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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

| | |
|----------------------------|---|
| Product Status | Active |
| Core Processor | ARM® Cortex®-M3 |
| Core Size | 32-Bit Single-Core |
| Speed | 32MHz |
| Connectivity | I ² C, IrDA, LINbus, SPI, UART/USART, USB |
| Peripherals | Brown-out Detect/Reset, DMA, I ² S, LCD, POR, PWM, WDT |
| Number of I/O | 83 |
| Program Memory Size | 256KB (256K x 8) |
| Program Memory Type | FLASH |
| EEPROM Size | 8K x 8 |
| RAM Size | 32K x 8 |
| Voltage - Supply (Vcc/Vdd) | 1.8V ~ 3.6V |
| Data Converters | A/D 25x12b; D/A 2x12b |
| Oscillator Type | Internal |
| Operating Temperature | -40°C ~ 85°C (TA) |
| Mounting Type | Surface Mount |
| Package / Case | 100-UFBGA |
| Supplier Device Package | 100-UFBGA (7x7) |
| Purchase URL | https://www.e-xfl.com/product-detail/stmicroelectronics/stm32l162vch6tr |

2 Description

The ultra-low-power STM32L162xC devices incorporate the connectivity power of the universal serial bus (USB) with the high-performance ARM® Cortex®-M3 32-bit RISC core operating at a frequency of 32 MHz (33.3 DMIPS), a memory protection unit (MPU), high-speed embedded memories (Flash memory up to 256 Kbytes and RAM up to 32 Kbytes) and an extensive range of enhanced I/Os and peripherals connected to two APB buses.

The STM32L162xC devices offer two operational amplifiers, one 12-bit ADC, two DACs, two ultra-low-power comparators, AES, one general-purpose 32-bit timer, six general-purpose 16-bit timers and two basic timers, which can be used as time bases.

Moreover, the STM32L162xC devices contain standard and advanced communication interfaces: up to two I2Cs, three SPIs, two I2S, three USARTs and an USB. The STM32L162xC devices offer up to 23 capacitive sensing channels to simply add a touch sensing functionality to any application.

They also include a real-time clock and a set of backup registers that remain powered in Standby mode.

Finally, the integrated LCD controller has a built-in LCD voltage generator that allows to drive up to 8 multiplexed LCDs with the contrast independent of the supply voltage.

The ultra-low-power STM32L162xC devices operate from a 1.8 to 3.6 V power supply (down to 1.65 V at power down) with BOR and from a 1.65 to 3.6 V power supply without BOR option. They are available in the -40 to +85 °C and -40 to +105 °C temperature ranges. A comprehensive set of power-saving modes allows the design of low-power applications.



Table 5. Functionalities depending on the working mode (from Run/active down to standby) (continued)

| Ips | Run/Active | Sleep | Low-power Run | Low-power Sleep | Stop | | Standby | |
|--|--------------------------------------|---------------------------------------|---------------------|---------------------|---|-------------------|---|-------------------|
| | | | | | | Wakeup capability | | Wakeup capability |
| ADC | Y | Y | -- | -- | -- | -- | -- | -- |
| DAC | Y | Y | Y | Y | Y | -- | -- | -- |
| Tempsensor | Y | Y | Y | Y | Y | -- | -- | -- |
| OP amp | Y | Y | Y | Y | Y | -- | -- | -- |
| Comparators | Y | Y | Y | Y | Y | Y | -- | -- |
| 16-bit and 32-bit Timers | Y | Y | Y | Y | -- | -- | -- | -- |
| IWDG | Y | Y | Y | Y | Y | Y | Y | Y |
| WWDG | Y | Y | Y | Y | -- | -- | -- | -- |
| Touch sensing | Y | Y | -- | -- | -- | -- | -- | -- |
| Systic Timer | Y | Y | Y | Y | | -- | -- | -- |
| GPIOs | Y | Y | Y | Y | Y | Y | -- | 3 pins |
| Wakeup time to Run mode | 0 μ s | 0.4 μ s | 3 μ s | 46 μ s | < 8 μ s | | 58 μ s | |
| Consumption $V_{DD}=1.8$ to 3.6 V (Typ) | Down to 185 μ A/MHz (from Flash) | Down to 34.5 μ A/MHz (from Flash) | Down to 8.6 μ A | Down to 4.4 μ A | 0.43 μ A (no RTC) $V_{DD}=1.8$ V | | 0.29 μ A (no RTC) $V_{DD}=1.8$ V | |
| | | | | | 1.15 μ A (with RTC) $V_{DD}=1.8$ V | | 0.9 μ A (with RTC) $V_{DD}=1.8$ V | |
| | | | | | 0.44 μ A (no RTC) $V_{DD}=3.0$ V | | 0.29 μ A (no RTC) $V_{DD}=3.0$ V | |
| | | | | | 1.4 μ A (with RTC) $V_{DD}=3.0$ V | | 1.15 μ A (with RTC) $V_{DD}=3.0$ V | |

1. The startup on communication line wakes the CPU which was made possible by an EXTI, this induces a delay before entering run mode.

3.2 ARM[®] Cortex[®]-M3 core with MPU

The ARM[®] Cortex[®]-M3 processor is the industry leading processor for embedded systems. It has been developed to provide a low-cost platform that meets the needs of MCU implementation, with a reduced pin count and low-power consumption, while delivering outstanding computational performance and an advanced system response to interrupts.

The ARM[®] Cortex[®]-M3 32-bit RISC processor features exceptional code-efficiency, delivering the high-performance expected from an ARM core in the memory size usually associated with 8- and 16-bit devices.

3.7 Memories

The STM32L162xC devices have the following features:

- 32 Kbytes of embedded RAM accessed (read/write) at CPU clock speed with 0 wait states. With the enhanced bus matrix, operating the RAM does not lead to any performance penalty during accesses to the system bus (AHB and APB buses).
- The non-volatile memory is divided into three arrays:
 - 256 Kbytes of embedded Flash program memory
 - 8 Kbytes of data EEPROM
 - Options bytes

The options bytes are used to write-protect or read-out protect the memory (with 4 Kbytes granularity) and/or readout-protect the whole memory with the following options:

- Level 0: no readout protection
- Level 1: memory readout protection, the Flash memory cannot be read from or written to if either debug features are connected or boot in RAM is selected
- Level 2: chip readout protection, debug features (ARM Cortex-M3 JTAG and serial wire) and boot in RAM selection disabled (JTAG fuse)

The whole non-volatile memory embeds the error correction code (ECC) feature.

The user area of the Flash memory can be protected against Dbus read access by PCROP feature (see RM0038 for details).

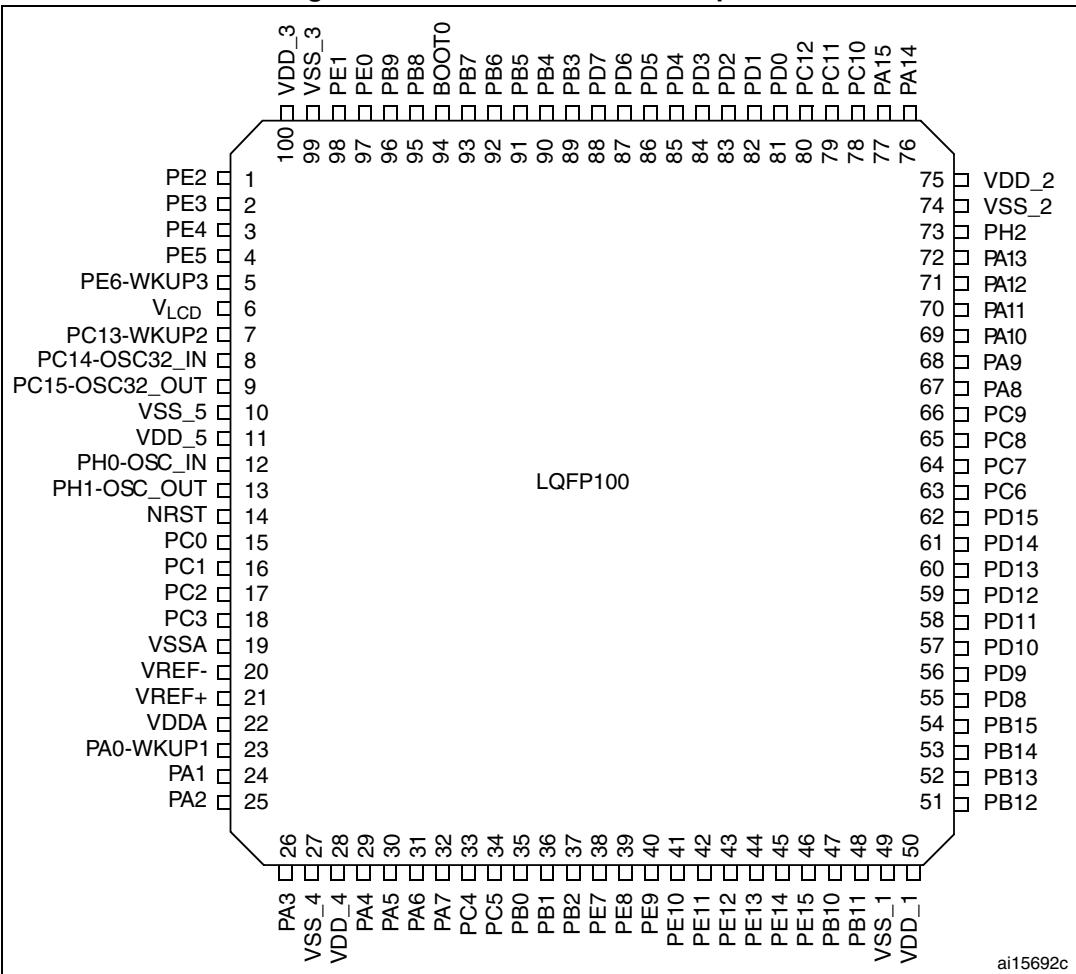
3.8 DMA (direct memory access)

The flexible 12-channel, general-purpose DMA is able to manage memory-to-memory, peripheral-to-memory and memory-to-peripheral transfers. The DMA controller supports circular buffer management, avoiding the generation of interrupts when the controller reaches the end of the buffer.

Each channel is connected to dedicated hardware DMA requests, with software trigger support for each channel. Configuration is done by software and transfer sizes between source and destination are independent.

The DMA can be used with the main peripherals: AES, SPI, I²C, USART, general-purpose timers, DAC and ADC.

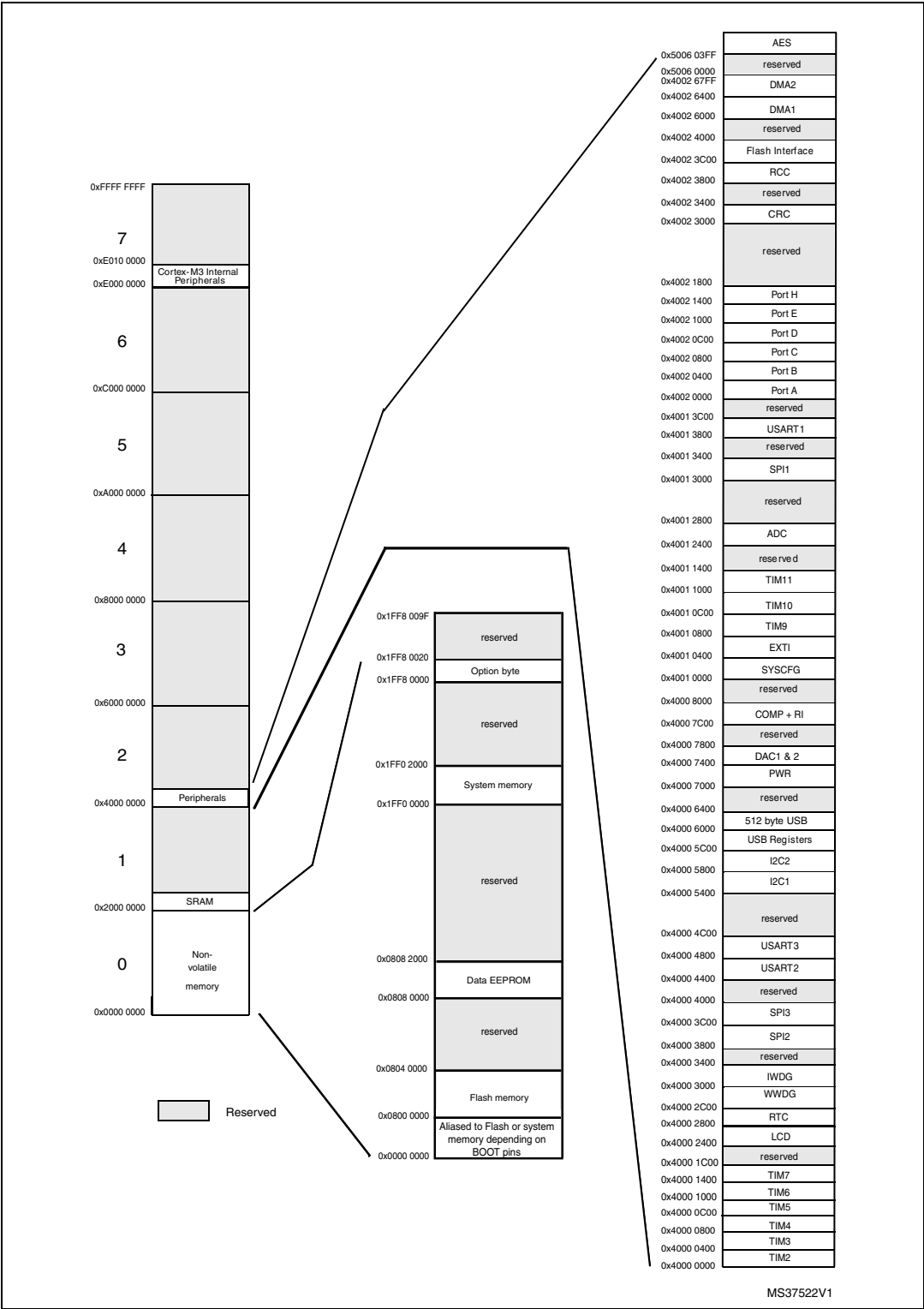
Figure 4. STM32L162VC LQFP100 pinout



1. This figure shows the package top view.

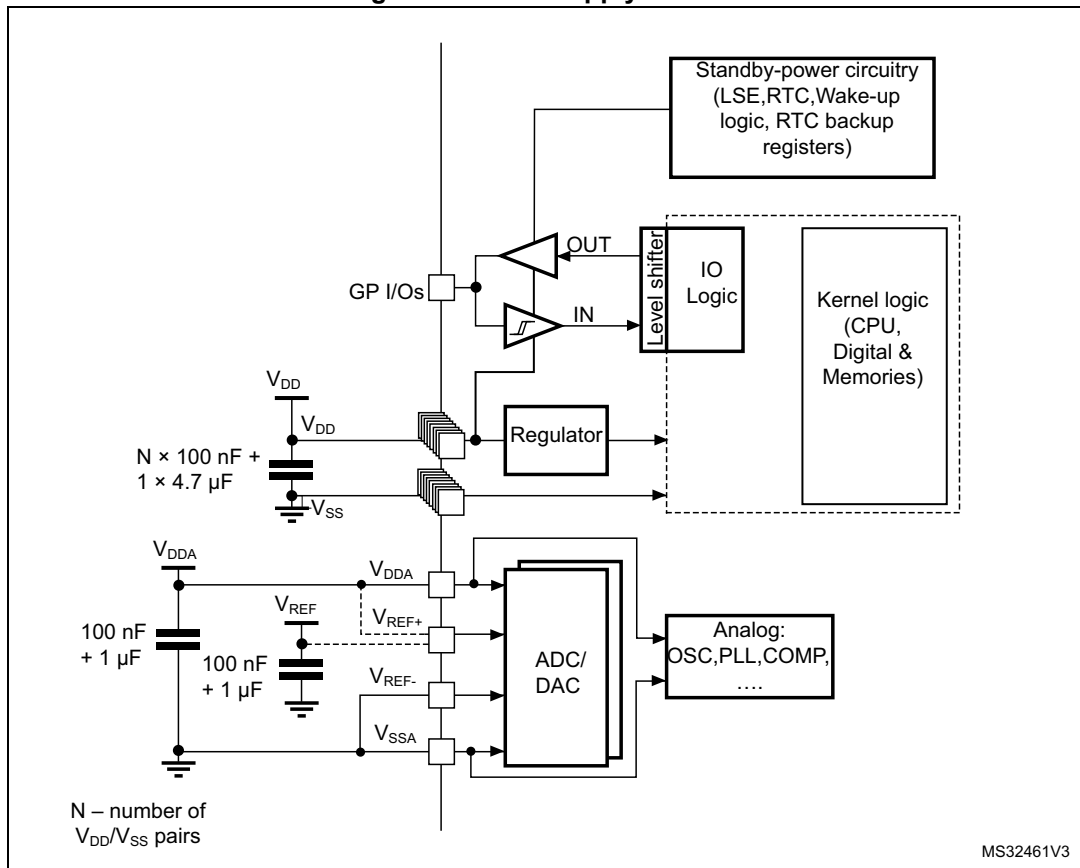
5 Memory mapping

Figure 6. Memory map



6.1.6 Power supply scheme

Figure 9. Power supply scheme



4. Positive current injection is not possible on these I/Os. A negative injection is induced by $V_{IN} < V_{SS}$. $I_{INJ(PIN)}$ must never be exceeded. Refer to [Table 11](#) for maximum allowed input voltage values.
5. A positive injection is induced by $V_{IN} > V_{DD}$ while a negative injection is induced by $V_{IN} < V_{SS}$. $I_{INJ(PIN)}$ must never be exceeded. Refer to [Table 11: Voltage characteristics](#) for the maximum allowed input voltage values.
6. When several inputs are submitted to a current injection, the maximum $\Sigma I_{INJ(PIN)}$ is the absolute sum of the positive and negative injected currents (instantaneous values).

Table 13. Thermal characteristics

| Symbol | Ratings | Value | Unit |
|-----------|------------------------------|-------------|------|
| T_{STG} | Storage temperature range | -65 to +150 | °C |
| T_J | Maximum junction temperature | 150 | °C |

6.3 Operating conditions

6.3.1 General operating conditions

Table 14. General operating conditions

| Symbol | Parameter | Conditions | Min | Max | Unit |
|-----------------|---|--|------|---------------------|------|
| f_{HCLK} | Internal AHB clock frequency | - | 0 | 32 | MHz |
| f_{PCLK1} | Internal APB1 clock frequency | - | 0 | 32 | |
| f_{PCLK2} | Internal APB2 clock frequency | - | 0 | 32 | |
| V_{DD} | Standard operating voltage | BOR detector disabled | 1.65 | 3.6 | V |
| | | BOR detector enabled, at power on | 1.8 | 3.6 | |
| | | BOR detector disabled, after power on | 1.65 | 3.6 | |
| $V_{DDA}^{(1)}$ | Analog operating voltage (ADC and DAC not used) | Must be the same voltage as $V_{DD}^{(2)}$ | 1.65 | 3.6 | V |
| | Analog operating voltage (ADC or DAC used) | | 1.8 | 3.6 | |
| V_{IN} | I/O input voltage | FT pins; $2.0\text{ V} \leq V_{DD}$ | -0.3 | 5.5 ⁽³⁾ | V |
| | | FT pins; $V_{DD} < 2.0\text{ V}$ | -0.3 | 5.25 ⁽³⁾ | |
| | | BOOT0 pin | 0 | 5.5 | |
| | | Any other pin | -0.3 | $V_{DD}+0.3$ | |
| P_D | Power dissipation at $T_A = 85\text{ °C}$ for suffix 6 or $T_A = 105\text{ °C}$ for suffix 7 ⁽⁴⁾ | LQFP48 package | - | 364 | mW |
| | | LQFP100 package | - | 465 | |
| | | LQFP64 package | - | 435 | |
| | | UFQFPN48 package | - | 625 | |
| | | UFBGA100 | - | 339 | |
| | | WLCSP63 package | - | 408 | |

Table 29. HSE oscillator characteristics⁽¹⁾⁽²⁾

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|------------------------------|--|---|-----|-----|------------------------------------|------------|
| f_{OSC_IN} | Oscillator frequency | - | 1 | | 24 | MHz |
| R_F | Feedback resistor | - | - | 200 | - | k Ω |
| C | Recommended load capacitance versus equivalent serial resistance of the crystal (R_S) ⁽³⁾ | $R_S = 30 \Omega$ | - | 20 | - | pF |
| I_{HSE} | HSE driving current | $V_{DD} = 3.3 V$, $V_{IN} = V_{SS}$ with 30 pF load | - | - | 3 | mA |
| $I_{DD(HSE)}$ | HSE oscillator power consumption | $C = 20 pF$ $f_{OSC} = 16 MHz$ | - | - | 2.5 (startup) 0.7 (stabilized) | mA |
| | | $C = 10 pF$ $f_{OSC} = 16 MHz$ | - | - | 2.5 (startup) 0.46 (stabilized) | |
| g_m | Oscillator transconductance | Startup | 3.5 | - | - | mA /V |
| $t_{SU(HSE)}$ ⁽⁴⁾ | Startup time | V_{DD} is stabilized | - | 1 | - | ms |

1. Resonator characteristics given by the crystal/ceramic resonator manufacturer.
2. Guaranteed by characterization results.
3. The relatively low value of the RF resistor offers a good protection against issues resulting from use in a humid environment, due to the induced leakage and the bias condition change. However, it is recommended to take this point into account if the MCU is used in tough humidity conditions.
4. $t_{SU(HSE)}$ is the startup time measured from the moment it is enabled (by software) to a stabilized 8 MHz oscillation is reached. This value is measured for a standard crystal resonator and it can vary significantly with the crystal manufacturer.

For C_{L1} and C_{L2} , it is recommended to use high-quality external ceramic capacitors in the 5 pF to 25 pF range (typ.), designed for high-frequency applications, and selected to match the requirements of the crystal or resonator (see [Figure 14](#)). C_{L1} and C_{L2} are usually the same size. The crystal manufacturer typically specifies a load capacitance which is the series combination of C_{L1} and C_{L2} . PCB and MCU pin capacitance must be included (10 pF can be used as a rough estimate of the combined pin and board capacitance) when sizing C_{L1} and C_{L2} . Refer to the application note AN2867 "Oscillator design guide for ST microcontrollers" available from the ST website www.st.com.

6.3.8 PLL characteristics

The parameters given in [Table 34](#) are derived from tests performed under the conditions summarized in [Table 14](#).

Table 34. PLL characteristics

| Symbol | Parameter | Value | | | Unit |
|------------------------|---|-------|-----|--------------------|------|
| | | Min | Typ | Max ⁽¹⁾ | |
| f _{PLL_IN} | PLL input clock ⁽²⁾ | 2 | - | 24 | MHz |
| | PLL input clock duty cycle | 45 | - | 55 | % |
| f _{PLL_OUT} | PLL output clock | 2 | - | 32 | MHz |
| t _{LOCK} | PLL lock time PLL input = 16 MHz PLL VCO = 96 MHz | - | 115 | 160 | μs |
| Jitter | Cycle-to-cycle jitter | - | - | ±600 | ps |
| I _{DDA} (PLL) | Current consumption on V _{DDA} | - | 220 | 450 | μA |
| I _{DD} (PLL) | Current consumption on V _{DD} | - | 120 | 150 | |

1. Guaranteed by characterization results.
2. Take care of using the appropriate multiplier factors so as to have PLL input clock values compatible with the range defined by f_{PLL_OUT}.

6.3.9 Memory characteristics

The characteristics are given at T_A = -40 to 105 °C unless otherwise specified.

RAM memory

Table 35. RAM and hardware registers

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--------|------------------------------------|----------------------|------|-----|-----|------|
| VRM | Data retention mode ⁽¹⁾ | STOP mode (or RESET) | 1.65 | - | - | V |

1. Minimum supply voltage without losing data stored in RAM (in Stop mode or under Reset) or in hardware registers (only in Stop mode).

To complete these trials, ESD stress can be applied directly on the device, over the range of specification values. When unexpected behavior is detected, the software can be hardened to prevent unrecoverable errors occurring (see application note AN1015).

Electromagnetic Interference (EMI)

The electromagnetic field emitted by the device are monitored while a simple application is executed (toggling 2 LEDs through the I/O ports). This emission test is compliant with IEC 61967-2 standard which specifies the test board and the pin loading.

Table 39. EMI characteristics

| Symbol | Parameter | Conditions | Monitored frequency band | Max vs. frequency range | | | Unit |
|------------------|------------|--|--------------------------|-------------------------|------------------------|------------------------|------|
| | | | | 4 MHz voltage range 3 | 16 MHz voltage range 2 | 32 MHz voltage range 1 | |
| S _{EMI} | Peak level | V _{DD} = 3.3 V, T _A = 25 °C, LQFP100 package compliant with IEC 61967-2 | 0.1 to 30 MHz | 3 | -6 | -5 | dBμV |
| | | | 30 to 130 MHz | 18 | 4 | -7 | |
| | | | 130 MHz to 1GHz | 15 | 5 | -7 | |
| | | | SAE EMI Level | 2.5 | 2 | 1 | - |

6.3.11 Electrical sensitivity characteristics

Based on three different tests (ESD, LU) using specific measurement methods, the device is stressed in order to determine its performance in terms of electrical sensitivity.

Electrostatic discharge (ESD)

Electrostatic discharges (a positive then a negative pulse separated by 1 second) are applied to the pins of each sample according to each pin combination. The sample size depends on the number of supply pins in the device (3 parts × (n+1) supply pins). This test conforms to the JESD22-A114, ANSI/ESD STM5.3.1. standard.

Table 40. ESD absolute maximum ratings

| Symbol | Ratings | Conditions | Class | Maximum value ⁽¹⁾ | Unit |
|-----------------------|---|---|-------|------------------------------|------|
| V _{ESD(HBM)} | Electrostatic discharge voltage (human body model) | T _A = +25 °C, conforming to JESD22-A114 | 2 | 2000 | V |
| V _{ESD(CDM)} | Electrostatic discharge voltage (charge device model) | T _A = +25 °C, conforming to ANSI/ESD STM5.3.1. | C4 | 500 | V |

1. Guaranteed by characterization results.

SPI characteristics

Unless otherwise specified, the parameters given in the following table are derived from tests performed under the conditions summarized in [Table 14](#).

Refer to [Section 6.3.12: I/O current injection characteristics](#) for more details on the input/output alternate function characteristics (NSS, SCK, MOSI, MISO).

Table 50. SPI characteristics⁽¹⁾

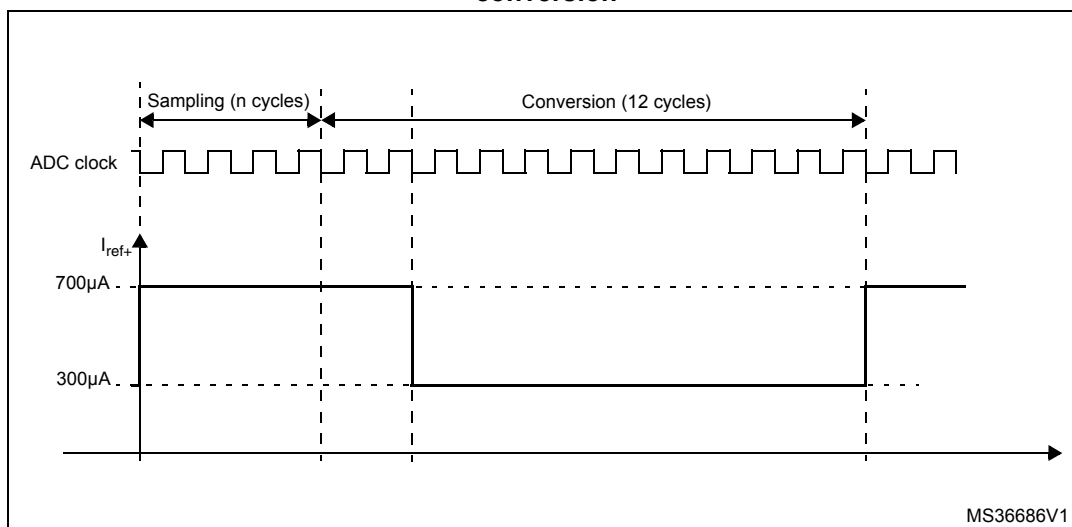
| Symbol | Parameter | Conditions | Min | Max ⁽²⁾ | Unit |
|--|----------------------------------|----------------------------|---------------|--------------------|------|
| f_{SCK} $1/t_{c(SCK)}$ | SPI clock frequency | Master mode | - | 16 | MHz |
| | | Slave mode | - | 16 | |
| | | Slave transmitter | - | 12 ⁽³⁾ | |
| $t_{r(SCK)}^{(2)}$ $t_{f(SCK)}^{(2)}$ | SPI clock rise and fall time | Capacitive load: C = 30 pF | - | 6 | ns |
| DuCy(SCK) | SPI slave input clock duty cycle | Slave mode | 30 | 70 | % |
| $t_{su(NSS)}$ | NSS setup time | Slave mode | $4t_{HCLK}$ | - | ns |
| $t_{h(NSS)}$ | NSS hold time | Slave mode | $2t_{HCLK}$ | - | |
| $t_{w(SCKH)}^{(2)}$ $t_{w(SCKL)}^{(2)}$ | SCK high and low time | Master mode | $t_{SCK}/2-5$ | $t_{SCK}/2+3$ | |
| $t_{su(MI)}^{(2)}$ | Data input setup time | Master mode | 5 | - | |
| $t_{su(SI)}^{(2)}$ | | Slave mode | 6 | - | |
| $t_{h(MI)}^{(2)}$ | Data input hold time | Master mode | 5 | - | |
| $t_{h(SI)}^{(2)}$ | | Slave mode | 5 | - | |
| $t_{a(SO)}^{(4)}$ | Data output access time | Slave mode | 0 | $3t_{HCLK}$ | |
| $t_{v(SO)}^{(2)}$ | Data output valid time | Slave mode | - | 33 | |
| $t_{v(MO)}^{(2)}$ | Data output valid time | Master mode | - | 6.5 | |
| $t_{h(SO)}^{(2)}$ | Data output hold time | Slave mode | 17 | - | |
| $t_{h(MO)}^{(2)}$ | | Master mode | 0.5 | - | |

1. The characteristics above are given for voltage range 1.
2. Guaranteed by characterization results.
3. The maximum SPI clock frequency in slave transmitter mode is given for an SPI slave input clock duty cycle (DuCy(SCK)) ranging between 40 to 60%.
4. Min time is for the minimum time to drive the output and max time is for the maximum time to validate the data.

Table 56. ADC characteristics (continued)

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|------------------------|--|---|---|-----|---------------------|--------------------|
| $t_S^{(5)}$ | Sampling time | Direct channels $2.4\text{ V} \leq V_{DDA} \leq 3.6\text{ V}$ | 0.25 | - | - | μs |
| | | Multiplexed channels $2.4\text{ V} \leq V_{DDA} \leq 3.6\text{ V}$ | 0.56 | - | - | |
| | | Direct channels $1.8\text{ V} \leq V_{DDA} \leq 2.4\text{ V}$ | 0.56 | - | - | |
| | | Multiplexed channels $1.8\text{ V} \leq V_{DDA} \leq 2.4\text{ V}$ | 1 | - | - | |
| | | - | 4 | - | 384 | $1/f_{\text{ADC}}$ |
| t_{CONV} | Total conversion time (including sampling time) | $f_{\text{ADC}} = 16\text{ MHz}$ | 1 | - | 24.75 | μs |
| | | - | 4 to 384 (sampling phase) + 12 (successive approximation) | | | $1/f_{\text{ADC}}$ |
| C_{ADC} | Internal sample and hold capacitor | Direct channels | - | 16 | - | pF |
| | | Multiplexed channels | - | | - | |
| f_{TRIG} | External trigger frequency Regular sequencer | 12-bit conversions | - | - | $T_{\text{conv}}+1$ | $1/f_{\text{ADC}}$ |
| | | 6/8/10-bit conversions | - | - | T_{conv} | $1/f_{\text{ADC}}$ |
| f_{TRIG} | External trigger frequency Injected sequencer | 12-bit conversions | - | - | $T_{\text{conv}}+2$ | $1/f_{\text{ADC}}$ |
| | | 6/8/10-bit conversions | - | - | $T_{\text{conv}}+1$ | $1/f_{\text{ADC}}$ |
| $R_{\text{AIN}}^{(6)}$ | Signal source impedance | | - | - | 50 | $\text{k}\Omega$ |
| t_{lat} | Injection trigger conversion latency | $f_{\text{ADC}} = 16\text{ MHz}$ | 219 | - | 281 | ns |
| | | - | 3.5 | - | 4.5 | $1/f_{\text{ADC}}$ |
| t_{latr} | Regular trigger conversion latency | $f_{\text{ADC}} = 16\text{ MHz}$ | 156 | - | 219 | ns |
| | | - | 2.5 | - | 3.5 | $1/f_{\text{ADC}}$ |
| t_{STAB} | Power-up time | - | - | - | 3.5 | μs |

1. The $V_{\text{ref+}}$ input can be grounded if neither the ADC nor the DAC are used (this allows to shut down an external voltage reference).
2. The current consumption through V_{REF} is composed of two parameters:
 - one constant (max 300 μA)
 - one variable (max 400 μA), only during sampling time + 2 first conversion pulses
 So, peak consumption is $300+400 = 700\text{ }\mu\text{A}$ and average consumption is $300 + [(4\text{ sampling} + 2) / 16] \times 400 = 450\text{ }\mu\text{A}$ at 1Msps
3. $V_{\text{REF+}}$ can be internally connected to V_{DDA} and $V_{\text{REF-}}$ can be internally connected to V_{SSA} , depending on the package. Refer to [Section 4: Pin descriptions](#) for further details.
4. V_{SSA} or $V_{\text{REF-}}$ must be tied to ground.
5. Minimum sampling time is reached for an external input impedance limited to a value as defined in [Table 58: Maximum source impedance \$R_{\text{AIN max}}\$](#) .
6. External impedance has another high value limitation when using short sampling time as defined in [Table 58: Maximum source impedance \$R_{\text{AIN max}}\$](#) .

Figure 27. Maximum dynamic current consumption on V_{REF+} supply pin during ADC conversion**Table 58. Maximum source impedance $R_{AIN\ max}^{(1)}$**

| Ts (μs) | R _{AIN} max (kΩ) | | | | Ts (cycles) f _{ADC} =16 MHz ⁽²⁾ |
|------------|----------------------------------|----------------------------------|----------------------------------|----------------------------------|--|
| | Multiplexed channels | | Direct channels | | |
| | 2.4 V < V _{DDA} < 3.6 V | 1.8 V < V _{DDA} < 2.4 V | 2.4 V < V _{DDA} < 3.6 V | 1.8 V < V _{DDA} < 2.4 V | |
| 0.25 | Not allowed | Not allowed | 0.7 | Not allowed | 4 |
| 0.5625 | 0.8 | Not allowed | 2.0 | 1.0 | 9 |
| 1 | 2.0 | 0.8 | 4.0 | 3.0 | 16 |
| 1.5 | 3.0 | 1.8 | 6.0 | 4.5 | 24 |
| 3 | 6.8 | 4.0 | 15.0 | 10.0 | 48 |
| 6 | 15.0 | 10.0 | 30.0 | 20.0 | 96 |
| 12 | 32.0 | 25.0 | 50.0 | 40.0 | 192 |
| 24 | 50.0 | 50.0 | 50.0 | 50.0 | 384 |

1. Guaranteed by design.
2. Number of samples calculated for $f_{ADC} = 16\ MHz$. For $f_{ADC} = 8$ and $4\ MHz$ the number of sampling cycles can be reduced with respect to the minimum sampling time T_s (μs),

General PCB design guidelines

Power supply decoupling should be performed as shown in [Figure 9](#). The applicable procedure depends on whether V_{REF+} is connected to V_{DDA} or not. The $100\ nF$ capacitors should be ceramic (good quality). They should be placed as close as possible to the chip.

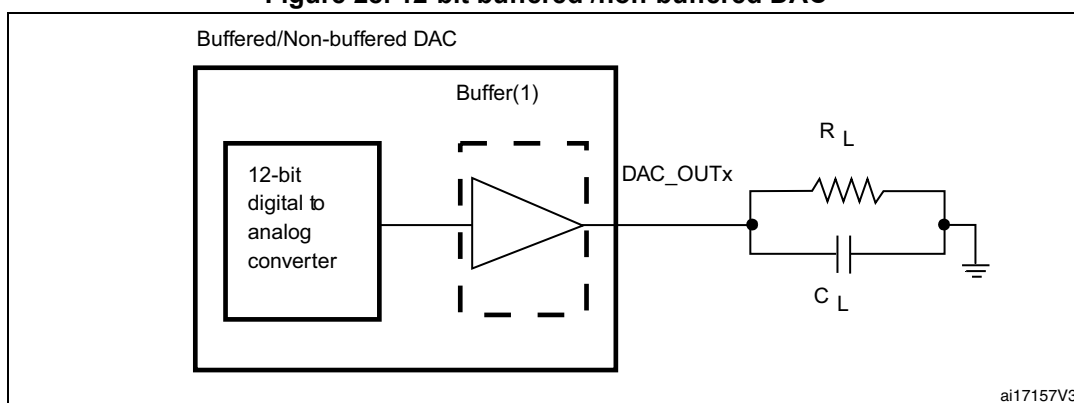
6.3.18 DAC electrical specifications

Data guaranteed by design, unless otherwise specified.

Table 59. DAC characteristics

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-------------------------------------|--|---|------------------|------|--------------------------|------|
| V _{DDA} | Analog supply voltage | - | 1.8 | - | 3.6 | V |
| V _{REF+} | Reference supply voltage | V _{REF+} must always be below V _{DDA} | 1.8 | - | 3.6 | |
| V _{REF-} | Lower reference voltage | - | V _{SSA} | | | |
| I _{DDVREF+} ⁽¹⁾ | Current consumption on V _{REF+} supply V _{REF+} = 3.3 V | No load, middle code (0x800) | - | 130 | 220 | μA |
| | | No load, worst code (0x000) | - | 220 | 350 | |
| I _{DDA} ⁽¹⁾ | Current consumption on V _{DDA} supply V _{DDA} = 3.3 V | No load, middle code (0x800) | - | 210 | 320 | |
| | | No load, worst code (0xF1C) | - | 320 | 520 | |
| R _L ⁽²⁾ | Resistive load | DAC output buffer ON | 5 | - | - | kΩ |
| C _L ⁽²⁾ | Capacitive load | | - | - | 50 | pF |
| R _O | Output impedance | DAC output buffer OFF | 12 | 16 | 20 | kΩ |
| V _{DAC_OUT} | Voltage on DAC_OUT output | DAC output buffer ON | 0.2 | - | V _{DDA} – 0.2 | V |
| | | DAC output buffer OFF | 0.5 | - | V _{REF+} – 1LSB | mV |
| DNL ⁽¹⁾ | Differential non linearity ⁽³⁾ | C _L ≤ 50 pF, R _L ≥ 5 kΩ DAC output buffer ON | - | 1.5 | 3 | LSB |
| | | No R _L , C _L ≤ 50 pF DAC output buffer OFF | - | 1.5 | 3 | |
| INL ⁽¹⁾ | Integral non linearity ⁽⁴⁾ | C _L ≤ 50 pF, R _L ≥ 5 kΩ DAC output buffer ON | - | 2 | 4 | |
| | | No R _L , C _L ≤ 50 pF DAC output buffer OFF | - | 2 | 4 | |
| Offset ⁽¹⁾ | Offset error at code 0x800 ⁽⁵⁾ | C _L ≤ 50 pF, R _L ≥ 5 kΩ DAC output buffer ON | - | ±10 | ±25 | |
| | | No R _L , C _L ≤ 50 pF DAC output buffer OFF | - | ±5 | ±8 | |
| Offset1 ⁽¹⁾ | Offset error at code 0x001 ⁽⁶⁾ | No R _L , C _L ≤ 50 pF DAC output buffer OFF | - | ±1.5 | ±5 | |

4. Difference between measured value at Code i and the value at Code i on a line drawn between Code 0 and last Code 4095.
5. Difference between the value measured at Code (0x800) and the ideal value = $V_{REF+}/2$.
6. Difference between the value measured at Code (0x001) and the ideal value.
7. Difference between ideal slope of the transfer function and measured slope computed from code 0x000 and 0xFFFF when buffer is OFF, and from code giving 0.2 V and ($V_{DDA} - 0.2$) V when buffer is ON.
8. In buffered mode, the output can overshoot above the final value for low input code (starting from min value).

Figure 28. 12-bit buffered /non-buffered DAC

1. The DAC integrates an output buffer that can be used to reduce the output impedance and to drive external loads directly without the use of an external operational amplifier. The buffer can be bypassed by configuring the BOFFx bit in the DAC_CR register.

6.3.19 Operational amplifier characteristics

Table 60. Operational amplifier characteristics

| Symbol | Parameter | | Condition ⁽¹⁾ | Min ⁽²⁾ | Typ | Max ⁽²⁾ | Unit |
|------------------------|------------------------------|---------------------------|--------------------------|--------------------|-----|--------------------|-------------------|
| CMIR | Common mode input range | | - | 0 | - | V_{DD} | |
| V_{I_OFFSET} | Input offset voltage | Maximum calibration range | - | - | - | ± 15 | mV |
| | | After offset calibration | - | - | - | ± 1.5 | |
| ΔV_{I_OFFSET} | Input offset voltage drift | Normal mode | - | - | - | ± 40 | $\mu V/^{\circ}C$ |
| | | Low-power mode | - | - | - | ± 80 | |
| I_{IB} | Input current bias | Dedicated input | 75 °C | - | - | 1 | nA |
| | | General purpose input | | - | - | 10 | |
| I_{LOAD} | Drive current | Normal mode | - | - | - | 500 | μA |
| | | Low-power mode | - | - | - | 100 | |
| I_{DD} | Consumption | Normal mode | No load, quiescent mode | - | 100 | 220 | μA |
| | | Low-power mode | | - | 30 | 60 | |
| CMRR | Common mode rejection ration | Normal mode | - | - | -85 | - | dB |
| | | Low-power mode | - | - | -90 | - | |

6.3.20 Temperature sensor characteristics

Table 61. Temperature sensor calibration values

| Calibration value name | Description | Memory address |
|------------------------|---|---------------------------|
| TS_CAL1 | TS ADC raw data acquired at temperature of 30 °C ± 5 °C $V_{DDA} = 3 \text{ V} \pm 10 \text{ mV}$ | 0x1FF8 00FA - 0x1FF8 00FB |
| TS_CAL2 | TS ADC raw data acquired at temperature of 110 °C ± 5 °C $V_{DDA} = 3 \text{ V} \pm 10 \text{ mV}$ | 0x1FF8 00FE - 0x1FF8 00FF |

Table 62. Temperature sensor characteristics

| Symbol | Parameter | Min | Typ | Max | Unit |
|--------------------------|--|------|---------|---------|-------|
| $T_L^{(1)}$ | V_{SENSE} linearity with temperature | - | ± 1 | ± 2 | °C |
| Avg_Slope ⁽¹⁾ | Average slope | 1.48 | 1.61 | 1.75 | mV/°C |
| V_{110} | Voltage at 110 °C ± 5 °C ⁽²⁾ | 612 | 626.8 | 641.5 | mV |
| $I_{DDA(TEMP)}^{(3)}$ | Current consumption | - | 3.4 | 6 | μA |
| $t_{START}^{(3)}$ | Startup time | - | - | 10 | μs |
| $T_{S_temp}^{(3)}$ | ADC sampling time when reading the temperature | 4 | - | - | |

1. Guaranteed by characterization results.

2. Measured at $V_{DD} = 3 \text{ V} \pm 10 \text{ mV}$. V_{110} ADC conversion result is stored in the TS_CAL2 byte.

3. Guaranteed by design.

6.3.21 Comparator

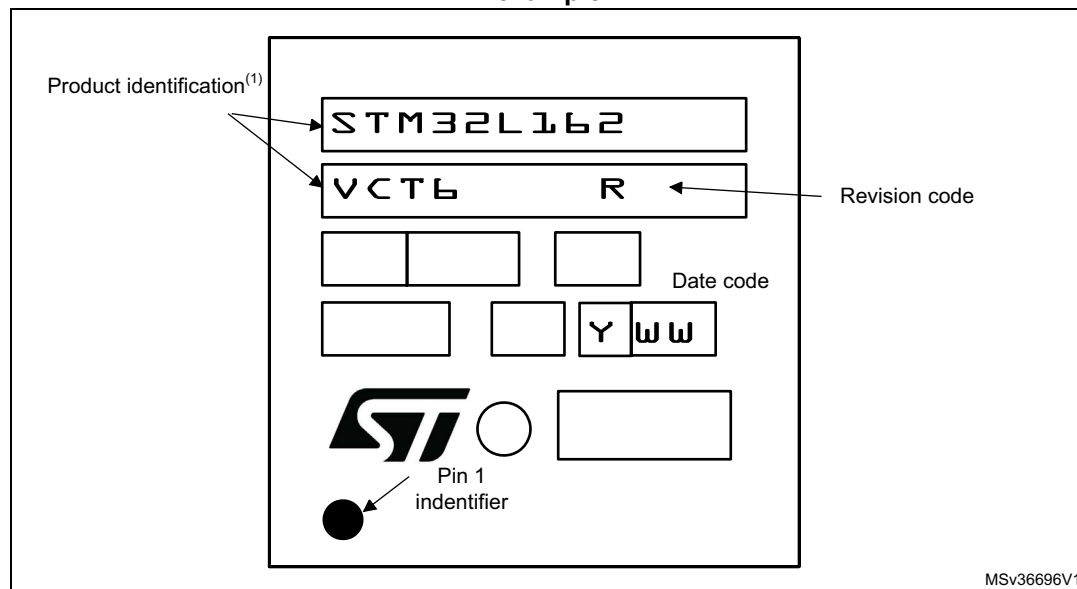
Table 63. Comparator 1 characteristics

| Symbol | Parameter | Conditions | Min ⁽¹⁾ | Typ | Max ⁽¹⁾ | Unit |
|---------------------|--|---|--------------------|---------|--------------------|-----------|
| V_{DDA} | Analog supply voltage | - | 1.65 | | 3.6 | V |
| R_{400K} | R_{400K} value | - | - | 400 | - | kΩ |
| R_{10K} | R_{10K} value | - | - | 10 | - | |
| V_{IN} | Comparator 1 input voltage range | - | 0.6 | - | V_{DDA} | V |
| t_{START} | Comparator startup time | - | - | 7 | 10 | μs |
| t_d | Propagation delay ⁽²⁾ | - | - | 3 | 10 | |
| V_{offset} | Comparator offset | - | - | ± 3 | ± 10 | mV |
| $d_{V_{offset}}/dt$ | Comparator offset variation in worst voltage stress conditions | $V_{DDA} = 3.6 \text{ V}$ $V_{IN+} = 0 \text{ V}$ $V_{IN-} = V_{REFINT}$ $T_A = 25 \text{ °C}$ | 0 | 1.5 | 10 | mV/1000 h |
| I_{COMP1} | Current consumption ⁽³⁾ | - | - | 160 | 260 | nA |

Marking of engineering samples

The following figure gives an example of topside marking orientation versus pin 1 identifier location.

Figure 31. LQFP100, 14 x 14 mm, 100-pin low-profile quad flat package top view example

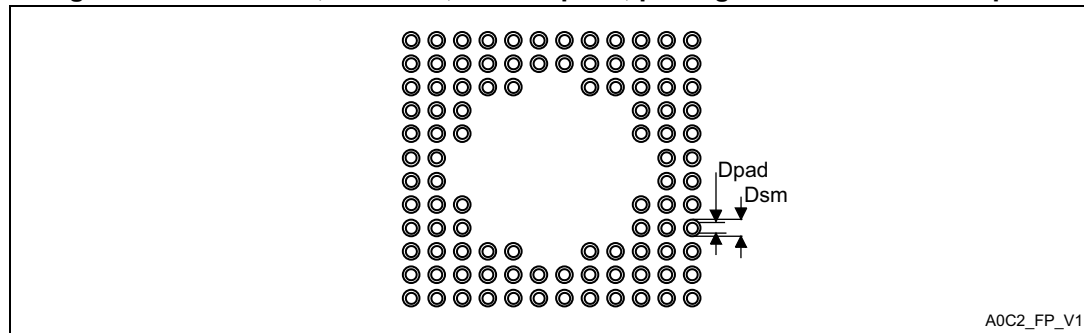


1. Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering samples to run qualification activity

Table 68. UFBGA100, 7 x 7 mm, 0.5 mm pitch package mechanical data (continued)

| Symbol | millimeters | | | inches ⁽¹⁾ | | |
|--------|-------------|-----|-------|-----------------------|-----|--------|
| | Min | Typ | Max | Min | Typ | Max |
| eee | - | - | 0.150 | - | - | 0.0059 |
| fff | - | - | 0.050 | - | - | 0.0020 |

1. Values in inches are converted from mm and rounded to 4 decimal digits.

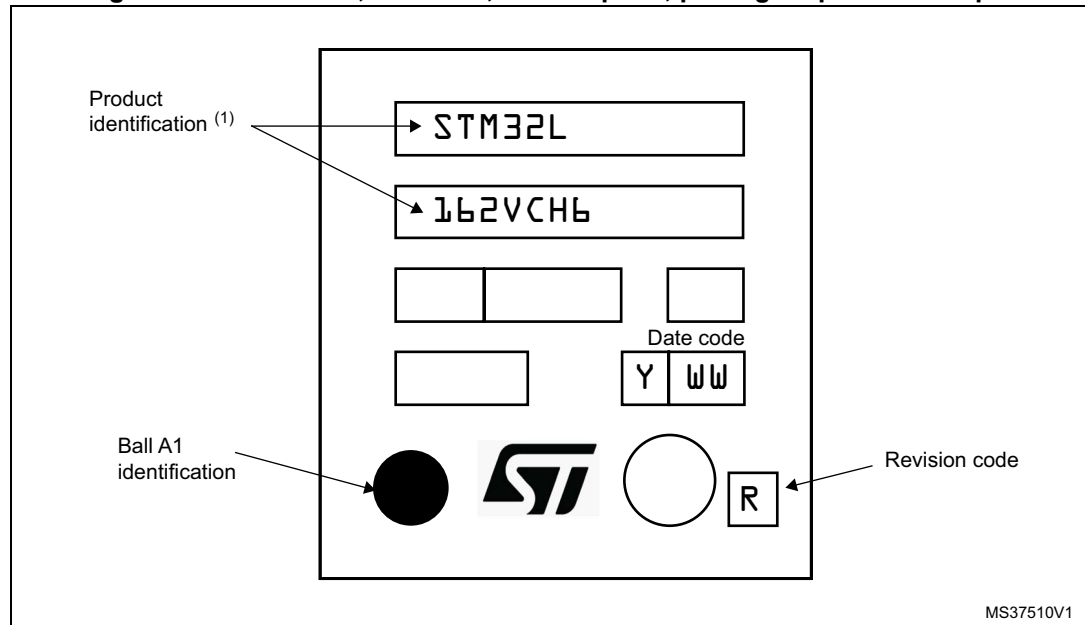
Figure 36. UFBGA100, 7 x 7 mm, 0.5 mm pitch, package recommended footprint**Table 69. UFBGA100, 7 x 7 mm, 0.50 mm pitch, recommended PCB design rules**

| Dimension | Recommended values |
|-------------------|--|
| Pitch | 0.5 |
| Dpad | 0.280 mm |
| Dsm | 0.370 mm typ. (depends on the soldermask registration tolerance) |
| Stencil opening | 0.280 mm |
| Stencil thickness | Between 0.100 mm and 0.125 mm |

Marking of engineering samples

The following figure gives an example of topside marking orientation versus ball A1 identifier location.

Figure 37. UFBGA100, 7 x 7 mm, 0.5 mm pitch, package top view example



1. Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering samples to run qualification activity

Table 72. Document revision history (continued)

| Date | Revision | Changes |
|-------------|------------------|---|
| 19-May-2014 | 6 (continued) | <p>Updated Table 48: I2C characteristics.</p> <p>Removed minimum values for f_S in Table 56: ADC characteristics.</p> <p>Updated Output impedance values in Table 59: DAC characteristics.</p> <p>Moved Table 61: Temperature sensor calibration values from Section 3.10.1: Temperature sensor to Section 6.3.20: Temperature sensor characteristics and updated the table. Removed note 4 in Table 62: Temperature sensor characteristics.</p> <p>Modified General PCB design guidelines.</p> <p>Removed figures "Power supply and reference decoupling (V_{REF+} not connected to V_{DDA})" and "Power supply and reference decoupling (V_{REF+} connected to V_{DDA})".</p> <p>Updated Figure 26: Typical connection diagram using the ADC.</p> <p>Added "Marking of engineering samples" sections in Figure : In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: www.st.com. ECOPACK® is an ST trademark..</p> <p>Updated the conditions in Table 26: Low-power mode wakeup timings.</p> <p>Removed ambiguity of "ambient temperature" in the electrical characteristics description.</p> |
| 13-Oct-2014 | 7 | <p>Updated Section 3.18: Communication interfaces putting I2S characteristics inside.</p> <p>Updated DMIPS features in cover page and Section 2: Description.</p> <p>Updated max temperature at 105°C instead of 85°C in the whole datasheet.</p> <p>Updated Table 9: STM32L162xC pin definitions with additional functions column.</p> <p>Updated current consumption in Table 20: Current consumption in Sleep mode.</p> <p>Updated Table 25: Peripheral current consumption with new measured current values.</p> <p>Updated Table 58: Maximum source impedance RAIN max adding note 2.</p> |
| 06-Mar-2015 | 8 | <p>Updated Section 7: Package information with new package device marking.</p> <p>Updated Figure 6: Memory map.</p> |