FJ256GB110 FAMILY
	DEVICES

Device	Program Memory (Words)	Configuration Word Addresses
PIC24FJ64GB	22,016	00ABFAh: 00ABFEh
PIC24FJ128GB	44,032	0157FAh: 0157FEh
PIC24FJ192GB	67,072	020BFAh: 020BFEh
PIC24FJ256GB	87,552	02ABFAh: 02ABFEh

FIGURE 4-2: PROGRAM MEMORY ORGANIZATION

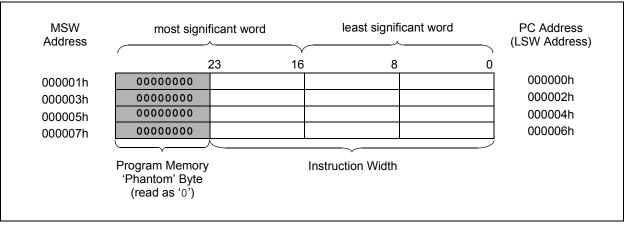


TABLE 4-28: SYSTEM REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
RCON	0740	TRAPR	IOPUWR	_	_	_	_	СМ	PMSLP	EXTR	SWR	SWDTEN	WDTO	SLEEP	IDLE	BOR	POR	Note 1
OSCCON	0742	_	COSC2	COSC1	COSC0	_	NOSC2	NOSC1	NOSC0	CLKLOCK	IOLOCK	LOCK	_	CF	POSCEN	SOSCEN	OSWEN	Note 2
CLKDIV	0744	ROI	DOZE2	DOZE1	DOZE0	DOZEN	RCDIV2	RCDIV1	RCDIV0	CPDIV1	CPDIV0	_	_	_	_	—	_	0100
OSCTUN	0748	_	_	_	_		_	_	_	_		TUN5	TUN4	TUN3	TUN2	TUN1	TUN0	0000
REFOCON	074E	ROEN	—	ROSSLP	ROSEL	RODIV3	RODIV2	RODIV1	RODIV0	-		_	—	_	_			0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: The Reset value of the RCON register is dependent on the type of Reset event. See Section 6.0 "Resets" for more information.

2: The Reset value of the OSCCON register is dependent on both the type of Reset event and the device configuration. See Section 8.0 "Oscillator Configuration" for more information.

TABLE 4-29: NVM REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
NVMCON	0760	WR	WREN	WRERR	—	_	_	_	_	-	ERASE	_	—	NVMOP3	NVMOP2	NVMOP1	NVMOP0	0000 (1)
NVMKEY	0766	_	_	—	—	_	_	_	_	NVMKEY Register<7:0>						0000		

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: Reset value shown is for POR only. Value on other Reset states is dependent on the state of memory write or erase operations at the time of Reset.

TABLE 4-30: PMD REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PMD1	0770	T5MD	T4MD	T3MD	T2MD	T1MD	-	—	_	I2C1MD	U2MD	U1MD	SPI2MD	SPI1MD	—	_	ADC1MD	0000
PMD2	0772	IC8MD	IC7MD	IC6MD	IC5MD	IC4MD	IC3MD	IC2MD	IC1MD	OC8MD	OC7MD	OC6MD	OC5MD	OC4MD	OC3MD	OC2MD	OC1MD	0000
PMD3	0774	_	_	_	_	—	CMPMD	RTCCMD	PMPMD	CRCMD	_	_	_	U3MD	I2C3MD	I2C2MD	_	0000
PMD4	0776	_	_	_	_	_	_	_		_	UPWMMD	U4MD	_	REFOMD	CTMUMD	LVDMD	USB1MD	0000
PMD5	0778	—	_	—	—	_	—	—	IC9MD	_	—	—	—	—	_	_	OC9MD	0000
PMD6	077A	_		_	_			_	_		_	_			—	_	SPI3MD	0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
	_	PMPIF	OC8IF	OC7IF	OC6IF	OC5IF	IC6IF				
oit 15							bit				
R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	R/W-0	R/W-0				
IC5IF	IC4IF	IC3IF	_		<u> </u>	SPI2IF	SPF2IF				
pit 7	10 11	loon				01 1211	bit				
L egend: R = Readat	le hit	W = Writable	hit	II = I Inimplem	nented bit, read	1 as '0'					
n = Value a		'1' = Bit is set		'0' = Bit is clea		x = Bit is unkr	iown				
oit 15-14	•	nted: Read as '									
oit 13		Illel Master Port		Status bit							
		request has oc request has no									
oit 12				pt Flag Status b	bit						
		request has oc									
pit 11	-	request has no		unt Elon Statua k	.i+						
	•	request has oc		pt Flag Status b	л						
		request has no									
oit 10	-	OC6IF: Output Compare Channel 6 Interrupt Flag Status bit									
		request has oc request has no									
oit 9	-	-		pt Flag Status b	bit						
	-	request has oc									
	-	request has no									
oit 8		Capture Chann	-	lag Status bit							
		request has oc request has no									
oit 7	•	Capture Chann		lag Status bit							
		request has oc									
	-	request has no									
oit 6		Capture Chann request has oc	-	lag Status bit							
		request has no									
oit 5	IC3IF: Input	Capture Chann	el 3 Interrupt F	lag Status bit							
		request has oc request has no									
oit 4-2		nted: Read as '									
bit 4-2 bit 1	-	2 Event Interrup		it							
		request has oc	-								
	-	request has no									
	OBEALE OD										
oit 0		2 Fault Interrup request has oc	-	it							

REGISTER 7-23: IPC6: INTERRUPT PRIORITY CONTROL REGISTER 6

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0									
_	T4IP2	T4IP1	T4IP0		OC4IP2	OC4IP1	OC4IP0									
bit 15		•		·		•	bit 8									
U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0									
—	OC3IP2	OC3IP1	OC3IP0	—	_	—	—									
bit 7							bit									
Legend:																
R = Readab	ole bit	W = Writable	bit	U = Unimpler	nented bit, read	l as '0'										
-n = Value a	t POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown									
bit 15	Unimplemer	nted: Read as 'o)'													
bit 14-12	T4IP<2:0>: Timer4 Interrupt Priority bits															
	111 = Interru	pt is priority 7 (ł	nighest priority	interrupt)												
	•															
	•															
	001 = Interru	pt is priority 1														
		pt source is dis	abled													
bit 11	Unimplemer	nted: Read as 'd)'													
bit 10-8	OC4IP<2:0>: Output Compare Channel 4 Interrupt Priority bits															
	111 = Interru	pt is priority 7 (ł	nighest priority	interrupt)												
	•															
	•															
		int is priority 1														
	001 = Interru															
	001 = Interru 000 = Interru		abled			000 = Interrupt source is disabled										
bit 7	000 = Interru															
bit 7 bit 6-4	000 = Interru Unimplemer	pt source is dis)'	Interrupt Priorit	y bits											
	000 = Interru Unimplemer OC3IP<2:0>	ipt source is dis ited: Read as '()' re Channel 3	•	y bits											
	000 = Interru Unimplemer OC3IP<2:0>	ipt source is dis ited: Read as '(: Output Compa)' re Channel 3	•	y bits											
	000 = Interru Unimplemer OC3IP<2:0>	ipt source is dis ited: Read as '(: Output Compa)' re Channel 3	•	y bits											
	000 = Interru Unimplemer OC3IP<2:0> 111 = Interru • •	ipt source is dis ited: Read as '(: Output Compa)' re Channel 3	•	y bits											
	000 = Interru Unimplemen OC3IP<2:0> 111 = Interru • • 001 = Interru	ipt source is dis ited: Read as '(: Output Compa ipt is priority 7 (H	₎ , re Channel 3 highest priority	•	y bits											

REGISTER 7-31: IPC15: INTERRUPT PRIORITY CONTROL REGISTER 15

U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0
—			—	—	RTCIP2	RTCIP1	RTCIP0
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-11 Unimplemented: Read as '0'

- bit 10-8 **RTCIP<2:0>:** Real-Time Clock/Calendar Interrupt Priority bits 111 = Interrupt is priority 7 (highest priority interrupt)
 - •
 - 001 = Interrupt is priority 1
 - 000 = Interrupt source is disabled
- bit 7-0 Unimplemented: Read as '0'

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
_	CRCIP2	CRCIP1	CRCIP0	—	U2ERIP2	U2ERIP1	U2ERIP0
bit 15							bit 8
U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
	U1ERIP2	U1ERIP1	U1ERIP0				
bit 7							bit 0
[
Legend:							
R = Readab		W = Writable		-	nented bit, read		
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown
bit 15	-	ted: Read as '					
bit 14-12	CRCIP<2:0>:	CRC Generate	or Error Interru	upt Priority bits			
	111 = Interru	pt is priority 7 (I	highest priority	/ interrupt)			
	•						
	•						
	001 = Interru	pt is priority 1					
		pt source is dis	abled				
bit 11	Unimplemen	ted: Read as '	D'				
bit 10-8	U2ERIP<2:0>	: UART2 Error	Interrupt Prio	rity bits			
	111 = Interru	pt is priority 7 (I	highest priority	/ interrupt)			
	•						
	•						
	001 = Interru	pt is priority 1					
		pt source is dis	abled				
bit 7	Unimplemen	ted: Read as '	o'				
bit 6-4	U1ERIP<2:0>	-: UART1 Error	Interrupt Prio	rity bits			
	111 = Interru	pt is priority 7 (l	highest priority	/ interrupt)			
	•						
	•						
	• 001 = Interru	nt is priority 1					
		pt is priority i pt source is dis	abled				
bit 3-0	-	ted: Read as '					
	•						

REGISTER 7-32: IPC16: INTERRUPT PRIORITY CONTROL REGISTER 16

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
_	U4ERIP2	U4ERIP1	U4ERIP0	—	USB1IP2	USB1IP1	USB1IP0
bit 15							bit 8

REGISTER 7-36: IPC21: INTERRUPT PRIORITY CONTROL REGISTER 21

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	MI2C3P2	MI2C3P1	MI2C3P0	—	SI2C3P2	SI2C3P1	SI2C3P0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	1 as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15	Unimplemented: Read as '0'
bit 14-12	U4ERIP<2:0>: UART4 Error Interrupt Priority bits
	111 = Interrupt is priority 7 (highest priority interrupt)
	•
	•
	• 001 = Interrupt is priority 1
	000 = Interrupt source is disabled
bit 11	Unimplemented: Read as '0'
bit 10-8	USB1IP<2:0>: USB1 (USB OTG) Interrupt Priority bits
	111 = Interrupt is priority 7 (highest priority interrupt)
	•
	•
	•
	001 = Interrupt is priority 1
	000 = Interrupt source is disabled
bit 7	Unimplemented: Read as '0'
bit 6-4	MI2C3P<2:0>: Master I2C3 Event Interrupt Priority bits
	 111 = Interrupt is priority 7 (highest priority interrupt)
	•
	001 = Interrupt is priority 1
	000 = Interrupt source is disabled
bit 3	Unimplemented: Read as '0'
bit 2-0	SI2C3P<2:0>: Slave I2C3 Event Interrupt Priority bits
	111 = Interrupt is priority 7 (highest priority interrupt)
	•
	•
	• 001 = Interrupt is priority 1
	000 = Interrupt source is disabled

REGISTER 15-1: SPIx STATUS AND CONTROL REGISTER (CONTINUED)

- bit 1 SPITBF: SPIx Transmit Buffer Full Status bit 1 = Transmit not yet started, SPIxTXB is full 0 = Transmit started, SPIxTXB is empty In Standard Buffer mode: Automatically set in hardware when CPU writes SPIxBUF location, loading SPIxTXB. Automatically cleared in hardware when SPIx module transfers data from SPIxTXB to SPIxSR. In Enhanced Buffer mode: Automatically set in hardware when CPU writes SPIxBUF location, loading the last available buffer location. Automatically cleared in hardware when a buffer location is available for a CPU write. bit 0 SPIRBF: SPIx Receive Buffer Full Status bit 1 = Receive complete, SPIxRXB is full 0 = Receive is not complete, SPIxRXB is empty In Standard Buffer mode: Automatically set in hardware when SPIx transfers data from SPIxSR to SPIxRXB. Automatically cleared in hardware when core reads SPIxBUF location, reading SPIxRXB. In Enhanced Buffer mode: Automatically set in hardware when SPIx transfers data from SPIxSR to buffer, filling the last unread buffer location. Automatically cleared in hardware when a buffer location is available for a transfer from SPIxSR.
- **Note 1:** If SPIEN = 1, these functions must be assigned to available RPn pins before use. See **Section 10.4** "**Peripheral Pin Select**" for more information.

18.1 Hardware Configuration

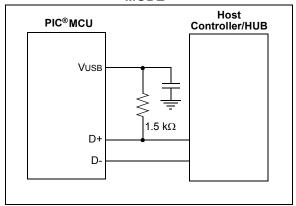
18.1.1 DEVICE MODE

18.1.1.1 D+ Pull-up Resistor

PIC24FJ256GB110 family devices have a built-in 1.5 kΩ resistor on the D+ line that is available when the microcontroller in operating in device mode. This is used to signal an external Host that the device is operating in Full Speed Device mode. It is engaged by setting the DPPULUP bit (U10TGCON<7>).

Alternatively, an external resistor may be used on D+, as shown in Figure 18-2.

FIGURE 18-2: EXTERNAL PULL-UP FOR FULL-SPEED DEVICE MODE



18.1.1.2 Power Modes

Many USB applications will likely have several different sets of power requirements and configuration. The most common power modes encountered are:

- Bus Power Only,
- · Self-Power Only and
- Dual Power with Self-Power Dominance.

Bus Power Only mode (Figure 18-3) is effectively the simplest method. All power for the application is drawn from the USB.

To meet the inrush current requirements of the USB 2.0 Specification, the total effective capacitance appearing across VBUs and ground must be no more than 10 μ F.

In the USB Suspend mode, devices must consume no more than 2.5 mA from the 5V VBUS line of the USB cable. During the USB Suspend mode, the D+ or D-pull-up resistor must remain active, which will consume some of the allowed suspend current.

In Self-Power Only mode (Figure 18-4), the USB application provides its own power, with very little power being pulled from the USB. Note that an attach indication is added to indicate when the USB has been connected and the host is actively powering VBUS.

To meet compliance specifications, the USB module (and the D+ or D- pull-up resistor) should not be enabled until the host actively drives VBUS high. One of the 5.5V tolerant I/O pins may be used for this purpose.

The application should never source any current onto the 5V VBUS pin of the USB cable.

The Dual-power option with Self-Power Dominance (Figure 18-5) allows the application to use internal power primarily, but switch to power from the USB when no internal power is available. Dual-power devices must also meet all of the special requirements for inrush current and Suspend mode current previously described, and must not enable the USB module until VBUS is driven high.



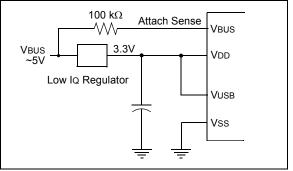


FIGURE 18-4: SELF-POWER ONLY

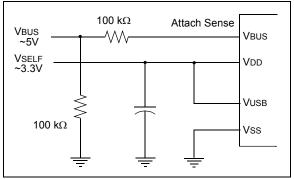
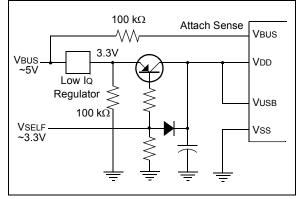


FIGURE 18-5:

DUAL POWER EXAMPLE



18.7.1 USB OTG MODULE CONTROL REGISTERS

REGISTER 18-3: U1OTGSTAT: USB OTG STATUS REGISTER (HOST MODE ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit
R-0, HSC	U-0	R-0, HSC	U-0	R-0, HSC	R-0, HSC	U-0	R-0, HSC
ID	—	LSTATE	_	SESVD	SESEND	_	VBUSVD
bit 7							bit
Legend:				U = Unimplem	ented bit, read	l as '0'	
R = Readab	ole bit	W = Writable b	pit	HSC = Hardw	are Settable/C	learable bit	
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unk	nown
bit 7 bit 6 bit 5	0 = A type A Unimplement LSTATE: Line 1 = The USB	s attached, or a plug has been p ted: Read as '0 e State Stable In line state (as d	dicator bit efined by SE0	and JSTATE) I	cle nas been stable		ous 1 ms
bit 4		line state has N ted: Read as '0		ole for the previ	ous 1 ms		
bit 3	SESVD: Sess 1 = The VBUS B-device	sion Valid Indica S voltage is abo	tor bit ve VA_SESS_V			ΓG Specificati	on) on the A o
		s voltage is belo	W VA_SESS_VI	_D on the A or E			
bit 2	SESEND: B-S 1 = The VBU: B-device	S voltage is beic Session End Inc S voltage is be	licator bit low VB_SESS_	_END (as define	ed in the USE	3 OTG Specif	ïcation) on th
	SESEND: B-S 1 = The VBU B-device 0 = The VBUS	Session End Inc s voltage is be	licator bit low VB_SESS_ ve VB_SESS_E	_END (as define	ed in the USE	3 OTG Specif	ïcation) on th
bit 2 bit 1 bit 0	SESEND: B-S 1 = The VBU: B-device 0 = The VBUS Unimplemen	Session End Inc s voltage is be s voltage is abo	licator bit low VB_sess_ ve VB_sess_e	_END (as define	ed in the USE	3 OTG Specif	ïcation) on th

REGISTER 18-5: U1PWRC: USB POWER CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0, HS	U-0	U-0	R/W-0	U-0	U-0	R/W-0, HC	R/W-0
UACTPND	—	—	USLPGRD	—	—	USUSPND	USBPWR
bit 7 bit 0							

Legend:	HS = Hardware Settable bit	HC = Hardware Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-8	Unimplemented: Read as '0'
bit 7	UACTPND: USB Activity Pending bit
	 1 = Module should not be suspended at the moment (requires USLPGRD bit to be set) 0 = Module may be suspended or powered down
bit 6-5	Unimplemented: Read as '0'
bit 4	USLPGRD: Sleep/Suspend Guard bit
	 1 = Indicate to the USB module that it is about to be suspended or powered down 0 = No suspend
bit 3-2	Unimplemented: Read as '0'
bit 1	USUSPND: USB Suspend Mode Enable bit
	 1 = USB OTG module is in Suspend mode; USB clock is gated and the transceiver is placed in a low-power state
	0 = Normal USB OTG operation
bit 0	USBPWR: USB Operation Enable bit
	1 = USB OTG module is enabled (1)
	$0 = \text{USB OTG module is disabled}^{(1)}$
Nata A.	

Note 1: Do not clear this bit unless the HOSTEN, USBEN and OTGEN bits (U1CON<3,0> and U1OTGCON<2>) are all cleared.

REGISTER 18-7:	U1CON: USB CONTROL REGISTER (DEVICE MODE)	
-----------------------	---	--

					,		
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15		•					bit 8
U-0	R-x, HSC	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	SE0	PKTDIS	—	HOSTEN	RESUME	PPBRST	USBEN
bit 7		•					bit 0

Legend:	U = Unimplemented bit, read as '0'				
R = Readable bit	W = Writable bit	HSC = Hardware Settable/Clearable bit			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		

bit 15-7	Unimplemented: Read as '0'
bit 6	SE0: Live Single-Ended Zero Flag bit
	1 = Single-ended zero active on the USB bus0 = No single-ended zero detected
bit 5	PKTDIS: Packet Transfer Disable bit
	 1 = SIE token and packet processing disabled; automatically set when a SETUP token is received 0 = SIE token and packet processing enabled
bit 4	Unimplemented: Read as '0'
bit 3	HOSTEN: Host Mode Enable bit
	 1 = USB host capability enabled; pull-downs on D+ and D- are activated in hardware 0 = USB host capability disabled
bit 2	RESUME: Resume Signaling Enable bit
	1 = Resume signaling activated0 = Resume signaling disabled
bit 1	PPBRST: Ping-Pong Buffers Reset bit
	 Reset all Ping-Pong Buffer Pointers to the EVEN BD banks Ping-Pong Buffer Pointers not reset
bit 0	USBEN: USB Module Enable bit
	 1 = USB module and supporting circuitry enabled (device attached); D+ pull-up is activated in hardware 0 = USB module and supporting circuitry disabled (device detached)

21.3 Registers

There are four registers used to control programmable CRC operation:

- CRCCON
- CRCXOR
- CRCDAT
- CRCWDAT

REGISTER 21-1: CRCCON: CRC CONTROL REGISTER

U-0	U-0	R/W-0	R-0	R-0	R-0	R-0	R-0
—	—	CSIDL	VWORD4	VWORD3	VWORD2	VWORD1	VWORD0
bit 15							bit 8

R-0	R-1	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CRCFUL	CRCMPT	—	CRCGO	PLEN3	PLEN2	PLEN1	PLEN0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14	Unimplemented: Read as '0'
bit 13	CSIDL: CRC Stop in Idle Mode bit
	1 = Discontinue module operation when device enters Idle mode0 = Continue module operation in Idle mode
bit 12-8	VWORD<4:0>: Pointer Value bits
	Indicates the number of valid words in the FIFO. Has a maximum value of 8 when PLEN<3:0> > 7, or 16 when PLEN<3:0> \leq 7.
bit 7	CRCFUL: FIFO Full bit
	1 = FIFO is full
	0 = FIFO is not full
bit 6	CRCMPT: FIFO Empty Bit
	1 = FIFO is empty
	0 = FIFO is not empty
bit 5	Unimplemented: Read as '0'
bit 4	CRCGO: Start CRC bit
	1 = Start CRC serial shifter
	0 = CRC serial shifter turned off
bit 3-0	PLEN<3:0>: Polynomial Length bits
	Denotes the length of the polynomial to be generated minus 1.

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0				
_	—	_	—	—	_	—	—				
bit 15							bit 8				
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
CVREN	CVROE	CVRR	CVRSS	CVR3	CVR2	CVR1	CVR0				
bit 7							bit (
Legend: R = Readab	lo hit	W = Writable	hit	II – Unimplom	onted hit read	d ac 'O'					
				U = Unimplem							
-n = Value a	IT POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	IOWN				
bit 15-8	Unimplemen	ted: Read as '	0'								
bit 7	CVREN: Comparator Voltage Reference Enable bit										
	1 = CVREF circuit powered on										
	0 = CVREF circuit powered down										
bit 6	CVROE: Comparator VREF Output Enable bit										
	1 = CVREF voltage level is output on CVREF pin										
	0 = CVREF voltage level is disconnected from CVREF pin										
bit 5	CVRR: Comparator VREF Range Selection bit										
	 1 = CVRSRC range should be 0 to 0.625 CVRSRC with CVRSRC/24 step size 0 = CVRSRC range should be 0.25 to 0.719 CVRSRC with CVRSRC/32 step size 										
		•			JVRSRC/32 ste	p size					
bit 4	CVRSS: Comparator VREF Source Selection bit										
 1 = Comparator reference source CVRSRC = VREF+ – VREF- 0 = Comparator reference source CVRSRC = AVDD – AVSS 											
bit 3-0	CVR<3:0>: Comparator VREF Value Selection $0 \le CVR3:CVR0 \le 15$ bits										
	When $CVRR = 1$:										
	$\frac{\text{VHen CVRR} - 1}{\text{CVRFF}} = (\text{CVR} < 3:0 > /24) \bullet (\text{CVRSRC})$										
	When CVRR = 0:										
	CVREF = 1/4										

REGISTER 24-1: CVRCON: COMPARATOR VOLTAGE REFERENCE CONTROL REGISTER

26.0 SPECIAL FEATURES

- Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the following sections of the "PIC24F Family Reference Manual":
 Section 9. "Watchdog Timer (WDT)" (DS39697)
 - Section 32. "High-Level Device Integration" (DS39719)
 - Section 33. "Programming and Diagnostics" (DS39716)

PIC24FJ256GB110 family devices include several features intended to maximize application flexibility and reliability, and minimize cost through elimination of external components. These are:

- · Flexible Configuration
- Watchdog Timer (WDT)
- Code Protection
- · JTAG Boundary Scan Interface
- In-Circuit Serial Programming
- In-Circuit Emulation

26.1 Configuration Bits

The Configuration bits can be programmed (read as '0'), or left unprogrammed (read as '1'), to select various device configurations. These bits are mapped starting at program memory location F80000h. A detailed explanation of the various bit functions is provided in Register 26-1 through Register 26-5.

Note that address F80000h is beyond the user program memory space. In fact, it belongs to the configuration memory space (800000h-FFFFFFh) which can only be accessed using table reads and table writes.

26.1.1 CONSIDERATIONS FOR CONFIGURING PIC24FJ256GB110 FAMILY DEVICES

In PIC24FJ256GB110 family devices, the configuration bytes are implemented as volatile memory. This means that configuration data must be programmed each time the device is powered up. Configuration data is stored in the three words at the top of the on-chip program memory space, known as the Flash Configuration Words. Their specific locations are shown in Table 26-1. These are packed representations of the actual device Configuration bits, whose actual locations are distributed among several locations in configuration space. The configuration data is automatically loaded from the Flash Configuration Words to the proper Configuration registers during device Resets.

Note: Configuration data is reloaded on all types of device Resets.

When creating applications for these devices, users should always specifically allocate the location of the Flash Configuration Word for configuration data. This is to make certain that program code is not stored in this address when the code is compiled.

The upper byte of all Flash Configuration Words in program memory should always be '1111 1111'. This makes them appear to be NOP instructions in the remote event that their locations are ever executed by accident. Since Configuration bits are not implemented in the corresponding locations, writing '1's to these locations has no effect on device operation.

Note: Performing a page erase operation on the last page of program memory clears the Flash Configuration Words, enabling code protection as a result. Therefore, users should avoid performing page erase operations on the last page of program memory.

TABLE 26-1: FLASH CONFIGURATION WORD LOCATIONS FOR PIC24FJ256GB110 FAMILY DEVICES

Device	Co	Configuration Word Addresses				
Device	1	2	3			
PIC24FJ64GB1	ABFEh	ABFCh	ABFAh			
PIC24FJ128GB1	157FEh	157FC	157FA			
PIC24FJ192GB1	20BFEh	20BFC	20BFA			
PIC24FJ256GB1	2ABFEh	2ABFC	2ABFA			

26.2.2 ON-CHIP REGULATOR AND POR

When the voltage regulator is enabled, it takes approximately 10 μ s for it to generate output. During this time, designated as TVREG, code execution is disabled. TVREG is applied every time the device resumes operation after any power-down, including Sleep mode. The length of TVREG is determined by the PMSLP bit (RCON<8>), as described in Section 26.2.5 "Voltage Regulator Standby Mode".

If the regulator is disabled, a separate Power-up Timer (PWRT) is automatically enabled. The PWRT adds a fixed delay of 64 ms nominal delay at device start-up (POR or BOR only). When waking up from Sleep with the regulator disabled, the PMSLP bit determines the wake-up time. When operating with the regulator disabled, setting PMSLP can decrease the device wake-up time.

26.2.3 ON-CHIP REGULATOR AND BOR

When the on-chip regulator is enabled, PIC24FJ256GB110 family devices also have a simple brown-out capability. If the voltage supplied to the regulator is inadequate to maintain the tracking level, the regulator Reset circuitry will generate a Brown-out Reset. This event is captured by the BOR flag bit (RCON<1>). The brown-out voltage specifications are provided in the *"PIC24FJ Family Reference Manual"*, **Section 7. "Reset"** (DS39712).

26.2.4 POWER-UP REQUIREMENTS

The on-chip regulator is designed to meet the power-up requirements for the device. If the application does not use the regulator, then strict power-up conditions must be adhered to. While powering up, VDDCORE must never exceed VDD by 0.3 volts.

Note: For more information, see Section 29.0 "Electrical Characteristics".

26.2.5 VOLTAGE REGULATOR STANDBY MODE

When enabled, the on-chip regulator always consumes a small incremental amount of current over IDD/IPD, including when the device is in Sleep mode, even though the core digital logic does not require power. To provide additional savings in applications where power resources are critical, the regulator automatically disables itself whenever the device goes into Sleep mode. This feature is controlled by the PMSLP bit (RCON<8>). By default, the bit is cleared, which removes power from the Flash program memory and thus enables Standby mode. When waking up from Standby mode, the regulator must wait for TVREG to expire before wake-up. This extra time is needed to ensure that the regulator can source enough current to power the Flash memory. For applications which require a faster wake-up time, it is possible to disable regulator Standby mode. The PMSLP bit can be set to turn off Standby mode so that the Flash stays powered when in Sleep mode and the device can wake-up without waiting for TVREG. When PMSLP is set, the power consumption while in Sleep mode, will be approximately 40 μ A higher than power consumption when the regulator is allowed to enter Standby mode.

26.3 Watchdog Timer (WDT)

For PIC24FJ256GB110 family devices, the WDT is driven by the LPRC Oscillator. When the WDT is enabled, the clock source is also enabled.

The nominal WDT clock source from LPRC is 31 kHz. This feeds a prescaler that can be configured for either 5-bit (divide-by-32) or 7-bit (divide-by-128) operation. The prescaler is set by the FWPSA Configuration bit. With a 31 kHz input, the prescaler yields a nominal WDT time-out period (TWDT) of 1 ms in 5-bit mode, or 4 ms in 7-bit mode.

A variable postscaler divides down the WDT prescaler output and allows for a wide range of time-out periods. The postscaler is controlled by the WDTPS<3:0> Configuration bits (CW1<3:0>), which allow the selection of a total of 16 settings, from 1:1 to 1:32,768. Using the prescaler and postscaler, time-out periods ranging from 1 ms to 131 seconds can be achieved.

The WDT, prescaler and postscaler are reset:

- · On any device Reset
- On the completion of a clock switch, whether invoked by software (i.e., setting the OSWEN bit after changing the NOSC bits) or by hardware (i.e., Fail-Safe Clock Monitor)
- When a PWRSAV instruction is executed (i.e., Sleep or Idle mode is entered)
- When the device exits Sleep or Idle mode to resume normal operation
- By a CLRWDT instruction during normal execution

If the WDT is enabled, it will continue to run during Sleep or Idle modes. When the WDT time-out occurs, the device will wake the device and code execution will continue from where the PWRSAV instruction was executed. The corresponding SLEEP or IDLE bits (RCON<3:2>) will need to be cleared in software after the device wakes up.

The WDT Flag bit, WDTO (RCON<4>), is not automatically cleared following a WDT time-out. To detect subsequent WDT events, the flag must be cleared in software.

Note: The CLRWDT and PWRSAV instructions clear the prescaler and postscaler counts when executed.

Assembly Mnemonic	Assembly Syntax		Description	# of Words	# of Cycles	Status Flags Affected
TBLRDH	TBLRDH	Ws,Wd	Read Prog<23:16> to Wd<7:0>	1	2	None
TBLRDL	TBLRDL	Ws,Wd	Read Prog<15:0> to Wd	1	2	None
TBLWTH	TBLWTH	Ws,Wd	Write Ws<7:0> to Prog<23:16>	1	2	None
TBLWTL	TBLWTL	Ws,Wd	Write Ws to Prog<15:0>	1	2	None
ULNK	ULNK		Unlink Frame Pointer	1	1	None
XOR	XOR	f	f = f .XOR. WREG	1	1	N, Z
	XOR	f,WREG	WREG = f .XOR. WREG	1	1	N, Z
	XOR	#lit10,Wn	Wd = lit10 .XOR. Wd	1	1	N, Z
	XOR	Wb,Ws,Wd	Wd = Wb .XOR. Ws	1	1	N, Z
	XOR	Wb,#lit5,Wd	Wd = Wb .XOR. lit5	1	1	N, Z
ZE	ZE	Ws,Wnd	Wnd = Zero-Extend Ws	1	1	C, Z, N

TABLE 28-2: INSTRUCTION SET OVERVIEW (CONTINUED)

DC CHARACTERISTICS		Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)					
			Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial				
Param No.	Sym	Characteristic	Min	Typ ⁽¹⁾	Мах	Units	Conditions
	VIL	Input Low Voltage ⁽⁴⁾					
DI10		I/O Pins with ST Buffer	Vss	_	0.2 VDD	V	
DI11		I/O Pins with TTL Buffer	Vss	_	0.15 VDD	V	
DI15		MCLR	Vss	_	0.2 VDD	V	
DI16		OSC1 (XT mode)	Vss	_	0.2 VDD	V	
DI17		OSC1 (HS mode)	Vss	_	0.2 VDD	V	
DI18		I/O Pins with I ² C™ Buffer:	Vss	_	0.3 VDD	V	
DI19		I/O Pins with SMBus Buffer:	Vss	_	0.8	V	SMBus enabled
	VIH	Input High Voltage ⁽⁴⁾					
DI20		I/O Pins with ST Buffer: with Analog Functions, Digital Only	0.8 Vdd 0.8 Vdd	_	VDD 5.5	V V	
DI21		I/O Pins with TTL Buffer: with Analog Functions, Digital Only	0.25 Vdd + 0.8 0.25 Vdd + 0.8	_	VDD 5.5	V V	
DI25		MCLR	0.8 VDD	_	Vdd	V	
DI26		OSC1 (XT mode)	0.7 Vdd	_	Vdd	V	
DI27		OSC1 (HS mode)	0.7 Vdd	_	Vdd	V	
DI28		I/O Pins with I ² C Buffer: with Analog Functions, Digital Only	0.7 Vdd 0.7 Vdd	_	VDD 5.5	V V	
DI29		I/O Pins with SMBus Buffer: with Analog Functions, Digital Only	2.1 2.1		VDD 5.5	V V	$2.5V \le VPIN \le VDD$
DI30	ICNPU	CNxx Pull-up Current	50	250	400	μA	VDD = 3.3V, VPIN = VSS
DI30A	ICNPD	CNxx Pull-Down Current	—	80	_	μA	VDD = 3.3V, VPIN = VDD
	lı∟	Input Leakage Current ^(2,3)					
DI50		I/O Ports	—	—	<u>+</u> 1	μA	Vss ≤ VPIN ≤ VDD, Pin at high-impedance
DI51		Analog Input Pins	—	—	<u>+</u> 1	μA	$Vss \le VPIN \le VDD,$ Pin at high-impedance
DI52		USB Differential Pins (D+, D-)	—	—	<u>+</u> 1	μΑ	$V \text{USB} \geq V \text{DD}$
DI55		MCLR	_	—	<u>+</u> 1	μA	$Vss \leq V \text{PIN} \leq V \text{DD}$
DI56		OSC1	—	_	<u>+</u> 1	μA	$\label{eq:VSS} \begin{split} &V{\sf SS} \leq V{\sf PIN} \leq V{\sf DD}, \\ &X{\sf T} \text{ and } H{\sf S} \text{ modes} \end{split}$

TABLE 29-7: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS

Note 1: Data in "Typ" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

2: The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.

3: Negative current is defined as current sourced by the pin.

4: Refer to Table 1-4 for I/O pins buffer types.

APPENDIX A: REVISION HISTORY

Revision A (October 2007)

Original data sheet for the PIC24FJ256GB110 family of devices.

Revision B (March 2008)

Changes to **Section 29.0 "Electrical Characteristics"** and minor edits to text throughout document.

Revision C (December 2009)

Updates all Pin Diagrams to reflect the correct order of priority for multiplexed peripherals.

Adds packaging information for the new 64-pin QFN package to **Section 30.0** "**Packaging Information**" and the Product Information System.

Updates **Section 5.0 "Flash Program Memory"** with revised code examples in assembler, and new code examples in C.

Updates **Section 6.2** "Device Reset Times" with revised information, particularly Table 6-3.

Adds the INTTREG register to Section 4.0 "Memory Organization" and Section 7.0 "Interrupt Controller".

Makes several additions and changes to **Section 10.0** "I/O Ports", including:

- revision of Section 10.4.2.1 "Peripheral Pin Select Function Priority"
- revisions to Table 10-3, "Selectable Output Sources"

Makes several changes and additions to Section 18.0 "Universal Serial Bus with On-The-Go Support (USB OTG)", including:

- changes the name of the bit U1CON<x> from RESET to USBRST
- replaces the former Section 18.3 with Section 18.1 "Hardware Configuration", including an expanded discussion of how to interface the microcontroller to application in different USB modes

Updates Section 21.0 "Programmable Cyclic Redundancy Check (CRC) Generator" with new illustrations, and a revised Section 21.1 "User Interface".

Updates Section 22.0 "10-Bit High-Speed A/D Converter" by changing all references to AD1CHS0, to AD1CHS (as well as other locations in the document). Also revises bit field descriptions in registers, AD1CON3 (bits 7:0) and AD1CHS (bits 12:8).

Makes minor text edits to bit descriptions in Section 23.0 "Triple Comparator Module" (Register 23-1) and Section 25.0 "Charge Time Measurement Unit (CTMU)" (Register 25-1). Updates **Section 26.0** "**Special Features**" with revised text on the operation of the regulator during POR and Standby mode.

Updates **Section 26.5 "JTAG Interface"** to remove references to programming via the interface.

Makes multiple additions and changes to **Section 29.0** "Electrical Characteristics", including:

- Addition of IPD specifications for operation at 60°C
- New DC characteristics of VBOR, VBG, TBG and ICNPD
- Addition of new VPEW specification for VDDCORE
- New AC characteristics for internal oscillator start-up time (TLPRC)
- Combination of all Internal RC accuracy information into a single table

Makes other minor typographic corrections throughout the text.