Microchip Technology - PIC32MM0016GPL020T-I/SS Datasheet

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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	MIPS32® microAptiv™
Core Size	32-Bit Single-Core
Speed	25MHz
Connectivity	IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, HLVD, I²S, POR, PWM, WDT
Number of I/O	16
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 11x10/12b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	20-SSOP (0.209", 5.30mm Width)
Supplier Device Package	20-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic32mm0016gpl020t-i-ss

The MIPS® architecture defines that the result of a multiply or divide operation be placed in the HI and LO registers. Using the Move-From-HI (MFHI) and Move-From-LO (MFLO) instructions, these values can be transferred to the General Purpose Register file.

In addition to the HI/LO targeted operations, the MIPS architecture also defines a Multiply instruction, MUL, which places the least significant results in the primary register file instead of the HI/LO register pair. By avoiding the explicit MFLO instruction, required when using the LO register, and by supporting multiple destination registers, the throughput of multiply-intensive operations is increased.

Two other instructions, Multiply-Add (MADD) and Multiply-Subtract (MSUB), are used to perform the multiply-accumulate and multiply-subtract operations. The MADD instruction multiplies two numbers and then adds the product to the current contents of the HI and LO registers. Similarly, the MSUB instruction multiplies two operands and then subtracts the product from the HI and LO registers. The MADD and MSUB operations are commonly used in DSP algorithms.

3.2.3 SYSTEM CONTROL COPROCESSOR (CP0)

In the MIPS architecture, CP0 is responsible for the virtual-to-physical address translation, the exception control system, the processor's diagnostics capability, the operating modes (Kernel, User and Debug) and whether interrupts are enabled or disabled. These configuration options and other system information is available by accessing the CP0 registers listed in Table 3-2.

REGISTER 6-1: RCON: RESET CONTROL REGISTER(1) (CONTINUED)

bit 3 **SLEEP:** Wake from Sleep Flag bit
1 = Device was in Sleep mode
0 = Device was not in Sleep mode

bit 2 **IDLE:** Wake from Idle Flag bit(2)
1 = Device was in Idle mode
0 = Device was not in Idle mode

bit 1 **BOR:** Brown-out Reset Flag bit
1 = Brown-out Reset has occurred
0 = Brown-out Reset has not occurred

bit 0 **POR:** Power-on Reset Flag bit
1 = Power-on Reset has occurred
0 = Power-on Reset has not occurred

Note 1: User software must clear bits in this register to view the next detection.
2: The IDLE bit will also be set when the device wakes from Sleep mode.

REGISTER 6-2: RSWRST: SOFTWARE RESET REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
7:0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	W-0, HC
	—	—	—	—	—	—	—	SWRST(1,2)

Legend:	HC = Hardware Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-1 **Unimplemented:** Read as '0'

bit 0 **SWRST:** Software Reset Trigger bit(1,2)
1 = Enables Software Reset event
0 = No effect

Note 1: The system unlock sequence must be performed before the SWRST bit can be written. Refer to **Section 23.4 "System Registers Write Protection"** for details.
2: Once this bit is set, any read of the RSWRST register will cause a Reset to occur.

REGISTER 7-7: IPCx: INTERRUPT PRIORITY CONTROL REGISTER x(1)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	IP3<2:0>			IS3<1:0>	
23:16	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	IP2<2:0>			IS2<1:0>	
15:8	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	IP1<2:0>			IS1<1:0>	
7:0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	IP0<2:0>			IS0<1:0>	

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-29 **Unimplemented:** Read as '0'

bit 28-26 **IP3<2:0>:** Interrupt Priority bits
- 111 = Interrupt priority is 7
- •
- •
- •
- 010 = Interrupt priority is 2
- 001 = Interrupt priority is 1
- 000 = Interrupt is disabled

bit 25-24 **IS3<1:0>:** Interrupt Subpriority bits
- 11 = Interrupt subpriority is 3
- 10 = Interrupt subpriority is 2
- 01 = Interrupt subpriority is 1
- 00 = Interrupt subpriority is 0

bit 23-21 **Unimplemented:** Read as '0'

bit 20-18 **IP2<2:0>:** Interrupt Priority bits
- 111 = Interrupt priority is 7
- •
- •
- •
- 010 = Interrupt priority is 2
- 001 = Interrupt priority is 1
- 000 = Interrupt is disabled

bit 17-16 **IS2<1:0>:** Interrupt Subpriority bits
- 11 = Interrupt subpriority is 3
- 10 = Interrupt subpriority is 2
- 01 = Interrupt subpriority is 1
- 00 = Interrupt subpriority is 0

bit 15-13 **Unimplemented:** Read as '0'

Note 1: This register represents a generic definition of the IPCx register. Refer to Table 7-3 for the exact bit definitions.

REGISTER 7-7: IPCx: INTERRUPT PRIORITY CONTROL REGISTER x(1) (CONTINUED)

bit 12-10 **IP1<2:0>:** Interrupt Priority bits
111 = Interrupt priority is 7
•
•
•
010 = Interrupt priority is 2
001 = Interrupt priority is 1
000 = Interrupt is disabled

bit 9-8 **IS1<1:0>:** Interrupt Subpriority bits
11 = Interrupt subpriority is 3
10 = Interrupt subpriority is 2
01 = Interrupt subpriority is 1
00 = Interrupt subpriority is 0

bit 7-5 **Unimplemented:** Read as '0'

bit 4-2 **IP0<2:0>:** Interrupt Priority bits
111 = Interrupt priority is 7
•
•
•
010 = Interrupt priority is 2
001 = Interrupt priority is 1
000 = Interrupt is disabled

bit 1-0 **IS0<1:0>:** Interrupt Subpriority bits
11 = Interrupt subpriority is 3
10 = Interrupt subpriority is 2
01 = Interrupt subpriority is 1
00 = Interrupt subpriority is 0

Note 1: This register represents a generic definition of the IPCx register. Refer to Table 7-3 for the exact bit definitions.

9.9 I/O Ports Control Registers

TABLE 9-4: PORTA REGISTER MAP

Virtual Address (BF80_#)	Register Name(3)	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
2600	ANSELA	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	ANSA<3:0>				000F
2610	TRISA	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	TRISA9(1,2)	—	—	—	—	TRISA<4:0>					021F
2620	PORTA	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	RA9(1,2)	—	—	—	—	RA<4:0>					xxxx
2630	LATA	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	LATA9(1,2)	—	—	—	—	LATA<4:0>					0000
2640	ODCA	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	ODCA9(1,2)	—	—	—	—	ODCA<4:0>					0000
2650	CNPUA	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	CNPUA9(1,2)	—	—	—	—	CNPUA<4:0>					0000
2660	CNPDA	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	CNPDA9(1,2)	—	—	—	—	CNPDA<4:0>					0000
2670	CNCONA	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	ON	—	—	—	CNSTYLE	—	—	—	—	—	—	—	—	—	—	—	0000
2680	CNEN0A	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	CNIEA9(1,2)	—	—	—	—	CNIEA<4:0>					0000
2690	CNSTATA	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	CNSTATA9(1,2)	—	—	—	—	CNSTATA<4:0>					0000
26A0	CNEN1A	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	CNIE1A9(1,2)	—	—	—	—	CNIE1A<4:0>					0000
26B0	CNFA	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	CNFA9(1,2)		—	—	—	CNFA<4:0>					0000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: These bits are not implemented in 20-pin devices.

2: These bits are not implemented in 28-pin devices.

3: All registers in this table have corresponding CLR, SET and INV registers at their virtual address, plus an offset of 0x4, 0x8 and 0xC, respectively.

12.0 CAPTURE/COMPARE/PWM/ TIMER MODULES (MCCP AND SCCP)

Note: This data sheet summarizes the features of the PIC32MM0064GPL036 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 30. "Capture/Compare/PWM/Timer (MCCP and SCCP)"** (DS60001381) in the *"PIC32 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com/PIC32). The information in this data sheet supersedes the information in the FRM.

12.1 Introduction

PIC32MM0064GPL036 family devices include three Capture/Compare/PWM/Timer (CCP) modules. These modules are similar to the multipurpose timer modules found on many other 32-bit microcontrollers. They also provide the functionality of the comparable input capture, output compare and general purpose timer peripherals found in all earlier PIC32 devices.

CCP modules can operate in one of three major modes:

- General Purpose Timer
- Input Capture
- Output Compare/PWM

There are two different forms of the module, distinguished by the number of PWM outputs that the module can generate. Single Capture/Compare/PWM/Timer (SCCPs) output modules provide only one PWM output. Multiple Capture/Compare/PWM/Timer (MCCPs) output modules can provide up to six outputs and an extended range of output control features, depending on the pin count of the particular device.

All modules (SCCP and MCCP) include these features:

- User-Selectable Clock Inputs, including System Clock and External Clock Input Pins
- Input Clock Prescaler for Time Base
- Output Postscaler for module Interrupt Events or Triggers
- Synchronization Output Signal for Coordinating other MCCP/SCCP modules with User-Configurable Alternate and Auxiliary Source Options
- Fully Asynchronous Operation in all modes and in Low-Power Operation
- Special Output Trigger for ADC Conversions
- 16-Bit and 32-Bit General Purpose Timer modes with Optional Gated Operation for Simple Time Measurements
- Capture modes:
  - Backward compatible with previous input capture peripherals of the PIC32 family
  - 16-bit or 32-bit capture of time base on external event
  - Up to four-level deep FIFO capture buffer
  - Capture source input multiplexer
  - Gated capture operation to reduce noise-induced false captures
- Output Compare/PWM modes:
  - Backward compatible with previous output compare peripherals of the PIC32 family
  - Single Edge and Dual Edge Compare modes
  - Center-Aligned Compare mode
  - Variable Frequency Pulse mode
  - External Input mode

MCCP modules also include these extended PWM features:

- Single Output Steerable mode
- Brush DC Motor (Forward and Reverse) modes
- Half-Bridge with Dead-Time Delay mode
- Push-Pull PWM mode
- Output Scan mode
- Auto-Shutdown with Programmable Source and Shutdown State
- Programmable Output Polarity

The SCCP and MCCP modules can be operated in only one of the three major modes (Capture, Compare or Timer) at any time. The other modes are not available unless the module is reconfigured.

A conceptual block diagram for the module is shown in Figure 12-1. All three modes use the time base generator and the common Timer register pair (CCPxTMR). Other shared hardware components, such as comparators and buffer registers, are activated and used as a particular mode requires.

NOTES:

REGISTER 13-3: SPIxSTAT: SPIx STATUS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	R-0	R-0	R-0	R-0	R-0
	—	—	—	RXBUFELM<4:0>				
23:16	U-0	U-0	U-0	R-0	R-0	R-0	R-0	R-0
	—	—	—	TXBUFELM<4:0>				
15:8	U-0	U-0	U-0	R/C-0, HS	R-0	U-0	U-0	R-0
	—	—	—	FRMERR	SPIBUSY	—	—	SPITUR
7:0	R-0	R/W-0	R-0	U-0	R-1	U-0	R-0	R-0
	SRMT	SPIROV	SPIRBE	—	SPITBE	—	SPITBF	SPIRBF

Legend:	C = Clearable bit	HS = Hardware Settable bit	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-29 **Unimplemented:** Read as '0'

bit 28-24 **RXBUFELM<4:0>:** Receive Buffer Element Count bits (valid only when ENHBUF = 1)

bit 23-21 **Unimplemented:** Read as '0'

bit 20-16 **TXBUFELM<4:0>:** Transmit Buffer Element Count bits (valid only when ENHBUF = 1)

bit 15-13 **Unimplemented:** Read as '0'

bit 12 **FRMERR:** SPIx Frame Error status bit
1 = Frame error is detected
0 = No frame error is detected
This bit is only valid when FRMEN = 1.

bit 11 **SPIBUSY:** SPIx Activity Status bit
1 = SPIx peripheral is currently busy with some transactions
0 = SPIx peripheral is currently Idle

bit 10-9 **Unimplemented:** Read as '0'

bit 8 **SPITUR:** SPIx Transmit Underrun (TUR) bit
1 = Transmit buffer has encountered an underrun condition
0 = Transmit buffer has no underrun condition
This bit is only valid in Framed Sync mode; the underrun condition must be cleared by disabling/re-enabling the module.

bit 7 **SRMT:** Shift Register Empty bit (valid only when ENHBUF = 1)
1 = When the SPIx Shift register is empty
0 = When the SPIx Shift register is not empty

bit 6 **SPIROV:** SPIx Receive Overflow (ROV) Flag bit
1 = New data is completely received and discarded; the user software has not read the previous data in the SPIxBUF register
0 = No overflow has occurred
This bit is set in hardware; it can only be cleared (= 0) in software.

bit 5 **SPIRBE:** SPIx RX FIFO Empty bit (valid only when ENHBUF = 1)
1 = RX FIFO is empty (CPU Read Pointer (CRPTR) = SPI Write Pointer (SWPTR))
0 = RX FIFO is not empty (CRPTR ≠ SWPTR)

bit 4 **Unimplemented:** Read as '0'

TABLE 23-4: ALTERNATE CONFIGURATION WORDS SUMMARY

Virtual Address (BFC0_#)	Register Name	Bit Range	Bits															
			31\15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0
1740	RESERVED	31:16	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1
		15:0	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1
1744	AFDEVOPT	31:16	USERID<15:0>															
		15:0	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	SOSCHP	r-1	r-1	r-1
1748	AFICD	31:16	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1
		15:0	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	ICS<1:0>		JTAGEN	r-1	r-1
174C	AFPOR	31:16	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1
		15:0	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	LPBOREN	RETVR	BOREN<1:0>	
1750	AFWDT	31:16	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1
		15:0	FWDTEN	RCLKSEL<1:0>		RWDTPS<4:0>					WINDIS	FWDTWINSZ<1:0>		SWDTPS<4:0>				
1754	AFOSCSEL	31:16	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1
		15:0	FCKSM<1:0>		r-1	SOSCSEL	r-1	OSCIOFNC	POSCMOD<1:0>		IESO	SOSCEN	r-1	PLLSRC	r-1	FNOSC<2:0>		
1758	AFSEC	31:16	CP	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1
		15:0	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1
175C	RESERVED	31:16	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1
		15:0	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1
1760	RESERVED	31:16	r-0	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1
		15:0	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1
1764	RESERVED	31:16	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1
		15:0	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1

Legend: r-0 = Reserved bit, must be programmed as '0'; r-1 = Reserved bit, must be programmed as '1'.

25.0 INSTRUCTION SET

The PIC32MM0064GPL036 family instruction set complies with the MIPS® Release 3 instruction set architecture. Only microMIPS32™ instructions are supported. The PIC32MM0064GPL036 family does not have the following features:

- Core extend instructions
- Coprocessor 1 instructions
- Coprocessor 2 instructions

Note: Refer to the *"MIPS® Architecture for Programmers Volume II-B: The microMIPS32™ Instruction Set"* at www.imgtec.com for more information.

TABLE 26-10: I/O PIN OUTPUT SPECIFICATIONS

Operating Conditions: 2.0V ≤ VDD ≤ 3.6V, -40°C ≤ TA ≤ +85°C (unless otherwise stated)						
Param No.	**Symbol**	**Characteristic**	**Min**	**Max**	**Units**	**Conditions**
	VOL	**Output Low Voltage**				
DO10		I/O Ports	—	0.36	V	IOL = 6.0 mA, VDD = 3.6V
			—	0.21	V	IOL = 3.0 mA, VDD = 2V
DO16		RA3, RB8, RB9 and RB15 I/O Ports	—	0.16	V	IOL = 6.0 mA, VDD = 3.6V
			—	0.12	V	IOL = 3.0 mA, VDD = 2V
	VOH	**Output High Voltage**				
DO20		I/O Ports	3.25	—	V	IOH = -6.0 mA, VDD = 3.6V
			1.4	—	V	IOH = -3.0 mA, VDD = 2V
DO26		RA3, RB8, RB9 and RB15 I/O Ports	3.3	—	V	IOH = -6.0 mA, VDD = 3.6V
			1.55	—	V	IOH = -3.0 mA, VDD = 2V

TABLE 26-11: PROGRAM FLASH MEMORY SPECIFICATIONS

Operating Conditions: 2.0V ≤ VDD ≤ 3.6V, -40°C ≤ TA ≤ +85°C (unless otherwise stated)							
Param No.	**Symbol**	**Characteristic**	**Min**	**Typ(1)**	**Max**	**Units**	**Conditions**
D130	EP	Cell Endurance	10000	20000	—	E/W	
D131	VICSP	VDD for In-Circuit Serial Programming™ (ICSP™)	VBOR	—	3.6	V	
D132	VRTSP	VDD for Run-Time Self-Programming (RTSP)	2.0	—	3.6	V	
D133	TIW	Self-Timed Double-Word Write Cycle Time	19.7	21.0	22.3	µs	8 bytes, data is not all ‘1’s
		Self-Timed Row Write Cycle Time	1.3	1.4	1.5	ms	256 bytes, data is not all ‘1’s, SYSCLK > 2 MHz
D133	TIE	Self-Timed Page Erase Time	15.0	16.0	17.0	ms	2048 bytes
D134	TRETD	Characteristic Retention	20	—	—	Year	If no other specifications are violated
D136	TCE	Self-Timed Chip Erase Time	16.0	17.0	18.0	ms	

Note 1: Data in the “Typ” column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

TABLE 26-14: COMPARATOR SPECIFICATIONS

Operating Conditions: 2.0V < VDD < 3.6V, -40°C < TA < +85°C (unless otherwise stated)						
Param No.	**Symbol**	**Characteristic**	**Min**	**Typ(2)**	**Max**	**Units**
D300	VIOFF	Input Offset Voltage	-20	—	20	mV
D301	VICM	Input Common-Mode Voltage	AVSS – 0.3V	—	AVDD + 0.3V	V
D307	TRESP(1)	Response Time	—	150	—	ns

Note 1: Measured with one input at VDD/2 and the other transitioning from VSS to VDD.

2: Data in the "Typ" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

TABLE 26-15: VOLTAGE REFERENCE SPECIFICATIONS

Operating Conditions: 2.0V < VDD < 3.6V, -40°C < TA < +85°C (unless otherwise stated)						
Param No.	**Symbol**	**Characteristic**	**Min**	**Typ(2)**	**Max**	**Units**
VRD310	TSET	Settling Time(1)	—	—	10	µs
VRD311	VRA	Accuracy	-1	—	1	LSb
VRD312	VRUR	Unit Resistor Value (R)	—	4.5	—	kΩ

Note 1: Measures the interval while VRDAT<4:0> transitions from '11111' to '00000'.

2: Data in the "Typ" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

FIGURE 26-5: TIMER1 EXTERNAL CLOCK TIMING CHARACTERISTICS

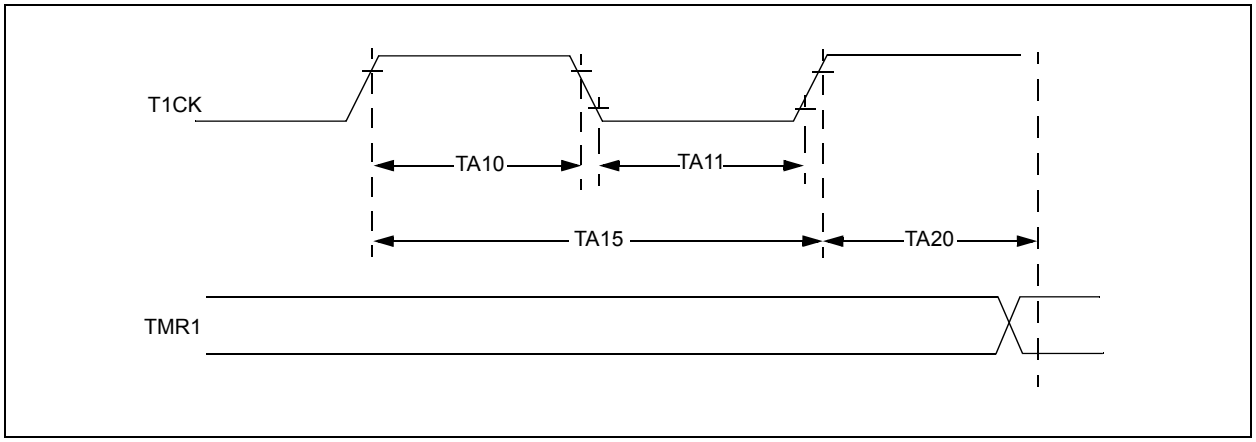


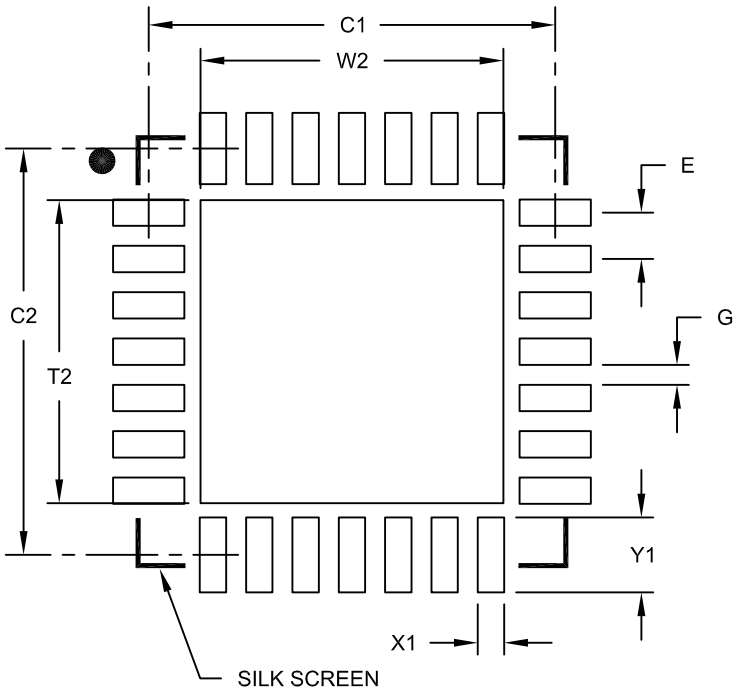
TABLE 26-23: MCCP/SCCP TIMER1 EXTERNAL CLOCK TIMING CHARACTERISTICS

Operating Conditions: 2.0V ≤ VDD ≤ 3.6V, -40°C ≤ TA ≤ +85°C (unless otherwise stated)							
Param. No.	**Symbol**	**Characteristics(1)**		**Min**	**Max**	**Units**	**Conditions**
TA10	TCKH	T1CK High Time	Synchronous	1	—	TPBCLK	Must also meet Parameter TA15
			Asynchronous	10	—	ns	
TA11	TCKL	T1CK Low Time	Synchronous	1	—	TPBCLK	Must also meet Parameter TA15
			Asynchronous	10	—	ns	
TA15	TCKP	T1CK Input Period	Synchronous	2	—	TPBCLK	
			Asynchronous	20	—	ns	
TA20	TCKEXTMRL	Delay from External T1CK Clock Edge to Timer Increment		—	3	TPBCLK	Synchronous mode

Note 1: These parameters are characterized but not tested in manufacturing.

28-Lead Plastic Quad Flat, No Lead Package (ML) – 6x6 mm Body [QFN] with 0.55 mm Contact Length

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E		0.65 BSC	
Optional Center Pad Width	W2			4.25
Optional Center Pad Length	T2			4.25
Contact Pad Spacing	C1		5.70	
Contact Pad Spacing	C2		5.70	
Contact Pad Width (X28)	X1			0.37
Contact Pad Length (X28)	Y1			1.00
Distance Between Pads	G	0.20		

Notes:

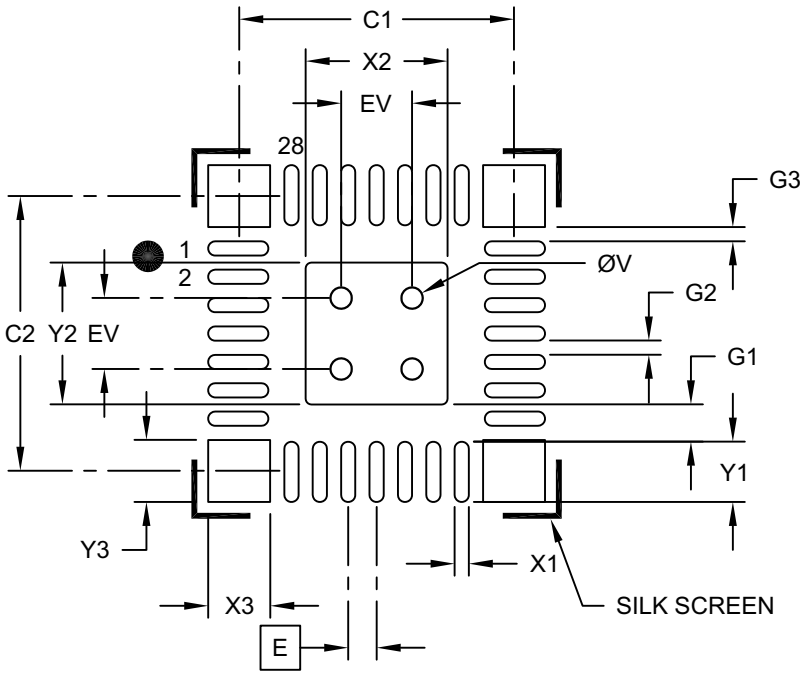
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2105A

28-Lead Ultra Thin Plastic Quad Flat, No Lead Package (M6) - 4x4x0.6 mm Body [UQFN] With Corner Anchors

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E		0.40 BSC	
Center Pad Width	X2			2.00
Center Pad Length	Y2			2.00
Contact Pad Spacing	C1		3.90	
Contact Pad Spacing	C2		3.90	
Contact Pad Width (X28)	X1			0.20
Contact Pad Length (X28)	Y1			0.85
Contact Pad to Center Pad (X28)	G1		0.52	
Contact Pad to Pad (X24)	G2	0.20		
Contact Pad to Corner Pad (X8)	G3	0.20		
Corner Anchor Width (X4)	X3			0.78
Corner Anchor Length (X4)	Y3			0.78
Thermal Via Diameter	V		0.30	
Thermal Via Pitch	EV		1.00	

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-2333-M6 Rev B

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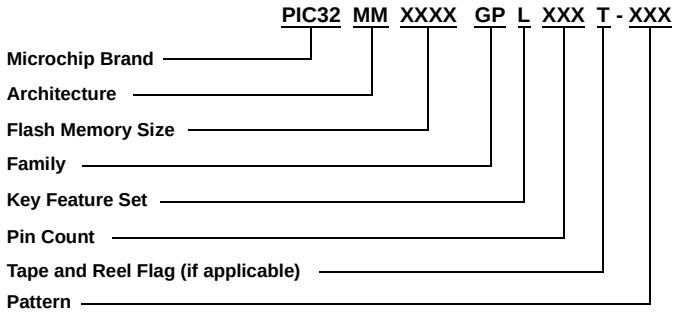

Architecture	MM	= MIPS32® microAptiv™ UC CPU Core
Flash Memory Size	0016 0032 0064	= 16 Kbytes = 32 Kbytes = 64 Kbytes
Family	GP	= General Purpose Family
Key Feature	L	= Up to 25 MHz operating frequency with basic peripheral set of 2 UART and 2 SPI modules
Pin Count	020 028 036	= 20-pin = 28-pin = 36/40-pin
Pattern	Three-digit QTP, SQTP, Code or Special Requirements (blank otherwise) ES	= Engineering Sample

Example:

PIC32MM0064GPL036-I/M2: PIC32 General Purpose Device with MIPS32® microAptiv™ UC Core, 64-Kbyte Program Memory, 36-Pin Package.

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