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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Obsolete
Number of LABs/CLBs	200
Number of Logic Elements/Cells	-
Total RAM Bits	-
Number of I/O	70
Number of Gates	1500
Voltage - Supply	4.5V ~ 5.5V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 85°C (TA)
Package / Case	84-LCC (J-Lead)
Supplier Device Package	84-PLCC (29.31x29.31)
Purchase URL	https://www.e-xfl.com/product-detail/microsemi/a1415a-1plg84i

Logic Modules

ACT 3 logic modules are enhanced versions of the 1200XL family logic modules. As in the 1200XL family, there are two types of modules: C-modules and S-modules (Figure 2-2 and Figure 2-3). The C-module is functionally equivalent to the 1200XL C-module and implements high fanin combinatorial macros, such as 5-input AND, 5-input OR, and so on. It is available for use as the CM8 hard macro. The S-module is designed to implement high-speed sequential functions within a single module.

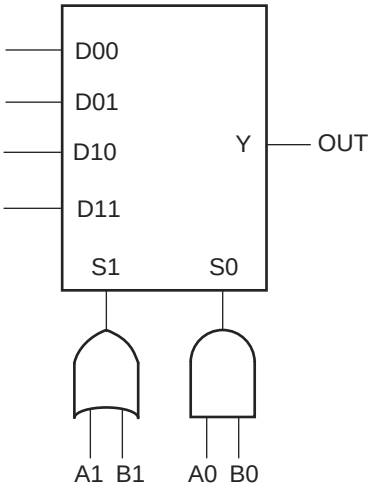


Figure 2-2 • **C-Module Diagram**

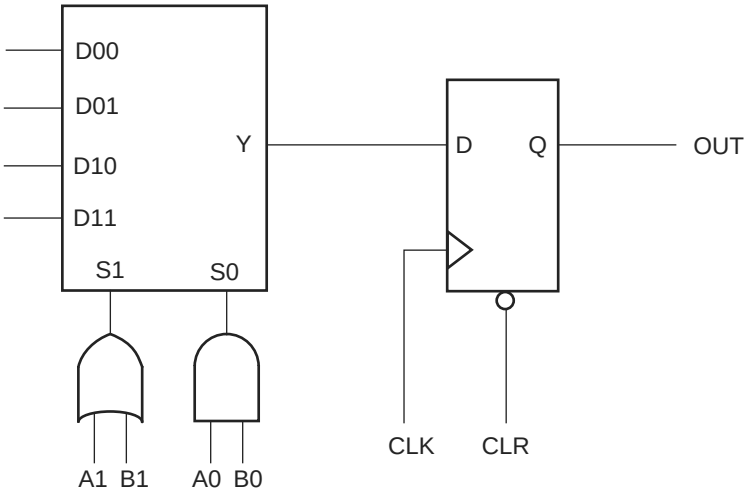


Figure 2-3 • **S-Module Diagram**

S-modules consist of a full C-module driving a flip-flop, which allows an additional level of logic to be implemented without additional propagation delay. It is available for use as the DFM8A/B and DLM8A/B hard macros. C-modules and S-modules are arranged in pairs called module-pairs. Module-pairs are arranged in alternating patterns and make up the bulk of the array. This arrangement allows the placement software to support two-module macros of four types (CC, CS, SC, and SS). The C-module implements the following function:

Y = !S1 * !S0 * D00 + !S1 * S0 * D01 + S1 * !S0 * D10 + S1 * S0 * D11

EQ 1

where: S0 = A0 * B0 and S1 = A1 + B1

Antifuse Connections

An antifuse is a “normally open” structure as opposed to the normally closed fuse structure used in PROMs or PALs. The use of antifuses to implement a programmable logic device results in highly testable structures as well as an efficient programming architecture. The structure is highly testable because there are no preexisting connections; temporary connections can be made using pass transistors. These temporary connections can isolate individual antifuses to be programmed as well as isolate individual circuit structures to be tested. This can be done both before and after programming. For example, all metal tracks can be tested for continuity and shorts between adjacent tracks, and the functionality of all logic modules can be verified.

Four types of antifuse connections are used in the routing structure of the ACT 3 array. (The physical structure of the antifuse is identical in each case; only the usage differs.)

Table 2-1 shows four types of antifuses.

Table 2-1 • **Antifuse Types**

Type	Description
XF	Horizontal-to-vertical connection
HF	Horizontal-to-horizontal connection
VF	Vertical-to-vertical connection
FF	"Fast" vertical connection

Examples of all four types of connections are shown in Figure 2-7 on page 2-6 and Figure 2-8 on page 2-6.

Module Interface

Connections to Logic and I/O modules are made through vertical segments that connect to the module inputs and outputs. These vertical segments lie on vertical tracks that span the entire height of the array.

Module Input Connections

The tracks dedicated to module inputs are segmented by pass transistors in each module row. During normal user operation, the pass transistors are inactive, which isolates the inputs of a module from the inputs of the module directly above or below it. During certain test modes, the pass transistors are active to verify the continuity of the metal tracks. Vertical input segments span only the channel above or the channel below. The logic modules are arranged such that half of the inputs are connected to the channel above and half of the inputs to segments in the channel below, as shown in Figure 2-9.

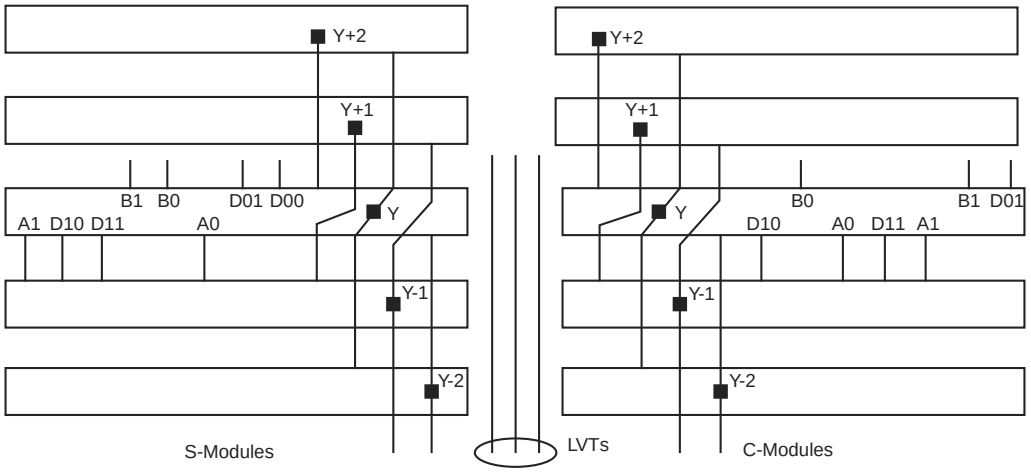


Figure 2-9 • **Logic Module Routing Interface**

Module Output Connections

Module outputs have dedicated output segments. Output segments extend vertically two channels above and two channels below, except at the top or bottom of the array. Output segments twist, as shown in Figure 10, so that only four vertical tracks are required.

LVT Connections

Outputs may also connect to nondedicated segments called Long Vertical Tracks (LVTs). Each module pair in the array shares four LVTs that span the length of the column. Any module in the column pair can connect to one of the LVTs in the column using an FF connection. The FF connection uses antifuses connected directly to the driver stage of the module output, bypassing the isolation transistor. FF antifuses are programmed at a higher current level than HF, VF, or XF antifuses to produce a lower resistance value.

Antifuse Connections

In general every intersection of a vertical segment and a horizontal segment contains an unprogrammed antifuse (XF-type). One exception is in the case of the clock networks.

Clock Connections

To minimize loading on the clock networks, a subset of inputs has antifuses on the clock tracks. Only a few of the C-module and S-module inputs can be connected to the clock networks. To further reduce loading on the clock network, only a subset of the horizontal routing tracks can connect to the clock inputs of the S-module.

Programming and Test Circuits

The array of logic and I/O modules is surrounded by test and programming circuits controlled by the temporary special I/O pins MODE, SDI, and DCLK. The function of these pins is similar to all ACT family devices. The ACT 3 family also includes support for two Actionprobe® circuits, allowing complete observability of any logic or I/O module in the array using the temporary special I/O pins, PRA and PRB.

3.3 V Operating Conditions

Table 2-5 • **Absolute Maximum Ratings[1], Free Air Temperature Range**

Symbol	Parameter	Limits	Units
VCC	DC supply voltage	–0.5 to +7.0	V
VI	Input voltage	–0.5 to VCC + 0.5	V
VO	Output voltage	–0.5 to VCC + 0.5	V
IIO	I/O source sink current[2]	±20	mA
T_{STG}	Storage temperature	–65 to +150	°C

Notes:

1. *Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. Exposure to absolute maximum rated conditions for extended periods may affect device reliability. Device should not be operated outside the recommended operating conditions.*
2. *Device inputs are normally high impedance and draw extremely low current. However, when input voltage is greater than VCC + 0.5 V for less than GND –0.5 V, the internal protection diodes will forward bias and can draw excessive current.*

Table 2-6 • **Recommended Operating Conditions**

Parameter	Commercial	Units
Temperature range*	0 to +70	°C
Power supply tolerance	3.0 to 3.6	V

*Note: *Ambient temperature (T_A) is used for commercial.*

Table 2-7 • **Electrical Specifications**

Parameter		Commercial		Units
		Min.	Max.	
VOH[1]	IOH = –4 mA	2.15	–	V
	IOH = –3.2 mA	2.4		V
VOL[1]	IOL = 6 mA		0.4	V
VIL		–0.3	0.8	V
VIH		2.0	VCC + 0.3	V
Input transition time t_R, t_F[2]	VI = VCC or GND	–10	+10	µA
C_{IO} I/O Capacitance[2,3]			10	pF
Standby current, ICC[4] (typical = 0.3 mA)			0.75	mA
Leakage current[5]		–10	10	µA

1. *Only one output tested at a time. VCC = minimum.*
2. *Not tested; for information only.*
3. *Includes worst-case 84-pin PLCC package capacitance. VOUT = 0 V, f - 1 MHz.*
4. *Typical standby current = 0.3 mA. All outputs unloaded. All inputs = VCC or GND.*
5. *VO, VIN = VCC or GND*

Equivalent capacitance is calculated by measuring ICC active at a specified frequency and voltage for each circuit component of interest. Measurements have been made over a range of frequencies at a fixed value of VCC. Equivalent capacitance is frequency independent so that the results may be used over a wide range of operating conditions. Equivalent capacitance values are shown in Figure 2-10.

***Table 2-10* • CEQ Values for Microsemi FPGAs**

Item	CEQ Value
Modules (C_{EQM})	6.7
Input Buffers (C_{EQI})	7.2
Output Buffers (C_{EQO})	10.4
Routed Array Clock Buffer Loads (C_{EQCR})	1.6
Dedicated Clock Buffer Loads (C_{EQCD})	0.7
I/O Clock Buffer Loads ($C_{EQCI)}$	0.9

To calculate the active power dissipated from the complete design, the switching frequency of each part of the logic must be known. EQ 5 shows a piece-wise linear summation over all components.

$$\text{Power} = VCC^2 * [(m * C_{EQM} * f_m)_{modules} + (n * C_{EQI} * f_n)_{inputs} + (p * (C_{EQO} + C_L) * fp)_{outputs} + 0.5 * (q1 * C_{EQCR} * f_{q1})_{routed\_Clk1} + (r1 * fq1)_{routed\_Clk1} + 0.5 * (q2 * C_{EQCR} * fq2)_{routed\_Clk2} + (r_2 * f_{q2})_{routed\_Clk2} + 0.5 * (s_1 * C_{EQCD} * f_{s1})_{dedicated\_Clk} + (s_2 * C_{EQCI} * f_{s2})_{IO\_Clk}]$$

EQ 5

Where:

m = Number of logic modules switching at f_m
n = Number of input buffers switching at f_n
p = Number of output buffers switching at f_p
q1 = Number of clock loads on the first routed array clock
q2 = Number of clock loads on the second routed array clock
r_1 = Fixed capacitance due to first routed array clock
r_2 = Fixed capacitance due to second routed array clock
s_1 = Fixed number of clock loads on the dedicated array clock
s_2 = Fixed number of clock loads on the dedicated I/O clock
C_{EQM} = Equivalent capacitance of logic modules in pF
C_{EQI} = Equivalent capacitance of input buffers in pF
C_{EQO} = Equivalent capacitance of output buffers in pF
C_{EQCR} = Equivalent capacitance of routed array clock in pF
C_{EQCD} = Equivalent capacitance of dedicated array clock in pF
C_{EQCI} = Equivalent capacitance of dedicated I/O clock in pF
C_L = Output lead capacitance in pF
f_m = Average logic module switching rate in MHz
f_n = Average input buffer switching rate in MHz
f_p = Average output buffer switching rate in MHz
f_{q1} = Average first routed array clock rate in MHz
f_{q2} = Average second routed array clock rate in MHz
f_{s1} = Average dedicated array clock rate in MHz
f_{s2} = Average dedicated I/O clock rate in MHz

***Table 2-11* • Fixed Capacitance Values for Microsemi FPGAs**

Device Type	r1, routed_Clk1	r2, routed_Clk2
A1415A	60	60
A14V15A	57	57
A1425A	75	75
A14V25A	72	72
A1440A	105	105
A14V40A	100	100
A1440B	105	105
A1460A	165	165
A14V60A	157	157
A1460B	165	165
A14100A	195	195
A14V100A	185	185
A14100B	195	195

***Table 2-12* • Fixed Clock Loads (s1/s2)**

Device Type	s1, Clock Loads on Dedicated Array Clock	s2, Clock Loads on Dedicated I/O Clock
A1415A	104	80
A14V15A	104	80
A1425A	160	100
A14V25A	160	100
A1440A	288	140
A14V40A	288	140
A1440B	288	140
A1460A	432	168
A14V60A	432	168
A1460B	432	168
A14100A	697	228
A14V100A	697	228
A14100B	697	228

Determining Average Switching Frequency

To determine the switching frequency for a design, you must have a detailed understanding of the data input values to the circuit. The following guidelines are meant to represent worst-case scenarios so that they can be generally used to predict the upper limits of power dissipation. These guidelines are as follows:

***Table 2-13* • Guidelines for Predicting Power Dissipation**

Data	Value
Logic Modules (m)	80% of modules
Inputs switching (n)	# inputs/4
Outputs switching (p)	# output/4
First routed array clock loads (q1)	40% of sequential modules
Second routed array clock loads (q2)	40% of sequential modules
Load capacitance (CL)	35 pF
Average logic module switching rate (fm)	F/10
Average input switching rate (fn)	F/5
Average output switching rate (fp)	F/10
Average first routed array clock rate (fq1)	F/2
Average second routed array clock rate (fq2)	F/2
Average dedicated array clock rate (fs1)	F
Average dedicated I/O clock rate (f_{s2})	F

A1415A, A14V15A Timing Characteristics

Table 2-18 • A1415A, A14V15A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C[1]

Logic Module Propagation Delays[2]		–3 Speed[3]		–2 Speed[3]		–1 Speed		Std. Speed		3.3 V Speed[1]		Units
Parameter/Description		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
t_{PD}	Internal Array Module		2.0		2.3		2.6		3.0		3.9	ns
t_{CO}	Sequential Clock to Q		2.0		2.3		2.6		3.0		3.9	ns
t_{CLR}	Asynchronous Clear to Q		2.0		2.3		2.6		3.0		3.9	ns
Predicted Routing Delays[4]												
t_{RD1}	FO = 1 Routing Delay		0.9		1.0		1.1		1.3		1.7	ns
t_{RD2}	FO = 2 Routing Delay		1.2		1.4		1.6		1.8		2.4	ns
t_{RD3}	FO = 3 Routing Delay		1.4		1.6		1.8		2.1		2.8	ns
t_{RD4}	FO = 4 Routing Delay		1.7		1.9		2.2		2.5		3.3	ns
t_{RD8}	FO = 8 Routing Delay		2.8		3.2		3.6		4.2		5.5	ns
Logic Module Sequential Timing												
t_{SUD}	Flip-Flop Data Input Setup	0.5		0.6		0.7		0.8		0.8		ns
t_{HD}	Flip-Flop Data Input Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{SUD}	Latch Data Input Setup	0.5		0.6		0.7		0.8		0.8		ns
t_{HD}	Latch Data Input Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{WASYN}	Asynchronous Pulse Width	1.9		2.4		3.2		3.8		4.8		ns
t_{WCLKA}	Flip-Flop Clock Pulse Width	1.9		2.4		3.2		3.8		4.8		ns
t_A	Flip-Flop Clock Input Period	4.0		5.0		6.8		8.0		10.0		ns
f_{MAX}	Flip-Flop Clock Frequency		250		200		150		125		100	MHz

Notes:

1. *VCC = 3.0 V for 3.3 V specifications.*
2. *For dual-module macros, use $t_{PD} + t_{RD1} + t_{PDn} + t_{CO} + t_{RD1} + t_{PDn}$ or $t_{PD1} + t_{RD1} + t_{SUD}$, whichever is appropriate.*
3. *The –2 and –3 speed grades have been discontinued. Please refer to the Product Discontinuation Notices (PDNs) listed below:*

   PDN March 2001
   PDN 0104
   PDN 0203
   PDN 0604
   PDN 1004
4. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.*

A1425A, A14V25A Timing Characteristics (continued)

***Table 2-23* • A1425A, A14V25A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C**

I/O Module Input Propagation Delays		–3 Speed[1]		–2 Speed[1]		–1 Speed		Std. Speed		3.3 V Speed[1]		Units
Parameter/Description		**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	
t_{INY}	Input Data Pad to Y		2.8		3.2		3.6		4.2		5.5	ns
t_{ICKY}	Input Reg IOCLK Pad to Y		4.7		5.3		6.0		7.0		9.2	ns
t_{OCKY}	Output Reg IOCLK Pad to Y		4.7		5.3		6.0		7.0		9.2	ns
t_{ICLRY}	Input Asynchronous Clear to Y		4.7		5.3		6.0		7.0		9.2	ns
t_{OCLRY}	Output Asynchronous Clear to Y		4.7		5.3		6.0		7.0		9.2	ns
Predicted Input Routing Delays[2]												
t_{RD1}	FO = 1 Routing Delay		0.9		1.0		1.1		1.3		1.7	ns
t_{RD2}	FO = 2 Routing Delay		1.2		1.4		1.6		1.8		2.4	ns
t_{RD3}	FO = 3 Routing Delay		1.4		1.6		1.8		2.1		2.8	ns
t_{RD4}	FO = 4 Routing Delay		1.7		1.9		2.2		2.5		3.3	ns
t_{RD8}	FO = 8 Routing Delay		2.8		3.2		3.6		4.2		5.5	ns
I/O Module Sequential Timing (wrt IOCLK pad)												
t_{INH}	Input F-F Data Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{INSU}	Input F-F Data Setup	1.8		2.0		2.3		2.7		3.0		ns
t_{IDEH}	Input Data Enable Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{IDESU}	Input Data Enable Setup	5.8		6.5		7.5		8.6		8.6		ns
t_{OUTH}	Output F-F Data hold	0.7		0.8		0.9		1.0		1.0		ns
t_{OUTSU}	Output F-F Data Setup	0.7		0.8		0.9		1.0		1.0		ns
t_{ODEH}	Output Data Enable Hold	0.3		0.4		0.4		0.5		0.5		ns
f_{ODESU}	Output Data Enable Setup	1.3		1.5		1.7		2.0		2.0		ns

*Notes: **

1. *The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.*
2. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.*

A1425A, A14V25A Timing Characteristics (continued)

Table 2-24 • A1425A, A14V25A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

I/O Module – TTL Output Timing[1]		–3 Speed[2]		–2 Speed[2]		–1 Speed		Std. Speed		3.3 V Speed[1]		Units
Parameter/Description		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
t_{DHS}	Data to Pad, High Slew		5.0		5.6		6.4		7.5		9.8	ns
t_{DLS}	Data to Pad, Low Slew		8.0		9.0		10.2		12.0		15.6	ns
t_{ENZHS}	Enable to Pad, Z to H/L, High Slew		4.0		4.5		5.1		6.0		7.8	ns
t_{ENZLS}	Enable to Pad, Z to H/L, Low Slew		7.4		8.3		9.4		11.0		14.3	ns
t_{ENHSZ}	Enable to Pad, H/L to Z, High Slew		6.5		7.5		8.5		10.0		13.0	ns
t_{ENLSZ}	Enable to Pad, H/L to Z, Low Slew		6.5		7.5		8.5		10.0		13.0	ns
t_{CKHS}	IOCLK Pad to Pad H/L, High Slew		7.5		7.5		9.0		10.0		13.0	ns
t_{CKLS}	IOCLK Pad to Pad H/L, Low Slew		11.3		11.3		13.5		15.0		19.5	ns
d_{TLHHS}	Delta Low to High, High Slew		0.02		0.02		0.03		0.03		0.04	ns/pF
d_{TLHLS}	Delta Low to High, Low Slew		0.05		0.05		0.06		0.07		0.09	ns/pF
d_{THLHS}	Delta High to Low, High Slew		0.04		0.04		0.04		0.05		0.07	ns/pF
d_{THLLS}	Delta High to Low, Low Slew		0.05		0.05		0.06		0.07		0.09	ns/pF
I/O Module – CMOS Output Timing[1]												
t_{DHS}	Data to Pad, High Slew		6.2		7.0		7.9		9.3		12.1	ns
t_{DLS}	Data to Pad, Low Slew		11.7		13.1		14.9		17.5		22.8	ns
t_{ENZHS}	Enable to Pad, Z to H/L, High Slew		5.2		5.9		6.6		7.8		10.1	ns
t_{ENZLS}	Enable to Pad, Z to H/L, Low Slew		8.9		10.0		11.3		13.3		17.3	ns
t_{ENHSZ}	Enable to Pad, H/L to Z, High Slew		6.7		7.5		8.5		10.0		13.0	ns
t_{ENLSZ}	Enable to Pad, H/L to Z, Low Slew		6.7		7.5		9.0		10.0		13.0	ns
t_{CKHS}	IOCLK Pad to Pad H/L, High Slew		8.9		8.9		10.7		11.8		15.3	ns
t_{CKLS}	IOCLK Pad to Pad H/L, Low Slew		13.0		13.0		15.6		17.3		22.5	ns
d_{TLHHS}	Delta Low to High, High Slew		0.04		0.04		0.05		0.06		0.08	ns/pF
d_{TLHLS}	Delta Low to High, Low Slew		0.07		0.08		0.09		0.11		0.14	ns/pF
d_{THLHS}	Delta High to Low, High Slew		0.03		0.03		0.03		0.04		0.05	ns/pF
d_{THLLS}	Delta High to Low, Low Slew		0.04		0.04		0.04		0.05		0.07	ns/pF

*Notes: **

1. *Delays based on 35 pF loading.*
2. *The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.*

A1425A, A14V25A Timing Characteristics (continued)

***Table 2-25* • A1425A, A14V25A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C**

Dedicated (hardwired) I/O Clock Network		–3 Speed[1]		–2 Speed[1]		–1 Speed		Std. Speed		3.3 V Speed[1]		Units
Parameter/Description		**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	**Min.**	**Max.**	
t_{IOCKH}	Input Low to High (pad to I/O module input)		2.0		2.3		2.6		3.0		3.5	ns
t_{IOPWH}	Minimum Pulse Width High	1.9		2.4		3.3		3.8		4.8		ns
t_{IPOWL}	Minimum Pulse Width Low	1.9		2.4		3.3		3.8		4.8		ns
t_{IOSAPW}	Minimum Asynchronous Pulse Width	1.9		2.4		3.3		3.8		4.8		ns
t_{IOCKSW}	Maximum Skew		0.4		0.4		0.4		0.4		0.4	ns
t_{IOP}	Minimum Period	4.0		5.0		6.8		8.0		10.0		ns
f_{IOMAX}	Maximum Frequency		250		200		150		125		100	MHz
Dedicated (hardwired) Array Clock												
t_{HCKH}	Input Low to High (pad to S-module input)		3.0		3.4		3.9		4.5		5.5	ns
t_{HCKL}	Input High to Low (pad to S-module input)		3.0		3.4		3.9		4.5		5.5	ns
t_{HPWH}	Minimum Pulse Width High	1.9		2.4		3.3		3.8		4.8		ns
t_{HPWL}	Minimum Pulse Width Low	1.9		2.4		3.3		3.8		4.8		ns
t_{HCKSW}	Delta High to Low, Low Slew		0.3		0.3		0.3		0.3		0.3	ns
t_{HP}	Minimum Period	4.0		5.0		6.8		8.0		10.0		ns
f_{HMAX}	Maximum Frequency		250		200		150		125		100	MHz
Routed Array Clock Networks												
t_{RCKH}	Input Low to High (FO = 64)		3.7		4.1		4.7		5.5		9.0	ns
t_{RCKL}	Input High to Low (FO = 64)		4.0		4.5		5.1		6.0		9.0	ns
t_{RPWH}	Min. Pulse Width High (FO = 64)	3.3		3.8		4.2		4.9		6.5		ns
t_{RPWL}	Min. Pulse Width Low (FO = 64)	3.3		3.8		4.2		4.9		6.5		ns
t_{RCKSW}	Maximum Skew (FO = 128)		0.7		0.8		0.9		1.0		1.0	ns
t_{RP}	Minimum Period (FO = 64)	6.8		8.0		8.7		10.0		13.4		ns
f_{RMAX}	Maximum Frequency (FO = 64)		150		125		115		100		75	MHz
Clock-to-Clock Skews												
$t_{IOHCKSW}$	I/O Clock to H-Clock Skew	0.0	1.7	0.0	1.8	0.0	2.0	0.0	2.2	0.0	3.0	ns
$t_{IORCKSW}$	I/O Clock to R-Clock Skew (FO = 64) (FO = 80)	0.0 0.0	1.0 3.0	0.0 0.0	1.0 3.0	0.0 0.0	1.0 3.0	0.0 0.0	1.0 3.0	0.0 0.0	3.0 3.0	ns
t_{HRCKSW}	H-Clock to R-Clock Skew (FO = 64) (FO = 80)	0.0 0.0	1.0 3.0	0.0 0.0	1.0 3.0	0.0 0.0	1.0 3.0	0.0 0.0	1.0 3.0	0.0 0.0	1.0 3.0	ns

Notes:

1. *The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.*
2. *Delays based on 35 pF loading.*

A1440A, A14V40A Timing Characteristics

Table 2-26 • A1440A, A14V40A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C[1]

Logic Module Propagation Delays[2]		–3 Speed [3]		–2 Speed[3]		–1 Speed		Std. Speed		3.3 V Speed[1]		Units
Parameter/Description		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
t_{PD}	Internal Array Module		2.0		2.3		2.6		3.0		3.9	ns
t_{CO}	Sequential Clock to Q		2.0		2.3		2.6		3.0		3.9	ns
t_{CLR}	Asynchronous Clear to Q		2.0		2.3		2.6		3.0		3.9	ns
Predicted Routing Delays[4]												
t_{RD1}	FO = 1 Routing Delay		0.9		1.0		1.1		1.3		1.7	ns
t_{RD2}	FO = 2 Routing Delay		1.2		1.4		1.6		1.8		2.4	ns
t_{RD3}	FO = 3 Routing Delay		1.4		1.6		1.8		2.1		2.8	ns
t_{RD4}	FO = 4 Routing Delay		1.7		1.9		2.2		2.5		3.3	ns
t_{RD8}	FO = 8 Routing Delay		2.8		3.2		3.6		4.2		5.5	ns
Logic Module Sequential Timing												
t_{SUD}	Flip-Flop Data Input Setup	0.5		0.6		0.7		0.8		0.8		ns
t_{HD}	Flip-Flop Data Input Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{SUD}	Latch Data Input Setup	0.5		0.6		0.7		0.8		0.8		ns
t_{HD}	Latch Data Input Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{WASYN}	Asynchronous Pulse Width	1.9		2.4		3.2		3.8		4.8		ns
t_{WCLKA}	Flip-Flop Clock Pulse Width	1.9		2.4		3.2		3.8		4.8		ns
t_A	Flip-Flop Clock Input Period	4.0		5.0		6.8		8.0		10.0		ns
f_{MAX}	Flip-Flop Clock Frequency		250		200		150		125		100	MHz

Notes:

1. *VCC = 3.0 V for 3.3 V specifications.*
2. *For dual-module macros, use $t_{PD} + t_{RD1} + t_{PDn} + t_{CO} + t_{RD1} + t_{PDn}$ or $t_{PD1} + t_{RD1} + t_{SUD}$, whichever is appropriate.*
3. *The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.*
4. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.*

A1440A, A14V40A Timing Characteristics (continued)

Table 2-27 • A1440A, A14V40A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

I/O Module Input Propagation Delays		–3 Speed[1]		–2 Speed[1]		–1 Speed		Std. Speed		3.3 V Speed[1]		Units
Parameter/Description		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
t_{INY}	Input Data Pad to Y		2.8		3.2		3.6		4.2		5.5	ns
t_{ICKY}	Input Reg IOCLK Pad to Y		4.7		5.3		6.0		7.0		9.2	ns
t_{OCKY}	Output Reg IOCLK Pad to Y		4.7		5.3		6.0		7.0		9.2	ns
t_{ICLRY}	Input Asynchronous Clear to Y		4.7		5.3		6.0		7.0		9.2	ns
t_{OCLRY}	Output Asynchronous Clear to Y		4.7		5.3		6.0		7.0		9.2	ns
Predicted Input Routing Delays[2]												
t_{RD1}	FO = 1 Routing Delay		0.9		1.0		1.1		1.3		1.7	ns
t_{RD2}	FO = 2 Routing Delay		1.2		1.4		1.6		1.8		2.4	ns
t_{RD3}	FO = 3 Routing Delay		1.4		1.6		1.8		2.1		2.8	ns
t_{RD4}	FO = 4 Routing Delay		1.7		1.9		2.2		2.5		3.3	ns
t_{RD8}	FO = 8 Routing Delay		2.8		3.2		3.6		4.2		5.5	ns
I/O Module Sequential Timing (wrt IOCLK pad)												
t_{INH}	Input F-F Data Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{INSU}	Input F-F Data Setup	1.8		1.7		2.0		2.3		2.3		ns
t_{IDEH}	Input Data Enable Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{IDESU}	Input Data Enable Setup	5.8		6.5		7.5		8.6		8.6		ns
t_{OUTH}	Output F-F Data hold	0.7		0.8		0.9		1.0		1.0		ns
t_{OUTSU}	Output F-F Data Setup	0.7		0.8		0.9		1.0		1.0		ns
t_{ODEH}	Output Data Enable Hold	0.3		0.4		0.4		0.5		0.5		ns
f_{ODESU}	Output Data Enable Setup	1.3		1.5		1.7		2.0		2.0		ns

Notes:

1. *The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.*
2. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.*

A1460A, A14V60A Timing Characteristics

Table 2-30 • A1460A, A14V60A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C[1]

Logic Module Propagation Delays[2]		–3 Speed[3]		–2 Speed [3]		–1 Speed		Std. Speed		3.3 V Speed[1]		Units
Parameter/Description		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
t_{PD}	Internal Array Module		2.0		2.3		2.6		3.0		3.9	ns
t_{CO}	Sequential Clock to Q		2.0		2.3		2.6		3.0		3.9	ns
t_{CLR}	Asynchronous Clear to Q		2.0		2.3		2.6		3.0		3.9	ns
Predicted Routing Delays[4]												
t_{RD1}	FO = 1 Routing Delay		0.9		1.0		1.1		1.3		1.7	ns
t_{RD2}	FO = 2 Routing Delay		1.2		1.4		1.6		1.8		2.4	ns
t_{RD3}	FO = 3 Routing Delay		1.4		1.6		1.8		2.1		2.8	ns
t_{RD4}	FO = 4 Routing Delay		1.7		1.9		2.2		2.5		3.3	ns
t_{RD8}	FO = 8 Routing Delay		2.8		3.2		3.6		4.2		5.5	ns
Logic Module Sequential Timing												
t_{SUD}	Flip-Flop Data Input Setup	0.5		0.6		0.7		0.8		0.8		ns
t_{HD}	Flip-Flop Data Input Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{SUD}	Latch Data Input Setup	0.5		0.6		0.7		0.8		0.8		ns
t_{HD}	Latch Data Input Hold	0.0		0.0		0.0		0.0		0.0		ns
t_{WASYN}	Asynchronous Pulse Width	2.4		3.2		3.8		4.8		6.5		ns
t_{WCLKA}	Flip-Flop Clock Pulse Width	2.4		3.2		3.8		4.8		6.5		ns
t_A	Flip-Flop Clock Input Period	5.0		6.8		8.0		10.0		13.4		ns
f_{MAX}	Flip-Flop Clock Frequency		200		150		125		100		75	MHz

Notes:

1. *VCC = 3.0 V for 3.3 V specifications.*
2. *For dual-module macros, use $t_{PD} + t_{RD1} + t_{PDn} + t_{CO} + t_{RD1} + t_{PDn}$ or $t_{PD1} + t_{RD1} + t_{SUD}$, whichever is appropriate.*
3. *The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.*
4. *Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.*

A14100A, A14V100A Timing Characteristics (continued)

Table 2-36 • A14100A, A14V100A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

I/O Module – TTL Output Timing[1]		–3 Speed[2]		–2 Speed[2]		–1 Speed		Std. Speed		3.3 V Speed[1]		Units
Parameter/Description		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
t_{DHS}	Data to Pad, High Slew		5.0		5.6		6.4		7.5		9.8	ns
t_{DLS}	Data to Pad, Low Slew		8.0		9.0		10.2		12.0		15.6	ns
t_{ENZHS}	Enable to Pad, Z to H/L, High Slew		4.0		4.5		5.1		6.0		7.8	ns
t_{ENZLS}	Enable to Pad, Z to H/L, Low Slew		7.4		8.3		9.4		11.0		14.3	ns
t_{ENHSZ}	Enable to Pad, H/L to Z, High Slew		8.0		9.0		10.2		12.0		15.6	ns
t_{ENLSZ}	Enable to Pad, H/L to Z, Low Slew		7.4		8.3		9.4		11.0		14.3	ns
t_{CKHS}	IOCLK Pad to Pad H/L, High Slew		9.5		9.5		10.5		12.0		15.6	ns
t_{CKLS}	IOCLK Pad to Pad H/L, Low Slew		12.8		12.8		15.3		17.0		22.1	ns
d_{TLHHS}	Delta Low to High, High Slew		0.02		0.02		0.03		0.03		0.04	ns/pF
d_{TLHLS}	Delta Low to High, Low Slew		0.05		0.05		0.06		0.07		0.09	ns/pF
d_{THLHS}	Delta High to Low, High Slew		0.04		0.04		0.04		0.05		0.07	ns/pF
d_{THLLS}	Delta High to Low, Low Slew		0.05		0.05		0.06		0.07		0.09	ns/pF
I/O Module – CMOS Output Timing[1]												
t_{DHS}	Data to Pad, High Slew		6.2		7.0		7.9		9.3		12.1	ns
t_{DLS}	Data to Pad, Low Slew		11.7		13.1		14.9		17.5		22.8	ns
t_{ENZHS}	Enable to Pad, Z to H/L, High Slew		5.2		5.9		6.6		7.8		10.1	ns
t_{ENZLS}	Enable to Pad, Z to H/L, Low Slew		8.9		10.0		11.3		13.3		17.3	ns
t_{ENHSZ}	Enable to Pad, H/L to Z, High Slew		8.0		9.0		10.0		12.0		15.6	ns
t_{ENLSZ}	Enable to Pad, H/L to Z, Low Slew		7.4		8.3		9.4		11.0		14.3	ns
t_{CKHS}	IOCLK Pad to Pad H/L, High Slew		10.4		10.4		12.4		13.8		17.9	ns
t_{CKLS}	IOCLK Pad to Pad H/L, Low Slew		14.5		14.5		17.4		19.3		25.1	ns
d_{TLHHS}	Delta Low to High, High Slew		0.04		0.04		0.05		0.06		0.08	ns/pF
d_{TLHLS}	Delta Low to High, Low Slew		0.07		0.08		0.09		0.11		0.14	ns/pF
d_{THLHS}	Delta High to Low, High Slew		0.03		0.03		0.03		0.04		0.05	ns/pF
d_{THLLS}	Delta High to Low, Low Slew		0.04		0.04		0.04		0.05		0.07	ns/pF

*Notes: **

1. *Delays based on 35 pF loading.*
2. *The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.*

Pin Descriptions

CLKA Clock A (Input)

Clock input for clock distribution networks. The Clock input is buffered prior to clocking the logic modules. This pin can also be used as an I/O.

CLKB Clock B (Input)

Clock input for clock distribution networks. The Clock input is buffered prior to clocking the logic modules. This pin can also be used as an I/O.

GND Ground

LOW supply voltage.

HCLK Dedicated (Hard-wired) Array Clock (Input)

Clock input for sequential modules. This input is directly wired to each S-Module and offers clock speeds independent of the number of S-Modules being driven. This pin can also be used as an I/O.

I/O Input/Output (Input, Output)

The I/O pin functions as an input, output, three-state, or bidirectional buffer. Input and output levels are compatible with standard TTL and CMOS specifications. Unused I/O pins are tristated by the Designer Series software.

IOCLK Dedicated (Hard-wired) I/O Clock (Input)

Clock input for I/O modules. This input is directly wired to each I/O module and offers clock speeds independent of the number of I/O modules being driven. This pin can also be used as an I/O.

IOPCL Dedicated (Hard-wired) I/O Preset/Clear (Input)

Input for I/O preset or clear. This global input is directly wired to the preset and clear inputs of all I/O registers. This pin functions as an I/O when no I/O preset or clear macros are used.

MODE Mode (Input)

The MODE pin controls the use of diagnostic pins (DCLK, PRA, PRB, SDI). When the MODE pin is HIGH, the special functions are active. When the MODE pin is LOW, the pins function as I/Os. To provide Actionprobe capability, the MODE pin should be terminated to GND through a 10K resistor so that the MODE pin can be pulled high when required.

NC No Connection

This pin is not connected to circuitry within the device.

PRA Probe A (Output)

The Probe A pin is used to output data from any user-defined design node within the device. This independent diagnostic pin can be used in conjunction with the Probe B pin to allow real-time diagnostic output of any signal path within the device. The Probe A pin can be used as a user-defined I/O when debugging has been completed. The pin's probe capabilities can be permanently disabled to protect programmed design confidentiality. PRA is accessible when the MODE pin is HIGH. This pin functions as an I/O when the MODE pin is LOW.

PRB Probe B (Output)

The Probe B pin is used to output data from any user-defined design node within the device. This independent diagnostic pin can be used in conjunction with the Probe A pin to allow real-time diagnostic output of any signal path within the device. The Probe B pin can be used as a user-defined I/O when debugging has been completed. The pin's probe capabilities can be permanently disabled to protect programmed design confidentiality. PRB is accessible when the MODE pin is HIGH. This pin functions as an I/O when the MODE pin is LOW.

SDI Serial Data Input (Input)

Serial data input for diagnostic probe and device programming. SDI is active when the MODE pin is HIGH. This pin functions as an I/O when the MODE pin is LOW.

TQ176		
Pin Number	**A1440, A14V40 Function**	**A1460, A14V60 Function**
1	GND	GND
2	SDI, I/O	SDI, I/O
10	MODE	MODE
11	VCC	VCC
20	NC	I/O
21	GND	GND
22	VCC	VCC
23	GND	GND
32	VCC	VCC
33	VCC	VCC
44	GND	GND
49	NC	I/O
51	NC	I/O
63	NC	I/O
64	PRB, I/O	PRB, I/O
65	GND	GND
66	VCC	VCC
67	VCC	VCC
69	HCLK, I/O	HCLK, I/O
82	NC	I/O
83	NC	I/O
87	SDO	SDO
88	IOPCL, I/O	IOPCL, I/O

TQ176		
Pin Number	**A1440, A14V40 Function**	**A1460, A14V60 Function**
89	GND	GND
98	VCC	VCC
99	VCC	VCC
108	GND	GND
109	VCC	VCC
110	GND	GND
119	NC	I/O
121	NC	I/O
122	VCC	VCC
123	GND	GND
124	VCC	VCC
132	IOCLK, I/O	IOCLK, I/O
133	GND	GND
138	NC	I/O
152	CLKA, I/O	CLKA, I/O
153	CLKB, I/O	CLKB, I/O
154	VCC	VCC
155	GND	GND
156	VCC	VCC
157	PRA, I/O	PRA, I/O
158	NC	I/O
170	NC	I/O
176	DCLK, I/O	DCLK, I/O

Notes:

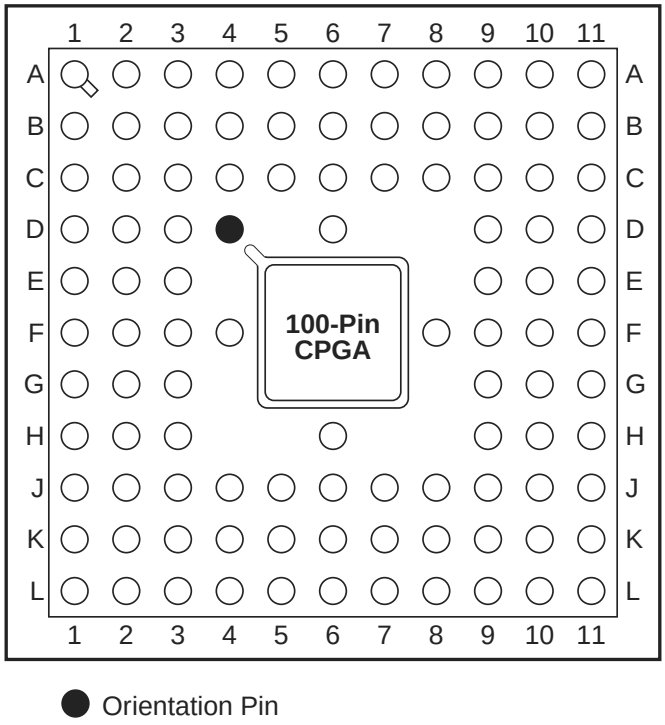
1. All unlisted pin numbers are user I/Os.
2. NC denotes no connection.
3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.

BG225	
A1460 Function	**Location**
CLKA or I/O	C8
CLKB or I/O	B8
DCLK or I/O	B2
GND	A1, A15, D15, F8, G7, G8, G9, H6, H7, H8, H9, H10, J7, J8, J9, K8, P2, R15
HCLK or I/O	P9
IOCLK or I/O	B14
IOPCL or I/O	P14
MODE	D1
NC	A11, B5, B7, D8, D12, F6, F11, H1, H12, H14, K11, L1, L13, N8, P5, R1, R8, R11, R14
PRA or I/O	A7
PRB or I/O	L7
SDI or I/O	D4
SDO	N13
VCC	A8, B12, D5, D14, E3, E8, E13, H2, H3, H11, H15, K4, L2, L12, M8, M15, P4, P8, R13

Notes:

1. All unlisted pin numbers are user I/Os.
2. NC denotes no connection.
3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.
4. The BG225 package has been discontinued.

PG100



Note: This is the top view.

Note

For Package Manufacturing and Environmental information, visit the Resource Center at http://www.microsemi.com/soc/products/solutions/package/docs.aspx

Datasheet Categories

Categories

In order to provide the latest information to designers, some datasheet parameters are published before data has been fully characterized from silicon devices. The data provided for a given device is designated as either "Product Brief," "Advance," "Preliminary," or "Production." The definitions of these categories are as follows:

Product Brief

The product brief is a summarized version of a datasheet (advance or production) and contains general product information. This document gives an overview of specific device and family information.

Advance

This version contains initial estimated information based on simulation, other products, devices, or speed grades. This information can be used as estimates, but not for production. This label only applies to the DC and Switching Characteristics chapter of the datasheet and will only be used when the data has not been fully characterized.

Preliminary

The datasheet contains information based on simulation and/or initial characterization. The information is believed to be correct, but changes are possible.

Production

This version contains information that is considered to be final.

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