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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

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Details

Product Status	Active
Core Processor	XC800
Core Size	8-Bit
Speed	24MHz
Connectivity	CANbus, SSI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	34
Program Memory Size	32KB (32K x 8)
Program Memory Type	ROM
EEPROM Size	-
RAM Size	1.75K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	PG-TQFP-48
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/xc886cm8rfa5vaakzza1

General Device Information
Table 3 Pin Definitions and Functions (cont'd)

Symbol	Pin Number (TQFP-48/64)	Type	Reset State	Function
P1		I/O		Port 1 Port 1 is an 8-bit bidirectional general purpose I/O port. It can be used as alternate functions for the JTAG, CCU6, UART, Timer 0, Timer 1, Timer 2, Timer 21, MultiCAN and SSC.
P1.0	26/34		PU	RXD_0 UART Receive Data Input T2EX Timer 2 External Trigger Input RXDC0_0 MultiCAN Node 0 Receiver Input
P1.1	27/35		PU	EXINT3 External Interrupt Input 3 T0_1 Timer 0 Input TDO_1 JTAG Serial Data Output TXD_0 UART Transmit Data Output/Clock Output TXDC0_0 MultiCAN Node 0 Transmitter Output
P1.2	28/36		PU	SCK_0 SSC Clock Input/Output
P1.3	29/37		PU	MTSR_0 SSC Master Transmit Output/Slave Receive Input TXDC1_3 MultiCAN Node 1 Transmitter Output
P1.4	30/38		PU	MRST_0 SSC Master Receive Input/ Slave Transmit Output EXINT0_1 External Interrupt Input 0 RXDC1_3 MultiCAN Node 1 Receiver Input
P1.5	31/39		PU	CCPOS0_1 CCU6 Hall Input 0 EXINT5 External Interrupt Input 5 T1_1 Timer 1 Input EXF2_0 Timer 2 External Flag Output RXDO_0 UART Transmit Data Output

General Device Information

Table 3 Pin Definitions and Functions (cont'd)

Symbol	Pin Number (TQFP-48/64)	Type	Reset State	Function	
P4		I/O		Port 4 Port 4 is an 8-bit bidirectional general purpose I/O port. It can be used as alternate functions for CCU6, Timer 0, Timer 1, Timer 21 and MultiCAN.	
P4.0	45/59		Hi-Z	RXDC0_3 CC60_1	MultiCAN Node 0 Receiver Input Output of Capture/Compare channel 0
P4.1	46/60		Hi-Z	TXDC0_3 COUT60_1	MultiCAN Node 0 Transmitter Output Output of Capture/Compare channel 0
P4.2	–/61		PU	EXINT6_1 T21_0	External Interrupt Input 6 Timer 21 Input
P4.3	32/40		Hi-Z	EXF21_1 COUT63_2	Timer 21 External Flag Output Output of Capture/Compare channel 3
P4.4	–/45		Hi-Z	CCPOS0_3 T0_0 CC61_4	CCU6 Hall Input 0 Timer 0 Input Output of Capture/Compare channel 1
P4.5	–/46		Hi-Z	CCPOS1_3 T1_0 COUT61_2	CCU6 Hall Input 1 Timer 1 Input Output of Capture/Compare channel 1
P4.6	–/47		Hi-Z	CCPOS2_3 T2_0 CC62_2	CCU6 Hall Input 2 Timer 2 Input Output of Capture/Compare channel 2
P4.7	–/48		Hi-Z	CTRAP_3 COUT62_2	CCU6 Trap Input Output of Capture/Compare channel 2

Functional Description

Table 4 Flash Protection Modes (cont'd)

Flash Protection	Without hardware protection	With hardware protection	
P-Flash program and erase	Possible	Not possible	Not possible
D-Flash contents can be read by	Read instructions in any program memory	Read instructions in any program memory	Read instructions in the P-Flash or D-Flash
External access to D-Flash	Not possible	Not possible	Not possible
D-Flash program	Possible	Possible	Not possible
D-Flash erase	Possible	Possible, on condition that bit DFLASHEN in register MISC_CON is set to 1 prior to each erase operation	Not possible

BSL mode 6, which is used for enabling Flash protection, can also be used for disabling Flash protection. Here, the programmed password must be provided by the user. A password match triggers an automatic erase of the protected P-Flash and D-Flash contents, including the programmed password. The Flash protection is then disabled upon the next reset.

For the ROM device, the ROM is protected at all times and BSL mode 6 is used only to block external access to the device. However, unlike the Flash device, it is not possible to disable the memory protection of the ROM device. Here, entering BSL mode 6 will result in a protection error.

Note: If ROM read-out protection is enabled, only read instructions in the ROM memory can target the ROM contents.

Although no protection scheme can be considered infallible, the XC886/888 memory protection strategy provides a very high level of protection for a general purpose microcontroller.

Functional Description

- Overwrite the contents of PAGE with the contents of STx, ignoring the value written to the bit positions of PAGE
(this is done at the end of the interrupt routine to restore the previous page setting before the interrupt occurred)

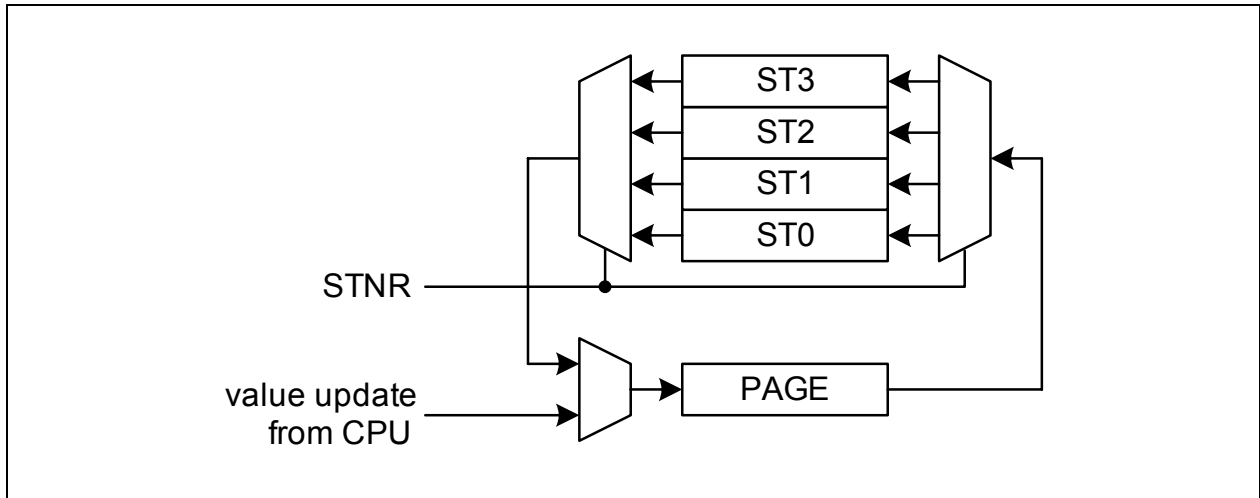


Figure 10 Storage Elements for Paging

With this mechanism, a certain number of interrupt routines (or other routines) can perform page changes without reading and storing the previously used page information. The use of only write operations makes the system simpler and faster. Consequently, this mechanism significantly improves the performance of short interrupt routines.

The XC886/888 supports local address extension for:

- Parallel Ports
- Analog-to-Digital Converter (ADC)
- Capture/Compare Unit 6 (CCU6)
- System Control Registers

Functional Description
Table 5 CPU Register Overview (cont'd)

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
A8 _H	IEN0 Reset: 00_H Interrupt Enable Register 0	Bit Field	EA	0	ET2	ES	ET1	EX1	ET0	EX0
		Type	rw	r	rw	rw	rw	rw	rw	rw
B8 _H	IP Reset: 00_H Interrupt Priority Register	Bit Field	0		PT2	PS	PT1	PX1	PT0	PX0
		Type	r		rw	rw	rw	rw	rw	rw
B9 _H	IPH Reset: 00_H Interrupt Priority High Register	Bit Field	0		PT2H	PSH	PT1H	PX1H	PT0H	PX0H
		Type	r		rw	rw	rw	rw	rw	rw
D0 _H	PSW Reset: 00_H Program Status Word Register	Bit Field	CY	AC	F0	RS1	RS0	OV	F1	P
		Type	rwh	rwh	rw	rw	rw	rwh	rw	rh
E0 _H	ACC Reset: 00_H Accumulator Register	Bit Field	ACC7	ACC6	ACC5	ACC4	ACC3	ACC2	ACC1	ACC0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
E8 _H	IEN1 Reset: 00_H Interrupt Enable Register 1	Bit Field	ECCIP 3	ECCIP 2	ECCIP 1	ECCIP 0	EXM	EX2	ESSC	EADC
		Type	rw	rw	rw	rw	rw	rw	rw	rw
F0 _H	B Reset: 00_H B Register	Bit Field	B7	B6	B5	B4	B3	B2	B1	B0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
F8 _H	IP1 Reset: 00_H Interrupt Priority 1 Register	Bit Field	PCCIP 3	PCCIP 2	PCCIP 1	PCCIP 0	PXM	PX2	PSSC	PADC
		Type	rw	rw	rw	rw	rw	rw	rw	rw
F9 _H	IPH1 Reset: 00_H Interrupt Priority 1 High Register	Bit Field	PCCIP 3H	PCCIP 2H	PCCIP 1H	PCCIP 0H	PXMH	PX2H	PSSC H	PADC H
		Type	rw	rw	rw	rw	rw	rw	rw	rw

3.2.4.2 MDU Registers

The MDU SFRs can be accessed in the mapped memory area (RMAP = 1).

Table 6 MDU Register Overview

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
RMAP = 1										
B0 _H	MDUSTAT Reset: 00_H MDU Status Register	Bit Field	0					BSY	IERR	IRDY
		Type	r					rh	rwh	rwh
B1 _H	MDUCON Reset: 00_H MDU Control Register	Bit Field	IE	IR	RSEL	STAR T	OPCODE			
		Type	rw	rw	rw	rwh	rw			
B2 _H	MD0 Reset: 00_H MDU Operand Register 0	Bit Field	DATA							
		Type	rw							
B2 _H	MR0 Reset: 00_H MDU Result Register 0	Bit Field	DATA							
		Type	rh							
B3 _H	MD1 Reset: 00_H MDU Operand Register 1	Bit Field	DATA							
		Type	rw							

Functional Description
Table 11 ADC Register Overview (cont'd)

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
D3 _H	ADC_RESR3H Reset: 00 _H Result Register 3 High	Bit Field	RESULT							
		Type	rh							
RMAP = 0, PAGE 3										
CA _H	ADC_RESRA0L Reset: 00 _H Result Register 0, View A Low	Bit Field	RESULT			VF	DRC	CHNR		
		Type	rh			rh	rh	rh		
CB _H	ADC_RESRA0H Reset: 00 _H Result Register 0, View A High	Bit Field	RESULT							
		Type	rh							
CC _H	ADC_RESRA1L Reset: 00 _H Result Register 1, View A Low	Bit Field	RESULT			VF	DRC	CHNR		
		Type	rh			rh	rh	rh		
CD _H	ADC_RESRA1H Reset: 00 _H Result Register 1, View A High	Bit Field	RESULT							
		Type	rh							
CE _H	ADC_RESRA2L Reset: 00 _H Result Register 2, View A Low	Bit Field	RESULT			VF	DRC	CHNR		
		Type	rh			rh	rh	rh		
CF _H	ADC_RESRA2H Reset: 00 _H Result Register 2, View A High	Bit Field	RESULT							
		Type	rh							
D2 _H	ADC_RESRA3L Reset: 00 _H Result Register 3, View A Low	Bit Field	RESULT			VF	DRC	CHNR		
		Type	rh			rh	rh	rh		
D3 _H	ADC_RESRA3H Reset: 00 _H Result Register 3, View A High	Bit Field	RESULT							
		Type	rh							
RMAP = 0, PAGE 4										
CA _H	ADC_RCR0 Reset: 00 _H Result Control Register 0	Bit Field	VFCT R	WFR	0	IEN	0			DRCT R
		Type	rw	rw	r	rw	r			rw
CB _H	ADC_RCR1 Reset: 00 _H Result Control Register 1	Bit Field	VFCT R	WFR	0	IEN	0			DRCT R
		Type	rw	rw	r	rw	r			rw
CC _H	ADC_RCR2 Reset: 00 _H Result Control Register 2	Bit Field	VFCT R	WFR	0	IEN	0			DRCT R
		Type	rw	rw	r	rw	r			rw
CD _H	ADC_RCR3 Reset: 00 _H Result Control Register 3	Bit Field	VFCT R	WFR	0	IEN	0			DRCT R
		Type	rw	rw	r	rw	r			rw
CE _H	ADC_VFCR Reset: 00 _H Valid Flag Clear Register	Bit Field	0				VFC3	VFC2	VFC1	VFC0
		Type	r				w	w	w	w
RMAP = 0, PAGE 5										
CA _H	ADC_CHINFR Reset: 00 _H Channel Interrupt Flag Register	Bit Field	CHINF 7	CHINF 6	CHINF 5	CHINF 4	CHINF 3	CHINF 2	CHINF 1	CHINF 0
		Type	rh	rh	rh	rh	rh	rh	rh	rh
CB _H	ADC_CHINCR Reset: 00 _H Channel Interrupt Clear Register	Bit Field	CHINC 7	CHINC 6	CHINC 5	CHINC 4	CHINC 3	CHINC 2	CHINC 1	CHINC 0
		Type	w	w	w	w	w	w	w	w

Functional Description
Table 11 ADC Register Overview (cont'd)

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
CC _H	ADC_CHINSR Reset: 00_H Channel Interrupt Set Register	Bit Field	CHINS 7	CHINS 6	CHINS 5	CHINS 4	CHINS 3	CHINS 2	CHINS 1	CHINS 0
		Type	w	w	w	w	w	w	w	w
CD _H	ADC_CHINPR Reset: 00_H Channel Interrupt Node Pointer Register	Bit Field	CHINP 7	CHINP 6	CHINP 5	CHINP 4	CHINP 3	CHINP 2	CHINP 1	CHINP 0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
CE _H	ADC_EVINFR Reset: 00_H Event Interrupt Flag Register	Bit Field	EVINF 7	EVINF 6	EVINF 5	EVINF 4	0		EVINF 1	EVINF 0
		Type	rh	rh	rh	rh	r		rh	rh
CF _H	ADC_EVINCR Reset: 00_H Event Interrupt Clear Flag Register	Bit Field	EVINC 7	EVINC 6	EVINC 5	EVINC 4	0		EVINC 1	EVINC 0
		Type	w	w	w	w	r		w	w
D2 _H	ADC_EVINSR Reset: 00_H Event Interrupt Set Flag Register	Bit Field	EVINS 7	EVINS 6	EVINS 5	EVINS 4	0		EVINS 1	EVINS 0
		Type	w	w	w	w	r		w	w
D3 _H	ADC_EVINPR Reset: 00_H Event Interrupt Node Pointer Register	Bit Field	EVINP 7	EVINP 6	EVINP 5	EVINP 4	0		EVINP 1	EVINP 0
		Type	rw	rw	rw	rw	r		rw	rw
RMAP = 0, PAGE 6										
CA _H	ADC_CRCR1 Reset: 00_H Conversion Request Control Register 1	Bit Field	CH7	CH6	CH5	CH4	0			
		Type	rwh	rwh	rwh	rwh	r			
CB _H	ADC_CRPR1 Reset: 00_H Conversion Request Pending Register 1	Bit Field	CHP7	CHP6	CHP5	CHP4	0			
		Type	rwh	rwh	rwh	rwh	r			
CC _H	ADC_CMR1 Reset: 00_H Conversion Request Mode Register 1	Bit Field	Rsv	LDEV	CLRP ND	SCAN	ENSI	ENTR	0	ENGT
		Type	r	w	w	rw	rw	rw	r	rw
CD _H	ADC_QMR0 Reset: 00_H Queue Mode Register 0	Bit Field	CEV	TREV	FLUS H	CLRV	0	ENTR	0	ENGT
		Type	w	w	w	w	r	rw	r	rw
CE _H	ADC_QSR0 Reset: 20_H Queue Status Register 0	Bit Field	Rsv	0	EMPT Y	EV	0		FILL	
		Type	r	r	rh	rh	r		rh	
CF _H	ADC_Q0R0 Reset: 00_H Queue 0 Register 0	Bit Field	EXTR	ENSI	RF	V	0	REQCHNR		
		Type	rh	rh	rh	rh	r	rh		
D2 _H	ADC_QBUR0 Reset: 00_H Queue Backup Register 0	Bit Field	EXTR	ENSI	RF	V	0	REQCHNR		
		Type	rh	rh	rh	rh	r	rh		
D2 _H	ADC_QINR0 Reset: 00_H Queue Input Register 0	Bit Field	EXTR	ENSI	RF	0		REQCHNR		
		Type	w	w	w	r		w		

Functional Description

3.2.4.8 Timer 2 Registers

The Timer 2 SFRs can be accessed in the standard memory area (RMAP = 0).

Table 12 T2 Register Overview

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
RMAP = 0										
C0 _H	T2_T2CON Reset: 00 _H Timer 2 Control Register	Bit Field	TF2	EXF2	0		EXEN 2	TR2	C/ $\overline{T2}$	CP/ RL2
		Type	rwh	rwh	r		rw	rwh	rw	rw
C1 _H	T2_T2MOD Reset: 00 _H Timer 2 Mode Register	Bit Field	T2RE GS	T2RH EN	EDGE SEL	PREN	T2PRE			DCEN
		Type	rw	rw	rw	rw	rw	rw	rw	rw
C2 _H	T2_RC2L Reset: 00 _H Timer 2 Reload/Capture Register Low	Bit Field	RC2							
		Type	rwh							
C3 _H	T2_RC2H Reset: 00 _H Timer 2 Reload/Capture Register High	Bit Field	RC2							
		Type	rwh							
C4 _H	T2_T2L Reset: 00 _H Timer 2 Register Low	Bit Field	THL2							
		Type	rwh							
C5 _H	T2_T2H Reset: 00 _H Timer 2 Register High	Bit Field	THL2							
		Type	rwh							

3.2.4.9 Timer 21 Registers

The Timer 21 SFRs can be accessed in the mapped memory area (RMAP = 1).

Table 13 T21 Register Overview

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
RMAP = 1										
C0 _H	T21_T2CON Reset: 00 _H Timer 2 Control Register	Bit Field	TF2	EXF2	0		EXEN 2	TR2	C/ $\overline{T2}$	CP/ RL2
		Type	rwh	rwh	r		rw	rwh	rw	rw
C1 _H	T21_T2MOD Reset: 00 _H Timer 2 Mode Register	Bit Field	T2RE GS	T2RH EN	EDGE SEL	PREN	T2PRE			DCEN
		Type	rw	rw	rw	rw	rw	rw	rw	rw
C2 _H	T21_RC2L Reset: 00 _H Timer 2 Reload/Capture Register Low	Bit Field	RC2							
		Type	rwh							
C3 _H	T21_RC2H Reset: 00 _H Timer 2 Reload/Capture Register High	Bit Field	RC2							
		Type	rwh							
C4 _H	T21_T2L Reset: 00 _H Timer 2 Register Low	Bit Field	THL2							
		Type	rwh							

3.5 Parallel Ports

The XC886 has 34 port pins organized into five parallel ports, Port 0 (P0) to Port 4 (P4), while the XC888 has 48 port pins organized into six parallel ports, Port 0 (P0) to Port 5 (P5). Each pin has a pair of internal pull-up and pull-down devices that can be individually enabled or disabled. Ports P0, P1, P3, P4 and P5 are bidirectional and can be used as general purpose input/output (GPIO) or to perform alternate input/output functions for the on-chip peripherals. When configured as an output, the open drain mode can be selected. Port P2 is an input-only port, providing general purpose input functions, alternate input functions for the on-chip peripherals, and also analog inputs for the Analog-to-Digital Converter (ADC).

Bidirectional Port Features

- Configurable pin direction
- Configurable pull-up/pull-down devices
- Configurable open drain mode
- Transfer of data through digital inputs and outputs (general purpose I/O)
- Alternate input/output for on-chip peripherals

Input Port Features

- Configurable input driver
- Configurable pull-up/pull-down devices
- Receive of data through digital input (general purpose input)
- Alternate input for on-chip peripherals
- Analog input for ADC module

Functional Description

Figure 20 shows the structure of an input-only port pin.

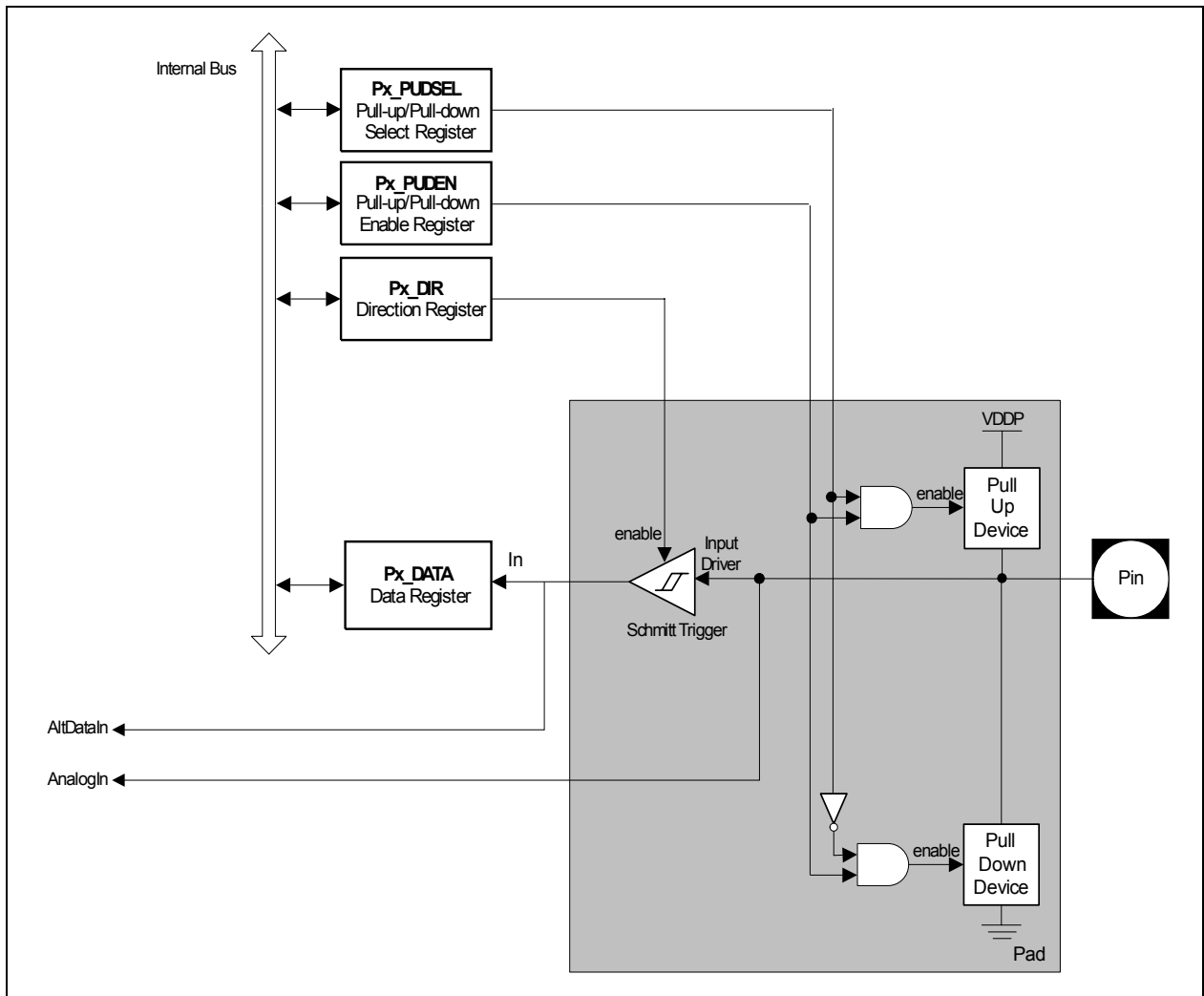


Figure 20 General Structure of Input Port

Functional Description

- 1) BSL mode is automatically entered if no valid password is installed and data at memory address 0000H equals zero.
- 2) OSC is bypassed in MultiCAN BSL mode
- 3) Normal user mode with standard JTAG (TCK,TDI,TDO) pins for hot-attach purpose.

Note: The boot options are valid only with the default set of UART and JTAG pins.

3.8 Clock Generation Unit

The Clock Generation Unit (CGU) allows great flexibility in the clock generation for the XC886/888. The power consumption is indirectly proportional to the frequency, whereas the performance of the microcontroller is directly proportional to the frequency. During user program execution, the frequency can be programmed for an optimal ratio between performance and power consumption. Therefore the power consumption can be adapted to the actual application state.

Features

- Phase-Locked Loop (PLL) for multiplying clock source by different factors
- PLL Base Mode
- Prescaler Mode
- PLL Mode
- Power-down mode support

The CGU consists of an oscillator circuit and a PLL. In the XC886/888, the oscillator can be from either of these two sources: the on-chip oscillator (9.6 MHz) or the external oscillator (4 MHz to 12 MHz). The term “oscillator” is used to refer to both on-chip oscillator and external oscillator, unless otherwise stated. After the reset, the on-chip oscillator will be used by default. The external oscillator can be selected via software. In addition, the PLL provides a fail-safe logic to perform oscillator run and loss-of-lock detection. This allows emergency routines to be executed for system recovery or to perform system shut down.

Functional Description

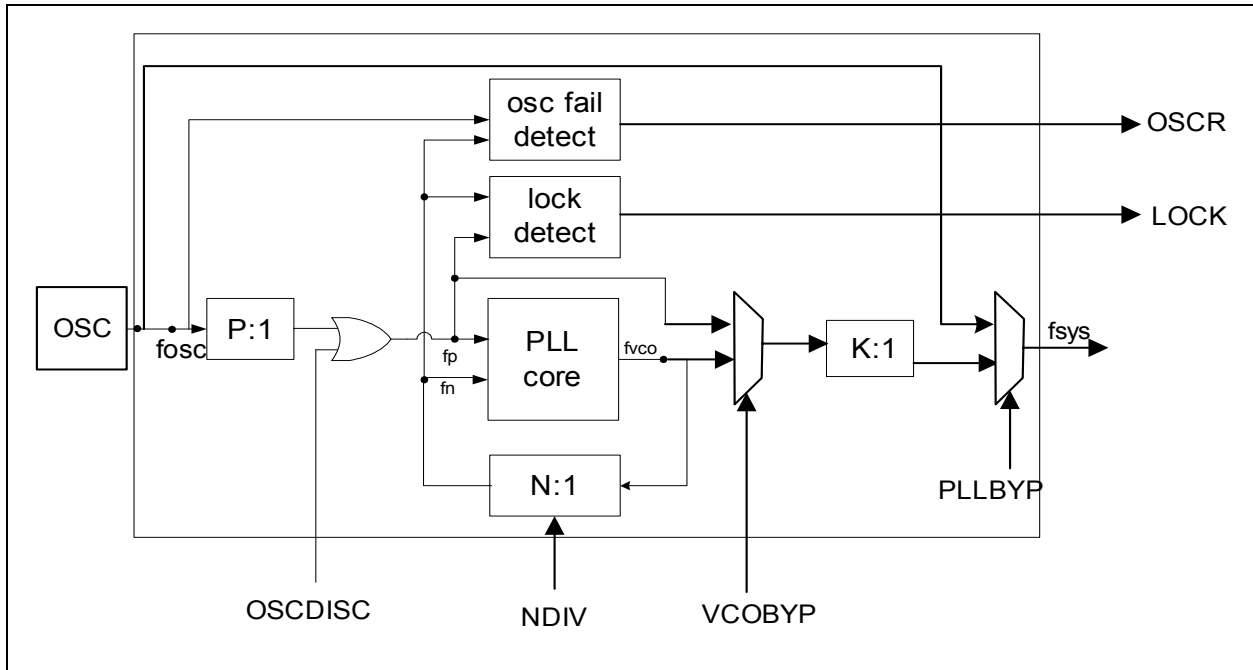


Figure 24 CGU Block Diagram

PLL Base Mode

When the oscillator is disconnected from the PLL, the system clock is derived from the VCO base (free running) frequency clock ([Table 25](#)) divided by the K factor.

$$f_{SYS} = f_{VCObase} \times \frac{1}{K}$$

(3.1)

Prescaler Mode (VCO Bypass Operation)

In VCO bypass operation, the system clock is derived from the oscillator clock, divided by the P and K factors.

$$f_{SYS} = f_{OSC} \times \frac{1}{P \times K}$$

(3.2)

Functional Description

For power saving purposes, the clocks may be disabled or slowed down according to [Table 26](#).

Table 26 **System frequency ($f_{\text{sys}} = 96 \text{ MHz}$)**

Power Saving Mode	Action
Idle	Clock to the CPU is disabled.
Slow-down	Clocks to the CPU and all the peripherals are divided by a common programmable factor defined by bit field CMCON.CLKREL.
Power-down	Oscillator and PLL are switched off.

3.9 Power Saving Modes

The power saving modes of the XC886/888 provide flexible power consumption through a combination of techniques, including:

- Stopping the CPU clock
- Stopping the clocks of individual system components
- Reducing clock speed of some peripheral components
- Power-down of the entire system with fast restart capability

After a reset, the active mode (normal operating mode) is selected by default (see [Figure 27](#)) and the system runs in the main system clock frequency. From active mode, different power saving modes can be selected by software. They are:

- Idle mode
- Slow-down mode
- Power-down mode

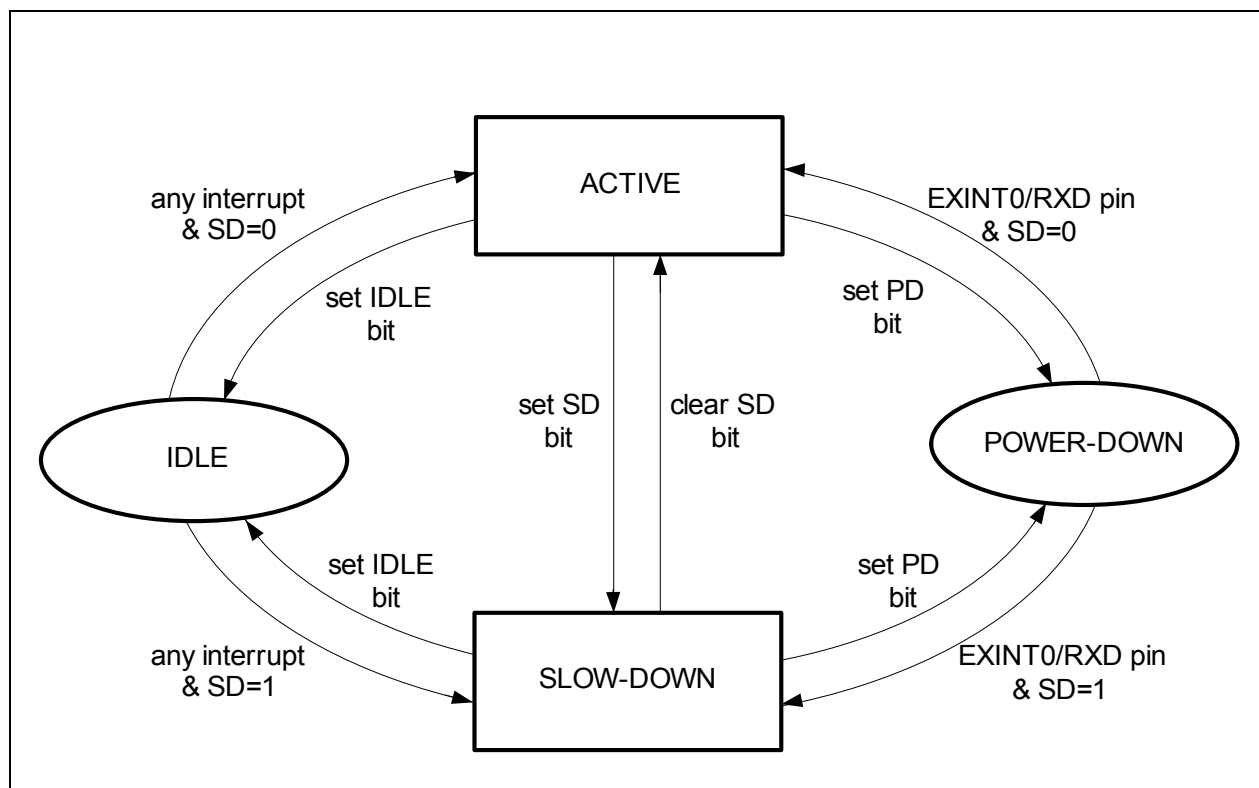


Figure 27 Transition between Power Saving Modes

3.16 High-Speed Synchronous Serial Interface

The High-Speed Synchronous Serial Interface (SSC) supports full-duplex and half-duplex synchronous communication. The serial clock signal can be generated by the SSC internally (master mode), using its own 16-bit baud-rate generator, or can be received from an external master (slave mode). Data width, shift direction, clock polarity and phase are programmable. This allows communication with SPI-compatible devices or devices using other synchronous serial interfaces.

Features

- Master and slave mode operation
 - Full-duplex or half-duplex operation
- Transmit and receive buffered
- Flexible data format
 - Programmable number of data bits: 2 to 8 bits
 - Programmable shift direction: LSB or MSB shift first
 - Programmable clock polarity: idle low or high state for the shift clock
 - Programmable clock/data phase: data shift with leading or trailing edge of the shift clock
- Variable baud rate
- Compatible with Serial Peripheral Interface (SPI)
- Interrupt generation
 - On a transmitter empty condition
 - On a receiver full condition
 - On an error condition (receive, phase, baud rate, transmit error)

Data is transmitted or received on lines TXD and RXD, which are normally connected to the pins MTSR (Master Transmit/Slave Receive) and MRST (Master Receive/Slave Transmit). The clock signal is output via line MS_CLK (Master Serial Shift Clock) or input via line SS_CLK (Slave Serial Shift Clock). Both lines are normally connected to the pin SCLK. Transmission and reception of data are double-buffered.

Figure 32 shows the block diagram of the SSC.

Functional Description

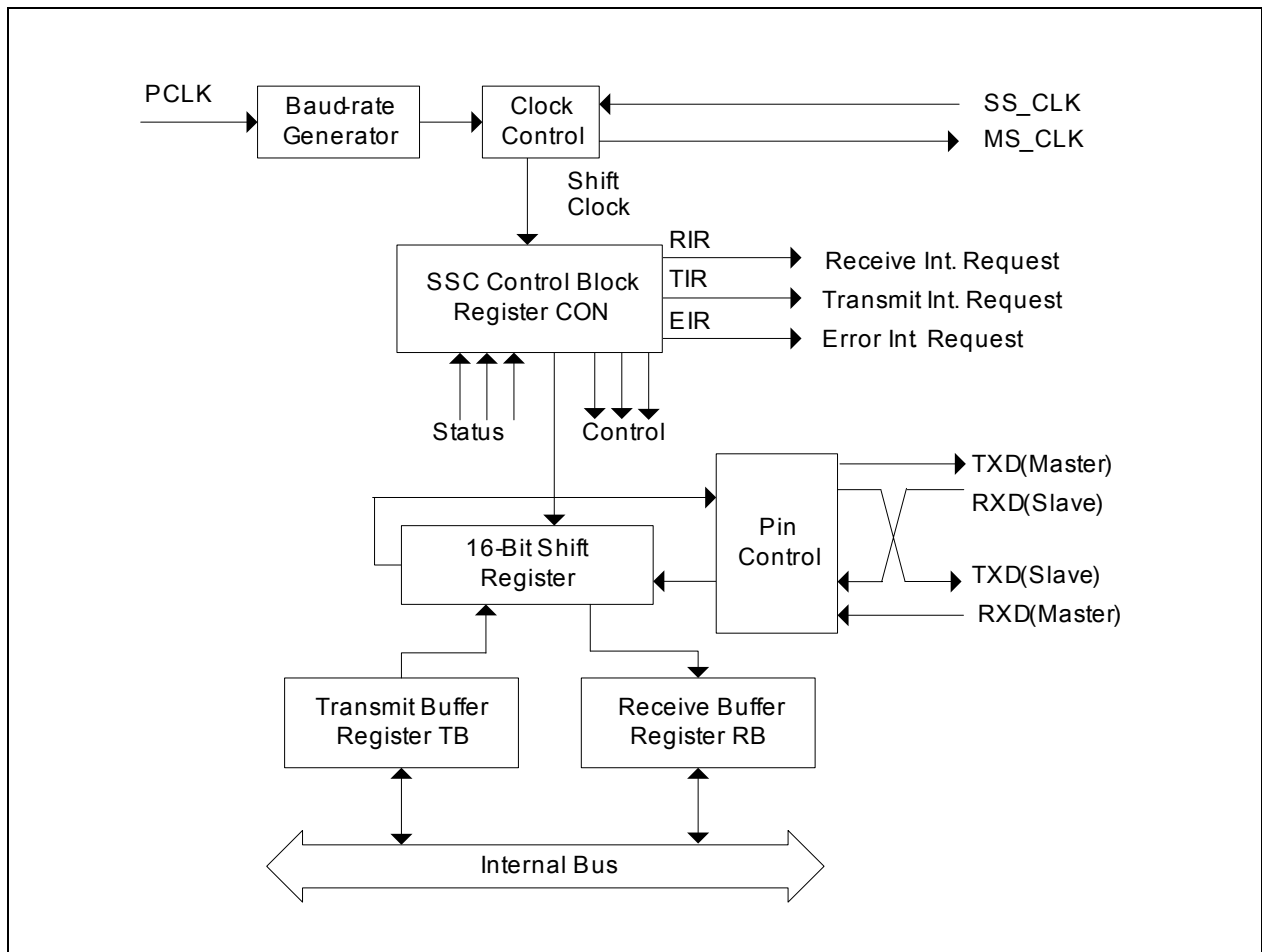


Figure 32 SSC Block Diagram

Functional Description
Table 36 Chip Identification Number (cont'd)

Product Variant	Chip Identification Number		
	AA-Step	AB-Step	AC-Step
XC886-6FFA 3V3	-	095D1562 _H	0B5D1562 _H
XC888-6FFA 3V3	-	095D1563 _H	0B5D1563 _H
XC886CLM-8FFA 5V	-	09900102 _H	0B900102 _H
XC888CLM-8FFA 5V	-	09900103 _H	0B900103 _H
XC886LM-8FFA 5V	-	09900122 _H	0B900122 _H
XC888LM-8FFA 5V	-	09900123 _H	0B900123 _H
XC886CLM-6FFA 5V	-	09951502 _H	0B951502 _H
XC888CLM-6FFA 5V	-	09951503 _H	0B951503 _H
XC886LM-6FFA 5V	-	09951522 _H	0B951522 _H
XC888LM-6FFA 5V	-	09951523 _H	0B951523 _H
XC886CM-8FFA 5V	-	09980102 _H	0B980102 _H
XC888CM-8FFA 5V	-	09980103 _H	0B980103 _H
XC886C-8FFA 5V	-	09980142 _H	0B980142 _H
XC888C-8FFA 5V	-	09980143 _H	0B980143 _H
XC886-8FFA 5V	-	09980162 _H	0B980162 _H
XC888-8FFA 5V	-	09980163 _H	0B980163 _H
XC886CM-6FFA 5V	-	099D1502 _H	0B9D1502 _H
XC888CM-6FFA 5V	-	099D1503 _H	0B9D1503 _H
XC886C-6FFA 5V	-	099D1542 _H	0B9D1542 _H
XC888C-6FFA 5V	-	099D1543 _H	0B9D1543 _H
XC886-6FFA 5V	-	099D1562 _H	0B9D1562 _H
XC888-6FFA 5V	-	099D1563 _H	0B9D1563 _H

ROM Devices

XC886CLM-8RFA 3V3	22400502 _H	-	-
XC888CLM-8RFA 3V3	22400503 _H	-	-
XC886LM-8RFA 3V3	22400522 _H	-	-
XC888LM-8RFA 3V3	22400523 _H	-	-
XC886CLM-6RFA 3V3	22411502 _H	-	-
XC888CLM-6RFA 3V3	22411503 _H	-	-

Electrical Parameters

4.1.2 Absolute Maximum Rating

Maximum ratings are the extreme limits to which the XC886/888 can be subjected to without permanent damage.

Table 4-1 Absolute Maximum Rating Parameters

Parameter	Symbol	Limit Values		Unit	Notes
		min.	max.		
Ambient temperature	T_A	-40	125	°C	under bias
Storage temperature	T_{ST}	-65	150	°C	¹⁾
Junction temperature	T_J	-40	150	°C	under bias ¹⁾
Voltage on power supply pin with respect to V_{SS}	V_{DDP}	-0.5	6	V	¹⁾
Voltage on any pin with respect to V_{SS}	V_{IN}	-0.5	$V_{DDP} + 0.5$ or max. 6	V	whichever is lower ¹⁾
Input current on any pin during overload condition	I_{IN}	-10	10	mA	¹⁾
Absolute sum of all input currents during overload condition	$\Sigma I_{IN} $	—	50	mA	¹⁾

1) Not subjected to production test, verified by design/characterization.

Note: Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. During absolute maximum rating overload conditions ($V_{IN} > V_{DDP}$ or $V_{IN} < V_{SS}$) the voltage on V_{DDP} pin with respect to ground (V_{SS}) must not exceed the values defined by the absolute maximum ratings.

Electrical Parameters

4.2.4 Power Supply Current

Table 41, Table 42, Table 43 and Table 44 provide the characteristics of the power supply current in the XC886/888.

**Table 41 Power Supply Current Parameters (Operating Conditions apply;
 $V_{DDP} = 5V$ range)**

Parameter	Symbol	Limit Values		Unit	Test Condition
		typ. ¹⁾	max. ²⁾		
V_{DDP} = 5V Range					
Active Mode	I_{DDP}	27.2	32.8	mA	Flash Device ³⁾
		24.3	29.8	mA	ROM Device ³⁾
Idle Mode	I_{DDP}	21.1	25.3	mA	Flash Device ⁴⁾
		18.2	21.6	mA	ROM Device ⁴⁾
Active Mode with slow-down enabled	I_{DDP}	14.1	17.0	mA	Flash Device ⁵⁾
		11.9	14.3	mA	ROM Device ⁵⁾
Idle Mode with slow-down enabled	I_{DDP}	11.7	15.0	mA	Flash Device ⁶⁾
		9.7	11.9	mA	ROM Device ⁶⁾

- 1) The typical I_{DDP} values are periodically measured at $T_A = +25^\circ\text{C}$ and $V_{DDP} = 5.0\text{ V}$.
- 2) The maximum I_{DDP} values are measured under worst case conditions ($T_A = +125^\circ\text{C}$ and $V_{DDP} = 5.5\text{ V}$).
- 3) I_{DDP} (active mode) is measured with: CPU clock and input clock to all peripherals running at 24 MHz (set by on-chip oscillator of 9.6 MHz and NDIV in PLL_CON to 1001_B), $\overline{\text{RESET}} = V_{DDP}$, no load on ports.
- 4) I_{DDP} (idle mode) is measured with: CPU clock disabled, watchdog timer disabled, input clock to all peripherals enabled and running at 24 MHz, $\overline{\text{RESET}} = V_{DDP}$, no load on ports.
- 5) I_{DDP} (active mode with slow-down mode) is measured with: CPU clock and input clock to all peripherals running at 8 MHz by setting CLKREL in CMCON to 0110_B, $\overline{\text{RESET}} = V_{DDP}$, no load on ports.
- 6) I_{DDP} (idle mode with slow-down mode) is measured with: CPU clock disabled, watchdog timer disabled, input clock to all peripherals enabled and running at 8 MHz by setting CLKREL in CMCON to 0110_B, $\overline{\text{RESET}} = V_{DDP}$, no load on ports.

Package and Quality Declaration

5.2 Package Outline

Figure 48 shows the package outlines of the XC886.

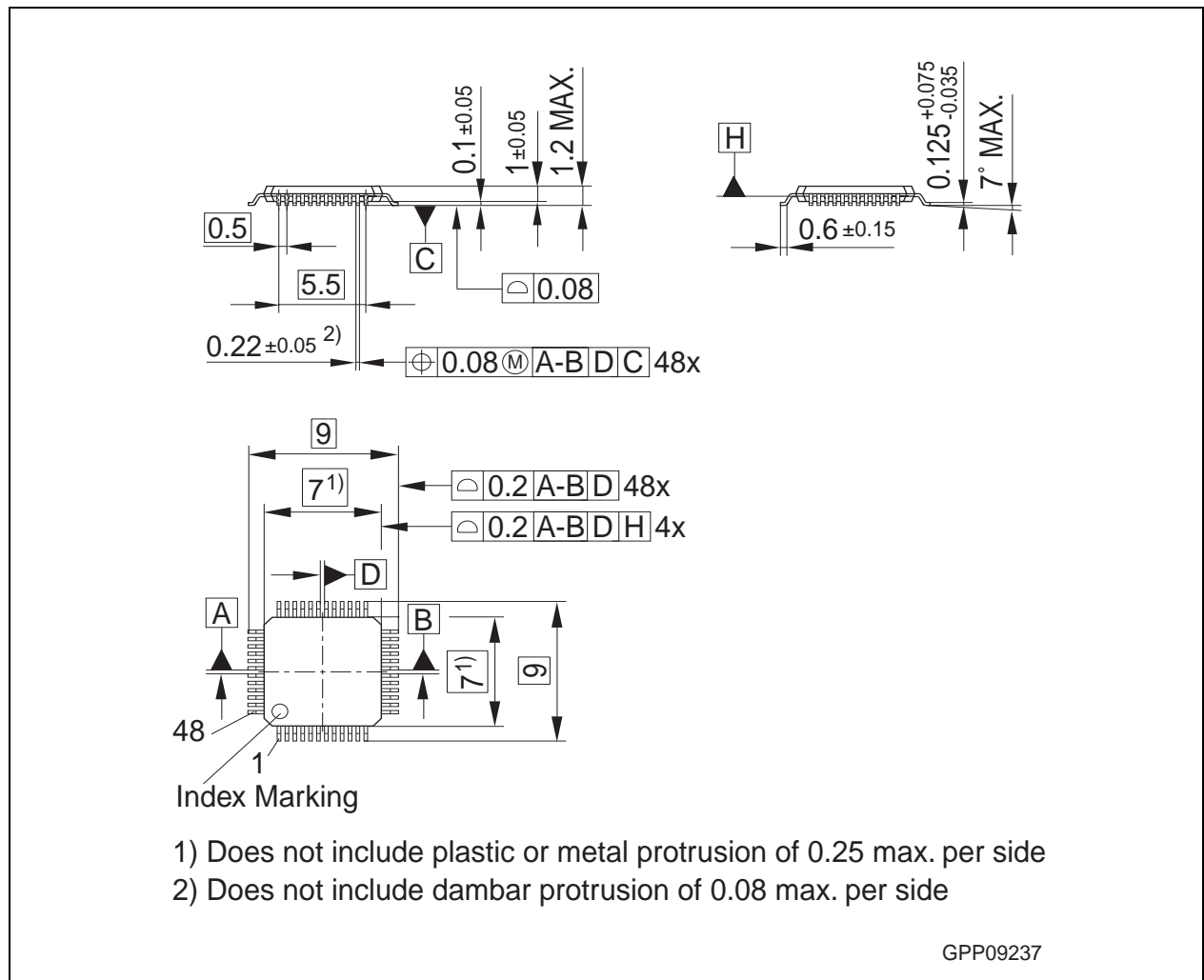


Figure 48 PG-TQFP-48 Package Outline