



Welcome to [E-XFL.COM](#)

### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

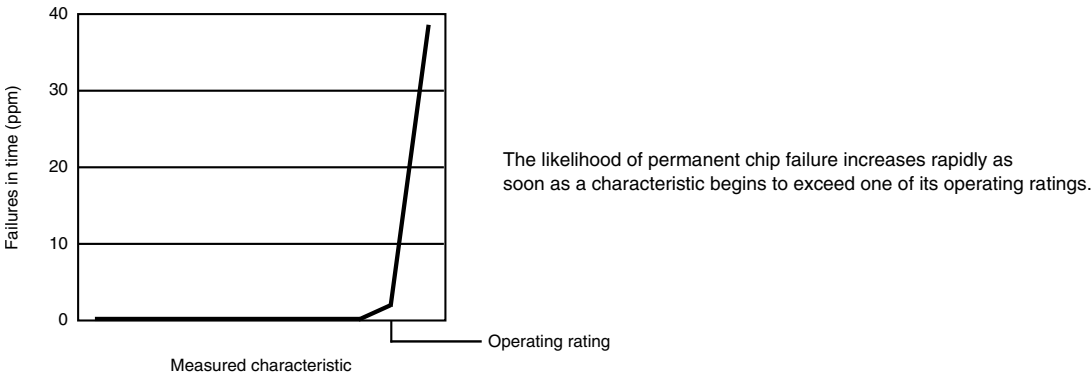
Product Status	Obsolete
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	50MHz
Connectivity	I <sup>2</sup> C, IrDA, SPI, UART/USART, USB, USB OTG
Peripherals	DMA, I <sup>2</sup> S, LVD, POR, PWM, WDT
Number of I/O	60
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	64K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 3.6V
Data Converters	A/D 20x16b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	80-LQFP
Supplier Device Package	80-FQFP (12x12)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/nxp-semiconductors/mk21dn512vlk5">https://www.e-xfl.com/product-detail/nxp-semiconductors/mk21dn512vlk5</a>

### 3.4.1 Example

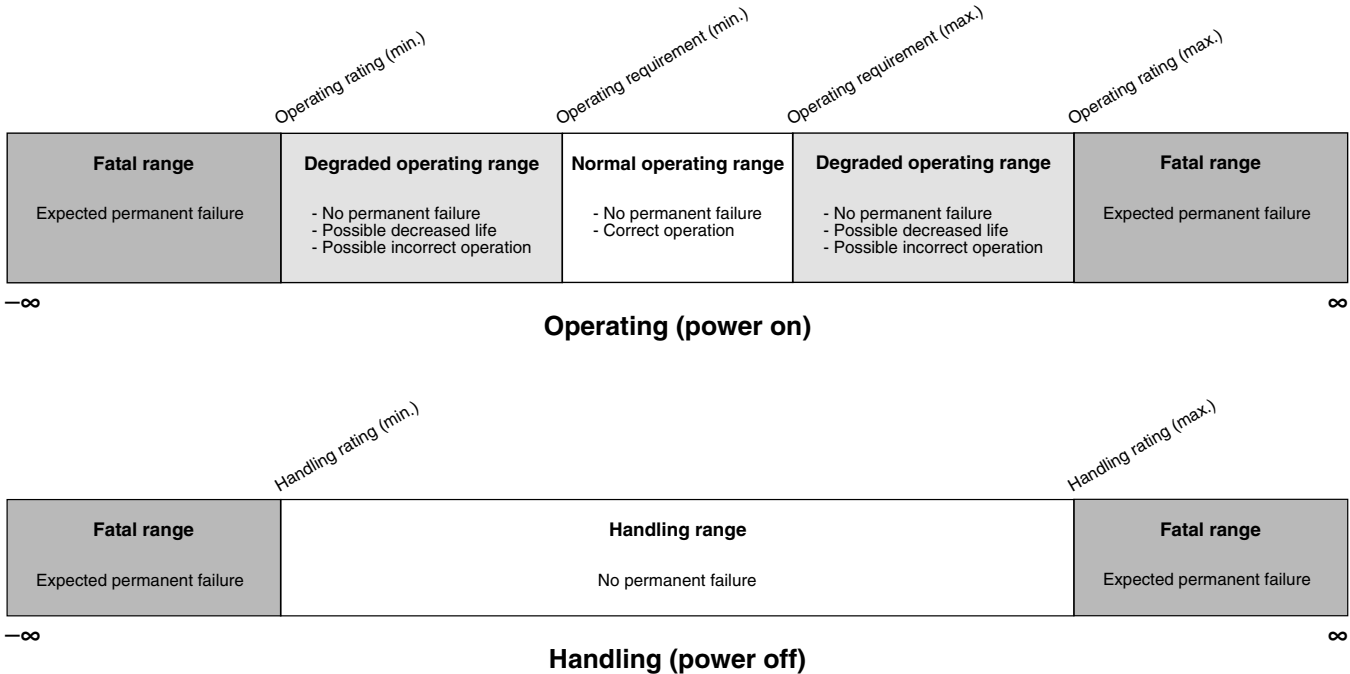
This is an example of an operating rating:

Symbol	Description	Min.	Max.	Unit
V <sub>DD</sub>	1.0 V core supply voltage	-0.3	1.2	V

### 3.5 Result of exceeding a rating



### 3.6 Relationship between ratings and operating requirements



## 5.1 AC electrical characteristics

Unless otherwise specified, propagation delays are measured from the 50% to the 50% point, and rise and fall times are measured at the 20% and 80% points, as shown in the following figure.

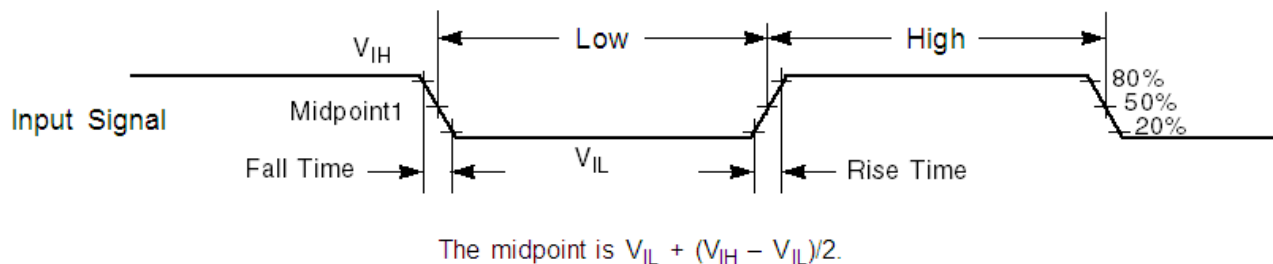


Figure 1. Input signal measurement reference

## 5.2 Nonswitching electrical specifications

### 5.2.1 Voltage and current operating requirements

Table 1. Voltage and current operating requirements

Symbol	Description	Min.	Max.	Unit	Notes
$V_{DD}$	Supply voltage	1.71	3.6	V	
$V_{DDA}$	Analog supply voltage	1.71	3.6	V	
$V_{DD} - V_{DDA}$	$V_{DD}$ -to- $V_{DDA}$ differential voltage	-0.1	0.1	V	
$V_{SS} - V_{SSA}$	$V_{SS}$ -to- $V_{SSA}$ differential voltage	-0.1	0.1	V	
$V_{BAT}$	RTC battery supply voltage	1.71	3.6	V	
$V_{IH}$	Input high voltage <ul style="list-style-type: none"> <li><math>2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}</math></li> <li><math>1.7\text{ V} \leq V_{DD} \leq 2.7\text{ V}</math></li> </ul>	$0.7 \times V_{DD}$	—	V	
		$0.75 \times V_{DD}$	—	V	
$V_{IL}$	Input low voltage <ul style="list-style-type: none"> <li><math>2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}</math></li> <li><math>1.7\text{ V} \leq V_{DD} \leq 2.7\text{ V}</math></li> </ul>	—	$0.35 \times V_{DD}$	V	
		—	$0.3 \times V_{DD}$	V	
$V_{HYS}$	Input hysteresis	$0.06 \times V_{DD}$	—	V	
$I_{CIO}$	I/O pin DC injection current — single pin <ul style="list-style-type: none"> <li><math>V_{IN} &lt; V_{SS}-0.3\text{V}</math> (Negative current injection)</li> <li><math>V_{IN} &gt; V_{DD}+0.3\text{V}</math> (Positive current injection)</li> </ul>	-3	—	mA	1
		—	+3		

Table continues on the next page...

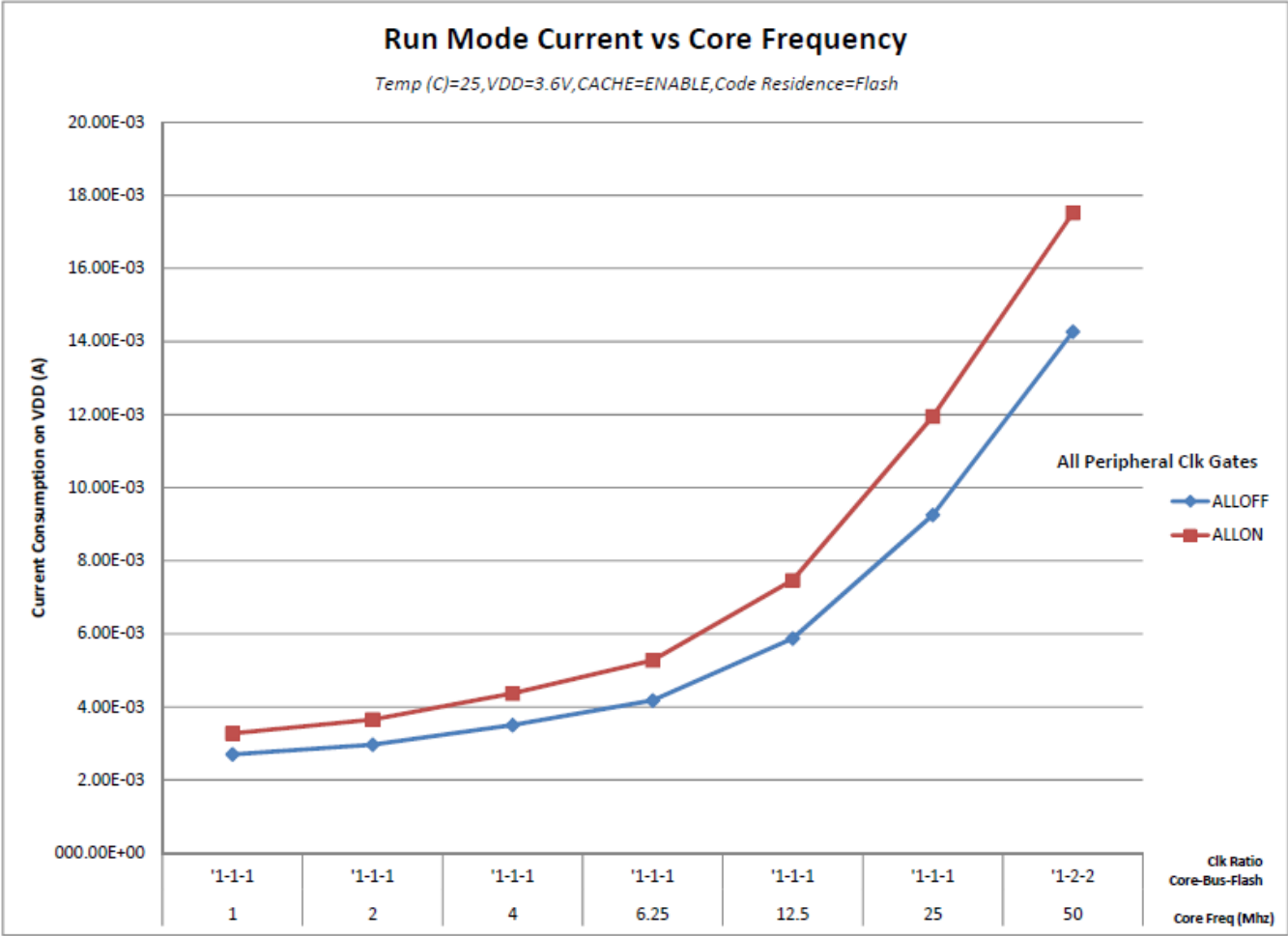


Figure 2. Run mode supply current vs. core frequency

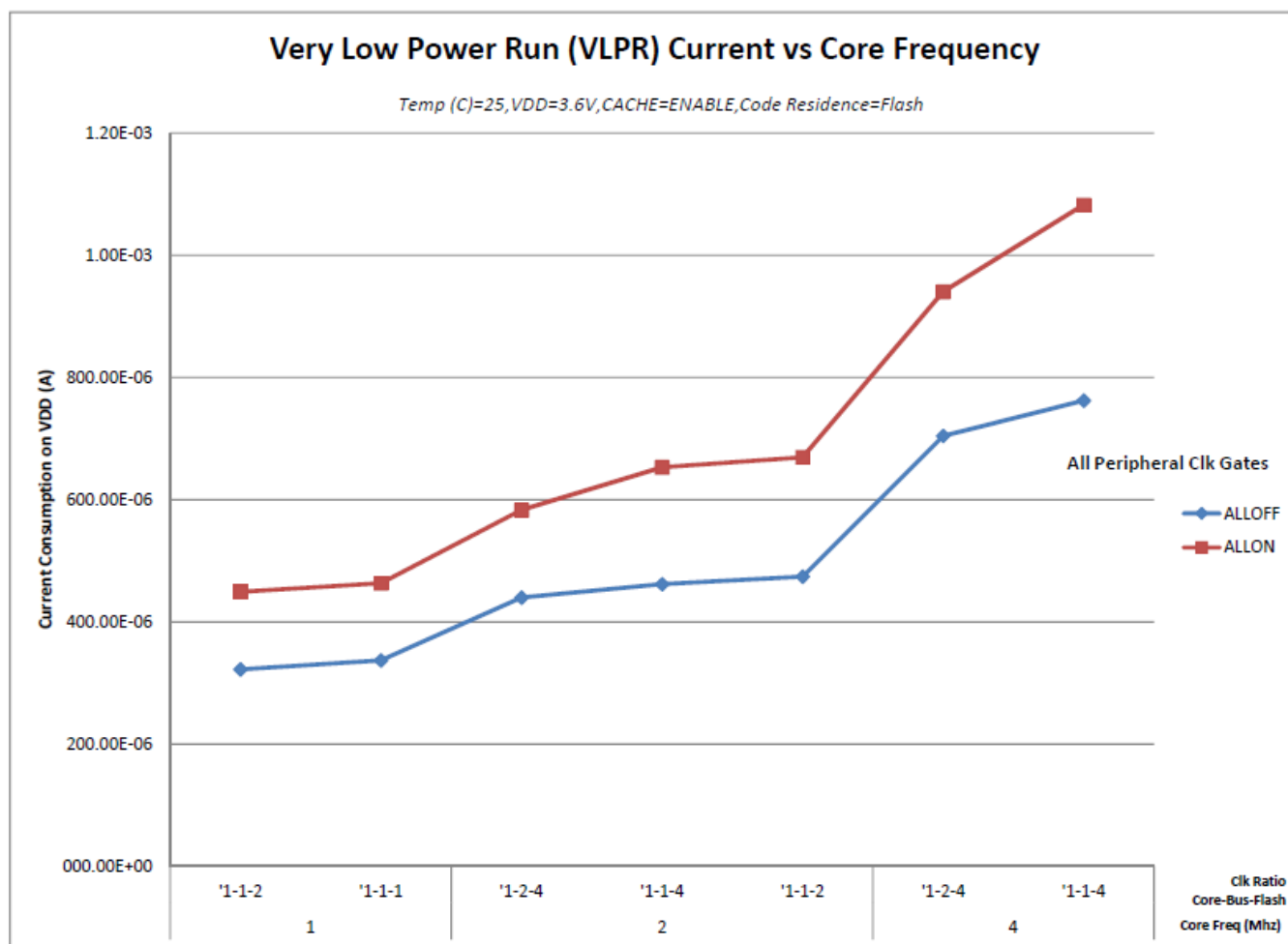


Figure 3. VLPR mode supply current vs. core frequency

## 5.2.6 EMC radiated emissions operating behaviors

Table 7. EMC radiated emissions operating behaviors 1

Symbol	Description	Frequency band (MHz)	Typ.	Unit	Notes
V <sub>RE1</sub>	Radiated emissions voltage, band 1	0.15–50	19	dBμV	2, 3
V <sub>RE2</sub>	Radiated emissions voltage, band 2	50–150	21	dBμV	
V <sub>RE3</sub>	Radiated emissions voltage, band 3	150–500	19	dBμV	
V <sub>RE4</sub>	Radiated emissions voltage, band 4	500–1000	11	dBμV	
V <sub>RE_IEC</sub>	IEC level	0.15–1000	L	—	3, 4

1. This data was collected on a MK20DN128VLH5 64pin LQFP device.
2. Determined according to IEC Standard 61967-1, *Integrated Circuits - Measurement of Electromagnetic Emissions, 150 kHz to 1 GHz Part 1: General Conditions and Definitions* and IEC Standard 61967-2, *Integrated Circuits - Measurement of Electromagnetic Emissions, 150 kHz to 1 GHz Part 2: Measurement of Radiated Emissions—TEM Cell and Wideband TEM Cell Method*. Measurements were made while the microcontroller was running basic application code. The reported emission level is the value of the maximum measured emission, rounded up to the next whole number, from among the measured orientations in each frequency range.

3.  $V_{DD} = 3.3\text{ V}$ ,  $T_A = 25\text{ }^{\circ}\text{C}$ ,  $f_{OSC} = 12\text{ MHz}$  (crystal),  $f_{SYS} = 48\text{ MHz}$ ,  $f_{BUS} = 48\text{ MHz}$
4. Specified according to Annex D of IEC Standard 61967-2, *Measurement of Radiated Emissions—TEM Cell and Wideband TEM Cell Method*

## 5.2.7 Designing with radiated emissions in mind

To find application notes that provide guidance on designing your system to minimize interference from radiated emissions:

1. Go to [www.freescale.com](http://www.freescale.com).
2. Perform a keyword search for “EMC design.”

## 5.2.8 Capacitance attributes

**Table 8. Capacitance attributes**

Symbol	Description	Min.	Max.	Unit
$C_{IN\_A}$	Input capacitance: analog pins	—	7	pF
$C_{IN\_D}$	Input capacitance: digital pins	—	7	pF

## 5.3 Switching specifications

### 5.3.1 Device clock specifications

**Table 9. Device clock specifications**

Symbol	Description	Min.	Max.	Unit	Notes
Normal run mode					
$f_{SYS}$	System and core clock	—	50	MHz	
	System and core clock when Full Speed USB in operation	20	—	MHz	
$f_{BUS}$	Bus clock	—	50	MHz	
$f_{FLASH}$	Flash clock	—	25	MHz	
$f_{LPTMR}$	LPTMR clock	—	25	MHz	
VLPR mode <sup>1</sup>					
$f_{SYS}$	System and core clock	—	4	MHz	
$f_{BUS}$	Bus clock	—	4	MHz	
$f_{FLASH}$	Flash clock	—	1	MHz	
$f_{ERCLK}$	External reference clock	—	16	MHz	
$f_{LPTMR\_pin}$	LPTMR clock	—	25	MHz	

Table continues on the next page...

3. This is the minimum pulse width that is guaranteed to be recognized as a pin interrupt request in Stop, VLPS, LLS, and VLLSx modes.
4. 75 pF load
5. 15 pF load

## 5.4 Thermal specifications

### 5.4.1 Thermal operating requirements

Table 11. Thermal operating requirements

Symbol	Description	Min.	Max.	Unit
$T_J$	Die junction temperature	−40	125	°C
$T_A$	Ambient temperature	−40	105	°C

### 5.4.2 Thermal attributes

Board type	Symbol	Description	80 LQFP	Unit	Notes
Single-layer (1s)	$R_{\theta JA}$	Thermal resistance, junction to ambient (natural convection)	50	°C/W	1, 2
Four-layer (2s2p)	$R_{\theta JA}$	Thermal resistance, junction to ambient (natural convection)	35	°C/W	1, 3
Single-layer (1s)	$R_{\theta JMA}$	Thermal resistance, junction to ambient (200 ft./min. air speed)	39	°C/W	1,3
Four-layer (2s2p)	$R_{\theta JMA}$	Thermal resistance, junction to ambient (200 ft./min. air speed)	29	°C/W	1,3
—	$R_{\theta JB}$	Thermal resistance, junction to board	19	°C/W	4
—	$R_{\theta JC}$	Thermal resistance, junction to case	8	°C/W	5

Table continues on the next page...

**Table 12. JTAG limited voltage range electricals (continued)**

Symbol	Description	Min.	Max.	Unit
J5	Boundary scan input data setup time to TCLK rise	20	—	ns
J6	Boundary scan input data hold time after TCLK rise	0	—	ns
J7	TCLK low to boundary scan output data valid	—	25	ns
J8	TCLK low to boundary scan output high-Z	—	25	ns
J9	TMS, TDI input data setup time to TCLK rise	8	—	ns
J10	TMS, TDI input data hold time after TCLK rise	1	—	ns
J11	TCLK low to TDO data valid	—	17	ns
J12	TCLK low to TDO high-Z	—	17	ns
J13	TRST assert time	100	—	ns
J14	TRST setup time (negation) to TCLK high	8	—	ns

**Table 13. JTAG full voltage range electricals**

Symbol	Description	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V
J1	TCLK frequency of operation <ul style="list-style-type: none"> <li>Boundary Scan</li> <li>JTAG and CJTAG</li> <li>Serial Wire Debug</li> </ul>	0 0 0	10 20 40	MHz
J2	TCLK cycle period	1/J1	—	ns
J3	TCLK clock pulse width <ul style="list-style-type: none"> <li>Boundary Scan</li> <li>JTAG and CJTAG</li> <li>Serial Wire Debug</li> </ul>	50 25 12.5	— — —	ns ns ns
J4	TCLK rise and fall times	—	3	ns
J5	Boundary scan input data setup time to TCLK rise	20	—	ns
J6	Boundary scan input data hold time after TCLK rise	0	—	ns
J7	TCLK low to boundary scan output data valid	—	25	ns
J8	TCLK low to boundary scan output high-Z	—	25	ns
J9	TMS, TDI input data setup time to TCLK rise	8	—	ns
J10	TMS, TDI input data hold time after TCLK rise	1.4	—	ns
J11	TCLK low to TDO data valid	—	22.1	ns
J12	TCLK low to TDO high-Z	—	22.1	ns
J13	TRST assert time	100	—	ns
J14	TRST setup time (negation) to TCLK high	8	—	ns



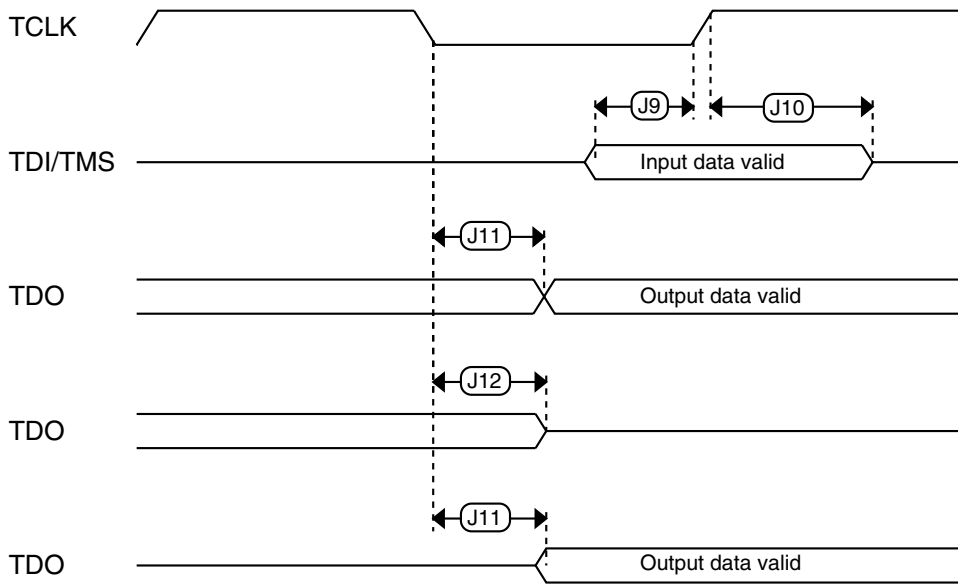


Figure 6. Test Access Port timing

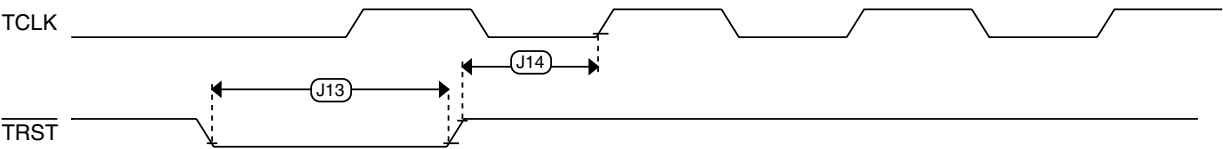


Figure 7.  $\overline{\text{TRST}}$  timing

## 6.2 System modules

There are no specifications necessary for the device's system modules.

## 6.3 Clock modules

**Table 14. MCG specifications (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$J_{cyc\_fll}$	FLL period jitter <ul style="list-style-type: none"> <li><math>f_{DCO} = 48 \text{ MHz}</math></li> <li><math>f_{DCO} = 98 \text{ MHz}</math></li> </ul>	—	180	—	ps	
$t_{fll\_acquire}$	FLL target frequency acquisition time	—	—	1	ms	7
PLL						
$f_{vco}$	VCO operating frequency	48.0	—	100	MHz	
$I_{pll}$	PLL operating current <ul style="list-style-type: none"> <li>PLL @ 96 MHz (<math>f_{osc\_hi\_1} = 8 \text{ MHz}</math>, <math>f_{pll\_ref} = 2 \text{ MHz}</math>, VDIV multiplier = 48)</li> </ul>	—	1060	—	$\mu\text{A}$	8
$I_{pll}$	PLL operating current <ul style="list-style-type: none"> <li>PLL @ 48 MHz (<math>f_{osc\_hi\_1} = 8 \text{ MHz}</math>, <math>f_{pll\_ref} = 2 \text{ MHz}</math>, VDIV multiplier = 24)</li> </ul>	—	600	—	$\mu\text{A}$	8
$f_{pll\_ref}$	PLL reference frequency range	2.0	—	4.0	MHz	
$J_{cyc\_pll}$	PLL period jitter (RMS) <ul style="list-style-type: none"> <li><math>f_{vco} = 48 \text{ MHz}</math></li> <li><math>f_{vco} = 100 \text{ MHz}</math></li> </ul>	—	120	—	ps	9
$J_{acc\_pll}$	PLL accumulated jitter over 1 $\mu\text{s}$ (RMS) <ul style="list-style-type: none"> <li><math>f_{vco} = 48 \text{ MHz}</math></li> <li><math>f_{vco} = 100 \text{ MHz}</math></li> </ul>	—	1350	—	ps	9
$D_{lock}$	Lock entry frequency tolerance	$\pm 1.49$	—	$\pm 2.98$	%	
$D_{unl}$	Lock exit frequency tolerance	$\pm 4.47$	—	$\pm 5.97$	%	
$t_{pll\_lock}$	Lock detector detection time	—	—	$150 \times 10^{-6} + 1075(1/f_{pll\_ref})$	s	10

1. This parameter is measured with the internal reference (slow clock) being used as a reference to the FLL (FEI clock mode).
2.  $2 \text{ V} \leq VDD \leq 3.6 \text{ V}$ .
3. These typical values listed are with the slow internal reference clock (FEI) using factory trim and DMX32=0.
4. The resulting system clock frequencies should not exceed their maximum specified values. The DCO frequency deviation ( $\Delta f_{dco\_t}$ ) over voltage and temperature should be considered.
5. These typical values listed are with the slow internal reference clock (FEI) using factory trim and DMX32=1.
6. The resulting clock frequency must not exceed the maximum specified clock frequency of the device.
7. This specification applies to any time the FLL reference source or reference divider is changed, trim value is changed, DMX32 bit is changed, DRS bits are changed, or changing from FLL disabled (BLPE, BLPI) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.
8. Excludes any oscillator currents that are also consuming power while PLL is in operation.
9. This specification was obtained using a Freescale developed PCB. PLL jitter is dependent on the noise characteristics of each PCB and results will vary.
10. This specification applies to any time the PLL VCO divider or reference divider is changed, or changing from PLL disabled (BLPE, BLPI) to PLL enabled (PBE, PEE). If a crystal/resonator is being used as the reference, this specification assumes it is already running.

## 6.3.2 Oscillator electrical specifications

### 6.4.1.1 Flash timing specifications — program and erase

The following specifications represent the amount of time the internal charge pumps are active and do not include command overhead.

**Table 19. NVM program/erase timing specifications**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$t_{hvp\text{gm}4}$	Longword Program high-voltage time	—	7.5	18	$\mu\text{s}$	
$t_{h\text{versscr}}$	Sector Erase high-voltage time	—	13	113	ms	1
$t_{h\text{versblk}256\text{k}}$	Erase Block high-voltage time for 256 KB	—	104	904	ms	1

1. Maximum time based on expectations at cycling end-of-life.

### 6.4.1.2 Flash timing specifications — commands

**Table 20. Flash command timing specifications**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$t_{\text{rd}1\text{blk}64\text{k}}$	Read 1s Block execution time • 64 KB data flash	—	—	0.9	ms	
$t_{\text{rd}1\text{blk}256\text{k}}$	• 256 KB program flash	—	—	1.7	ms	
$t_{\text{rd}1\text{sec}2\text{k}}$	Read 1s Section execution time (flash sector)	—	—	60	$\mu\text{s}$	1
$t_{\text{pgmchk}}$	Program Check execution time	—	—	45	$\mu\text{s}$	1
$t_{\text{rd}r\text{src}}$	Read Resource execution time	—	—	30	$\mu\text{s}$	1
$t_{\text{pgm}4}$	Program Longword execution time	—	65	145	$\mu\text{s}$	
$t_{\text{ersblk}64\text{k}}$	Erase Flash Block execution time • 64 KB data flash	—	58	580	ms	2
$t_{\text{ersblk}256\text{k}}$	• 256 KB program flash	—	122	985	ms	
$t_{\text{ersscr}}$	Erase Flash Sector execution time	—	14	114	ms	2
$t_{\text{pgmsec}512}$	Program Section execution time • 512 bytes flash	—	2.4	—	ms	
$t_{\text{pgmsec}1\text{k}}$	• 1 KB flash	—	4.7	—	ms	
$t_{\text{pgmsec}2\text{k}}$	• 2 KB flash	—	9.3	—	ms	
$t_{\text{rd}1\text{all}}$	Read 1s All Blocks execution time	—	—	1.8	ms	
$t_{\text{rdonce}}$	Read Once execution time	—	—	25	$\mu\text{s}$	1
$t_{\text{pgmonce}}$	Program Once execution time	—	65	—	$\mu\text{s}$	
$t_{\text{ersall}}$	Erase All Blocks execution time	—	250	2000	ms	2
$t_{\text{vfykey}}$	Verify Backdoor Access Key execution time	—	—	30	$\mu\text{s}$	1

Table continues on the next page...

**Table 20. Flash command timing specifications (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$t_{\text{swapx01}}$	Swap Control execution time	—	200	—	$\mu\text{s}$	
$t_{\text{swapx02}}$	• control code 0x02	—	70	150	$\mu\text{s}$	
$t_{\text{swapx04}}$	• control code 0x04	—	70	150	$\mu\text{s}$	
$t_{\text{swapx08}}$	• control code 0x08	—	—	30	$\mu\text{s}$	
$t_{\text{pgmpart64k}}$	Program Partition for EEPROM execution time	—	138	—	ms	
$t_{\text{setramff}}$	Set FlexRAM Function execution time:	—	70	—	$\mu\text{s}$	
$t_{\text{setram32k}}$	• 32 KB EEPROM backup	—	0.8	1.2	ms	
$t_{\text{setram64k}}$	• 64 KB EEPROM backup	—	1.3	1.9	ms	
Byte-write to FlexRAM for EEPROM operation						
$t_{\text{eewr8bers}}$	Byte-write to erased FlexRAM location execution time	—	175	260	$\mu\text{s}$	3
$t_{\text{eewr8b32k}}$	Byte-write to FlexRAM execution time:	—	385	1800	$\mu\text{s}$	
$t_{\text{eewr8b64k}}$	• 32 KB EEPROM backup	—	475	2000	$\mu\text{s}$	
	• 64 KB EEPROM backup	—	475	2000	$\mu\text{s}$	
Word-write to FlexRAM for EEPROM operation						
$t_{\text{eewr16bers}}$	Word-write to erased FlexRAM location execution time	—	175	260	$\mu\text{s}$	
$t_{\text{eewr16b32k}}$	Word-write to FlexRAM execution time:	—	385	1800	$\mu\text{s}$	
$t_{\text{eewr16b64k}}$	• 32 KB EEPROM backup	—	475	2000	$\mu\text{s}$	
	• 64 KB EEPROM backup	—	475	2000	$\mu\text{s}$	
Longword-write to FlexRAM for EEPROM operation						
$t_{\text{eewr32bers}}$	Longword-write to erased FlexRAM location execution time	—	360	540	$\mu\text{s}$	
$t_{\text{eewr32b32k}}$	Longword-write to FlexRAM execution time:	—	630	2050	$\mu\text{s}$	
$t_{\text{eewr32b64k}}$	• 32 KB EEPROM backup	—	810	2250	$\mu\text{s}$	
	• 64 KB EEPROM backup	—	810	2250	$\mu\text{s}$	

1. Assumes 25 MHz flash clock frequency.
2. Maximum times for erase parameters based on expectations at cycling end-of-life.
3. For byte-writes to an erased FlexRAM location, the aligned word containing the byte must be erased.

### 6.4.1.3 Flash high voltage current behaviors

Table 21. Flash high voltage current behaviors

Symbol	Description	Min.	Typ.	Max.	Unit
I <sub>DD_PGM</sub>	Average current adder during high voltage flash programming operation	—	2.5	6.0	mA
I <sub>DD_ERS</sub>	Average current adder during high voltage flash erase operation	—	1.5	4.0	mA

### 6.4.1.4 Reliability specifications

Table 22. NVM reliability specifications

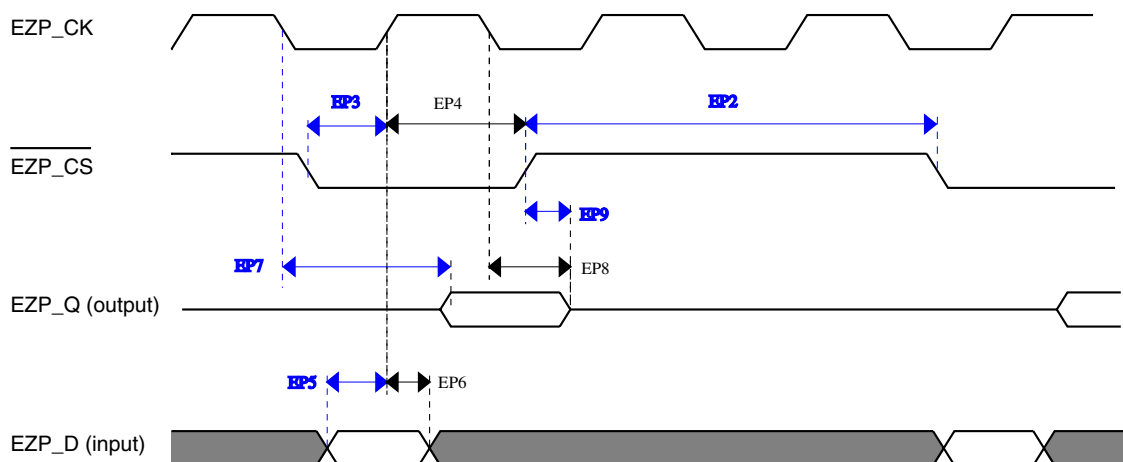
Symbol	Description	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
Program Flash						
t <sub>nvmretp10k</sub>	Data retention after up to 10 K cycles	5	50	—	years	
t <sub>nvmretp1k</sub>	Data retention after up to 1 K cycles	20	100	—	years	
n <sub>nvmcycp</sub>	Cycling endurance	10 K	50 K	—	cycles	2
Data Flash						
t <sub>nvmretd10k</sub>	Data retention after up to 10 K cycles	5	50	—	years	
t <sub>nvmretd1k</sub>	Data retention after up to 1 K cycles	20	100	—	years	
n <sub>nvmcycd</sub>	Cycling endurance	10 K	50 K	—	cycles	2
FlexRAM as EEPROM						
t <sub>nvmreteee100</sub>	Data retention up to 100% of write endurance	5	50	—	years	
t <sub>nvmreteee10</sub>	Data retention up to 10% of write endurance	20	100	—	years	
n <sub>nvmwree16</sub>	Write endurance	35 K	175 K	—	writes	3
n <sub>nvmwree128</sub>	• EEPROM backup to FlexRAM ratio = 16	315 K	1.6 M	—	writes	
n <sub>nvmwree512</sub>	• EEPROM backup to FlexRAM ratio = 128	1.27 M	6.4 M	—	writes	
n <sub>nvmwree4k</sub>	• EEPROM backup to FlexRAM ratio = 512	10 M	50 M	—	writes	

1. Typical data retention values are based on measured response accelerated at high temperature and derated to a constant 25 °C use profile. Engineering Bulletin EB618 does not apply to this technology. Typical endurance defined in Engineering Bulletin EB619.
2. Cycling endurance represents number of program/erase cycles at -40 °C ≤ T<sub>j</sub> ≤ °C.
3. Write endurance represents the number of writes to each FlexRAM location at -40 °C ≤ T<sub>j</sub> ≤ °C influenced by the cycling endurance of the FlexNVM (same value as data flash) and the allocated EEPROM backup per subsystem. Minimum and typical values assume all byte-writes to FlexRAM.

## 6.4.2 EzPort switching specifications

**Table 23. EzPort switching specifications**

Num	Description	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V
EP1	EZP_CK frequency of operation (all commands except READ)	—	$f_{SYS}/2$	MHz
EP1a	EZP_CK frequency of operation (READ command)	—	$f_{SYS}/8$	MHz
EP2	EZP_CS negation to next EZP_CS assertion	$2 \times t_{EZP\_CK}$	—	ns
EP3	EZP_CS input valid to EZP_CK high (setup)	5	—	ns
EP4	EZP_CK high to EZP_CS input invalid (hold)	5	—	ns
EP5	EZP_D input valid to EZP_CK high (setup)	2	—	ns
EP6	EZP_CK high to EZP_D input invalid (hold)	5	—	ns
EP7	EZP_CK low to EZP_Q output valid	—	—	ns
EP8	EZP_CK low to EZP_Q output invalid (hold)	0	—	ns
EP9	EZP_CS negation to EZP_Q tri-state	—	12	ns



**Figure 8. EzPort Timing Diagram**

## 6.5 Security and integrity modules

## 6.5.1 DryIce Tamper Electrical Specifications

Information about security-related modules is not included in this document and is available only after a nondisclosure agreement (NDA) has been signed. To request an NDA, please contact your local Freescale sales representative.

## 6.6 Analog

### 6.6.1 ADC electrical specifications

The 16-bit accuracy specifications listed in [Table 24](#) and [Table 25](#) are achievable on the differential pins ADCx\_DP0, ADCx\_DM0.

All other ADC channels meet the 13-bit differential/12-bit single-ended accuracy specifications.

#### 6.6.1.1 16-bit ADC operating conditions

**Table 24. 16-bit ADC operating conditions**

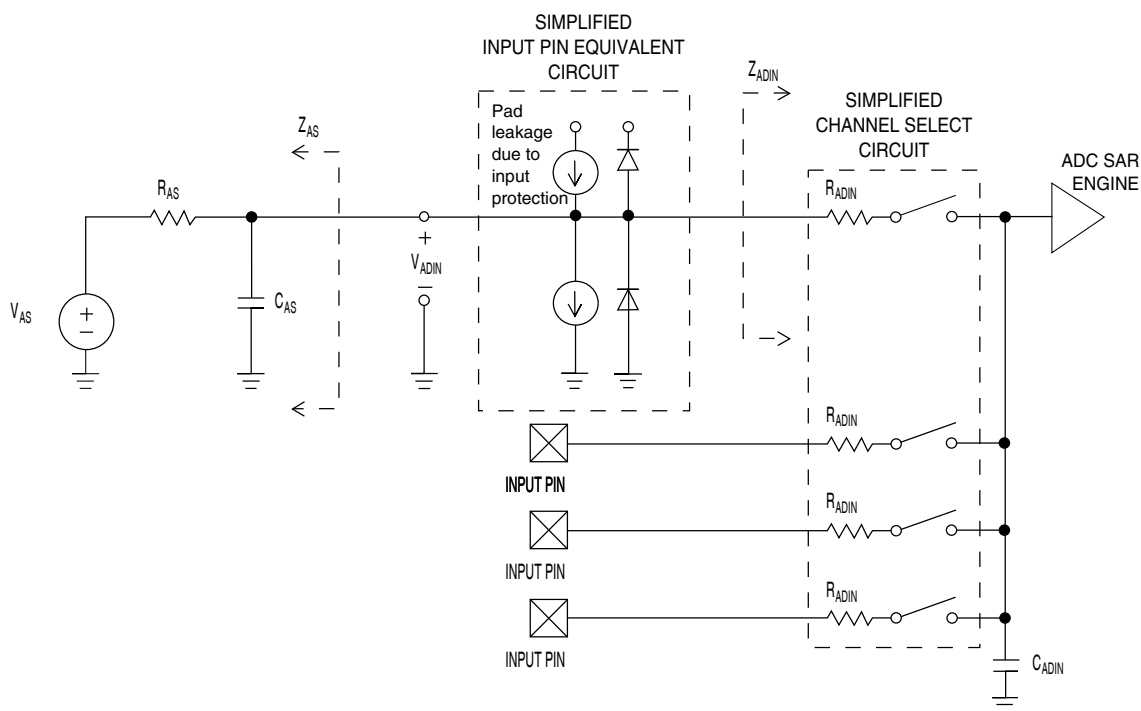
Symbol	Description	Conditions	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
$V_{DDA}$	Supply voltage	Absolute	1.71	—	3.6	V	
$\Delta V_{DDA}$	Supply voltage	Delta to $V_{DD}$ ( $V_{DD} - V_{DDA}$ )	-100	0	+100	mV	<a href="#">2</a>
$\Delta V_{SSA}$	Ground voltage	Delta to $V_{SS}$ ( $V_{SS} - V_{SSA}$ )	-100	0	+100	mV	<a href="#">2</a>
$V_{REFH}$	ADC reference voltage high		1.13	$V_{DDA}$	$V_{DDA}$	V	
$V_{REFL}$	ADC reference voltage low		$V_{SSA}$	$V_{SSA}$	$V_{SSA}$	V	
$V_{ADIN}$	Input voltage	<ul style="list-style-type: none"> <li>16-bit differential mode</li> <li>All other modes</li> </ul>	$V_{REFL}$ $V_{REFL}$	— —	31/32 * $V_{REFH}$ $V_{REFH}$	V	
$C_{ADIN}$	Input capacitance	<ul style="list-style-type: none"> <li>16-bit mode</li> <li>8-bit / 10-bit / 12-bit modes</li> </ul>	— —	8 4	10 5	pF	
$R_{ADIN}$	Input resistance		—	2	5	k $\Omega$	
$R_{AS}$	Analog source resistance	13-bit / 12-bit modes $f_{ADCK} < 4$ MHz	—	—	5	k $\Omega$	<a href="#">3</a>
$f_{ADCK}$	ADC conversion clock frequency	$\leq$ 13-bit mode	1.0	—	18.0	MHz	<a href="#">4</a>
$f_{ADCK}$	ADC conversion clock frequency	16-bit mode	2.0	—	12.0	MHz	<a href="#">4</a>

Table continues on the next page...

**Table 24. 16-bit ADC operating conditions (continued)**

Symbol	Description	Conditions	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
$C_{rate}$	ADC conversion rate	$\leq 13$ -bit modes No ADC hardware averaging Continuous conversions enabled, subsequent conversion time	20.000	—	818.330	Ksps	5
$C_{rate}$	ADC conversion rate	16-bit mode No ADC hardware averaging Continuous conversions enabled, subsequent conversion time	37.037	—	461.467	Ksps	5

1. Typical values assume  $V_{DDA} = 3.0$  V, Temp = 25 °C,  $f_{ADCK} = 1.0$  MHz, unless otherwise stated. Typical values are for reference only, and are not tested in production.
2. DC potential difference.
3. This resistance is external to MCU. To achieve the best results, the analog source resistance must be kept as low as possible. The results in this data sheet were derived from a system that had  $< 8 \Omega$  analog source resistance. The  $R_{AS}/C_{AS}$  time constant should be kept to  $< 1$  ns.
4. To use the maximum ADC conversion clock frequency, CFG2[ADHSC] must be set and CFG1[ADLPC] must be clear.
5. For guidelines and examples of conversion rate calculation, download the [ADC calculator tool](#).



**Figure 9. ADC input impedance equivalency diagram**



## 6.8.2 USB DCD electrical specifications

**Table 27. USB DCD electrical specifications**

Symbol	Description	Min.	Typ.	Max.	Unit
V <sub>DP_SRC</sub>	USB_DP source voltage (up to 250 $\mu$ A)	0.5	—	0.7	V
V <sub>LGC</sub>	Threshold voltage for logic high	0.8	—	2.0	V
I <sub>DP_SRC</sub>	USB_DP source current	7	10	13	$\mu$ A
I <sub>DM_SINK</sub>	USB_DM sink current	50	100	150	$\mu$ A
R <sub>DM_DWN</sub>	D- pulldown resistance for data pin contact detect	14.25	—	24.8	k $\Omega$
V <sub>DAT_REF</sub>	Data detect voltage	0.25	0.33	0.4	V

## 6.8.3 VREG electrical specifications

**Table 28. VREG electrical specifications**

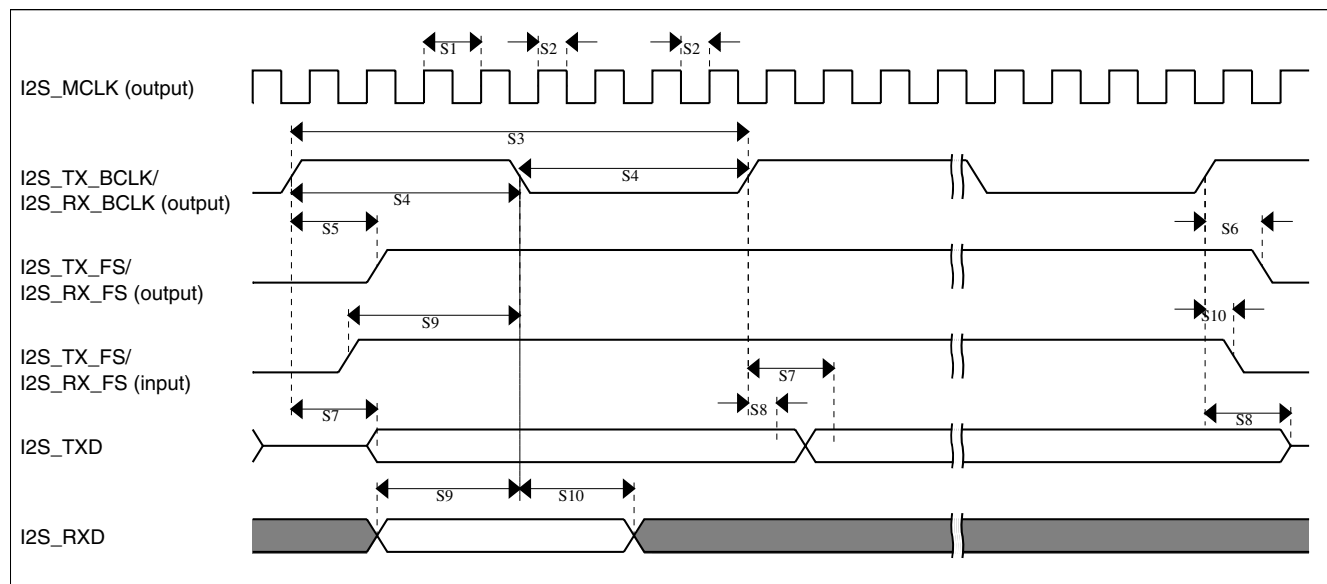
Symbol	Description	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
V <sub>REGIN</sub>	Input supply voltage	2.7	—	5.5	V	
I <sub>DDon</sub>	Quiescent current — Run mode, load current equal zero, input supply (V <sub>REGIN</sub> ) > 3.6 V	—	125	186	$\mu$ A	
I <sub>DDstby</sub>	Quiescent current — Standby mode, load current equal zero	—	1.1	10	$\mu$ A	
I <sub>DDoff</sub>	Quiescent current — Shutdown mode <ul style="list-style-type: none"> <li>V<sub>REGIN</sub> = 5.0 V and temperature=25 °C</li> <li>Across operating voltage and temperature</li> </ul>	—	650	—	nA	
		—	—	4	$\mu$ A	
I <sub>LOADstby</sub>	Maximum load current — Standby mode	—	—	1	mA	
V <sub>Reg33out</sub>	Regulator output voltage — Input supply (V <sub>REGIN</sub> ) > 3.6 V <ul style="list-style-type: none"> <li>Run mode</li> <li>Standby mode</li> </ul>	3	3.3	3.6	V	
		2.1	2.8	3.6	V	
V <sub>Reg33out</sub>	Regulator output voltage — Input supply (V <sub>REGIN</sub> ) < 3.6 V, pass-through mode	2.1	—	3.6	V	2
C <sub>OUT</sub>	External output capacitor	1.76	2.2	8.16	$\mu$ F	
ESR	External output capacitor equivalent series resistance	1	—	100	m $\Omega$	
I <sub>LIM</sub>	Short circuit current	—	315	—	mA	

1. Typical values assume V<sub>REGIN</sub> = 5.0 V, Temp = 25 °C unless otherwise stated.

2. Operating in pass-through mode: regulator output voltage equal to the input voltage minus a drop proportional to I<sub>Load</sub>.

**Table 33. I2S/SAI master mode timing (continued)**

Num.	Characteristic	Min.	Max.	Unit
S8	I2S_TX_BCLK to I2S_TXD invalid	0	—	ns
S9	I2S_RXD/I2S_RX_FS input setup before I2S_RX_BCLK	25	—	ns
S10	I2S_RXD/I2S_RX_FS input hold after I2S_RX_BCLK	0	—	ns

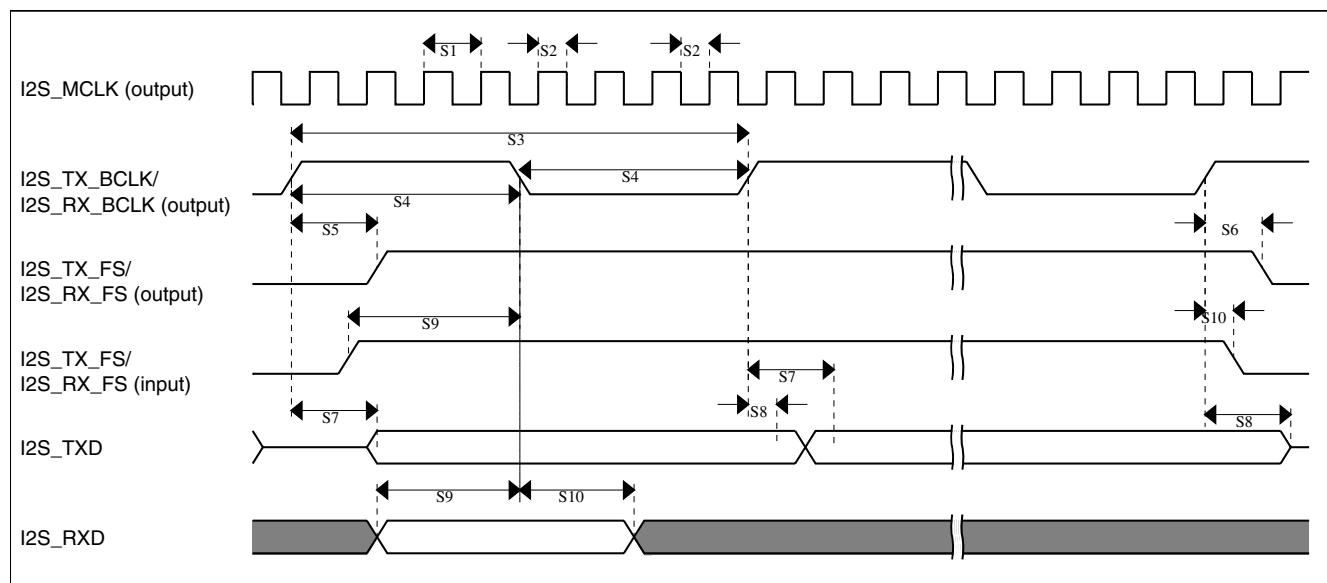


**Figure 18. I2S/SAI timing — master modes**

**Table 34. I2S/SAI slave mode timing**

Num.	Characteristic	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V
S11	I2S_TX_BCLK/I2S_RX_BCLK cycle time (input)	80	—	ns
S12	I2S_TX_BCLK/I2S_RX_BCLK pulse width high/low (input)	45%	55%	MCLK period
S13	I2S_TX_FS/I2S_RX_FS input setup before I2S_TX_BCLK/I2S_RX_BCLK	10	—	ns
S14	I2S_TX_FS/I2S_RX_FS input hold after I2S_TX_BCLK/I2S_RX_BCLK	2	—	ns
S15	I2S_TX_BCLK to I2S_TXD/I2S_TX_FS output valid	—	29	ns
S16	I2S_TX_BCLK to I2S_TXD/I2S_TX_FS output invalid	0	—	ns
S17	I2S_RXD setup before I2S_RX_BCLK	10	—	ns
S18	I2S_RXD hold after I2S_RX_BCLK	2	—	ns
S19	I2S_TX_FS input assertion to I2S_TXD output valid <sup>1</sup>	—	21	ns

1. Applies to first bit in each frame and only if the TCR4[FSE] bit is clear



**Figure 20. I2S/SAI timing — master modes**

**Table 36. I2S/SAI slave mode timing in VLPR, VLPW, and VLPS modes (full voltage range)**

Num.	Characteristic	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V
S11	I2S_TX_BCLK/I2S_RX_BCLK cycle time (input)	250	—	ns
S12	I2S_TX_BCLK/I2S_RX_BCLK pulse width high/low (input)	45%	55%	MCLK period
S13	I2S_TX_FS/I2S_RX_FS input setup before I2S_TX_BCLK/I2S_RX_BCLK	30	—	ns
S14	I2S_TX_FS/I2S_RX_FS input hold after I2S_TX_BCLK/I2S_RX_BCLK	2	—	ns
S15	I2S_TX_BCLK to I2S_TXD/I2S_TX_FS output valid	—	87	ns
S16	I2S_TX_BCLK to I2S_TXD/I2S_TX_FS output invalid	0	—	ns
S17	I2S_RXD setup before I2S_RX_BCLK	30	—	ns
S18	I2S_RXD hold after I2S_RX_BCLK	2	—	ns
S19	I2S_TX_FS input assertion to I2S_TXD output valid <sup>1</sup>	—	72	ns

1. Applies to first bit in each frame and only if the TCR4[FSE] bit is clear

K12, K21, and K22 devices and are not present on K10 and K20 devices.

- The TRACE signals on PTE0, PTE1, PTE2, PTE3, and PTE4 are available only for K11, K12, K21, and K22 devices and are not present on K10 and K20 devices.
- If the VBAT pin is not used, the VBAT pin should be left floating. Do not connect VBAT pin to VSS.
- The FTM\_CLKIN signals on PTB16 and PTB17 are available only for K11, K12, K21, and K22 devices and is not present on K10 and K20 devices. For K22D devices this signal is on ALT4, and for K22F devices, this signal is on ALT7.
- The FTM0\_CH2 signal on PTC5/LLWU\_P9 is available only for K11, K12, K21, and K22 devices and is not present on K10 and K20 devices.
- The I2C0\_SCL signal on PTD2/LLWU\_P13 and I2C0\_SDA signal on PTD3 are available only for K11, K12, K21, and K22 devices and are not present on K10 and K20 devices.

80 LQFP	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
1	ADC0_SE10	ADC0_SE10	PTE0	SPI1_PCS1	UART1_TX		TRACE_CLKOUT	I2C1_SDA	RTC_CLKOUT	
2	ADC0_SE11	ADC0_SE11	PTE1/ LLWU_P0	SPI1_SOUT	UART1_RX		TRACE_D3	I2C1_SCL	SPI1_SIN	
3	ADC0_DP1	ADC0_DP1	PTE2/ LLWU_P1	SPI1_SCK	UART1_CTS_b		TRACE_D2			
4	ADC0_DM1	ADC0_DM1	PTE3	SPI1_SIN	UART1_RTS_b		TRACE_D1		SPI1_SOUT	
5	DISABLED		PTE4/ LLWU_P2	SPI1_PCS0	UART3_TX		TRACE_D0			
6	DISABLED		PTE5	SPI1_PCS2	UART3_RX					
7	VDD	VDD								
8	VSS	VSS								
9	USB0_DP	USB0_DP								
10	USB0_DM	USB0_DM								
11	VOUT33	VOUT33								
12	VREGIN	VREGIN								
13	ADC0_DP0	ADC0_DP0								
14	ADC0_DM0	ADC0_DM0								
15	ADC0_DP3	ADC0_DP3								
16	ADC0_DM3	ADC0_DM3								
17	VDDA	VDDA								
18	VREFH	VREFH								
19	VREFL	VREFL								

**How to Reach Us:****Home Page:**

[freescale.com](http://freescale.com)

**Web Support:**

[freescale.com/support](http://freescale.com/support)

Information in this document is provided solely to enable system and software implementers to use Freescale products. There are no express or implied copyright licenses granted hereunder to design or fabricate any integrated circuits based on the information in this document.

Freescale reserves the right to make changes without further notice to any products herein. Freescale makes no warranty, representation, or guarantee regarding the suitability of its products for any particular purpose, nor does Freescale assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation consequential or incidental damages. "Typical" parameters that may be provided in Freescale data sheets and/or specifications can and do vary in different applications, and actual performance may vary over time. All operating parameters, including "typicals," must be validated for each customer application by customer's technical experts. Freescale does not convey any license under its patent rights nor the rights of others. Freescale sells products pursuant to standard terms and conditions of sale, which can be found at the following address: [freescale.com/SalesTermsandConditions](http://freescale.com/SalesTermsandConditions).

Freescale, the Freescale logo, Energy Efficient Solutions logo, and Kinetis are trademarks of Freescale Semiconductor, Inc., Reg. U.S. Pat. & Tm. Off. All other product or service names are the property of their respective owners. ARM and Cortex are the registered trademarks of ARM Limited.

© 2012-2013 Freescale Semiconductor, Inc.