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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	I²C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, LCD, POR, PWM, WDT
Number of I/O	24
Program Memory Size	14KB (8K x 14)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 5.5V
Data Converters	A/D 20x12b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16f19155-i-ss

TABLE 4-12: SPECIAL FUNCTION REGISTER SUMMARY BANKS 0-63 PIC16(L)F19155/56/75/76/85/86 (CONTINUED)

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on: MCLR
Bank 9											
CPU CORE REGISTERS; see Table 4-3 for specifics											
48Ch	SMT1TMRL	SMT1TMR								0000 0000	0000 0000
48Dh	SMT1TMRH	SMT1TMR								0000 0000	0000 0000
48Eh	SMT1TMRU	SMT1TMR								0000 0000	0000 0000
48Fh	SMT1CPRL	CPR								xxxx xxxx	xxxx xxxx
490h	SMT1CPRH	CPR								xxxx xxxx	xxxx xxxx
491h	SMT1CPRU	CPR								xxxx xxxx	xxxx xxxx
492h	SMT1CPWL	CPW								xxxx xxxx	xxxx xxxx
493h	SMT1CPWH	CPW								xxxx xxxx	xxxx xxxx
494h	SMT1CPWU	CPW								xxxx xxxx	xxxx xxxx
495h	SMT1PRL	SMT1PR								1111 1111	1111 1111
496h	SMT1PRH	SMT1PR								1111 1111	1111 1111
497h	SMT1PRU	SMT1PR								1111 1111	1111 1111
498h	SMT1CON0	EN	—	STP	WPOL	SPOL	CPOL	SMT1PS<1:0>		0-00 0000	0-00 0000
499h	SMT1CON1	SMT1GO	REPEAT	—	—	MODE<3:0>				00-- 0000	00-- 0000
49Ah	SMT1STAT	CPRUP	CPWUP	RST	—	—	TS	WS	AS	000- -000	000- -000
49Bh	SMT1CLK	—	—	—	—	—	CSEL<2:0>			0000 0000	0000 0000
49Ch	SMT1SIG	—	—	—	SSEL<4:0>					0000 0000	0000 0000
49Dh	SMT1WIN	—	—	—	WSEL<4:0>					0000 0000	0000 0000
49Eh	—	Unimplemented								---- ----	---- ----
49Fh	—	Unimplemented								---- ----	---- ----

Legend: x = unknown, u = unchanged, q = depends on condition, - = unimplemented, read as '0', r = reserved. Shaded locations unimplemented, read as '0'.

Note 1: Unimplemented data memory locations, read as '0'.

TABLE 4-12: SPECIAL FUNCTION REGISTER SUMMARY BANKS 0-63 PIC16(L)F19155/56/75/76/85/86 (CONTINUED)

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on: MCLR
Bank 60											
CPU CORE REGISTERS; see Table 4-3 for specifics											
1E0Ch	—	Unimplemented								---- ----	---- ----
1E0Dh	—	Unimplemented								---- ----	---- ----
1E0Eh	—	Unimplemented								---- ----	---- ----
1E0Fh	CLCDATA	—	—	—	—	MLC4OUT	MLC3OUT	MLC2OUT	MLC1OUT	0000 0000	0000 0000
1E10h	CLC1CON	LC1EN	—	LC1OUT	LC1INTP	LC1INTN	LC1MODE<2:0>			0-000000	0-000000
1E11h	CLC1POL	LC1POL	—	—	—	LC1G4POL	LC1G3POL	LC1G2POL	LC1G1POL	0--- xxxx	0--- uuuu
1E12h	CLC1SEL0	—	—	LC1D1S<5:0>						xxxx xxxx	uuuu uuuu
1E13h	CLC1SEL1	—	—	LC1D2S<5:0>						xxxx xxxx	uuuu uuuu
1E14h	CLC1SEL2	—	—	LC1D3S<5:0>						xxxx xxxx	uuuu uuuu
1E15h	CLC1SEL3	—	—	LC1D4S<5:0>						xxxx xxxx	uuuu uuuu
1E16h	CLC1GLS0	LC1G1D4T	LC1G1D4N	LC1G1D3T	LC1G1D3N	LC1G1D2T	LC1G1D2N	LC1G1D1T	LC1G1D1N	xxxx xxxx	uuuu uuuu
1E17h	CLC1GLS1	LC1G2D4T	LC1G2D4N	LC1G2D3T	LC1G2D3N	LC1G2D2T	LC1G2D2N	LC1G2D1T	LC1G2D1N	xxxx xxxx	uuuu uuuu
1E18h	CLC1GLS2	LC1G3D4T	LC1G3D4N	LC1G3D3T	LC1G3D3N	LC1G3D2T	LC1G3D2N	LC1G3D1T	LC1G3D1N	xxxx xxxx	uuuu uuuu
1E19h	CLC1GLS3	LC1G4D4T	LC1G4D4N	LC1G4D3T	LC1G4D3N	LC1G4D2T	LC1G4D2N	LC1G4D1T	LC1G4D1N	xxxx xxxx	uuuu uuuu
1E1Ah	CLC2CON	LC2EN	—	LC2OUT	LC2INTP	LC2INTN	LC2MODE<2:0>			0-00 0000	0-00 0000
1E1Bh	CLC2POL	LC2POL	—	—	—	LC2G4POL	LC2G3POL	LC2G2POL	LC2G1POL	0--- xxxx	0--- uuuu
1E1Ch	CLC2SEL0	—	—	LC2D1S<5:0>						xxxx xxxx	uuuu uuuu
1E1Dh	CLC2SEL1	—	—	LC2D2S<5:0>						xxxx xxxx	uuuu uuuu
1E1Eh	CLC2SEL2	—	—	LC2D3S<5:0>						xxxx xxxx	uuuu uuuu
1E1Fh	CLC2SEL3	—	—	LC2D4S<5:0>						xxxx xxxx	uuuu uuuu
1E20h	CLC2GLS0	LC2G1D4T	LC1G1D4N	LC2G1D3T	LC2G1D3N	LC2G1D2T	LC2G1D2N	LC2G1D1T	LC2G1D1N	--xx xxxx	uuuu uuuu
1E21h	CLC2GLS1	LC2G2D4T	LC1G2D4N	LC2G2D3T	LC2G2D3N	LC2G2D2T	LC2G2D2N	LC2G2D1T	LC2G2D1N	xxxx xxxx	uuuu uuuu

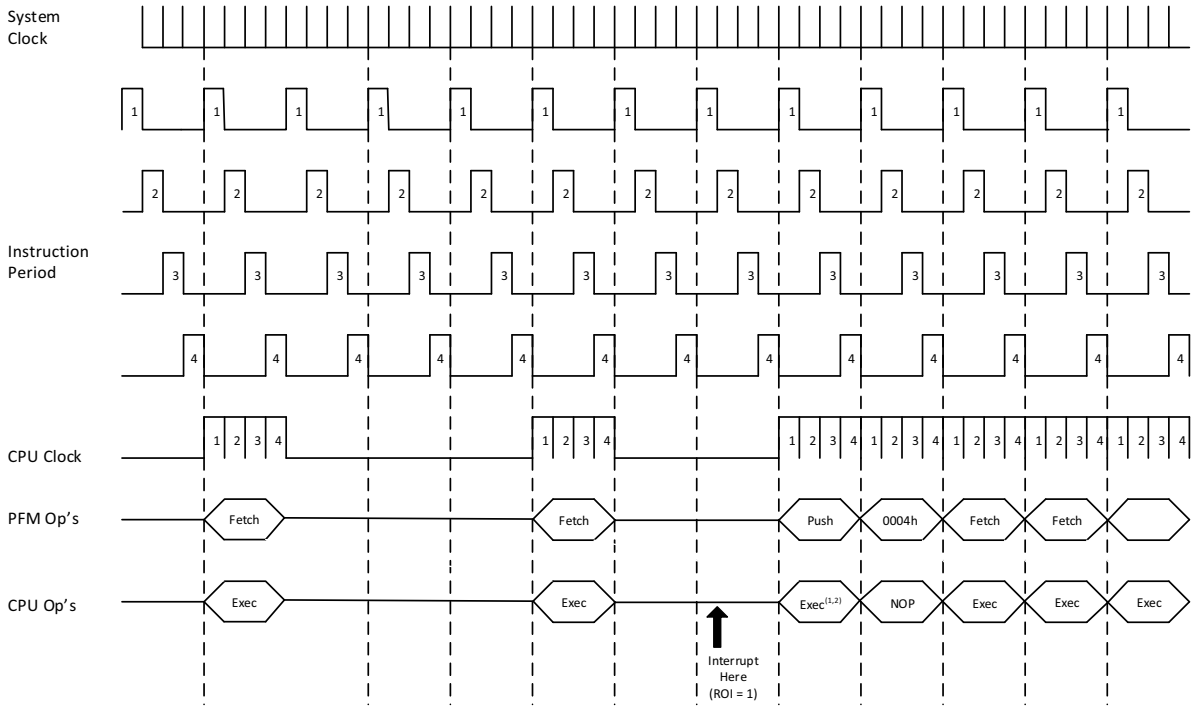
Legend: x = unknown, u = unchanged, q = depends on condition, - = unimplemented, read as '0', r = reserved. Shaded locations unimplemented, read as '0'.

Note 1: Unimplemented data memory locations, read as '0'.

9.5 Active Clock Tuning

The Active Clock Tuning module (ACT) takes the SOSC frequency of 32.768 kHz and uses that time base to adjust the frequency of the HFINTOSC over voltage and temperature. The ACT module uses the same TUN<5:0> bits as supplied to the user. When clock recovery is enabled, the TUN bits are read-only to the user, and automatically updated.

FIGURE 11-1: DOZE MODE OPERATION EXAMPLE



Note 1: Multi-cycle instructions are executed to completion before fetching 0004h.
2: If the pre-fetched instruction clears GIE, the ISR will not occur, but DOZEN is still cleared and the CPU will resume execution at full speed.

11.2 Sleep Mode

Sleep mode is entered by executing the SLEEP instruction, while the Idle Enable (IDLEN) bit of the CPUDOZE register is clear (IDLEN = 0). If the SLEEP instruction is executed while the IDLEN bit is set (IDLEN = 1), the CPU will enter the IDLE mode (**Section 11.2.3 "Low-Power Sleep Mode"**).

Upon entering Sleep mode, the following conditions exist:

1. WWDT will be cleared but keeps running if enabled for operation during Sleep
2. The $\overline{PD}$ bit of the STATUS register is cleared
3. The $\overline{TO}$ bit of the STATUS register is set
4. CPU Clock and System Clock
5. 31 kHz LFINTOSC, HFINTOSC and SOSC are unaffected and peripherals using them may continue operation in Sleep.
6. ADC is unaffected if the dedicated FRC oscillator is selected the conversion will be left abandoned if FOSC is selected and ADRES will have an incorrect value
7. I/O ports maintain the status they had before Sleep was executed (driving high, low, or high-impedance). This does not apply in the case of any asynchronous peripheral which is active and may affect the I/O port value
8. Resets other than WWDT are not affected by Sleep mode

Refer to individual chapters for more details on peripheral operation during Sleep.

REGISTER 13-5: NVMCON1: NONVOLATILE MEMORY CONTROL 1 REGISTER

U-0	R/W-0/0	R/W-0/0	R/W/HC-0/0	R/W/HC-x/q	R/W-0/0	R/S/HC-0/0	R/S/HC-0/0
—	NVMREGS	LWLO	FREE	WRERR(1,2,3)	WREN	WR(4,5,6)	RD
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
S = Bit can only be set	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	HC = Bit is cleared by hardware

bit 7 **Unimplemented:** Read as '0'

bit 6 **NVMREGS:** Configuration Select bit
1 = Access EEPROM, DIA, DCI, Configuration, User ID and Device ID Registers
0 = Access PFM

bit 5 **LWLO:** Load Write Latches Only bit
When FREE = 0:
1 = The next WR command updates the write latch for this word within the row; no memory operation is initiated.
0 = The next WR command writes data or erases
Otherwise: The bit is ignored

bit 4 **FREE:** PFM Erase Enable bit
When NVMREGS:NVMADR points to a PFM location:
1 = Performs an erase operation with the next WR command; the 32-word pseudo-row containing the indicated address is erased (to all 1s) to prepare for writing.
0 = All erase operations have completed normally

bit 3 **WRERR:** Program/Erase Error Flag bit(1,2,3)
This bit is normally set by hardware.
1 = A write operation was interrupted by a Reset, interrupted unlock sequence, or WR was written to one while NVMADR points to a write-protected address.
0 = The program or erase operation completed normally

bit 2 **WREN:** Program/Erase Enable bit
1 = Allows program/erase cycles
0 = Inhibits programming/erasing of program Flash

bit 1 **WR:** Write Control bit(4,5,6)
When NVMREG:NVMADR points to a PFM location:
1 = Initiates the operation indicated by Table 13-4
0 = NVM program/erase operation is complete and inactive.

bit 0 **RD:** Read Control bit(7)
1 = Initiates a read at address = NVMADR1, and loads data to NVMDAT Read takes one instruction cycle and the bit is cleared when the operation is complete. The bit can only be set (not cleared) in software.
0 = NVM read operation is complete and inactive

Note 1: Bit is undefined while WR = 1.
2: Bit must be cleared by software; hardware will not clear this bit.
3: Bit may be written to '1' by software in order to implement test sequences.
4: This bit can only be set by following the unlock sequence of **Section 13.4.2 "NVM Unlock Sequence"**.
5: Operations are self-timed, and the WR bit is cleared by hardware when complete.
6: Once a write operation is initiated, setting this bit to zero will have no effect.
7: Reading from EEPROM loads only NVMDATL<7:0> (Register 13-1).

19.1 ADC Configuration

When configuring and using the ADC the following functions must be considered:

- Port Configuration
- Channel Selection
- ADC Voltage Reference Selection
- ADC Conversion Clock Source
- Interrupt Control
- Result Formatting
- Conversion Trigger Selection
- ADC Acquisition Time
- ADC Precharge Time
- Additional Sample and Hold Capacitor
- Single/Double Sample Conversion
- Guard Ring Outputs

19.1.1 PORT CONFIGURATION

The ADC can be used to convert both analog and digital signals. When converting analog signals, the I/O pin should be configured for analog by setting the associated TRIS and ANSEL bits. Refer to **Section 14.0 "I/O Ports"** for more information.

Note:	Analog voltages on any pin that is defined as a digital input may cause the input buffer to conduct excess current.

19.1.2 CHANNEL SELECTION

There are several channel selections available:

- Seven PORTA pins
- Eight PORTB pins
- Eight PORTD pins
- Temperature Indicator
- Seven PORTE pins
- Eight PORTF pins
- Seven PORTG pins
- VLCD3 Voltage divided by 4
- V_{BAT} Voltage divided by 3
- DAC output
- Fixed Voltage Reference (FVR)
- V_{SS} (ground)

The ADPCH register determines which channel is connected to the sample and hold circuit.

When changing channels, a delay is required before starting the next conversion.

Refer to **Section 19.2 "ADC Operation"** for more information.

19.1.3 ADC VOLTAGE REFERENCE

The PREF<1:0> bits of the ADREF register provide control of the positive voltage reference (V_{REF+}). The positive voltage reference can be:

- V_{REF+} pin
- V_{DD}
- FVR outputs

The negative voltage reference (V_{REF-}) source is:

- V_{SS}

See **Section 18.0 "Fixed Voltage Reference (FVR)"** for more details on the Fixed Voltage Reference.

19.1.4 CONVERSION CLOCK

The source of the conversion clock is software selectable via the ADCLK register and the CS bits of the ADCON0 register. If F_{OSC} is selected as the ADC clock, there is a prescaler available to divide the clock so that it meets the ADC clock period specification. The ADC clock source options are the following:

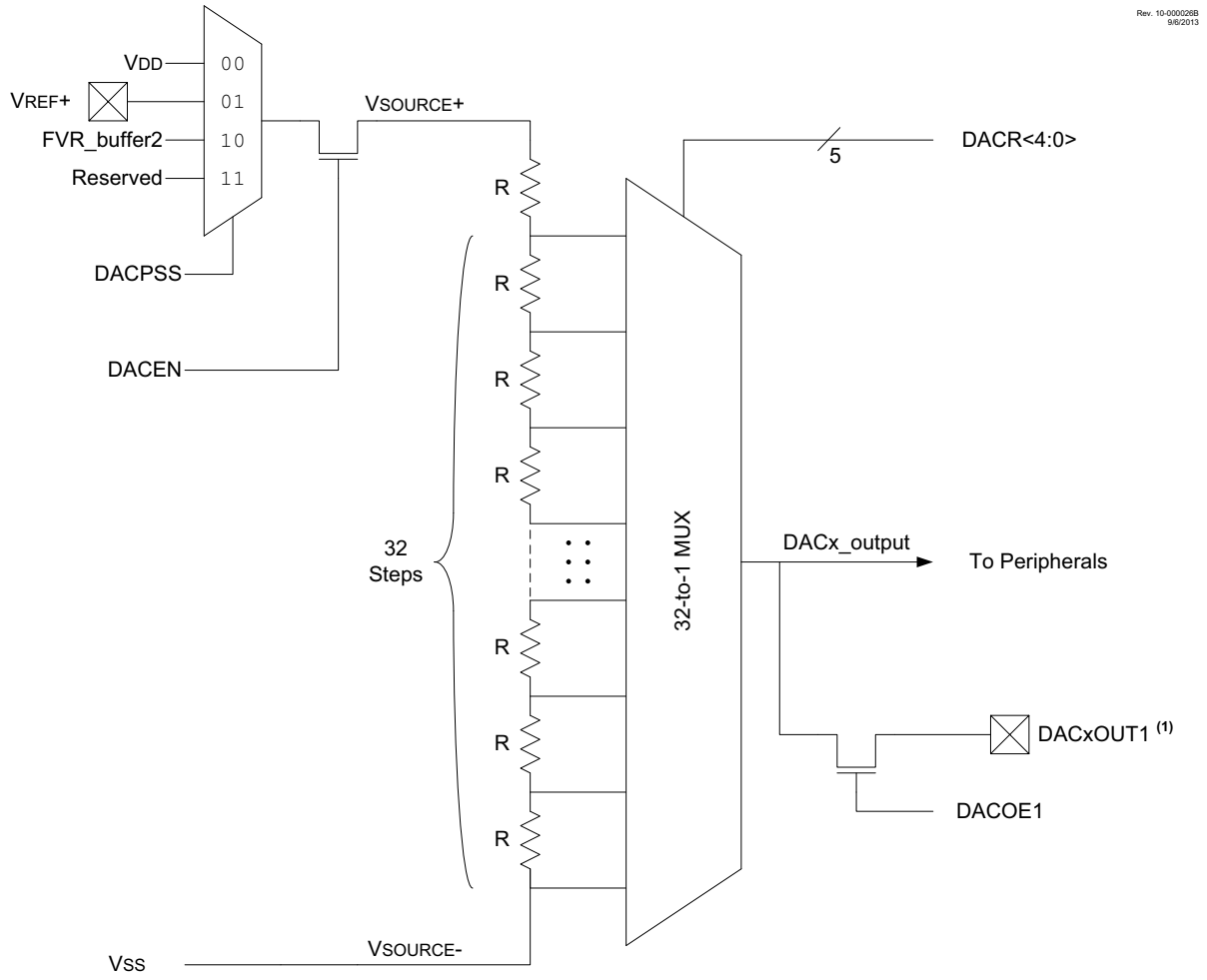
- $F_{OSC}/(2*n)$(where n is from 1 to 128)
- FRC (dedicated RC oscillator)

The time to complete one bit conversion is defined as T_{AD}. Refer to Figure 19-2 for the complete timing details of the ADC conversion.

For correct conversion, the appropriate T_{AD} specification must be met. Refer to Table 39-13 for more information. Table 19-1 gives examples of appropriate ADC clock selections.

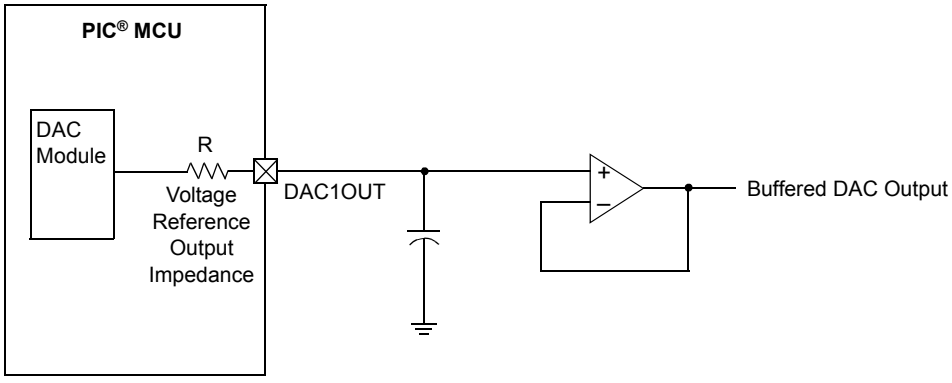
Note 1:	Unless using the FRC, any changes in the system clock frequency will change the ADC clock frequency, which may adversely affect the ADC result.
2:	The internal control logic of the ADC runs off of the clock selected by the CS bit of ADCON0. What this can mean is when the CS bit of ADCON0 is set to '1' (ADC runs on FRC), there may be unexpected delays in operation when setting ADC control bits.

FIGURE 21-1: DIGITAL-TO-ANALOG CONVERTER BLOCK DIAGRAM



Note 1: The unbuffered DACx_output is provided on the DACxOUT pin(s).

FIGURE 21-2: VOLTAGE REFERENCE OUTPUT BUFFER EXAMPLE



22.9 Comparator Response Time

The comparator output is indeterminate for a period of time after the change of an input source or the selection of a new reference voltage. This period is referred to as the response time. The response time of the comparator differs from the settling time of the voltage reference. Therefore, both of these times must be considered when determining the total response time to a comparator input change. See the Comparator and Voltage Reference Specifications in Table 39-14 and Table 39-15 for more details.

22.10 Analog Input Connection Considerations

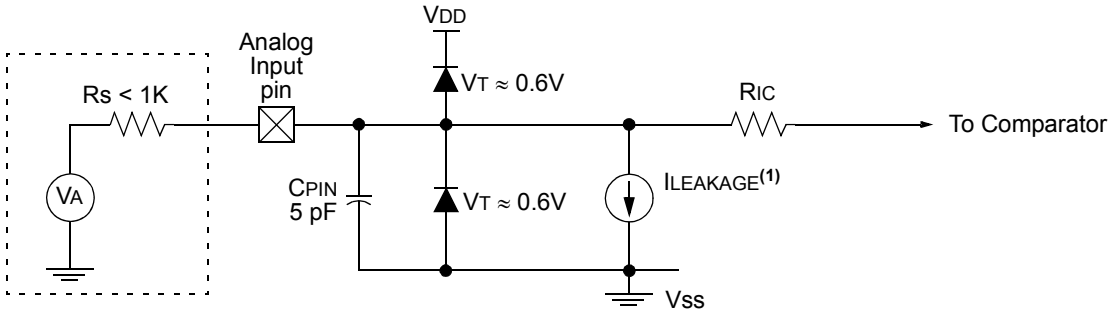
A simplified circuit for an analog input is shown in Figure 22-3. Since the analog input pins share their connection with a digital input, they have reverse biased ESD protection diodes to V_{DD} and V_{SS}. The analog input, therefore, must be between V_{SS} and V_{DD}. If the input voltage deviates from this range by more than 0.6V in either direction, one of the diodes is forward biased and a latch-up may occur.

A maximum source impedance of 1kΩ is recommended for the analog sources. Also, any external component connected to an analog input pin, such as a capacitor or a Zener diode, should have very little leakage current to minimize inaccuracies introduced.

Note 1: When reading a PORT register, all pins configured as analog inputs will read as a '0'. Pins configured as digital inputs will convert as an analog input, according to the input specification.

2: Analog levels on any pin defined as a digital input, may cause the input buffer to consume more current than is specified.

FIGURE 22-3: ANALOG INPUT MODEL



Legend: C_{PIN} = Input Capacitance
$I_{LEAKAGE}$ = Leakage Current at the pin due to various junctions
R_{IC} = Interconnect Resistance
R_S = Source Impedance
V_A = Analog Voltage
V_T = Threshold Voltage

Note 1: See I/O Ports in Table 39-4.

REGISTER 24-2: RTCCAL: RTC CALIBRATION REGISTER

R/W-0/u	R/W-0/u	R/W-0/u	R/W-0/u	R/W-0/u	R/W-0/u	R/W-0/u	R/W-0/u
CAL7	CAL6	CAL5	CAL4	CAL3	CAL2	CAL1	CAL0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	u = Bit is unchanged
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7-0 **CAL<7:0>:** RTC Drift Calibration bits

01111111 = Maximum positive adjustment; adds 508 RTC clock pulses every one minute
.
.
.
00000001 = Minimum positive adjustment; adds four RTC clock pulses every one minute
00000000 = No adjustment
11111111 = Minimum negative adjustment; subtracts four RTC clock pulses every one minute
.
.
.
10000000 = Maximum negative adjustment; subtracts 512 RTC clock pulses every one minute

REGISTER 24-3: YEAR(1): YEAR VALUE REGISTER

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
YEARH<3:0>				YEARL<3:0>			
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7-4 **YEARH<3:0>:** Binary Coded Decimal value of years '10' digit; contains a value from 0 to 9

bit 3-0 **YEARL<3:0>:** Binary Coded Decimal value of years '1' digit; contains a value from 0 to 9

Note 1: Writes to the YEAR register is only allowed when RTCWREN = 1.

REGISTER 24-4: MONTH(1): MONTH VALUE REGISTER

U-0	U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	—	—	MONTHH	MONTHL<3:0>			
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7-5 **Unimplemented:** Read as '0'

bit 4 **MONTHH<0>:** Binary Coded Decimal value of months '10' digit; valid values from 0 to 1

bit 3-0 **MONTHL<3:0>:** Binary Coded Decimal value of months '1' digit; valid values from 0 to 9

Note 1: Writes to the MONTH registers are only allowed when RTCWREN = 1.

26.1 Timer1 Operation

The Timer1 modules are 16-bit incrementing counters which are accessed through the TMR1H:TMR1L register pairs. Writes to TMR1H or TMR1L directly update the counter.

When used with an internal clock source, the module is a timer and increments on every instruction cycle. When used with an external clock source, the module can be used as either a timer or counter and increments on every selected edge of the external source.

The timer is enabled by configuring the TMR1ON and GE bits in the T1CON and T1GCON registers, respectively. Table 26-1 displays the Timer1 enable selections.

TABLE 26-1: TIMER1 ENABLE SELECTIONS

TMR1ON	TMR1GE	Timer1 Operation
1	1	Count Enabled
1	0	Always On
0	1	Off
0	0	Off

26.2 Clock Source Selection

The T1CLK register is used to select the clock source for the timer. Register 26-3 shows the possible clock sources that may be selected to make the timer increment.

26.2.1 INTERNAL CLOCK SOURCE

When the internal clock source FOSC is selected, the TMR1H:TMR1L register pair will increment on multiples of FOSC as determined by the respective Timer1 prescaler.

When the FOSC internal clock source is selected, the timer register value will increment by four counts every instruction clock cycle. Due to this condition, a 2 LSB error in resolution will occur when reading the TMR1H:TMR1L value. To utilize the full resolution of the timer in this mode, an asynchronous input signal must be used to gate the timer clock input.

Out of the total timer gate signal sources, the following subset of sources can be asynchronous and may be useful for this purpose:

- CLC4 output
- CLC3 output
- CLC2 output
- CLC1 output
- Zero-Cross Detect output
- Comparator2 output
- Comparator1 output
- TxG PPS remappable input pin

26.2.2 EXTERNAL CLOCK SOURCE

When the timer is enabled and the external clock input source (ex: T1CKI PPS remappable input) is selected as the clock source, the timer will increment on the rising edge of the external clock input.

When using an external clock source, the timer can be configured to run synchronously or asynchronously, as described in **Section 26.5 "Timer Operation in Asynchronous Counter Mode"**.

When used as a timer with a clock oscillator, an external 32.768 kHz crystal can be used connected to the SOSCI/SOSCO pins.

Note: In Counter mode, a falling edge must be registered by the counter prior to the first incrementing rising edge after any one or more of the following conditions:

- The timer is first enabled after POR
- Firmware writes to TMR1H or TMR1L
- The timer is disabled
- The timer is re-enabled (e.g., TMR1ON-->1) when the T1CKI signal is currently logic low.

27.6 Timer2/4 Operation During Sleep

When PSYNC = 1, Timer2/4 cannot be operated while the processor is in Sleep mode. The contents of the TMR2 and T2PR registers will remain unchanged while processor is in Sleep mode.

When PSYNC = 0, Timer2/4 will operate in Sleep as long as the clock source selected is also still running. Selecting the LFINTOSC, MFINTOSC, or HFINTOSC oscillator as the timer clock source will keep the selected oscillator running during Sleep.

REGISTER 28-2: SMTxCON1: SMT CONTROL REGISTER 1

R/W/HC-0/0	R/W-0/0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
SMTxGO	REPEAT	—	—	MODE<3:0>			
bit 7							bit 0

Legend:		
HC = Bit is cleared by hardware		HS = Bit is set by hardware
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
‘1’ = Bit is set	‘0’ = Bit is cleared	q = Value depends on condition

bit 7 **SMTxGO:** SMT GO Data Acquisition bit
1 = Incrementing, acquiring data is enabled
0 = Incrementing, acquiring data is disabled

bit 6 **REPEAT:** SMT Repeat Acquisition Enable bit
1 = Repeat Data Acquisition mode is enabled
0 = Single Acquisition mode is enabled

bit 5-4 **Unimplemented**: Read as ‘0’

bit 3-0 **MODE<3:0>** SMT Operation Mode Select bits
1111 = Reserved
•
•
•
1011 = Reserved
1010 = Windowed counter
1001 = Gated counter
1000 = Counter
0111 = Capture
0110 = Time of flight
0101 = Gated windowed measure
0100 = Windowed measure
0011 = High and low time measurement
0010 = Period and Duty-Cycle Acquisition
0001 = Gated Timer
0000 = Timer

31.1.2 PUSH-PULL MODE

In Push-Pull mode, two output signals are generated, alternating copies of the input as illustrated in Figure 31-2. This alternation creates the push-pull effect required for driving some transformer-based power supply designs.

The push-pull sequencer is reset whenever EN = 0 or if an auto-shutdown event occurs. The sequencer is clocked by the first input pulse, and the first output appears on CWG1A.

The unused outputs CWG1C and CWG1D drive copies of CWG1A and CWG1B, respectively, but with polarity controlled by the POLC and POLD bits of the CWG1CON1 register, respectively.

31.1.3 FULL-BRIDGE MODES

In Forward and Reverse Full-Bridge modes, three outputs drive static values while the fourth is modulated by the input data signal. In Forward Full-Bridge mode, CWG1A is driven to its active state, CWG1B and CWG1C are driven to their inactive state, and CWG1D is modulated by the input signal. In Reverse Full-Bridge mode, CWG1C is driven to its active state, CWG1A and CWG1D are driven to their inactive states, and CWG1B is modulated by the input signal. In Full-Bridge mode, the dead-band period is used when there is a switch from forward to reverse or vice-versa. This dead-band control is described in **Section 31.5 "Dead-Band Control"**, with additional details in **Section 31.6 "Rising Edge and Reverse Dead Band"** and **Section 31.7 "Falling Edge and Forward Dead Band"**.

The mode selection may be toggled between forward and reverse toggling the MODE<0> bit of the CWG1CON0 while keeping MODE<2:1> static, without disabling the CWG module.

REGISTER 31-2: CWG1CON1: CWG1 CONTROL REGISTER 1

U-0	U-0	R-x	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	IN	—	POLD	POLC	POLB	POLA
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	q = Value depends on condition

bit 7-6 **Unimplemented:** Read as '0'

bit 5 **IN:** CWG Input Value bit

bit 4 **Unimplemented:** Read as '0'

bit 3 **POLD:** CWG1D Output Polarity bit
1 = Signal output is inverted polarity
0 = Signal output is normal polarity

bit 2 **POLC:** CWG1C Output Polarity bit
1 = Signal output is inverted polarity
0 = Signal output is normal polarity

bit 1 **POLB:** CWG1B Output Polarity bit
1 = Signal output is inverted polarity
0 = Signal output is normal polarity

bit 0 **POLA:** CWG1A Output Polarity bit
1 = Signal output is inverted polarity
0 = Signal output is normal polarity

33.5.3 SLAVE TRANSMISSION

When the R/$\overline{W}$ bit of the incoming address byte is set and an address match occurs, the R/$\overline{W}$ bit of the SSPxSTAT register is set. The received address is loaded into the SSPxBUF register, and an $\overline{ACK}$ pulse is sent by the slave on the ninth bit.

Following the $\overline{ACK}$, slave hardware clears the CKP bit and the SCL pin is held low (see **Section 33.5.6 "Clock Stretching"** for more detail). By stretching the clock, the master will be unable to assert another clock pulse until the slave is done preparing the transmit data.

The transmit data must be loaded into the SSPxBUF register which also loads the SSPxSR register. Then the SCL pin should be released by setting the CKP bit of the SSPxCON1 register. The eight data bits are shifted out on the falling edge of the SCL input. This ensures that the SDA signal is valid during the SCL high time.

The $\overline{ACK}$ pulse from the master-receiver is latched on the rising edge of the ninth SCL input pulse. This $\overline{ACK}$ value is copied to the ACKSTAT bit of the SSPxCON2 register. If ACKSTAT is set (not $\overline{ACK}$), then the data transfer is complete. When the not $\overline{ACK}$ is latched by the slave, the slave goes idle and waits for another occurrence of the Start bit. If the SDA line was low ($\overline{ACK}$), the next transmit data must be loaded into the SSPxBUF register. Again, the SCL pin must be released by setting bit CKP.

An MSSP interrupt is generated for each data transfer byte. The SSPxIF bit must be cleared by software and the SSPxSTAT register is used to determine the status of the byte. The SSPxIF bit is set on the falling edge of the ninth clock pulse.

33.5.3.1 Slave Mode Bus Collision

A slave receives a read request and begins shifting data out on the SDA line. If a bus collision is detected and the SBCDE bit of the SSPxCON3 register is set, the BCL1IF bit of the PIR3 register is set. Once a bus collision is detected, the slave goes idle and waits to be addressed again. User software can use the BCL1IF bit to handle a slave bus collision.

33.5.3.2 7-bit Transmission

A master device can transmit a read request to a slave, and then clock data out of the slave. The list below outlines what software for a slave will need to do to accomplish a standard transmission. Figure 33-18 can be used as a reference to this list.

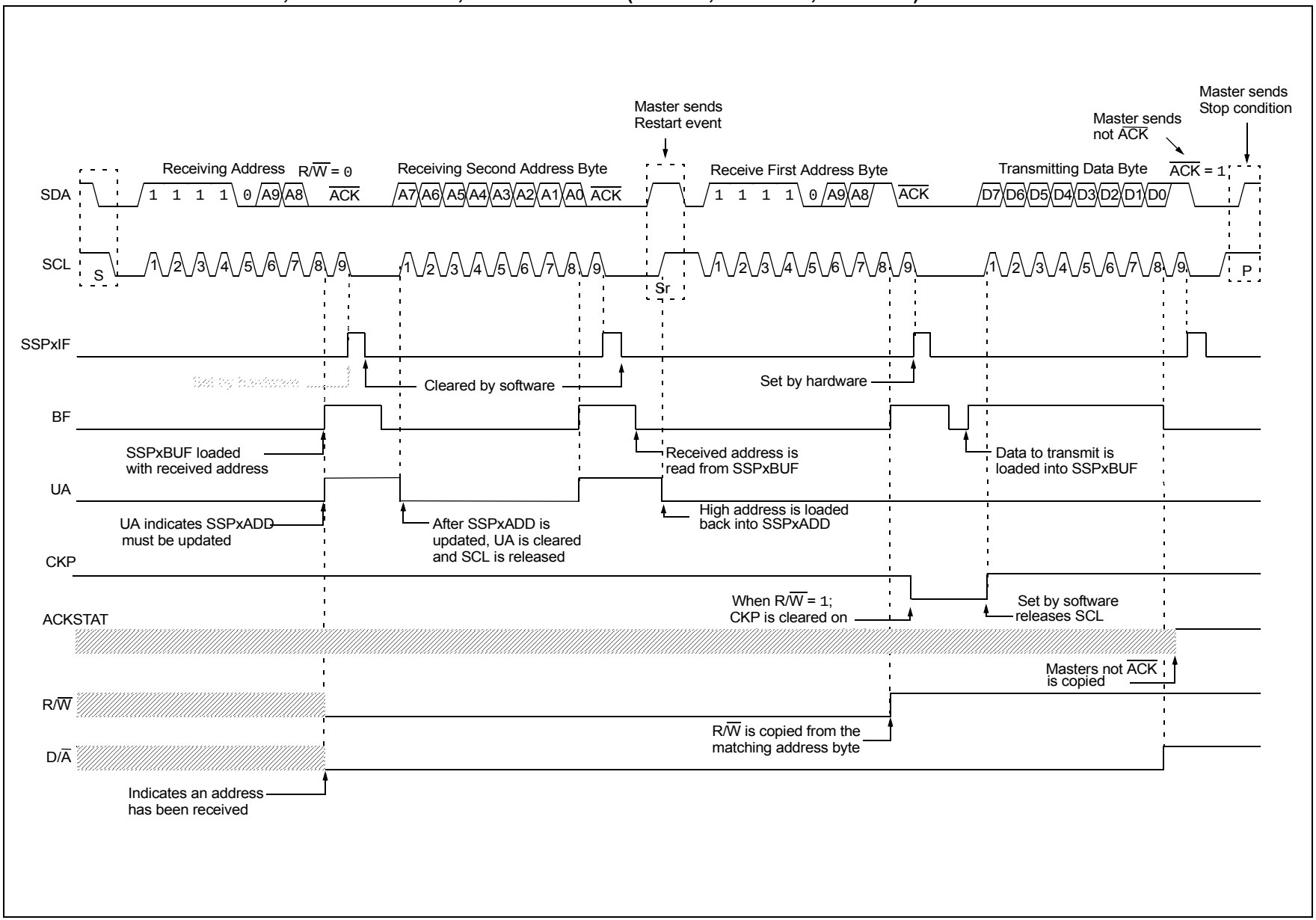
1. Master sends a Start condition on SDA and SCL.
2. S bit of SSPxSTAT is set; SSPxIF is set if interrupt on Start detect is enabled.
3. Matching address with R/$\overline{W}$ bit set is received by the Slave setting SSPxIF bit.
4. Slave hardware generates an $\overline{ACK}$ and sets SSPxIF.
5. SSPxIF bit is cleared by user.
6. Software reads the received address from SSPxBUF, clearing BF.
7. R/$\overline{W}$ is set so CKP was automatically cleared after the $\overline{ACK}$.
8. The slave software loads the transmit data into SSPxBUF.
9. CKP bit is set releasing SCL, allowing the master to clock the data out of the slave.
10. SSPxIF is set after the $\overline{ACK}$ response from the master is loaded into the ACKSTAT register.
11. SSPxIF bit is cleared.
12. The slave software checks the ACKSTAT bit to see if the master wants to clock out more data.

Note 1: If the master $\overline{ACK}$s the clock will be stretched.

2: ACKSTAT is the only bit updated on the rising edge of SCL (9th) rather than the falling.

13. Steps 9-13 are repeated for each transmitted byte.
14. If the master sends a not $\overline{ACK}$; the clock is not held, but SSPxIF is still set.
15. The master sends a Restart condition or a Stop.
16. The slave is no longer addressed.

FIGURE 33-22: I²C SLAVE, 10-BIT ADDRESS, TRANSMISSION (SEN = 0, AHEN = 0, DHEN = 0)



REGISTER 35-5: LCDVCON1: LCD VOLTAGE CONTROL 1 BITS

R/W-0/0	R/W-0/0	R-0	R-0	R-0	R/W-0/0	R/W-0/0	R/W-0/0
LPEN	EN5V	—	—	—	BIAS2	BIAS1	BIAS0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7 **LPEN**: LCD Charge Pump Low Power Enable (Low-Current (LC) mode enable)
1 = LCD Charge Pump is operating in Low-Current mode
0 = LCD Charge Pump is operating in Normal-Current mode

bit 6 **EN5V:** 5V Range Enable bit
1 = The pump generates 5.0V voltage range
0 = The pump generates 3.5V voltage range

bit 5-3 **Reserved**: Read as '0'

bit 2-0 **BIAS<2:0>:** Boost Pump Voltage Output Control bits (Only valid when LCDVSRC<2:0> = 100, 101, 110)
When EN5V = 0
111 = Set boost pump output to 3.50V
110 = Set boost pump output to 3.40V
101 = Set boost pump output to 3.30V
100 = Set boost pump output to 3.20V
011 = Set boost pump output to 3.10V
010 = Set boost pump output to 3.00V
001 = Set boost pump output to 2.90V
000 = Set boost pump output to 2.80V
When EN5V = 1
111 = Set boost pump output to 5.01V
110 = Set boost pump output to 4.83V
101 = Set boost pump output to 4.66V
100 = Set boost pump output to 4.48V
011 = Set boost pump output to 4.31V
010 = Set boost pump output to 4.13V
001 = Set boost pump output to 3.95V
000 = Set boost pump output to 3.78V

TABLE 38-1: REGISTER FILE SUMMARY FOR PIC16(L)F19155/56/75/76/85/86 DEVICES

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on page
51Bh	—	Unimplemented								
51Ch	—	Unimplemented								
51Dh	—	Unimplemented								
51Eh	—	Unimplemented								
51Fh	—	Unimplemented								
58Ch	—	Unimplemented								
58Dh	—	Unimplemented								
58Eh	—	Unimplemented								
58Fh	—	Unimplemented								
590h	—	Unimplemented								
591h	—	Unimplemented								
592h	—	Unimplemented								
593h	—	Unimplemented								
594h	—	Unimplemented								
595h	—	Unimplemented								
596h	—	Unimplemented								
597h	—	Unimplemented								
598h	—	Unimplemented								
599h	—	Unimplemented								
59Ah	—	Unimplemented								
59Bh	—	Unimplemented								
59Ch	TMR0L	TMR0L								
59Dh	TMR0H	TMR0H								
		T0PR								
59Eh	T0CON0	T0EN	—	T0OUT	T016BIT	T0OUTPS<3:0>				368
59Fh	T0CON1	T0CS<2:0>			T0ASYNC	T0CKPS<3:0>				369
60Ch	CWG1CLKCON	—	—	—	—	—	—	—	CS	492
60Dh	CWG1ISM	—	—	—	—	IS<3:0>				492
60Eh	CWG1DBR	—	—	DBR<5:0>						488
60Fh	CWG1DBF	—	—	DBF<5:0>						488
610h	CWG1CON0	EN	LD	—	—	—	MODE<2:0>			486
611h	CWG1CON1	—	—	IN	—	POLD	POLC	POLB	POLA	487
612h	CWG1AS0	SHUT-DOWN	REN	LSBD<1:0>		LSAC<1:0>		—	—	489
613h	CWG1AS1	—	—	—	AS4E	AS3E	AS2E	AS1E	AS0E	490
614h	CWG1STR	OVRD	OVRC	OVRB	OVRA	STRD	STRC	STRB	STRA	491
615h	—	Unimplemented								
616h	—	Unimplemented								
617h	—	Unimplemented								
618h	—	Unimplemented								
619h	—	Unimplemented								
61Ah	—	Unimplemented								
61Bh	—	Unimplemented								
61Ch	—	Unimplemented								
61Dh	—	Unimplemented								
61Eh	—	Unimplemented								
61Fh	—	Unimplemented								
68Ch	—	Unimplemented								

Legend: x = unknown, u = unchanged, q = depends on condition, - = unimplemented, read as '0', r = reserved. Shaded locations unimplemented, read as '0'.

Note 1: Unimplemented data memory locations, read as '0'.

TABLE 39-11: RESET, WDT, OSCILLATOR START-UP TIMER, POWER-UP TIMER, BROWN-OUT RESET AND LOW-POWER BROWN-OUT RESET SPECIFICATIONS

Standard Operating Conditions (unless otherwise stated)							
Param. No.	**Sym.**	**Characteristic**	**Min.**	**Typ†**	**Max.**	**Units**	**Conditions**
RST01*	TMCLR	$\overline{MCLR}$ Pulse Width Low to ensure Reset	2	—	—	µs	
RST02*	TIOZ	I/O high-impedance from Reset detection	—	—	2	µs	
RST03	TWDT	Watchdog Timer Time-out Period	—	16	—	ms	16 ms Nominal Reset Time
RST04*	TPWRT	Power-up Timer Period	—	65	—	ms	
RST05	VBOR	Brown-out Reset Voltage(4)	— — —	2.70 2.45 1.90	— — —	V V V	BORV = 0 BORV = 1 (PIC16F19155/56/75/76/85/86) BORV = 1 (PIC16(L)F19155/56/75/76/85/86)
RST06	VBORHYS	Brown-out Reset Hysteresis	—	40	—	mV	
RST07	TBORDC	Brown-out Reset Response Time	—	3	—	µs	
RST08	VLPBOR	Low-Power Brown-out Reset Voltage	—	2.45	—	V	

* These parameters are characterized but not tested.

† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: To ensure these voltage tolerances, VDD and VSS must be capacitively decoupled as close to the device as possible. 0.1 µF and 0.01 µF values in parallel are recommended.

TABLE 39-12: ANALOG-TO-DIGITAL CONVERTER (ADC) ACCURACY SPECIFICATIONS(1,2)

Standard Operating Conditions (unless otherwise stated) VDD = 3.0V, TA = 25°C							
Param. No.	**Sym.**	**Characteristic**	**Min.**	**Typ†**	**Max.**	**Units**	**Conditions**
AD01	NR	Resolution	—	—	12	bit	
AD02	EIL	Integral Error	—	±0.2	±1.0	LSb	ADCREF+ = 3.0V
AD03	EDL	Differential Error	—	±0.2	±1.0	LSb	ADCREF+ = 3.0V
AD04	EOFF	Offset Error	—	6	—	LSb	ADCREF+ = 3.0V
AD05	EGN	Gain Error	—	6	—	LSb	ADCREF+ = 3.0V
AD06	VADREF	ADC Reference Voltage	1.8	—	VDD	V	
AD07	VAIN	Full-Scale Range	—	—	ADREF+	V	
AD08	ZAIN	Recommended Impedance of Analog Voltage Source	—	1	—	kΩ	
AD09	RVREF	ADC Voltage Reference Ladder Impedance	—	50	—	kΩ	

* These parameters are characterized but not tested.

† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: Use of the ADC charge pump to improve linearity performance is recommended for VDD <= 2.5V

2: This is the impedance seen by the VREF pads when the external reference pads are selected.

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