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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	XC800
Core Size	8-Bit
Speed	24MHz
Connectivity	SSI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	34
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1.75K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	PG-TQFP-48
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/saf-xc886-8ffi-3v3-ac

Summary of Features

Features: (continued)

- Power-on reset generation
- Brownout detection for core logic supply
- On-chip OSC and PLL for clock generation
 - PLL loss-of-lock detection
- Power saving modes
 - slow-down mode
 - idle mode
 - power-down mode with wake-up capability via RXD or EXINT0
 - clock gating control to each peripheral
- Programmable 16-bit Watchdog Timer (WDT)
- Six ports
 - Up to 48 pins as digital I/O
 - 8 pins as digital/analog input
- 8-channel, 10-bit ADC
- Four 16-bit timers
 - Timer 0 and Timer 1 (T0 and T1)
 - Timer 2 and Timer 21 (T2 and T21)
- Multiplication/Division Unit for arithmetic operations (MDU)
- Software libraries to support floating point and MDU calculations
- CORDIC Coprocessor for computation of trigonometric, hyperbolic and linear functions
- MultiCAN with 2 nodes, 32 message objects
- Capture/compare unit for PWM signal generation (CCU6)
- Two full-duplex serial interfaces (UART and UART1)
- Synchronous serial channel (SSC)
- On-chip debug support
 - 1 Kbyte of monitor ROM (part of the 12-Kbyte Boot ROM)
 - 64 bytes of monitor RAM
- Packages:
 - PG-TQFP-48
 - PG-TQFP-64
- Temperature range T_A :
 - SAF (-40 to 85 °C)
 - SAK (-40 to 125 °C)

Summary of Features
Table 2 Device Profile (cont'd)

Sales Type	Device Type	Program Memory (Kbytes)	Power Supply (V)	Temperature (°C)	Quality Profile
SAK-XC886*/888*-8FFA 3V3	Flash	32	3.3	-40 to 125	Automotive
SAK-XC886*/888*-6FFA 3V3	Flash	24	3.3	-40 to 125	Automotive
SAF-XC886*/888*-8FFA 3V3	Flash	32	3.3	-40 to 85	Automotive
SAF-XC886*/888*-6FFA 3V3	Flash	24	3.3	-40 to 85	Automotive
SAF-XC886*/888*-8FFI 3V3	Flash	32	3.3	-40 to 85	Industrial
SAF-XC886*/888*-6FFI 3V3	Flash	24	3.3	-40 to 85	Industrial

Note: The asterisk () above denotes the device configuration letters from [Table 1](#). Corresponding ROM derivatives will be available on request.*

Note: For variants with LIN BSL support, only LIN BSL is available regardless of the availability of the CAN module.

As this document refers to all the derivatives, some description may not apply to a specific product. For simplicity, all versions are referred to by the term XC886/888 throughout this document.

Ordering Information

The ordering code for Infineon Technologies microcontrollers provides an exact reference to the required product. This ordering code identifies:

- The derivative itself, i.e. its function set, the temperature range, and the supply voltage
- The package and the type of delivery

For the available ordering codes for the XC886/888, please refer to your responsible sales representative or your local distributor.

Note: The ordering codes for the Mask-ROM versions are defined for each product after verification of the respective ROM code.

General Device Information

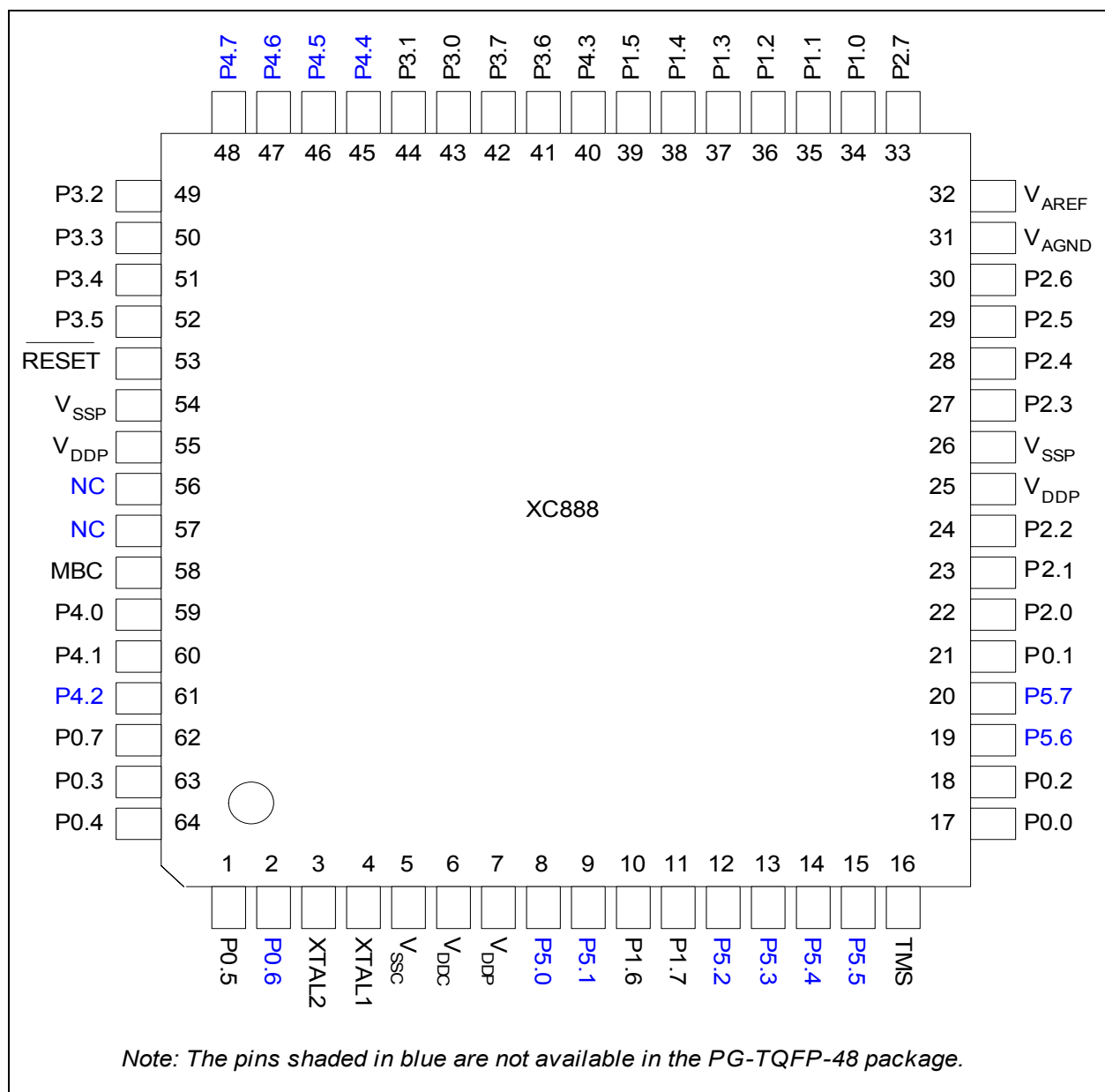


Figure 5 XC888 Pin Configuration, PG-TQFP-64 Package (top view)

General Device Information

Table 3 Pin Definitions and Functions (cont'd)

Symbol	Pin Number (TQFP-48/64)	Type	Reset State	Function
P3		I/O		Port 3 Port 3 is an 8-bit bidirectional general purpose I/O port. It can be used as alternate functions for CCU6, UART1, Timer 21 and MultiCAN.
P3.0	35/43		Hi-Z	CCPOS1_2 CCU6 Hall Input 1 CC60_0 Input/Output of Capture/Compare channel 0 RXDO1_1 UART1 Transmit Data Output
P3.1	36/44		Hi-Z	CCPOS0_2 CCU6 Hall Input 0 CC61_2 Input/Output of Capture/Compare channel 1 COUT60_0 Output of Capture/Compare channel 0 TXD1_1 UART1 Transmit Data Output/Clock Output
P3.2	37/49		Hi-Z	CCPOS2_2 CCU6 Hall Input 2 RXDC1_1 MultiCAN Node 1 Receiver Input RXD1_1 UART1 Receive Data Input CC61_0 Input/Output of Capture/Compare channel 1
P3.3	38/50		Hi-Z	COUT61_0 Output of Capture/Compare channel 1 TXDC1_1 MultiCAN Node 1 Transmitter Output
P3.4	39/51		Hi-Z	CC62_0 Input/Output of Capture/Compare channel 2 RXDC0_1 MultiCAN Node 0 Receiver Input T2EX1_0 Timer 21 External Trigger Input
P3.5	40/52		Hi-Z	COUT62_0 Output of Capture/Compare channel 2 EXF21_0 Timer 21 External Flag Output TXDC0_1 MultiCAN Node 0 Transmitter Output
P3.6	33/41		PD	CTRAP_0 CCU6 Trap Input

General Device Information

Table 3 Pin Definitions and Functions (cont'd)

Symbol	Pin Number (TQFP-48/64)	Type	Reset State	Function
P5		I/O		Port 5 Port 5 is an 8-bit bidirectional general purpose I/O port. It can be used as alternate functions for UART, UART1 and JTAG.
P5.0	–/8		PU	EXINT1_1 External Interrupt Input 1
P5.1	–/9		PU	EXINT2_1 External Interrupt Input 2
P5.2	–/12		PU	RXD_2 UART Receive Data Input
P5.3	–/13		PU	TXD_2 UART Transmit Data Output/Clock Output
P5.4	–/14		PU	RXDO_2 UART Transmit Data Output
P5.5	–/15		PU	TDO_2 JTAG Serial Data Output TXD1_2 UART1 Transmit Data Output/ Clock Output
P5.6	–/19		PU	TCK_2 JTAG Clock Input RXDO1_2 UART1 Transmit Data Output
P5.7	–/20		PU	TDI_2 JTAG Serial Data Input RXD1_2 UART1 Receive Data Input

General Device Information

Table 3 Pin Definitions and Functions (cont'd)

Symbol	Pin Number (TQFP-48/64)	Type	Reset State	Function
V_{DDP}	7, 17, 43/ 7, 25, 55	—	—	I/O Port Supply (3.3 or 5.0 V) Also used by EVR and analog modules. All pins must be connected.
V_{SSP}	18, 42/26, 54	—	—	I/O Port Ground All pins must be connected.
V_{DDC}	6/6	—	—	Core Supply Monitor (2.5 V)
V_{SSC}	5/5	—	—	Core Supply Ground
V_{AREF}	24/32	—	—	ADC Reference Voltage
V_{AGND}	23/31	—	—	ADC Reference Ground
XTAL1	4/4	I	Hi-Z	External Oscillator Input (backup for on-chip OSC, normally NC)
XTAL2	3/3	O	Hi-Z	External Oscillator Output (backup for on-chip OSC, normally NC)
TMS	10/16	I	PD	Test Mode Select
RESET	41/53	I	PU	Reset Input
MBC¹⁾	44/58	I	PU	Monitor & BootStrap Loader Control
NC	—/56, 57	—	—	No Connection

1) An external pull-up device in the range of 4.7 k Ω to 100 k Ω . is required to enter user mode. Alternatively MBC can be tied to high if alternate functions (for debugging) of the pin are not utilized.

3.2.2 Special Function Register

The Special Function Registers (SFRs) occupy direct internal data memory space in the range 80_H to FF_H . All registers, except the program counter, reside in the SFR area. The SFRs include pointers and registers that provide an interface between the CPU and the on-chip peripherals. As the 128-SFR range is less than the total number of registers required, address extension mechanisms are required to increase the number of addressable SFRs. The address extension mechanisms include:

- Mapping
- Paging

3.2.2.1 Address Extension by Mapping

Address extension is performed at the system level by mapping. The SFR area is extended into two portions: the standard (non-mapped) SFR area and the mapped SFR area. Each portion supports the same address range 80_H to FF_H , bringing the number of addressable SFRs to 256. The extended address range is not directly controlled by the CPU instruction itself, but is derived from bit RMAP in the system control register SYSCON0 at address $8F_H$. To access SFRs in the mapped area, bit RMAP in SFR SYSCON0 must be set. Alternatively, the SFRs in the standard area can be accessed by clearing bit RMAP. The SFR area can be selected as shown in [Figure 8](#).

As long as bit RMAP is set, the mapped SFR area can be accessed. This bit is not cleared automatically by hardware. Thus, before standard/mapped registers are accessed, bit RMAP must be cleared/set, respectively, by software.

Functional Description

SYSCON0

System Control Register 0

Reset Value: 04_H

7	6	5	4	3	2	1	0
0			IMODE	0	1	0	RMAP
r			rw	r	r	r	rw

Field	Bits	Type	Description
RMAP	0	rw	Interrupt Node XINTR0 Enable 0 The access to the standard SFR area is enabled 1 The access to the mapped SFR area is enabled
1	2	r	Reserved Returns 1 if read; should be written with 1.
0	[7:5], 3,1	r	Reserved Returns 0 if read; should be written with 0.

Note: The RMAP bit should be cleared/set by ANL or ORL instructions.

3.2.2.2 Address Extension by Paging

Address extension is further performed at the module level by paging. With the address extension by mapping, the XC886/888 has a 256-SFR address range. However, this is still less than the total number of SFRs needed by the on-chip peripherals. To meet this requirement, some peripherals have a built-in local address extension mechanism for increasing the number of addressable SFRs. The extended address range is not directly controlled by the CPU instruction itself, but is derived from bit field PAGE in the module page register MOD_PAGE. Hence, the bit field PAGE must be programmed before accessing the SFR of the target module. Each module may contain a different number of pages and a different number of SFRs per page, depending on the specific requirement. Besides setting the correct RMAP bit value to select the SFR area, the user must also ensure that a valid PAGE is selected to target the desired SFR. A page inside the extended address range can be selected as shown in [Figure 9](#).

Functional Description

Table 7 CORDIC Register Overview (cont'd)

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
A0 _H	CD_STATC Reset: 00 _H CORDIC Status and Data Control Register	Bit Field	KEEP Z	KEEP Y	KEEP X	DMAP	INT_EN	EOC	ERROR	BSY
		Type	rw	rw	rw	rw	rw	rwh	rh	rh
A1 _H	CD_CON Reset: 00 _H CORDIC Control Register	Bit Field	MPS		X_USIGN	ST_MODE	ROTV EC	MODE		ST
		Type	rw		rw	rw	rw	rw		rwh

3.2.4.4 System Control Registers

The system control SFRs can be accessed in the mapped memory area (RMAP = 0).

Table 8 SCU Register Overview

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
RMAP = 0 or 1										
8F _H	SYSCON0 Reset: 04_H System Control Register 0	Bit Field	0			IMOD E	0	1	0	RMAP
		Type	r			rw	r	r	r	rw
RMAP = 0										
BF _H	SCU_PAGE Reset: 00_H Page Register	Bit Field	OP		STNR		0	PAGE		
		Type	w		w		r	rw		
RMAP = 0, PAGE 0										
B3 _H	MODPISEL Reset: 00_H Peripheral Input Select Register	Bit Field	0	URRIS H	JTAGT DIS	JTAGT CKS	EXINT 2IS	EXINT 1IS	EXINT 0IS	URRIS
		Type	r	rw	rw	rw	rw	rw	rw	rw
B4 _H	IRCON0 Reset: 00_H Interrupt Request Register 0	Bit Field	0	EXINT 6	EXINT 5	EXINT 4	EXINT 3	EXINT 2	EXINT 1	EXINT 0
		Type	r	rwh	rwh	rwh	rwh	rwh	rwh	rwh
B5 _H	IRCON1 Reset: 00_H Interrupt Request Register 1	Bit Field	0	CANS RC2	CANS RC1	ADCS R1	ADCS R0	RIR	TIR	EIR
		Type	r	rwh	rwh	rwh	rwh	rwh	rwh	rwh
B6 _H	IRCON2 Reset: 00_H Interrupt Request Register 2	Bit Field	0			CANS RC3	0			CANS RC0
		Type	r			rwh	r			rwh
B7 _H	EXICON0 Reset: F0_H External Interrupt Control Register 0	Bit Field	EXINT3		EXINT2		EXINT1		EXINT0	
		Type	rw		rw		rw		rw	
BA _H	EXICON1 Reset: 3F_H External Interrupt Control Register 1	Bit Field	0		EXINT6		EXINT5		EXINT4	
		Type	r		rw		rw		rw	
BB _H	NMICON Reset: 00_H NMI Control Register	Bit Field	0	NMI ECC	NMI VDDP	NMI VDD	NMI OCDS	NMI FLASH	NMI PLL	NMI WDT
		Type	r	rw	rw	rw	rw	rw	rw	rw

Functional Description
Table 10 Port Register Overview (cont'd)

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
RMAP = 0, PAGE 1										
80 _H	P0_PUDSEL Reset: FF_H P0 Pull-Up/Pull-Down Select Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
86 _H	P0_PUDEN Reset: C4_H P0 Pull-Up/Pull-Down Enable Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
90 _H	P1_PUDSEL Reset: FF_H P1 Pull-Up/Pull-Down Select Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
91 _H	P1_PUDEN Reset: FF_H P1 Pull-Up/Pull-Down Enable Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
92 _H	P5_PUDSEL Reset: FF_H P5 Pull-Up/Pull-Down Select Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
93 _H	P5_PUDEN Reset: FF_H P5 Pull-Up/Pull-Down Enable Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
A0 _H	P2_PUDSEL Reset: FF_H P2 Pull-Up/Pull-Down Select Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
A1 _H	P2_PUDEN Reset: 00_H P2 Pull-Up/Pull-Down Enable Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
B0 _H	P3_PUDSEL Reset: BF_H P3 Pull-Up/Pull-Down Select Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
B1 _H	P3_PUDEN Reset: 40_H P3 Pull-Up/Pull-Down Enable Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
C8 _H	P4_PUDSEL Reset: FF_H P4 Pull-Up/Pull-Down Select Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
C9 _H	P4_PUDEN Reset: 04_H P4 Pull-Up/Pull-Down Enable Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
RMAP = 0, PAGE 2										
80 _H	P0_ALTSEL0 Reset: 00_H P0 Alternate Select 0 Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
86 _H	P0_ALTSEL1 Reset: 00_H P0 Alternate Select 1 Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
90 _H	P1_ALTSEL0 Reset: 00_H P1 Alternate Select 0 Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
91 _H	P1_ALTSEL1 Reset: 00_H P1 Alternate Select 1 Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
92 _H	P5_ALTSEL0 Reset: 00_H P5 Alternate Select 0 Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw

Functional Description

3.2.4.12 SSC Registers

The SSC SFRs can be accessed in the standard memory area (RMAP = 0).

Table 16 SSC Register Overview

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
RMAP = 0										
A9 _H	SSC_PISEL Reset: 00 _H Port Input Select Register	Bit Field	0					CIS	SIS	MIS
		Type	r					rw	rw	rw
AA _H	SSC_CONL Reset: 00 _H Control Register Low Programming Mode	Bit Field	LB	PO	PH	HB	BM			
		Type	rw	rw	rw	rw	rw			
AA _H	SSC_CONL Reset: 00 _H Control Register Low Operating Mode	Bit Field	0				BC			
		Type	r				rh			
AB _H	SSC_CONH Reset: 00 _H Control Register High Programming Mode	Bit Field	EN	MS	0	AREN	BEN	PEN	REN	TEN
		Type	rw	rw	r	rw	rw	rw	rw	rw
AB _H	SSC_CONH Reset: 00 _H Control Register High Operating Mode	Bit Field	EN	MS	0	BSY	BE	PE	RE	TE
		Type	rw	rw	r	rh	rwh	rwh	rwh	rwh
AC _H	SSC_TBL Reset: 00 _H Transmitter Buffer Register Low	Bit Field	TB_VALUE							
		Type	rw							
AD _H	SSC_RBL Reset: 00 _H Receiver Buffer Register Low	Bit Field	RB_VALUE							
		Type	rh							
AE _H	SSC_BRL Reset: 00 _H Baud Rate Timer Reload Register Low	Bit Field	BR_VALUE							
		Type	rw							
AF _H	SSC_BRH Reset: 00 _H Baud Rate Timer Reload Register High	Bit Field	BR_VALUE							
		Type	rw							

3.2.4.13 MultiCAN Registers

The MultiCAN SFRs can be accessed in the standard memory area (RMAP = 0).

Table 17 CAN Register Overview

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
RMAP = 0										
D8 _H	ADCON Reset: 00 _H CAN Address/Data Control Register	Bit Field	V3	V2	V1	V0	AUAD		BSY	RWEN
		Type	rw	rw	rw	rw	rw		rh	rw
D9 _H	ADL Reset: 00 _H CAN Address Register Low	Bit Field	CA9	CA8	CA7	CA6	CA5	CA4	CA3	CA2
		Type	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh
DA _H	ADH Reset: 00 _H CAN Address Register High	Bit Field	0				CA13	CA12	CA11	CA10
		Type	r				rwh	rwh	rwh	rwh

Functional Description

3.4 Interrupt System

The XC800 Core supports one non-maskable interrupt (NMI) and 14 maskable interrupt requests. In addition to the standard interrupt functions supported by the core, e.g., configurable interrupt priority and interrupt masking, the XC886/888 interrupt system provides extended interrupt support capabilities such as the mapping of each interrupt vector to several interrupt sources to increase the number of interrupt sources supported, and additional status registers for detecting and determining the interrupt source.

3.4.1 Interrupt Source

Figure 13 to **Figure 17** give a general overview of the interrupt sources and nodes, and their corresponding control and status flags.

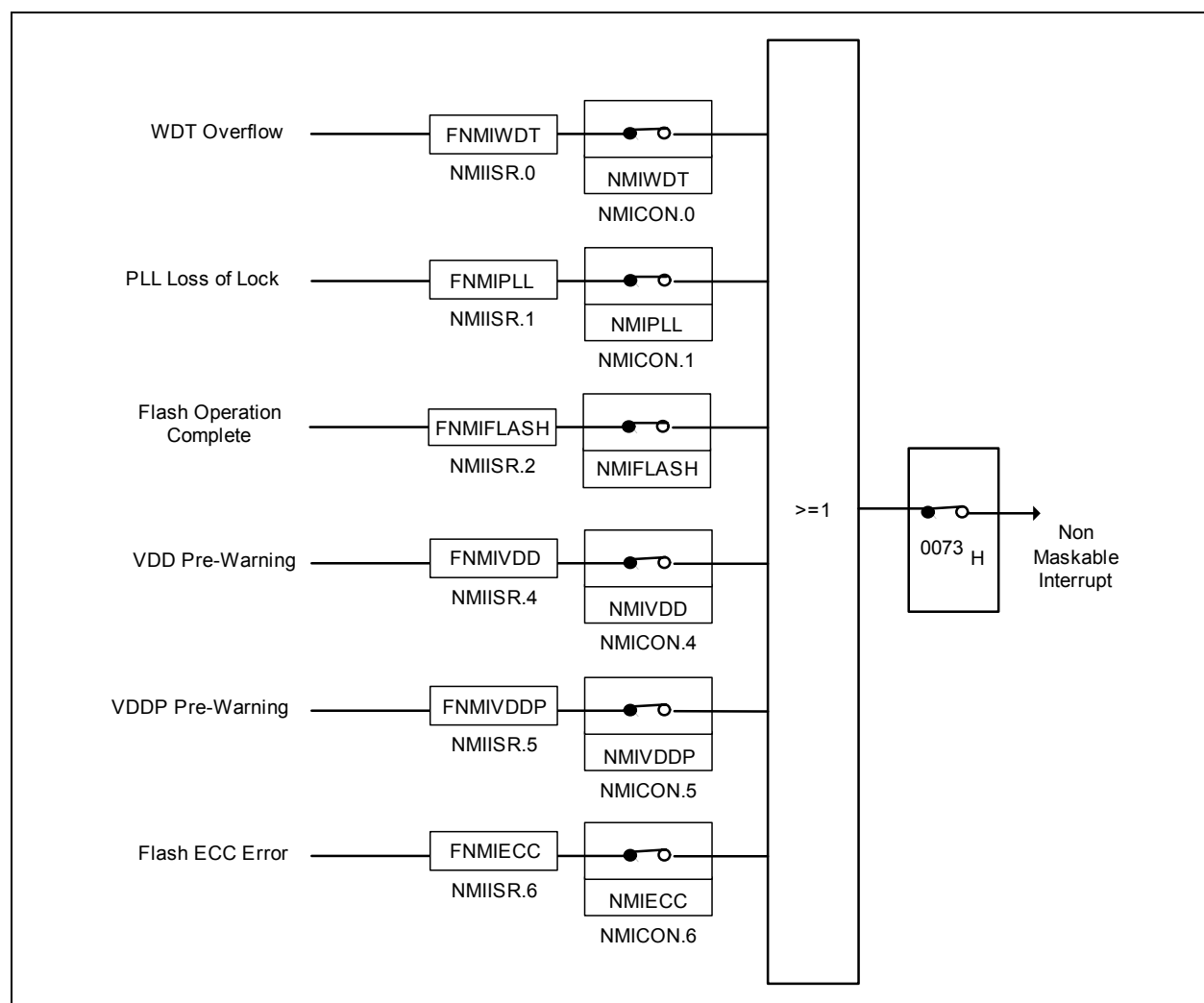


Figure 13 Non-Maskable Interrupt Request Sources

Functional Description

Figure 19 shows the structure of a bidirectional port pin.

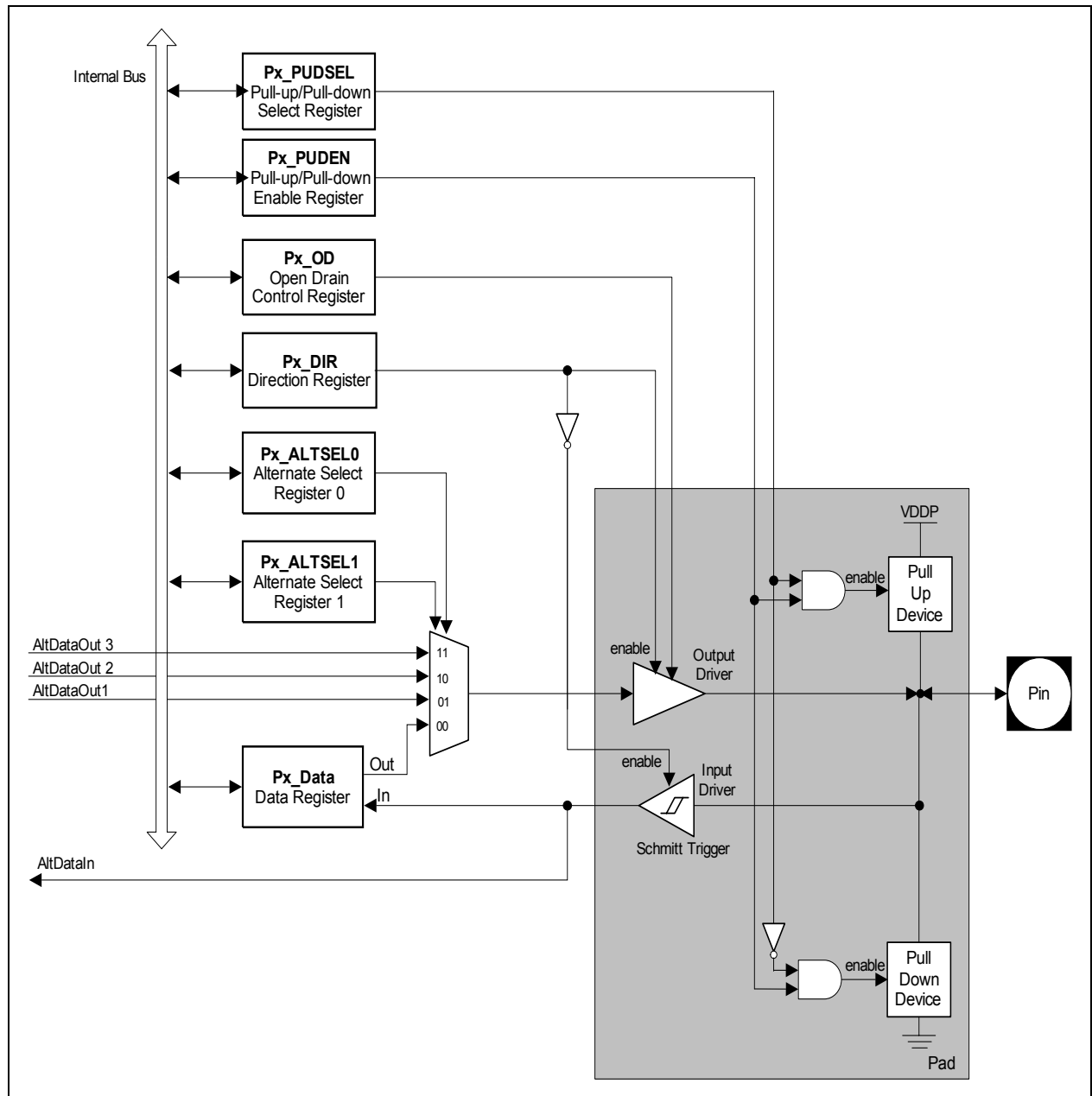


Figure 19 General Structure of Bidirectional Port

Functional Description

Figure 20 shows the structure of an input-only port pin.

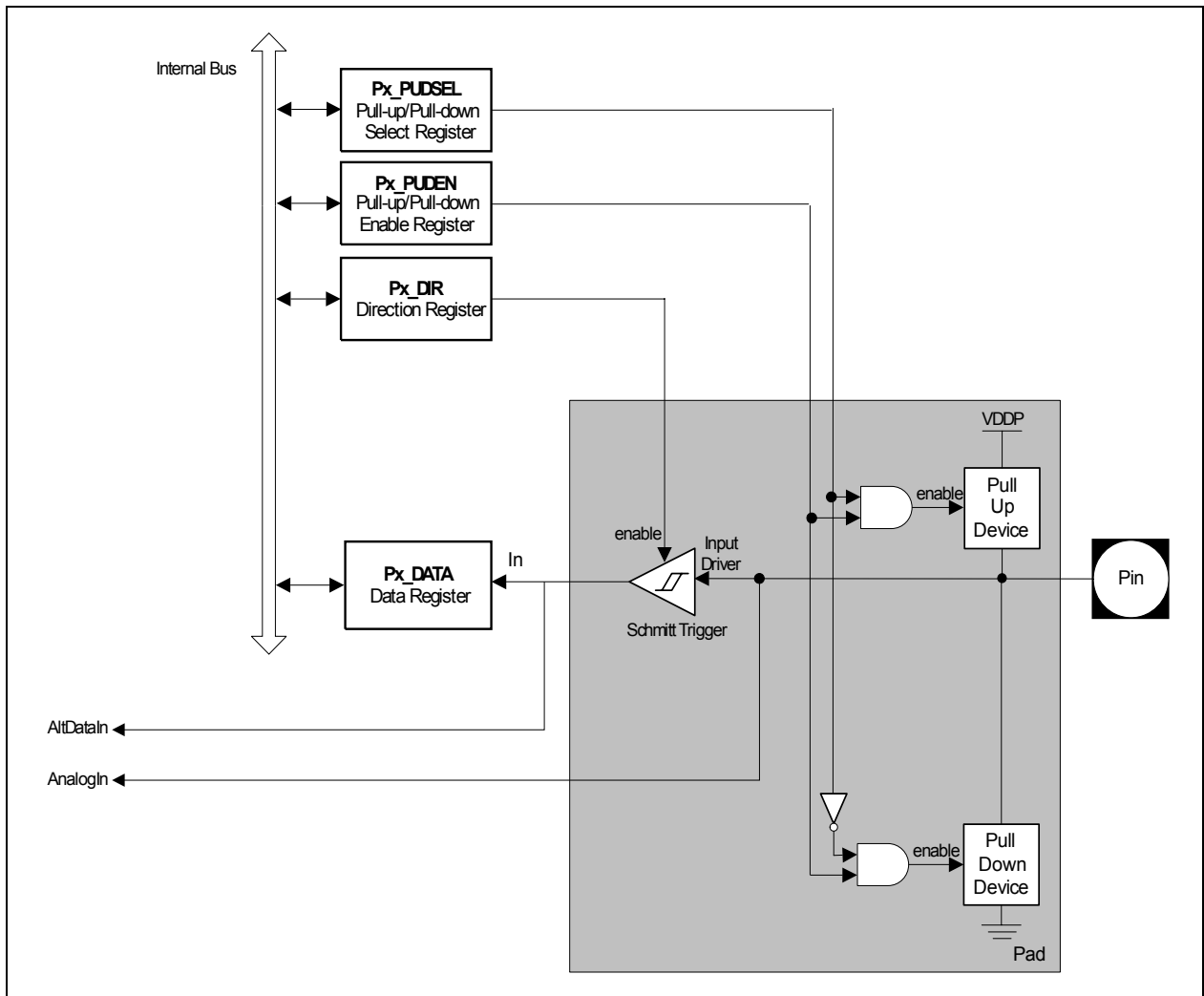


Figure 20 General Structure of Input Port

Functional Description

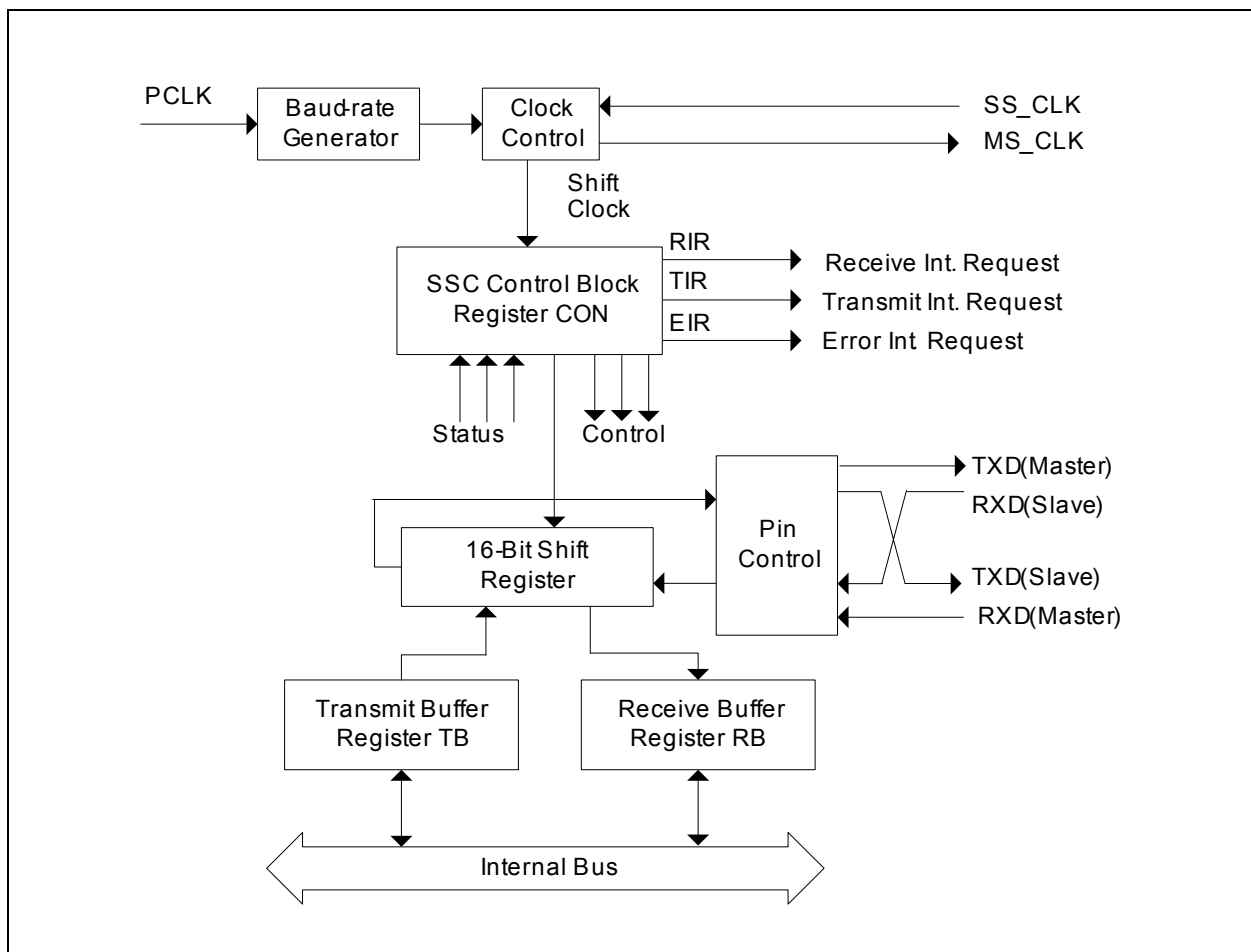


Figure 32 SSC Block Diagram

3.23 Chip Identification Number

The XC886/888 identity (ID) register is located at Page 1 of address B3_H. The value of ID register is 09_H for Flash devices and 22_H for ROM devices. However, for easy identification of product variants, the Chip Identification Number, which is an unique number assigned to each product variant, is available. The differentiation is based on the product, variant type and device step information.

Two methods are provided to read a device's chip identification number:

- In-application subroutine, GET_CHIP_INFO
- Bootstrap loader (BSL) mode A

Table 36 lists the chip identification numbers of available XC886/888 Flash and ROM device variants.

Table 36 Chip Identification Number

Product Variant	Chip Identification Number		
	AA-Step	AB-Step	AC-Step
Flash Devices			
XC886CLM-8FFA 3V3	-	09500102 _H	0B500102 _H
XC888CLM-8FFA 3V3	-	09500103 _H	0B500103 _H
XC886LM-8FFA 3V3	-	09500122 _H	0B500122 _H
XC888LM-8FFA 3V3	-	09500123 _H	0B500123 _H
XC886CLM-6FFA 3V3	-	09551502 _H	0B551502 _H
XC888CLM-6FFA 3V3	-	09551503 _H	0B551503 _H
XC886LM-6FFA 3V3	-	09551522 _H	0B551522 _H
XC888LM-6FFA 3V3	-	09551523 _H	0B551523 _H
XC886CM-8FFA 3V3	-	09580102 _H	0B580102 _H
XC888CM-8FFA 3V3	-	09580103 _H	0B580103 _H
XC886C-8FFA 3V3	-	09580142 _H	0B580142 _H
XC888C-8FFA 3V3	-	09580143 _H	0B580143 _H
XC886-8FFA 3V3	-	09580162 _H	0B580162 _H
XC888-8FFA 3V3	-	09580163 _H	0B580163 _H
XC886CM-6FFA 3V3	-	095D1502 _H	0B5D1502 _H
XC888CM-6FFA 3V3	-	095D1503 _H	0B5D1503 _H
XC886C-6FFA 3V3	-	095D1542 _H	0B5D1542 _H
XC888C-6FFA 3V3	-	095D1543 _H	0B5D1543 _H

Electrical Parameters

4.1.2 Absolute Maximum Rating

Maximum ratings are the extreme limits to which the XC886/888 can be subjected to without permanent damage.

Table 4-1 Absolute Maximum Rating Parameters

Parameter	Symbol	Limit Values		Unit	Notes
		min.	max.		
Ambient temperature	T_A	-40	125	°C	under bias
Storage temperature	T_{ST}	-65	150	°C	¹⁾
Junction temperature	T_J	-40	150	°C	under bias ¹⁾
Voltage on power supply pin with respect to V_{SS}	V_{DDP}	-0.5	6	V	¹⁾
Voltage on any pin with respect to V_{SS}	V_{IN}	-0.5	$V_{DDP} + 0.5$ or max. 6	V	whichever is lower ¹⁾
Input current on any pin during overload condition	I_{IN}	-10	10	mA	¹⁾
Absolute sum of all input currents during overload condition	$\Sigma I_{IN} $	—	50	mA	¹⁾

1) Not subjected to production test, verified by design/characterization.

Note: Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. During absolute maximum rating overload conditions ($V_{IN} > V_{DDP}$ or $V_{IN} < V_{SS}$) the voltage on V_{DDP} pin with respect to ground (V_{SS}) must not exceed the values defined by the absolute maximum ratings.

Electrical Parameters

4.2 DC Parameters

The electrical characteristics of the DC Parameters are detailed in this section.

4.2.1 Input/Output Characteristics

Table 38 provides the characteristics of the input/output pins of the XC886/888.

Table 38 Input/Output Characteristics (Operating Conditions apply)

Parameter	Symbol		Limit Values		Unit	Test Conditions
			min.	max.		
$V_{DDP} = 5\text{ V Range}$						
Output low voltage	V_{OL}	CC	–	1.0	V	$I_{OL} = 15\text{ mA}$
			–	1.0	V	$I_{OL} = 5\text{ mA}$, current into all pins $> 60\text{ mA}$
			–	0.4	V	$I_{OL} = 5\text{ mA}$, current into all pins $\leq 60\text{ mA}$
Output high voltage	V_{OH}	CC	$V_{DDP} - 1.0$	–	V	$I_{OH} = -15\text{ mA}$
			$V_{DDP} - 1.0$	–	V	$I_{OH} = -5\text{ mA}$, current from all pins $> 60\text{ mA}$
			$V_{DDP} - 0.4$	–	V	$I_{OH} = -5\text{ mA}$, current from all pins $\leq 60\text{ mA}$
Input low voltage on port pins (all except P0.0 & P0.1)	V_{ILP}	SR	–	$0.3 \times V_{DDP}$	V	CMOS Mode
Input low voltage on P0.0 & P0.1	V_{ILP0}	SR	-0.2	$0.3 \times V_{DDP}$	V	CMOS Mode
Input low voltage on RESET pin	V_{ILR}	SR	–	$0.3 \times V_{DDP}$	V	CMOS Mode
Input low voltage on TMS pin	V_{ILT}	SR	–	$0.3 \times V_{DDP}$	V	CMOS Mode
Input high voltage on port pins (all except P0.0 & P0.1)	V_{IHP}	SR	$0.7 \times V_{DDP}$	–	V	CMOS Mode
Input high voltage on P0.0 & P0.1	V_{IHP0}	SR	$0.7 \times V_{DDP}$	V_{DDP}	V	CMOS Mode

Electrical Parameters
Table 38 Input/Output Characteristics (Operating Conditions apply) (cont'd)

Parameter	Symbol		Limit Values		Unit	Test Conditions
			min.	max.		
Input high voltage on RESET pin	V_{IHR}	SR	$0.7 \times V_{DDP}$	–	V	CMOS Mode
Input high voltage on TMS pin	V_{IHT}	SR	$0.75 \times V_{DDP}$	–	V	CMOS Mode
Input Hysteresis on port pins	$HYSP$	CC	$0.07 \times V_{DDP}$	–	V	CMOS Mode ¹⁾
Input Hysteresis on XTAL1	$HYSX$	CC	$0.07 \times V_{DDC}$	–	V	¹⁾
Input low voltage at XTAL1	V_{ILX}	SR	$V_{SS} - 0.5$	$0.3 \times V_{DDC}$	V	
Input high voltage at XTAL1	V_{IHX}	SR	$0.7 \times V_{DDC}$	$V_{DDC} + 0.5$	V	
Pull-up current	I_{PU}	SR	–	-10	μA	$V_{IHP,min}$
			-150	–	μA	$V_{ILP,max}$
Pull-down current	I_{PD}	SR	–	10	μA	$V_{ILP,max}$
			150	–	μA	$V_{IHP,min}$
Input leakage current	I_{OZ1}	CC	-1	1	μA	$0 < V_{IN} < V_{DDP}$, $T_A \leq 125^\circ C$ ²⁾
Input current at XTAL1	I_{ILX}	CC	-10	10	μA	
Overload current on any pin	I_{OV}	SR	-5	5	mA	
Absolute sum of overload currents	$\Sigma I_{OV} $	SR	–	25	mA	³⁾
Voltage on any pin during V_{DDP} power off	V_{PO}	SR	–	0.3	V	⁴⁾
Maximum current per pin (excluding V_{DDP} and V_{SS})	I_M	SR	–	15	mA	
Maximum current for all pins (excluding V_{DDP} and V_{SS})	$\Sigma I_M $	SR	–	90	mA	
Maximum current into V_{DDP}	I_{MVDDP}	SR	–	120	mA	³⁾

Electrical Parameters
Table 38 Input/Output Characteristics (Operating Conditions apply) (cont'd)

Parameter	Symbol		Limit Values		Unit	Test Conditions
			min.	max.		
Maximum current out of V_{SS}	I_{MVSS}	SR	–	120	mA	³⁾
$V_{DDP} = 3.3 \text{ V Range}$						
Output low voltage	V_{OL}	CC	–	1.0	V	$I_{OL} = 8 \text{ mA}$
			–	0.4	V	$I_{OL} = 2.5 \text{ mA}$
Output high voltage	V_{OH}	CC	$V_{DDP} - 1.0$	–	V	$I_{OH} = -8 \text{ mA}$
			$V_{DDP} - 0.4$	–	V	$I_{OH} = -2.5 \text{ mA}$
Input low voltage on port pins (all except P0.0 & P0.1)	V_{ILP}	SR	–	$0.3 \times V_{DDP}$	V	CMOS Mode
Input low voltage on P0.0 & P0.1	V_{ILP0}	SR	-0.2	$0.3 \times V_{DDP}$	V	CMOS Mode
Input low voltage on RESET pin	V_{ILR}	SR	–	$0.3 \times V_{DDP}$	V	CMOS Mode
Input low voltage on TMS pin	V_{ILT}	SR	–	$0.3 \times V_{DDP}$	V	CMOS Mode
Input high voltage on port pins (all except P0.0 & P0.1)	V_{IHP}	SR	$0.7 \times V_{DDP}$	–	V	CMOS Mode
Input high voltage on P0.0 & P0.1	V_{IHP0}	SR	$0.7 \times V_{DDP}$	V_{DDP}	V	CMOS Mode
Input high voltage on RESET pin	V_{IHR}	SR	$0.7 \times V_{DDP}$	–	V	CMOS Mode
Input high voltage on TMS pin	V_{IHT}	SR	$0.75 \times V_{DDP}$	–	V	CMOS Mode
Input Hysteresis	HYS	CC	$0.03 \times V_{DDP}$	–	V	CMOS Mode ¹⁾
Input Hysteresis on XTAL1	$HYSX$	CC	$0.07 \times V_{DDC}$	–	V	¹⁾
Input low voltage at XTAL1	V_{ILX}	SR	$V_{SS} - 0.5$	$0.3 \times V_{DDC}$	V	