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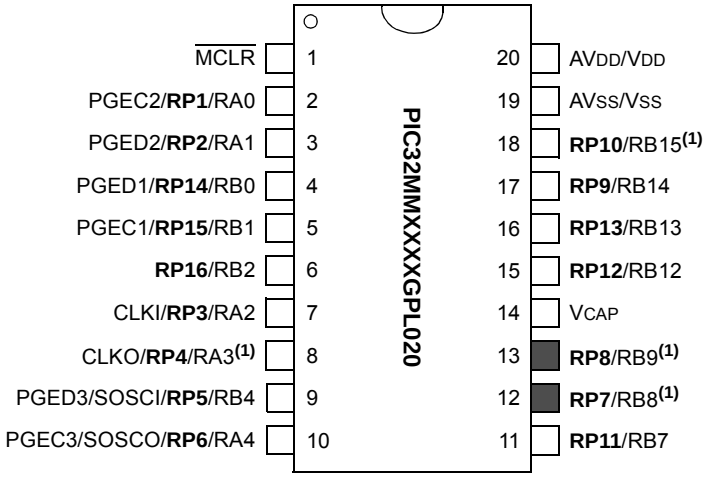
Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	MIPS32® microAptiv™
Core Size	32-Bit Single-Core
Speed	25MHz
Connectivity	IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, HLVD, I²S, POR, PWM, WDT
Number of I/O	22
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 12x10/12b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic32mm0032gpl028-i-ss

Pin Diagrams

20-Pin SSOP



Legend: Shaded pins are up to 5V tolerant.

Note 1: Pin has an increased current drive strength. Refer to **Section 26.0 "Electrical Characteristics"** for details.

TABLE 2: COMPLETE PIN FUNCTION DESCRIPTIONS FOR 20-PIN SSOP DEVICES

Pin	Function	Pin	Function
1	$\overline{\text{MCLR}}$	11	**RP11**/RB7
2	PGEC2/VREF+/AN0/**RP1**/OCM1E/INT3/RA0	12	TCK/**RP7**/$\overline{\text{U1CTS}}$/SCK1/OCM1A/RB8(1)
3	PGED2/VREF-/AN1/**RP2**/OCM1F/RA1	13	TMS/REFCLKI/**RP8**/T1CK/T1G/$\overline{\text{U1RTS}}$/U1BCLK/SDO1/C2OUT/OCM1B/INT2/RB9(1)
4	PGED1/AN2/C1IND/C2INB/**RP14**/RB0	14	VCAP
5	PGEC1/AN3/C1INC/C2INA/**RP15**/RB1	15	TDO/AN7/LVDIN/**RP12**/RB12
6	AN4/**RP16**/RB2	16	TDI/AN8/**RP13**/RB13
7	OSC1/CLKI/AN5/C1INB/**RP3**/OCM1C/RA2	17	CDAC1/AN9/**RP9**/RTCC/U1TX/SDI1/C1OUT/INT1/RB14
8	OSC2/CLKO/AN6/C1INA/**RP4**/OCM1D/RA3(1)	18	AN10/REFCLKO/**RP10**/U1RX/$\overline{\text{SS1}}$/FSYNC1/INT0/RB15(1)
9	PGED3/SOSCI/**RP5**/RB4	19	AVSS/VSS
10	PGEC3/SOSCO/SCLKI/**RP6**/PWRLCLK/RA4	20	AVDD/VDD

Note 1: Pin has an increased current drive strength.

NOTES:

3.0 CPU

Note: This data sheet summarizes the features of the PIC32MM0064GPL036 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 50. "CPU for Devices with MIPS32® microAptiv™ and M-Class Cores"** (DS60001192) in the *"PIC32 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com/PIC32). MIPS32® microAptiv™ UC microprocessor core resources are available at: www.imgtec.com. The information in this data sheet supersedes the information in the FRM.

The MIPS32® microAptiv™ UC microprocessor core is the heart of the PIC32MM0064GPL036 family devices. The CPU fetches instructions, decodes each instruction, fetches source operands, executes each instruction and writes the results of the instruction execution to the proper destinations.

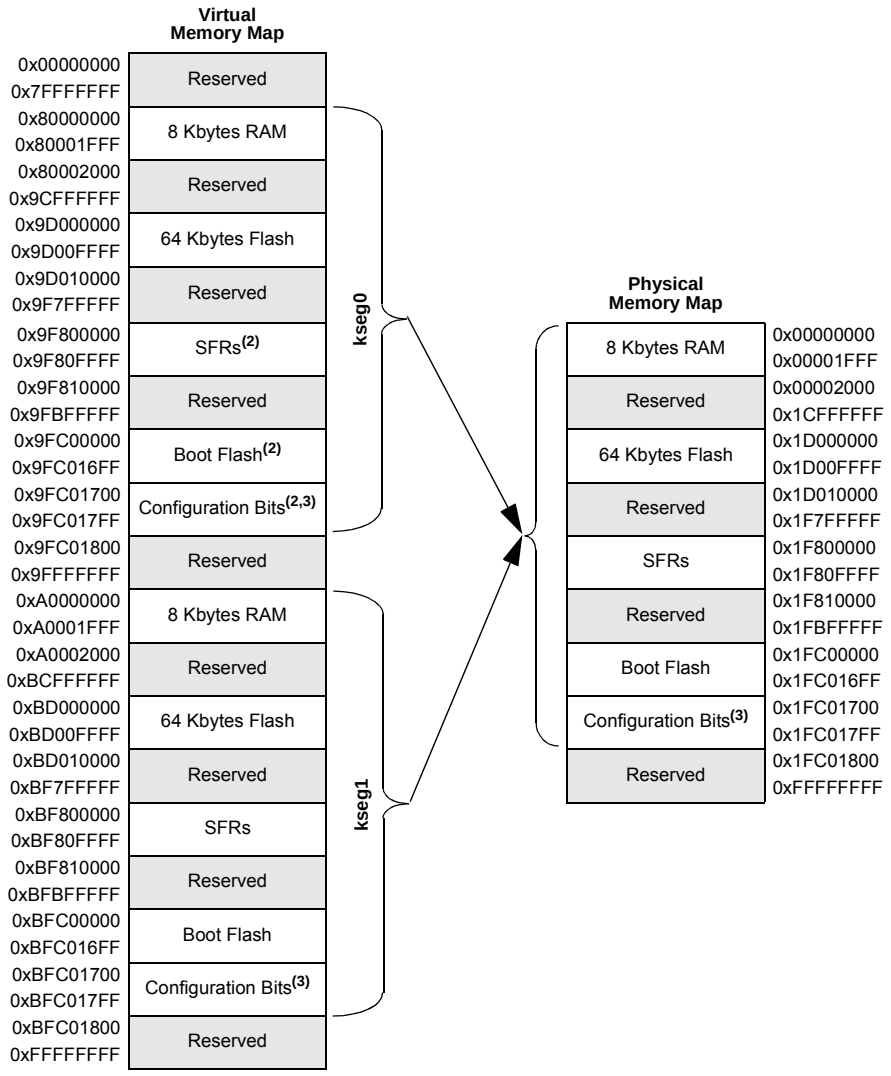
3.1 Features

The PIC32MM0064GPL036 family processor core key features include:

- 5-Stage Pipeline
- 32-Bit Address and Data Paths
- MIPS32 Enhanced Architecture:
  - Multiply-add and multiply-subtract instructions
  - Targeted multiply instruction
  - Zero and one detect instructions
  - `WAIT` instruction
  - Conditional move instructions
  - Vectored interrupts
  - Atomic interrupt enable/disable
  - One GPR shadow set to minimize latency of interrupts
  - Bit field manipulation instructions
- microMIPS™ Instruction Set:
  - microMIPS allows improving the code size density over MIPS32, while maintaining MIPS32 performance.
  - microMIPS supports all MIPS32 instructions (except for branch-likely instructions) with new optimized 32-bit encoding. Frequent MIPS32 instructions are available as 16-bit instructions.
  - Added seventeen new and thirty-five MIPS32® corresponding commonly used instructions in 16-bit opcode format.
  - Stack Pointer implicit in instruction.
  - MIPS32 assembly and ABI compatible.
- Memory Management Unit with Simple Fixed Mapping Translation (FMT) Mechanism
- Multiply/Divide Unit (MDU):
  - Configurable using high-performance multiplier array.
  - Maximum issue rate of one 32x16 multiply per clock.
  - Maximum issue rate of one 32x32 multiply every other clock.
  - Early-in iterative divide. Minimum 11 and maximum 33 clock latency (dividend (rs) sign extension dependent).
- Power Control:
  - No minimum frequency: 0 MHz.
  - Power-Down mode (triggered by `WAIT` instruction).
- EJTAG Debug/Profiling:
  - CPU control with start, stop and single stepping.
  - Software breakpoints via the `SDBBP` instruction.
  - Optional simple hardware breakpoints on virtual addresses, 4 instruction and 2 data breakpoints.
  - PC and/or load/store address sampling for profiling.
  - Performance counters.
  - Supports Fast Debug Channel (FDC).

A block diagram of the PIC32MM0064GPL036 family processor core is shown in Figure 3-1.

FIGURE 4-3: MEMORY MAP FOR DEVICES WITH 64 Kbytes OF PROGRAM MEMORY(1)



Note 1: Memory areas are not shown to scale.

2: This region should be accessed from kseg1 space only.

3: Primary Configuration bits area is located at the address range, from 0x1FC01780 to 0x1FC017E8. Alternate Configuration bits area is located at the address range, from 0x1FC01700 to 0x1FC01768. Refer to **Section 4.1 "Alternate Configuration Bits Space"** for more information.

5.2 Flash Control Registers

TABLE 5-1: FLASH CONTROLLER REGISTER MAP

Virtual Address (BF80_#)	Register Name	Bit Range	Bits															All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
2380	NVMCON(1)	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	WR	WREN	WRERR	LVDERR	—	—	—	—	—	—	—	—	NVMOP<3:0>				0000
2390	NVMKEY	31:16	NVMKEY<31:0>																0000
		15:0																	0000
23A0	NVMADDR(1)	31:16	NVMADDR<31:0>																0000
		15:0																	0000
23B0	NVMDATA0	31:16	NVMDATA0<31:0>																0000
		15:0																	0000
23C0	NVMDATA1	31:16	NVMDATA1<31:0>																0000
		15:0																	0000
23D0	NVMSRCADDR	31:16	NVMSRCADDR<31:0>																0000
		15:0																	0000
23E0	NVMPWP(1)	31:16	PWPULOCK	—	—	—	—	—	—	—	PWP<23:16>								8000
		15:0	PWP<15:0>																0000
23F0	NVMBWP(1)	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	BWPULOCK	—	—	—	—	BWP<2:0>			—	—	—	—	—	—	—	—	8700

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: These registers have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively.

REGISTER 6-4: PWRCON: POWER CONTROL REGISTER(1)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
7:0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
	—	—	—	—	—	SBOREN(3)	RETEN(2)	VREGS(2)

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-3 **Unimplemented:** Read as '0'

bit 2 **SBOREN:** BOR During Sleep Control bit(3)
- 1 = BOR is turned on
- 0 = BOR is turned off

bit 1 **RETEN:** Output Level of the Regulator During Sleep Selection bit(2)
- 1 = Writing a '1' to this bit will cause the main regulator to be put in a low-power state during Sleep mode
- 0 = Writing a '0' to this bit will have no effect

bit 0 **VREGS:** Voltage Regulator Standby Enable bit(2)
- 1 = Voltage regulator will remain active during Sleep mode
- 0 = Voltage regulator will go to Standby mode during Sleep mode

Note 1: Writes to this register require an unlock sequence. Refer to **Section 23.4 "System Registers Write Protection"** for details.

2: Refer to **Section 22.4 "On-Chip Voltage Regulator Low-Power Modes"** for details.

3: This bit is enabled only when the BOREN<1:0> Configuration bits (FPOR<1:0>) are set to '01'.

TABLE 7-1: MIPS32® microAptiv™ UC MICROPROCESSOR CORE EXCEPTION TYPES (CONTINUED)

Exception Type (In Order of Priority)	Description	Branches to	Status Bits Set	Debug Bits Set	EXCCODE	XC32 Function Name
CpU	Execution of a coprocessor instruction for a coprocessor that is not enabled.	EBASE + 0x180	CU, EXL	—	CpU (0x0B)	_general_exception_handler
RI	Execution of a reserved instruction.	EBASE + 0x180	EXL	—	RI (0x0A)	_general_exception_handler
Ov	Execution of an arithmetic instruction that overflowed.	EBASE + 0x180	EXL	—	Ov (0x0C)	_general_exception_handler
Tr	Execution of a trap (when trap condition is true).	EBASE + 0x180	EXL	—	Tr (0x0D)	_general_exception_handler
DDBL	EJTAG data address break (address only) or EJTAG data value break on load (address and value).	0xBFC0_0480 (ProbEn = 0 in ECR) 0xBFC0_0200 (ProbEn = 1 in ECR)	—	DDBL for a load instruction or DDBS for a store instruction	—	—
DDBS	EJTAG data address break (address only) or EJTAG data value break on store (address and value).	0xBFC0_0480 (ProbEn = 0 in ECR) 0xBFC0_0200 (ProbEn = 1 in ECR)	—	DDBL for a load instruction or DDBS for a store instruction	—	—
AdES	Store address alignment error.	EBASE + 0x180	EXL	—	ADES (0x05)	_general_exception_handler
DBE	Load or store bus error.	EBASE + 0x180	EXL	—	DBE (0x07)	_general_exception_handler
CBrk	EJTAG complex breakpoint.	0xBFC0_0480 (ProbEn = 0 in ECR) 0xBFC0_0200 (ProbEn = 1 in ECR)	—	DIBImpr, DDBLImpr and/or DDBSImpr	—	—
Lowest Priority						

TABLE 7-2: INTERRUPTS (CONTINUED)

Interrupt Source	MPLAB® XC32 Vector Name	Vector Number	Interrupt Related Bits Location				Persistent Interrupt
			Flag	Enable	Priority	Subpriority	
UART1 Reception	_UART1_RX_VECTOR	23	IFS0<23>	IEC0<23>	IPC5<28:26>	IPC5<25:24>	Yes
UART1 Transmission	_UART1_TX_VECTOR	24	IFS0<24>	IEC0<24>	IPC6<4:2>	IPC6<1:0>	Yes
UART1 Error	_UART1_ERR_VECTOR	25	IFS0<25>	IEC0<25>	IPC6<12:10>	IPC6<9:8>	Yes
CCP1 Input Capture or Output Compare	_CCP1_VECTOR	29	IFS0<29>	IEC0<29>	IPC7<12:10>	IPC7<9:8>	No
CCP1 Timer	_CCT1_VECTOR	30	IFS0<30>	IEC0<30>	IPC7<20:18>	IPC7<17:16>	No
CCP2 Input Capture or Output Compare	_CCP2_VECTOR	31	IFS0<31>	IEC0<31>	IPC7<28:26>	IPC7<25:24>	No
CCP2 Timer	_CCT2_VECTOR	32	IFS1<0>	IEC1<0>	IPC8<4:2>	IPC8<1:0>	No
CCP3 Input Capture or Output Compare	_CCP3_VECTOR	33	IFS1<1>	IEC1<1>	IPC8<12:10>	IPC8<9:8>	No
CCP3 Timer	_CCT3_VECTOR	34	IFS1<2>	IEC1<2>	IPC8<20:18>	IPC8<17:16>	No
RESERVED	—	35	—	—	—	—	—
RESERVED	—	36	—	—	—	—	—
SPI2 Error	_SPI2_ERR_VECTOR	37	IFS1<5>	IEC1<5>	IPC9<12:10>	IPC9<9:8>	Yes
SPI2 Transmission	_SPI2_TX_VECTOR	38	IFS1<6>	IEC1<6>	IPC9<20:18>	IPC9<17:16>	Yes
SPI2 Reception	_SPI2_RX_VECTOR	39	IFS1<7>	IEC1<7>	IPC9<28:26>	IPC9<25:24>	Yes
UART2 Reception	_UART2_RX_VECTOR	40	IFS1<8>	IEC1<8>	IPC10<4:2>	IPC10<1:0>	Yes
UART2 Transmission	_UART2_TX_VECTOR	41	IFS1<9>	IEC1<9>	IPC10<12:10>	IPC10<9:8>	Yes
UART2 Error	_UART2_ERR_VECTOR	42	IFS1<10>	IEC1<10>	IPC10<20:18>	IPC10<17:16>	Yes
NVM Program or Erase Complete	_NVM_VECTOR	46	IFS1<14>	IEC1<14>	IPC11<20:18>	IPC11<17:16>	Yes
Core Performance Counter	_PERFORMANCE_COUNTER_VECTOR	47	IFS1<15>	IEC1<15>	IPC11<28:26>	IPC11<25:24>	No

REGISTER 12-1: CCPxCON1: CAPTURE/COMPARE/PWMx CONTROL 1 REGISTER (CONTINUED)

bit 7-6 **TMRPS<1:0>:** CCPx Time Base Prescale Select bits
11 = 1:64 prescaler
10 = 1:16 prescaler
01 = 1:4 prescaler
00 = 1:1 prescaler

bit 5 **T32:** 32-Bit Time Base Select bit
1 = 32-bit time base for timer, single edge output compare or input capture function
0 = 16-bit time base for timer, single edge output compare or input capture function

bit 4 **CCSEL:** Capture/Compare Mode Select bit
1 = Input Capture mode
0 = Output Compare/PWM or Timer mode (exact function is selected by the MOD<3:0> bits)

bit 3-0 **MOD<3:0>:** CCPx Mode Select bits
CCSEL = 1 (Input Capture modes):
1xxx = Reserved
011x = Reserved
0101 = Capture every 16th rising edge
0100 = Capture every 4th rising edge
0011 = Capture every rising and falling edge
0010 = Capture every falling edge
0001 = Capture every rising edge
0000 = Capture every rising and falling edge (Edge Detect mode)
CCSEL = 0 (Output Compare modes):
1111 = External Input mode: Pulse generator is disabled, source is selected by ICS<2:0>
1110 = Reserved
110x = Reserved
10xx = Reserved
0111 = Variable Frequency Pulse mode
0110 = Center-Aligned Pulse Compare mode, buffered
0101 = Dual Edge Compare mode, buffered
0100 = Dual Edge Compare mode
0011 = 16-Bit/32-Bit Single Edge mode: Toggles output on compare match
0010 = 16-Bit/32-Bit Single Edge mode: Drives output low on compare match
0001 = 16-Bit/32-Bit Single Edge mode: Drives output high on compare match
0000 = 16-Bit/32-Bit Timer mode: Output functions are disabled

Note 1: This control bit has no function in Input Capture modes.
2: This control bit has no function when TRIGEN = 0.
3: Values greater than '0011' will cause a FIFO buffer overflow in Input Capture mode.

REGISTER 13-3: SPIxSTAT: SPIx STATUS REGISTER (CONTINUED)

bit 3 **SPITBE:** SPIx Transmit Buffer Empty Status bit
1 = Transmit buffer, SPIxTXB, is empty
0 = Transmit buffer, SPIxTXB, is not empty
Automatically set in hardware when SPIx transfers data from SPIxTXB to SPIxSR. Automatically cleared in hardware when SPIxBUF is written to, loading SPIxTXB.

bit 2 **Unimplemented:** Read as '0'

bit 1 **SPITBF:** SPIx Transmit Buffer Full Status bit
1 = Transmit has not yet started, SPIxTXB is full
0 = Transmit buffer is not full
Standard Buffer mode:
Automatically set in hardware when the core writes to the SPIxBUF location, loading SPIxTXB. Automatically cleared in hardware when the SPIx module transfers data from SPIxTXB to SPIxSR.
Enhanced Buffer mode:
Set when the CPU Write Pointer (CWPTR) + 1 = SPI Read Pointer (SRPTR); cleared otherwise.

bit 0 **SPIRBF:** SPIx Receive Buffer Full Status bit
1 = Receive buffer, SPIxRXB, is full
0 = Receive buffer, SPIxRXB, is not full
Standard Buffer mode:
Automatically set in hardware when the SPIx module transfers data from SPIxSR to SPIxRXB. Automatically cleared in hardware when SPIxBUF is read from, reading SPIxRXB.
Enhanced Buffer mode:
Set when SWPTR + 1 = CRPTR; cleared otherwise.

16.0 12-BIT ANALOG-TO-DIGITAL CONVERTER WITH THRESHOLD DETECT

Note: This data sheet summarizes the features of the PIC32MM0064GPL036 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 25. "12-Bit Analog-to-Digital Converter (ADC) with Threshold Detect"** (DS60001359) in the *"PIC32 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com/PIC32). The information in this data sheet supersedes the information in the FRM.

16.1 Introduction

The 12-bit ADC Converter with Threshold Detect includes the following features:

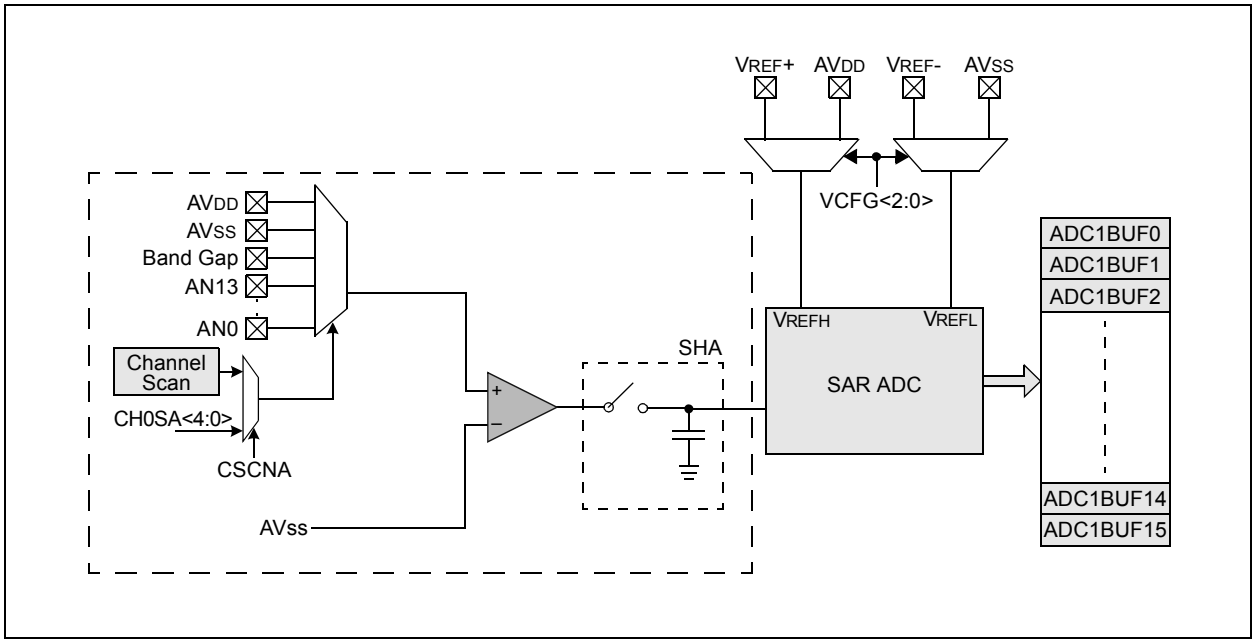
- Successive Approximation Register (SAR) Conversion
- User-Selectable Resolution of 10 or 12 Bits
- Conversion Speeds of up to 200 ksps for 12-bit mode and 300 ksps for 10-bit mode
- Up to 17 Analog Inputs (internal and external)
- External Voltage Reference Input Pins
- Unipolar Differential Sample-and-Hold Amplifier (SHA)
- Automated Threshold Scan and Compare Operation to Pre-Evaluate Conversion Results
- Selectable Conversion Trigger Source
- Fixed-Length Configurable Conversion Result Buffer
- Eight Options for Result Alignment and Encoding
- Configurable Interrupt Generation
- Operation during CPU Sleep and Idle modes

Figure 16-1 illustrates a block diagram of the 12-bit ADC. The 12-bit ADC has 14 external analog inputs, AN0 through AN13, and 3 internal analog inputs connected to VDD, VSS and band gap. In addition, there are two analog input pins for external voltage reference connections.

The analog inputs are connected through a multiplexer to the SHA. Unipolar differential conversions are possible on all inputs (see Figure 16-1).

The Automatic Input Scan mode sequentially converts multiple analog inputs. A special control register specifies which inputs will be included in the scanning sequence. The 12-bit ADC is connected to a 16-word result buffer. The 12-bit result is converted to one of eight output formats in either 32-bit or 16-bit word widths.

FIGURE 16-1: ADC BLOCK DIAGRAM



REGISTER 16-1: AD1CON1: ADC CONTROL REGISTER 1 (CONTINUED)

bit 7-4 **SSRC<3:0>:** Conversion Trigger Source Select bits
1111-1101 = Reserved
1100 = CLC2 module event ends sampling and starts conversion
1011 = CLC1 module event ends sampling and starts conversion
1010 = SCCP3 module event ends sampling and starts conversion
1001 = SCCP2 module event ends sampling and starts conversion
1000 = MCCP1 module event ends sampling and starts conversion
0111 = Internal counter ends sampling and starts conversion (auto-convert)
0110 = Timer1 period match ends sampling and starts conversion (can trigger during Sleep mode)
0101 = Timer1 period match ends sampling and starts conversion (will not trigger during Sleep mode)
0100-0010 = Reserved
0001 = Active transition on INT0 pin ends sampling and starts conversion
0000 = Clearing the SAMP bit ends sampling and starts conversion

bit 3 **MODE12:** 12-Bit Operation Mode bit
1 = 12-bit ADC operation
0 = 10-bit ADC operation

bit 2 **ASAM:** ADC Sample Auto-Start bit
1 = Sampling begins immediately after last conversion completes; SAMP bit is automatically set
0 = Sampling begins when SAMP bit is set

bit 1 **SAMP:** ADC Sample Enable bit(1)
1 = The ADC Sample-and-Hold Amplifier (SHA) is sampling
0 = The ADC Sample-and-Hold Amplifier is holding

bit 0 **DONE:** ADC Conversion Status bit(2)
1 = Analog-to-Digital conversion is done
0 = Analog-to-Digital conversion is not done or has not started
Clearing this bit will not affect any operation in progress.

Note 1: The SAMP bit is cleared and cannot be written if the ADC is disabled (ON bit = 0).
2: The DONE bit is not persistent in Automatic modes; it is cleared by hardware at the beginning of the next sample.

REGISTER 16-6: AD1CSS: ADC INPUT SCAN SELECT REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0
	—	CSS<30:28>			—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	CSS<13:8>(1,2)					
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	CSS<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31 **Unimplemented:** Read as '0'

bit 30-28 **CSS<30:28>:** ADC Input Pin Scan Selection bits
1 = Selects ANx for the input scan
0 = Skips ANx for the input scan

bit 27-14 **Unimplemented:** Read as '0'

bit 13-0 **CSS<13:0>:** ADC Input Pin Scan Selection bits(1,2)
1 = Selects ANx for the input scan
0 = Skips ANx for the input scan

Note 1: The CSS<13:11> bits are not implemented in 20-pin devices.
2: The CSS<13:12> bits are not implemented in 28-pin devices.

REGISTER 18-3: CLCxGLS: CLCx GATE LOGIC INPUT SELECT REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	G4D4T	G4D4N	G4D3T	G4D3N	G4D2T	G4D2N	G4D1T	G4D1N
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	G3D4T	G3D4N	G3D3T	G3D3N	G3D2T	G3D2N	G3D1T	G3D1N
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	G2D4T	G2D4N	G2D3T	G2D3N	G2D2T	G2D2N	G2D1T	G2D1N
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	G1D4T	G1D4N	G1D3T	G1D3N	G1D2T	G1D2N	G1D1T	G1D1N

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31 **G4D4T:** Gate 4 Data Source 4 True Enable bit
1 = The Data Source 4 signal is enabled for Gate 4
0 = The Data Source 4 signal is disabled for Gate 4

bit 30 **G4D4N:** Gate 4 Data Source 4 Negated Enable bit
1 = The Data Source 4 inverted signal is enabled for Gate 4
0 = The Data Source 4 inverted signal is disabled for Gate 4

bit 29 **G4D3T:** Gate 4 Data Source 3 True Enable bit
1 = The Data Source 3 signal is enabled for Gate 4
0 = The Data Source 3 signal is disabled for Gate 4

bit 28 **G4D3N:** Gate 4 Data Source 3 Negated Enable bit
1 = The Data Source 3 inverted signal is enabled for Gate 4
0 = The Data Source 3 inverted signal is disabled for Gate 4

bit 27 **G4D2T:** Gate 4 Data Source 2 True Enable bit
1 = The Data Source 2 signal is enabled for Gate 4
0 = The Data Source 2 signal is disabled for Gate 4

bit 26 **G4D2N:** Gate 4 Data Source 2 Negated Enable bit
1 = The Data Source 2 inverted signal is enabled for Gate 4
0 = The Data Source 2 inverted signal is disabled for Gate 4

bit 25 **G4D1T:** Gate 4 Data Source 1 True Enable bit
1 = The Data Source 1 signal is enabled for Gate 4
0 = The Data Source 1 signal is disabled for Gate 4

bit 24 **G4D1N:** Gate 4 Data Source 1 Negated Enable bit
1 = The Data Source 1 inverted signal is enabled for Gate 4
0 = The Data Source 1 inverted signal is disabled for Gate 4

bit 23 **G3D4T:** Gate 3 Data Source 4 True Enable bit
1 = The Data Source 4 signal is enabled for Gate 3
0 = The Data Source 4 signal is disabled for Gate 3

bit 22 **G3D4N:** Gate 3 Data Source 4 Negated Enable bit
1 = The Data Source 4 inverted signal is enabled for Gate 3
0 = The Data Source 4 inverted signal is disabled for Gate 3

bit 21 **G3D3T:** Gate 3 Data Source 3 True Enable bit
1 = The Data Source 3 signal is enabled for Gate 3
0 = The Data Source 3 signal is disabled for Gate 3

24.0 DEVELOPMENT SUPPORT

The PIC® microcontrollers (MCU) and dsPIC® digital signal controllers (DSC) are supported with a full range of software and hardware development tools:

- Integrated Development Environment
  - MPLAB® X IDE Software
- Compilers/Assemblers/Linkers
  - MPLAB XC Compiler
  - MPASM™ Assembler
  - MPLINK™ Object Linker/ MPLIB™ Object Librarian
  - MPLAB Assembler/Linker/Librarian for Various Device Families
- Simulators
  - MPLAB X SIM Software Simulator
- Emulators
  - MPLAB REAL ICE™ In-Circuit Emulator
- In-Circuit Debuggers/Programmers
  - MPLAB ICD 3
  - PICkit™ 3
- Device Programmers
  - MPLAB PM3 Device Programmer
- Low-Cost Demonstration/Development Boards, Evaluation Kits and Starter Kits
- Third-party development tools

24.1 MPLAB X Integrated Development Environment Software

The MPLAB X IDE is a single, unified graphical user interface for Microchip and third-party software, and hardware development tool that runs on Windows®, Linux and Mac OS® X. Based on the NetBeans IDE, MPLAB X IDE is an entirely new IDE with a host of free software components and plug-ins for high-performance application development and debugging. Moving between tools and upgrading from software simulators to hardware debugging and programming tools is simple with the seamless user interface.

With complete project management, visual call graphs, a configurable watch window and a feature-rich editor that includes code completion and context menus, MPLAB X IDE is flexible and friendly enough for new users. With the ability to support multiple tools on multiple projects with simultaneous debugging, MPLAB X IDE is also suitable for the needs of experienced users.

Feature-Rich Editor:

- Color syntax highlighting
- Smart code completion makes suggestions and provides hints as you type
- Automatic code formatting based on user-defined rules
- Live parsing

User-Friendly, Customizable Interface:

- Fully customizable interface: toolbars, toolbar buttons, windows, window placement, etc.
- Call graph window

Project-Based Workspaces:

- Multiple projects
- Multiple tools
- Multiple configurations
- Simultaneous debugging sessions

File History and Bug Tracking:

- Local file history feature
- Built-in support for Bugzilla issue tracker

24.2 MPLAB XC Compilers

The MPLAB XC Compilers are complete ANSI C compilers for all of Microchip's 8, 16 and 32-bit MCU and DSC devices. These compilers provide powerful integration capabilities, superior code optimization and ease of use. MPLAB XC Compilers run on Windows, Linux or MAC OS X.

For easy source level debugging, the compilers provide debug information that is optimized to the MPLAB X IDE.

The free MPLAB XC Compiler editions support all devices and commands, with no time or memory restrictions, and offer sufficient code optimization for most applications.

MPLAB XC Compilers include an assembler, linker and utilities. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. MPLAB XC Compiler uses the assembler to produce its object file. Notable features of the assembler include:

- Support for the entire device instruction set
- Support for fixed-point and floating-point data
- Command-line interface
- Rich directive set
- Flexible macro language
- MPLAB X IDE compatibility

24.3 MPASM Assembler

The MPASM Assembler is a full-featured, universal macro assembler for PIC10/12/16/18 MCUs.

The MPASM Assembler generates relocatable object files for the MPLINK Object Linker, Intel® standard HEX files, MAP files to detail memory usage and symbol reference, absolute LST files that contain source lines and generated machine code, and COFF files for debugging.

The MPASM Assembler features include:

- Integration into MPLAB X IDE projects
- User-defined macros to streamline assembly code
- Conditional assembly for multipurpose source files
- Directives that allow complete control over the assembly process

24.4 MPLINK Object Linker/ MPLIB Object Librarian

The MPLINK Object Linker combines relocatable objects created by the MPASM Assembler. It can link relocatable objects from precompiled libraries, using directives from a linker script.

The MPLIB Object Librarian manages the creation and modification of library files of precompiled code. When a routine from a library is called from a source file, only the modules that contain that routine will be linked in with the application. This allows large libraries to be used efficiently in many different applications.

The object linker/library features include:

- Efficient linking of single libraries instead of many smaller files
- Enhanced code maintainability by grouping related modules together
- Flexible creation of libraries with easy module listing, replacement, deletion and extraction

24.5 MPLAB Assembler, Linker and Librarian for Various Device Families

MPLAB Assembler produces relocatable machine code from symbolic assembly language for PIC24, PIC32 and dsPIC DSC devices. MPLAB XC Compiler uses the assembler to produce its object file. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. Notable features of the assembler include:

- Support for the entire device instruction set
- Support for fixed-point and floating-point data
- Command-line interface
- Rich directive set
- Flexible macro language
- MPLAB X IDE compatibility

25.0 INSTRUCTION SET

The PIC32MM0064GPL036 family instruction set complies with the MIPS® Release 3 instruction set architecture. Only microMIPS32™ instructions are supported. The PIC32MM0064GPL036 family does not have the following features:

- Core extend instructions
- Coprocessor 1 instructions
- Coprocessor 2 instructions

Note: Refer to the *"MIPS® Architecture for Programmers Volume II-B: The microMIPS32™ Instruction Set"* at www.imgtec.com for more information.

26.0 ELECTRICAL CHARACTERISTICS

This section provides an overview of the PIC32MM0064GPL036 family electrical characteristics. Additional information will be provided in future revisions of this document as it becomes available.

Absolute maximum ratings for the PIC32MM0064GPL036 family are listed below. Exposure to these maximum rating conditions for extended periods may affect device reliability. Functional operation of the device at these, or any other conditions above the parameters indicated in the operation listings of this specification, is not implied.

Absolute Maximum Ratings(†)

Ambient temperature under bias ..... -40°C to +105°C
Storage temperature ..... -65°C to +150°C
Voltage on V_{DD} with respect to V_{SS} ..... -0.3V to +4.0V
Voltage on any general purpose digital or analog pin (not 5.5V tolerant) with respect to V_{SS} ..... -0.3V to (V_{DD} + 0.3V)
Voltage on any general purpose digital or analog pin (5.5V tolerant) with respect to V_{SS}:
- When V_{DD} = 0V: ..... -0.3V to +4.0V
- When $V_{DD} \geq$ 2.0V: ..... -0.3V to +6.0V

Voltage on AV_{DD} with respect to V_{SS} ..... (V_{DD} – 0.3V) to (lesser of: 4.0V or (V_{DD} + 0.3V))
Voltage on AV_{SS} with respect to V_{SS} ..... -0.3V to +0.3V
Maximum current out of V_{SS} pin ..... 100 mA
Maximum current into V_{DD} pin(1) ..... 300 mA
Maximum output current sunk by I/O pin ..... 11 mA
Maximum output current sourced by I/O pin ..... 16 mA
Maximum output current sunk by I/O pin with increased current drive strength (RA3, RB8, RB9 and RB15) ..... 17 mA
Maximum output current sourced by I/O pin with increased current drive strength (RA3, RB8, RB9 and RB15) ..... 24 mA
Maximum current sunk by all ports ..... 300 mA
Maximum current sourced by all ports(1) ..... 300 mA

Note 1: Maximum allowable current is a function of device maximum power dissipation (see Table 26-1).

† **NOTICE:** Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

26.2 AC Characteristics and Timing Parameters

FIGURE 26-2: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS

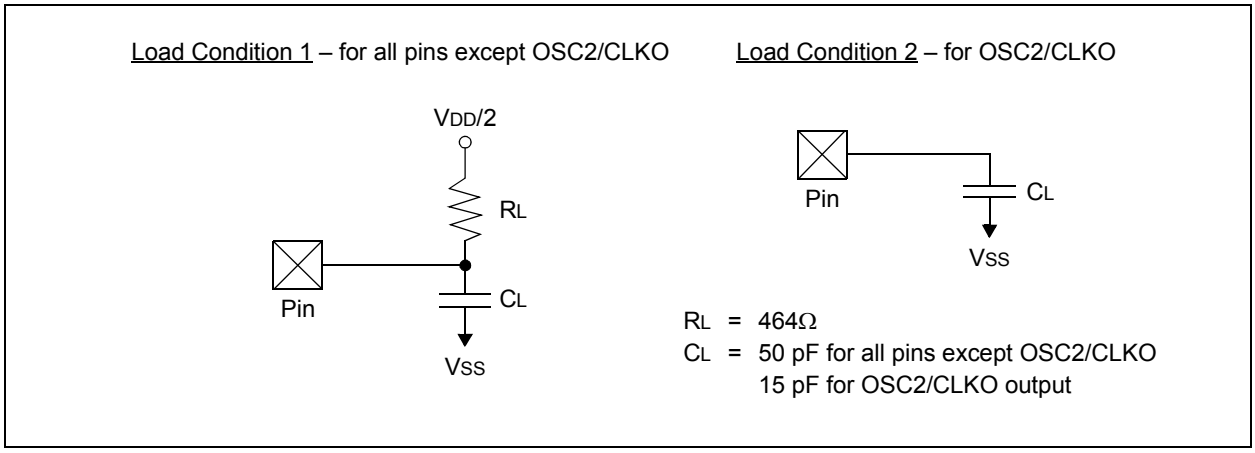
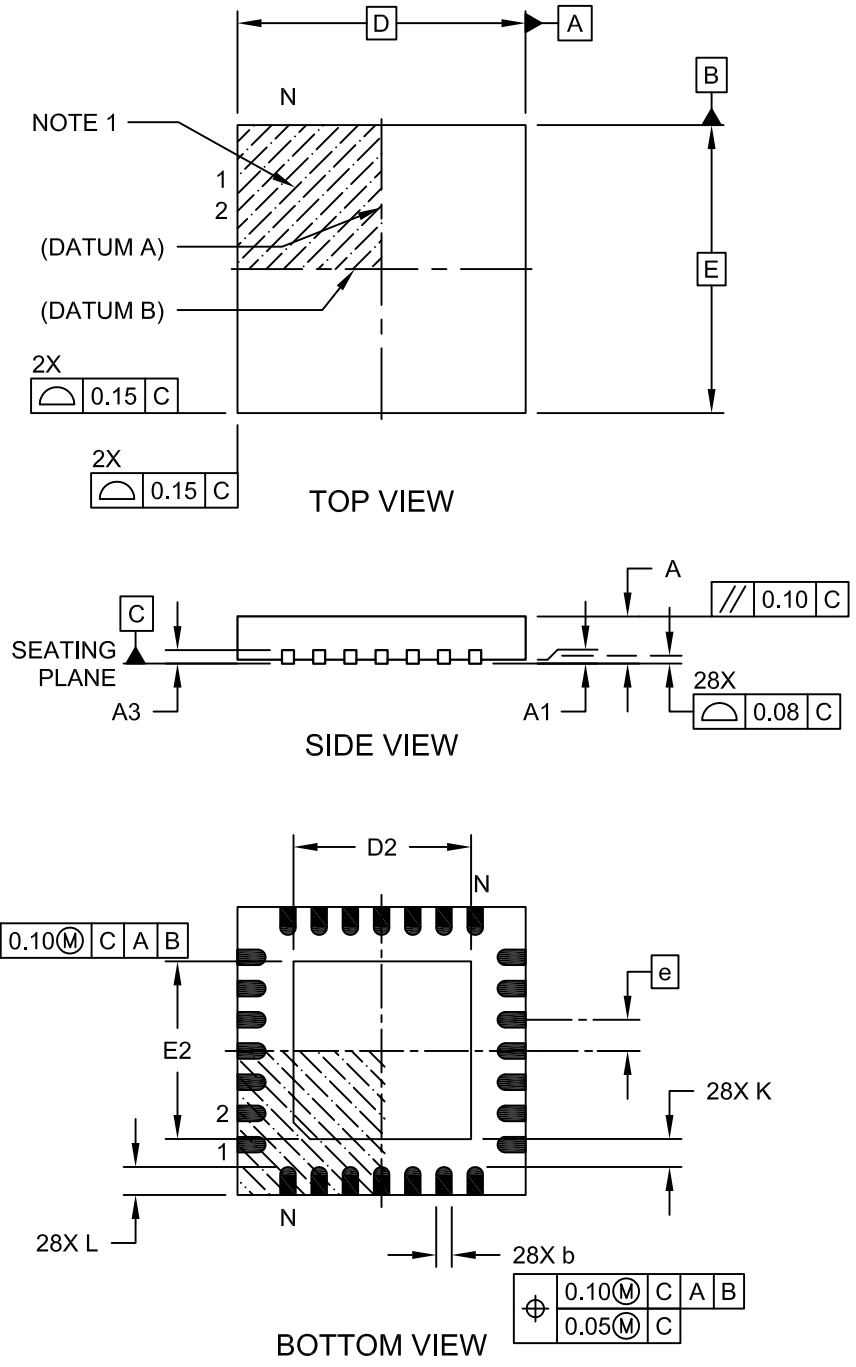


TABLE 26-16: CAPACITIVE LOADING CONDITIONS ON OUTPUT PINS

Param No.	Symbol	Characteristic	Min	Max	Units	Conditions
DO50	COSCO	OSC2/CLKO Pin	—	15	pF	In XT and HS modes when external clock is used to drive OSC1/CLKI
DO56	CIO	All I/O Pins and OSC2	—	50	pF	EC mode

28-Lead Plastic Quad Flat, No Lead Package (ML) - 6x6 mm Body [QFN]
With 0.55 mm Terminal Length

Note:	For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



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