E·XFL



Welcome to E-XFL.COM

Understanding <u>Embedded - FPGAs (Field</u> <u>Programmable Gate Array)</u>

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

| Details | |
|--------------------------------|--|
| Product Status | Obsolete |
| Number of LABs/CLBs | 310 |
| Number of Logic Elements/Cells | - |
| Total RAM Bits | - |
| Number of I/O | 83 |
| Number of Gates | 2500 |
| Voltage - Supply | 4.5V ~ 5.5V |
| Mounting Type | Surface Mount |
| Operating Temperature | -40°C ~ 85°C (TA) |
| Package / Case | 100-TQFP |
| Supplier Device Package | 100-VQFP (14x14) |
| Purchase URL | https://www.e-xfl.com/product-detail/microsemi/a1425a-1vqg100i |
| | |

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



ACT 3 Family Overview

| General Description | 1-1 |
|-------------------------|-----|
| Detailed Specifications | |
| Topology | 2-1 |
| Logic Modules | 2-2 |
| //Os | 2-3 |

| 1/03 | | | | | | • • • • • | |
|--------------------------------|----|------|------|------|------|---------------|----------|
| Clock Networks | | | | | | | 2-4 |
| Routing Structure | | | | | | | 2-5 |
| 5 V Operating Conditions | | | | | | | 2-9 |
| 3.3 V Operating Conditions | | | | | | | 2-10 |
| Package Thermal Characteristic | cs | | | | | | 2-11 |
| ACT 3 Timing Model | | | | | | | 2-16 |
| Pin Descriptions | | | | | | | 2-42 |

Package Pin Assignments

| PL84 | |
|--------------|------|
| PQ100 | |
| PQ160 | 3-5 |
| PQ208, RQ208 | |
| VQ100 | 3-12 |
| CQ132 | |
| CQ196 | |
| CQ256 | |
| BG225 | 3-20 |
| BG313 | |
| PG100 | 3-24 |
| PG133 | |
| PG175 | 3-28 |
| PG207 | |
| PG257 | 3-32 |
| | |

Datasheet Information

| List of Changes | 4-1 |
|---|-----|
| Datasheet Categories | 4-3 |
| Safety Critical, Life Support, and High-Reliability Applications Policy | 4-3 |



2 – Detailed Specifications

This section of the datasheet is meant to familiarize the user with the architecture of the ACT 3 family of FPGA devices. A generic description of the family will be presented first, followed by a detailed description of the logic blocks, the routing structure, the antifuses, and the special function circuits. The on-chip circuitry required to program the devices is not covered.

Topology

The ACT 3 family architecture is composed of six key elements: Logic modules, I/O modules, I/O Pad Drivers, Routing Tracks, Clock Networks, and Programming and Test Circuits. The basic structure is similar for all devices in the family, differing only in the number of rows, columns, and I/Os. The array itself consists of alternating rows of modules and channels. The logic modules and channels are in the center of the array; the I/O modules are located along the array periphery. A simplified floor plan is depicted in Figure 2-1.



Figure 2-1 • Generalized Floor Plan of ACT 3 Device



Dedicated Clocks

Dedicated clock networks support high performance by providing sub-nanosecond skew and guaranteed performance. Dedicated clock networks contain no programming elements in the path from the I/O Pad Driver to the input of S-modules or I/O modules. There are two dedicated clock networks: one for the array registers (HCLK), and one for the I/O registers (IOCLK). The clock networks are accessed by special I/Os.



Figure 2-6 • Clock Networks

The routed clock networks are referred to as CLK0 and CLK1. Each network is connected to a clock module (CLKMOD) that selects the source of the clock signal and may be driven as follows (Figure 2-6):

- Externally from the CLKA pad
- Externally from the CLKB pad
- Internally from the CLKINA input
- Internally from the CLKINB input

The clock modules are located in the top row of I/O modules. Clock drivers and a dedicated horizontal clock track are located in each horizontal routing channel. The function of the clock module is determined by the selection of clock macros from the macro library. The macro CLKBUF is used to connect one of the two external clock pins to a clock network, and the macro CLKINT is used to connect an internally generated clock signal to a clock network. Since both clock networks are identical, the user does not care whether CLK0 or CLK1 is being used. Routed clocks can also be used to drive high fanout nets like resets, output enables, or data enables. This saves logic modules and results in performance increases in some cases.

Routing Structure

The ACT 3 architecture uses vertical and horizontal routing tracks to connect the various logic and I/O modules. These routing tracks are metal interconnects that may either be of continuous length or broken into segments. Segments can be joined together at the ends using antifuses to increase their lengths up to the full length of the track.

Antifuse Connections

An antifuse is a "normally open" structure as opposed to the normally closed fuse structure used in PROMs or PALs. The use of antifuses to implement a programmable logic device results in highly testable structures as well as an efficient programming architecture. The structure is highly testable because there are no preexisting connections; temporary connections can be made using pass transistors. These temporary connections can isolate individual antifuses to be programmed as well as isolate individual circuit structures to be tested. This can be done both before and after programming. For example, all metal tracks can be tested for continuity and shorts between adjacent tracks, and the functionality of all logic modules can be verified.

Four types of antifuse connections are used in the routing structure of the ACT 3 array. (The physical structure of the antifuse is identical in each case; only the usage differs.)

Table 2-1 shows four types of antifuses.

| Table 2-1 • | Antifuse | Types |
|-------------|----------|-------|
|-------------|----------|-------|

| Туре | Description |
|------|-------------------------------------|
| XF | Horizontal-to-vertical connection |
| HF | Horizontal-to-horizontal connection |
| VF | Vertical-to-vertical connection |
| FF | "Fast" vertical connection |

Examples of all four types of connections are shown in Figure 2-7 on page 2-6 and Figure 2-8 on page 2-6.

Module Interface

Connections to Logic and I/O modules are made through vertical segments that connect to the module inputs and outputs. These vertical segments lie on vertical tracks that span the entire height of the array.

Module Input Connections

The tracks dedicated to module inputs are segmented by pass transistors in each module row. During normal user operation, the pass transistors are inactive, which isolates the inputs of a module from the inputs of the module directly above or below it. During certain test modes, the pass transistors are active to verify the continuity of the metal tracks. Vertical input segments span only the channel above or the channel below. The logic modules are arranged such that half of the inputs are connected to the channel above and half of the inputs to segments in the channel below, as shown in Figure 2-9.



Figure 2-9 • Logic Module Routing Interface

A1415A, A14V15A Timing Characteristics (continued)

Table 2-21 • A1415A, A14V15A Worst-Case Commercial Conditions, VCC = 4.75 V, $T_J = 70^{\circ}C$

| Dedicate | d (hardwired) I/O Clock Network | -3 Speed | | -2 Speed | | -1 Speed | | Std. Speed | | I 3.3 V Speed ¹ | | Units |
|----------------------|---|----------|------|----------|------|----------|------|------------|------|----------------------------|------------|-------|
| Paramete | er/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{IOCKH} | Input Low to High (pad to I/O module input) | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.5 | ns |
| t _{IOPWH} | Minimum Pulse Width High | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{IPOWL} | Minimum Pulse Width Low | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{IOSAPW} | Minimum Asynchronous Pulse Width | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{IOCKSW} | Maximum Skew | | 0.4 | | 0.4 | | 0.4 | | 0.4 | | 0.4 | ns |
| t _{IOP} | Minimum Period | 4.0 | | 5.0 | | 6.8 | | 8.0 | | 10.0 | | ns |
| f _{IOMAX} | Maximum Frequency | | 250 | | 200 | | 150 | | 125 | | 100 | MHz |
| Dedicate | d (hardwired) Array Clock | | | | | | | | | | | |
| ^t нскн | Input Low to High (pad to S-module input) | | 3.0 | | 3.4 | | 3.9 | | 4.5 | | 5.5 | ns |
| t _{HCKL} | Input High to Low (pad to S-module input) | | 3.0 | | 3.4 | | 3.9 | | 4.5 | | 5.5 | ns |
| t _{HPWH} | Minimum Pulse Width High | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{HPWL} | Minimum Pulse Width Low | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{HCKSW} | Delta High to Low, Low Slew | | 0.3 | | 0.3 | | 0.3 | | 0.3 | | 0.3 | ns |
| t _{HP} | Minimum Period | 4.0 | | 5.0 | | 6.8 | | 8.0 | | 10.0 | | ns |
| f _{HMAX} | Maximum Frequency | | 250 | | 200 | | 150 | | 125 | | 100 | MHz |
| Routed A | rray Clock Networks | | | • | • | | | | - | | | |
| t _{RCKH} | Input Low to High (FO = 64) | | 3.7 | | 4.1 | | 4.7 | | 5.5 | | 9.0 | ns |
| t _{RCKL} | Input High to Low (FO = 64) | | 4.0 | | 4.5 | | 5.1 | | 6.0 | | 9.0 | ns |
| t _{RPWH} | Min. Pulse Width High (FO = 64) | 3.3 | | 3.8 | | 4.2 | | 4.9 | | 6.5 | | ns |
| t _{RPWL} | Min. Pulse Width Low (FO = 64) | 3.3 | | 3.8 | | 4.2 | | 4.9 | | 6.5 | | ns |
| t _{RCKSW} | Maximum Skew (FO = 128) | | 0.7 | | 0.8 | | 0.9 | | 1.0 | | 1.0 | ns |
| t _{RP} | Minimum Period (FO = 64) | 6.8 | | 8.0 | | 8.7 | | 10.0 | | 13.4 | | ns |
| f _{RMAX} | Maximum Frequency (FO = 64) | | 150 | | 125 | | 115 | | 100 | | 75 | MHz |
| Clock-to- | Clock Skews | | | • | | | | | - | | | |
| t _{IOHCKSW} | I/O Clock to H-Clock Skew | 0.0 | 1.7 | 0.0 | 1.8 | 0.0 | 2.0 | 0.0 | 2.2 | 0.0 | 3.0 | ns |
| t _{IORCKSW} | I/O Clock to R-Clock Skew (FO = 64) | 0.0 | 1.0 | 0.0 | 1.0 | 0.0 | 1.0 | 0.0 | 1.0 | 0.0 | 3.0 | ns |
| t _{HRCKSW} | H-Clock to R-Clock Skew (FO = 64) (FO = 50% maximum) | 0.0 | 1.0 | 0.0 | 1.0 | 0.0 | 1.0 | 0.0 | 1.0 | 0.0 0.0 | 3.0 3.0 | ns |

Notes:

1. Delays based on 35 pF loading.

2. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.



A1440A, A14V40A Timing Characteristics (continued)

Table 2-28 • A1440A, A14V40A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

| I/O Moo | dule – TTL Output Timing ¹ | -3 Sp | beed ² | -2 Sp | beed ² | –1 S | peed | Std. | Speed | I 3.3 V Speed ¹ | | Units |
|-----------------------|--|-------|-------------------|-------|-------------------|------|------|------|-------|----------------------------|------|-------|
| Parameter/Description | | | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{DHS} | Data to Pad, High Slew | | 5.0 | | 5.6 | | 6.4 | | 7.5 | | 9.8 | ns |
| t _{DLS} | Data to Pad, Low Slew | | 8.0 | | 9.0 | | 10.2 | | 12.0 | | 15.6 | ns |
| t _{ENZHS} | Enable to Pad, Z to H/L, High Slew | | 4.0 | | 4.5 | | 5.1 | | 6.0 | | 7.8 | ns |
| t _{ENZLS} | Enable to Pad, Z to H/L, Low Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{ENHSZ} | Enable to Pad, H/L to Z, High Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{ENLSZ} | Enable to Pad, H/L to Z, Low Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{CKHS} | IOCLK Pad to Pad H/L, High Slew | | 8.5 | | 8.5 | | 9.5 | | 11.0 | | 14.3 | ns |
| t _{CKLS} | IOCLK Pad to Pad H/L, Low Slew | | 11.3 | | 11.3 | | 13.5 | | 15.0 | | 19.5 | ns |
| d _{TLHHS} | Delta Low to High, High Slew | | 0.02 | | 0.02 | | 0.03 | | 0.03 | | 0.04 | ns/pF |
| d _{TLHLS} | Delta Low to High, Low Slew | | 0.05 | | 0.05 | | 0.06 | | 0.07 | | 0.09 | ns/pF |
| d _{THLHS} | Delta High to Low, High Slew | | 0.04 | | 0.04 | | 0.04 | | 0.05 | | 0.07 | ns/pF |
| d _{THLLS} | Delta High to Low, Low Slew | | 0.05 | | 0.05 | | 0.06 | | 0.07 | | 0.09 | ns/pF |
| I/O Moo | dule – CMOS Output Timing ¹ | • | | | • | | | | | | | |
| t _{DHS} | Data to Pad, High Slew | | 6.2 | | 7.0 | | 7.9 | | 9.3 | | 12.1 | ns |
| t _{DLS} | Data to Pad, Low Slew | | 11.7 | | 13.1 | | 14.9 | | 17.5 | | 22.8 | ns |
| t _{ENZHS} | Enable to Pad, Z to H/L, High Slew | | 5.2 | | 5.9 | | 6.6 | | 7.8 | | 10.1 | ns |
| t _{ENZLS} | Enable to Pad, Z to H/L, Low Slew | | 8.9 | | 10.0 | | 11.3 | | 13.3 | | 17.3 | ns |
| t _{ENHSZ} | Enable to Pad, H/L to Z, High Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{ENLSZ} | Enable to Pad, H/L to Z, Low Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{CKHS} | IOCLK Pad to Pad H/L, High Slew | | 9.0 | | 9.0 | | 10.1 | | 11.8 | | 14.3 | ns |
| t _{CKLS} | IOCLK Pad to Pad H/L, Low Slew | | 13.0 | | 13.0 | | 15.6 | | 17.3 | | 22.5 | ns |
| d _{TLHHS} | Delta Low to High, High Slew | | 0.04 | | 0.04 | | 0.05 | | 0.06 | | 0.08 | ns/pF |
| d _{TLHLS} | Delta Low to High, Low Slew | | 0.07 | | 0.08 | | 0.09 | | 0.11 | | 0.14 | ns/pF |
| d _{THLHS} | Delta High to Low, High Slew | | 0.03 | | 0.03 | | 0.03 | | 0.04 | | 0.05 | ns/pF |
| d _{THLLS} | Delta High to Low, Low Slew | | 0.04 | | 0.04 | | 0.04 | | 0.05 | | 0.07 | ns/pF |

Notes:

1. Delays based on 35 pF loading.

2. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.



A1460A, A14V60A Timing Characteristics

| Table 2-30 • A1460A | , A14V60A Worst-Case Commercial | Conditions | $VCC = 4.75 V_{1} T_{1} = 70^{\circ}C^{1}$ |
|---------------------|---------------------------------|------------|--|
| | | oonantiono | |

| Logic Module Propagation Delays ² | | | -3 Speed ³ | | -2 Speed ³ | | -1 Speed | | Speed | 3.3 V Speed ¹ | | Units |
|--|--------------------------------|------|-----------------------|------|-----------------------|------|----------|------|-------|--------------------------|------|-------|
| Parame | eter/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{PD} | Internal Array Module | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns |
| t _{CO} | Sequential Clock to Q | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns |
| t _{CLR} | Asynchronous Clear to Q | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns |
| Predict | ed Routing Delays ⁴ | | | | | | | | | | | |
| t _{RD1} | FO = 1 Routing Delay | | 0.9 | | 1.0 | | 1.1 | | 1.3 | | 1.7 | ns |
| t _{RD2} | FO = 2 Routing Delay | | 1.2 | | 1.4 | | 1.6 | | 1.8 | | 2.4 | ns |
| t _{RD3} | FO = 3 Routing Delay | | 1.4 | | 1.6 | | 1.8 | | 2.1 | | 2.8 | ns |
| t _{RD4} | FO = 4 Routing Delay | | 1.7 | | 1.9 | | 2.2 | | 2.5 | | 3.3 | ns |
| t _{RD8} | FO = 8 Routing Delay | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| Logic N | Nodule Sequential Timing | | | | | | | | | | | |
| t _{SUD} | Flip-Flop Data Input Setup | 0.5 | | 0.6 | | 0.7 | | 0.8 | | 0.8 | | ns |
| t _{HD} | Flip-Flop Data Input Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{SUD} | Latch Data Input Setup | 0.5 | | 0.6 | | 0.7 | | 0.8 | | 0.8 | | ns |
| t _{HD} | Latch Data Input Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{WASYN} | Asynchronous Pulse Width | 2.4 | | 3.2 | | 3.8 | | 4.8 | | 6.5 | | ns |
| t _{WCLKA} | Flip-Flop Clock Pulse Width | 2.4 | | 3.2 | | 3.8 | | 4.8 | | 6.5 | | ns |
| t _A | Flip-Flop Clock Input Period | 5.0 | | 6.8 | | 8.0 | | 10.0 | | 13.4 | | ns |
| f _{MAX} | Flip-Flop Clock Frequency | | 200 | | 150 | | 125 | | 100 | | 75 | MHz |

Notes:

1. VCC = 3.0 V for 3.3 V specifications.

2. For dual-module macros, use $t_{PD} + t_{RD1} + t_{PDn} + t_{CO} + t_{RD1} + t_{PDn}$ or $t_{PD1} + t_{RD1} + t_{SUD}$, whichever is appropriate.

3. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

4. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.

A1460A, A14V60A Timing Characteristics (continued)

| Table 2-31 • A1460A | A14V60A Worst-Case | Commercial Conditions | , VCC = 4.75 V, T _J = 70°C |
|-----------------------|---------------------|-----------------------|---------------------------------------|
| Table 2-31 • A 1400A, | A 14VOUA WUISI-Case | Commercial Conditions | , VCC = 4.75 V, Ij = 70 C |

| I/O Module Input Propagation Delays | | | beed ¹ | -2 Sp | beed ¹ | -1 Speed | | Std. Speed | | 3.3 V Speed ¹ | | Units |
|-------------------------------------|--------------------------------------|------|-------------------|-------|-------------------|----------|------|------------|------|--------------------------|------|-------|
| Parameter/Description | | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{INY} | Input Data Pad to Y | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| t _{ICKY} | Input Reg IOCLK Pad to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{OCKY} | Output Reg IOCLK Pad to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{ICLRY} | Input Asynchronous Clear to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{OCLRY} | Output Asynchronous Clear to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| Predict | ed Input Routing Delays ² | | | | | | • | | | | | |
| t _{RD1} | FO = 1 Routing Delay | | 0.9 | | 1.0 | | 1.1 | | 1.3 | | 1.7 | ns |
| t _{RD2} | FO = 2 Routing Delay | | 1.2 | | 1.4 | | 1.6 | | 1.8 | | 2.4 | ns |
| t _{RD3} | FO = 3 Routing Delay | | 1.4 | | 1.6 | | 1.8 | | 2.1 | | 2.8 | ns |
| t _{RD4} | FO = 4 Routing Delay | | 1.7 | | 1.9 | | 2.2 | | 2.5 | | 3.3 | ns |
| t _{RD8} | FO = 8 Routing Delay | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| I/O Mod | ule Sequential Timing (wrt IOCLK | pad) | | | | | • | | | | | |
| t _{INH} | Input F-F Data Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{INSU} | Input F-F Data Setup | 1.3 | | 1.5 | | 1.8 | | 2.0 | | 2.0 | | ns |
| t _{IDEH} | Input Data Enable Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{IDESU} | Input Data Enable Setup | 5.8 | | 6.5 | | 7.5 | | 8.6 | | 8.6 | | ns |
| t _{OUTH} | Output F-F Data hold | 0.7 | | 0.8 | | 0.9 | | 1.0 | | 1.0 | | ns |
| t _{OUTSU} | Output F-F Data Setup | 0.7 | | 0.8 | | 0.9 | | 1.0 | | 1.0 | | ns |
| t _{ODEH} | Output Data Enable Hold | 0.3 | | 0.4 | | 0.4 | | 0.5 | | 0.5 | | ns |
| f _{ODESU} | Output Data Enable Setup | 1.3 | | 1.5 | | 1.7 | | 2.0 | | 2.0 | | ns |

Notes:

5. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

6. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.



A1460A, A14V60A Timing Characteristics (continued)

Table 2-32 • A1460A, A14V60A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

| I/O Moo | dule – TTL Output Timing ¹ | –3 Sj | beed ² | -2 Sp | beed ² | –1 S | -1 Speed Std. Speed | | | 3.3 V Speed ¹ | | Units |
|--------------------|--|-------|-------------------|-------|-------------------|------|---------------------|------|------|--------------------------|------|-------|
| Parame | eter/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{DHS} | Data to Pad, High Slew | | 5.0 | | 5.6 | | 6.4 | | 7.5 | | 9.8 | ns |
| t _{DLS} | Data to Pad, Low Slew | | 8.0 | | 9.0 | | 10.2 | | 12.0 | | 15.6 | ns |
| t _{ENZHS} | Enable to Pad, Z to H/L, High Slew | | 4.0 | | 4.5 | | 5.1 | | 6.0 | | 7.8 | ns |
| t _{ENZLS} | Enable to Pad, Z to H/L, Low Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{ENHSZ} | Enable to Pad, H/L to Z, High Slew | | 7.8 | | 8.7 | | 9.9 | | 11.6 | | 15.1 | ns |
| t _{ENLSZ} | Enable to Pad, H/L to Z, Low Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{CKHS} | IOCLK Pad to Pad H/L, High Slew | | 9.0 | | 9.0 | | 10.0 | | 11.5 | | 15.0 | ns |
| t _{CKLS} | IOCLK Pad to Pad H/L, Low Slew | | 12.8 | | 12.8 | | 15.3 | | 17.0 | | 22.1 | ns |
| d _{TLHHS} | Delta Low to High, High Slew | | 0.02 | | 0.02 | | 0.03 | | 0.03 | | 0.04 | ns/pF |
| d _{TLHLS} | Delta Low to High, Low Slew | | 0.05 | | 0.05 | | 0.06 | | 0.07 | | 0.09 | ns/pF |
| d _{THLHS} | Delta High to Low, High Slew | | 0.04 | | 0.04 | | 0.04 | | 0.05 | | 0.07 | ns/pF |
| d _{THLLS} | Delta High to Low, Low Slew | | 0.05 | | 0.05 | | 0.06 | | 0.07 | | 0.09 | ns/pF |
| I/O Moo | dule – CMOS Output Timing ¹ | • | | | • | | • | | | | | |
| t _{DHS} | Data to Pad, High Slew | | 6.2 | | 7.0 | | 7.9 | | 9.3 | | 12.1 | ns |
| t _{DLS} | Data to Pad, Low Slew | | 11.7 | | 13.1 | | 14.9 | | 17.5 | | 22.8 | ns |
| t _{ENZHS} | Enable to Pad, Z to H/L, High Slew | | 5.2 | | 5.9 | | 6.6 | | 7.8 | | 10.1 | ns |
| t _{ENZLS} | Enable to Pad, Z to H/L, Low Slew | | 8.9 | | 10.0 | | 11.3 | | 13.3 | | 17.3 | ns |
| t _{ENHSZ} | Enable to Pad, H/L to Z, High Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{ENLSZ} | Enable to Pad, H/L to Z, Low Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{CKHS} | IOCLK Pad to Pad H/L, High Slew | | 10.4 | | 10.4 | | 12.1 | | 13.8 | | 17.9 | ns |
| t _{CKLS} | IOCLK Pad to Pad H/L, Low Slew | | 14.5 | | 14.5 | | 17.4 | | 19.3 | | 25.1 | ns |
| d _{TLHHS} | Delta Low to High, High Slew | | 0.04 | | 0.04 | | 0.05 | | 0.06 | | 0.08 | ns/pF |
| d _{TLHLS} | Delta Low to High, Low Slew | | 0.07 | | 0.08 | | 0.09 | | 0.11 | | 0.14 | ns/pF |
| d _{THLHS} | Delta High to Low, High Slew | | 0.03 | | 0.03 | | 0.03 | | 0.04 | | 0.05 | ns/pF |
| d _{THLLS} | Delta High to Low, Low Slew | | 0.04 | | 0.04 | | 0.04 | | 0.05 | | 0.07 | ns/pF |

Notes:

1. Delays based on 35 pF loading.

2. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

A14100A, A14V100A Timing Characteristics (continued)

Table 2-35 • A14100A, A14V100A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

| I/O Module Input Propagation Delays | | | beed ¹ | -2 Sp | beed ¹ | -1 Speed | | Std. Speed | | 3.3 V Speed ¹ | | Units |
|-------------------------------------|--------------------------------------|------|-------------------|-------|-------------------|----------|------|------------|------|--------------------------|------|-------|
| Parameter/Description | | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{INY} | Input Data Pad to Y | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| t _{ICKY} | Input Reg IOCLK Pad to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{OCKY} | Output Reg IOCLK Pad to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{ICLRY} | Input Asynchronous Clear to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{OCLRY} | Output Asynchronous Clear to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| Predict | ed Input Routing Delays ² | | | | | | | | | | | |
| t _{RD1} | FO = 1 Routing Delay | | 0.9 | | 1.0 | | 1.1 | | 1.3 | | 1.7 | ns |
| t _{RD2} | FO = 2 Routing Delay | | 1.2 | | 1.4 | | 1.6 | | 1.8 | | 2.4 | ns |
| t _{RD3} | FO = 3 Routing Delay | | 1.4 | | 1.6 | | 1.8 | | 2.1 | | 2.8 | ns |
| t _{RD4} | FO = 4 Routing Delay | | 1.7 | | 1.9 | | 2.2 | | 2.5 | | 3.3 | ns |
| t _{RD8} | FO = 8 Routing Delay | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| I/O Mod | ule Sequential Timing (wrt IOCLK | pad) | | | | | | | | | | |
| t _{INH} | Input F-F Data Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{INSU} | Input F-F Data Setup | 1.2 | | 1.4 | | 1.5 | | 1.8 | | 1.8 | | ns |
| t _{IDEH} | Input Data Enable Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{IDESU} | Input Data Enable Setup | 5.8 | | 6.5 | | 7.5 | | 8.6 | | 8.6 | | ns |
| t _{OUTH} | Output F-F Data hold | 0.7 | | 0.8 | | 1.0 | | 1.0 | | 1.0 | | ns |
| t _{OUTSU} | Output F-F Data Setup | 0.7 | | 0.8 | | 1.0 | | 1.0 | | 1.0 | | ns |
| t _{ODEH} | Output Data Enable Hold | 0.3 | | 0.4 | | 0.5 | | 0.5 | | 0.5 | | ns |
| f _{ODESU} | Output Data Enable Setup | 1.3 | | 1.5 | | 2.0 | | 2.0 | | 2.0 | | ns |

Notes: *

1. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

 Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.



Pin Descriptions

CLKA Clock A (Input)

Clock input for clock distribution networks. The Clock input is buffered prior to clocking the logic modules. This pin can also be used as an I/O.

CLKB Clock B (Input)

Clock input for clock distribution networks. The Clock input is buffered prior to clocking the logic modules. This pin can also be used as an I/O.

GND Ground

LOW supply voltage.

HCLK Dedicated (Hard-wired) Array Clock (Input)

Clock input for sequential modules. This input is directly wired to each S-Module and offers clock speeds independent of the number of S-Modules being driven. This pin can also be used as an I/O.

I/O Input/Output (Input, Output)

The I/O pin functions as an input, output, three-state, or bidirectional buffer. Input and output levels are compatible with standard TTL and CMOS specifications. Unused I/O pins are tristated by the Designer Series software.

IOCLK Dedicated (Hard-wired) I/O Clock (Input)

Clock input for I/O modules. This input is directly wired to each I/O module and offers clock speeds independent of the number of I/O modules being driven. This pin can also be used as an I/O.

IOPCL Dedicated (Hard-wired) I/O Preset/Clear (Input)

Input for I/O preset or clear. This global input is directly wired to the preset and clear inputs of all I/O registers. This pin functions as an I/O when no I/O preset or clear macros are used.

MODE Mode (Input)

The MODE pin controls the use of diagnostic pins (DCLK, PRA, PRB, SDI). When the MODE pin is HIGH, the special functions are active. When the MODE pin is LOW, the pins function as I/Os. To provide Actionprobe capability, the MODE pin should be terminated to GND through a 10K resistor so that the MODE pin can be pulled high when required.

NC No Connection

This pin is not connected to circuitry within the device.

PRA Probe A (Output)

The Probe A pin is used to output data from any user-defined design node within the device. This independent diagnostic pin can be used in conjunction with the Probe B pin to allow real-time diagnostic output of any signal path within the device. The Probe A pin can be used as a user-defined I/O when debugging has been completed. The pin's probe capabilities can be permanently disabled to protect programmed design confidentiality. PRA is accessible when the MODE pin is HIGH. This pin functions as an I/O when the MODE pin is LOW.

PRB Probe B (Output)

The Probe B pin is used to output data from any user-defined design node within the device. This independent diagnostic pin can be used in conjunction with the Probe A pin to allow real-time diagnostic output of any signal path within the device. The Probe B pin can be used as a user-defined I/O when debugging has been completed. The pin's probe capabilities can be permanently disabled to protect programmed design confidentiality. PRB is accessible when the MODE pin is HIGH. This pin functions as an I/O when the MODE pin is LOW.

SDI Serial Data Input (Input)

Serial data input for diagnostic probe and device programming. SDI is active when the MODE pin is HIGH. This pin functions as an I/O when the MODE pin is LOW.



SDO Serial Data Output (Output)

Serial data output for diagnostic probe. SDO is active when the MODE pin is High. This pin functions as an I/O when the MODE pin is Low.

DCLK Diagnostic Clock (Input)

Clock input for diagnostic probe and device programming. DCLK is active when the MODE pin is HIGH. This pin functions as an I/O when the MODE pin is LOW.

VCC 5 V Supply Voltage

HIGH supply voltage.



| PL84 | | | | | | |
|------------|------------------------|------------------------|------------------------|--|--|--|
| Pin Number | A1415, A14V15 Function | A1425, A14V25 Function | A1440, A14V40 Function | | | |
| 1 | VCC | VCC | VCC | | | |
| 2 | GND | GND | GND | | | |
| 3 | VCC | VCC | VCC | | | |
| 4 | PRA, I/O | PRA, I/O | PRA, I/O | | | |
| 11 | DCLK, I/O | DCLK, I/O | DCLK, I/O | | | |
| 12 | SDI, I/O | SDI, I/O | SDI, I/O | | | |
| 16 | MODE | MODE | MODE | | | |
| 27 | GND | GND | GND | | | |
| 28 | VCC | VCC | VCC | | | |
| 40 | PRB, I/O | PRB, I/O | PRB, I/O | | | |
| 41 | VCC | VCC | VCC | | | |
| 42 | GND | GND | GND | | | |
| 43 | VCC | VCC | VCC | | | |
| 45 | HCLK, I/O | HCLK, I/O | HCLK, I/O | | | |
| 52 | SDO | SDO | SDO | | | |
| 53 | IOPCL, I/O | IOPCL, I/O | IOPCL, I/O | | | |
| 59 | VCC | VCC | VCC | | | |
| 60 | VCC | VCC | VCC | | | |
| 61 | GND | GND | GND | | | |
| 68 | VCC | VCC | VCC | | | |
| 69 | GND | GND | GND | | | |
| 74 | IOCLK, I/O | IOCLK, I/O | IOCLK, I/O | | | |
| 83 | CLKA, I/O | CLKA, I/O | CLKA, I/O | | | |
| 84 | CLKB, I/O | CLKB, I/O | CLKB, I/O | | | |

Notes:

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.

PQ100



Note: This is the top view of the package.

Note

For Package Manufacturing and Environmental information, visit the Resource Center at http://www.microsemi.com/soc/products/solutions/package/docs.aspx



| | TQ176 | | TQ176 | | | | | | |
|------------|---------------------------|---------------------------|------------|---------------------------|---------------------------|--|--|--|--|
| Pin Number | A1440, A14V40 Function | A1460, A14V60 Function | Pin Number | A1440, A14V40 Function | A1460, A14V60 Function | | | | |
| 1 | GND | GND | 89 | GND | GND | | | | |
| 2 | SDI, I/O | SDI, I/O | 98 | VCC | VCC | | | | |
| 10 | MODE | MODE | 99 | VCC | VCC | | | | |
| 11 | VCC | VCC | 108 | GND | GND | | | | |
| 20 | NC | I/O | 109 | VCC | VCC | | | | |
| 21 | GND | GND | 110 | GND | GND | | | | |
| 22 | VCC | VCC | 119 | NC | I/O | | | | |
| 23 | GND | GND | 121 | NC | I/O | | | | |
| 32 | VCC | VCC | 122 | VCC | VCC | | | | |
| 33 | VCC | VCC | 123 | GND | GND | | | | |
| 44 | GND | GND | 124 | VCC | VCC | | | | |
| 49 | NC | I/O | 132 | IOCLK, I/O | IOCLK, I/O | | | | |
| 51 | NC | I/O | 133 | GND | GND | | | | |
| 63 | NC | I/O | 138 | NC | I/O | | | | |
| 64 | PRB, I/O | PRB, I/O | 152 | CLKA, I/O | CLKA, I/O | | | | |
| 65 | GND | GND | 153 | CLKB, I/O | CLKB, I/O | | | | |
| 66 | VCC | VCC | 154 | VCC | VCC | | | | |
| 67 | VCC | VCC | 155 | GND | GND | | | | |
| 69 | HCLK, I/O | HCLK, I/O | 156 | VCC | VCC | | | | |
| 82 | NC | I/O | 157 | PRA, I/O | PRA, I/O | | | | |
| 83 | NC | I/O | 158 | NC | I/O | | | | |
| 87 | SDO | SDO | 170 | NC | I/O | | | | |
| 88 | IOPCL, I/O | IOPCL, I/O | 176 | DCLK, I/O | DCLK, I/O | | | | |

Notes:

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.



CQ132



Note: This is the top view

Note

For Package Manufacturing and Environmental information, visit the Resource Center at http://www.microsemi.com/soc/products/solutions/package/docs.aspx



PG100





Note

For Package Manufacturing and Environmental information, visit the Resource Center at http://www.microsemi.com/soc/products/solutions/package/docs.aspx

| | PG175 | | | | | | |
|----------------|--|--|--|--|--|--|--|
| A1440 Function | Location | | | | | | |
| CLKA or I/O | C9 | | | | | | |
| CLKB or I/O | А9 | | | | | | |
| DCLK or I/O | D5 | | | | | | |
| GND | D4, D8, D11, D12, E4, E14, H4, H12, L4, L12, M4, M8, M12 | | | | | | |
| HCLK or I/O | R8 | | | | | | |
| IOCLK or I/O | E12 | | | | | | |
| IOPCL or I/O | P13 | | | | | | |
| MODE | F3 | | | | | | |
| NC | A1, A2, A15, B2, B3, P2, P14, R1, R2, R14, R15 | | | | | | |
| PRA or I/O | B8 | | | | | | |
| PRB or I/O | R7 | | | | | | |
| SDI or I/O | D3 | | | | | | |
| SDO | N12 | | | | | | |
| VCC | C3, C8, C13, E15, H3, H13, L1, L14, N3, N8, N13 | | | | | | |

Notes:

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.
- 4. The PG175 package has been discontinued.



| Revision | Changes | Page |
|---------------------------|--|------|
| Revision 2 (continued) | In the "Package Pin Assignments" section, notes were added to the pin tables for the following packages, stating that they are discontinued: | |
| | "BG225" | 3-20 |
| | "PG100" | 3-24 |
| | "PG133" | 3-26 |
| | "PG175" | 3-28 |
| Revision 1 (June 2006) | RoHS compliant information was added to the "Ordering Information" section. | II |



Microsemi Corporate Headquarters One Enterprise, Aliso Viejo CA 92656 USA Within the USA: +1 (949) 380-6100 Sales: +1 (949) 380-6136 Fax: +1 (949) 215-4996 Microsemi Corporation (NASDAQ: MSCC) offers a comprehensive portfolio of semiconductor solutions for: aerospace, defense and security; enterprise and communications; and industrial and alternative energy markets. Products include high-performance, high-reliability analog and RF devices, mixed signal and RF integrated circuits, customizable SoCs, FPGAs, and complete subsystems. Microsemi is headquartered in Aliso Viejo, Calif. Learn more at **www.microsemi.com**.

© 2012 Microsemi Corporation. All rights reserved. Microsemi and the Microsemi logo are trademarks of Microsemi Corporation. All other trademarks and service marks are the property of their respective owners.