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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Obsolete
Core Processor	XC800
Core Size	8-Bit
Speed	24MHz
Connectivity	SSI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	34
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1.75K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	PG-TQFP-48
Purchase URL	<a href="https://www.e-xfl.com/product-detail/infineon-technologies/xc8868ffi5vackxuma1">https://www.e-xfl.com/product-detail/infineon-technologies/xc8868ffi5vackxuma1</a>

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## Summary of Features

### Features: (continued)

- Power-on reset generation
- Brownout detection for core logic supply
- On-chip OSC and PLL for clock generation
  - PLL loss-of-lock detection
- Power saving modes
  - slow-down mode
  - idle mode
  - power-down mode with wake-up capability via RXD or EXINT0
  - clock gating control to each peripheral
- Programmable 16-bit Watchdog Timer (WDT)
- Six ports
  - Up to 48 pins as digital I/O
  - 8 pins as digital/analog input
- 8-channel, 10-bit ADC
- Four 16-bit timers
  - Timer 0 and Timer 1 (T0 and T1)
  - Timer 2 and Timer 21 (T2 and T21)
- Multiplication/Division Unit for arithmetic operations (MDU)
- Software libraries to support floating point and MDU calculations
- CORDIC Coprocessor for computation of trigonometric, hyperbolic and linear functions
- MultiCAN with 2 nodes, 32 message objects
- Capture/compare unit for PWM signal generation (CCU6)
- Two full-duplex serial interfaces (UART and UART1)
- Synchronous serial channel (SSC)
- On-chip debug support
  - 1 Kbyte of monitor ROM (part of the 12-Kbyte Boot ROM)
  - 64 bytes of monitor RAM
- Packages:
  - PG-TQFP-48
  - PG-TQFP-64
- Temperature range  $T_A$ :
  - SAF (-40 to 85 °C)
  - SAK (-40 to 125 °C)

## General Device Information

Table 3 Pin Definitions and Functions (cont'd)

Symbol	Pin Number (TQFP-48/64)	Type	Reset State	Function
<b>P5</b>		I/O		<b>Port 5</b> Port 5 is an 8-bit bidirectional general purpose I/O port. It can be used as alternate functions for UART, UART1 and JTAG.
P5.0	–/8		PU	EXINT1_1 External Interrupt Input 1
P5.1	–/9		PU	EXINT2_1 External Interrupt Input 2
P5.2	–/12		PU	RXD_2 UART Receive Data Input
P5.3	–/13		PU	TXD_2 UART Transmit Data Output/Clock Output
P5.4	–/14		PU	RXDO_2 UART Transmit Data Output
P5.5	–/15		PU	TDO_2 JTAG Serial Data Output TXD1_2 UART1 Transmit Data Output/ Clock Output
P5.6	–/19		PU	TCK_2 JTAG Clock Input RXDO1_2 UART1 Transmit Data Output
P5.7	–/20		PU	TDI_2 JTAG Serial Data Input RXD1_2 UART1 Receive Data Input

### 3.2.2 Special Function Register

The Special Function Registers (SFRs) occupy direct internal data memory space in the range  $80_H$  to  $FF_H$ . All registers, except the program counter, reside in the SFR area. The SFRs include pointers and registers that provide an interface between the CPU and the on-chip peripherals. As the 128-SFR range is less than the total number of registers required, address extension mechanisms are required to increase the number of addressable SFRs. The address extension mechanisms include:

- Mapping
- Paging

#### 3.2.2.1 Address Extension by Mapping

Address extension is performed at the system level by mapping. The SFR area is extended into two portions: the standard (non-mapped) SFR area and the mapped SFR area. Each portion supports the same address range  $80_H$  to  $FF_H$ , bringing the number of addressable SFRs to 256. The extended address range is not directly controlled by the CPU instruction itself, but is derived from bit RMAP in the system control register SYSCON0 at address  $8F_H$ . To access SFRs in the mapped area, bit RMAP in SFR SYSCON0 must be set. Alternatively, the SFRs in the standard area can be accessed by clearing bit RMAP. The SFR area can be selected as shown in [Figure 8](#).

As long as bit RMAP is set, the mapped SFR area can be accessed. This bit is not cleared automatically by hardware. Thus, before standard/mapped registers are accessed, bit RMAP must be cleared/set, respectively, by software.

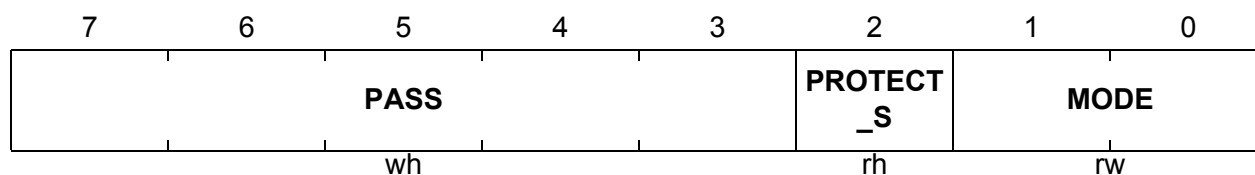
## Functional Description

### 3.2.3.1 Password Register

PASSWD

Password Register

Reset Value: 07<sub>H</sub>



Field	Bits	Type	Description
MODE	[1:0]	rw	<b>Bit Protection Scheme Control Bits</b> 00 Scheme disabled - direct access to the protected bits is allowed. 11 Scheme enabled - the bit field PASS has to be written with the passwords to open and close the access to protected bits. (default) Others: Scheme Enabled.  These two bits cannot be written directly. To change the value between 11 <sub>B</sub> and 00 <sub>B</sub> , the bit field PASS must be written with 11000 <sub>B</sub> ; only then, will the MODE[1:0] be registered.
PROTECT_S	2	rh	<b>Bit Protection Signal Status Bit</b> This bit shows the status of the protection. 0 Software is able to write to all protected bits. 1 Software is unable to write to any protected bits.
PASS	[7:3]	wh	<b>Password Bits</b> The Bit Protection Scheme only recognizes three patterns. 11000 <sub>B</sub> Enables writing of the bit field MODE. 10011 <sub>B</sub> Opens access to writing of all protected bits. 10101 <sub>B</sub> Closes access to writing of all protected bits

**Functional Description**
**Table 9 WDT Register Overview (cont'd)**

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
BE <sub>H</sub>	<b>WDTL</b> <b>Reset: 00<sub>H</sub></b> Watchdog Timer Register Low	Bit Field	WDT							
		Type	rh							
BF <sub>H</sub>	<b>WDTH</b> <b>Reset: 00<sub>H</sub></b> Watchdog Timer Register High	Bit Field	WDT							
		Type	rh							

**3.2.4.6 Port Registers**

The Port SFRs can be accessed in the standard memory area (RMAP = 0).

**Table 10 Port Register Overview**

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
RMAP = 0										
B2 <sub>H</sub>	<b>PORT_PAGE</b> <b>Reset: 00<sub>H</sub></b> Page Register	Bit Field	OP		STNR		0	PAGE		
		Type	w		w		r	rw		
RMAP = 0, PAGE 0										
80 <sub>H</sub>	<b>P0_DATA</b> <b>Reset: 00<sub>H</sub></b> P0 Data Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
86 <sub>H</sub>	<b>P0_DIR</b> <b>Reset: 00<sub>H</sub></b> P0 Direction Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
90 <sub>H</sub>	<b>P1_DATA</b> <b>Reset: 00<sub>H</sub></b> P1 Data Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
91 <sub>H</sub>	<b>P1_DIR</b> <b>Reset: 00<sub>H</sub></b> P1 Direction Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
92 <sub>H</sub>	<b>P5_DATA</b> <b>Reset: 00<sub>H</sub></b> P5 Data Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
93 <sub>H</sub>	<b>P5_DIR</b> <b>Reset: 00<sub>H</sub></b> P5 Direction Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
A0 <sub>H</sub>	<b>P2_DATA</b> <b>Reset: 00<sub>H</sub></b> P2 Data Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
A1 <sub>H</sub>	<b>P2_DIR</b> <b>Reset: 00<sub>H</sub></b> P2 Direction Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
B0 <sub>H</sub>	<b>P3_DATA</b> <b>Reset: 00<sub>H</sub></b> P3 Data Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
B1 <sub>H</sub>	<b>P3_DIR</b> <b>Reset: 00<sub>H</sub></b> P3 Direction Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
C8 <sub>H</sub>	<b>P4_DATA</b> <b>Reset: 00<sub>H</sub></b> P4 Data Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
C9 <sub>H</sub>	<b>P4_DIR</b> <b>Reset: 00<sub>H</sub></b> P4 Direction Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw

**Functional Description**
**Table 10 Port Register Overview (cont'd)**

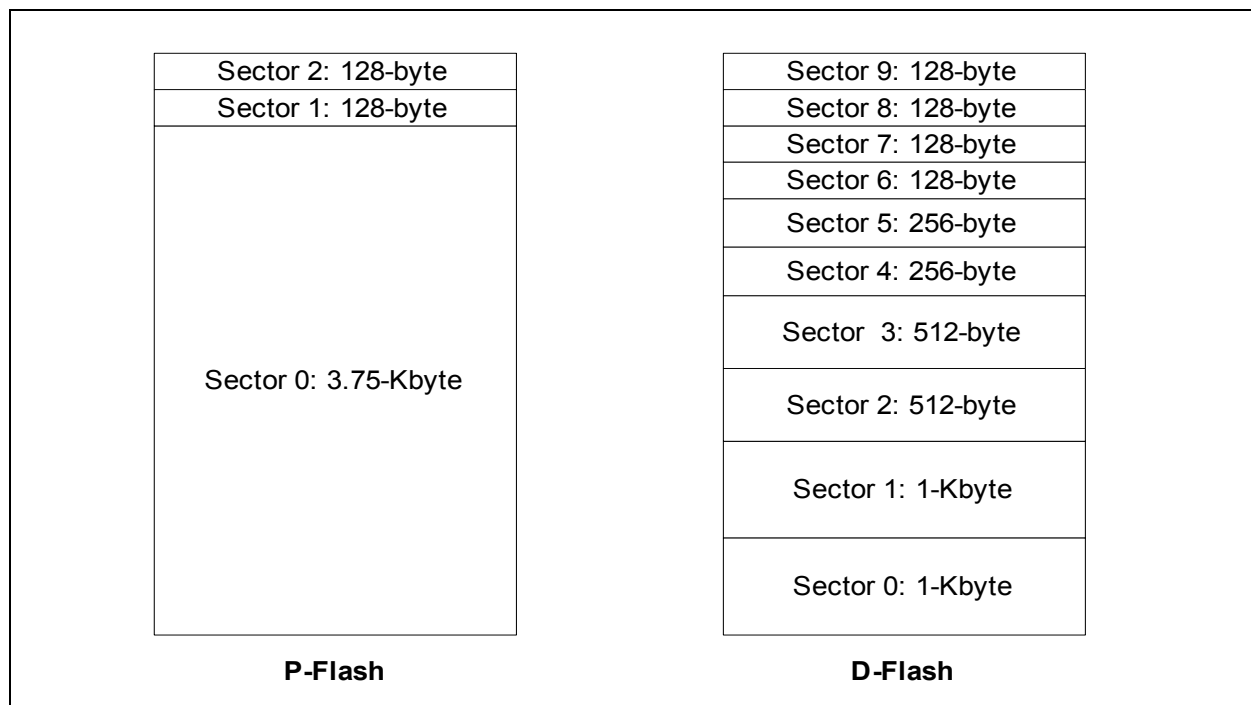
Addr	Register Name	Bit	7	6	5	4	3	2	1	0
RMAP = 0, PAGE 1										
80 <sub>H</sub>	<b>P0_PUDSEL</b> <b>Reset: FF<sub>H</sub></b> P0 Pull-Up/Pull-Down Select Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
86 <sub>H</sub>	<b>P0_PUDEN</b> <b>Reset: C4<sub>H</sub></b> P0 Pull-Up/Pull-Down Enable Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
90 <sub>H</sub>	<b>P1_PUDSEL</b> <b>Reset: FF<sub>H</sub></b> P1 Pull-Up/Pull-Down Select Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
91 <sub>H</sub>	<b>P1_PUDEN</b> <b>Reset: FF<sub>H</sub></b> P1 Pull-Up/Pull-Down Enable Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
92 <sub>H</sub>	<b>P5_PUDSEL</b> <b>Reset: FF<sub>H</sub></b> P5 Pull-Up/Pull-Down Select Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
93 <sub>H</sub>	<b>P5_PUDEN</b> <b>Reset: FF<sub>H</sub></b> P5 Pull-Up/Pull-Down Enable Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
A0 <sub>H</sub>	<b>P2_PUDSEL</b> <b>Reset: FF<sub>H</sub></b> P2 Pull-Up/Pull-Down Select Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
A1 <sub>H</sub>	<b>P2_PUDEN</b> <b>Reset: 00<sub>H</sub></b> P2 Pull-Up/Pull-Down Enable Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
B0 <sub>H</sub>	<b>P3_PUDSEL</b> <b>Reset: BF<sub>H</sub></b> P3 Pull-Up/Pull-Down Select Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
B1 <sub>H</sub>	<b>P3_PUDEN</b> <b>Reset: 40<sub>H</sub></b> P3 Pull-Up/Pull-Down Enable Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
C8 <sub>H</sub>	<b>P4_PUDSEL</b> <b>Reset: FF<sub>H</sub></b> P4 Pull-Up/Pull-Down Select Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
C9 <sub>H</sub>	<b>P4_PUDEN</b> <b>Reset: 04<sub>H</sub></b> P4 Pull-Up/Pull-Down Enable Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
RMAP = 0, PAGE 2										
80 <sub>H</sub>	<b>P0_ALTSEL0</b> <b>Reset: 00<sub>H</sub></b> P0 Alternate Select 0 Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
86 <sub>H</sub>	<b>P0_ALTSEL1</b> <b>Reset: 00<sub>H</sub></b> P0 Alternate Select 1 Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
90 <sub>H</sub>	<b>P1_ALTSEL0</b> <b>Reset: 00<sub>H</sub></b> P1 Alternate Select 0 Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
91 <sub>H</sub>	<b>P1_ALTSEL1</b> <b>Reset: 00<sub>H</sub></b> P1 Alternate Select 1 Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
92 <sub>H</sub>	<b>P5_ALTSEL0</b> <b>Reset: 00<sub>H</sub></b> P5 Alternate Select 0 Register	Bit Field	P7	P6	P5	P4	P3	P2	P1	P0
		Type	rw	rw	rw	rw	rw	rw	rw	rw

**Functional Description**
**Table 18 OCDS Register Overview (cont'd)**

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
E <sub>CH</sub>	<b>MMWR2</b> <b>Reset: 00<sub>H</sub></b> Monitor Work Register 2	Bit Field	MMWR2							
		Type	rw							



## Functional Description



**Figure 11 Flash Bank Sectorization**

The internal structure of each Flash bank represents a sector architecture for flexible erase capability. The minimum erase width is always a complete sector, and sectors can be erased separately or in parallel. Contrary to standard EPROMs, erased Flash memory cells contain 0s.

The D-Flash bank is divided into more physical sectors for extended erasing and reprogramming capability; even numbers for each sector size are provided to allow greater flexibility and the ability to adapt to a wide range of application requirements.

### 3.3.2 Parallel Read Access of P-Flash

To enhance system performance, the P-Flash banks are configured for parallel read to allow two bytes of linear code to be read in 4 x CCLK cycles, compared to 6 x CCLK cycles if serial read is performed. This is achieved by reading two bytes in parallel from a P-Flash bank pair within the 3 x CCLK cycles access time and storing them in a cache. Subsequent read from the cache by the CPU does not require a wait state and can be completed within 1 x CCLK cycle. The result is the average instruction fetch time from the P-Flash banks is reduced and thus, the MIPS (Mega Instruction Per Second) of the system is increased.

However, if the parallel read feature is not desired due to certain timing constraints, it can be disabled by calling the parallel read disable subroutine.

**Functional Description**
**3.4.2 Interrupt Source and Vector**

Each interrupt event source has an associated interrupt vector address for the interrupt node it belongs to. This vector is accessed to service the corresponding interrupt node request. The interrupt service of each interrupt source can be individually enabled or disabled via an enable bit. The assignment of the XC886/888 interrupt sources to the interrupt vector address and the corresponding interrupt node enable bits are summarized in [Table 20](#).

**Table 20 Interrupt Vector Addresses**

Interrupt Source	Vector Address	Assignment for XC886/888	Enable Bit	SFR
NMI	0073 <sub>H</sub>	Watchdog Timer NMI	NMIWDT	NMICON
		PLL NMI	NMIPLL	
		Flash NMI	NMIFLASH	
		VDDC Prewarning NMI	NMIVDD	
		VDDP Prewarning NMI	NMIVDDP	
		Flash ECC NMI	NMIECC	
XINTR0	0003 <sub>H</sub>	External Interrupt 0	EX0	IEN0
XINTR1	000B <sub>H</sub>	Timer 0	ET0	
XINTR2	0013 <sub>H</sub>	External Interrupt 1	EX1	
XINTR3	001B <sub>H</sub>	Timer 1	ET1	
XINTR4	0023 <sub>H</sub>	UART	ES	
XINTR5	002B <sub>H</sub>	T2	ET2	
		UART Fractional Divider (Normal Divider Overflow)		
		MultiCAN Node 0		
		LIN		

**Functional Description**
**Table 20 Interrupt Vector Addresses (cont'd)**

Interrupt Source	Vector Address	Assignment for XC886/888	Enable Bit	SFR
XINTR6	0033 <sub>H</sub>	MultiCAN Nodes 1 and 2	EADC	IEN1
		ADC[1:0]		
XINTR7	003B <sub>H</sub>	SSC	ESSC	
XINTR8	0043 <sub>H</sub>	External Interrupt 2	EX2	
		T21		
		CORDIC		
		UART1		
		UART1 Fractional Divider (Normal Divider Overflow)		
		MDU[1:0]		
XINTR9	004B <sub>H</sub>	External Interrupt 3	EXM	
		External Interrupt 4		
		External Interrupt 5		
		External Interrupt 6		
		MultiCAN Node 3		
XINTR10	0053 <sub>H</sub>	CCU6 INP0	ECCIP0	
		MultiCAN Node 4		
XINTR11	005B <sub>H</sub>	CCU6 INP1	ECCIP1	
		MultiCAN Node 5		
XINTR12	0063 <sub>H</sub>	CCU6 INP2	ECCIP2	
		MultiCAN Node 6		
XINTR13	006B <sub>H</sub>	CCU6 INP3	ECCIP3	
		MultiCAN Node 7		

### 3.5 Parallel Ports

The XC886 has 34 port pins organized into five parallel ports, Port 0 (P0) to Port 4 (P4), while the XC888 has 48 port pins organized into six parallel ports, Port 0 (P0) to Port 5 (P5). Each pin has a pair of internal pull-up and pull-down devices that can be individually enabled or disabled. Ports P0, P1, P3, P4 and P5 are bidirectional and can be used as general purpose input/output (GPIO) or to perform alternate input/output functions for the on-chip peripherals. When configured as an output, the open drain mode can be selected. Port P2 is an input-only port, providing general purpose input functions, alternate input functions for the on-chip peripherals, and also analog inputs for the Analog-to-Digital Converter (ADC).

#### Bidirectional Port Features

- Configurable pin direction
- Configurable pull-up/pull-down devices
- Configurable open drain mode
- Transfer of data through digital inputs and outputs (general purpose I/O)
- Alternate input/output for on-chip peripherals

#### Input Port Features

- Configurable input driver
- Configurable pull-up/pull-down devices
- Receive of data through digital input (general purpose input)
- Alternate input for on-chip peripherals
- Analog input for ADC module

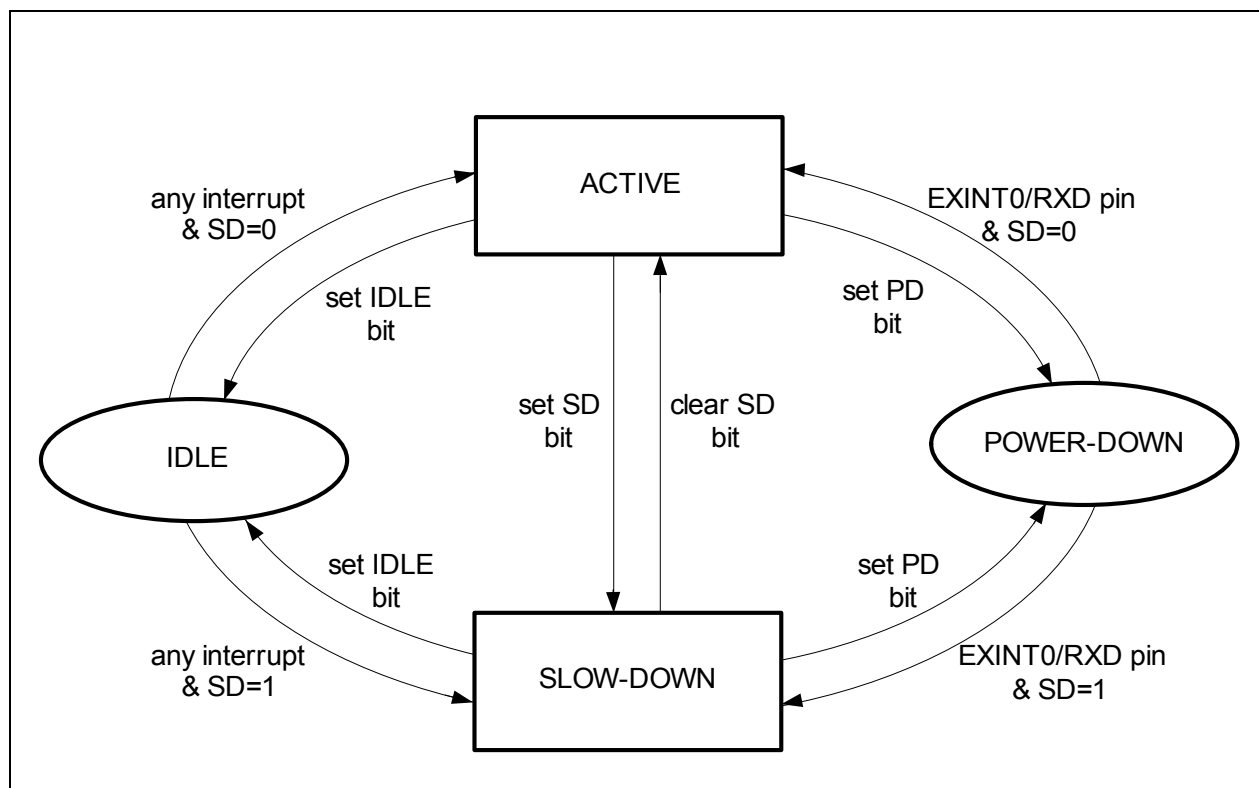
### 3.9 Power Saving Modes

The power saving modes of the XC886/888 provide flexible power consumption through a combination of techniques, including:

- Stopping the CPU clock
- Stopping the clocks of individual system components
- Reducing clock speed of some peripheral components
- Power-down of the entire system with fast restart capability

After a reset, the active mode (normal operating mode) is selected by default (see [Figure 27](#)) and the system runs in the main system clock frequency. From active mode, different power saving modes can be selected by software. They are:

- Idle mode
- Slow-down mode
- Power-down mode



**Figure 27 Transition between Power Saving Modes**

## Functional Description

### 3.10 Watchdog Timer

The Watchdog Timer (WDT) provides a highly reliable and secure way to detect and recover from software or hardware failures. The WDT is reset at a regular interval that is predefined by the user. The CPU must service the WDT within this interval to prevent the WDT from causing an XC886/888 system reset. Hence, routine service of the WDT confirms that the system is functioning properly. This ensures that an accidental malfunction of the XC886/888 will be aborted in a user-specified time period.

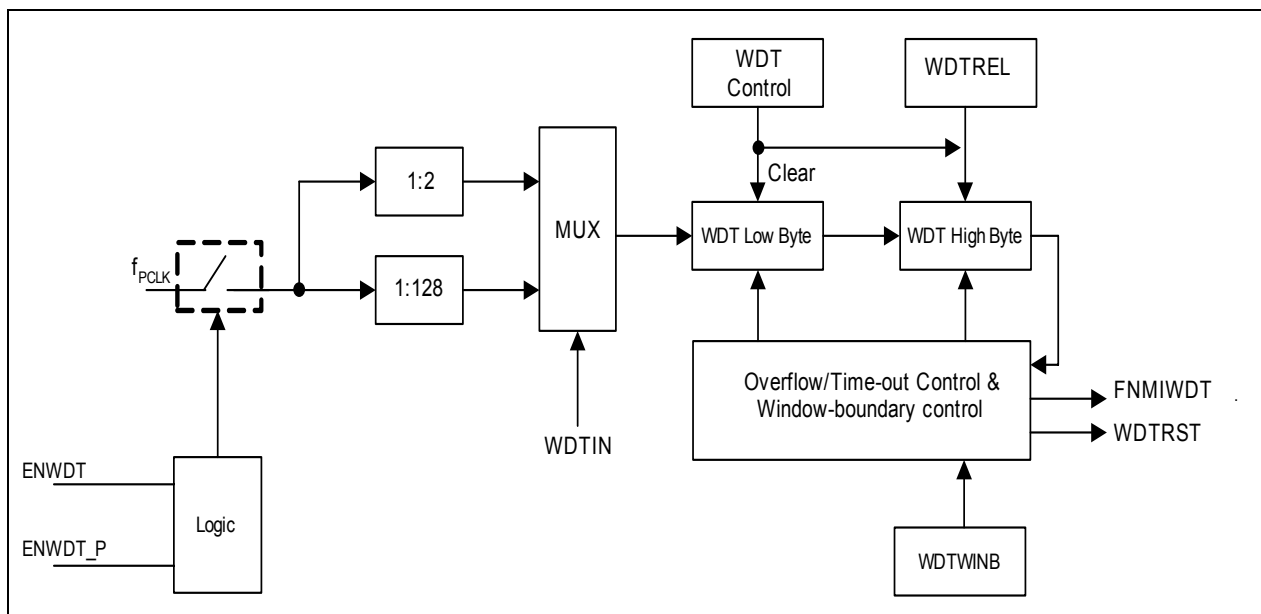
In debug mode, the WDT is default suspended and stops counting. Therefore, there is no need to refresh the WDT during debugging.

#### Features

- 16-bit Watchdog Timer
- Programmable reload value for upper 8 bits of timer
- Programmable window boundary
- Selectable input frequency of  $f_{PCLK}/2$  or  $f_{PCLK}/128$
- Time-out detection with NMI generation and reset prewarning activation (after which a system reset will be performed)

The WDT is a 16-bit timer incremented by a count rate of  $f_{PCLK}/2$  or  $f_{PCLK}/128$ . This 16-bit timer is realized as two concatenated 8-bit timers. The upper 8 bits of the WDT can be preset to a user-programmable value via a watchdog service access in order to modify the watchdog expire time period. The lower 8 bits are reset on each service access.

**Figure 28** shows the block diagram of the WDT unit.



**Figure 28 WDT Block Diagram**

**Functional Description**
**Table 36 Chip Identification Number (cont'd)**

Product Variant	Chip Identification Number		
	AA-Step	AB-Step	AC-Step
XC886-6FFA 3V3	-	095D1562 <sub>H</sub>	0B5D1562 <sub>H</sub>
XC888-6FFA 3V3	-	095D1563 <sub>H</sub>	0B5D1563 <sub>H</sub>
XC886CLM-8FFA 5V	-	09900102 <sub>H</sub>	0B900102 <sub>H</sub>
XC888CLM-8FFA 5V	-	09900103 <sub>H</sub>	0B900103 <sub>H</sub>
XC886LM-8FFA 5V	-	09900122 <sub>H</sub>	0B900122 <sub>H</sub>
XC888LM-8FFA 5V	-	09900123 <sub>H</sub>	0B900123 <sub>H</sub>
XC886CLM-6FFA 5V	-	09951502 <sub>H</sub>	0B951502 <sub>H</sub>
XC888CLM-6FFA 5V	-	09951503 <sub>H</sub>	0B951503 <sub>H</sub>
XC886LM-6FFA 5V	-	09951522 <sub>H</sub>	0B951522 <sub>H</sub>
XC888LM-6FFA 5V	-	09951523 <sub>H</sub>	0B951523 <sub>H</sub>
XC886CM-8FFA 5V	-	09980102 <sub>H</sub>	0B980102 <sub>H</sub>
XC888CM-8FFA 5V	-	09980103 <sub>H</sub>	0B980103 <sub>H</sub>
XC886C-8FFA 5V	-	09980142 <sub>H</sub>	0B980142 <sub>H</sub>
XC888C-8FFA 5V	-	09980143 <sub>H</sub>	0B980143 <sub>H</sub>
XC886-8FFA 5V	-	09980162 <sub>H</sub>	0B980162 <sub>H</sub>
XC888-8FFA 5V	-	09980163 <sub>H</sub>	0B980163 <sub>H</sub>
XC886CM-6FFA 5V	-	099D1502 <sub>H</sub>	0B9D1502 <sub>H</sub>
XC888CM-6FFA 5V	-	099D1503 <sub>H</sub>	0B9D1503 <sub>H</sub>
XC886C-6FFA 5V	-	099D1542 <sub>H</sub>	0B9D1542 <sub>H</sub>
XC888C-6FFA 5V	-	099D1543 <sub>H</sub>	0B9D1543 <sub>H</sub>
XC886-6FFA 5V	-	099D1562 <sub>H</sub>	0B9D1562 <sub>H</sub>
XC888-6FFA 5V	-	099D1563 <sub>H</sub>	0B9D1563 <sub>H</sub>

**ROM Devices**

XC886CLM-8RFA 3V3	22400502 <sub>H</sub>	-	-
XC888CLM-8RFA 3V3	22400503 <sub>H</sub>	-	-
XC886LM-8RFA 3V3	22400522 <sub>H</sub>	-	-
XC888LM-8RFA 3V3	22400523 <sub>H</sub>	-	-
XC886CLM-6RFA 3V3	22411502 <sub>H</sub>	-	-
XC888CLM-6RFA 3V3	22411503 <sub>H</sub>	-	-

## Functional Description

**Table 36**      **Chip Identification Number (cont'd)**

Product Variant	Chip Identification Number		
	AA-Step	AB-Step	AC-Step
XC886LM-6RFA 3V3	22411522 <sub>H</sub>	-	-
XC888LM-6RFA 3V3	22411523 <sub>H</sub>	-	-
XC886CM-8RFA 3V3	22480502 <sub>H</sub>	-	-
XC888CM-8RFA 3V3	22480503 <sub>H</sub>	-	-
XC886C-8RFA 3V3	22480542 <sub>H</sub>	-	-
XC888C-8RFA 3V3	22480543 <sub>H</sub>	-	-
XC886-8RFA 3V3	22480562 <sub>H</sub>	-	-
XC888-8RFA 3V3	22480563 <sub>H</sub>	-	-
XC886CM-6RFA 3V3	22491502 <sub>H</sub>	-	-
XC888CM-6RFA 3V3	22491503 <sub>H</sub>	-	-
XC886C-6RFA 3V3	22491542 <sub>H</sub>	-	-
XC888C-6RFA 3V3	22491543 <sub>H</sub>	-	-
XC886-6RFA 3V3	22491562 <sub>H</sub>	-	-
XC888-6RFA 3V3	22491563 <sub>H</sub>	-	-
XC886CLM-8RFA 5V	22800502 <sub>H</sub>	-	-
XC888CLM-8RFA 5V	22800503 <sub>H</sub>	-	-
XC886LM-8RFA 5V	22800522 <sub>H</sub>	-	-
XC888LM-8RFA 5V	22800523 <sub>H</sub>	-	-
XC886CLM-6RFA 5V	22811502 <sub>H</sub>	-	-
XC888CLM-6RFA 5V	22811503 <sub>H</sub>	-	-
XC886LM-6RFA 5V	22811522 <sub>H</sub>	-	-
XC888LM-6RFA 5V	22811523 <sub>H</sub>	-	-
XC886CM-8RFA 5V	22880502 <sub>H</sub>	-	-
XC888CM-8RFA 5V	22880503 <sub>H</sub>	-	-
XC886C-8RFA 5V	22880542 <sub>H</sub>	-	-
XC888C-8RFA 5V	22880543 <sub>H</sub>	-	-
XC886-8RFA 5V	22880562 <sub>H</sub>	-	-
XC888-8RFA 5V	22880563 <sub>H</sub>	-	-
XC886CM-6RFA 5V	22891502 <sub>H</sub>	-	-



## Electrical Parameters

### 4.1.2 Absolute Maximum Rating

Maximum ratings are the extreme limits to which the XC886/888 can be subjected to without permanent damage.

**Table 4-1 Absolute Maximum Rating Parameters**

Parameter	Symbol	Limit Values		Unit	Notes
		min.	max.		
Ambient temperature	$T_A$	-40	125	°C	under bias
Storage temperature	$T_{ST}$	-65	150	°C	<sup>1)</sup>
Junction temperature	$T_J$	-40	150	°C	under bias <sup>1)</sup>
Voltage on power supply pin with respect to $V_{SS}$	$V_{DDP}$	-0.5	6	V	<sup>1)</sup>
Voltage on any pin with respect to $V_{SS}$	$V_{IN}$	-0.5	$V_{DDP} + 0.5$ or max. 6	V	whichever is lower <sup>1)</sup>
Input current on any pin during overload condition	$I_{IN}$	-10	10	mA	<sup>1)</sup>
Absolute sum of all input currents during overload condition	$\Sigma I_{IN} $	—	50	mA	<sup>1)</sup>

1) Not subjected to production test, verified by design/characterization.

*Note: Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. During absolute maximum rating overload conditions ( $V_{IN} > V_{DDP}$  or  $V_{IN} < V_{SS}$ ) the voltage on  $V_{DDP}$  pin with respect to ground ( $V_{SS}$ ) must not exceed the values defined by the absolute maximum ratings.*

**Electrical Parameters**
**Table 38 Input/Output Characteristics (Operating Conditions apply) (cont'd)**

Parameter	Symbol		Limit Values		Unit	Test Conditions
			min.	max.		
Input high voltage at XTAL1	$V_{IHx}$	SR	$0.7 \times V_{DDC}$	$V_{DDC} + 0.5$	V	
Pull-up current	$I_{PU}$	SR	–	-5	$\mu A$	$V_{IHP,min}$
			-50	–	$\mu A$	$V_{ILP,max}$
Pull-down current	$I_{PD}$	SR	–	5	$\mu A$	$V_{ILP,max}$
			50	–	$\mu A$	$V_{IHP,min}$
Input leakage current	$I_{OZ1}$	CC	-1	1	$\mu A$	$0 < V_{IN} < V_{DDP}$ , $T_A \leq 125^\circ C^{2)}$
Input current at XTAL1	$I_{ILx}$	CC	- 10	10	$\mu A$	
Overload current on any pin	$I_{OV}$	SR	-5	5	mA	
Absolute sum of overload currents	$\Sigma  I_{OV} $	SR	–	25	mA	<sup>3)</sup>
Voltage on any pin during $V_{DDP}$ power off	$V_{PO}$	SR	–	0.3	V	<sup>4)</sup>
Maximum current per pin (excluding $V_{DDP}$ and $V_{SS}$ )	$I_M$	SR SR	–	15	mA	
Maximum current for all pins (excluding $V_{DDP}$ and $V_{SS}$ )	$\Sigma  I_M $	SR	–	90	mA	
Maximum current into $V_{DDP}$	$I_{MVDDP}$	SR	–	120	mA	<sup>3)</sup>
Maximum current out of $V_{SS}$	$I_{MVSS}$	SR	–	120	mA	<sup>3)</sup>

- 1) Not subjected to production test, verified by design/characterization. Hysteresis is implemented to avoid meta stable states and switching due to internal ground bounce. It cannot be guaranteed that it suppresses switching due to external system noise.
- 2) An additional error current ( $I_{INJ}$ ) will flow if an overload current flows through an adjacent pin. TMS pin and RESET pin have internal pull devices and are not included in the input leakage current characteristic.
- 3) Not subjected to production test, verified by design/characterization.
- 4) Not subjected to production test, verified by design/characterization. However, for applications with strict low power-down current requirements, it is mandatory that no active voltage source is supplied at any GPIO pin when  $V_{DDP}$  is powered off.

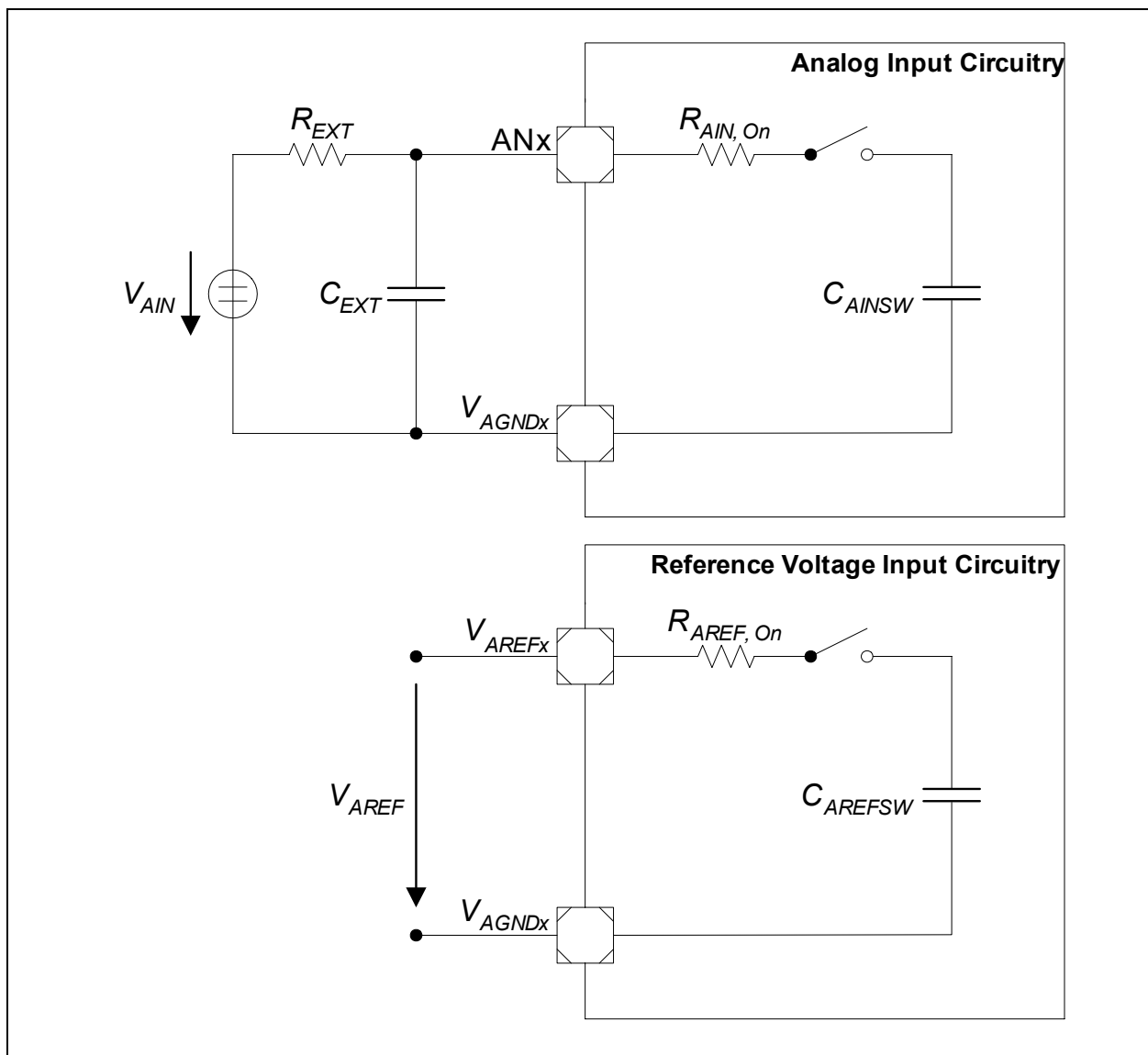


Figure 39 ADC Input Circuits

**Electrical Parameters**
**4.3.5 External Clock Drive XTAL1**

**Table 48** shows the parameters that define the external clock supply for XC886/888. These timing parameters are based on the direct XTAL1 drive of clock input signals. They are not applicable if an external crystal or ceramic resonator is considered.

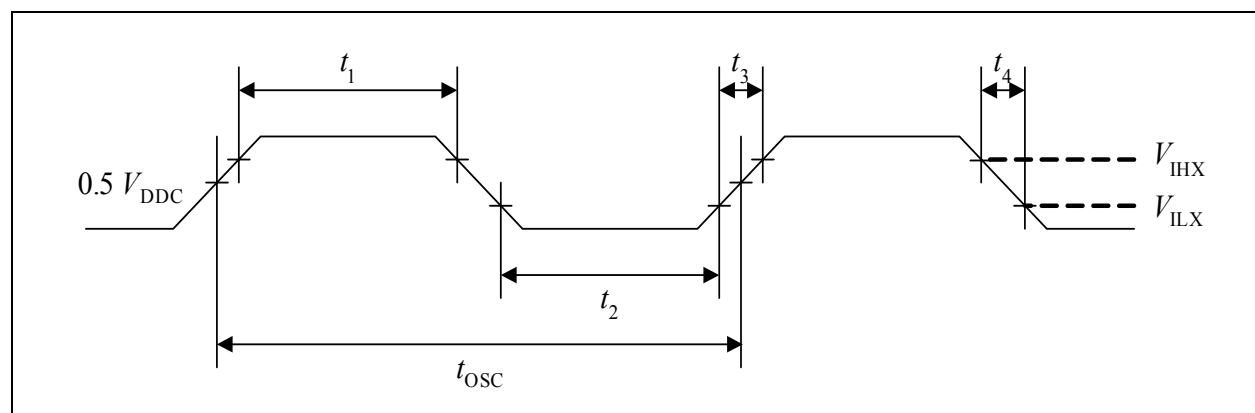
**Table 48 External Clock Drive Characteristics (Operating Conditions apply)**

Parameter	Symbol		Limit Values		Unit	Test Conditions
			Min.	Max.		
Oscillator period	$t_{osc}$	SR	83.3	250	ns	1)2)
High time	$t_1$	SR	25	-	ns	2)3)
Low time	$t_2$	SR	25	-	ns	2)3)
Rise time	$t_3$	SR	-	20	ns	2)3)
Fall time	$t_4$	SR	-	20	ns	2)3)

1) The clock input signals with 45-55% duty cycle are used.

2) Not all parameters are 100% tested, but are verified by design/characterization and test correlation.

3) The clock input signal must reach the defined levels  $V_{ILX}$  and  $V_{IHx}$ .



**Figure 45 External Clock Drive XTAL1**

