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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	40MHz
Connectivity	CSIO, I ² C, LINbus, SmartCard, UART/USART, USB
Peripherals	I ² S, LCD, LVD, POR, PWM, WDT
Number of I/O	65
Program Memory Size	304KB (304K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.65V ~ 3.6V
Data Converters	A/D 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	80-LQFP
Supplier Device Package	80-LQFP (12x12)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/s6e1b84ehagv20000

1. Product Lineup

Memory Size

Product Name		S6E1B84E/F/G	S6E1B86E/F/G
On-chip Flash memory	Upper Bank	256 Kbytes	512 Kbytes
	Lower Bank	48 Kbytes	48 Kbytes
On-chip SRAM		32 Kbytes	64 Kbytes

Function

Product Name			S6E1B84E0A S6E1B86E0A S6E1B84EHA S6E1B86EHA	S6E1B84F0A S6E1B86F0A S6E1B84FHA S6E1B86FHA	S6E1B84G0A S6E1B86G0A S6E1B84GHA S6E1B86GHA		
Pin count			80		100	120	
CPU			Cortex-M0+				
Frequency			40.8 MHz				
Power supply voltage range			1.65 V to 3.6 V				
USB 2.0 (Device/Host)			1 unit				
DSTC			64ch				
Multi-function Serial Interface (UART/CSIO (SPI)/I ² C/I ² S)			8ch (Max) with 128 bytes FIFO I ² S: ch.5, ch.6				
Base Timer (PWC/Reload timer/PWM/PPG)			8ch (Max)				
LCD controller			20SEG x 8COM(Max) / 24SEG x 4COM(Max)	32SEG x 8COM(Max) / 36SEG x 4COM(Max)	40SEG x 8COM(Max) / 44SEG x 4COM(Max)		
Multi-function Timer	A/D activation compare	6ch	1 unit				
	Input capture	4ch					
	Free-run timer	3ch					
	Output compare	6ch					
	Waveform generator	3ch					
	PPG	3ch					
Dual Timer			1 unit				
HDMI-CEC/ Remote Control Receiver			2ch (max)				
Smart Card Interface			2ch (max)				
Real-time Clock			1 unit (with battery power)				
Watch Counter			1 unit				
CRC Accelerator			Yes				
Watchdog timer			1ch (SW) + 1ch (HW)				
External Interrupt			24 pins (Max), NMI × 1				
I/O port			65 pins (Max)	82 pins (Max)	102 pins (Max)		
12-bit A/D converter			16ch (1 unit)	23ch (1 unit)	24ch (1 unit)		
CSV (Clock Supervisor)			Yes				
LVD (Low-voltage Detection)			2ch				
Built-in CR	High-speed		4 MHz				
	Low-speed		100 kHz				
Debug Function			SW-DP				
Unique ID			Yes				
AES Calculator			-	Yes ^{*1}	-	Yes ^{*1}	

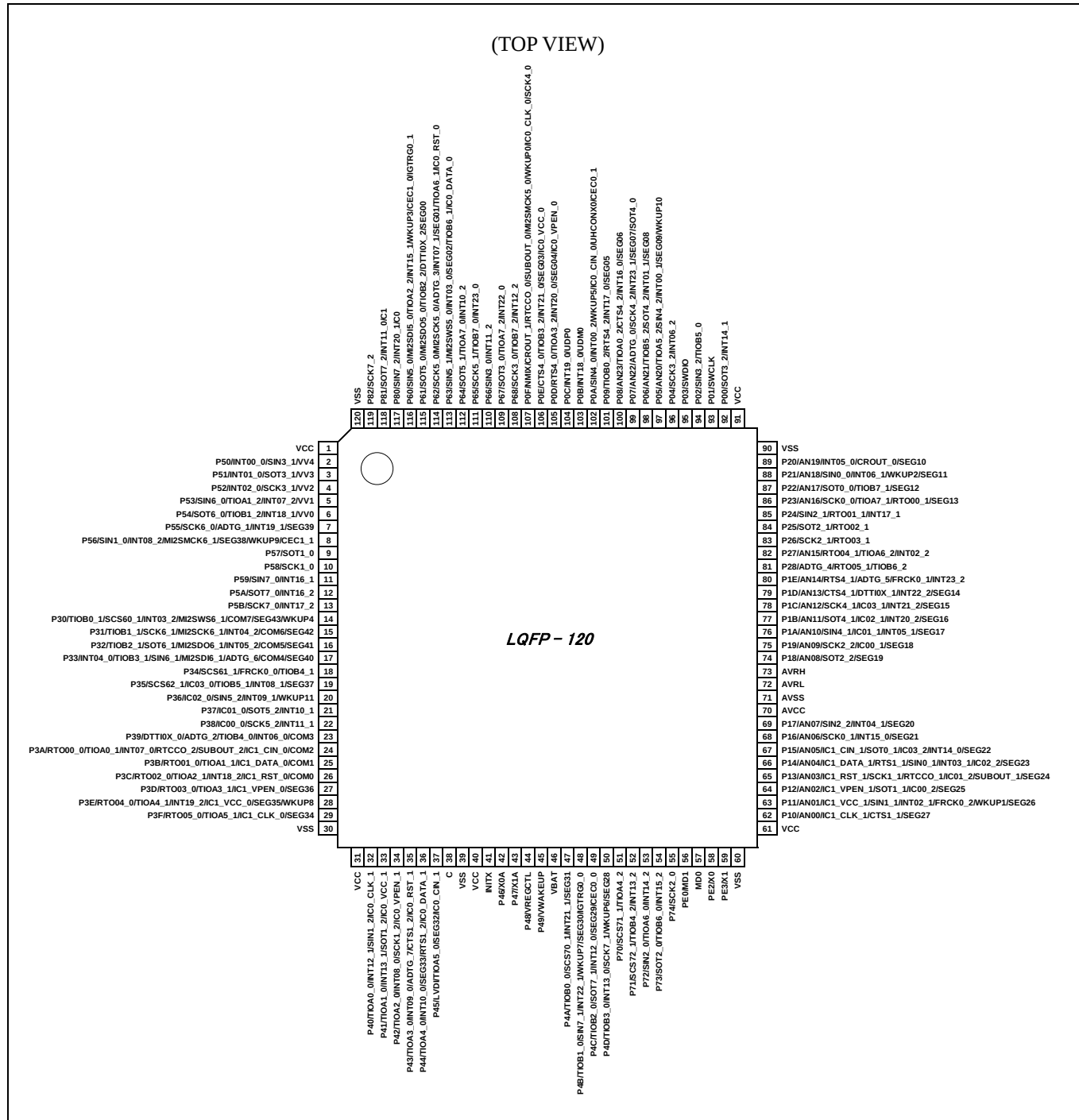
*1: AES Calculator is built in following products.

S6E1B86GHA, S6E1B84GHA, S6E1B86FHA, S6E1B84FHA, S6E1B86EHA, S6E1B84EHA

Note:

- All signals of the peripheral function in each product cannot be allocated by limiting the pins of package. It is necessary to use the port relocate function of the I/O port according to your function use.
See "11 Electrical Characteristics 11.4 AC Characteristics 11.4.3 Built-in CR Oscillation Characteristics" for accuracy of built-in CR.

FPT-120P-M21



Note:

- The number after the underscore ("_") in a pin name such as XXX_1 and XXX_2 indicates the relocated port number. The channel on such pin has multiple functions, each of which has its own pin name. Use the Extended Port Function Register (EPFR) to select the pin to be used.

4. List of Pin Functions

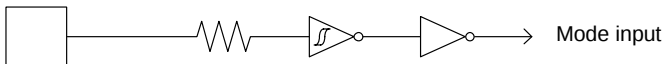
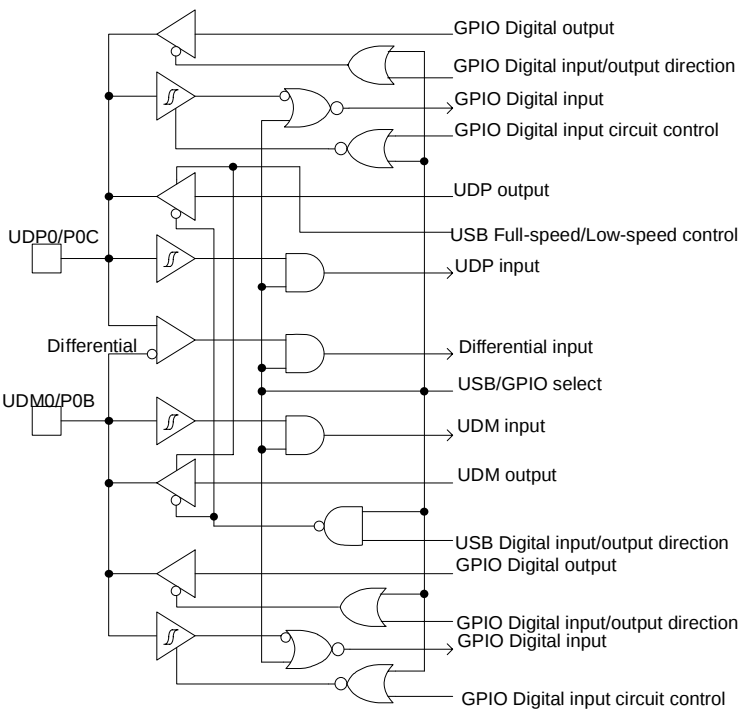
List of Pin Numbers

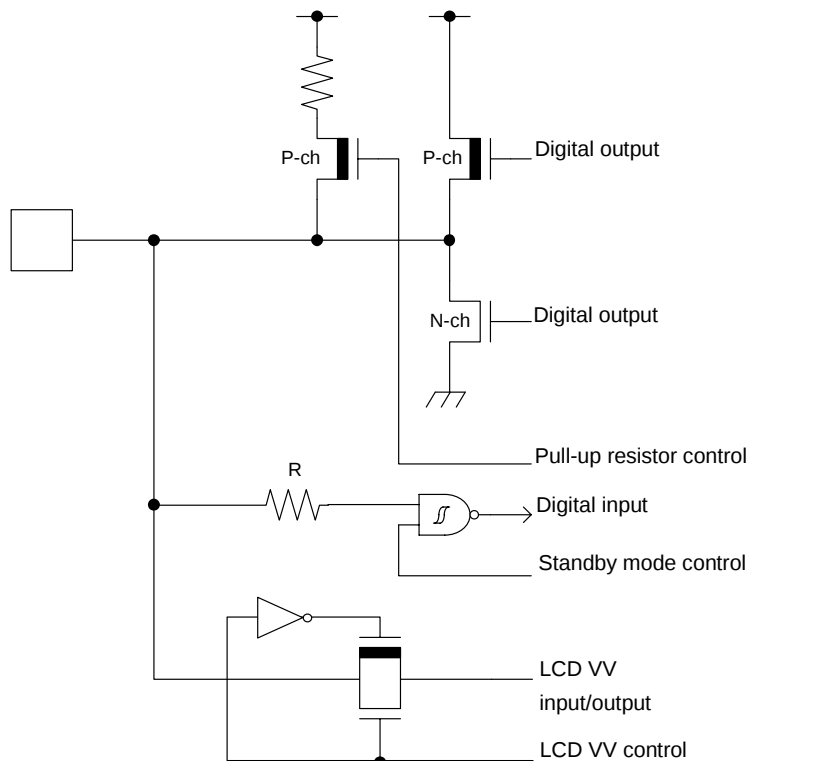
The number after the underscore ("_") in a pin name such as XXX_1 and XXX_2 indicates the relocated port number. The channel on such pin has multiple functions, each of which has its own pin name. Use the Extended Port Function Register (EPFR) to select the pin to be used.

Pin No.			Pin Name	I/O Circuit Type	Pin State Type
LQFP-120	LQFP-100	LQFP-80			
1	1	1	VCC	-	
2	2	2	P50	Q	X
			SIN3_1		
			INT00_0		
			VV4		
3	3	3	P51	Q	X
			SOT3_1		
			INT01_0		
			VV3		
4	4	4	P52	Q	X
			SCK3_1		
			INT02_0		
			VV2		
5	5	5	P53	Q	X
			SIN6_0		
			TIOA1_2		
			INT07_2		
6	6	6	VV1	Q	X
			P54		
			SOT6_0		
			TIOB1_2		
7	7	7	INT18_1	Q	X
			VV0		
			P55		
			SCK6_0		
8	8	8	ADTG_1	L	S
			INT19_1		
			SEG39		
			P56		
9	8	8	MI2SMCK6_1	L	U
			CEC1_1		
			INT08_2		
			WKUP9		
10	-	-	SEG38	F	I
			SIN1_0		
			P57		
			SOT1_0		
11	-	-	P58	F	J
			SCK1_0		
			P59		
			SIN7_0		
			INT16_1		

Pin No.			Pin Name	I/O Circuit Type	Pin State Type
LQFP-120	LQFP-100	LQFP-80			
49	44	34	P4C	L	R
			TIOB2_0		
			SOT7_1		
			CEC0_0		
			INT12_0		
			SEG29		
50	45	35	P4D	L	T
			TIOB3_0		
			SCK7_1		
			INT13_0		
			WKUP6		
			SEG28		
51	-	-	P70	F	I
			TIOA4_2		
			SCS71_1		
52	-	-	P71	F	J
			TIOB4_2		
			SCS72_1		
			INT13_2		
53	-	-	P72	F	J
			SIN2_0		
			TIOA6_0		
			INT14_2		
54	-	-	P73	F	J
			SOT2_0		
			TIOB6_0		
			INT15_2		
55	-	-	P74	F	I
			SCK2_0		
56	46	36	PE0	C	D
			MD1		
57	47	37	MD0	J	M
58	48	38	PE2	A	A
			X0		
59	49	39	PE3	A	B
			X1		
60	50	40	VSS	-	-
61	51	41	VCC	-	-
62	52	42	P10	P	K
			IC1_CLK_1		
			CTS1_1		
			AN00		
			SEG27		
63	53	43	P11	P	W
			IC1_VCC_1		
			SIN1_1		
			FRCK0_2		
			INT02_1		
			WKUP1		
			AN01		
			SEG26		

Pin No.			Pin Name	I/O Circuit Type	Pin State Type
LQFP-120	LQFP-100	LQFP-80			
64	54	44	P12	P	K
			IC1_VPEN_1		
			SOT1_1		
			IC00_2		
			AN02		
			SEG25		
65	55	45	P13	P	K
			IC1_RST_1		
			SCK1_1		
			RTCCO_1		
			IC01_2		
			SUBOUT_1		
			AN03		
66	56	46	SEG24	P	V
			P14		
			IC1_DATA_1		
			RTS1_1		
			SIN0_1		
			IC02_2		
			INT03_1		
67	57	47	AN04	P	V
			SEG23		
			P15		
			IC1_CIN_1		
			SOT0_1		
			IC03_2		
			INT14_0		
68	58	48	AN05	P	V
			SEG22		
			P16		
			SCK0_1		
			INT15_0		
69	59	49	AN06	P	V
			SEG21		
			P17		
			SIN2_2		
			INT04_1		
70	60	50	AN07	P	K
71	61	51	SEG20		
72	62	52	AVCC		
73	63	53	AVSS		
			AVRL		
			AVRH	P	K
74	64	54	P18		
			SOT2_2		
			AN08		
			SEG19		
75	65	55	P19	P	K
			SCK2_2		
			IC00_1		
			AN09		
			SEG18		

Type	Circuit	Remarks
J		• CMOS level hysteresis input
K		It is possible to select the USB I/O / GPIO function. When the USB I/O is selected. • Full-speed, Low-speed control When the GPIO is selected. • CMOS level output • CMOS level hysteresis input • With standby mode control

Type	Circuit	Remarks
Q	 The circuit diagram for the Q pin shows a multi-functional input/output. The pin is connected to a pull-up resistor. The circuit includes a P-ch MOSFET for digital output, an N-ch MOSFET for digital output, a pull-up resistor control, a digital input with a pull-up resistor R, a standby mode control, an LCD VV input/output, and an LCD VV control.	• CMOS level output • CMOS level hysteresis input • With input control • 5 V tolerant • LCD VV input/output • With pull-up resistor control • With standby mode control • Pull-up resistor : Approximately 33 kΩ • $I_{OH} = -4 \text{ mA}$, $I_{OL} = 4 \text{ mA}$ • Available to control of PZR registers. • When this pin is used as an I²C pin, the digital output P-ch transistor is always off

Surface Mount Type

Surface mount packaging has longer and thinner leads than lead-insertion packaging, and therefore leads are more easily deformed or bent. The use of packages with higher pin counts and narrower pin pitch results in increased susceptibility to open connections caused by deformed pins, or shorting due to solder bridges.

You must use appropriate mounting techniques. Spansion recommends the solder reflow method, and has established a ranking of mounting conditions for each product. Users are advised to mount packages in accordance with Spansion ranking of recommended conditions.

Lead-Free Packaging

CAUTION: When ball grid array (BGA) packages with Sn-Ag-Cu balls are mounted using Sn-Pb eutectic soldering, junction strength may be reduced under some conditions of use.

Storage of Semiconductor Devices

Because plastic chip packages are formed from plastic resins, exposure to natural environmental conditions will cause absorption of moisture. During mounting, the application of heat to a package that has absorbed moisture can cause surfaces to peel, reducing moisture resistance and causing packages to crack. To prevent, do the following:

- (1) Avoid exposure to rapid temperature changes, which cause moisture to condense inside the product.
Store products in locations where temperature changes are slight.
- (2) Use dry boxes for product storage. Products should be stored below 70% relative humidity, and at temperatures between 5 °C and 30 °C.
When you open Dry Package that recommends humidity 40% to 70% relative humidity.
- (3) When necessary, Spansion packages semiconductor devices in highly moisture-resistant aluminum laminate bags, with a silica gel desiccant. Devices should be sealed in their aluminum laminate bags for storage.
- (4) Avoid storing packages where they are exposed to corrosive gases or high levels of dust.

Baking

Packages that have absorbed moisture may be de-moisturized by baking (heat drying). Follow the Spansion recommended conditions for baking.

Condition: 125°C/24 h

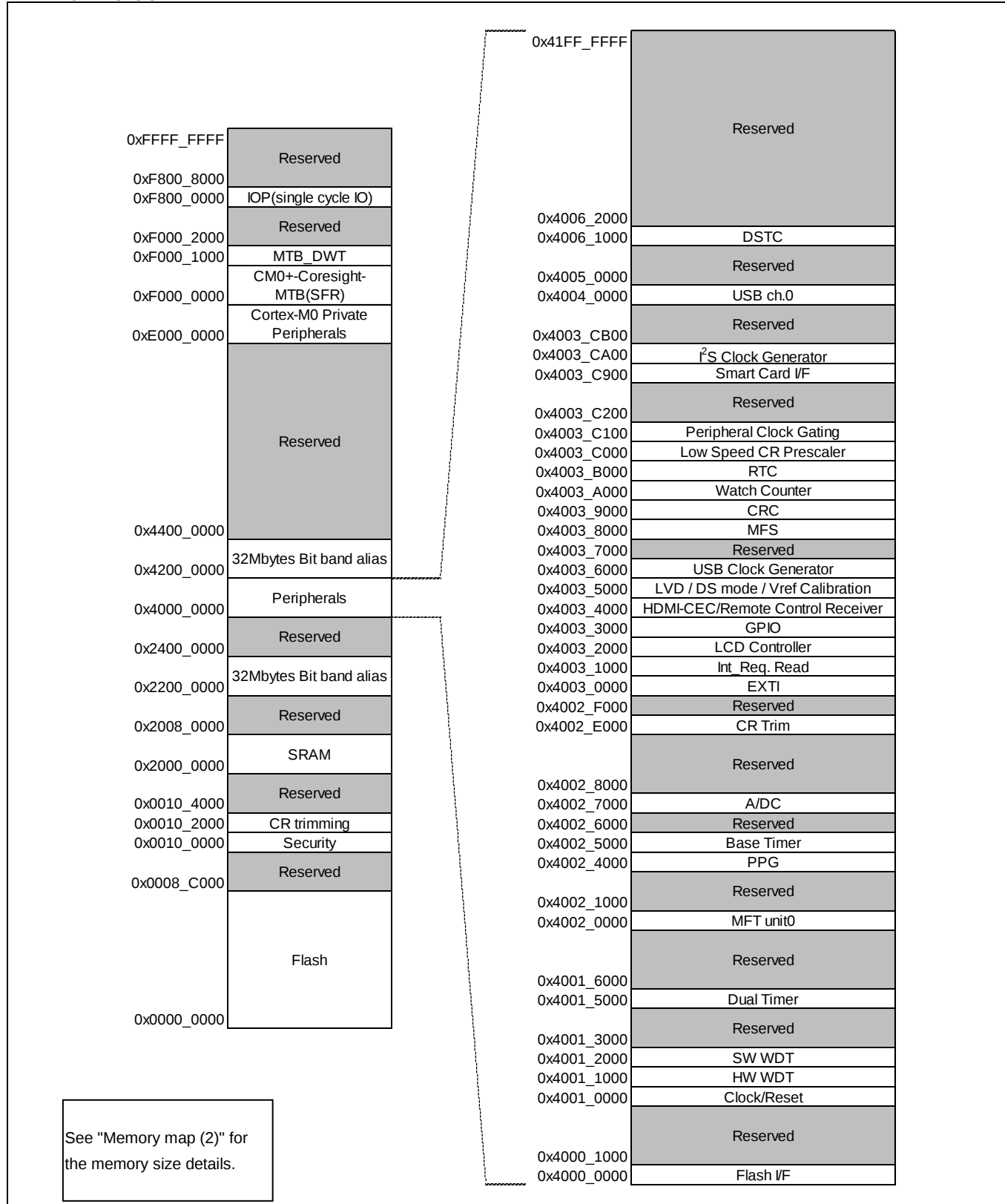
Static Electricity

Because semiconductor devices are particularly susceptible to damage by static electricity, you must take the following precautions:

- (1) Maintain relative humidity in the working environment between 40% and 70%.
Use of an apparatus for ion generation may be needed to remove electricity.
- (2) Electrically ground all conveyors, solder vessels, soldering irons and peripheral equipment.
- (3) Eliminate static body electricity by the use of rings or bracelets connected to ground through high resistance (on the level of 1 MΩ).
Wearing of conductive clothing and shoes, use of conductive floor mats and other measures to minimize shock loads is recommended.
- (4) Ground all fixtures and instruments, or protect with anti-static measures.
- (5) Avoid the use of styrofoam or other highly static-prone materials for storage of completed board assemblies.

9. Memory Map

Memory Map (1)



10. Pin Status in Each CPU State

The terms used for pin status have the following meanings.

■ INITX=0

This is the period when the INITX pin is the "L" level.

■ INITX=1

This is the period when the INITX pin is the "H" level.

■ SPL=0

This is the status that the standby pin level setting bit (SPL) in the Standby Mode Control Register (STB_CTL) is set to "0".

■ SPL=1

This is the status that the standby pin level setting bit (SPL) in the Standby Mode Control Register (STB_CTL) is set to "1".

■ Input enabled

Indicates that the input function can be used.

■ Internal input fixed at "0"

This is the status that the input function cannot be used. Internal input is fixed at "L".

■ Hi-Z

Indicates that the pin drive transistor is disabled and the pin is put in the Hi-Z state.

■ Setting disabled

Indicates that the setting is disabled.

■ Maintain previous state

Maintains the state in which a pin was immediately prior to entering the current mode.
If a built-in peripheral function is operating, the output follows the peripheral function.
If the pin is being used as a port, that output is maintained.

■ Analog input is enabled

Indicates that the analog input is enabled.

■ Trace output

Indicates that the trace function can be used.

■ GPIO selected

In Deep standby mode, pins switch to the general-purpose I/O port.

11.3 DC Characteristics

11.3.1 Current Rating

Symbol (Pin Name)	Conditions		HCLK Frequency ^{*4}	Value		Unit	Remarks
				Typ ^{*1}	Max ^{*2}		
I _{CC} (VCC)	Run mode, code executed from Flash	4 MHz external clock input, PLL ON ^{*8} NOP code executed Built-in high speed CR stopped All peripheral clock stopped by CKENx	4 MHz	0.7	TBD	mA	*3
			8 MHz	1.15	TBD		
			20 MHz	2.25	TBD		
			40 MHz	4.5	TBD		
		4 MHz external clock input, PLL ON ^{*8} Benchmark code executed Built-in high speed CR stopped PCLK1 stopped	4 MHz	0.75	TBD	mA	*3
			8 MHz	1.25	TBD		
			20 MHz	2.5	TBD		
			40 MHz	5.0	TBD		
		4 MHz crystal oscillation, PLL ON ^{*8} NOP code executed Built-in high speed CR stopped All peripheral clock stopped by CKENx	4 MHz	0.8	TBD	mA	*3
			8 MHz	1.4	TBD		
			20 MHz	2.75	TBD		
			40 MHz	5.5	TBD		
	Run mode, code executed from RAM	4 MHz external clock input, PLL ON ^{*8} NOP code executed Built-in high speed CR stopped All peripheral clock stopped by CKENx	4 MHz	0.6	TBD	mA	*3
			8 MHz	1.2	TBD		
			20 MHz	2.4	TBD		
			40 MHz	4.8	TBD		
	Run mode, code executed from Flash	4 MHz external clock input, PLL ON NOP code executed Built-in high speed CR stopped PCLK1 stopped	40 MHz	2.6	TBD	mA	*3,*6,*7
	Run mode, code executed from Flash	Built-in high speed CR ^{*5} NOP code executed All peripheral clock stopped by CKENx	4 MHz	1.2	TBD	mA	*3
		32 kHz crystal oscillation NOP code executed All peripheral clock stopped by CKENx	32 kHz	96	TBD		
		Built-in low speed CR NOP code executed All peripheral clock stopped by CKENx	100 kHz	120	TBD		
I _{CCS} (VCC)	Sleep operation	4 MHz external clock input, PLL ON ^{*8} All peripheral clock stopped by CKENx	4 MHz	0.6	TBD	mA	*3
			8 MHz	1.1	TBD		
			20 MHz	1.9	TBD		
			40 MHz	3.2	TBD		
		Built-in high speed CR ^{*5} All peripheral clock stopped by CKENx	4 MHz	0.5	TBD	mA	*3
		32 kHz crystal oscillation All peripheral clock stopped by CKENx	32 kHz	94	TBD		
		Built-in low speed CR All peripheral clock stopped by CKENx	100 kHz	105	TBD		

*1 : T_A=+25°C, V_{CC}=3.3 V

*2 : T_A=+105°C, V_{CC}=3.6 V

*3 : All ports are fixed

*4 : PCLK0 is set to divided rate 8

*5 : The frequency is set to 4 MHz by trimming

*6 : Flash sync down is set to FRWTR.RWT=11 and FSYNDN.SD=1111

*7 : VCC=1.65 V

*8 : When HCLK=4 MHz, PLL OFF

Parameter	Symbol (Pin Name)	Conditions			Value		Unit	Remarks
					Typ	Max		
Power supply current	I _{CC} HD (VCC)	Deep standby Stop mode	RAM off	T _A =25°C V _{CC} =3.3 V	0.75	TBD	μA	*1
				T _A =25°C V _{CC} =1.65 V	0.7	TBD	μA	*1
				T _A =105°C V _{CC} =3.6 V	-	TBD	μA	*1
			RAM on	T _A =25°C V _{CC} =3.3 V	1.1	TBD	μA	*1
				T _A =25°C V _{CC} =1.65 V	1.0	TBD	μA	*1
				T _A =105°C V _{CC} =3.6 V	-	TBD	μA	*1
	I _{CC} RD (VCC)	Deep standby RTC mode	RAM off	T _A =25°C V _{CC} =3.3 V	1.7	TBD	μA	*1
				T _A =25°C V _{CC} =1.65 V	1.6	TBD	μA	*1
				T _A =105°C V _{CC} =3.6 V	-	TBD	μA	*1
			RAM on	T _A =25°C V _{CC} =3.3 V	1.9	TBD	μA	*1
				T _A =25°C V _{CC} =1.65 V	1.7	TBD	μA	*1
				T _A =105°C V _{CC} =3.6 V	-	TBD	μA	*1

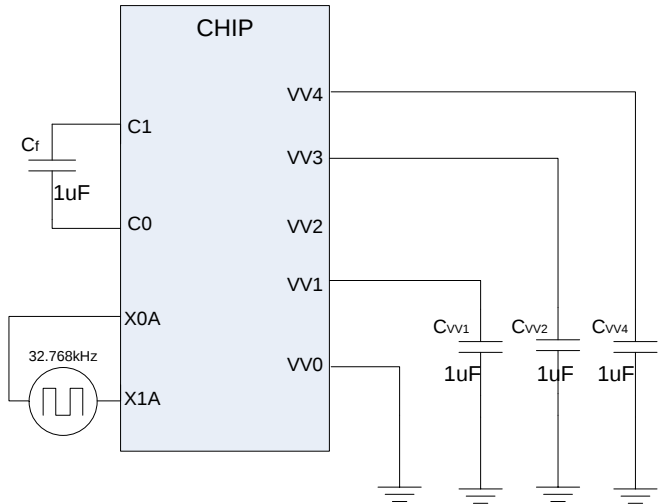
*1: All ports are fixed. LVD off.

11.3.3 LCD Characteristic

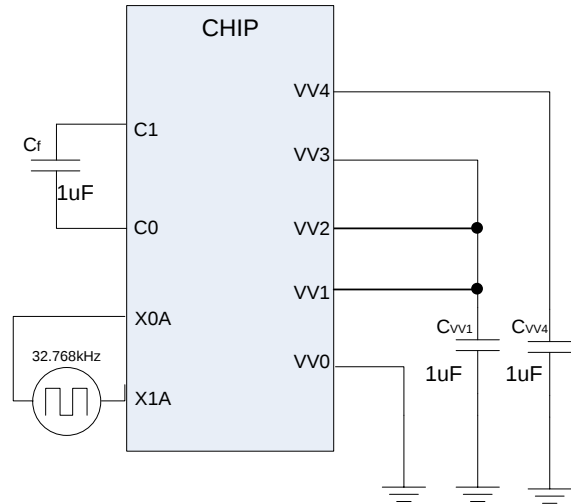
11.3.3.1 LCD Characteristic Without Booster

($V_{CC}=AV_{CC}=1.65\text{ V to }3.6\text{ V}$, $V_{SS}=AV_{SS}=0\text{ V}$, $T_A=-40^{\circ}\text{C to }+105^{\circ}\text{C}$)

Parameter	Symbol	Pin Name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
VV0 to VV3 output voltage (1/4 bias)	V _{VV0}	VV0	When using internal dividing register	0	-	$V_{VV4} \times 5\%$	V	
	V _{VV1}	VV1		$V_{VV4} \times 1/4$ -10%	-	$V_{VV4} \times 1/4$ +10%		
	V _{VV2}	VV2		$V_{VV4} \times 1/2$ -10%	-	$V_{VV4} \times 1/2$ +10%		
	V _{VV3}	VV3		$V_{VV4} \times 3/4$ -10%	-	$V_{VV4} \times 3/4$ +10%		
VV0 to VV3 output voltage (1/3 bias)	V _{VV0}	VV0	When using internal dividing register	0	-	$V_{VV4} \times 5\%$	V	
	V _{VV1}	VV1		$V_{VV4} \times 1/3$ -10%	-	$V_{VV4} \times 1/3$ +10%		
	V _{VV2}	VV2		$V_{VV4} \times 2/3$ -10%	-	$V_{VV4} \times 2/3$ +10%		
	V _{VV3}	VV3		$V_{VV4} \times 2/3$ -10%	-	$V_{VV4} \times 2/3$ +10%		
VV0 to VV3 output voltage (1/2 bias)	V _{VV0}	VV0	When using internal dividing register	0	-	$V_{VV4} \times 5\%$	V	
	V _{VV1}	VV1		$V_{VV4} \times 1/2$ -10%	-	$V_{VV4} \times 1/2$ +10%		
	V _{VV2}	VV2		$V_{VV4} \times 1/2$ -10%	-	$V_{VV4} \times 1/2$ +10%		
	V _{VV3}	VV3		$V_{VV4} \times 1/2$ -10%	-	$V_{VV4} \times 1/2$ +10%		
VV4 Active current (1/4 bias)	I _{R100K}	VV4	When using 100 kΩ internal dividing resistor	-	10	TBD	μA	
	I _{R10K}	VV4	When using 10 kΩ internal dividing resistor	-	100	TBD	μA	
VV4 Active current (1/3 bias)	I _{R100K}	VV4	When using 100 kΩ internal dividing resistor	-	12	TBD	μA	
	I _{R10K}	VV4	When using 10 kΩ internal dividing resistor	-	120	TBD	μA	
VV4 Active current (1/2 bias)	I _{R100K}	VV4	When using 100 kΩ internal dividing resistor	-	18	TBD	μA	
	I _{R10K}	VV4	When using 10 kΩ internal dividing resistor	-	180	TBD	μA	
VV4 static current	I _{OFF_VV4}	VV4	When LCD stops	-	0.5	TBD	μA	
VV0 output voltage in using external resistor	V _{VV0E}	VV0	I _{OL} =1 mA	-	-	0.66	V	



LCD Booster 1/3 mode (BIAS[1:0]=2'b01)

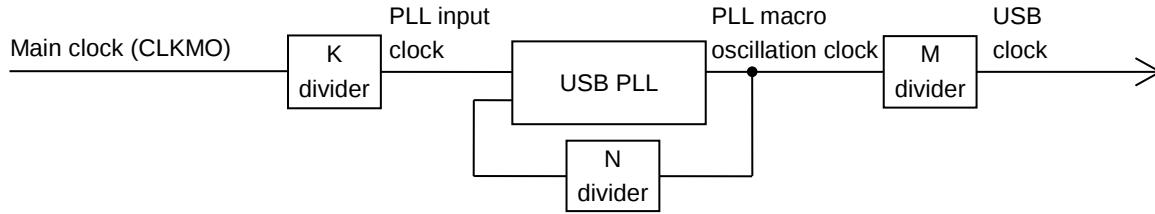


LCD Booster 1/2 mode (BIAS[1:0]=2'b00)

DC Electrical Specifications of Internal reference output voltage setting

 ($V_{CC} = AV_{CC} = 1.65 \text{ V to } 3.6 \text{ V}$, $V_{SS} = AV_{SS} = 0 \text{ V}$, $T_A = -40^\circ\text{C to } +105^\circ\text{C}$)

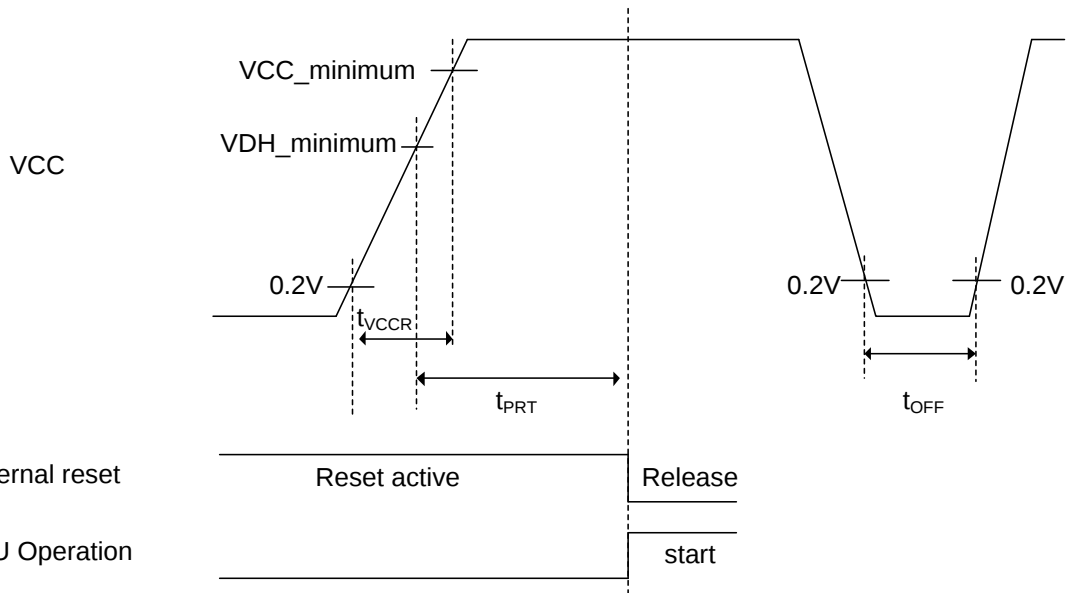
Parameter	Symbol	Pin Name	Conditions		Value			Unit	Remarks
			TRC[1:0] ^{*1}	TRF[3:0] ^{*1}	Min	Typ	Max		
Internal reference output voltage setting	VV1A	VV1	00	1010	0.89	1.00	1.11	V	BIAS[1:0]=10 ^{*4} Other BIAS[1:0] setting is inhibited
			00	1011	0.94	1.05	1.16		
			00	1100	0.99	1.10	1.21		
			00	1101	1.03	1.15	1.27		
			00	1110	1.07	1.20	1.38		
			01	0111	1.11	1.25	1.38	V	BIAS[1:0]=01 ^{*3} Other BIAS[1:0] setting is inhibited
			01	1000	1.16	1.30	1.44		
			01	1001	1.20	1.35	1.49		
			01	1010	1.25	1.40	1.55		
			01	1011	1.30	1.45	1.60		
			01	1100	1.34	1.50	1.65		
			01	1101	1.39	1.55	1.71		
			01	1110	1.44	1.60	1.76		
			10	0101	1.46	1.65	1.83	V	BIAS[1:0]=00 ^{*2} Other BIAS[1:0] setting is inhibited
			10	1100	1.79	2.00	2.21		
			10	1101	1.84	2.05	2.26		
			10	1110	1.89	2.10	2.32		
			11	0010	1.85	2.15	2.39		
			11	0011	1.90	2.20	2.44		

USB PLL connection

11.4.6 Reset Input Characteristics
 $(V_{CC}=AV_{CC}=1.65\text{ V to }3.6\text{ V}, V_{SS}=AV_{SS}=0\text{ V}, T_A=-40^{\circ}\text{C to }+105^{\circ}\text{C})$

Parameter	Symbol	Pin Name	Conditions	Value		Unit	Remarks
				Min	Max		
Reset input time	t_{INITX}	INITX	-	500	-	ns	

11.4.7 Power-on Reset Timing
 $(V_{CC}=AV_{CC}=1.65\text{ V to }3.6\text{ V}, V_{SS}=AV_{SS}=0\text{ V}, T_A=-40^{\circ}\text{C to }+105^{\circ}\text{C})$

Parameter	Symbol	Pin Name	Value		Unit	Remarks
			Min	Max		
Power supply rising time	t_{VCCR}	VCC	0	-	ms	
Power supply shut down time	t_{OFF}		1	-	ms	
Time until releasing Power-on reset	t_{PRT}		0.43	3.4	ms	

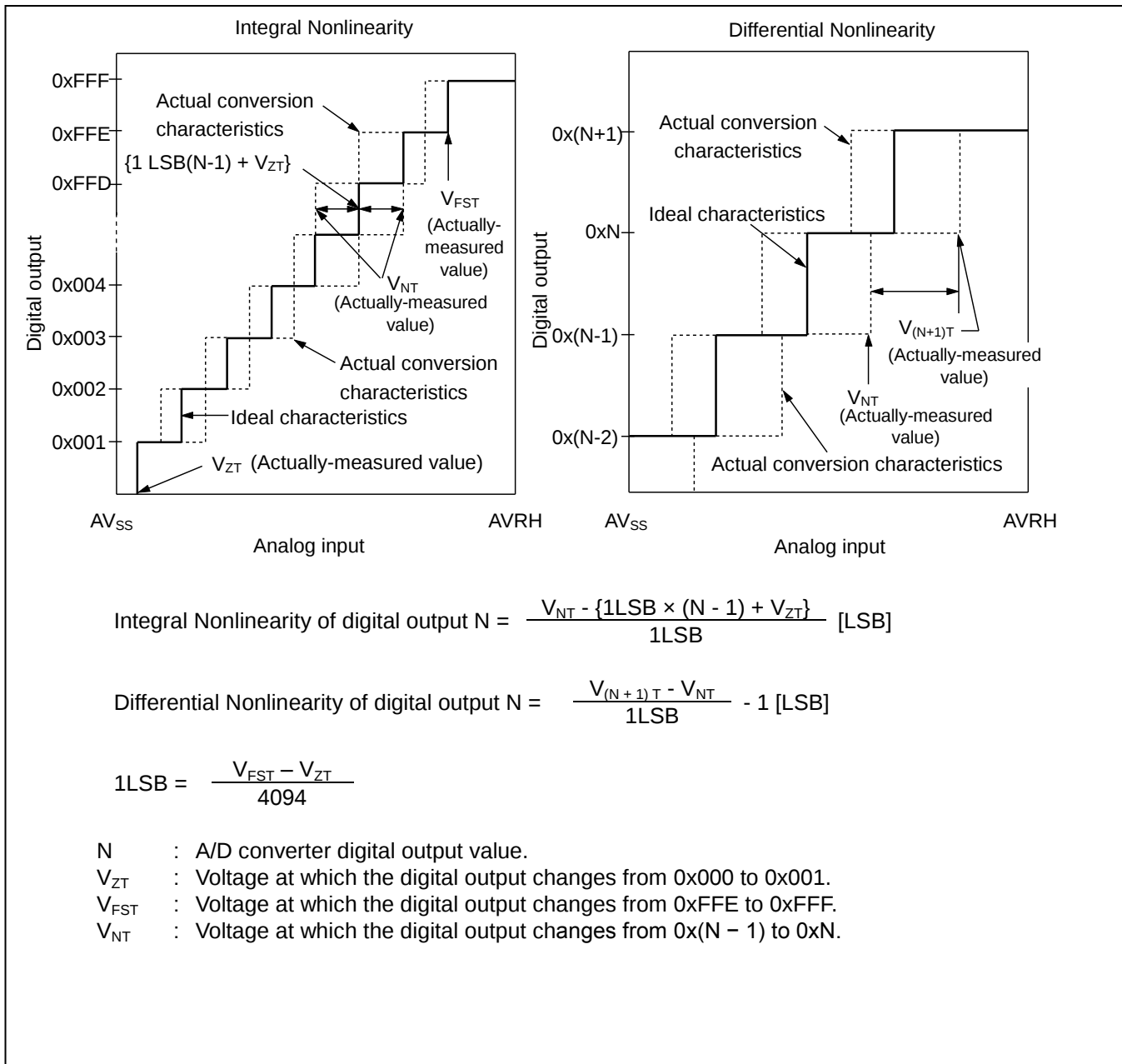

Glossary

- $V_{CC_minimum}$: Minimum V_{CC} of recommended operating conditions.
- $VDH_minimum$: Minimum detection voltage of Low-Voltage detection reset.

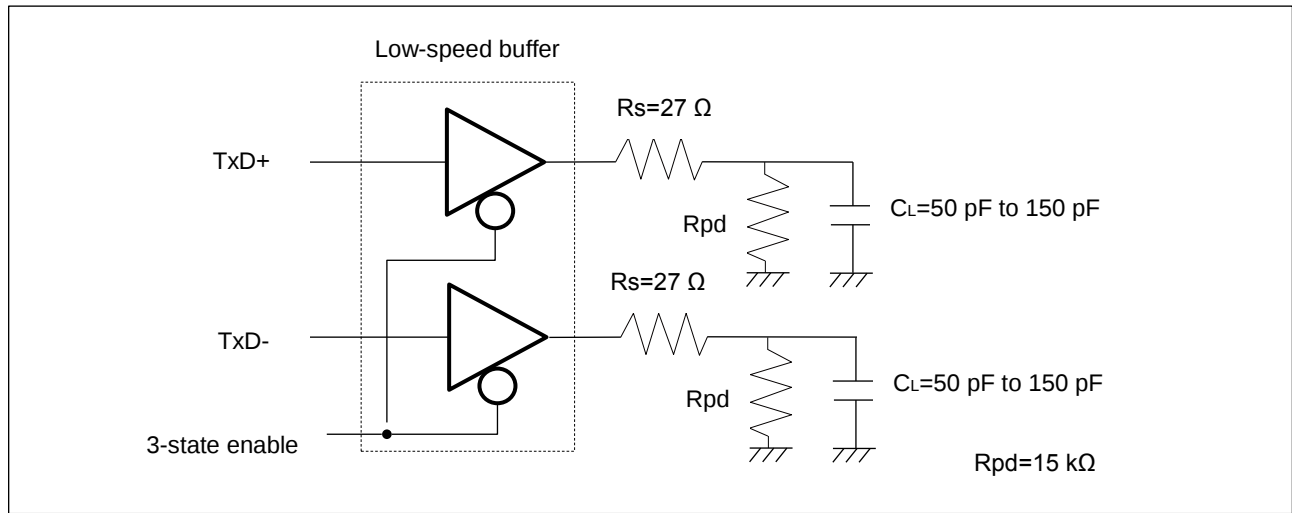
See "11.7 Low-Voltage Detection Characteristics".

Definitions of 12-bit A/D Converter Terms

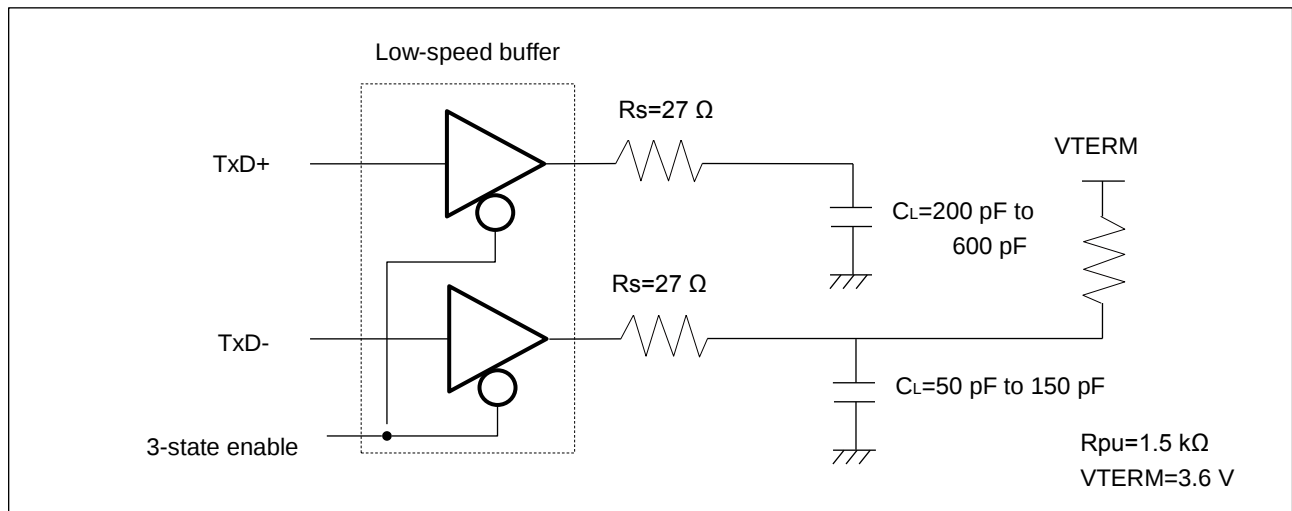
- Resolution: Analog variation that is recognized by an A/D converter.
- Integral Nonlinearity: Deviation of the line between the zero-transition point (0b000000000000 $\longleftrightarrow$ 0b000000000001) and the full-scale transition point (0b111111111110 $\longleftrightarrow$ 0b111111111111) from the actual conversion characteristics.
- Differential Nonlinearity: Deviation from the ideal value of the input voltage that is required to change the output code by 1 LSB.



• Low-Speed Load (Upstream Port Load) – Reference 1



• Low-Speed Load (Downstream Port Load) – Reference 2



11.8 Flash Memory Write/Erase Characteristics

 (V_{CC}=1.65 V to 3.6 V, T_A=- 40°C to +105°C)

Parameter		Value			Unit	Remarks
		Min	Typ*	Max*		
Sector erase time	Large sector	-	1.1	2.7	s	The sector erase time includes the time of writing prior to internal erase.
	Small sector	-	0.3	0.9		
Halfword (16-bit) write time		-	30	528	μs	The halfword (16-bit) write time excludes the system-level overhead.
Chip erase time		-	11.2	28.8	s	The chip erase time includes the time of writing prior to internal erase.

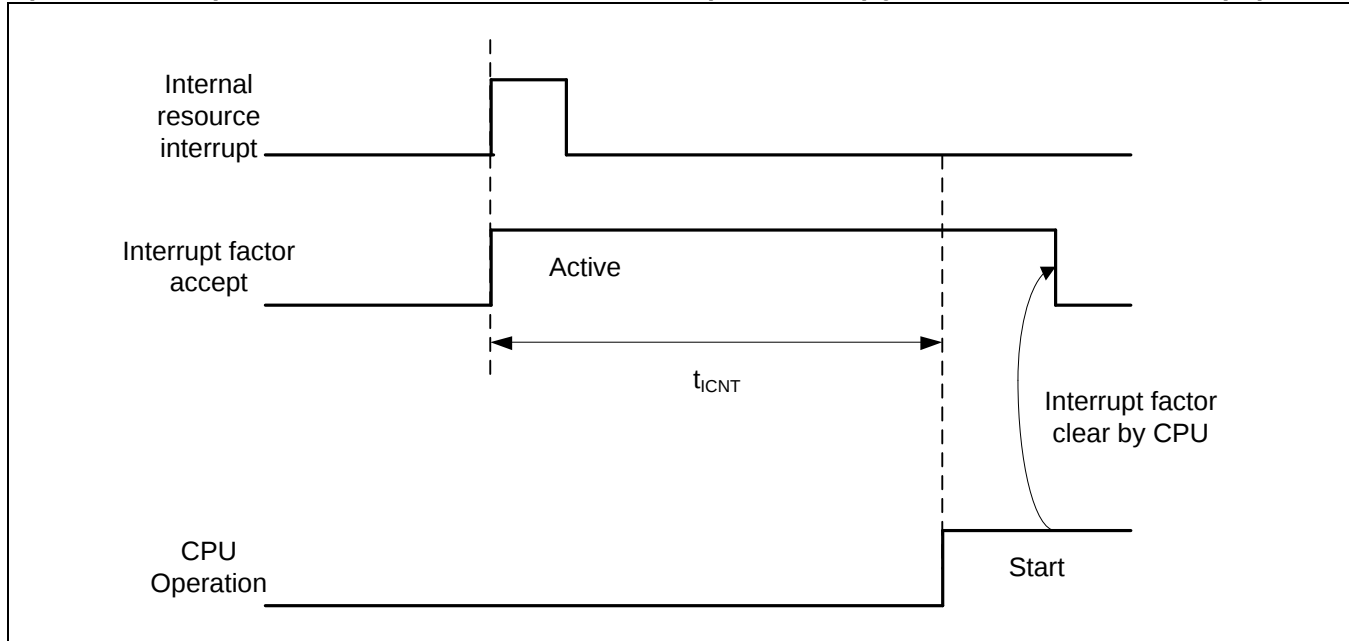
*: The typical value is immediately after shipment, the maximum value is guarantee value under 10,000 cycle of erase/write.

Write/Erase Cycle and Data Hold Time (Target Value)

Write/Erase Cycle	Data Hold Time (Year)	Remarks
1,000	20*	
10,000	10*	

*: At average + 85°C

Operation Example of Return from Low-Power Consumption Mode (by Internal Resource Interrupt*)



*: Internal resource interrupt is not included in return factor by the kind of Low-Power consumption mode.

Notes:

- The return factor is different in each Low-Power consumption modes.
See "Chapter: Low Power Consumption Mode" and "Operations of Standby Modes" in FM0+ Family Peripheral Manual.
- When interrupt recovers, the operation mode that CPU recovers depends on the state before the Low-Power consumption mode transition. See "Chapter: Low Power Consumption Mode" in "FM0+ Family Peripheral Manual".

Document History

Document Title: S6E1B8 Series 32-bit ARM® Cortex®-M0+ FM0+ Microcontroller

Document Number: 001-99223

Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	4889752	TEKA	08/31/2015	New Spec.